

# PROJECT: FIR Filter Design and Implementation

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## FIR Filter Basics

An FIR (Finite Impulse Response) filter calculates the output as a weighted sum of current and past input samples. Mathematically, the output  $y[n]$  is given by:

$$y[n] = \sum_{k=0}^{N-1} h[k] \cdot x[n-k] \quad (1)$$

where:

- $y[n]$ : Filtered output at sample  $n$
- $x[n-k]$ : Input sample delayed by  $k$
- $h[k]$ : Filter coefficients (impulse response)
- $N$ : Number of filter coefficients (filter order + 1)

## Filter Design in MATLAB

The filter is designed with the following specifications:

- Sampling Frequency:  $F_s = 48000 \text{ Hz}$
- Stopband Frequencies:

$$f_{\text{stop1}} = 500 \text{ Hz}$$

$$f_{\text{stop2}} = 9000 \text{ Hz}$$

$$f_{\text{pass1}} = 1500 \text{ Hz}$$

$$f_{\text{pass2}} = 8000 \text{ Hz}$$

Normalized frequencies are calculated by dividing by the Nyquist frequency ( $F_N = F_s/2 = 24000 \text{ Hz}$ ):

$$f_{\text{stop1(norm)}} = \frac{500}{24000} = 0.0208$$

$$f_{\text{pass1(norm)}} = \frac{1500}{24000} = 0.0625$$

$$f_{\text{pass2(norm)}} = \frac{8000}{24000} = 0.3333$$

$$f_{\text{stop2(norm)}} = \frac{9000}{24000} = 0.3750$$

## Fixed-Point Conversion (Q(2,14))

In Q(2,14) format, numbers are represented as signed fixed-point values with:

- 2 integer bits (including sign bit)
- 14 fractional bits

Thus, the range of values is:

$$-2.0 \leq x < +1.9999\dots$$

To convert a floating-point coefficient to Q(2,14):

$$h[k]_{Q(2,14)} = \text{round}(h[k] \times 2^{14})$$

For example, for coefficient  $h[k] = 0.1234$ :

$$h[k]_{Q(2,14)} = \text{round}(0.1234 \times 2^{14}) = 2023$$

Overflow handling:

- If value exceeds +32767, wrap within signed 16-bit range.
- If value goes below -32768, wrap similarly.

## Sinewave Generation

The equation for generating a sinewave is:

$$x(t) = A \sin(2\pi ft)$$

For a sinewave frequency  $f_i$  sampled at  $F_s = 48000 \text{ Hz}$ , the duration of one cycle is:

$$T_i = \frac{1}{f_i}$$

The total time for 5 cycles:

$$T_{\text{total}} = 5 \times T_i = \frac{5}{f_i}$$

Number of samples required:

$$N_{\text{samples}} = T_{\text{total}} \times F_s$$

Example calculation for  $f_1 = 100 \text{ Hz}$ :

$$T_1 = \frac{1}{100} = 0.01 \text{ s}, \quad T_{\text{total}} = \frac{5}{100} = 0.05 \text{ s}, \quad N_{\text{samples}} = 0.05 \times 48000 = 2400 \text{ samples}.$$

Repeat similarly for frequencies  $f_2 = 2000 \text{ Hz}$ ,  $f_3 = 6000 \text{ Hz}$ , and  $f_4 = 11000 \text{ Hz}$ .

## FIR Filtering (Convolution)

Filtering involves convolving the input signal with the filter coefficients:

$$y[n] = h[0]x[n] + h[1]x[n-1] + \dots + h[N-1]x[n-(N-1)]$$

This can also be expressed as a dot product between the filter coefficients and a sliding window of input samples.

## Verilog Implementation (MAC Operation)

Filtering in Verilog uses Multiply-and-Accumulate (MAC):

$$y[n] += h[k] \times x[n-k]$$

Inputs  $(x[n-k], h[k])$  are in Q(2,14). The output  $y[n]$  is scaled back from Q(2,28) to Q(2,14).

## Verification: MATLAB vs Verilog Output Comparison

To verify correctness, compare MATLAB and Verilog outputs for all input signals. Ensure both outputs match within acceptable error margins due to fixed-point rounding.

