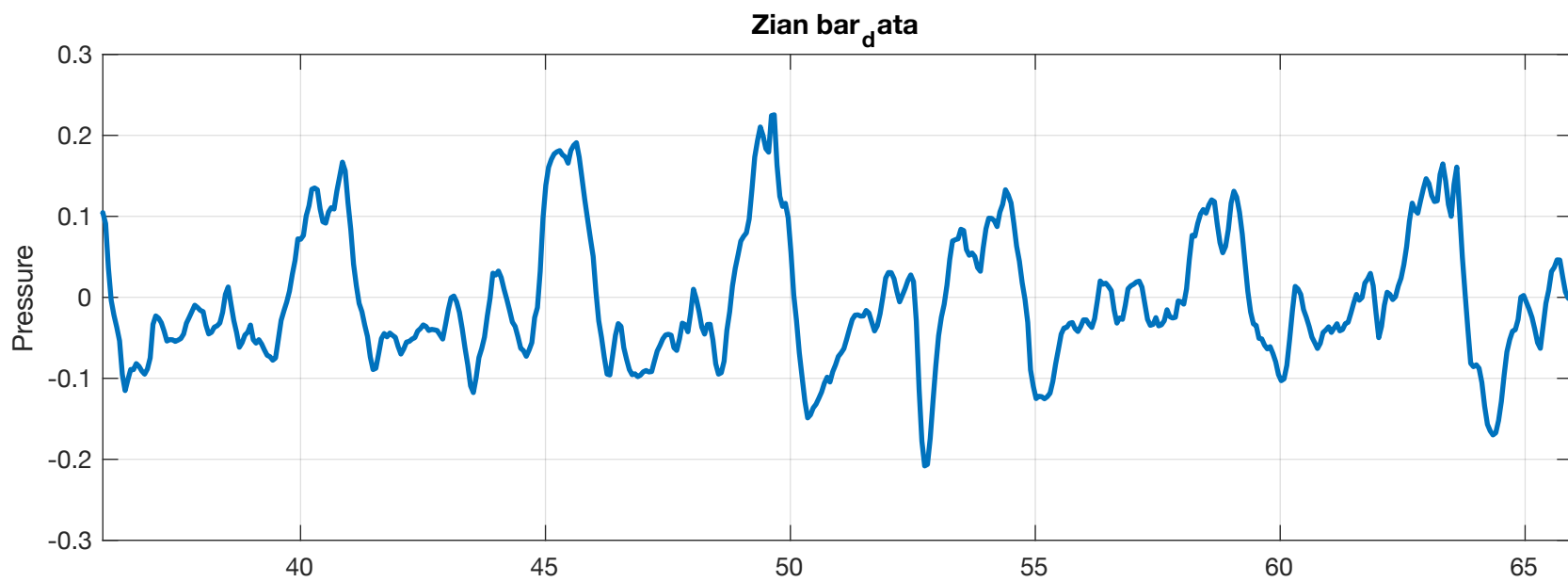
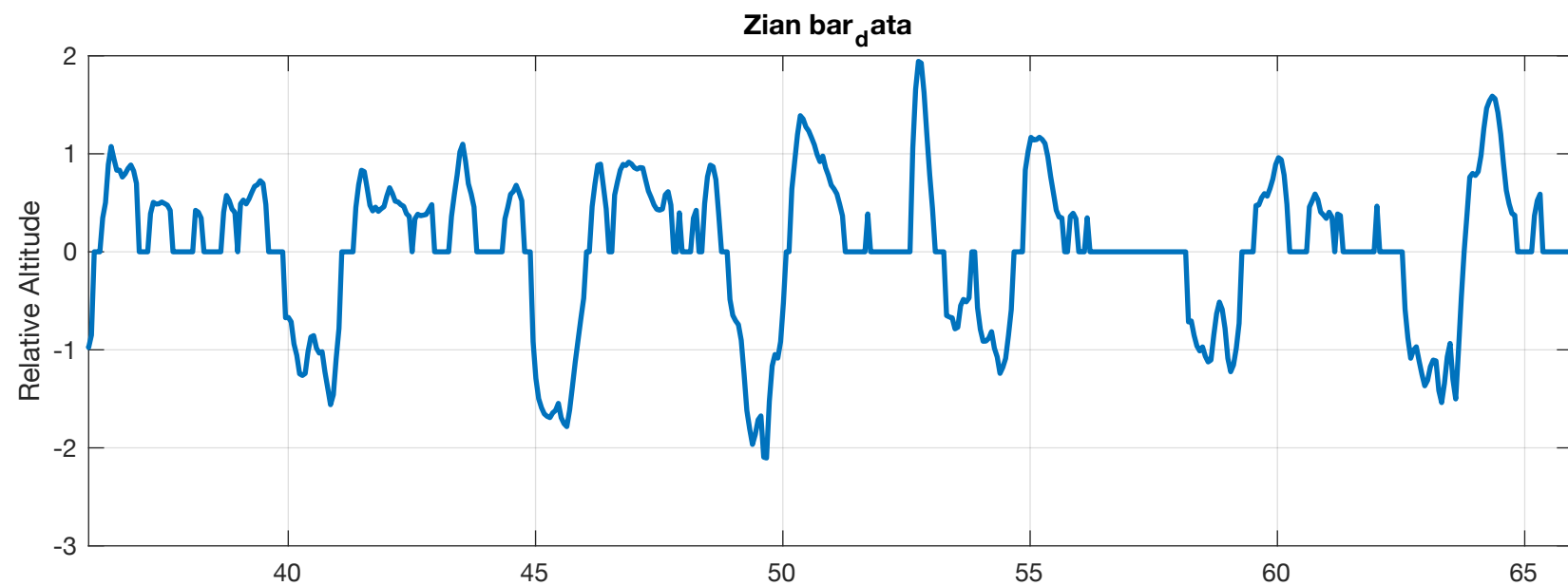
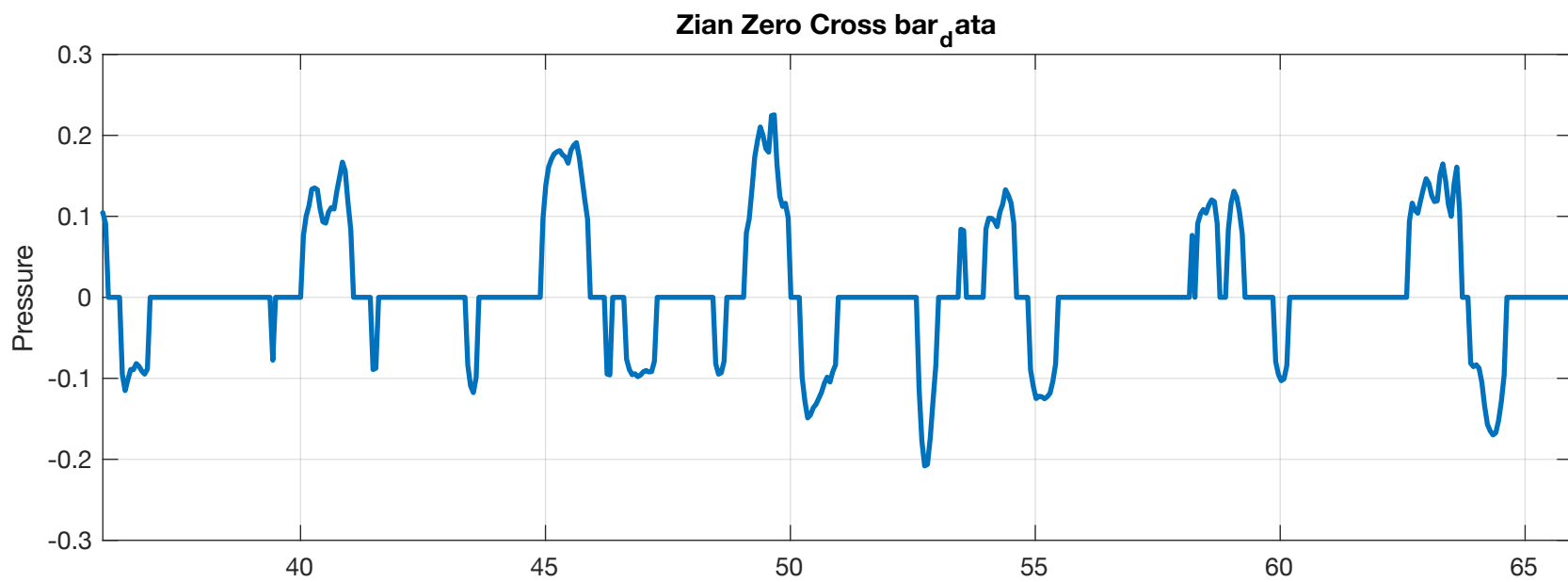
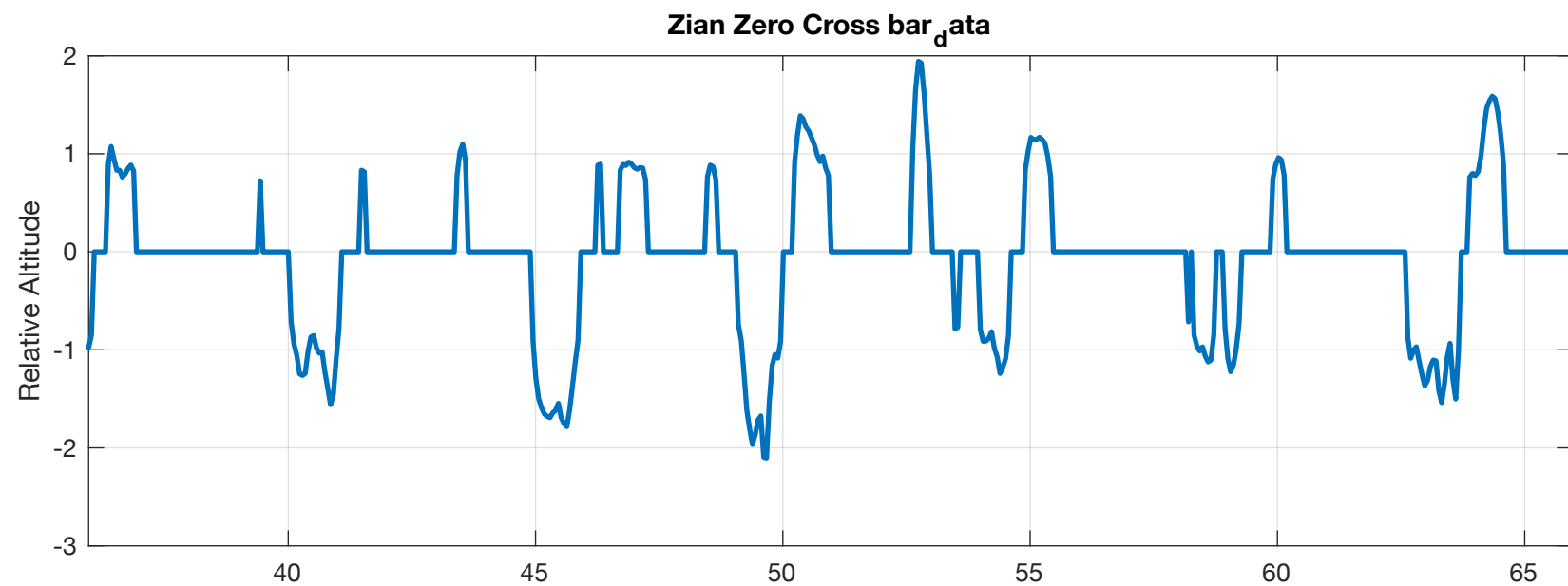
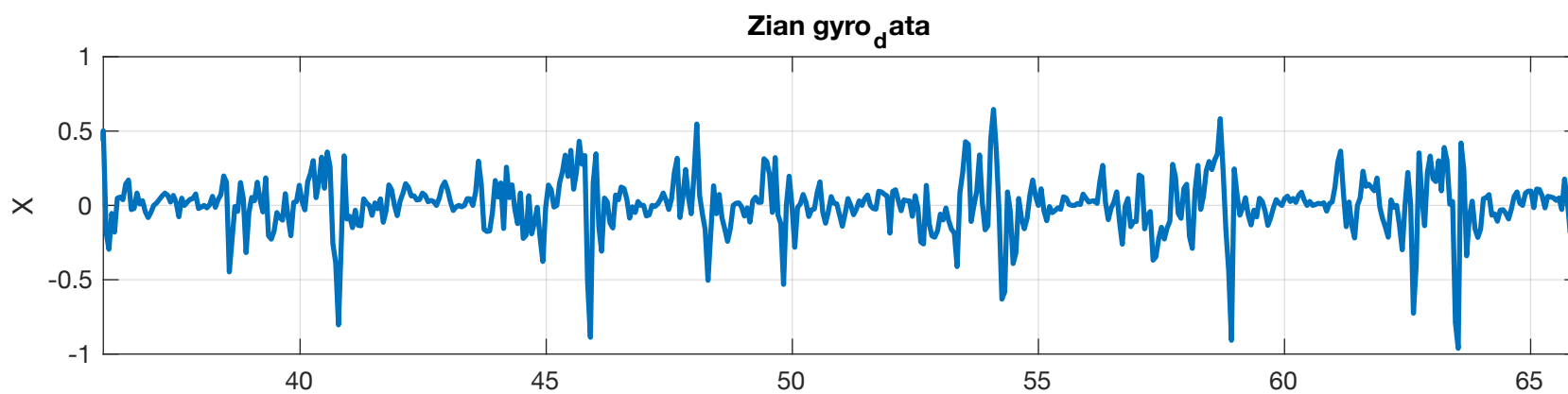
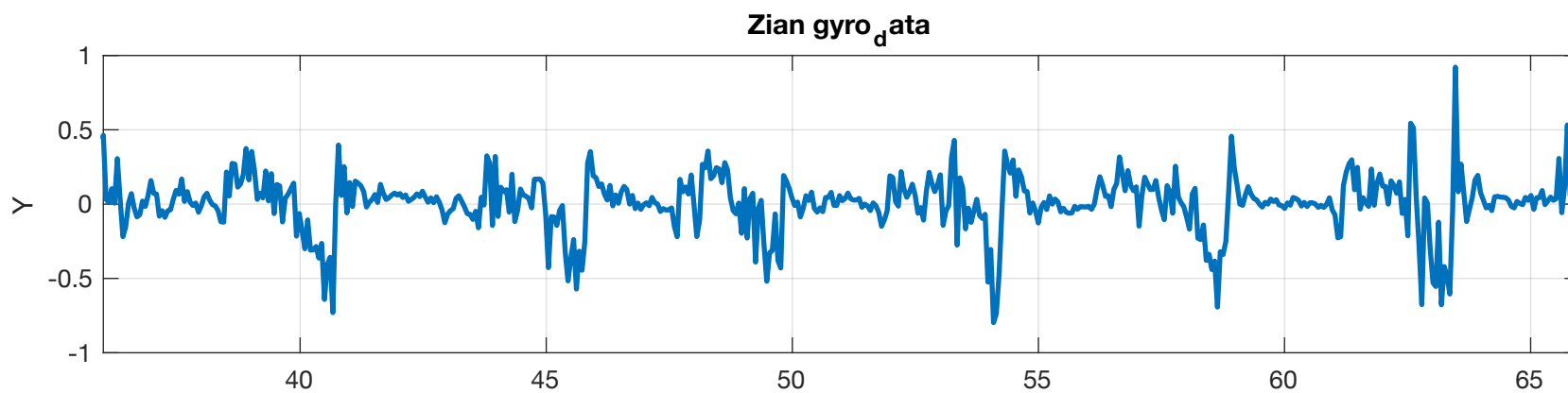


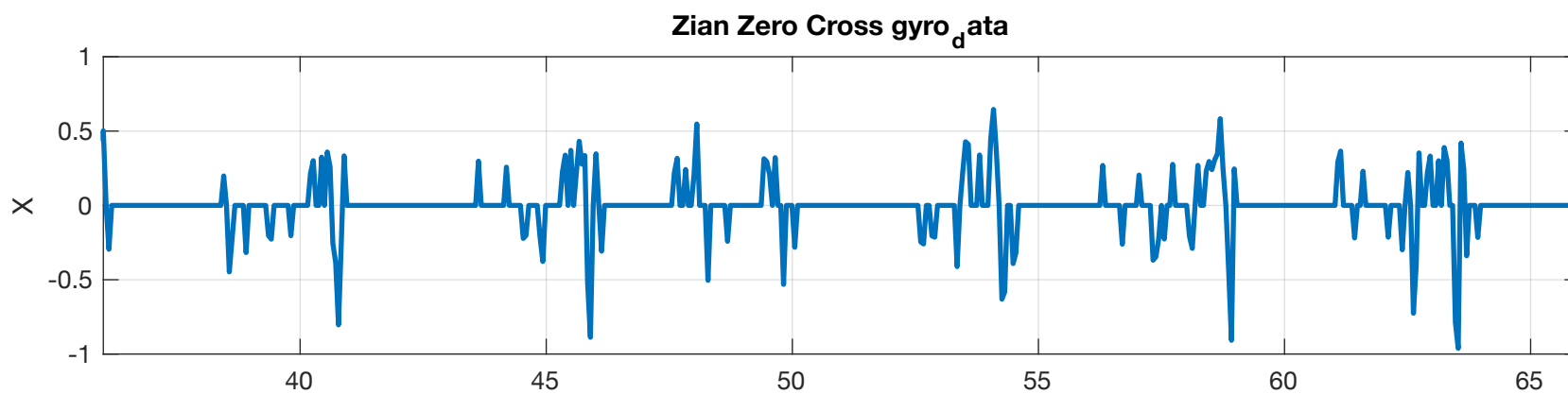
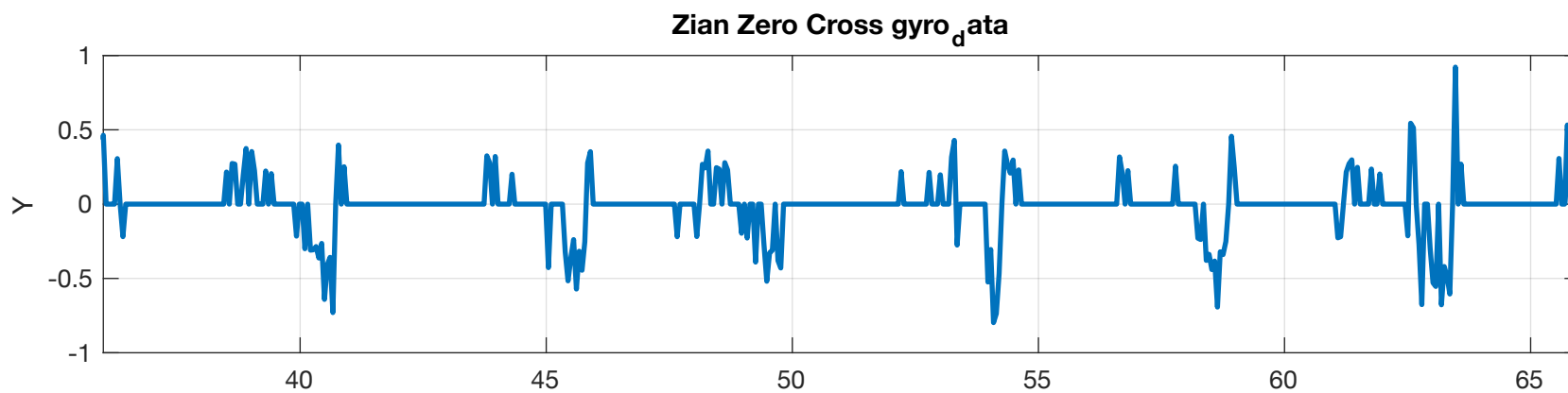
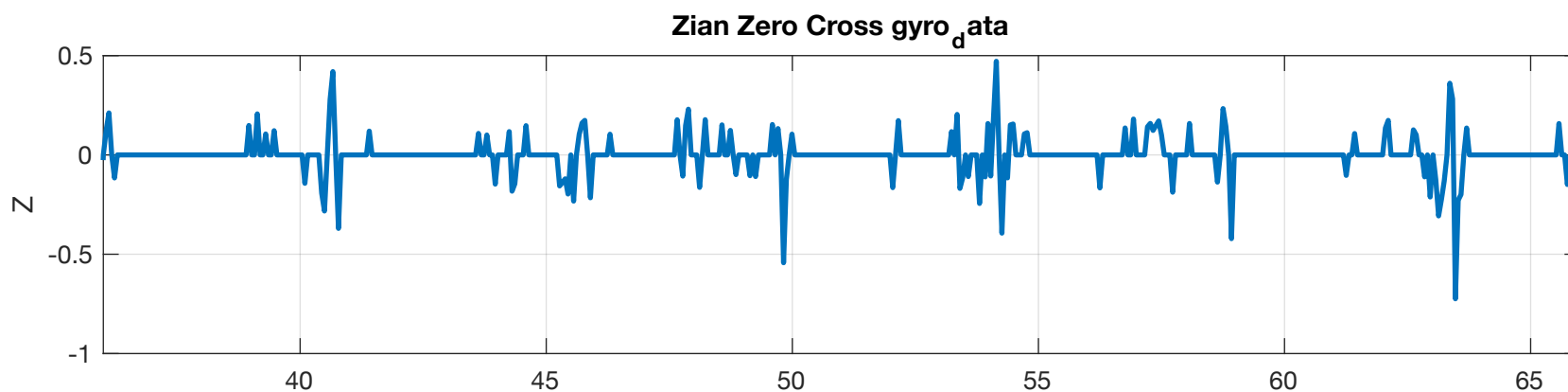
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-262.000	-201.000	-65.000	-77.500	"accel_data"
'Y'	-303.000	-265.000	-86.000	-64.000	"accel_data"
'X'	-282.000	-228.000	-76.000	-66.500	"accel_data"



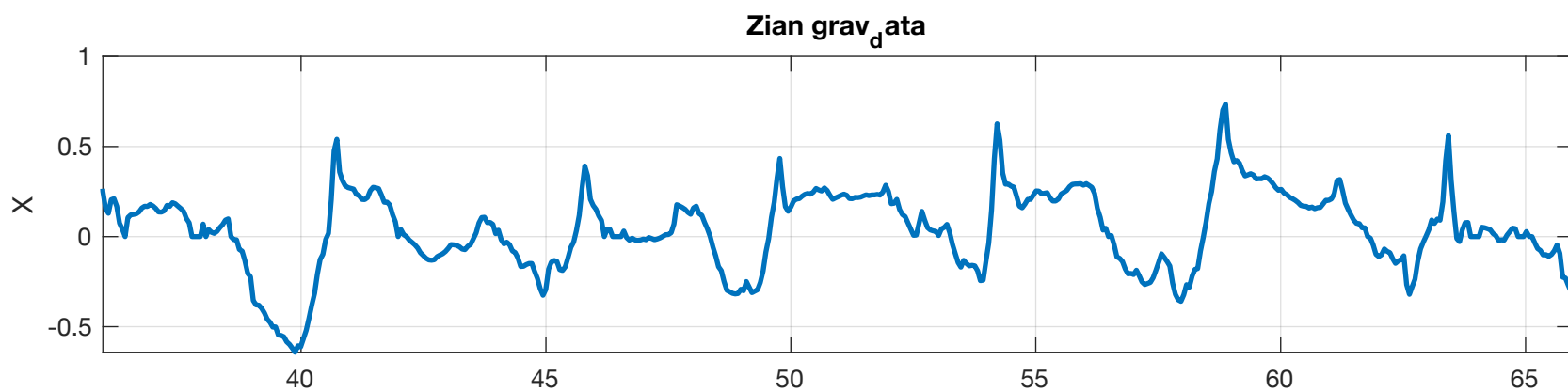
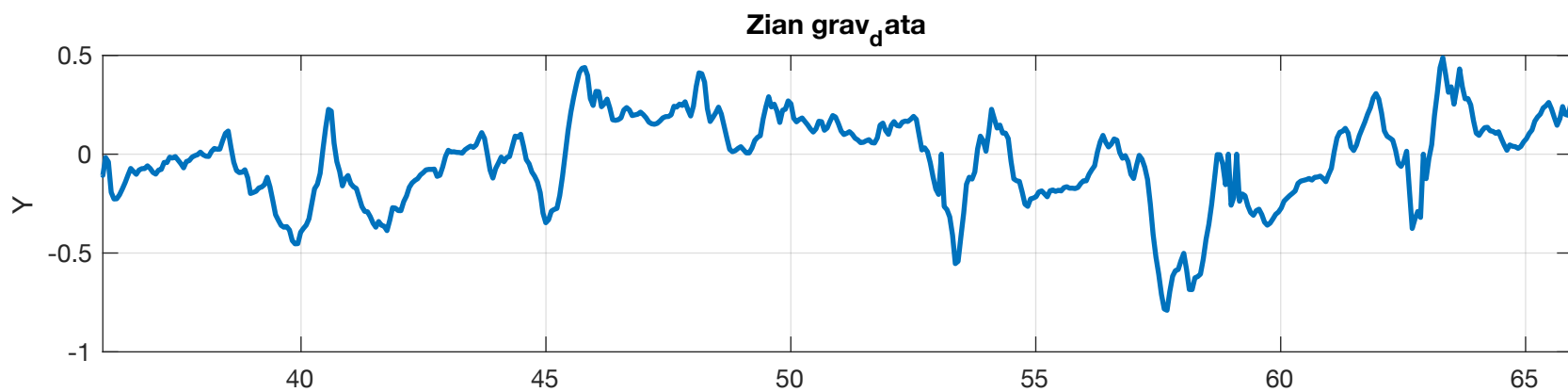
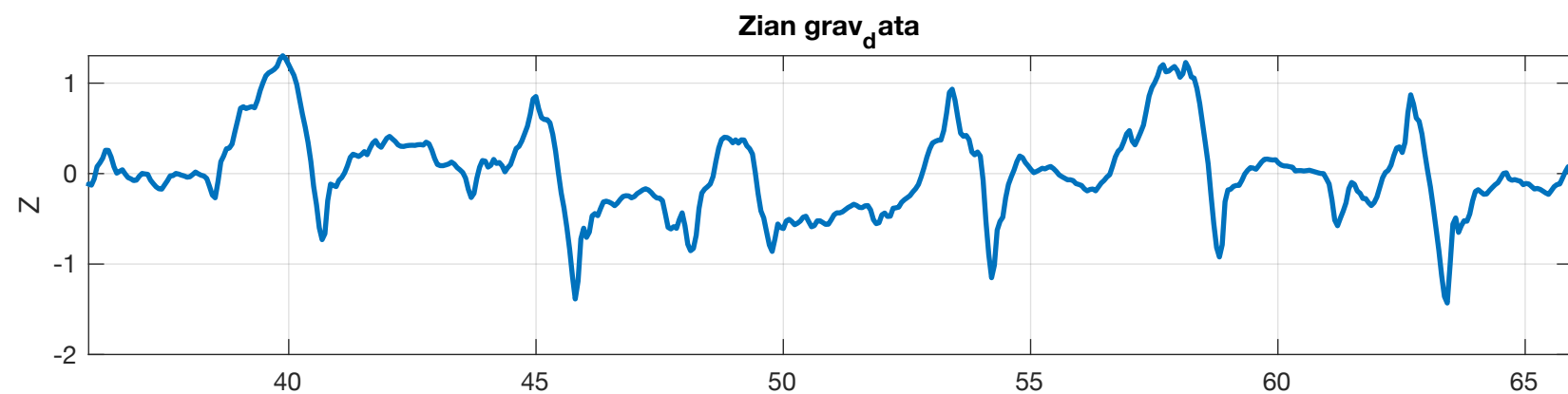


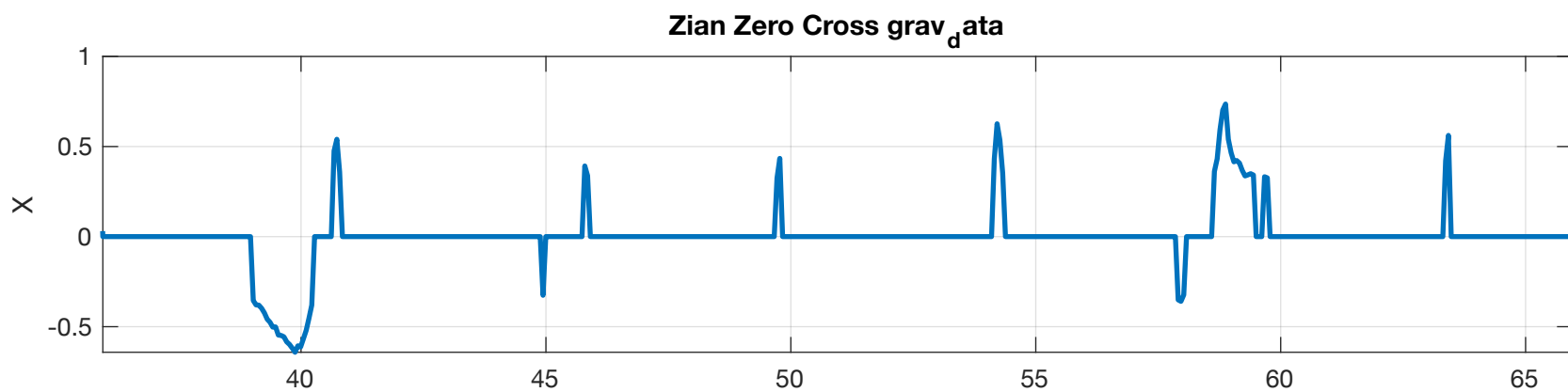
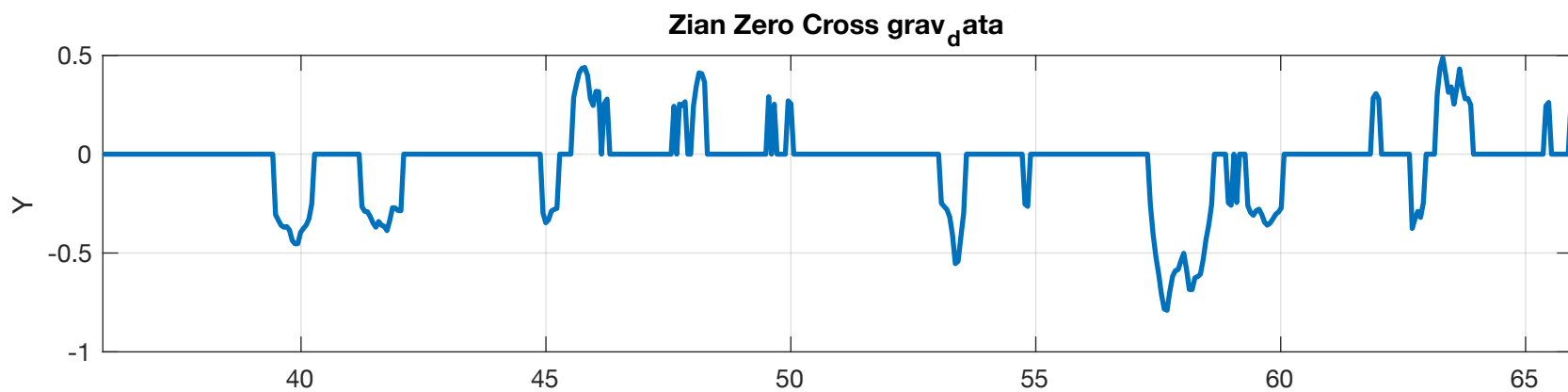
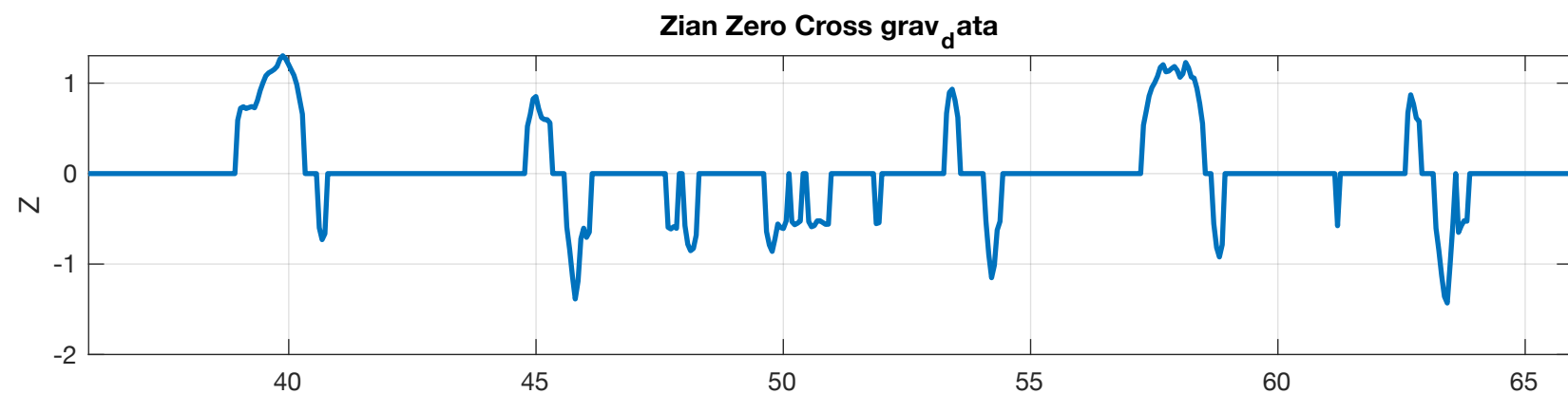
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-80.000	-55.000	-13.000	-8.500	"bar_data"
"Pressure"	-113.000	-58.000	-18.000	-8.500	"bar_data"



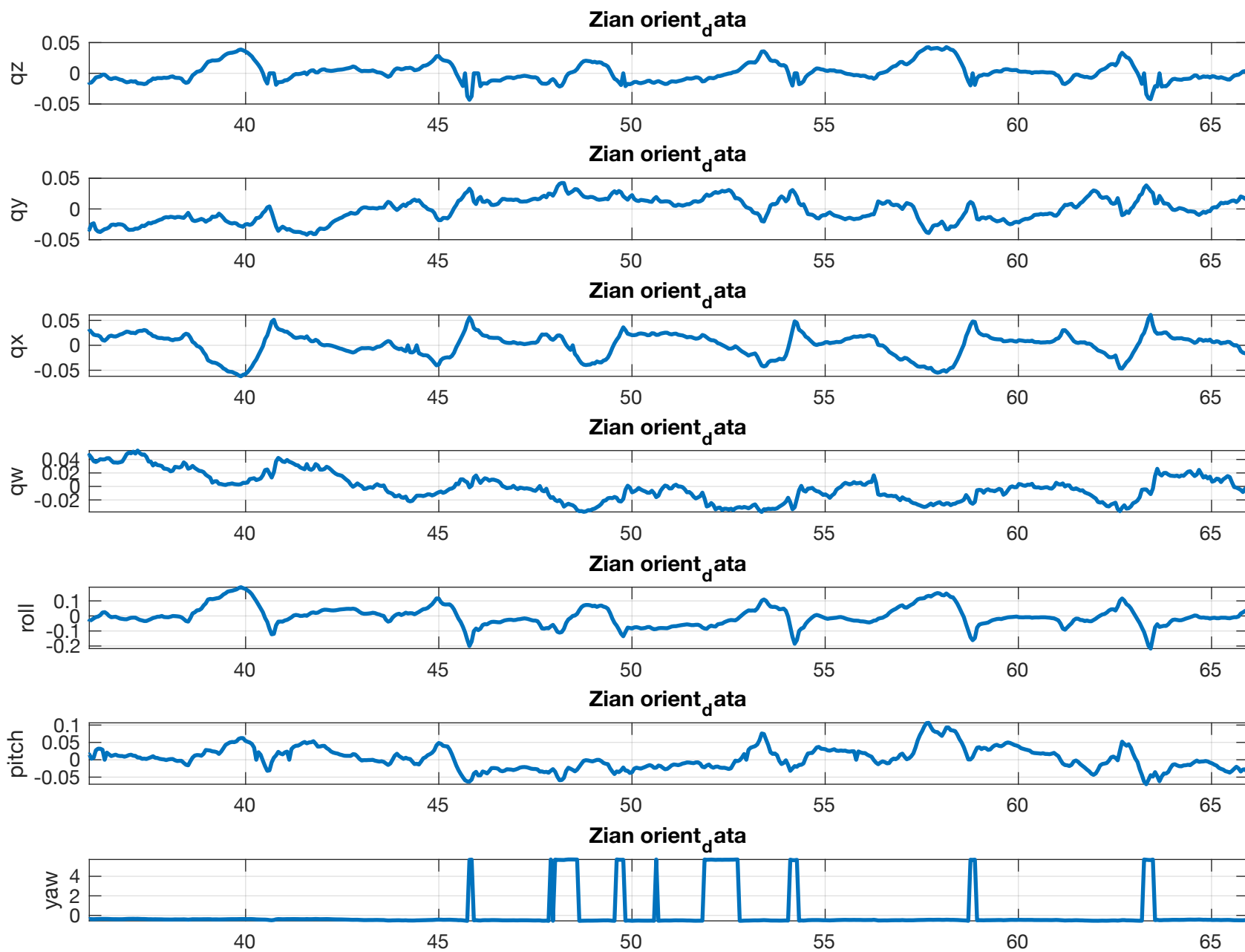


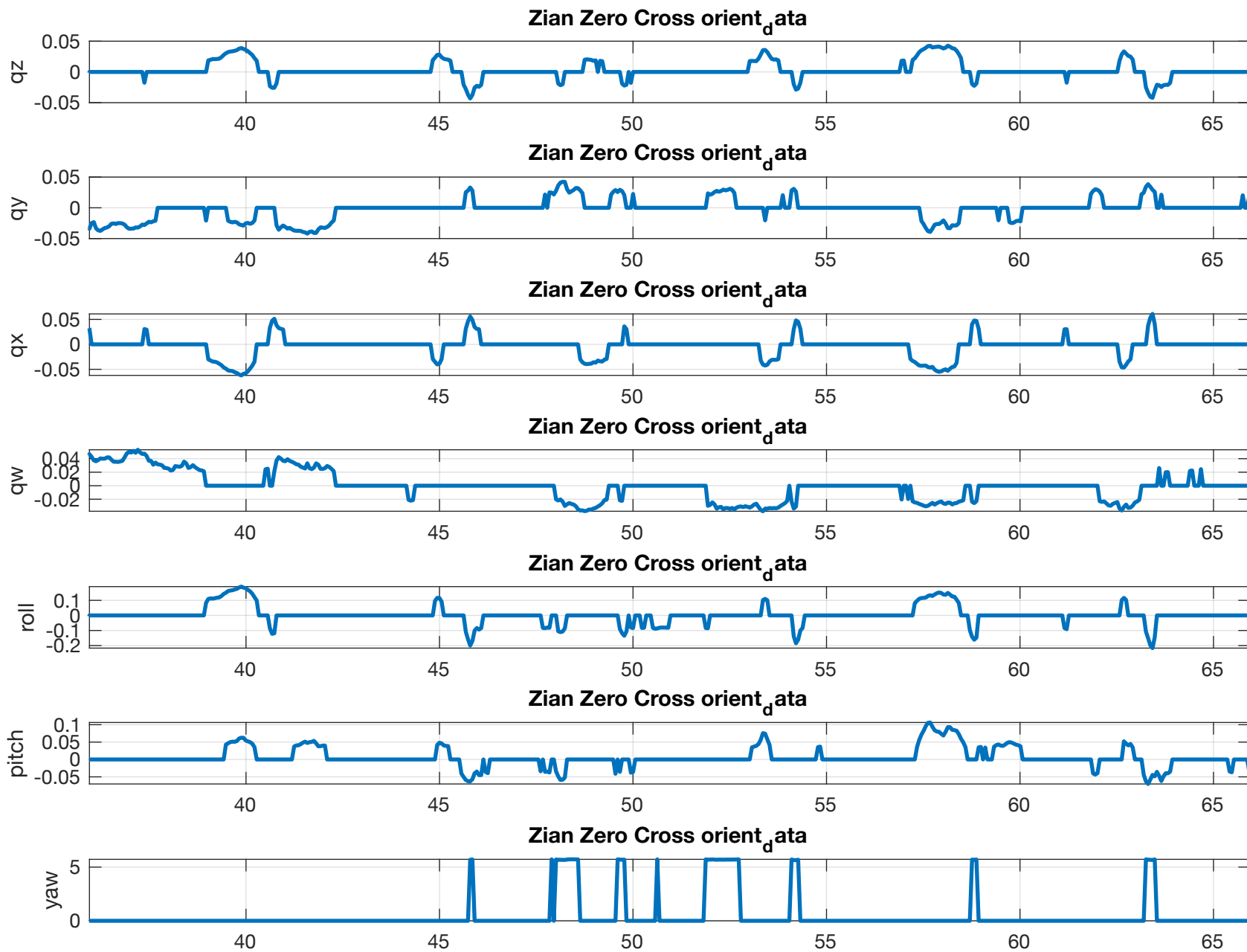
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-264.000	-203.000	-71.000	-62.000	"gyro_data"
'Y'	-289.000	-233.000	-68.000	-43.500	"gyro_data"
'X'	-244.000	-207.000	-65.000	-48.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-116.000	-52.000	-13.000	-3.500	"grav_data"
'Y'	-153.000	-91.000	-18.000	-8.000	"grav_data"
'X'	-129.000	-75.000	-15.000	-1.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-139.000	-49.000	-7.000	-3.500	"orient_data"
'qy'	-178.000	-105.000	-19.000	-5.500	"orient_data"
'qx'	-127.000	-80.000	-19.000	-2.500	"orient_data"
'qw'	-193.000	-99.000	-18.000	-7.000	"orient_data"
'roll'	-113.000	-48.000	-12.000	-3.000	"orient_data"
'pitch'	-154.000	-73.000	-12.000	-8.000	"orient_data"
'yaw'	-191.000	-18.000	-4.000	3.500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Y"	'zero_cross'	64.000
'bar_data'	"Relative Altitude"	'zero_cross'	8.500
'gyro_data'	"Y"	'zero_cross'	43.500
'grav_data'	"X"	'zero_cross'	1.000
'orient_data'	"qx"	'zero_cross'	2.500