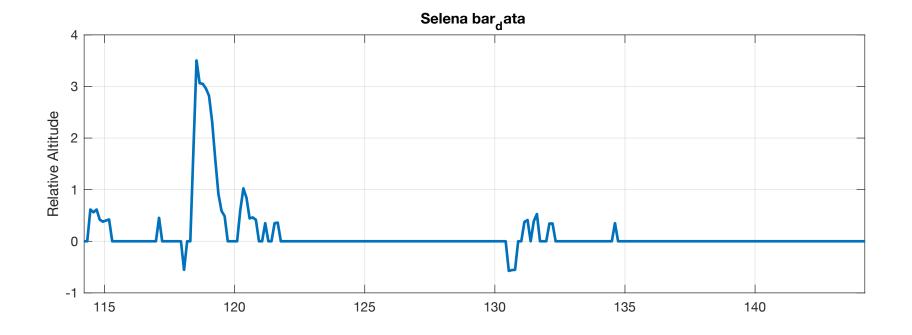
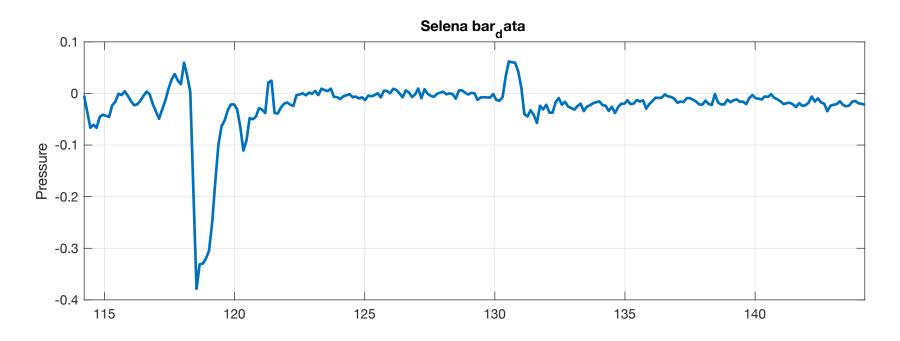
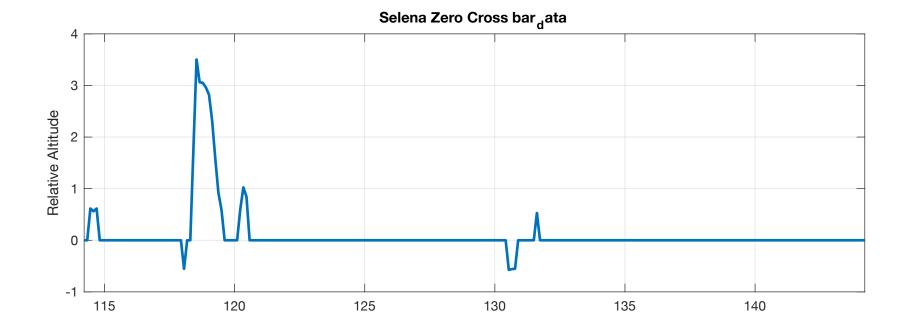
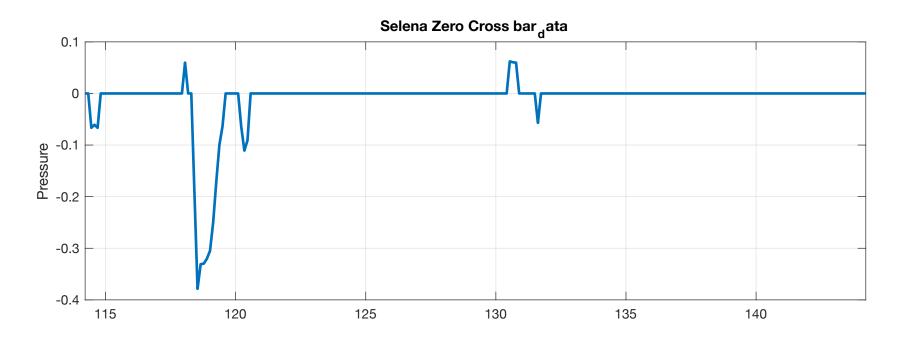


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-396.000	-339.000	-131.000	-80.000	"accel_data"
'Y'	-558.000	-519.000	-183.000	-61.000	"accel_data"
'X'	-487.000	-407.000	-153.000	-59.000	"accel_data"

