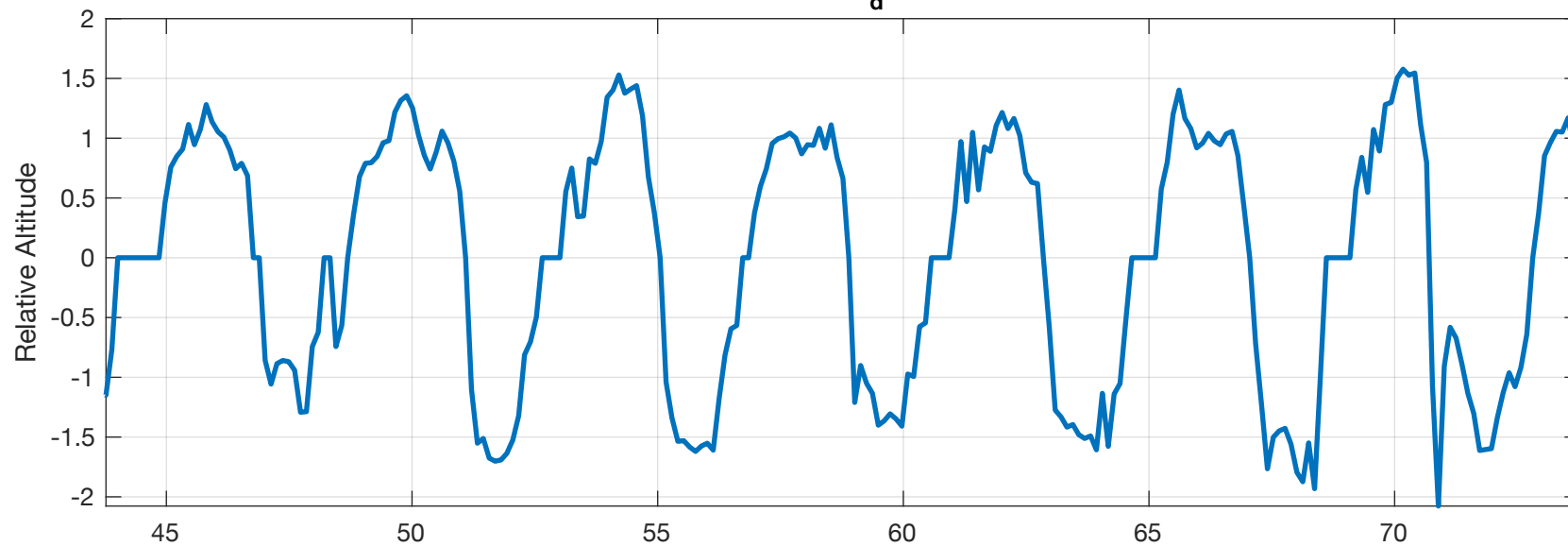
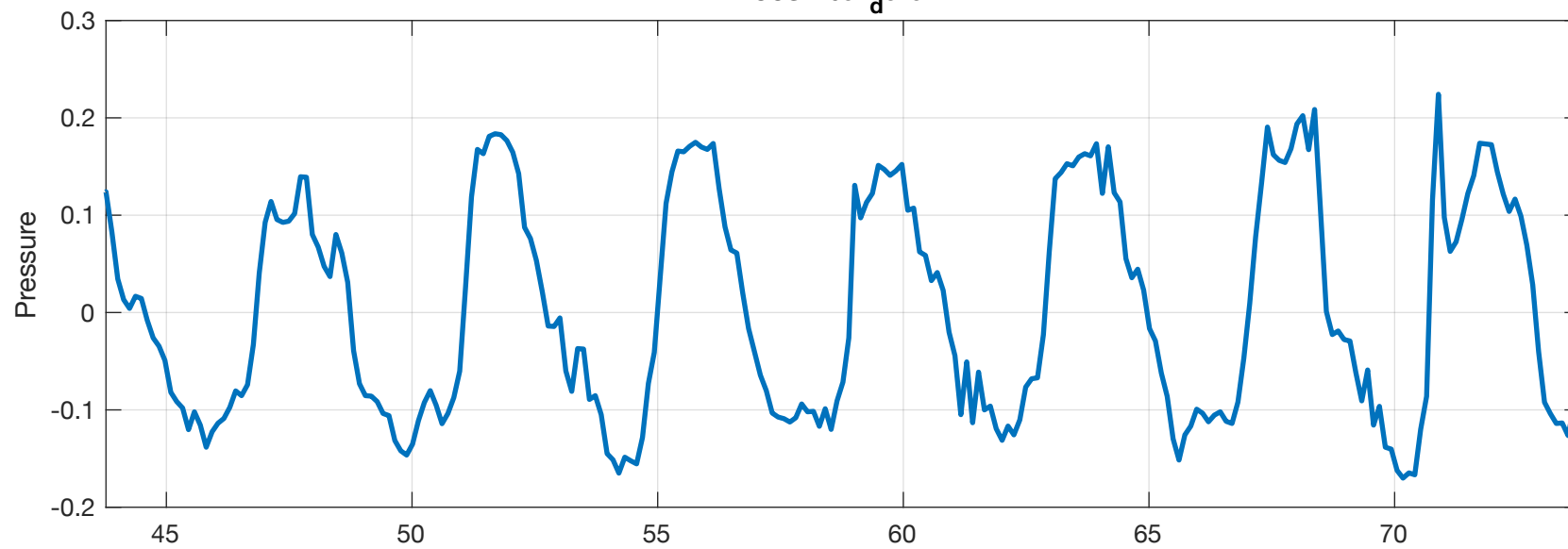


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-232.000	-208.000	-67.000	-67.500	"accel_data"
'Y'	-267.000	-253.000	-75.000	-84.000	"accel_data"
'X'	-274.000	-230.000	-79.000	-71.500	"accel_data"

