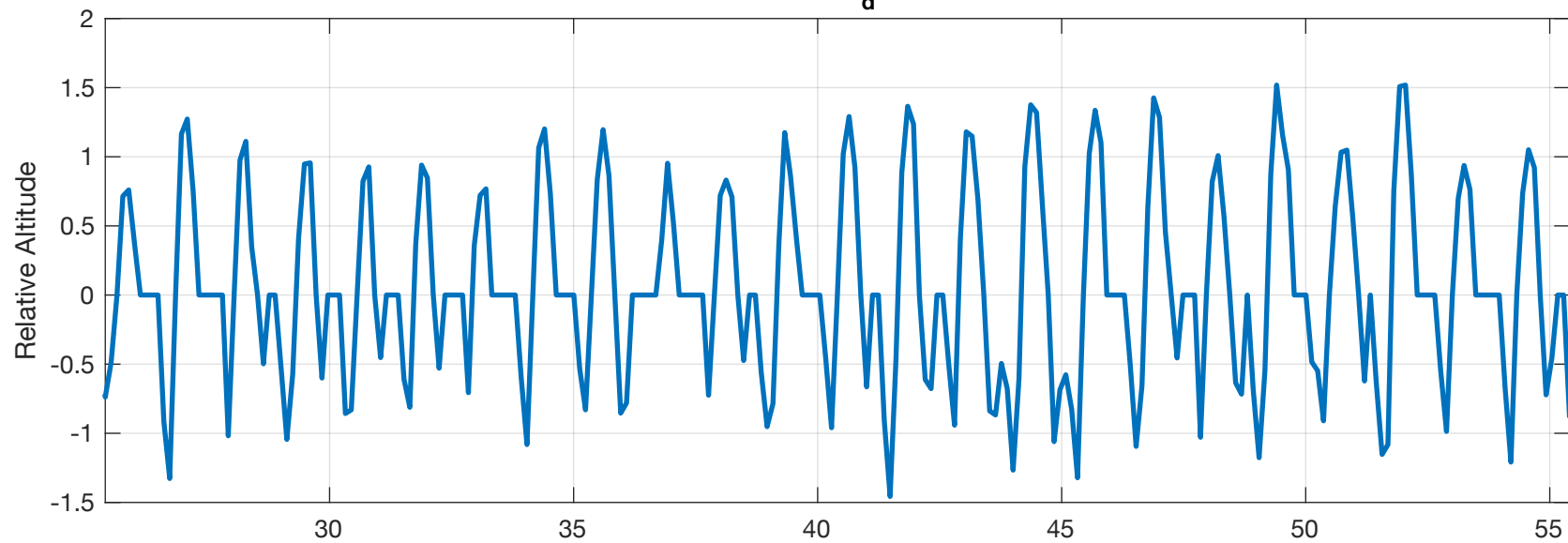
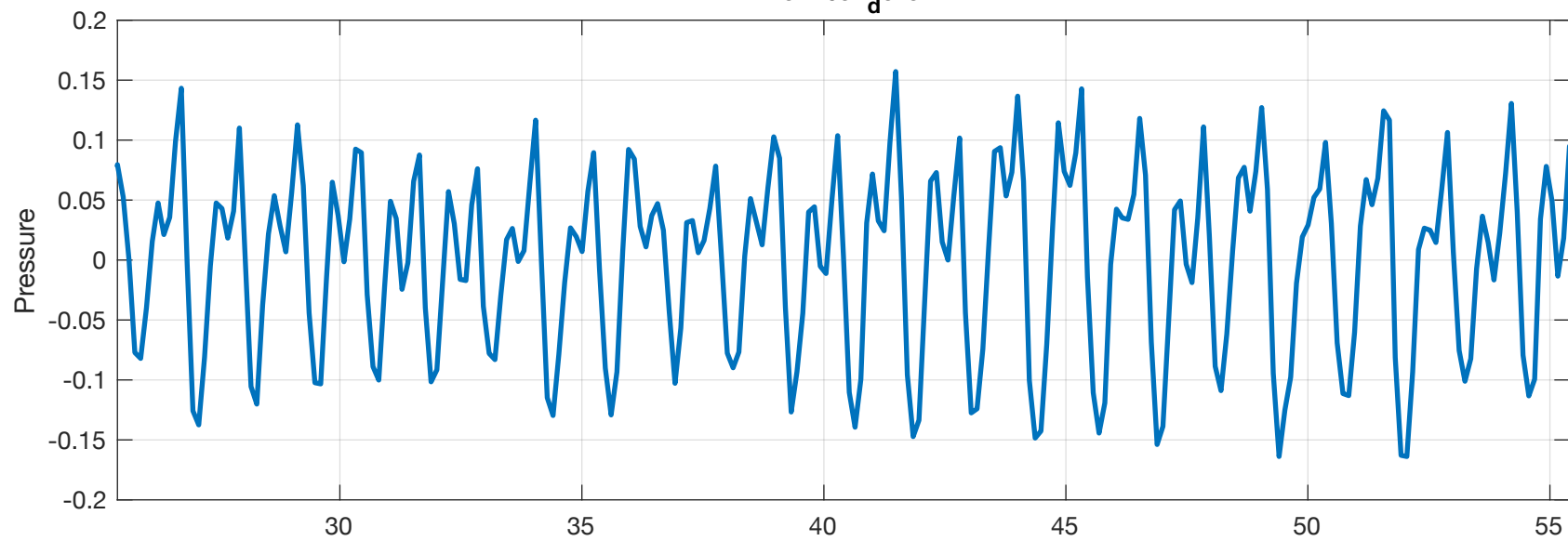


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-318.000	-243.000	-42.000	-22.000	"accel_data"
'Y'	-302.000	-126.000	-34.000	-23.500	"accel_data"
'X'	-317.000	-201.000	-15.000	-10.000	"accel_data"

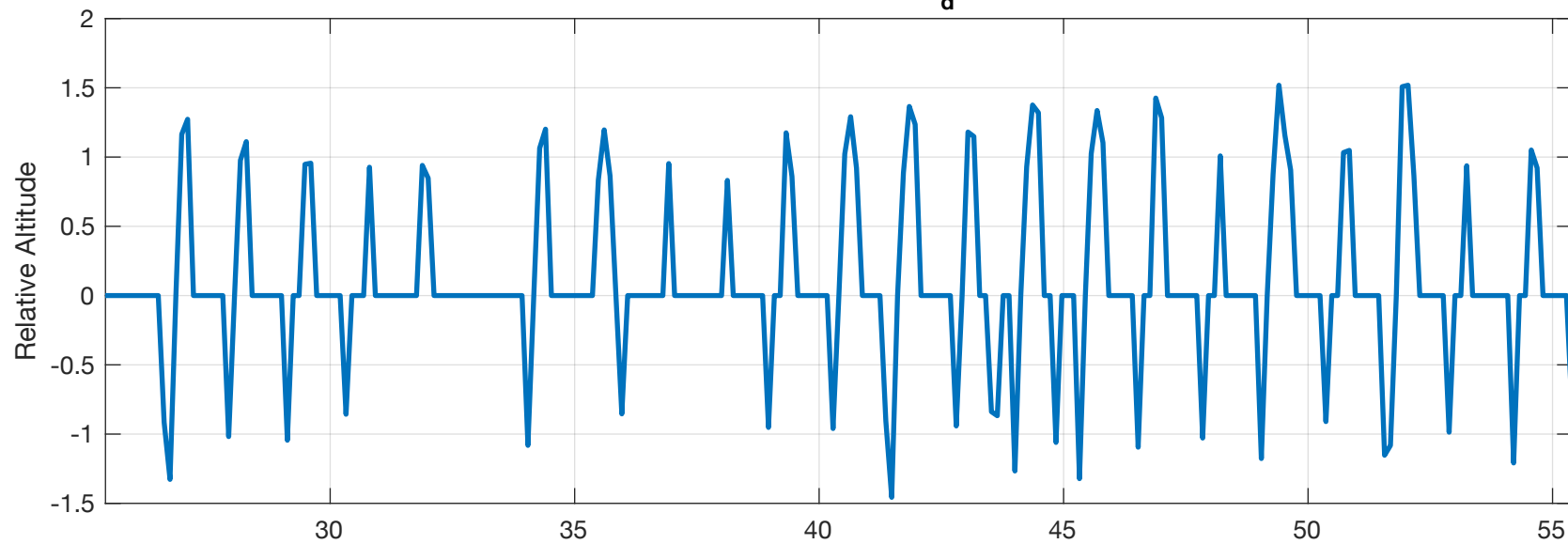
