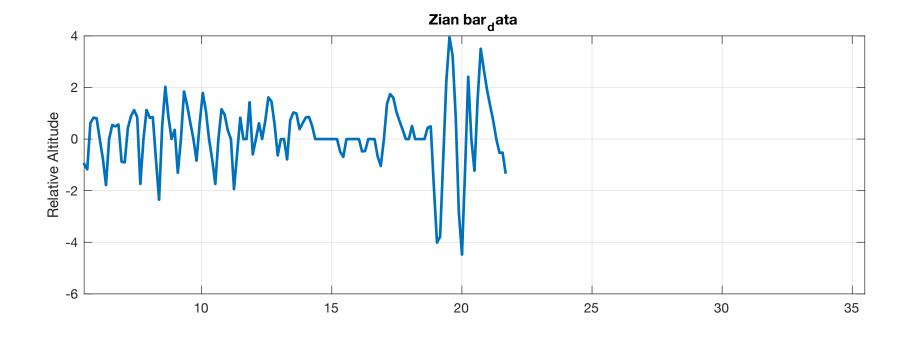
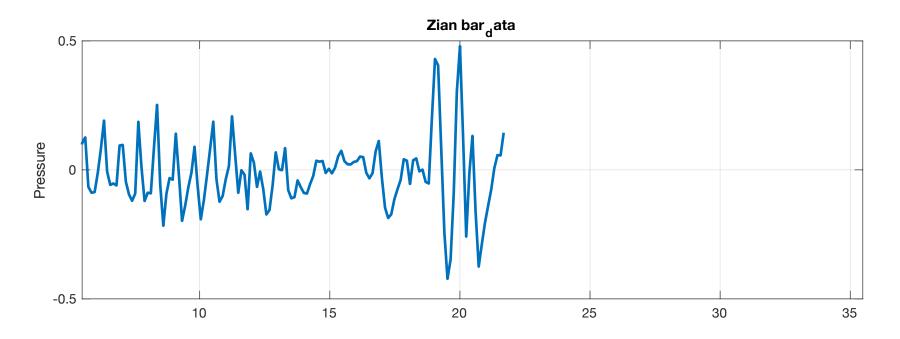
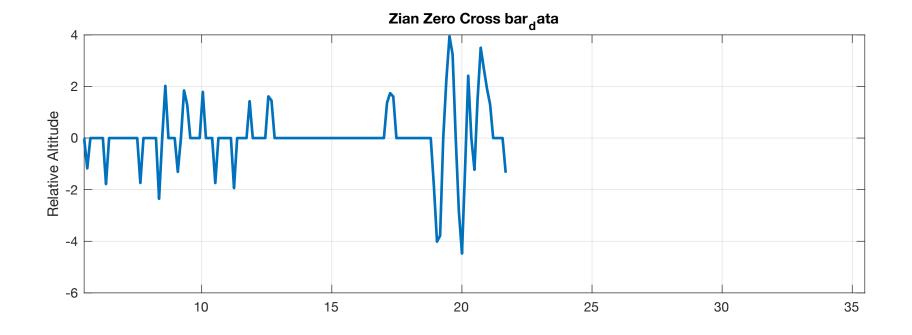
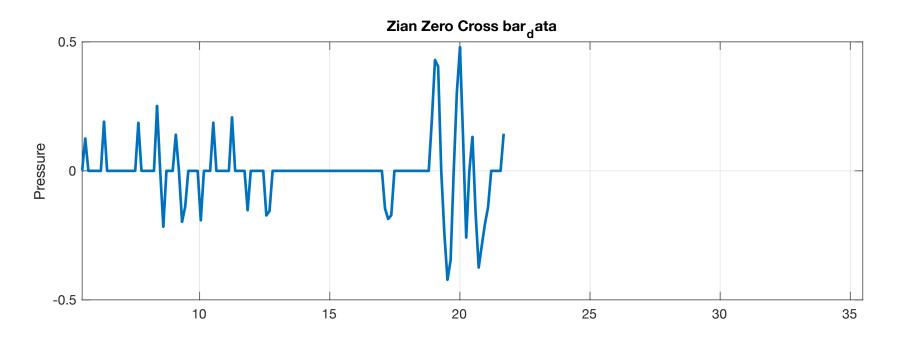


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-97.000	-81.000	-31.000	-24.000	"accel_data"
'Y'	-82.000	-61.000	-27.000	-24.500	"accel_data"
'X'	-111.000	-91.000	-33.000	-24.000	"accel_data"

