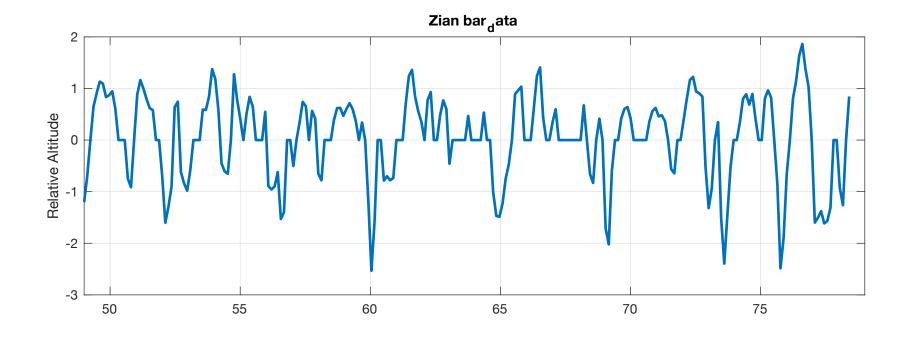
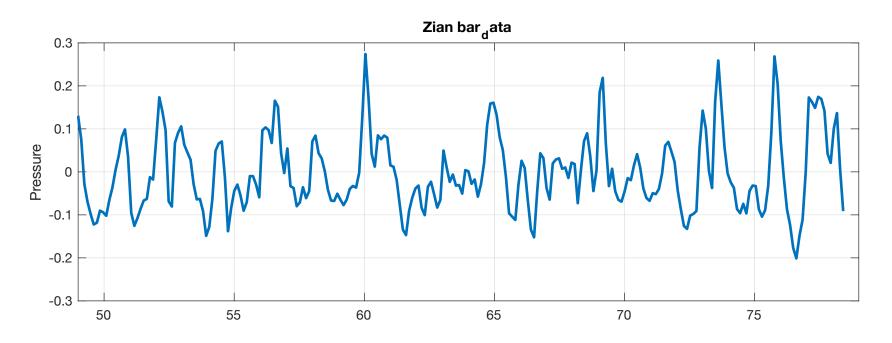
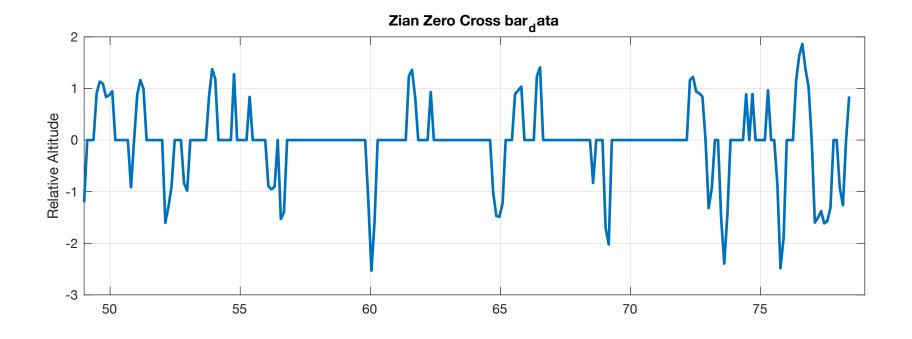
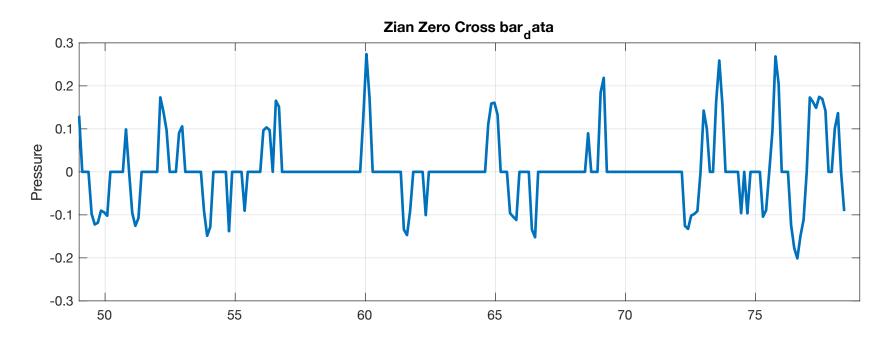


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-192.000	-152.000	-48.000	-63.000	"accel_data"
'Y'	-226.000	-205.000	-63.000	-48.500	"accel_data"
'X'	-197.000	-173.000	-58.000	-41.500	"accel_data"

