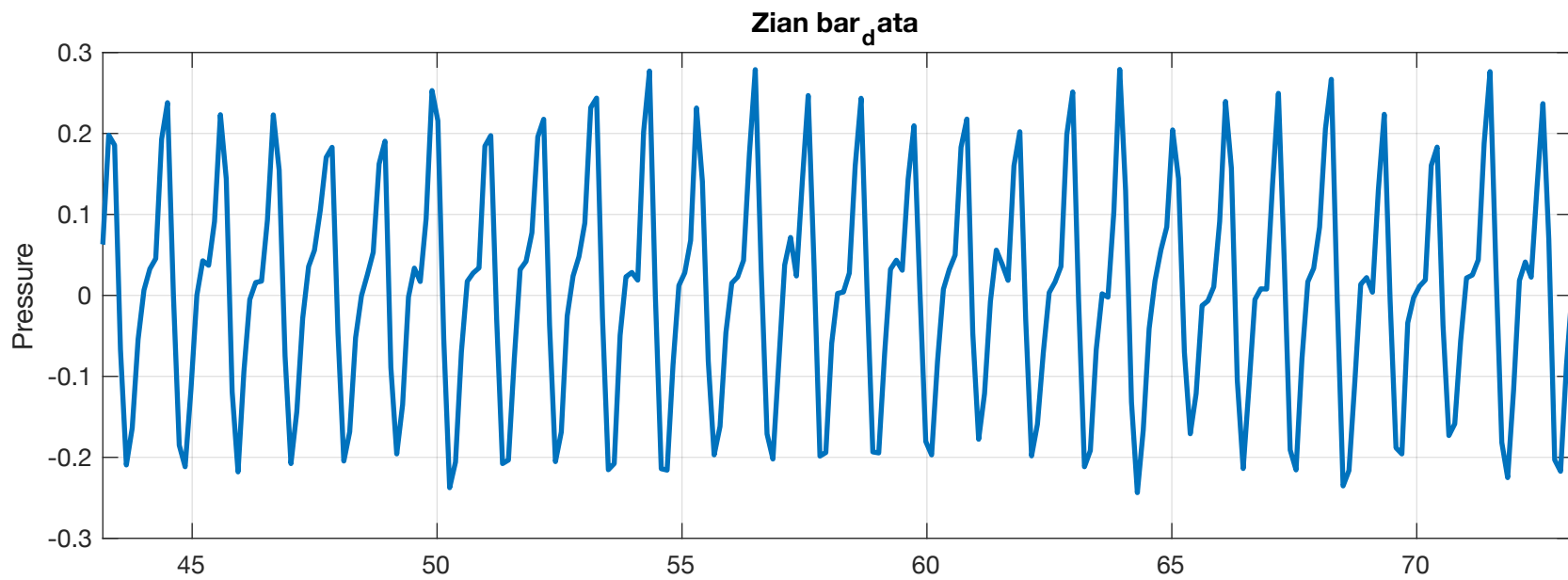
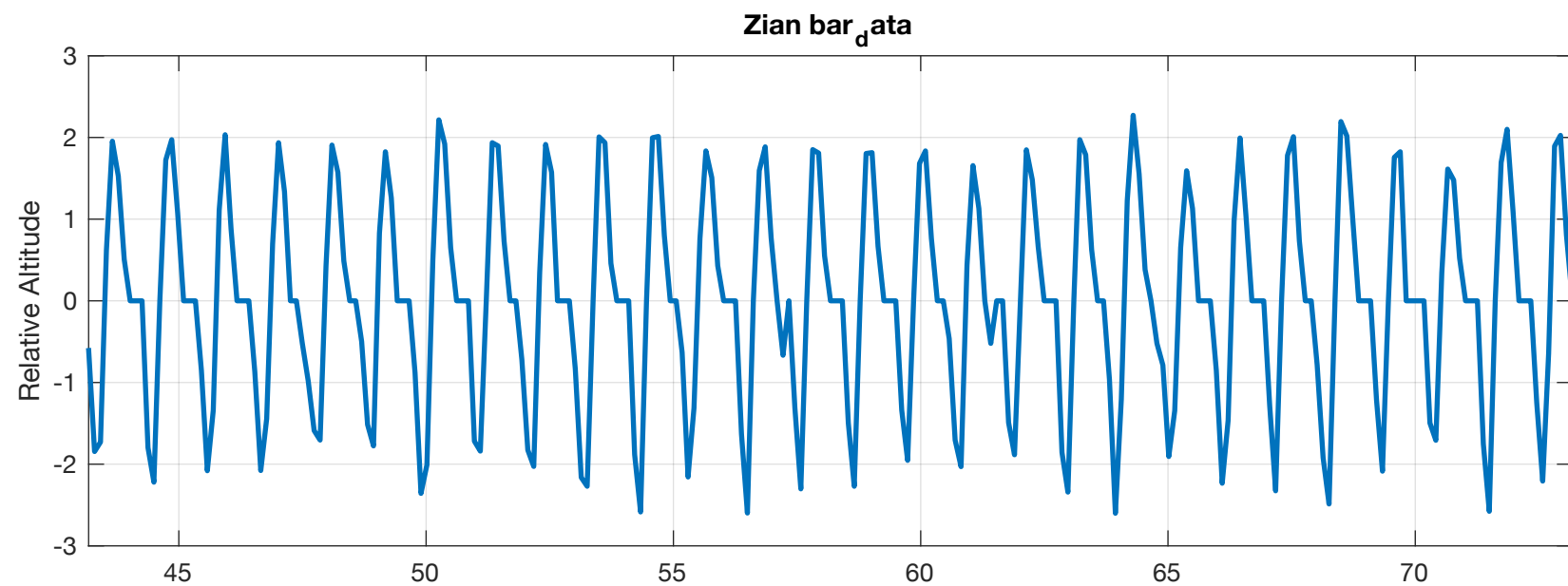
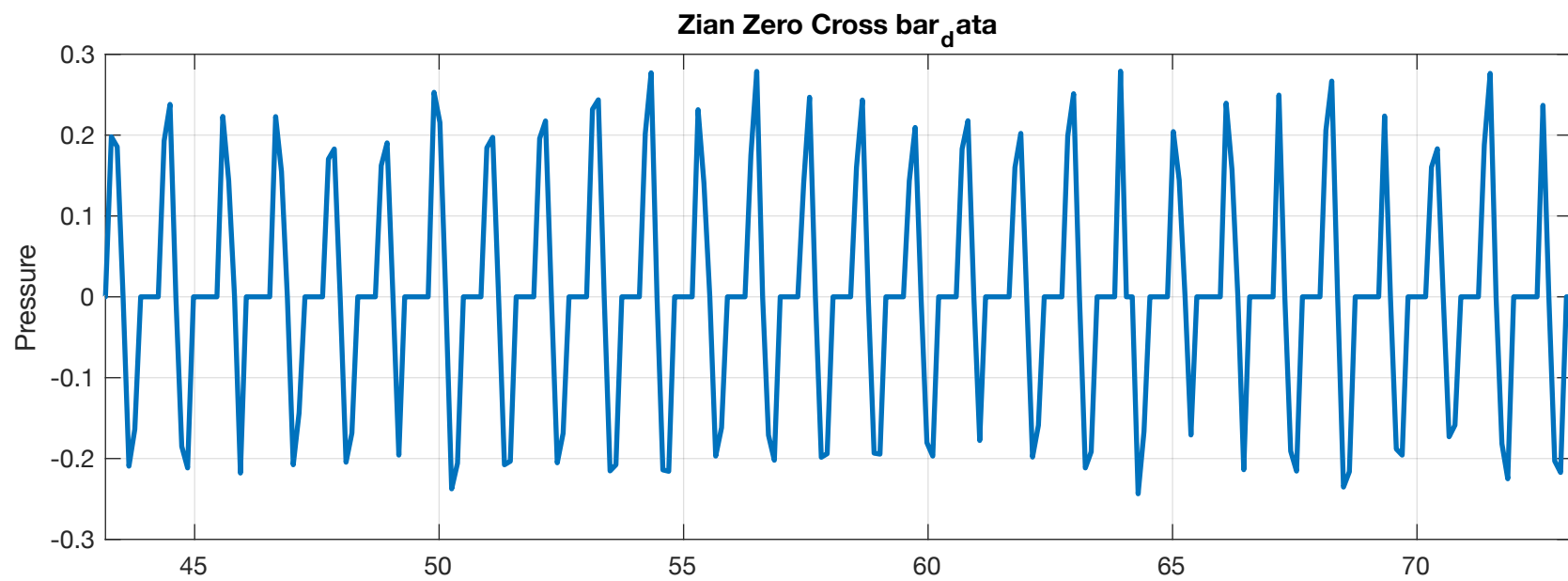
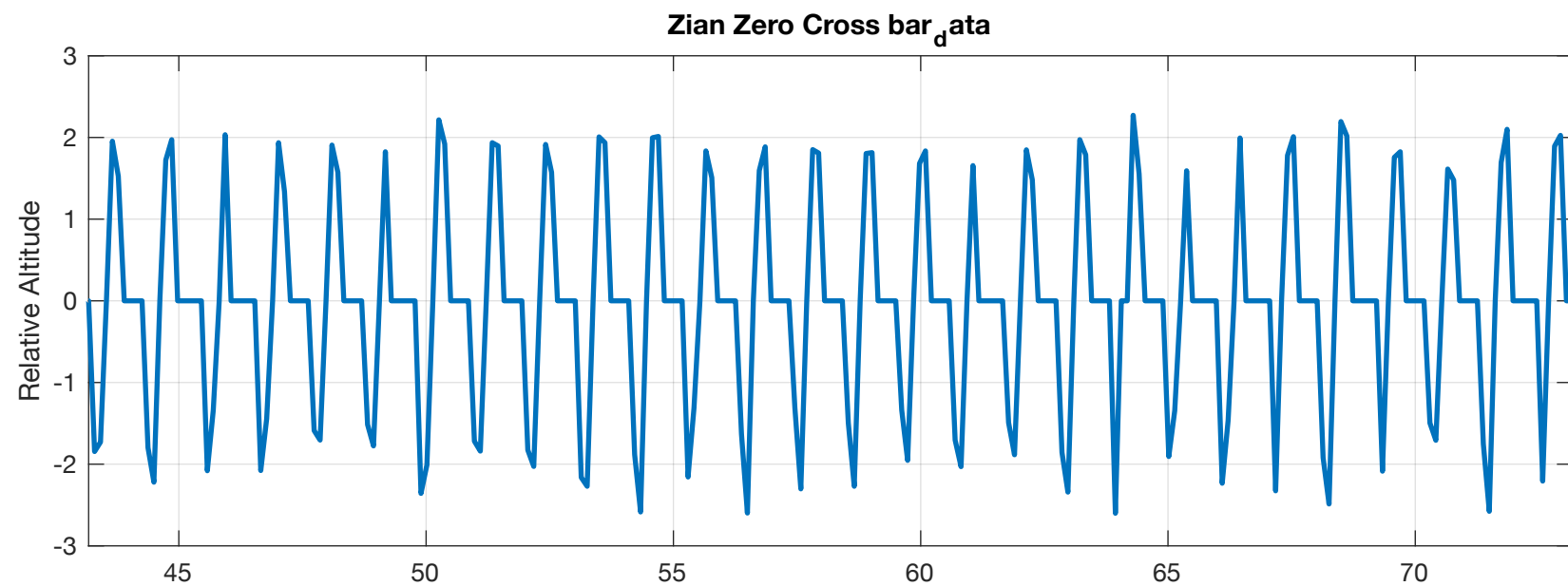
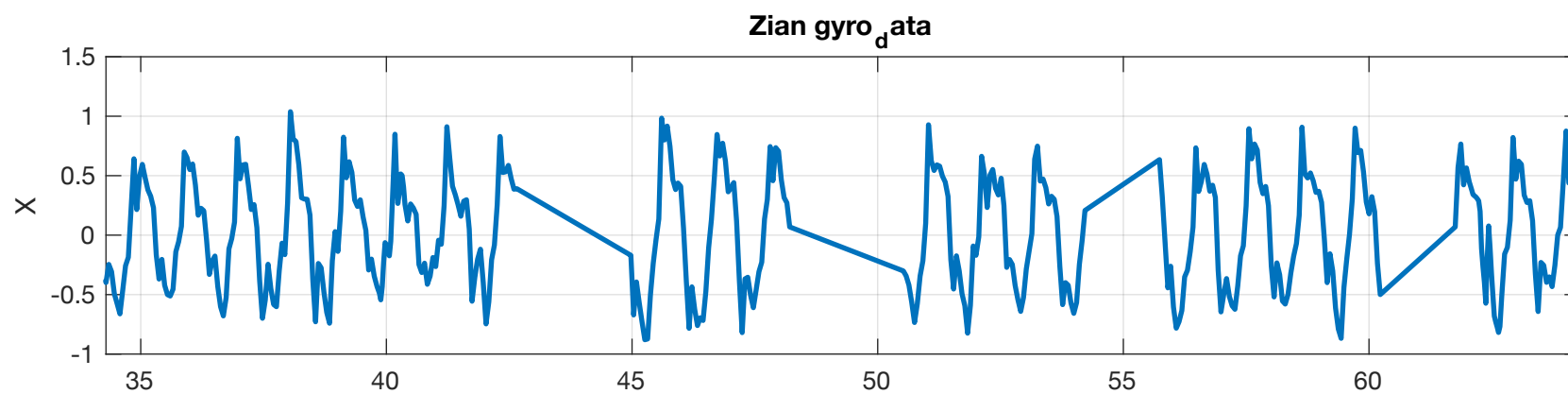


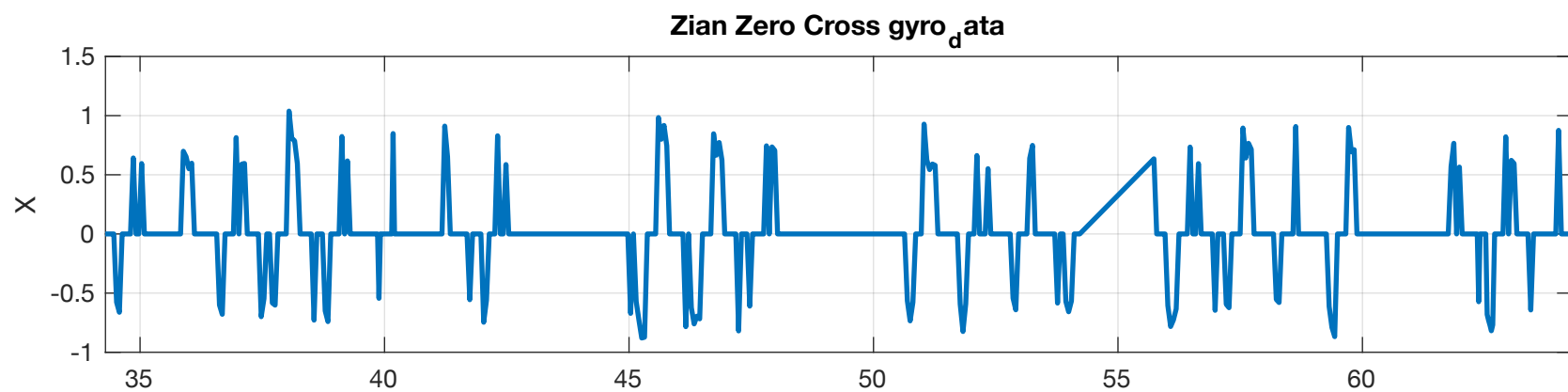
