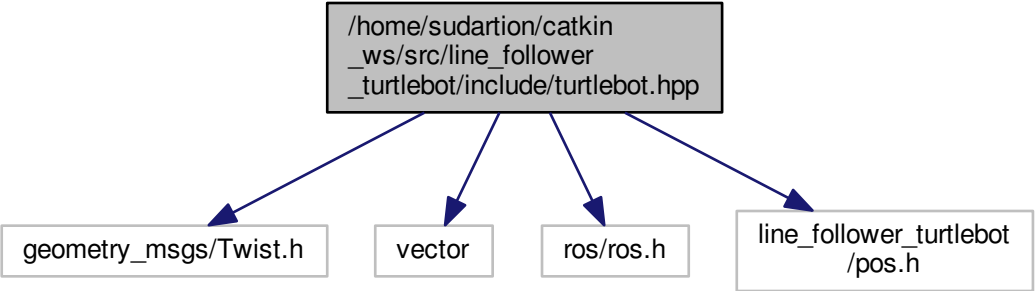


/home/sudartion/catkin  
\_ws/src/line\_follower  
\_turtlebot/include/turtlebot.hpp



```
graph TD; A["/home/sudartion/catkin_ws/src/line_follower_turtlebot/include/turtlebot.hpp"] --> B["geometry_msgs/Twist.h"]; A --> C["vector"]; A --> D["ros/ros.h"]; A --> E["line_follower_turtlebot/pos.h"];
```

The diagram illustrates the include dependencies for the file `turtlebot.hpp`. A central box at the top lists the file's path. Four arrows point downwards from this box to four separate boxes, each representing an included header file: `geometry_msgs/Twist.h`, `vector`, `ros/ros.h`, and `line_follower_turtlebot/pos.h`.

geometry\_msgs/Twist.h

vector

ros/ros.h

line\_follower\_turtlebot  
/pos.h