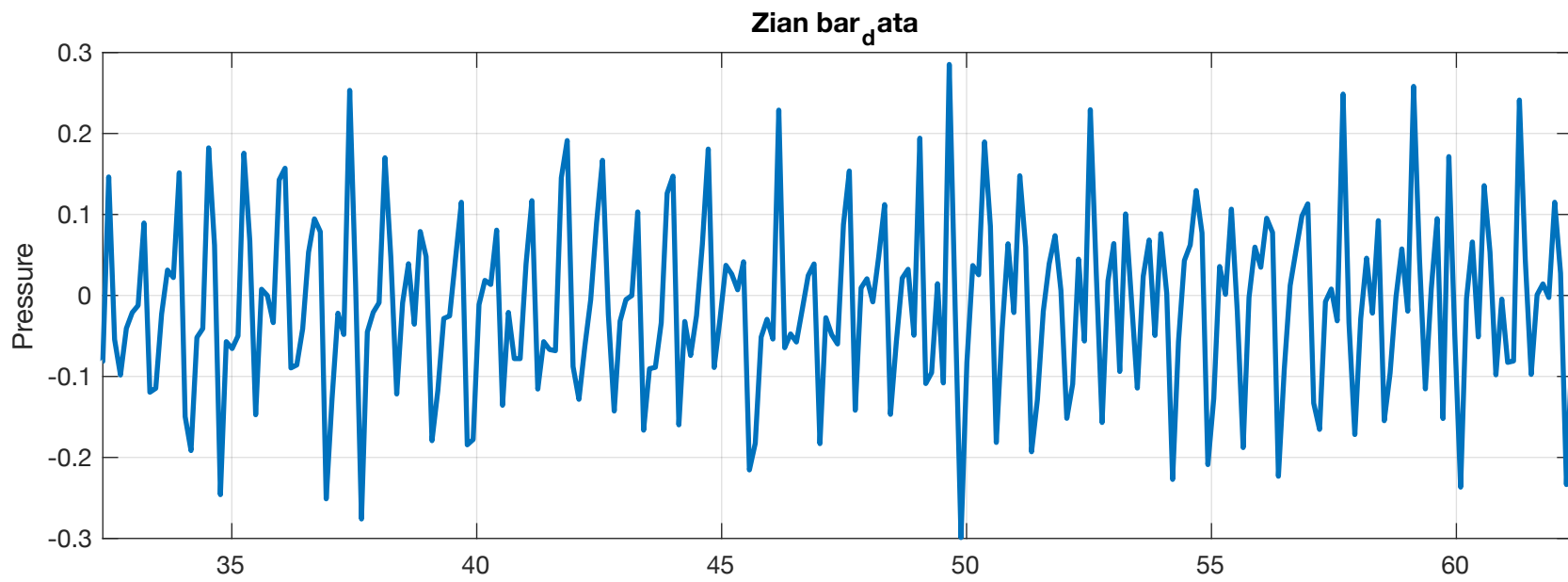
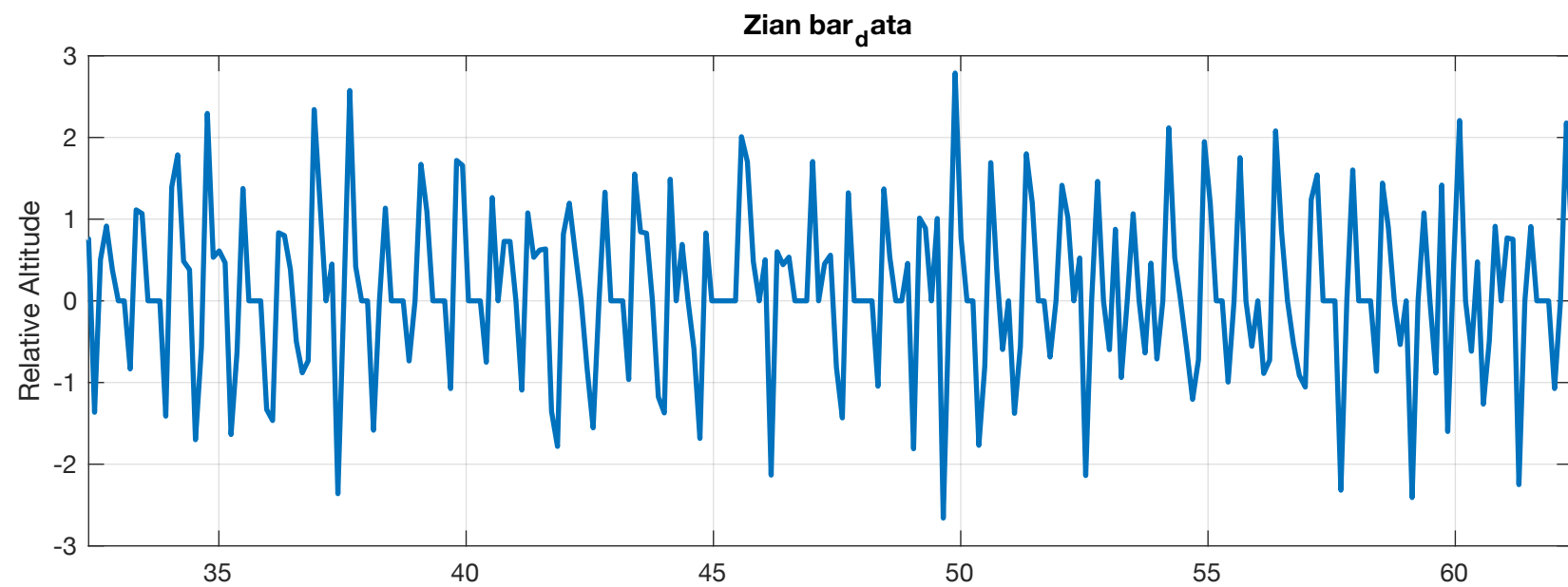
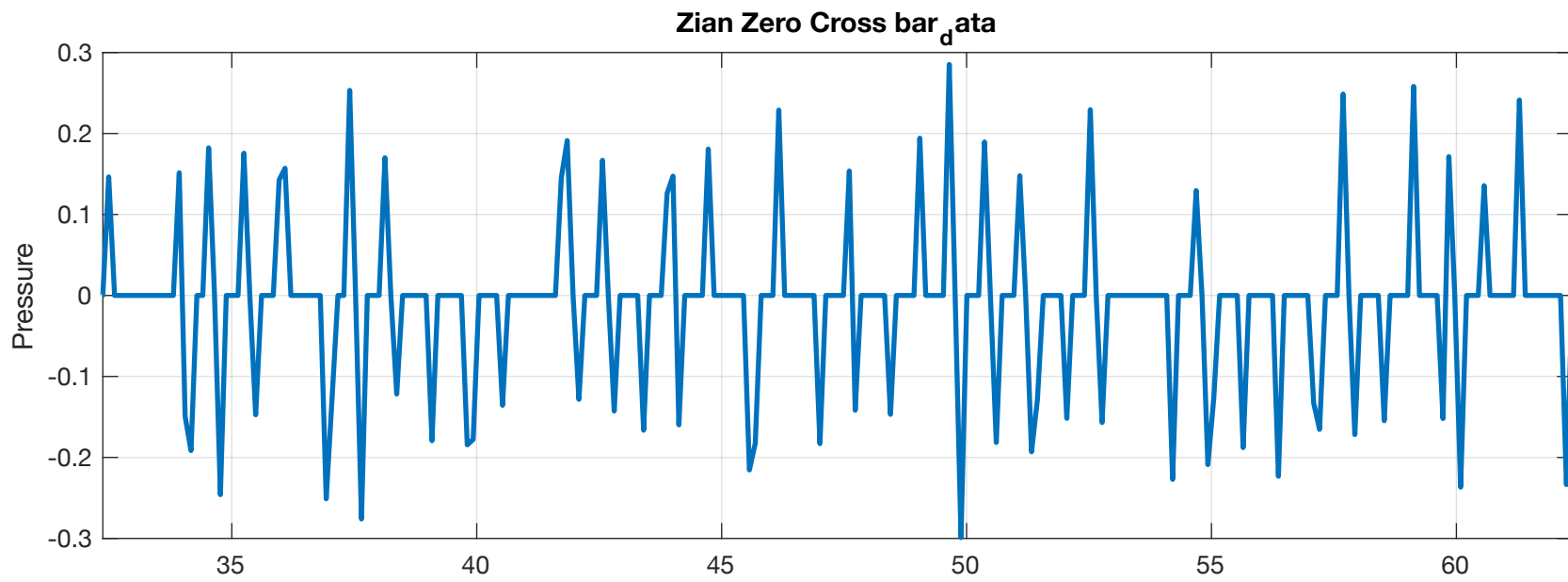
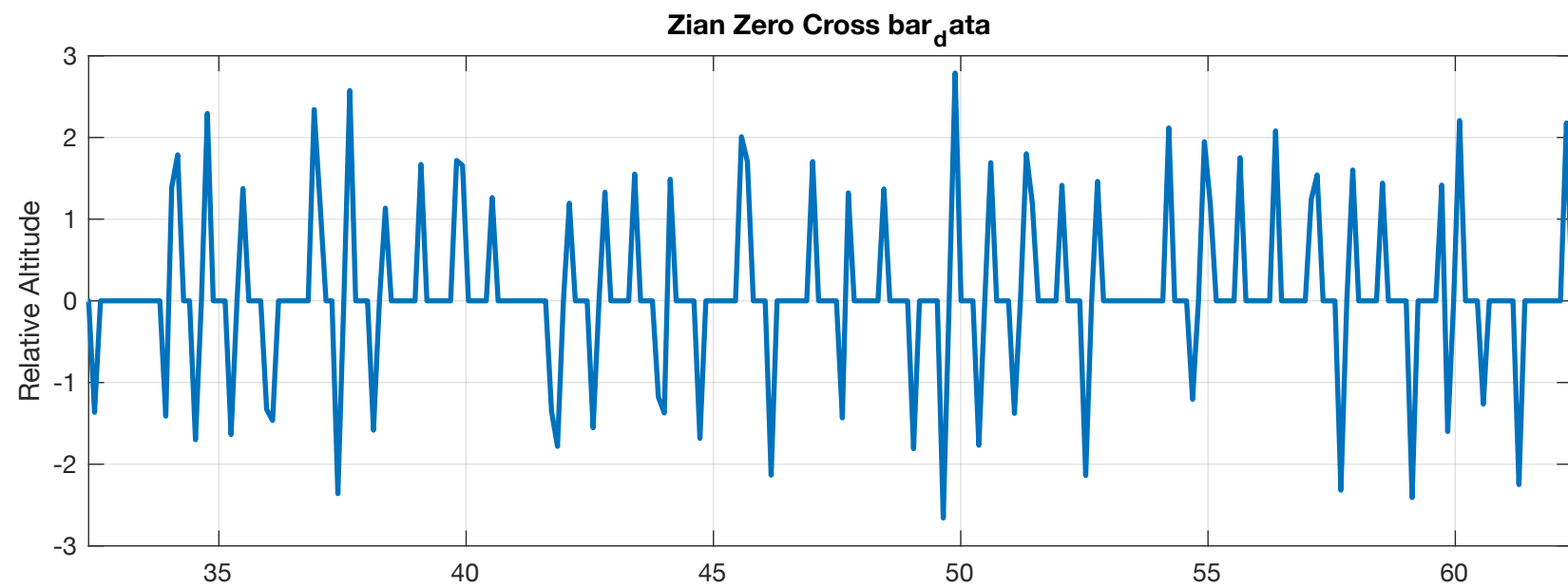
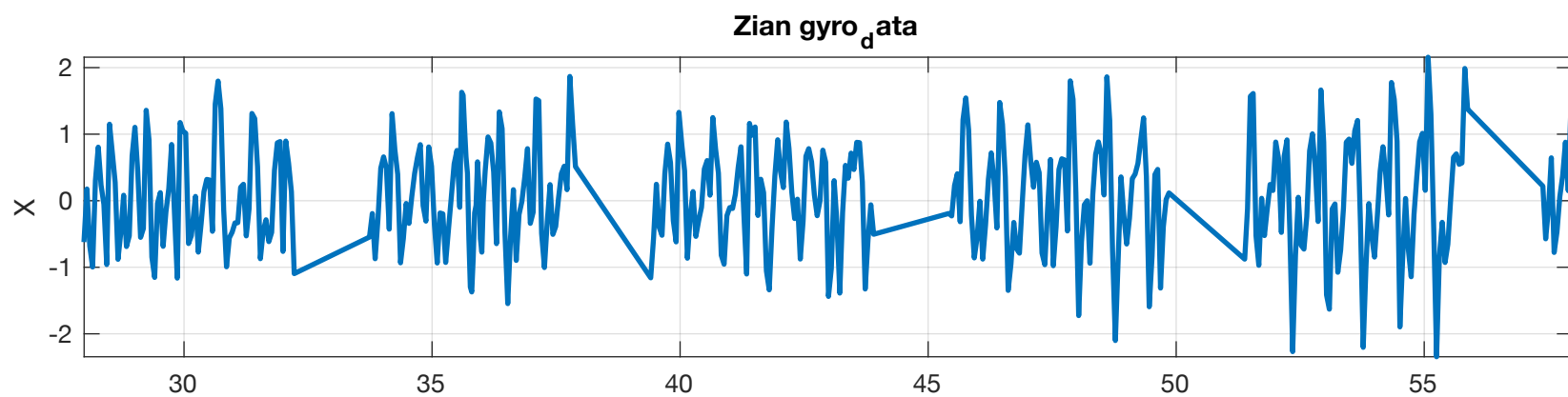
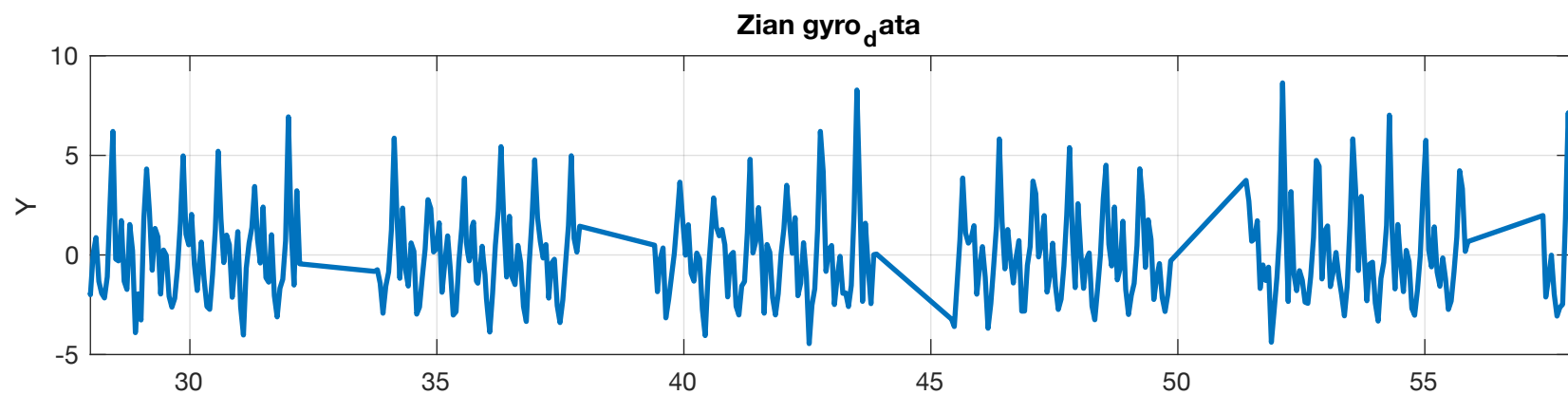
