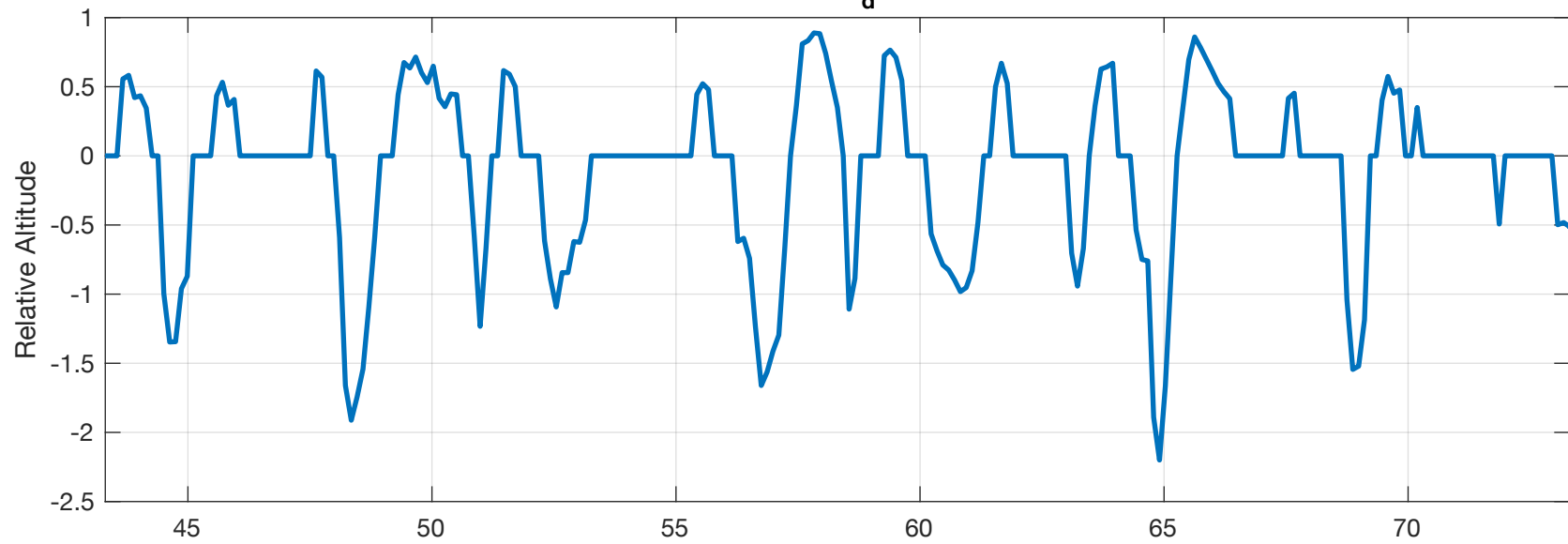
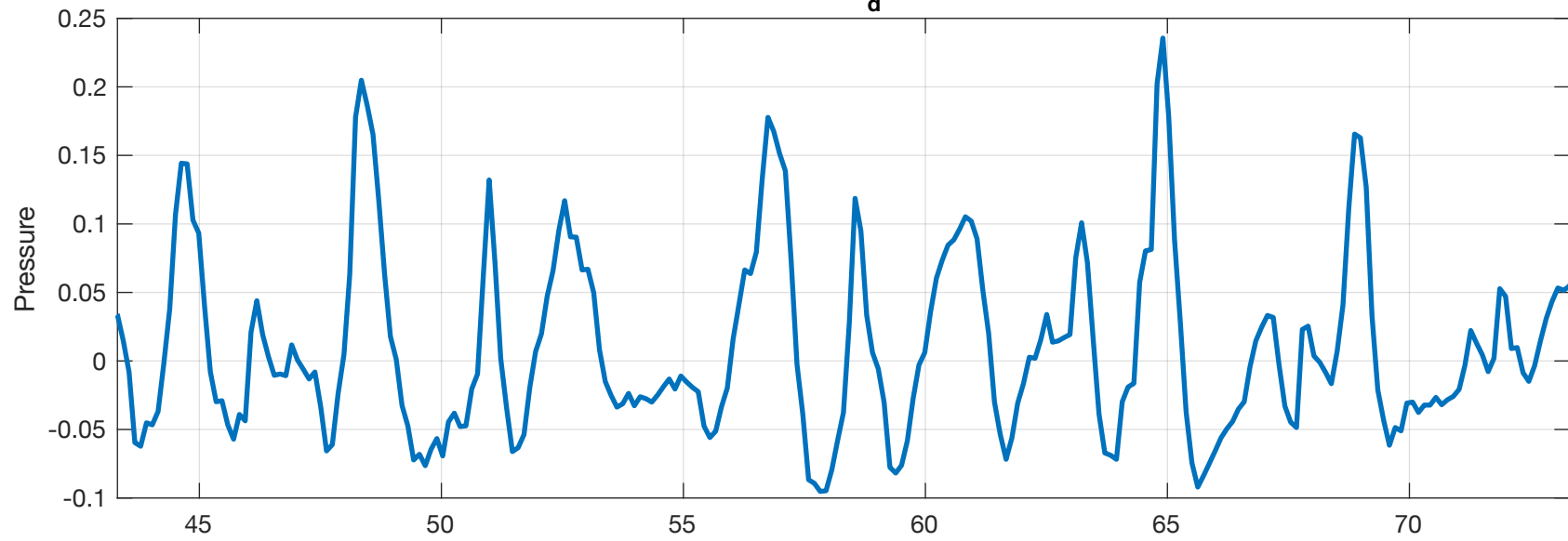


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-211.000	-132.000	-43.000	-11.500	"accel_data"
'Y'	-235.000	-182.000	-59.000	-32.500	"accel_data"
'X'	-207.000	-157.000	-44.000	-35.500	"accel_data"

