# dog\_app

May 9, 2020

## 1 Convolutional Neural Networks

## 1.1 Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

**Note**: Once you have completed all of the code implementations, you need to finalize your work by exporting the Jupyter Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to **File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

**Note:** Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this Jupyter notebook.

## Step 0: Import Datasets

Make sure that you've downloaded the required human and dog datasets:

Note: if you are using the Udacity workspace, you *DO NOT* need to re-download these - they can be found in the /data folder as noted in the cell below.

- Download the dog dataset. Unzip the folder and place it in this project's home directory, at the location /dog\_images.
- Download the human dataset. Unzip the folder and place it in the home directory, at location /lfw.

Note: If you are using a Windows machine, you are encouraged to use 7zip to extract the folder. In the code cell below, we save the file paths for both the human (LFW) dataset and dog dataset in the numpy arrays human\_files and dog\_files.

## Step 1: Detect Humans

In this section, we use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

OpenCV provides many pre-trained face detectors, stored as XML files on github. We have downloaded one of these detectors and stored it in the haarcascades directory. In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

```
In [17]: import cv2
    import matplotlib.pyplot as plt
    %matplotlib inline

# extract pre-trained face detector
    face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')

# load color (BGR) image
    img = cv2.imread(human_files[0])
    # convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
    faces = face_cascade.detectMultiScale(gray)

# print number of faces detected in the image
    print('Number of faces detected:', len(faces))
```

```
# get bounding box for each detected face
for (x,y,w,h) in faces:
    # add bounding box to color image
    cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)

# convert BGR image to RGB for plotting
cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)

# display the image, along with bounding box
plt.imshow(cv_rgb)
plt.show()
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face\_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

#### 1.1.1 Write a Human Face Detector

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face\_detector, takes a string-valued file path to an image as input and appears in the code block below.

#### 1.1.2 (IMPLEMENTATION) Assess the Human Face Detector

**Question 1:** Use the code cell below to test the performance of the face\_detector function.

- What percentage of the first 100 images in human\_files have a detected human face?
- What percentage of the first 100 images in dog\_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human\_files\_short and dog\_files\_short.

**Answer:** (You can print out your results and/or write your percentages in this cell) the accuracy of face\_detector on humans====> 98% the accuracy of face\_detector on dog====> 17%

```
In [4]: from tqdm import tqdm
        human_files_short = human_files[:100]
        dog_files_short = dog_files[:100]
        #-#-# Do NOT modify the code above this line. #-#-#
        def acc_test(files):
         0 = 6
         for i in files:
            if face_detector(i)==False:
                d+=1
        return 100-d
        ## TODO: Test the performance of the face_detector algorithm
        ## on the images in human_files_short and dog_files_short.
        print('the accuracy of face_detector on humans=====>',acc_test(human_files_short))
        print('the accuracy of face_detector on dog=====>',acc_test(dog_files_short))
the accuracy of face_detector on humans====> 98
the accuracy of face_detector on dog=====> 17
```

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make

use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

## Step 2: Detect Dogs

In this section, we use a pre-trained model to detect dogs in images.

#### 1.1.3 Obtain Pre-trained VGG-16 Model

The code cell below downloads the VGG-16 model, along with weights that have been trained on ImageNet, a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories.

```
In [19]: import torch
         import torchvision.models as models
         # define VGG16 model
         VGG16 = models.vgg16(pretrained=True)
         # check if CUDA is available
         use_cuda = torch.cuda.is_available()
         # move model to GPU if CUDA is available
         if use cuda:
             VGG16 = VGG16.cuda()
         VGG16
Out[19]: VGG(
           (features): Sequential(
             (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (1): ReLU(inplace)
             (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (3): ReLU(inplace)
             (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
             (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (6): ReLU(inplace)
             (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (8): ReLU(inplace)
             (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
             (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (11): ReLU(inplace)
             (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
```

