# AI & Robotics

**Environment setup** 



## Goals

#### The junior-colleague

• has a working anaconda environment



#### **Environment**







1. Download the Anaconda bash script at

https://www.anaconda.com/download/

2. Run the Anaconda script

```
$ bash Anaconda3-2018.12-Linux-x86_64.sh
```

Enter "yes" to everything!

At the end you will receive the following output

```
installation finished.
Do you wish the installer to prepend the Anaconda3 install location
to PATH in your /home/sammy/.bashrc ? [yes|no]
[no] >>>
```

Watch out with this!
ROS will stop working if this remains in your .bashrc

```
# enable programmable completion features (you don't need to enable
# this, if it's already enabled in /etc/bash.bashrc and /etc/profile
# sources /etc/bash.bashrc).
if ! shopt -oq posix; then
    if [ -f /usr/share/bash-completion/bash_completion ]; then
        . /usr/share/bash-completion/bash_completion
    elif [ -f /etc/bash_completion ]; then
        . /etc/bash_completion
    fi
fi
source /opt/ros/melodic/setup.bash
source ~/catkin_ws/devel/setup.bash
```

#### Separate anaconda.bash file!



After sourcing your anaconda.bash file, execute:

\$ anaconda-navigator

If this command is not immediately found, you forgot to source your anaconda.bash file!