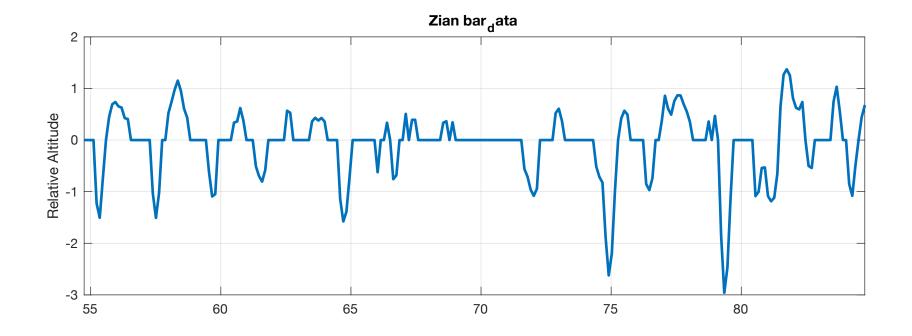
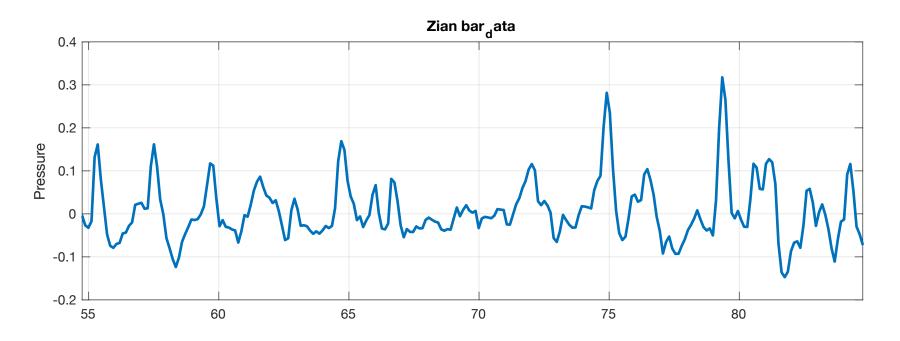
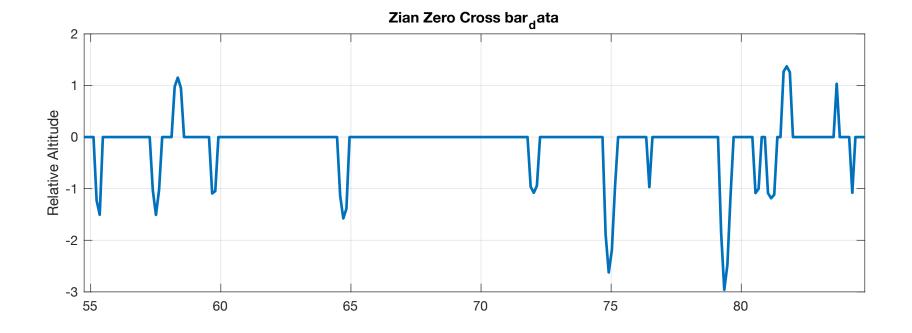
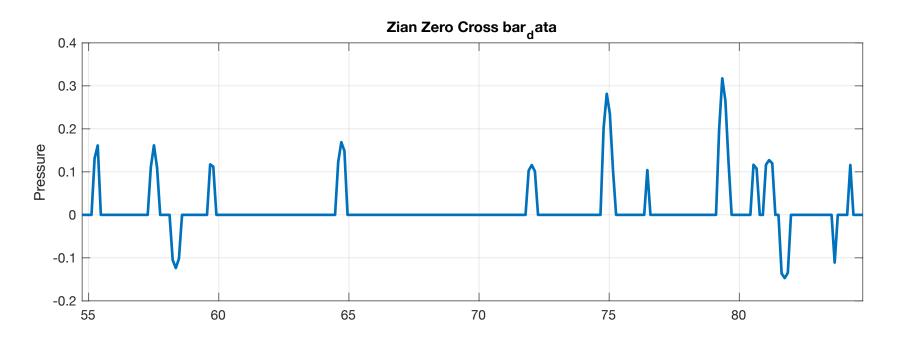


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-330.000	-269.000	-86.000	-26.500	"accel_data"
'Y'	-412.000	-340.000	-113.000	-52.500	"accel_data"
'X'	-384.000	-297.000	-96.000	-47.000	"accel_data"