```
(13): ReLU(inplace)
    (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (15): ReLU(inplace)
    (16): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (17): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (18): ReLU(inplace)
    (19): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (20): ReLU(inplace)
    (21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (22): ReLU(inplace)
    (23): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (24): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (25): ReLU(inplace)
    (26): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (27): ReLU(inplace)
    (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (29): ReLU(inplace)
    (30): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (classifier): Sequential(
    (0): Linear(in_features=25088, out_features=4096, bias=True)
    (1): ReLU(inplace)
    (2): Dropout(p=0.5)
    (3): Linear(in_features=4096, out_features=4096, bias=True)
    (4): ReLU(inplace)
    (5): Dropout(p=0.5)
    (6): Linear(in_features=4096, out_features=1000, bias=True)
 )
)
```

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

#### 1.1.4 (IMPLEMENTATION) Making Predictions with a Pre-trained Model

In the next code cell, you will write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher\_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model. The output should always be an integer between 0 and 999, inclusive.

Before writing the function, make sure that you take the time to learn how to appropriately pre-process tensors for pre-trained models in the PyTorch documentation.

```
predicted ImageNet class for image at specified path
            Args:
                img_path: path to an image
            Returns:
                Index corresponding to VGG-16 model's prediction
            ## TODO: Complete the function.
            ## Load and pre-process an image from the given img_path
            ## Return the *index* of the predicted class for that image
            img = Image.open(img_path)
            transform = transforms.Compose(
                [transforms.Resize((224, 224)),
                 transforms.ToTensor(),
                 transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])
            img = transform(img)
            if use_cuda:
                    img = img.cuda()
            VGG16.eval()
            with torch.no_grad():
                out = VGG16(img.unsqueeze_(0))
                pred = out.cpu().data.numpy().argmax()
            VGG16.train()
            return pred # predicted class index
In [6]: ###### draft
In [7]: ###testing the functiion
        VGG16_predict(human_files[8])
Out[7]: 906
```

#### 1.1.5 (IMPLEMENTATION) Write a Dog Detector

While looking at the dictionary, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained VGG-16 model, we need only check if the pre-trained model predicts an index between 151 and 268 (inclusive).

Use these ideas to complete the dog\_detector function below, which returns True if a dog is detected in an image (and False if not).

## 1.1.6 (IMPLEMENTATION) Assess the Dog Detector

**Question 2:** Use the code cell below to test the performance of your dog\_detector function.

- What percentage of the images in human\_files\_short have a detected dog?
- What percentage of the images in dog\_files\_short have a detected dog?

#### **Answer:**

the accuracy of dog\_detector on humans====> 0% the accuracy of dog\_detector on dog====> 100%

## In [13]: ####draft###

We suggest VGG-16 as a potential network to detect dog images in your algorithm, but you are free to explore other pre-trained networks (such as Inception-v3, ResNet-50, etc). Please use the code cell below to test other pre-trained PyTorch models. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

## Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain a test accuracy of at least 10%. In Step 4 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have trouble distinguishing between a Brittany and a Welsh Springer Spaniel.

Brittany Welsh Springer Spaniel

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).

Curly-Coated Retriever American Water Spaniel

Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.

Yellow Labrador Chocolate Labrador

We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

#### 1.1.7 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dog\_images/train, dog\_images/valid, and dog\_images/test, respectively). You may find this documentation on custom datasets to be a useful resource. If you are interested in augmenting your training and/or validation data, check out the wide variety of transforms!

