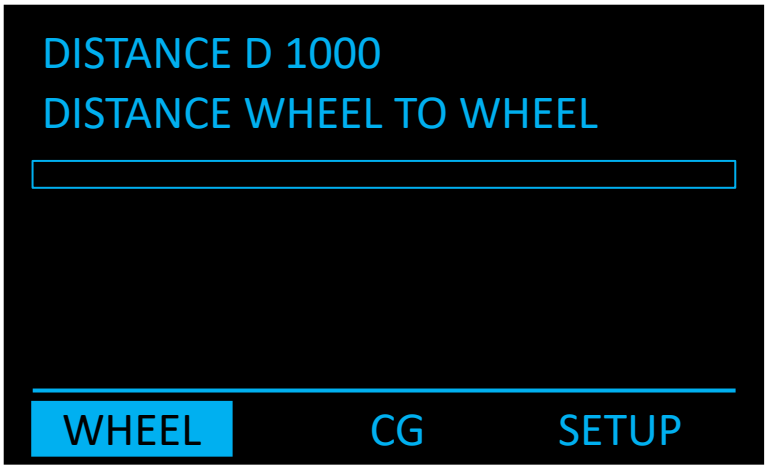
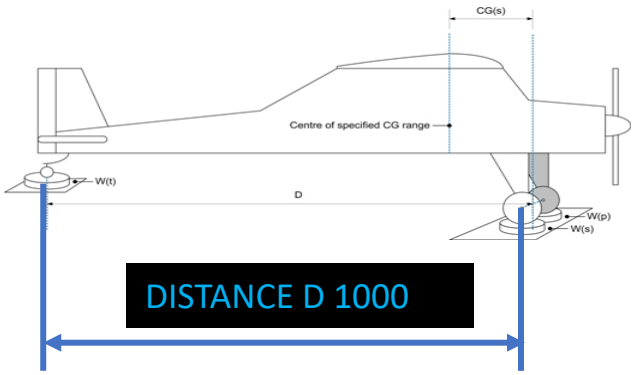
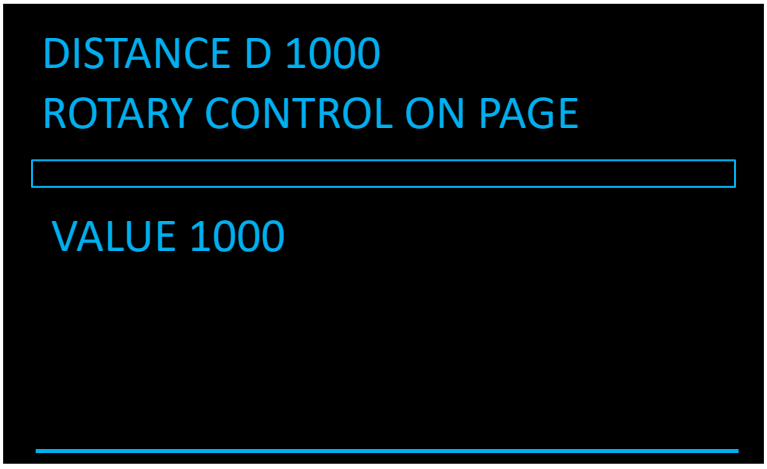
Arduino On / There should be nothing on the load

