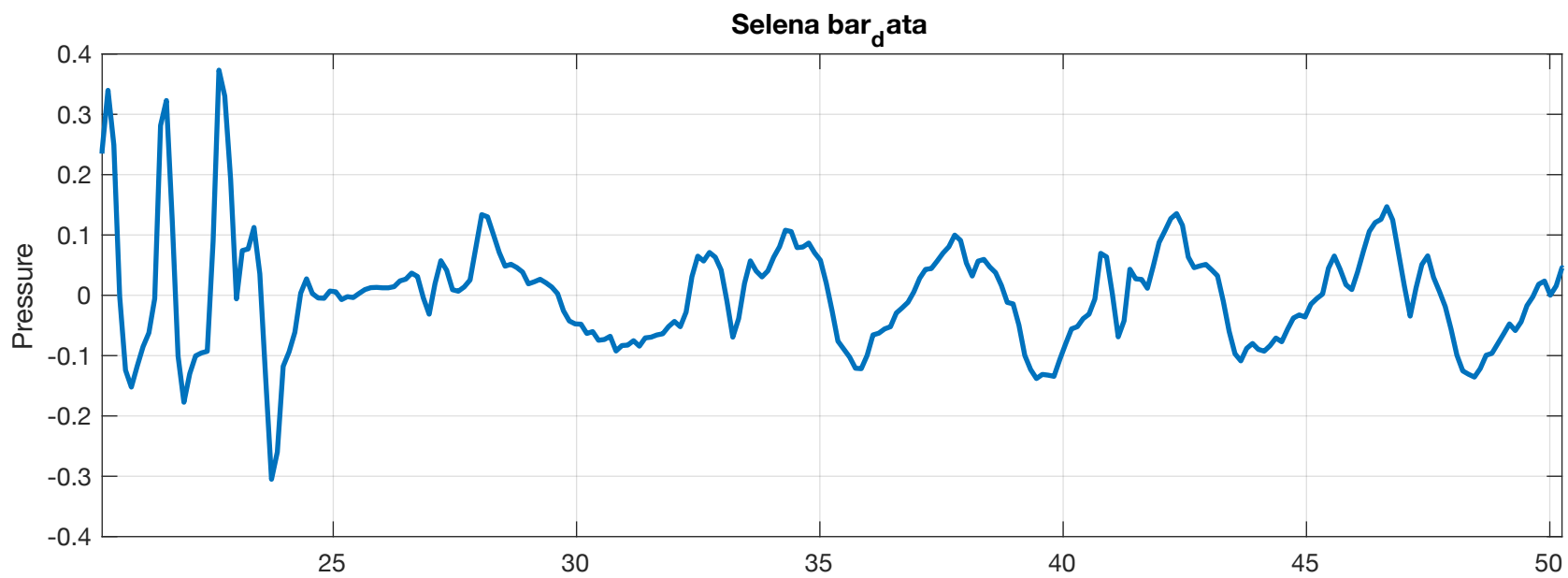
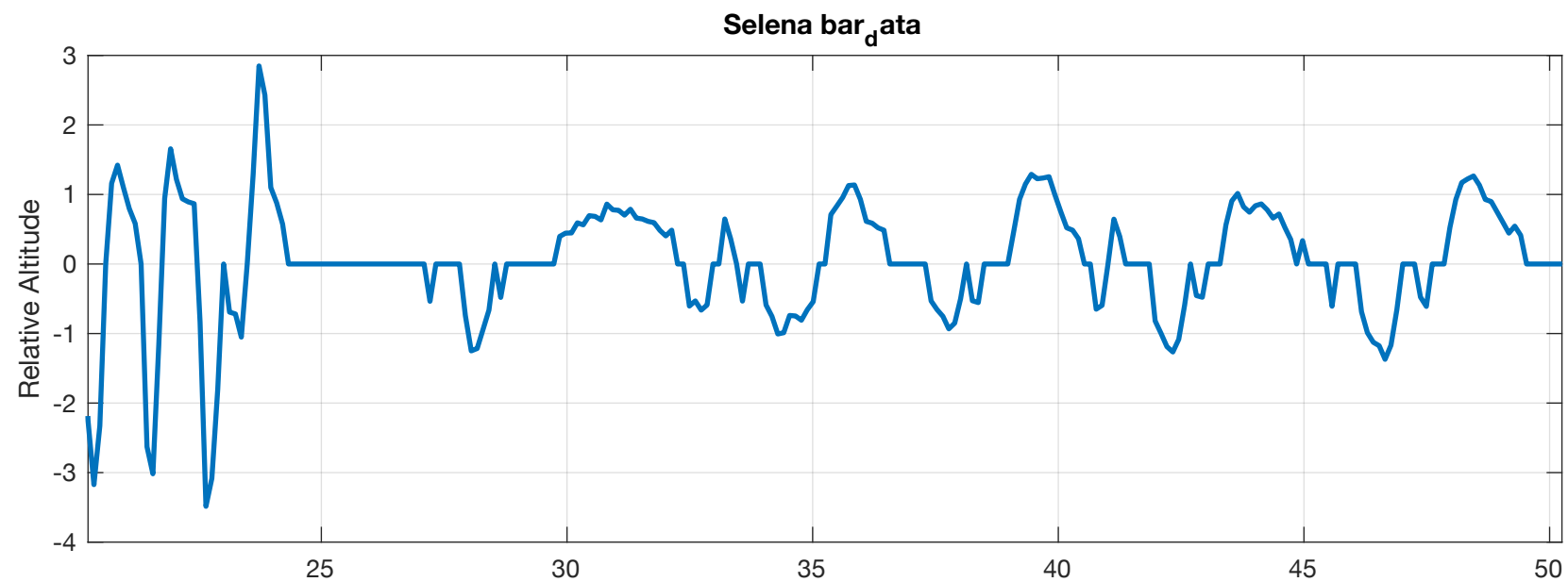
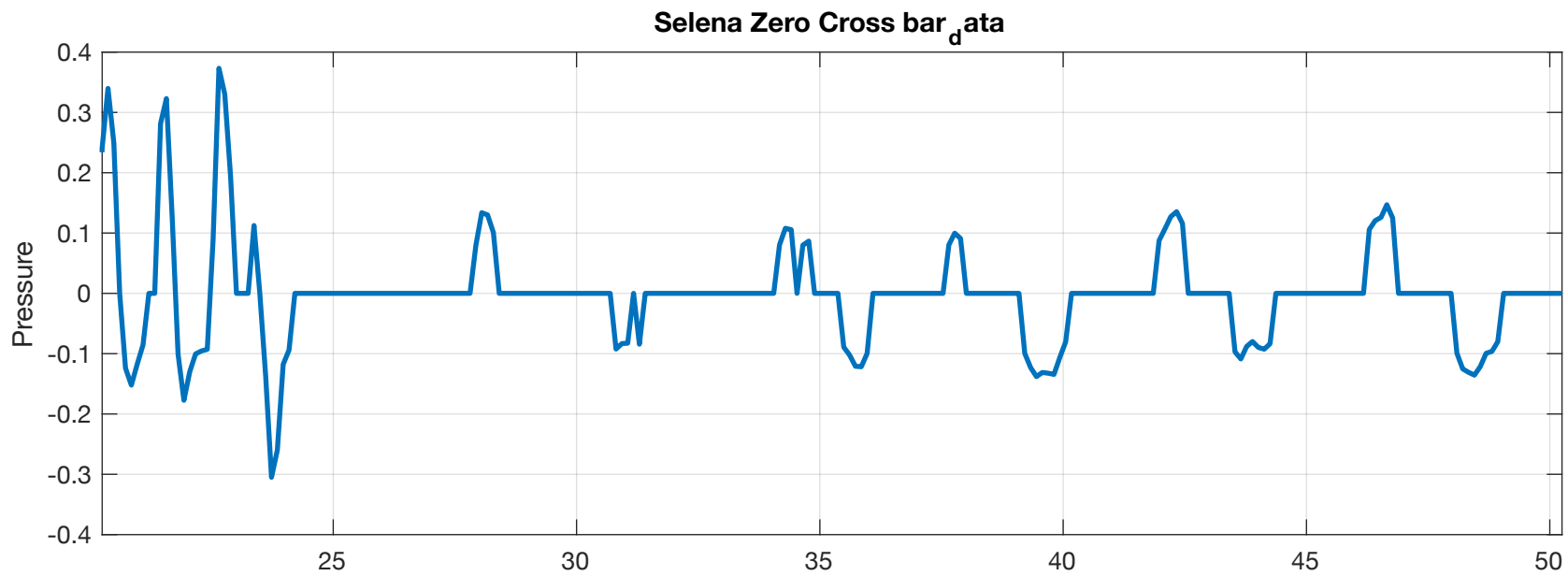
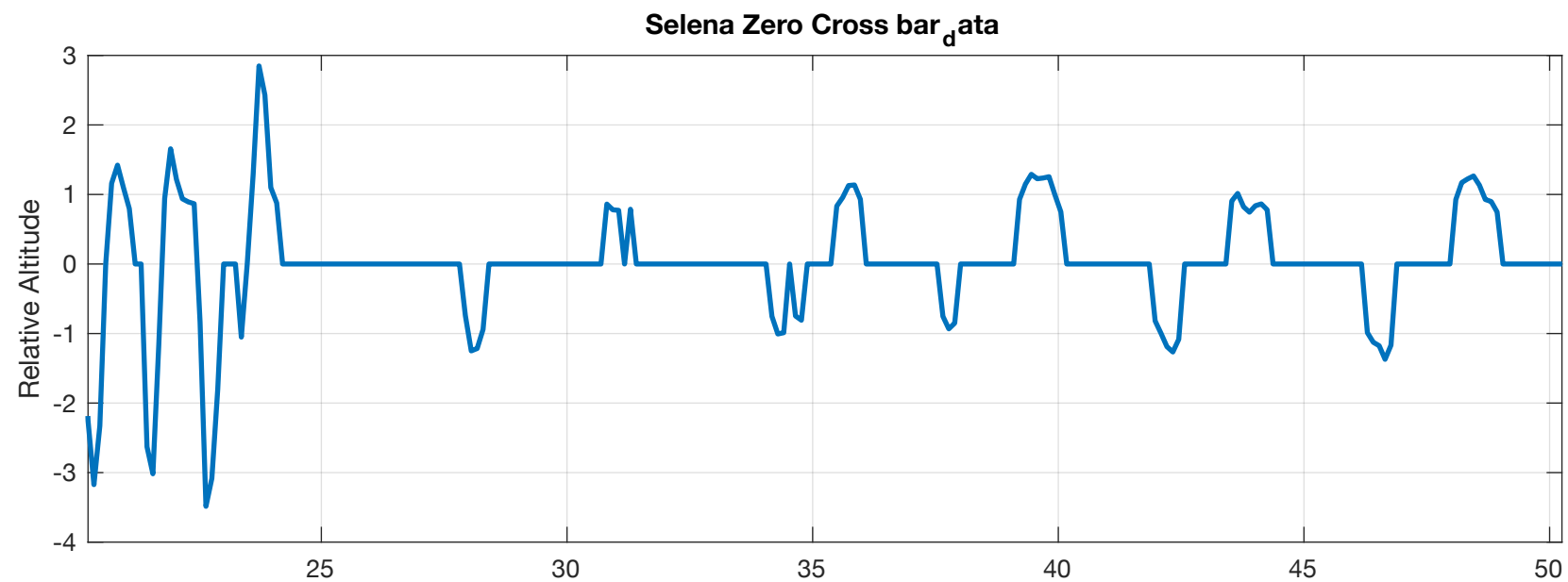
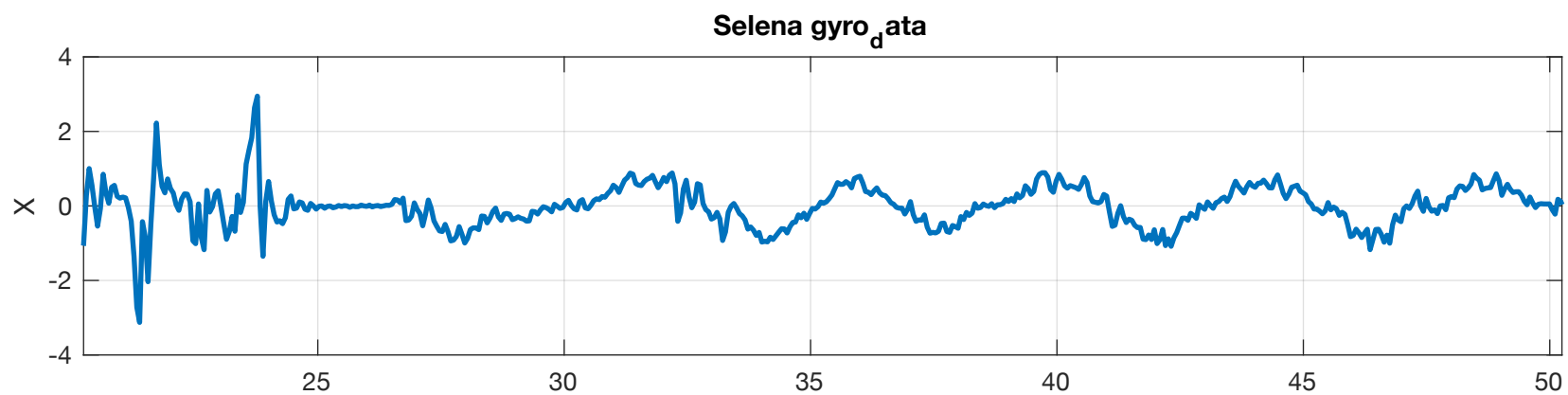
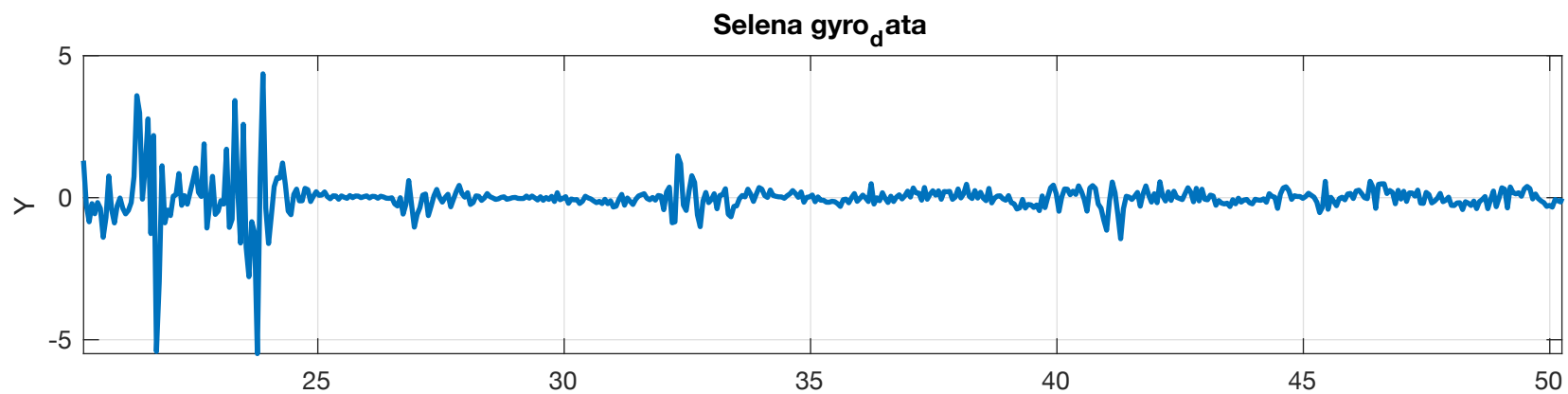
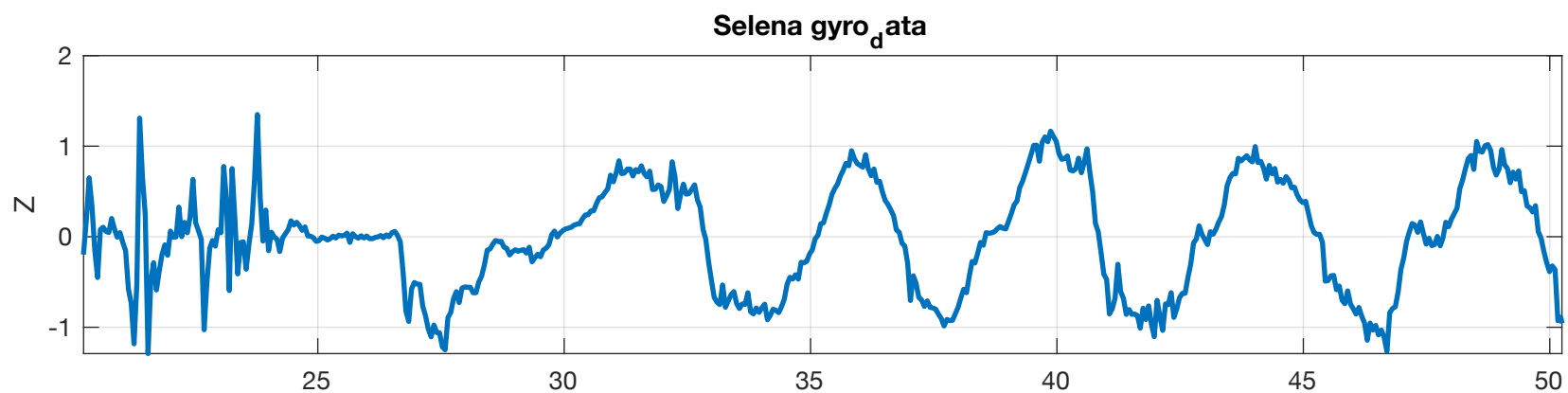


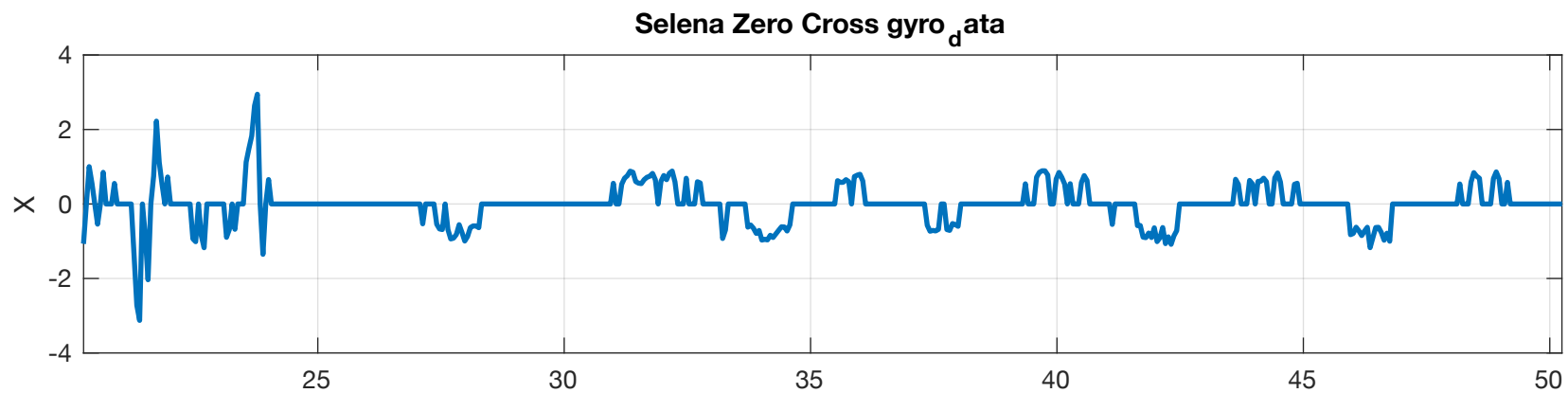
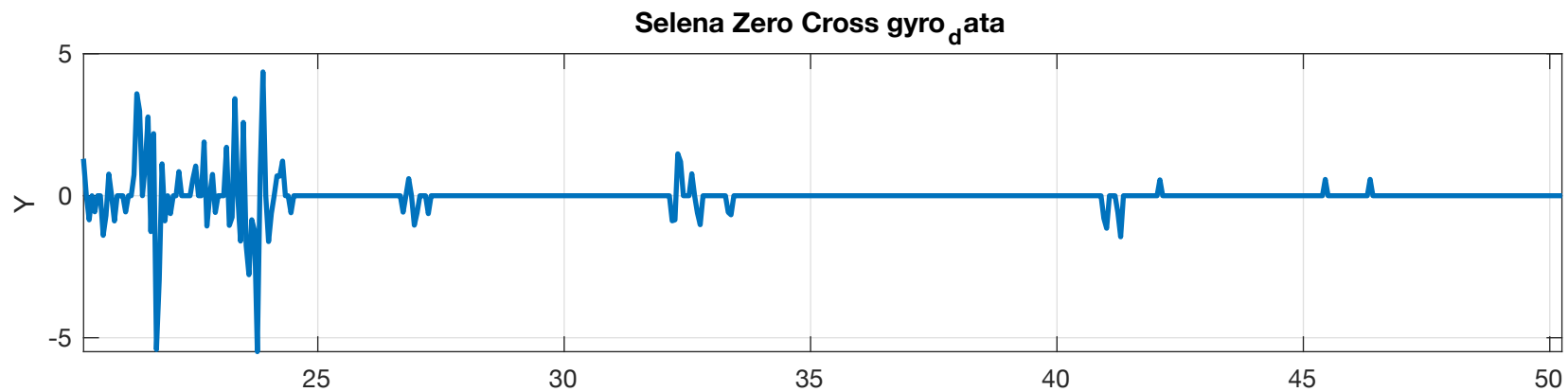
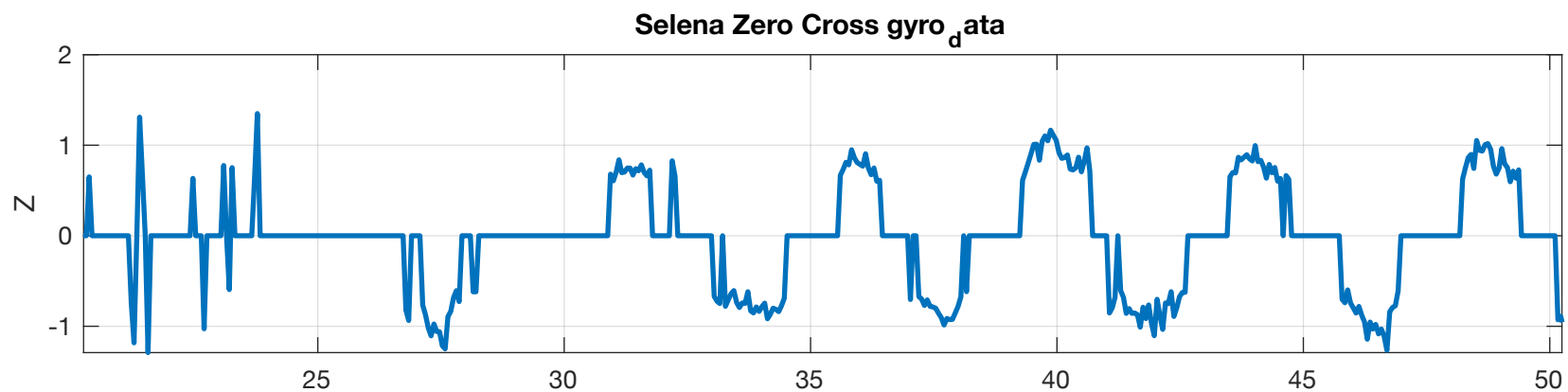
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-391.000	-349.000	-115.000	-105.000	"accel_data"
'Y'	-428.000	-365.000	-128.000	-118.500	"accel_data"
'X'	-415.000	-318.000	-121.000	-67.500	"accel_data"





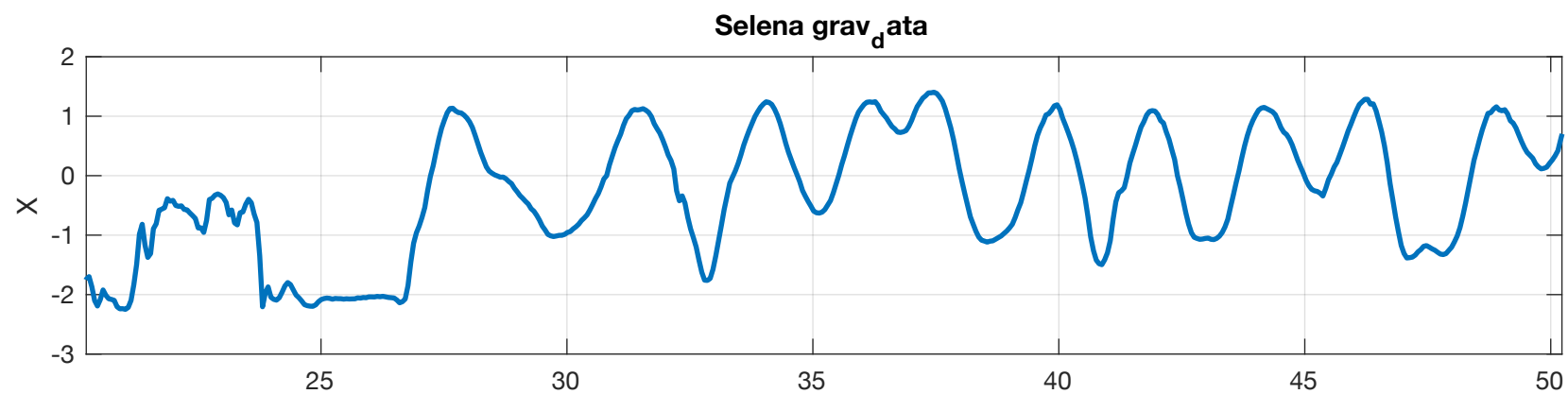
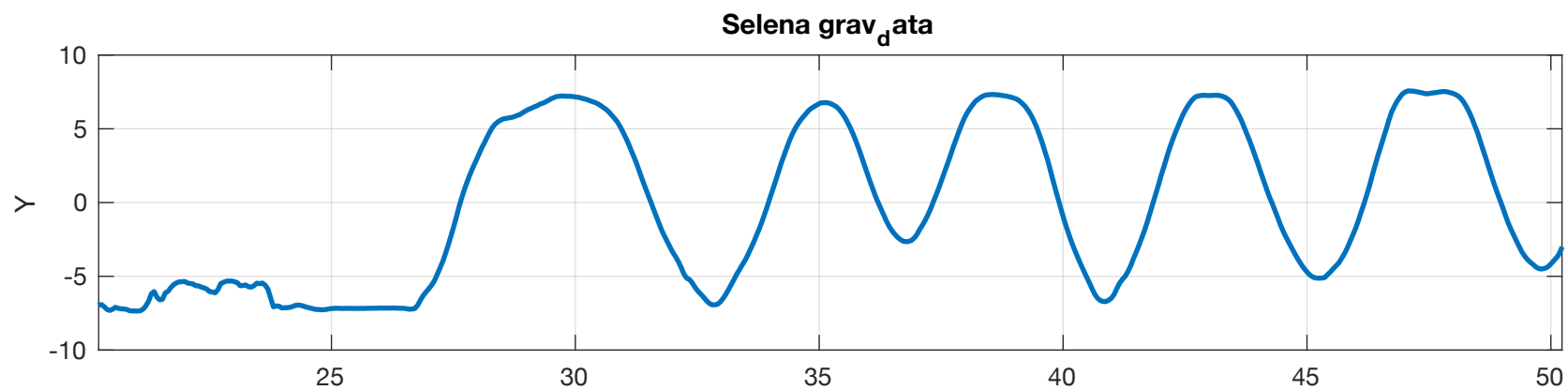
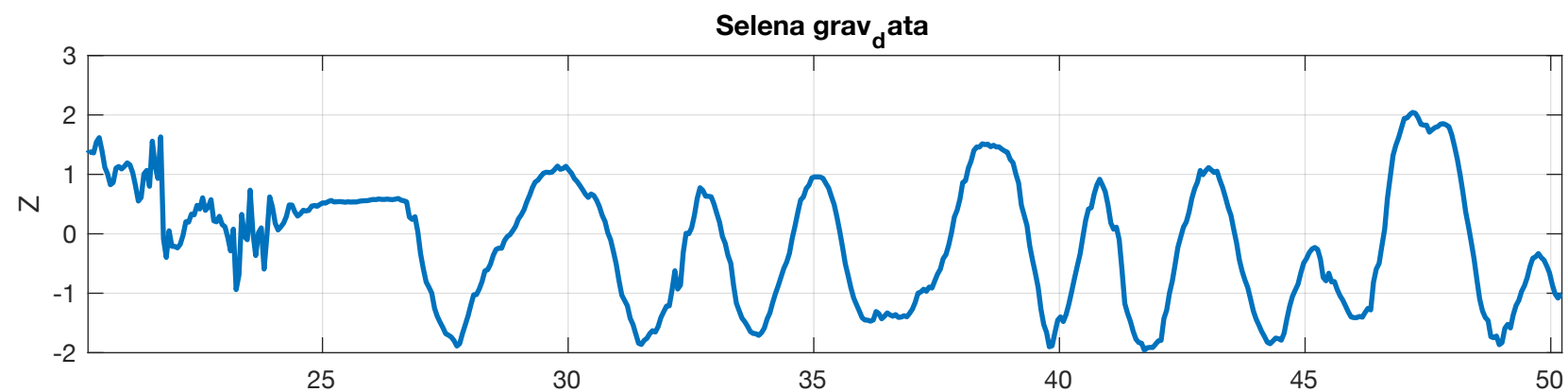
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-64.000	-48.000	-13.000	-14.500	"bar_data"
"Pressure"	-92.000	-60.000	-16.000	-14.500	"bar_data"

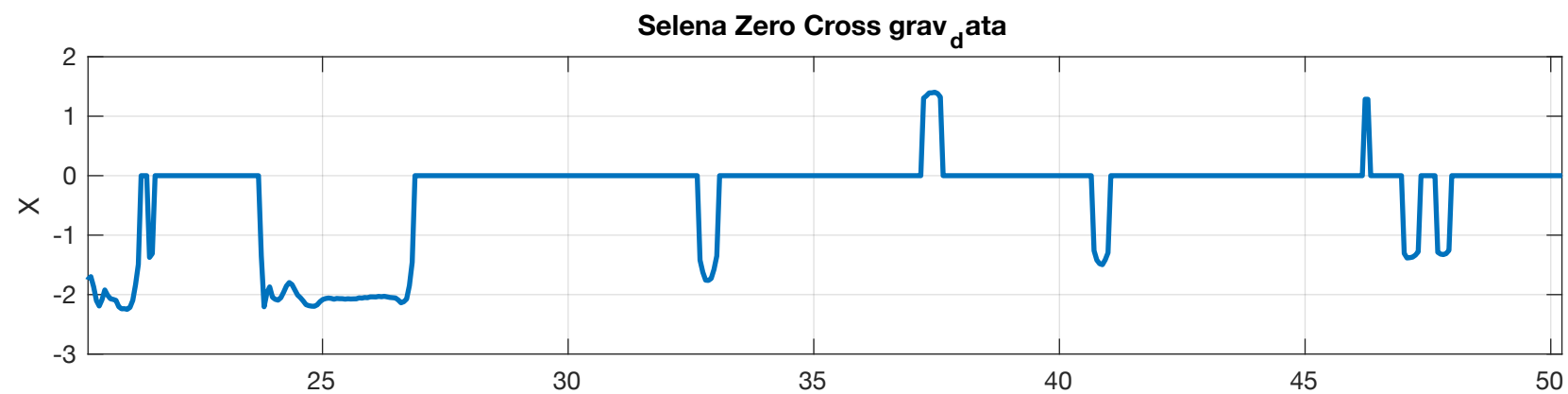
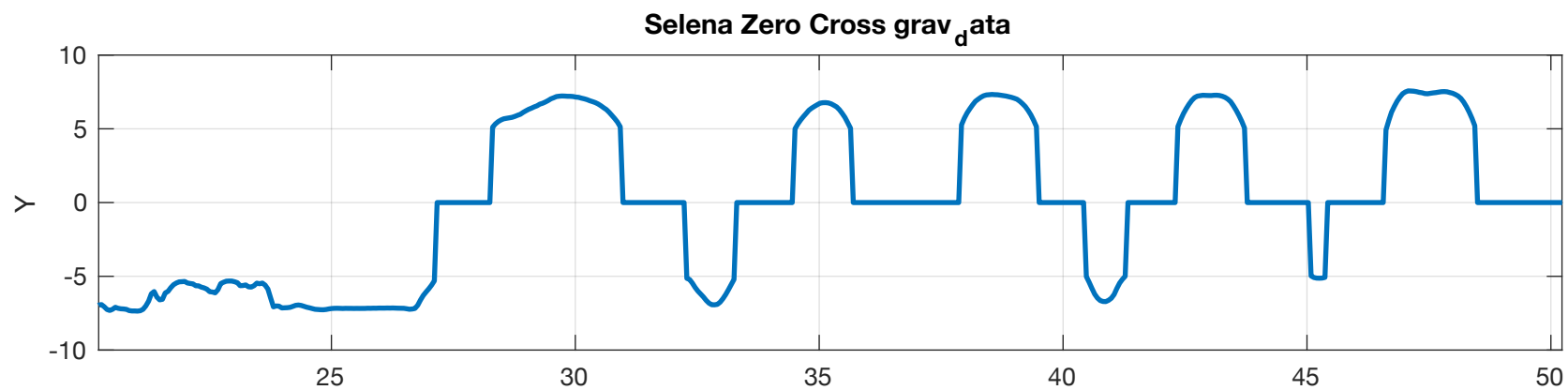
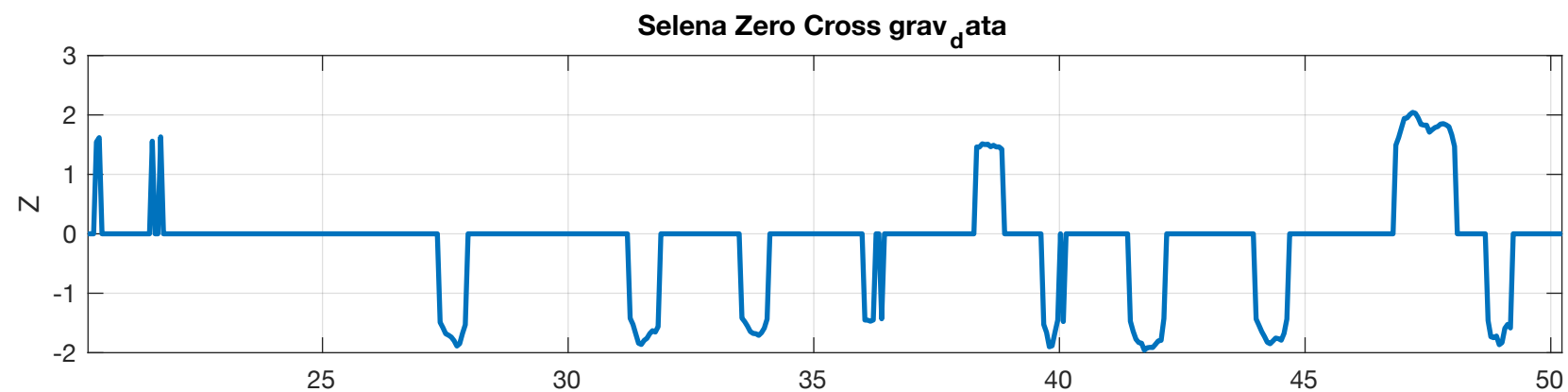




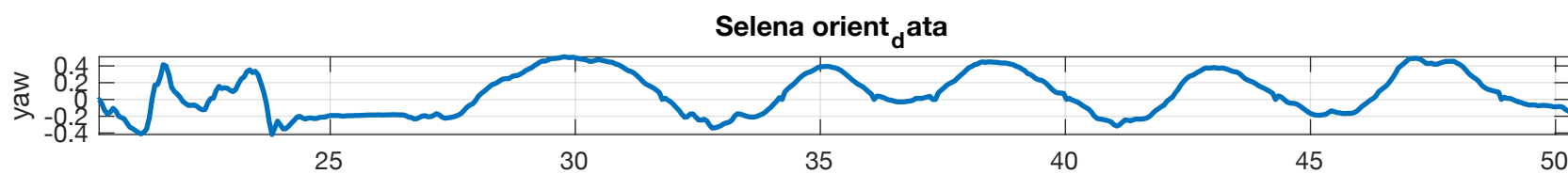
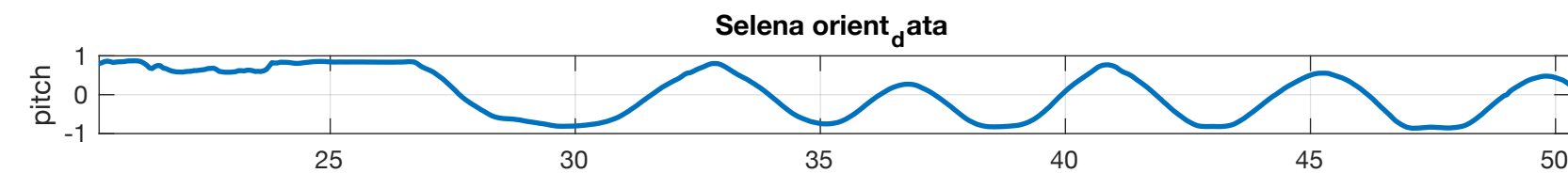
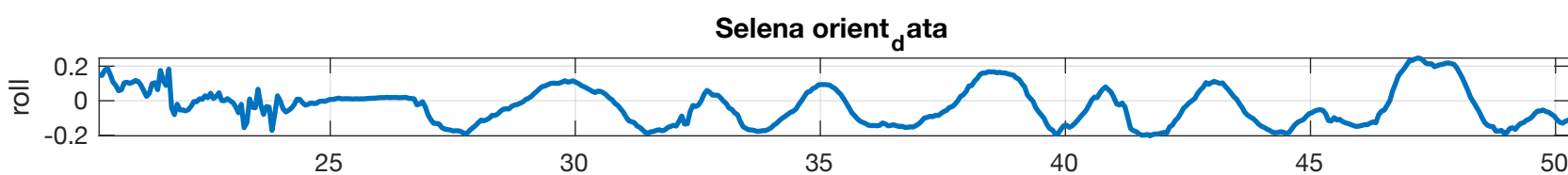
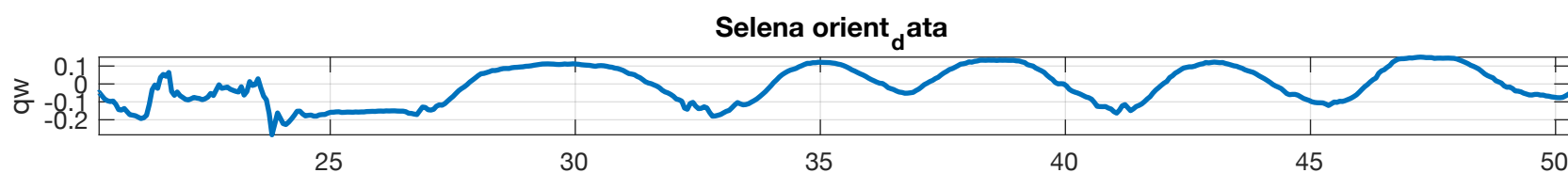
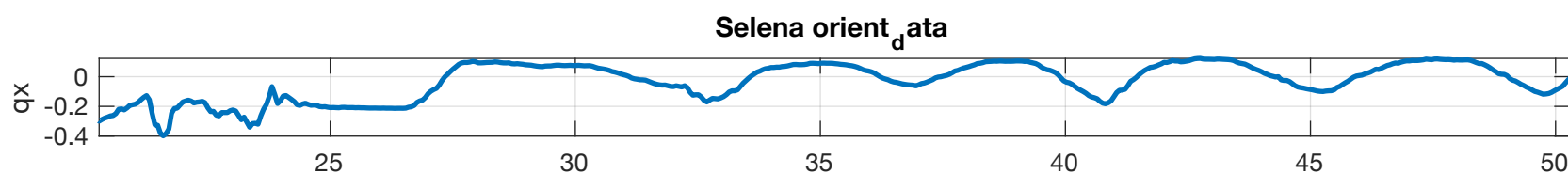
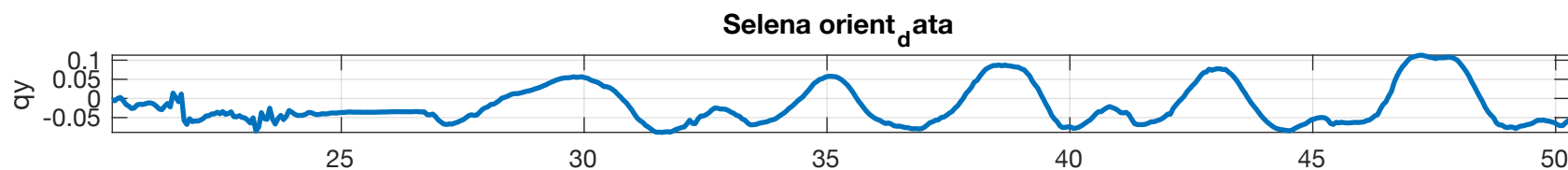
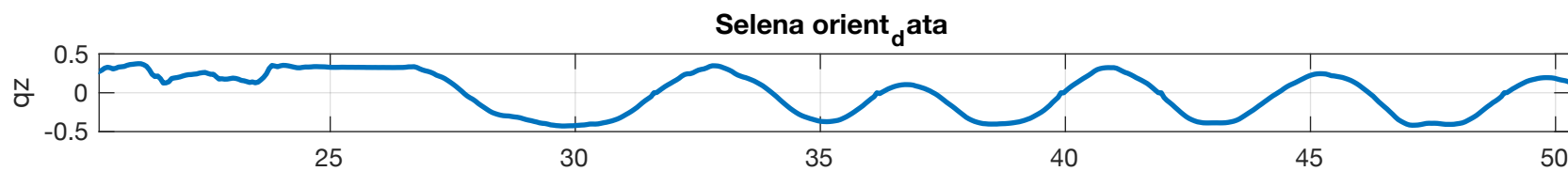


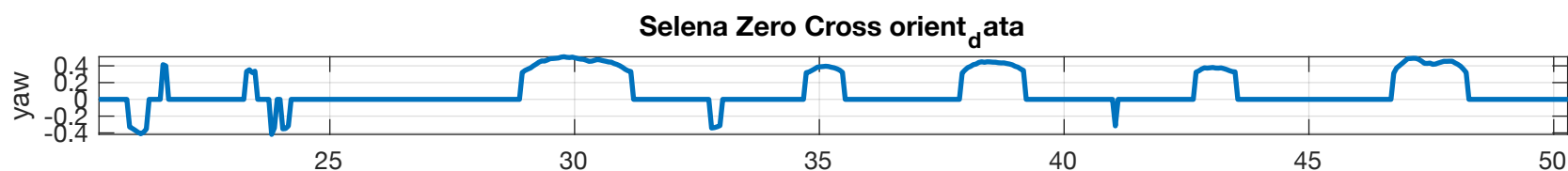
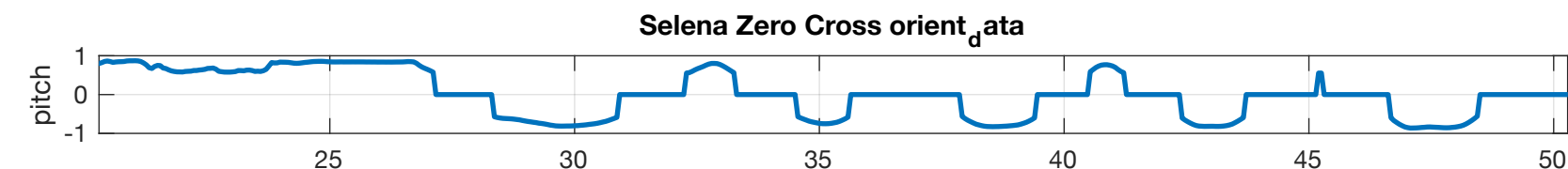
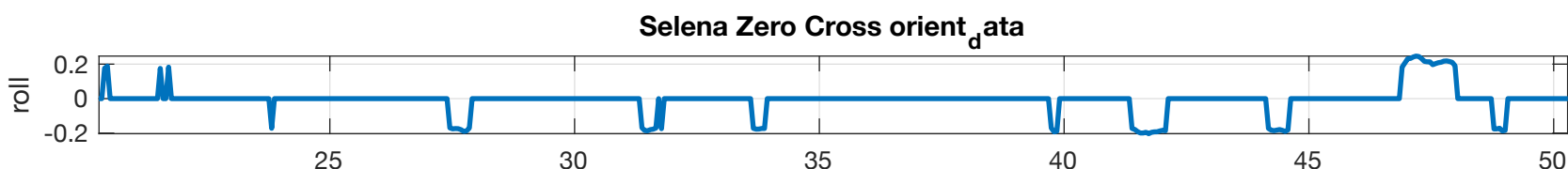
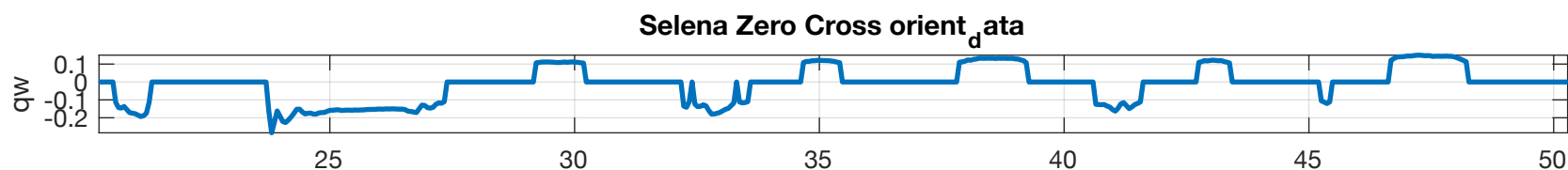
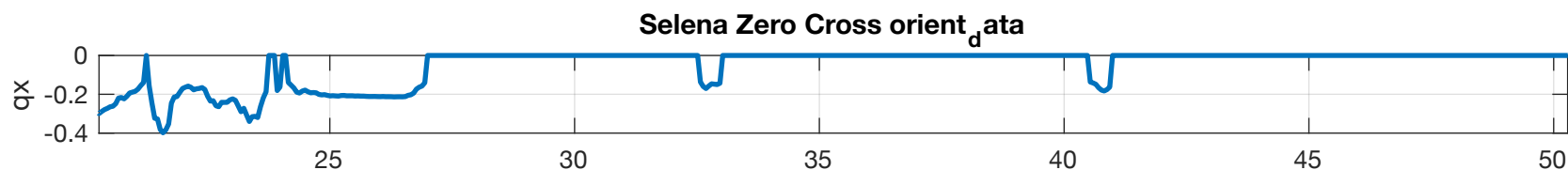
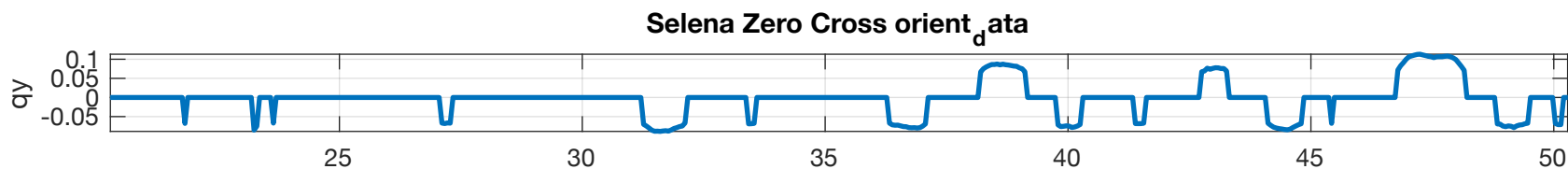
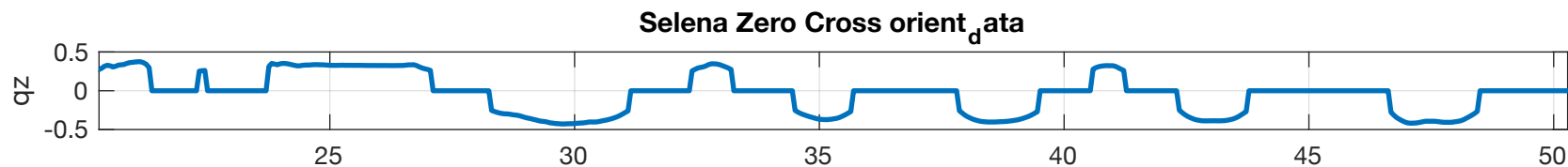
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-341.000	-214.000	-55.000	-22.000	"gyro_data"
'Y'	-400.000	-320.000	-99.000	-57.750	"gyro_data"
'X'	-327.000	-212.000	-65.000	-49.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-184.000	-105.000	-28.000	-8.750	"grav_data"
'Y'	-69.000	-19.000	0.000	1.000	"grav_data"
'X'	-107.000	-70.000	-18.000	-6.500	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-83.000	-62.000	-13.000	-0.500	"orient_data"
'qy'	-159.000	-42.000	-17.000	-3.500	"orient_data"
'qx'	-145.000	-73.000	-14.000	-3.250	"orient_data"
'qw'	-163.000	-76.000	-18.000	-6.250	"orient_data"
'roll'	-199.000	-98.000	-28.000	-7.750	"orient_data"
'pitch'	-70.000	-56.000	-10.000	1.000	"orient_data"
'yaw'	-141.000	-52.000	-8.000	-4.250	"orient_data"

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Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'zero_cross'	67.500
'bar_data'	"Relative Altitude"	'double_findpeaks'	13.000
'gyro_data'	"Z"	'zero_cross'	22.000
'grav_data'	"Y"	'double_findpeaks'	0.000
'orient_data'	"qz"	'zero_cross'	0.500