```
### TODO: Write data loaders for training, validation, and test sets
         ## Specify appropriate transforms, and batch_sizes
         train_dir = '/data/dog_images/train'
         valid_dir = '/data/dog_images/valid'
         test_dir = '/data/dog_images/test'
         train_transforms = transforms.Compose([transforms.Resize(300),
                                                transforms.CenterCrop(256),
                                                transforms.RandomRotation(30),
                                                transforms RandomHorizontalFlip(),
                                                transforms.ToTensor(),
                                                transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5,
         tv_transforms = transforms.Compose([transforms.Resize(300),
                                             transforms.CenterCrop(256),
                                           transforms.ToTensor(),
                                           transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5)
         train_data = datasets.ImageFolder(train_dir, transform=train_transforms)
         trainloader = torch.utils.data.DataLoader(train_data, batch_size=32, shuffle=True)
         test_data = datasets.ImageFolder(test_dir, transform=tv_transforms)
         testloader = torch.utils.data.DataLoader(test_data, batch_size=32, shuffle=True)
         valid_data = datasets.ImageFolder(valid_dir, transform=tv_transforms)
         validloader = torch.utils.data.DataLoader(valid_data, batch_size=32, shuffle=True)
         loaders_scratch = {'train':trainloader ,'test':testloader ,'valid':validloader}
In [14]: ##draft
```

**Question 3:** Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

#### Answer:

1)i resized the image and done some operation like rotation and random sizing to generalize our modle you you might notice that i made the pictuers size 300300 and crop it from the center to be 256256 i choose this tensor size becauce when i searched the internet for a good arcticture i found the one i implemented below so i choose this tensor to fit in the fully connected layer

2)i choose to add random rotation and RandomHorizontalFlip to add some generalization for the model

#### 1.1.8 (IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. Use the template in the code cell below.

```
# define the CNN architecture
class Net(nn.Module):
    ### TODO: choose an architecture, and complete the class
    def __init__(self):
        super(Net, self).__init__()
        ## Define layers of a CNN
        self.conv1 = nn.Conv2d(3, 64, 3, padding=1)
        self.conv2 = nn.Conv2d(64, 64, 3, padding=1)
        self.conv3 = nn.Conv2d(64, 512, 3, padding=1)
        # max pooling layer
        self.pool = nn.MaxPool2d(4, 4)
        self.fc1 = nn.Linear(512 * 4 * 4, 1500)
        # linear layer (500 -> 10)
        self.fc2 = nn.Linear(1500, 133)
        self.dropout = nn.Dropout(0.2)
    def forward(self, x):
        ## Define forward behavior
        x = self.pool(F.relu(self.conv1(x)))
        x = self.pool(F.relu(self.conv2(x)))
        x = self.pool(F.relu(self.conv3(x)))
        # flatten image input
        x = x.view(-1, 512 * 4 * 4)
        # add dropout layer
        x = self.dropout(F.relu(self.fc1(x)))
        x = self.fc2(x)
        return x
#-#-# You so NOT have to modify the code below this line. #-#-#
# instantiate the CNN
model_scratch = Net()
# move tensors to GPU if CUDA is available
if use_cuda:
    model_scratch.cuda()
```

**Question 4:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

**Answer:** i started with 3 convlution layers and max pool with sride and kernel of 4 i applied relu and max pool to every condution layer the i flatenned the out of the convlution layer to pass it to the fully connected layer we have two layers although one is enought but i think to take the input in two steps is better and find some pattern in the previous layer.

## 1.1.9 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_scratch, and the optimizer as optimizer\_scratch below.

#### 1.1.10 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_scratch.pt'.

```
In [14]: def train(n_epochs, loaders, model, optimizer, criterion, use_cuda, save_path):
             """returns trained model"""
             # initialize tracker for minimum validation loss
             valid_loss_min = np.Inf
             for epoch in range(1, n_epochs+1):
                 # initialize variables to monitor training and validation loss
                 train loss = 0.0
                 valid_loss = 0.0
                 ##################
                 # train the model #
                 ###################
                 model.train()
                 for batch_idx, (data, target) in enumerate(loaders['train']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.cuda(), target.cuda()
                     optimizer.zero_grad()
                 # forward pass: compute predicted outputs by passing inputs to the model
                     output = model(data)
                 # calculate the batch loss
                     loss = criterion(output, target)
                 # backward pass: compute gradient of the loss with respect to model parameters
                     loss.backward()
                 # perform a single optimization step (parameter update)
                     optimizer.step()
                 # update training loss
                     train_loss += loss.item()*data.size(0)
```

######################

