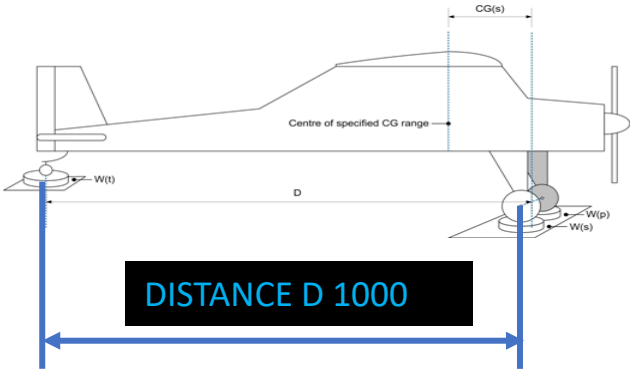# Arduino On / There should be nothing on the load

Main Page

DISTANCE D 1000
DISTANCE WHEEL TO WHEEL

WHEEL   CG   SETUP

CG(s)

Centre of specified CG range

W(t)

D

W(p)
W(s)

DISTANCE D 1000

Sub page of Main Page

DISTANCE D 1000
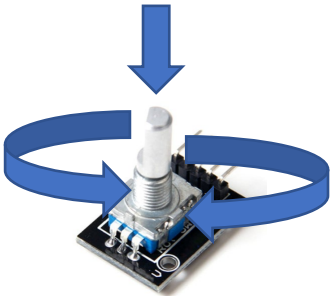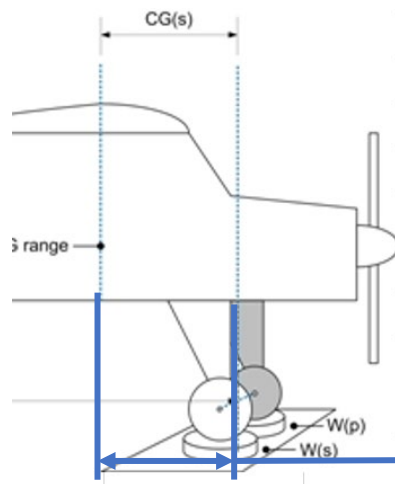ROTARY CONTROL ON PAGE

VALUE 1000
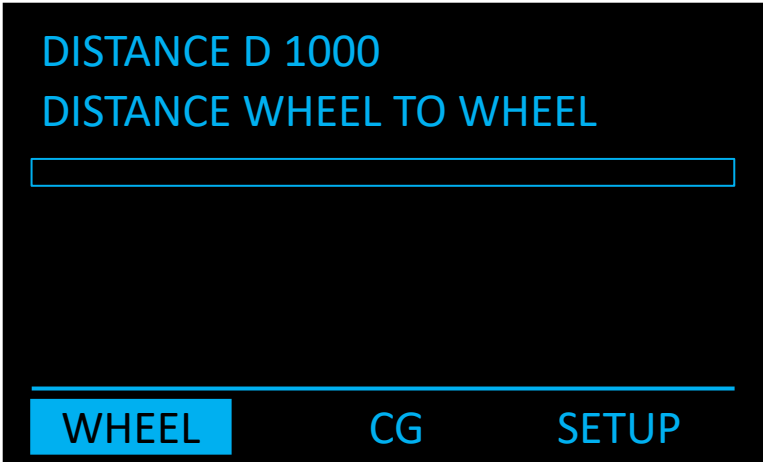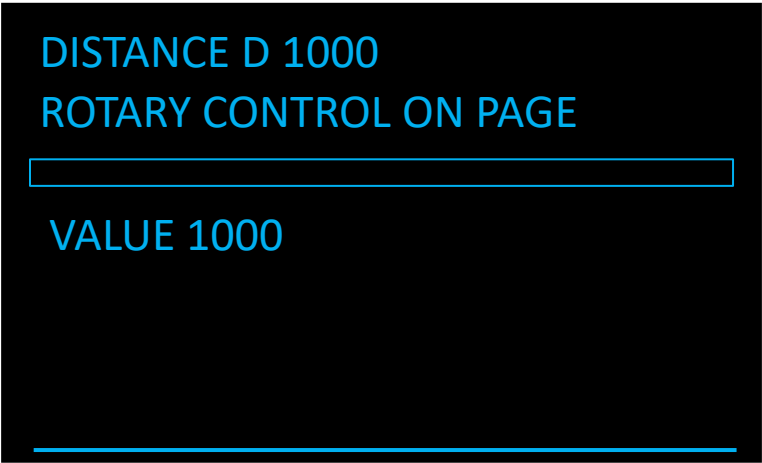
Access Sus-Page

Move submenu using rotary switch, Enter D value using rotary,
Move main page using rotary switch.
When moving the main page using the rotary switch, the value
is automatically stored in the EEPROM.

Second Page

DISTANCE CG 1000
DISTANCE WHEEL TO CG

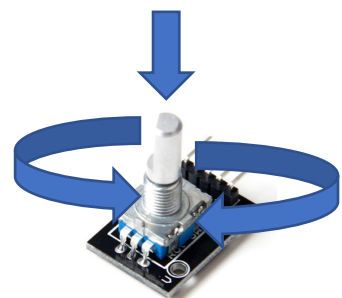WHEEL   CG   SETUP

CG(s)

range

W(p)
W(s)

DISTANCE CG 1000
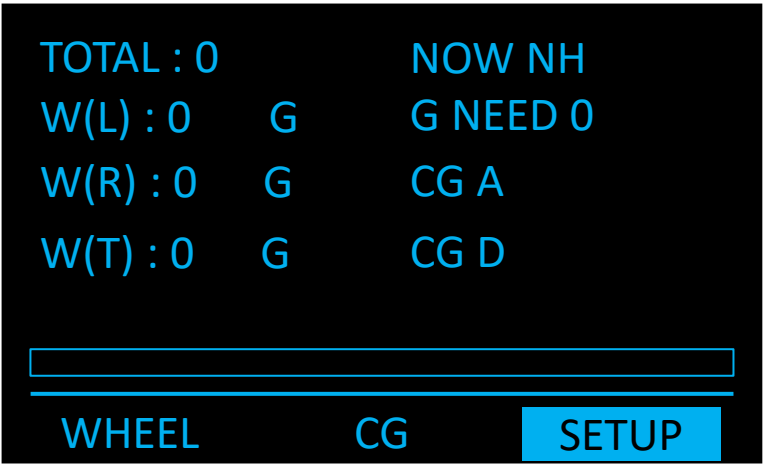
Sub page of Second Page

DISTANCE CG 1000
ROTARY CONTROL ON PAGE

VALUE 1000

Access Sus-Page

Move submenu using rotary switch, Enter CG value using rotary,
Move main page using rotary switch.
When moving the Second page using the rotary switch, the
value is automatically stored in the EEPROM.

TOTAL : 0	NOW NH
W(L) : 0 G	G NEED 0
W(R) : 0 G	CG A
W(T) : 0 G	CG D

| WHEEL | CG | SETUP |

TOTAL : 0	Total weight / Unit g
W(L) : G	Left wheel weight/ Unit g
W(R) : G	Right wheel weight / Unit g
W(T) : G	Tail wheel weight / Unit g
NOW NH	If the Head is heavy (Tail Light)
NOW TH	If the Tail is heavy (Head heavy)
NEED 0	Weight required for Valence
CG A	Current CG location
CG D	CG location entered