Columbia Manual of Ammanition

$$T(x_1,x_2,x_3) = (x_1,x_2,0) \text{ gives}$$

$$T(1,0,0) = (1,0,0) = 1(1,0,0) + 0(0,1,0) + 0(0,0,1)$$

$$T(0,1,0) = (0,1,0) = 0(1,0,0) + 1(0,1,0) + 0(0,0,1)$$

$$T(0,0,1) = (0,0,0) = 0(1,0,0) + 0(0,1,0) + 0(0,0,1)$$
Thus, the mank of linear transformation is  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ 

(ii) Find the matrix of the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by  $T(x_1, x_2, x_3) = (2x_1, x_2, 0)$  with respect to the standard basis for  $\mathbb{R}^3$ 

Sol: The standard bases for  $R^3$  is  $\{(1,0,0),(0,1,0),(0,0,1)\}$ .  $V_{0,0}$   $T(x_1,x_2,x_3)=(2x_1,x_2,0)$  gives T(1,0,0)=(2,0,0)=2(1,0,0)+0(0,1,0)+0(0,0,1) T(0,1,0)=(0,1,0)=0(1,0,0)+1(0,1,0)+0(0,0,1)

T(0,0,1) = (0,0,0) = 0(1,0,0) + 0(0,1,0) + 0(0,0,1)Thus, the matrix of linear transformation is  $A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$ .

0 0 0

(iii) Find the matrix of the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by  $T(x_1, x_2, x_3) = (x_1, 2x_2, x_3)$  with respect to the standard basis for  $\mathbb{R}^3$ .

**Sol:** The standard bases for  $\mathbb{R}^3$  is  $\{(1,0,0),(0,1,0),(0,0,1)\}$ . Now  $T(x_1,x_2,x_3)=(x_1,2x_2,x_3)$  gives

$$T(1,0,0) = (1,0,0) = 1(1,0,0) + 0(0,1,0) + 0(0,0,1)$$
  
 $T(0,1,0) = (0,2,0) = 0(1,0,0) + 2(0,1,0) + 0(0,0,1)$   
 $T(0,0,1) = (0,0,1) = 0(1,0,0) + 0(0,1,0) + 1(0,0,1)$ 

Thus, the matrix of linear transformation is  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$ 

(iv) Find the matrix of the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by  $T(x_1, x_2, x_3) = (x_1 + x_2, -x_1 - x_2, x_3)$  with respect to the standard basis for  $\mathbb{R}^3$ .

Sol: The standard bases for  $R^3$  is  $\{(1,0,0),(0,1,0),(0,0,1)\}$ . Now  $T(x_1,x_2,x_3)=(x_1+x_2,-x_1-x_2,x_3)$  gives T(1,0,0)=(1,-1,0)=1(1,0,0)-1(0,1,0)+0(0,0,1) T(0,1,0)=(1,-1,0)=1(1,0,0)-1(0,1,0)+0(0,0,1)

$$T(0,0,1) = (0,0,1) = 0(1,0,0) + 0(0,1,0) + 1(0,0,1)$$

Thus, the matrix of linear transformation is 
$$A = \begin{bmatrix} 1 & 1 & 0 \\ -1 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- Find the matrix of linear transformation  $T: R \to R^2$  defined by T(x) = (2x,5x) with respect to the standard bases of R and  $R^2$ .
- Standard bases for R and  $R^2$  are  $\{e\}$ ,  $\{e_1, e_2\}$  respectively, where  $e = (1), e_1 = (1, 0), e_2 = (0, 1)$ . Now T(x) = (2x, 5x) gives  $T(e) = T(1) = (2, 5) = (2, 0) + (0, 5) = 2(1, 0) + 5(0, 1) = 2e_1 + 5e_2$

This shows that the matrix of linear transformation is  $A = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$ .

## **Long Questions**

Find the matrix of the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^4$  defined by  $T(x_1, x_2, x_3) = (x_1 + x_2, x_2 + x_3, x_1 - x_3, x_1)$  with respect to the standard bases for  $\mathbb{R}^3$  and  $\mathbb{R}^4$ .

