

4.9 Matrix of Linear Transformation

Coordinate Vector

Let V and W be finite dimensional vector spaces over the same field F with $\dim V = n$ and $\dim W = m$. Let $B = \{v_1, v_2, \dots, v_n\}$ and $E = \{w_1, w_2, \dots, w_m\}$ be any bases for V and W respectively. Any vector v in V can be expressed in a unique way as a linear combination of v_1, v_2, \dots, v_n , i.e.

$$v = x_1 v_1 + x_2 v_2 + \dots + x_n v_n, \quad x_i \in F \quad (1 \leq i \leq n)$$

We call (x_1, x_2, \dots, x_n) the *coordinate vector* of v relative to the basis B .

If $T: V \rightarrow W$ is a linear transformation, then the images $T(v_1), \dots, T(v_n)$ are elements of W and each can be expressed uniquely as a linear combination of the basis vectors w_1, w_2, \dots, w_m , i.e.

$$T(v_1) = a_{11}w_1 + a_{21}w_2 + \dots + a_{m1}w_m$$

$$T(v_2) = a_{12}w_1 + a_{22}w_2 + \dots + a_{m2}w_m$$

$$\vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots$$

$$T(v_j) = a_{1j}w_1 + a_{2j}w_2 + \dots + a_{mj}w_m$$

$$\vdots \quad \quad \quad \vdots \quad \quad \quad \vdots \quad \quad \quad \vdots$$

$$T(v_n) = a_{1n}w_1 + a_{2n}w_2 + \dots + a_{mn}w_m$$

where $a_{ij} \in F$. The $m \times n$ matrix whose j th column is the coordinate vector of $T(v_j)$ is called the *matrix of linear transformation* T with respect to the bases B and E . Thus, the matrix of $T: V \rightarrow W$ relative to the bases B and E is

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1j} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2j} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mj} & \cdots & a_{mn} \end{bmatrix}$$

Conversely, if $A = [a_{ij}]$ is an $m \times n$ matrix with entries $a_{ij} \in F$, then A represents a linear transformation $T: F^n \rightarrow F^m$ defined by the equation $T(x) = Ax$, where

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \text{ is column vector of } F^n.$$

Example 1: Find the matrix of the linear transformation $T: R^3 \rightarrow R^4$ defined by $T(x_1, x_2, x_3) = (x_1 + x_2, x_2 + x_3, x_3, x_1)$ with respect to the standard bases for R^3 and R^4 .

Solution: $T(x_1, x_2, x_3) = (x_1 + x_2, x_2 + x_3, x_3, x_1)$

...(1)

Standard basis for R^3 is $B = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$, so by (1)

$$T(1, 0, 0) = (1, 0, 0, 1) = 1(1, 0, 0, 0) + 0(0, 1, 0, 0) + 1(0, 0, 1, 0) + 1(0, 0, 0, 1)$$

$$T(0, 1, 0) = (1, 1, 0, 0) = 1(1, 0, 0, 0) + 1(0, 1, 0, 0) + 0(0, 0, 1, 0) + 0(0, 0, 0, 1)$$

$$T(0, 0, 1) = (0, 1, 1, 0) = 0(1, 0, 0, 0) + 1(0, 1, 0, 0) + 1(0, 0, 1, 0) + 0(0, 0, 0, 1)$$

Thus, the matrix of linear transformation T is $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$.

Example 2: Find the determinant of the matrix obtained from the linear transformation $T: R^3 \rightarrow R^3$ defined by $T(x, y, z) = (3x - 2z, 5y + 7z, x + y + z)$.

Solution: $T(x, y, z) = (3x - 2z, 5y + 7z, x + y + z)$

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...(1)

Standard basis for R^3 is $B = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$, so by (1)

$$T(1, 0, 0) = (3, 0, 1) = 3(1, 0, 0) + 0(0, 1, 0) + 1(0, 0, 1)$$

$$T(0, 1, 0) = (0, 5, 1) = 0(1, 0, 0) + 5(0, 1, 0) + 1(0, 0, 1)$$

$$T(0, 0, 1) = (-2, 7, 1) = -2(1, 0, 0) + 7(0, 1, 0) + 1(0, 0, 1)$$

Matrix of linear transformation T is $A = \begin{bmatrix} 3 & 0 & -2 \\ 0 & 5 & 7 \\ 1 & 1 & 1 \end{bmatrix}$.

Determinant of linear transformation T is

$$\begin{aligned}\det A &= \begin{vmatrix} 3 & 0 & -2 \\ 0 & 5 & 7 \\ 1 & 1 & 1 \end{vmatrix} = 3(5-7) - 0 - 2(0-5) \\ &= 3(-2) - 2(-5) = -6 + 10 = 4\end{aligned}$$

Example 3: A linear transformation $T: R^2 \rightarrow R^3$ maps the vector $(1,1)$ into $(0,1,2)$ and the vector $(-1,1)$ into $(2,1,0)$. What matrix does T represent with respect to the standard bases for R^2 and R^3 ?

