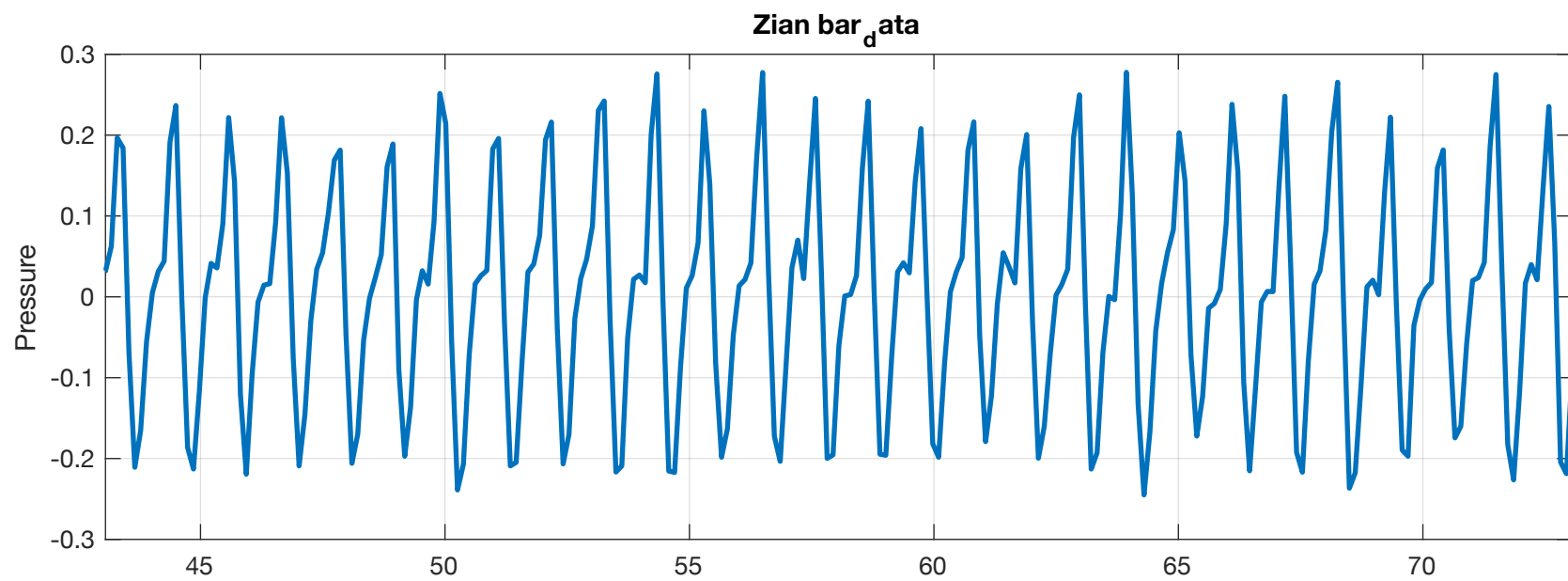
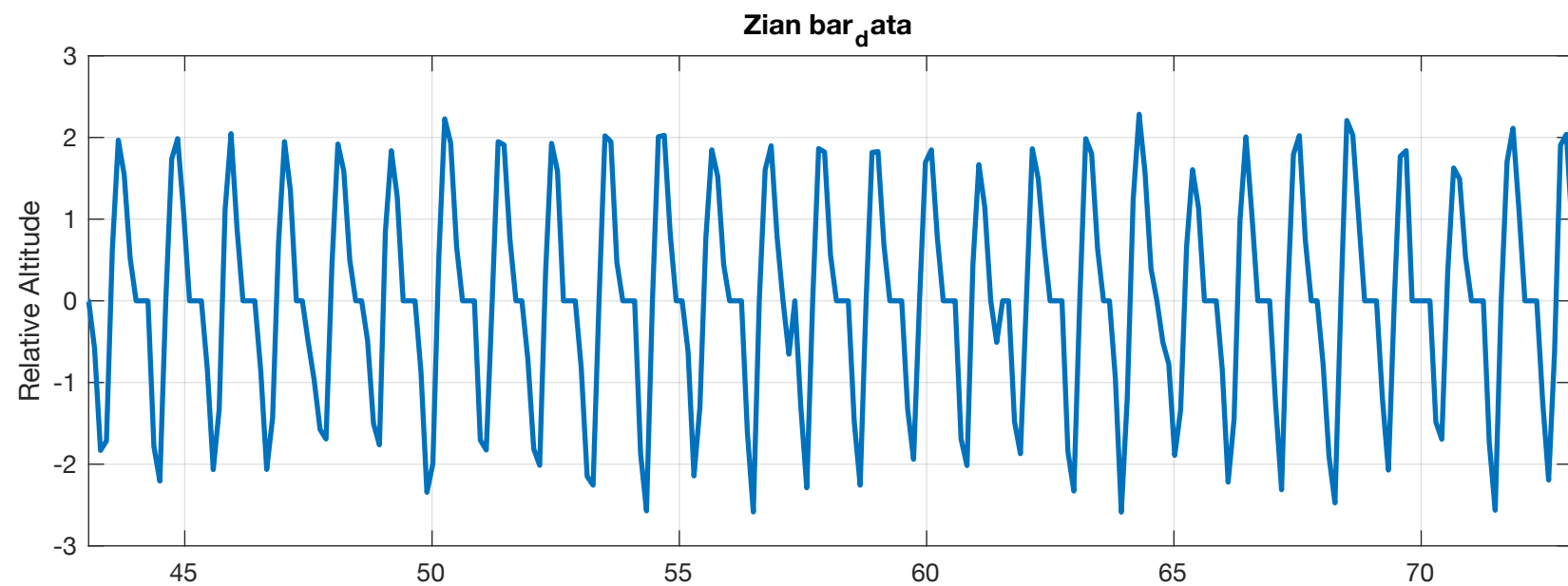
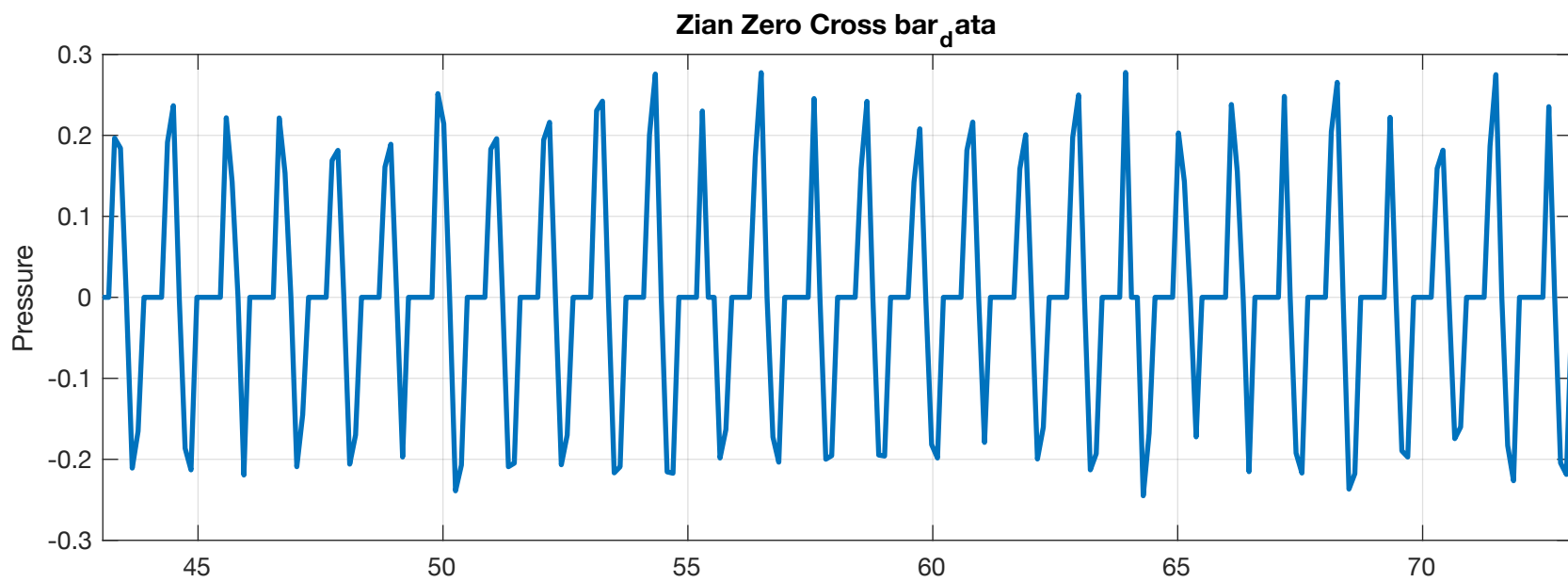
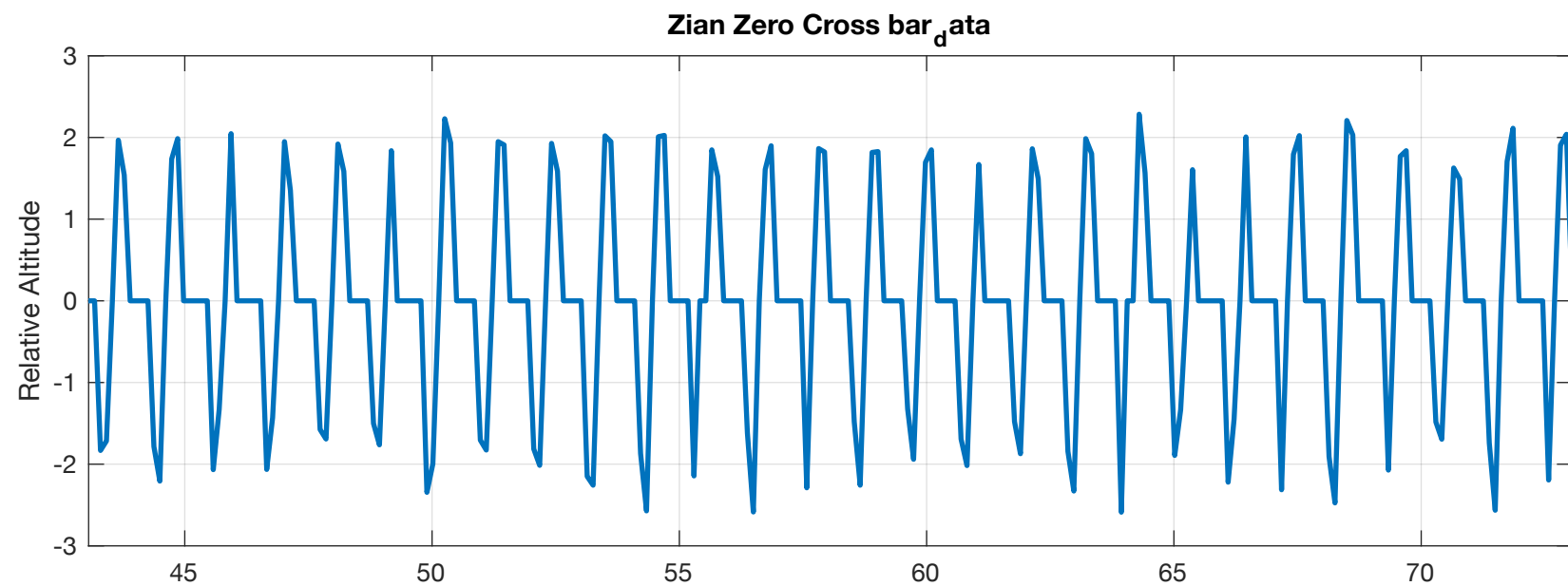
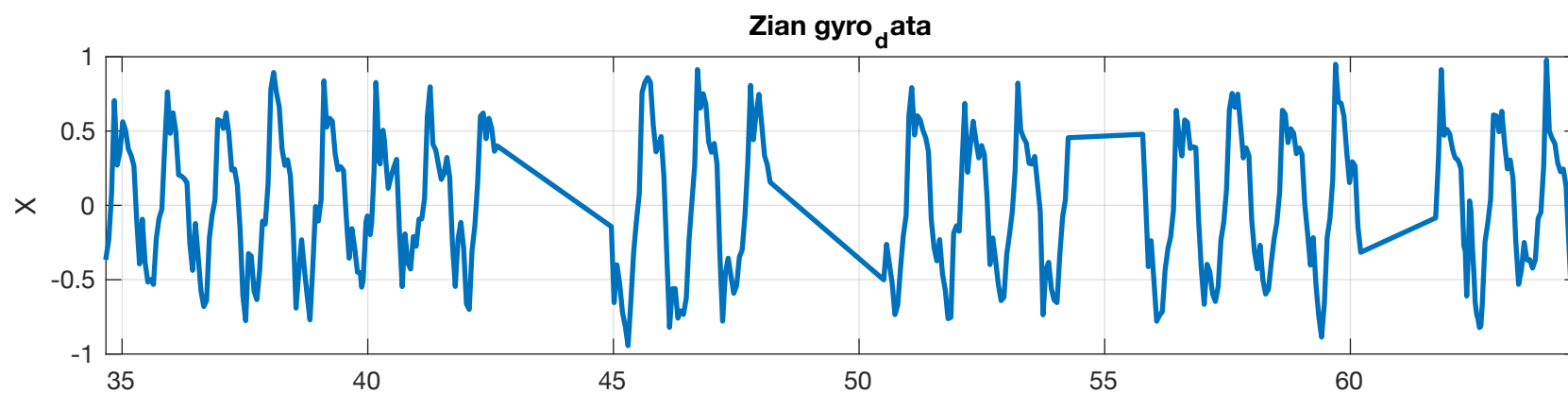
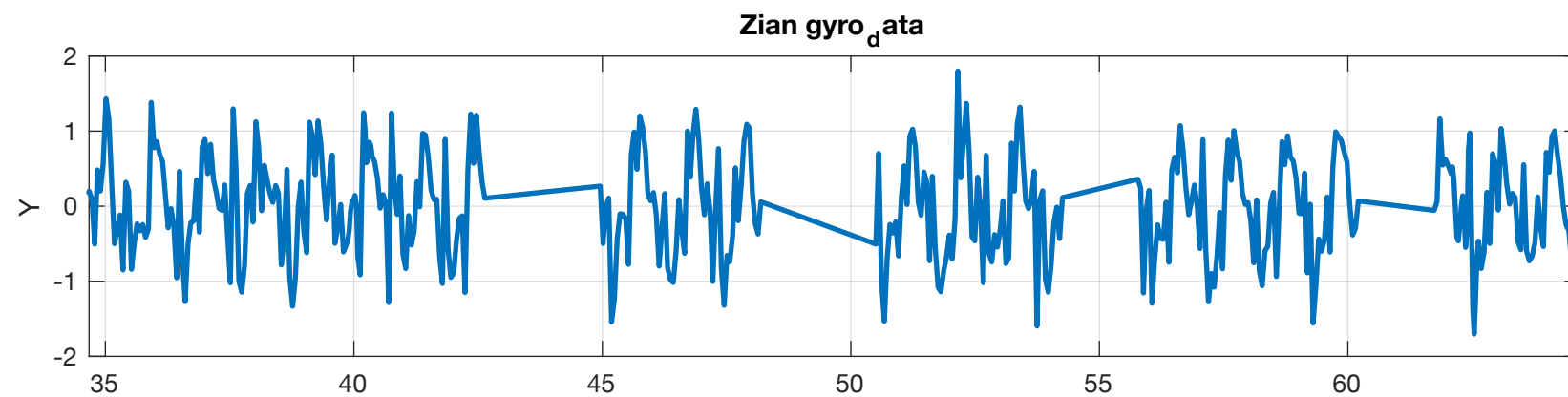


