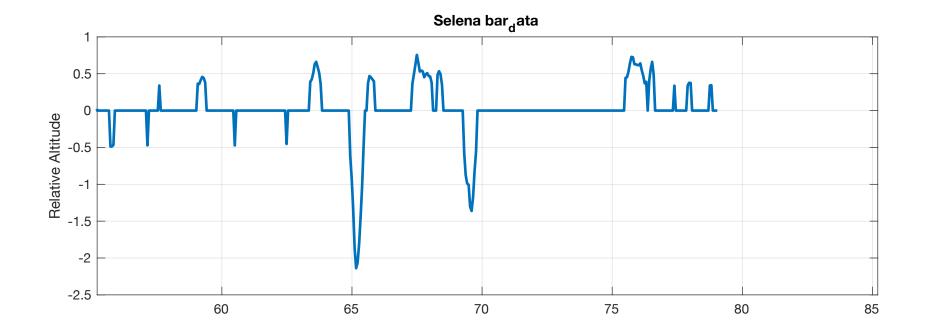
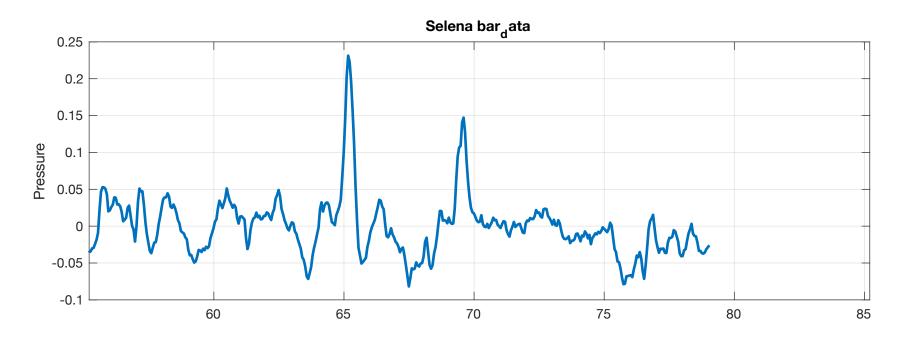
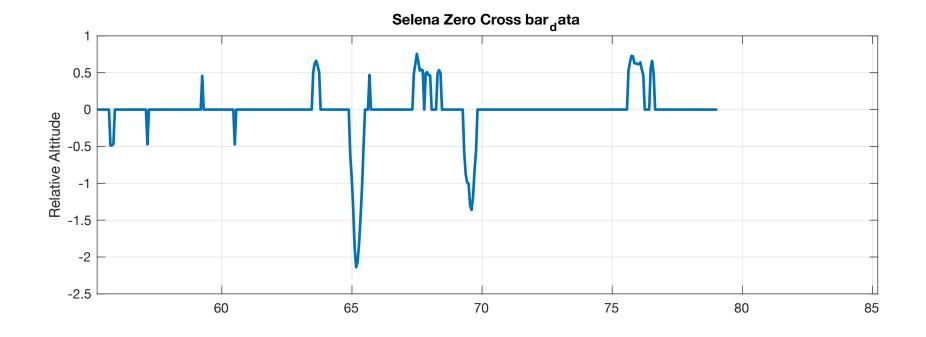
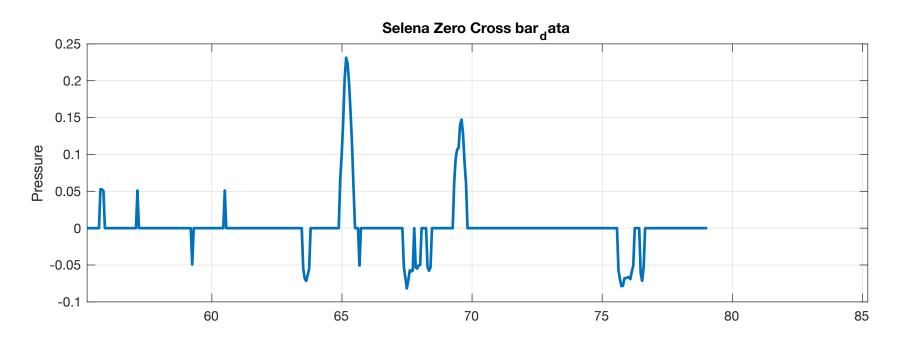


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-178.000	-146.000	-51.000	-54.000	"accel_data"
'Y'	-211.000	-172.000	-65.000	-40.250	"accel_data"
'X'	-181.000	-132.000	-47.000	-41.750	"accel_data"

