

# Deep Learning

Winter term 25/26 – Exercise Sheet **ML Recap**

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$\mathcal{X}$	Space of inputs (e.g., $\mathbb{R}^d$ or space of images)
$x \in \mathcal{X}$	sample from $\mathcal{X}$
$\mathcal{Y}$	Space of outputs/targets/labels (e.g., $\mathbb{R}$ for regression or $\{0, 1\}$ for binary classification)
$y \in \mathcal{Y}$	true label/target value in $\mathcal{Y}$
$\mathbb{P}_{\text{data}}$	data generating distribution over $\mathcal{X} \times \mathcal{Y}$
$\mathcal{H}$	hypothesis space, set of learnable models $f$
$f : \mathcal{X} \rightarrow \mathcal{Y}$	model/hypothesis, $f \in \mathcal{H}$
$f(x)$	output/prediction for input $x \in \mathcal{X}$
$L(y, f(x))$	Loss function for sample $(x, y) \in \mathcal{X} \times \mathcal{Y}$
$\mathcal{D}_{\text{train}}$	Set of training samples $\{(x_1, y_1), \dots, (x_n, y_n)\}$ , used for training a model
$\mathcal{D}_{\text{val}}$	Set of validation samples $\{(x_1, y_1), \dots, (x_n, y_n)\}$ , used for fine tuning parameters for example
$\mathcal{D}_{\text{test}}$	Set of test samples $\{(x_1, y_1), \dots, (x_n, y_n)\}$ , used for estimating the risk of the model, should not be used in any other operations with the model
$R(f)$	risk of model $f$ , defined as $R(f) = \mathbb{E}_{(x,y) \sim \mathbb{P}_{\text{data}}} [L(y, f(x))]$
$R_{\text{emp}}(f)$	empirical risk of $f$ , for $\mathcal{D}_{\text{train}}$ defined as $R_{\text{emp}}(f) = \frac{1}{n} \sum_{i=1}^n [L(y_i, f(x_i))]$

**Note** that we always consider multi-dimensional samples to be columns, e.g., having dimensionality  $(p, 1)$ , where  $p$  is the amount of features. Therefore, applying a model to

an input to get a prediction is always  $\theta^T x$ , thus parameters  $\theta$  of the model are also a column (or multiple columns when output is multidimensional) of dimensionality  $(p, 1)$ . **Note** we consider models  $f(x)$  that are characterized by parameters  $\theta$ . The notation for such models is  $f(\theta; x)$ ; sometimes we also use  $f(x|\theta)$  to emphasize the dependency on parameters.

### 1. Goal of Machine Learning

- Construction of a learner, i.e., an algorithm that learns a function (model/ hypothesis) from feature space to target space, based on training data, that maps unseen test data into label space proficiently.

### 2. Components of a Learning Algorithm

- Hypothesis space (Space of functions "learnable" by our algorithm)
- Evaluation (Performance measure of any given hypothesis in mapping unseen features to targets)
- Optimization (Search method within hypothesis space)

### 3. Different Kinds of Learning

- Supervised learning
- Unsupervised learning
- Reinforcement learning