

# Learning From Data Lecture 2 The Perceptron

The Learning Setup A Simple Learning Algorithm: PLA Other Views of Learning Is Learning Feasible: A Puzzle

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## RECAP: The Key Players

• Salary, debt, years in residence, . . .

input 
$$\mathbf{x} \in \mathbb{R}^d = \mathcal{X}$$
.

• Approve credit or not

output 
$$y \in \{-1, +1\} = \mathcal{Y}$$
.

 $\bullet$  True relationship between **x** and y

target function  $f: \mathcal{X} \mapsto \mathcal{Y}$ .

(The target f is unknown.)

• Data on customers

data set 
$$\mathcal{D} = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N).$$
  
 $(y_n = f(\mathbf{x}_n).)$ 

 $\mathcal{X} \mathcal{Y}$  and  $\mathcal{D}$  are *given* by the learning problem; The target f is fixed but unknown.

We learn the function f from the data  $\mathcal{D}$ .

### RECAP: Summary of the Learning Setup

# UNKNOWN TARGET FUNCTION $f: \mathcal{X} \mapsto \mathcal{Y}$ (ideal credit approval formula) $y_n = f(\mathbf{x}_n)$ TRAINING EXAMPLES $(\mathbf{x}_1,y_1),(\mathbf{x}_2,y_2),\ldots,(\mathbf{x}_N,y_N)$ (historical records of credit customers) **FINAL LEARNING HYPOTHESIS** ALGORITHM $g \approx f$ $\mathcal{A}$ (learned credit approval formula) HYPOTHESIS SET $\mathcal{H}$ (set of candidate formulas)

## A Simple Learning Model

- Input vector  $\mathbf{x} = [x_1, \dots, x_d]^{\mathrm{T}}$ .
- Give importance weights to the different inputs and compute a "Credit Score"

"Credit Score" = 
$$\sum_{i=1}^{d} w_i x_i$$
.

• Approve credit if the "Credit Score" is acceptable.

Approve credit if 
$$\sum_{i=1}^{d} w_i x_i > \text{threshold}$$
, ("Credit Score" is good)

Deny credit if  $\sum_{i=1}^{d} w_i x_i < \text{threshold}$ . ("Credit Score" is bad)

