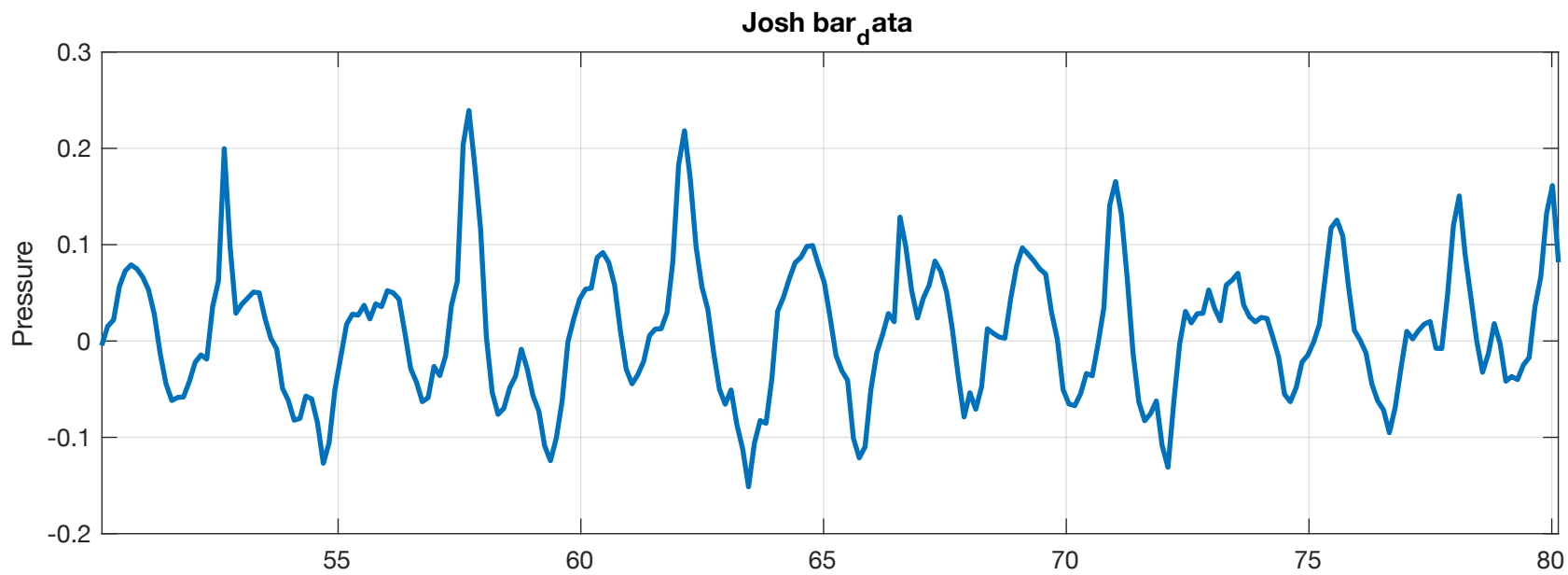
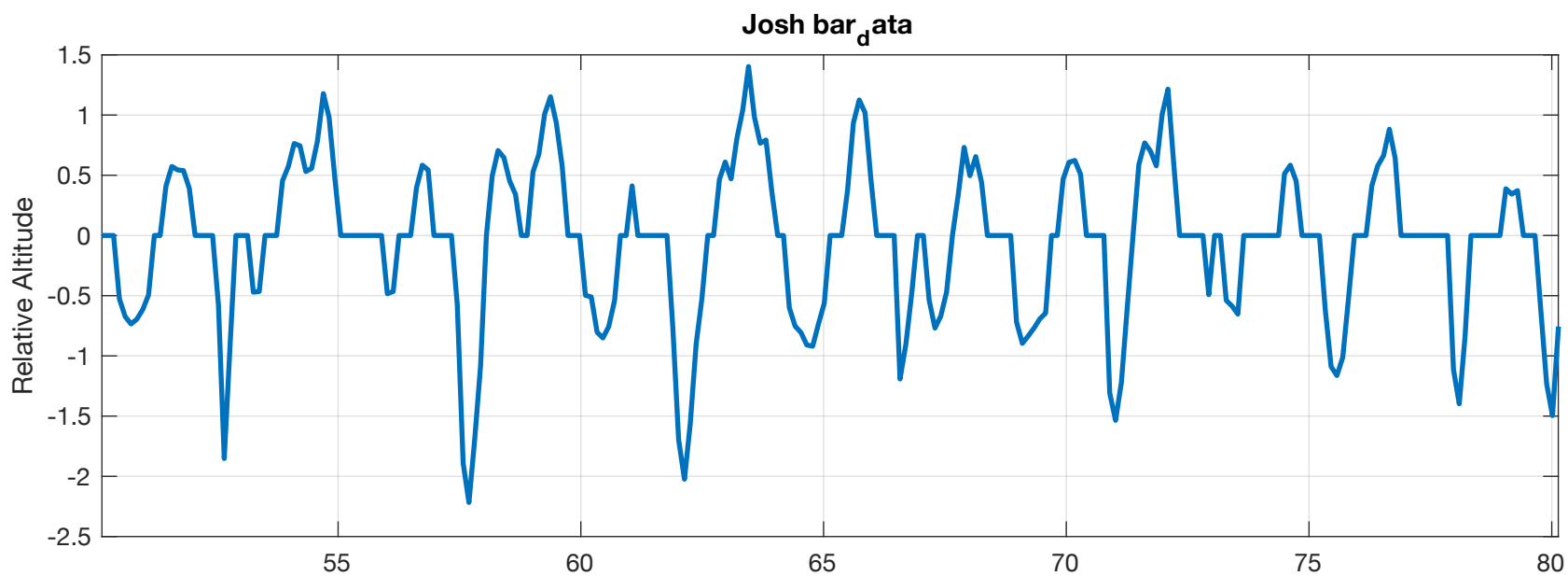
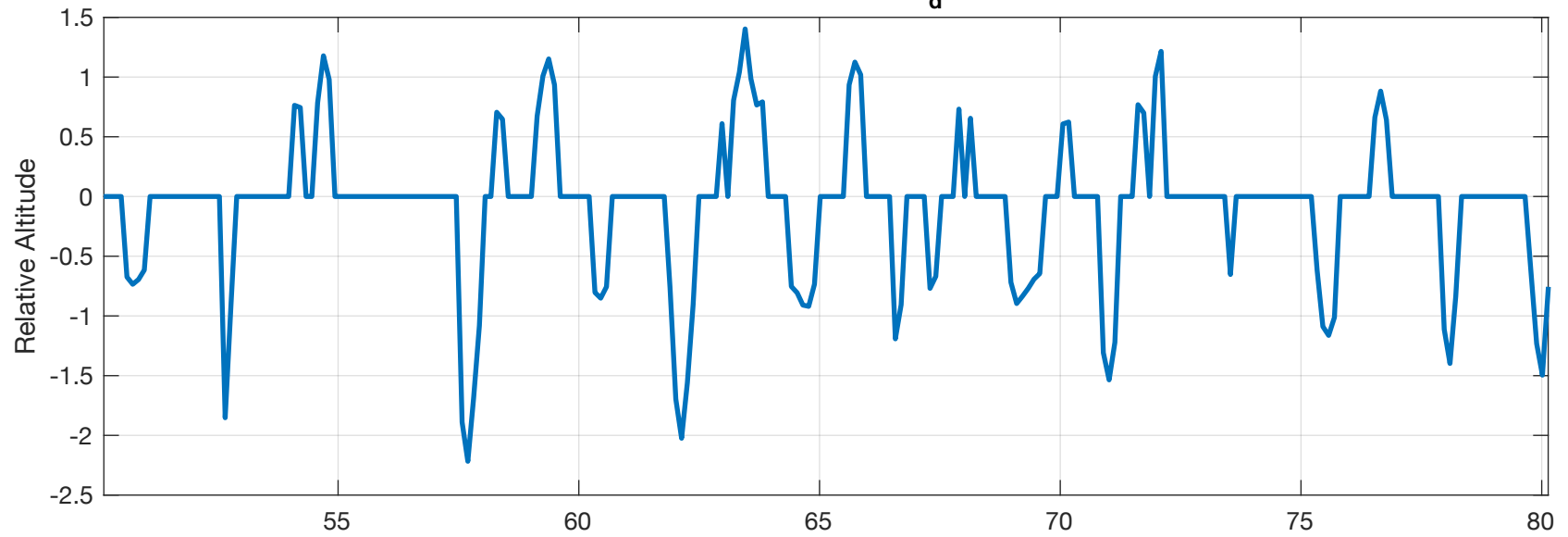


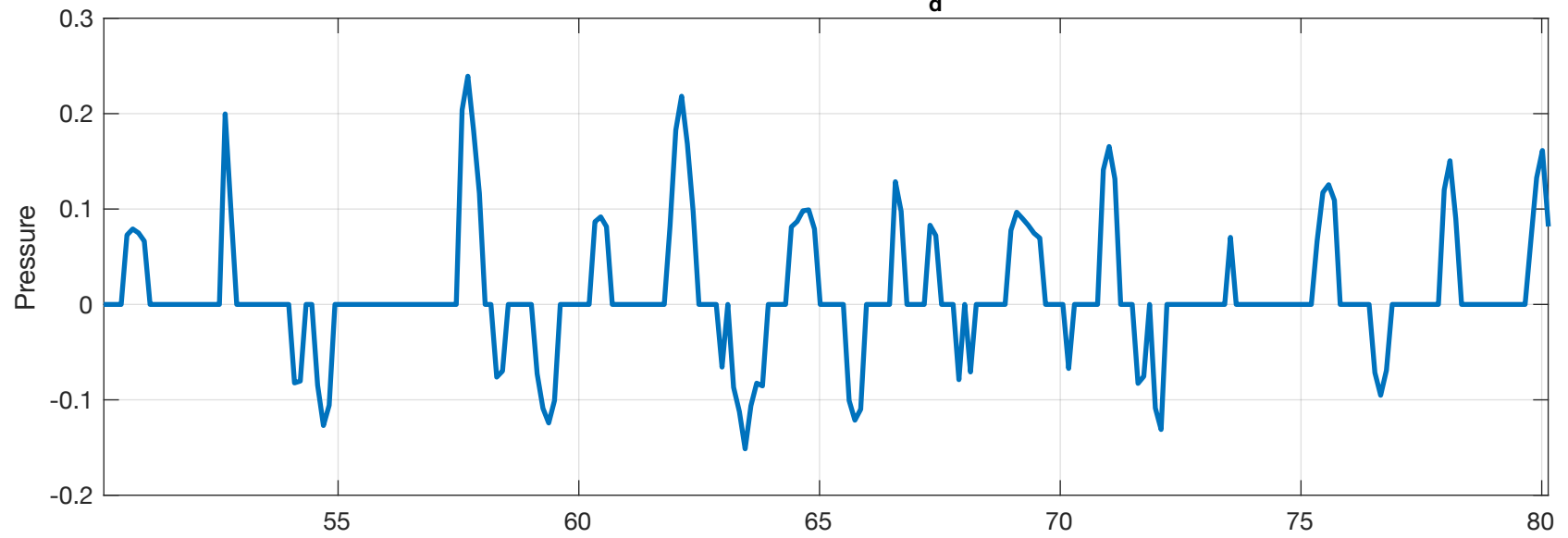
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-359.000	-306.000	-98.000	-114.500	"accel_data"
'Y'	-379.000	-308.000	-107.000	-137.000	"accel_data"