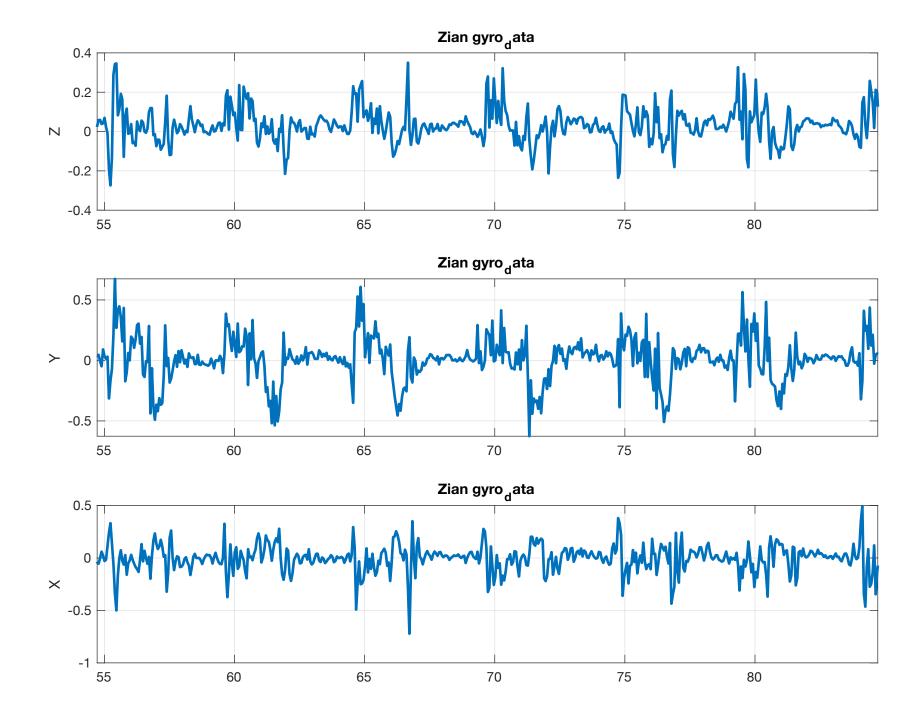


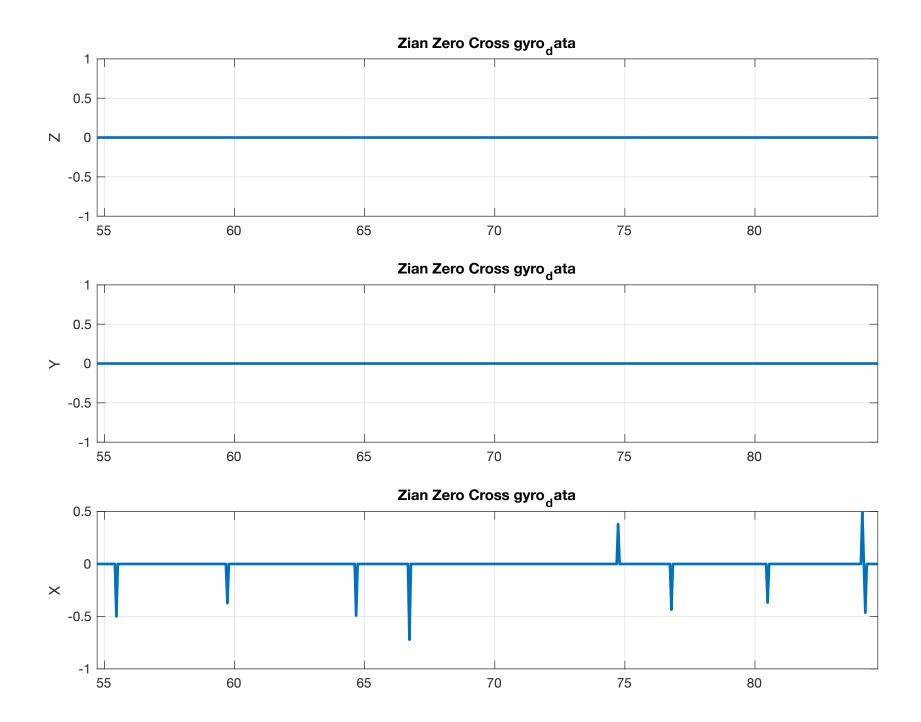




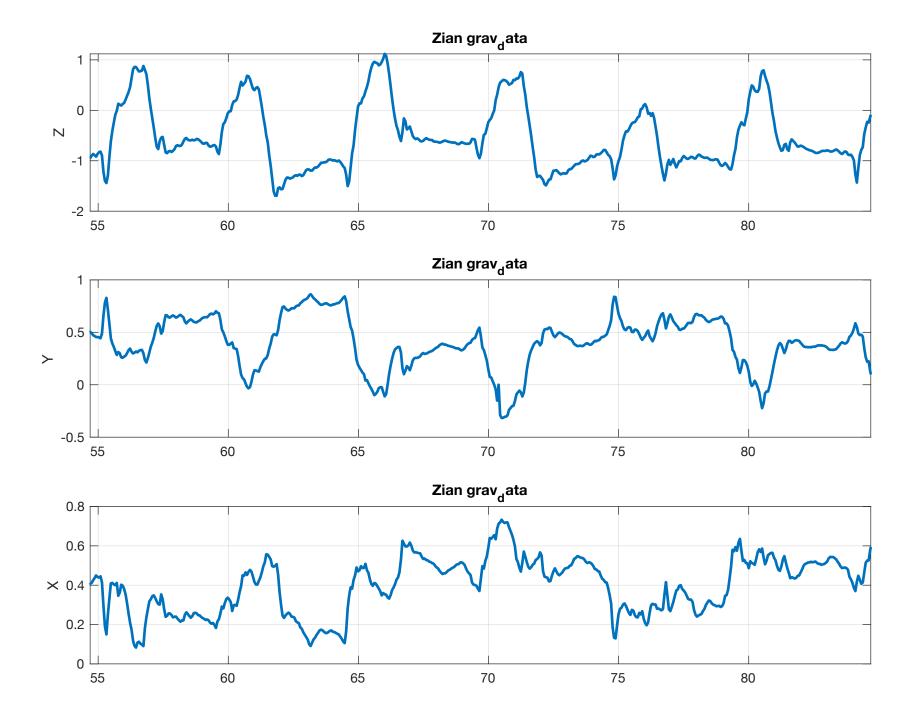


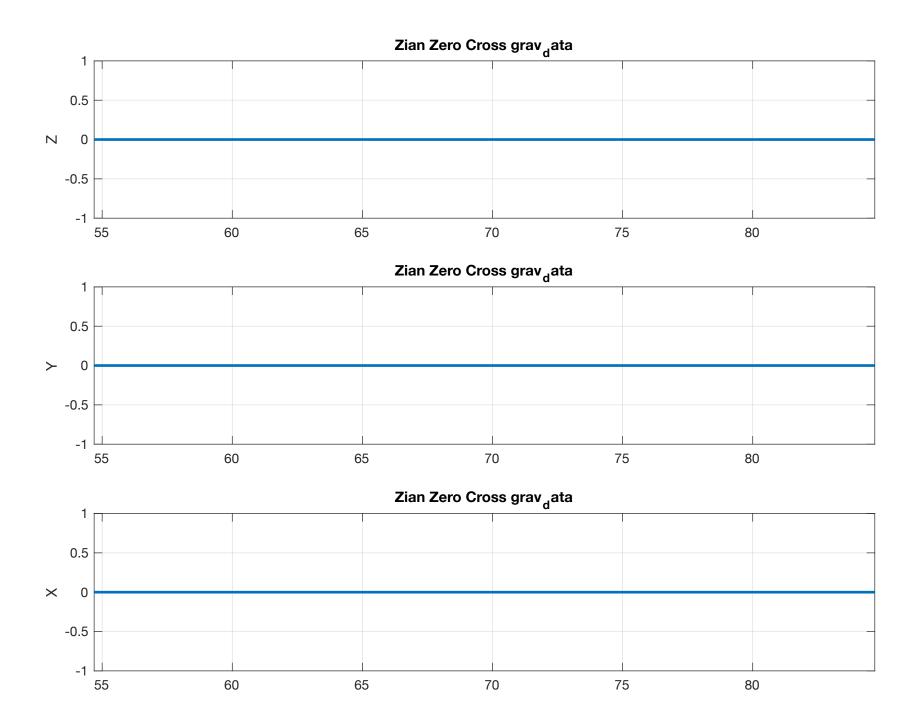
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-48.000	-37.000	-4.000	2.500	"bar_data"
"Pressure"	-101.000	-60.000	-20.000	2.000	"bar_data"



