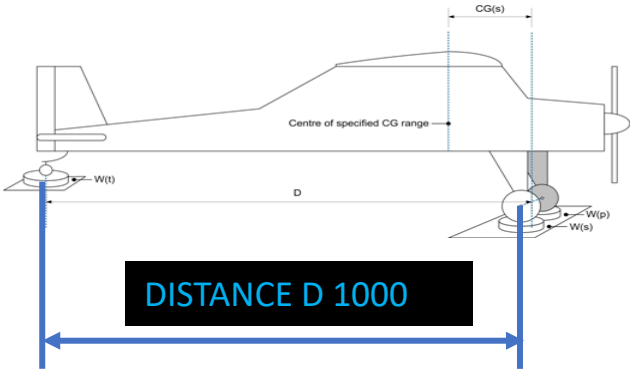# Arduino On / There should be nothing on the load

Main Page

```
DISTANCE D 1000
DISTANCE WHEEL TO WHEEL
[                                    ]


WHEEL          CG          SETUP
```


CG(s)

Centre of specified CG range

W(t)

D

W(p)
W(s)

DISTANCE D 1000

Sub page of Main Page

```
DISTANCE D 1000
ROTARY CONTROL ON PAGE
[                        ]

VALUE 1000
```
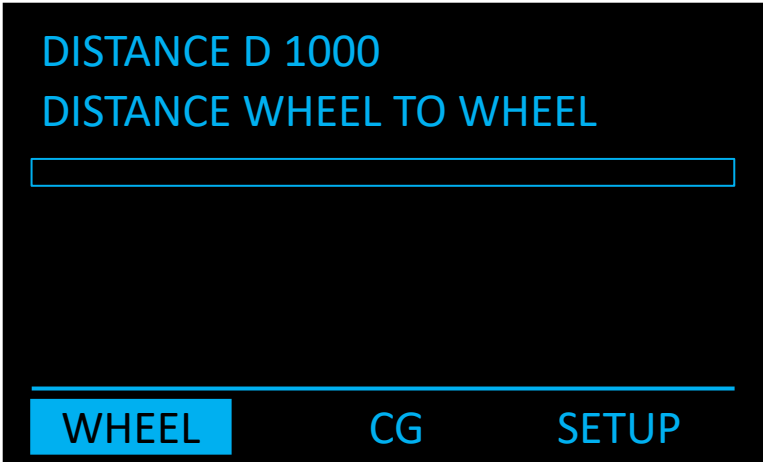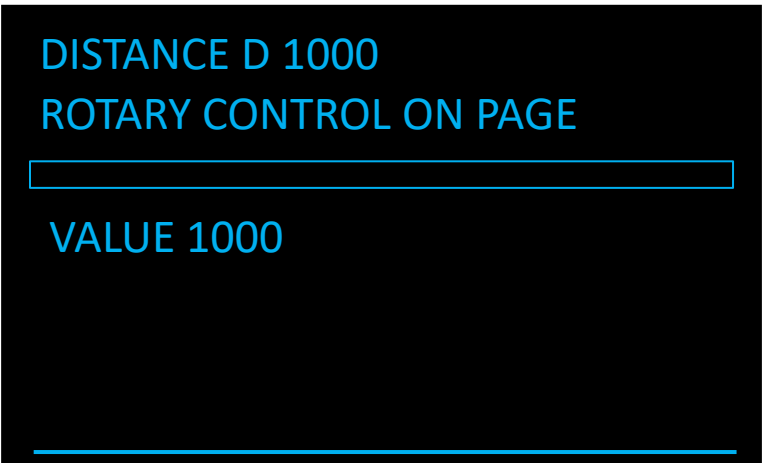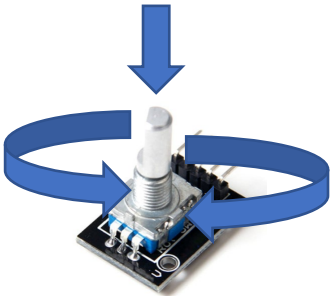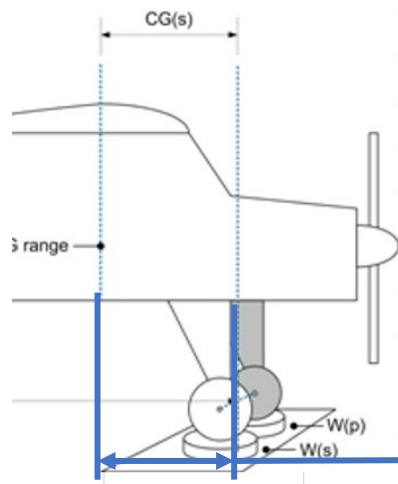
Access Sus-Page

Move submenu using rotary switch, Enter D value using rotary, Move main page using rotary switch.
When moving the main page using the rotary switch, the value is automatically stored in the EEPROM.

Second Page

DISTANCE CG 1000
DISTANCE WHEEL TO CG
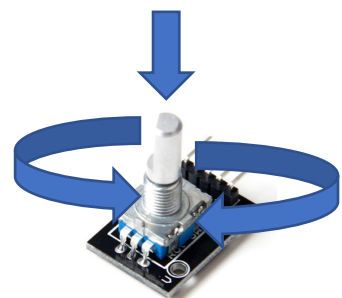
| WHEEL | CG | SETUP |

CG(s)

range

W(p)
W(s)

DISTANCE CG 1000
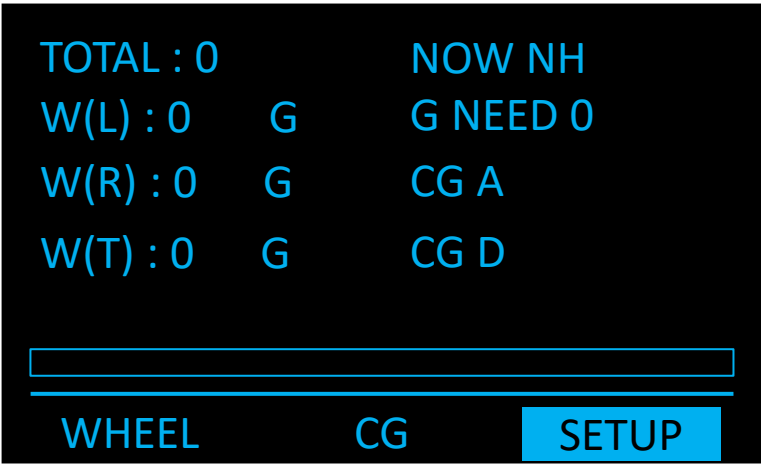
Sub page of Second Page

DISTANCE CG 1000
ROTARY CONTROL ON PAGE

VALUE 1000

Access Sus-Page

Move submenu using rotary switch, Enter CG value using rotary, Move main page using rotary switch.
When moving the Second page using the rotary switch, the value is automatically stored in the EEPROM.

TOTAL : 0	**NOW NH**
W(L) : 0 G	**G NEED 0**
W(R) : 0 G	**CG A**
W(T) : 0 G	**CG D**

WHEEL	**CG**	**SETUP**

TOTAL : 0	Total weight / Unit g
W(L) : G	Left wheel weight/ Unit g
W(R) : G	Right wheel weight / Unit g
W(T) : G	Tail wheel weight / Unit g
NOW NH	If the Head is heavy (Tail Light)
NOW TH	If the Tail is heavy (Head Light)
NEED 0	Weight required for Valence
CG A	Current CG location
CG D	Distance difference from CG entered