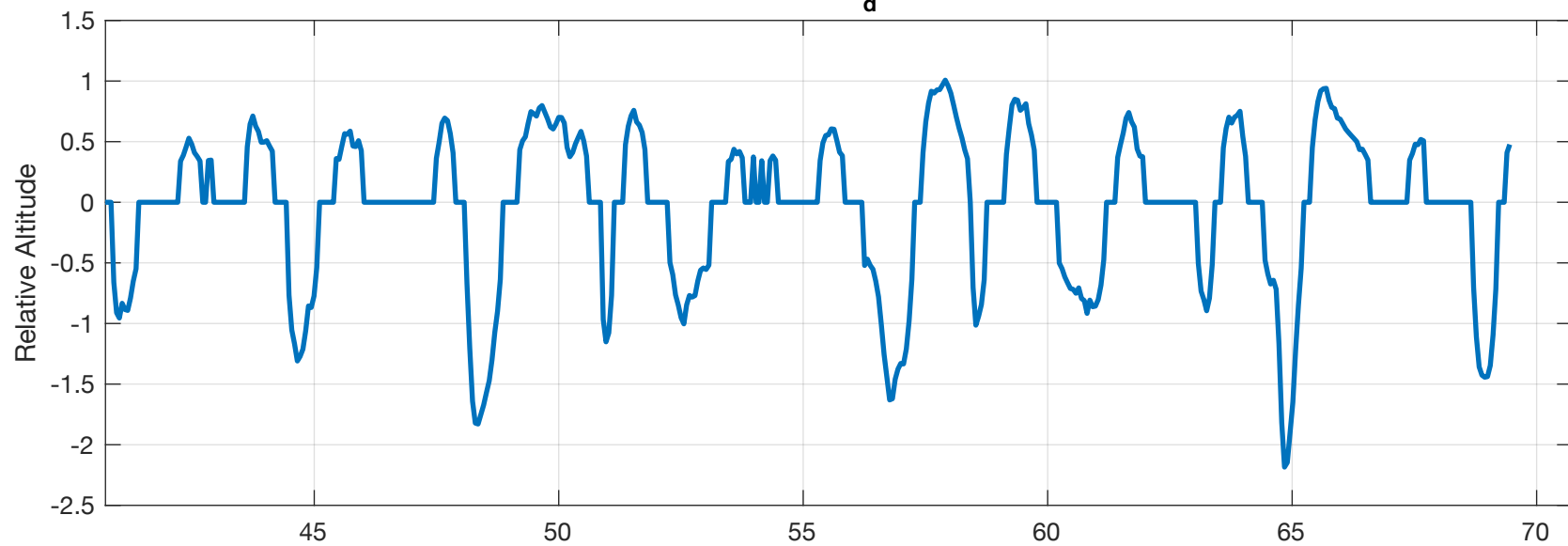
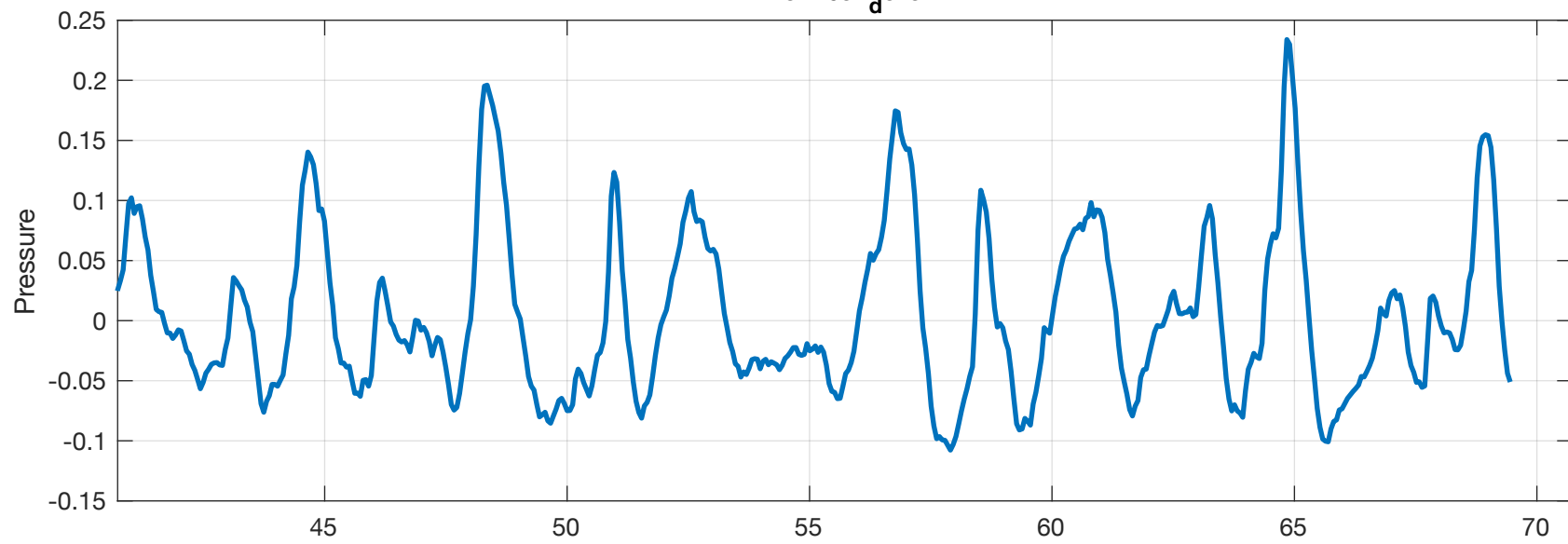


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-183.000	-86.000	-27.000	-32.500	"accel_data"
'Y'	-177.000	-135.000	-45.000	-22.500	"accel_data"
'X'	-180.000	-134.000	-40.000	-25.000	"accel_data"