'X'	-334.000	-296.000	-96.000	-115.750	"accel_data"



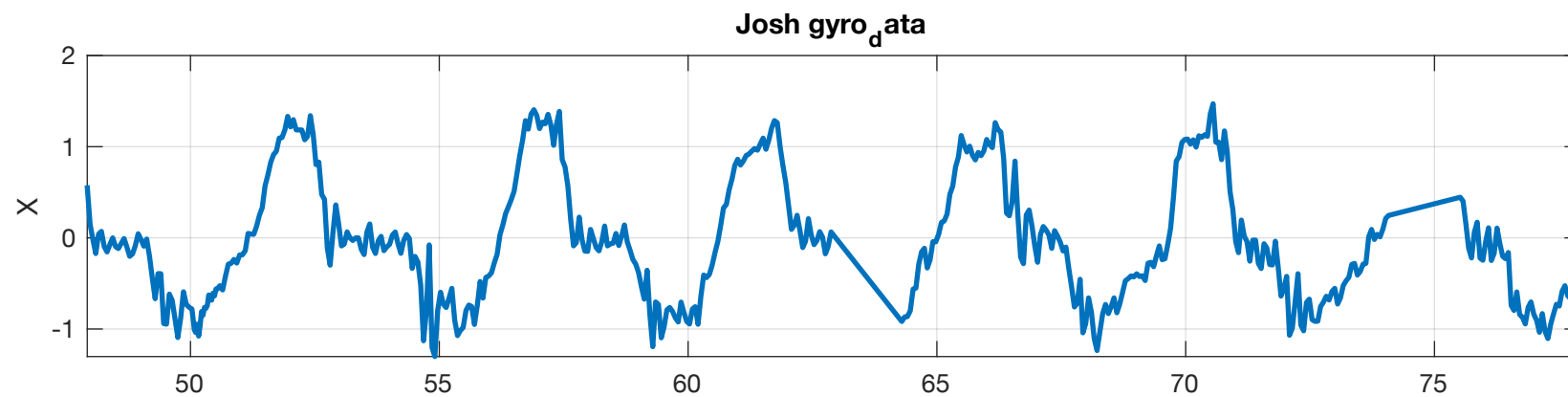
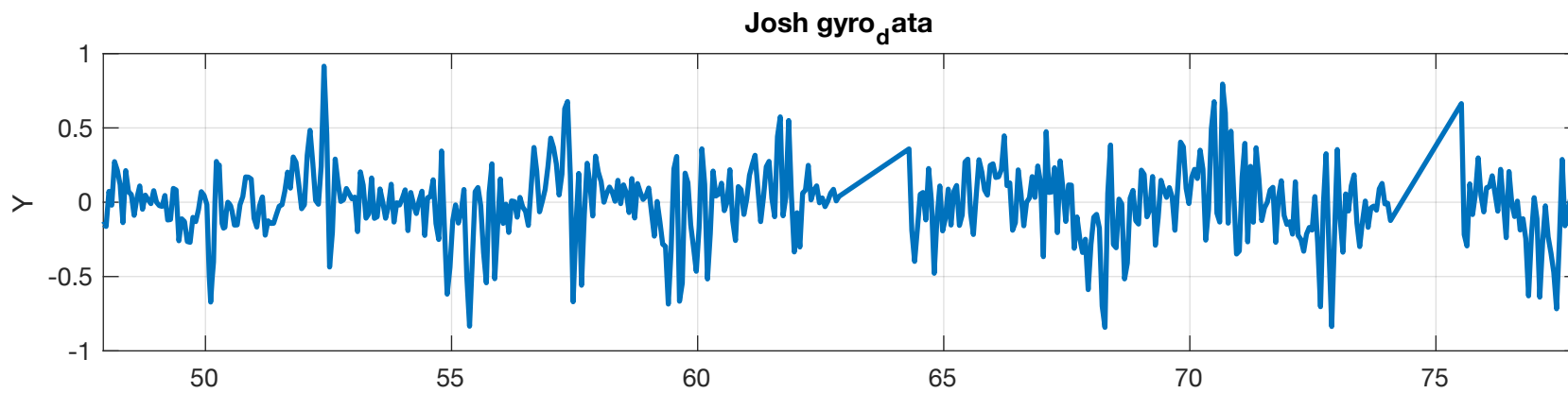
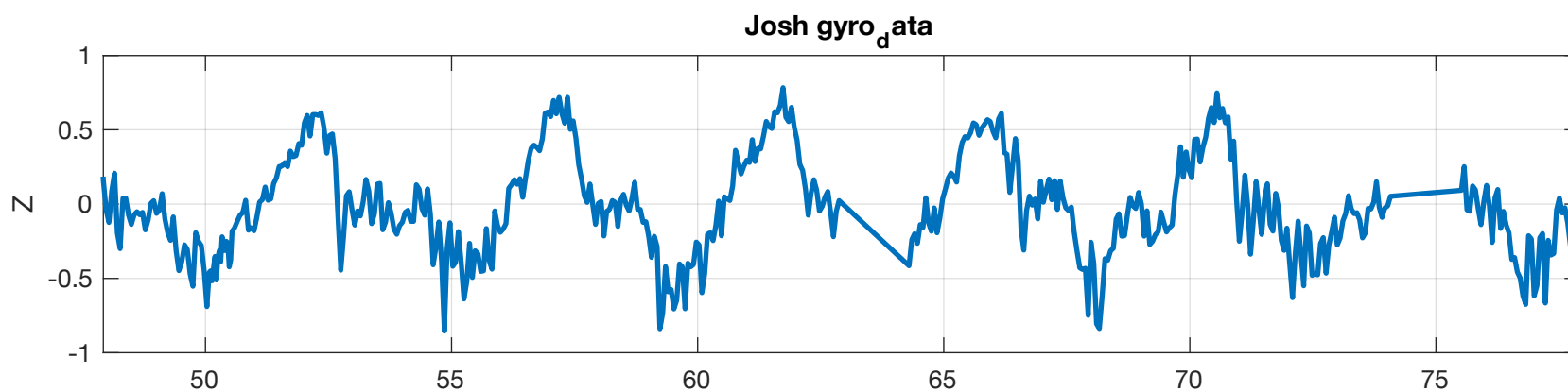
Josh Zero Cross bar_data

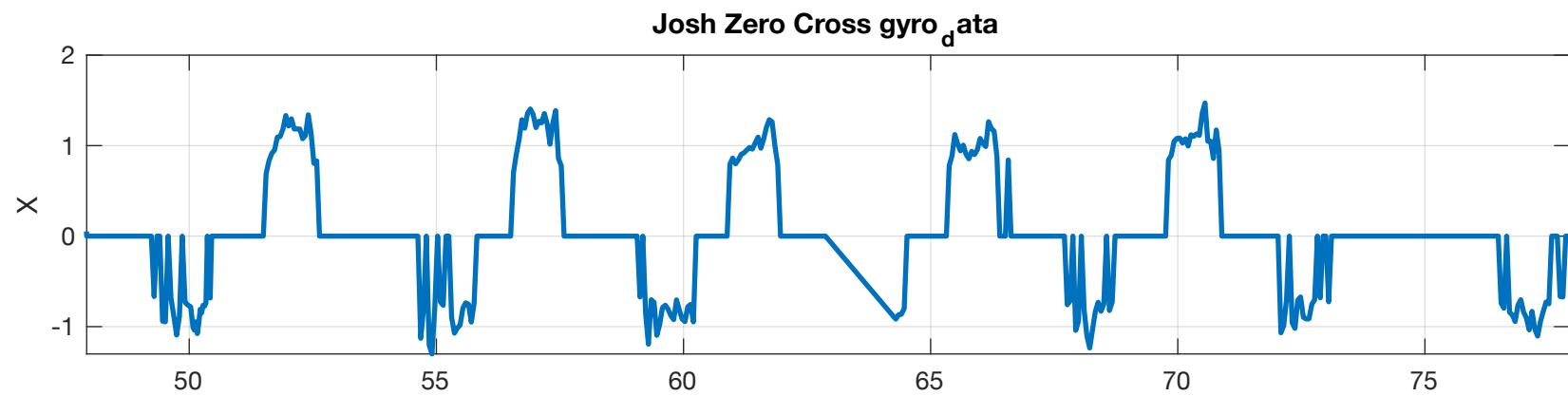
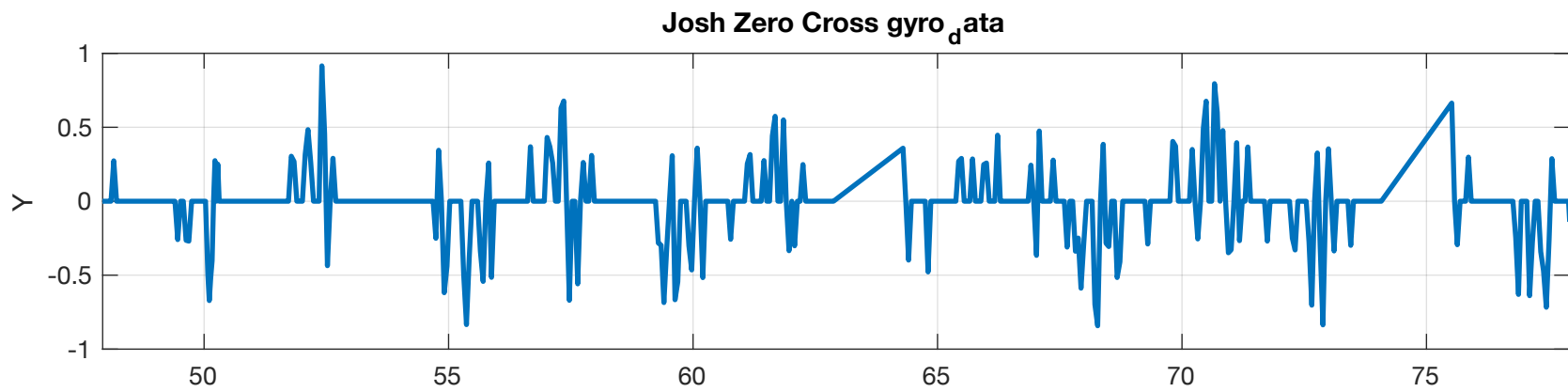
