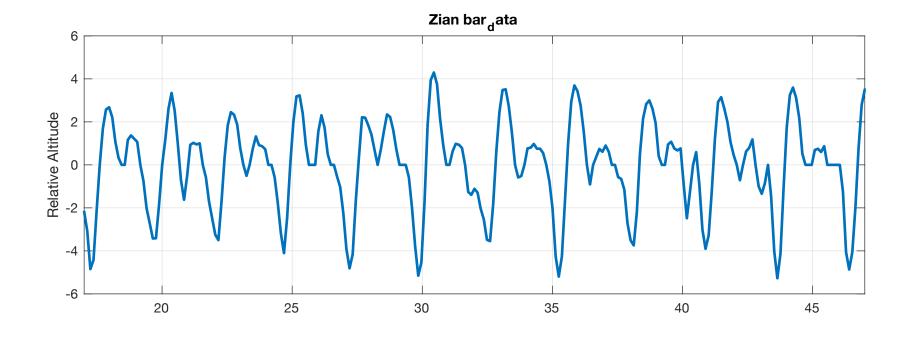
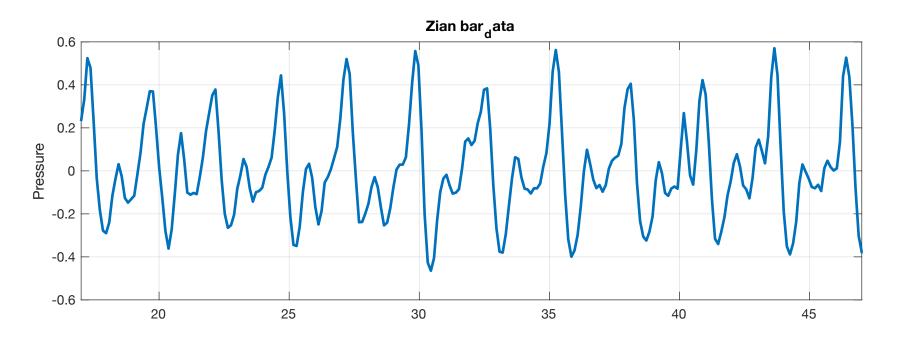
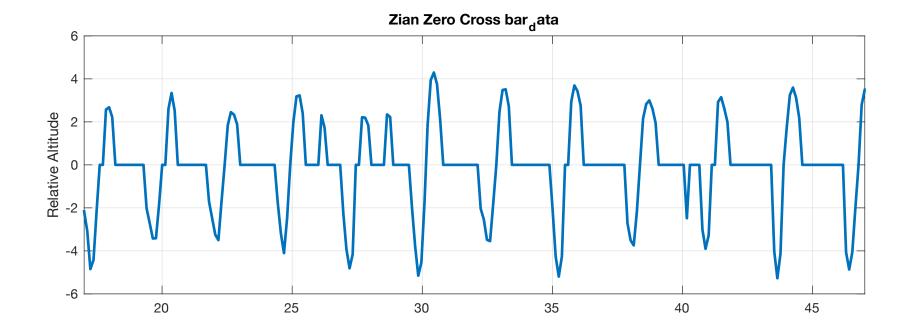
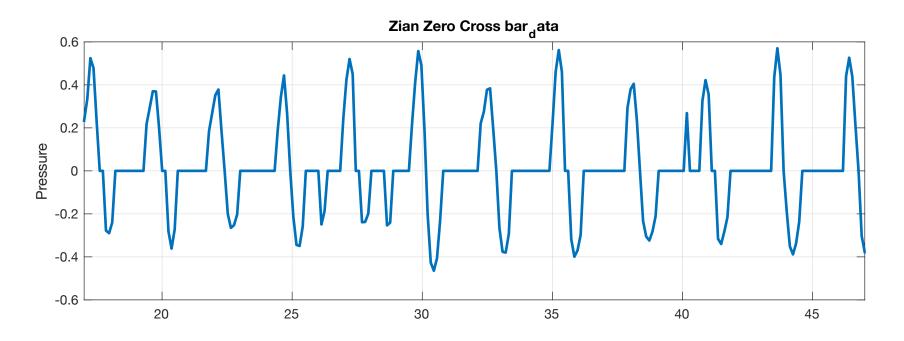


s findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
-415.000	-357.000	-117.000	-27.500	"accel_data"
-424.000	-389.000	-116.000	-52.000	"accel_data"
-414.000	-311.000	-95.000	-55.000	"accel_data"
	-415.000 -424.000	-415.000 -357.000 -424.000 -389.000	-415.000 -357.000 -117.000 -424.000 -389.000 -116.000	-424.000 -389.000 -116.000 -52.000