```
######################
                 model.eval()
                 for batch_idx, (data, target) in enumerate(loaders['valid']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.cuda(), target.cuda()
                     ## update the average validation loss
                     output = model(data)
                 # calculate the batch loss
                     loss = criterion(output, target)
                 # update average validation loss
                     valid_loss += loss.item()*data.size(0)
                 # print training/validation statistics
                 train_loss = train_loss/len(trainloader.sampler)
                 valid_loss = valid_loss/len(validloader.sampler)
                 print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
                     epoch,
                     train_loss,
                     valid_loss
                     ))
                 \#\# TODO: save the model if validation loss has decreased
                 if valid_loss <= valid_loss_min:</pre>
                  print('Validation loss decreased ({:.6f} --> {:.6f}). Saving model ...'.forma
                  valid_loss_min,
                  valid_loss))
                  torch.save(model.state_dict(), save_path)
                  valid_loss_min = valid_loss
             # return trained model
             return model
         # train the model
         model_scratch = train(15, loaders_scratch, model_scratch, optimizer_scratch,
                               criterion_scratch, use_cuda, 'model_scratch.pt')
         # load the model that got the best validation accuracy
         model_scratch.load_state_dict(torch.load('model_scratch.pt'))
Epoch: 1
                 Training Loss: 4.879693
                                                 Validation Loss: 4.862168
Validation loss decreased (inf --> 4.862168). Saving model ...
Epoch: 2
                Training Loss: 4.839317
                                                 Validation Loss: 4.777234
Validation loss decreased (4.862168 --> 4.777234). Saving model ...
                 Training Loss: 4.679975
                                                Validation Loss: 4.598844
Epoch: 3
Validation loss decreased (4.777234 --> 4.598844). Saving model ...
```

# validate the model #

```
Training Loss: 4.468937
Epoch: 4
                                                Validation Loss: 4.454929
Validation loss decreased (4.598844 --> 4.454929). Saving model ...
                Training Loss: 4.339468
                                                Validation Loss: 4.316132
Epoch: 5
Validation loss decreased (4.454929 --> 4.316132). Saving model ...
                Training Loss: 4.228187
Epoch: 6
                                                Validation Loss: 4.226393
Validation loss decreased (4.316132 --> 4.226393). Saving model ...
Epoch: 7
                Training Loss: 4.141958
                                              Validation Loss: 4.301202
Epoch: 8
                Training Loss: 4.043466
                                                Validation Loss: 4.125783
Validation loss decreased (4.226393 --> 4.125783). Saving model ...
Epoch: 9
                Training Loss: 3.956284
                                                Validation Loss: 4.147149
                 Training Loss: 3.878084
                                                 Validation Loss: 4.056465
Epoch: 10
Validation loss decreased (4.125783 --> 4.056465). Saving model ...
                 Training Loss: 3.777106
                                                Validation Loss: 4.045132
Validation loss decreased (4.056465 --> 4.045132). Saving model ...
                                                 Validation Loss: 3.956378
Epoch: 12
                 Training Loss: 3.678199
Validation loss decreased (4.045132 --> 3.956378). Saving model ...
Epoch: 13
                 Training Loss: 3.593989
                                                Validation Loss: 3.944545
Validation loss decreased (3.956378 --> 3.944545). Saving model ...
                 Training Loss: 3.490375
                                                 Validation Loss: 3.788721
Epoch: 14
Validation loss decreased (3.944545 --> 3.788721). Saving model ...
Epoch: 15
                 Training Loss: 3.382321
                                               Validation Loss: 3.846833
```

#### 1.1.11 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 10%.

```
In [17]: import numpy as np
         model_scratch.load_state_dict(torch.load('model_scratch.pt'))
         def test(loaders, model, criterion, use_cuda):
             # monitor test loss and accuracy
             test_loss = 0.
             correct = 0.
             total = 0.
             model.eval()
             for batch_idx, (data, target) in enumerate(loaders['test']):
                 # move to GPU
                 if use cuda:
                     data, target = data.cuda(), target.cuda()
                 # forward pass: compute predicted outputs by passing inputs to the model
                 output = model(data)
                 # calculate the loss
                 loss = criterion(output, target)
                 # update average test loss
                 test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
```

#### 2 ---

## Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

## 2.0.1 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dogImages/train, dogImages/valid, and dogImages/test, respectively).

If you like, **you are welcome to use the same data loaders from the previous step**, when you created a CNN from scratch.