Zian bar<sub>d</sub>ata



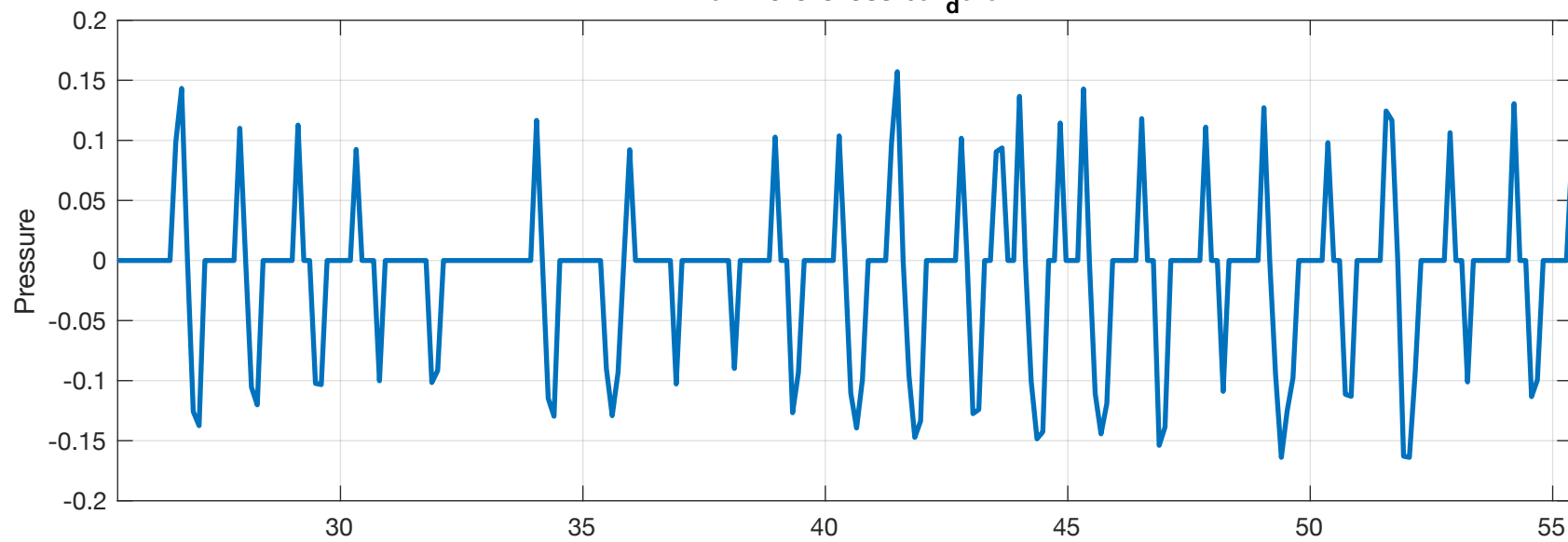
Zian bar<sub>d</sub>ata



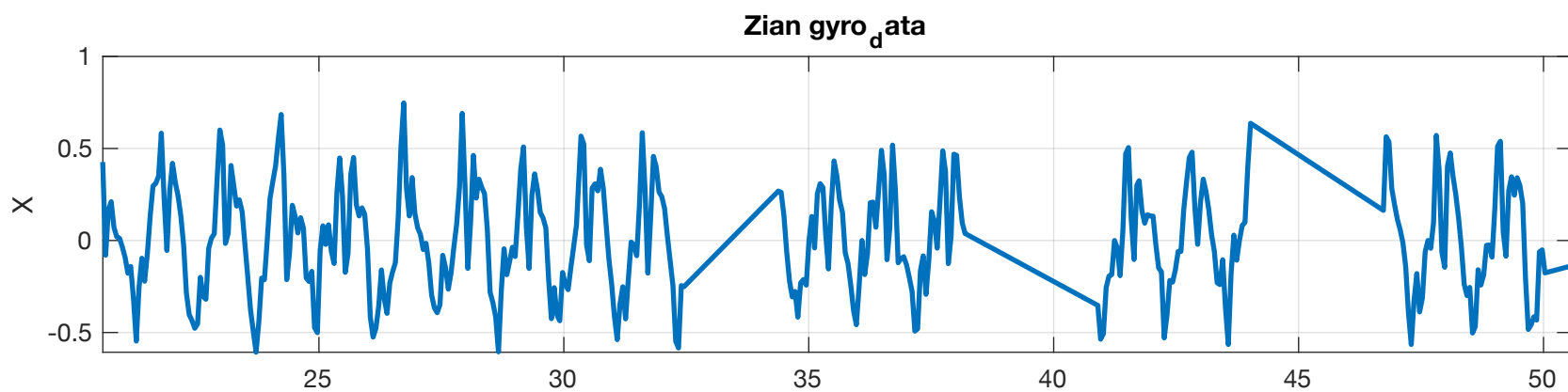
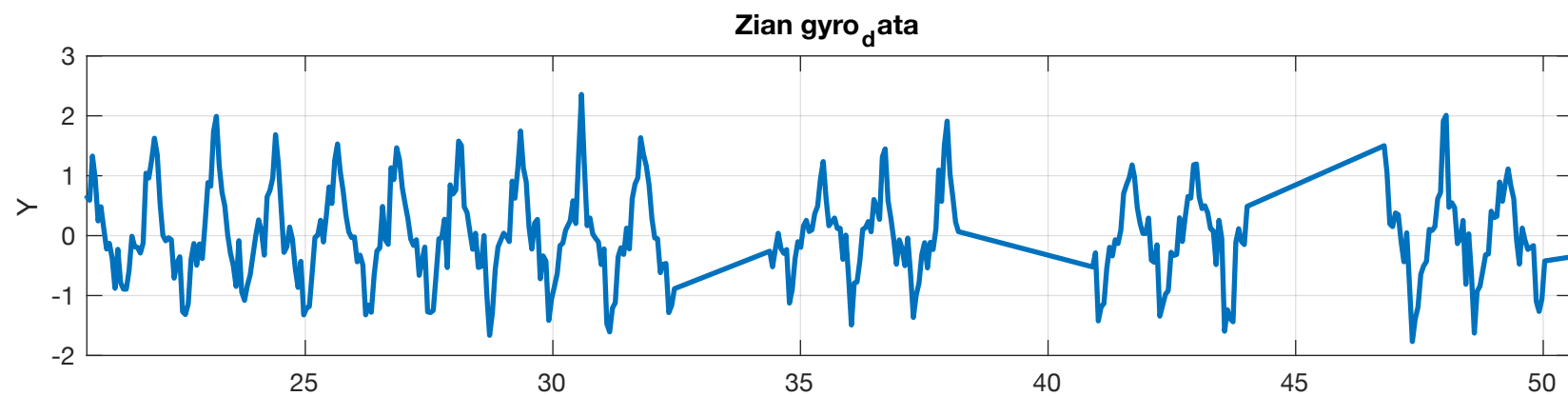
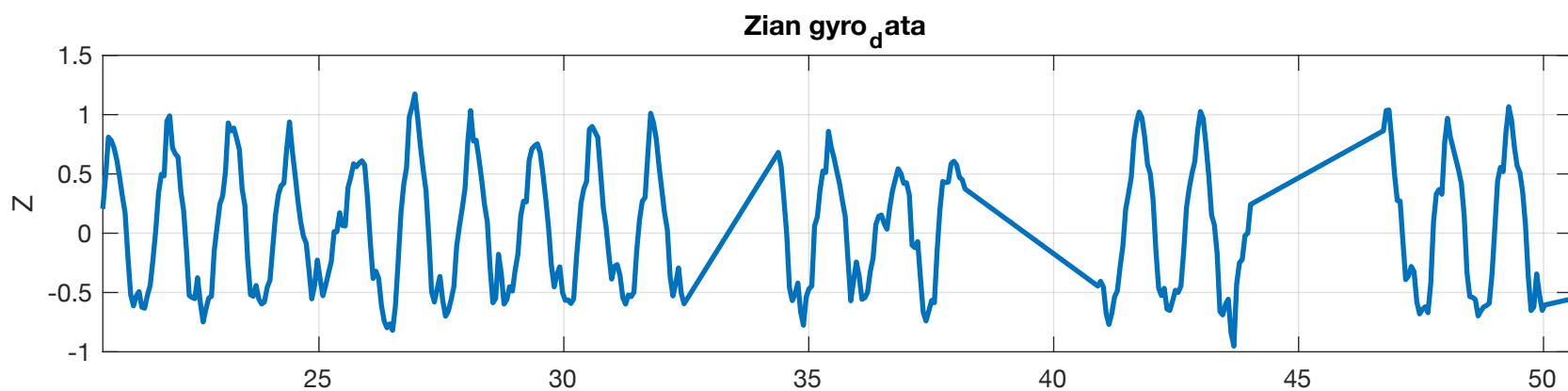
Zian Zero Cross bar<sub>d</sub>ata

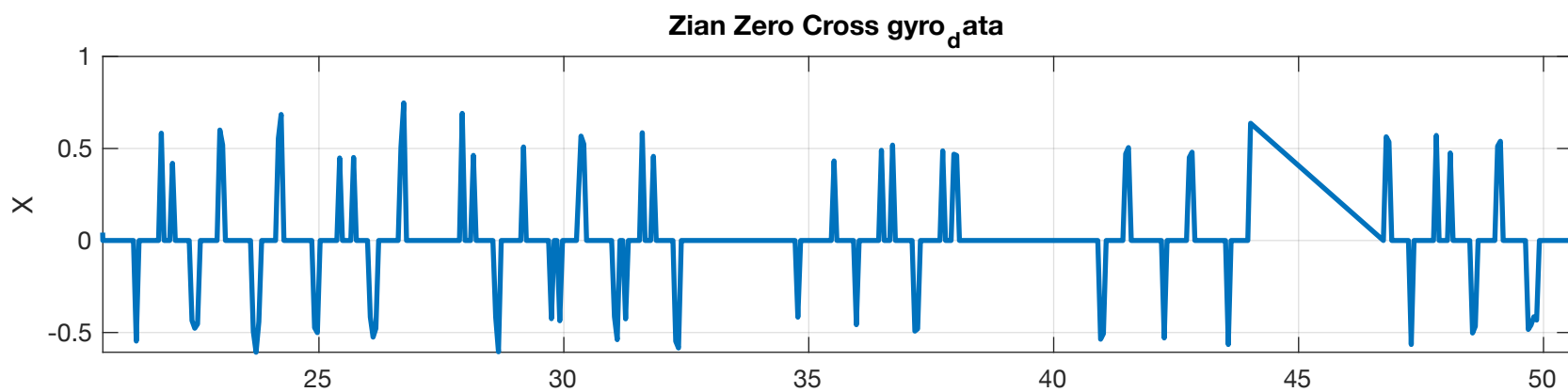
