Motion Planning for Mobile Robots - HW3

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1. Matlab 版寻找到的路径如 Fig.1所示
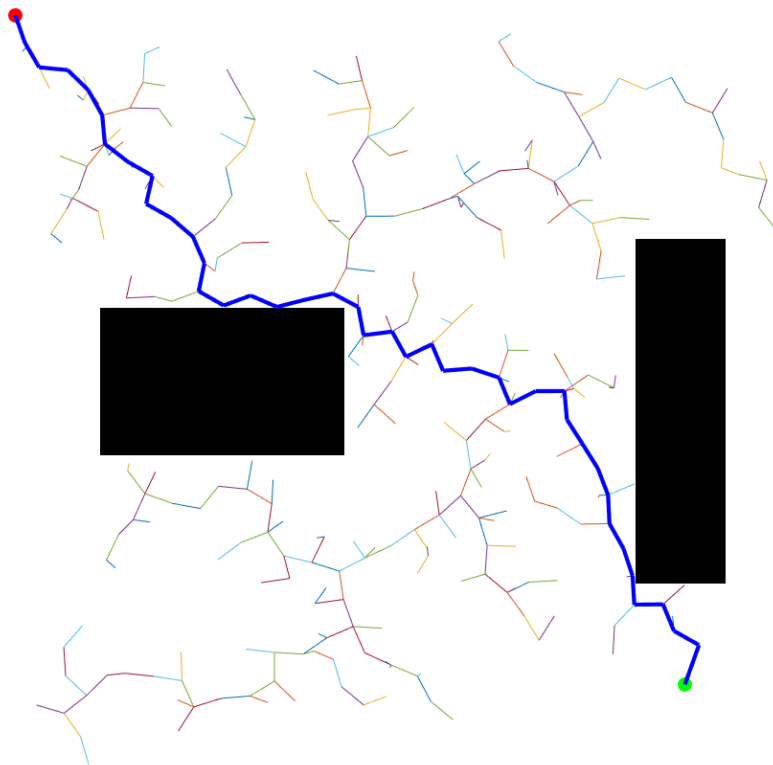

Figure 1: RRT

2. ROS 版寻找到的路径如 Fig.1所示
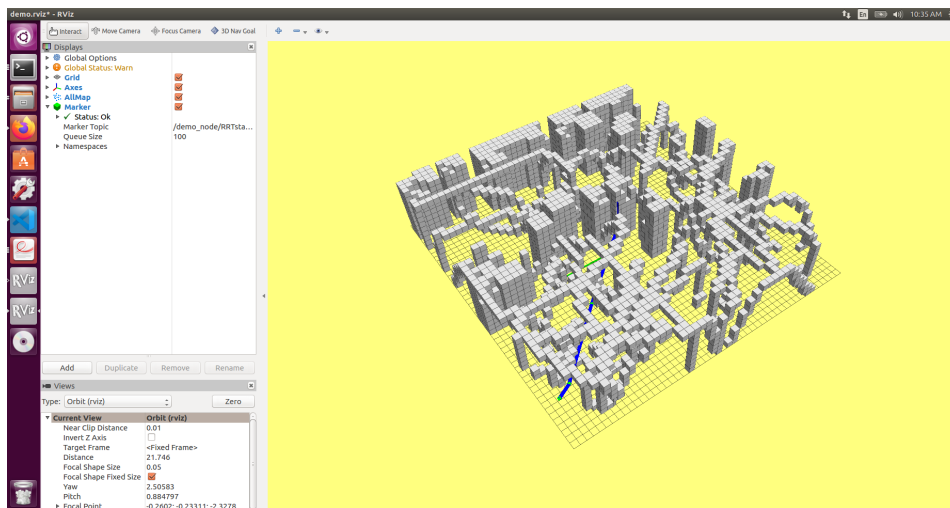
Figure 2: RRT*