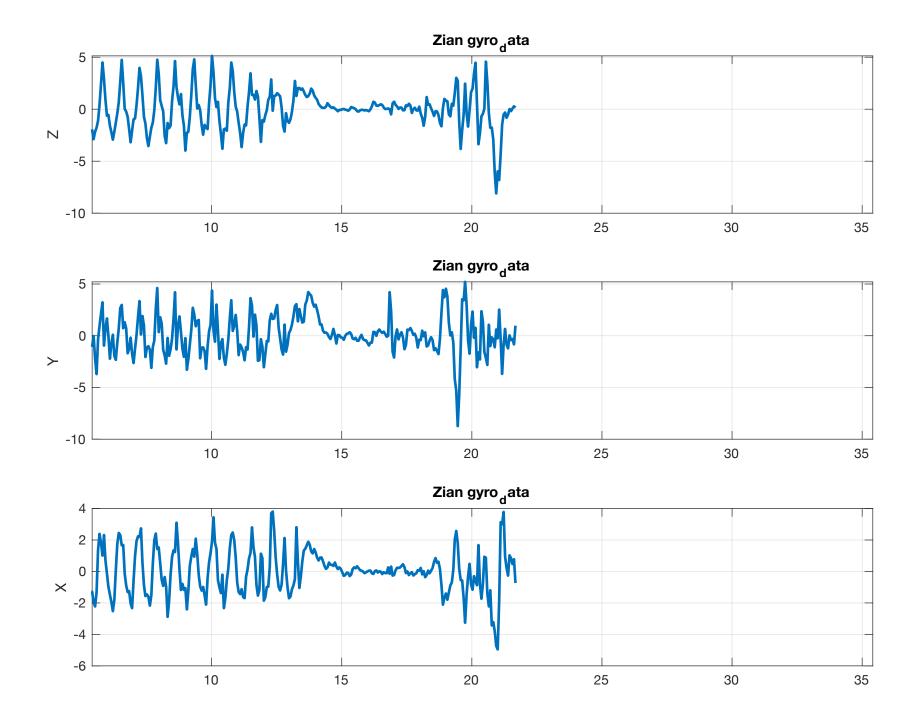


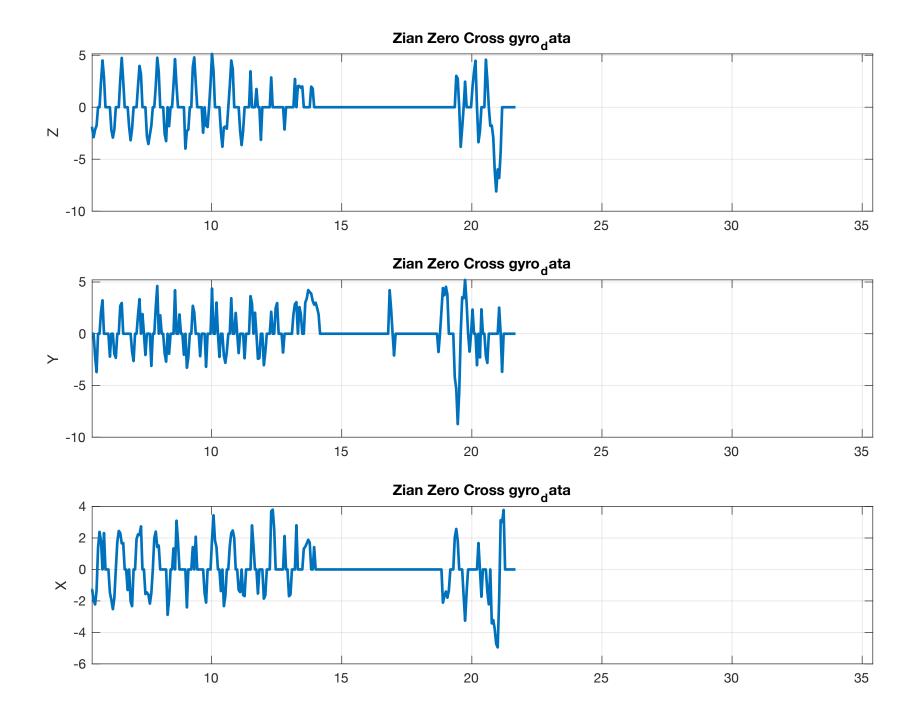




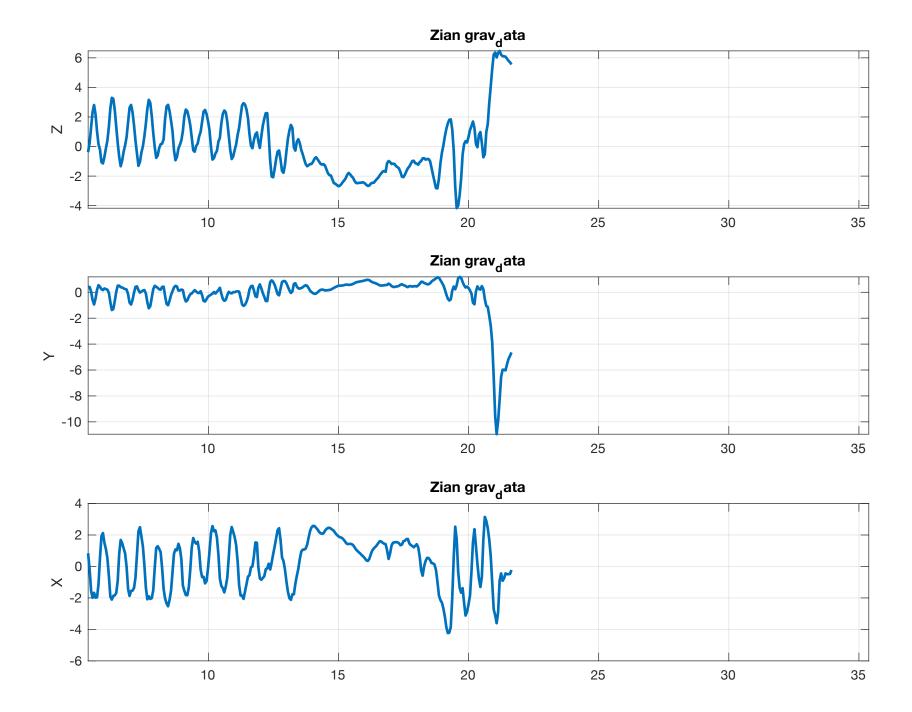


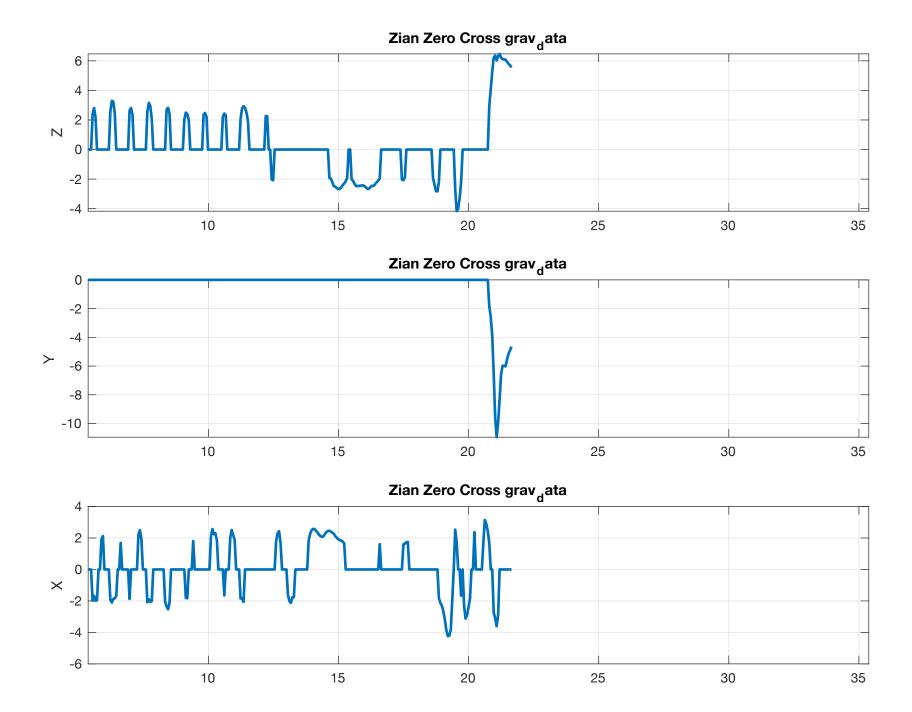
Axis	findpeaks	findpeaks_above_zero	${\bf double_findpeaks}$	zero_cross	Sensor
"Relative Altitude"	-36.000	-27.000	-12.000	-11.250	"bar_data"
"Pressure"	-40.000	-33.000	-14.000	-11.250	"bar_data"



