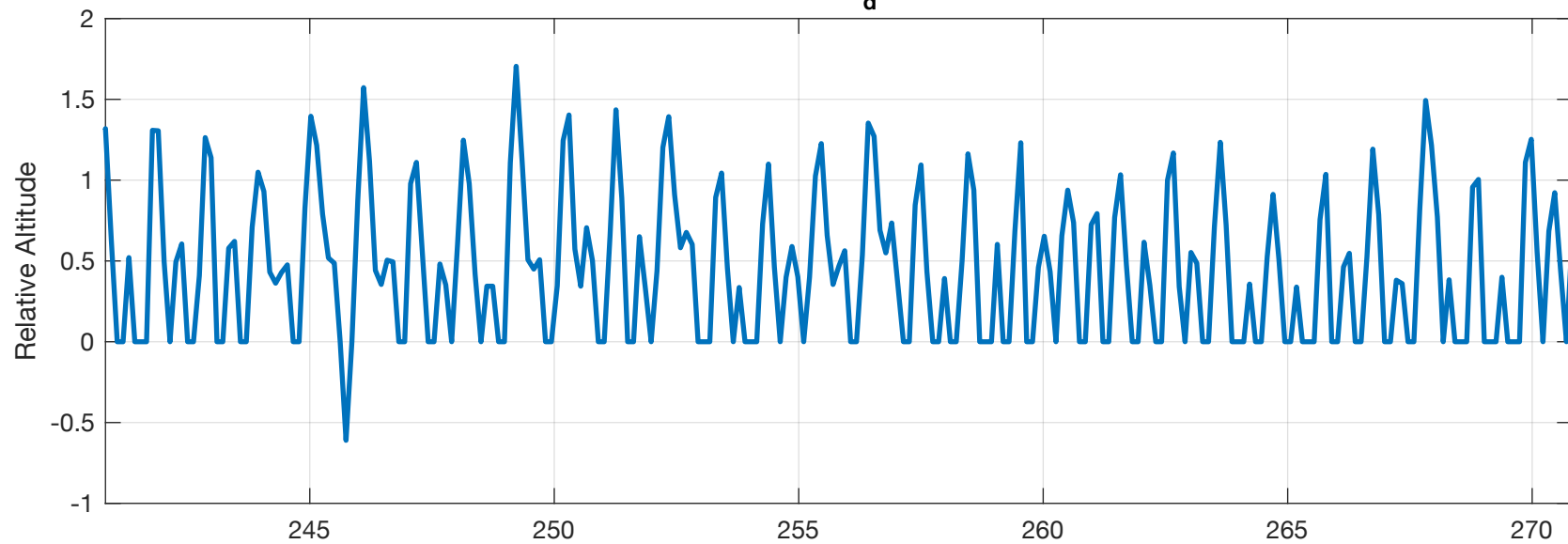
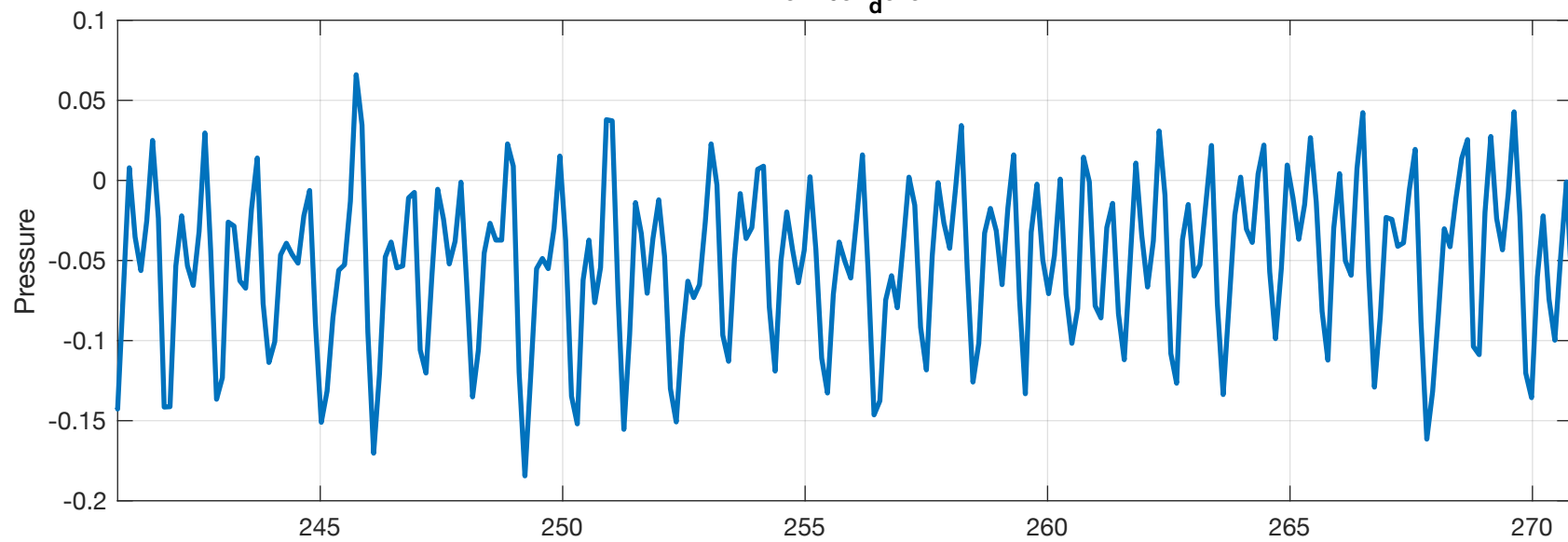


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-4999.000	-4260.000	-1691.000	-1625.500	"accel_data"
'Y'	-3161.000	-2701.000	-1227.000	-1841.000	"accel_data"
'X'	-3920.000	-2682.000	-1097.000	-1374.500	"accel_data"