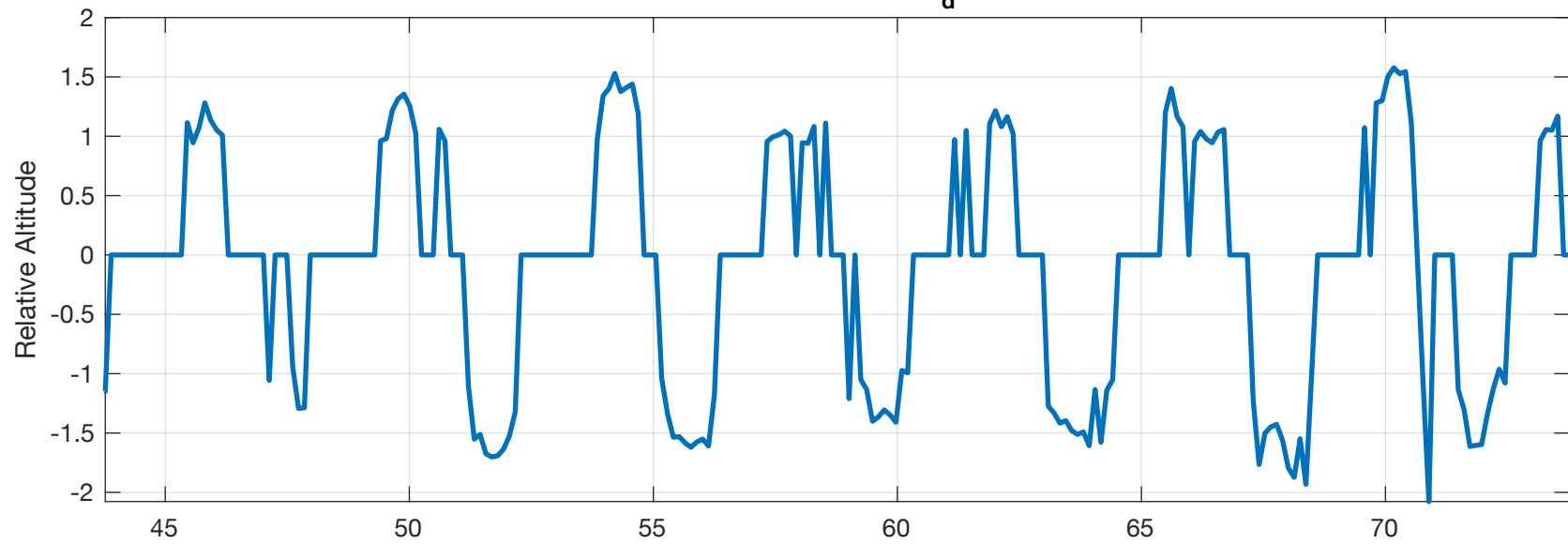
Josh bar_data



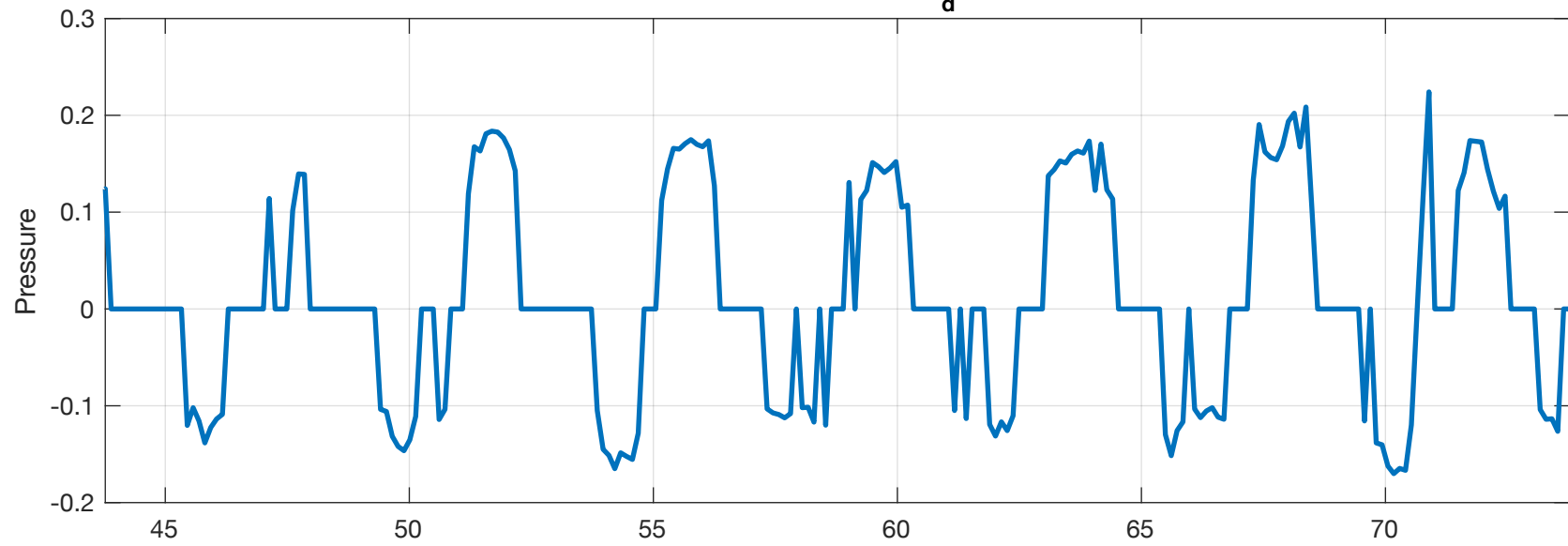
Josh bar_data



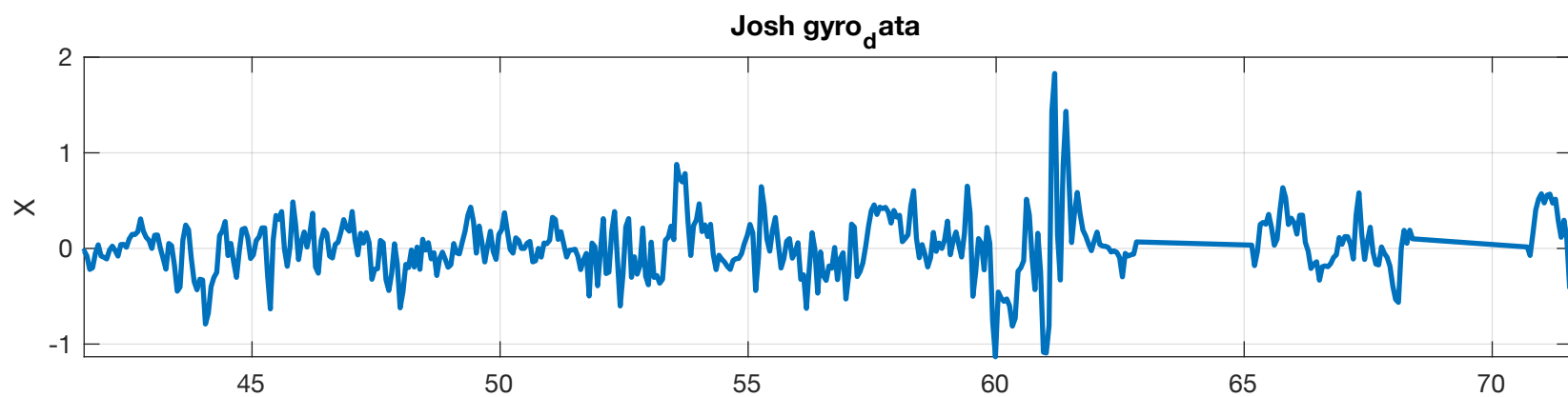
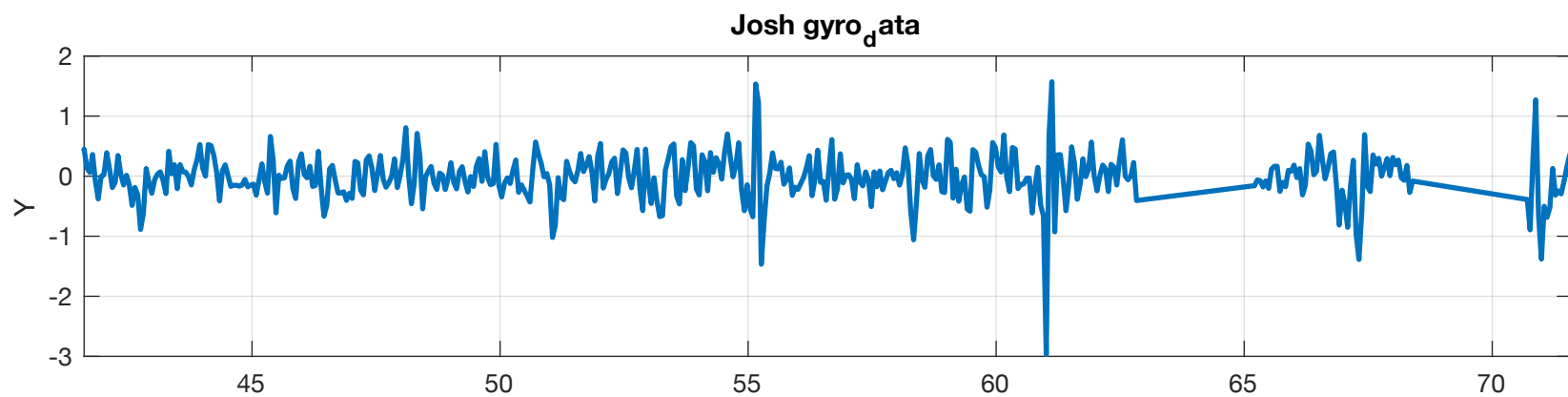
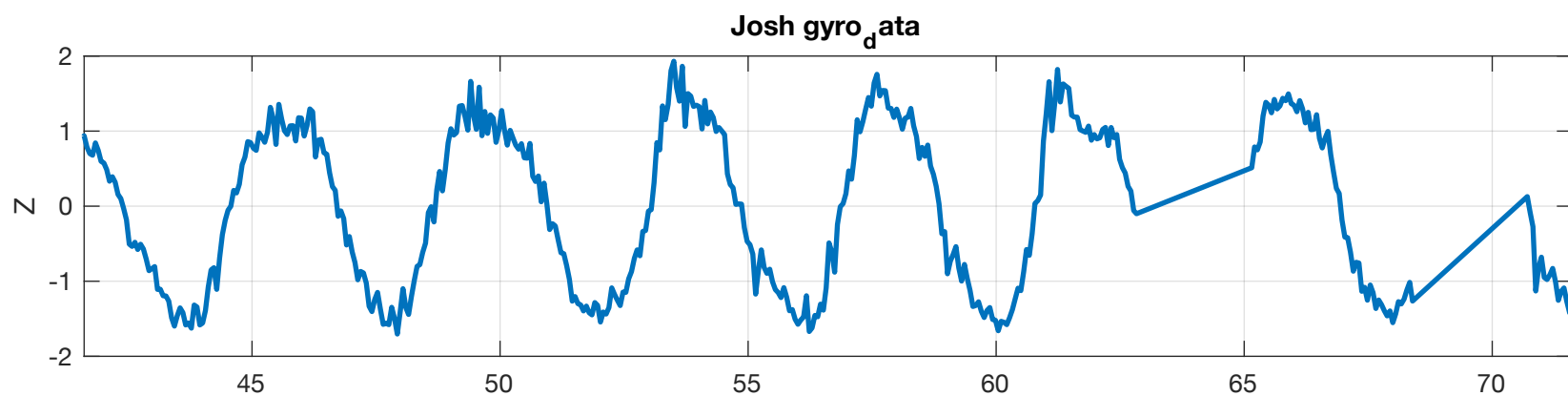
