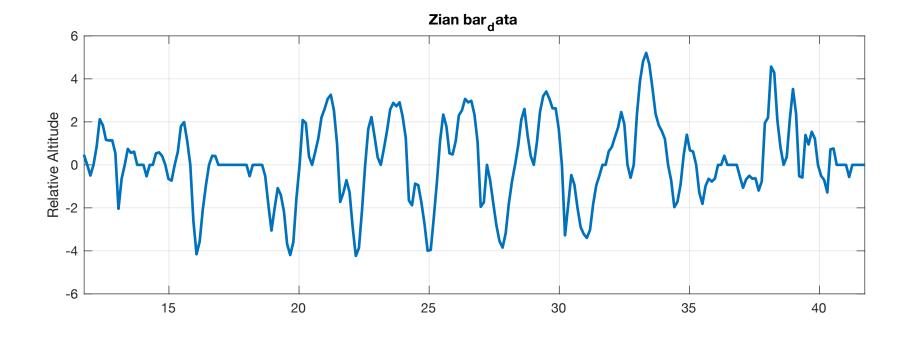
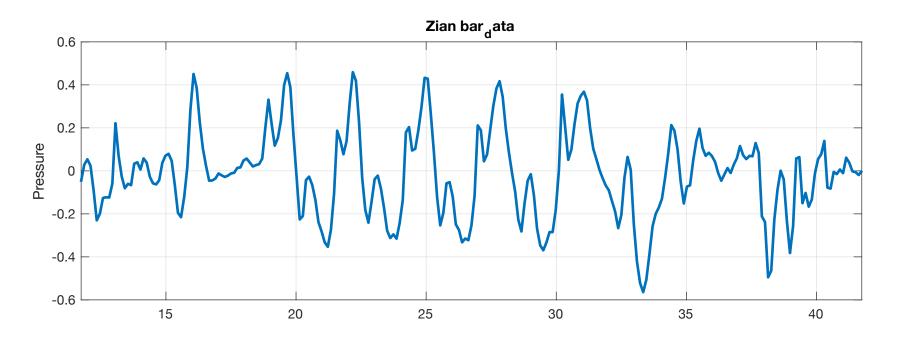
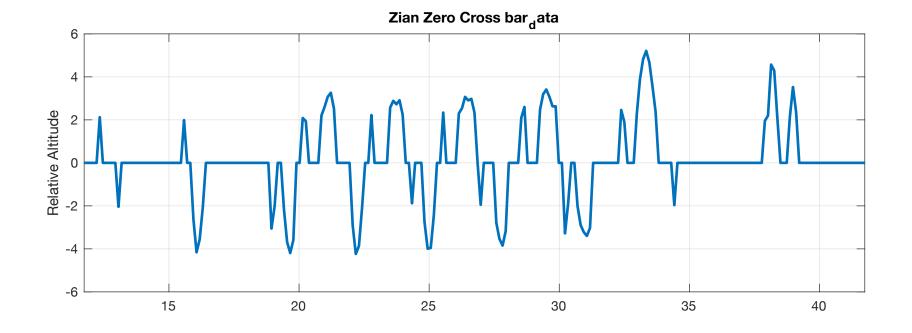
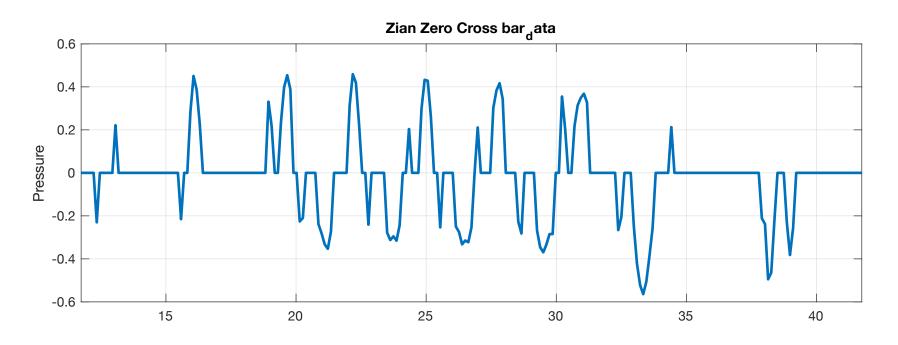


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-249.000	-214.000	-78.000	-54.500	"accel_data"
'Y'	-238.000	-207.000	-73.000	-46.000	"accel_data"
'X'	-256.000	-217.000	-74.000	-67.000	"accel_data"

