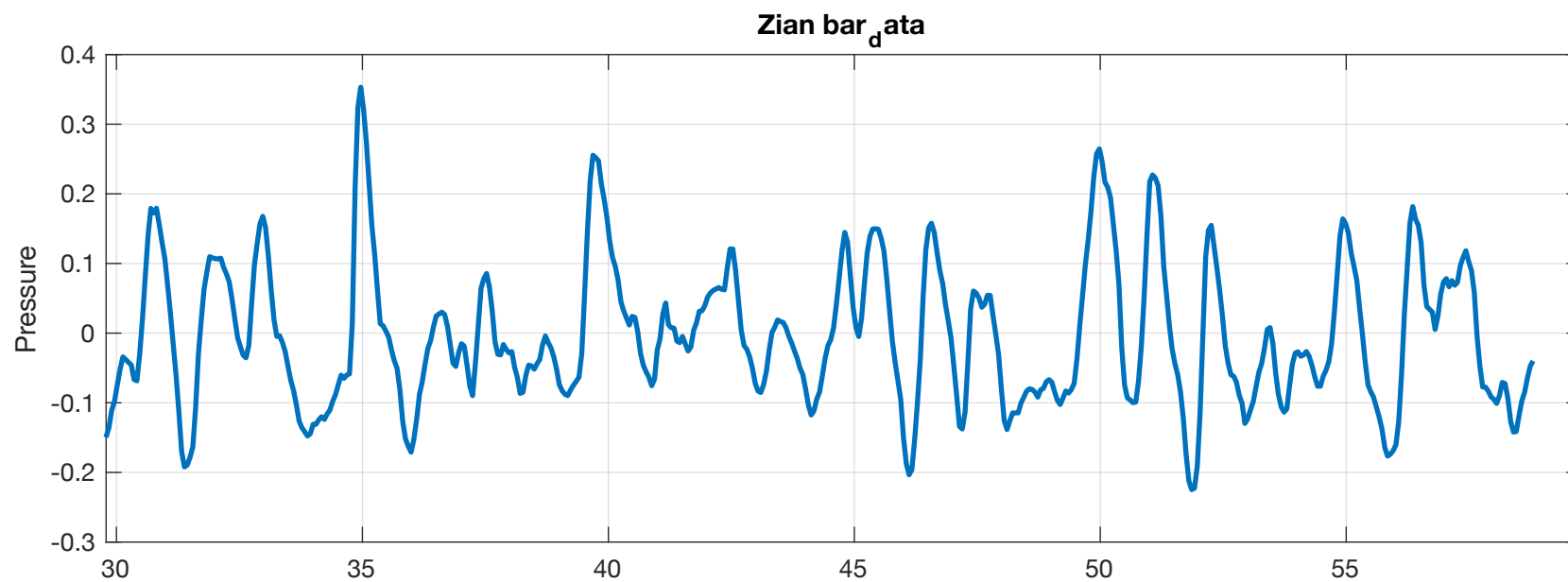
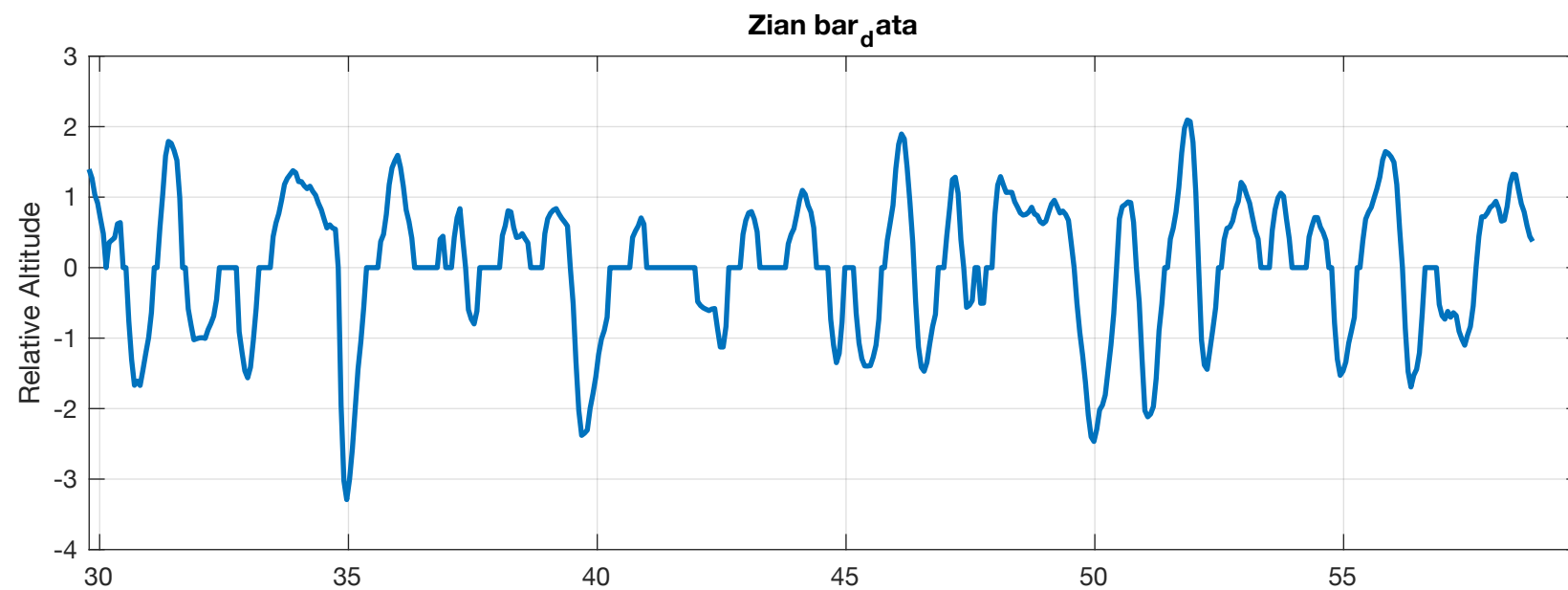
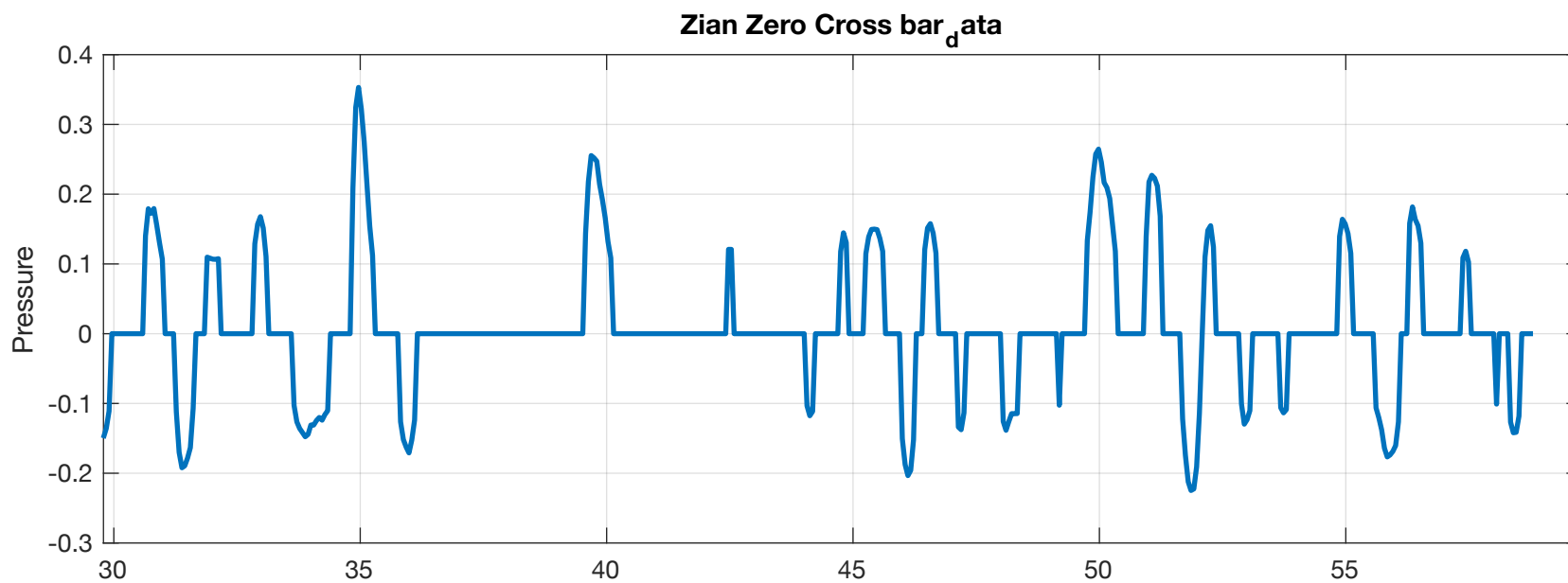
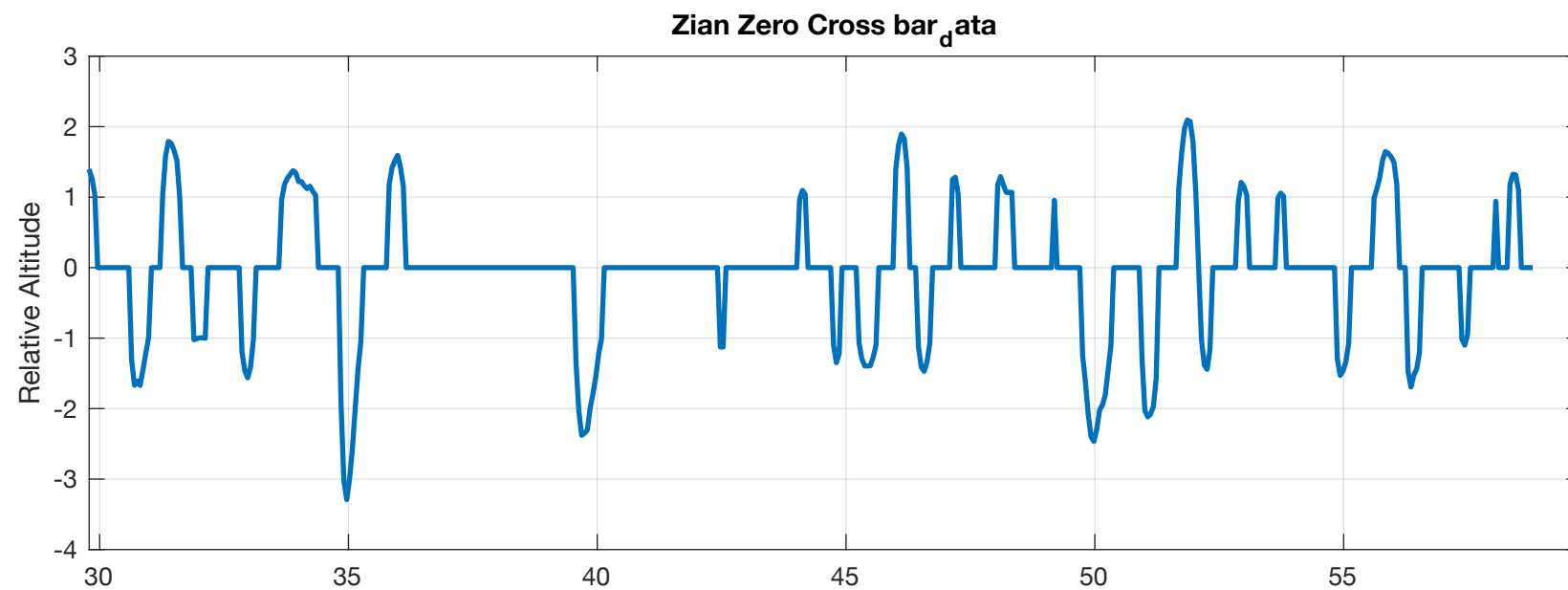
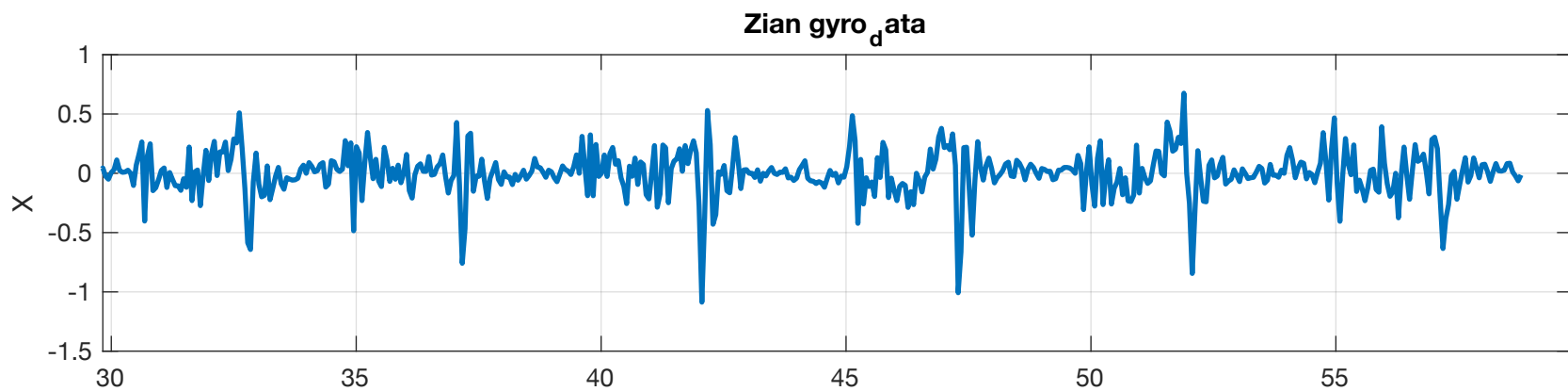
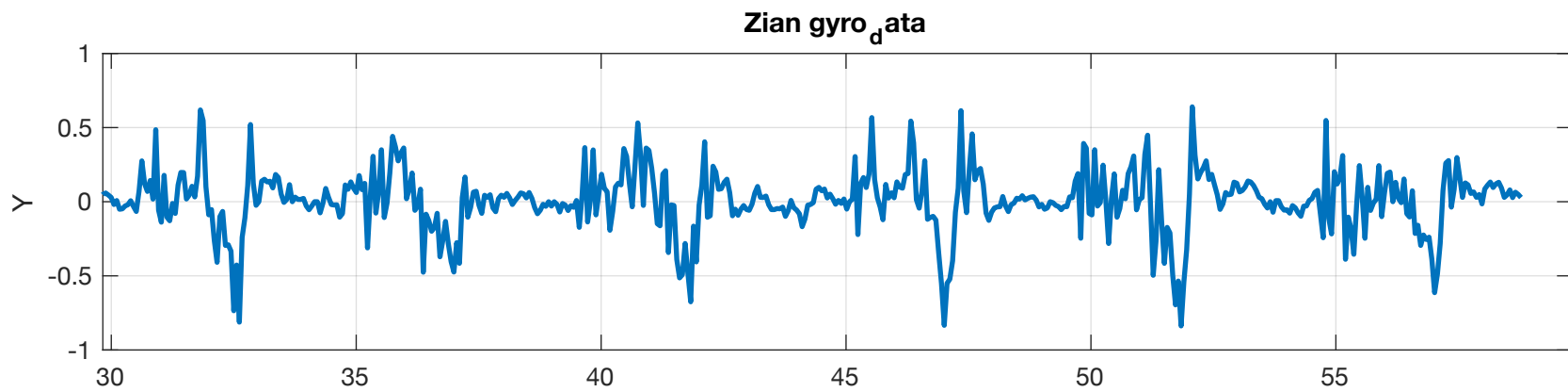