Josh Zero Cross bar_data

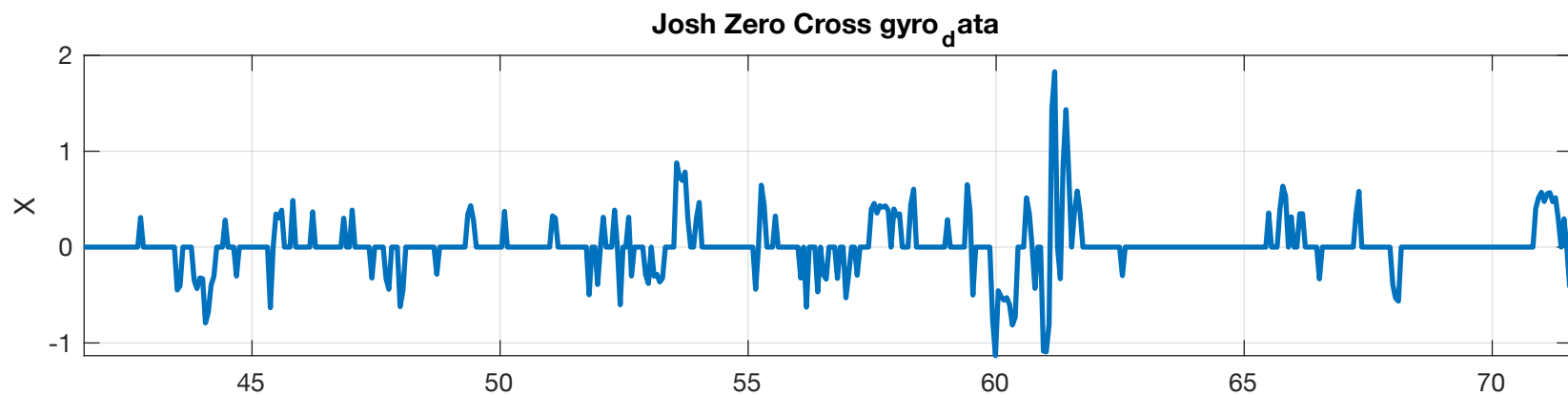
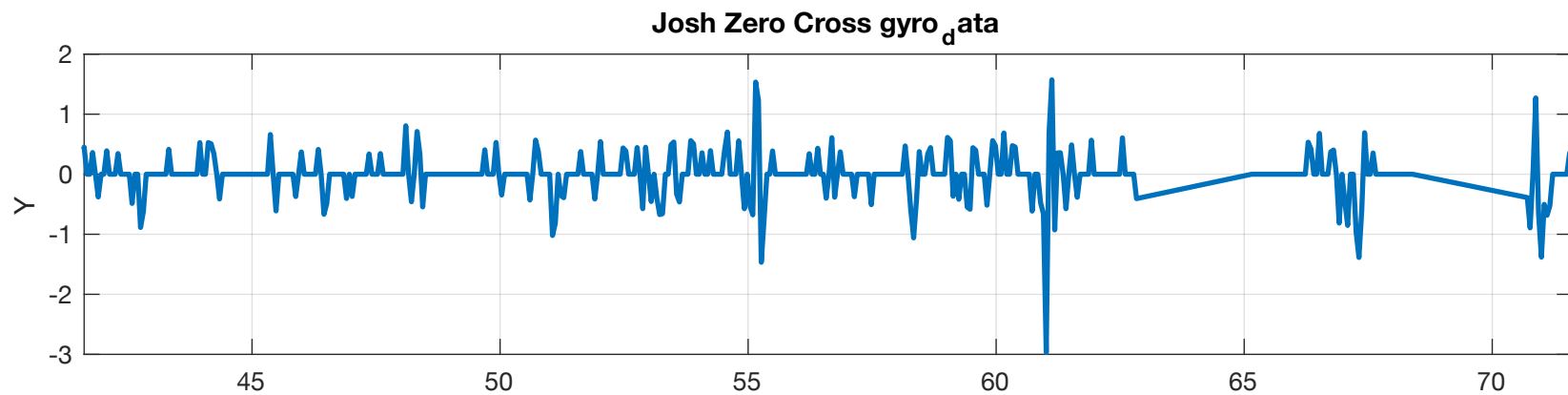
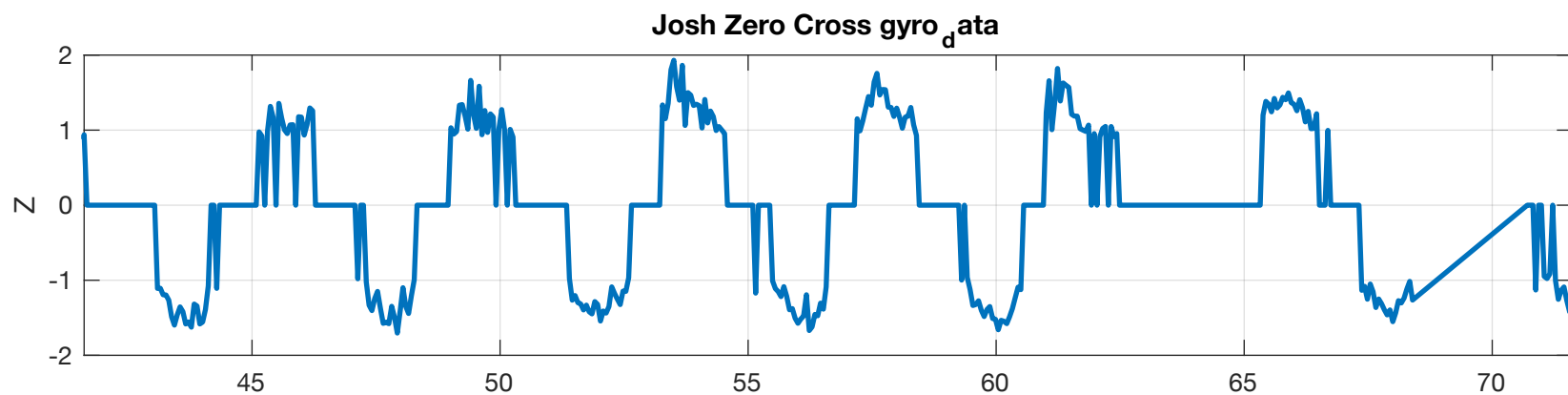


Josh Zero Cross bar_data

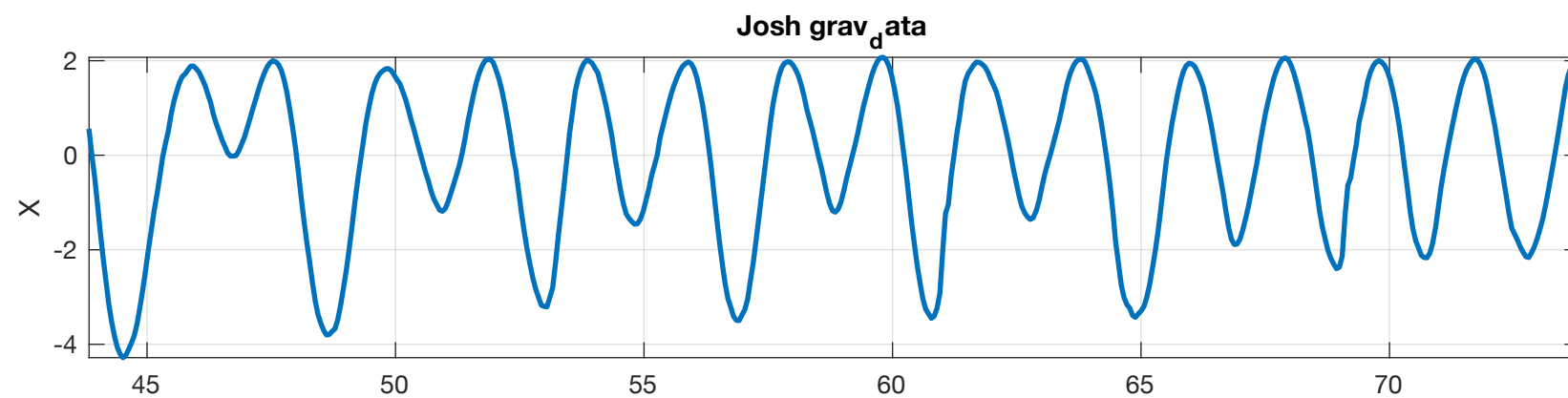
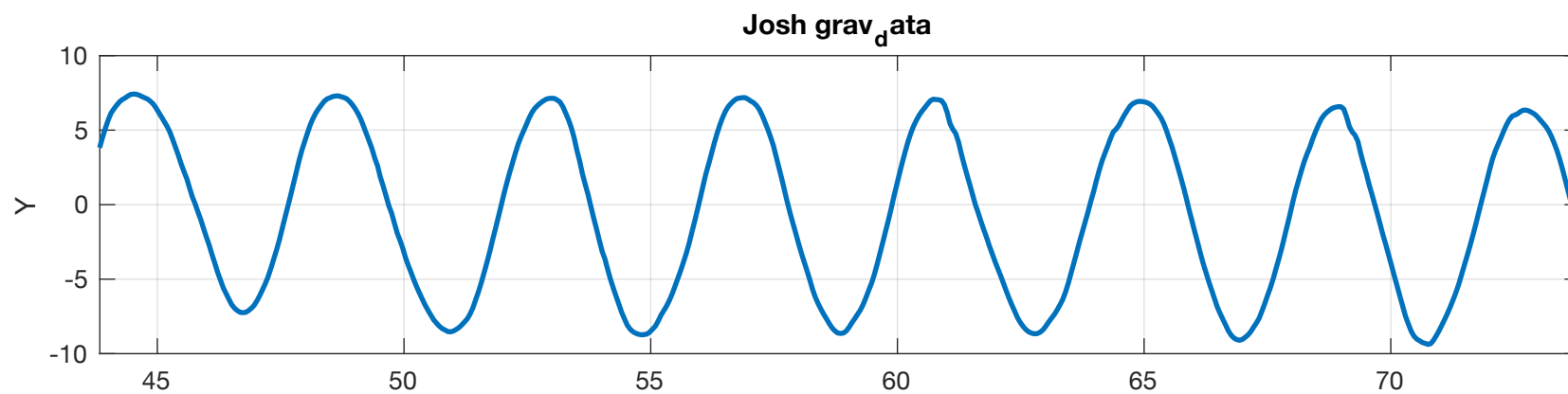
