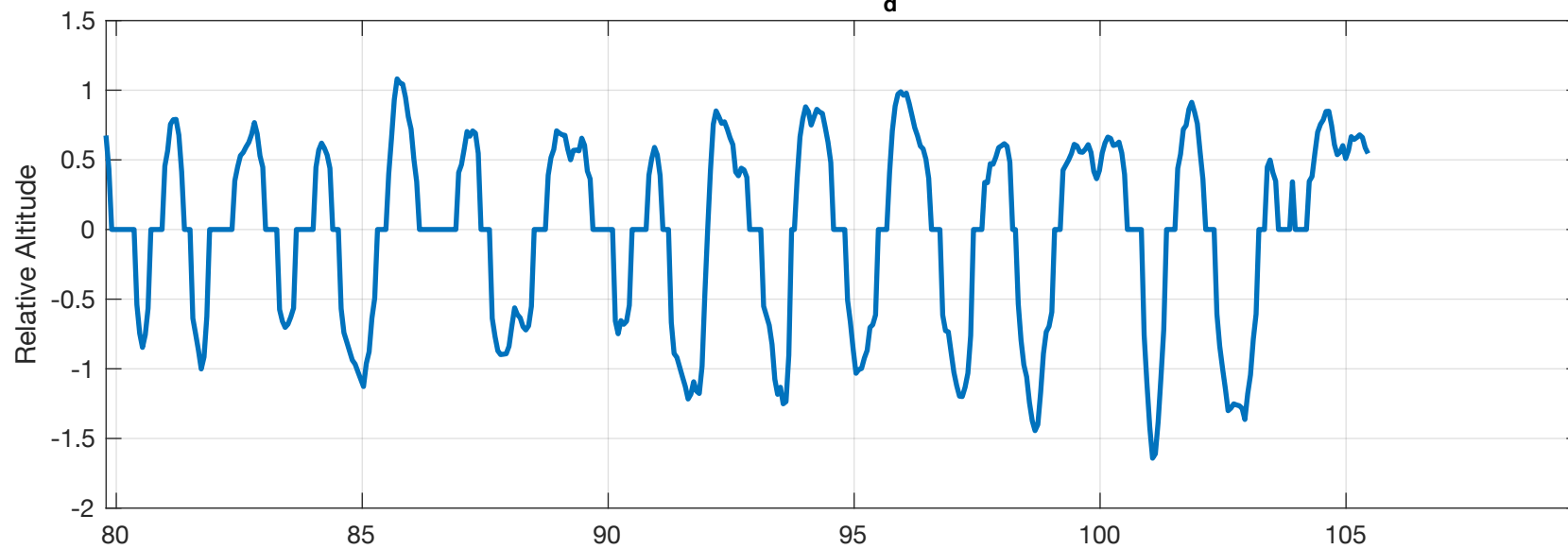
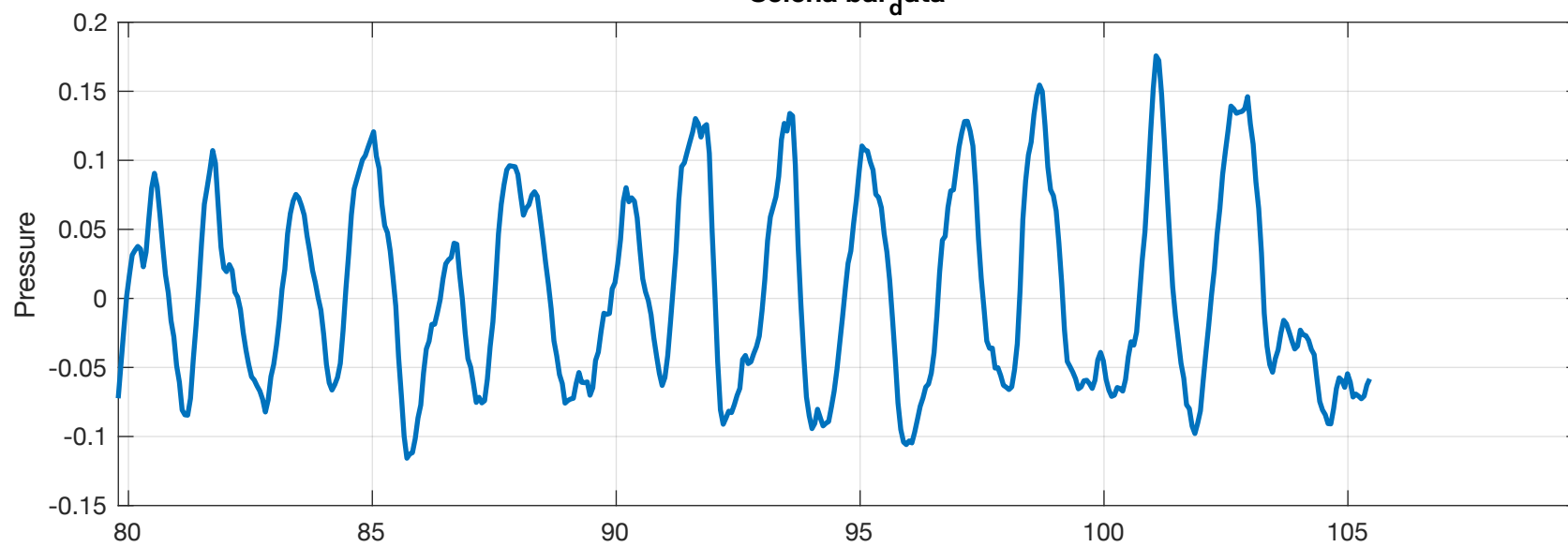


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-163.000	-142.000	-51.000	-60.000	"accel_data"
'Y'	-176.000	-152.000	-52.000	-57.500	"accel_data"
'X'	-176.000	-135.000	-40.000	-52.750	"accel_data"

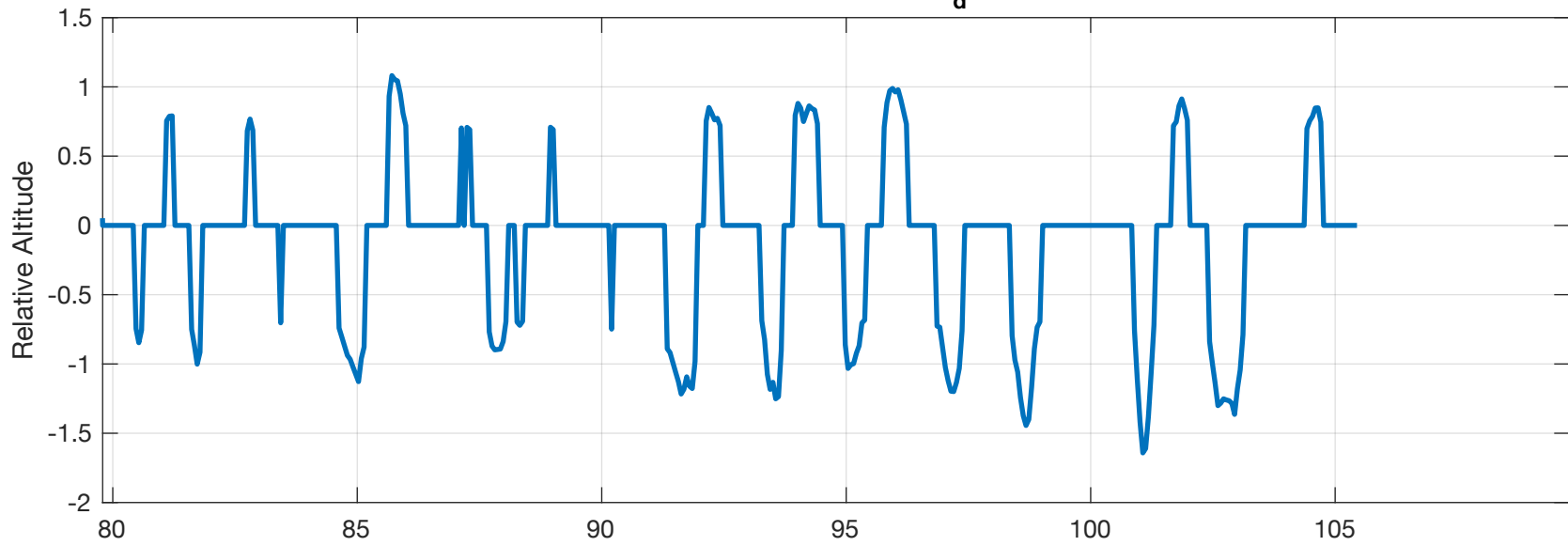