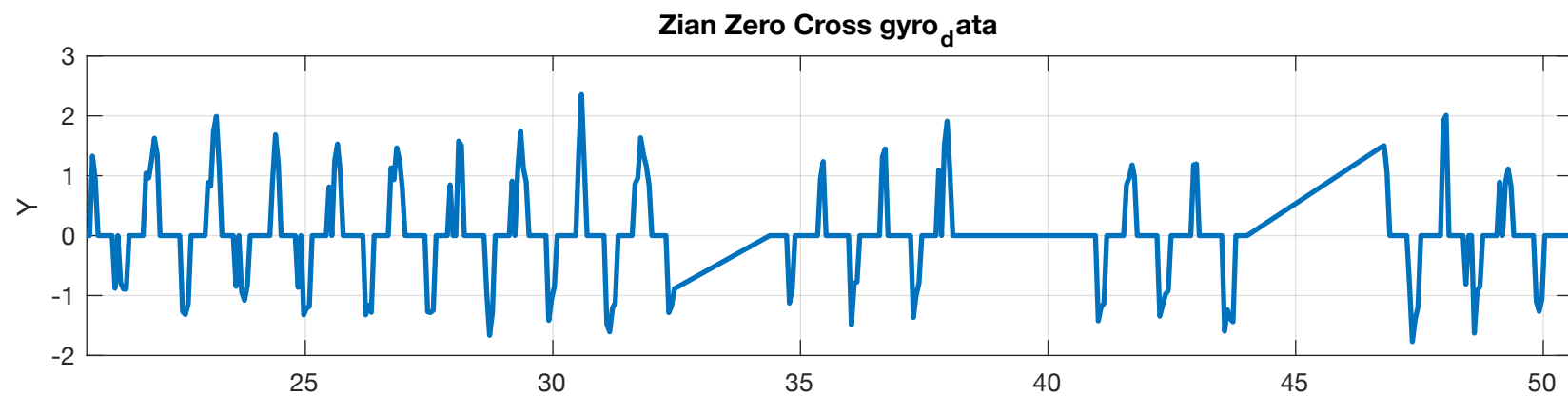
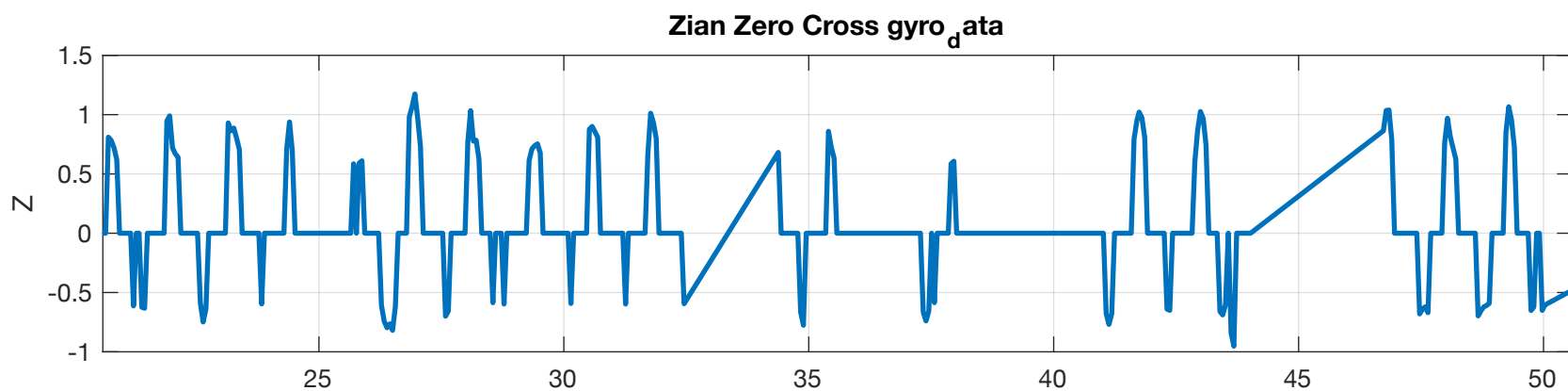


Zian Zero Cross bar<sub>d</sub>ata



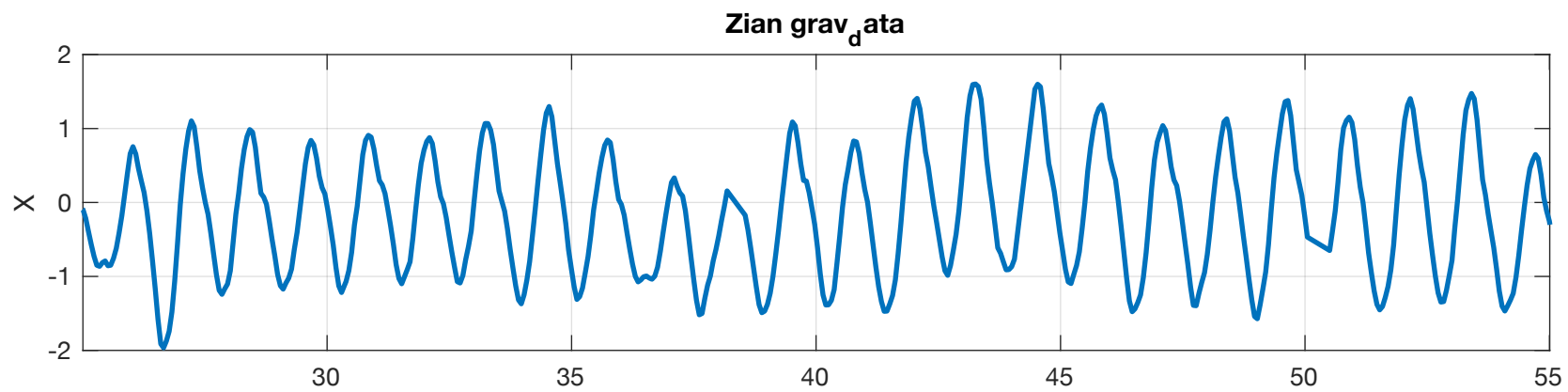
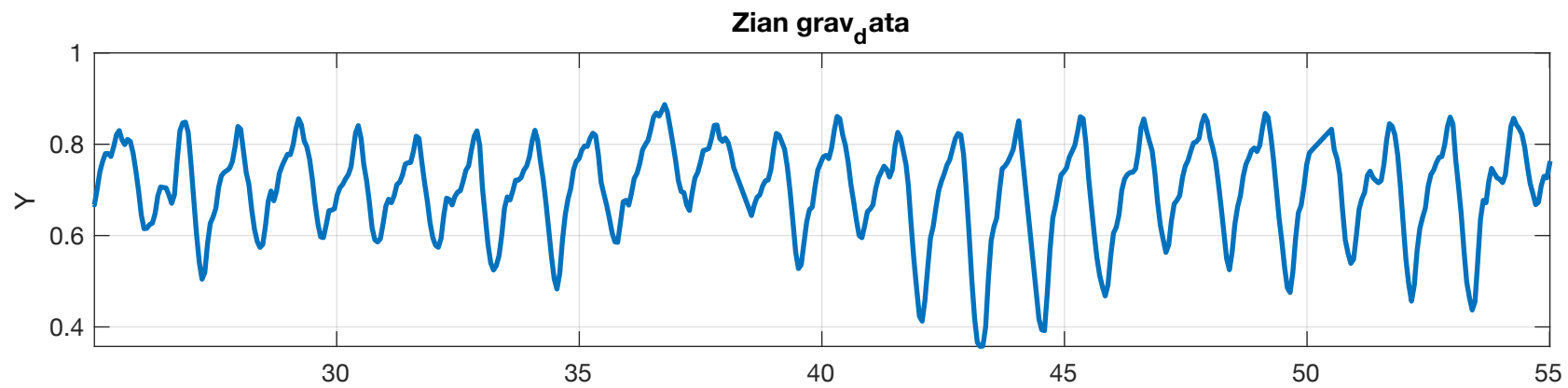
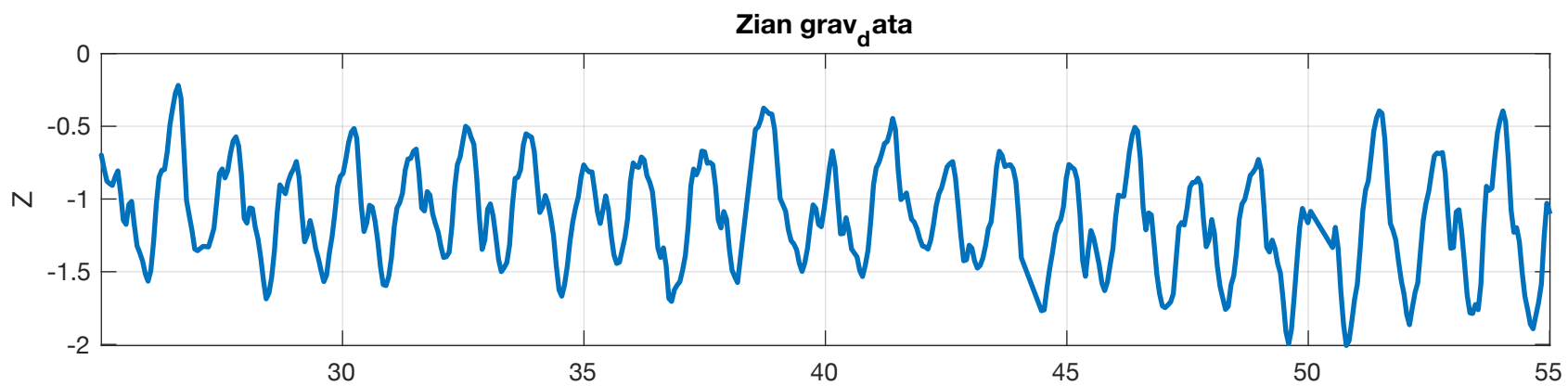
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	0.000	39.000	64.000	50.000	"bar_data"