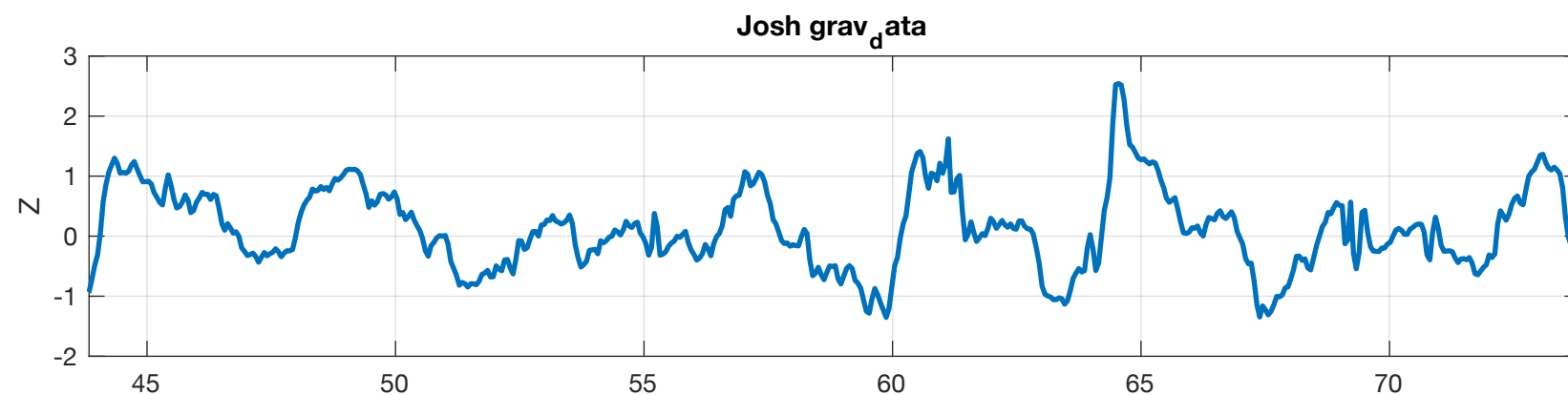


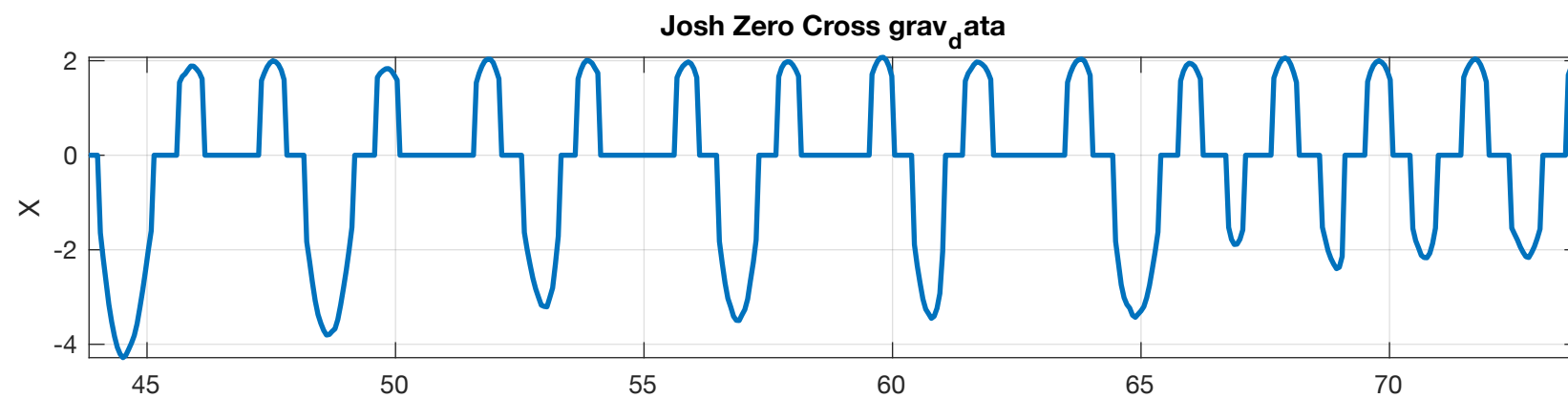
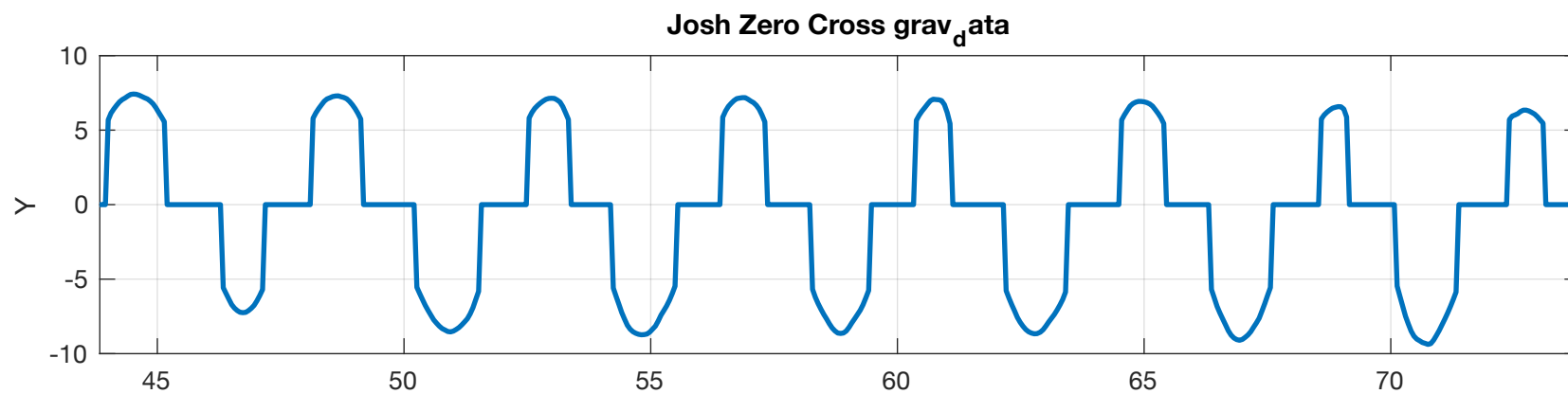
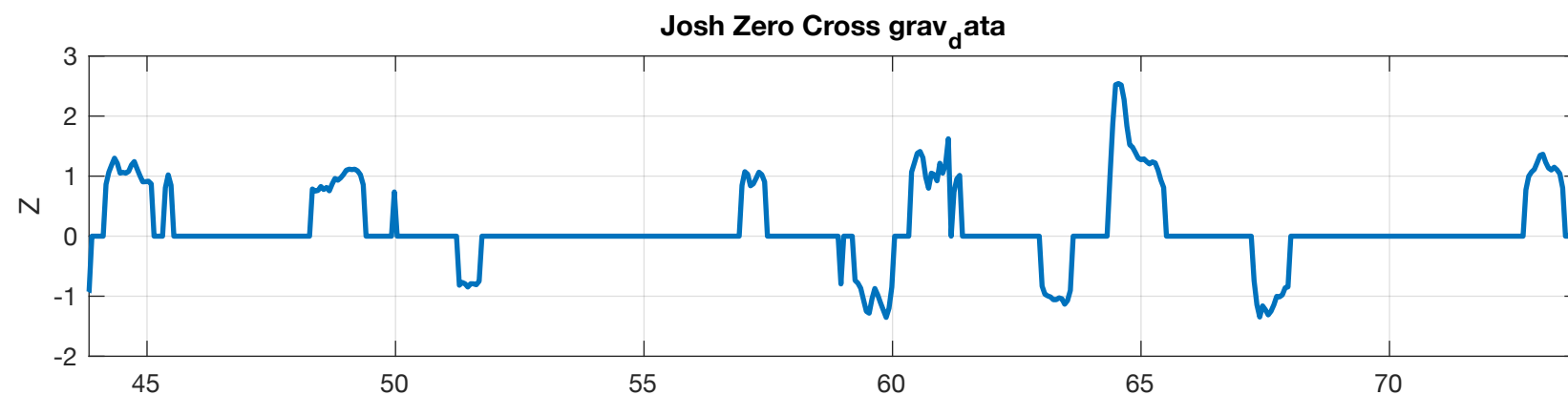
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-53.000	-32.000	-6.000	-7.500	"bar_data"