```
In [9]: ## TODO: Specify data loaders
    import torch
    import numpy as np
    import os
    from torchvision import datasets,transforms
    from PIL import ImageFile
    ImageFile.LOAD_TRUNCATED_IMAGES = True

### TODO: Write data loaders for training, validation, and test sets
    ## Specify appropriate transforms, and batch_sizes
    train_dir = '/data/dog_images/train'
    valid_dir = '/data/dog_images/valid'
    test_dir = '/data/dog_images/test'
    train_transforms = transforms.Compose([transforms.Resize(300),
```

```
transforms.CenterCrop(224),
                                       transforms.RandomRotation(30),
                                       transforms.RandomHorizontalFlip(),
                                       transforms.ToTensor(),
                                       transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5,
tv_transforms = transforms.Compose([transforms.Resize(300),
                                    transforms.CenterCrop(224),
                                  transforms.ToTensor(),
                                  transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))
train_data = datasets.ImageFolder(train_dir, transform=train_transforms)
trainloader = torch.utils.data.DataLoader(train_data, batch_size=20, shuffle=True)
test_data = datasets.ImageFolder(test_dir, transform=tv_transforms)
testloader = torch.utils.data.DataLoader(test_data, batch_size=20, shuffle=True)
valid_data = datasets.ImageFolder(valid_dir, transform=tv_transforms)
validloader = torch.utils.data.DataLoader(valid_data, batch_size=20, shuffle=True)
loaders = {'train':trainloader ,'test':testloader ,'valid':validloader}
```

#### 2.0.2 (IMPLEMENTATION) Model Architecture

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model\_transfer.

```
In [10]: import torchvision.models as models
         import torch.nn as nn
         ## TODO: Specify model architecture
         model_transfer = models.vgg16(pretrained=True)
         for param in model_transfer.features.parameters():
             param.requires_grad = False
         model_transfer.classifier[6] = nn.Linear(in_features=4096, out_features=133)
         for param in model_transfer.classifier.parameters():
             param.requires_grad = True
         # check if CUDA is available
         use_cuda = torch.cuda.is_available()
         if use_cuda:
             model_transfer = model_transfer.cuda()
         #print(model_transfer.classifier[6].out_features)
         model transfer
Out[10]: VGG(
```

```
(features): Sequential(
  (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (1): ReLU(inplace)
  (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (3): ReLU(inplace)
  (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (6): ReLU(inplace)
  (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (8): ReLU(inplace)
  (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (11): ReLU(inplace)
  (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (13): ReLU(inplace)
  (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (15): ReLU(inplace)
  (16): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (17): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (18): ReLU(inplace)
  (19): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (20): ReLU(inplace)
  (21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (22): ReLU(inplace)
  (23): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (24): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (25): ReLU(inplace)
  (26): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (27): ReLU(inplace)
  (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (29): ReLU(inplace)
  (30): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
(classifier): Sequential(
  (0): Linear(in_features=25088, out_features=4096, bias=True)
  (1): ReLU(inplace)
  (2): Dropout(p=0.5)
  (3): Linear(in_features=4096, out_features=4096, bias=True)
  (4): ReLU(inplace)
  (5): Dropout(p=0.5)
  (6): Linear(in_features=4096, out_features=133, bias=True)
)
```

**Question 5:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

## **Answer:**

)

i turned of the grad for the convlution layer changed the last fully connected layer this arctiture is

suitbale because it pretraind on image classfication including dogs.

## 2.0.3 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_transfer, and the optimizer as optimizer\_transfer below.

#### 2.0.4 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_transfer.pt'.