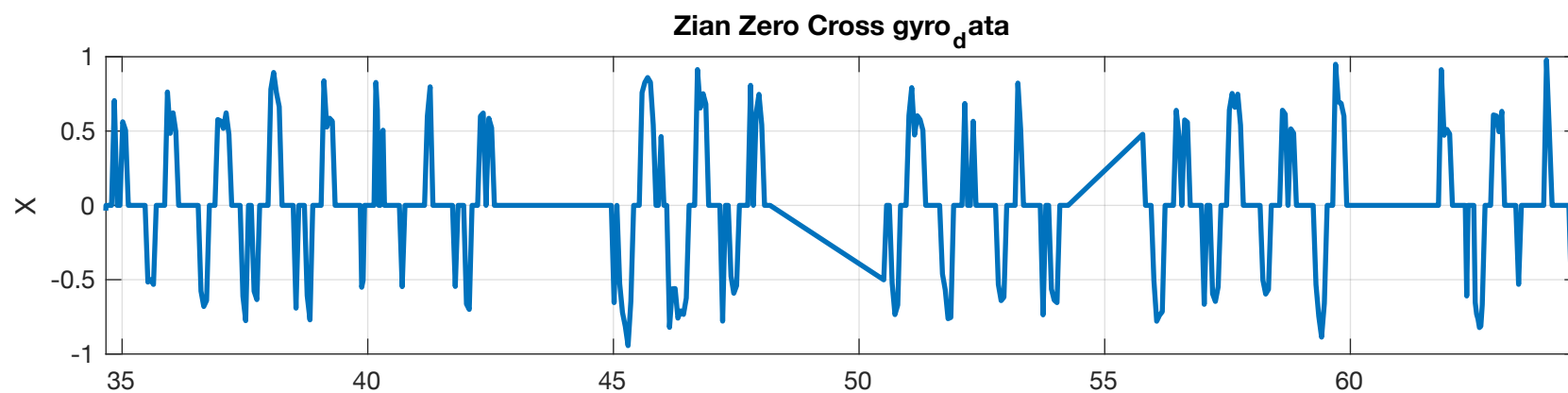
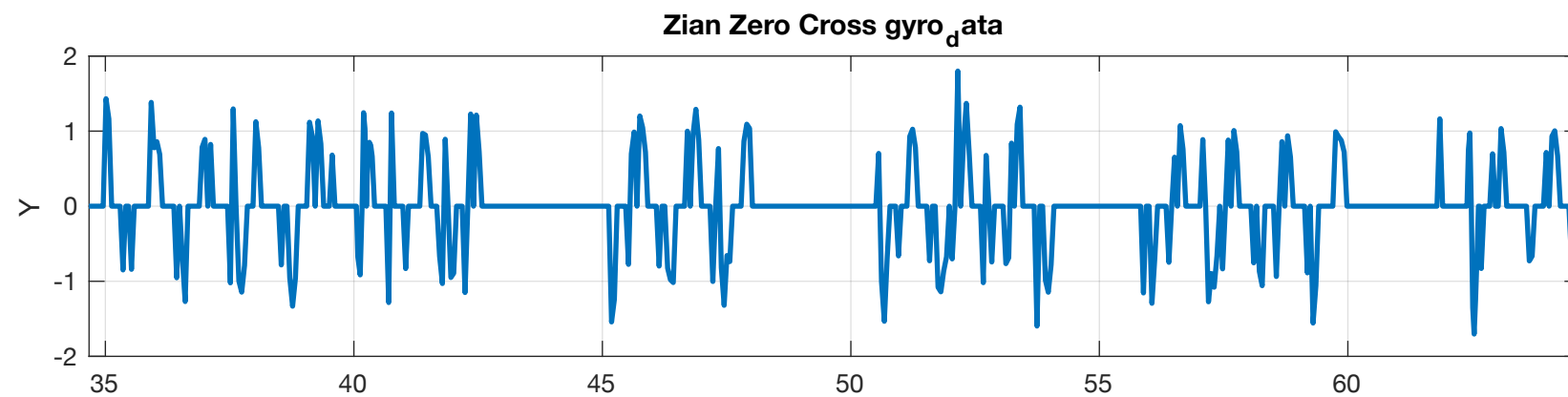
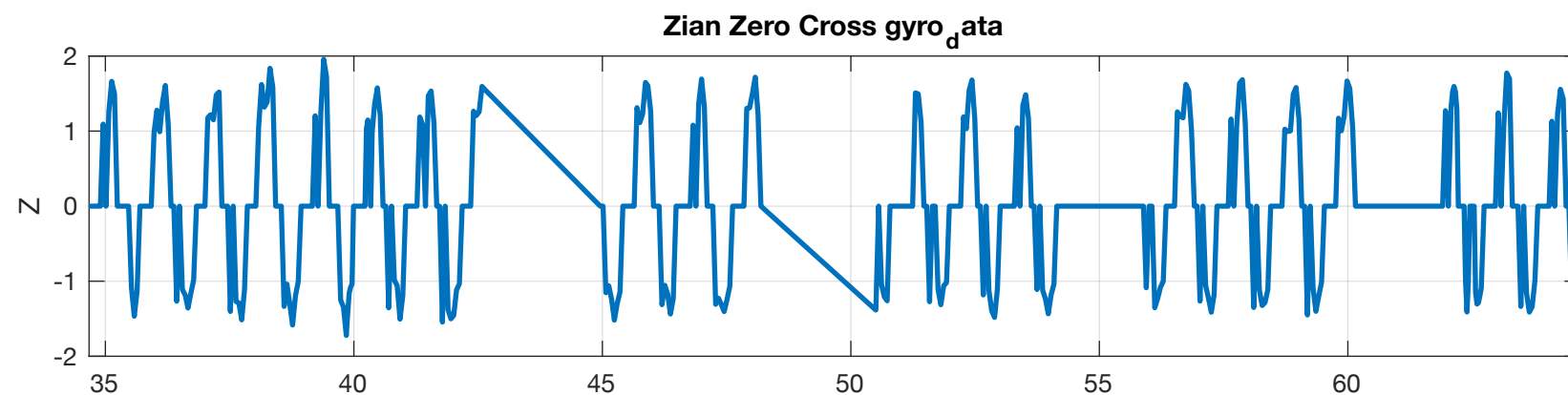
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-446.000	-149.000	26.000	85.000	"accel_data"
'Y'	-213.000	-143.000	95.000	4.000	"accel_data"
