Scientific software engineering with a simple ODE model as example

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Teaching material on scientific computing has traditionally been very on the mathematics and the applications, while details on how the comprogrammed to solve the problems have received little attention. Many writing as simple programs as possible and are not aware of much useful conscience technology that would increase the fun, efficiency, and reliability their scientific computing activities.

This document demonstrates a series of good practices and tools from computer science, using a very simple mathematical problem with a very implementation such that we minimize the mathematical details. Our granter increase the technological quality of computer programming and make if the more well-established quality of the mathematics of scientific computer specifically we address the following scientific topics:

- How to structure a code in terms of functions
- How to make a module
- How to read input data flexibly from the command line
- How to create graphical/web user interfaces
- How to write unit tests (test functions or doctests)
- How to refactor code in terms of classes (instead of functions only
- How to conduct and automate large-scale numerical experiments
- How to write scientific reports in various formats (LATEX, HTML)

The conventions and techniques outlined here will save you a lot of tin you incrementally extend software over time from simpler to more comproblems. In particular, you will benefit from many good habits:

- new code is added in a modular fashion to a library (modules),
- programs are run through convenient user interfaces,

- it takes one quick command to let all your code can undergo heavy testing,
- tedious manual work with running programs is automated,
- your scientific investigations are reproducible,
- scientific reports with top quality typesetting are produced both for paper and electronic devices.

Basic implementations

.1 Mathematical problem and solution technique

le address the perhaps simplest possible differential equation problem

$$u'(t) = -au(t), \quad t \in (0, T],$$
 (1)

$$u(0) = I, (2)$$

here a, I, and T are prescribed parameters, and u(t) is the unknown function b be estimated. This mathematical model is relevant for physical phenomena aturing exponential decay in time, e.g., vertical pressure variation in the tmosphere, cooling of an object, and radioactive decay.

The time domain is discretized with points $0 = t_0 < t_1 \cdots < t_{N_t} = T$, ere with a constant spacing Δt between the mesh points: $\Delta t = t_n - t_{n-1}$, $= 1, \ldots, N_t$. Let u^n be the numerical approximation to the exact solution at t_0 . A family of popular numerical methods can be written in the form

$$u^{n+1} = \frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t} u^n, \tag{3}$$

or $n = 0, 1, ..., N_t - 1$. This numerical scheme corresponds to the Forward uler¹ scheme when $\theta = 0$, the Backward Euler² scheme when $\theta = 1$, and the rank-Nicolson³ scheme when $\theta = 1/2$. The initial condition (2) is key to start ne recursion with a value for u^0 .

.2 A first, quick implementation

olving (3) in a program is very straightforward: just make a loop over n and valuate the formula. The $u(t_n)$ values for discrete n can be stored in an array. his makes it easy to also plot the solution. It would be natural to also add the ract solution curve $u(t) = Ie^{-at}$ to the plot.

Traditionally, a language like Fortran or C would be adopted for implemenation, but the enormous popularity of MATLAB in the computational science community over the last two decades, makes a high-level MATLAB-styl mentation natural. Below is such a code, written in Python with a synt to MATLAB and with a programming style heavenly influenced by "M scripting". A student or engineer would quickly put together statemethis:

```
from numpy import *
from matplotlib.pyplot import *
a = 2
T = 4
dt = 0.2
N = int(round(T/dt))
v = zeros(N+1)
t = linspace(0, T, N+1)
theta = 1
y[0] = A
for n in range(0, N):
    y[n+1] = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)*y[n]
y_e = A*exp(-a*t) - y
error = y_e - y
E = sqrt(dt*sum(error**2))
print 'Norm of the error: %.3E' % E
plot(t, v, 'r--o')
t_e = linspace(0, T, 1001)
y_e = A*exp(-a*t_e)
plot(t_e, y_e, 'b-')
legend(['numerical, theta=%g' % theta, 'exact'])
xlabel('t')
ylabel('y')
show()
```

This program is easy to read, and as long it is correct, many will cla it has sufficient quality. Nevertheless, the program suffers from serior that quickly become crucial for writing correct programs for more commathematical problems. First we list two serious bad habits:

- 1. The notation in the program does not correspond exactly to the r in the mathematical problem: the solution is called y and corresp u in the mathematical description, the variable A corresponds to the ematical parameter I, N in the program is called N_t in the mathe
- 2. There are no comments in the program.

1.3 A more decent, flat program

A code with more satisfactory quality arises from fixing the notation and comments:

¹http://en.wikipedia.org/wiki/Forward_Euler_method

²http://en.wikipedia.org/wiki/Backward_Euler_method

³http://en.wikipedia.org/wiki/Crank-Nicolson

```
from numpy import *
from matplotlib.pyplot import *
I = 1
a = 2
T = 4
dt = 0.2
Nt = int(round(T/dt))
                         # no of time intervals
u = zeros(Nt+1)
                         # array of u[n] values
t = linspace(0, T, Nt+1) # time mesh
theta = 1
                         # Backward Euler method
u[0] = I
                         # assign initial condition
for n in range(0, Nt): \# n=0,1,...,Nt-1
    u[n+1] = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)*u[n]
# Compute norm of the error
u_e = I*exp(-a*t) - u
                         # exact u at the mesh points
error = u e - u
E = sqrt(dt*sum(error**2))
print 'Norm of the error: %.3E' % E
# Compare numerical (u) and exact solution (u e) in a plot
plot(t, u, 'r--o')
                                # red dashes w/circles
t_e = linspace(0, T, 1001)
                                # very fine mesh for u_e
u = I * exp(-a * t e)
plot(t_e, u_e, 'b-')
                                # blue line for u e
legend(['numerical, theta=%g' % theta, 'exact'])
xlabel('t')
ylabel('u')
show()
```

At first sight, this is a good starting point for playing around with the athematical problem: we can just change parameters and rerun. Let us embed ne program in an IPython notebook such that we can get the plot up in the otebook, see Figure 1.

Although such an interactive session is good for initial exploration, one will one extend the experiments and start developing the code further. Say we want compare $\theta=0,1,0.5$ in the same plot. This extension requires changes all ver the code and quickly lead to errors. To do something serious with this rogram we have to break it into smaller pieces and make sure each piece is ell tested, is general, and can be reused in new contexts without changes. The ext natural step is therefore to isolate the numerical computations and the isualization in separate functions.

.4 Implementing the numerical algorithm in a function

he solution formula (3) is completely general and should be available as a ython function solver with all input data as function arguments and all utput data returned to the calling code. With this solver function we can sen solve all types of problems (1)-(2) by an easy-to-read one-line statement:

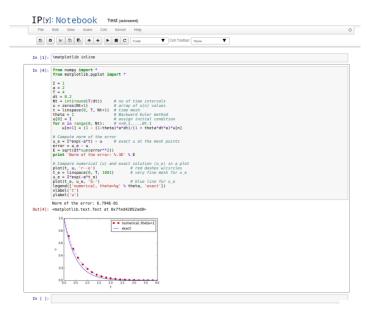


Figure 1: Flat experimental code in a notebook.

```
u, t = solver(I=1, a=2, T=4, dt=0.2, theta=0.5)
```

The implementation of the solver function in Python goes like this

Tip: Always use a doc string to document a function!

Python has a convention for documenting the purpose and usage function in a *doc string*: simply place the documentation in a on multi-line triple-quoted string right after the function header.

Be careful with unintended integer division!

Note that we in the solver function explicitly covert dt to a float object. If not, the updating formula for u[n+1] may evaluate to zero because of integer division when theta, a, and dt are integers!

One of the most serious flaws in computational work is to have several slightly ifferent implementations of the same computational algorithms lying around a various program files. This is very likely to happen, because busy scientists then want to test a slight variation of a code to see what happens. A quick copy and edit do the task, but such quick hacks have a tendency to survive. When real correction is needed in the implementation, it is difficult to ensure that he correction is done in all relevant files. In fact, this is a general problem in rogramming, which has led to an important principle.

The DRY principle: Don't repeat yourself!

When implementing a particular functionality in a computer program, make sure this functionality and its variations are implemented in just one piece of code. That is, if you need to revise the implementation, there should be *one and only one* place to edit. It follows that you should never duplicate code (don't repeat yourself!), and code snippets that are similar should be factored into one piece (function) and parameterized (by function arguments).

.5 Making a module

s soon as you start making Python functions in a program, you should make tre the program file fulfills the requirement of a module. This means that you an import and reuse your functions in other programs too. For example, if our olver function resides in a module decay in a module file decay.py, we can any program do

```
From decay import solver
1, t = solver(I=1, a=2, T=4, dt=0.2, theta=0.5)
```

r prefix function names by the module name:

```
import decay
1, t = decay.solver(I=1, a=2, T=4, dt=0.2, theta=0.5)
```

The requirements for a program to qualify for a module are simple:

1. The filename without .py must be a valid Python variable name.

2. The main program must be executed (through statements or a f call) in the *test block*.

The *test block* is normally placed at the end of a module file:

```
if __name__ == '__main__':
    # Statements
```

When the module file is executed as a stand-alone program, the if test and the indented statements are run, but when the module file is in <code>__name__</code> equals the module name and the test block is not executed.

To explain the importance of the test block, consider the trivial mohello.py with one function and a call to this function as main program

```
def hello(arg='World!'):
    print 'Hello, ' + arg

if __name__ == '__main__':
    hello()
```

Without the test block,

```
def hello(arg='World!'):
    print 'Hello, ' + arg
hello()
```

any attempt to import hello will also execute the call hello() and hen 'Hello, World!' to the screen. Such output is not desired when important module! However, with the test block, hello() is not called during important the file as python hello.py will make the block active and leadesired printing.