```
In [4]: def train(n_epochs, loaders, model, optimizer, criterion, use_cuda, save_path):
            """returns trained model"""
            # initialize tracker for minimum validation loss
            valid_loss_min = np.Inf
            for epoch in range(1, n_epochs+1):
                # initialize variables to monitor training and validation loss
                train_loss = 0.0
                valid_loss = 0.0
                ###################
                # train the model #
                ###################
                model.train()
                for batch_idx, (data, target) in enumerate(loaders['train']):
                    # move to GPU
                    if use_cuda:
                        data, target = data.cuda(), target.cuda()
                    optimizer.zero_grad()
                # forward pass: compute predicted outputs by passing inputs to the model
                    output = model(data)
                # calculate the batch loss
                    loss = criterion(output, target)
                # backward pass: compute gradient of the loss with respect to model parameters
                    loss.backward()
                # perform a single optimization step (parameter update)
                    optimizer.step()
                # update training loss
                    train_loss += loss.item()*data.size(0)
```

```
######################
                model.eval()
                for batch_idx, (data, target) in enumerate(loaders['valid']):
                    # move to GPU
                    if use_cuda:
                        data, target = data.cuda(), target.cuda()
                    ## update the average validation loss
                    output = model(data)
                # calculate the batch loss
                    loss = criterion(output, target)
                # update average validation loss
                    valid_loss += loss.item()*data.size(0)
                # print training/validation statistics
                train_loss = train_loss/len(trainloader.sampler)
                valid_loss = valid_loss/len(validloader.sampler)
                print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
                    epoch,
                    train_loss,
                    valid_loss
                    ))
                ## TODO: save the model if validation loss has decreased
                if valid_loss <= valid_loss_min:</pre>
                 print('Validation loss decreased ({:.6f} --> {:.6f}). Saving model ...'.format
                 valid_loss_min,
                 valid loss))
                 torch.save(model.state_dict(), save_path)
                 valid_loss_min = valid_loss
            # return trained model
            return model
        model_transfer = train(5, loaders, model_transfer, optimizer, criterion, use_cuda, 'mode
        # train(n_epochs, loaders_transfer, model_transfer, optimizer_transfer, criterion_transf
        # load the model that got the best validation accuracy (uncomment the line below)
        model_transfer.load_state_dict(torch.load('model_transfer.pt'))
                                                  Validation Loss: 0.919298
Epoch: 1
                 Training Loss: 2.359423
Validation loss decreased (inf --> 0.919298). Saving model ...
```

###################### # validate the model #

```
Epoch: 2 Training Loss: 1.202030 Validation Loss: 0.823602
Validation loss decreased (0.919298 --> 0.823602). Saving model ...

Epoch: 3 Training Loss: 1.005974 Validation Loss: 0.706248
Validation loss decreased (0.823602 --> 0.706248). Saving model ...

Epoch: 4 Training Loss: 0.876427 Validation Loss: 0.685346
Validation loss decreased (0.706248 --> 0.685346). Saving model ...

Epoch: 5 Training Loss: 0.772746 Validation Loss: 0.664473
Validation loss decreased (0.685346 --> 0.664473). Saving model ...
```

#### 2.0.5 (IMPLEMENTATION) Test the Model

Test Loss: 0.696334

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 60%.

```
In [10]: model_transfer.load_state_dict(torch.load('model_transfer.pt'))
        def test(loaders, model, criterion, use_cuda):
            # monitor test loss and accuracy
            test_loss = 0.
            correct = 0.
            total = 0.
            model.eval()
            for batch_idx, (data, target) in enumerate(loaders['test']):
                # move to GPU
                if use_cuda:
                   data, target = data.cuda(), target.cuda()
                # forward pass: compute predicted outputs by passing inputs to the model
                output = model(data)
                # calculate the loss
                loss = criterion(output, target)
                # update average test loss
                test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                # convert output probabilities to predicted class
                pred = output.data.max(1, keepdim=True)[1]
                # compare predictions to true label
                correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
                total += data.size(0)
            print('Test Loss: {:.6f}\n'.format(test_loss))
            print('\nTest Accuracy: %2d%% (%2d/%2d)' % (
                100. * correct / total, correct, total))
        test(loaders, model_transfer, criterion, use_cuda)
```

Test Accuracy: 78% (657/836)

## 2.0.6 (IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