'X'	-402.000	-319.000	113.000	3.500	"accel_data"



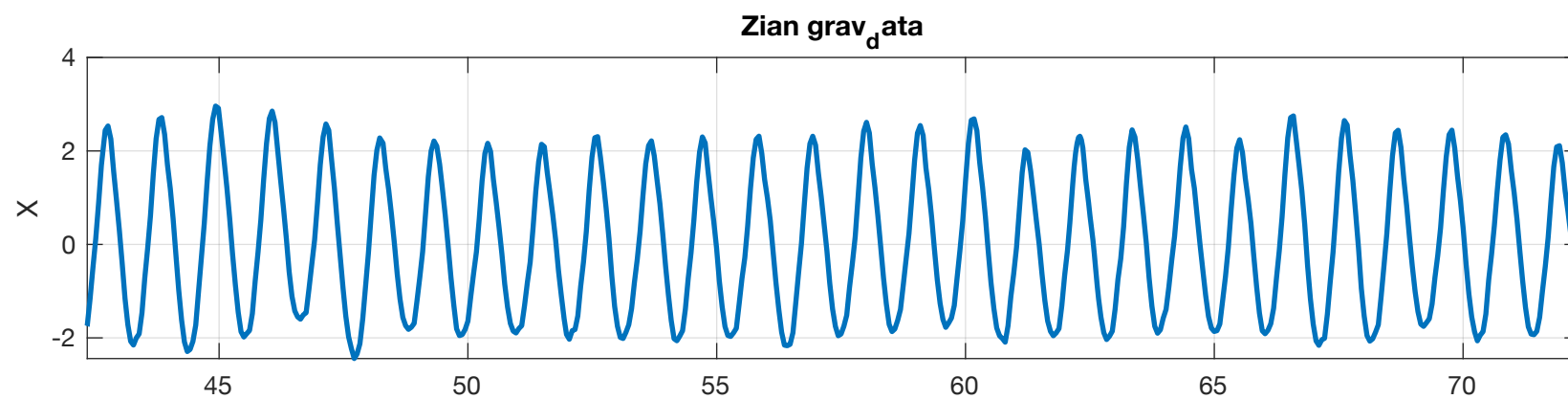
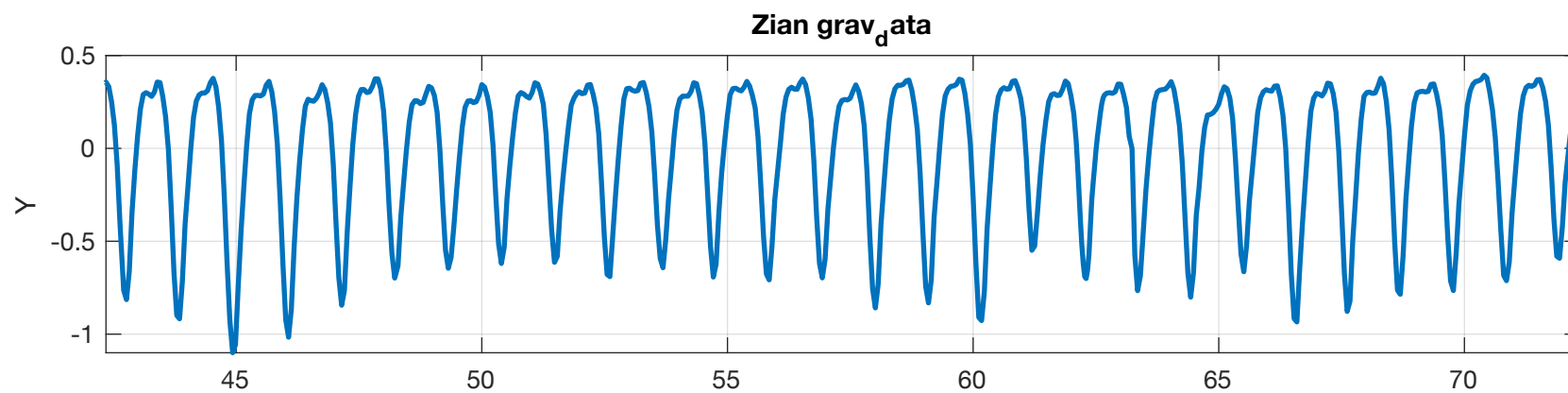
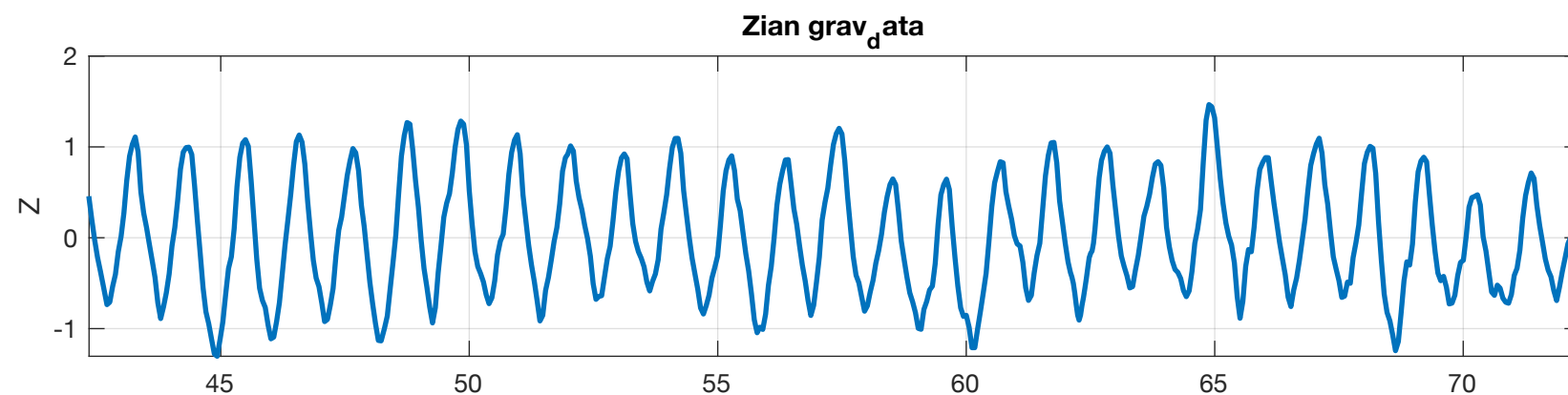


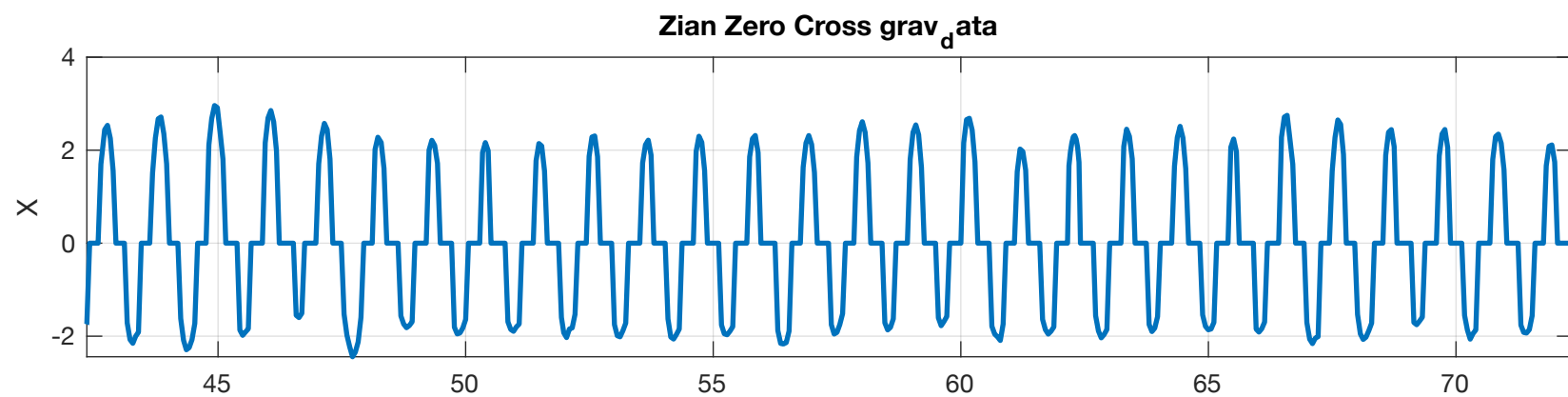
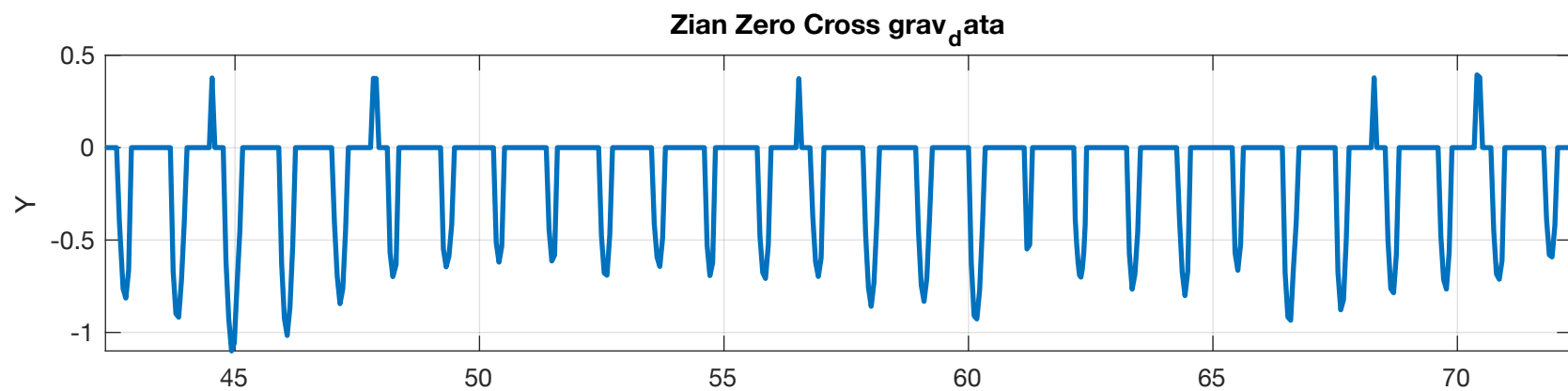
