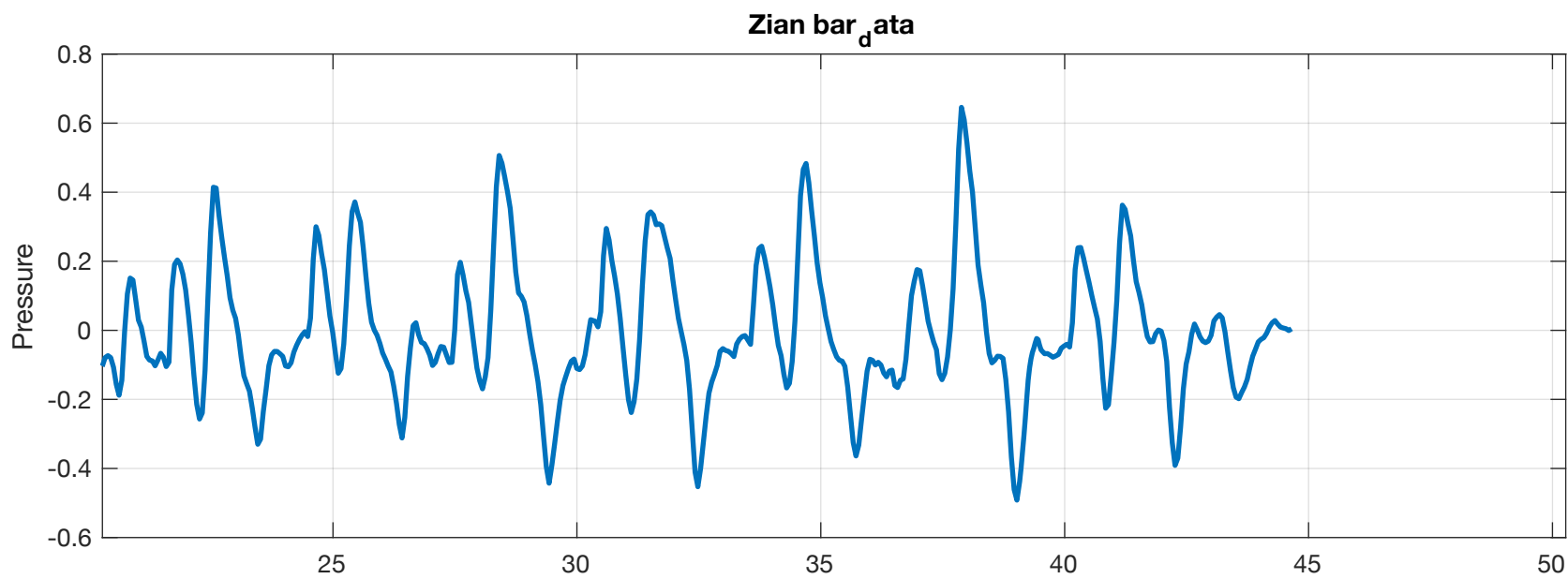
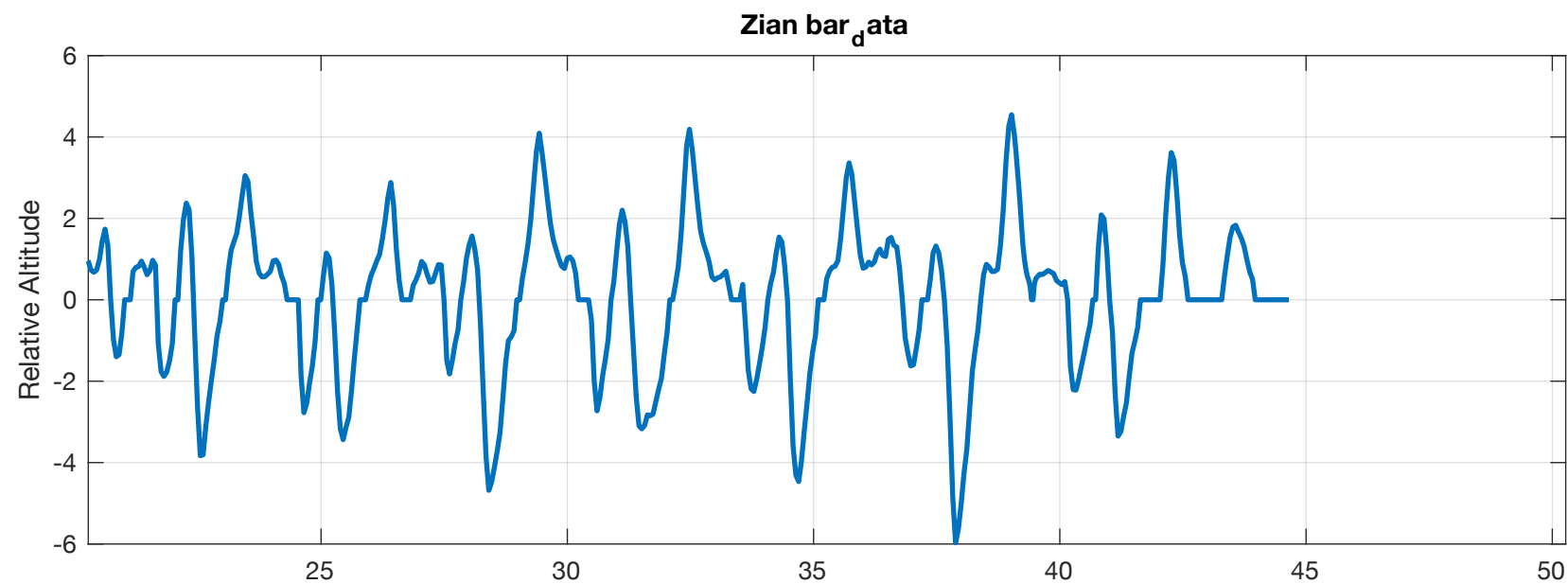
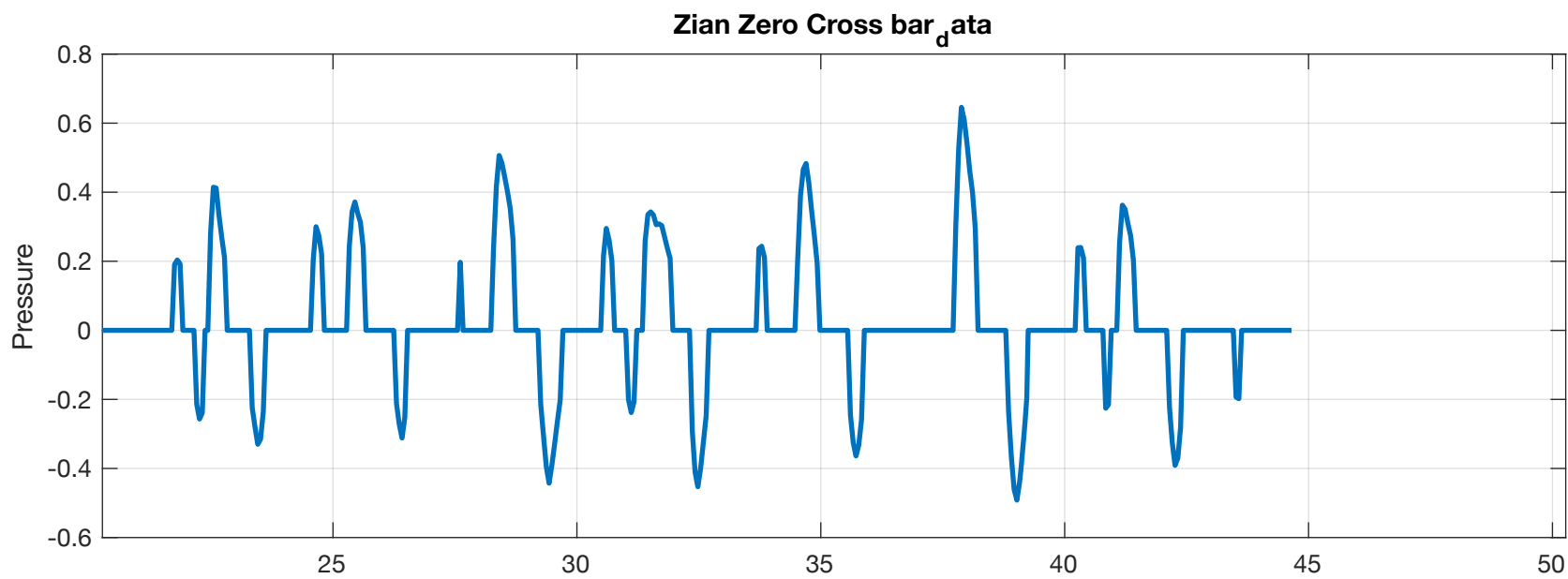
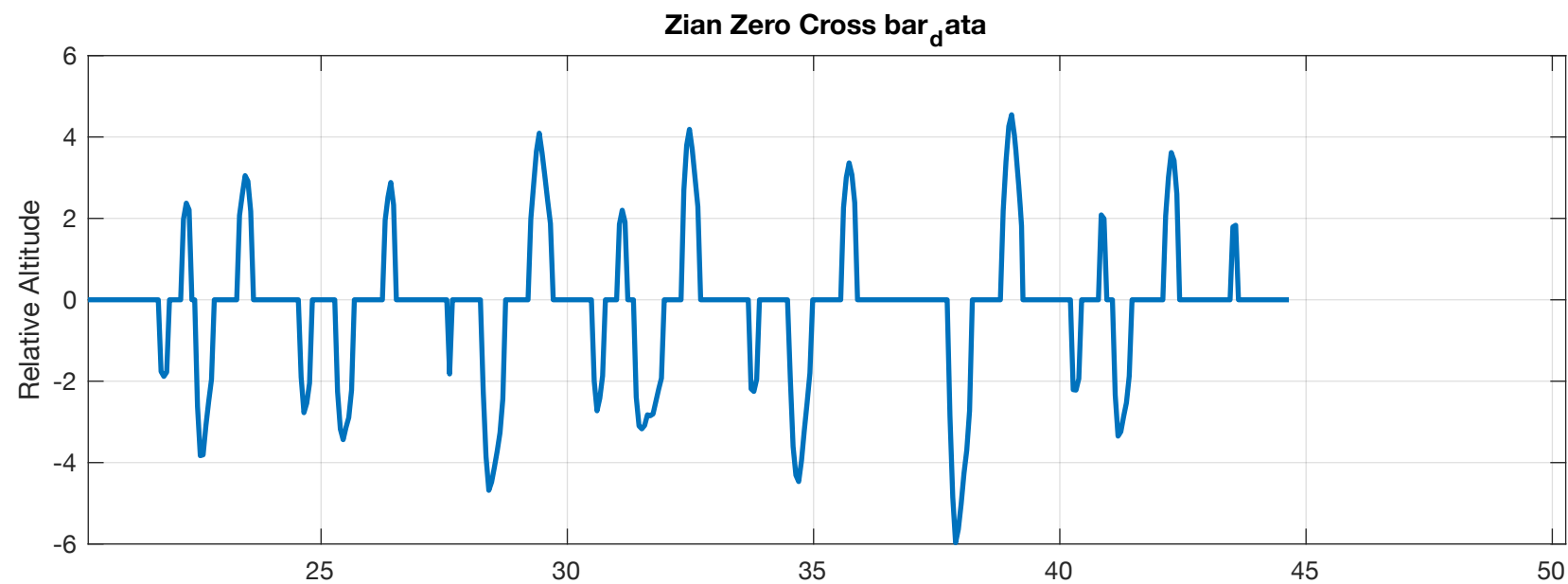
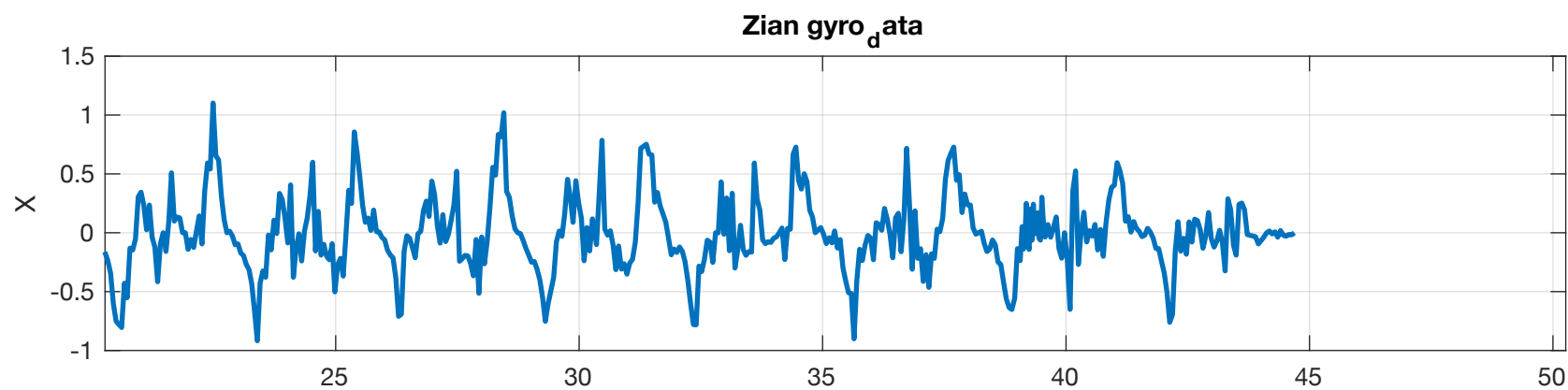
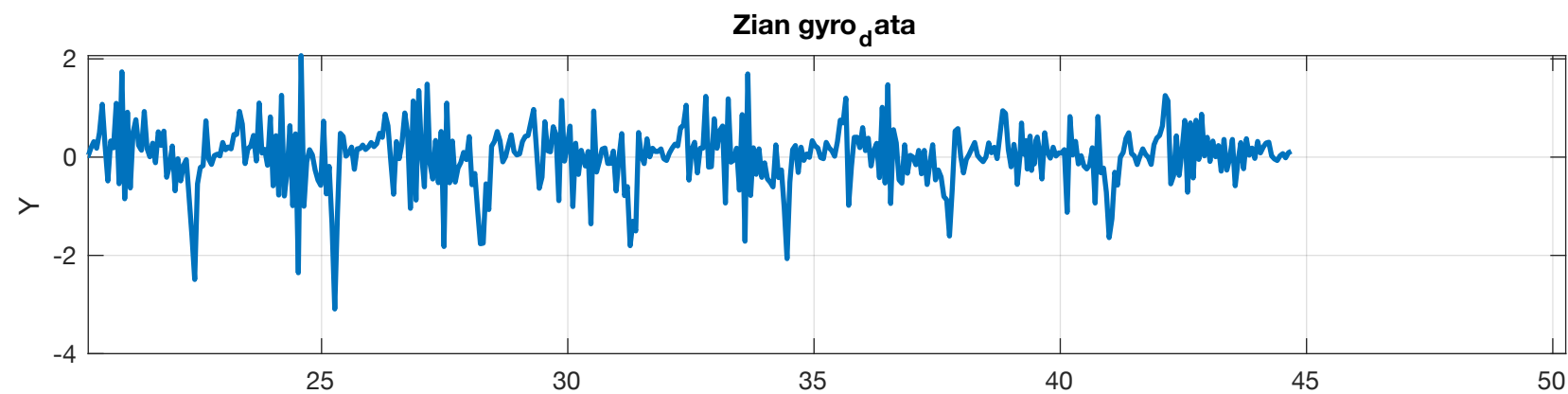