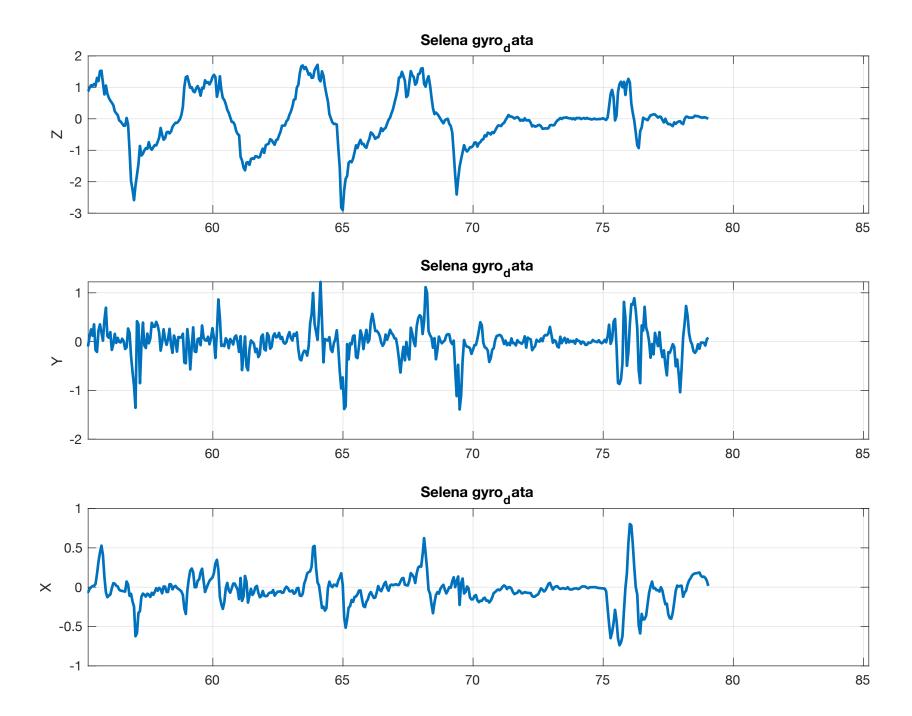


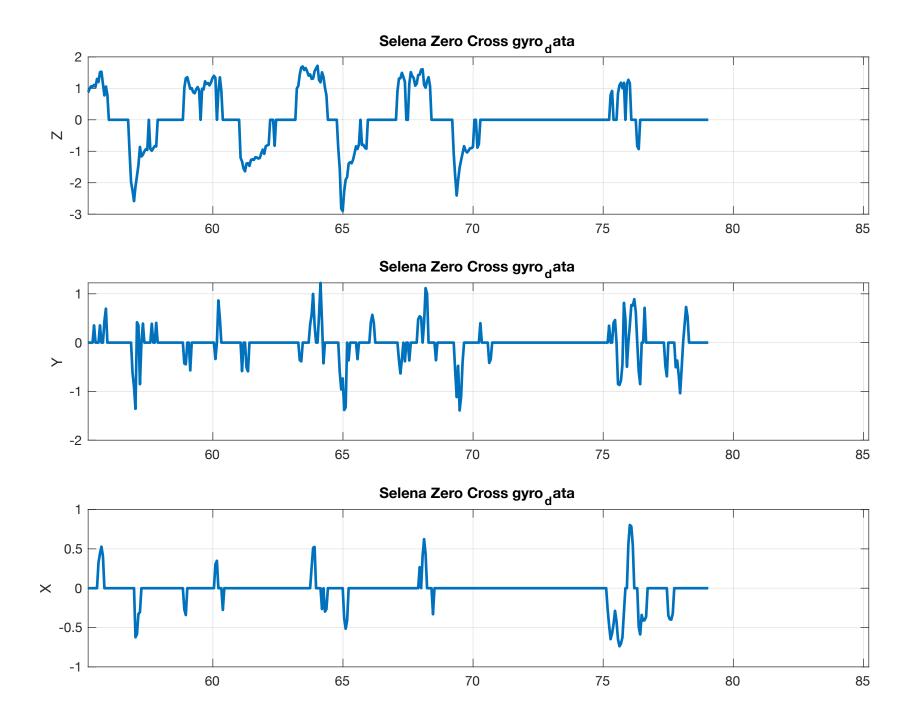




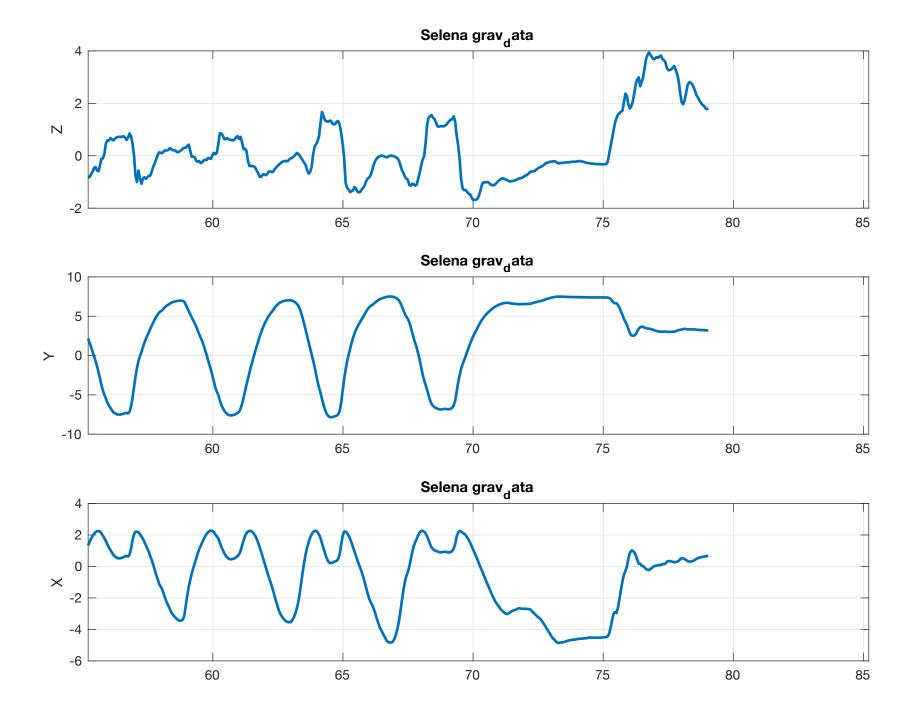


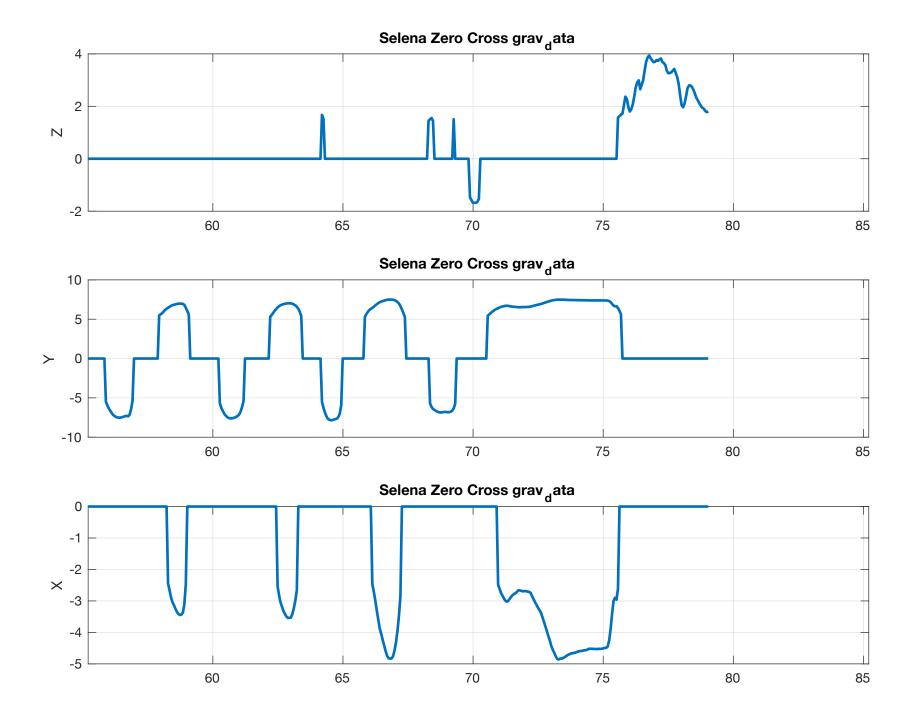
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-22.000	-19.000	-7.000	-8.000	"bar_data"
"Pressure"	-89.000	-58.000	-20.000	-8.000	"bar_data"