ullet How to choose the importance weights  $w_i$ 

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input x_i is important \implies large weight |w_i| input x_i beneficial for credit \implies positive weight w_i > 0 input x_i detrimental for credit \implies negative weight w_i < 0
```

## A Simple Learning Model

Approve credit if 
$$\sum_{i=1}^{d} w_i x_i > \text{threshold},$$

Deny credit if  $\sum_{i=1}^{d} w_i x_i < \text{threshold}.$ 

can be written formally as

$$h(\mathbf{x}) = \operatorname{sign}\left(\left(\sum_{i=1}^{d} w_i x_i\right) + w_0\right)$$

The "bias weight"  $w_0$  corresponds to the threshold. (How?)

## The Perceptron Hypothesis Set

We have defined a Hyopthesis set  $\mathcal{H}$ 

$$\mathcal{H} = \{h(\mathbf{x}) = \operatorname{sign}(\mathbf{w}^{\mathsf{T}}\mathbf{x})\}$$
 — uncountably infinite  $\mathcal{H}$ 

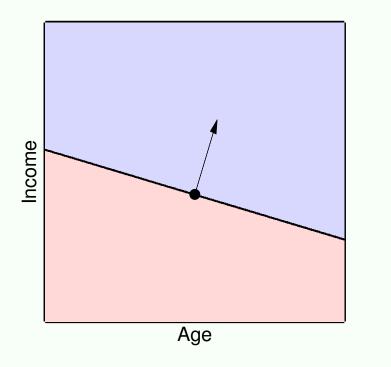
$$\mathbf{w} = \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ w_d \end{bmatrix} \in \mathbb{R}^{d+1}, \qquad \mathbf{x} = \begin{bmatrix} 1 \\ x_1 \\ \vdots \\ x_d \end{bmatrix} \in \{1\} \times \mathbb{R}^d.$$

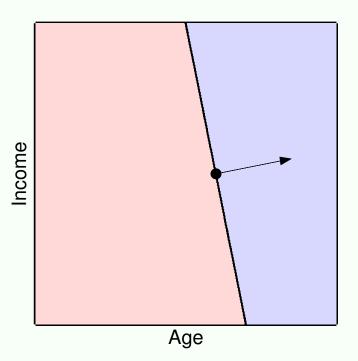
This hypothesis set is called the *perceptron* or *linear separator* 

# Geometry of The Perceptron

$$h(\mathbf{x}) = \operatorname{sign}(\mathbf{w}^{\mathsf{T}}\mathbf{x})$$

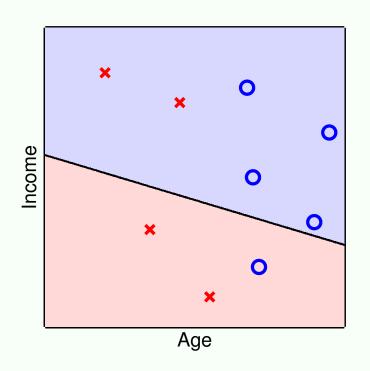
(Problem 1.2 in LFD)

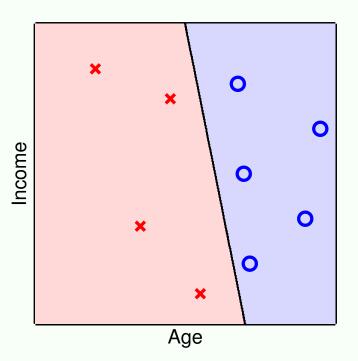




Which one should we pick?

#### Use the Data to Pick a Line





A perceptron fits the data by using a line to separate the +1 from -1 data.

**Fitting the data:** How to find a hyperplane that *separates* the data? ("It's obvious - just look at the data and draw the line," is not a valid solution.)

# How to Learn a Final Hypothesis g from $\mathcal{H}$

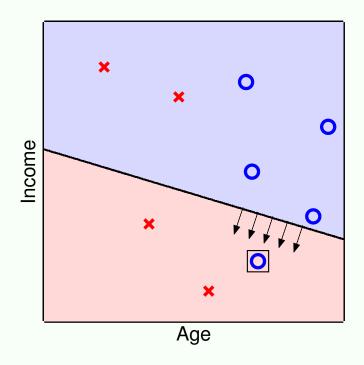
We want to select  $g \in \mathcal{H}$  so that  $g \approx f$ .

We certainly want  $g \approx f$  on the data set  $\mathcal{D}$ . Ideally,

$$g(\mathbf{x}_n) = y_n.$$

How do we find such a g in the *infinite* hypothesis set  $\mathcal{H}$ , if it exists?

Idea! Start with some weight vector and try to improve it.



# The Perceptron Learning Algorithm (PLA)

A simple iterative method.

1: 
$$\mathbf{w}(1) = \mathbf{0}$$

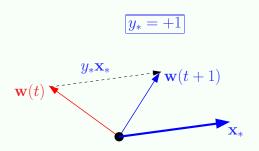
