

# AI & Robotics

Trees & Graphs

# Goals



## The **junior-colleague**

- can explain in own words what a tree is and its use cases
- can determine when a tree is a good data structure to use for a given problem
- can explain in own words what a binary tree is and its use cases
- can implement an arbitrary tree
- can implement pre-order, post-order and in-order tree traversal for arbitrary trees
- can explain in own words the state space of a problem
- can represent the state space of a problem
- can apply the state space procedure for a given problem
- can explain in own words what a graph is and its use cases
- can explain in own words the difference between undirected and directed in the context of graphs
- can explain in own words the difference between unweighted, weighted in context of graphs.
- can explain in own words the difference between acyclic and cyclic in context of graphs.
- can determine when a graph is a good data structure to use for a given problem
- can implement and differentiate the different graph representations

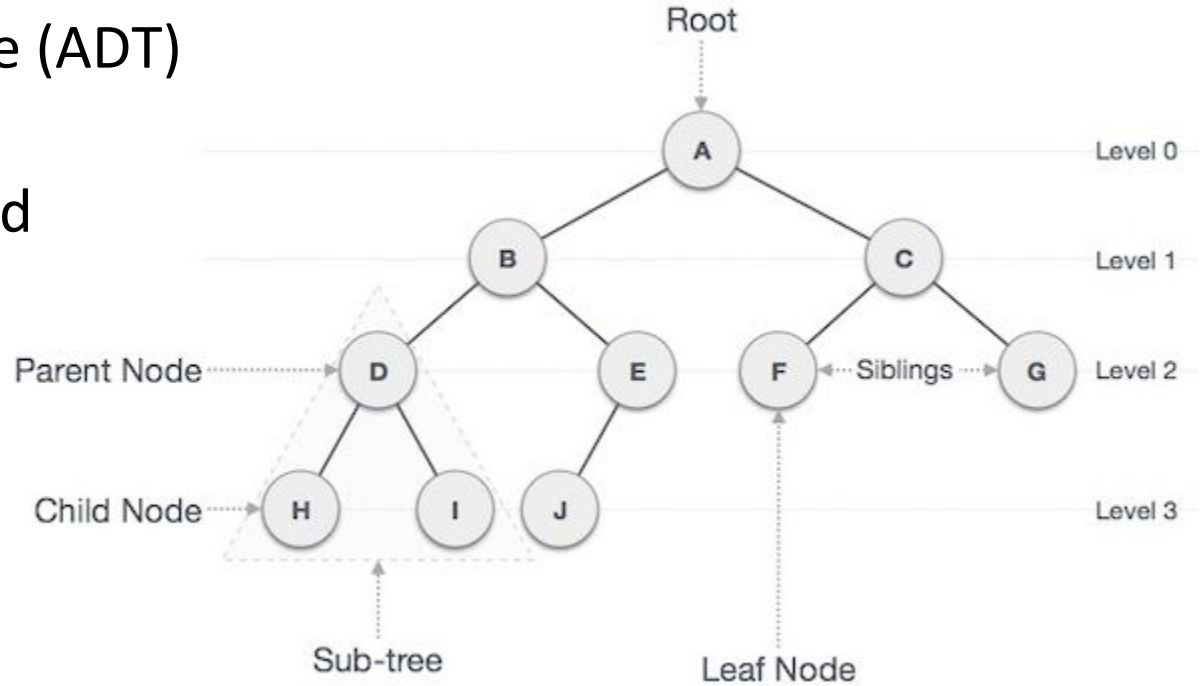
Trees





# Trees

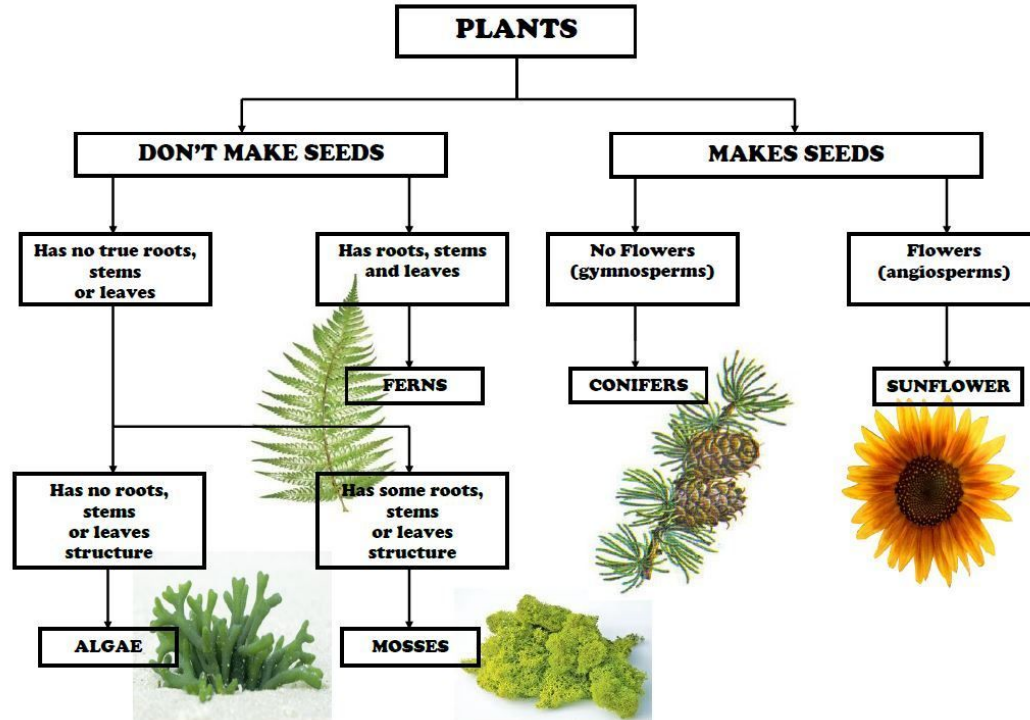
- Abstract Data Type (ADT)
- Hierarchical
- Recursively defined



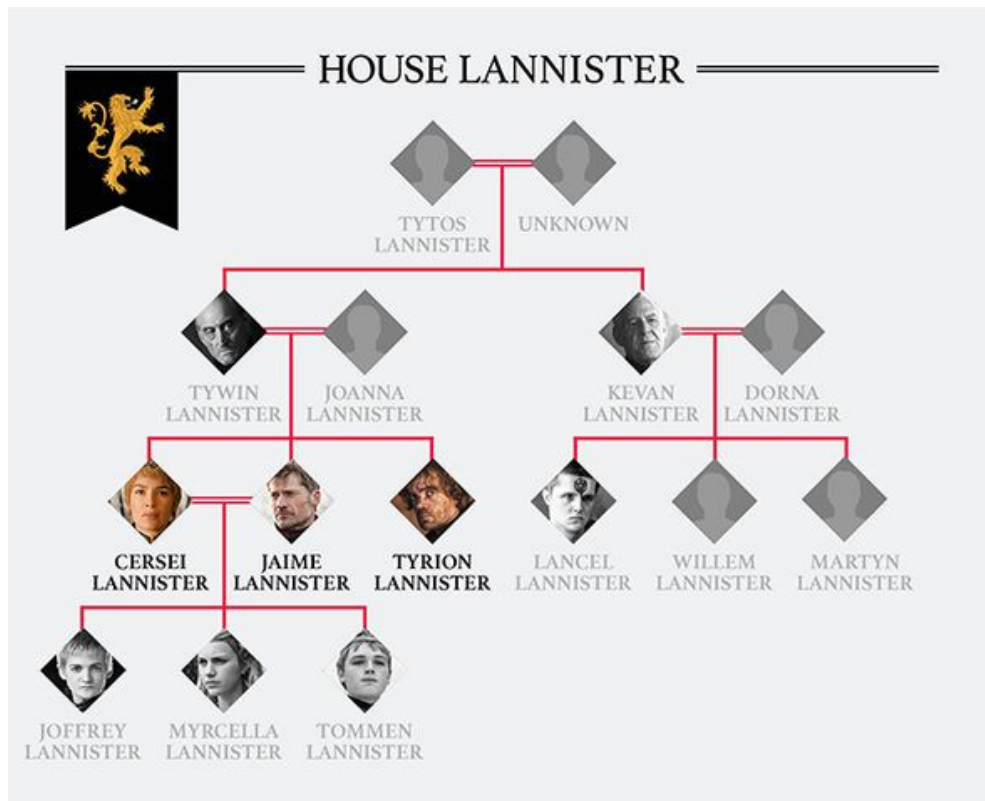
# Why?