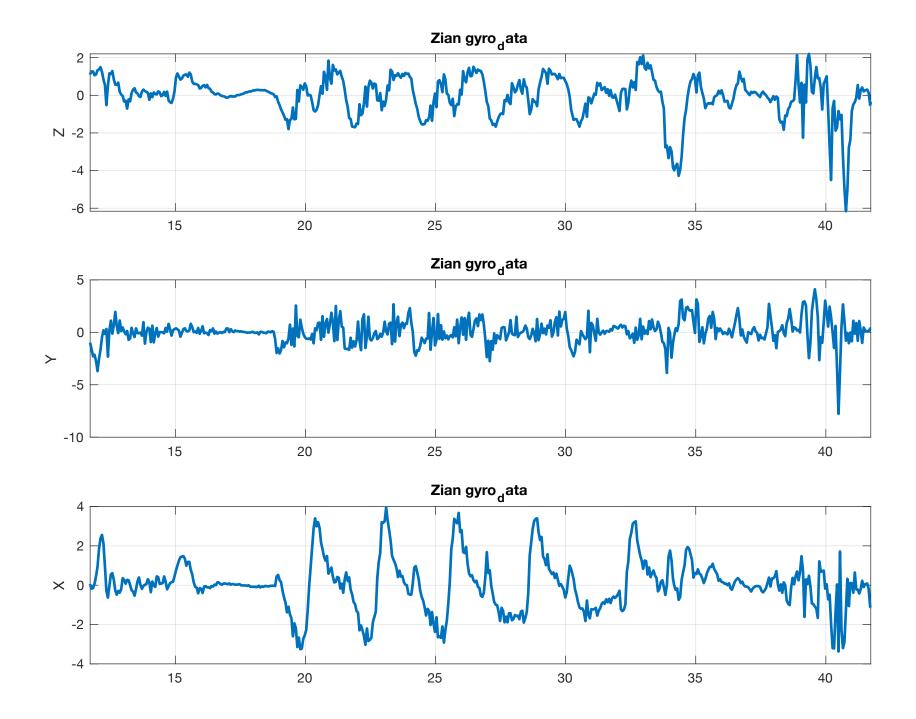


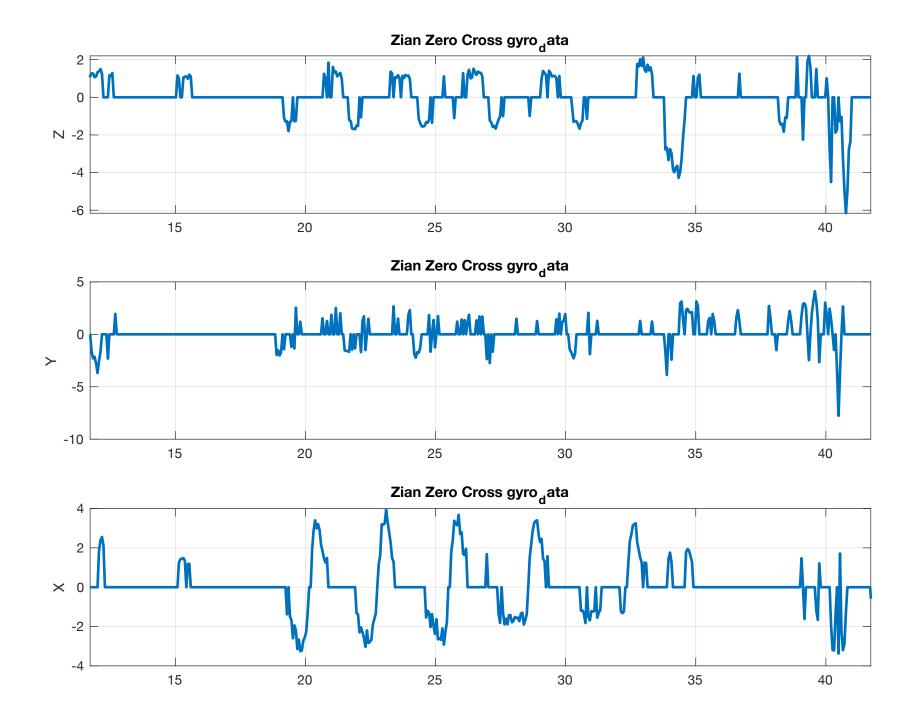




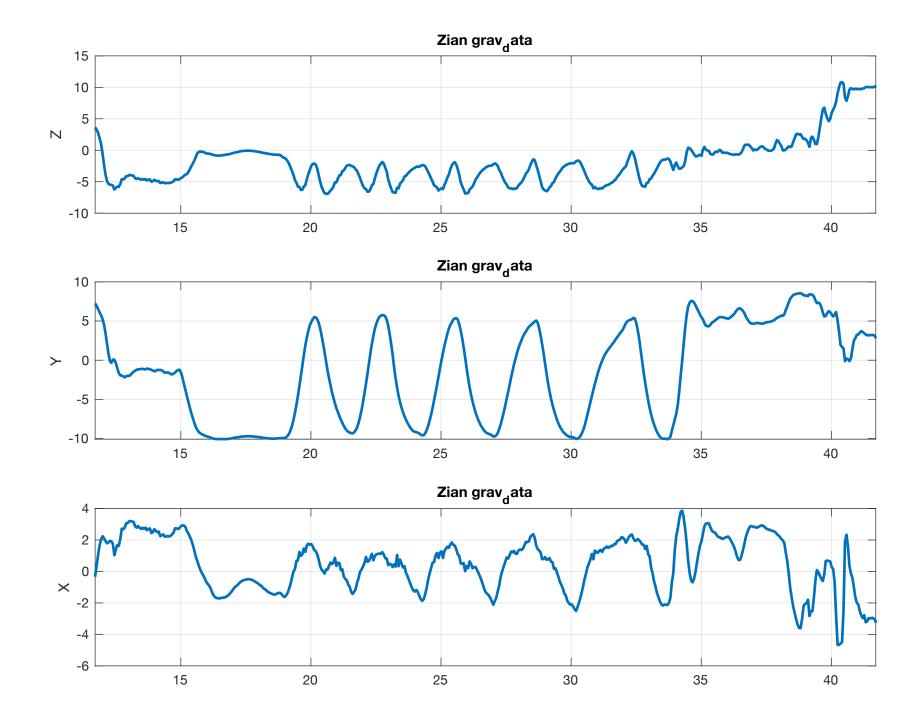


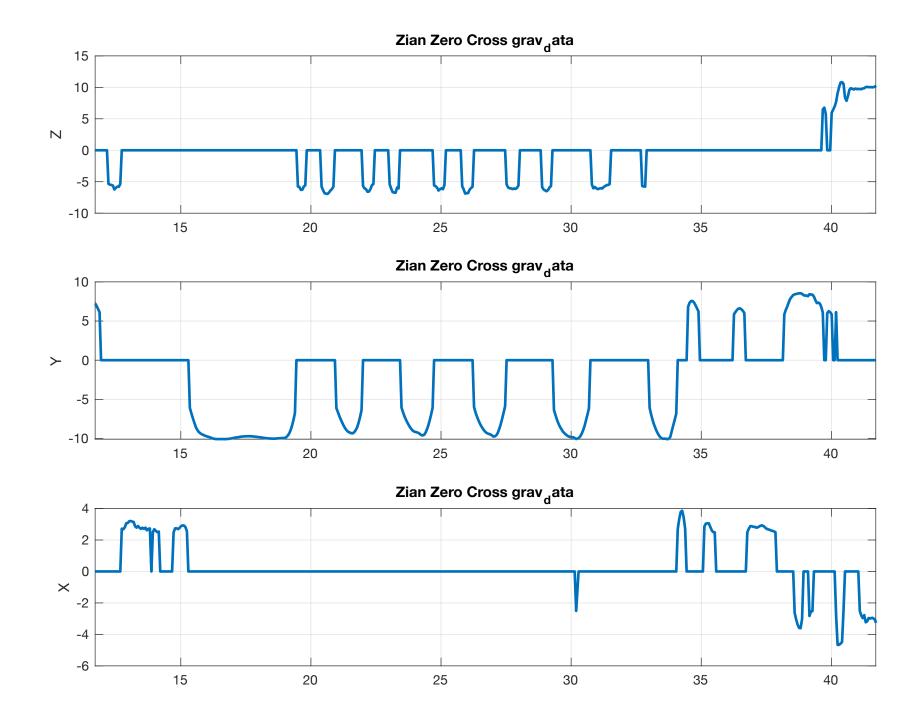
Axis	findpeaks	findpeaks_above_zero	$double_findpeaks$	zero_cross	Sensor
"Relative Altitude"	-51.000	-33.000	-9.000	-12.000	"bar_data"
"Pressure"	-57.000	-45.000	-13.000	-12.000	"bar_data"