## STEPS:

### 1 MATLAB CODE FOR FIR Filter Design and Export Coefficients:

```
1 % FIR Filter Design
2 filterDesigner; % Open the filter designer GUI
```

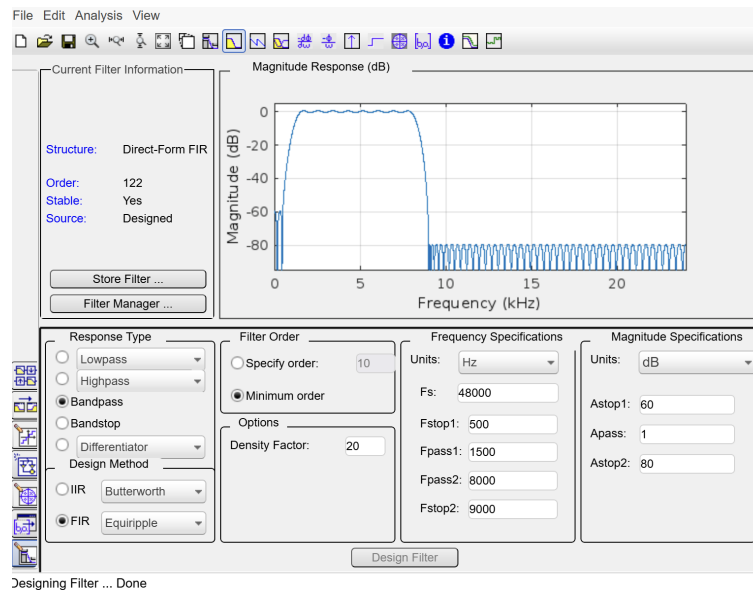


Figure 1: Response of BANDPASS FILTER

### 2 MATLAB CODE FOR Convert Coefficients to Fixed-Point Q(2,14):

```
1 % Load filter coefficients (replace 'Num' with your variable name)
2 load('filter_coefficients.mat'); % Load exported coefficients
3 coeff_fixed = round(Num * 2^14); % Convert to Q(2,14) format
4 coeff_fixed(coeff_fixed >= 2^15) = coeff_fixed(coeff_fixed >= 2^15)
5   - 2^16; % Handle overflow
6
6 % Save coefficients to a file
7 fileID = fopen('filter_coefficients_q214.txt', 'w');
8 fprintf(fileID, '%d\n', coeff_fixed);
9 fclose(fileID);
```

### 3 MATLAB CODE FOR Generate Input Signals:

```
1 fs = 48000; % Sampling frequency
2 t = 0:1/fs:5*(1/100); % Time vector for 5 cycles of the lowest
   frequency
3
4 % Generate sine waves
5 f1 = 100; f2 = 2000; f3 = 6000; f4 = 11000;
6 x1 = sin(2*pi*f1*t);
7 x2 = sin(2*pi*f2*t);
8 x3 = sin(2*pi*f3*t);
9 x4 = sin(2*pi*f4*t);
10
11 % Normalize and convert to Q(2,14)
12 signals = {x1, x2, x3, x4};
13 for i = 1:4
14     signal_fixed{i} = round(signals{i} * (2^14)); % Q(2,14)
15     signal_fixed{i}(signal_fixed{i} >= 2^15) = signal_fixed{i} -
        signal_fixed{i} >= 2^15; % Handle overflow
16
17     % Save each signal to a file
18     filename = sprintf('input_signal_%d_q214.txt', i);
19     fileID = fopen(filename, 'w');
20     fprintf(fileID, '%d\n', signal_fixed{i});
21     fclose(fileID);
22 end
```