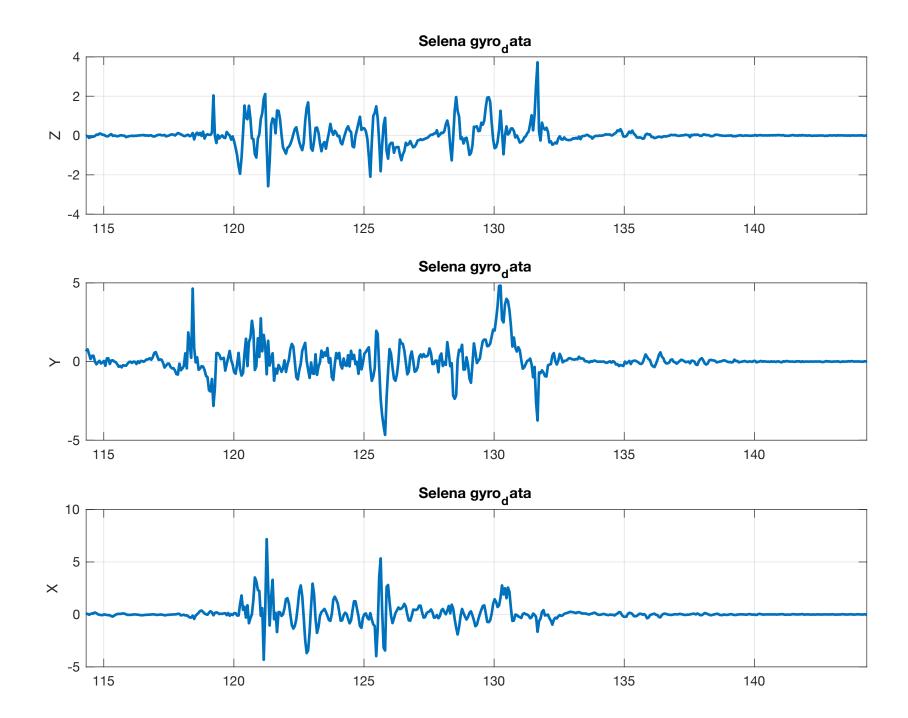


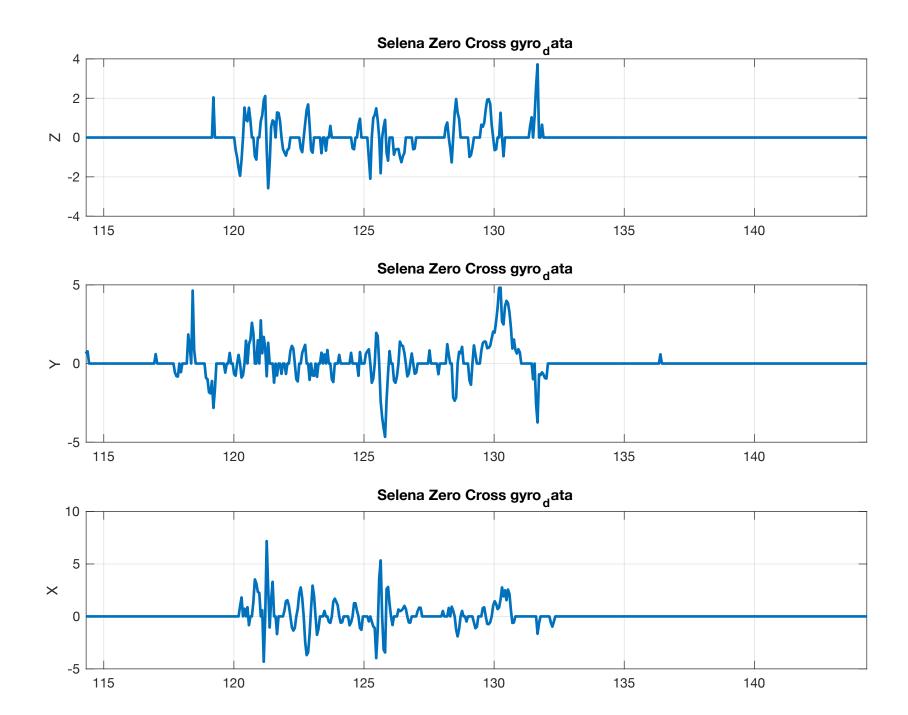




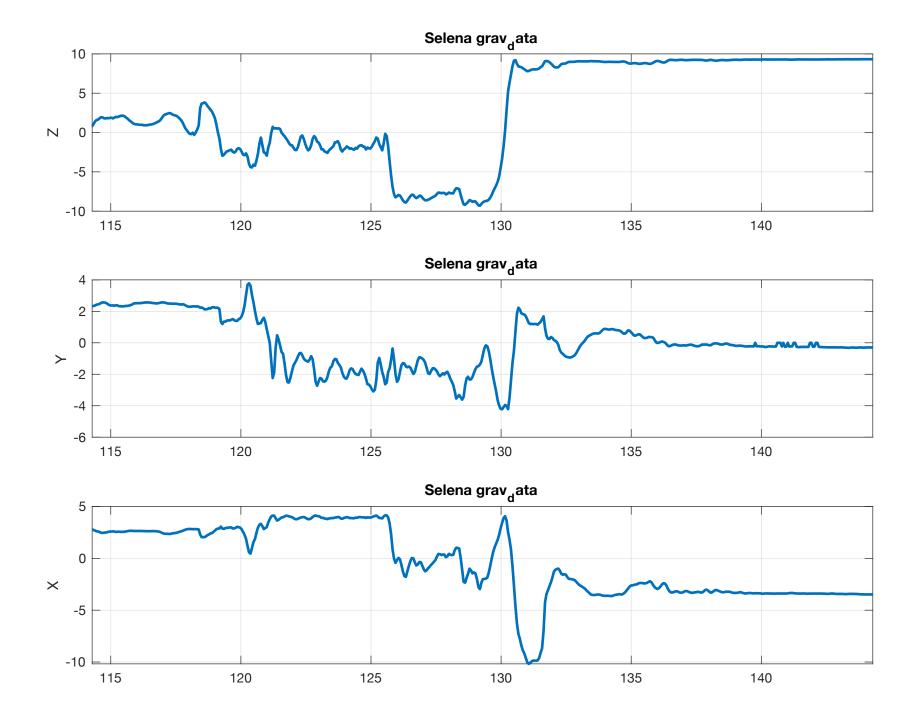


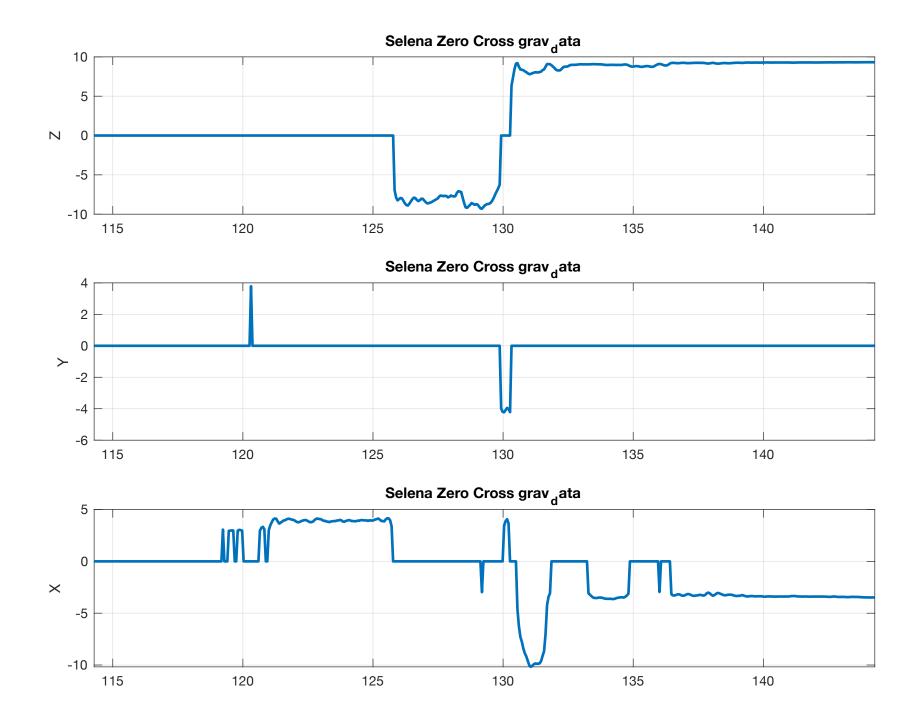
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-33.000	-31.000	-8.000	-7.000	"bar_data"
"Pressure"	-254.000	-151.000	-55.000	-7.000	"bar_data"