All coming functions are placed in a module.

The many functions to be explained in the following text are put in module file $decay.py^a$.

```
ahttp://tinyurl.com/nm5587k/softeng1/decay.py
```

What more than the solver function is needed in our decay modu everything we did in the previous, flat program? We need import star for numpy and matplotlib as well as another function for producing t It can also be convenient to put the exact solution in a Python function module decay.py then looks like this:

```
from numpy import *
from matplotlib.pyplot import *
```

```
lef solver(I, a, T, dt, theta):
lef exact_solution(t, I, a):
   return I*exp(-a*t)
lef experiment compare numerical and exact():
   I = 1; a = 2; T = 4; dt = 0.4; theta = 1
   u, t = solver(I, a, T, dt, theta)
   t e = linspace(0, T, 1001)
                                   # very fine mesh for u e
   u_e = exact_solution(t_e, I, a)
   plot(t, u, 'r--o')
                                   # dashed red line with circles
   plot(t_e, u_e, 'b-') # blue line for u_e
   legend(['numerical, theta=%g' % theta, 'exact'])
   xlabel('t')
   vlabel('u')
   plotfile = 'tmp'
   savefig(plotfile + '.png'); savefig(plotfile + '.pdf')
   error = exact solution(t, I, a) - u
   E = sqrt(dt*sum(error**2))
   print 'Error norm:', E
if __name__ == '__main__':
   experiment_compare_numerical_and_exact()
```

This module file does exactly the same as the previous, flat program, but becomes much easier to extend the code with other plots or experiments in ew functions. And even more important, the numerical algorithm is coded nd tested once and for all in the solver function, and any need to solve the nathematical problem is a matter of one function call.

.6 Prefixing imported functions by the module name

nport statements of the form from module import * import functions and ariables in module.py into the current file. For example, when doing

```
from numpy import *
from matplotlib.pyplot import *
```

e get mathematical functions like sin and exp as well as MATLAB-style motions like linspace and plot, which can be called by these well-known names. Infortunately, it sometimes becomes confusing to know where a particular motion comes from. Is it from numpy? Or matplotlib.pyplot? Or is it our wn function?

An alternative import is

```
import numpy
import matplotlib.pyplot
```

nd such imports require functions to be prefixed by the module name, e.g.,

```
t = numpy.linspace(0, T, Nt+1)
u_e = I*numpy.exp(-a*t)
matplotlib.pyplot.plot(t, u_e)
```

This is normally regarded as a better habit because it is explicitly stat which module a function comes from.

The modules numpy and matplotlib.pyplot are so frequently us their full names quite tedious to write, so two standard abbreviatio evolved in the Python scientific computing community:

```
import numpy as np
import matplotlib.pyplot as plt

t = np.linspace(0, T, Nt+1)
u_e = I*np.exp(-a*t)
plt.plot(t, u_e)
```

The downside of prefixing functions by the module name is that mather expressions like $e^{-at} \sin(2\pi t)$ get cluttered with module names,

```
numpy.exp(-a*t)*numpy.sin(2(numpy.pi*t)
# or
np.exp(-a*t)*np.sin(2*np.pi*t)
```

Such an expression looks like exp(-a*t)*sin(2*pi*t) in most other p ming languages. Similarly, np.linspace and plt.plot look less familiar ple who are used to MATLAB and who have not adopted Python's presewhether to do from module import * or import module depends on plaste and the problem at hand. In these writings we use from module in more basic, shorter programs where similarity with MATLAB coul advantage. Prefix of mathematical functions in formulas is something vavoid to obtain a one-to-one correspondence between mathematical feand the Python code.

Our decay module can be edited to use the module prefix for matplot1 and numpy:

```
import numpy as np
import matplotlib.pyplot as plt

def solver(I, a, T, dt, theta):
    ...

def exact_solution(t, I, a):
    return I*np.exp(-a*t)

def experiment_compare_numerical_and_exact():
    I = 1; a = 2; T = 4; dt = 0.4; theta = 1
    u, t = solver(I, a, T, dt, theta)

    t_e = np.linspace(0, T, 1001)  # very fine mesh for u_e
    u_e = exact_solution(t_e, I, a)
```

```
plt.plot(t, u, 'r--o')  # dashed red line with circles
plt.plot(t_e, u_e, 'b-')  # blue line for u_e
plt.legend(['numerical, theta=%g' % theta, 'exact'])
plt.xlabel('t')
plt.ylabel('u')
plotfile = 'tmp'
plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf')

error = exact_solution(t, I, a) - u
E = np.sqrt(dt*np.sum(error**2))
print 'Error norm:', E

if __name__ == '__main__':
    experiment_compare_numerical_and_exact()
```

We remark that some would prefer to get rid of the prefix in mathematical ormulas:

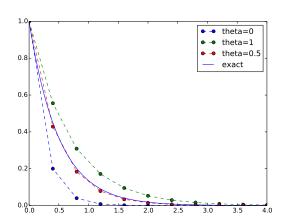
```
from numpy import exp, sum, sqrt
lef exact_solution(t, I, a):
    return I*exp(-a*t)

error = exact_solution(t, I, a) - u
E = sqrt(dt*sum(error**2))
```

.7 Comparing numerical schemes in one plot

et us specifically demonstrate one extension of the flat program in Section 1.2 nat would require substantial editing of the flat code, while in a structured nodule, we can simply add a new function without affecting the existing code and with reusing the implementation of the numerics.

Our aim is to make a comparison between the numerical solutions for various themes (θ values) and the exact solution:



Stop a minute!

Look at the flat program in Section 1.2, and try to imagine which that are required to solve this new problem.

With the solver function at hand, we can simply create a functior loop over theta values and add the necessary plot statements:

```
def experiment_compare_schemes():
    """Compare theta=0,1,0.5 in the same plot."""
    I = 1; a = 2; T = 4; dt = 0.4
   legends = []
    for theta in [0, 1, 0.5]:
        u, t = solver(I, a, T, dt, theta)
        plt.plot(t, u, '--o')
                                         # dashed lines with circ
        legends.append('theta=%g' % theta)
    t_e = np.linspace(0, T, 1001)
                                        # very fine mesh for u_e
    u e = exact solution(t e, I, a)
    plt.plot(t_e, u_e, 'b-')
                                         # blue line for u_e
    legends.append('exact')
    plt.legend(legends, loc='upper right')
    plotfile = 'tmp'
    plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf
```

A call to this experiment_compare_schemes function must be place test block, or you can run the program from IPython instead:

```
In[1]: from decay import *
In[2]: experiment_compare_schemes()
```

2 User interfaces

It is good programming practice to let programs read input from so *interface*, rather than requiring users to *edit* parameter values in the som With effective user interfaces it becomes easier and safer to apply the escientific investigations and in particular to automate large-scale invest by other programs (see Section 5).

Reading input data can be done in many ways. We have to decide ϵ functionality of the user interface, i.e., how we want to operate the ϵ when providing input, and then use appropriate tools to implement t interface. There are four basic types of user interface, listed here with in complexity of the implementation:

- 1. Questions and answers in the terminal window
- 2. Command-line arguments
- 3. Reading data from files

4. Graphical user interfaces (GUIs)

lternatives 2 and 4 are most popular and will be addressed next.

.1 Command-line arguments

he command-line arguments are all the words that appear on the command line fter the program name. Running a program prog as prog arg1 arg2 means not there are two command-line arguments (separated by white space): arg1 and rg2. Python stores all the command-line arguments in the list sys.argv, and nere are, in principle, two ways of programming with command-line arguments of Python:

- Decide upon a sequence of parameters on the command line and read their values directly from the sys.argv[1:] list (sys.argv[0] is the just program name).
- Use option-value pairs (--option value) on the command line to override default values of input parameters, and utilize the argparse. ArgumentParser tool to interact with the command line.

uppose we want to run our program <code>decay.py</code> with specification of a and Δt n the command line. With positional command-line arguments we write

```
erminal> python decay.py 2 0.5
```

nowing that the first argument 2 is a (a) and the second '0.5'is dt (Δt) . With option-value pairs we can run

```
erminal> python decay.py --a 2 --dt 0.5
```

oth a and dt are supposed to have default values in the program, so we need a specify only the parameter that is to be changed from its default value, e.g.,

```
erminal> python decay.py --a 2  # a=2, default dt
erminal> python decay.py --dt 0.7  # dt-0.7, default a
erminal> python decay.py  # default a and dt
```

As example, we want to read I, a, T, θ , and a range of Δt values from the ammand line. A plot is then to be made, comparing the different numerical plutions for different Δt values against the exact solution.

2.2 Positional command-line arguments

The simplest way of reading the input parameters is to decide on their s on the command line and just index the sys.argv list accordingly. sequence is I, a, T, θ followed by an arbitrary number of Δt values. The extract these positional command-line arguments:

```
import sys
I = float(sys.argv[1])
a = float(sys.argv[2])
T = float(sys.argv[3])
theta = float(sys.argv[4])
dt_values = [float(arg) for arg in sys.argv[5:]]
```

Command-line arguments are strings!

Note that all elements in sys.argv are string objects. If the values enter mathematical computations, we need to explicitly convert the st to numbers.