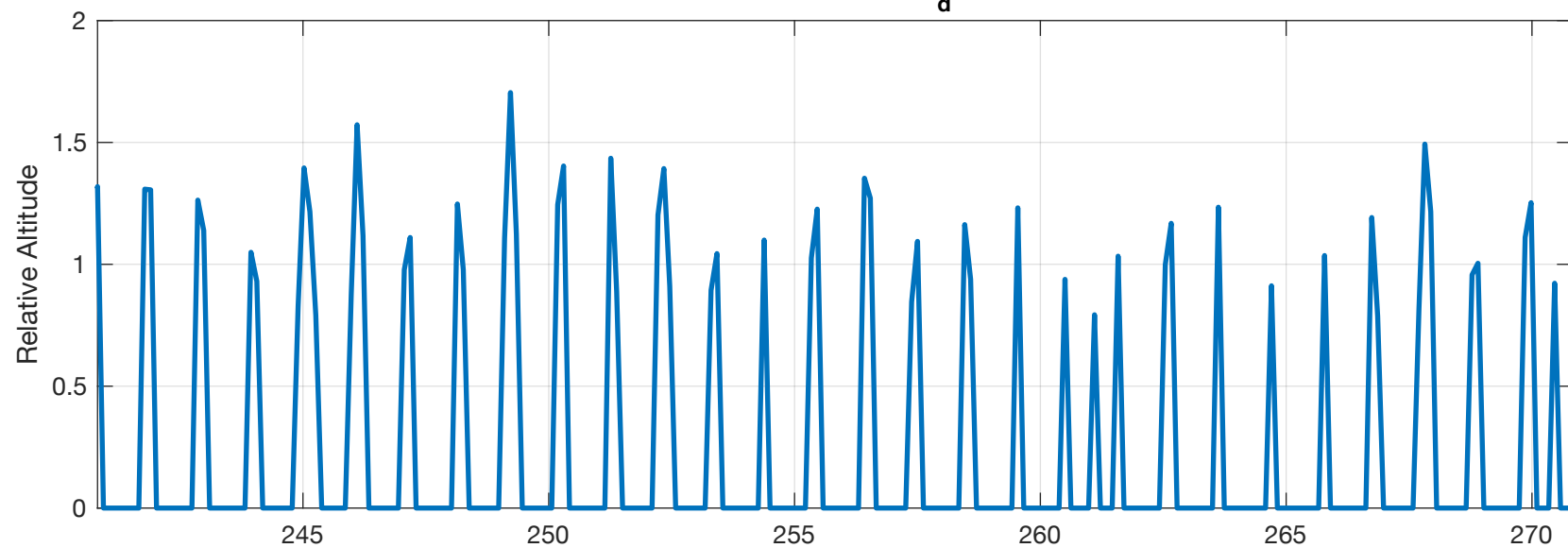
Zian bar_data



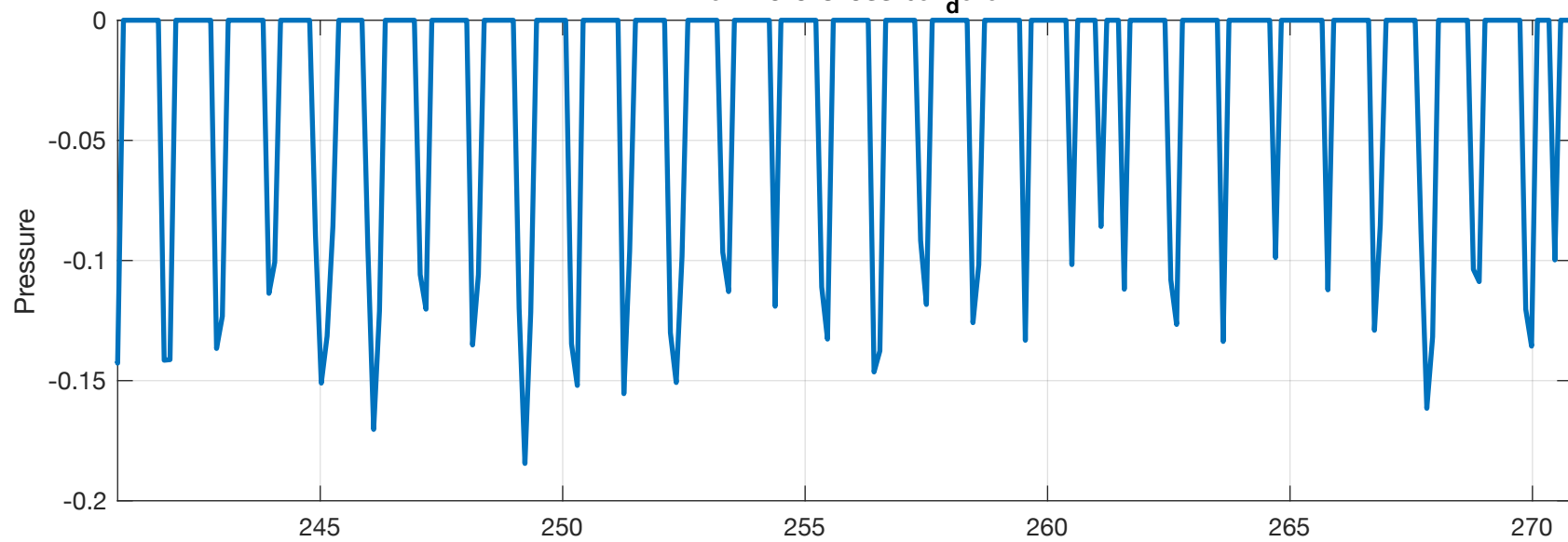
Zian bar_data



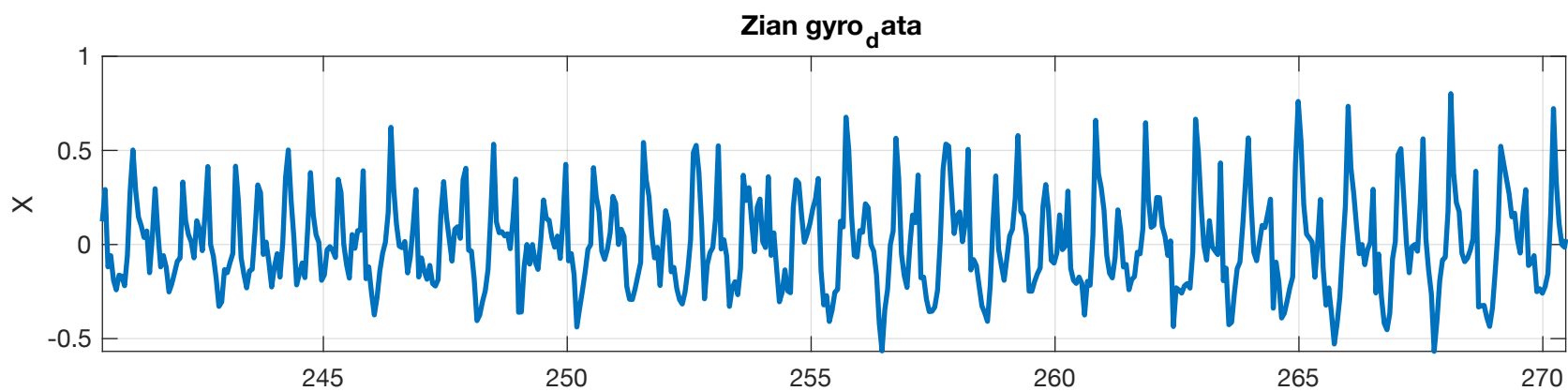
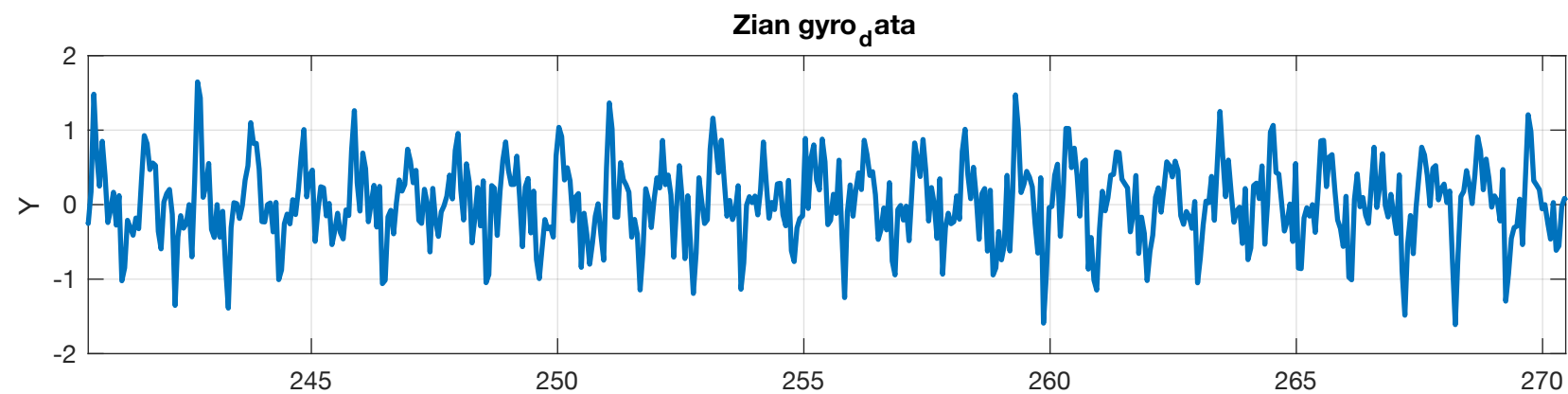
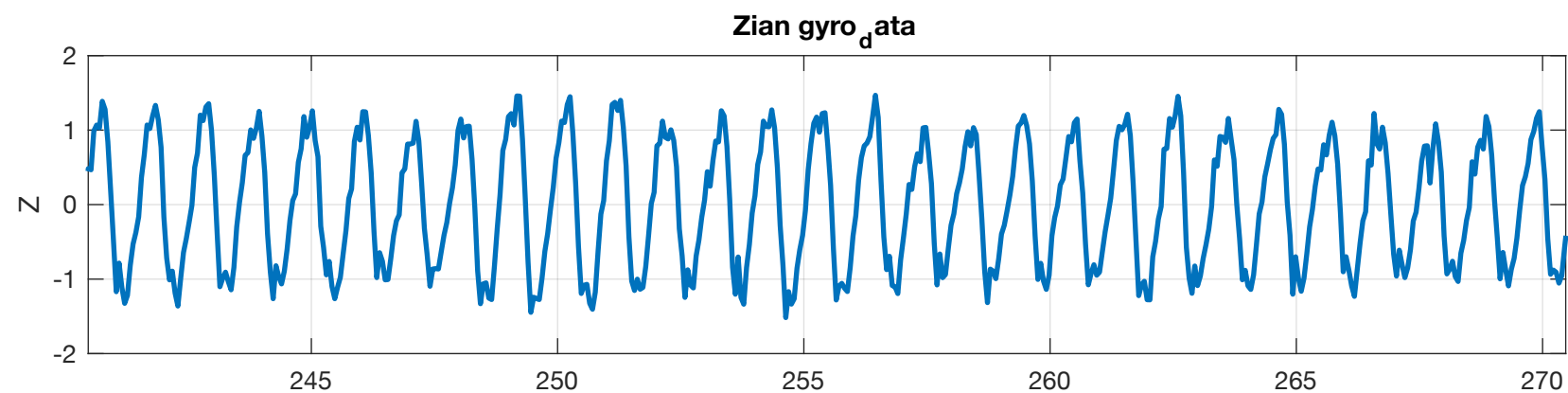
Zian Zero Cross bar_data