"Pressure"	-73.000	-30.000	-4.000	-7.500	"bar_data"



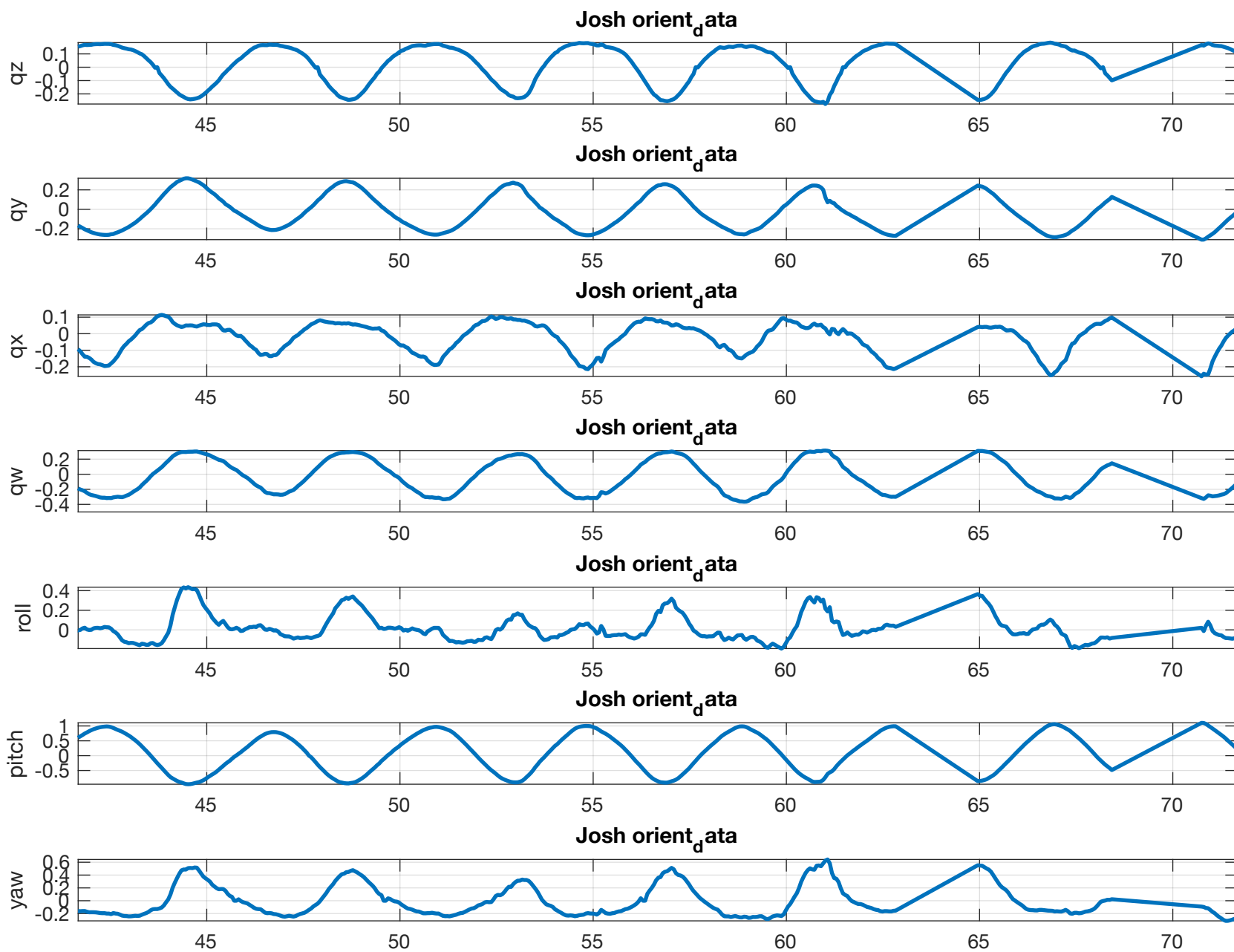


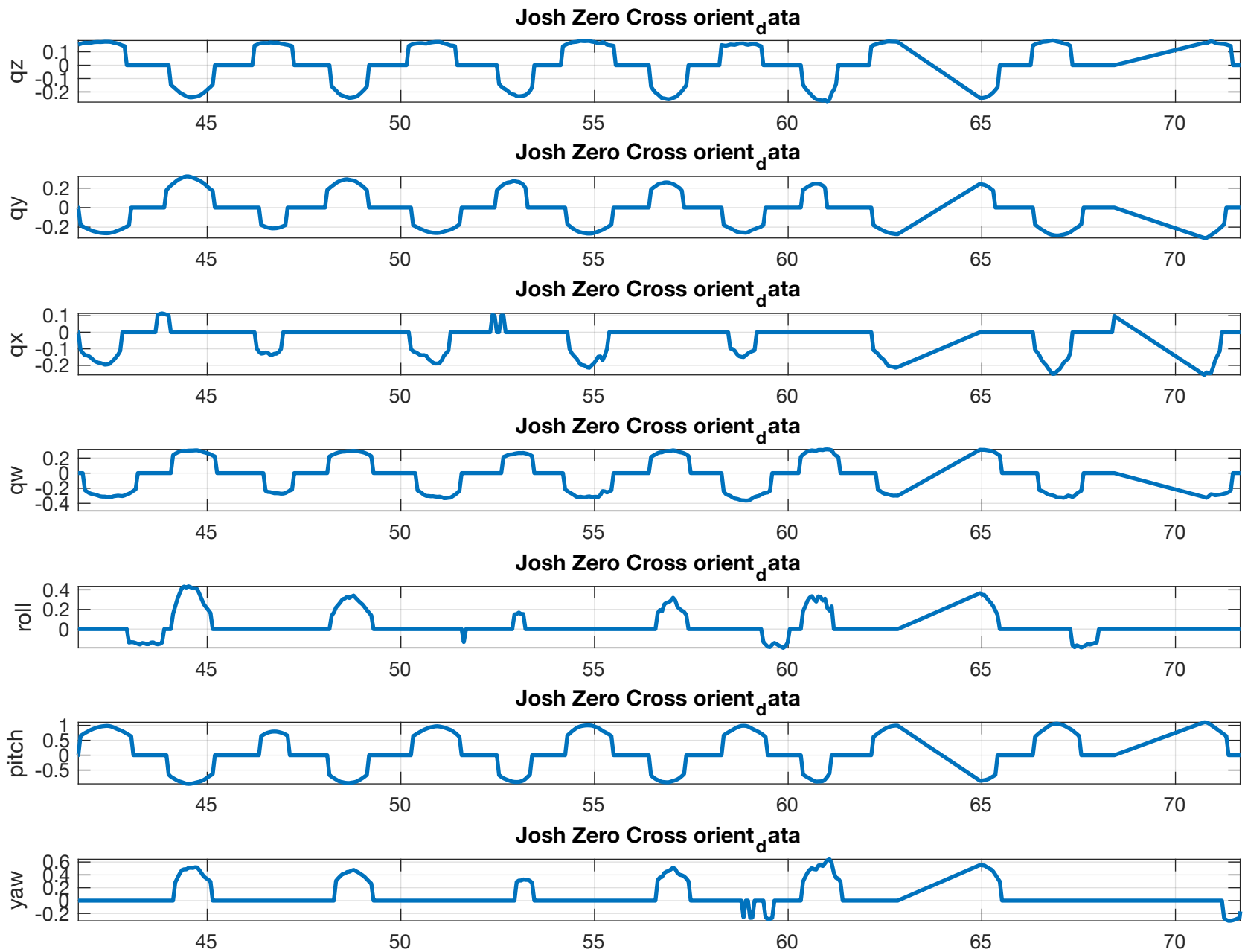
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-181.000	-95.000	-19.000	-9.500	"gyro_data"
'Y'	-206.000	-172.000	-57.000	-52.250	"gyro_data"
'X'	-181.000	-141.000	-39.000	-34.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-152.000	-87.000	-23.000	-4.250	"grav_data"
'Y'	-19.000	-18.000	5.000	0.500	"grav_data"
'X'	-29.000	-10.000	1.000	-7.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-47.000	-22.000	1.000	0.500	"orient_data"
'qy'	-16.000	-16.000	4.000	0.500	"orient_data"
'qx'	-70.000	-63.000	-7.000	0.000	"orient_data"
'qw'	-40.000	-19.000	-2.000	-0.250	"orient_data"
'roll'	-117.000	-57.000	-14.000	0.750	"orient_data"
'pitch'	-11.000	-1.000	7.000	1.000	"orient_data"
'yaw'	-66.000	-32.000	-3.000	3.250	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'double_findpeaks'	67.000
'bar_data'	"Pressure"	'double_findpeaks'	4.000
'gyro_data'	"Z"	'zero_cross'	9.500
'grav_data'	"Y"	'zero_cross'	0.500
'orient_data'	"qx"	'zero_cross'	0.000