

Motivation

Gradient Descent

Conjugate Gradient

Find A-conjugate
Directions

Mathematics Methods for Computer Science

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Lecture

Conjugate Gradients I: Setup

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$$A \in \mathbb{R}^{n \times n} \Rightarrow$$

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$$A \in \mathbb{R}^{n \times n} \Rightarrow O(n^3)$$

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"Easy to apply, hard to invert"

- ▶ Sparse matrices
- ▶ Special structure

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Iteratively improve approximation
rather than solve in closed form.

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$$A\vec{x} = \vec{b}$$

- ▶ Square
- ▶ Symmetric
- ▶ Positive Definite

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$$A\vec{x} = \vec{b}$$

$$\min_{\vec{x}} \left[\frac{1}{2} \vec{x}^\top A \vec{x} - \vec{b}^\top \vec{x} + c \right]$$

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- 1 Compute search direction

Gradient Descent Strategy

(梯度下降策略)

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- 1 Compute search direction

$$\vec{d}_k \equiv -\nabla f(\vec{x}_{k-1}) = \vec{b} - A\vec{x}_{k-1}$$

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$$\vec{d}_k \equiv -\nabla f(\vec{x}_{k-1}) = \vec{b} - A\vec{x}_{k-1}$$

- 2 Do line search to find

$$\vec{x} \equiv \vec{x}_{k-1} + \alpha_k \vec{d}_k$$

(fixed point iteration)

Line Search Along \vec{d} from \vec{x}

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$$\min_{\alpha} g(\alpha) \equiv f(\vec{x} + \alpha \vec{d})$$

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$$\min_{\alpha} g(\alpha) \equiv f(\vec{x} + \alpha \vec{d})$$

$$\alpha = \frac{\vec{d}^\top (\vec{b} - A\vec{x})}{\vec{d}^\top A\vec{d}}$$

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$$\vec{d}_k = \vec{b} - A\vec{x}_{k-1}$$

$$\alpha = \frac{\vec{d}^\top \vec{d}}{\vec{d}^\top A \vec{d}}$$

$$\vec{x} = \vec{x}_{k-1} + \alpha_k \vec{d}_k$$

Change of **backward errors** in iteration k (See book)

$$R_k \equiv \frac{f(\vec{x}_k) - f(\vec{x}^*)}{f(\vec{x}_{k-1}) - f(\vec{x}^*)} \leq 1 - \frac{1}{\text{cond}A}$$

后向误差 R_k 对于速度、质量的影响：
条件数越大，越poorly conditioned
，从而收敛越慢，需要的迭代次数越
多，并且误差较大。

Conclusions:

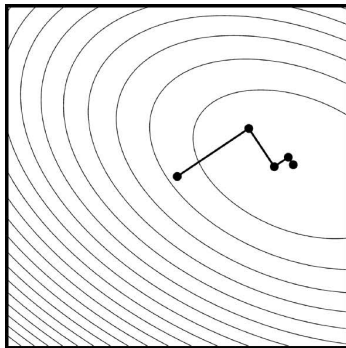
- ▷ **Conditioning** affects **speed** and **quality**
- ▷ **Unconditional convergence** ($\text{cond}A \geq 1$)

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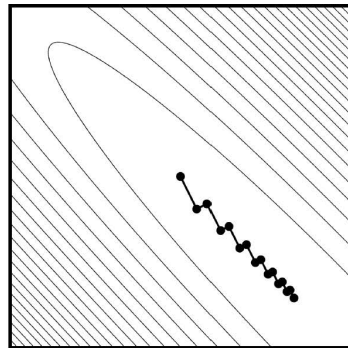
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Well conditioned A



Poorly conditioned A

此图说明了条件数对于梯度下降法找根的算法的性能影响很大。

- ▶ **Can iterate forever:**
Should stop after $O(n)$ iterations!
- ▶ **Lots of repeated work**
when **poorly conditioned**

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$$f(\vec{x}) = \frac{1}{2} (\vec{x} - \vec{x}^*)^\top A (\vec{x} - \vec{x}^*) + \text{const.}$$

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$$f(\vec{x}) = \frac{1}{2} (\vec{x} - \vec{x}^*)^\top A (\vec{x} - \vec{x}^*) + \text{const.}$$

$$A = LL^T$$

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$$f(\vec{x}) = \frac{1}{2} (\vec{x} - \vec{x}^*)^\top A (\vec{x} - \vec{x}^*) + \text{const.}$$

$$A = LL^\top$$

$$\implies f(\vec{x}) = \frac{1}{2} \|L^\top (\vec{x} - \vec{x}^*)\|_2^2 + \text{const.}$$