- 2: **for** iteration t = 1, 2, 3, ...
- 3: the weight vector is  $\mathbf{w}(t)$ .
- 4: From  $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)$  pick any misclassified example.
- 5: Call the misclassified example  $(\mathbf{x}_*, y_*)$ ,

$$sign\left(\mathbf{w}(t) \bullet \mathbf{x}_*\right) \neq y_*.$$

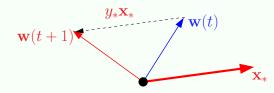
6: Update the weight:

$$\mathbf{w}(t+1) = \mathbf{w}(t) + y_* \mathbf{x}_*.$$

7: 
$$t \leftarrow t + 1$$



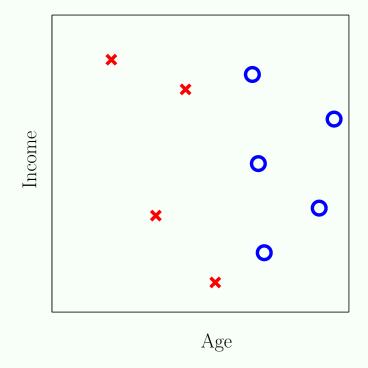




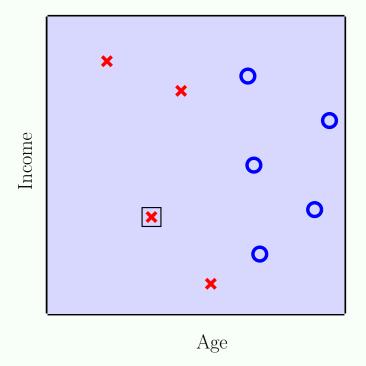
PLA implements our idea: start at some weights and try to improve.

"incremental learning" on a single example at a time

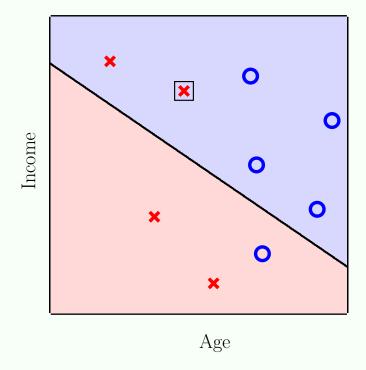
**Theorem.** If the data can be fit by a linear separator, then after some *finite* number of steps, PLA will find one.



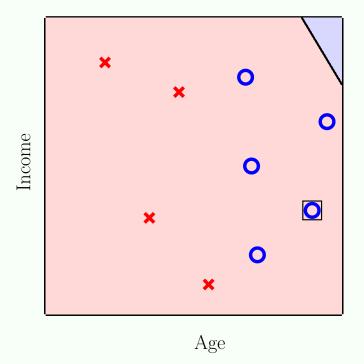
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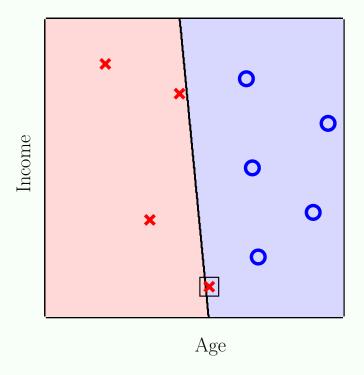
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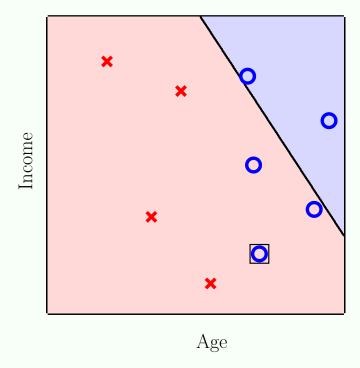


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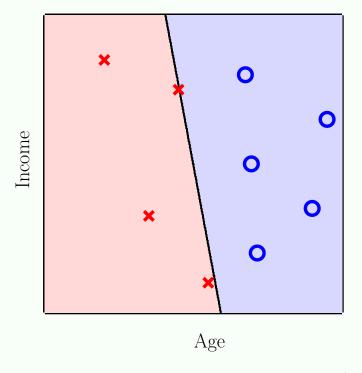
ITERATION 4

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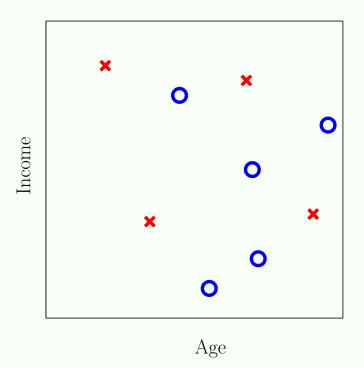
After how long?



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After how long?

What if the data cannot be fit by a perceptron?



#### We can Fit the Data

- We can find an h that works from <u>infinitely</u> many (for the perceptron). (So computationally, things seem good.)
- Ultimately, remember that we want to *predict*.

  We don't care about the data, we care about "outside the data".

Can a limited data set reveal enough information to pin down an entire target function, so that we can predict outside the data?

### Other Views of Learning

- Design: learning is from data, design is from specs and a model.
- Statistics, Function Approximation.
- Data Mining: find patterns in massive data (typically unsupervised).
- Three Learning Paradigms
  - Supervised: the data is  $(\mathbf{x}_n, f(\mathbf{x}_n))$  you are told the answer.
  - Reinforcement: you get feedback on potential answers you try:

 $\mathbf{x} \rightarrow \text{try something} \rightarrow \text{get feedback}.$ 

- Unsupervised: only given  $\mathbf{x}_n$ , learn to "organize" the data.