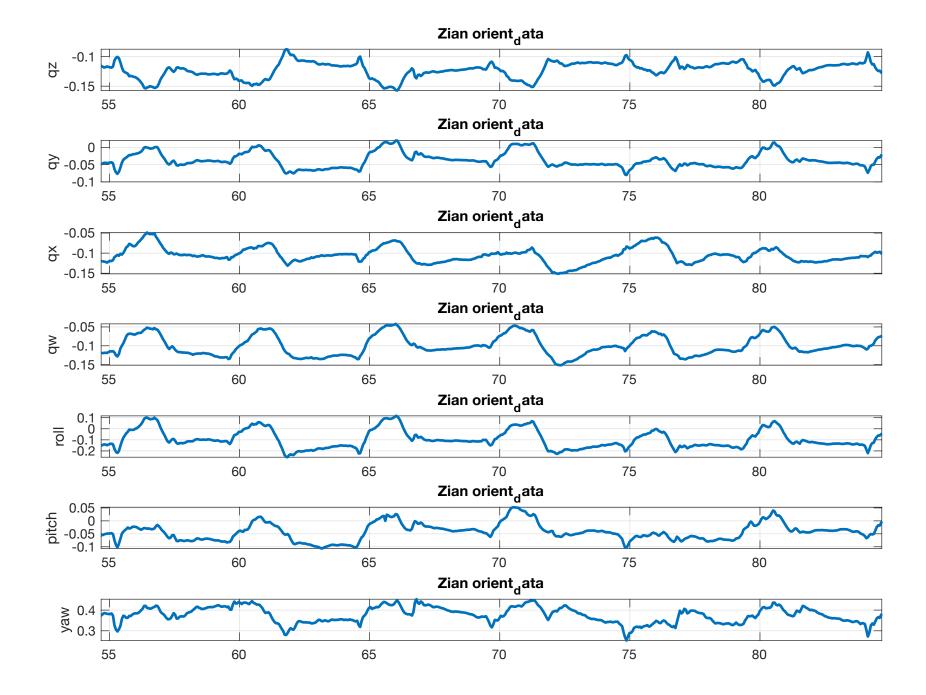


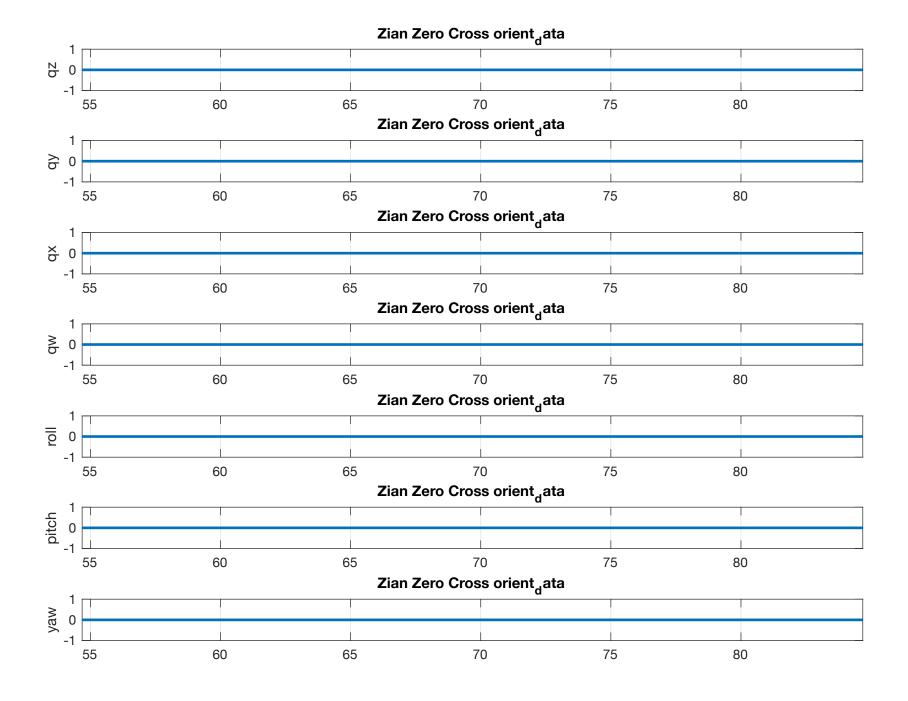
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-348.000	-302.000	-99.000	14.500	"gyro_data"
'Y'	-407.000	-324.000	-106.000	15.000	"gyro_data"
'X'	-329.000	-266.000	-91.000	5.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-154.000	-28.000	-4.000	15.500	"grav_data"
'Υ'	-157.000	-144.000	-25.000	16.000	"grav_data"
'X'	-184.000	-180.000	-28.000	16.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-160.000	16.000	16.000	16.000	"orient_data"
'qy'	-168.000	-10.000	1.000	16.000	"orient_data"
'qx'	-205.000	16.000	16.000	16.000	"orient_data"
'qw'	-146.000	16.000	16.000	16.000	"orient_data"
'roll'	-160.000	-24.000	-4.000	16.000	"orient_data"
'pitch'	-159.000	-14.000	3.000	16.000	"orient_data"
'yaw'	-188.000	-188.000	-36.000	16.000	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'zero_cross'	26.500
'bar_data'	"Pressure"	'zero_cross'	2.000
'gyro_data'	"X"	'zero_cross'	5.500
'grav_data'	"Z"	'double_findpeaks'	4.000
'orient_data'	"qy"	'double_findpeaks'	1.000