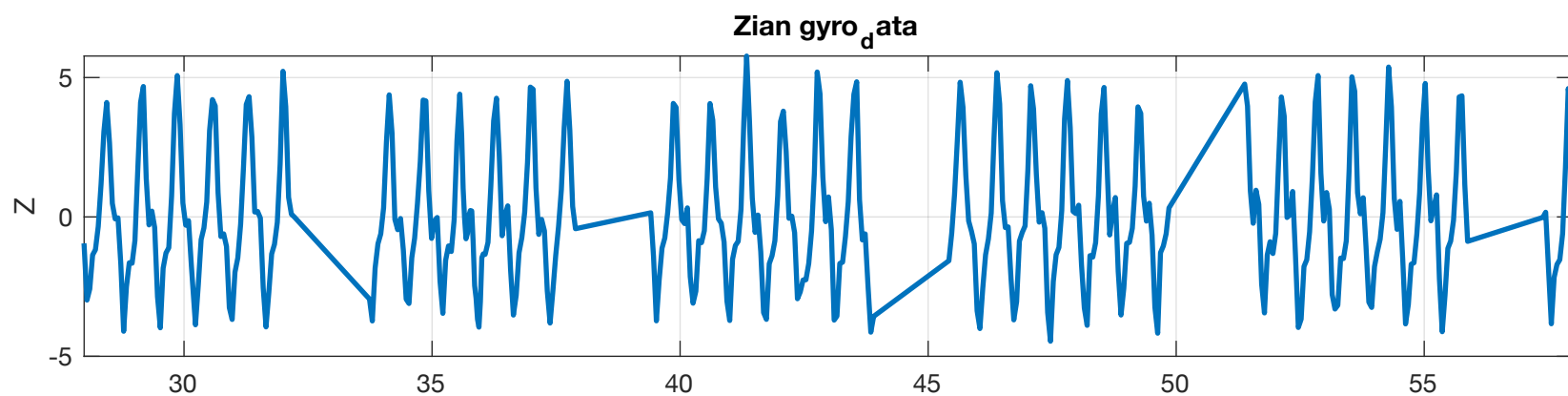


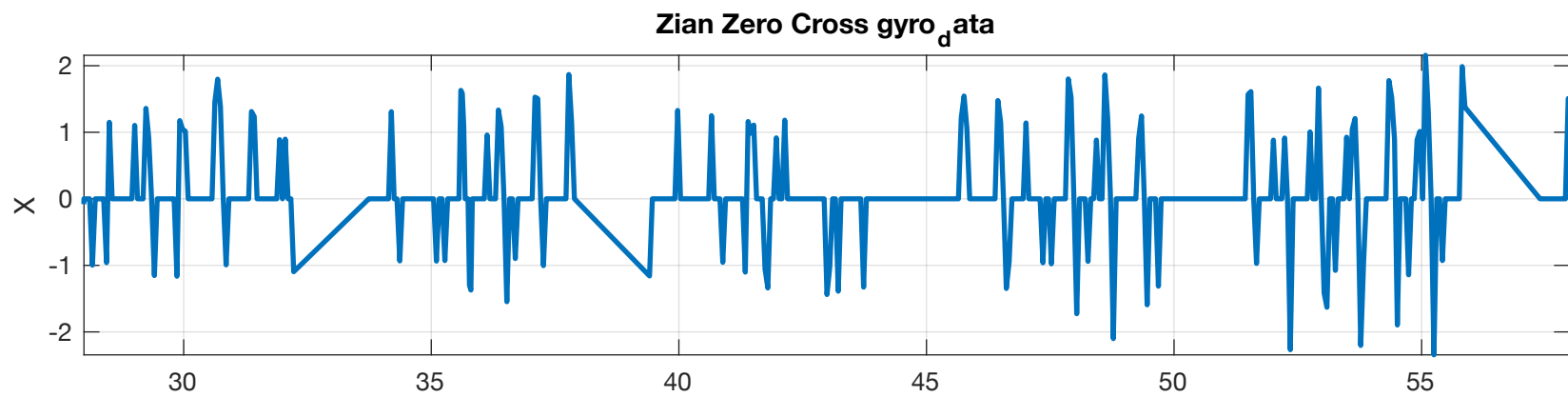
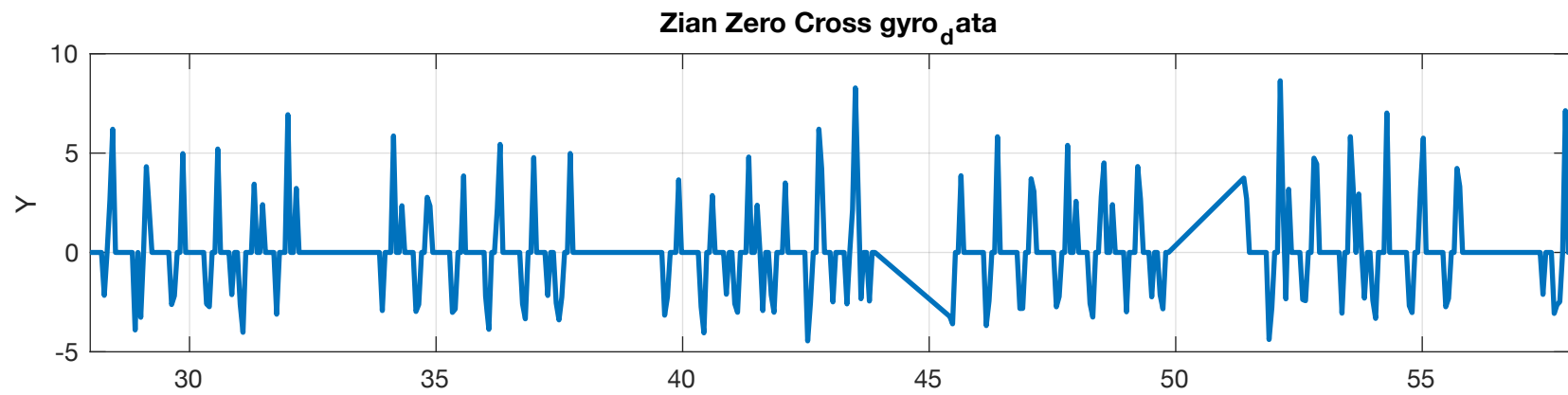
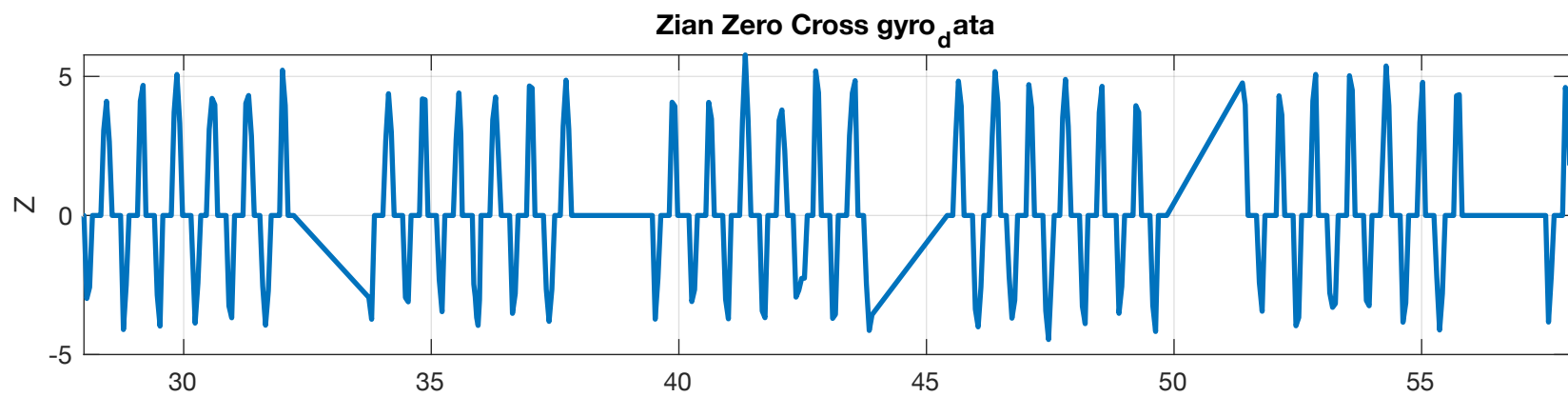
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-222.000	-164.000	115.000	34.500	"accel_data"
