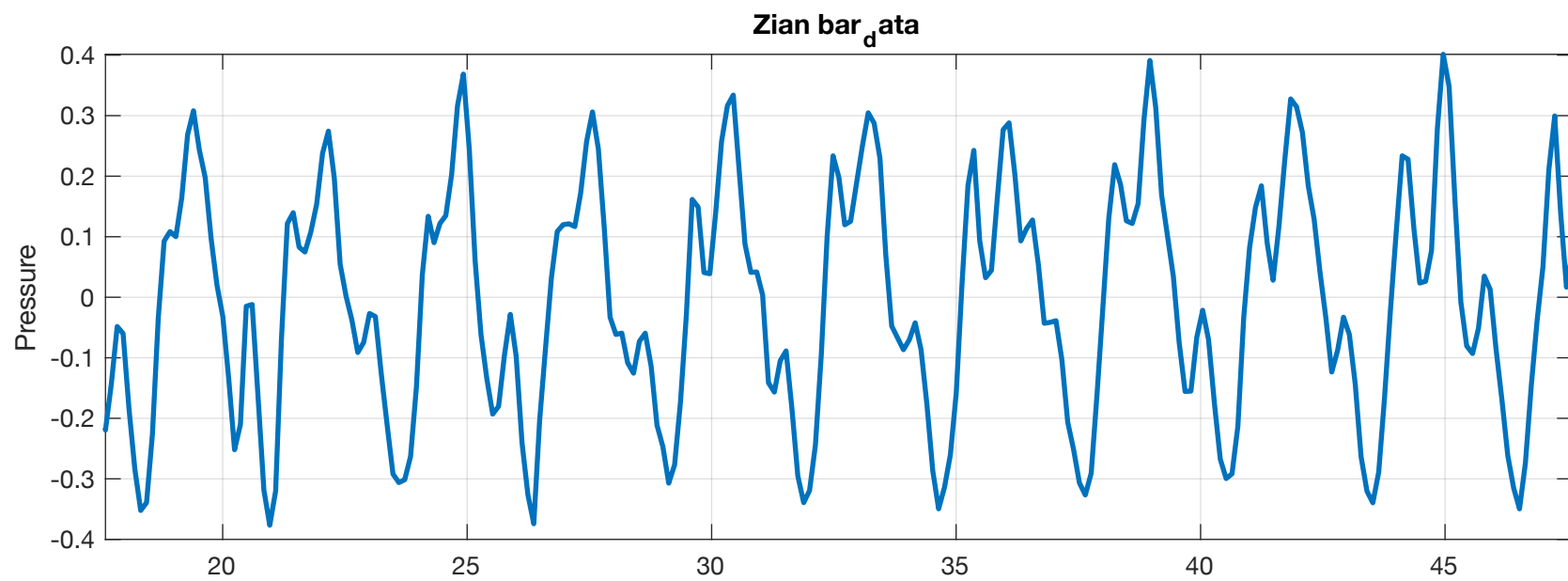
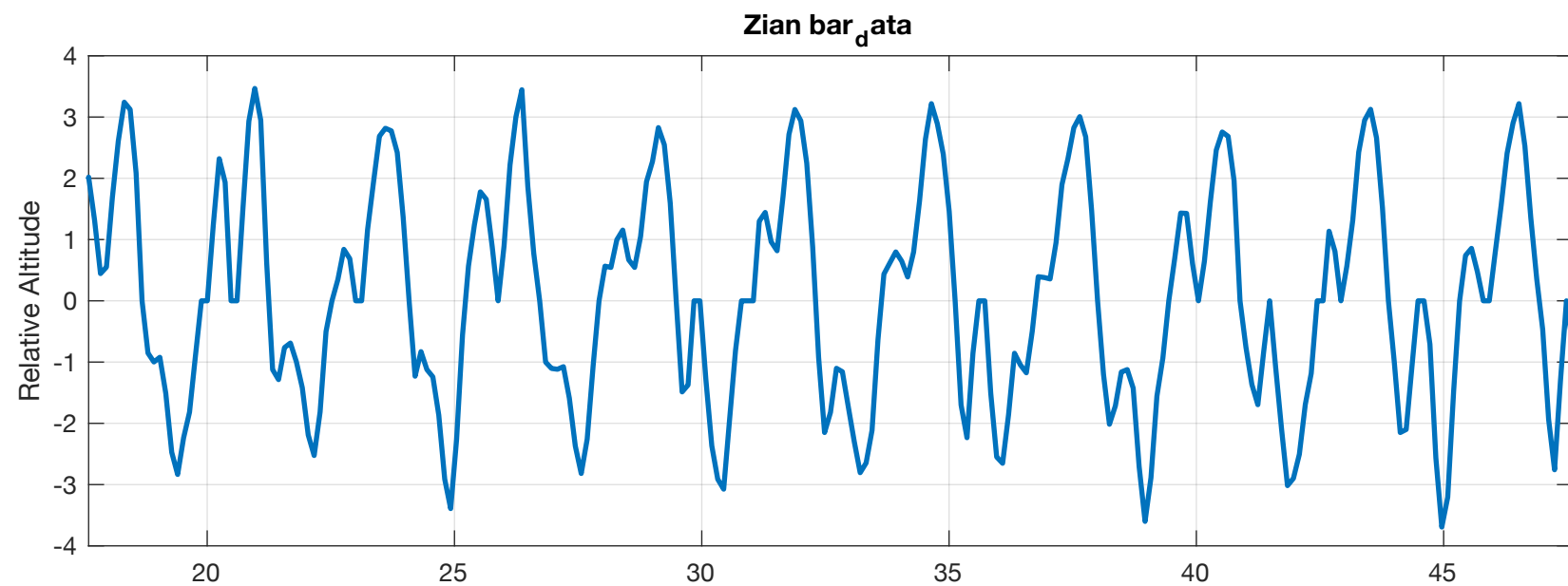
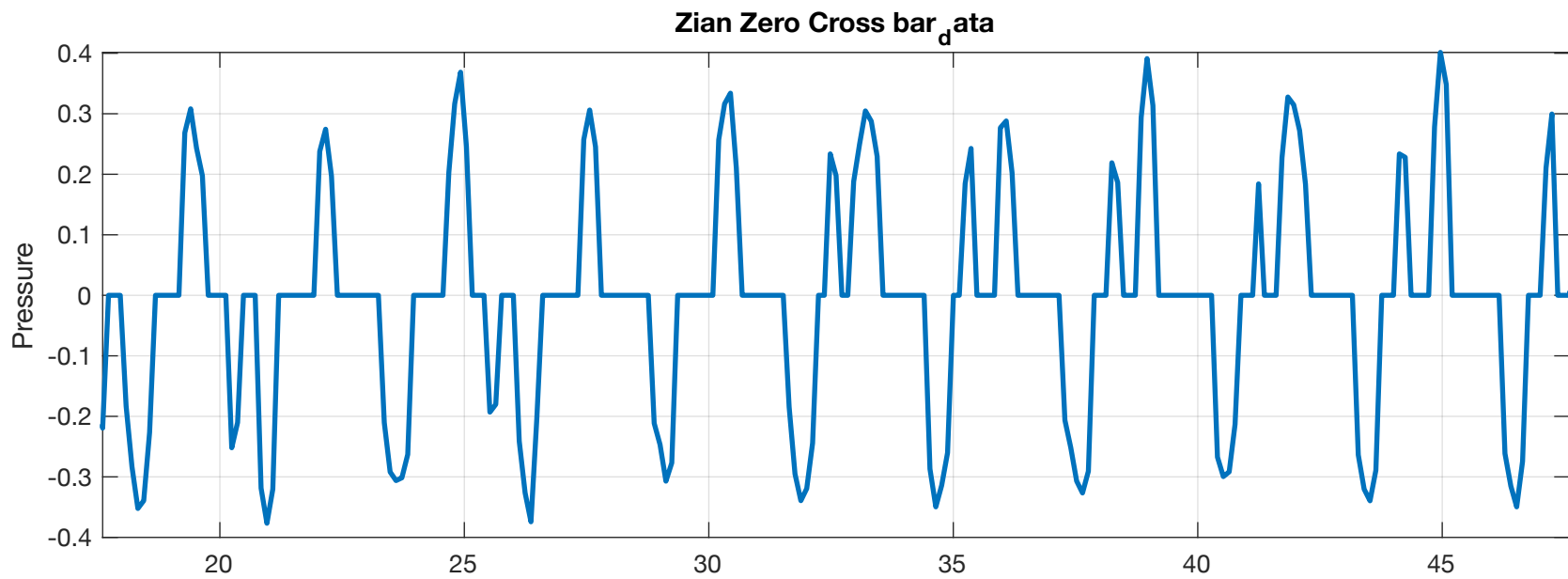
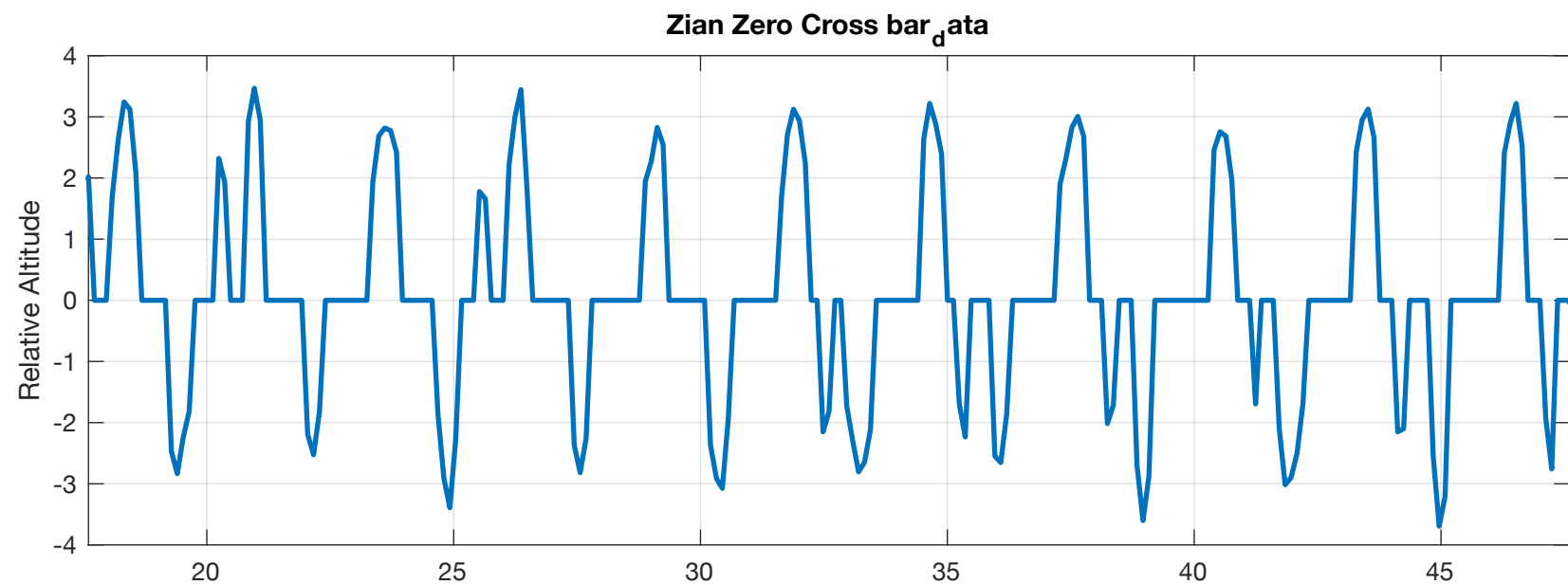
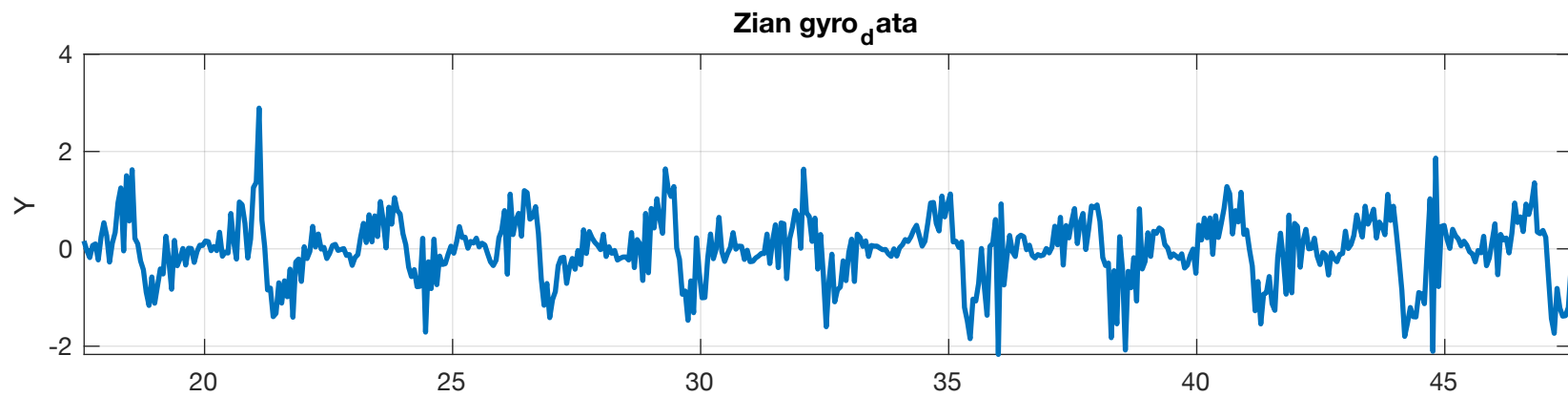


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-366.000	