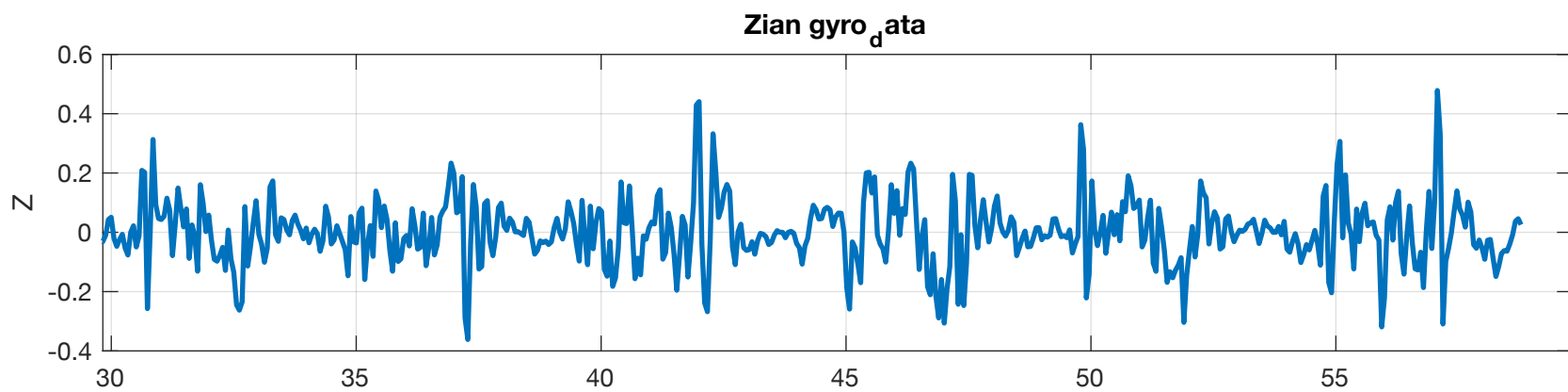


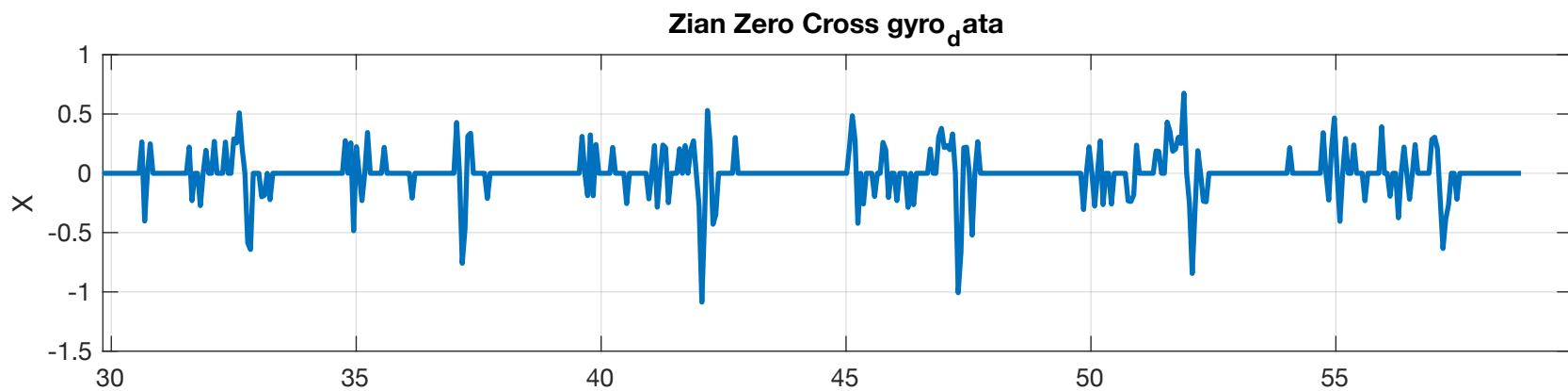
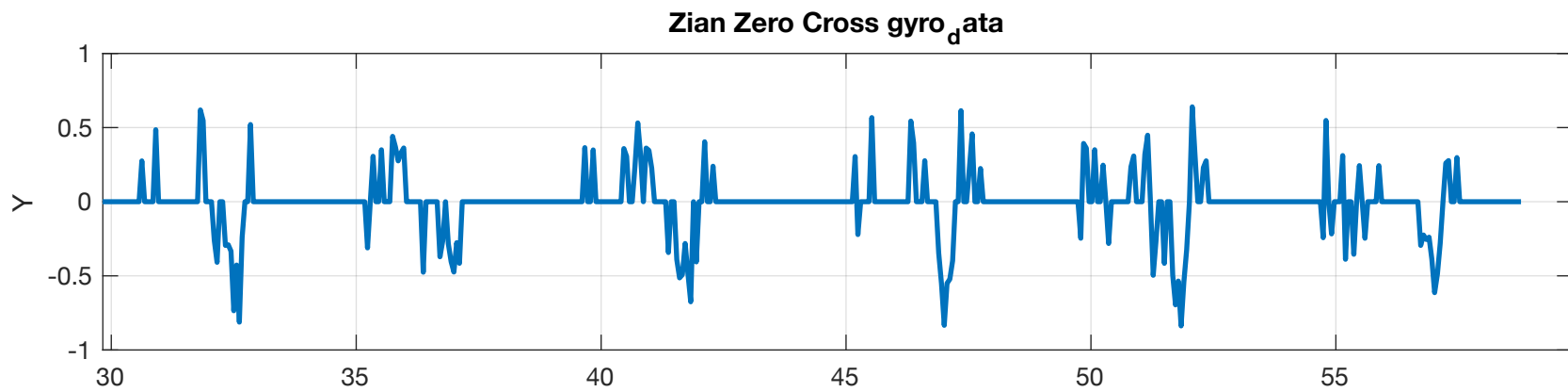
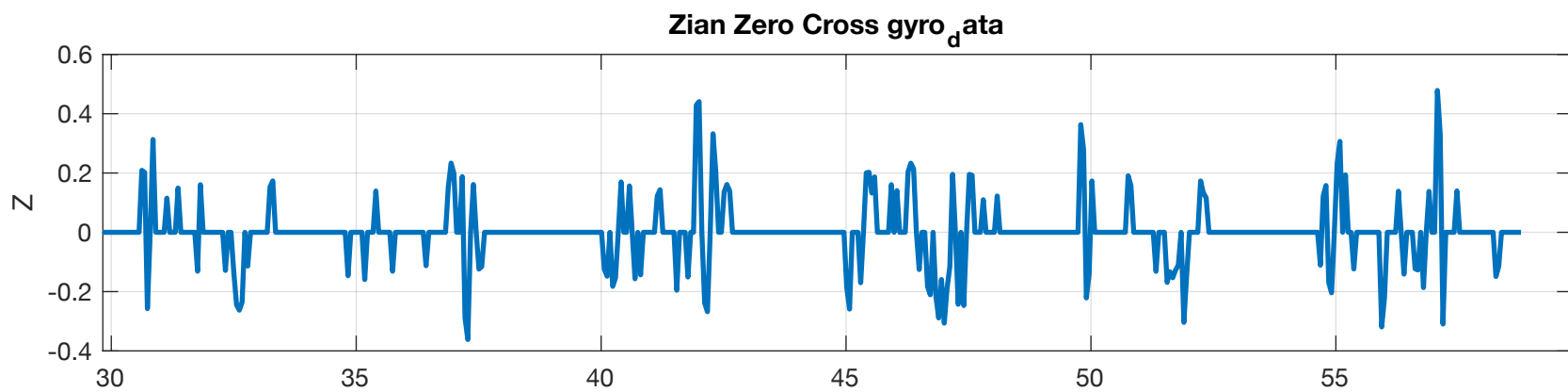
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-151.000	-121.000	-41.000	-46.750	"accel_data"