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$$\begin{aligned}\vec{y} &\equiv L^\top \vec{x}, & \vec{y}^* &\equiv L^\top \vec{x}^* \\ \implies \bar{f}(\vec{y}) &= \|\vec{y} - \vec{y}^*\|_2^2\end{aligned}$$

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Proposition

Suppose $\{\vec{w}_1, \dots, \vec{w}_n\}$ are orthogonal in \mathbb{R}^n . Then, \bar{f} is minimized in at most n steps by line searching in direction \vec{w}_1 , then direction \vec{w}_2 ; and so on.

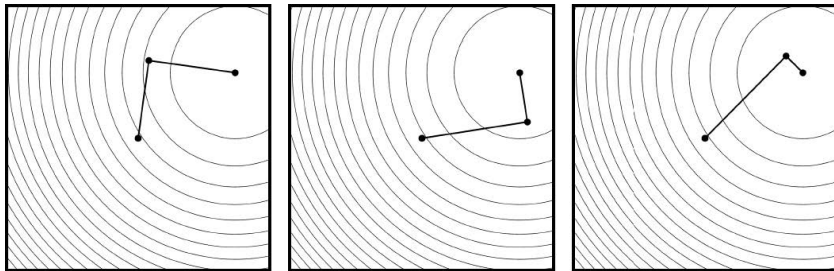
可以如此理解：取正交基 x, y, z ，则相当于在三个方向上面分别找到最小点，则组合起来就是空间上的最小点。

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Any two orthogonal directions suffice!

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Line search on \bar{f} along \vec{w} is the same as line search
on f along $(L^\top)^{-1}\vec{w}$.

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Line search on \bar{f} along \vec{w} is the same as line search on f along $(L^\top)^{-1}\vec{w}$.

$$\begin{aligned} 0 &= \vec{w}_i \cdot \vec{w}_j = (L^\top \vec{v}_i)^\top (L^\top \vec{v}_j) \\ &= \vec{v}_i^\top (LL^\top) \vec{v}_j = \vec{v}_i^\top A \vec{v}_j \end{aligned}$$

(A-共轭向量)

A-Conjugate Vectors

Two vectors \vec{v} and \vec{w} are A -conjugate if $\vec{v}A\vec{w} = 0$.

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A-Conjugate Vectors

Two vectors \vec{v} and \vec{w} are A -conjugate if $\vec{v}A\vec{w} = 0$.

Corollary

Suppose $\{\vec{v}_1, \dots, \vec{v}_n\}$ are **A-conjugate**. Then, f is minimized in at most n steps by line searching **in direction \vec{v}_1 ; then direction \vec{v}_2 , and so on.**

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- ▶ Steepest descent may not be fastest descent (surprising!)

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- ▶ Two inner products:

$$\vec{v} \cdot \vec{w}$$

$$\langle \vec{v}, \vec{w} \rangle_A \equiv \vec{v}^\top A \vec{w} \quad (\text{A内积})$$

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Find n A -conjugate directions.

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▷ Potentially unstable

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- ▶ Potentially unstable
- ▶ Storage increases with each iteration

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$$\vec{r}_k \equiv \vec{b} - A\vec{x}_k$$

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$$\begin{aligned}\vec{r}_k &\equiv \vec{b} - A\vec{x}_k \\ \vec{r}_{k+1} &= \vec{r}_k - \alpha_{k+1}A\vec{v}_{k+1}\end{aligned}$$

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$$\vec{r}_k \equiv \vec{b} - A\vec{x}_k$$
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Proposition

When performing gradient descent on f ,
 $\text{span} \{ \vec{r}_0, \dots, \vec{r}_k \} = \text{span} \{ \vec{r}_0, A\vec{r}_0, \dots, A^k \vec{r}_0 \}$

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Krylov space?!

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$$\vec{x}_k - \vec{x}_0 \neq \operatorname{argmin}_{\vec{v} \in \operatorname{span}\{\vec{r}_0, A\vec{r}_0, \dots, A^{k-1}\vec{r}_0\}} f(\vec{x}_0 + \vec{v})$$

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But if this did hold ...
Convergence in n steps!