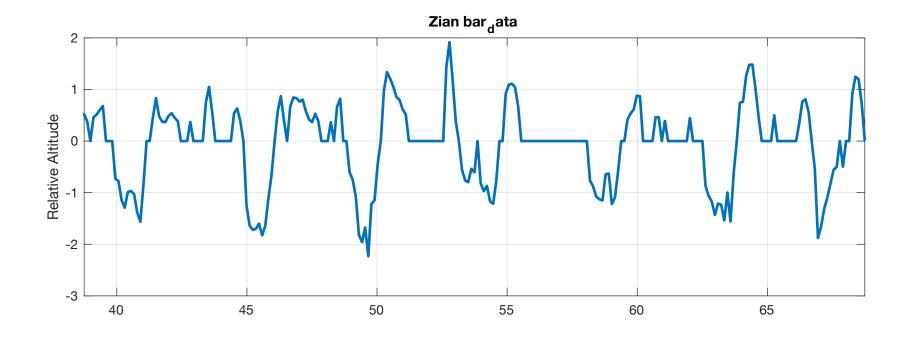
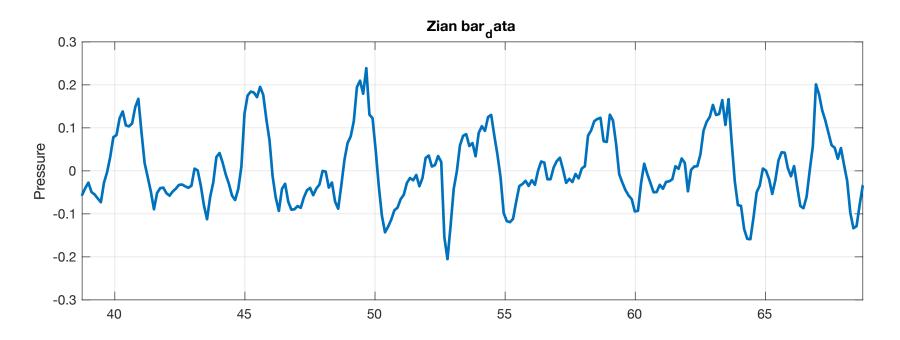
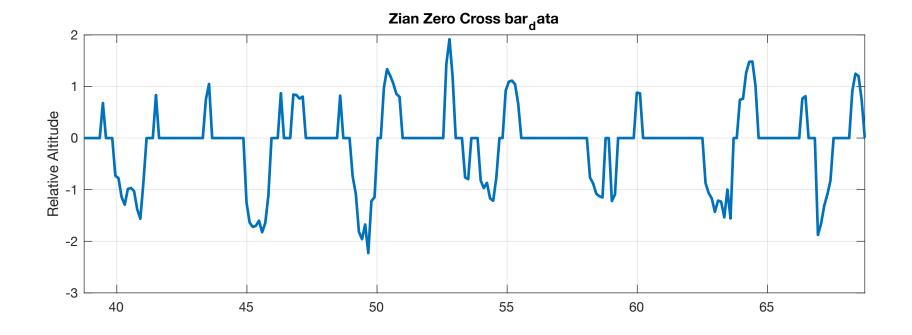
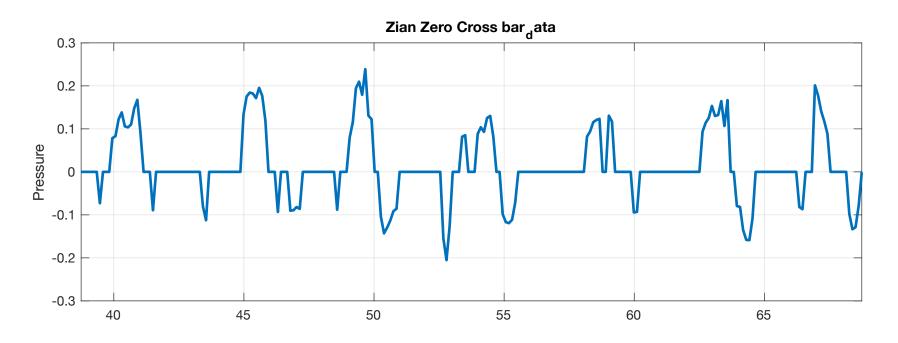


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-359.000	-274.000	-95.000	-75.000	"accel_data"
'Y'	-435.000	-362.000	-131.000	-91.500	"accel_data"
'X'	-406.000	-300.000	-107.000	-87.500	"accel_data"