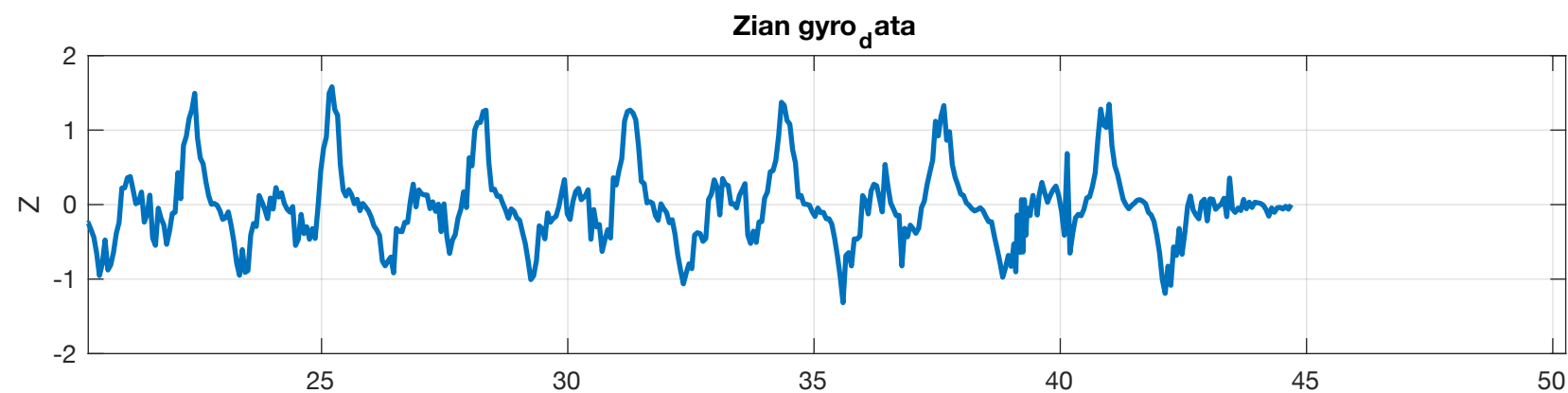


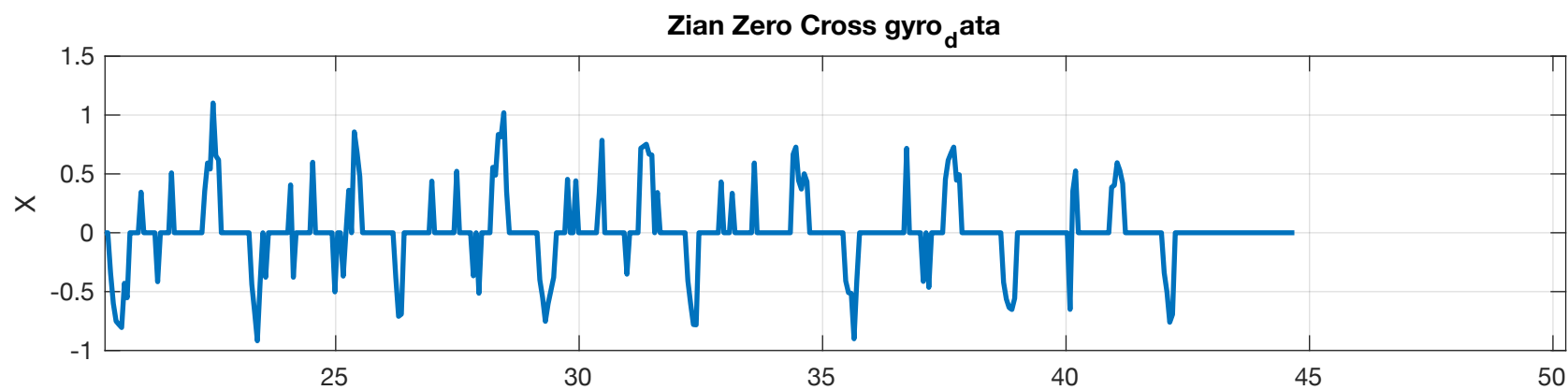
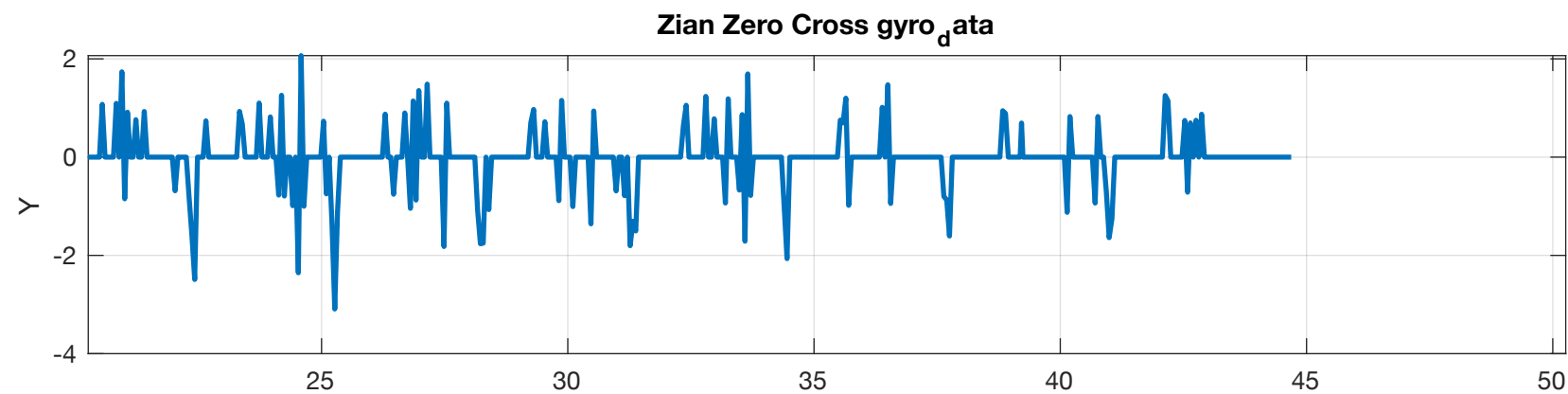
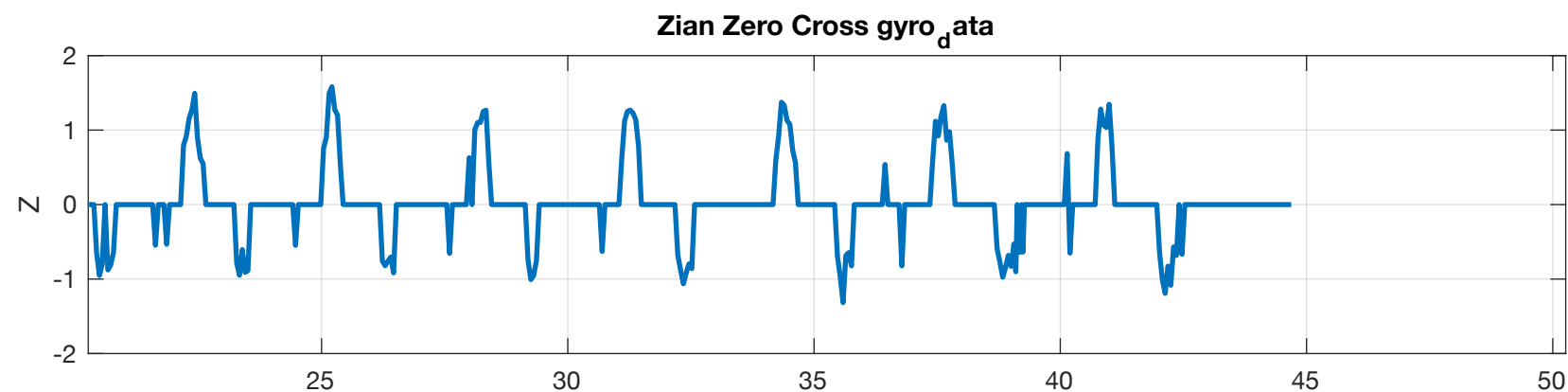
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-187.000	-151.000	-47.000	-60.000	"accel_data"