- Modeling hierarchical relationships
  - Biological taxonomies
  - Family trees
  - Organizational structure
  - etc

# Why?

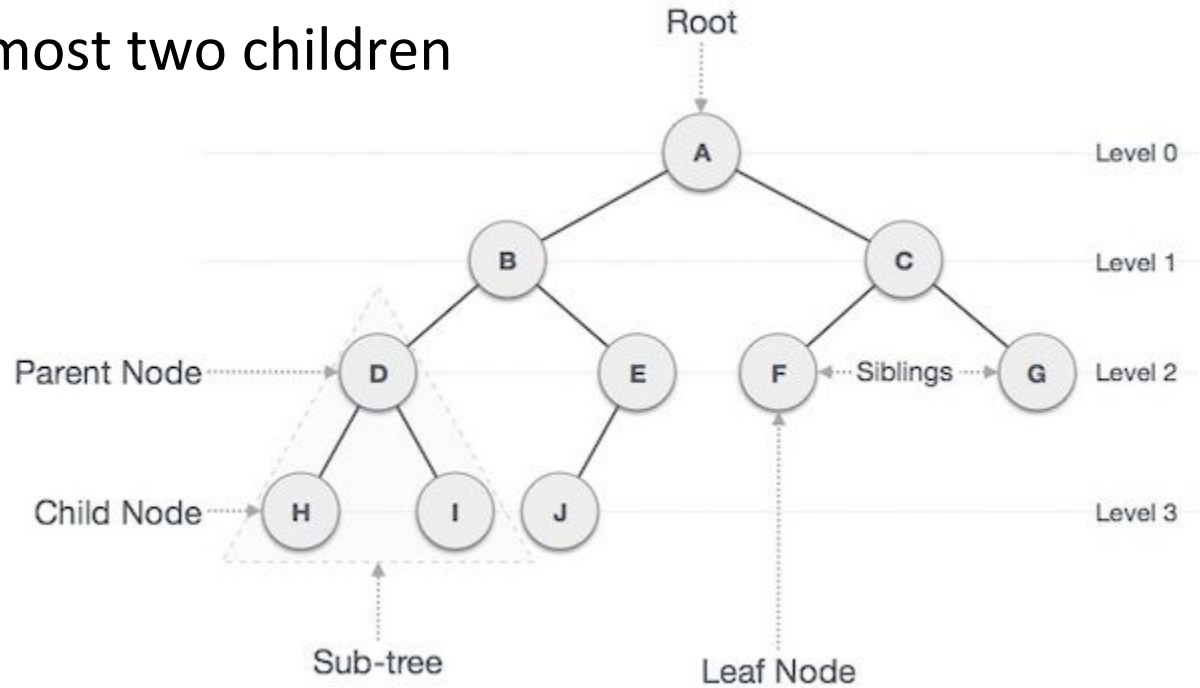


# Why?



# Binary Trees

- Each node has at most two children
  - Left child
  - Right child





# Representation

```
class Node:
    def __init__(self, data):
        self.left = None
        self.right = None
        self.data = data

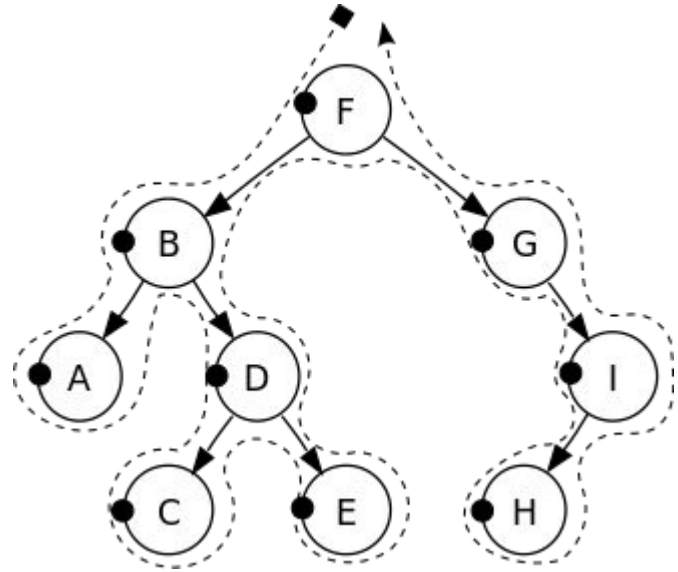
    def print_tree(self):
        print(self.data)
```