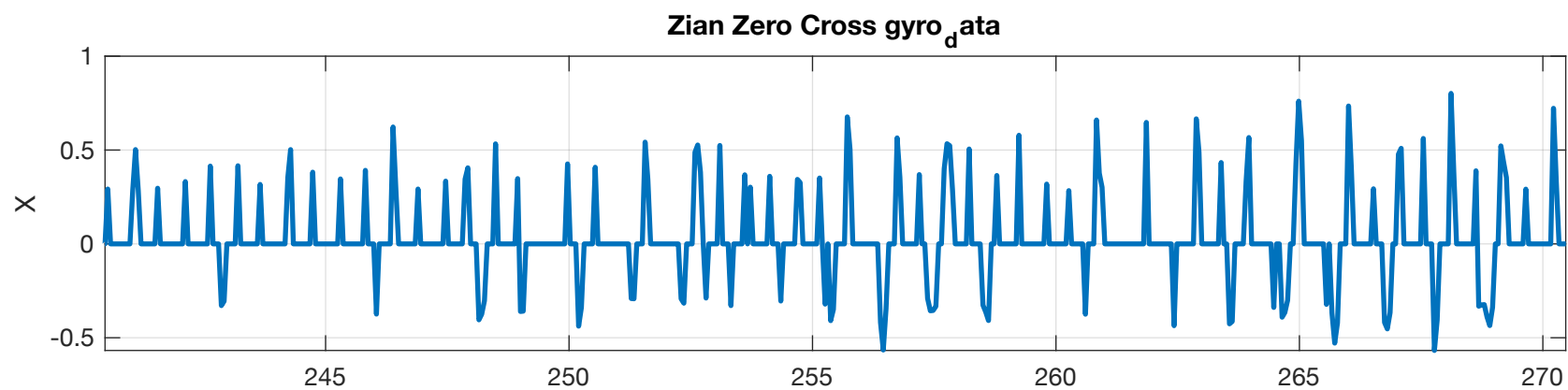
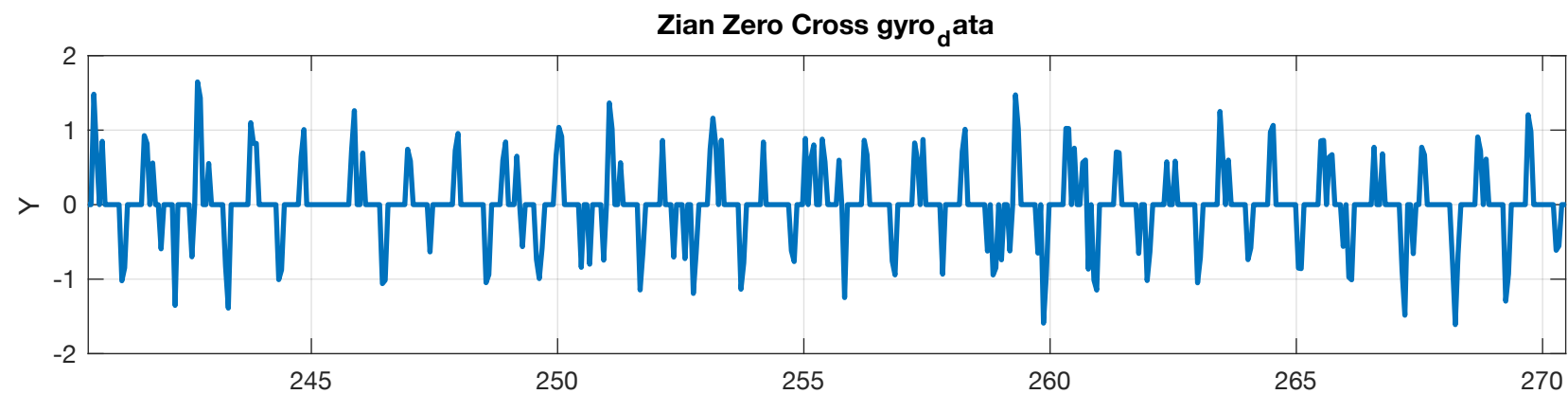
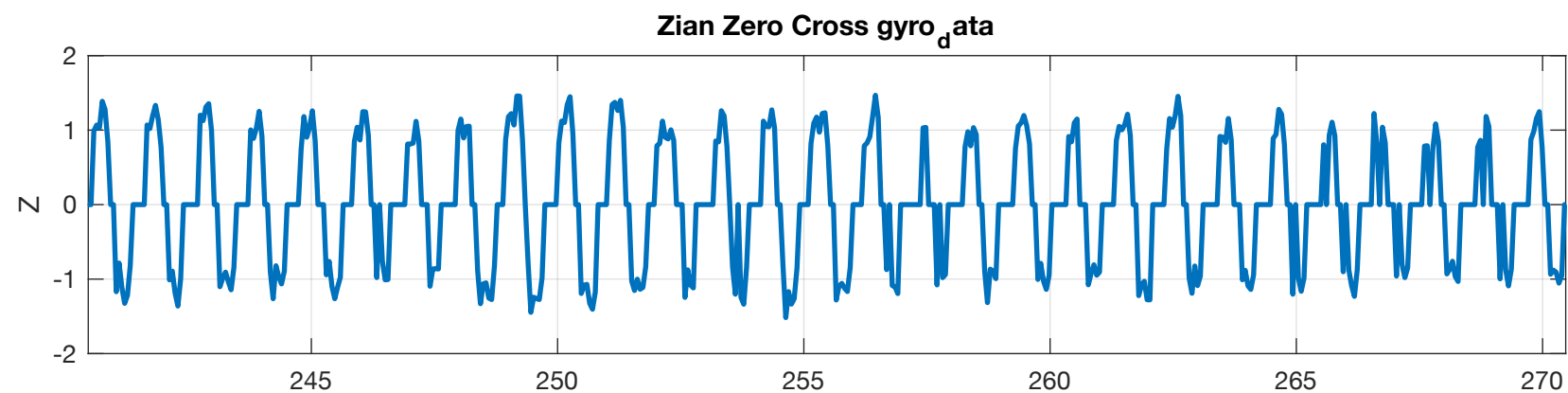


Zian Zero Cross bar_data

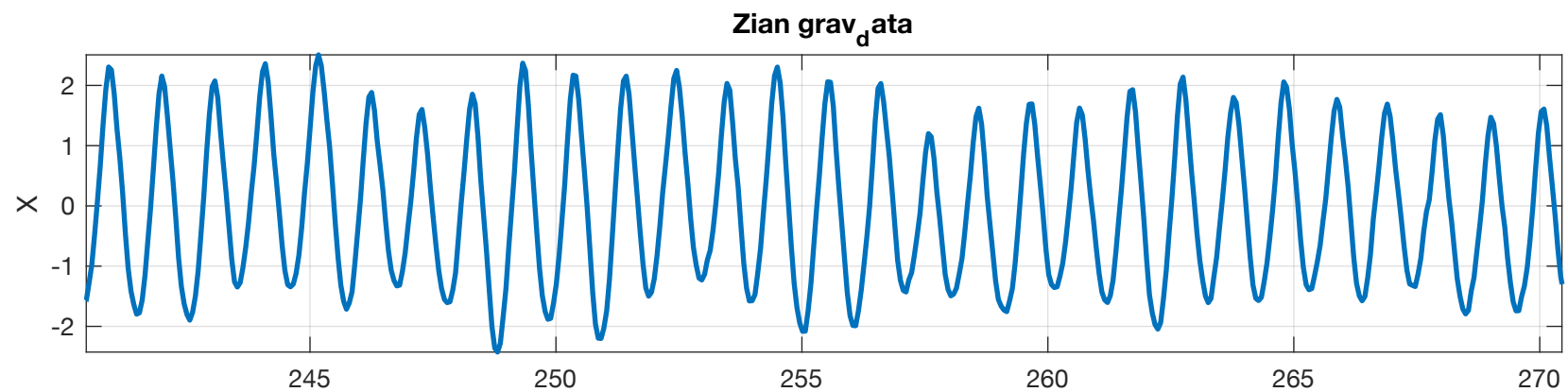
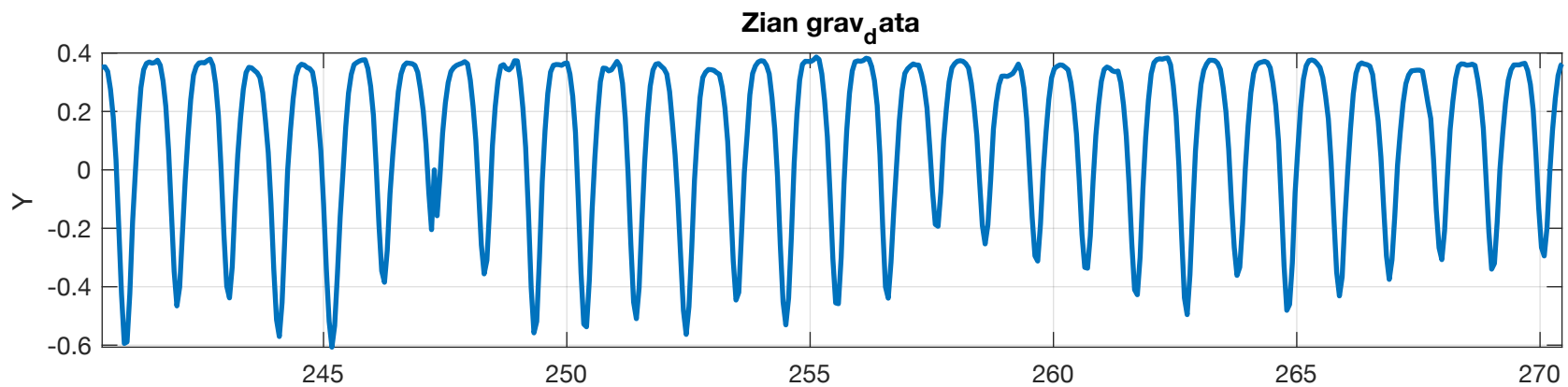
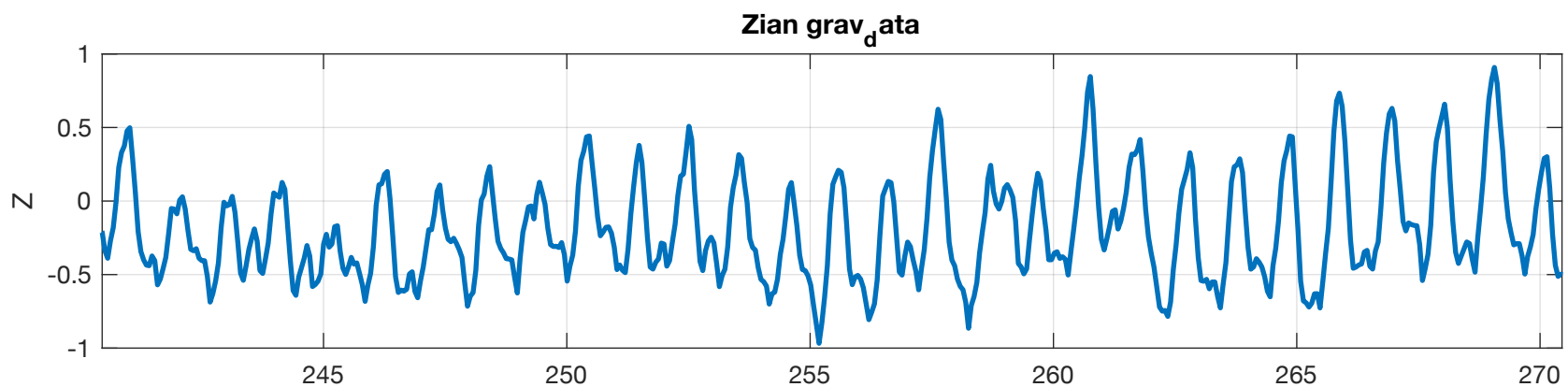