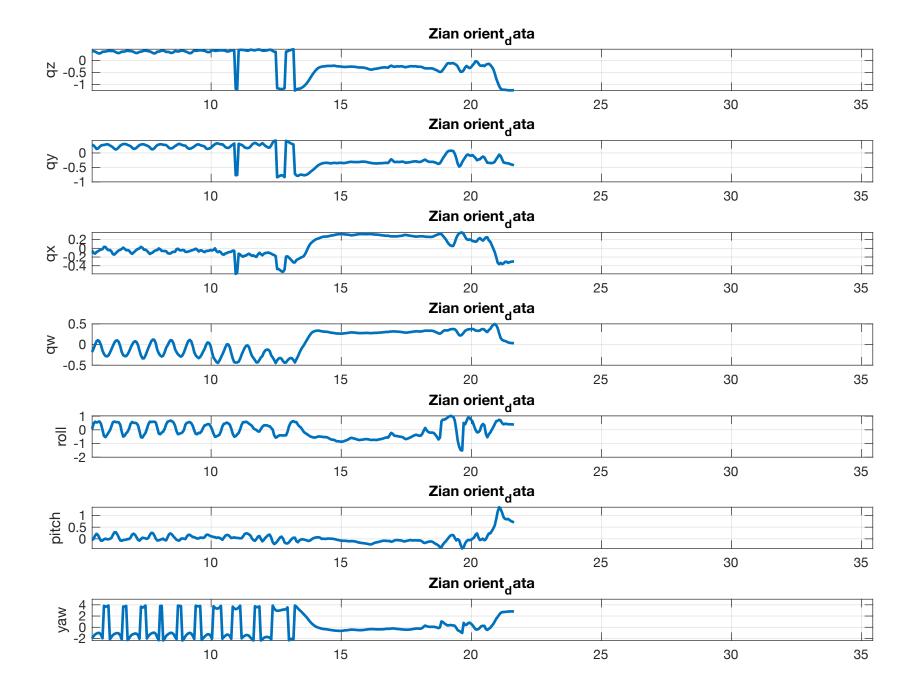


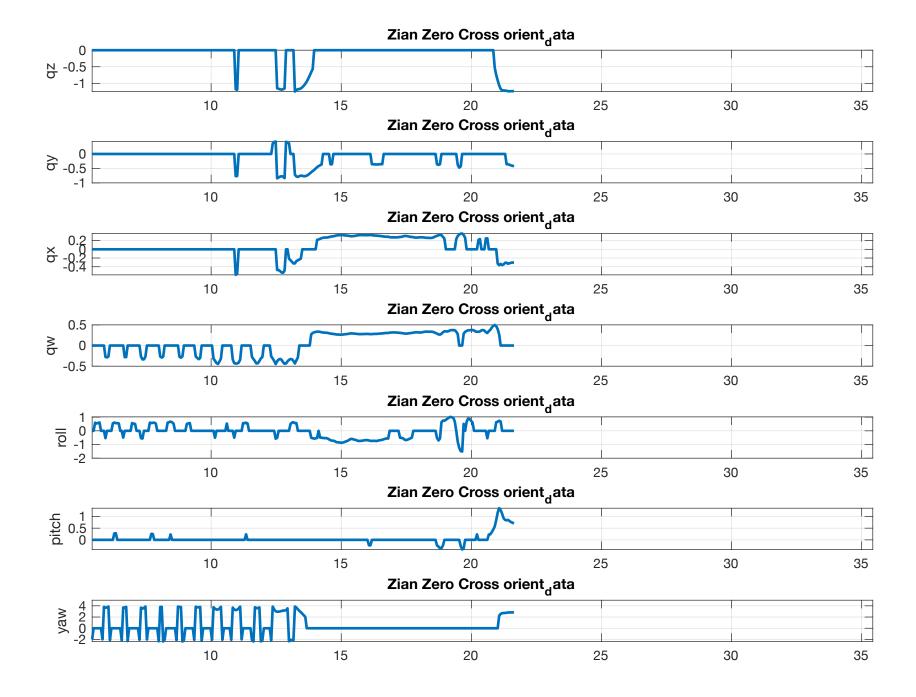
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-72.000	-54.000	-22.000	-19.500	"gyro_data"
'Y'	-92.000	-64.000	-27.000	-29.500	"gyro_data"
'X'	-83.000	-63.000	-27.000	-21.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-39.000	-21.000	-8.000	-10.250	"grav_data"
'Y'	-49.000	-48.000	-13.000	-0.750	"grav_data"
'X'	-38.000	-28.000	-13.000	-15.500	"grav data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-48.000	-29.000	-8.000	-2.250	"orient_data"
'qy'	-48.000	-28.000	-11.000	-5.750	"orient_data"
'qx'	-49.000	-17.000	-9.000	-4.250	"orient_data"
'qw'	-33.000	-23.000	-6.000	-7.500	"orient_data"
'roll'	-43.000	-31.000	-11.000	-15.000	"orient_data"
'pitch'	-51.000	-29.000	-15.000	-5.250	"orient_data"
'yaw'	-55.000	-33.000	-17.000	-20.750	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'zero_cross'	24.000
'bar_data'	"Relative Altitude"	'zero_cross'	11.250
'gyro_data'	"Z"	'zero_cross'	19.500
'grav_data'	"Y"	'zero_cross'	0.750
'orient data'	"qz"	'zero cross'	2.250