"Pressure"	-57.000	-36.000	45.000	51.000	"bar_data"

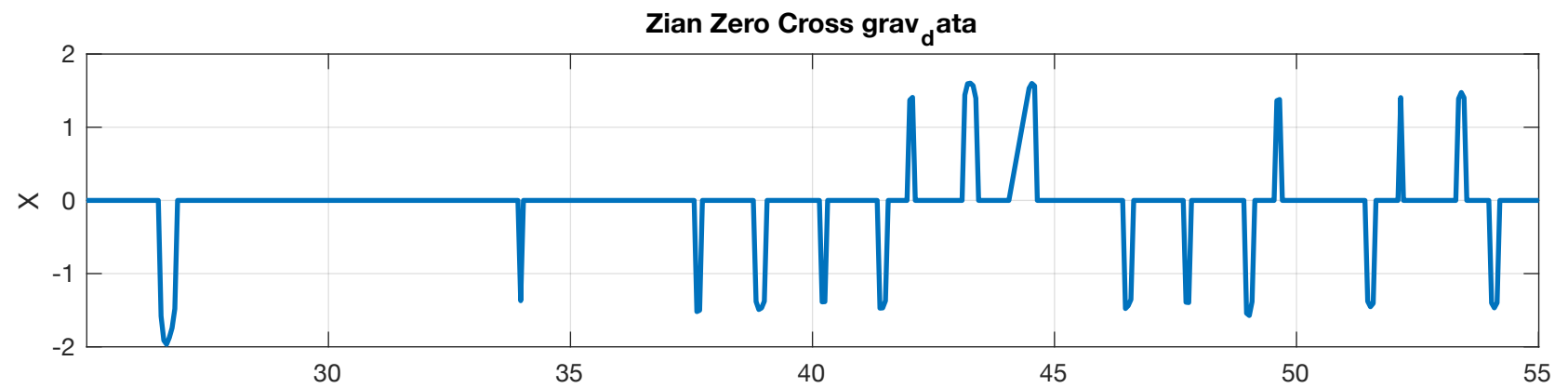
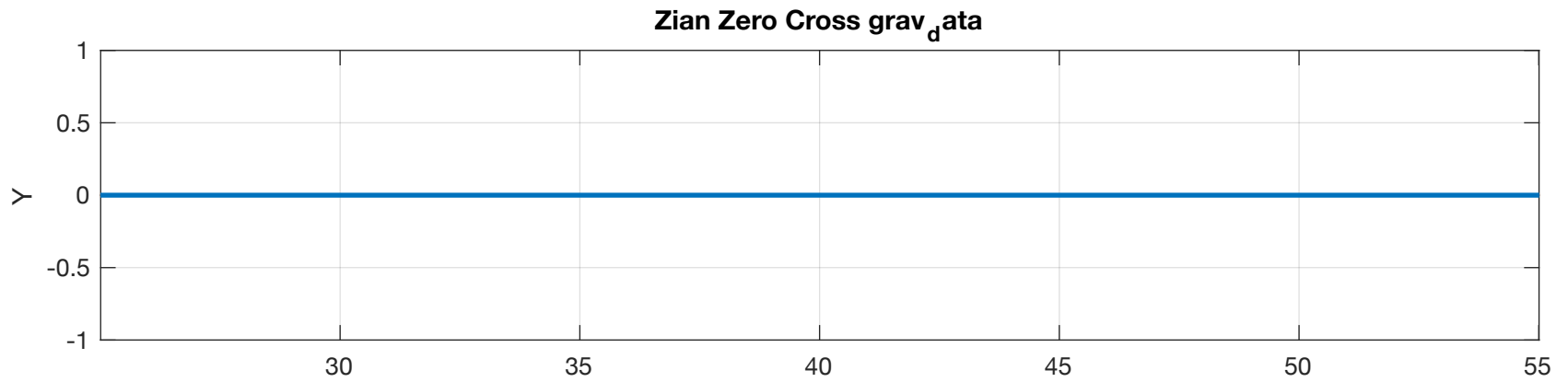
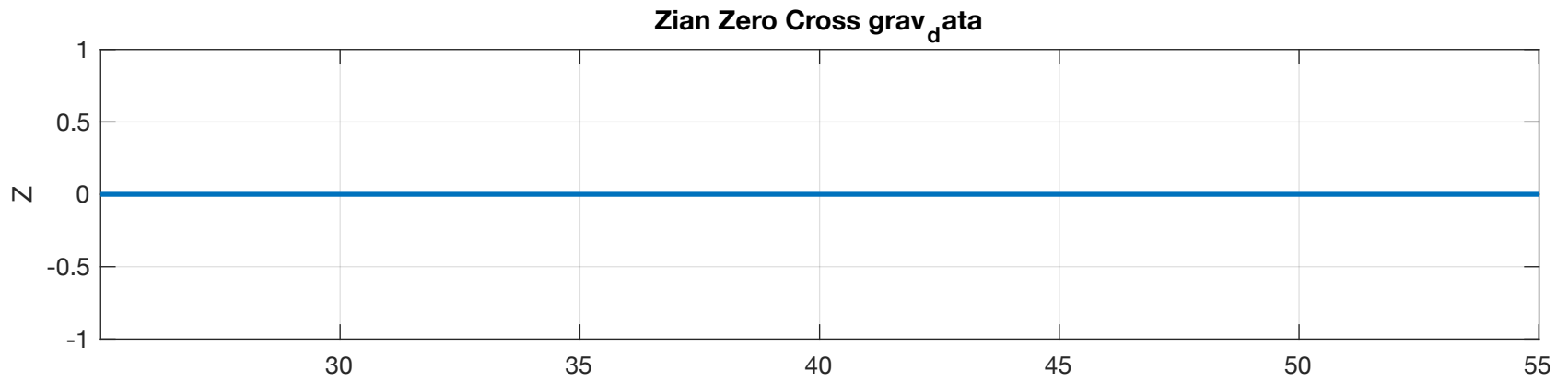




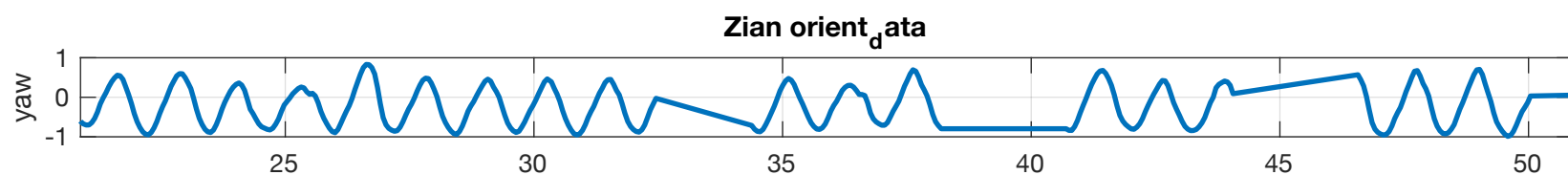
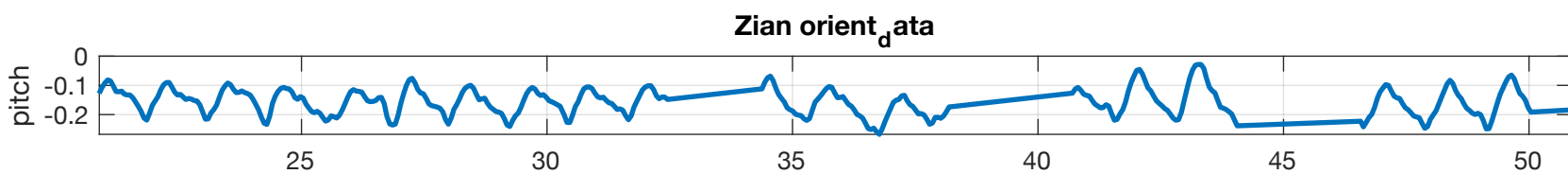
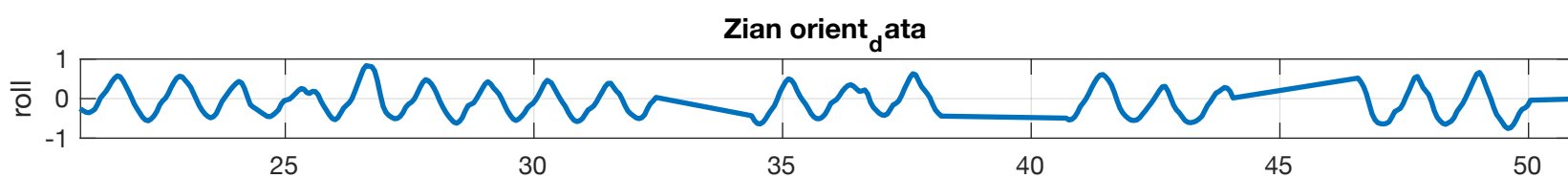