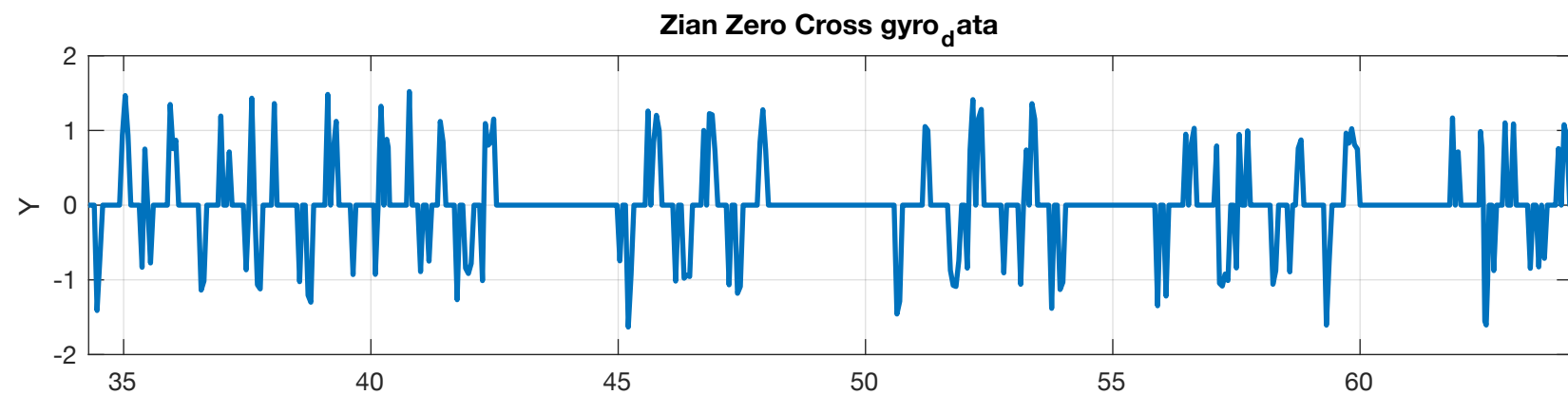
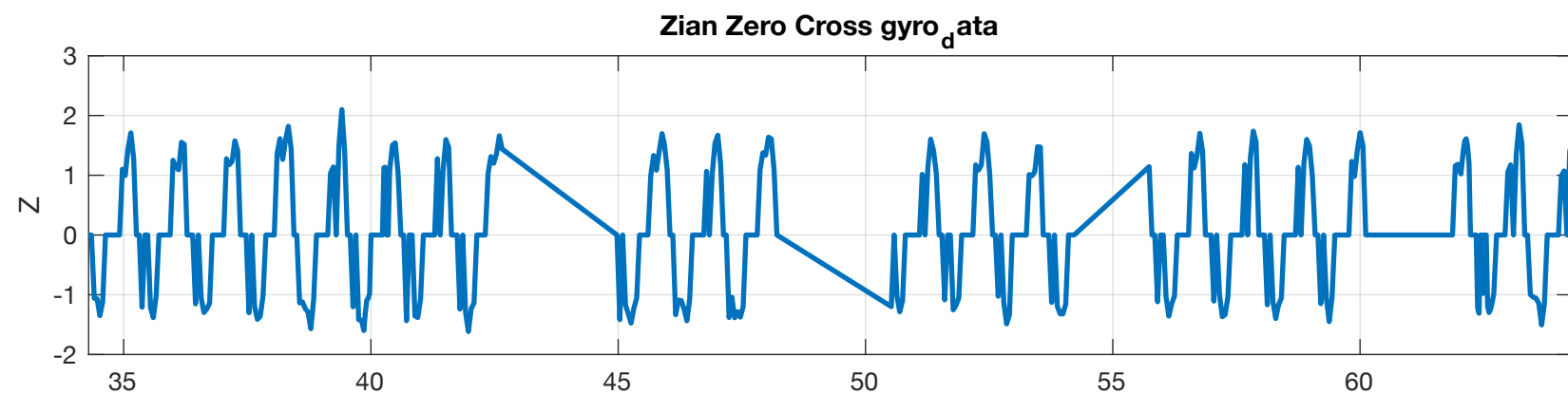
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-458.000	-151.000	28.000	99.500	"accel_data"
'Y'	-218.000	-144.000	97.000	1.500	"accel_data"