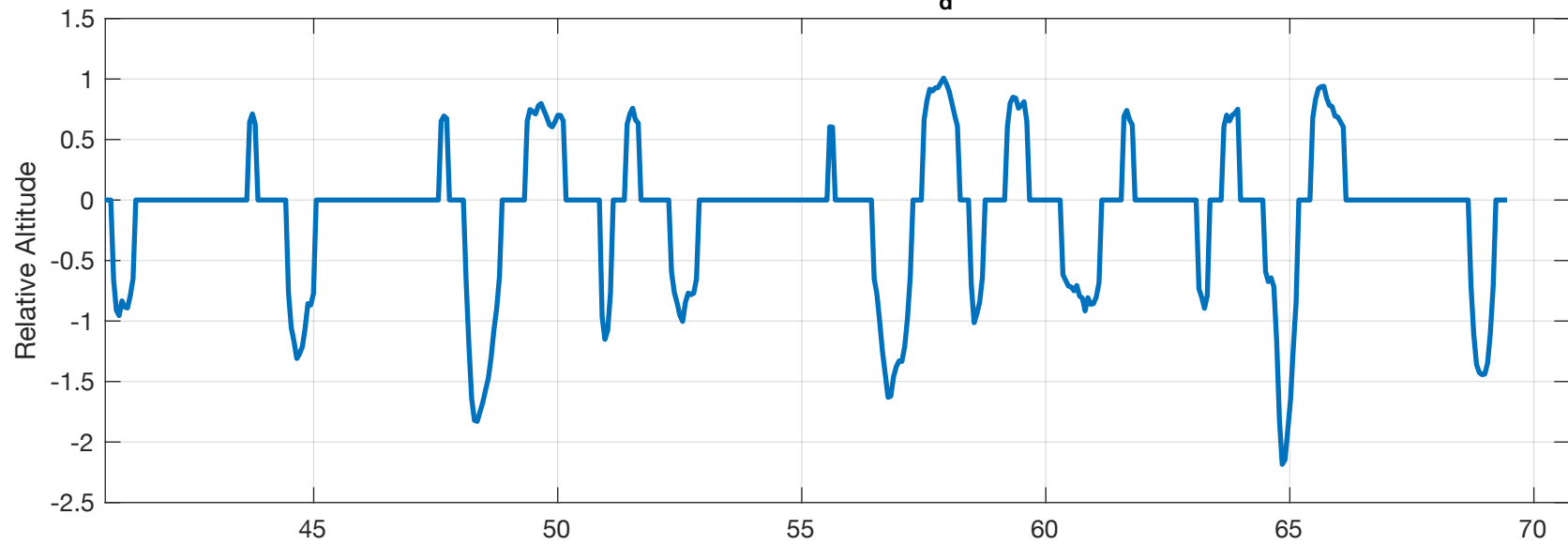
Zian bar_data



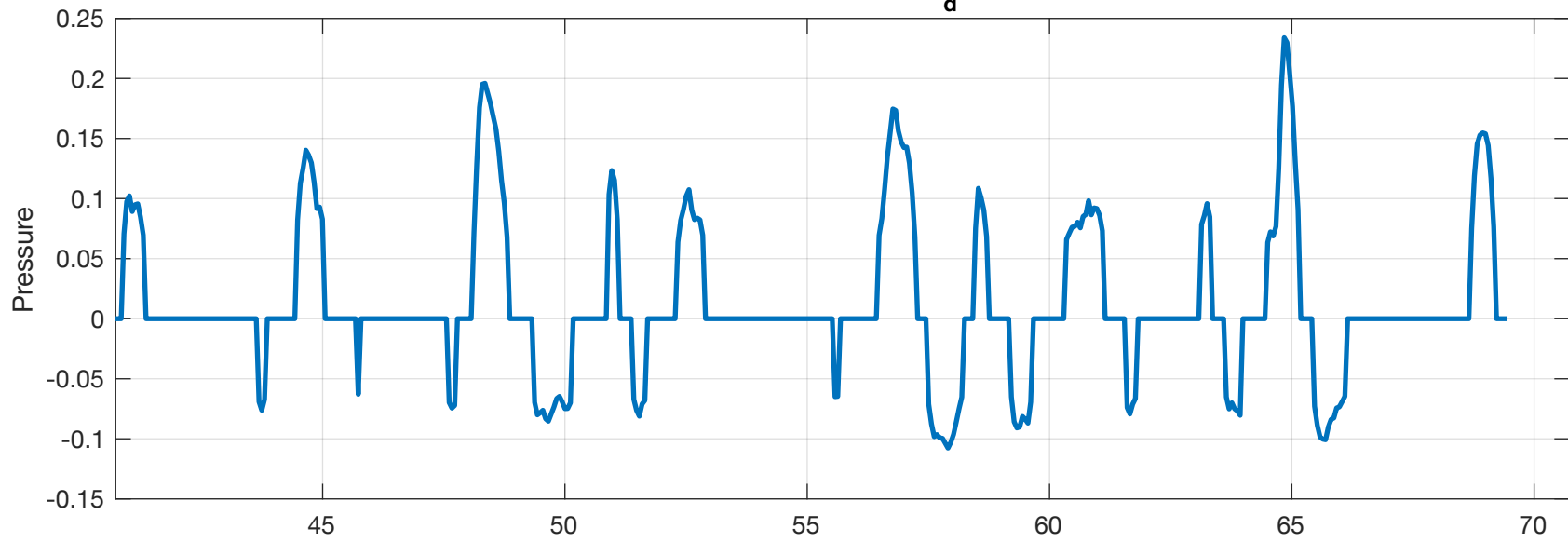
Zian bar_data



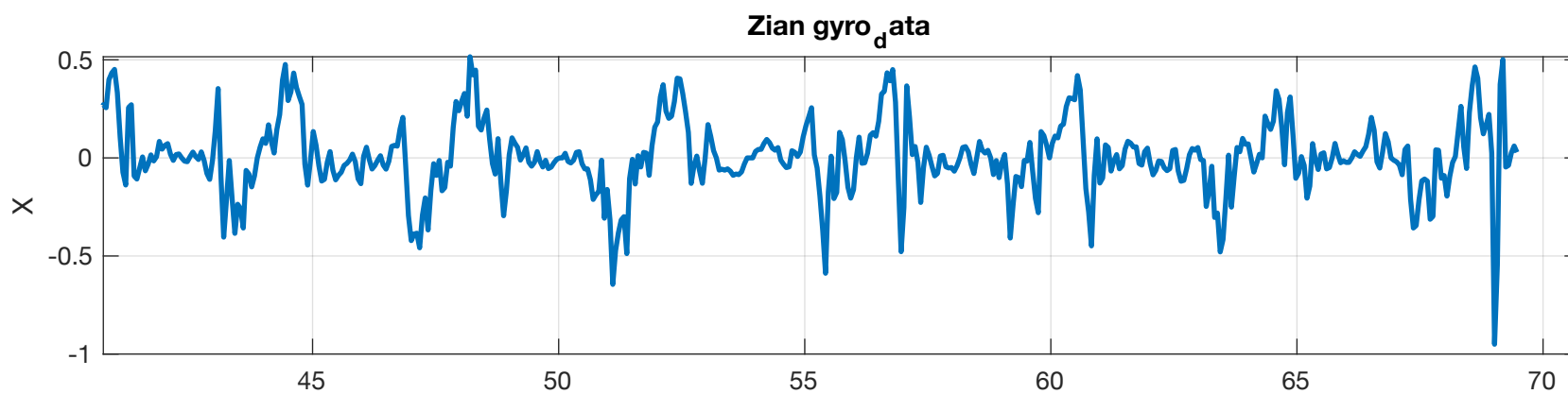
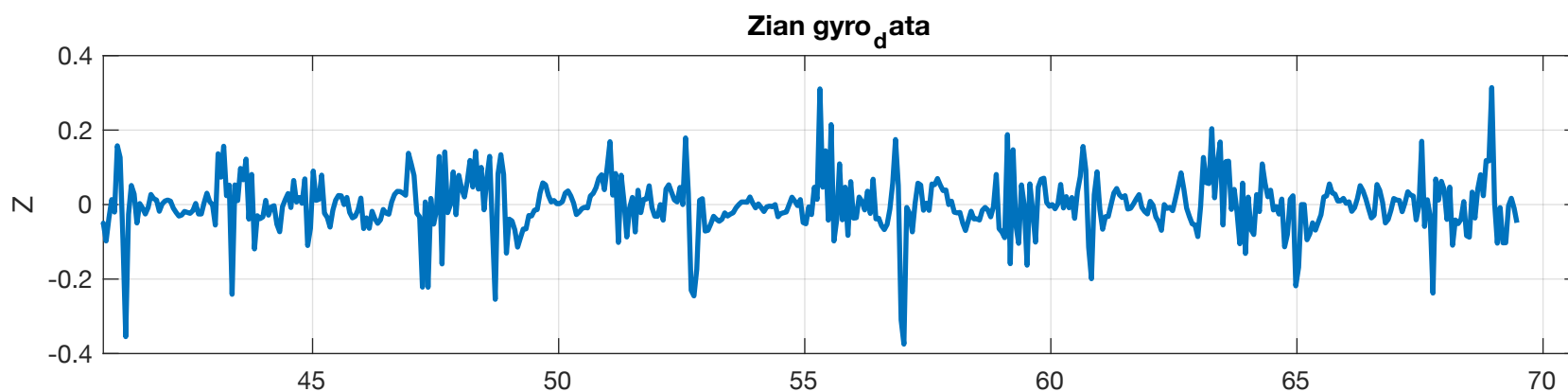
Zian Zero Cross bar_data