Sol:  $T(x_1, x_2, x_3) = (x_1 + x_2, x_2 + x_3, x_1 - x_3, x_1)$  PU, 2013, Mathematics A-III, BS (Math/Stat/Chem) ...(1)

Standard basis for  $R^3$  is  $B = \{(1,0,0),(0,1,0),(0,0,1)\}$ , so by (1) T(1,0,0) = (1,0,1,1) = 1(1,0,0,0) + 0(0,1,0,0) + 1(0,0,1,0) + 1(0,0,0,1) T(0,1,0) = (1,1,0,0) = 1(1,0,0,0) + 1(0,1,0,0) + 0(0,0,1,0) + 0(0,0,0,1)T(0,0,1) = (0,1,-1,0) = 0(1,0,0,0) + 1(0,1,0,0) - 1(0,0,1,0) + 0(0,0,0,1)

Thus, the matrix of linear transformation T is  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & -1 \\ 1 & 0 & 0 \end{bmatrix}$ 

3. Find the matrix of the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^4$  defined by  $T(x_1, x_2, x_3) = (2x_1, x_1 + x_2 + x_3, x_1 + 2x_2 - x_3, x_1 + 3x_3)$  with respect to the standard bases for  $\mathbb{R}^3$  and  $\mathbb{R}^4$ .

Sol:  $T(x_1, x_2, x_3) = (2x_1, x_1 + x_2 + x_3, x_1 + 2x_2 - x_3, x_1 + 3x_3)$  ...(1) Standard basis for  $R^3$  is  $B = \{(1,0,0), (0,1,0), (0,0,1)\}$ , so by (1)

T(1,0,0) = (2,1,1,1) = 2(1,0,0,0) + 1(0,1,0,0) + 1(0,0,1,0) + 1(0,0,0,1)

T(0,1,0) = (0,1,2,0) = 0(1,0,0,0) + 1(0,1,0,0) + 2(0,0,1,0) + 0(0,0,0,1)

T(0,0,1) = (0,1,-1,3) = 0(1,0,0,0) + 1(0,1,0,0) - 1(0,0,1,0) + 3(0,0,0,1)

Thus, the matrix of linear transformation T is

$$A = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & -1 \\ 1 & 0 & 3 \end{bmatrix}$$

- 4. Find the matrix of the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by  $T(x_1, x_2, x_3) = (x_1 + x_2, -x_2, x_3)$  with respect to the standard basis for  $\mathbb{R}^3$ .
- **Sol:** The standard bases for  $R^3$  is  $\{(1,0,0),(0,1,0),(0,0,1)\}$ .

Now 
$$T(x_1, x_2, x_3) = (x_1 + x_2, -x_2, x_3)$$
 gives  

$$T(1,0,0) = (1,0,0) = 1(1,0,0) + 0(0,1,0) + 0(0,0,1)$$

$$T(0,1,0) = (1,-1,0) = 1(1,0,0) - 1(0,1,0) + 0(0,0,1)$$

$$T(0,0,1) = (0,0,1) = 0(1,0,0) + 0(0,1,0) + 1(0,0,1)$$

Thus, the matrix of linear transformation is  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ .

- 5. Find the matrix of the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by  $T(x_1, x_2, x_3) = (x_2, -x_1, -x_3)$  with respect to the standard basis for  $\mathbb{R}^3$ .
- **Sol:** The standard bases for  $R^3$  is  $\{(1,0,0),(0,1,0),(0,0,1)\}$ .

Now 
$$T(x_1, x_2, x_3) = (x_2, -x_1, -x_3)$$
 gives  

$$T(1,0,0) = (0, -1,0) = 0(1,0,0) - 1(0,1,0) + 0(0,0,1)$$

$$T(0,1,0) = (1,0,0) = 1(1,0,0) + 0(0,1,0) + 0(0,0,1)$$

$$T(0,0,1) = (0,0,-1) = 0(1,0,0) + 0(0,1,0) - 1(0,0,1)$$

Thus, the matrix of linear transformation is  $A = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}$ .

- 6. Find the matrix of the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by  $T(x_1, x_2, x_3) = (x_2, x_1, x_3)$  with respect to the standard basis for  $\mathbb{R}^3$ .
- **Sol:** The standard bases for  $R^3$  is  $\{(1,0,0),(0,1,0),(0,0,1)\}$ .