'X'	-426.000	-347.000	109.000	9.000	"accel_data"



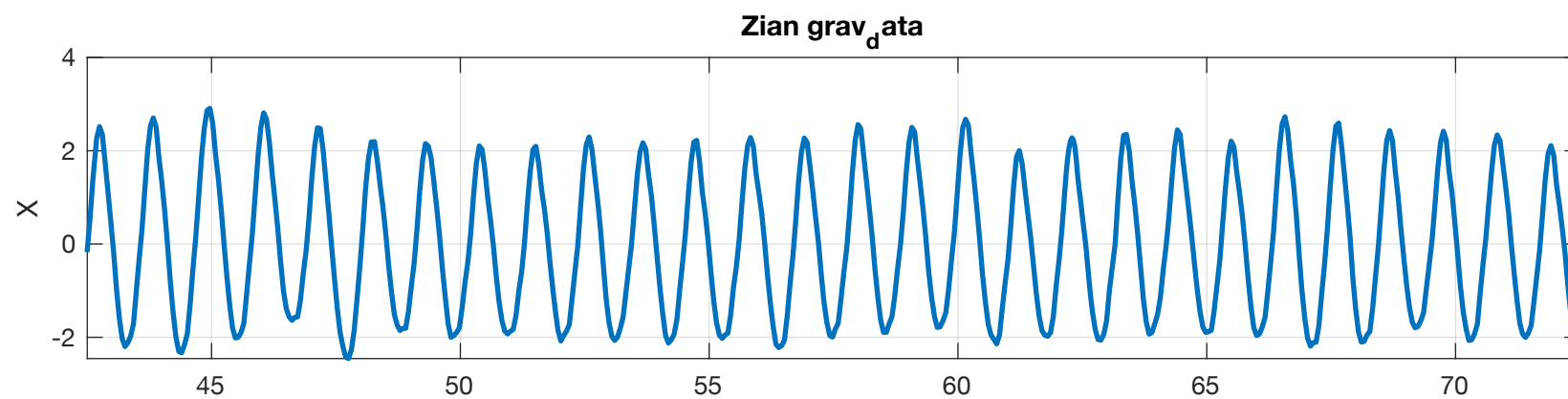
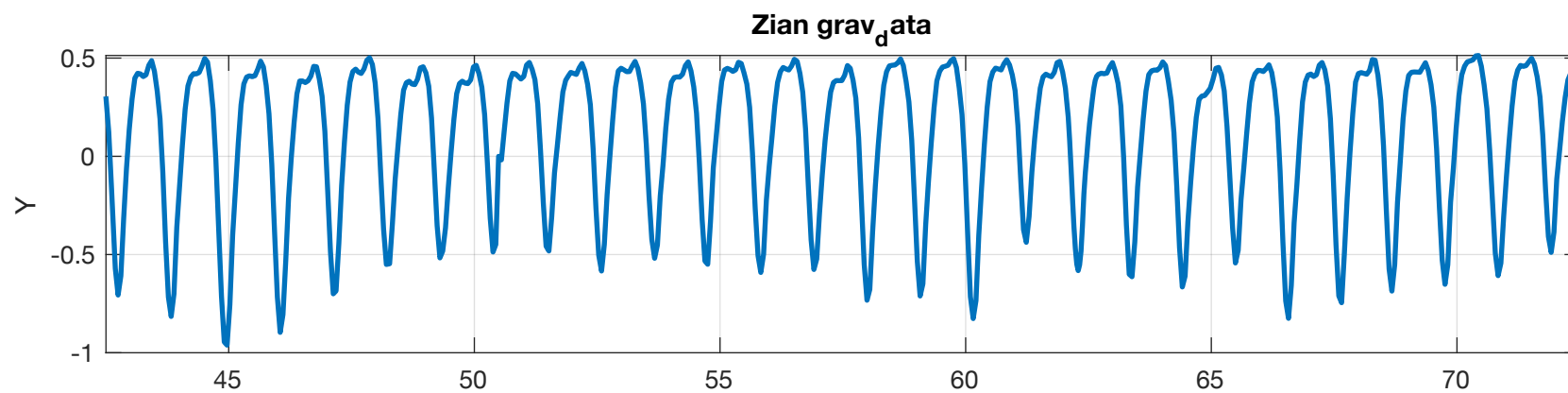
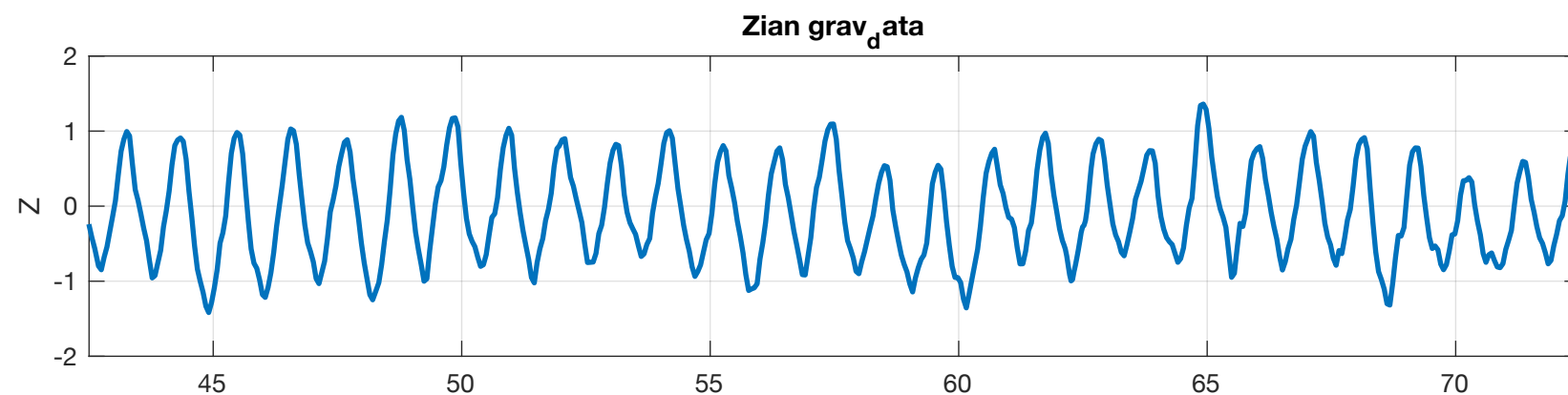


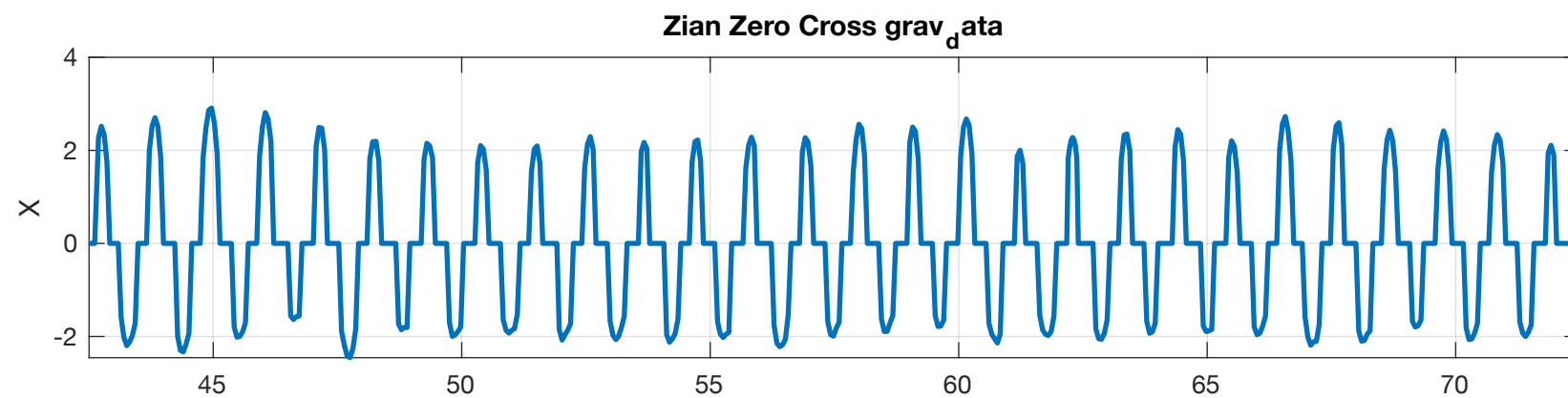
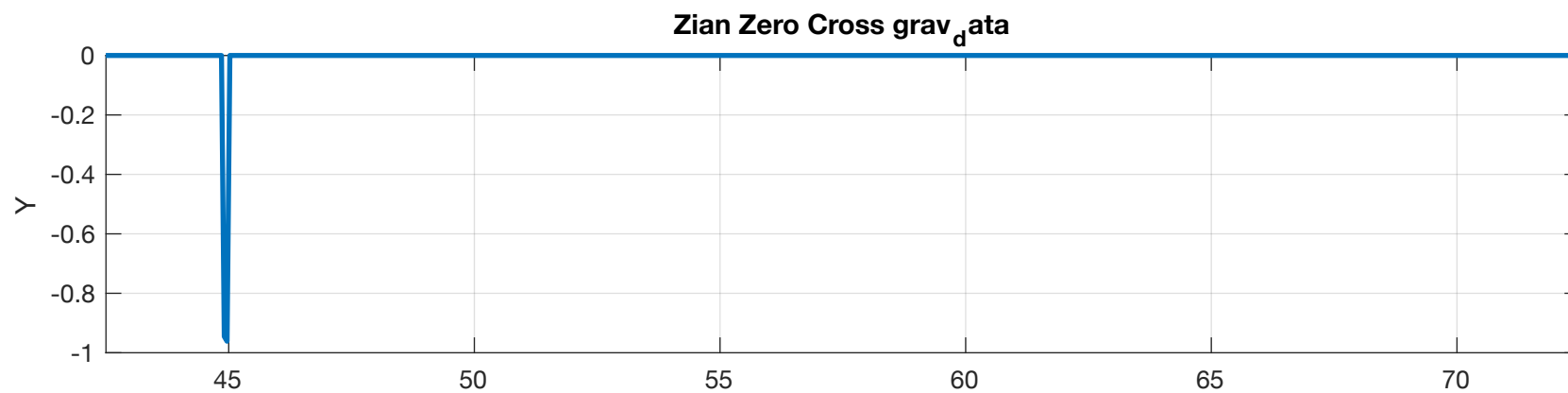