'Y'	-175.000	-157.000	-47.000	-45.500	"accel_data"
'X'	-142.000	-121.000	-39.000	-37.500	"accel_data"



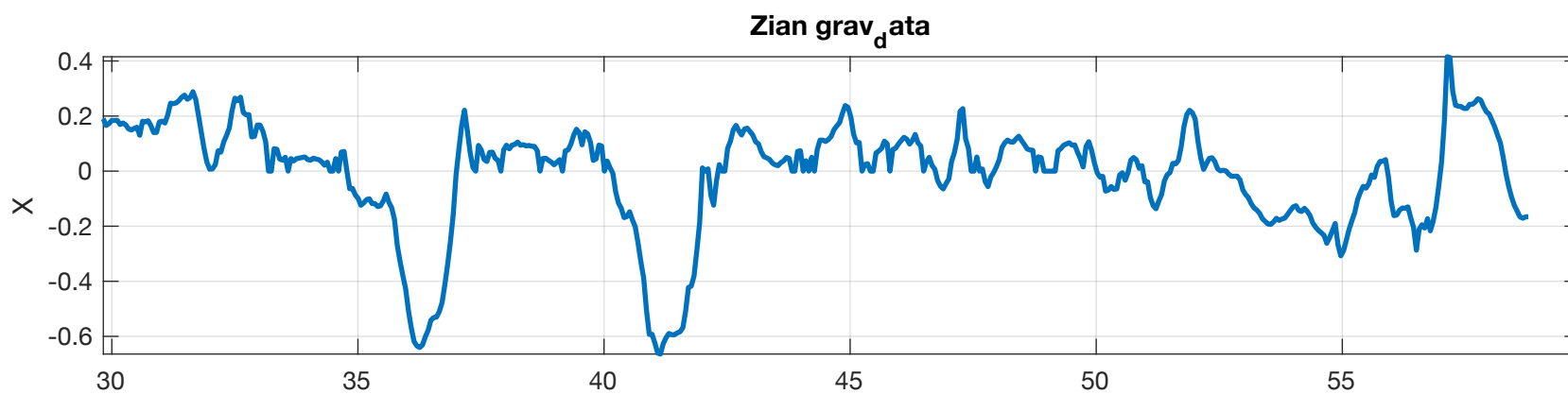
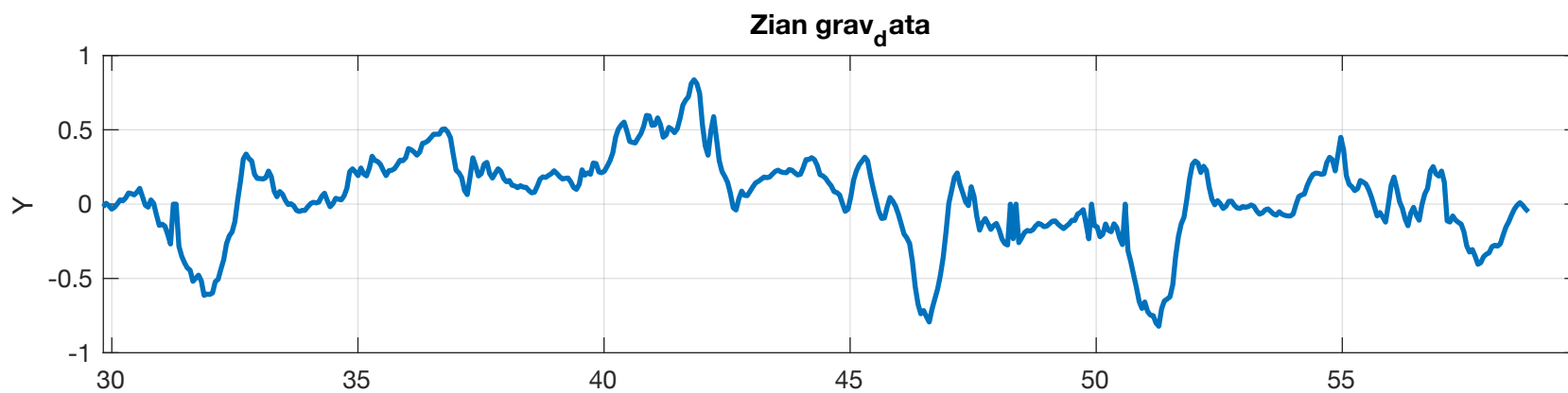
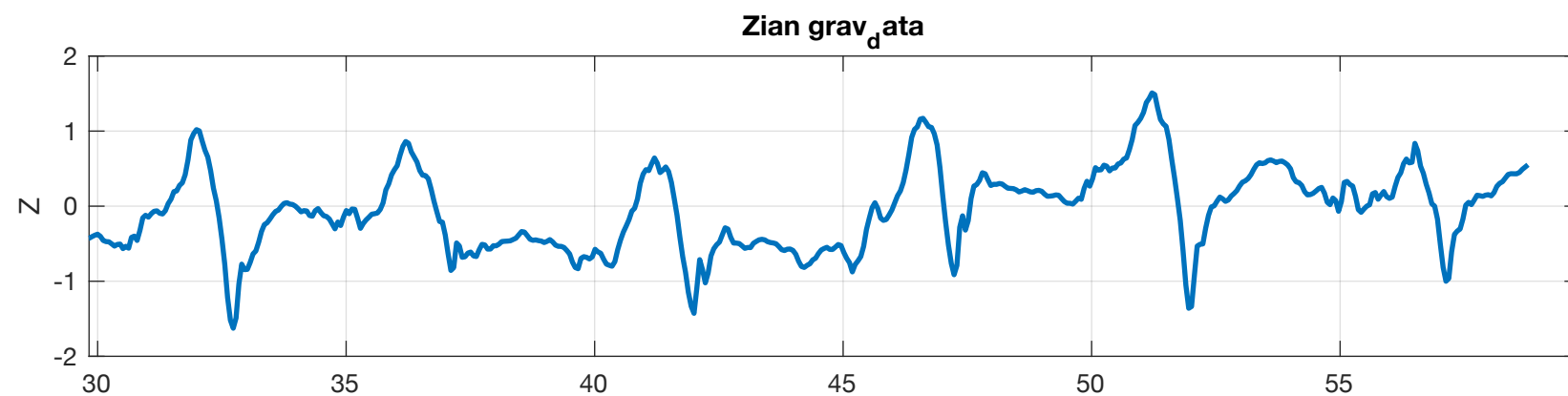


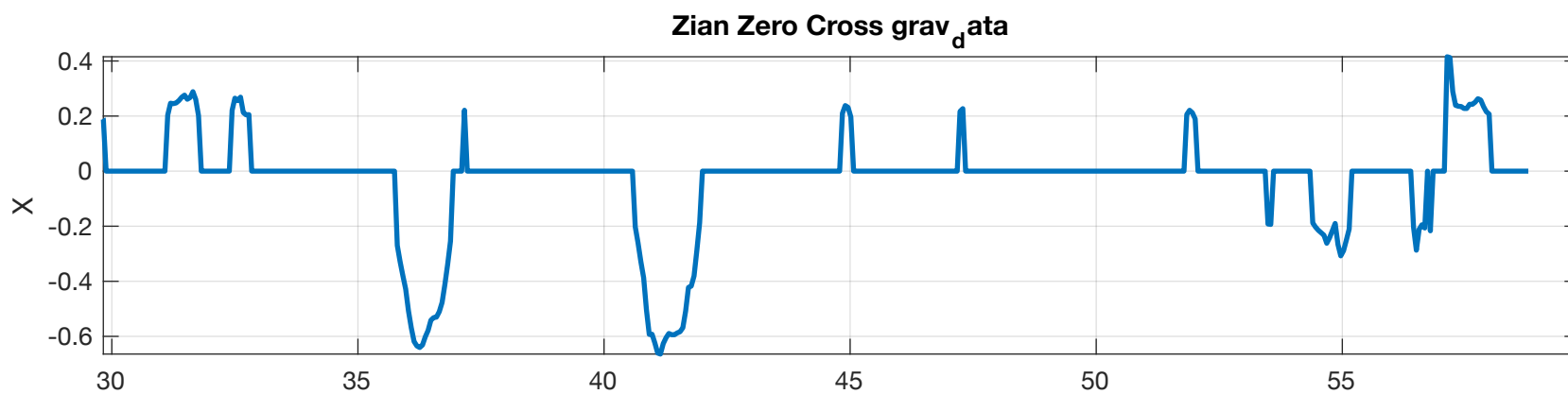
