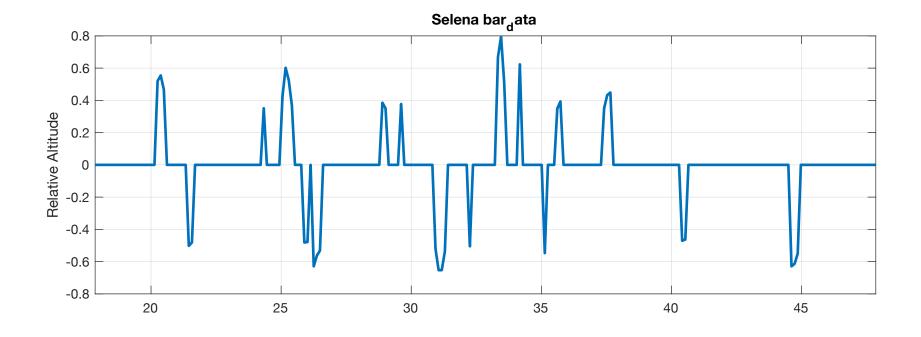
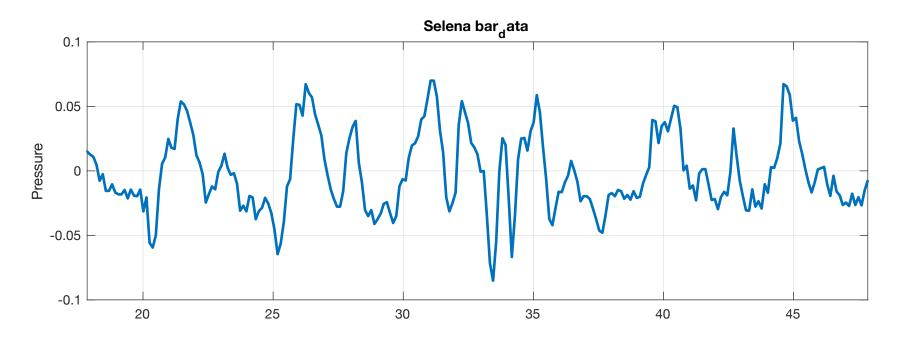
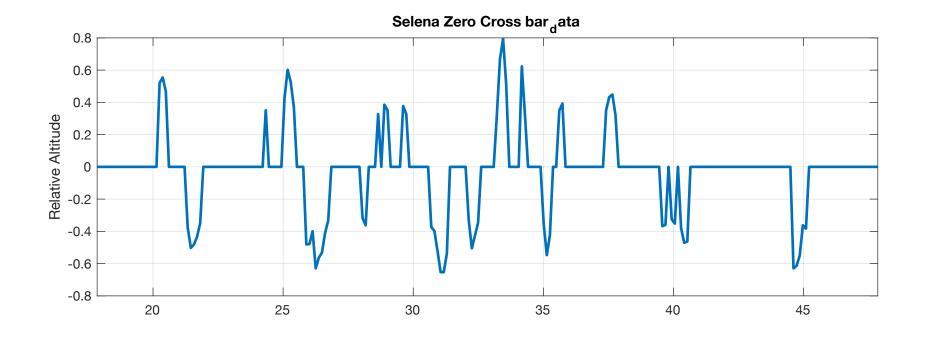
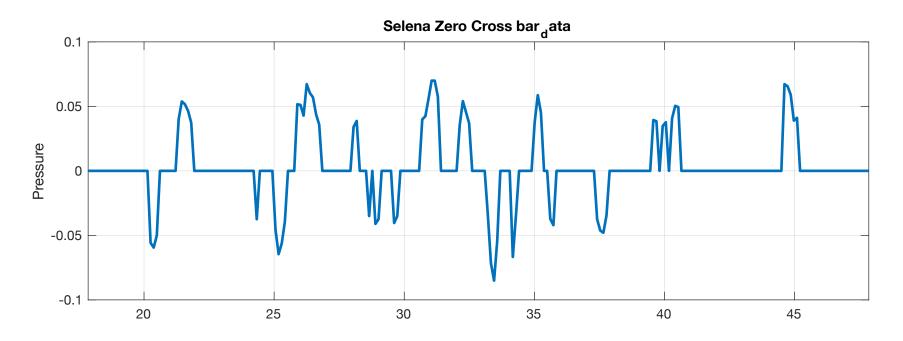


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-282.000	-208.000	-72.000	-72.750	"accel_data"
'Y'	-379.000	-264.000	-88.000	-72.500	"accel_data"
'X'	-382.000	-282.000	-96.000	-56.000	"accel_data"