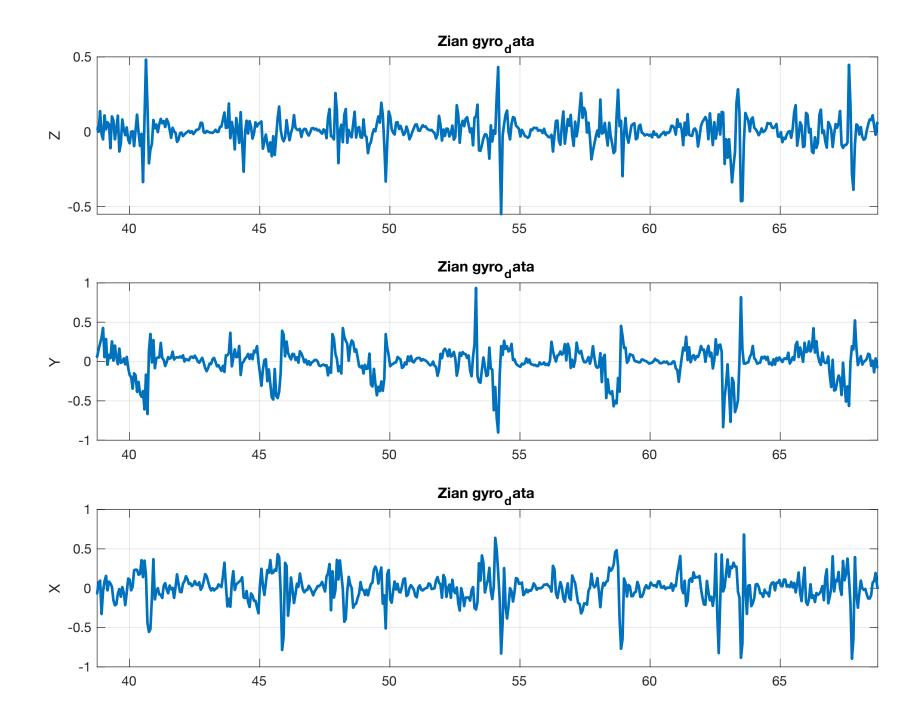


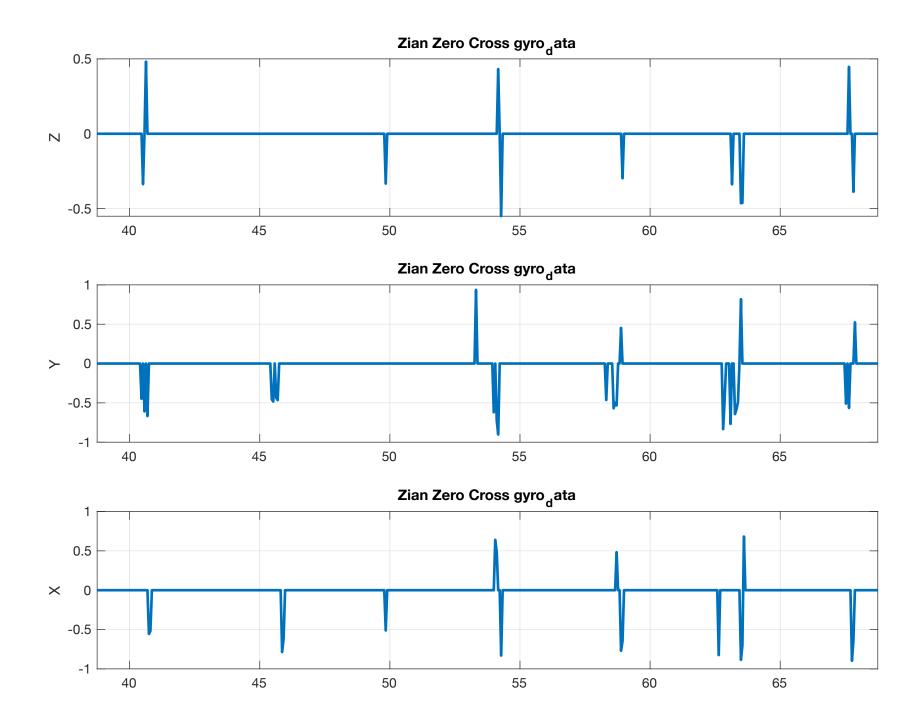




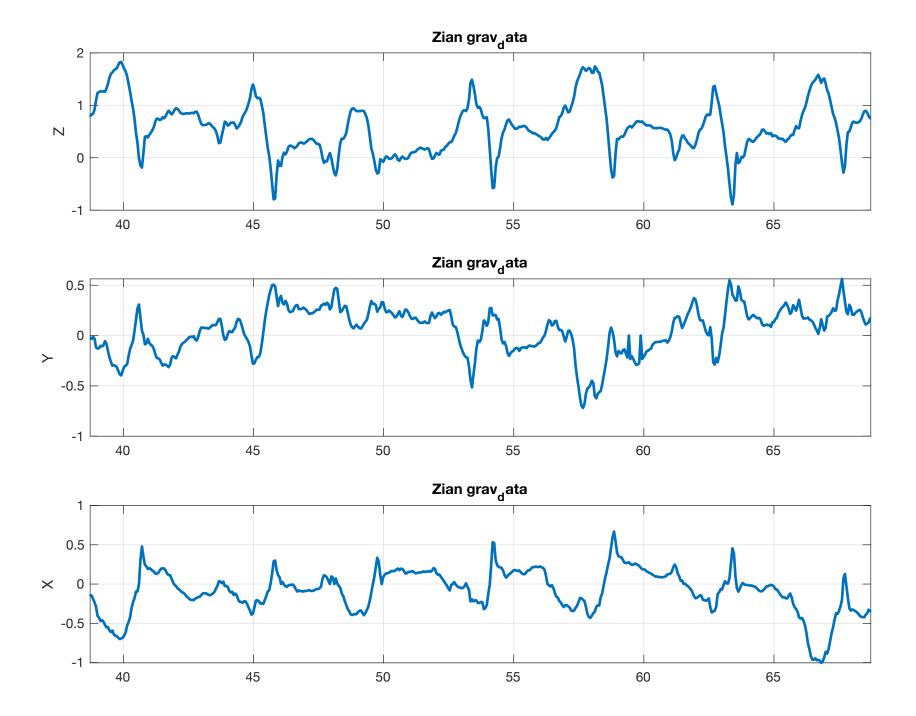


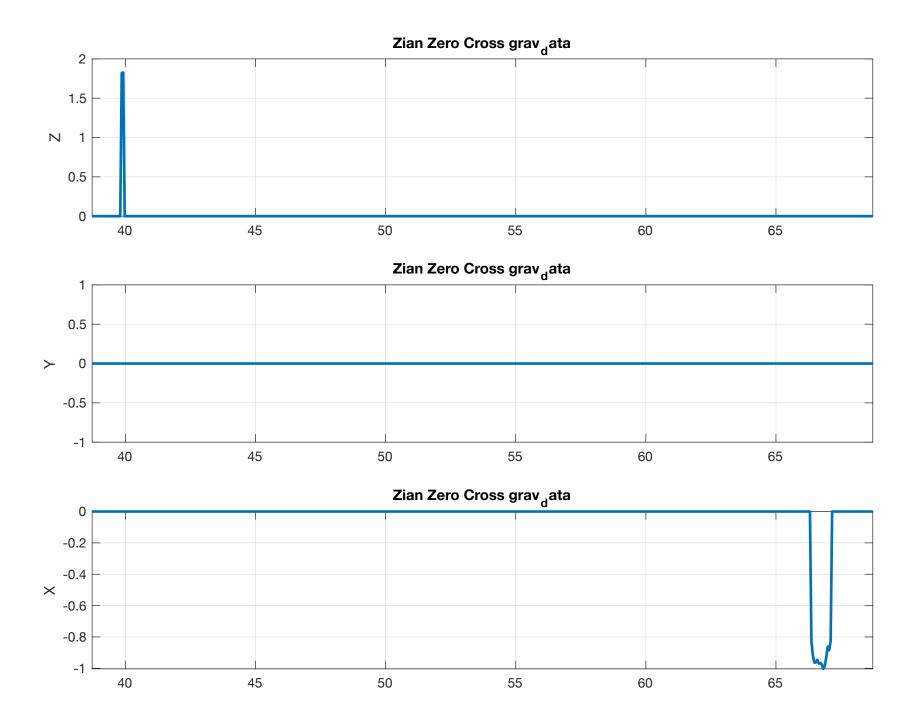
Axis	findpeaks	findpeaks_above_zero	${\bf double_findpeaks}$	zero_cross	Sensor
"Relative Altitude"	-62.000	-44.000	-10.000	-12.000	"bar_data"
"Pressure"	-98.000	-63.000	-19.000	-12.000	"bar_data"