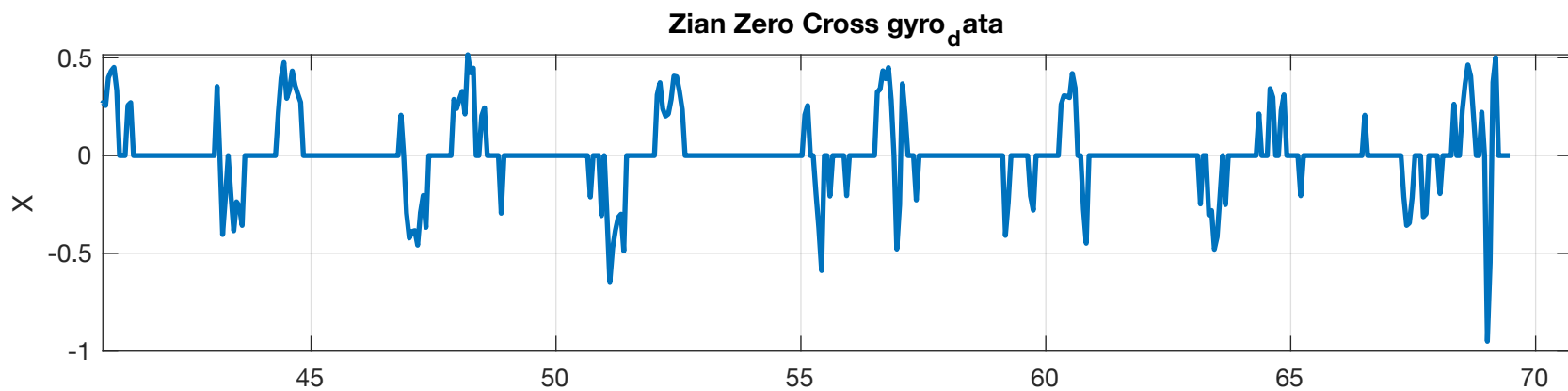
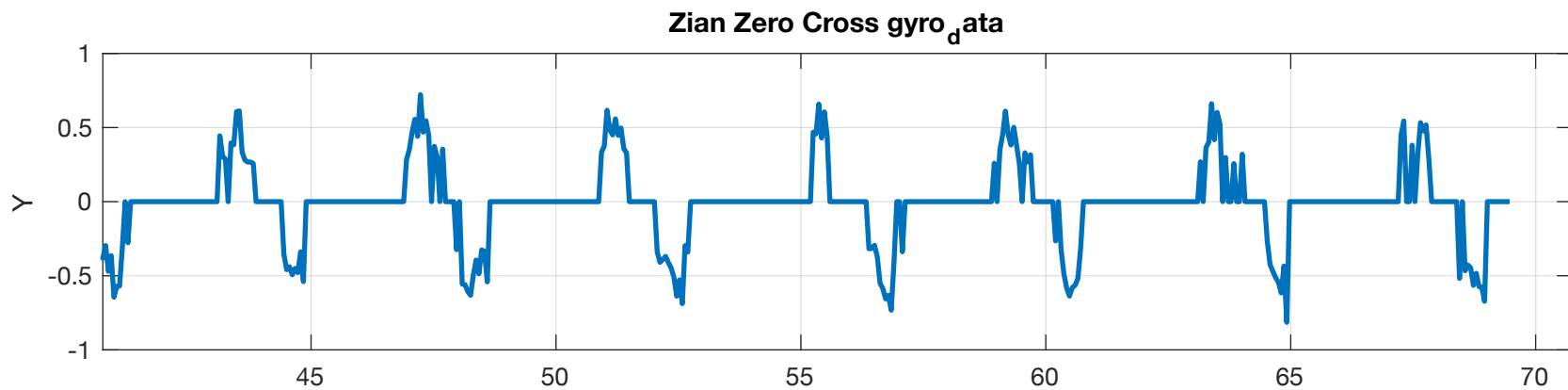
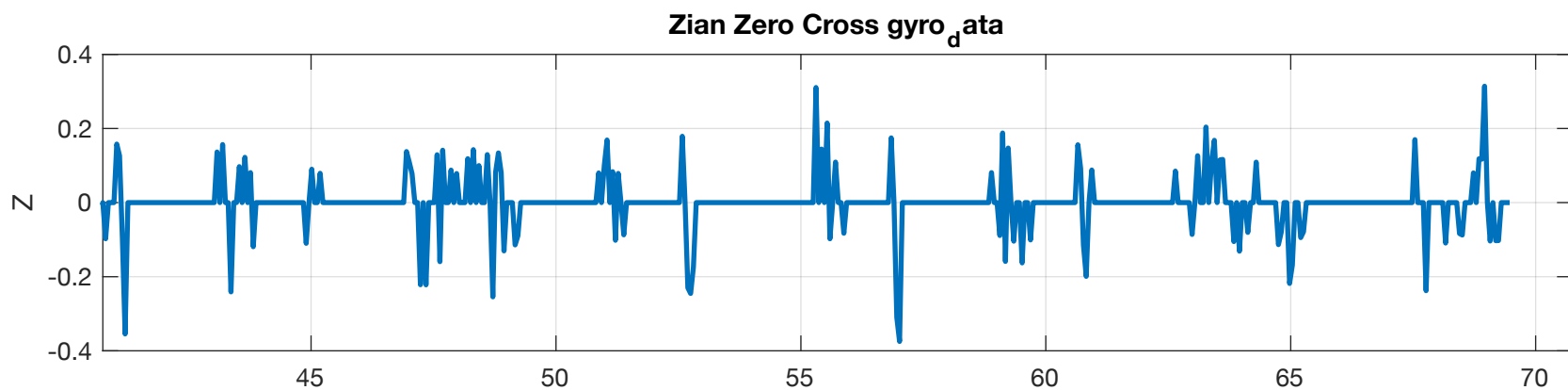


Zian Zero Cross bar_data

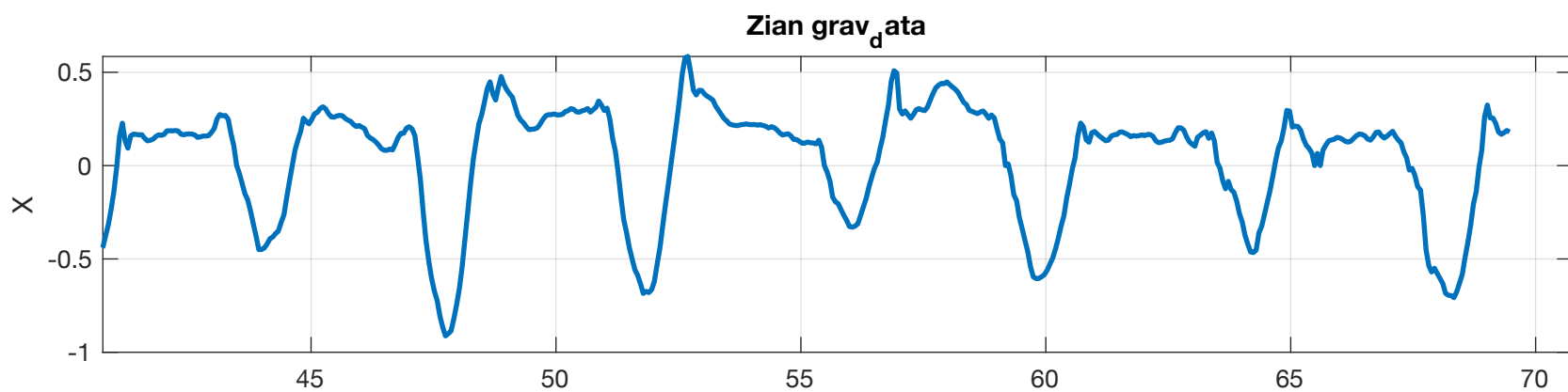
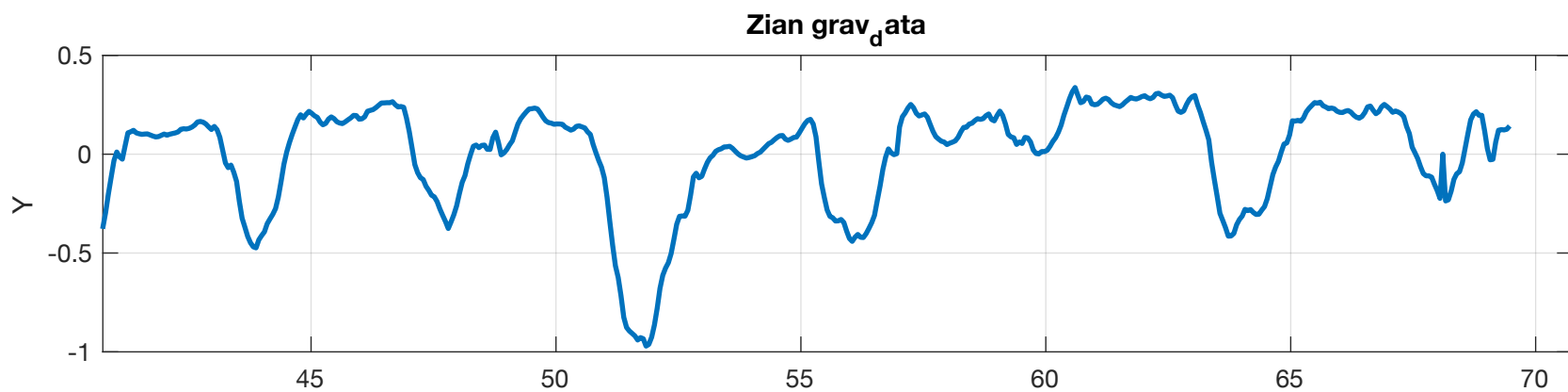
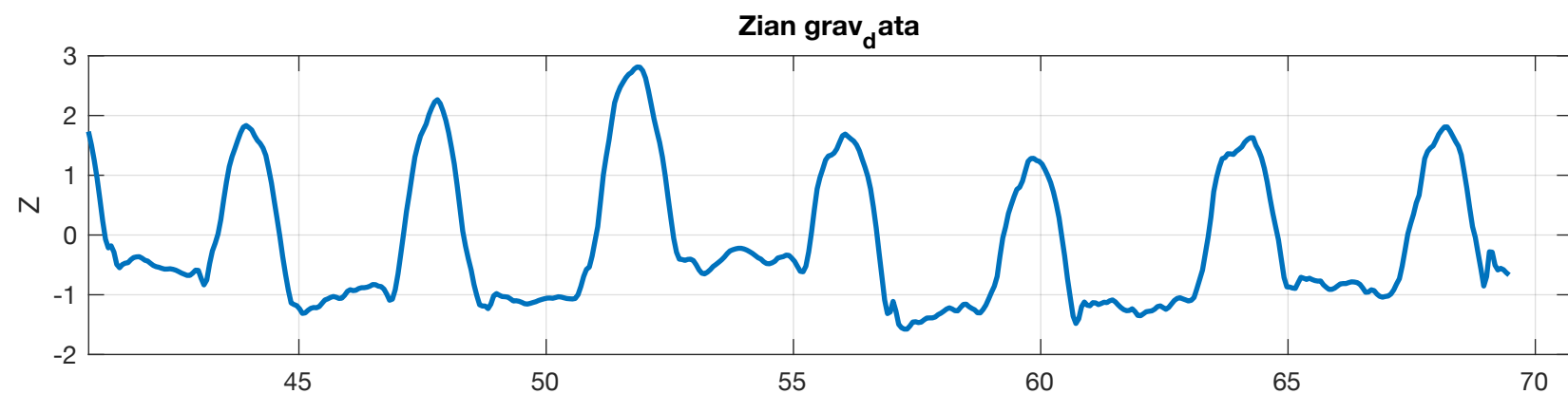