Main Page

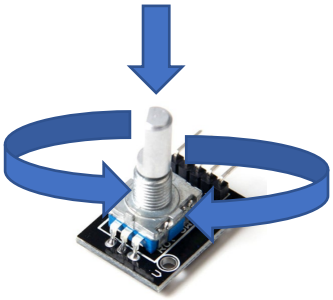




Sub page of Main Page

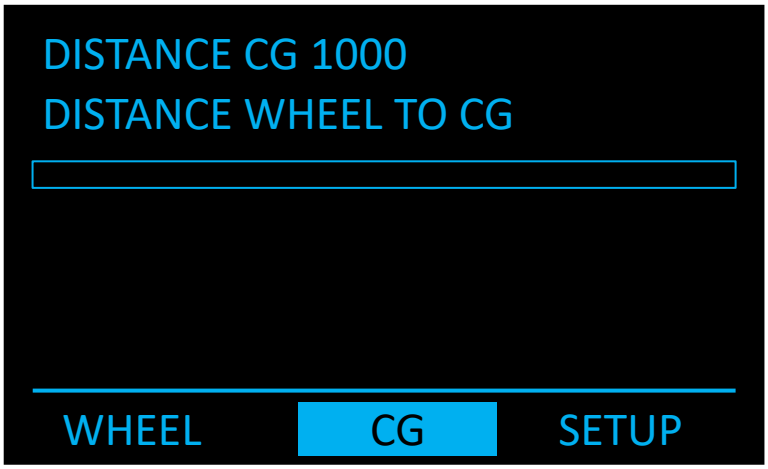


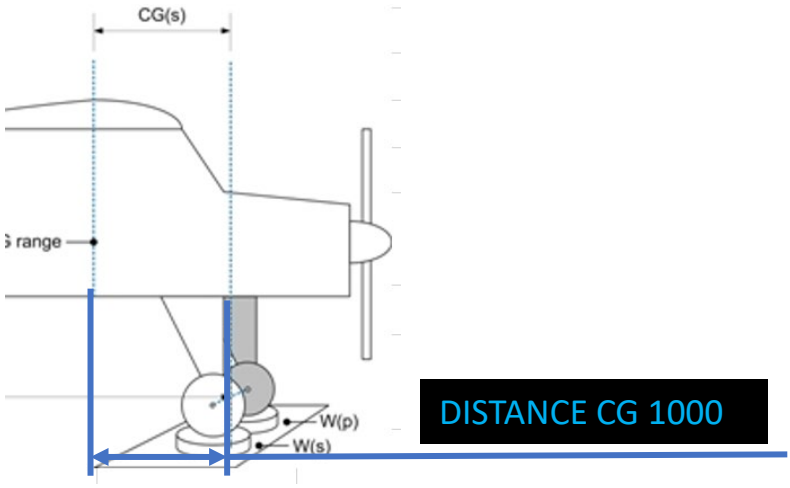
Access Sus-Page



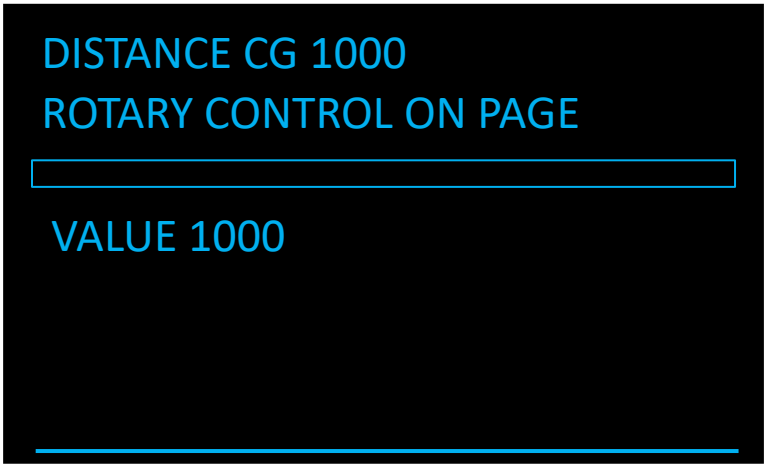
Move submenu using rotary switch, Enter D value using rotary, Move main page using rotary switch.
When moving the main page using the rotary switch, the value is automatically stored in the EEPROM.

Second Page

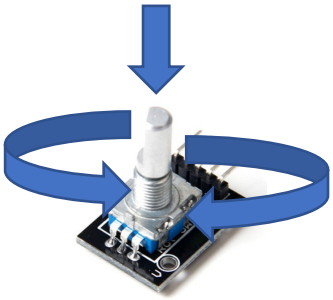




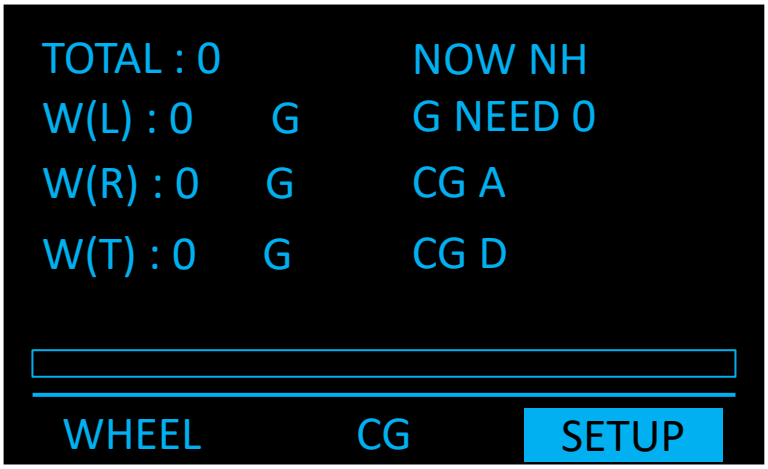
Sub page of Second Page



Access Sus-Page



Move submenu using rotary switch, Enter CG value using rotary, Move main page using rotary switch.
When moving the Second page using the rotary switch, the value is automatically stored in the EEPROM.



TOTAL : 0	Total weight / Unit g
W(L) : G	Left wheel weight/ Unit g
W(R) : G	Right wheel weight / Unit g
W(T) : G	Tail wheel weight / Unit g
NOW NH	If the Head is heavy (Tail Light)
NOW TH	If the Tail is heavy (Head heavy)
NEED 0	Weight required for Valence
CG A	Current CG location
CG D	Distance difference from CG entered