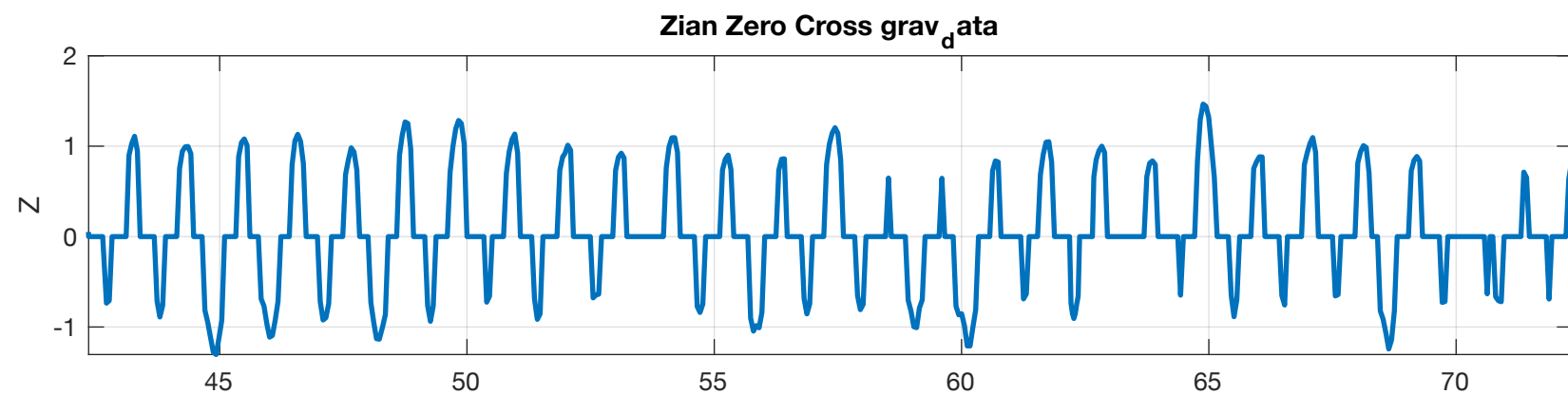
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	140.000	149.000	247.000	150.000	"bar_data"
"Pressure"	81.000	85.000	214.000	150.000	"bar_data"



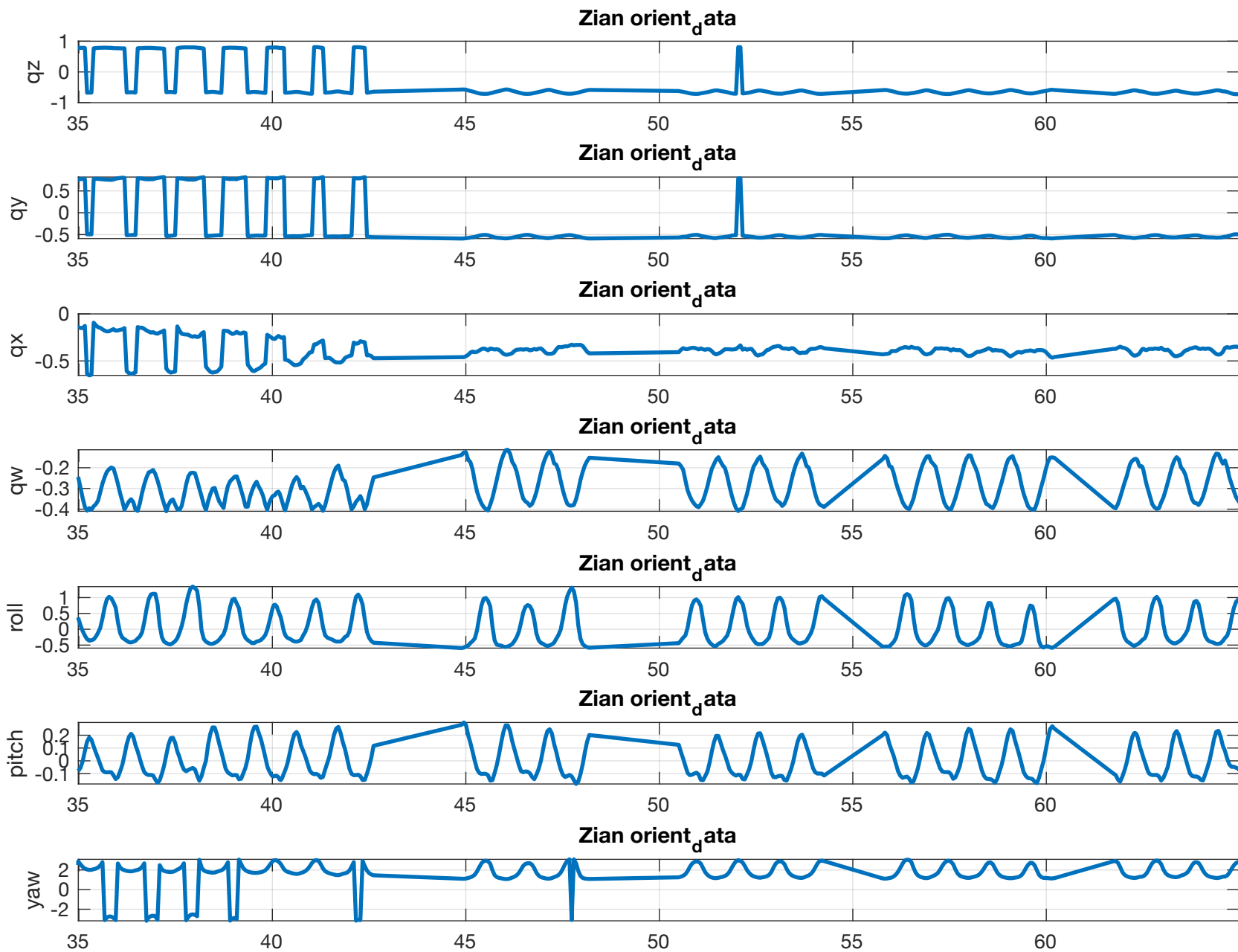