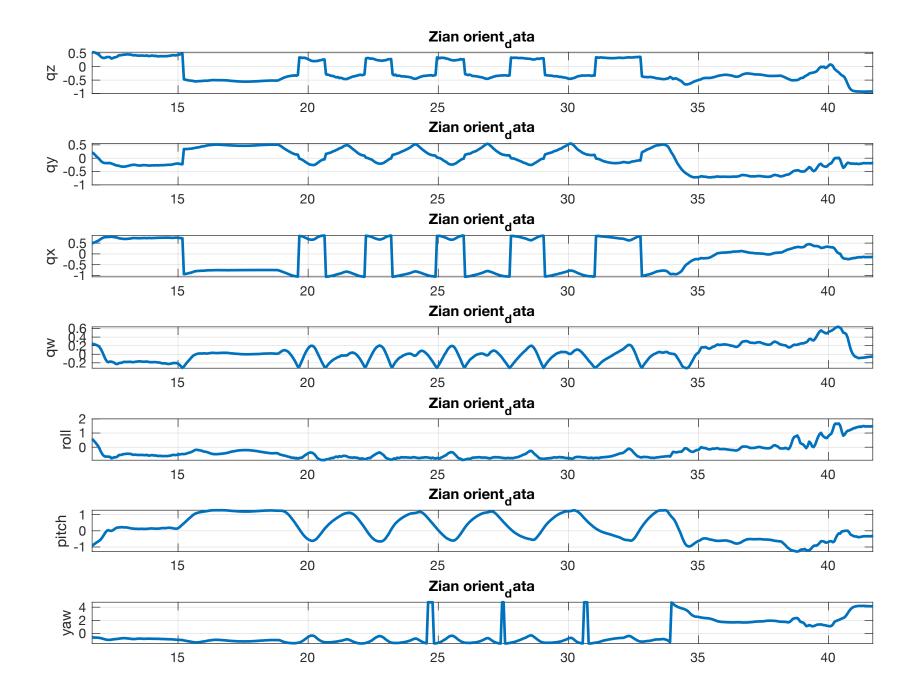


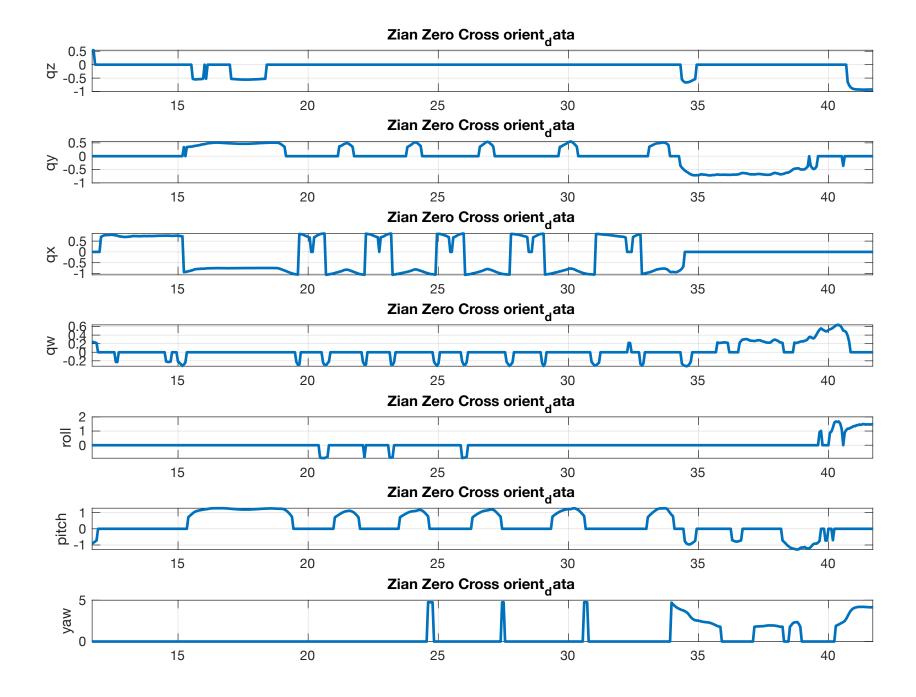
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
	-195.000	-149.000	-45.000	-21.000	"gyro_data"
'Y'	-237.000	-195.000	-62.000	-37.000	"gyro_data"
'X'	-177.000	-121.000	-39.000	-15.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-92.000	-37.000	-10.000	-3.750	"grav_data"
'Y'	-54.000	-39.000	-9.000	-3.000	"grav_data"
'X'	-111.000	-85.000	-15.000	-4.750	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-108.000	-64.000	-18.000	-1.750	"orient_data"
'qy'	-79.000	-30.000	-8.000	-2.000	"orient_data"
'qx'	-83.000	-41.000	-9.000	-6.000	"orient_data"
'qw'	-76.000	-41.000	-9.000	-7.500	"orient_data"
'roll'	-121.000	-33.000	-6.000	-0.250	"orient_data"
'pitch'	-51.000	-19.000	-2.000	-3.000	"orient_data"
'yaw'	-74.000	-28.000	-7.000	0.500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Y"	'zero_cross'	46.000
'bar_data'	"Relative Altitude"	'double_findpeaks'	9.000
'gyro_data'	"X"	'zero_cross'	15.500
'grav_data'	"Y"	'zero_cross'	3.000
'orient data'	"roll"	'zero cross'	0.250