Selena bar_data



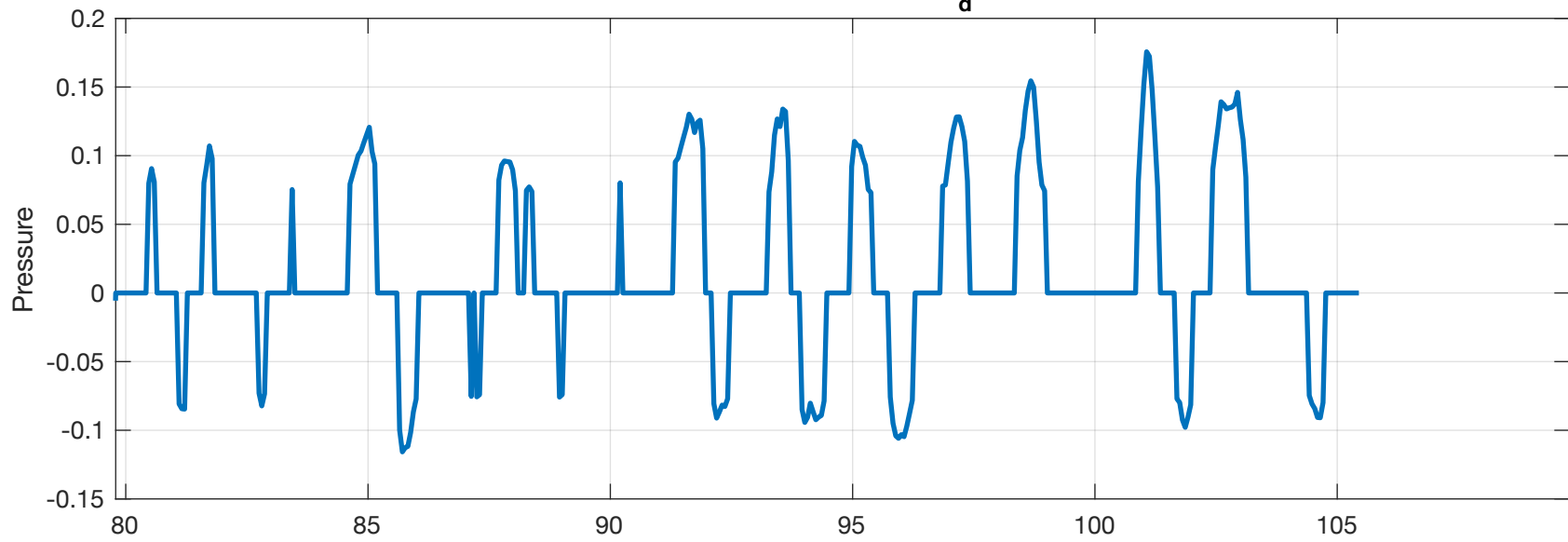
Selena bar_data



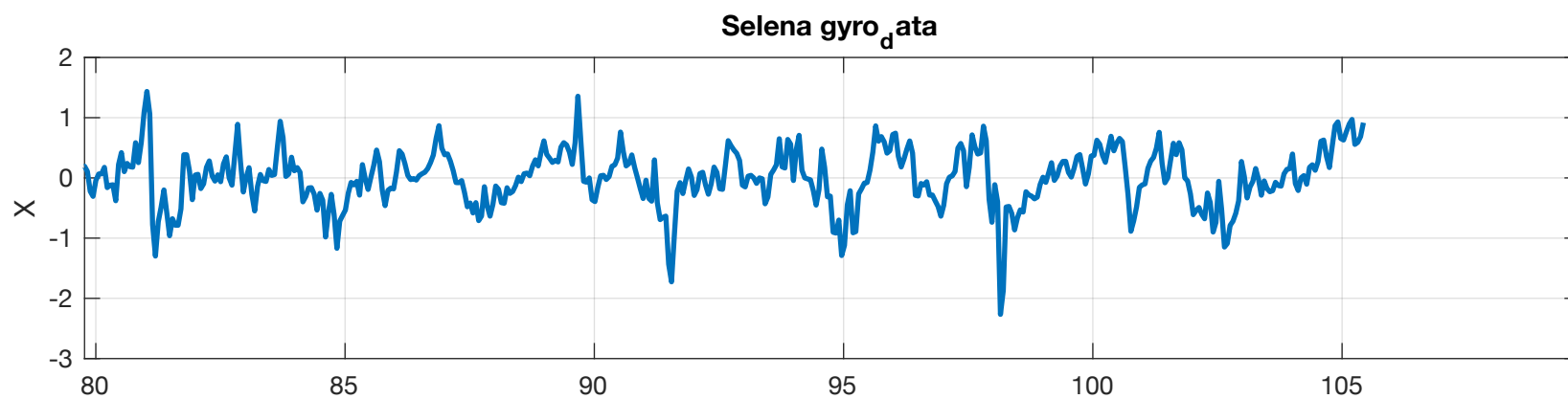
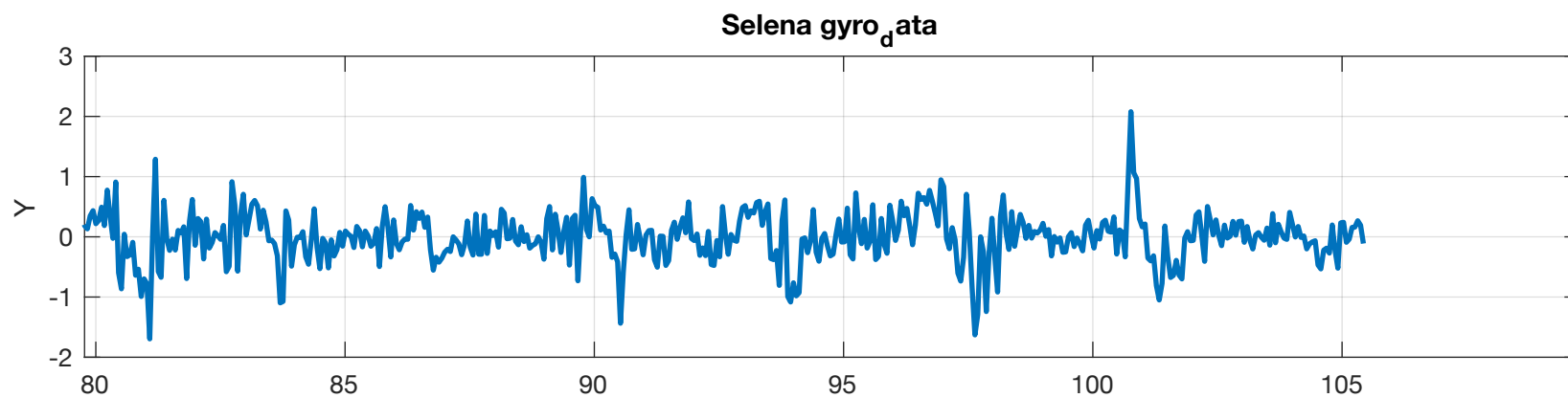
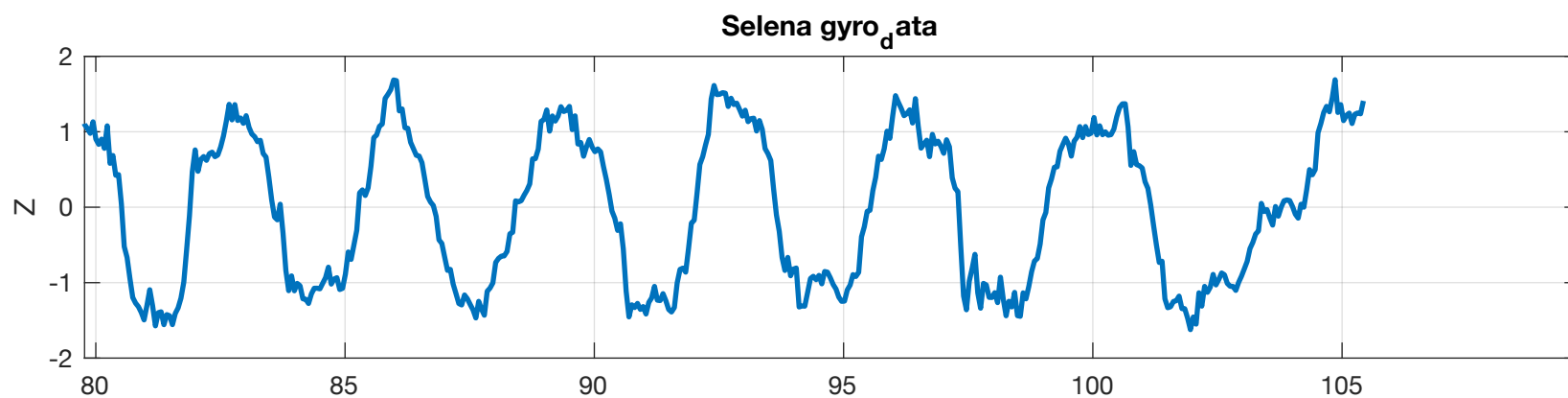
Selena Zero Cross bar_data

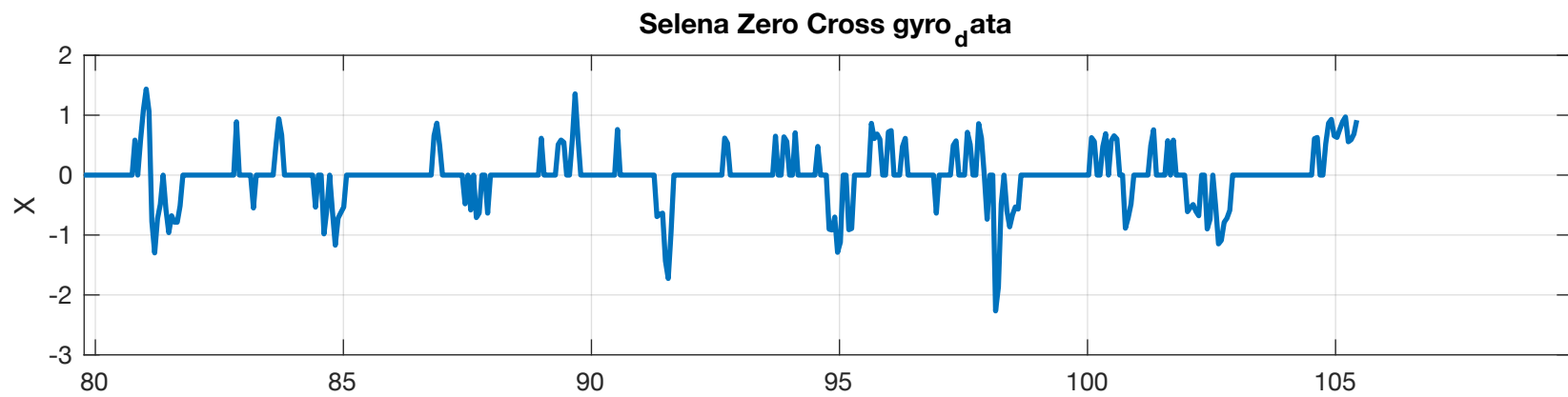
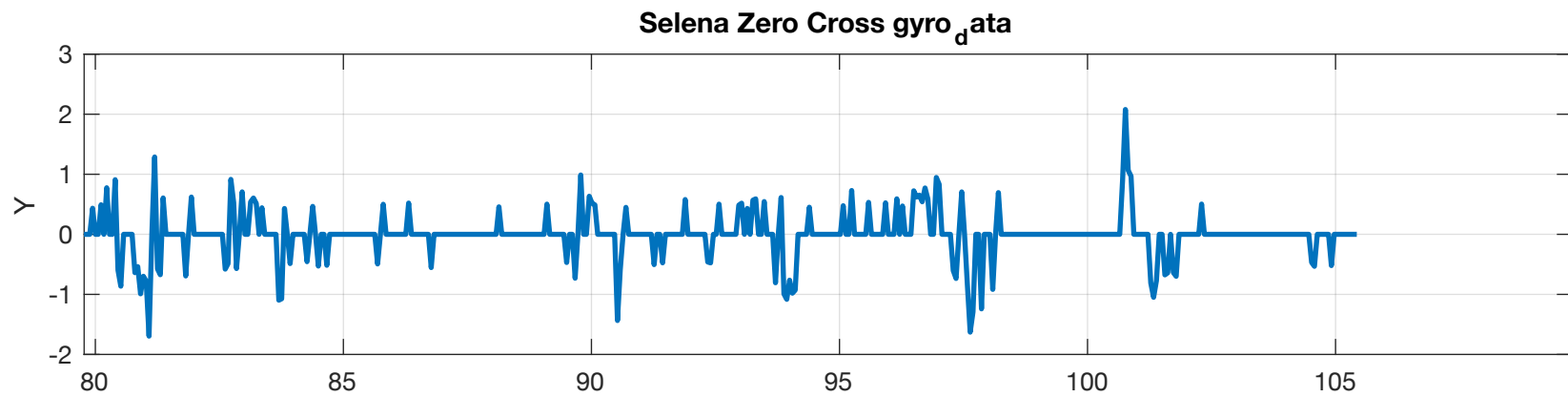