Instead of specifying the θ value, we could be a bit more sophisticated the user write the name of the scheme: BE for Backward Euler, FE for l Euler, and CN for Crank-Nicolson. Then we must map this string to the θ value, an operation elegantly done by a dictionary:

```
scheme = sys.argv[4]
scheme2theta = {'BE': 1, 'CN': 0.5, 'FE': 0}
if scheme in scheme2theta:
    theta = scheme2theta[scheme]
else:
    print 'Invalid scheme name:', scheme; sys.exit(1)
```

2.3 Option-value pairs on the command line

Now we want specify option-value pairs on the command line, using – (I), ––a for a (a), ––T for T (T), ––scheme for the scheme name (BE, FE, C) ––dt for the sequence of dt (Δt) values. Each parameter must have a default value so that we specify the option on the command line only w default value is not suitable. Here is a typical run:

```
Terminal> python decay.py --I 2.5 --dt 0.1 0.2 0.01 --a 0.4
```

Observe the major advantage over positional command-line arguments: the is much easier to read and much easier to write. With positional arguments easy to mess up the sequence of the input parameters and quite challer detect errors too, unless there are just a couple of arguments.

Python's ArgumentParser tool in the argparse module makes it easy to reate a professional command-line interface to any program. The documention of ArgumentParser⁴ demonstrates its versatile applications, so we shall ere just list an example containing basic features. It always pays off to use rgumentParser rather than trying to inspect and interpret sys.argv manually! The use of ArgumentParser typically involves three steps:

```
import argparse
parser = argparse.ArgumentParser()

# Step 1: add arguments
parser.add_argument('--option_name', ...)

# Step 2: interpret the command line
args = parser.parse_args()

# Step 3: extract values
7alue = args.option_name
```

A function for setting up all the options is handy:

```
lef define_command_line_options():
   import argparse
   parser = argparse.ArgumentParser()
   parser.add argument(
       '--I', '--initial_condition', type=float,
       default=1.0, help='initial condition, u(0)',
       metavar='I')
   parser.add_argument(
       '--a', type=float, default=1.0,
       help='coefficient in ODE', metavar='a')
   parser.add_argument(
       '--T', '--stop time', type=float,
       default=1.0, help='end time of simulation',
       metavar='T')
   parser.add_argument(
       '--scheme', type=str, default='CN',
       help='FE, BE, or CN')
   parser.add argument(
       '--dt', '--time_step_values', type=float,
       default=[1.0], help='time step values',
       metavar='dt', nargs='+', dest='dt values')
   return parser
```

Each command-line option is defined through the parser.add_argument ethod. Alternative options, like the short --I and the more explaining version <code>initial_condition</code> can be defined. Other arguments are type for the Python bject type, a default value, and a help string, which gets printed if the command-ne argument -h or --help is included. The metavar argument specifies the alue associated with the option when the help string is printed. For example, ne option for I has this help output:

```
Terminal> python decay.py -h
...
--I I, --initial_condition I
initial condition, u(0)
...
```

The structure of this output is

```
--I metavar, --initial_condition metavar help-string
```

Finally, the --dt option demonstrates how to allow for more than on (separated by blanks) through the nargs='+' keyword argument. A command line is parsed, we get an object where the values of the optistored as attributes. The attribute name is specified by the dist l argument, which for the --dt option is dt_values. Without the dest ar the value of an option --opt is stored as the attribute opt.

The code below demonstrates how to read the command line and ext values for each option:

As seen, the values of the command-line options are available as at in args: args.opt holds the value of option --opt, unless we used the argument (as for --dt_values) for specifying the attribute name. The arattribute has the object type specified by type (str by default).

The making of the plot is not dependent on whether we read data f command line as positional arguments or option-value pairs:

```
def experiment_compare_dt(option_value_pairs=False):
   I, a, T, theta, dt_values = \
      read_command_line_argparse() if option_value_pairs else \
      read command line positional()
   legends = []
   for dt in dt values:
       u, t = solver(I, a, T, dt, theta)
       plt.plot(t, u)
       legends.append('dt=%g' % dt)
    t_e = np.linspace(0, T, 1001)
                                        # very fine mesh for u_e
    u_e = exact_solution(t_e, I, a)
    plt.plot(t_e, u_e, '--')
                                        # dashed line for u e
    legends.append('exact')
    plt.legend(legends, loc='upper right')
    plt.title('theta=%g' % theta)
    plotfile = 'tmp'
    plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf
```

 $^{^4 {\}tt http://docs.python.org/library/argparse.html}$

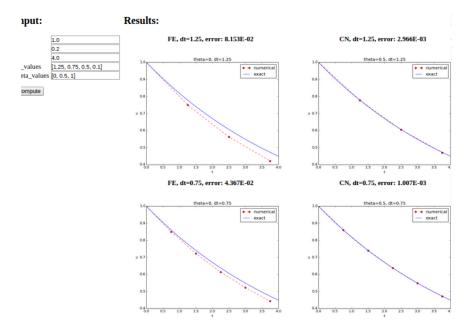


Figure 2: Automatically generated graphical web interface.

.4 Creating a graphical web user interface

he Python package Parampool⁵ can be used to automatically generate a web-ased *graphical user interface* (GUI) for our simulation program. Although ne programming technique dramatically simplifies the efforts to create a GUI, ne forthcoming material on equipping our decay module with a GUI is quite echnical and of significantly less importance than knowing how to make a paramand-line interface.

Taking a compute function. The first step is to identify a function that erforms the computations and that takes the necessary input variables as rguments. This is called the *compute function* in Parampool terminology. The urpose of this function is to take values of I, a, T together with a sequence of t values and a sequence of θ and plot the numerical against the exact solution or each pair of $(\theta, \Delta t)$. The plots can be arranged as a table with the columns eing scheme type $(\theta$ value) and the rows reflecting the discretization parameter Δt value). Figure 2 displays of the graphical web interface may look like after sults are computed (there are 3×3 plots in the GUI, but only 2×2 are visible 1 the figure).

To tell Parampool what type of input data we have, we assign defaul of the right type to all arguments in the compute function, here called ma

The compute function must return the HTML code we want for disther esult in a web page. Here we want to show a table of plots. Assume that the HTML code for one plot and the value of the norm of the enbe computed by some other function <code>compute4web</code>. The <code>main_GUI</code> function loop over Δt and θ values and put each plot in an HTML table. App code goes like

```
def main_GUI(I=1.0, a=.2, T=4.0,
            dt values=[1.25, 0.75, 0.5, 0.1],
            theta_values=[0, 0.5, 1]):
    # Build HTML code for web page. Arrange plots in columns
    # corresponding to the theta values, with dt down the rows
    theta2name = {0: 'FE', 1: 'BE', 0.5: 'CN'}
    html text = '\n'
   for dt in dt_values:
       html text += '\n'
       for theta in theta_values:
           E, html = compute4web(I, a, T, dt, theta)
           html text += """
<t.d>>
<center><b>%s, dt=%g, error: %.3E</b></center><br>
%s
""" % (theta2name[theta], dt, E, html)
       html text += '\n'
    html_text += '\n'
   return html text
```

Making one plot is done in compute4web. The statements should be a forward from earlier examples, but there is one new feature: we use a Parampool to embed the PNG code for a plot file directly in an HTMl tag. The details are hidden from the programmer, who can just rely on HTML code in the string html_text. The function looks like

```
def compute4web(I, a, T, dt, theta=0.5):
    """
Run a case with the solver, compute error measure,
    and plot the numerical and exact solutions in a PNG
    plot whose data are embedded in an HTML image tag.
    """
u, t = solver(I, a, T, dt, theta)
u_e = exact_solution(t, I, a)
e = u_e - u
E = np.sqrt(dt*np.sum(e**2))

plt.figure()
t_e = np.linspace(0, T, 1001)  # fine mesh for u_e
u_e = exact_solution(t_e, I, a)
```

 $^{^5 {\}tt https://github.com/hplgit/parampool}$

```
plt.plot(t, u, 'r--o')  # red dashes w/circles
plt.plot(t_e, u_e, 'b-')  # blue line for exact sol.
plt.legend(['numerical', 'exact'])
plt.xlabel('t')
plt.ylabel('u')
plt.title('theta=%g, dt=%g' % (theta, dt))
# Save plot to HTML img tag with PNG code as embedded data
from parampool.utils import save_png_to_str
html_text = save_png_to_str(plt, plotwidth=400)
return E, html_text
```

tenerating the user interface. The web GUI is automatically generated y the following code, placed in a file decay_GUI_generate.py⁶

unning the decay_GUI_generate.py program results in three new files whose ames are specified in the call to generate:

- decay_GUI_model.py defines HTML widgets to be used to set input data in the web interface.
- 2. templates/decay_GUI_views.py defines the layout of the web page,
- 3. decay_GUI_controller.py runs the web application.

/e only need to run the last program, and there is no need to look into these les.

tunning the web application. The web GUI is started by

```
erminal> python decay_GUI_controller.py
```

pen a web browser at the location 127.0.0.1:5000. Input fields for I, a, dt_values, and theta_values are presented. Figure 2 shows a part of the sulting page if we run with the default values for the input parameters. With ne techniques demonstrated here, one can easily create a tailored web GUI for particular type of application and use it to interactively explore physical and umerical effects.

3 Tests for verifying implementations

Any module with functions should have a set of tests that check the im tations. There exists well-established procedures and corresponding t automating the execution of such tests. One can in this way, with a command, run large test sets and confirm that the software works (as fa tests tells). Here we shall illustrate two important software testing tecl doctest and unit testing. The first one is Python specific, while unit to the dominating test technique for computer software today.