-311.000	-111.000	-83.000	"accel_data"
'Y'	-379.000	-330.000	-105.000	-103.500	"accel_data"
'X'	-407.000	-321.000	-115.000	-112.500	"accel_data"

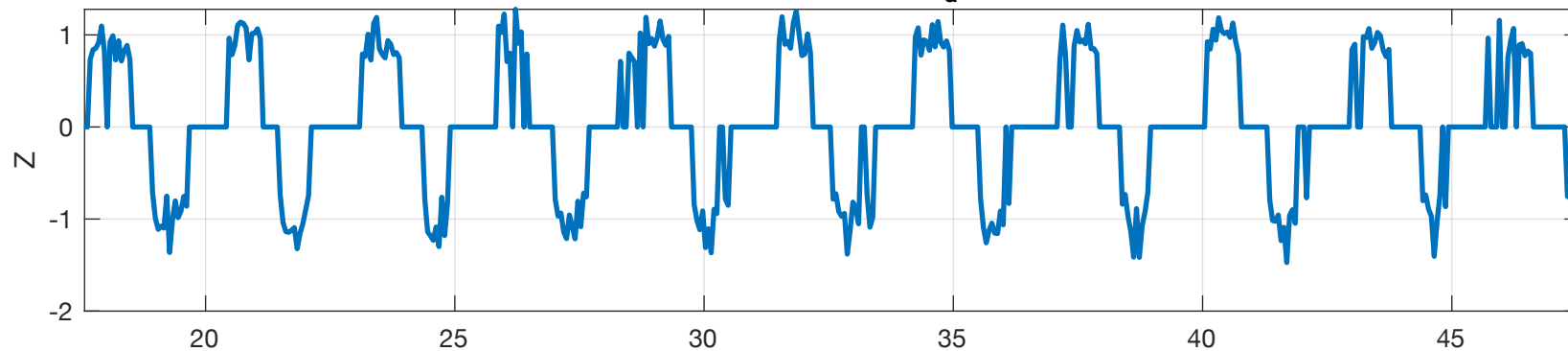




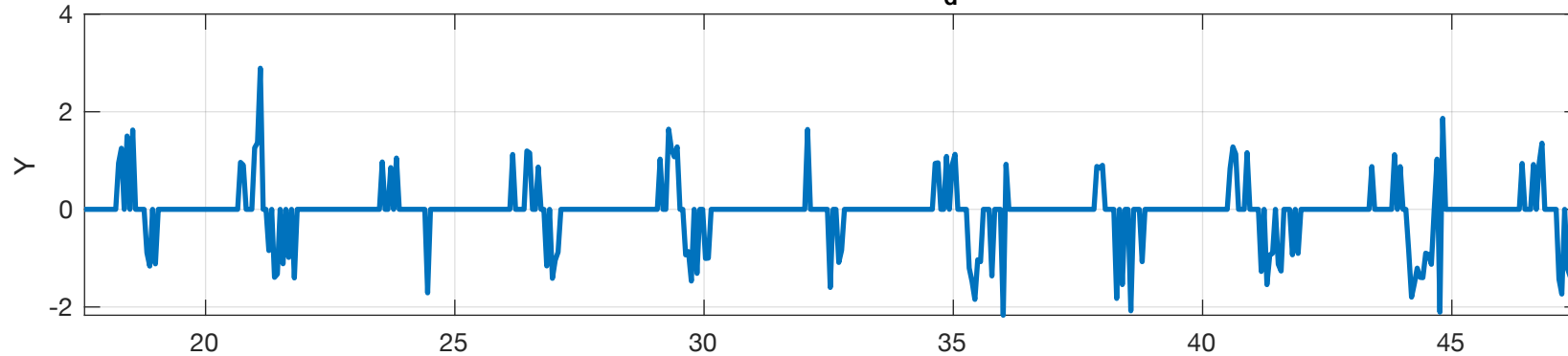