'Y'	-115.000	-22.000	148.000	9.500	"accel_data"
'X'	-263.000	-77.000	118.000	55.000	"accel_data"



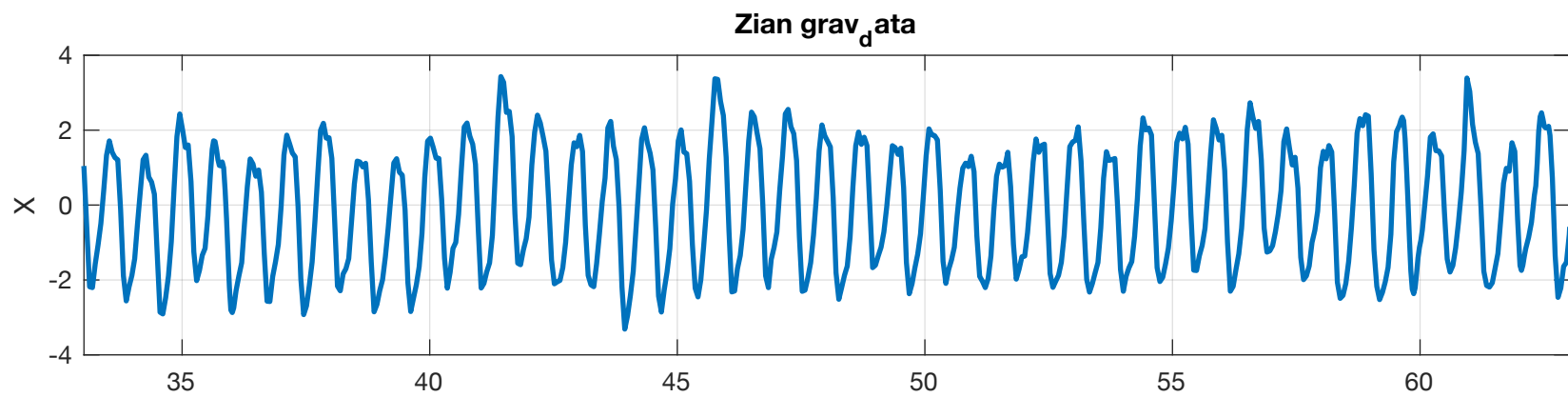
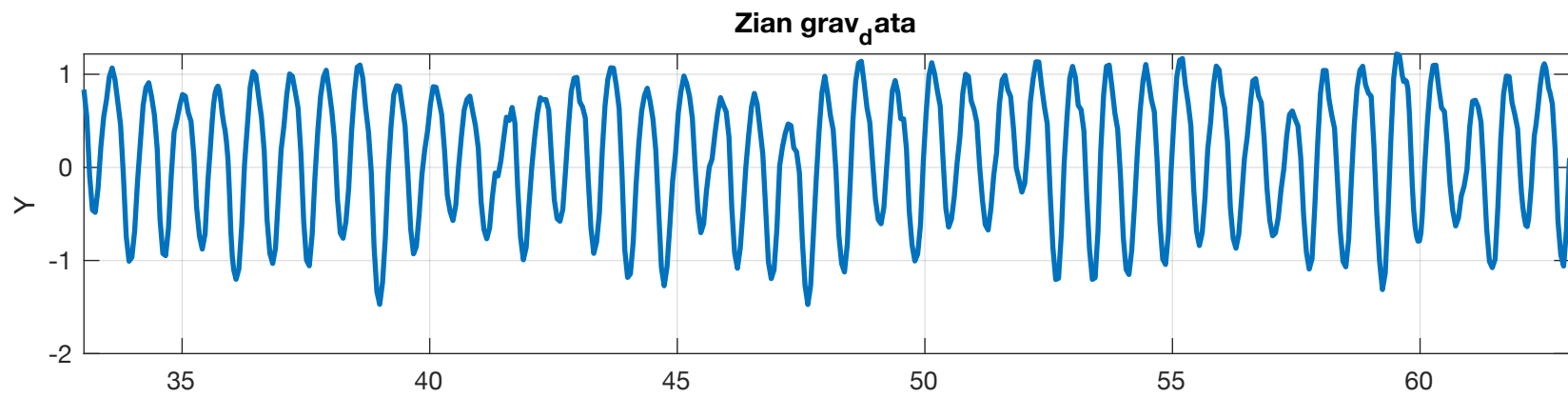
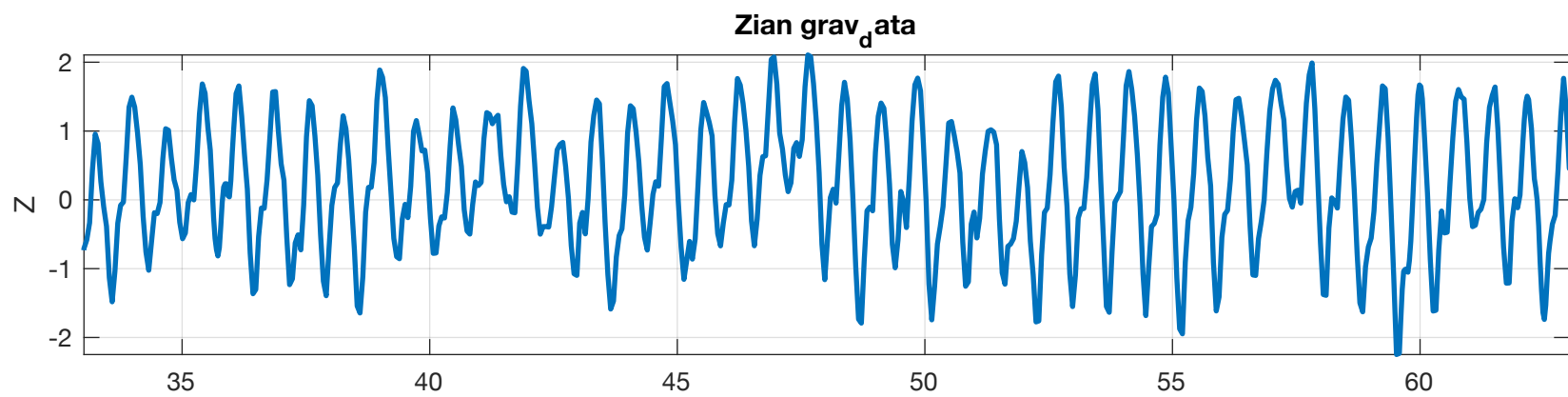


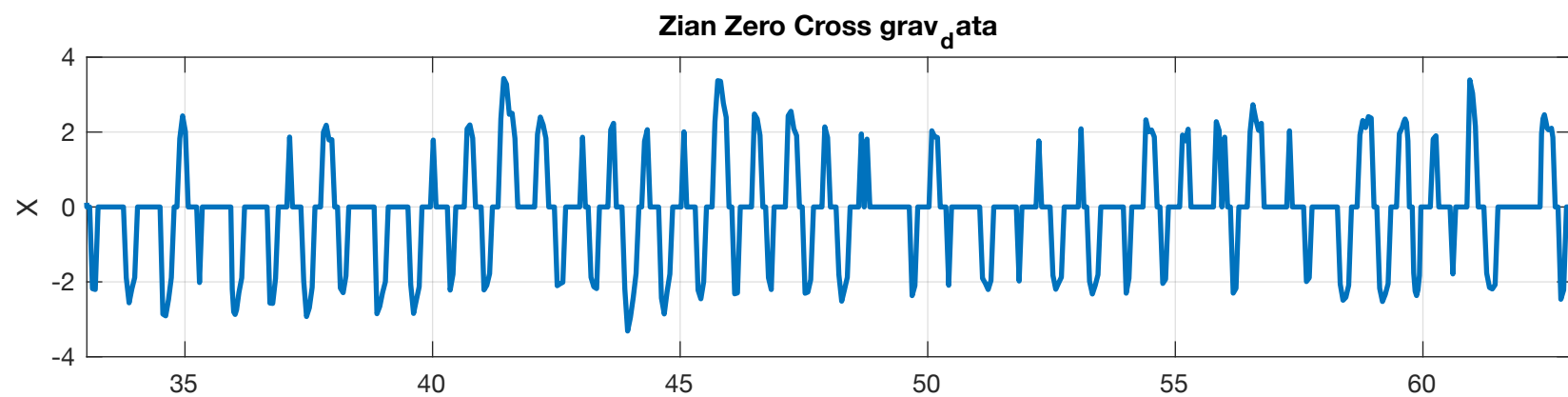