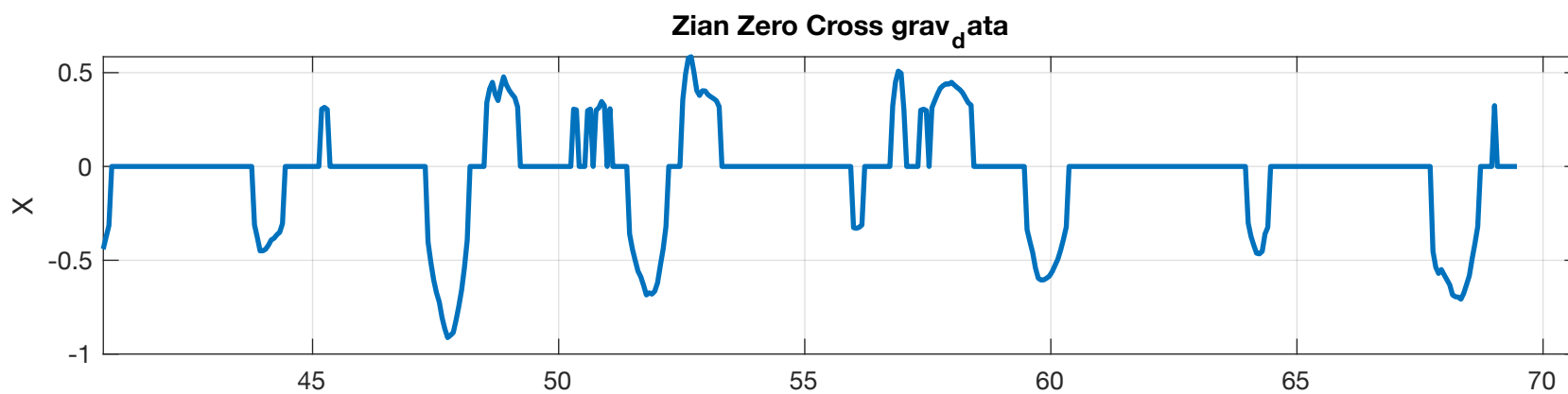
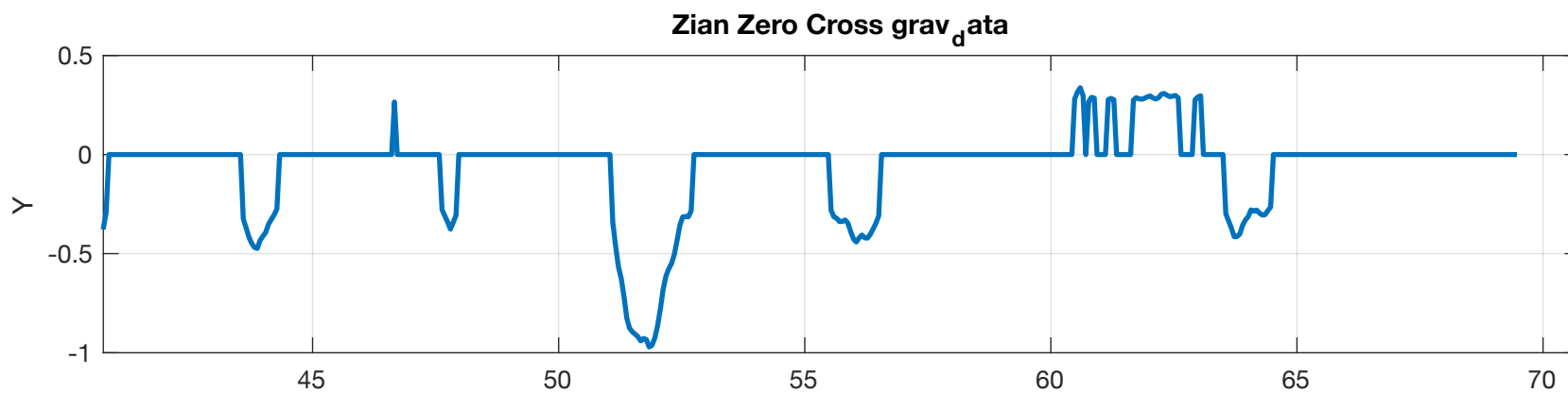
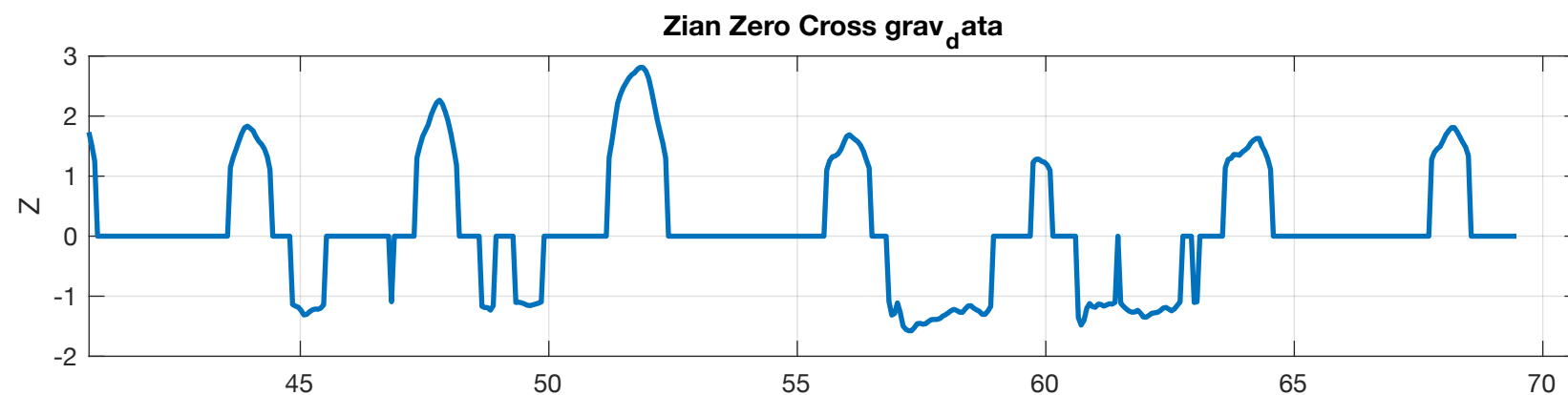
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-39.000	-29.000	-2.000	-2.000	"bar_data"
"Pressure"	-65.000	-30.000	-8.000	-2.500	"bar_data"