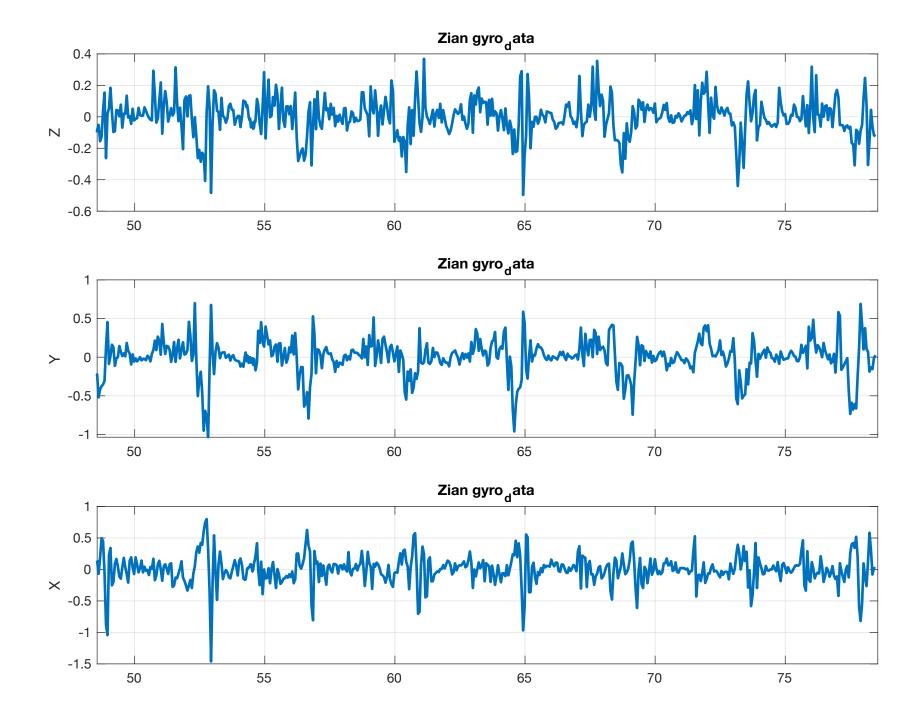


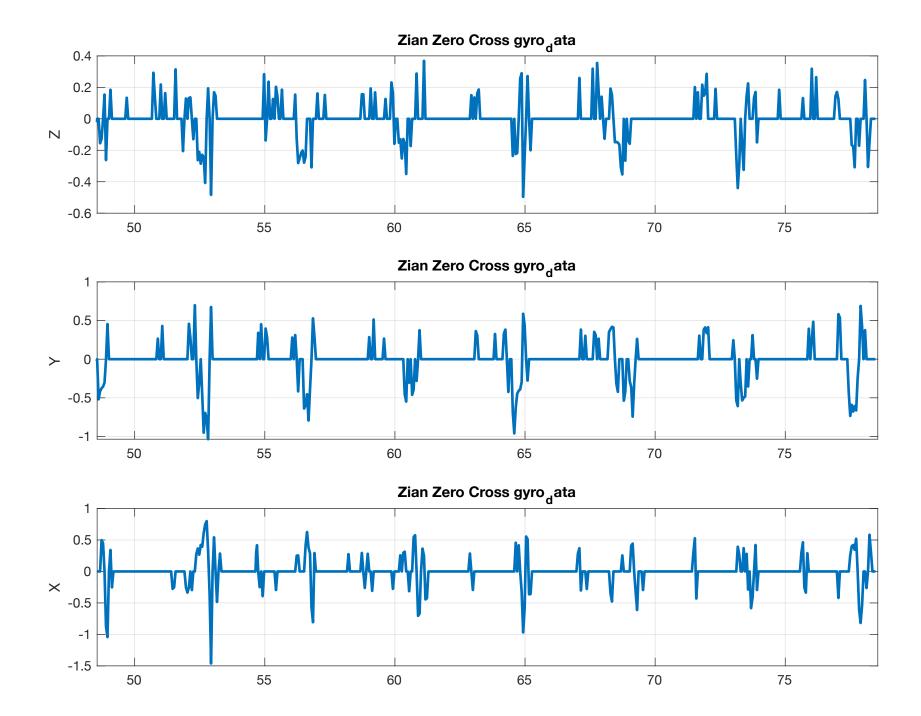




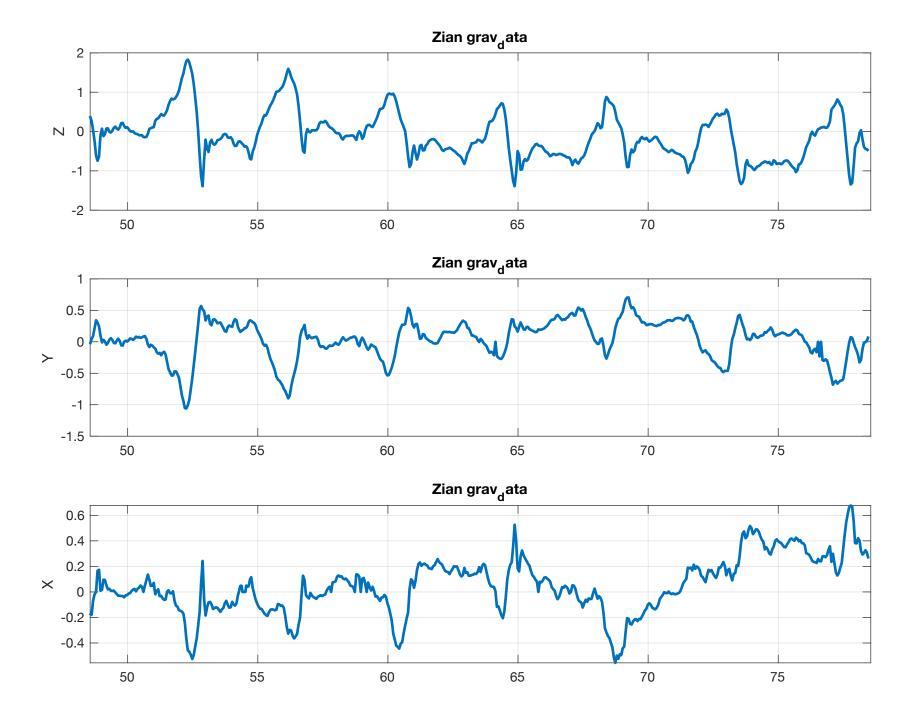


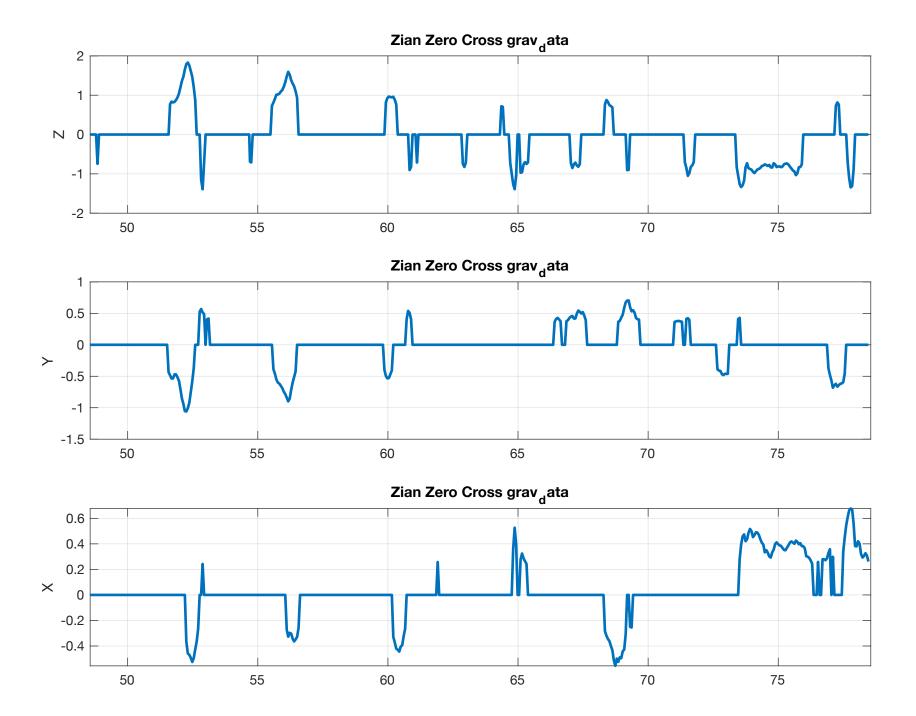
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-43.000	-32.000	-5.000	-8.750	"bar_data"
"Pressure"	-54.000	-31.000	-8.000	-8.750	"bar_data"