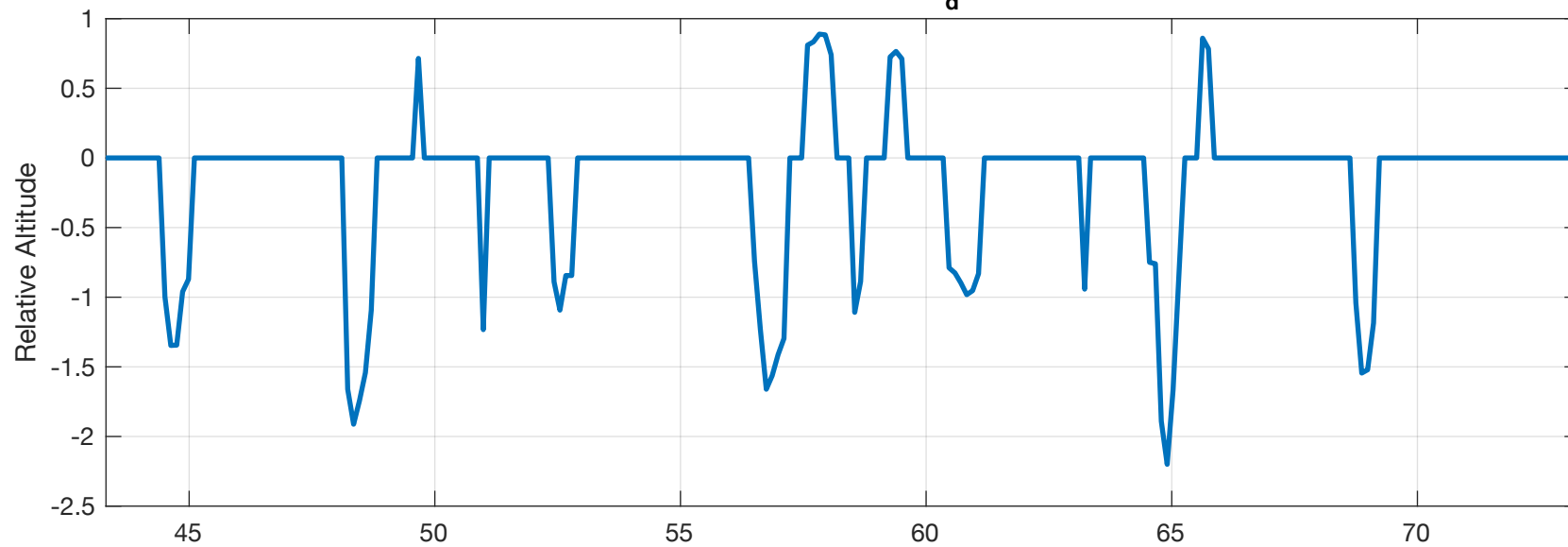
Zian bar_data



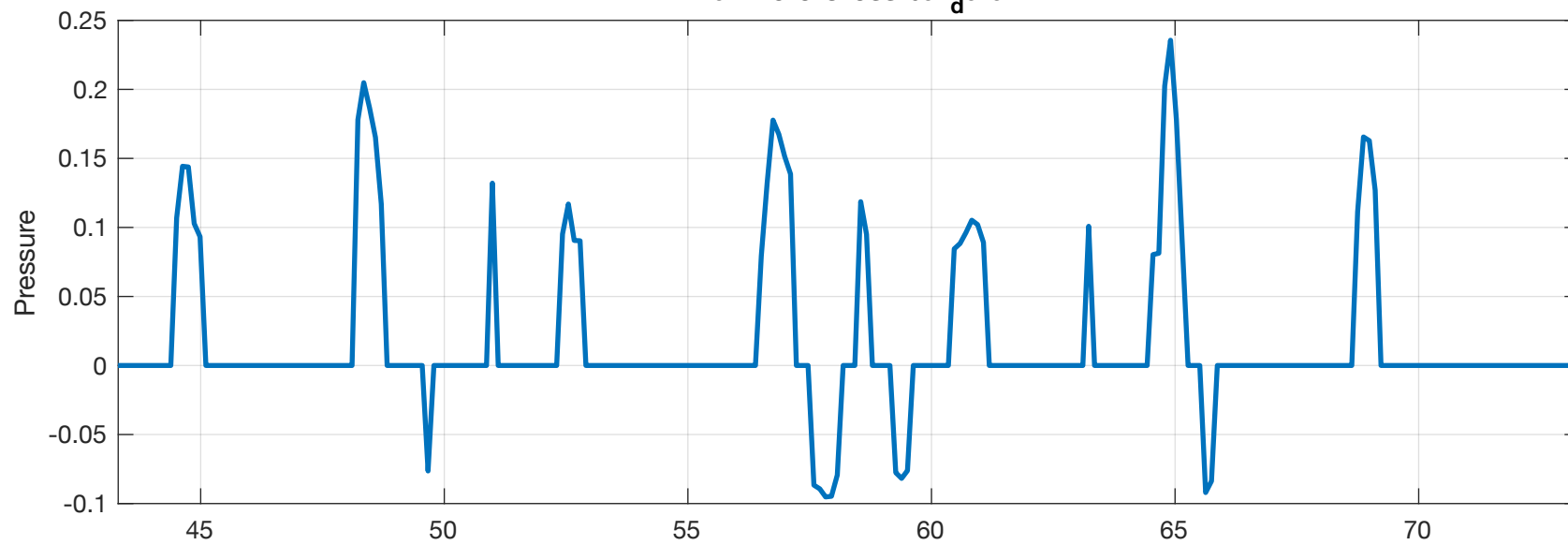
Zian bar_data



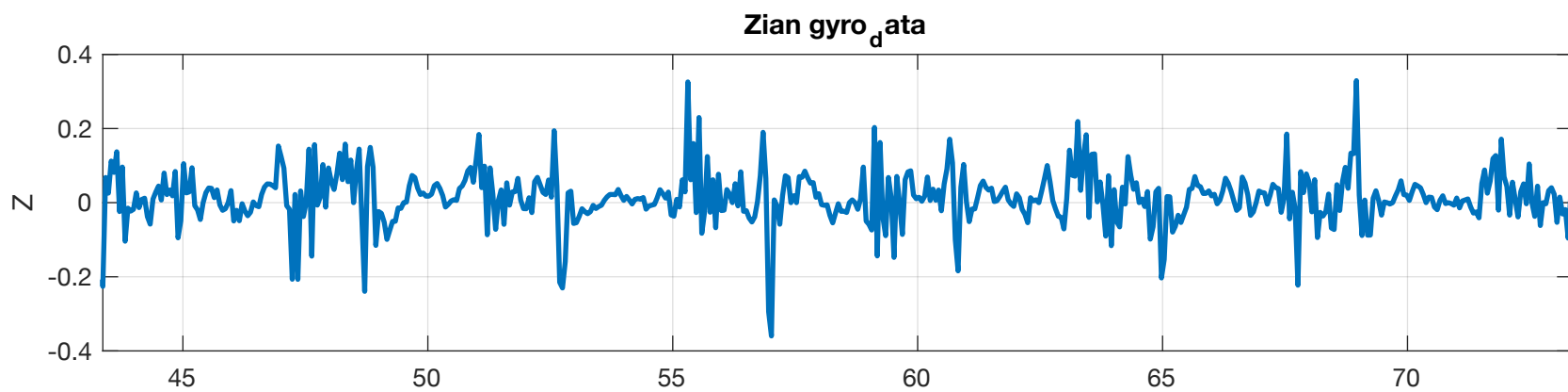
Zian Zero Cross bar_data

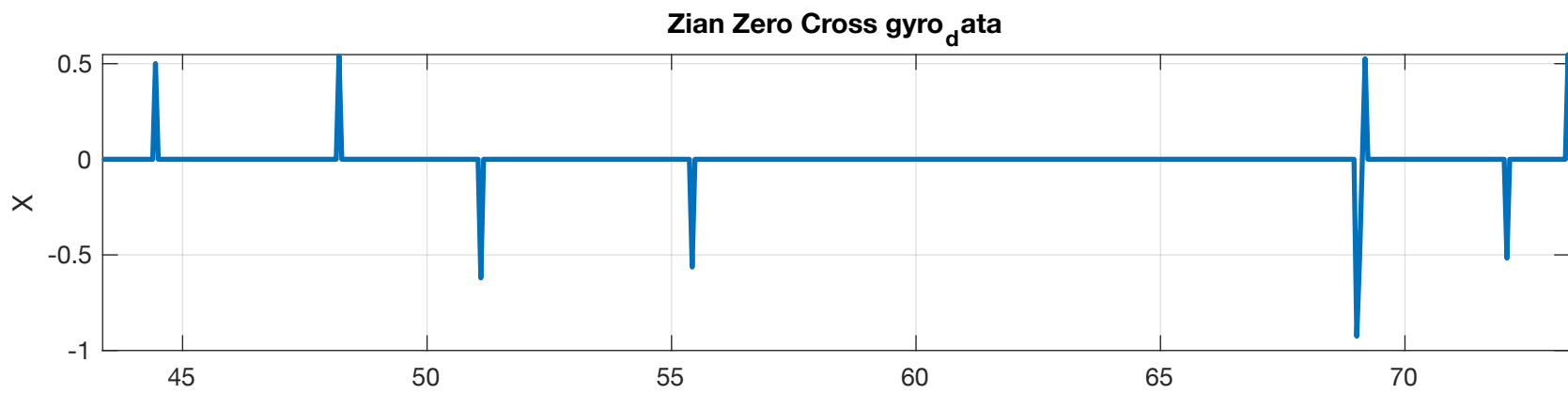
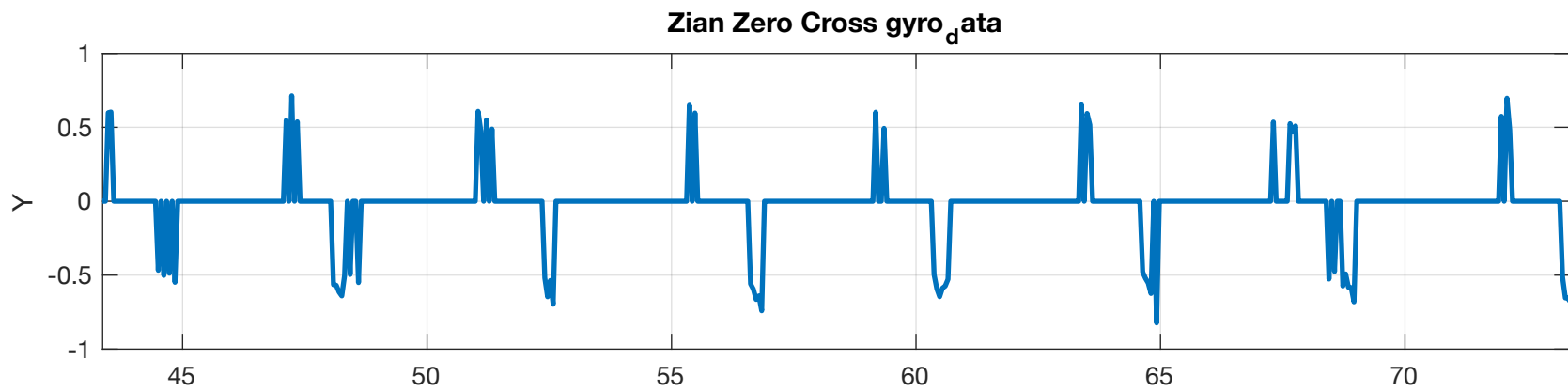
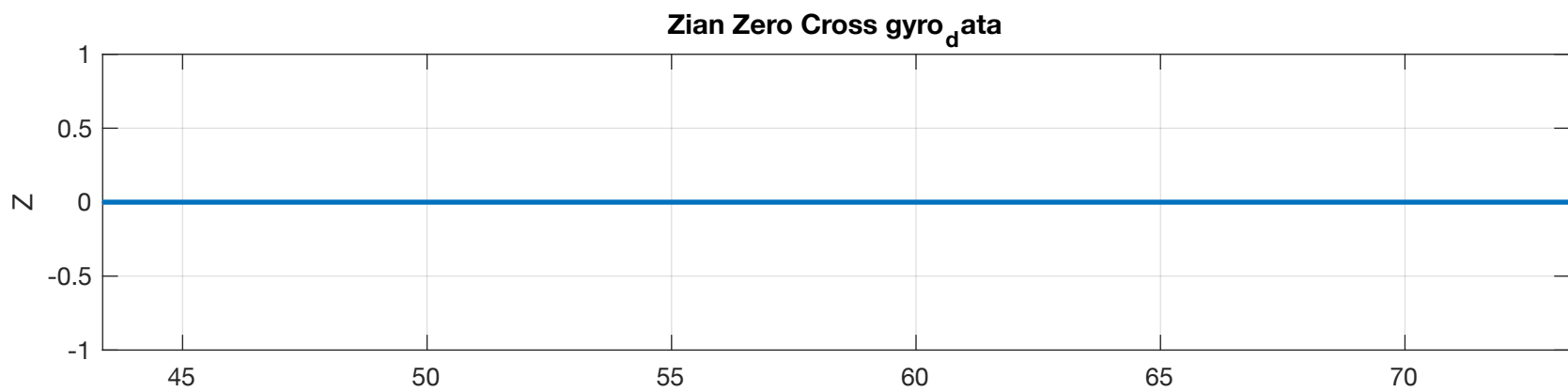