### 4 Apply FIR Filter in MATLAB:

```
1 % Apply FIR filter to each signal
2 outputs = cell(1,4);
3 for i = 1:4
4     outputs{i} = filter(Num, 1, signals{i}); % Apply filter in
        floating-point
5 end
6
7 % Plot outputs for visualization
8 figure;
9 for i = 1:4
10     subplot(4,1,i);
11     plot(outputs{i});
12     title(['Filtered Output for Signal ', num2str(i)]);
13 end
14
15 % Save outputs in Q(2,14)
16 for i = 1:4
17     output_fixed{i} = round(outputs{i} * (2^14)); % Q(2,14)
18     output_fixed{i}(output_fixed{i} >= 2^15) = output_fixed{i} -
        output_fixed{i} >= 2^15; % Handle overflow
19
20     filename = sprintf('output_signal_%d_q214.txt', i);
21     fileID = fopen(filename, 'w');
```

```

22     fprintf(fileID, '%d\n', output_fixed{i});
23     fclose(fileID);
24 end

```

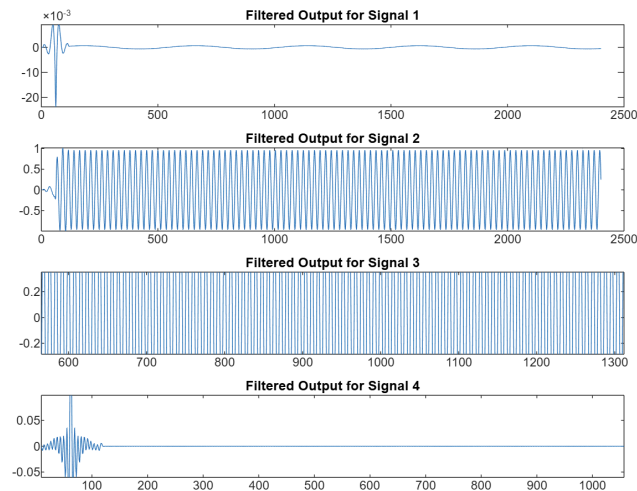


Figure 2:

## 5 For 5 Cycles:

```

1 % Sampling frequency
2 fs = 48000; % Sampling frequency in Hz
3
4 % Frequencies of the sinewaves
5 frequencies = [100, 2000, 6000, 11000]; % Frequencies in Hz
6
7 % Initialize cell array to store signals
8 signals = cell(1, length(frequencies));
9
10 % Generate sinewaves for each frequency
11 for i = 1:length(frequencies)
12     f = frequencies(i); % Current frequency
13     t = 0:1/fs:(5*(1/f)); % Time vector for 5 cycles of the current
        frequency
14     signals{i} = sin(2*pi*f*t); % Generate sinewave
15
16     % Save each signal to a file in Q(2,14) format
17     signal_fixed = round(signals{i} * (2^14)); % Convert to Q(2,14)
18     signal_fixed(signal_fixed >= 2^15) = signal_fixed(signal_fixed
        >= 2^15) - 2^16; % Handle overflow

```

```

19
20     filename = sprintf('input_signal_%dHz_q214.txt', f);
21     fileID = fopen(filename, 'w');
22     fprintf(fileID, '%d\n', signal_fixed);
23     fclose(fileID);
24
25     % Plot the sinewave
26     figure;
27     plot(t, signals{i});
28     title(['Sinewave for ', num2str(f), ' Hz (5 cycles)']);
29     xlabel('Time (s)');
30     ylabel('Amplitude');
31 end

```

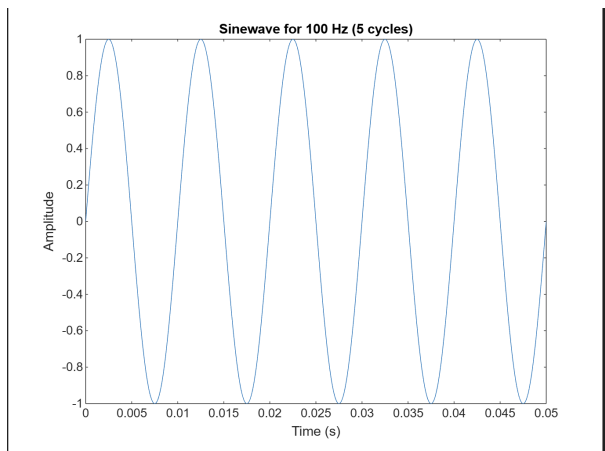


Figure 3:

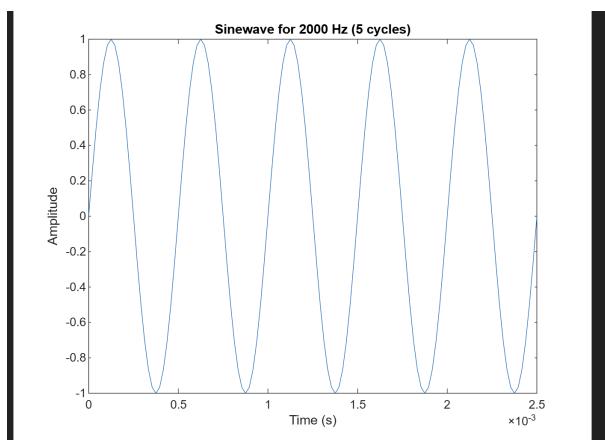


Figure 4:



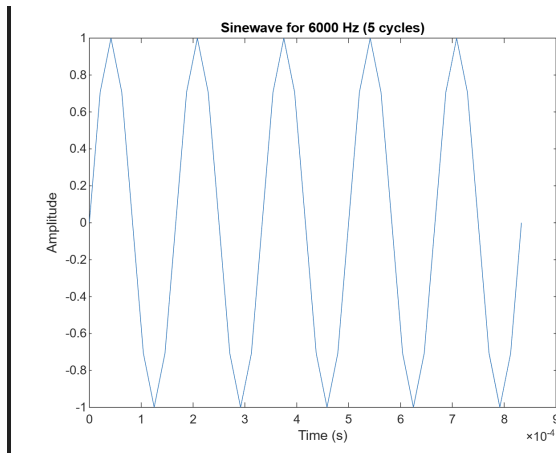


Figure 5:

## 6 Verilog Impletation:

```

1 module fir_filter(
2     input clk,
3     input reset,
4     input signed [15:0] x_in, // Input signal in Q(2,14)
5     output reg signed [31:0] y_out // Filtered output in Q(2,14)
6 );
7
8 parameter N = 20; // Number of filter coefficients (taps)
9
10 // Registers for coefficients and shift registers
11 reg signed [15:0] coeffs[N-1:0]; // Filter coefficients in Q(2,14)
12 reg signed [15:0] shift_reg[N-1:0]; // Shift register for input
    samples
13
14 integer i;
15
16 // Initialize coefficients from file
17 initial begin
18     $readmemb("filter_coefficients_q214.txt", coeffs); // Load
        coefficients from file
19 end
20
21 // FIR filter implementation
22 always @(posedge clk or posedge reset) begin
23     if (reset) begin
24         y_out <= 32'd0;
25         for (i = 0; i < N; i = i + 1) begin
26             shift_reg[i] <= 16'd0; // Clear shift registers on
                reset
27         end
28     end else begin

```

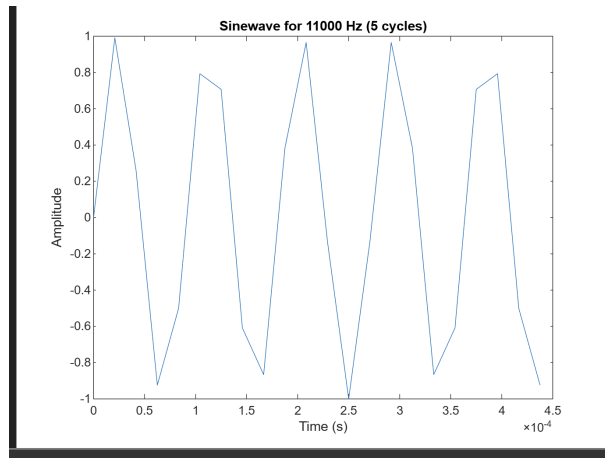


Figure 6:

```

29      // Shift input samples into the shift register
30      for (i = N-1; i > 0; i = i - 1) begin
31          shift_reg[i] <= shift_reg[i-1];
32      end
33      shift_reg[0] <= x_in;
34
35      // Multiply-Accumulate (MAC) operation to compute filter
36      output
37      y_out <= 32'd0; // Clear output accumulator
38      for (i = 0; i < N; i = i + 1) begin
39          y_out <= y_out + shift_reg[i] * coeffs[i];
40      end
41  end
42
43  endmodule