'Y'	-150.000	-123.000	-34.000	-23.500	"accel_data"
'X'	-187.000	-169.000	-52.000	-57.000	"accel_data"



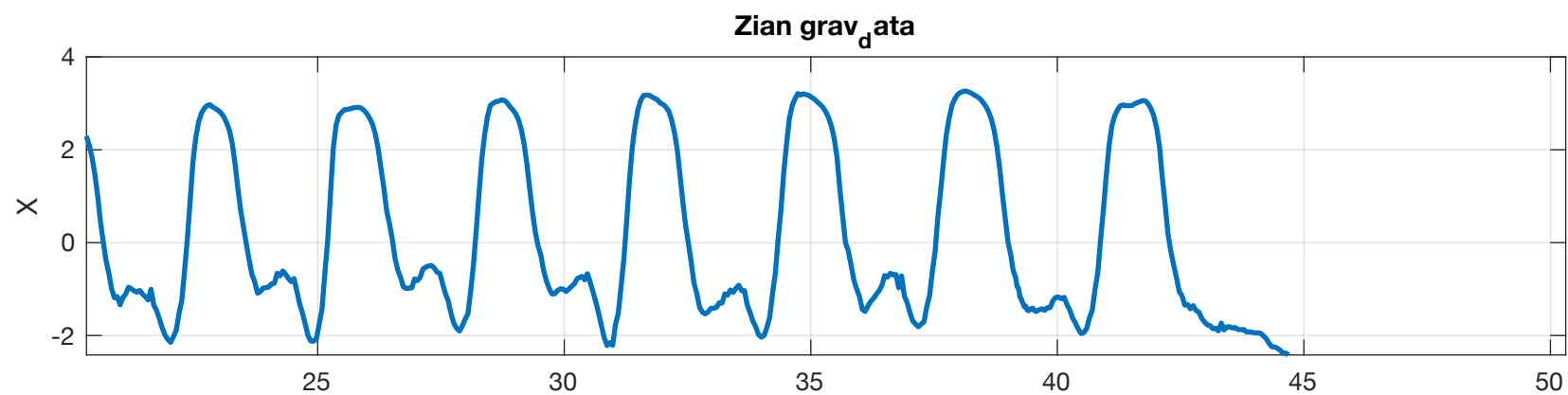
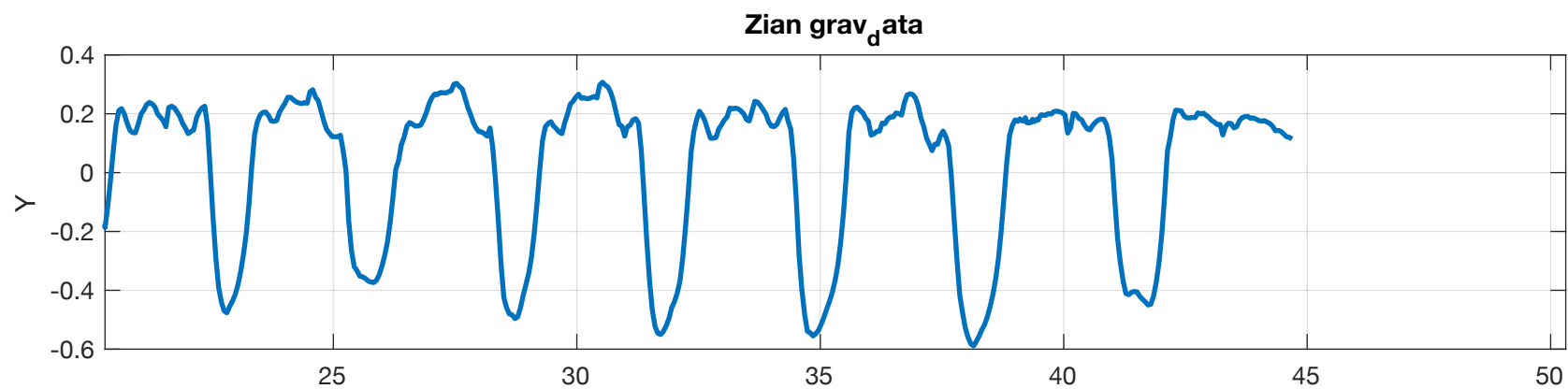
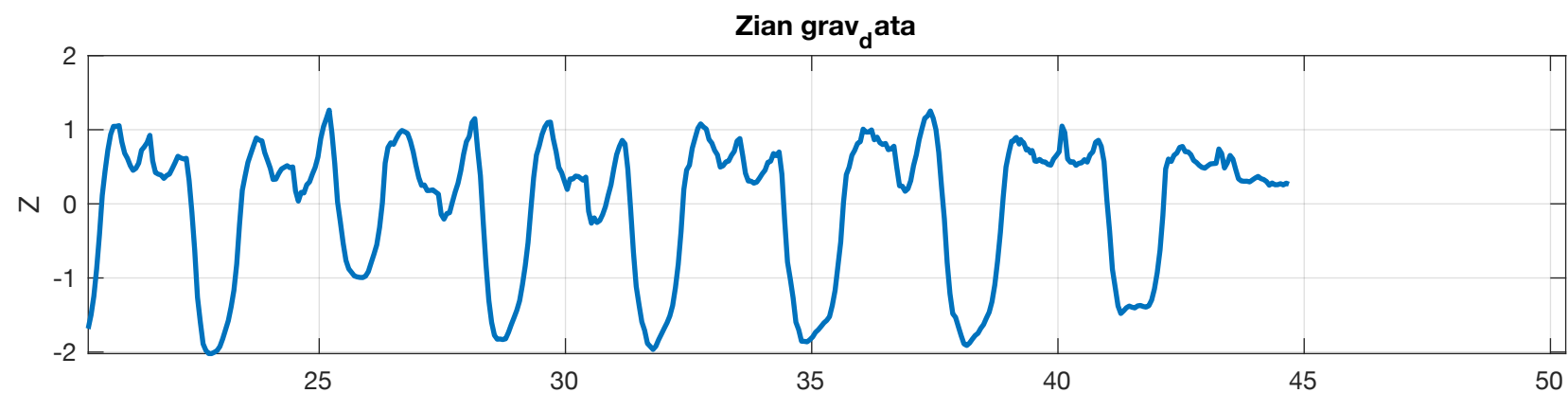


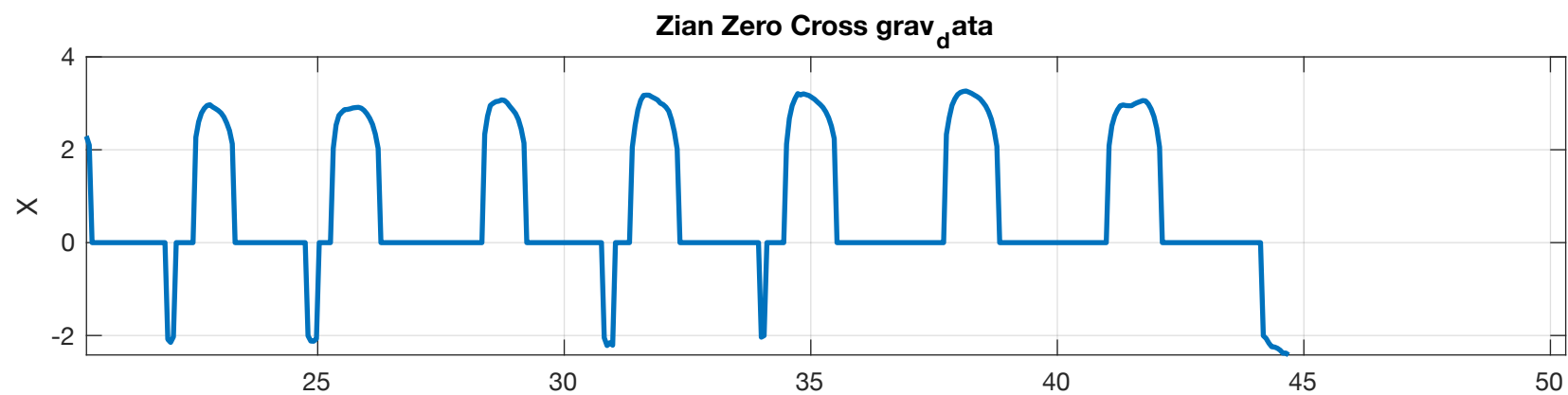
