## Deep Bayes summer school

## Practical Session: Approximate Bayesian inference

## August 20, 2019

Consider a clustering problem: we have a dataset  $X = \{x_i\}_{i=1}^N$ , where  $x_i \in \mathbb{R}$  — scalar features, and want to group these objects into K clusters. To do so we assume that points from the dataset were generated from a Gaussian Mixture Model (GMM) with K components. For each object  $x_i$  we establish additional latent variable  $z_i$  which denotes the index of the gaussian from which i-th object was generated. For convenience we use binary vector notation for  $z_i$ :  $z_i \in \{0,1\}^K$ ,  $\sum_{k=1}^K z_{ik} = 1$ .

Below we consider several variations of Gaussian Mixture Model for clustering problem with different prior assumptions. The task is to choose a suitable method of training for each of them and write down formulas for training: find optimal values of parameters and find a posterior distribution of latent variables.

1. [Basic GMM – no additional priors] A probabilistic model of standard GMM looks as follows:

$$p(X, Z | \pi, \mu, \lambda) = \prod_{i=1}^{N} p(z_i | \pi) p(x_i | z_i, \mu, \lambda) = \prod_{i=1}^{N} \prod_{k=1}^{K} \left[ \pi_k \mathcal{N}(x_i | \mu_k, \lambda_k^{-1}) \right]^{z_{ik}}$$

Parameter  $\pi = (\pi_1, \dots, \pi_K)$  denotes probabilities of Gaussian components in the mixture and is restricted to simplex:  $\sum_{k=1}^K \pi_k = 1$  and  $\pi_k \geq 0$  for  $k = 1, \dots, K$ .  $\mu$  and  $\lambda$  contain parameters of Gaussian components ( $\lambda$  contains inverse variances).

Before reading further, try to choose a suitable method to train this model by yourself.

We can train this model with EM-algorithm because (i) there are both latent variables and parameters in the model and (ii) the prior on Z and the likelihood are conjugate.

- (a) Check that the prior distribution  $p(Z|\pi)$  and the likelihood  $p(X|Z,\pi,\mu,\lambda)$  are conjugate.
- (b) E-step: derive the posterior distribution  $p(Z|X,\pi,\mu,\lambda)$ . Values of  $\pi,\mu,\lambda$  are fixed on this step.
- (c) M-step: compute optimal values of  $\pi, \mu, \lambda$  by maximizing  $\mathbb{E}_{p(Z|X,\pi,\mu,\lambda)} \log p(X,Z|\pi,\mu,\lambda)$ . Posterior distribution  $p(Z|X,\pi,\mu,\lambda)$  is fixed on this step.
- 2. [GMM with prior on  $\pi$ ] We can add Dirichlet prior on probabilities of Gaussian components  $\pi$  to obtain either sparse or more even clusters (depending on values of parameters  $\alpha$  of the prior). A probabilistic model, in this case, looks as follows:

$$p(X, Z, \pi | \mu, \lambda) = p(\pi) \prod_{i=1}^{N} p(z_i | \pi) p(x_i | z_i, \mu, \lambda) = \text{Dir}(\pi | \alpha) \prod_{i=1}^{N} \prod_{k=1}^{K} \left[ \pi_k \mathcal{N}(x_i | \mu_k, \lambda_k^{-1}) \right]^{z_{ik}}$$

Here parameter  $\alpha$  is fixed (we do not train it).  $\alpha < 1$  gives sparse solutions,  $\alpha > 1$  results in more even clusters. Before reading further, try to choose a suitable method to train this model by yourself.

To train this model we need variational EM-algorithm because the prior on  $Z, \pi$  and the likelihood are not conjugate.

- (a) Check that the prior distribution  $p(Z,\pi)$  and the likelihood  $p(X|Z,\pi,\mu,\lambda)$  are not conjugate.
- (b) Check that there is a conditional conjugacy between the prior and the likelihood if we use the following factorization:  $p(Z, \pi | X, \mu, \lambda) \approx q(Z, \pi) = q(Z)q(\pi)$ .
- (c) E-step: write down update rules for q(Z) and  $q(\pi)$  as in variational inference. Values of  $\mu, \lambda$  are fixed on this step.
- (d) M-step: compute optimal values of  $\mu, \lambda$  by maximizing  $\mathbb{E}_{p(Z|X,\pi,\mu,\lambda)} \log p(X,Z|\pi,\mu,\lambda)$ . Posterior approximation  $q(Z)q(\pi)$  is fixed on this step.

\* [GMM with priors on  $\pi, \mu, \lambda$ ] We can add Normal-Gamma priors on parameters of Gaussian components  $\mu_k, \lambda_k$  to make the model prefer clusters of specific form or location. A probabilistic model, in this case, looks as follows:

$$p(X, Z, \pi, \mu, \lambda) = p(\pi) \left[ \prod_{k=1}^{K} p(\mu_k, \lambda_k) \right] \prod_{i=1}^{N} p(z_i | \pi) p(x_i | z_i, \mu, \lambda)$$

$$= \operatorname{Dir}(\pi | \alpha) \left[ \prod_{k=1}^{K} \mathcal{N}(\mu_k | m, (\beta \lambda_k)^{-1}) \mathcal{G}(\lambda_k | a, b) \right] \prod_{i=1}^{N} \prod_{k=1}^{K} \left[ \pi_k \mathcal{N}(x_i | \mu_k, \lambda_k^{-1}) \right]^{z_{ik}}$$

Here  $\alpha, m, \beta, a, b$  are fised (we do not train them).

To train this model we need variational EM-algorithm because the prior on  $Z, \pi, \mu, \lambda$  and the likelihood are not conjugate. On E-step mean-field approximation should be used with the following factorization:

$$p(Z, \pi, \mu, \lambda | X) \approx q(Z, \pi, \mu, \lambda) = q(Z)q(\pi, \mu, \lambda).$$

## Useful formulas

Normal distribution:

$$\mathcal{N}(x|\mu,\lambda^{-1}) = \sqrt{\frac{\lambda}{2\pi}} \exp\left[-\frac{1}{2}(x-\mu)^2\lambda\right]$$

Dirichlet distribution:

$$Dir(\pi|\alpha) = \frac{1}{B(\alpha_1, \dots, \alpha_K)} \prod_{k=1}^K \pi_k^{\alpha_k - 1}, \quad \pi \in S_K$$