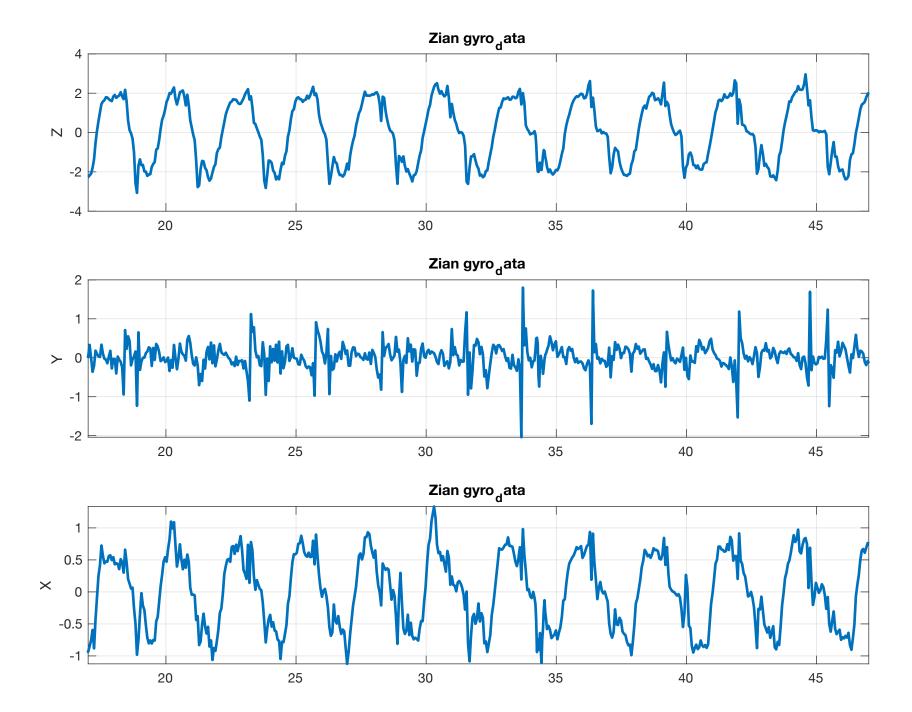


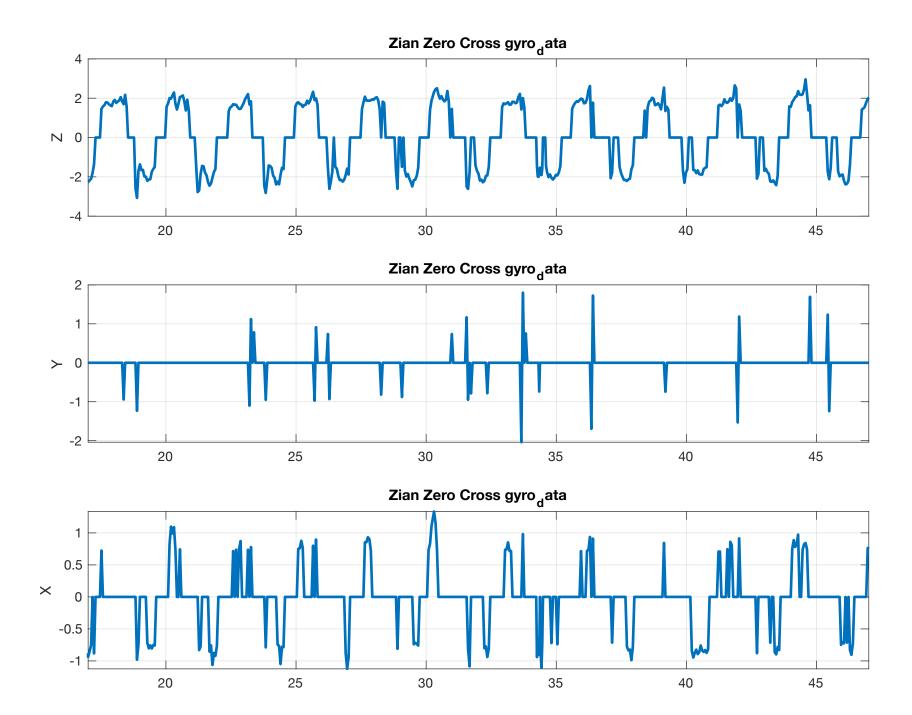




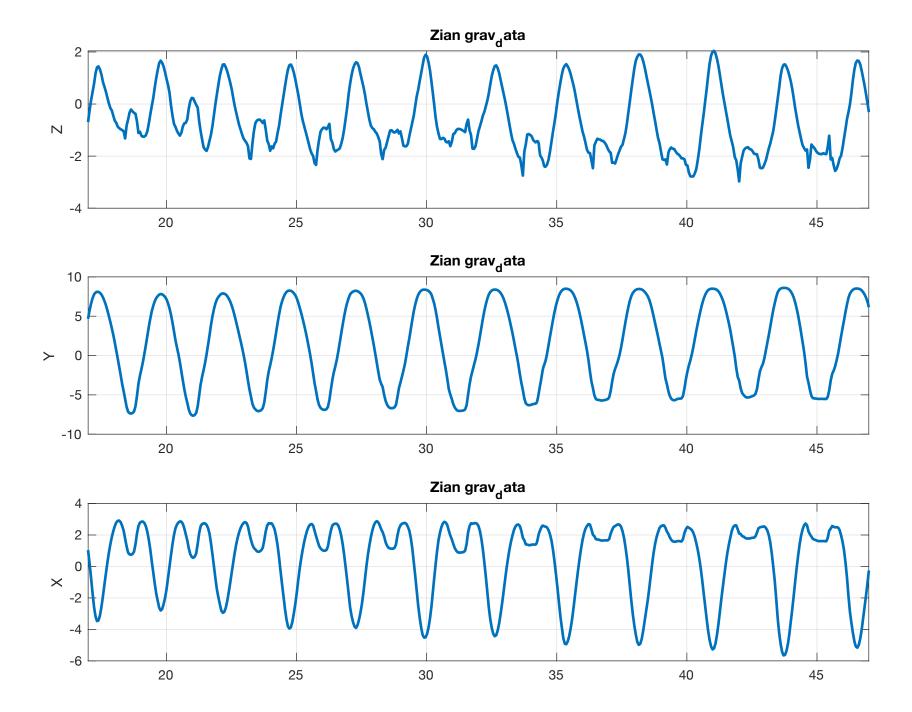


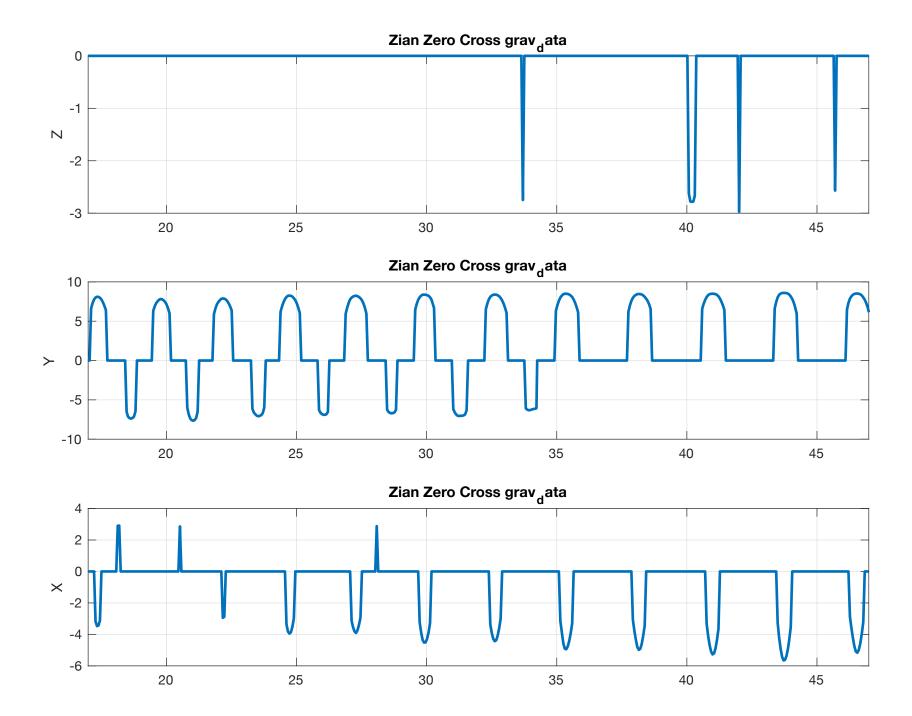
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-48.000	-39.000	-4.000	-7.500	"bar_data"
"Pressure"	-53.000	-39.000	-3.000	-7.500	"bar_data"