```
In [12]: ### TODO: Write a function that takes a path to an image as input
        ### and returns the dog breed that is predicted by the model.
         \#model\_transfer.load\_state\_dict(torch.load('model\_transfer.pt'))
         # list of class names by index, i.e. a name can be accessed like class_names[0]
        class_names = [item[4:].replace("_", " ") for item in loaders['train'].dataset.classes]
        def predict_breed_transfer(img_path):
            # load the image and return the predicted breed
            img = Image.open(img_path)
            transform = transforms.Compose([transforms.Resize(300),
                                            transforms.CenterCrop(224),
                                          transforms.ToTensor(),
                                          transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5)
            img = transform(img)
            if use_cuda:
                    img = img.cuda()
            model_transfer.eval()
            with torch.no_grad():
                out = model_transfer(img.unsqueeze_(0))
                pred = out.cpu().data.numpy().argmax()
            return class_names[pred]
         print(class_names)
['Affenpinscher', 'Afghan hound', 'Airedale terrier', 'Akita', 'Alaskan malamute', 'American esk
In [20]: predict_breed_transfer(dog_files[0])
Out[20]: 'Bullmastiff'
```

## Step 5: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then, - if a **dog** is detected in the image, return the predicted



Sample Human Output

breed. - if a **human** is detected in the image, return the resembling dog breed. - if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face\_detector and human\_detector functions developed above. You are **required** to use your CNN from Step 4 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!

### 2.0.7 (IMPLEMENTATION) Write your Algorithm

```
In [21]: predict_breed_transfer(human_files[0])
Out [21]: 'Dachshund'
In [22]: ### TODO: Write your algorithm.
         ### Feel free to use as many code cells as needed.
         from PIL import ImageFile
         import torchvision.transforms as transforms
         def run_app(img_path):
             ## handle cases for a human face, dog, and neither
             img = Image.open(img_path)
             transform = transforms.Compose(
                 [transforms.Resize((224, 224)),
                  transforms.ToTensor(),
                  transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])
             img = transform(img)
             if dog_detector(img_path) == True:
                 pred = predict_breed_transfer(img_path)
                 x = 'the breed of this dog is '
                 print(x+pred)
                 plt.imshow(Image.open(img_path))
                 plt.show()
             elif face_detector(img_path) == True:
                 pred = predict_breed_transfer(img_path)
```