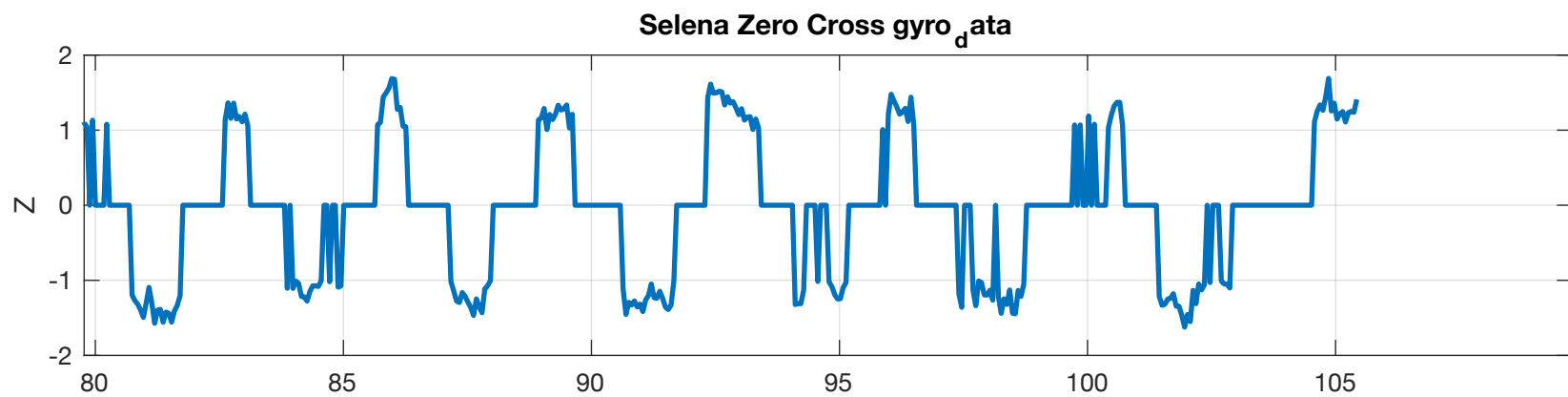


Selena Zero Cross bar_data

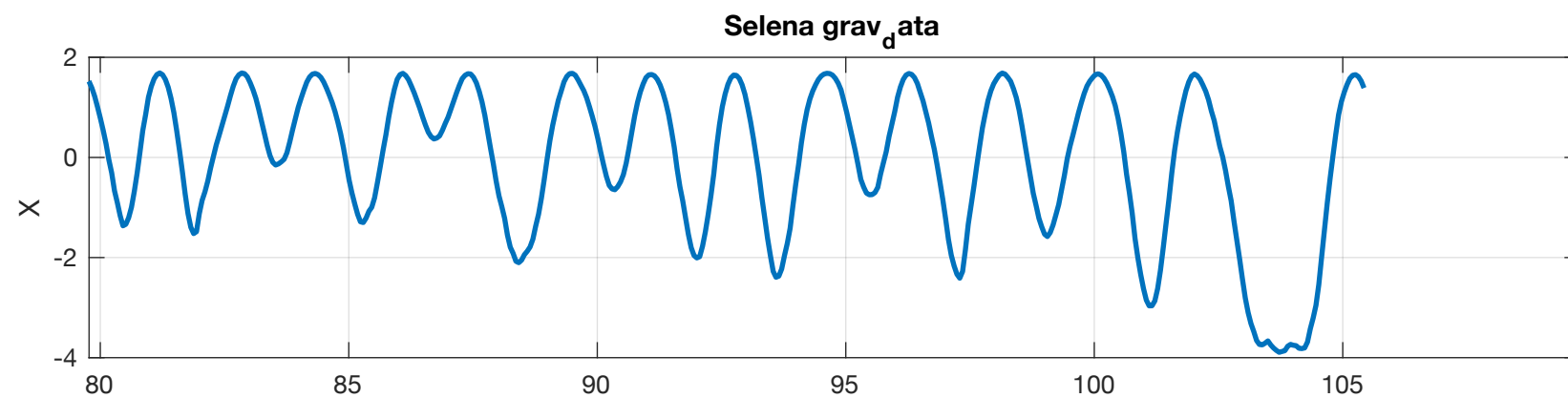
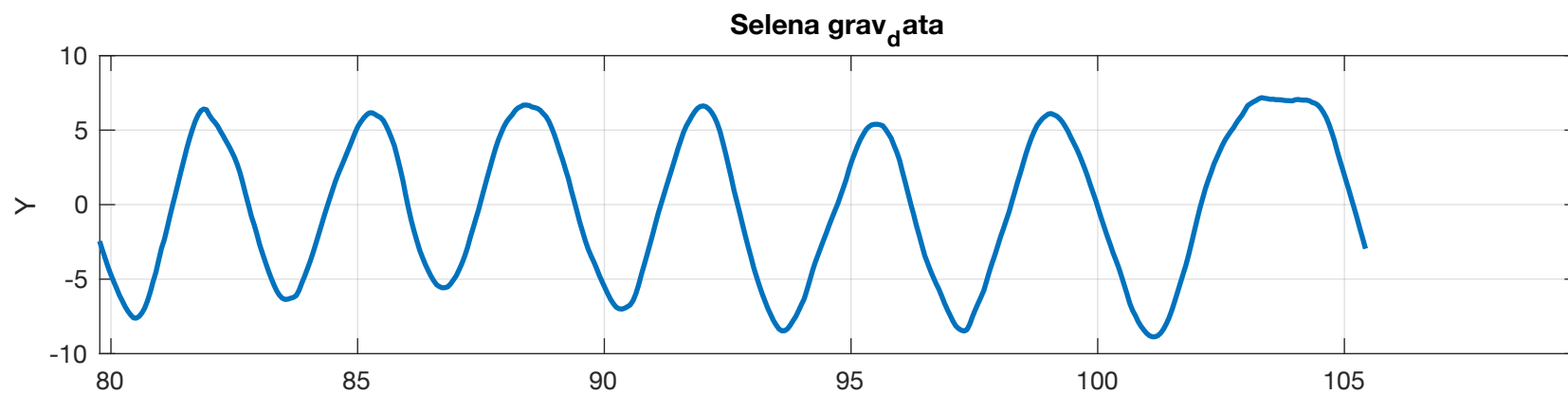
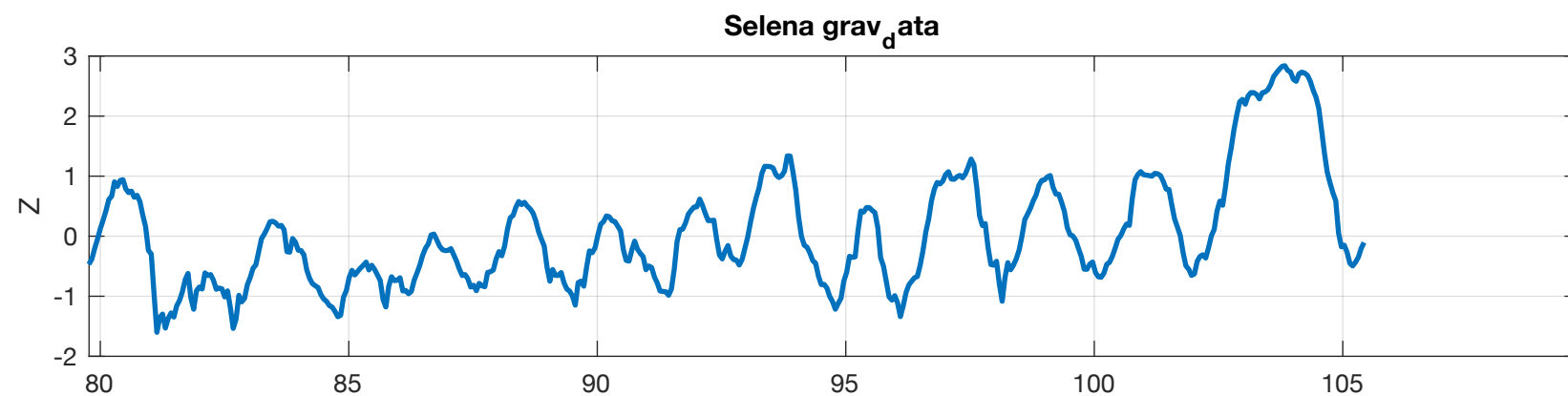


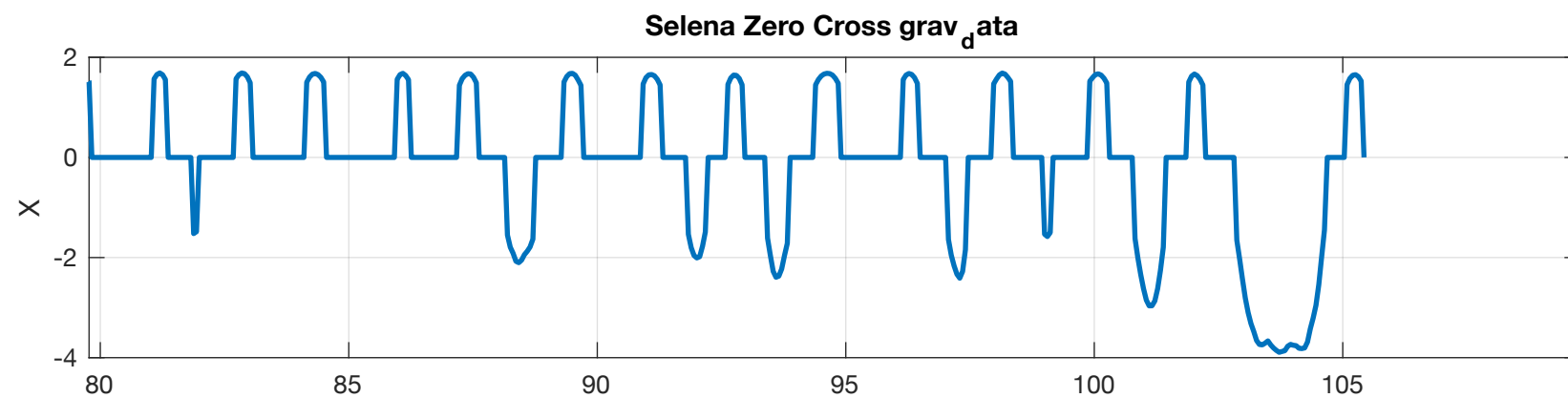
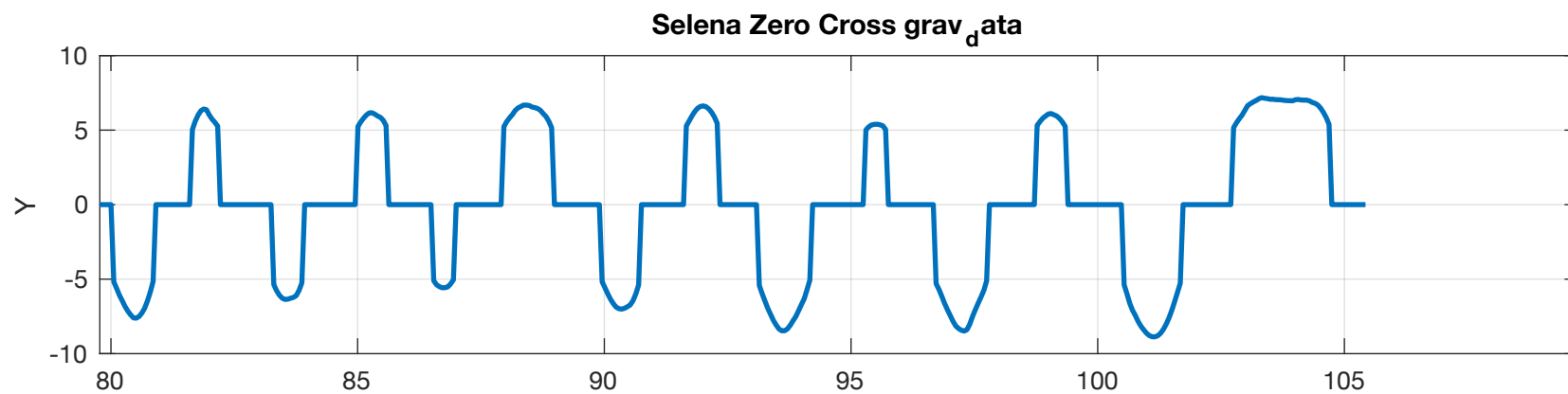
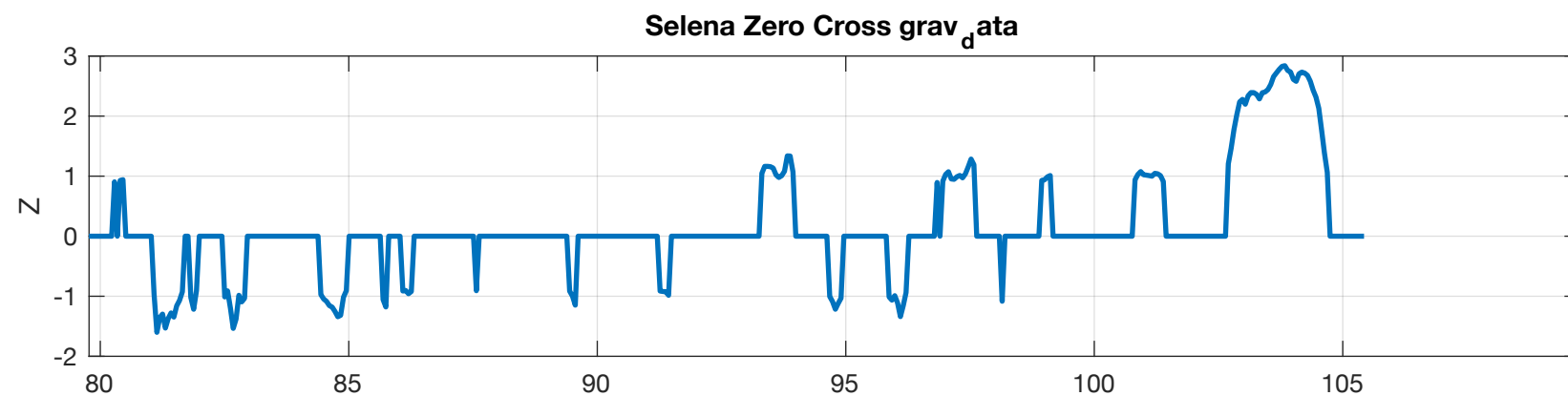