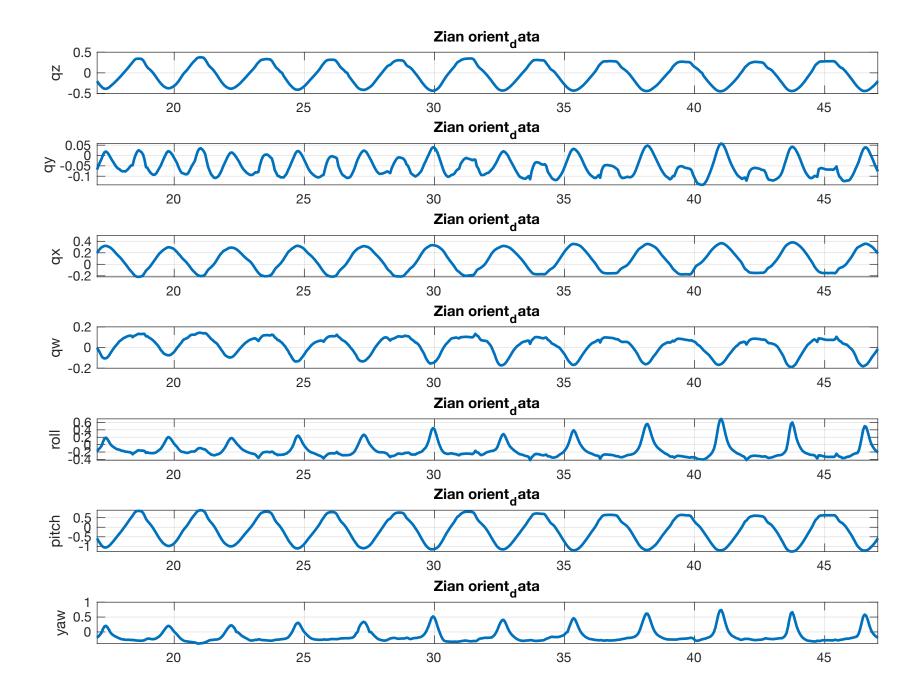


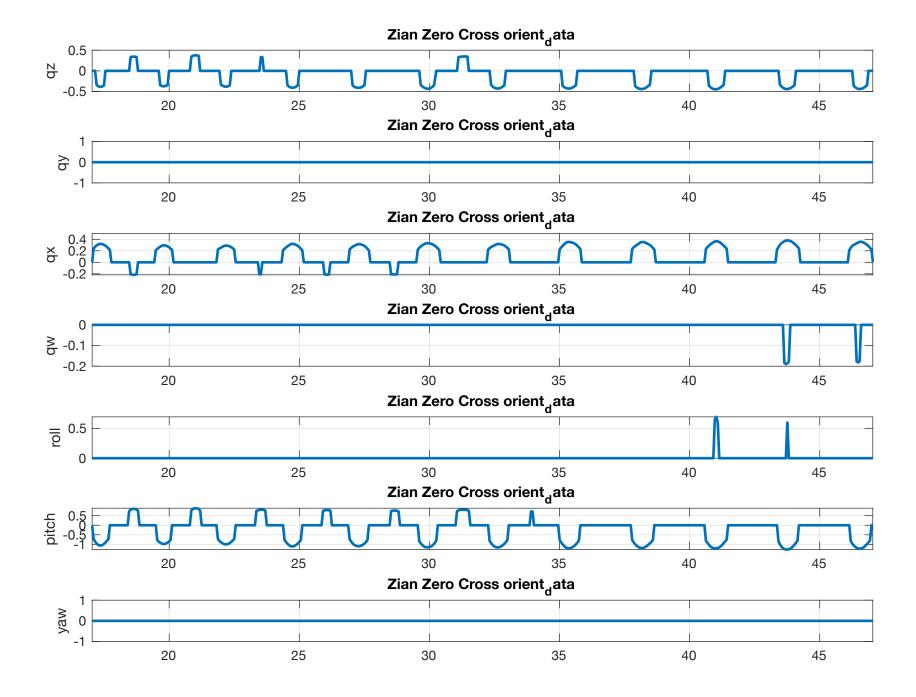
A	xis findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'	Z' -200.000	-132.000	-25.000	-11.500	"gyro_data"
IN	Y' -334.000	-257.000	-85.000	-16.000	"gyro_data"
ľ	X' -242.000	-151.000	-39.000	-23.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-92.000	-19.000	-4.000	10.500	"grav_data"
'Y'	-31.000	0.000	10.000	4.000	"grav_data"
'X'	-73.000	-72.000	-6.000	7.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-39.000	-38.000	1.000	5.000	"orient_data"
'qy'	-95.000	-30.000	-5.000	18.000	"orient_data"
'qx'	-38.000	-1.000	7.000	3.500	"orient_data"
'qw'	-87.000	-85.000	-7.000	14.500	"orient_data"
'roll'	-102.000	-16.000	-4.000	18.000	"orient_data"
'pitch'	-33.000	-33.000	7.000	3.500	"orient_data"
'yaw'	-95.000	-6.000	-1.000	19.500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'zero_cross'	27.500
'bar_data'	"Pressure"	'double_findpeaks'	3.000
'gyro_data'	"Z"	'zero_cross'	11.500
'grav_data'	"Y"	'findpeaks_above_zero'	0.000
'orient_data'	"qx"	'findpeaks_above_zero'	1.000