Now 
$$T(x_1, x_2, x_3) = (x_2, x_1, x_3)$$
 gives  

$$T(1,0,0) = (0,1,0) = 0(1,0,0) + 1(0,1,0) + 0(0,0,1)$$

$$T(0,1,0) = (1,0,0) = 1(1,0,0) + 0(0,1,0) + 0(0,0,1)$$

$$T(0,0,1) = (0,0,-1) = 0(1,0,0) + 0(0,1,0) + 1(0,0,1)$$

Thus, the matrix of linear transformation is  $A = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ 

Exercise 4.7 401

Find the matrix of the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by  $T(x_1, x_2, x_3) = (x_1, x_2 + x_3, x_1 + x_2 + x_3)$  with respect to the standard basis for  $\mathbb{R}^3$ .

The standard bases for  $R^3$  is  $\{(1,0,0),(0,1,0),(0,0,1)\}$ .

Now 
$$T(x_1,x_2,x_3) = (x_1,x_2 + x_3,x_1 + x_2 + x_3)$$
 gives  

$$T(1,0,0) = (1,0,1) = 1(1,0,0) + 0(0,1,0) + 1(0,0,1)$$

$$T(0,1,0) = (0,1,1) = 0(1,0,0) + 1(0,1,0) + 1(0,0,1)$$

$$T(0,0,1) = (0,1,1) = 0(1,0,0) + 1(0,1,0) + 1(0,0,1)$$

Thus, the matrix of linear transformation is  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ .

A linear transformation  $T: \mathbb{R}^2 \to \mathbb{R}^3$  maps the vector (1,1) into (0,1,3) and the vector (-1,1) into (2,1,0). What matrix does T represent with respect to the standard bases for  $\mathbb{R}^2$  and  $\mathbb{R}^3$ ?

**Sol:** Here 
$$T(1,1) = (0,1,3)$$
 and  $T(-1,1) = (2,1,0)$ . Let  $x = (x_1,x_2) \in \mathbb{R}^2$  and  $A = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix}$ 

be the matrix of linear transformation  $T: \mathbb{R}^2 \to \mathbb{R}^3$ , then

$$T(x) = Ax = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} ax_1 + bx_2 \\ cx_1 + dx_2 \\ ex_1 + fx_2 \end{bmatrix}$$

$$\Rightarrow T(x_1, x_2) = (ax_1 + bx_2, cx_1 + dx_2, ex_1 + fx_2)$$

$$\Rightarrow T(1,1) = (a + b, c + d, e + f)$$

$$\Rightarrow (0,1,3) = (a + b, c + d, e + f)$$

$$\Rightarrow a + b = 0, c + d = 1, e + f = 3 \qquad \dots (1)$$

And T(-1,1) = (21,0)

$$\Rightarrow (-a+b,-c+d,-e+f) = (2,1,0)$$
  
\Rightarrow -a+b=2,-c+d=1,-e+f=0 ...(2)

Solving (1) and (2), we have

$$a = -1, b = 1, c = 0, d = 1, e = \frac{3}{2}, f = \frac{3}{2}$$

Putting these values in matrix 
$$A$$
, we have  $A = \begin{bmatrix} -1 & 1 \\ 0 & 1 \\ \frac{3}{2} & \frac{3}{2} \end{bmatrix}$ .

9. A linear transformation  $T: \mathbb{R}^2 \to \mathbb{R}^3$  maps the vector (1,1) into (0,1,1) A linear transformation  $T: R \to R$  and the vector (-1,0) into (1,1,0). What matrix does T represent with respect to the standard bases for  $R^2$  and  $R^3$ ?

**Sol:** Here 
$$T(1,1) = (0,1,1)$$
 and  $T(-1,0) = (1,1,0)$ . Let  $x = (x_1,x_2) \in \mathbb{R}^2$  and  $A = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix}$ 

be the matrix of linear transformation  $T: \mathbb{R}^2 \to \mathbb{R}^3$ , then

$$T(x) = Ax = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} ax_1 + bx_2 \\ cx_1 + dx_2 \\ ex_1 + fx_2 \end{bmatrix}$$

$$\Rightarrow T(x_1, x_2) = (ax_1 + bx_2, cx_1 + dx_2, ex_1 + fx_2)$$

$$\Rightarrow T(1,1) = (a + b, c + d, e + f)$$

$$\Rightarrow (0,1,1) = (a + b, c + d, e + f)$$

$$\Rightarrow a + b = 0, c + d = 1, e + f = 1$$

And 
$$T(-1,0) = (1,1,0) \Rightarrow (-a+b,-c+d,-e+f) = (1,1,0)$$
 ...(1)

Solving (1) and (2), we have

$$a = -\frac{1}{2}, b = \frac{1}{2}, c = 0, d = 1, e = \frac{1}{2}, f = \frac{1}{2}$$

Putting these values in matrix A, we have  $A = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \\ 0 & 1 \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}$ .