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-40.000	-34.000	-7.000	-7.000	"bar_data"
"Pressure"	-43.000	-16.000	-3.000	-7.000	"bar_data"



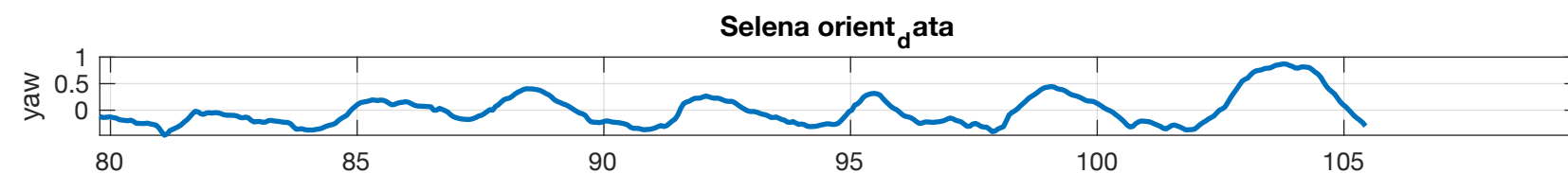
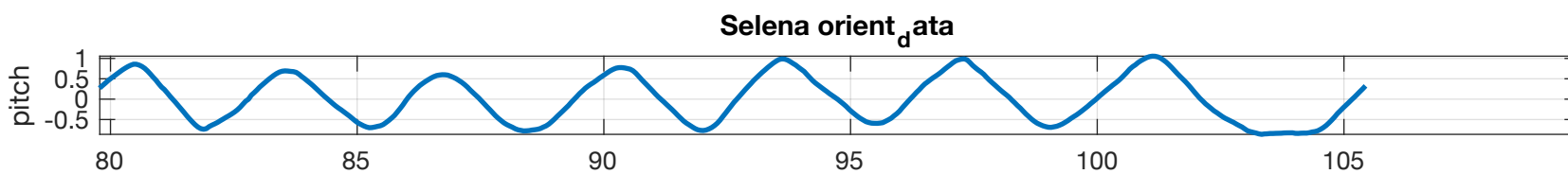
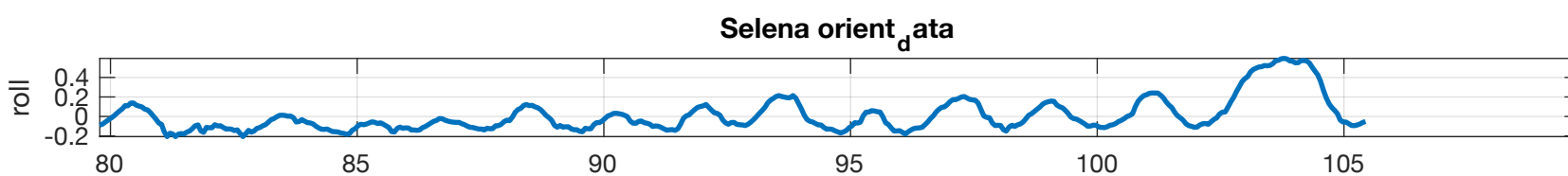
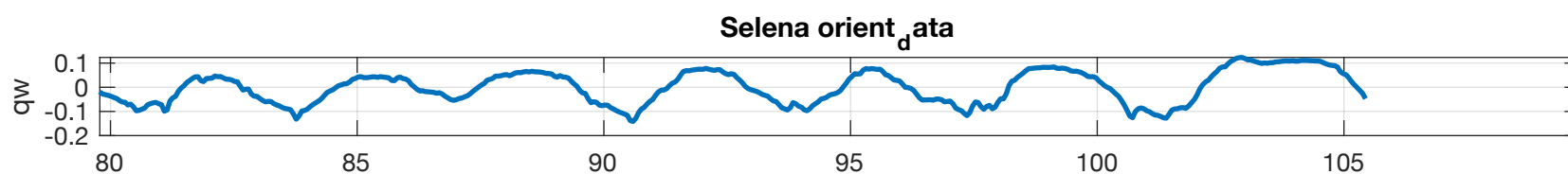
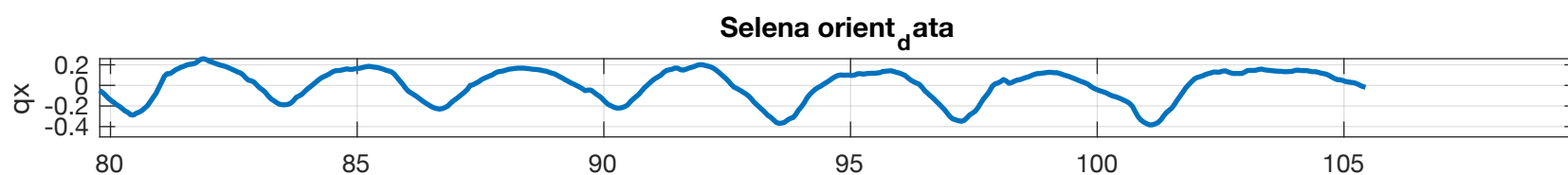