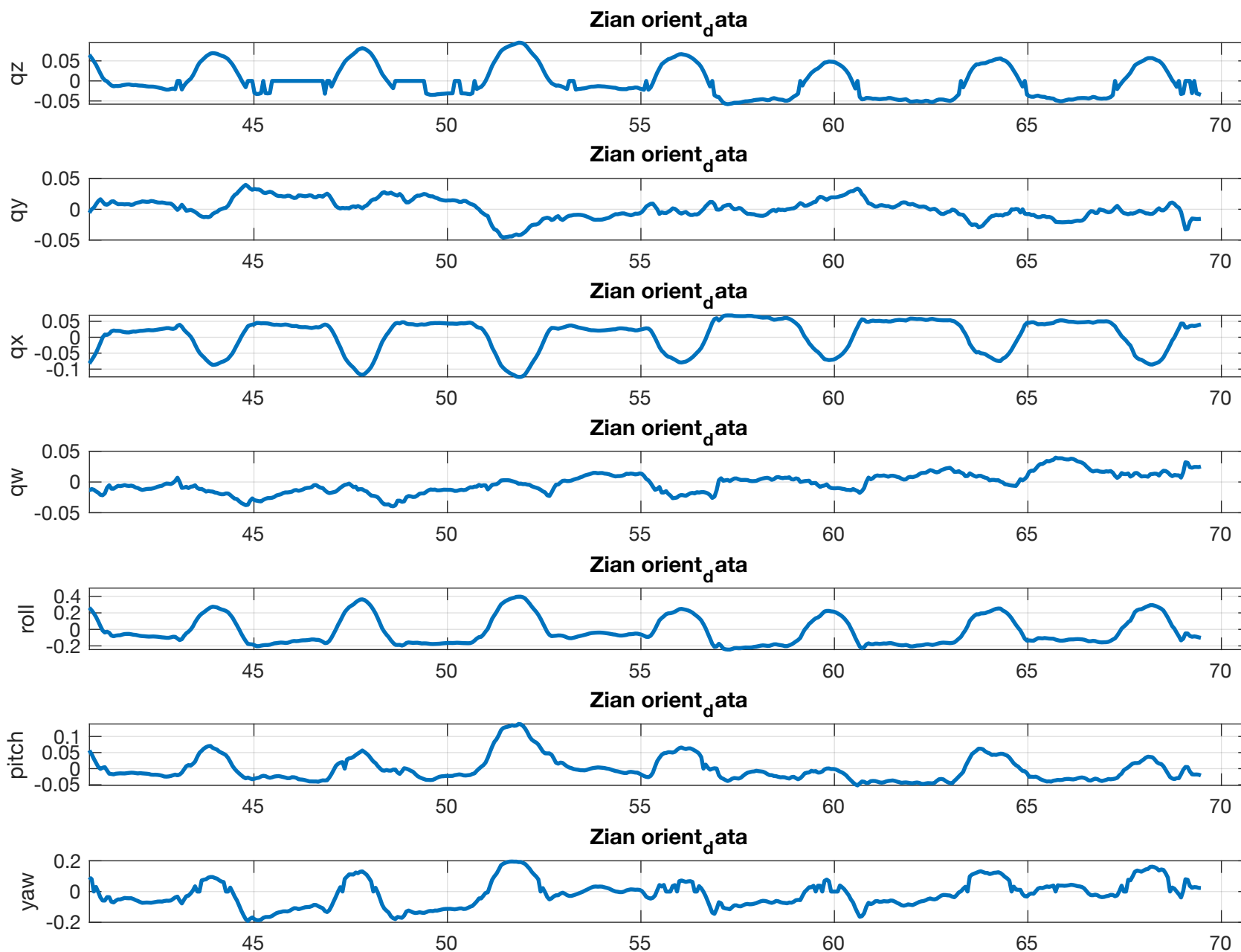


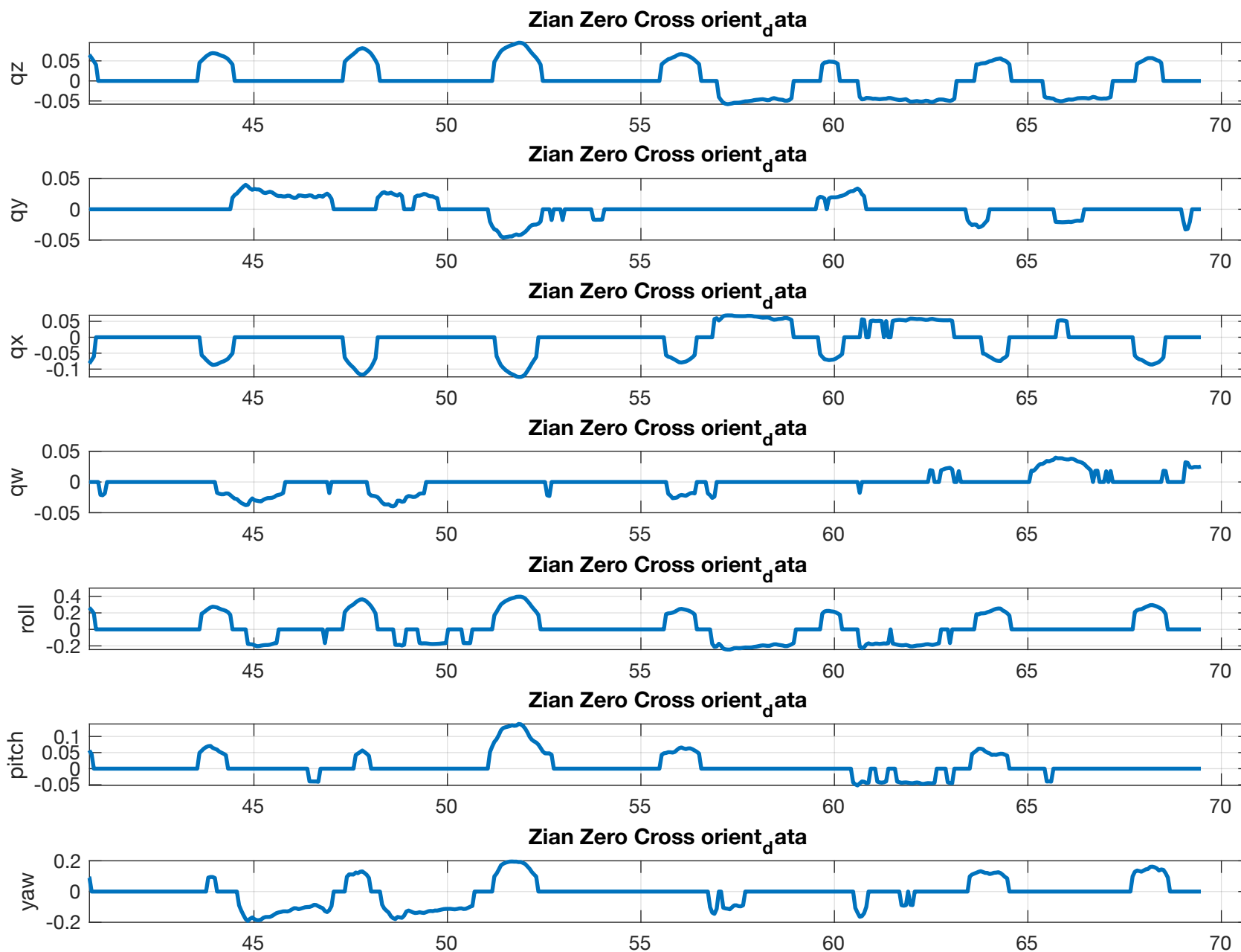
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-193.000	-147.000	-45.000	-38.000	"gyro_data"
'Y'	-169.000	-114.000	-29.000	-8.500	"gyro_data"
'X'	-147.000	-109.000	-26.000	-17.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-42.000	1.000	2.000	3.000	"grav_data"
'Y'	-66.000	-53.000	-8.000	4.000	"grav_data"
'X'	-64.000	-58.000	-5.000	1.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-51.000	-2.000	1.000	5.500	"orient_data"
'qy'	-92.000	-50.000	-9.000	2.000	"orient_data"
'qx'	-53.000	-51.000	-6.000	4.000	"orient_data"
'qw'	-108.000	-39.000	-4.000	0.750	"orient_data"
'roll'	-45.000	0.000	2.000	2.500	"orient_data"
'pitch'	-66.000	-17.000	-2.000	3.500	"orient_data"
'yaw'	-91.000	-42.000	-3.000	1.500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Y"	'zero_cross'	22.500
'bar_data'	"Relative Altitude"	'double_findpeaks'	2.000
'gyro_data'	"Y"	'zero_cross'	8.500
'grav_data'	"Z"	'findpeaks_above_zero'	1.000
'orient_data'	"roll"	'findpeaks_above_zero'	0.000