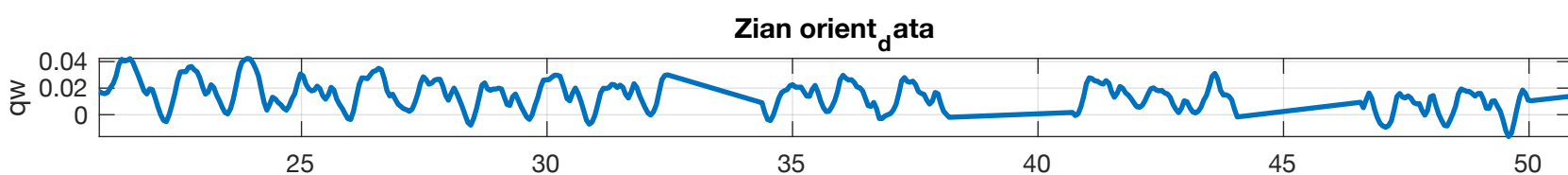
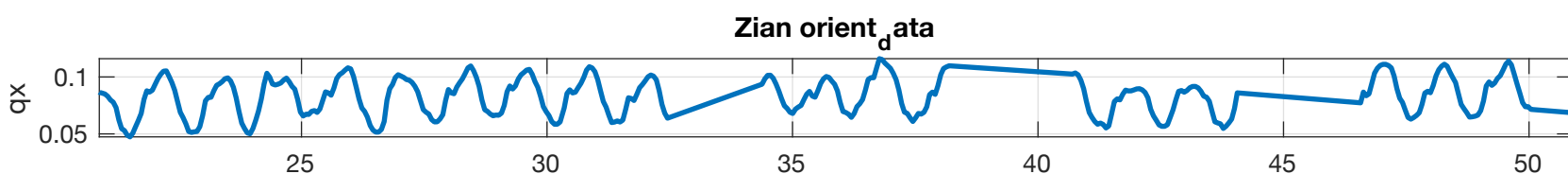
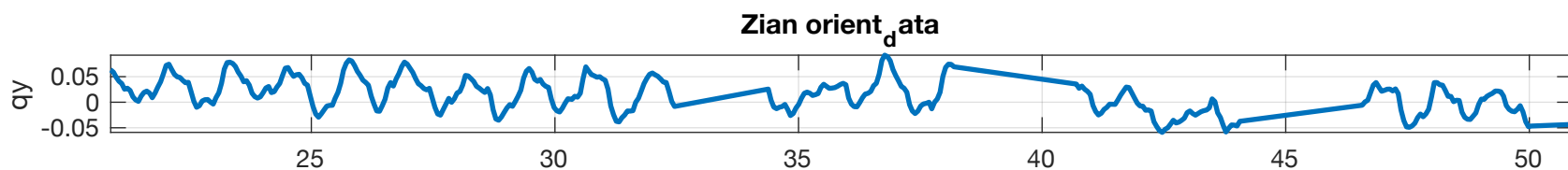
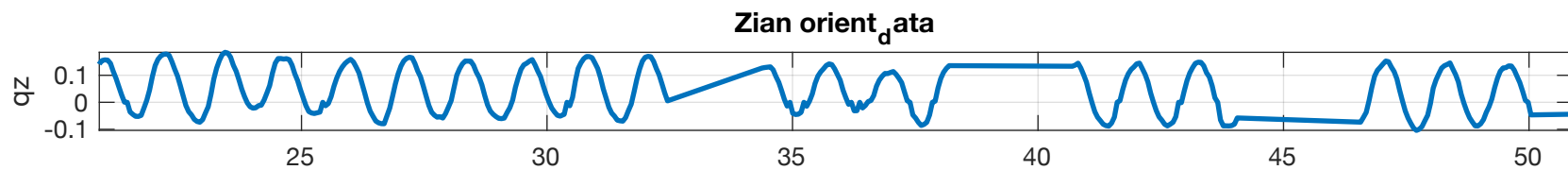


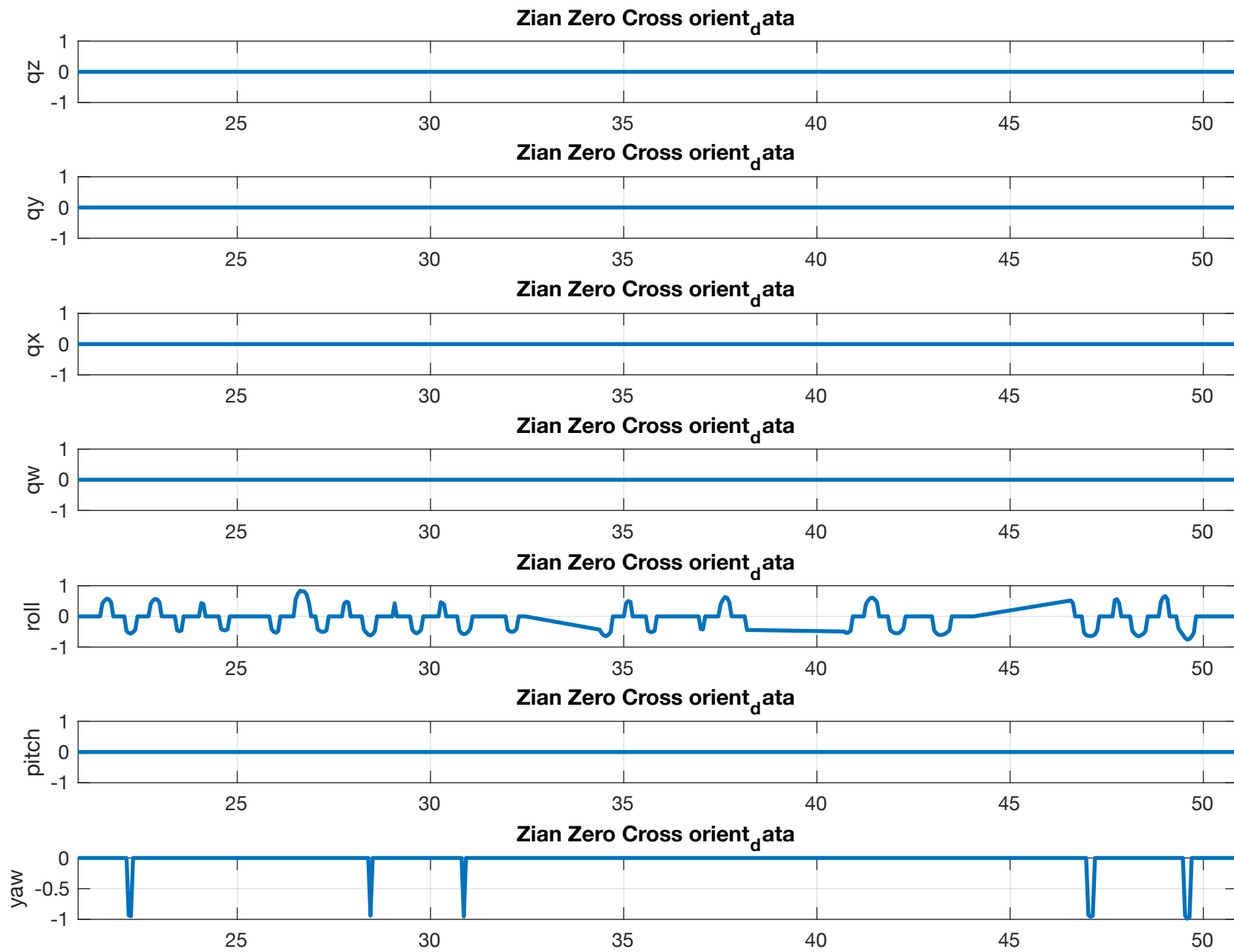
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-125.000	-62.000	27.000	52.500	"gyro_data"
'Y'	-219.000	-129.000	21.000	34.500	"gyro_data"
'X'	-170.000	-104.000	28.000	39.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-80.000	61.000	90.000	97.750	"grav_data"
'Y'	-57.000	-23.000	53.000	99.250	"grav_data"
'X'	-25.000	10.000	71.000	77.250	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-32.000	8.000	70.000	97.250	"orient_data"
'qy'	-85.000	-22.000	50.000	91.250	"orient_data"
'qx'	-43.000	-10.000	64.000	97.750	"orient_data"
'qw'	-66.000	-57.000	54.000	97.750	"orient_data"
'roll'	-18.000	24.000	73.000	67.250	"orient_data"
'pitch'	-41.000	68.000	92.000	97.250	"orient_data"
'yaw'	-12.000	38.000	78.000	93.250	"orient_data"

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Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'zero_cross'	10.000
'bar_data'	"Relative Altitude"	'findpeaks'	0.000
'gyro_data'	"Y"	'double_findpeaks'	21.000
'grav_data'	"X"	'findpeaks_above_zero'	10.000
'orient_data'	"qz"	'findpeaks_above_zero'	8.000