Zian Zero Cross bar_data

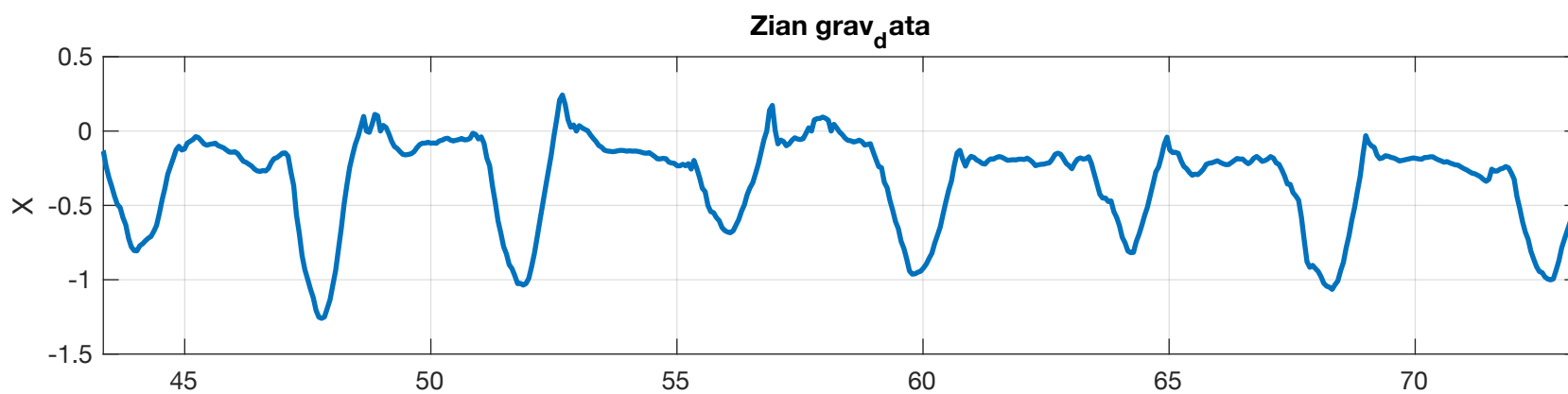
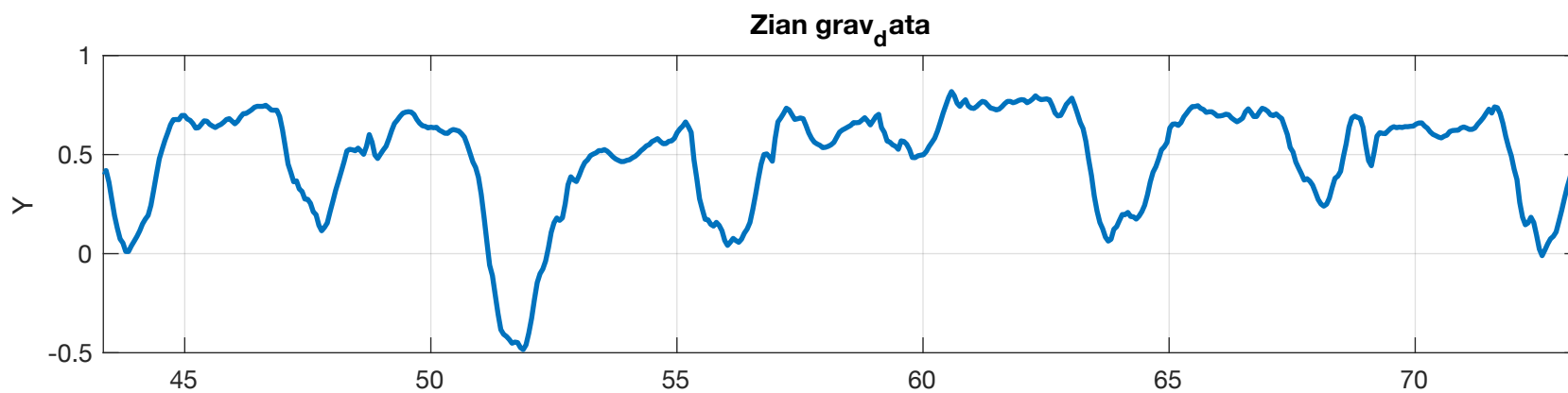
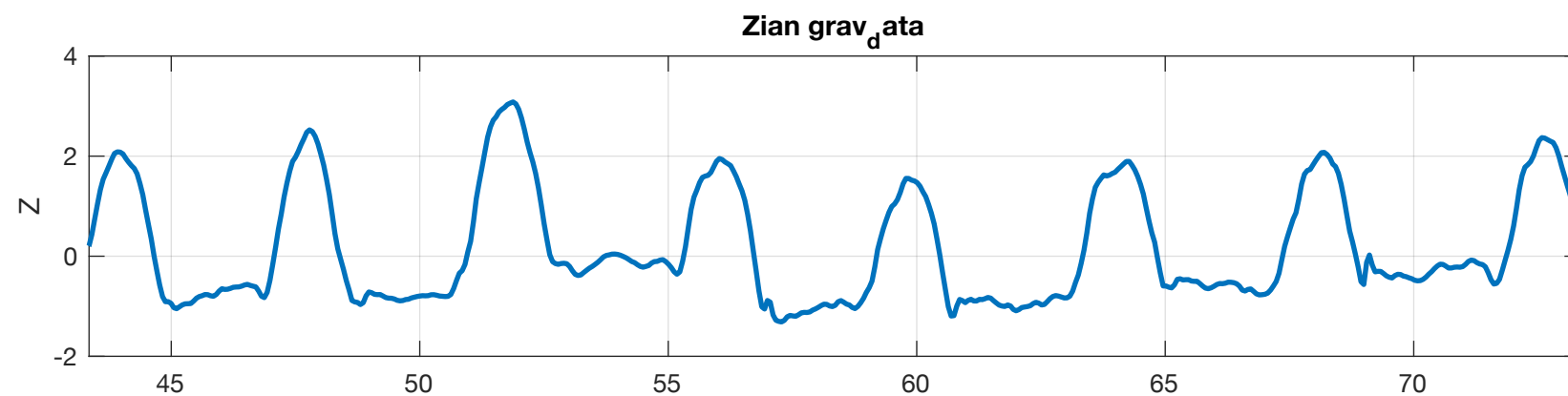


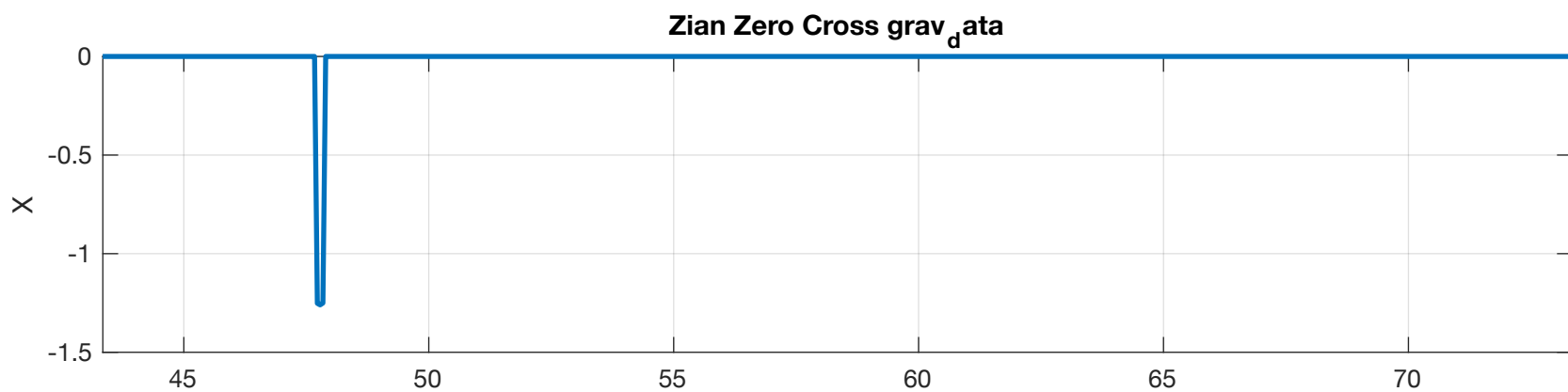
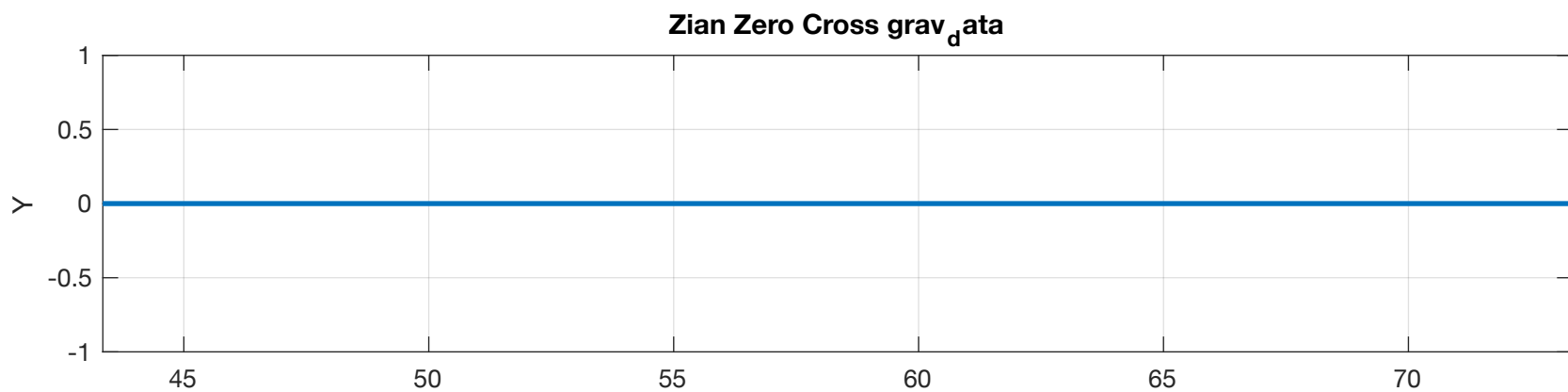
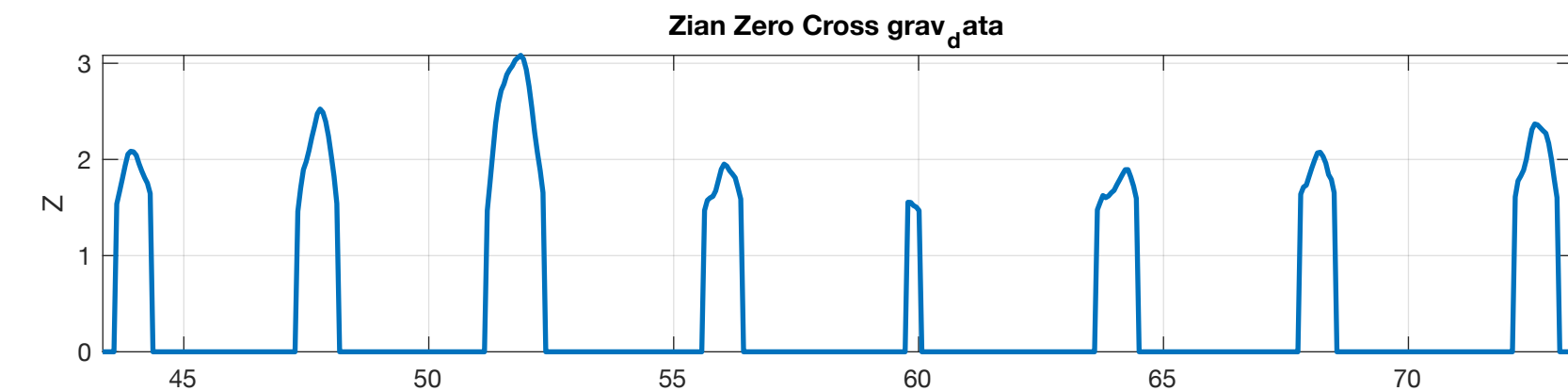