```

## 7 Test Bench:

```

1      module tb_fir_filter;
2
3      // Inputs and outputs for the DUT (Device Under Test)
4      reg clk;
5      reg reset;
6      reg signed [15:0] x_in;
7      wire signed [31:0] y_out;
8
9      // Instantiate the FIR filter module
10     fir_filter uut (
11         .clk(clk),
12         .reset(reset),

```

```

13     .x_in(x_in),
14     .y_out(y_out)
15 );
16
17 // File handling variables
18 integer infile, outfile;
19 integer scan;
20 reg signed [15:0] input_sample;
21
22 // Clock generation (50 MHz clock)
23 always #10 clk = ~clk;
24
25 initial begin
26     // Initialize clock and reset signals
27     clk = 0;
28     reset = 1;
29
30     #20 reset = 0; // Deassert reset after some time
31
32     // Process each input signal file one by one
33     process_signal("input_signal_100Hz_q214.txt", "
34         output_signal_100Hz_verilog_q214.txt");
35     process_signal("input_signal_2000Hz_q214.txt", "
36         output_signal_2000Hz_verilog_q214.txt");
37     process_signal("input_signal_6000Hz_q214.txt", "
38         output_signal_6000Hz_verilog_q214.txt");
39     process_signal("input_signal_11000Hz_q214.txt", "
40         output_signal_11000Hz_verilog_q214.txt");
41
42     $stop; // Stop simulation after processing all signals
43 end
44
45 // Task to process a single signal file through the FIR filter
46 task process_signal(input string infile_name, output string
47     outfile_name);
48 begin
49     infile = $fopen(infile_name, "r"); // Open input signal file
50     for reading
51     outfile = $fopen(outfile_name, "w"); // Open output file for
52     writing
53
54     if (infile == 0 || outfile == 0) begin
55         $display("Error opening file!");
56         $stop;
57     end
58
59     while (!$feof(infile)) begin
60         scan = $fscanf(infile, "%d\n", input_sample); // Read input
61         sample from file
62
63         @(posedge clk); // Wait for positive clock edge
64         x_in <= input_sample;
65
66         @(posedge clk); // Wait for another clock edge to capture
67         output sample
68     end
69 end

```

```

60         $fwrite(outfile, "%d\n", y_out >>> 14); // Write filtered
           output to file (scaled back to Q(2,14))
61     end
62
63     $fclose(infile); // Close input file after reading all samples
64     $fclose(outfile); // Close output file after writing all
           samples
65
66     $display("Processed %s -> %s", infile_name, outfile_name);
67 end
68 endtask
69
70 endmodule

```

## 8 Verification:

```

1     matlab_output = load('output_signal_100Hz_q214.txt');
2     verilog_output = load('output_signal_100Hz_verilog_q214.txt');
3
4     figure;
5     plot(matlab_output, 'b'); hold on;
6     plot(verilog_output, 'r--');
7     legend('MATLAB Output', 'Verilog Output');
8     title('Comparison of MATLAB and Verilog Outputs (100 Hz)');
9     xlabel('Samples'); ylabel('Amplitude');

```

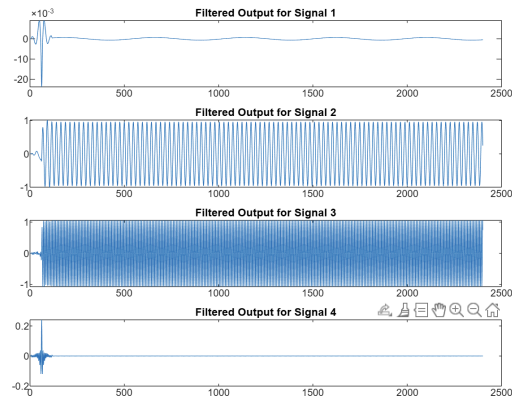


Figure 7: From Both