# Tree Traversal

- Visiting: checking the value of a node when control is on the node
- Traversing: passing through nodes in a specific order
  - Pre-order
  - In-order
  - Post-order

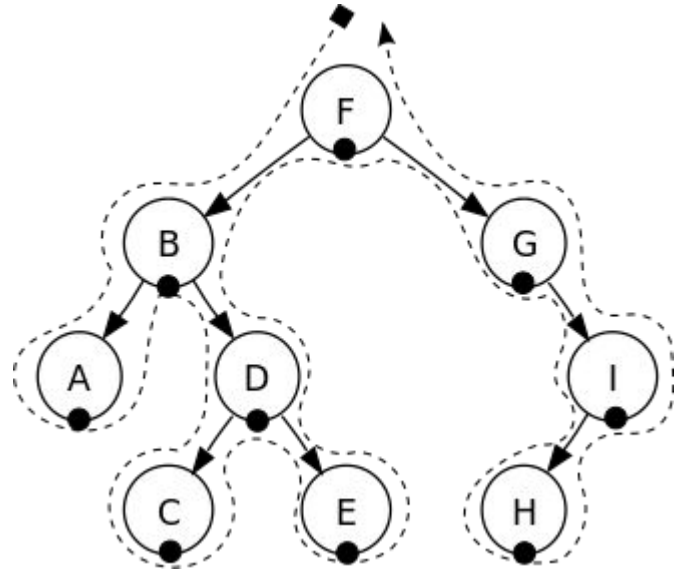
# Tree Traversal: Pre-order

```
def print_tree(self):  
    print(self.data)  
  
    if self.left:  
        self.left.print_tree()  
  
    if self.right:  
        self.right.print_tree()
```



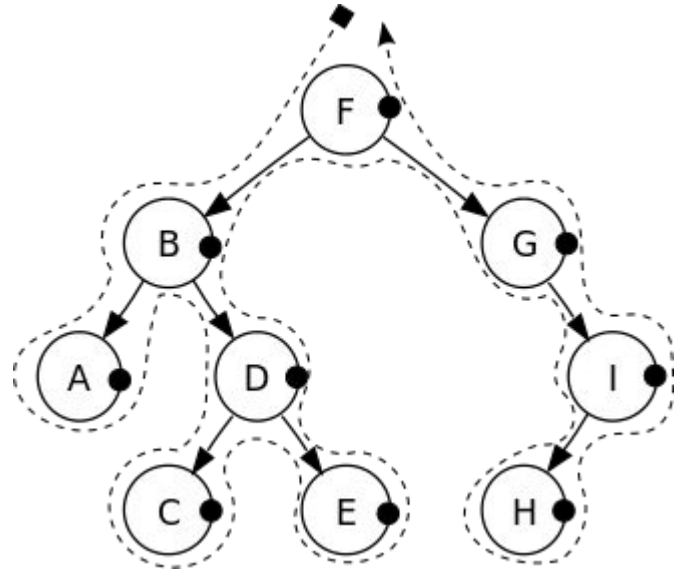
# Tree Traversal: In-order

```
def print_tree(self):  
    if self.left:  
        self.left.print_tree()  
  
    print(self.data)  
  
    if self.right:  
        self.right.print_tree()
```



# Tree Traversal: Post-order

```
def print_tree(self):  
    if self.left:  
        self.left.print_tree()  
  
    if self.right:  
        self.right.print_tree()  
  
    print(self.data)
```



State space representation



# State space representation

- World state includes every relevant detail of the environment
- Procedure:
  - Select some way to represent states in the problem in an unambiguous way.
  - Formulate all actions that can be performed in states including their preconditions and effects  
=> Production Rules
  - Represent the initial state (s).
  - Formulate precisely when a state satisfies the goal of our problem.
  - Activate the production rules on the initial state and its descendants, until a goal state is reached.