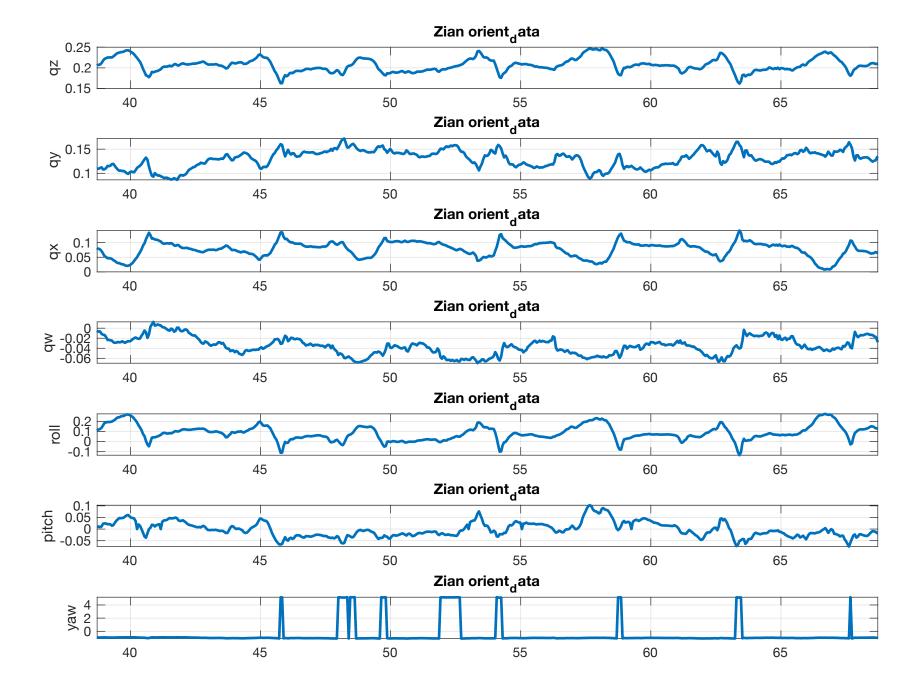


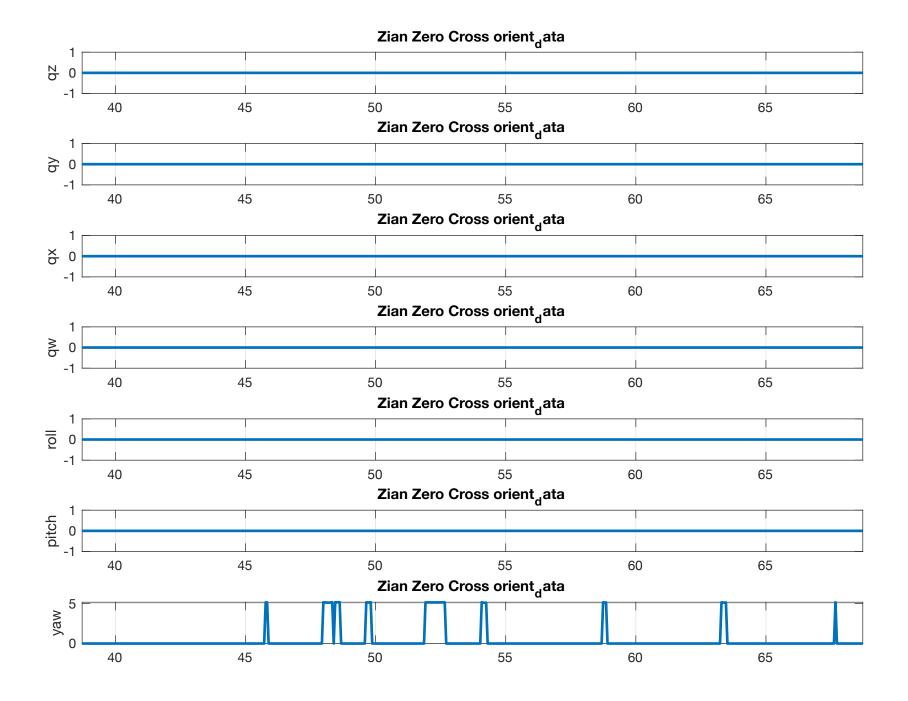
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-345.000	-285.000	-97.000	-8.000	"gyro_data"
'Y'	-396.000	-298.000	-102.000	-15.750	"gyro_data"
'X'	-336.000	-277.000	-90.000	-6.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-169.000	-143.000	-28.000	8.750	"grav_data"
'Y'	-200.000	-139.000	-29.000	9.250	"grav_data"
'X'	-179.000	-75.000	-16.000	4.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-178.000	-162.000	-31.000	11.250	"orient_data"
'qy'	-231.000	-214.000	-38.000	11.750	"orient_data"
'qx'	-178.000	-159.000	-29.000	10.750	"orient_data"
'qw'	-251.000	-22.000	0.000	10.250	"orient_data"
'roll'	-150.000	-128.000	-24.000	9.750	"orient_data"
'pitch'	-203.000	-91.000	-22.000	9.250	"orient_data"
'yaw'	-258.000	-36.000	-5.000	3.250	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'zero_cross'	75.000
'bar_data'	"Relative Altitude"	'double_findpeaks'	10.000
'gyro_data'	"X"	'zero_cross'	6.500
'grav_data'	"X"	'zero_cross'	4.000
'orient_data'	"qw"	'double_findpeaks'	0.000