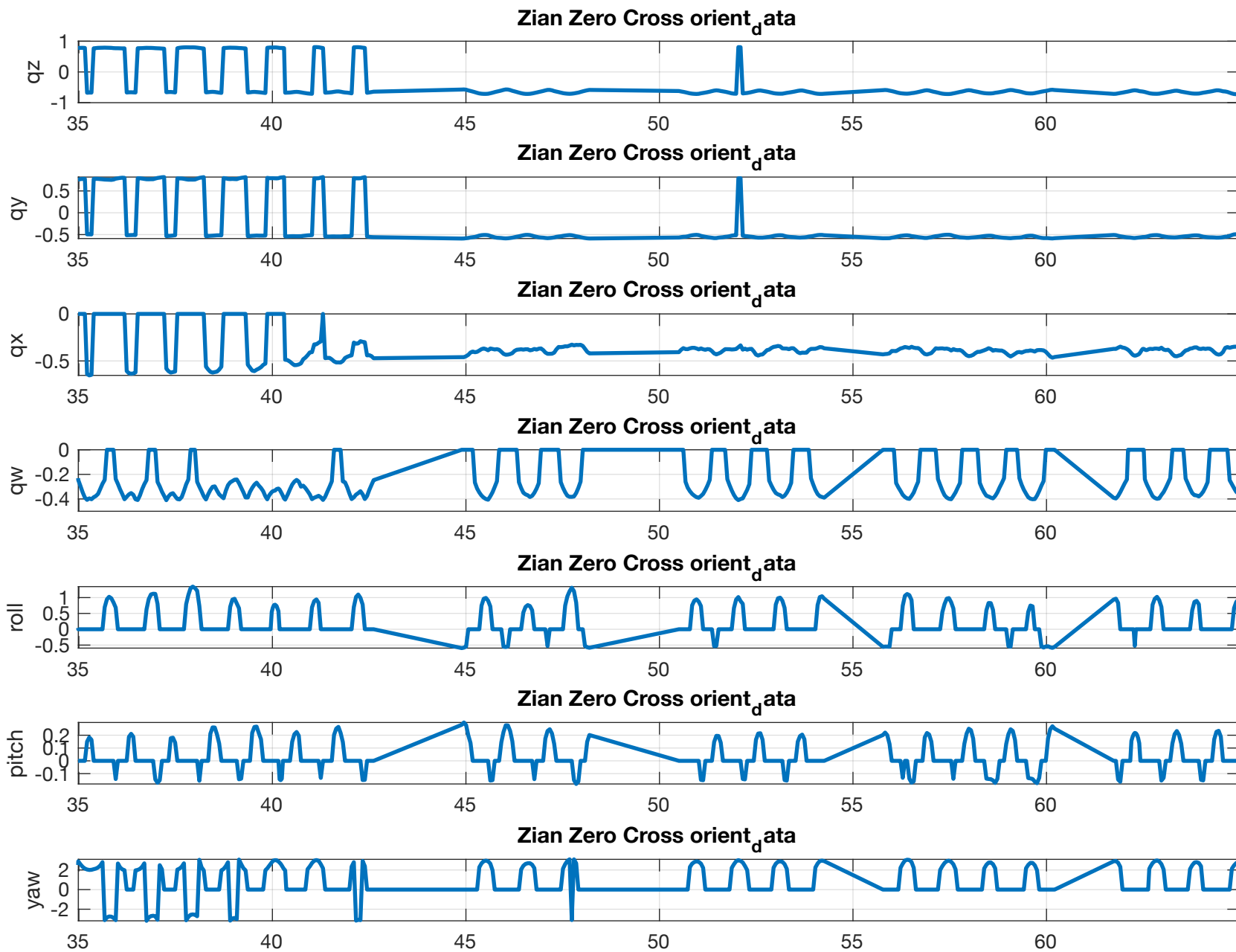
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-60.000	55.000	187.000	116.500	"gyro_data"
'Y'	-293.000	-152.000	129.000	99.000	"gyro_data"
'X'	-145.000	-8.000	179.000	136.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	111.000	138.000	241.000	181.250	"grav_data"
'Y'	33.000	39.000	189.000	208.500	"grav_data"
'X'	146.000	149.000	253.000	154.500	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	129.000	188.000	265.000	273.750	"orient_data"
'qy'	13.000	108.000	240.000	282.250	"orient_data"
'qx'	-1.000	169.000	253.000	283.000	"orient_data"
'qw'	137.000	200.000	270.000	266.000	"orient_data"
'roll'	156.000	183.000	259.000	222.250	"orient_data"
'pitch'	98.000	180.000	214.000	184.000	"orient_data"
'yaw'	128.000	193.000	258.000	238.750	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'zero_cross'	3.500
'bar_data'	"Pressure"	'findpeaks'	81.000
'gyro_data'	"X"	'findpeaks_above_zero'	8.000
'grav_data'	"Y"	'findpeaks'	33.000
'orient_data'	"qx"	'findpeaks'	1.000