3.1 Doctests

A doc string, the first string after the function header, is used to do the purpose of functions and their arguments (see Section 1.4). Very is instructive to include an example on how to use the function. Interval examples in the Python shell are most illustrative as we can see the resulting from function calls. For example, we can in the solver function an example on calling this function and printing the computed u and t

```
def solver(I, a, T, dt, theta):
    """
    Solve u'=-a*u, u(0)=I, for t in (0,T] with steps of dt.

>>> u, t = solver(I=0.8, a=1.2, T=1.5, dt=0.5, theta=0.5)
>>> for t_n, u_n in zip(t, u):
    ... print 't=%.1f, u=%.14f' % (t_n, u_n)
t=0.0, u=0.8000000000000
t=0.5, u=0.43076923076923
t=1.0, u=0.23195266272189
t=1.5, u=0.12489758761948
"""
...
```

When such interactive demonstrations are inserted in doc strings, F doctest⁷ module can be used to automate running all commands in int sessions and compare new output with the output appearing in the do All we have to do in the current example is to run the module file decay.

```
Terminal> python -m doctest decay.py
```

This command imports the doctest module, which runs all doctests f the file.

Doctests prevent command-line arguments!

⁶http://tinyurl.com/nm5587k/softeng1/decay_GUI_generate.py

⁷http://docs.python.org/library/doctest.html

No additional command-line argument is allowed when running doctests. If your program relies on command-line input, make sure the tests can be run with such input.

The execution command above will report any problem if a test fails. For xample, changing the last digit 8 in the output of the doctest to 7 triggers a port:

Pay attention to the number of digits in doctest results!

Note that in the output of t and u we write u with 14 digits. Writing all 16 digits is not a good idea: if the tests are run on different hardware, round-off errors might be different, and the **doctest** module detects that the numbers are not precisely the same and reports failures. In the present application, where $0 < u(t) \le 0.8$, we expect round-off errors to be of size 10^{-16} , so comparing 15 digits would probably be reliable, but we compare 14 to be on the safe side. On the other hand, comparing a small number of digits may hide software errors.

Doctests are highly encouraged as they do two things: 1) demonstrate how a unction is used and 2) test that the function works.

Caution.

Doctests requires careful coding if they use command-line input or print results to the terminal window. Command-line input must be simulated by filling sys.argv correctly, e.g., sys.argv = '--I 1.0 --a 5'.split. The output lines of print statements inside doctests must be copied exactly

as they appear when running the statements in an interactive Py shell.

3.2 Unit tests and test functions

The unit testing technique consists of identifying small units of code function, and write one or more tests for each unit. One test should, idea depend on the outcome of other tests. The recommended practice is act design and write the unit tests first and *then* implement the functions!

In scientific computing it is not always obvious how to best perfotesting. The units is naturally larger than in non-scientific software. Ve the solution procedure of a mathematical problem identifies a unit, sucl solver function.

Test frameworks: nose and pytest. Python offers two very easy software frameworks for implementing unit tests: nose and pytest. The (almost) in the same way, but my recommendation is to go for pytest.

Test function requirements. Each test can in these frameworks be as a *test function* that follows three rules:

- 1. The name must start with test.
- 2. Function arguments are not allowed.
- 3. An AssertionError exception must be raised if the test fails.

A specific example might be illustrative before proceeding. Given a f that doubles the argument,

```
def double(n):
    return 2*n
```

a corresponding test function may look like this:

```
def test_double():
    """Test that double(n) works for one specific n."""
    n = 4
    expected = 2*4
    computed = double(4)
    if expected != computed:
        raise AssertionError
```

The last two lines, however, are never written like this in unit tests. use Python's assert statement: assert success, msg, where successories boolean variable, here False if the test fails, and msg is an optional string that is printed when the test fails. In detail, the test function local string that is printed when the test fails.

```
lef test_double():
    """Test that double(n) works for one specific n."""
    n = 4
    expected = 2*4
    computed = double(4)
    msg = 'expected %g, computed %g' % (expected, computed)
    success = expected == computed
    assert success, msg
```

Comparison of real numbers. In scientific computing we very often have to eal with real numbers and round-off errors so the == operator must be replaced y a comparison within a tolerance. Consider testing this function instead,

```
lef third(x):
    return x/3.
```

Where the expected result is computed as $\frac{1}{3}x$ rather that x/3:

```
lef test_third():
    x = 0.1
    expected = (1/3.)*x
    computed = third(x)
    success = expected == computed
    assert success
```

his test_third function executes silently, i.e., no failure, for x = 0.1, but not we set x = 0.15. The latter x value gives a round-off error. The solution to nis problem is to compare expected and computed with a small tolerance:

```
lef test_third():
    x = 0.15
    expected = (1/3.)*x
    computed = third(x)
    tol = 1E-15
    success = abs(expected - computed) < tol
    assert success</pre>
```

pecial assert functions from nose. The nose test framework contains nore tailored *assert functions* that can be called instead of using the assert satement. For example, comparing two objects within a tolerance, as in the resent case, can be done by assert_almost_equal:

```
import nose.tools as nt

lef test_third():
    x = 0.15
    expected = (1/3.)*x
    computed = third(x)
    nt.assert_almost_equal(
        expected, computed, delta=1E-15,
        msg='diff=%.17E' % (expected - computed))
```

Locating test functions. Test functions can reside in a module togeth the functions they are supposed to verify, or the test functions can be c in separate files having names starting with test. Actually, nose and can automatically recursively run all test functions in all test*.py file current and all subdirectories!

The decay.py⁸ module file features test functions in the module, could equally well have made a subdirectory tests and put the test func (say) tests/test_decay.py.

Running tests. To run all test functions in the file decay.py do

```
Terminal> nosetests -s -v decay.py
Terminal> py.test -s -v decay.py
```

The -s option ensures that output from the test functions is printed terminal window, and -v prints the outcome of each individual test functions.

Alternatively, if the test functions are in some test*.py files, we write py.test -s -v to recursively run all test functions in the current d tree. The corresponding nosetests -s -v command does the same, but subdirectory names to start with test or end with _test or _tests (wl good habit anyway). An example of a tests directory with a test*.r found in src/softeng1/tests⁹.

Installing nose and pytest. With pip available, it is trivial to inst and/or pytest: sudo pip install nose and sudo pip install pyte

3.3 Test function for the solver

Finding good test problems for verifying the implementation of numerical ods is a topic on its own. The challenge is that we very seldom know we numerical errors are. For the present model problem (1)-(2) solved by can, fortunately, derive a formula for the numerical approximation:

$$u^{n} = I \left(\frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t} \right)^{n}.$$

Then we know that the implementation should produce numbers that agrathis formula to machine precision. The formula for u^n is known as a discrete solution of the problem:

```
def exact_discrete_solution(n, I, a, theta, dt):
    """Return exact discrete solution of the numerical schemes.""
    dt = float(dt)  # avoid integer division
    A = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)
    return I*A**n
```

⁸http://tinyurl.com/nm5587k/softeng1/decay.py

⁹http://tinyurl.com/nm5587k/softeng1/tests

test function can evaluate this solution on a time mesh and check that the ualues produced by the solver function do not deviate with more than a small plerance:

An important topic to address in test functions is potentially problematic put to functions. For example, if a, Δt , and θ are integers, one may face roblems with unintended integer division in the numerical solution algorithm or the present mathematical problem. We should therefore add a test to make are our solver function does not fall into this potential trap:

.4 Test function for reading positional command-line arguments

he function <code>read_command_line_positional</code> extracts numbers from the command line. To test it, decide on a set of numbers, fill <code>sys.argv</code> appropriately, and check that we get the expected numbers:

Note that sys.argv[0] is always the program name and that we have that string from the original sys.argv array to the new one we construct test function. (Actually, the test function destroys the original sys.ar Python fetched from the command line.)

Any numerical code writer should always be skeptical to the use of the equality operator == in test functions, since round-off errors often come in the Here, however, we set some real values, convert them to strings and convagain to real numbers (of the same precision). This string-number condoes not involve approximation so we can safely use == in tests. Note a the last element in expected and computed is the list dt_values, and = for comparing two lists too.

3.5 Test function for reading option-value pairs

Testing the function read_command_line_argparse follows the set up similar function for positional command-line arguments. However, the c tion of the command line is a bit more complicated. We find it conveconstruct the line as a string and then split the line into words to get the list sys.argv:

Let silent test functions speak up during development!

When you develop test functions in a module, it is common to use IPy to reload the module and call the test function as it gets developed:

```
In[1]: import decay
In[2]: decay.test_read_command_line_argparse()
In[3]: reload(decay) # force new import
In[2]: decay.test_read_command_line_argparse() # test again
```

However, a working test function is completely silent! Many find it ps logically annoying to convince themselves that a completely silent fun is doing the right things. It can therefore, during development of a test function, be convenient to insert print statements in the function to monitor that the function body is indeed executed... For example, one can print the expected and computed values in the terminal window.

.6 Classical class-based unit testing

he test functions written for the nose and pytest frameworks are very straightorward and to the point, with no framework-required boilerplate code. We just rite the statements we need to make the computations and comparisons and nen make the require assert.

The classical way implementing unit tests derives from the JUnit tool in ava and leads to much more comprehensive implementations with much more oilerplate code. Python comes with a built-in module unittest for doing this 7pe of unit tests. Although I strongly recommend to use nose or pytest over nittest, class-based unit testing in the style of unittest has a very strong osition in computer science and is so widespread that even computational cientists should have an idea how such unit test code is written. A short demofunittest is therefore included next.