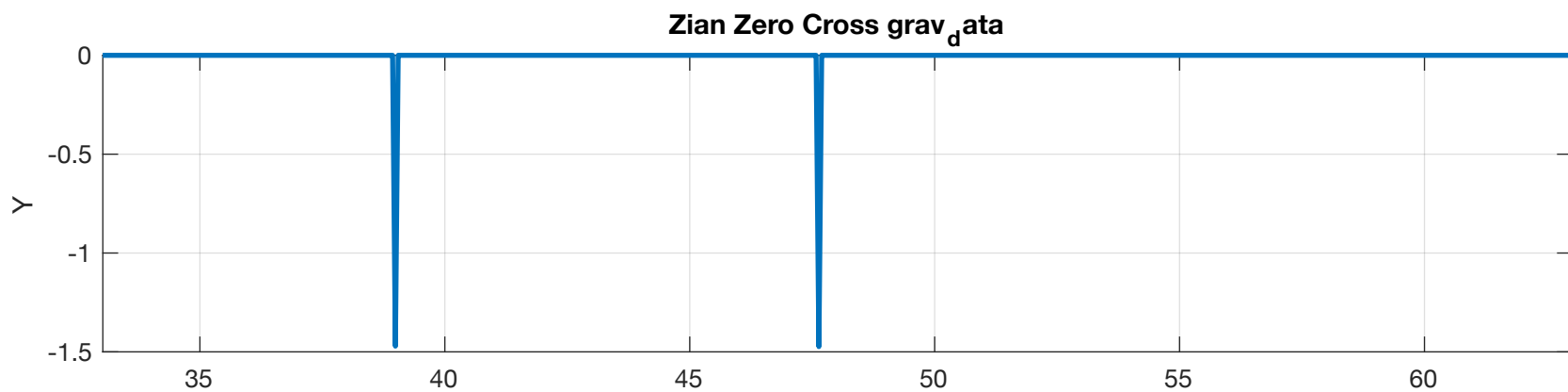
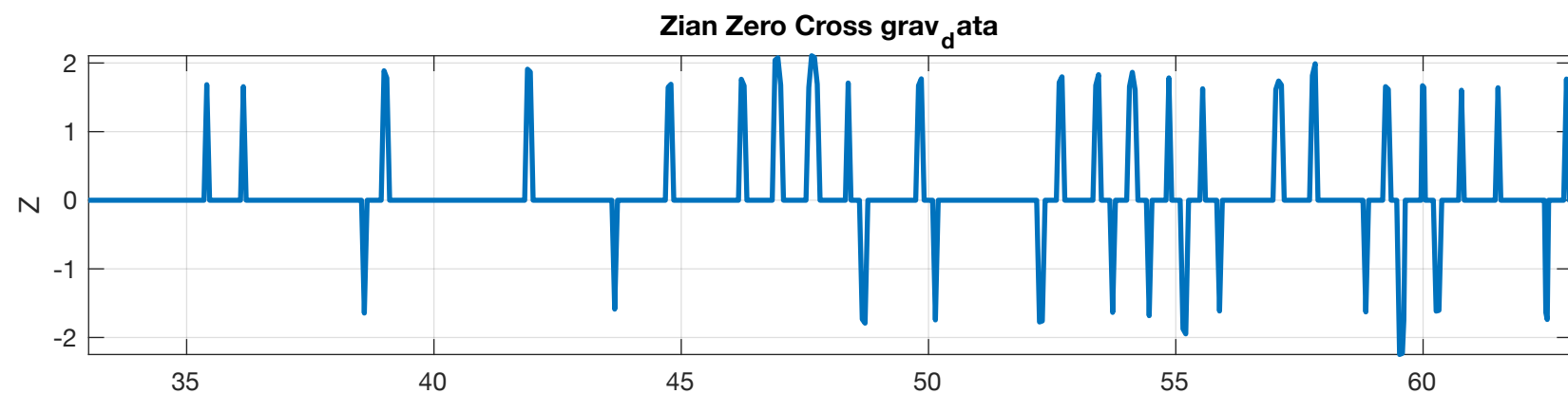
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	42.000	71.000	200.000	180.000	"bar_data"
"Pressure"	3.000	25.000	172.000	180.000	"bar_data"



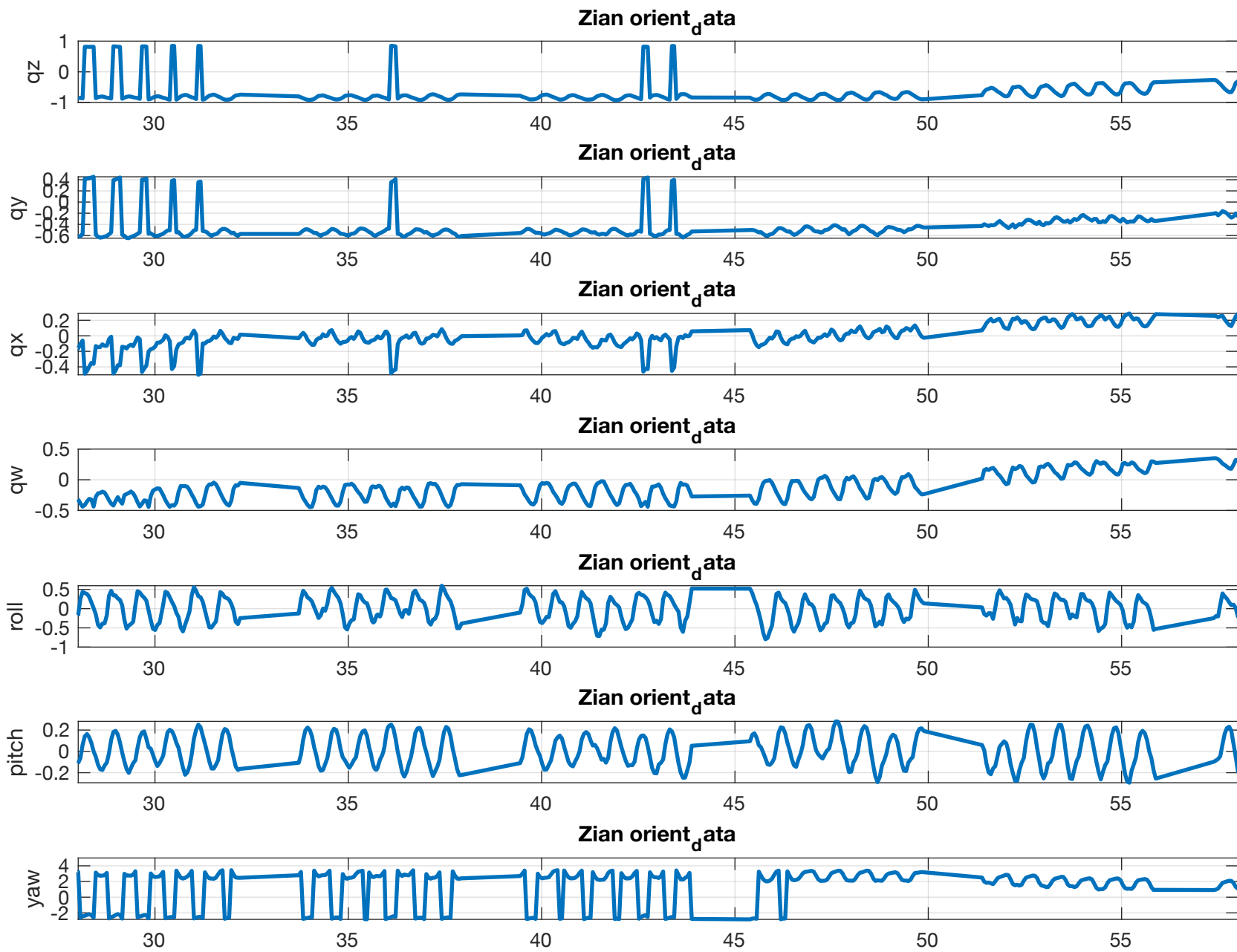