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-57.000	-35.000	-6.000	-13.500	"bar_data"
"Pressure"	-69.000	-46.000	-8.000	-13.500	"bar_data"



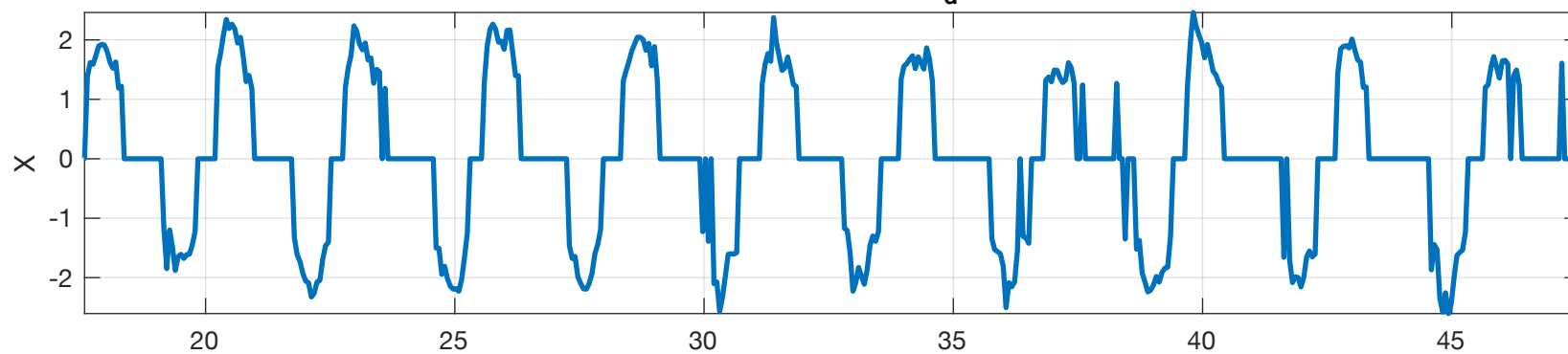
Zian Zero Cross gyro_data



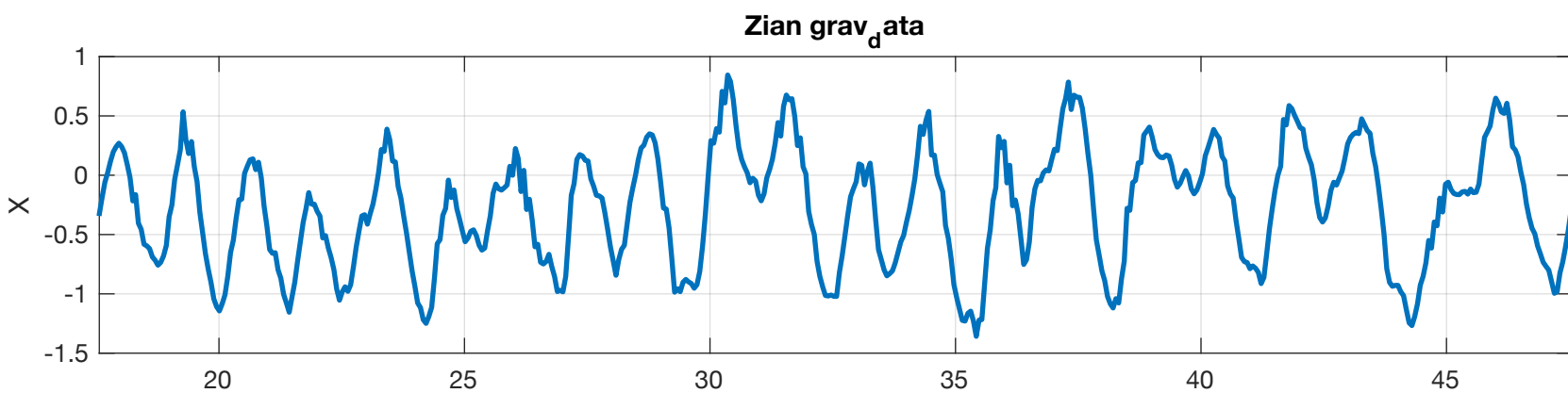
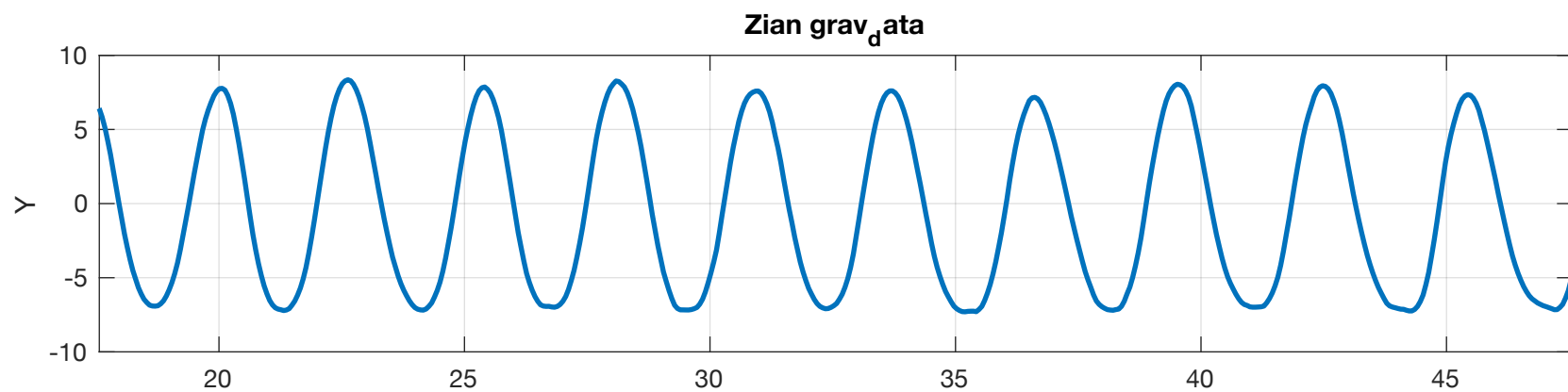