Suppose we have a function double(x) in a module file mymod.py:

```
lef double(x):
    return 2*x
```

nit testing with the aid of the unittest module consists of writing a file est_mymod.py for testing the functions in mymod.py. The individual tests ust be methods with names starting with test_ in a class derived from class estCase in unittest. With one test method for the function double, the est_mymod.py file becomes

```
import unittest
import mymod

class TestMyCode(unittest.TestCase):
    def test_double(self):
        x = 4
        expected = 2*x
        computed = mymod.double(x)
        self.assertEqual(expected, computed)

if __name__ == '__main__':
    unittest.main()
```

he test is run by executing the test file test_mymod.py as a standard Python rogram. There is no support in unittest for automatically locating and mning all tests in all test files in a directory tree.

We could use the basic assert statement as we did with nose and pytest inctions, but those who write code based on unittest almost exclusively use the wide range of built-in assert functions such as assertEqual, assertNc assertAlmostEqual, to mention some of them.

Translation of test_exact_discrete_solution, test_potential_i and the other test functions in decay.py to unittest means making a test_decay.py file with a test class TestDecay where the stand-alone fi for nose/pytest now become methods in this class.

```
import unittest
import decay
import numpy as np
def exact_discrete_solution(n, I, a, theta, dt):
class TestDecay(unittest.TestCase):
    def test_exact_discrete_solution(self):
        theta = 0.8; a = 2; I = 0.1; dt = 0.8
        Nt = int(8/dt) # no of steps
        u, t = decay.solver(I=I, a=a, T=Nt*dt, dt=dt, theta=theta
        # Evaluate exact discrete solution on the mesh
        u_de = np.array([exact_discrete_solution(n, I, a, theta,
                        for n in range(Nt+1)])
        diff = np.abs(u_de - u).max() # largest deviation
        self.assertAlmostEqual(diff, 0, delta=1E-14)
    def test_potential_integer_division(self):
        self.assertAlmostEqual(diff, 0, delta=1E-14)
    def test_read_command_line_positional(self):
        for expected_arg, computed_arg in zip(expected, computed)
            self.assertEqual(expected_arg, computed_arg)
    def test_read_command_line_argparse(self):
if __name__ == '__main__':
    unittest.main()
```

4 Classes for problem and solution method

The θ -rule was compactly and conveniently implemented in a function so Section 1.1. In more complicated problems it might be beneficial to use and introduce a class Problem to hold the definition of the physical $\mathfrak p$ and a class Solver to hold the data and methods needed to numerical the problem. This idea will now be illustrated, resulting in code that reparameters an alternative to the solver and experiment_* functions found in the module.

Explaining the details of class programming in Python is considered the scope of this text. Readers who are unfamiliar with Python class programould first consult one of the many electronic Python tutorials or texture.) come up to speed with concepts and syntax of Python classes before reading n. The author has a gentle introduction to class programming for scientific pplications in [1], see Chapter 7 and 9 and Appendix E. Other useful resources re

- The Python Tutorial: http://docs.python.org/2/tutorial/classes.
- Wiki book on Python Programming: http://en.wikibooks.org/wiki/ Python_Programming/Classes
- tutorialspoint.com: http://www.tutorialspoint.com/python/python_classes_objects.htm

.1 The problem class

he purpose of the problem class is to store all information about the mathenatical model. This usually means the physical parameters and formulas in the roblem. Looking at our model problem (1)-(2), the physical data cover I, a, and T. Since we have an analytical solution of the ODE problem, we may add is solution in terms of a Python function (or method) to the problem class as ell. A possible problem class is therefore

```
from numpy import exp

class Problem:
    def __init__(self, I=1, a=1, T=10):
        self.T, self.I, self.a = I, float(a), T

    def u_exact(self, t):
        I, a = self.I, self.a
        return I*exp(-a*t)
```

/e could in the u_exact method have written self.I*exp(-self.a*t), but sing local variables I and a allows the formula I*exp(-a*t) which looks closer the mathematical expression Ie^{-at} . This is not an important issue with the arrent compact formula, but is beneficial in more complicated problems with onger formulas to obtain the closest possible relationship between code and athematics. My coding style is to strip off the self prefix when the code spresses mathematical formulas.

The class data can be set either as arguments in the constructor or at any me later, e.g.,

```
problem = Problem(T=5)
problem.T = 8
problem.dt = 1.5
```

Some programmers prefer set and get functions for setting and getting data in asses, often implemented via *properties* in Python, but I consider that overkill hen we just have a few data items in a class.)

It would be convenient if class Problem could also initialize the data f command line. To this end, we add a method for defining a set of comm options and a method that sets the local attributes equal to what was for the command line. The default values associated with the command-line are taken as the values provided to the constructor. Class Problem now I

```
class Problem:
    def init (self, I=1, a=1, T=10):
        self.T. self.I. self.a = I. float(a). T
    def define command line options(self, parser=None):
        """Return updated (parser) or new ArgumentParser object."
        if parser is None:
            import argparse
            parser = argparse.ArgumentParser()
        parser.add argument(
            '--I', '--initial_condition', type=float,
            default=1.0, help='initial condition, u(0)',
            metavar='I')
        parser.add argument(
            '--a', type=float, default=1.0,
            help='coefficient in ODE', metavar='a')
        parser.add argument(
            '--T', '--stop_time', type=float,
            default=1.0, help='end time of simulation',
            metavar='T')
        return parser
    def init from command line(self. args):
        """Load attributes from ArgumentParser into instance."""
        self.I, self.a, self.T = args.I, args.a, args.T
    def u_exact(self, t):
        """Return the exact solution u(t)=I*exp(-a*t)."""
        I, a = self.I, self.a
        return I*exp(-a*t)
```

Observe that if the user already has an ArgumentParser object it can be s but if she does not have any, class Problem makes one. Python's None cused to indicate that a variable is not initialized with a proper value.

4.2 The solver class

The solver class stores data related to the numerical solution method and p a function solve for solving the problem. A problem object must be give constructor so that the solver can easily look up physical data. In the example, the data related to the numerical solution method consists of θ . We add, as in the problem class, functionality for reading Δt and θ f command line:

```
class Solver:
    def __init__(self, problem, dt=0.1, theta=0.5):
        self.problem = problem
```

```
self.dt, self.theta = float(dt), theta
def define_command_line_options(self, parser):
    """Return updated (parser) or new ArgumentParser object."""
    parser.add_argument(
        '--scheme', type=str, default='CN',
       help='FE, BE, or CN')
    parser.add argument(
        '--dt', '--time step values', type=float,
        default=[1.0], help='time step values',
       metavar='dt', nargs='+', dest='dt values')
    return parser
def init_from_command_line(self, args):
    """Load attributes from ArgumentParser into instance."""
    self.dt, self.theta = args.dt, args.theta
def solve(self):
    self.u. self.t = solver(
        self.problem.I, self.problem.a, self.problem.T,
       self.dt, self.theta)
def error(self):
    """Return norm of error at the mesh points."""
   u_e = self.problem.u_exact(self.t)
    e = u e - self.u
    E = sqrt(self.dt*sum(e**2))
   return E
```

ote that the solve method is just a wrapper of the previously developed and-alone solver function.

Sombining the objects. Eventually we need to show how the classes Problem and Solver play together:

```
lef experiment classes():
   problem = Problem()
   solver = Solver(problem)
   # Read input from the command line
   parser = problem.define_command_line options()
   parser = solver. define_command_line_options(parser)
   args = parser.parse args()
   problem.init_from_command_line(args)
   solver. init_from_command_line(args)
   # Solve and plot
   solver.solve()
   import matplotlib.pyplot as plt
   t_e = np.linspace(0, T, 1001)
                                    # very fine mesh for u_e
   u e = problem.u exact(t e)
   plt.plot(t, u, 'r--o')
                                    # dashed red line with circles
   plt.plot(t_e, u_e, 'b-')
                                    # blue line for u e
   plt.legend(['numerical, theta=%g' % theta, 'exact'])
   plt.xlabel('t')
   plt.ylabel('u')
   plotfile = 'tmp'
```

```
plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf
    error = problem.u_exact(t) - u
    E = np.sqrt(dt*np.sum(error**2))
    print 'Error norm:', E
    plt.show()

if __name__ == '__main__':
    experiment_compare_dt(True)
    plt.show()
```

4.3 Improving the problem and solver classes

The previous Problem and Solver classes containing parameters soon grepetitive code when the number of parameters increases. Much of this c be parameterized and be made more compact. For this purpose, we do collect all parameters in a dictionary, self.prm, with two associated dict self.type and self.help for holding associated object types and help For the specific ODE example we deal with, such dictionaries are

Provided a problem or solver class defines these three dictionaries in structor, using default or user-supplied values of the parameters, we can a super class Parameters with general code for defining command-line and reading them as well as methods for setting and getting a param Problem or Solver for a particular mathematical problem can then inhe of the needed functionality and code from the Parameters class.

A generic class for parameters. A simplified version of the paramelooks as follows:

```
class Parameters:
    def set(self, **parameters):
        for name in parameters:
            if name in self.prm:
                self.prm[name] = parameters[name]
        else:
                raise NameError('Illegal parameter name %s' % nam
    def get(self, name):
```

```
"""Return value of parameter with given name."""
    return self.prm[name]
def define_command_line_options(self, parser=None):
    """Automatic registering of options."""
    if parser is None:
       import argparse
       parser = argparse.ArgumentParser()
    for name in self.prm:
        tp = self.type[name] if name in self.type else str
       help = self.help[name] if name in self.help else None
       parser.add argument(
            '--' + name, default=self.get(name), metavar=name,
            type=tp, help=help)
    return parser
def init_from_command_line(self, args):
   for name in self.prm:
        self.prm[name] = getattr(args, name)
```

he file decay_oo.py¹⁰ contains a slightly more advanced version of class arameters where we in the set and get functions test for valid parametr names and raise exceptions with informative messages if any name is not egistered.