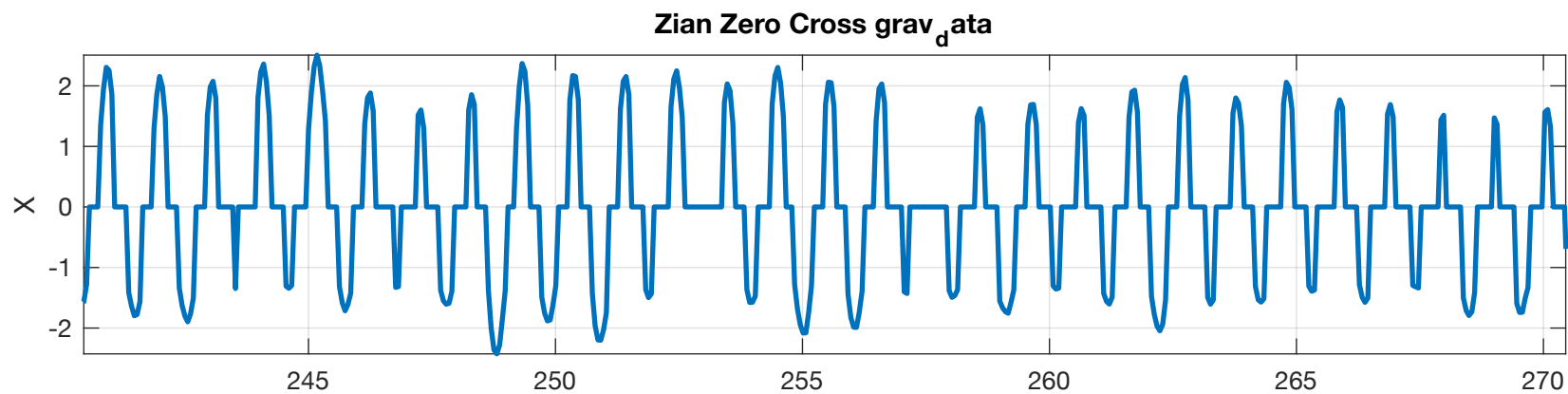
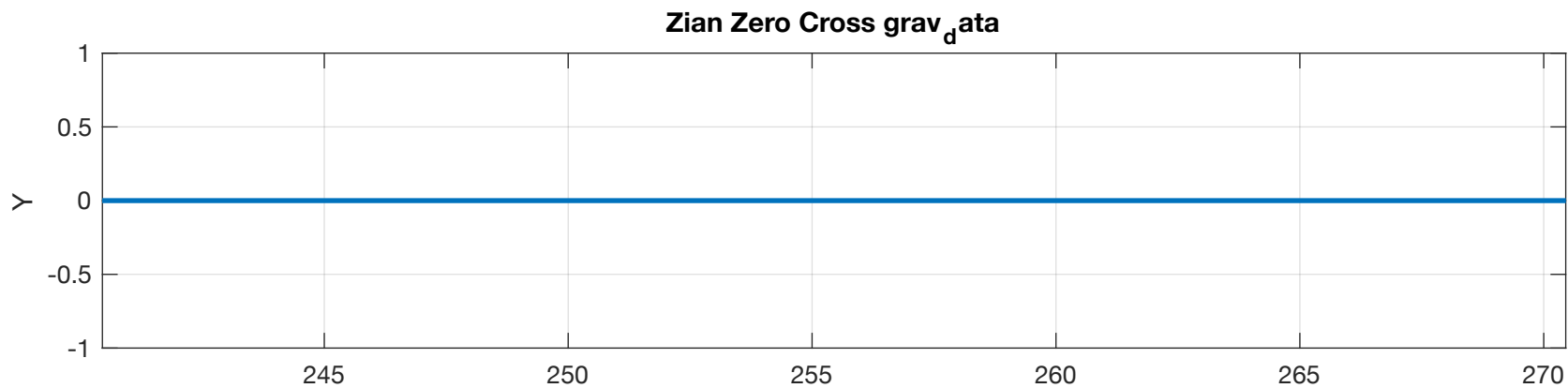
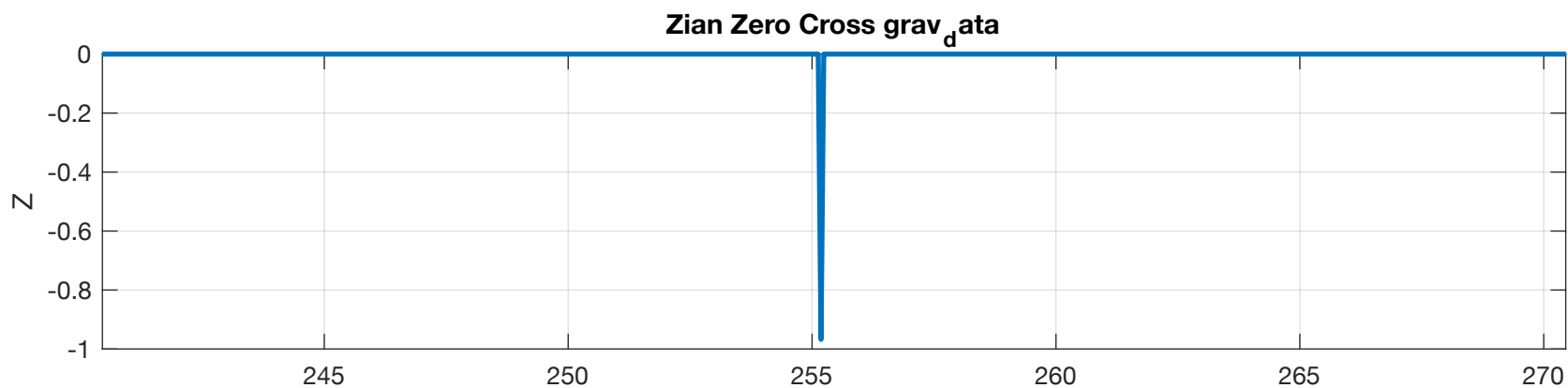
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-1563.000	-1115.000	-569.000	-547.250	"bar_data"
"Pressure"	-1754.000	-1245.000	-552.000	-547.250	"bar_data"