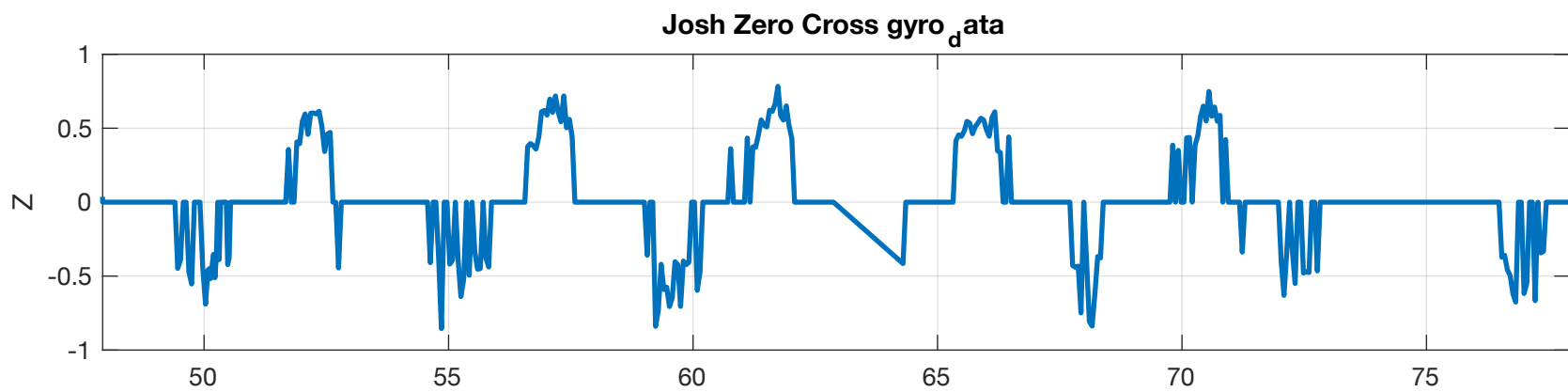


Josh Zero Cross bar_data

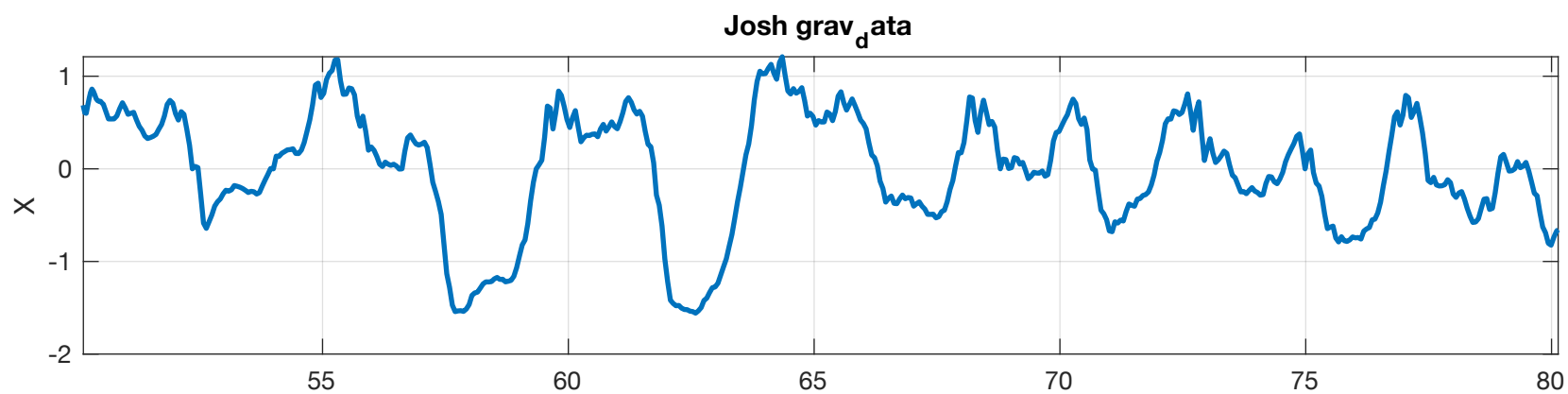
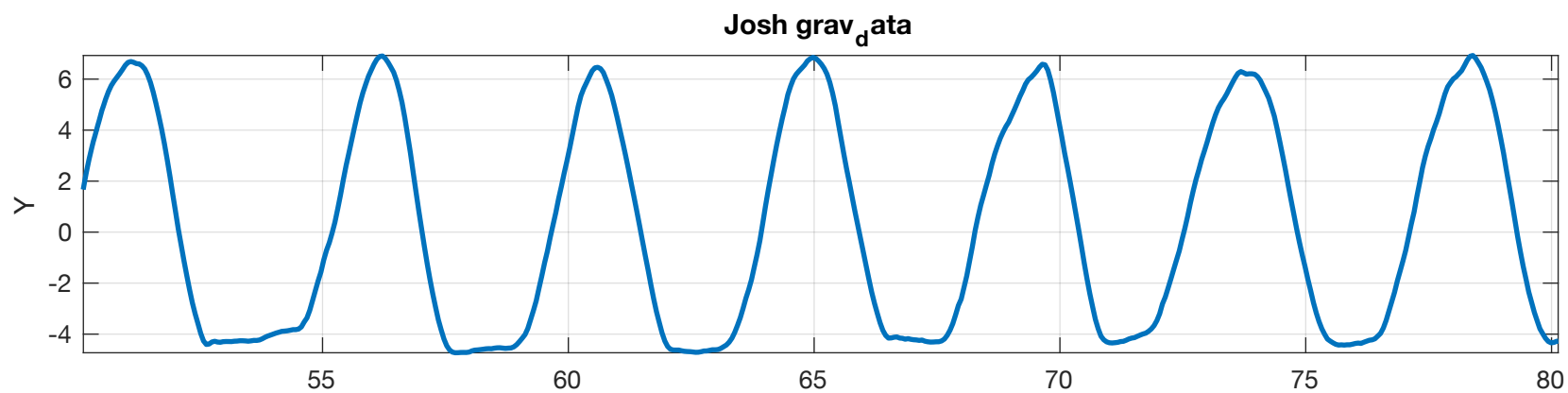
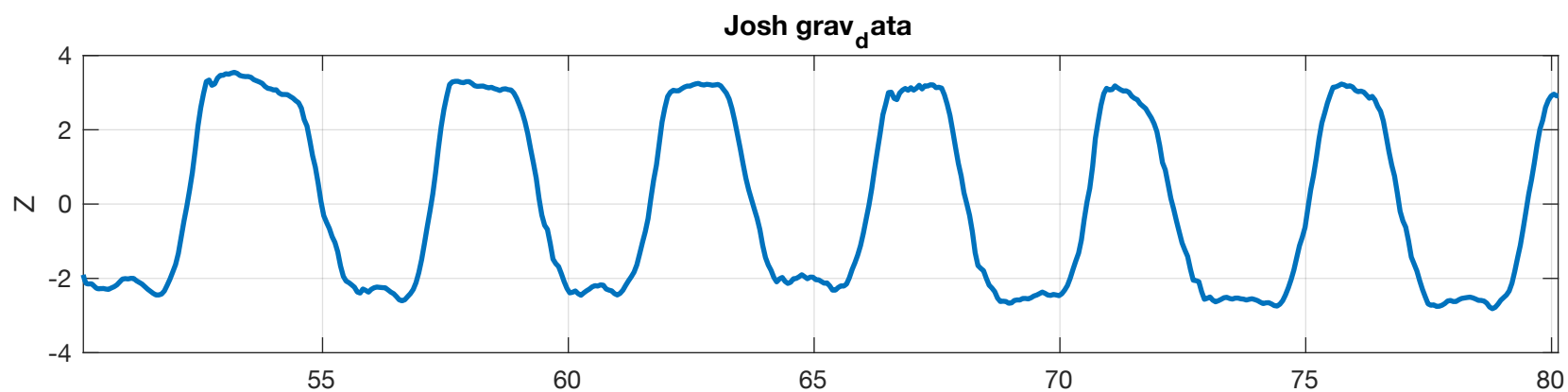


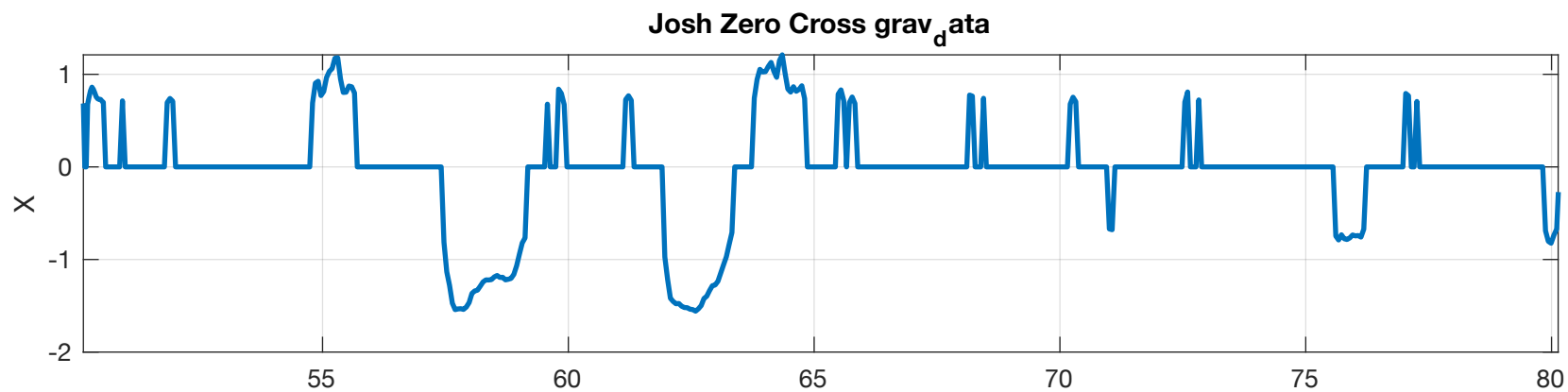
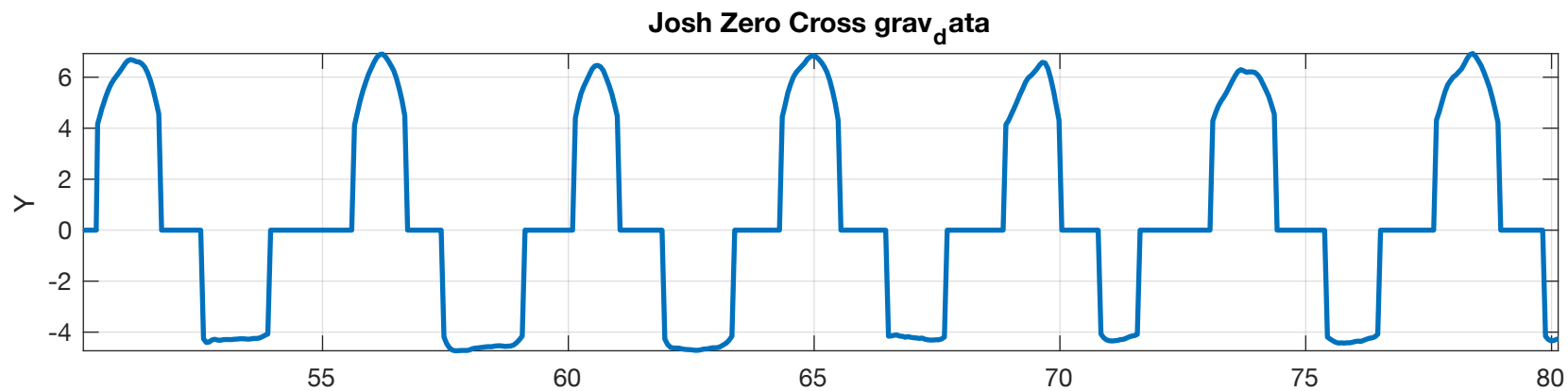