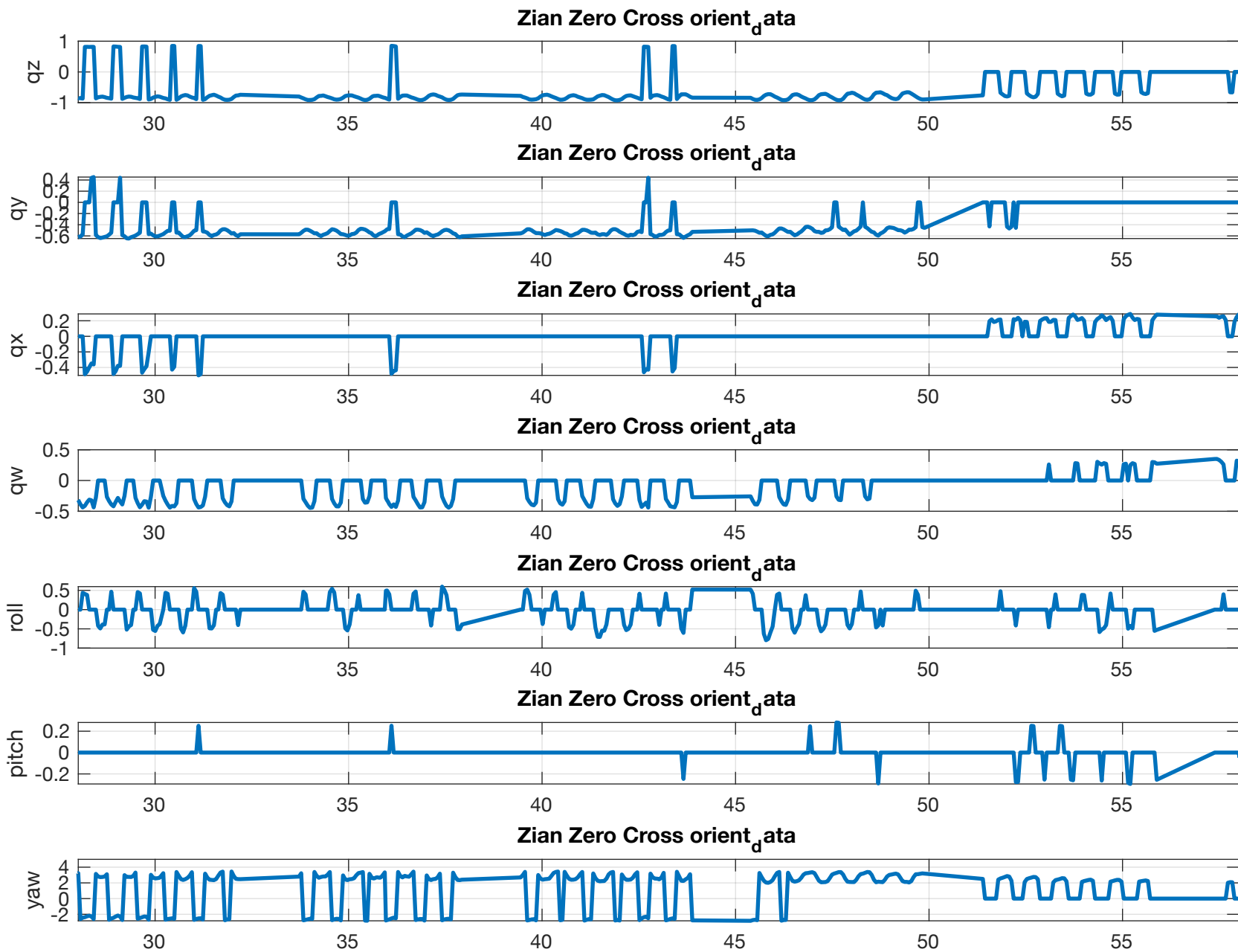
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	12.000	61.000	178.000	173.000	"gyro_data"
'Y'	-134.000	-69.000	164.000	125.000	"gyro_data"
'X'	-123.000	-57.000	164.000	135.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	35.000	118.000	204.000	246.750	"grav_data"
'Y'	122.000	123.000	241.000	296.000	"grav_data"
'X'	44.000	52.000	221.000	175.500	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	73.000	139.000	240.000	260.250	"orient_data"
'qy'	-1.000	96.000	232.000	253.250	"orient_data"
'qx'	-27.000	113.000	216.000	260.250	"orient_data"
'qw'	81.000	183.000	269.000	249.000	"orient_data"
'roll'	67.000	125.000	217.000	199.250	"orient_data"
'pitch'	148.000	172.000	255.000	258.500	"orient_data"
'yaw'	33.000	141.000	224.000	233.250	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Y"	'zero_cross'	9.500
'bar_data'	"Pressure"	'findpeaks'	3.000
'gyro_data'	"Z"	'findpeaks'	12.000
'grav_data'	"Z"	'findpeaks'	35.000
'orient_data'	"qy"	'findpeaks'	1.000