surgicus of a cector spine Definition: let le W be two subspaces of a vectorspace V. Define U+W= {u+w : a ell, wehl} Theorem: If u, W are subspaces of a vector space (3.16) 1 then U, W is a subspace of V V then U+W is a subspace of containing both UsiW. Further U, W is the smallest subspace containing both Usi W Proof: - UH = { unw : 4 EU, wEW}

Définition: Let u, W be subspaces of a vector que V. Sf UNW= {0} then U+W is called the direct sum of UE WE is written as UpW.

Définition: - let V be a vector space over a field F &' U & V. Then V is called linear combination of U, Uz, Un EV U=a,U, azUz + --- + an Un where aitf

4 n=1 a.s. gn=2 a.s.+a2.s.2

Definition :- Let S be a non-empty subset of a vector space V. The set of all linear combinations of finite number of elements of S is called the linear span of S is denoted by  $\langle S \rangle$ .

i.e  $\langle S \rangle = \{\sum_{i=1}^{n} a_i s_i : a_i \in F$ ,  $s_i \in S$ ,  $n \in N\}$ 

Theorem 8- let S be a finite set of vectors in (3.20)
(3.20)
(3 vector space V over a field F. Then

(5) is a subspace of V containing S

it is the smallest subspace containing S

Definition: A vectorspace V is usaid to be finite dimensional if there is a finite subset S in V such that

(S> = V

(ii) W= {(x,y,z) : x >0} Sol: let w = (x, y, z) EN & XER then dw, = d(x, y, z,) = (dx, dy, dz) As w, = (x1, y1, z1) (W then x1, 20 Xw, = (xxi, xyi, xzi) EW = = -1 , W = (1,2,3) EW So W is not a subspace of R3 (iii),  $W = \{ (x, y, z) : x^2 + y^2 + z^2 \le 1 \}$ Sol:- let & ER & W, = (x1, y1, z1) EN As w, Ew then xi+yi+zi ≤1 = (dx,, dy,, dz,) & W = Xw, EW : W1= (1,0,0) E W  $x = 2 \in R$ dw1 = 2(1,0,0) = (2,0,0) EN So W is not a subspace of R3

Définition: let V be a vector space over a field F. The vectors U, U2, -- Um EV are said to be linearly sadept ones F a, V, + a2 V2 + - - + am Um = 0 8' all ai + 0, ai EF, i=1,2,3,--m or if a1U1 + a2U2 + - - + am Um = 0 then at least one ai = o. Definition :- The vectors V., V2, -- Vm are said to be circarly independent over F if  $a_1 U_{1+} a_2 U_{2+--+} a_m U_m = 0 \text{ then all } ai = 0.$ independent set is defined to be linearly (ii) If V = 0 then [V] is linearly indept set

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Definition: - I set of linearly independent
   called a basis for V.
 Exp = 30 :- V = R^3 \approx B = \{e_1 = (1,0,0), e_2 = (0,1,0),
                               e3 = (0,0,1)
      Show that B is a basis for V.
Solicio Suppose areix ares + as es = 0
            ar(1,0,0) + ar(0,1,0) + ar(0,0,1) = 0
           (a,,0,0) + (0,0,0) + (0,0,03) = 0
           (a1+0+0, 0+02+0,0+0+03) =0
        (a_1, a_2, a_3) = (o, o, o)
       Q_1 = 0 , Q_2 = 0 , Q_3 = 0
    - B is linearly independent set.
   (ii) let U = (y, z) \in \mathbb{R}^3
     Suppose U= a, e, , axez , axez
      (x, y, z) = a, (1,0,0) + a, (0,1,0) + a, (0,0,1)
        (x, y, z) = (a_1, a_2, a_3)
          a, = x, a2 = y, a3 = Z
      :. U = xe, + ye, + ze3
.. < B > = R3
    Hence B is a basis for R3.
Q. (5). If u, v, w are linearly independent vectors
      Prove that
  (i) U+U-2w, U-V-w, U+w are linearly independel.
 Sol: Suppose a (U+U-200) + b(U-U-w) + c(U+w) =0
       => all +all - 2aw + bl- bl - bw + cll + cw = 0
         =) (a+b+c) U+ (a-b) U+ (-2a-b+c) w=0
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