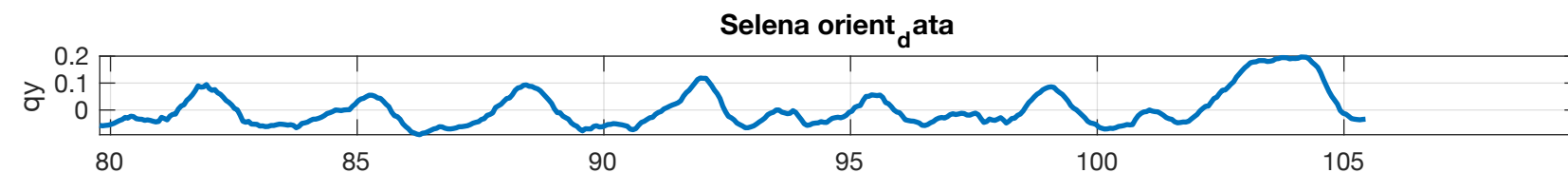
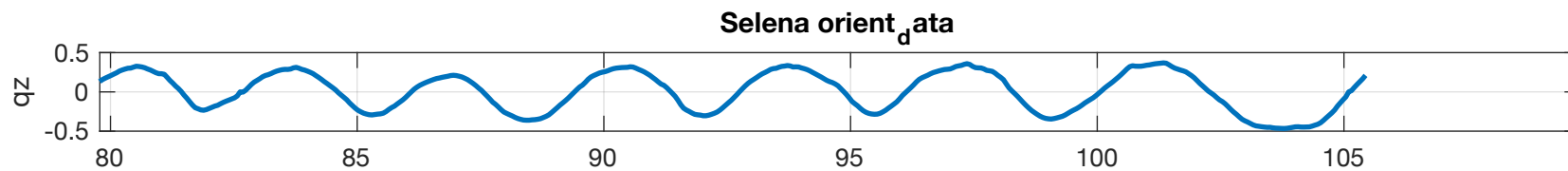


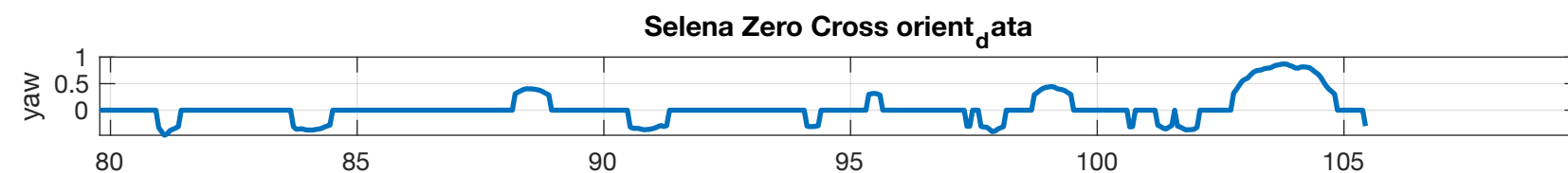
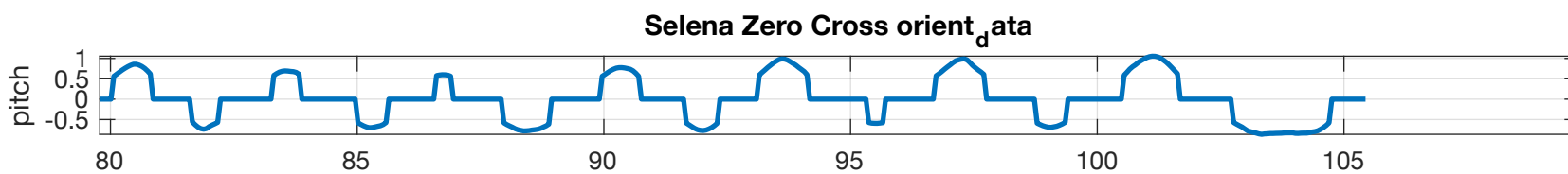
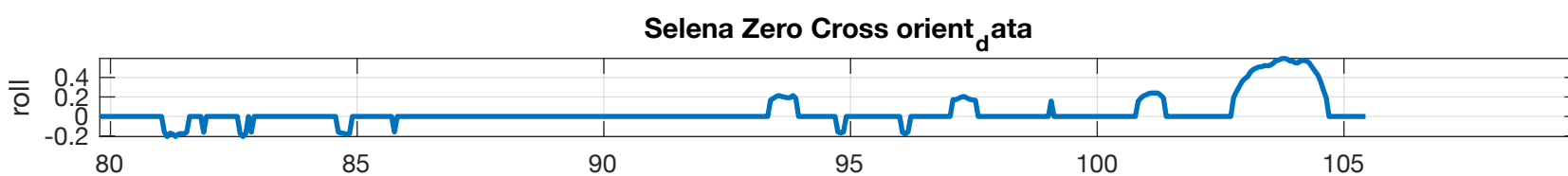
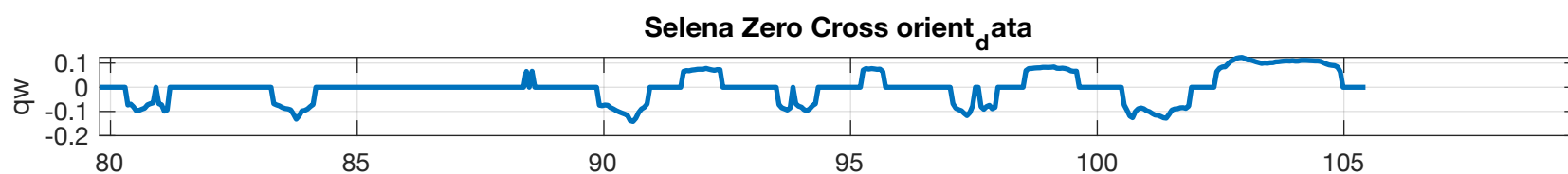
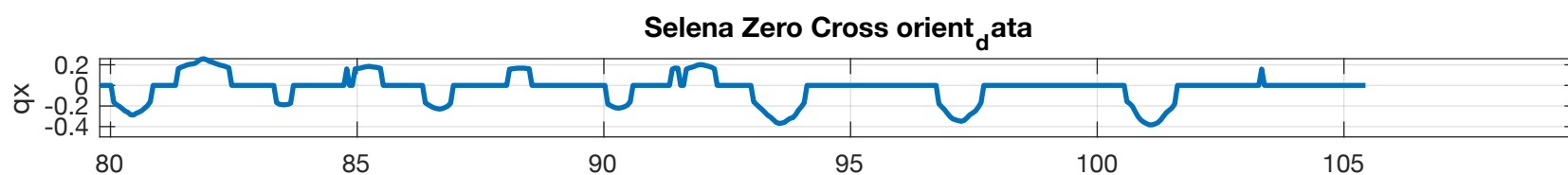
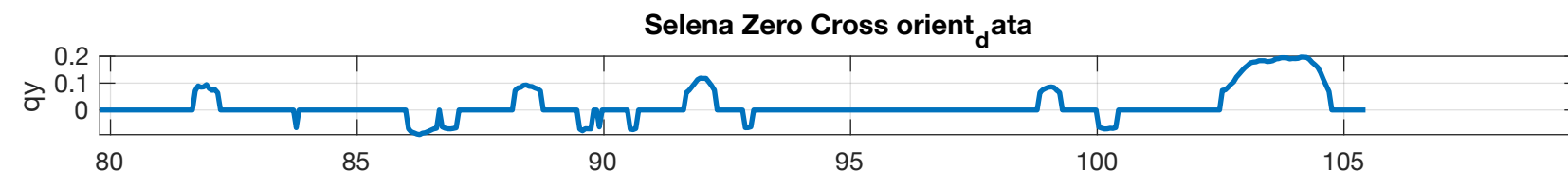