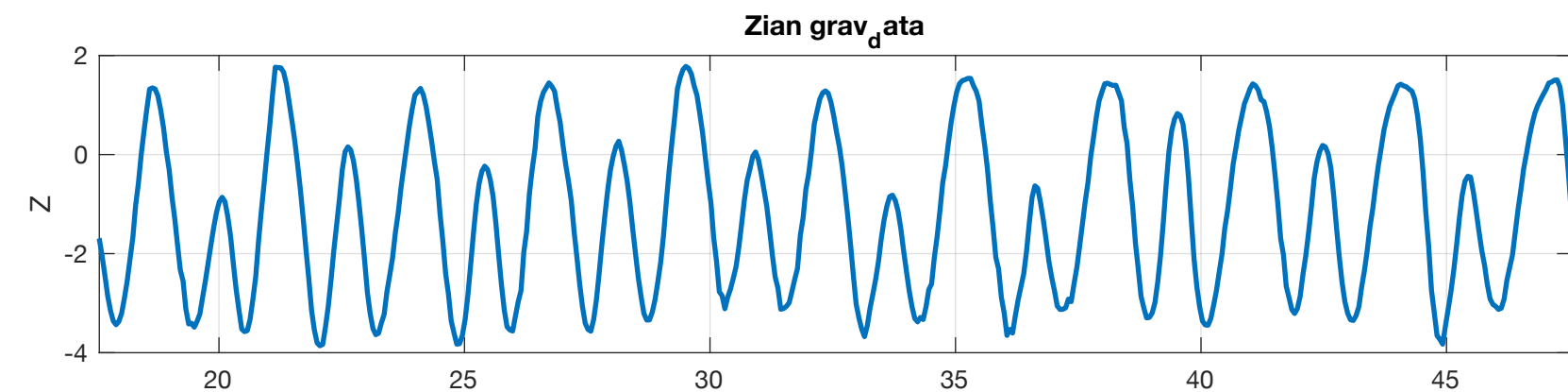
Zian Zero Cross gyro_data

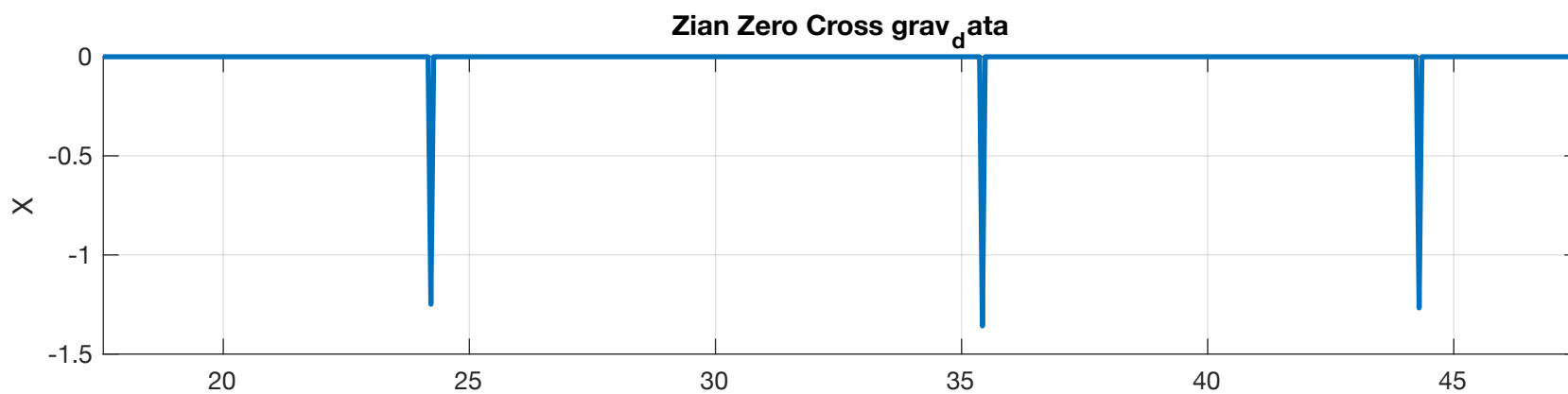
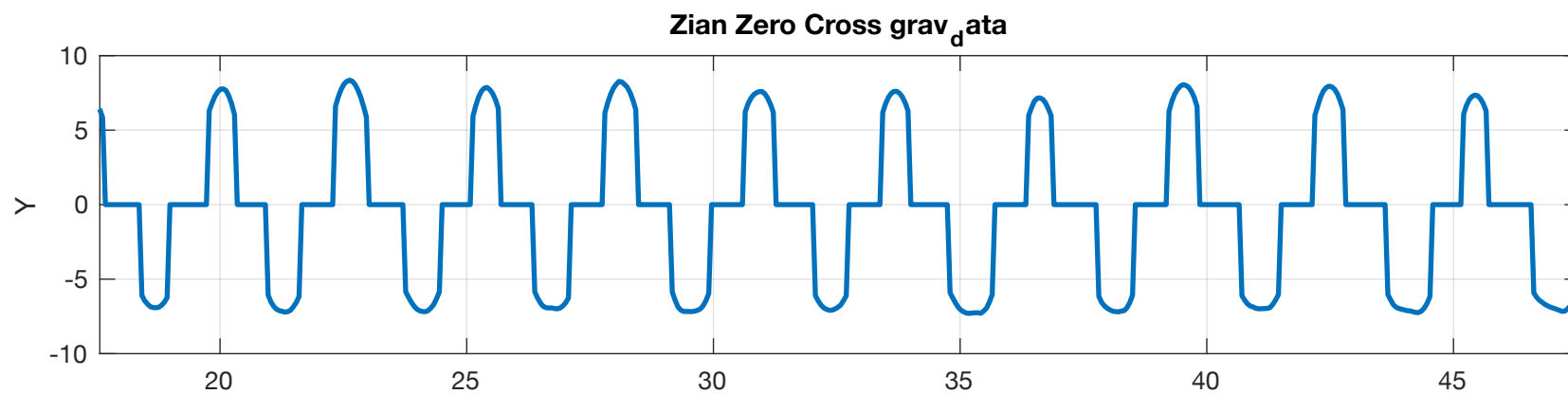
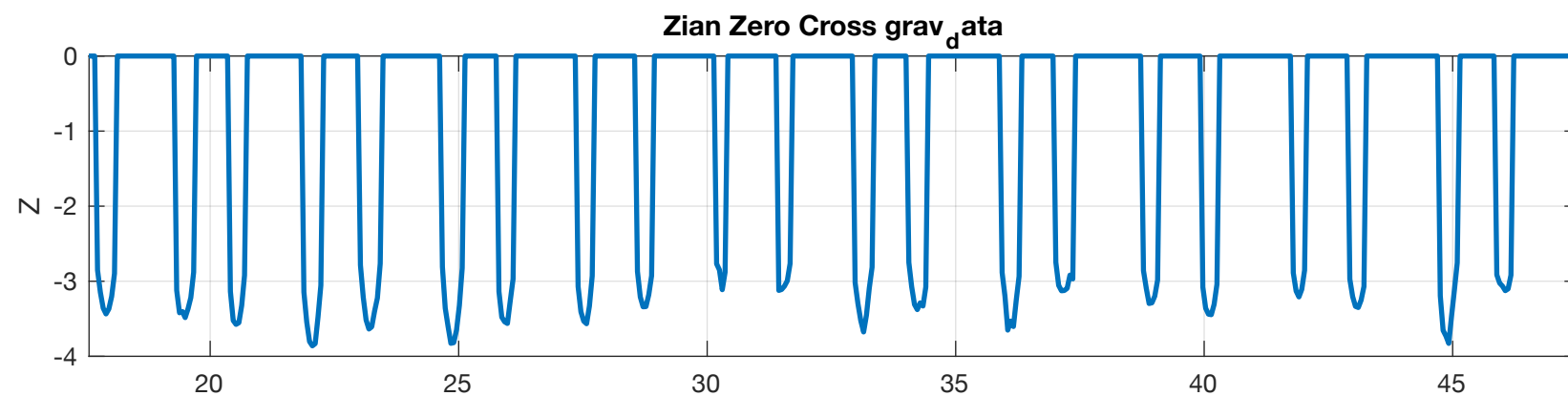


Zian Zero Cross gyro_data

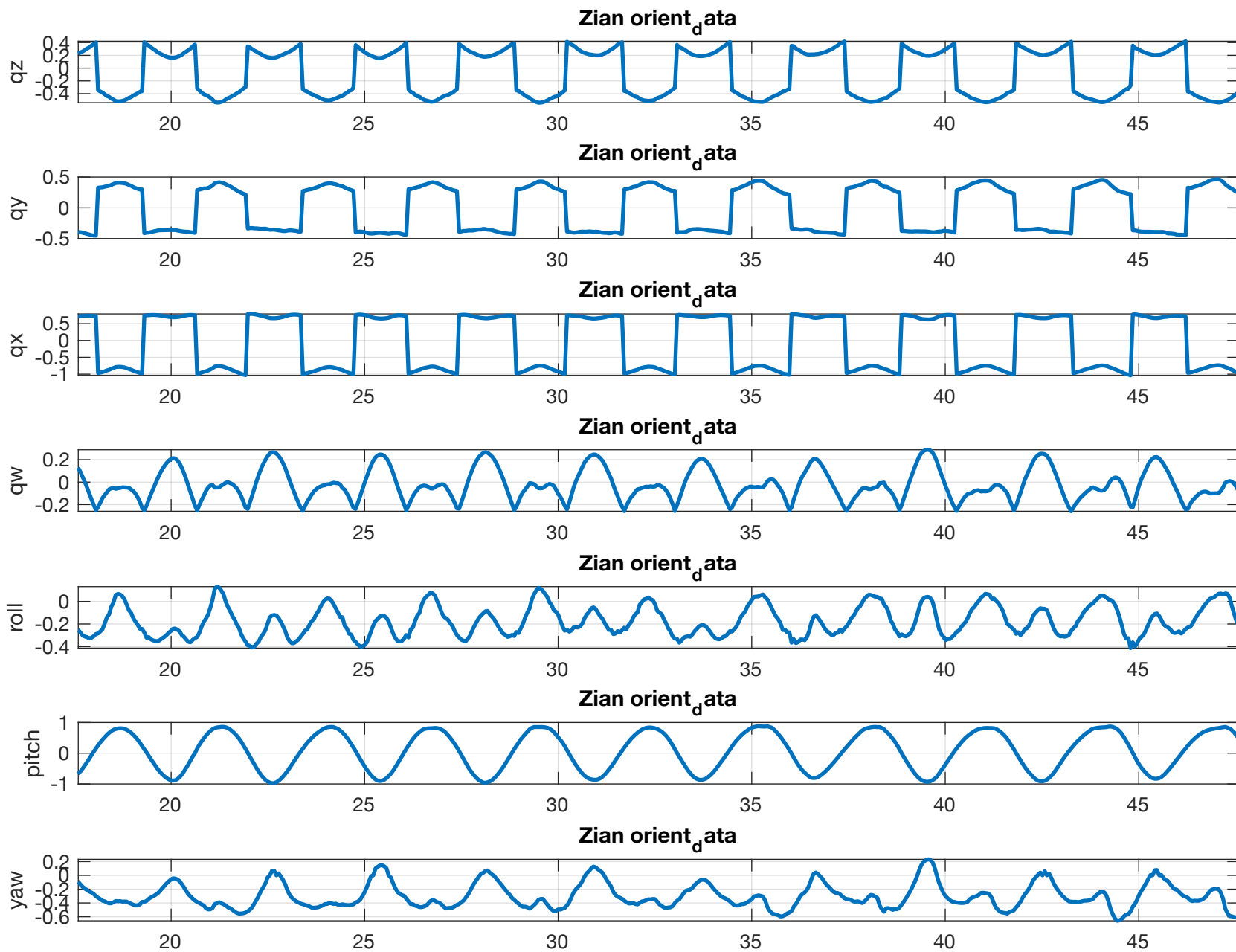