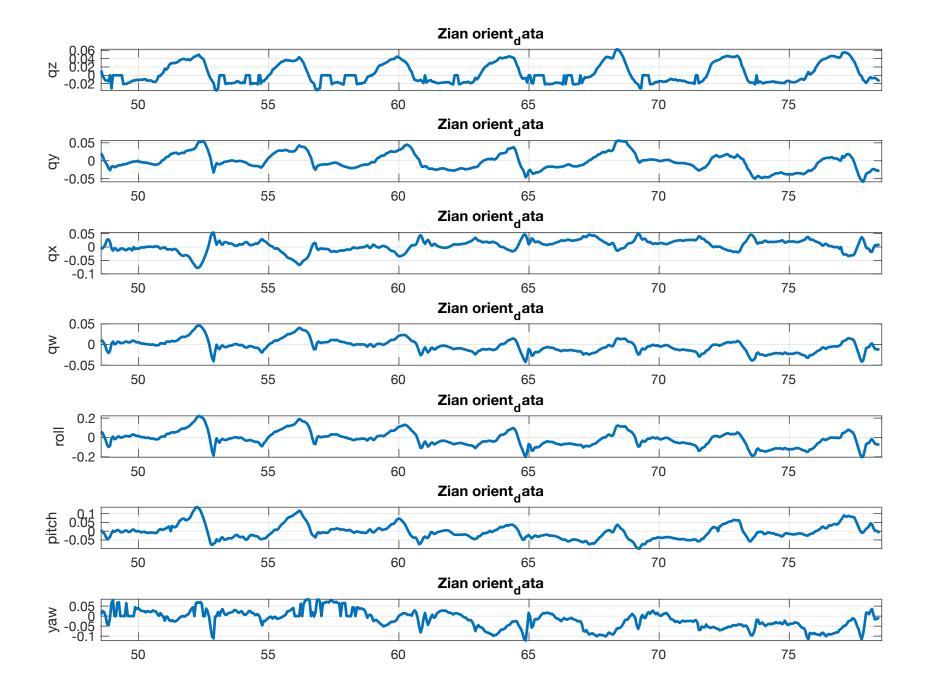


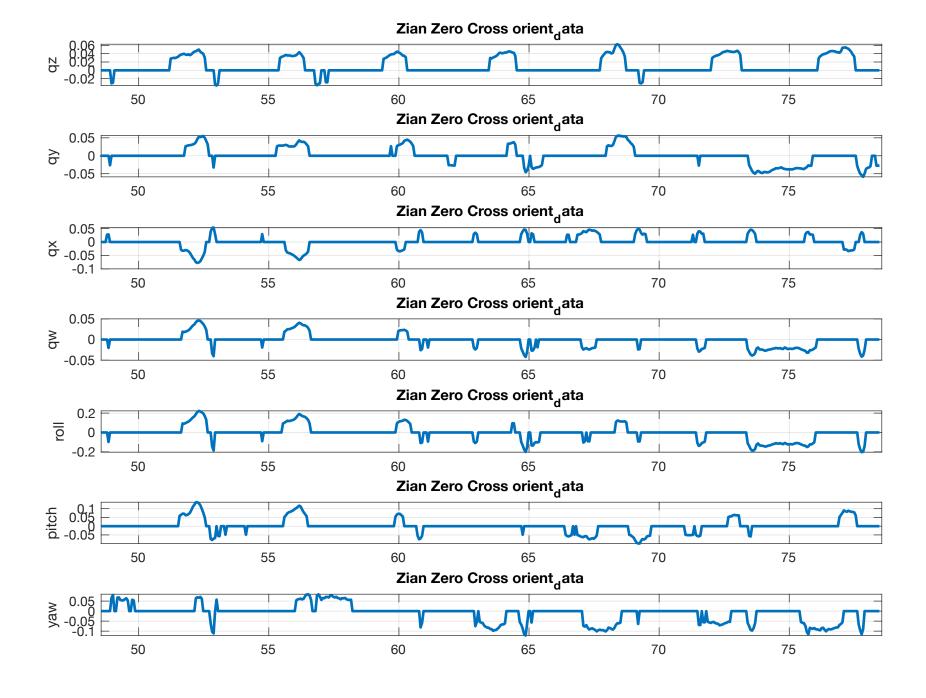
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
 'Z'	-190.000	-155.000	-45.000	-47.500	"gyro_data"
'Y'	-194.000	-152.000	-45.000	-31.000	"gyro_data"
'X'	-181.000	-145.000	-43.000	-39.000	"gyro_data"





'Y' -88.000 -67.000 -14.000 0.500 "grav_dat	Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
3 · = · · ·	'Z'	-73.000	-28.000	-3.000	-2.500	"grav_data"
	'Υ'	-88.000	-67.000	-14.000	0.500	"grav_data"
'X' -117.000 -71.000 -18.000 -0.250 "grav_dat	'X'	-117.000	-71.000	-18.000	-0.250	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-103.000	-24.000	-4.000	1.000	"orient_data"
'qy'	-76.000	-38.000	-6.000	-0.250	"orient_data"
'qx'	-96.000	-64.000	-13.000	-2.000	"orient_data"
'qw'	-80.000	-34.000	-3.000	-1.000	"orient_data"
'roll'	-80.000	-31.000	-6.000	-3.000	"orient_data"
'pitch'	-87.000	-36.000	-5.000	-1.500	"orient_data"
'yaw'	-128.000	-71.000	-14.000	-3.000	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'zero_cross'	41.500
'bar_data'	"Relative Altitude"	'double_findpeaks'	5.000
'gyro_data'	"Υ"	'zero_cross'	31.000
'grav_data'	"X"	'zero_cross'	0.250
'orient_data'	"qy"	'zero_cross'	0.250