Find the matrix of linear transformation  $T: R \to R^2$  defined by 10. T(x) = (x, 4x) with respect to the standard bases of R and  $R^2$ .

Standard bases for R and  $R^2$ Sol: are  $\{e\},\{e_1,e_2\}$  respectively, where  $e = (1), e_1 = (1,0), e_2 = (0,1)$ . Now T(x) = (x,4x) gives  $T(e) = T(1) = (1,4) = (1,0) + (0,4) = 1(1,0) + 4(0,1) = 1e_1 + 4e_2$ 

This shows that the matrix of linear transformation is  $A = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$ .

11. Find the matrix of linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^2$  defined by  $T(x_1, x_2, x_3) = (x_1 - 4x_2 + 9x_3, 5x_1 + 3x_2 - 2x_3)$  with respect to standard bases of  $R^3$  and  $R^2$ .

 $\{(1,0,0),(0,1,0),(0,0,1)\}$  and  $\{(1,0),(0,1)\}$  are the standard bases for  $R^3$  and  $R^2$ Sol: are respectively. Now  $T(x_1,x_2,x_3) = (x_1 - 4x_2 + 9x_3,5x_1 + 3x_2 - 2x_3)$  gives

17. The matrix of linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^3$  is  $A = \begin{bmatrix} 3 & 1 & 2 \\ 0 & 1 & 1 \\ -1 & 1 & 1 \end{bmatrix}$ 

Determine T in terms of coordinates of a vector  $x \in \mathbb{R}^3$ .

**Sol:** Let  $x = (x_1, x_2, x_3) \in \mathbb{R}^3$ , then T(x) = Ax gives

$$T\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 & 1 & 2 \\ 0 & 1 & 1 \\ -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3x_1 + x_2 + 2x_3 \\ 0x_1 + x_2 + x_3 \\ -x_1 + x_2 + x_3 \end{bmatrix}$$

$$\Rightarrow T(x_1, x_2, x_3) = (3x_1 + x_2 + 2x_3, x_2 + x_3, -x_1 + x_2 + x_3)$$

Chapter-4. Vester

The matrix of linear transformation 
$$T: \mathbb{R}^3 \to \mathbb{R}^3$$
 is  $A = \begin{bmatrix} 0 & 1 & 2 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ .

Determine T in terms of coordinates of a vector  $x \in \mathbb{R}^3$ .

sol: Let 
$$x = (x_1, x_2, x_3) \in \mathbb{R}^3$$
, then  $T(x) = Ax$  gives

$$T\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 & 1 & 2 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3x_1 + x_2 + 2x_3 \\ 0x_1 + x_2 + x_3 \\ x_1 + x_2 + x_3 \end{bmatrix}$$

$$\Rightarrow T(x_1, x_2, x_3) = (3x_1 + x_2 + 2x_3, x_2 + x_3, x_1 + x_2 + x_3)$$

 $T: \mathbb{R}^n \to \mathbb{R}^m$  Determine m, n and express T in terms of coordinates.

Sol: Since the number of columns of A determines n, so n = 5, and the number of rows of A determines m, so m = 3, therefore, we take  $x = (x_1, x_2, x_3, x_4, x_5)$ . Now T(x) = Ax gives

$$T\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 3 & 1 & 0 & 2 & 0 \\ 1 & 0 & 1 & 0 & 1 \\ 0 & -1 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 3x_1 + x_2 + 2x_4 \\ x_1 + x_3 + x_5 \\ -x_2 + x_4 + x_5 \end{bmatrix}$$

or 
$$T(x_1, x_2, x_3, x_4, x_5) = (3x_1 + x_2 + 2x_4, x_1 + x_3 + x_5 - x_2 - x_4 + x_5)$$

20. The matrix 
$$\begin{vmatrix} 0 & 1 \\ 1 & 0 & -1 \end{vmatrix}$$
 is the matrix of linear transformation  $\begin{vmatrix} -1 & -1 & 0 \end{vmatrix}$