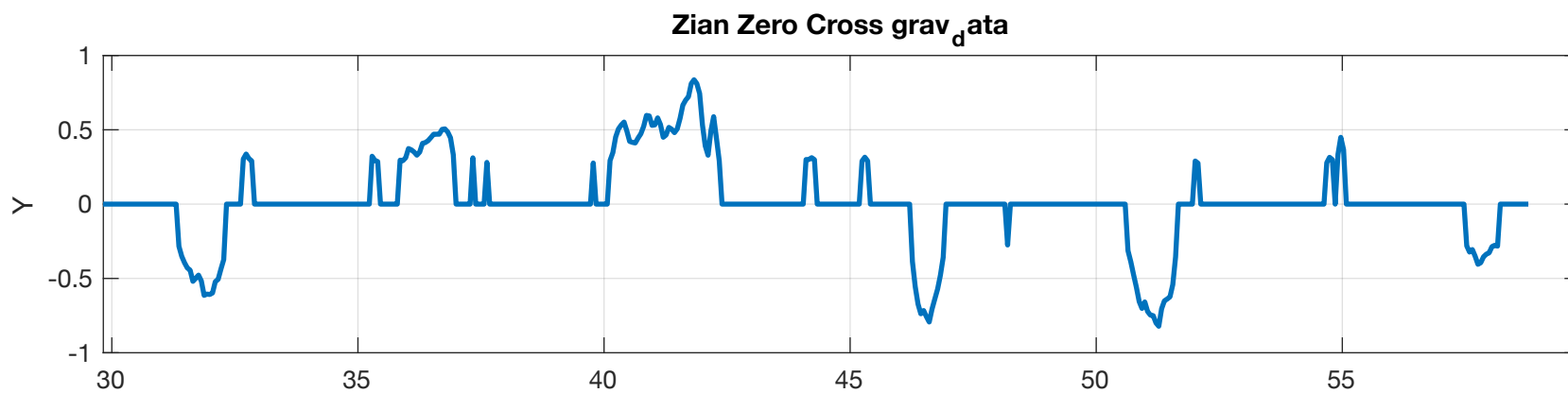
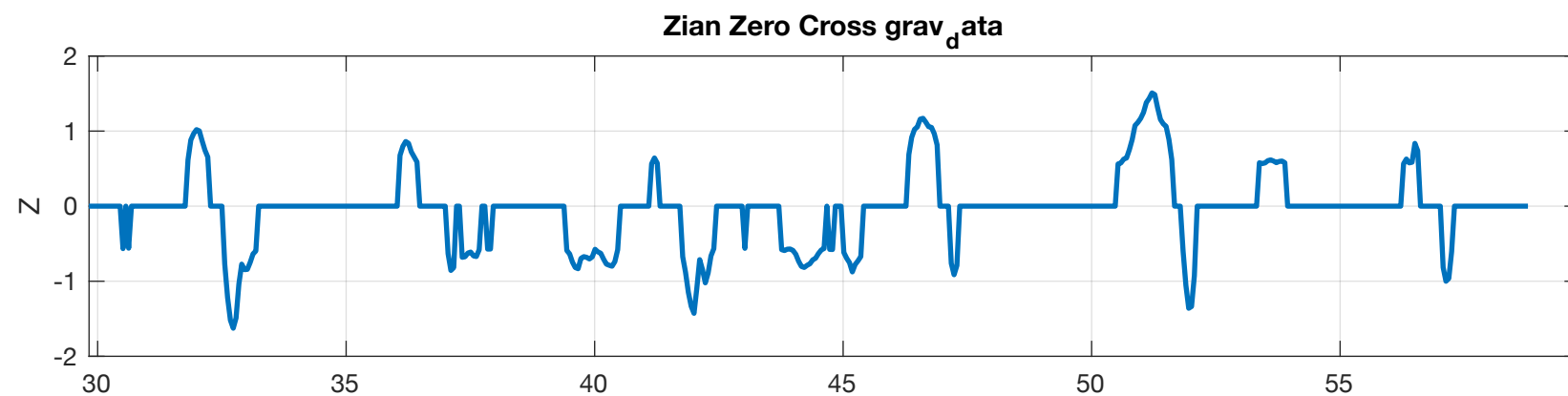
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-45.000	-31.000	-9.000	-11.000	"bar_data"
"Pressure"	-54.000	-33.000	-8.000	-11.000	"bar_data"



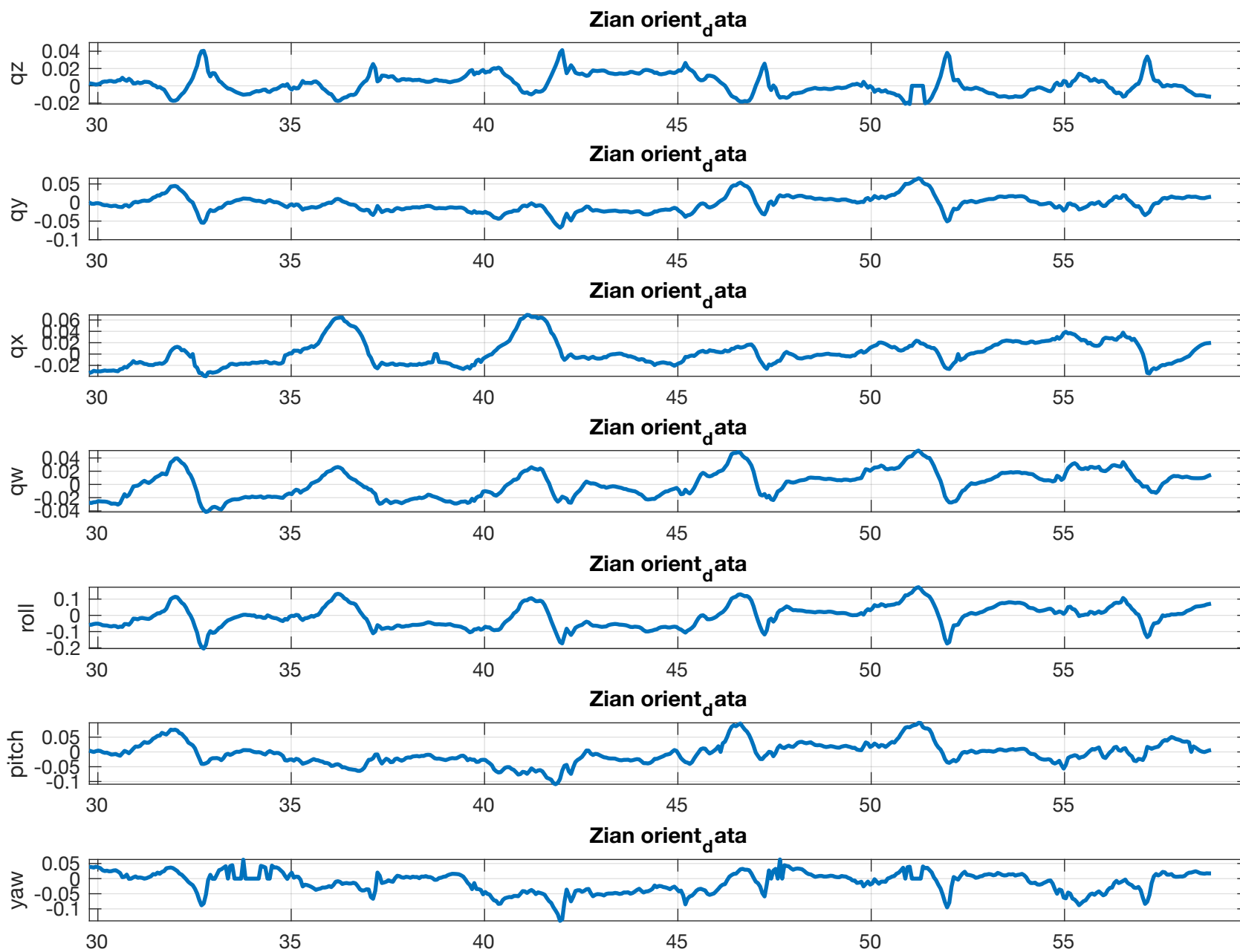


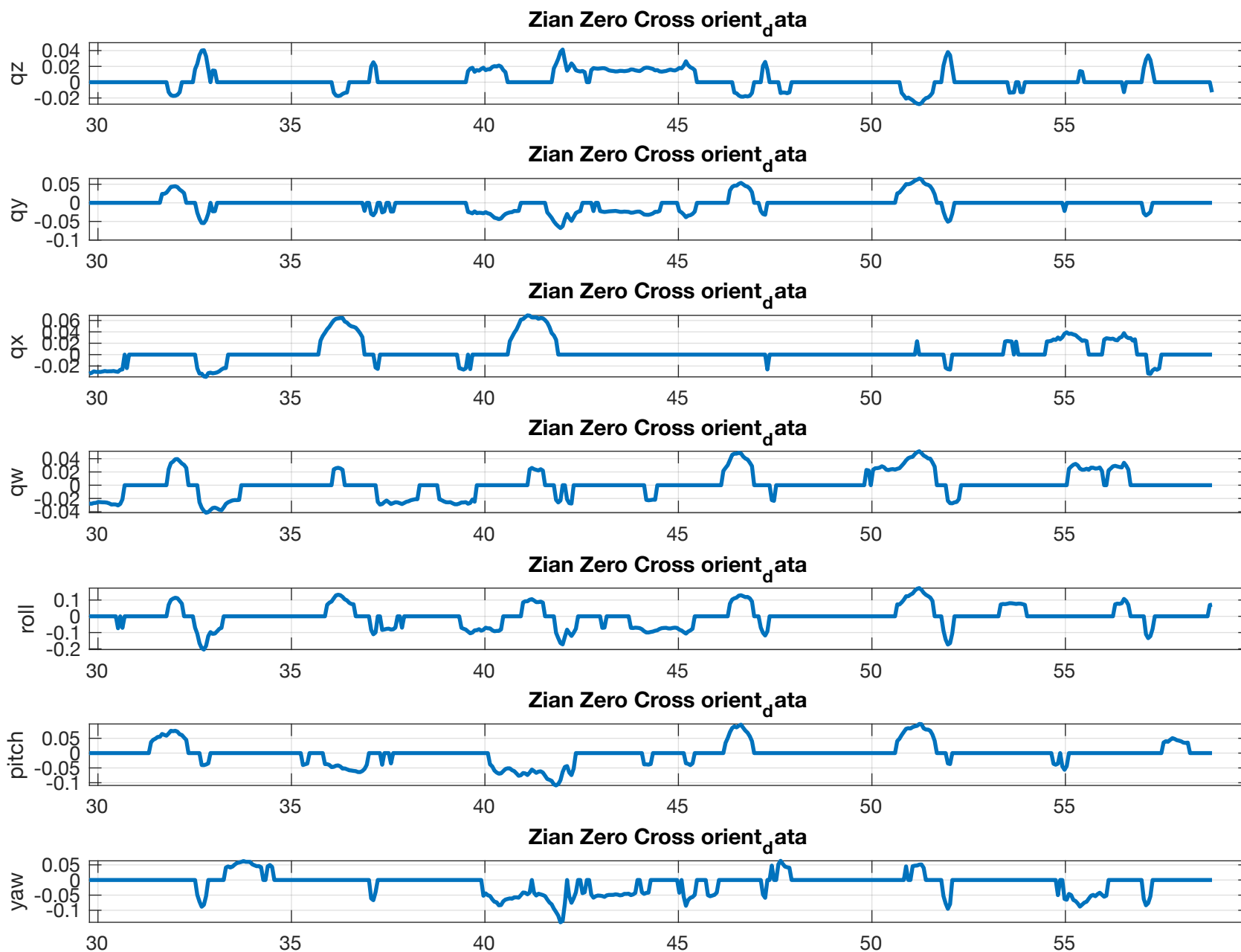
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-166.000	-138.000	-40.000	-45.500	"gyro_data"
'Y'	-185.000	-142.000	-41.000	-31.500	"gyro_data"
'X'	-182.000	-155.000	-46.000	-49.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-76.000	-40.000	-7.000	-6.000	"grav_data"
'Y'	-105.000	-62.000	-13.000	-4.500	"grav_data"
'X'	-122.000	-90.000	-21.000	-0.500	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-99.000	-58.000	-16.000	-5.750	"orient_data"
'qy'	-103.000	-53.000	-11.000	-6.000	"orient_data"
'qx'	-108.000	-48.000	-10.000	-2.500	"orient_data"
'qw'	-84.000	-37.000	-7.000	-4.000	"orient_data"
'roll'	-81.000	-41.000	-8.000	-4.250	"orient_data"
'pitch'	-106.000	-62.000	-12.000	-3.500	"orient_data"
'yaw'	-124.000	-78.000	-18.000	-6.000	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'zero_cross'	37.500
'bar_data'	"Pressure"	'double_findpeaks'	8.000
'gyro_data'	"Y"	'zero_cross'	31.500
'grav_data'	"X"	'zero_cross'	0.500
'orient_data'	"qx"	'zero_cross'	2.500