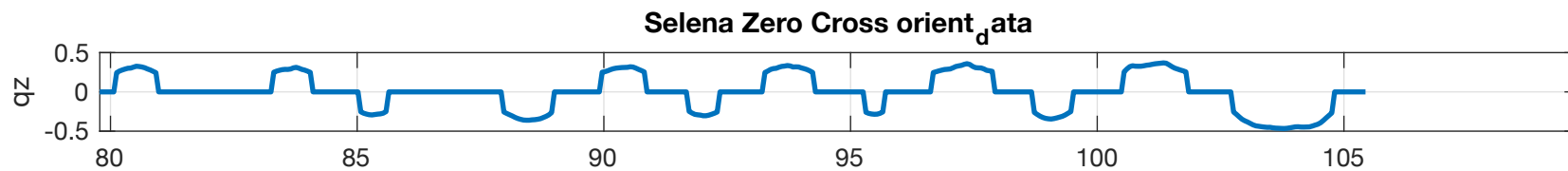
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-122.000	-68.000	-12.000	-8.750	"gyro_data"
'Y'	-177.000	-144.000	-41.000	-34.000	"gyro_data"
'X'	-127.000	-85.000	-23.000	-22.250	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-76.000	-31.000	-7.000	-5.500	"grav_data"
'Y'	-2.000	-2.000	7.000	0.500	"grav_data"
'X'	-11.000	-9.000	3.000	-5.500	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-9.000	-4.000	4.000	1.500	"orient_data"
'qy'	-40.000	-9.000	1.000	1.500	"orient_data"
'qx'	-25.000	-24.000	2.000	1.500	"orient_data"
'qw'	-64.000	-40.000	-2.000	-1.500	"orient_data"
'roll'	-60.000	-15.000	-5.000	1.000	"orient_data"
'pitch'	-1.000	1.000	8.000	0.500	"orient_data"
'yaw'	-38.000	-11.000	2.000	0.250	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'double_findpeaks'	40.000
'bar_data'	"Pressure"	'double_findpeaks'	3.000
'gyro_data'	"Z"	'zero_cross'	8.750
'grav_data'	"Y"	'zero_cross'	0.500
'orient_data'	"yaw"	'zero_cross'	0.250