# State space representation: example

- The farmer, fox, goose and grain.

*A farmer has to cross a river with his fox, goose and grain. His boat can only carry himself and one of his possessions, though. Thus he needs to make several crossings in order for all the animals to reach the other bank. However, bear in mind that an unguarded fox will eat the goose and an unguarded goose will eat the grain.*

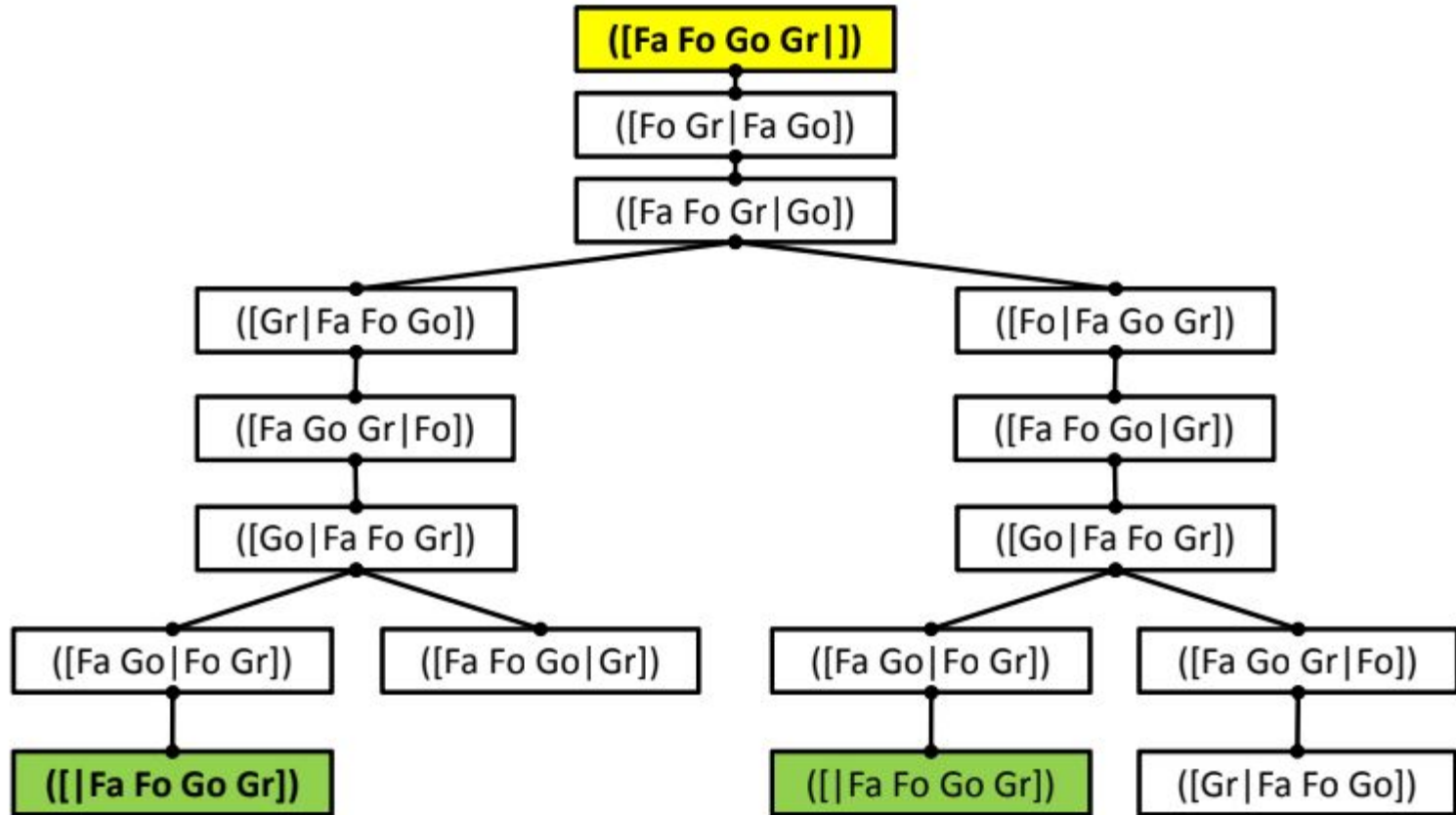
# State space representation: example

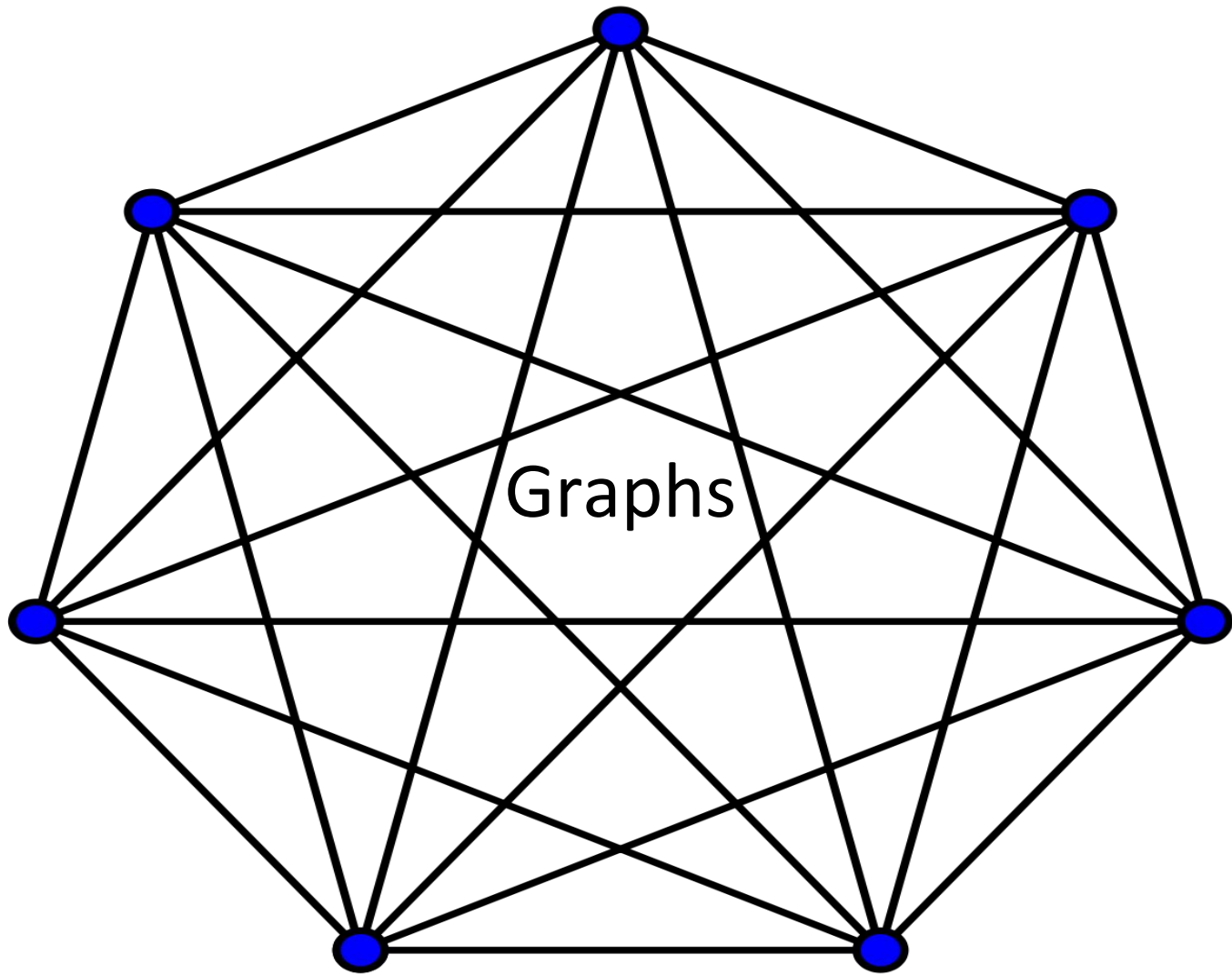
- States of the form  $[L|R]$ , where:
  - L: Items on left bank
  - R: Items on right bank
- L and R can contain:
  - Fa: Farmer
  - Fo: Fox
  - Go: Goose
  - Gr: Grain