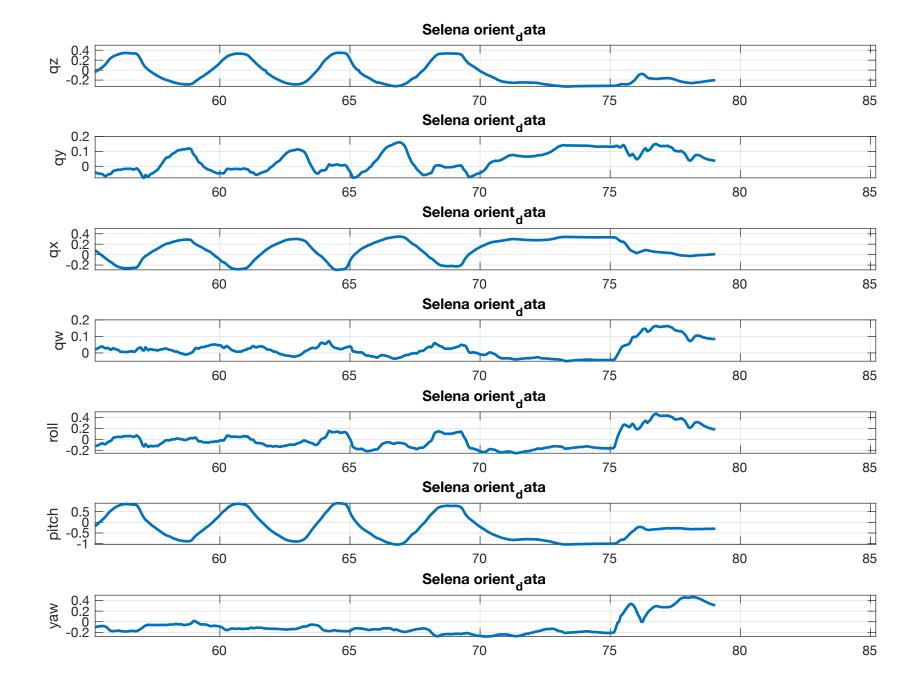


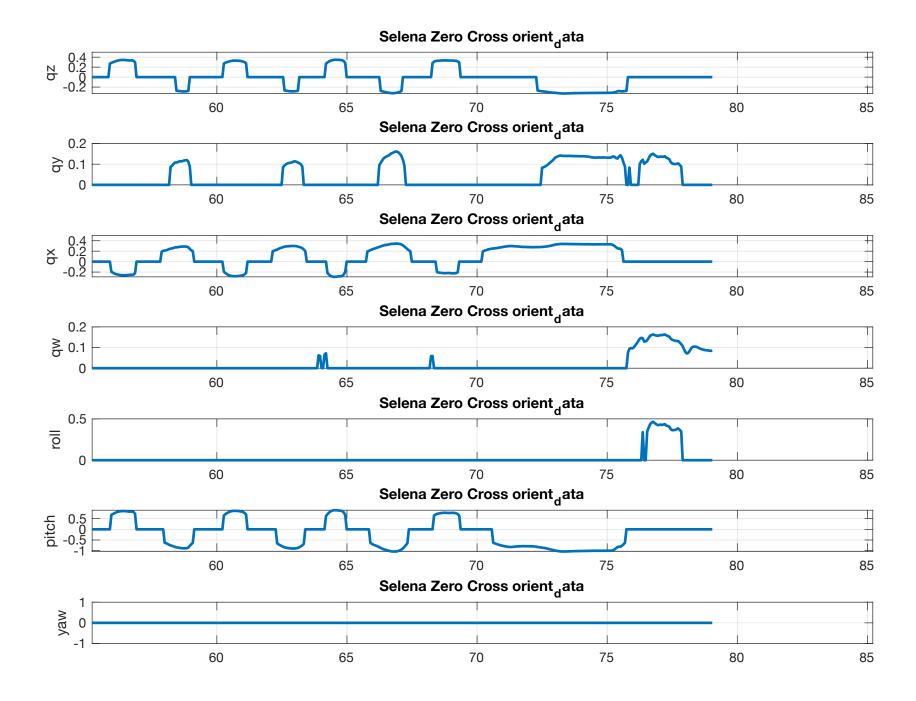
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
<u>'Z'</u>	-114.000	-65.000	-26.000	-11.500	"gyro_data"
'Y'	-145.000	-119.000	-42.000	-27.500	"gyro_data"
'X'	-117.000	-61.000	-28.000	-11.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-80.000	-40.000	-12.000	-2.250	"grav_data"
'Y'	-27.000	-16.000	-4.000	-5.000	"grav_data"
'X'	-33.000	-26.000	-8.000	-2.500	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-28.000	-15.000	-5.000	-5.500	"orient_data"
'qy'	-65.000	-34.000	-11.000	-4.000	"orient_data"
'qx'	-27.000	-12.000	-4.000	-5.500	"orient_data"
'qw'	-79.000	-48.000	-14.000	-1.750	"orient_data"
'roll'	-83.000	-31.000	-10.000	-1.000	"orient_data"
'pitch'	-27.000	-16.000	-3.000	-5.000	"orient_data"
'yaw'	-67.000	-6.000	-2.000	0.000	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Υ"	'zero_cross'	40.250
'bar_data'	"Relative Altitude"	'double_findpeaks'	7.000
'gyro_data'	"X"	'zero_cross'	11.000
'grav_data'	"Z"	'zero_cross'	2.250
'orient_data'	"yaw"	'zero_cross'	0.000