Solution: Here $T(1,1) = (0,1,2)$ and $T(-1,1) = (2,1,0)$. Let $x = (x_1, x_2) \in R^2$ and

$A = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix}$ be the matrix of linear transformation $T: R^2 \rightarrow R^3$, then

$$\begin{aligned}T(x) &= Ax = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} ax_1 + bx_2 \\ cx_1 + dx_2 \\ ex_1 + fx_2 \end{bmatrix} \\ \Rightarrow T(x_1, x_2) &= (ax_1 + bx_2, cx_1 + dx_2, ex_1 + fx_2) \\ \Rightarrow T(1,1) &= (a+b, c+d, e+f) \\ \Rightarrow (0,1,2) &= (a+b, c+d, e+f) \\ \Rightarrow a+b &= 0, c+d = 1, e+f = 2 \quad \dots(1)\end{aligned}$$

Similarly, $T(-1,1) = (2,1,0)$

$$\begin{aligned}\Rightarrow (-a+b, -c+d, -e+f) &= (2,1,0) \\ \Rightarrow -a+b &= 2, -c+d = 1, -e+f = 0 \quad \dots(2)\end{aligned}$$

Solving (1) and (2), we have $a = -1, b = 1, c = 0, d = 1, e = 1, f = 1$. Putting these values in

matrix A , we have $A = \begin{bmatrix} -1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}$.

Example 4: Find the matrix of linear transformation $T: R \rightarrow R^2$ defined by $T(x) = (3x, 5x)$ with respect to the standard bases of R and R^2 .

Solution: The standard bases for R and R^2 are $\{e\}, \{e_1, e_2\}$ respectively, where $e = (1), e_1 = (1,0), e_2 = (0,1)$. Now

$$T(e) = T(1) = (3,5) = (3,0) + (0,5) = 3(1,0) + 5(0,1) = 3e_1 + 5e_2$$

This shows that the matrix of linear transformation is $A = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$.

Example 5: Find the matrix of linear transformation $T: R^3 \rightarrow R^2$ defined by $T(x_1, x_2, x_3) = (3x_1 - 4x_2 + 9x_3, 5x_1 + 3x_2 - 2x_3)$ with respect to the standard bases of R^3 and R^2 .

Solution: The standard bases for R^3 and R^2 are $\{(1,0,0), (0,1,0), (0,0,1)\}$ and $\{(1,0), (0,1)\}$ respectively. Now

$$T(1,0,0) = (3,5) = (3,0) + (0,5) = 3(1,0) + 5(0,1)$$

$$T(0,1,0) = (-4,3) = (-4,0) + (0,3) = -4(1,0) + 3(0,1)$$

$$T(0,0,1) = (9,-2) = (9,0) + (0,-2) = 9(1,0) - 2(0,1)$$

Thus, the matrix of linear transformation is $A = \begin{bmatrix} 3 & -4 & 9 \\ 5 & 3 & -2 \end{bmatrix}$.

Example 6: Find the matrix of linear transformation $T: R^4 \rightarrow R$ defined by $T(x_1, x_2, x_3, x_4) = 2x_1 + 3x_2 - 7x_3 + x_4$ with respect to the standard bases of R^4 and R .

Solution: $\{(1,0,0,0), (0,1,0,0), (0,0,1,0), (0,0,0,1)\}$ and $\{(1)\}$ are the standard bases for R^4 and R respectively. Now

$$T(1,0,0,0) = 2 = 2(1)$$

$$T(0,1,0,0) = 3 = 3(1)$$

$$T(0,0,1,0) = -7 = -7(1)$$

$$T(0,0,0,1) = 1 = 1(1)$$

Thus, the matrix of linear transformation is $A = [2 \ 3 \ -7 \ 1]$.

Example 7: Find the matrix of linear transformation $T: R^2 \rightarrow R^4$ defined by $T(x_1, x_2) = (3x_1 + 4x_2, 5x_1 - 2x_2, x_1 + 7x_2, 4x_1)$ with respect to the standard bases of R^2 and R^4 .

Solution: $\{(1,0), (0,1)\}$ and $\{(1,0,0,0), (0,1,0,0), (0,0,1,0), (0,0,0,1)\}$ are the standard bases for R^2 and R^4 respectively. Now

$$T(1,0) = (3,5,1,4) = 3(1,0,0,0) + 5(0,1,0,0) + 1(0,0,1,0) + 4(0,0,0,1)$$

$$T(0,1) = (4,-2,7,0) = 4(1,0,0,0) - 2(0,1,0,0) + 7(0,0,1,0) + 0(0,0,0,1)$$

Thus, the matrix of linear transformation is $A = \begin{bmatrix} 3 & 4 \\ 5 & -2 \\ 1 & 7 \\ 4 & 0 \end{bmatrix}$.

Example 8: The matrix of a linear transformation $T: R^3 \rightarrow R^3$ is $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ -1 & -1 & 0 \end{bmatrix}$.