# State space representation: example

- Start: [Fa Fo Go Gr|]
- Goal: [| Fa Fo Go Gr]
- Rules:
  - R1: [Fa x| y]  $\Rightarrow$  [x| Fa y]
  - R2: [x| Fa y]  $\Rightarrow$  [Fa x| y]
  - R3: [Fa z x| y]  $\Rightarrow$  [x| Fa z y]
  - R4: [x| Fa z y]  $\Rightarrow$  [Fa z x| y]
- No combination (Fo,Go) or (Go,Gr) on either bank, without the farmer.

# State tree







# Graphs

- Object Set:

$$G = (V, E)$$

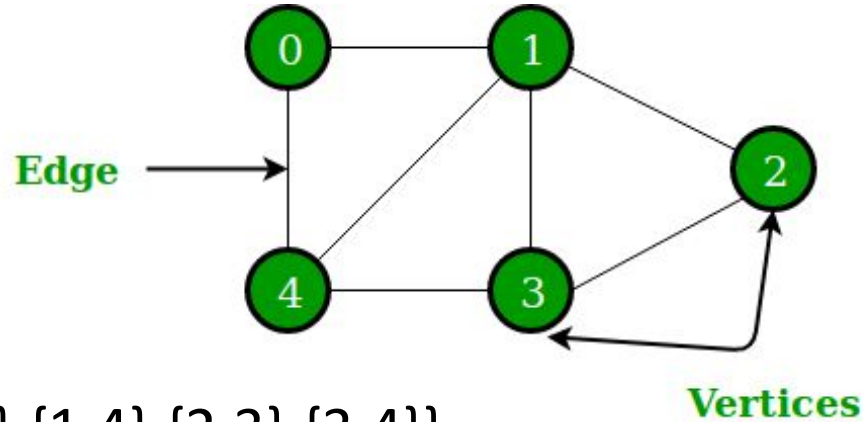
- V: set of vertices

$\{0,1,2,3,4\}$

- E: set of edges

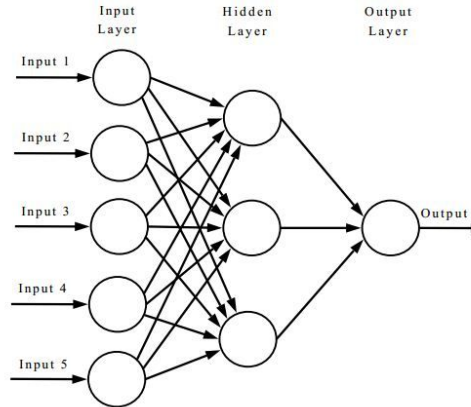
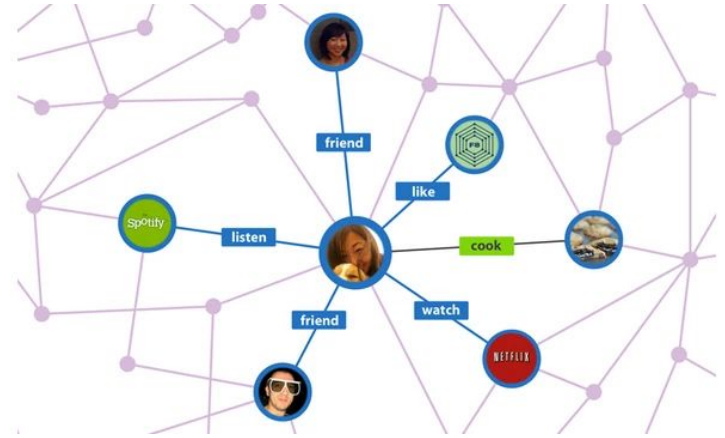
$\{\{0,1\},\{0,4\},\{1,2\},\{1,3\},\{1,4\},\{2,3\},\{3,4\}\}$

- Generalization of trees



# Why?

- Modeling complex relationships
  - Social relationships:
    - Facebook
    - LinkedIn
  - Maps
  - Neural networks
  - etc.