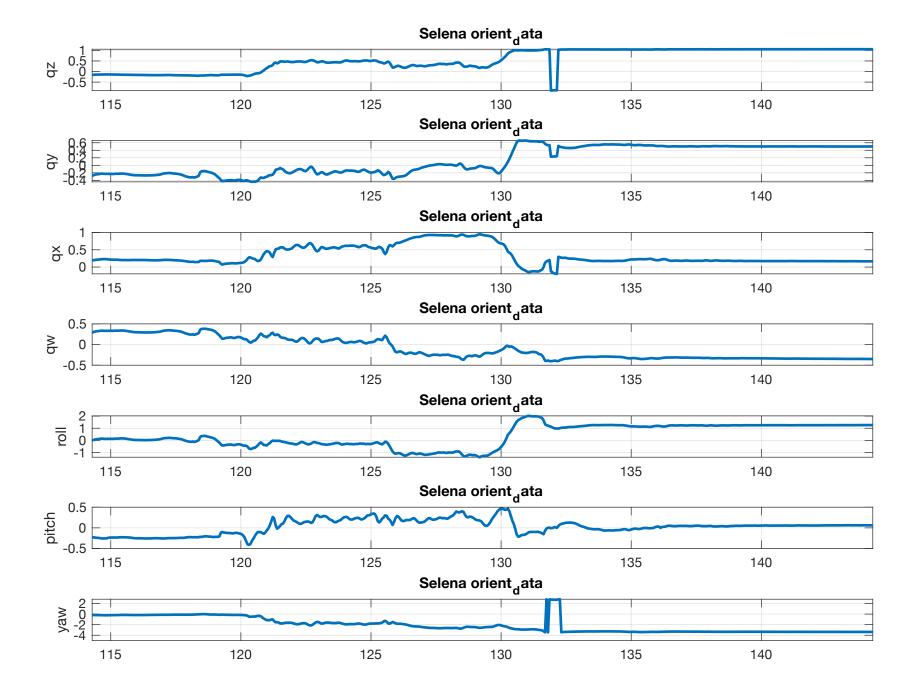


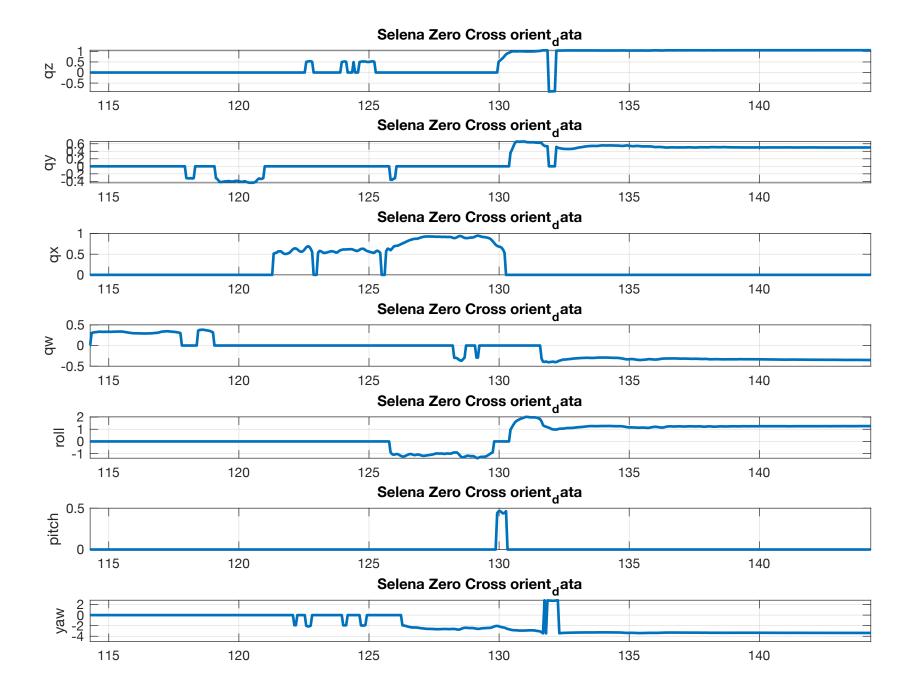
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-565.000	-471.000	-169.000	-34.000	"gyro_data"
'Y'	-528.000	-411.000	-149.000	-57.000	"gyro_data"
'X'	-461.000	-358.000	-129.000	-43.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-293.000	-160.000	-44.000	-1.250	"grav_data"
'Y'	-333.000	-129.000	-32.000	-4.500	"grav_data"
'X'	-303.000	-146.000	-49.000	-7.500	"grav data"





findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
-292.000	-96.000	-27.000	-4.000	"orient_data"
-284.000	-187.000	-42.000	-7.500	"orient_data"
-305.000	-202.000	-54.000	-5.750	"orient_data"
-307.000	-101.000	-26.000	-9.250	"orient_data"
-301.000	-164.000	-44.000	-2.750	"orient_data"
-332.000	-220.000	-53.000	-4.500	"orient_data"
-274.000	-134.000	-36.000	-7.750	"orient_data"
	-292.000 -284.000 -305.000 -307.000 -301.000 -332.000	-292.000 -96.000 -284.000 -187.000 -305.000 -202.000 -307.000 -101.000 -301.000 -164.000 -332.000 -220.000	-292.000 -96.000 -27.000 -284.000 -187.000 -42.000 -305.000 -202.000 -54.000 -307.000 -101.000 -26.000 -301.000 -164.000 -44.000 -332.000 -220.000 -53.000	-284.000 -187.000 -42.000 -7.500 -305.000 -202.000 -54.000 -5.750 -307.000 -101.000 -26.000 -9.250 -301.000 -164.000 -44.000 -2.750 -332.000 -220.000 -53.000 -4.500

Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'zero_cross'	59.000
'bar_data'	"Relative Altitude"	'zero_cross'	7.000
'gyro_data'	"Z"	'zero_cross'	34.000
'grav_data'	"Z"	'zero_cross'	1.250
'orient data'	"roll"	'zero cross'	2.750