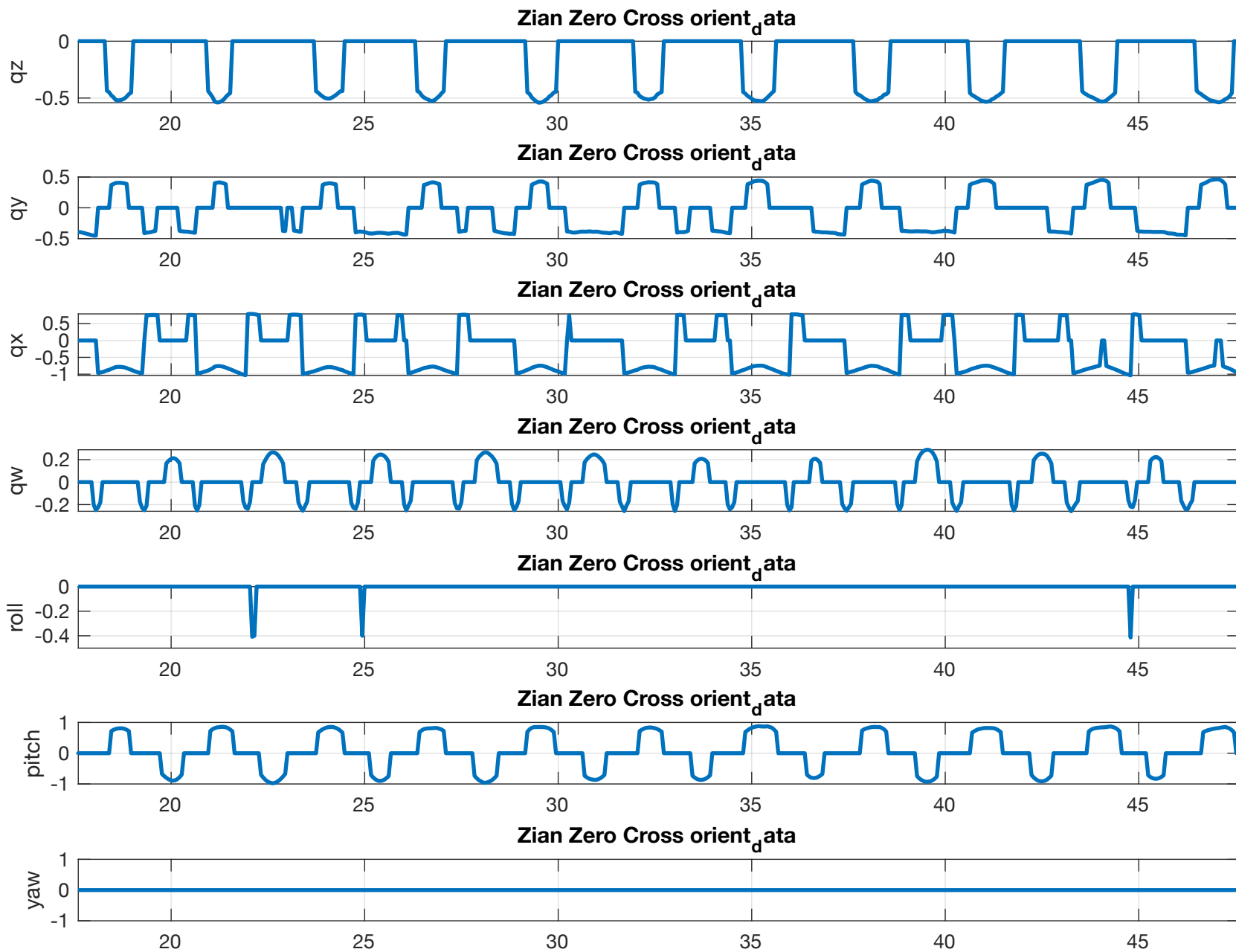
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-287.000	-185.000	-44.000	-22.500	"gyro_data"
'Y'	-373.000	-291.000	-84.000	-43.500	"gyro_data"
'X'	-251.000	-177.000	-42.000	-16.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-78.000	-54.000	-14.000	-2.250	"grav_data"
'Y'	-53.000	-27.000	2.000	-3.000	"grav_data"
'X'	-141.000	-73.000	-14.000	5.750	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-73.000	-50.000	-5.000	2.500	"orient_data"
'qy'	-112.000	-47.000	-11.000	-6.500	"orient_data"
'qx'	-101.000	-56.000	-11.000	-7.500	"orient_data"
'qw'	-87.000	-23.000	-6.000	-12.250	"orient_data"
'roll'	-102.000	-52.000	-13.000	10.250	"orient_data"
'pitch'	-52.000	-25.000	4.000	-3.000	"orient_data"
'yaw'	-98.000	-25.000	-4.000	13.750	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'zero_cross'	83.000
'bar_data'	"Relative Altitude"	'double_findpeaks'	6.000
'gyro_data'	"X"	'zero_cross'	16.000
'grav_data'	"Y"	'double_findpeaks'	2.000
'orient_data'	"qz"	'zero_cross'	2.500