'he problem class. A class Problem for the problem u' = -au, u(0) = I, $\in (0, T]$, with parameters input a, I, and T can now be coded as

'he solver class. Also the solver class is derived from class Parameters and orks with the prms, types, and help dictionaries in the same way as class roblem. Otherwise, the code is very similar to the previous class Solver:

```
class Solver(Parameters):
    def __init__(self, problem):
        self.problem = problem
        self.prm = dict(dt=0.5, theta=0.5)
        self.type = dict(dt=float, theta=float)
        self.help = dict(dt='time step value',
                         theta='time discretization parameter')
    def solve(self):
        from decay_mod import solver
        self.u, self.t = solver(
            self.problem.get('I'),
            self.problem.get('a'),
           self.problem.get('T'),
           self.get('dt').
           self.get('theta'))
    def error(self):
        try:
           u_e = self.problem.u_exact(self.t)
            e = u e - self.u
           E = np.sqrt(self.get('dt')*np.sum(e**2))
        except AttributeError:
           E = None
        return E
```

The advantage with the Parameters class is that it scales to proble a large number of physical and numerical parameters: as long as the par are defined once via a dictionary, the compact code in class Paramethandle any collection of parameters of any size.

5 Automating scientific experiments

Empirical scientific investigations based on running computer programs careful design of the experiments and accurate reporting of results. A there is a strong tradition to do such investigations manually, the crequirements to scientific accuracy make a program much better su conduct the experiments. We shall in this section outline how we can wr programs, often called *scripts*, for running other programs and archiv results.

Scientific investigation.

The purpose of the investigations is to explore the quality of nume solutions to an ordinary differential equation. More specifically, we the initial-value problem

$$u'(t) = -au(t), \quad u(0) = I, \quad t \in (0, T],$$

by the θ -rule:

¹⁰http://tinyurl.com/nm5587k/softeng1/decay_oo.py

$$u^{n+1} = \frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t} u^n, \quad u^0 = I.$$
 (5)

This scheme corresponds to well-known methods: $\theta = 0$ gives the Forward Euler (FE) scheme, $\theta = 1$ gives the Backward Euler (BE) scheme, and $\theta = \frac{1}{2}$ gives the Crank-Nicolson (CN) or midpoint/centered scheme.

For fixed I, a, and T, we run the three schemes for various values of Δt , and present in a report the following results:

- 1. visual comparison of the numerical and exact solution in a plot for each Δt and $\theta = 0, 1, \frac{1}{2}$,
- 2. a table and a plot of the norm of the numerical error versus Δt for $\theta = 0, 1, \frac{1}{2}$.

The report will also document the mathematical details of the problem under investigation.

.1 Available software

ppropriate software for implementing (5) is available in a program model.py¹¹, hich is run as

```
erminal> python model.py --I 1.5 --a 0.25 --T 6 --dt 1.25 0.75 0.5
```

he command-line input corresponds to setting I=1.5, a=0.25, T=6, and in three values of Δt : 1.25, 0.75, ad 0.5.

The results of running this model.py command are text in the terminal indow and a set of plot files. The plot files have names M_D.E, where M denotes 12 method (FE, BE, CN for $\theta = 0, 1, \frac{1}{2}$), D the time step length (here 1.25, 0.75, 0.5), and E is the plot file extension png or pdf. The text output looks like

0.0 1.25: 5.998E-01 0.0 0.75: 1.926E-01 0.0 0.50: 1.123E-01 0.0 0.10: 1.558E-02 0.5 1.25: 6.231E-02 0.5 0.75: 1.543E-02 0.5 0.50: 7.237E-03 0.5 0.10: 2.469E-04 1.0 1.25: 1.766E-01 1.0 0.75: 8.579E-02 1.0 0.50: 6.884E-02 1.0 0.10: 1.411E-02

he first column is the θ value, the next the Δt value, and the final column expresents the numerical error E (the norm of discrete error function on the lesh).

5.2 Required new results

The results we need for our investigations are slightly different than directly produced by model.py:

- 1. We need to collect all the plots for one numerical method (FE, I in a single plot. For example, if 4 Δt values are run, the summariz for the BE method has 2 × 2 subplots, with the subplot correspor the largest Δt is in the upper left corner and the smallest is in the right corner.
- 2. We need to have a table containing Δt values in the first columbe the numerical error E for $\theta 0, 0.5, 1$ in the next three columns. The should be available as a standard CSV file.
- 3. We need to plot the numerical error E versus Δt in a log-log plot

Consequently, we need to write a program (script) that can run mode described and produce the results 1-3 above. This requires combining a plot files into a file and interpreting the output from model.py as a plotting and file storage.

If the script's name is exper1.py, we run it with the desired Δt v positional command-line arguments:

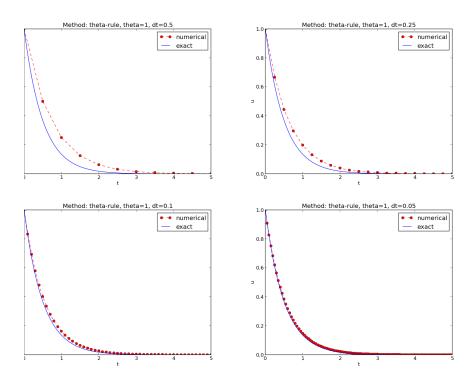
Terminal> python exper1.py 0.5 0.25 0.1 0.05

This run will then generate eight plot files: FE.png and FE.pdf summari plots with the FE method, BE.png and BE.pdf with the BE method, CN. CN.pdf with the CN method, and error.png and error.pdf with the plot of the numerical error versus Δt . In addition, the table with nu errors is written to a file error.csv.

Reproducible science.

A script that automates running our computer experiments will ensure the experiments can easily be rerun by ourselves or others in the fu either to check the results or redo the experiments with other input Also, whatever we did to produce the results is documented in every of in the script. Automating scripts are therefore essential to making research reproducible, which is a fundamental principle in science.

¹¹ http://hplgit.github.io/teamods/writing_reports/doconce_src/model.py



igure 3: Illustration of the Backward Euler method for four time step values.

.3 Combining plot files

nage files can be combined to new files using the montage 12 and convert 13 rograms in the ImageMagick software suite. However, these programs are best nited for PNG files. For vector plots in PDF format one needs other tools to reserve the quality: pdftk, pdfnup, and pdfcrop. Suppose you have four files 1.png, f2.png, f3.png, and f4.png and want to combine them into a 2×2 able of subplots in a new file f.png, see Figure 3 for an example.

The appropriate ImageMagick commands are

```
erminal> montage -background white -geometry 100% -tile 2x \
f1.png f2.png f3.png f4.png f.png
erminal> convert -trim f.png f.png
erminal> convert f.png -transparent white f.png
```

The first command mounts the four files in one, the next convert coremoves unnecessary surrounding white space, and the final convert comakes the white background transparent.

High-quality montage of PDF files f1.pdf, f2.pdf, f3.pdf, and f4.] f.pdf goes like

```
Terminal> pdftk f1.pdf f2.pdf f3.pdf f4.pdf output tmp.pdf
Terminal> pdfnup --nup 2x2 --outfile tmp.pdf tmp.pdf
Terminal> pdfcrop tmp.pdf f.pdf
Terminal> rm -f tmp.pdf
```

5.4 Running a program from Python

Suppose you want to run some operating system command stored in cmd. For example, cmd could be python model.py --I 1 --dt 0.5 0 following Python code executes cmd and loads the text output into a output:

```
from subprocess import Popen, PIPE, STDOUT
p = Popen(cmd, shell=True, stdout=PIPE, stderr=STDOUT)
output, dummy = p.communicate()

# Check if run was successful
failure = p.returncode
if failure:
    print 'Command failed:', cmd; sys.exit(1)
```

In our case, we need to interpret the contents of output and store t in an appropriate data structure. Since the content is basically a table a be transformed to a spread sheet format, we let the columns in the t lists, and we collect the columns in a dictionary whose keys are natural names: dt and the three values of θ . The following code translates ou such a dictionary of lists:

5.5 The automating script

Running model.py for a set of Δt values and producing files as describe can be done by the following code:

 $^{^{12} {\}tt http://www.imagemagick.org/script/montage.php}$

¹³http://www.imagemagick.org/script/convert.php

```
import os, sys, glob
import matplotlib.pyplot as plt
def run experiments(I=1, a=2, T=5):
    # The command line must contain dt values
    if len(sys.argv) > 1:
        dt values = [float(arg) for arg in sys.argv[1:]]
        print 'Usage: %s dt1 dt2 dt3 ...' % sys.argv[0]
        sys.exit(1) # abort
    # Run module file and grab output
    cmd = 'python model.py -- I %g -- a %g -- T %g' % (I, a, T)
    dt_values_str = ' '.join([str(v) for v in dt_values])
    cmd += ' --dt %s' % dt_values_str
    print cmd
    from subprocess import Popen, PIPE, STDOUT
    p = Popen(cmd, shell=True, stdout=PIPE, stderr=STDOUT)
    output, dummy = p.communicate()
    failure = p.returncode
    if failure:
        print 'Command failed:', cmd; sys.exit(1)
    errors = {'dt': dt values, 1: [], 0: [], 0.5: []}
    for line in output.splitlines():
        words = line.split()
        if words[0] in ('0.0', '0.5', '1.0'): # line with E?
            # typical line: 0.0 1.25: 7.463E+00
            theta = float(words[0])
            E = float(words[2])
            errors[theta].append(E)
    # Find min/max for the axis
    E_min = 1E+20; E_max = -E_min
    for theta in 0, 0.5, 1:
        E min = min(E min. min(errors[theta]))
        E max = max(E max, max(errors[theta]))
    plt.loglog(errors['dt'], errors[0], 'ro-')
    #plt.hold('on') # Matlab style...
    plt.loglog(errors['dt'], errors[0.5], 'b+-')
    plt.loglog(errors['dt'], errors[1], 'gx-')
    plt.legend(['FE', 'CN', 'BE'], loc='upper left')
    plt.xlabel('log(time step)')
    plt.ylabel('log(error)')
    plt.axis([min(dt_values), max(dt_values), E_min, E_max])
    plt.title('Error vs time step')
    plt.savefig('error.png')
    plt.savefig('error.pdf')
    # Write out a table in CSV format
    f = open('error.csv', 'w')
    f.write(r'$\Delta t$,$\theta=0$,$\theta=0.5$,$\theta=1$' + '\n')
    for dt, fe, cn, be in zip(
        errors['dt'], errors[0], errors[0.5], errors[1]):
        f.write(\%.2f,\%.4f,\%.4f,\%.4f ', (dt, fe, cn, be)
    f.close()
    # Combine images into rows with 2 plots in each row
    image_commands = []
    for method in 'BE', 'CN', 'FE':
```

```
pdf_files = ' '.join(['%s_%g.pdf' % (method, dt)
                              for dt in dt values])
       png_files = ', '.join(['%s_%g.png' % (method, dt)
                              for dt in dt values])
        image_commands.append(
            'montage -background white -geometry 100%' +
            '-tile 2x %s %s.png' % (png_files, method))
        image commands.append(
            'convert -trim %s.png %s.png' % (method, method))
       image_commands.append(
            'convert %s.png -transparent white %s.png' %
            (method, method))
        image commands.append(
            'pdftk %s output tmp.pdf' % pdf_files)
       num_rows = int(round(len(dt_values)/2.0))
        image commands.append(
            'pdfnup --nup 2x%d --outfile tmp.pdf tmp.pdf' % num_
        image_commands.append(
            'pdfcrop tmp.pdf %s.pdf' % method)
   for cmd in image_commands:
       print cmd
       failure = os.system(cmd)
       if failure:
            print 'Command failed:', cmd; sys.exit(1)
   # Remove the files generated above and by model.py
   from glob import glob
   filenames = glob('* *.png') + glob('* *.pdf') + glob('tmp*.p
   for filename in filenames:
       os.remove(filename)
if __name__ == '__main__':
   run experiments(I=1, a=2, T=5)
   plt.show() # at the end of the program
```

We may comment upon many useful constructs in this script:

- [float(arg) for arg in sys.argv[1:]] builds a list of real n from all the command-line arguments.
- failure = os.system(cmd) runs an operating system comman another program. The execution is successful only if failure is z
- Unsuccessful execution usually makes it meaningless to continue gram, and therefore we abort the program with sys.exit(1). At ment different from 0 signifies to the computer's operating system to program stopped with a failure.
- ['%s_%s.png' % (method, dt) for dt in dt_values] builds filenames from a list of numbers (dt values).
- All montage, convert, pdftk, pdfnup, and pdfcrop commands for composite figures are stored in a list and later executed in a loop.

- glob('* *.png') returns a list of the names of all files in the current directory where the filename matches the Unix wildcard notation ** *.png (meaning any text, underscore, any text, and then .png).
- os.remove(filename) removes the file with name filename.

Making a report

he results of running computer experiments are best documented in a little eport containing the problem to be solved, key code segments, and the plots om a series of experiments. At least the part of the report containing the lots should be automatically generated by the script that performs the set of speriments, because in that script we know exactly which input data that were sed to generate a specific plot, thereby ensuring that each figure is connected the right data. Take a look at an example at http://hplgit.github.io/ eamods/writing reports/sphinx-cloud/ to see what we have in mind.

'lain HTML. Scientific reports can be written in a variety of formats. Here e begin with the HTML¹⁵ format which allows efficient viewing of all the expernents in any web browser. The program exper1 html.py¹⁶ calls exper1.py perform the experiments and then runs statements for creating an HTML file ith a summary, a section on the mathematical problem, a section on the numeral method, a section on the solver function implementing the method, and a ection with subsections containing figures that show the results of experiments here Δt is varied for $\theta = 0, 0.5, 1$. The mentioned Python file contains all the etails for writing this HTML report¹⁷. You can view the report on http:// plgit.github.io/teamods/writing reports/ static/report html.html.

ITML with MathJax. Scientific reports usually need mathematical forrulas and hence mathematical typesetting. In plain HTML, as used in the xper1 html.py file, we have to use just the keyboard characters to write mathenatics. However, there is an extension to HTML, called MathJax¹⁸, which allows rmulas and equations to be typeset with LATEX syntax and nicely rendered in eb browsers, see Figure 4. A relatively small subset of LATEX environments is apported, but the syntax for formulas is quite rich. Inline formulas are look like (u'=-au \) while equations are surrounded by \$\$ signs. Inside such signs, one an use \[u'=-au \] for unnumbered equations, or \begin{equation} and end{equation} surrounding u'=-au for numbered equations, or \begin{align} nd \end{align} for multiple aligned equations. You need to be familiar with nathematical typesetting in LaTeX¹⁹.

We address the initial-value problen

$$u'(t) = -au(t), t \in (0, T],$$

 $u(0) = I$

where a, I, and T are prescribed parameters, and u(t) is the unknown function to be estimated. This mathematical model is relevant for physical

Numerical solution method

We introduce a mesh in time with points $0=t_0< t_1 \cdots < t_N=T$. For simplicity, we assume constant spacing Δt between the mesh points: $\Delta t = t_n - t_{n-1}$, $n = 1, \dots, N$. Let u^n be the numerical approximation to the exact solution at t_n . The θ -rule is used to solve (1) numerically:

$$u^{n+1} = \frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t}u^n,$$

for n = 0, 1, ..., N - 1. This scheme corresponds to

- The Forward Euler scheme when $\theta = 0$
- The Backward Euler scheme when $\theta = 1$ The Crank-Nicolson scheme when $\theta = 1/2$

```
The numerical method is implemented in a Python function:
def theta_rule(I, a, T, dt, theta):
    """Solve u'=-a'u, u(0)=I, for t in (0,T] with steps of dt."""
N = int(round(I/float(dt)))  # no of intervals
       u = zeros(N+1)
t = linspace(0, T, N+1)
```

Figure 4: Report in HTML format with MathJax.

The file exper1_mathjax.py²⁰ contains all the details for turning the 1 plain HTML report into web pages with nicely typeset mathematic corresponding HTML code²¹ be studied to see all details of the mathe typesetting.

LATEX. The de facto language for mathematical typesetting and s report writing is LaTeX²². A number of very sophisticated packages ha added to the language over a period of three decades, allowing very fin layout and typesetting. For output in the PDF format²³, see Figure ! example, LATEX is the definite choice when it comes to quality. The language used to write the reports has typically a lot of commands in backslashes and braces²⁴. For output on the web, using HTML (and not t directly in the browser window), LATEX struggles with delivering high typesetting. Other tools, especially Sphinx, give better results and o produce nice-looking PDFs. The file exper1 latex.py²⁵ shows how to s the LATEX source from a program.

Sphinx. Sphinx²⁶ is a typesetting language with similarities to HTl LATEX, but with much less tagging. It has recently become very pop software documentation and mathematical reports. Sphinx can utilize E

¹⁴http://en.wikipedia.org/wiki/Glob_(programming)

¹⁵http://en.wikipedia.org/wiki/HTML

¹⁶http://hplgit.github.io/teamods/writing_reports/report_generation/exper1_html.py

¹⁷ http://hplgit.github.io/teamods/writing reports/ static/report html.html.html

¹⁸http://www.mathjax.org/

¹⁹http://en.wikibooks.org/wiki/LaTeX/Mathematics

²⁰http://hplgit.github.io/teamods/writing reports/report generation/expe

²¹http://hplgit.github.io/teamods/writing_reports/_static/report_mathjax

²²http://en.wikipedia.org/wiki/LaTeX

²³http://hplgit.github.io/teamods/writing_reports/_static/report.pdf

²⁴http://hplgit.github.io/teamods/writing_reports/_static/report.tex.htm

²⁵http://hplgit.github.io/teamods/writing_reports/report_generation/expe

²⁶http://sphinx.pocoo.org/

3 Implementation

The numerical method is implemented in a Python function:

```
def theta_rule(I, a, T, dt, theta):
    """Solve u'=-a*u, u(0)=I, for t in (0,T] with steps of dt."""
N = int(round(Tfloat(dt)))  # no of intervals
u = zeros(N+1)
t = linspace(0, T, N+1)
u[0] = I
for n in range(0, N):
    u[n+1] = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)*u[n]
return u, t
```

4 Numerical experiments

We define a set of numerical experiments where I, a, and T are fixed, while Δt and θ are varied. In particular, I=1, a=2, $\Delta t=1.25, 0.75, 0.5, 0.1$.