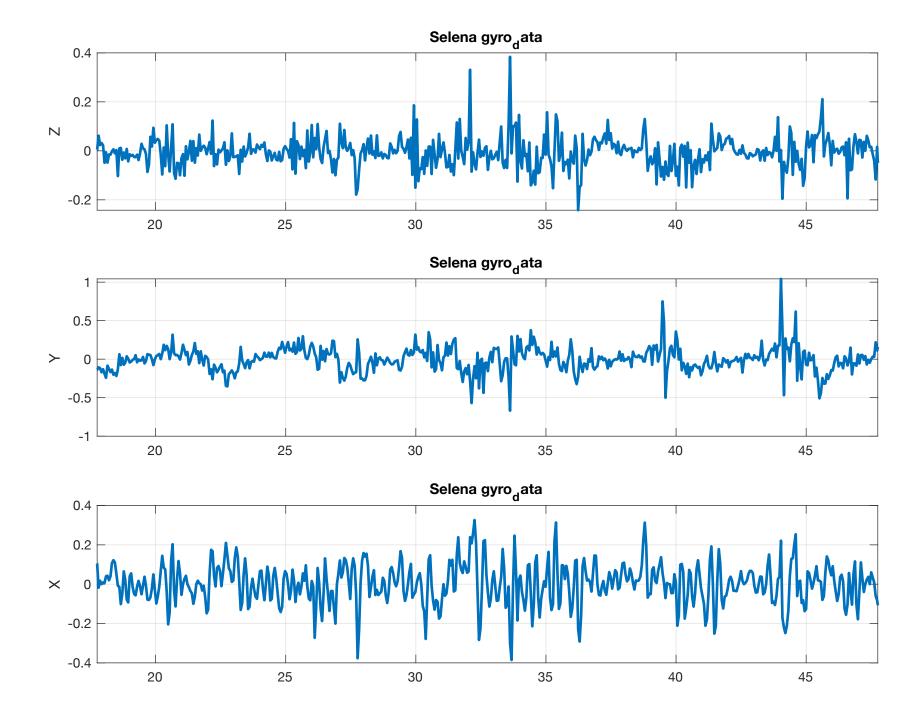


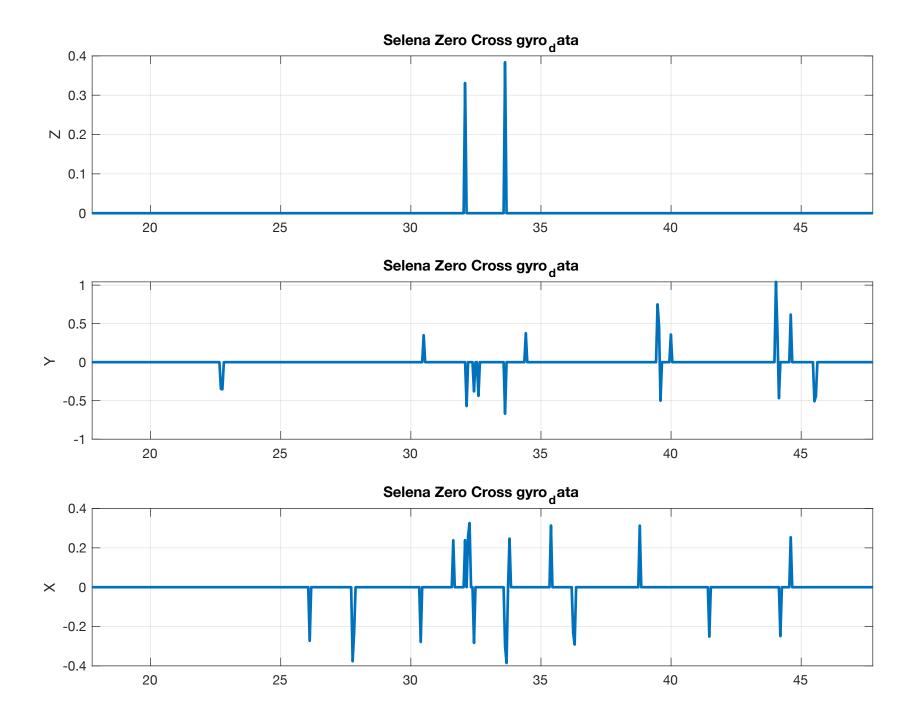




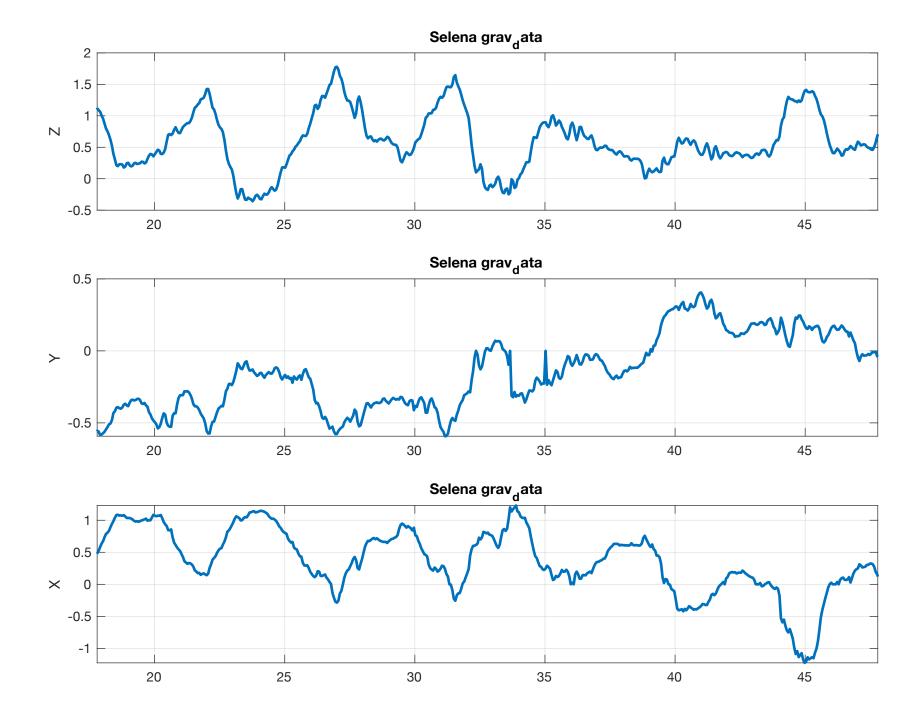


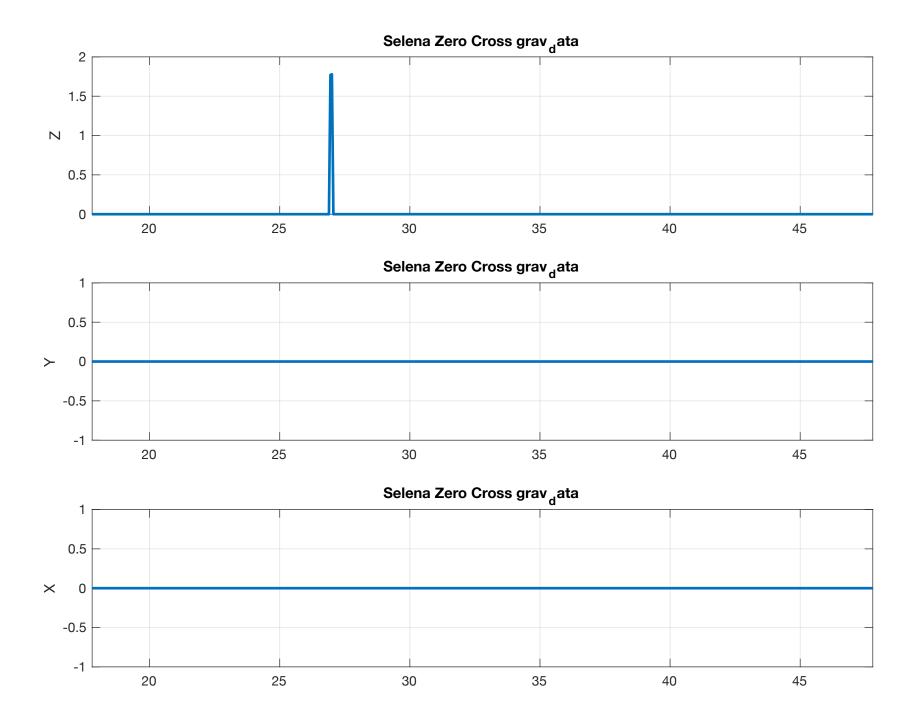
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-24.000	-15.000	1.000	-12.500	"bar_data"
"Pressure"	-117.000	-55.000	-22.000	-12.500	"bar_data"