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-26.000	-20.000	-1.000	0.500	"bar_data"
"Pressure"	-46.000	-27.000	-5.000	0.500	"bar_data"



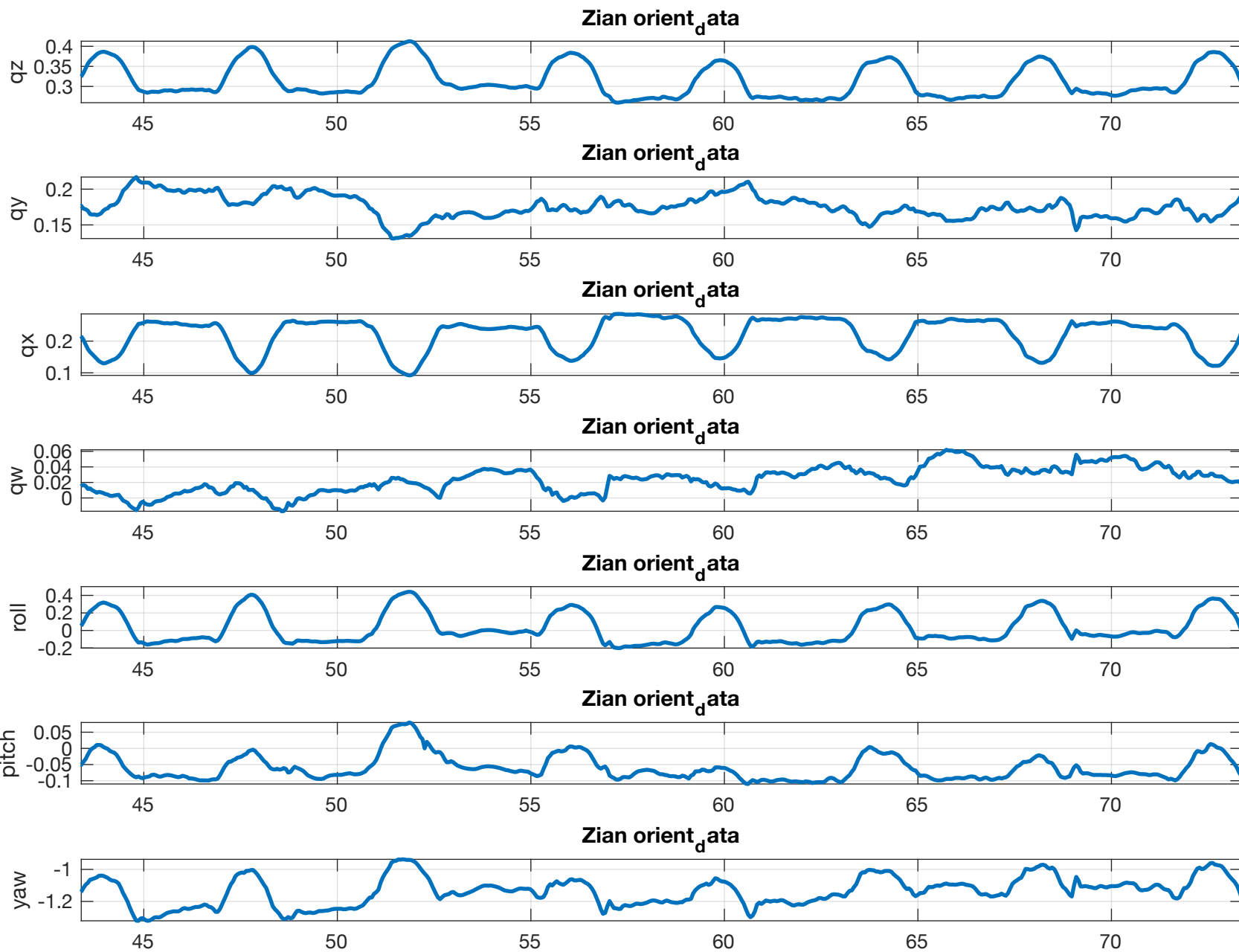


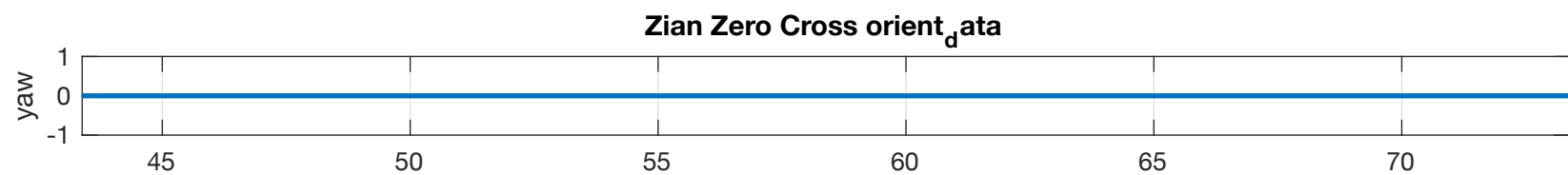
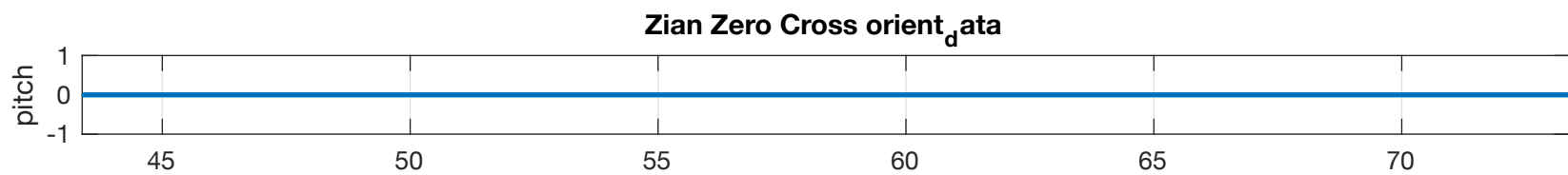
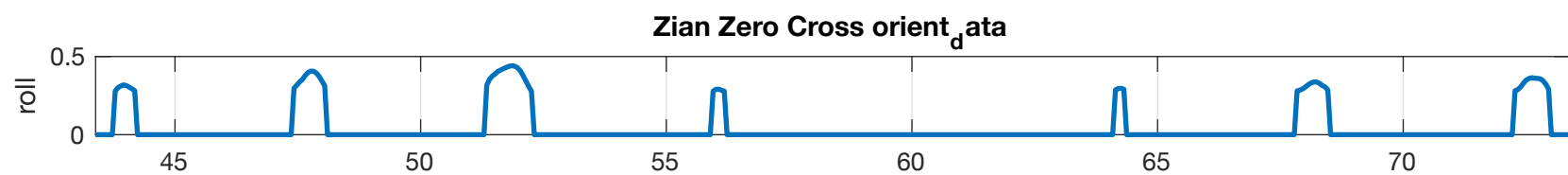