Figure 5: Report in PDF format generated from LATEX source.

nathematical formulas and equations (via MathJax or PNG images). Unfortuately, the subset of ETEX mathematics supported is less than in full MathJax n particular, numbering of multiple equations in an align type environment is ot supported). The Sphinx syntax²⁷ is an extension of the reStructuredText nguage. An attractive feature of Sphinx is its rich support for fancy layout of eb pages²⁸. In particular, Sphinx can easily be combined with various layout nemes that give a certain look and feel to the web site and that offers table of ontents, navigation, and search facilities, see Figure 6.

Tarkdown. A recently popular format for easy writing of web pages is Markown²⁹. Text is written very much like one would do in email, using spacing and pecial characters to naturally format the code instead of heavily tagging the ext as in LATEX and HTML. With the tool Pandoc³⁰ one can go from Markdown a variety of formats. HTML is a common output format, but LATEX, epub, ML, OpenOffice, MediaWiki, and MS Word are some other possibilities.

Viki formats. A range of wiki formats are popular for creating notes on ne web, especially documents which allow groups of people to edit and add ontent. Apart from MediaWiki³¹ (the wiki format used for Wikipedia), wiki rmats have no support for mathematical typesetting and also limited tools for

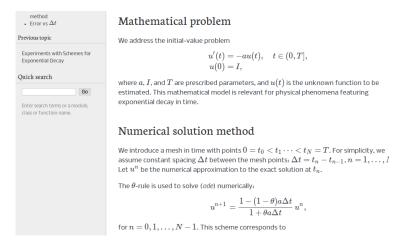


Figure 6: Report in HTML format generated from Sphinx source

displaying computer code in nice ways. Wiki formats are therefore less for scientific reports compared to the other formats mentioned here.

DocOnce. Since it is difficult to choose the right tool or format for w scientific report, it is advantageous to write the content in a format that translates to LATEX, HTML, Sphinx, Markdown, and various wikis. DocC such a tool. It is similar to Pandoc, but offers some special convenient feat writing about mathematics and programming. The tagging is modest, som between LATEX and Markdown. The program exper1_do.py³³ demon how to generate (and write) DocOnce code for a report.

Worked example. The HTML, LATEX (PDF), Sphinx, and DocOnce for the scientific report whose content is outlined above, are exemplification source codes and results at the web pages associated with this teaching rhttp://hplgit.github.io/teamods/writing_reports.

5.7 Publishing a complete project

A report documenting scientific investigations should be accompanied by software and data used for the investigations so that others have a possi redo the work and assess the qualify of the results. This possibility is im for *reproducible research* and hence reaching reliable scientific conclusion

One way of documenting a complete project is to make a directory to all relevant files. Preferably, the tree is published at some project hosting

 $^{^{27}} http://hplgit.github.io/teamods/writing_reports/_static/report_sphinx.rst.html$

 $^{^{28} \}texttt{http://hplgit.github.io/teamods/writing_reports/_static/sphinx-cloud/index.html}$

²⁹http://daringfireball.net/projects/markdown/

³⁰http://johnmacfarlane.net/pandoc/

³¹http://www.mediawiki.org/wiki/MediaWiki

³²https://github.com/hplgit/doconce

³³http://hplgit.github.io/teamods/writing_reports/report_generation/expe

it bucket or GitHub³⁴ so that others can download it as a tarfile, zip file, or clone ne files directly using the Git version control system. For the investigations utlined in Section 5.6, we can create a directory tree with files

```
setup.py
./src:
   model.py
./doc:
   ./src:
    exper1_mathjax.py
    make_report.sh
    run.sh
   ./pub:
    report.html
```

he src directory holds source code (modules) to be reused in other projects, ne setup.py builds and installs such software, the doc directory contains the ocumentation, with src for the source of the documentation and pub for eady-made, published documentation. The run.sh file is a simple Bash script sting the python command we used to run exper1_mathjax.py to generate ne experiments and the report.html file.

Exercises

'roblem 1: Make a tool for differentiating curves

uppose we have a curve specified through a set of discrete coordinates (x_i, y_i) , $= 0, \ldots, n$, where the x_i values are uniformly distributed with spacing Δx : $i = \Delta x$. The derivative of this curve, defined as a new curve with points (x_i, d_i) , an be computed via finite differences:

$$d_0 = \frac{y_1 - y_0}{\Delta x},\tag{6}$$

$$d_i = \frac{y_{i+1} - y_{i-1}}{2\Delta x}, \quad i = 1, \dots, n-1,$$
 (7)

$$d_n = \frac{y_n - y_{n-1}}{\Delta x} \,. \tag{8}$$

-) Write a function differentiate(x, y) for differentiating a curve with cordinates in the arrays x and y, using the formulas above. The function should eturn the coordinate arrays of the resulting differentiated curve.
-) Write a test function for the function in a).
-) Start with a curve corresponding to $y = \sin(\pi x)$ and n+1 points in [0,1] pply differentiate four times and plot the resulting curve and the exact $= \sin \pi x$ for n=6,11,21,41.

ilename: curvediff.py.

Problem 2: Make solid software for the Trapezoidal:

An integral

$$\int_{a}^{b} f(x)dx$$

can be numerically approximated by the Trapezoidal rule,

$$\int_{a}^{b} f(x)dx \approx \frac{h}{2}(f(a) + f(b)) + h \sum_{i=1}^{n-1} f(x_i),$$

where x_i is a set of uniformly spaced points in [a, b]:

$$h = \frac{b-a}{n}, \quad x_i = a+ih, \ i = 1, \dots, n-1.$$

Somebody has used this rule to compute the integral $\int_0^{\pi} sin^2x dx$:

```
from math import pi, sin
n = 20
h = pi/n
I = 0
for i in range(1, n):
    I += sin(i*h)**2
print I
```

- a) The "flat" implementation above suffers from three serious flaws:
 - 1. A general numerical algorithm (the Trapezoidal rule) is implemen specialized form where the formula for f is inserted directly into t for the general integration formula.
 - 2. A general numerical algorithm is not encapsulated as a general f with appropriate parameters, which can be reused across a wide applications.
 - 3. The lazy programmer dropped the first terms in the general form: $\sin(0) = \sin(\pi) = 0$.

Write a function trapezoidal that fixes these flaws. Place the function module trapezoidal.

b) Write a test function test_trapezoidal. Call the test function expl check that it works. Remove the call and run pytest on the module:

Terminal> py.test -s -v trapezoidal

³⁴http://hplgit.github.com/teamods/bitgit/html/

lint. Note that even if you know the value of the integral, you do not know ne error in the approximation produced by the Trapezoidal rule. However, the rapezoidal rule will integrate linear functions, and piecewise linear functions, ith discontinuities at the x_i points, exactly (i.e., to machine precision). Base a est function on such linear functions f(x).

) Add functionality for computing $\int_a^b f(x)dx$ by providing f, a, b, and n as ositional command-line arguments:

```
ərminal> python trapezoidal.py '\sin(x)**2' 0 pi 20
```

Note that the trapezoidal.py must still be a valid module file, so the iterpretation of command-line data and computation of the integral must be erformed from calls in a test block.

lint. To translate a string formula on the command line, like sin(x)**2, into Python function, you can wrap a function declaration around the formula and in exec on the string to turn it into live Python code:

```
import math, sys
formula = sys.argv[1]
floode = """
lef f(x):
    return %s
""" % formula
exec(code, math.__dict__)
```

he result is the same as if we had hardcoded

```
lef f(x):
    return sin(x)**2
```

1 the program. Note that exec needs the namespace $\mathtt{math.__dict__}$, i.e., all ames in the \mathtt{math} module, such that it understands \mathtt{sin} and other mathematical inctions. Similarly, to allow a and b to be \mathtt{math} values like \mathtt{pi} , do

```
= eval(sys.argv[2], math.__dict__)
= eval(sys.argv[2], math.__dict__)
```

) Write a test function for verifying the implementation of the reading data om the command line.

ilename: trapezoidal.py.

Problem 3: Implement classes for the Trapezoidal ru

We consider the same problem setting as in Problem 2. Make a module class Problem representing the mathematical problem to be solved and Solver representing the solution method. The rest of the functionality module, including test functions and reading data from the command line be as in Problem 2. Filename: trapezoidal class.py.

Problem 4: Write a doctest

Type in the following program and equip the roots function with a do

```
import sys
# This sqrt(x) returns real if x>0 and complex if x<0
from numpy.lib.scimath import sqrt

def roots(a, b, c):
    """
    Return the roots of the quadratic polynomial
    p(x) = a*x**2 + b*x + c.

    The roots are real or complex objects.
    """
    q = b**2 - 4*a*c
    r1 = (-b + sqrt(q))/(2*a)
    r2 = (-b - sqrt(q))/(2*a)
    return r1, r2

a, b, c = [float(arg) for arg in sys.argv[1:]]
print roots(a, b, c)</pre>
```

Make sure to test both real and complex roots. Write out numbers with 1 or less. Filename: doctest_roots.py.

Problem 5: Write a nose test

Make a test function for the roots function in Problem 4. Filename: test

Exercise 6: Make use of a class implementation

Implement the experiment_compare_dt function from decay.py usin Problem and class Solver from Section 4. The parameters I, a, T, the name, and a series of dt values should be read from the command line. F experiment_compare_dt_class.py.

References

[1] H. P. Langtangen. A Primer on Scientific Programming With Python in Computational Science and Engineering. Springer, fourth edition

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