# Properties

- Undirected vs. Directed
- Unweighted vs. Weighted
- Acyclic vs. Cyclic

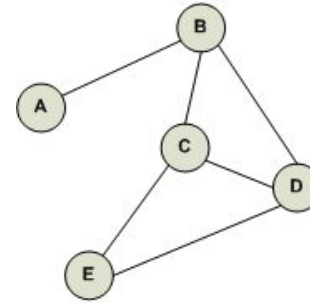
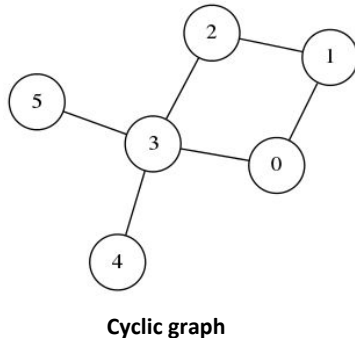
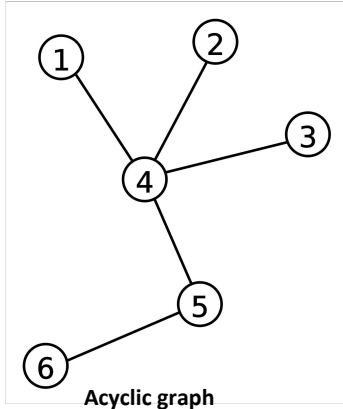


Fig 1. Undirected Graph

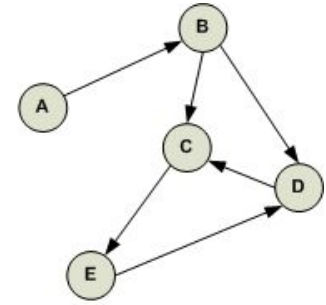
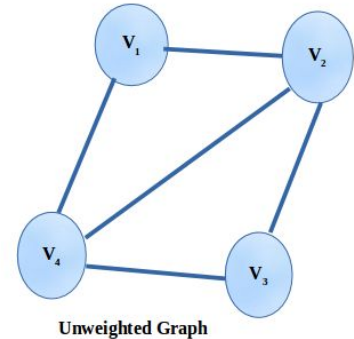
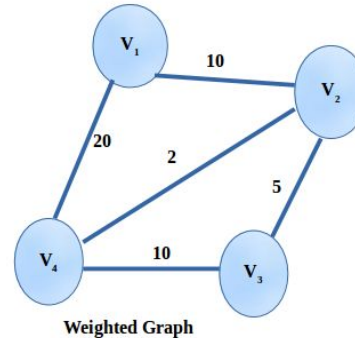


Fig 2. Directed Graph



# Trees vs. Graphs

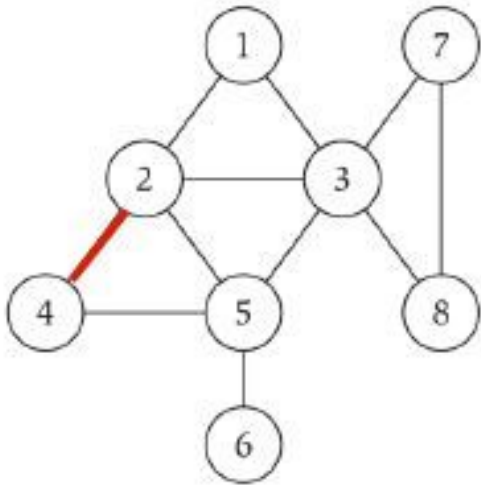
<b>Trees</b>	<b>Graphs</b>
only one path between any two vertices	more than one path between any two vertices
acyclic	cyclic or acyclic
undirected at first directed when a root node is chosen	directed or undirected
exactly one root node	no root node
$n-1$ edges	graph-dependent amount of edges
hierarchical model	network model

# Representation

- Adjacency matrix
- Adjacency List

# Adjacency matrix

- Good for dense graphs (lots of edges)



Nodes	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	1	0	0	0
3	1	1	0	0	1	0	1	1
4	0	1	0	0	1	0	0	0
5	0	1	1	1	0	1	0	0
6	0	0	0	0	1	0	0	0
7	0	0	1	0	0	0	0	1
8	0	0	1	0	0	0	1	0



# Adjacency list

- Good for sparse graphs (few edges)