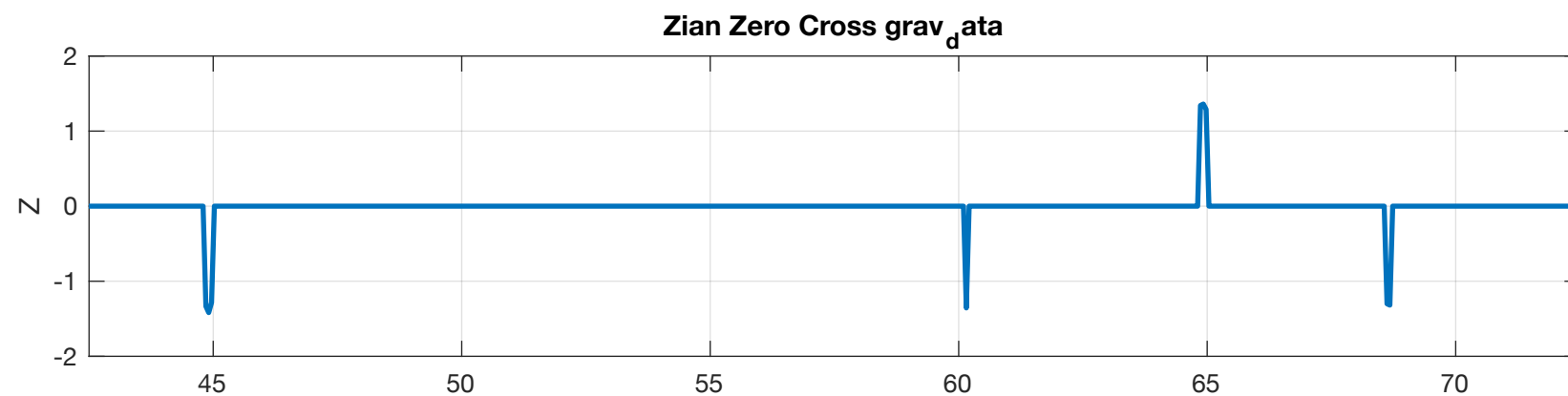
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	138.000	148.000	247.000	150.000	"bar_data"
"Pressure"	72.000	78.000	212.000	150.000	"bar_data"



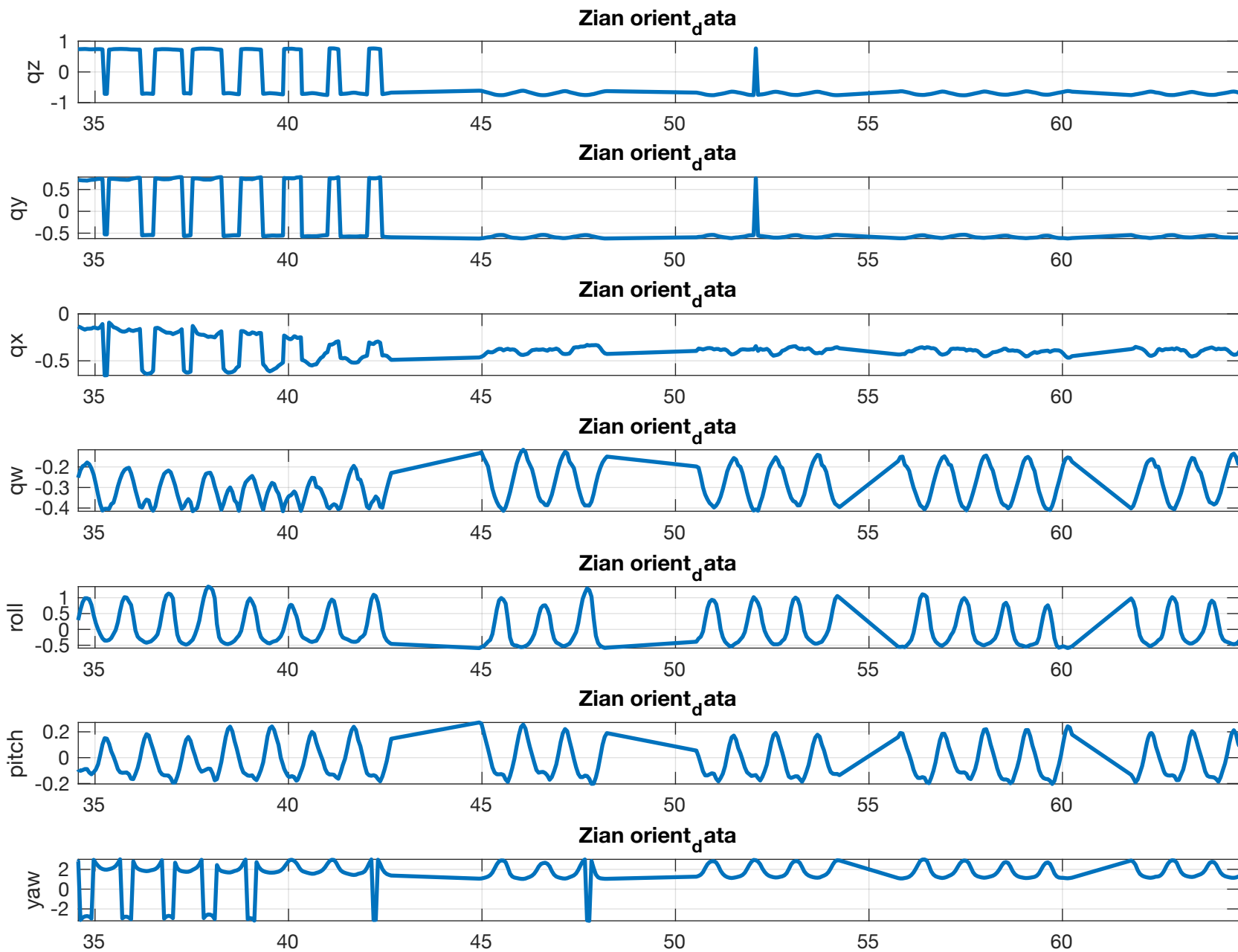


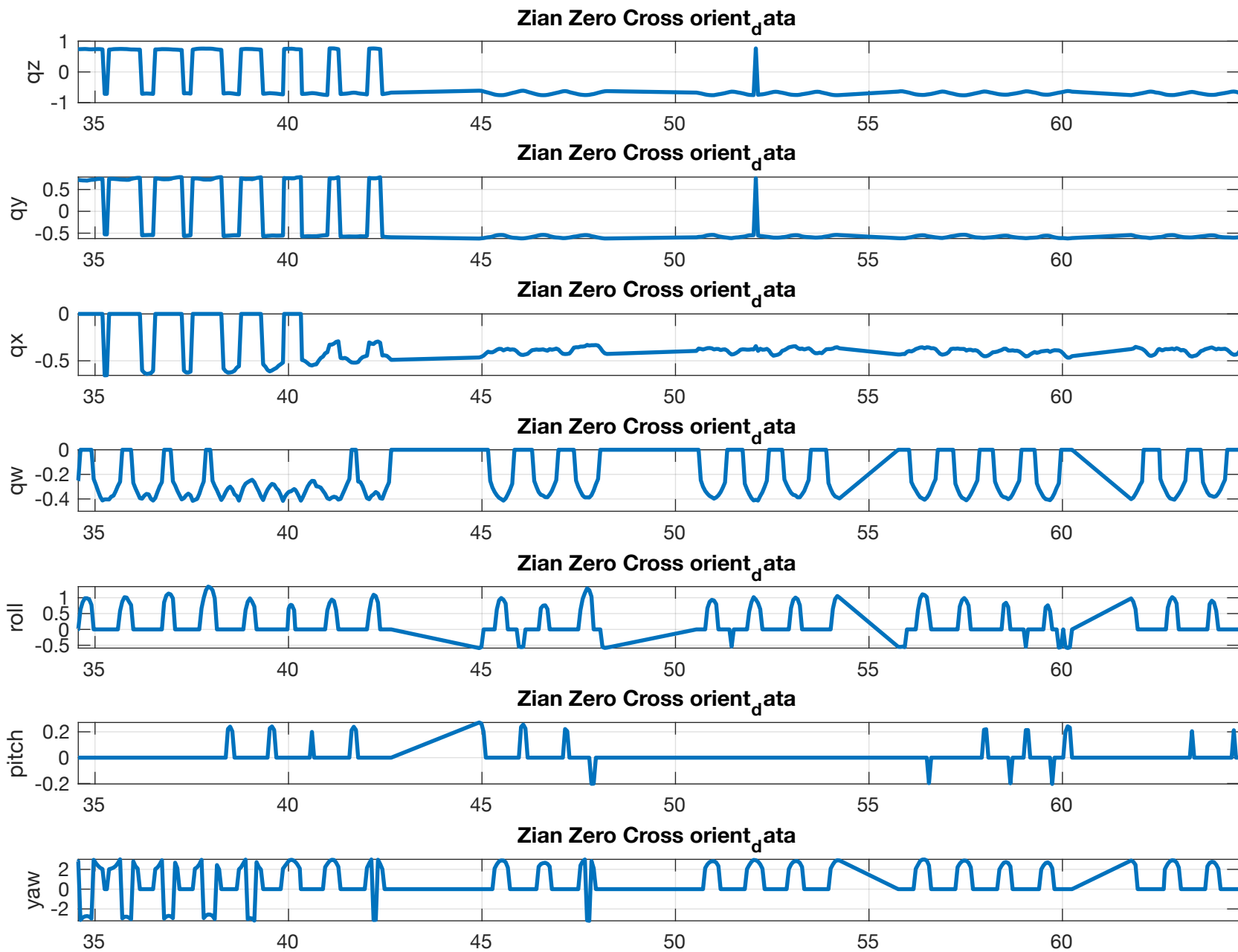
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-77.000	48.000	184.000	121.000	"gyro_data"
'Y'	-301.000	-156.000	129.000	118.000	"gyro_data"
'X'	-155.000	-24.000	175.000	147.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	103.000	138.000	242.000	285.000	"grav_data"
'Y'	26.000	31.000	182.000	298.000	"grav_data"
'X'	138.000	145.000	250.000	155.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	125.000	184.000	263.000	281.250	"orient_data"
'qy'	18.000	114.000	240.000	286.750	"orient_data"
'qx'	-15.000	152.000	248.000	283.000	"orient_data"
'qw'	136.000	203.000	273.000	265.000	"orient_data"
'roll'	155.000	181.000	258.000	224.250	"orient_data"
'pitch'	94.000	177.000	218.000	257.500	"orient_data"
'yaw'	127.000	192.000	259.000	237.750	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Y"	'zero_cross'	1.500
'bar_data'	"Pressure"	'findpeaks'	72.000
'gyro_data'	"X"	'findpeaks_above_zero'	24.000
'grav_data'	"Y"	'findpeaks'	26.000
'orient_data'	"qx"	'findpeaks'	15.000