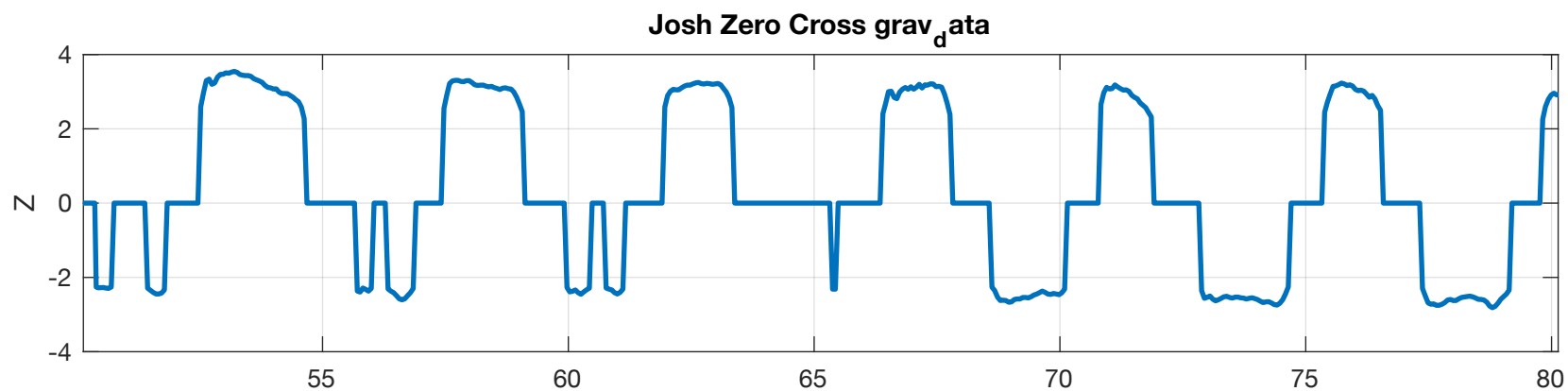
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-45.000	-38.000	-4.000	-10.250	"bar_data"
"Pressure"	-81.000	-47.000	-14.000	-10.250	"bar_data"



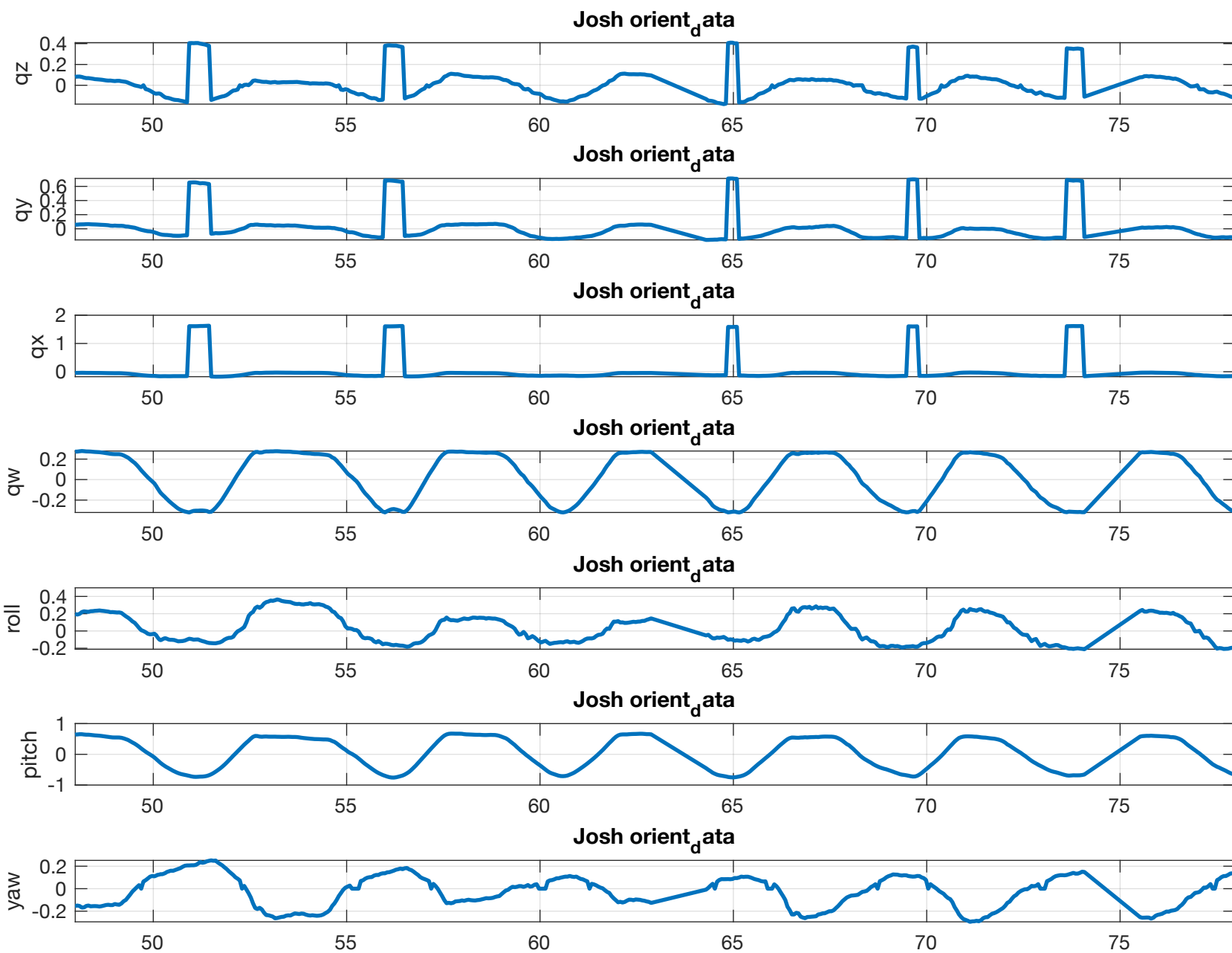


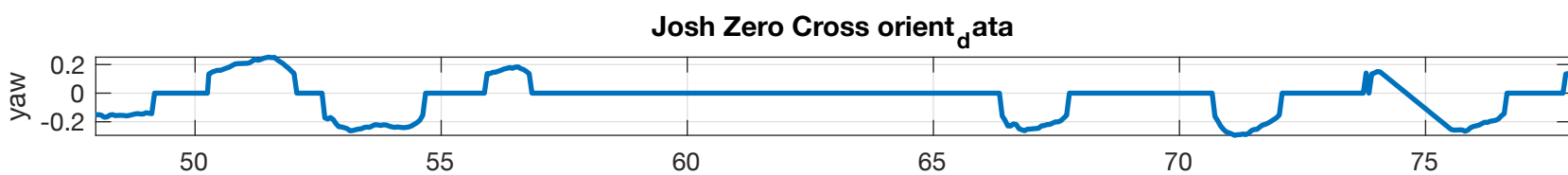
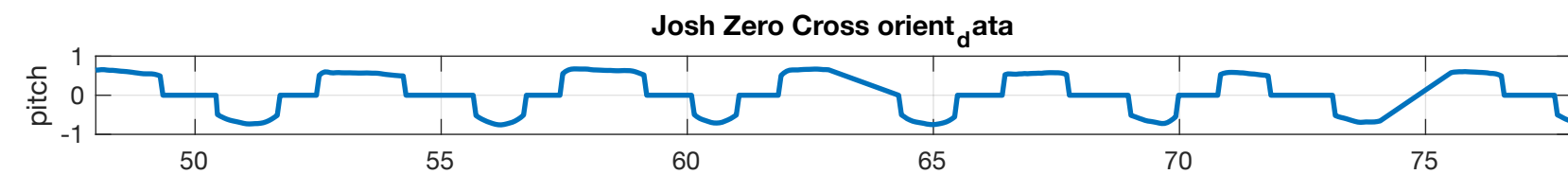