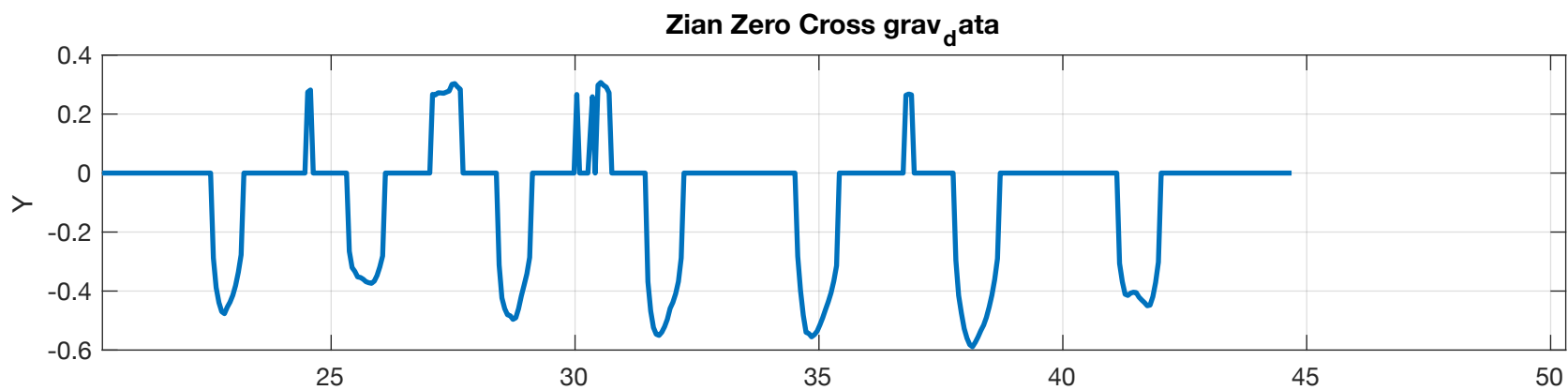
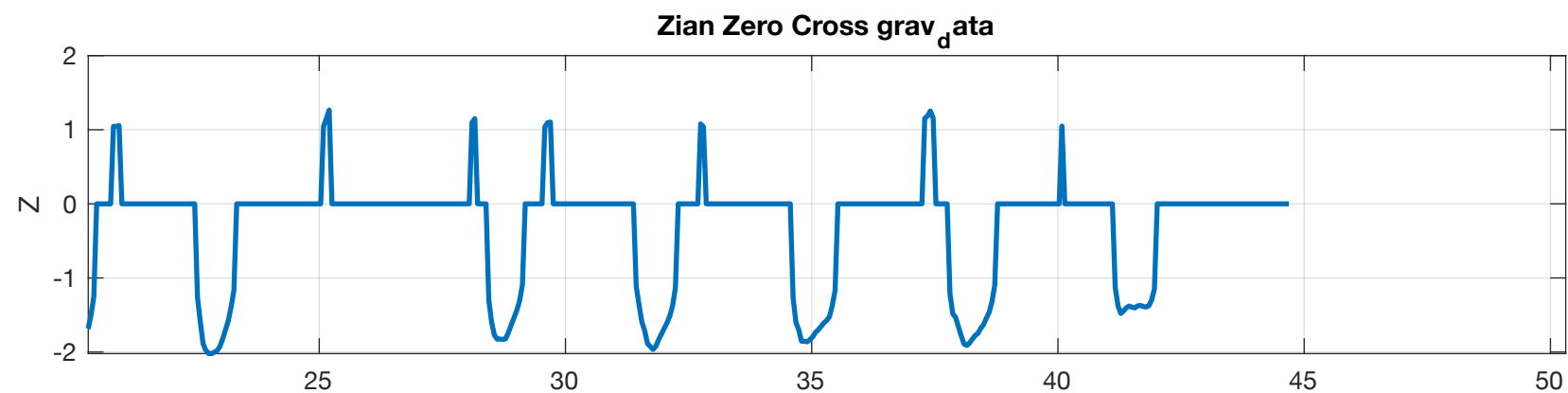
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-32.000	-31.000	-4.000	-7.000	"bar_data"
"Pressure"	-41.000	-24.000	-3.000	-7.000	"bar_data"