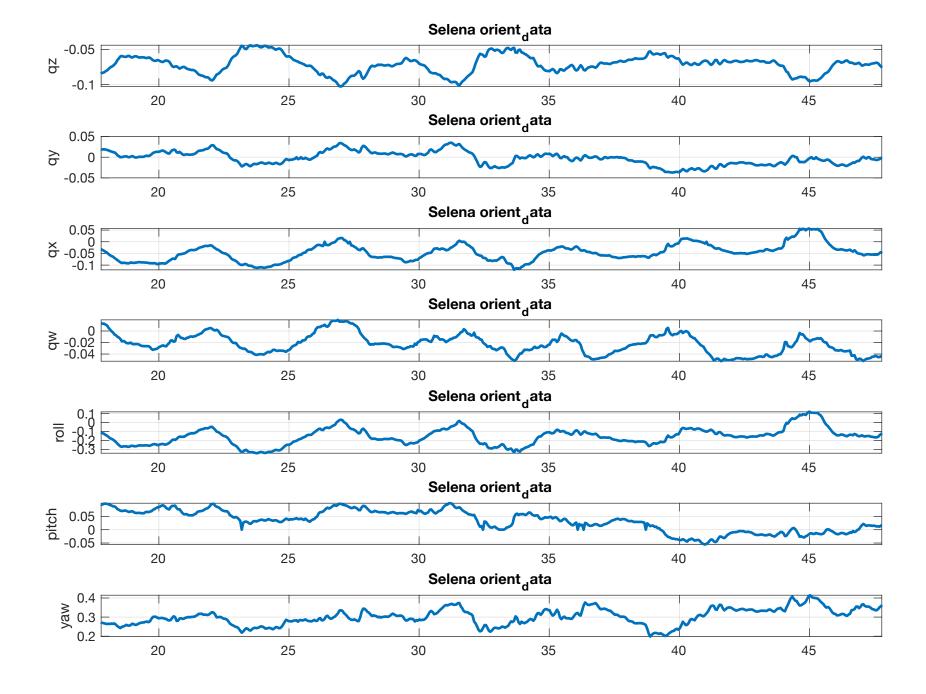


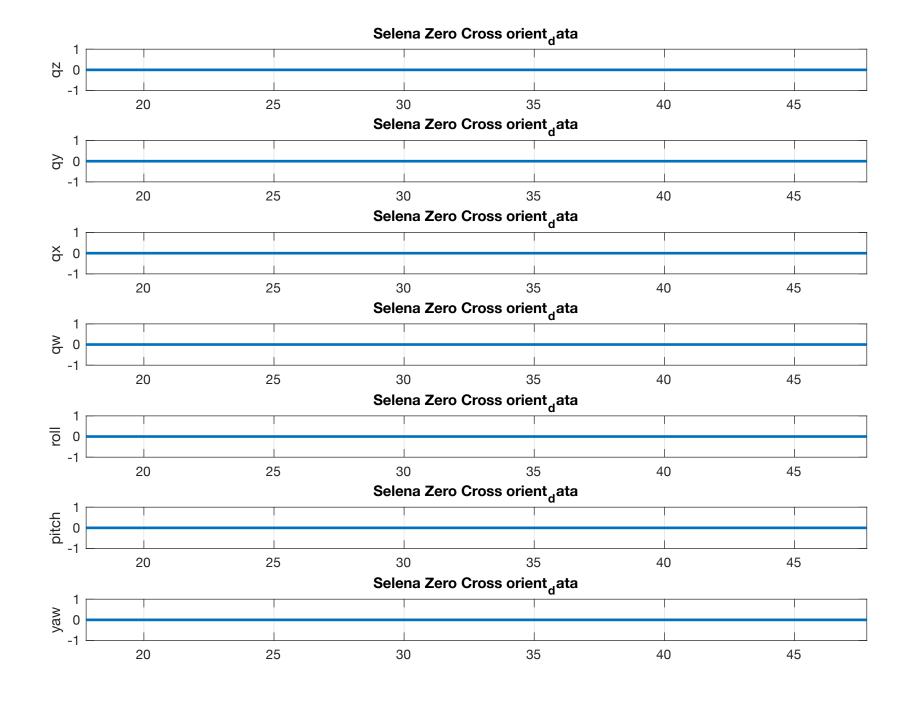
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-385.000	-278.000	-99.000	-7.000	"gyro_data"
'Y'	-351.000	-273.000	-82.000	-34.500	"gyro_data"
'X'	-256.000	-212.000	-66.000	-23.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-148.000	-117.000	-20.000	5.500	"grav_data"
'Y'	-169.000	-72.000	-14.000	7.750	"grav_data"
'X'	-163.000	-127.000	-30.000	7.750	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-149.000	-4.000	6.000	8.500	"orient_data"
'qy'	-170.000	-65.000	-15.000	6.500	"orient_data"
'qx'	-158.000	-41.000	-6.000	6.500	"orient_data"
'qw'	-176.000	-46.000	-8.000	3.250	"orient_data"
'roll'	-149.000	-14.000	-1.000	9.500	"orient_data"
'pitch'	-177.000	-125.000	-28.000	7.250	"orient_data"
'yaw'	-163.000	-150.000	-28.000	9.500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'zero_cross'	56.000
'bar_data'	"Relative Altitude"	'double_findpeaks'	1.000
'gyro_data'	"Z"	'zero_cross'	7.000
'grav_data'	"Z"	'zero_cross'	5.500
'orient data'	"roll"	'double findpeaks'	1.000