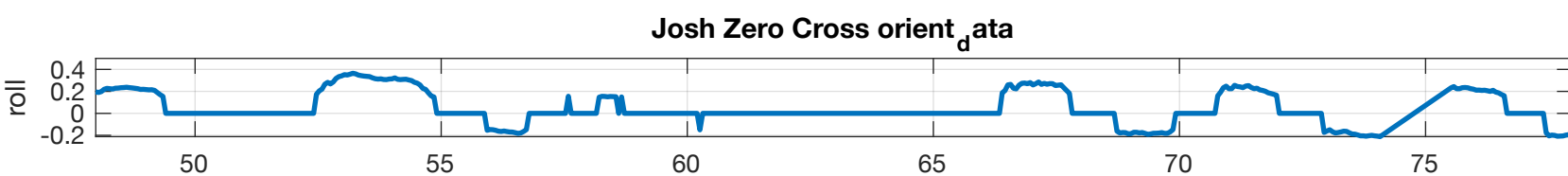
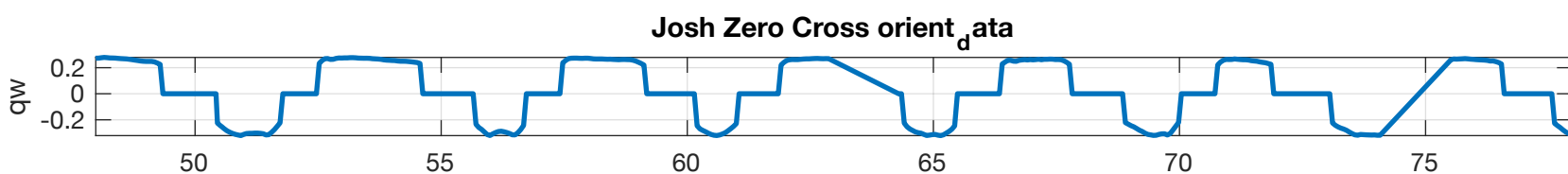
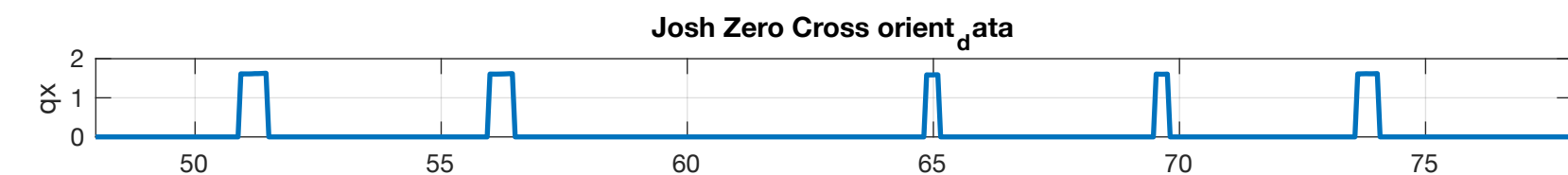
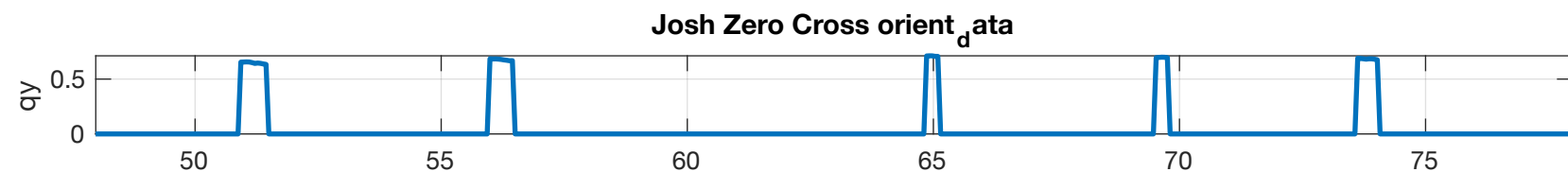
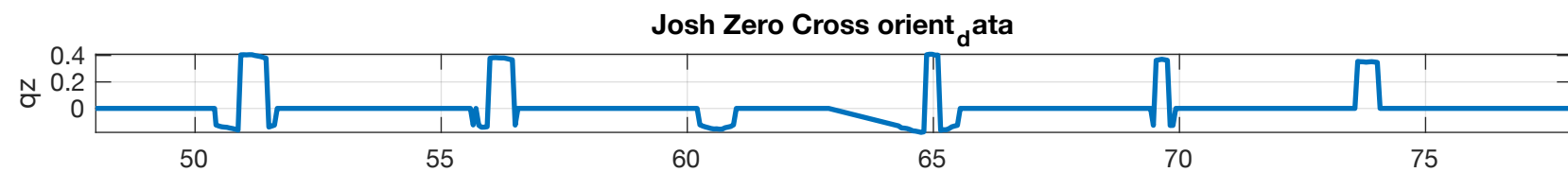
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-290.000	-175.000	-40.000	-31.000	"gyro_data"
'Y'	-293.000	-255.000	-81.000	-75.500	"gyro_data"
'X'	-243.000	-121.000	-27.000	-19.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-116.000	-57.000	-1.000	-2.500	"grav_data"
'Y'	-39.000	-4.000	2.000	0.500	"grav_data"
'X'	-179.000	-117.000	-20.000	-5.250	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-133.000	-80.000	-18.000	0.000	"orient_data"
'qy'	-109.000	-76.000	-16.000	8.500	"orient_data"
'qx'	-102.000	-5.000	4.000	10.000	"orient_data"
'qw'	-54.000	-40.000	-1.000	0.500	"orient_data"
'roll'	-166.000	-81.000	-10.000	0.500	"orient_data"
'pitch'	-28.000	-24.000	4.000	0.250	"orient_data"
'yaw'	-124.000	-75.000	-4.000	5.000	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'double_findpeaks'	96.000
'bar_data'	"Relative Altitude"	'double_findpeaks'	4.000
'gyro_data'	"X"	'zero_cross'	19.500
'grav_data'	"Y"	'zero_cross'	0.500
'orient_data'	"qz"	'zero_cross'	0.000