```
x = ''''hi human
you look like a '''
print(x + pred)
plt.imshow(Image.open(img_path))
plt.show()
else:
    pred = 'neither human nor dog'
    x = ''
    print(pred + x)
    plt.imshow(Image.open(img_path))
    plt.show()
In [19]: #draft
```

## Step 6: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that *you* look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

## 2.0.8 (IMPLEMENTATION) Test Your Algorithm on Sample Images!

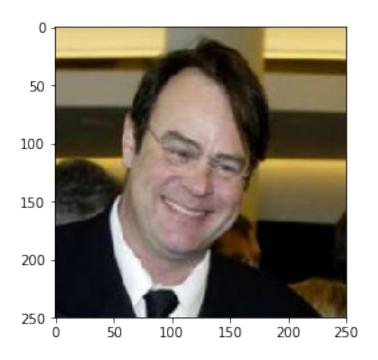
Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

**Question 6:** Is the output better than you expected :) ? Or worse :(? Provide at least three possible points of improvement for your algorithm.

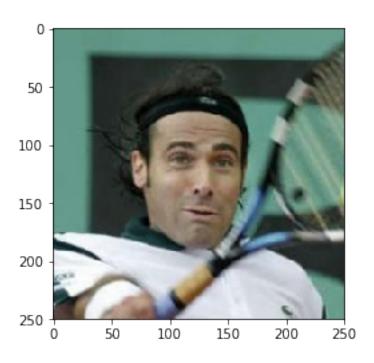
#### **Answer:**

the output is actually good it even get the breed of the pictures i uploaded right the model has done well for 5 epochs of training to make it better:-

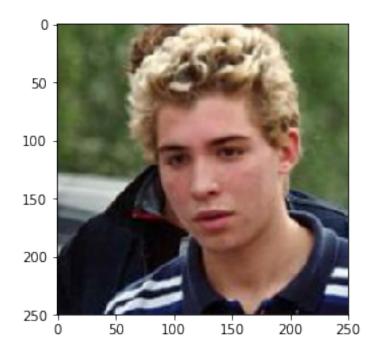
- 1)train it for more epochs
- 2) add more randoumness in the data
- 3)add more data



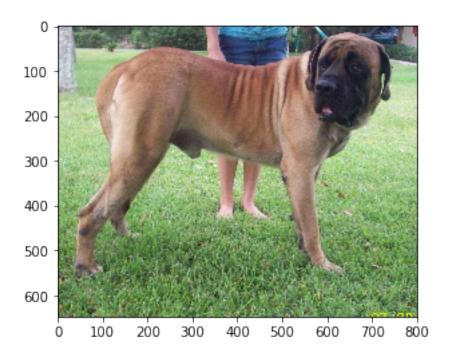
'hi human you look like a Dachshund



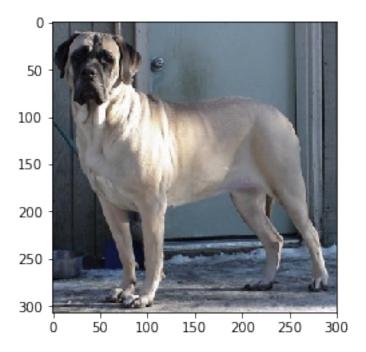
'hi human
you look like a Chinese crested



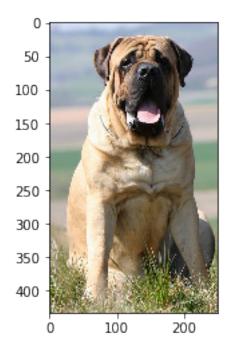
the breed of this dog is Bullmastiff



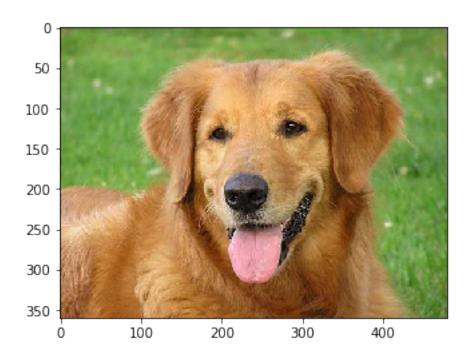
the breed of this dog is Mastiff



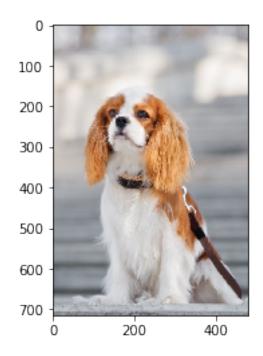
the breed of this dog is Mastiff



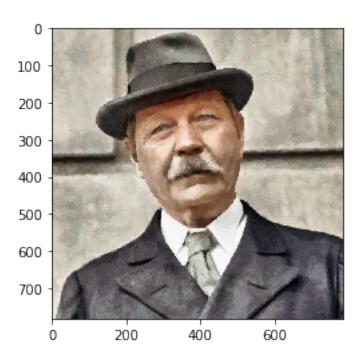
the breed of this dog is Golden retriever



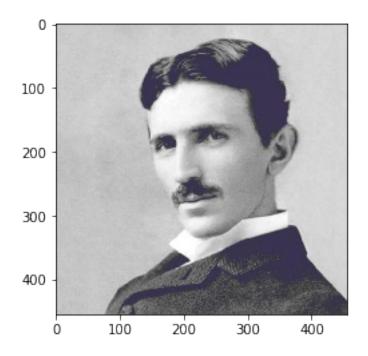
the breed of this dog is Cavalier king charles spaniel



'hi human you look like a Pharaoh hound



'hi human you look like a Dachshund



'hi human you look like a Dachshund



## neither human nor dog



In []: