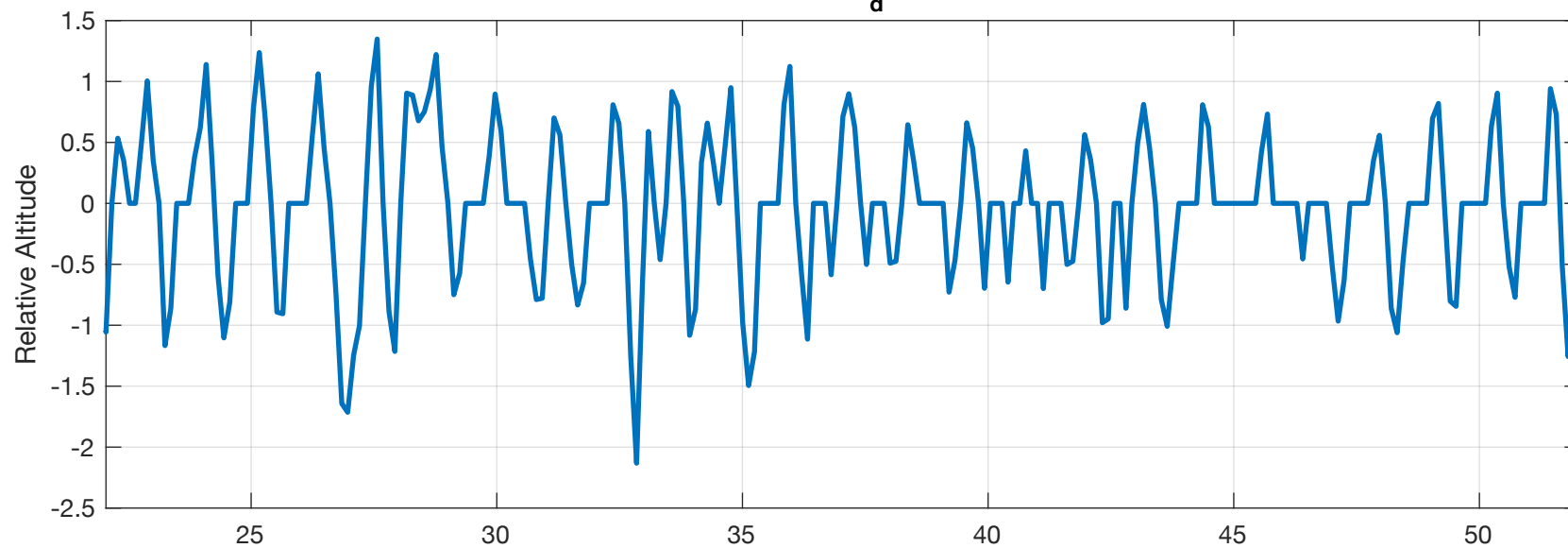
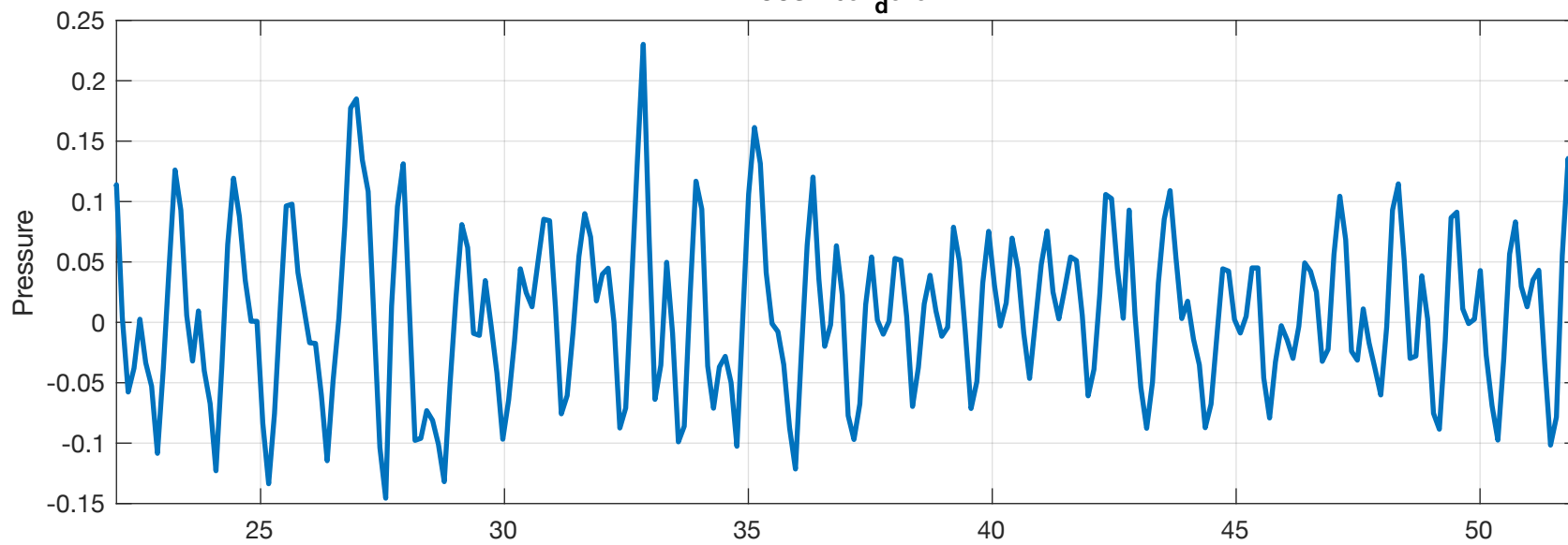


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-195.000	-112.000	2.000	-2.000	"accel_data"
'Y'	-160.000	-126.000	0.000	-11.000	"accel_data"
'X'	-151.000	-54.000	45.000	8.500	"accel_data"

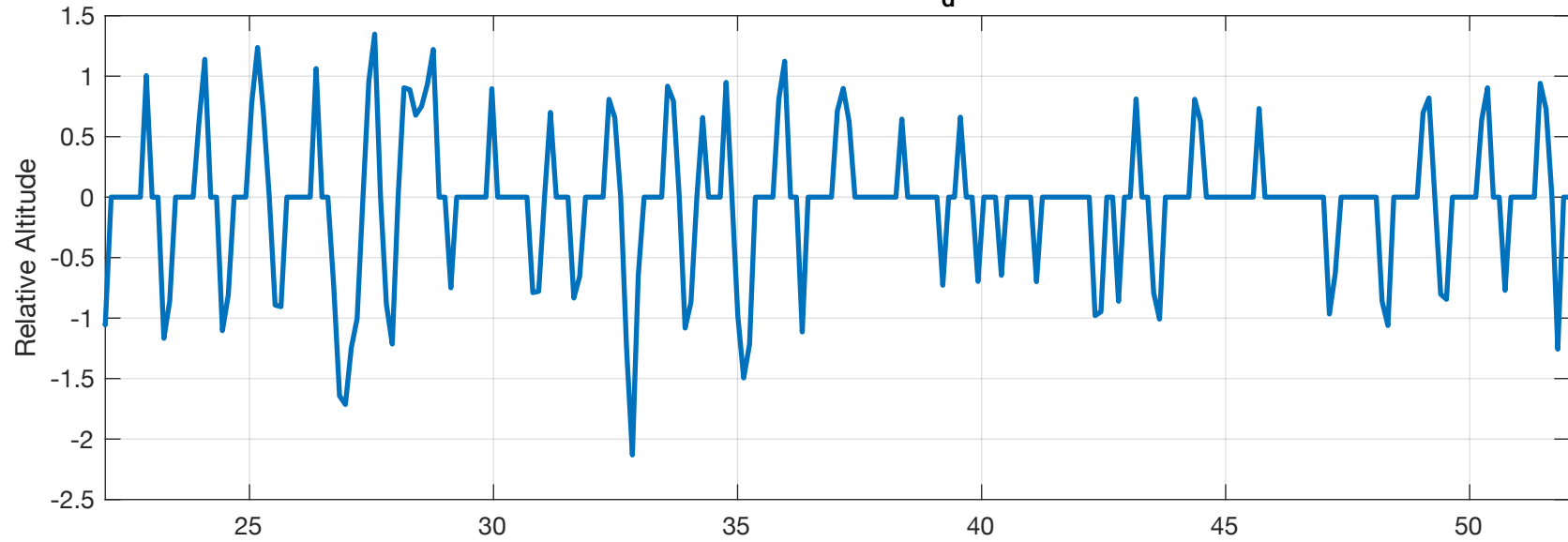
Josh bar_data



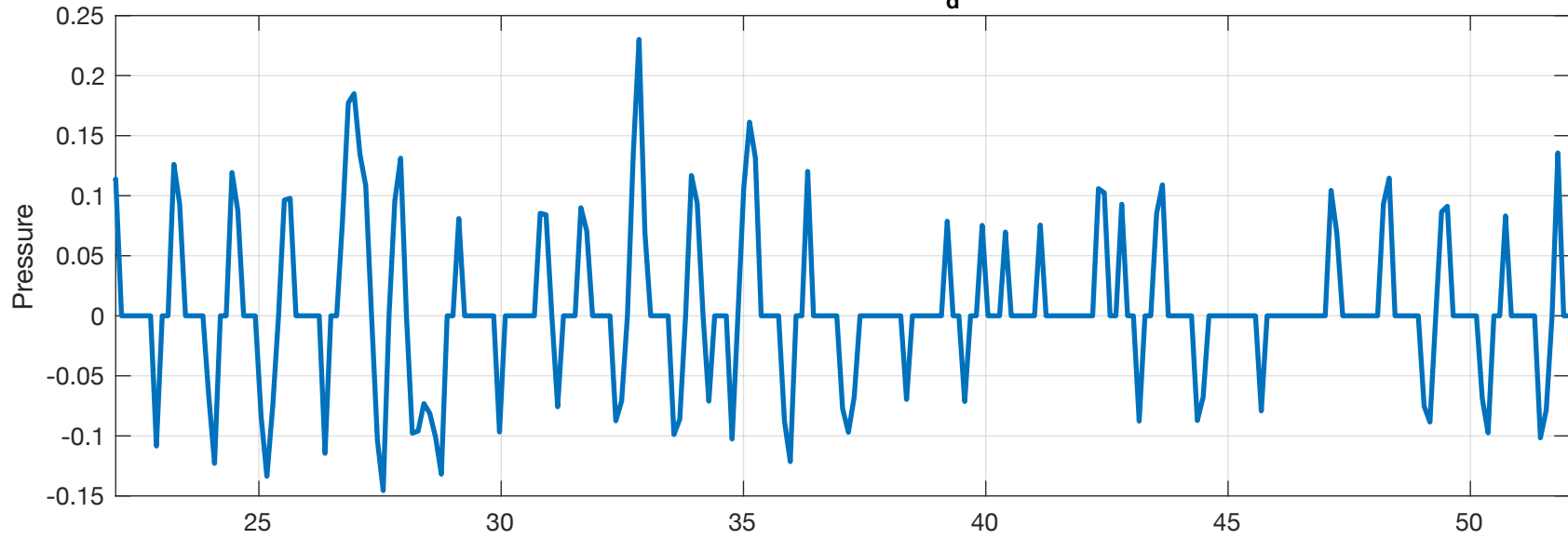
Josh bar_data



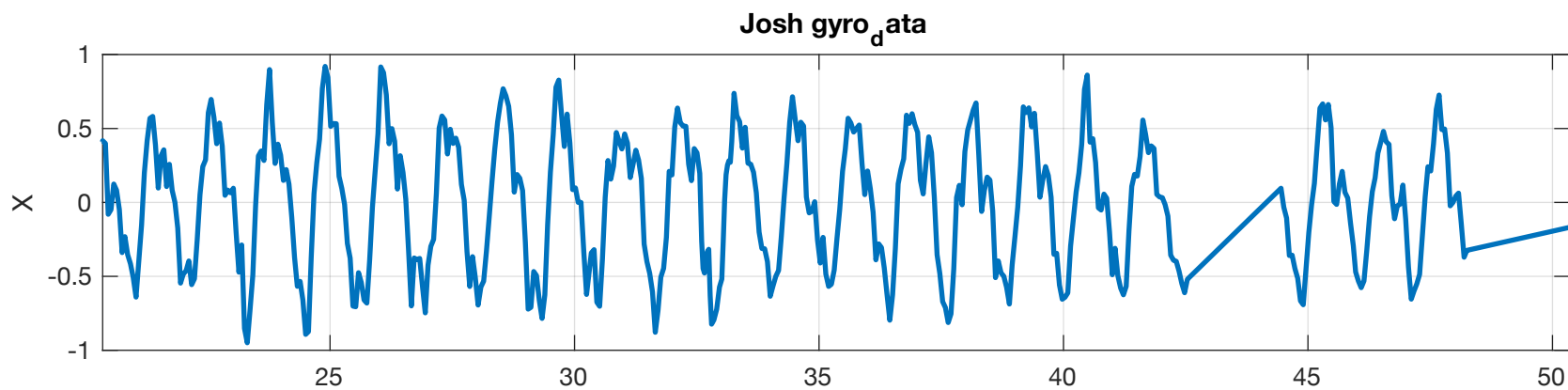
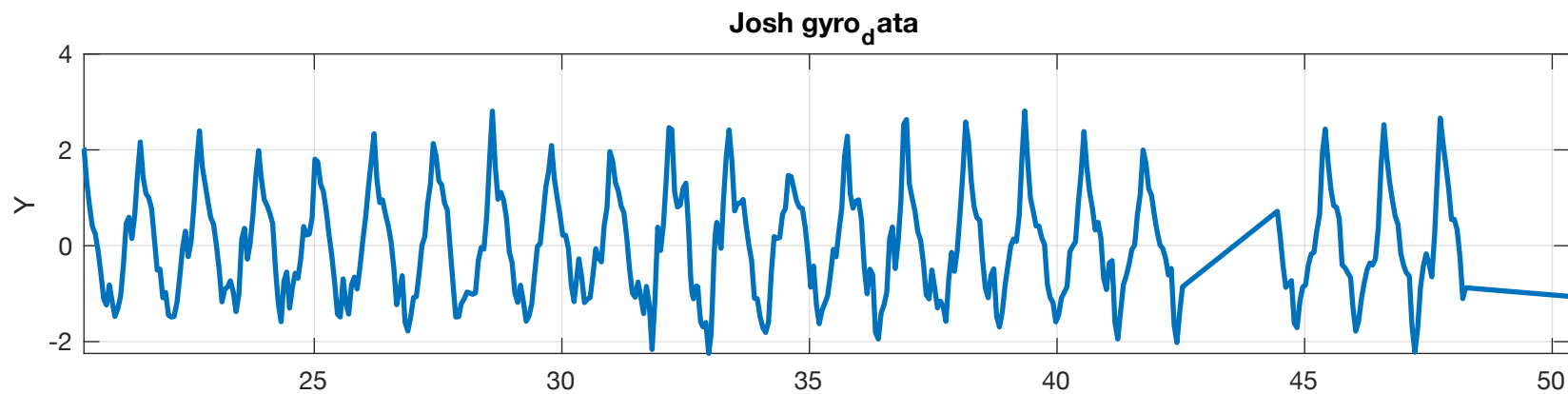
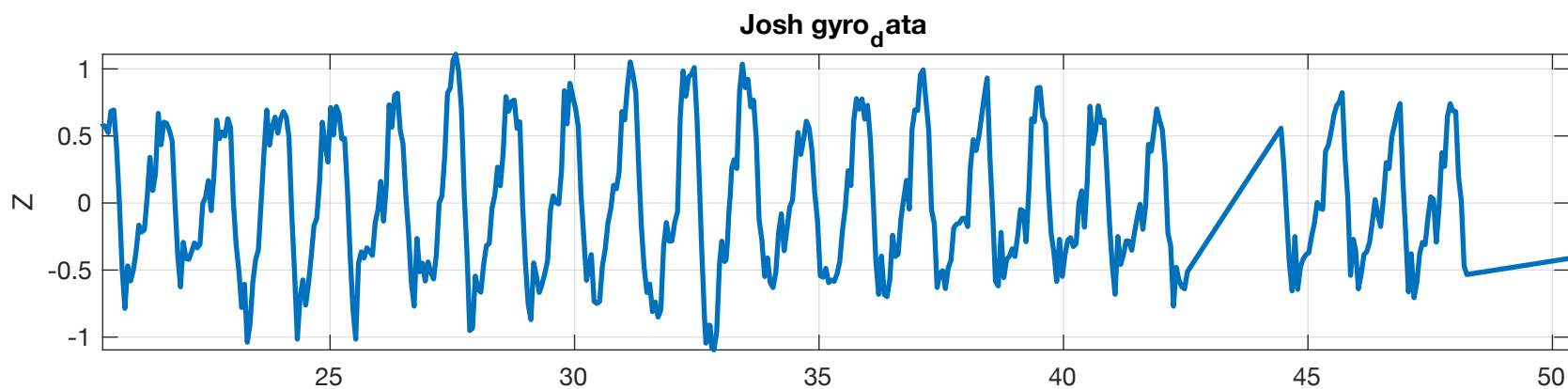
Josh Zero Cross bar_data

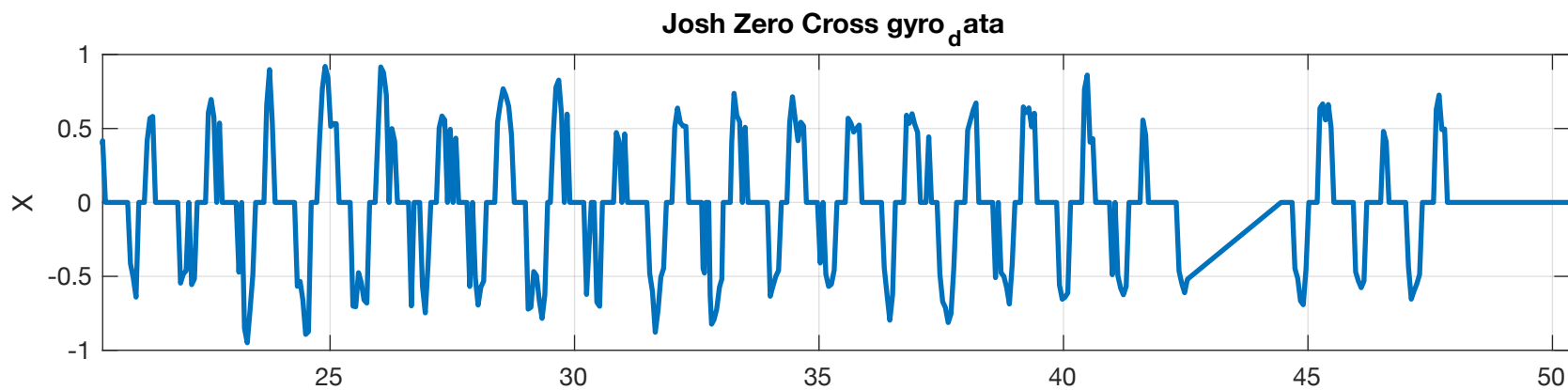
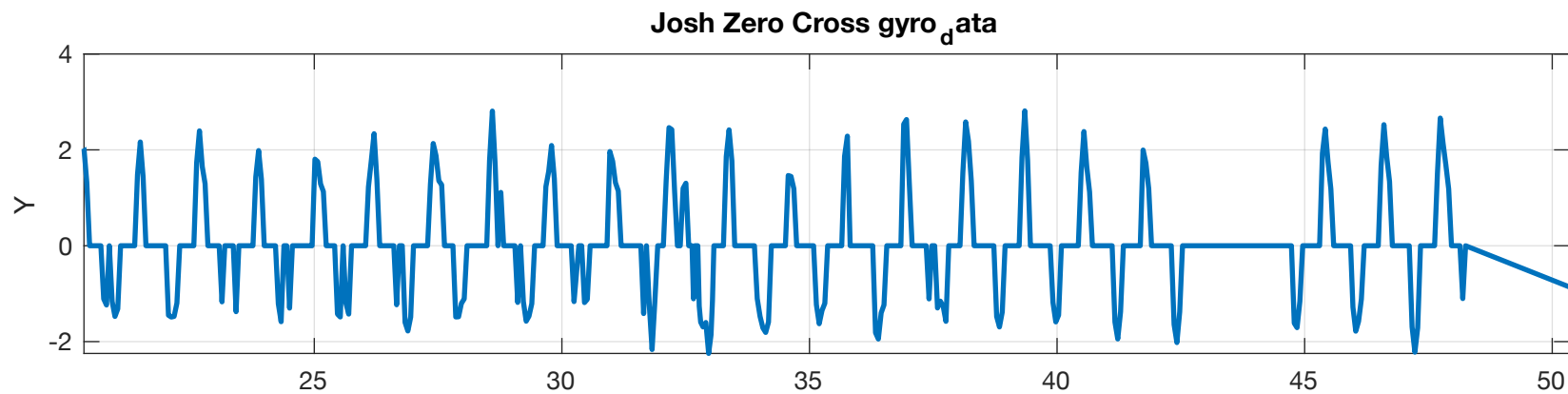
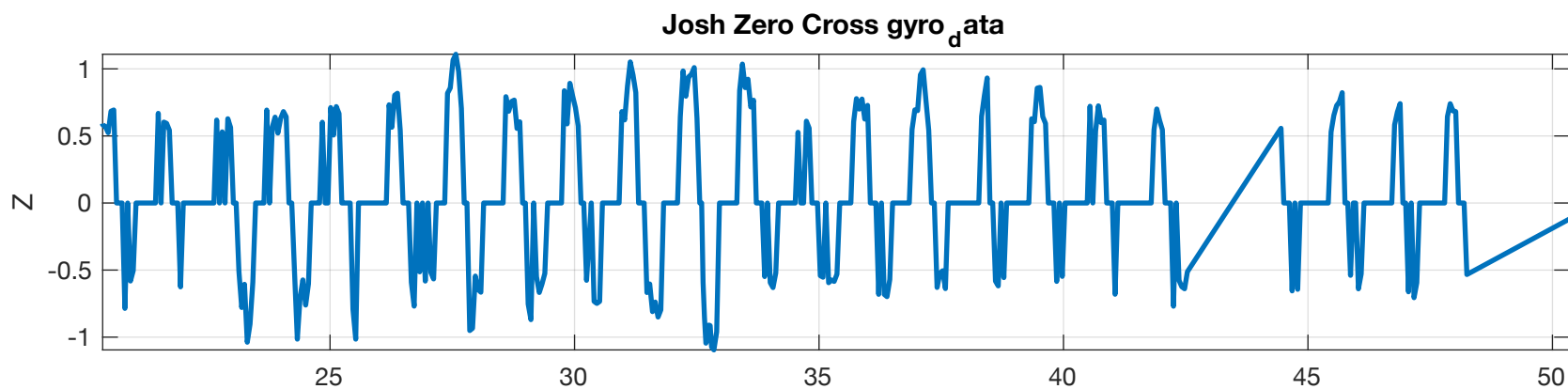


Josh Zero Cross bar_data

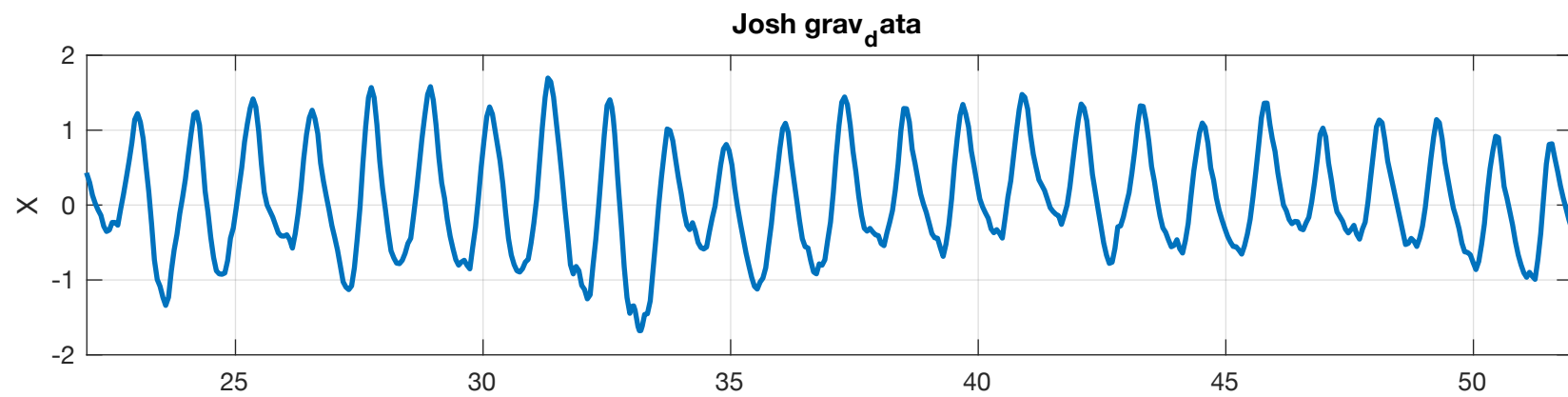
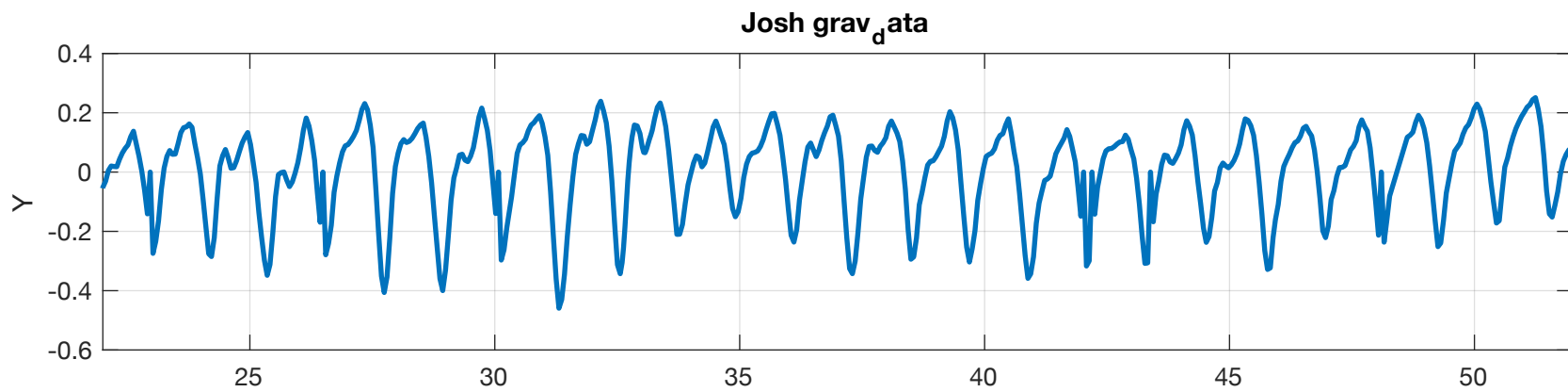
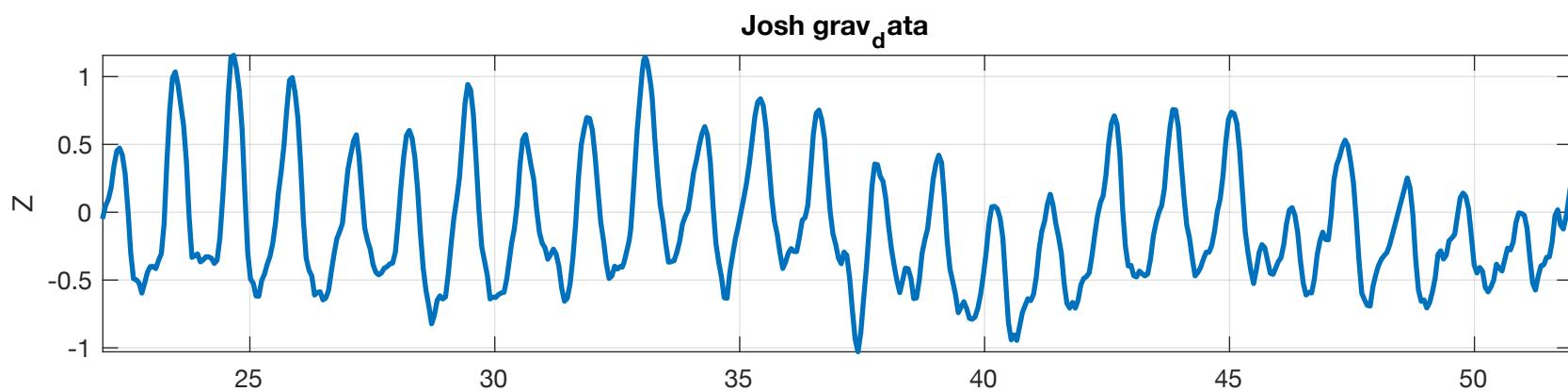


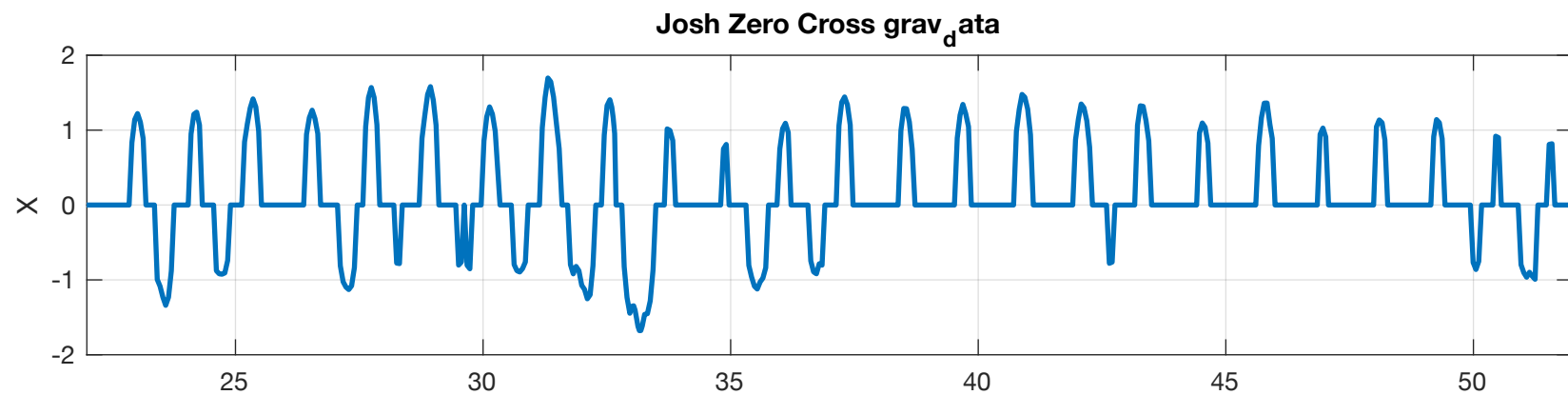
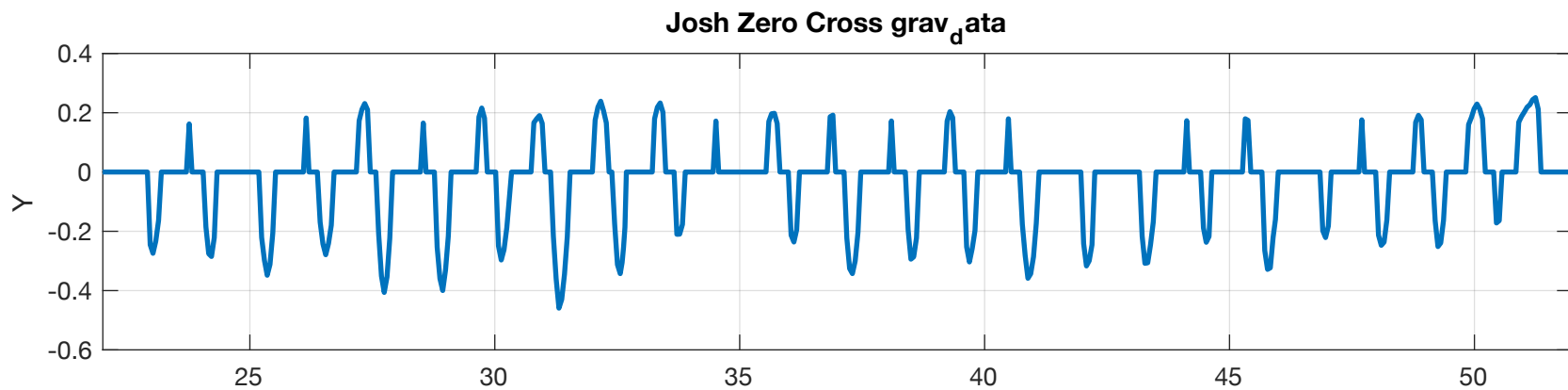
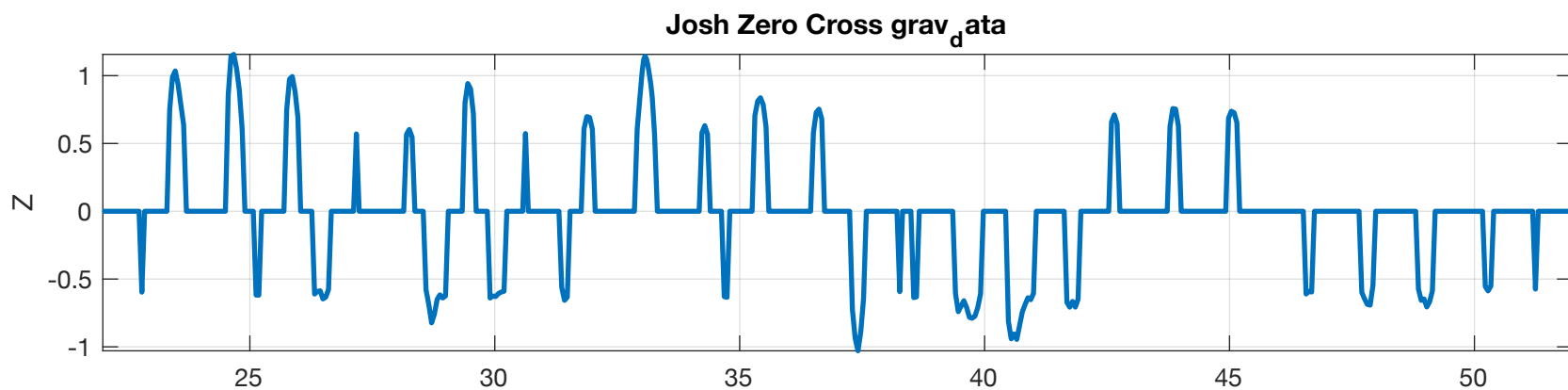
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	24.000	34.000	73.000	54.000	"bar_data"
"Pressure"	2.000	15.000	64.000	54.000	"bar_data"



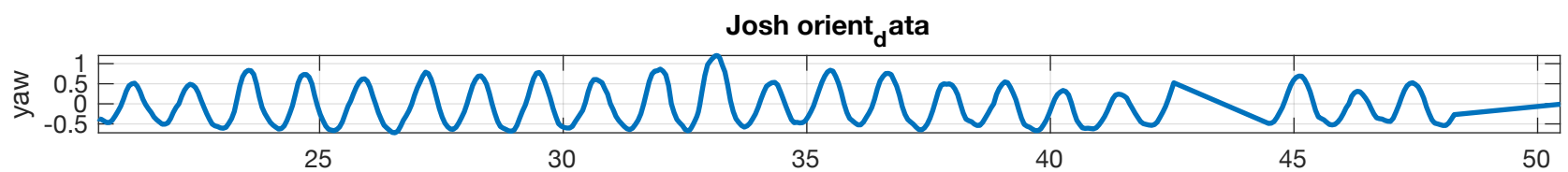
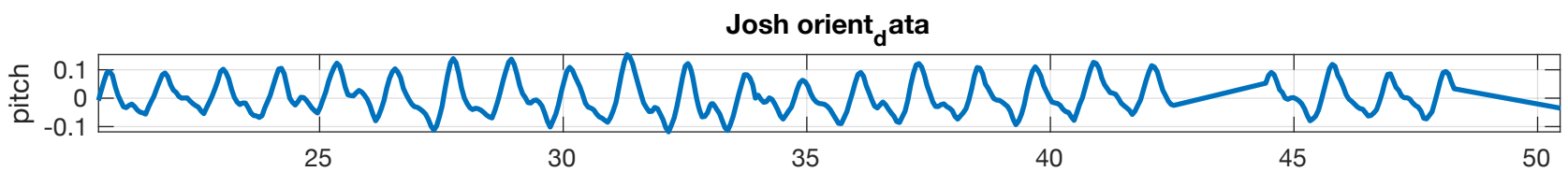
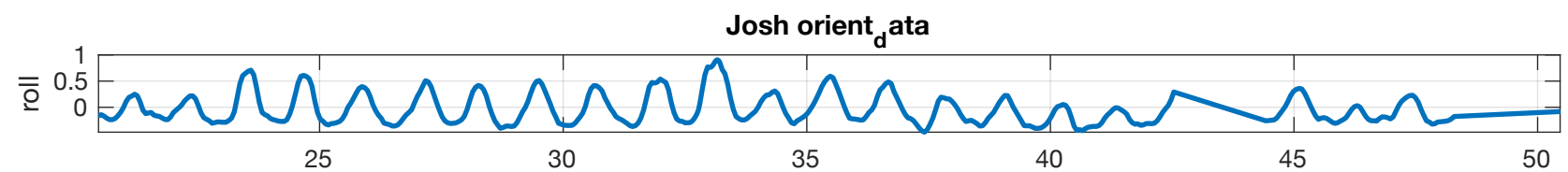
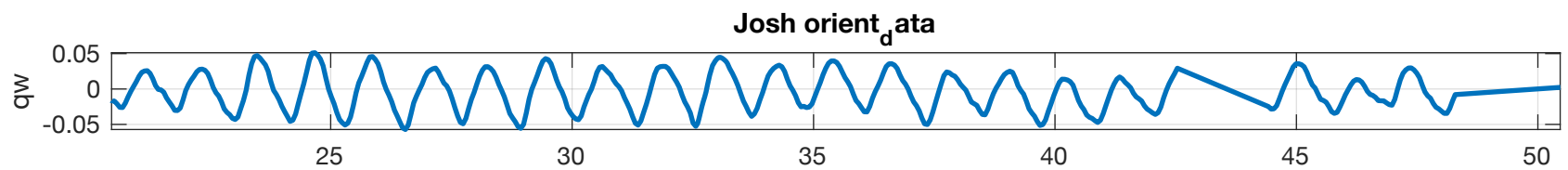
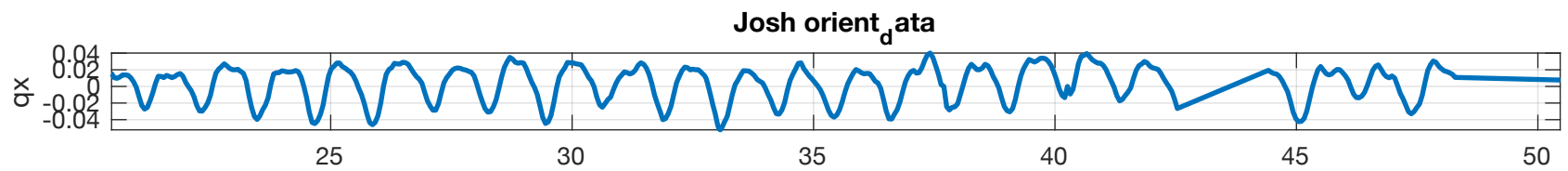
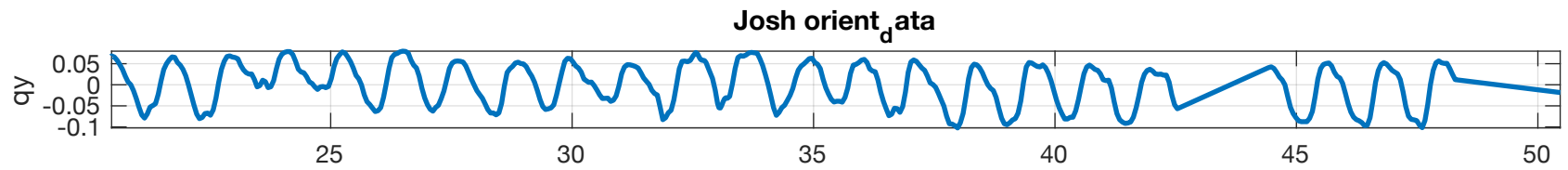
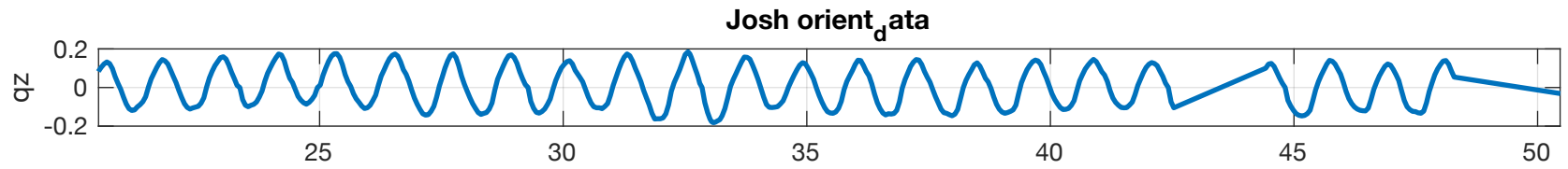


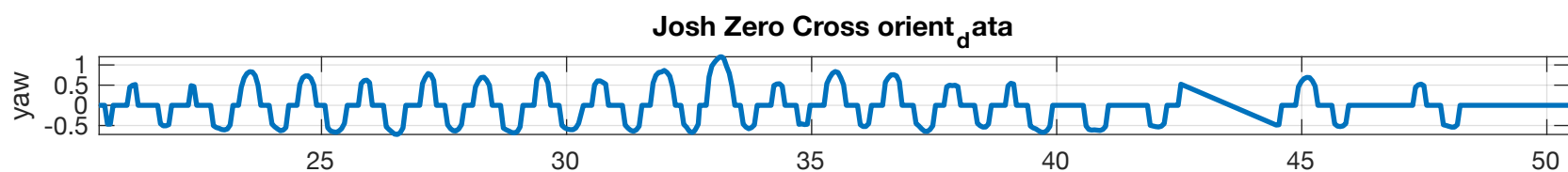
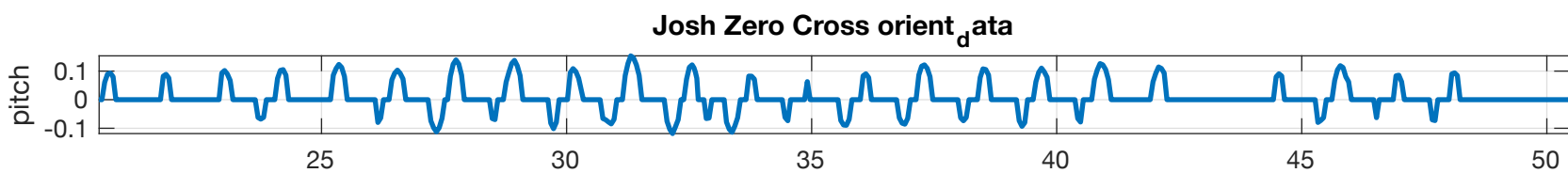
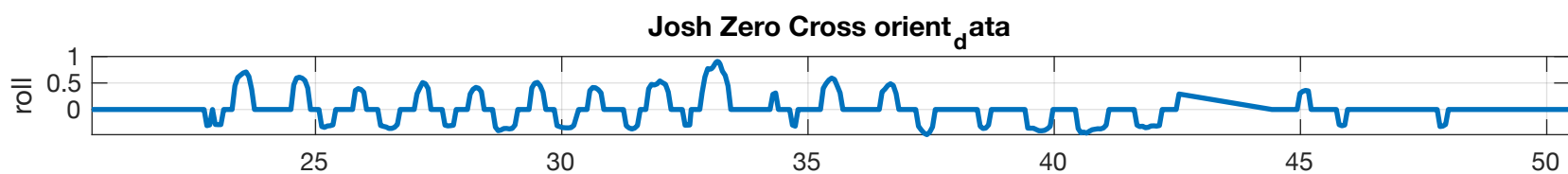
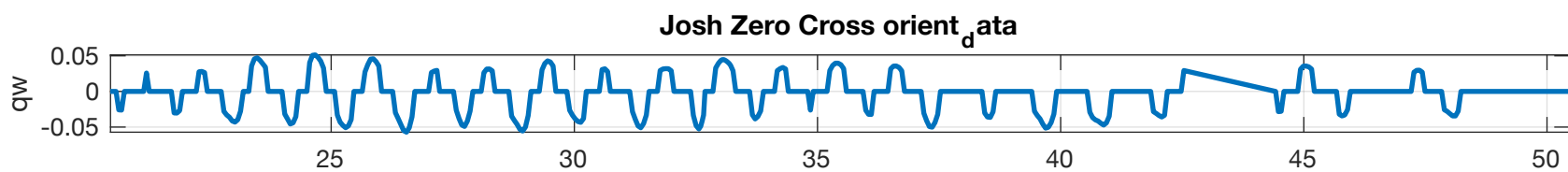
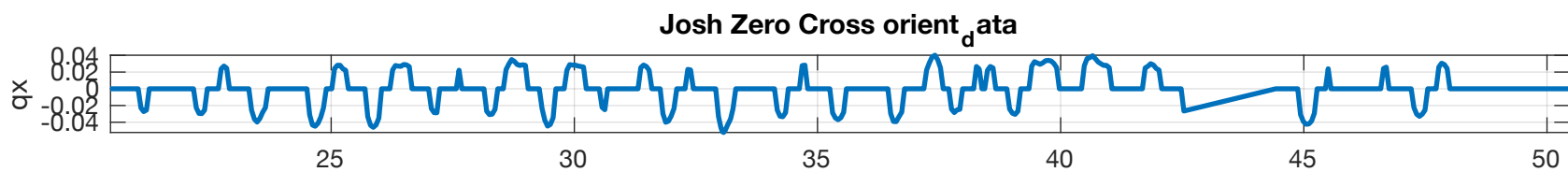
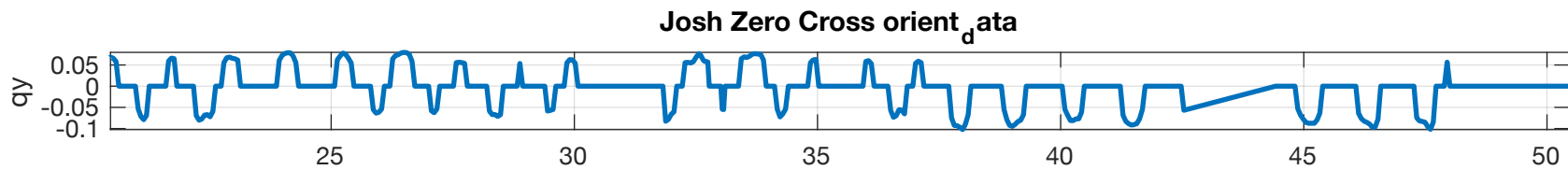
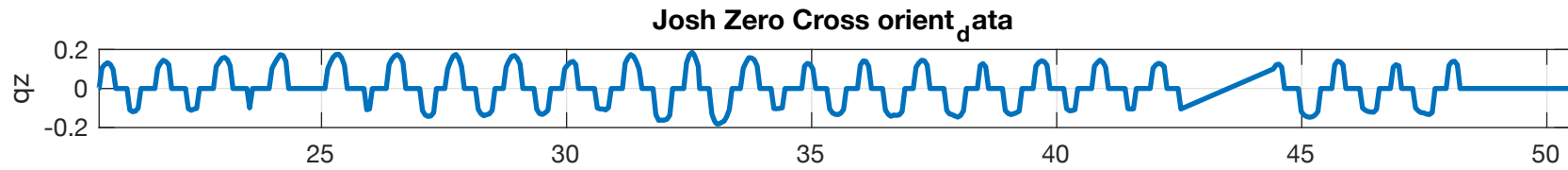
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-113.000	-34.000	50.000	38.500	"gyro_data"
'Y'	-60.000	6.000	52.000	45.500	"gyro_data"
'X'	-83.000	-41.000	52.000	44.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-17.000	36.000	56.000	72.750	"grav_data"
'Y'	-1.000	16.000	63.000	58.500	"grav_data"
'X'	12.000	52.000	69.000	62.500	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	38.000	48.000	83.000	58.000	"orient_data"
'qy'	12.000	30.000	71.000	64.000	"orient_data"
'qx'	9.000	13.000	70.000	66.250	"orient_data"
'qw'	46.000	50.000	84.000	65.250	"orient_data"
'roll'	12.000	46.000	69.000	72.750	"orient_data"
'pitch'	16.000	43.000	72.000	61.500	"orient_data"
'yaw'	47.000	52.000	83.000	59.750	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Y"	'double_findpeaks'	0.000
'bar_data'	"Pressure"	'findpeaks'	2.000
'gyro_data'	"Y"	'findpeaks_above_zero'	6.000
'grav_data'	"Y"	'findpeaks'	1.000
'orient_data'	"qx"	'findpeaks'	9.000