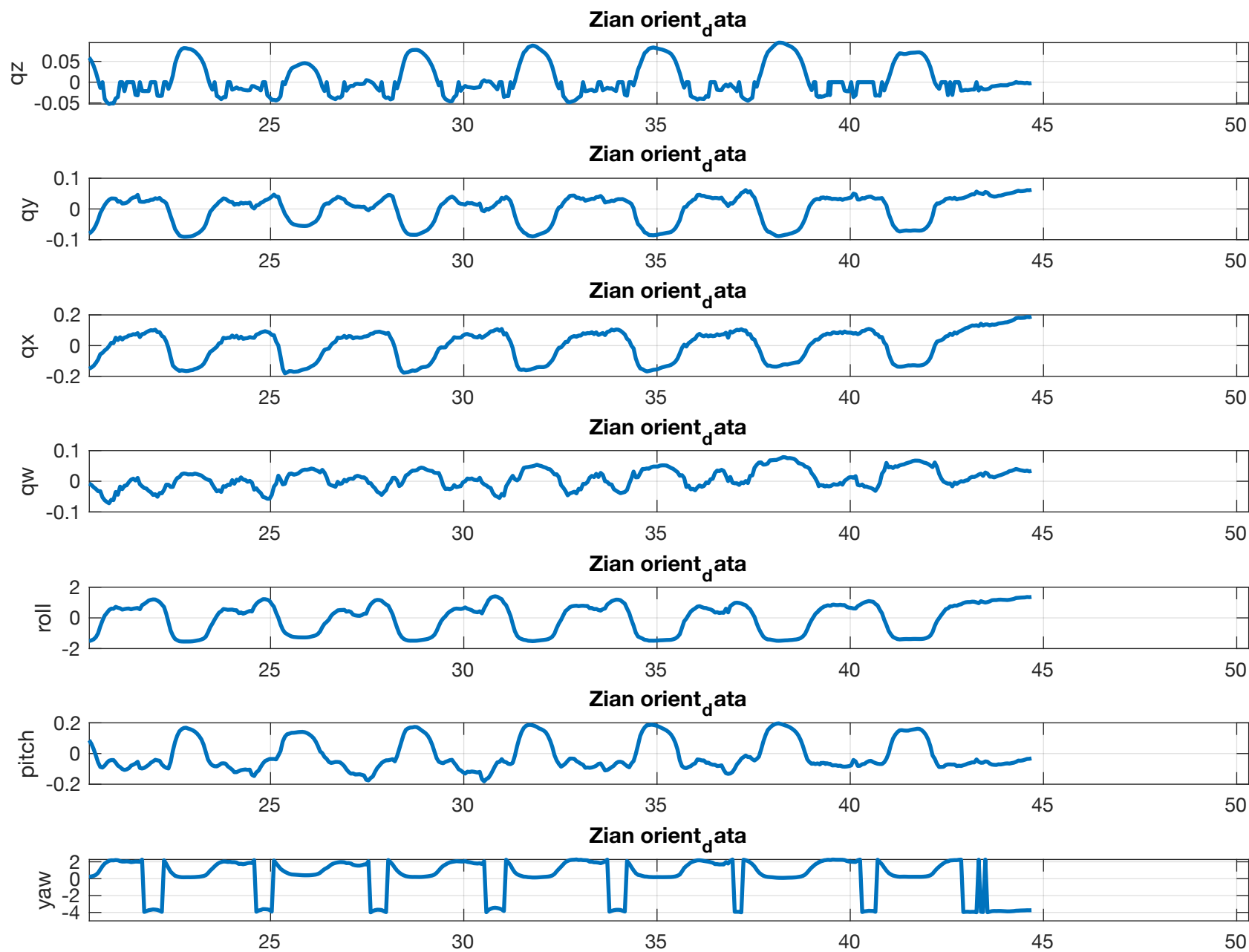


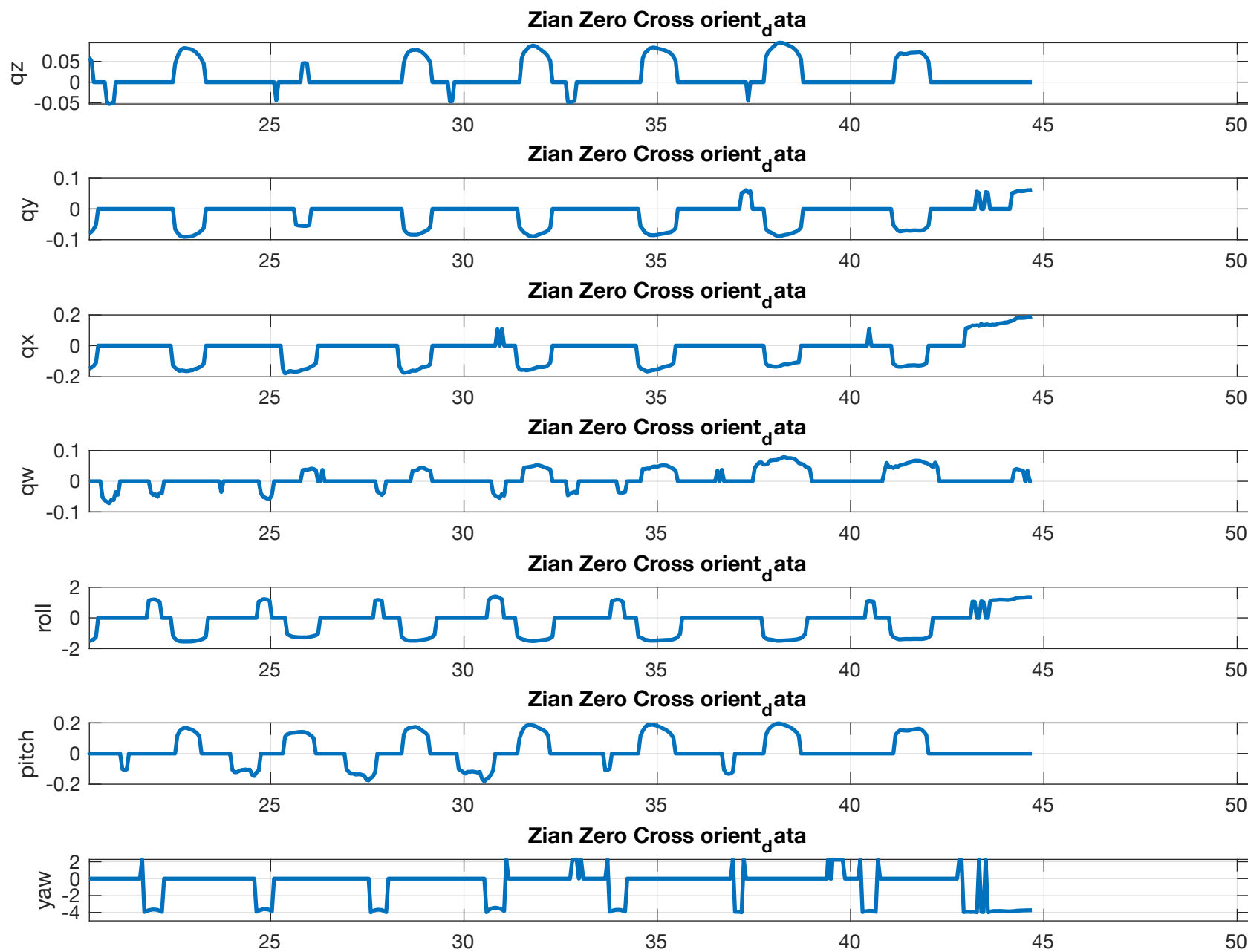
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-126.000	-74.000	-21.000	-8.000	"gyro_data"
'Y'	-186.000	-170.000	-53.000	-39.500	"gyro_data"
'X'	-150.000	-105.000	-33.000	-16.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-58.000	-54.000	-9.000	0.000	"grav_data"
'Y'	-62.000	-56.000	-9.000	1.500	"grav_data"
'X'	-50.000	-3.000	0.000	0.250	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-86.000	-6.000	-3.000	-0.500	"orient_data"
'qy'	-65.000	-60.000	-12.000	1.250	"orient_data"
'qx'	-83.000	-69.000	-8.000	2.250	"orient_data"
'qw'	-107.000	-50.000	-10.000	-3.500	"orient_data"
'roll'	-47.000	-41.000	-5.000	-0.750	"orient_data"
'pitch'	-60.000	-8.000	-2.000	1.000	"orient_data"
'yaw'	-64.000	-45.000	-17.000	-6.250	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Y"	'zero_cross'	23.500
'bar_data'	"Pressure"	'double_findpeaks'	3.000
'gyro_data'	"Z"	'zero_cross'	8.000
'grav_data'	"X"	'double_findpeaks'	0.000
'orient_data'	"qz"	'zero_cross'	0.500