



# Managing Latency in Continuous GNU Radio Flowgraphs

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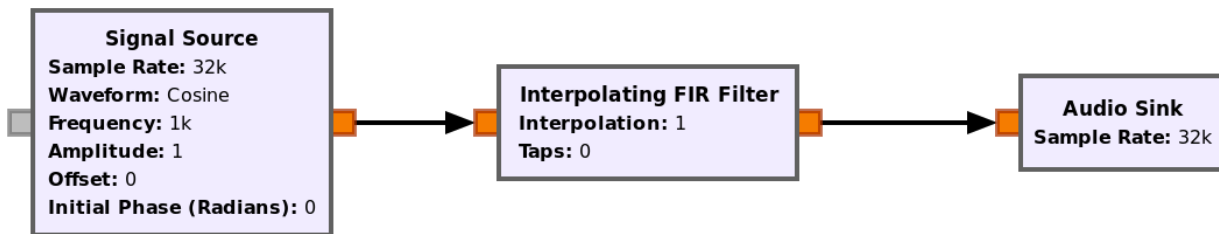
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GNU Radio Conference 2019

# Problem Statement

- What is Latency and where does it come from?
  - Inherent
  - Scheduler induced
    - Granularity of calls to work function
    - Thread latency, scheduler overhead, etc.
  - **Buffer induced**
- What causes buffer-induced latency?
- When is it a problem?
  - Generally only on TX
  - The „SkyBox Problem“
  - See `audio_latency.grc` flowgraph

# Buffers and the Scheduler



- What do the arrows really represent?
  - What happens when the arrows split?
- How does the scheduler work?
- What controls the rate of computation
- Great article by Marcus
  - <https://www.gnuradio.org/blog/2017-01-05-buffers/>

# Solutions

- Shrink buffers?
  - `myblock.set_max_output_buffer(num_items)`
  - NOOOOOO!!!!!!
    - Even minimum sized buffers can be too big in a large flowgraph
    - Some computations require buffers of a certain size
  - But *may* be useful to control scheduler-induced latency
- Drop items already in flight?
  - Dangerous, creates discontinuities
- Intelligently control the filling of buffers
  - Active Latency Management
  - Limit the number of in-flight data items between decision point and consumption
  - See solution flowgraph

# latency\_manager

```
int
latency_manager_impl::work(int noutput_items,
    gr_vector_const_void_star &input_items,
    gr_vector_void_star &output_items)
{
    const char *in = (const char*) input_items[0];
    char *out = (char *) output_items[0];

    int copy_count = std::min(noutput_items, d_tag_phase + d_tokens * d_tag_interval);
    std::memcpy(out, in, copy_count * d_itemsize);

    int tag_loc = d_tag_phase;
    while (tag_loc < copy_count) {
        d_tag.offset = nitems_written(0) + tag_loc;
        d_tag.value = pmt::from_long(tag_loc);
        add_item_tag(0, d_tag);
        tag_loc += d_tag_interval;
        d_tokens--;
    }
    d_tag_phase = tag_loc - copy_count;
    if(copy_count == 0) {
        boost::this_thread::sleep(boost::posix_time::microseconds(long(100)));
    }
    return copy_count;
}
```

# Use Cases

- Continuous Transmissions
  - Interactive Signal Generator
  - CW, RTTY, PSK31 for Hams
  - Dead man switch / self-destruct
  - Satellite TT&C (telemetry, control, and alarm) links
  - Muxed satellite downlink
- True Priority Muxes
- Realtime feedback control systems, hardware in the loop
- Can be extended for:
  - Mixed sample rate flowgraphs, and the two-clock problem
    - Control the arbitrary resampler to ensure buffer levels
  - Graceful handling of underruns

# Limitations and Future Work

- Only buffers within the feedback loop are managed
  - Sources could implement the latency manager
  - Sinks should report the latency tags
- Hardware buffers should be included in the loop as well
  - `audio_sink`
  - `uhd_sink`

- Thanks again to Derek
- Find the code at <https://github.com/dkozel/gr-workinprogress>
- Email -- [matt@ettus.net](mailto:matt@ettus.net)
- Twitter -- @Matt\_Rambling
- I'm hiring (@ Apple)
  - Communication Systems and Software Engineering
  - Intern (summer, winter, year-long)
  - Full Time