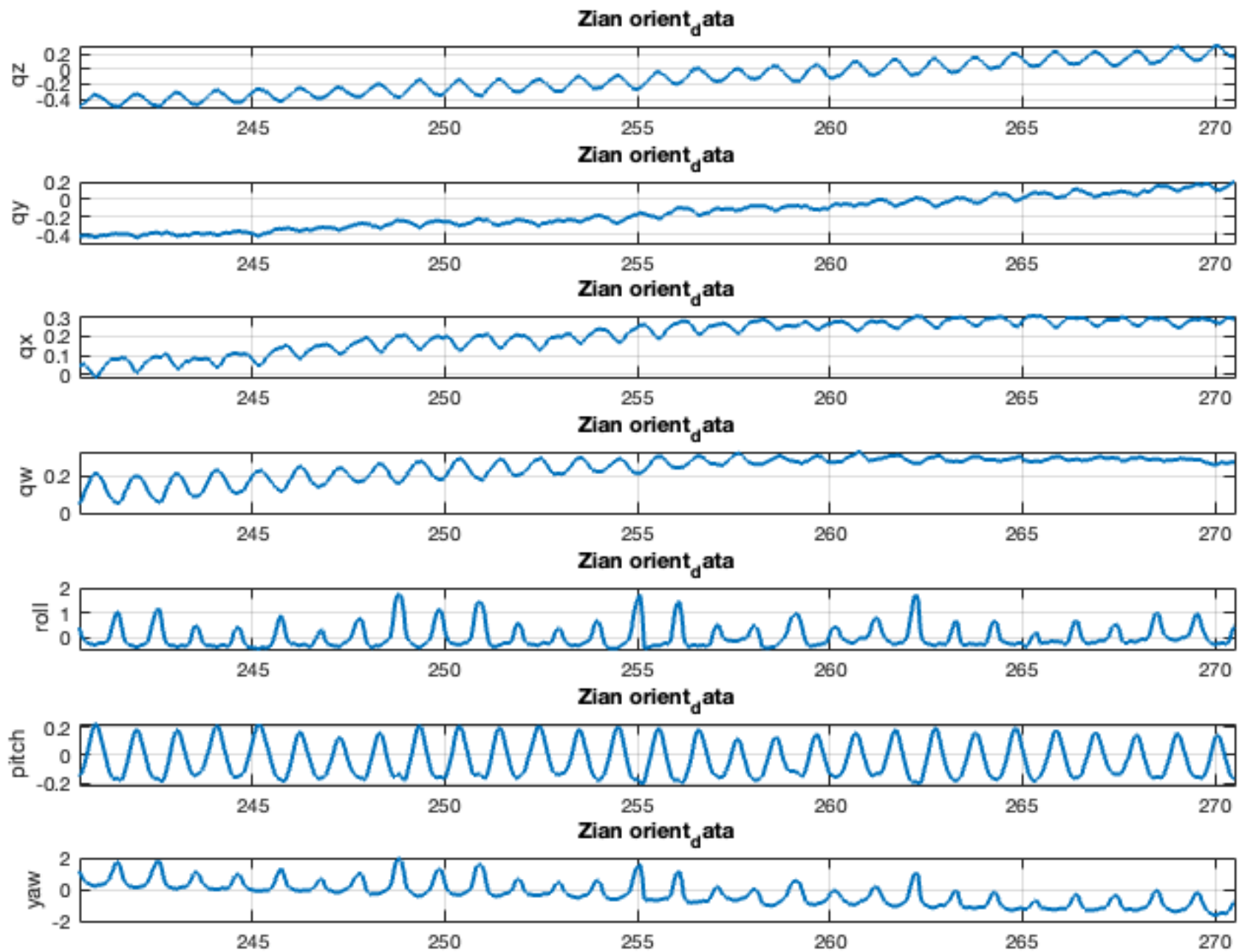


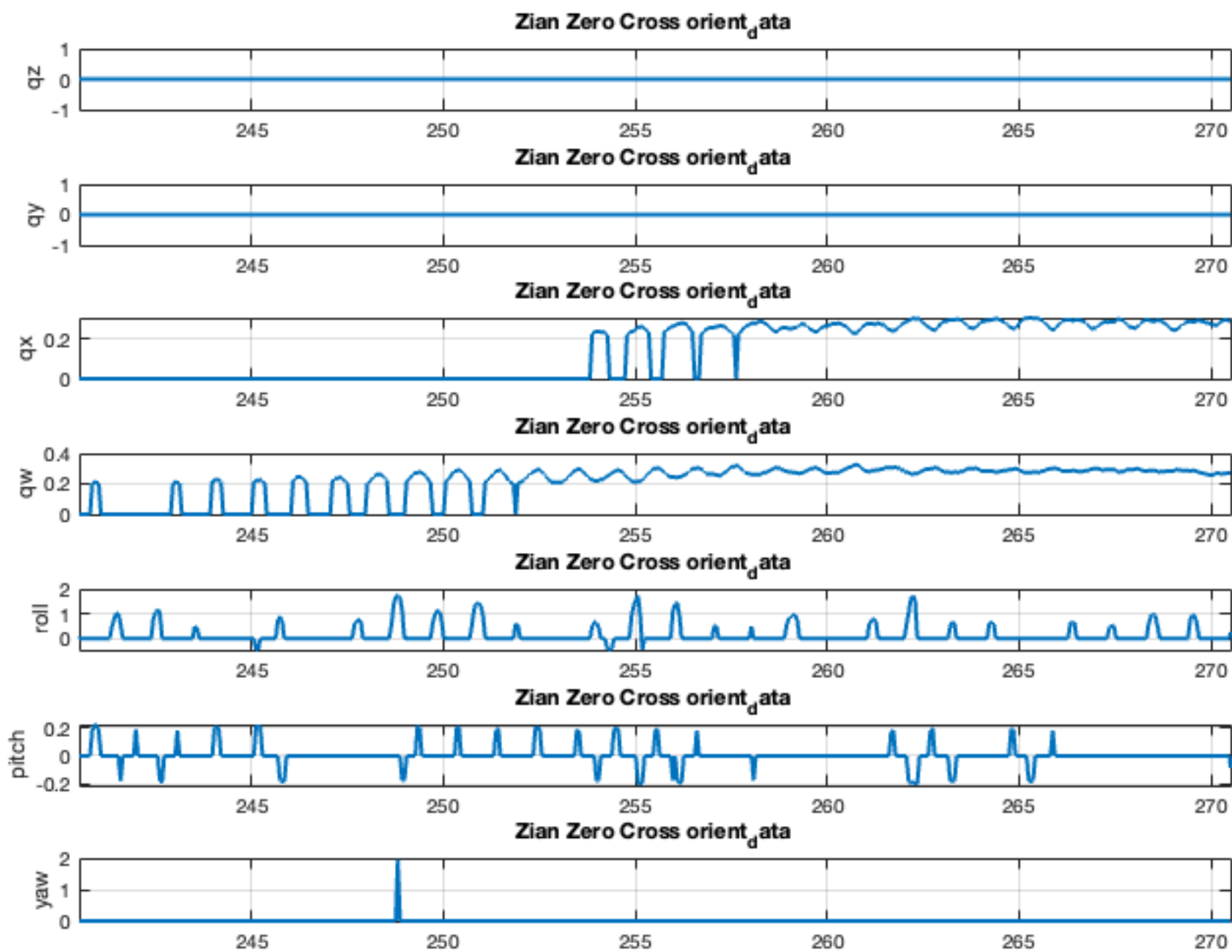
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-3028.000	-2072.000	-905.000	-1196.500	"gyro_data"
'Y'	-4631.000	-3808.000	-1283.000	-1483.500	"gyro_data"
'X'	-3821.000	-2714.000	-1447.000	-1282.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-2050.000	-1113.000	-715.000	-46.250	"grav_data"
'Y'	-1343.000	-1264.000	-423.000	-1.750	"grav_data"
'X'	-936.000	-911.000	-277.000	-648.750	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-1421.000	-741.000	-261.000	-142.750	"orient_data"
'qy'	-2423.000	-1009.000	-319.000	-106.000	"orient_data"
'qx'	-2508.000	-1399.000	-428.000	-161.000	"orient_data"
'qw'	-1321.000	-798.000	-284.000	-141.500	"orient_data"
'roll'	-1999.000	-850.000	-603.000	-368.000	"orient_data"
'pitch'	-1269.000	-913.000	-465.000	-284.250	"orient_data"
'yaw'	-1869.000	-1109.000	-471.000	-346.750	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'double_findpeaks'	1097.000
'bar_data'	"Relative Altitude"	'zero_cross'	547.250
'gyro_data'	"Z"	'double_findpeaks'	905.000
'grav_data'	"Y"	'zero_cross'	1.750
'orient_data'	"qy"	'zero_cross'	106.000