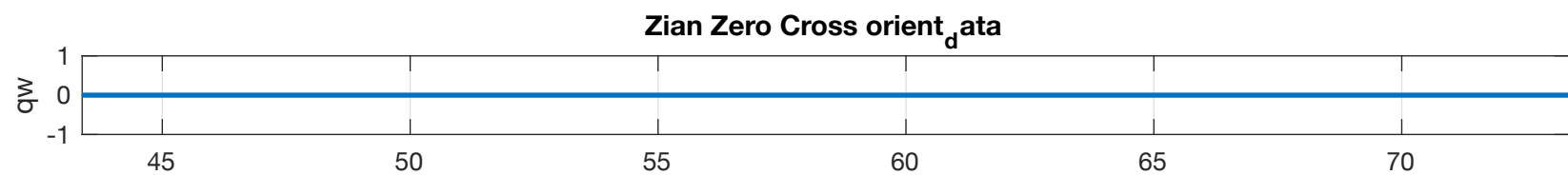
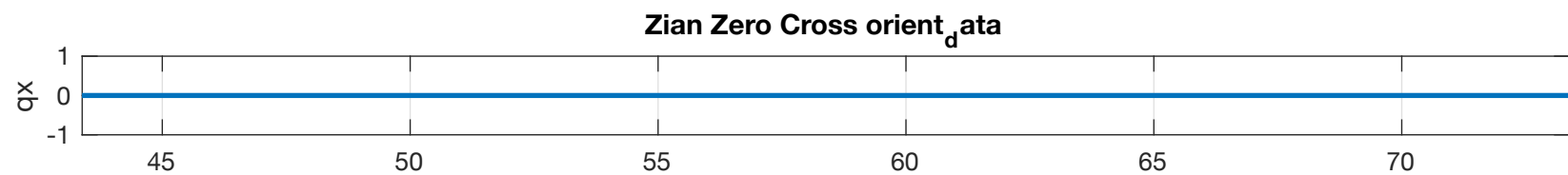
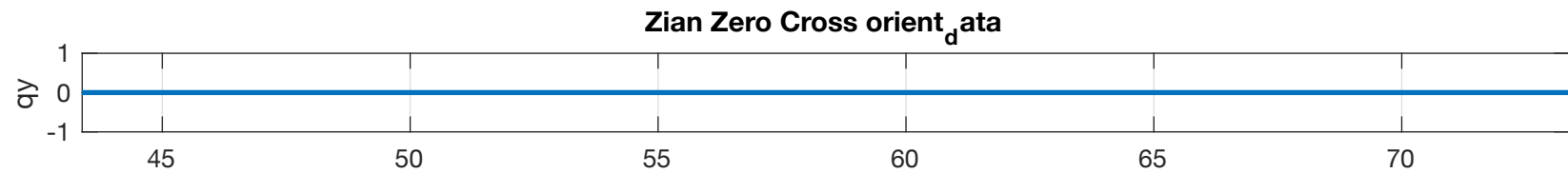
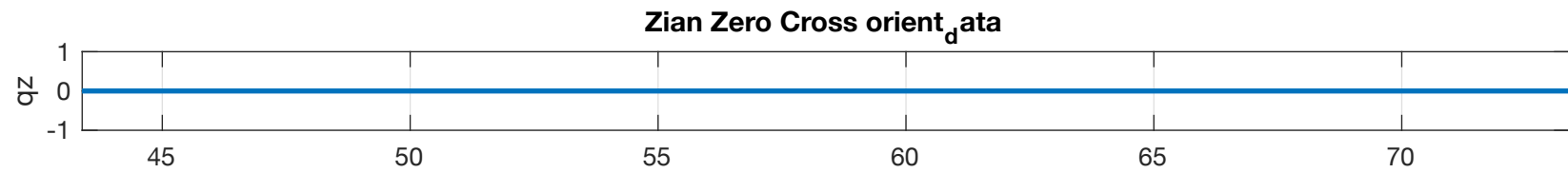
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-244.000	-216.000	-66.000	11.000	"gyro_data"
'Y'	-211.000	-136.000	-38.000	-10.500	"gyro_data"
'X'	-184.000	-152.000	-39.000	5.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-59.000	-7.000	-2.000	6.000	"grav_data"
'Y'	-83.000	-81.000	-13.000	12.000	"grav_data"
'X'	-88.000	2.000	8.000	11.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-60.000	-60.000	-10.000	12.000	"orient_data"
'qy'	-109.000	-109.000	-18.000	12.000	"orient_data"
'qx'	-75.000	-75.000	-11.000	12.000	"orient_data"
'qw'	-132.000	-126.000	-21.000	12.000	"orient_data"
'roll'	-57.000	-8.000	-2.000	6.500	"orient_data"
'pitch'	-87.000	-1.000	4.000	12.000	"orient_data"
'yaw'	-93.000	12.000	12.000	12.000	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'zero_cross'	11.500
'bar_data'	"Relative Altitude"	'zero_cross'	0.500
'gyro_data'	"X"	'zero_cross'	5.500
'grav_data'	"X"	'findpeaks_above_zero'	2.000
'orient_data'	"pitch"	'findpeaks_above_zero'	1.000