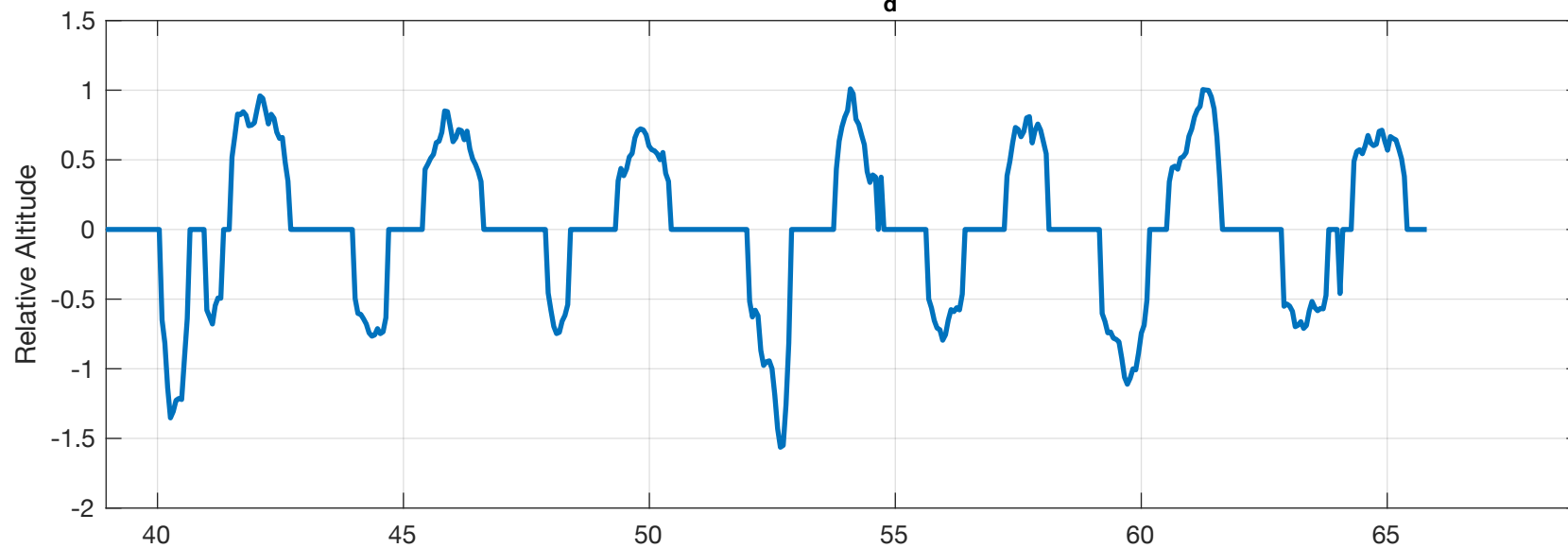
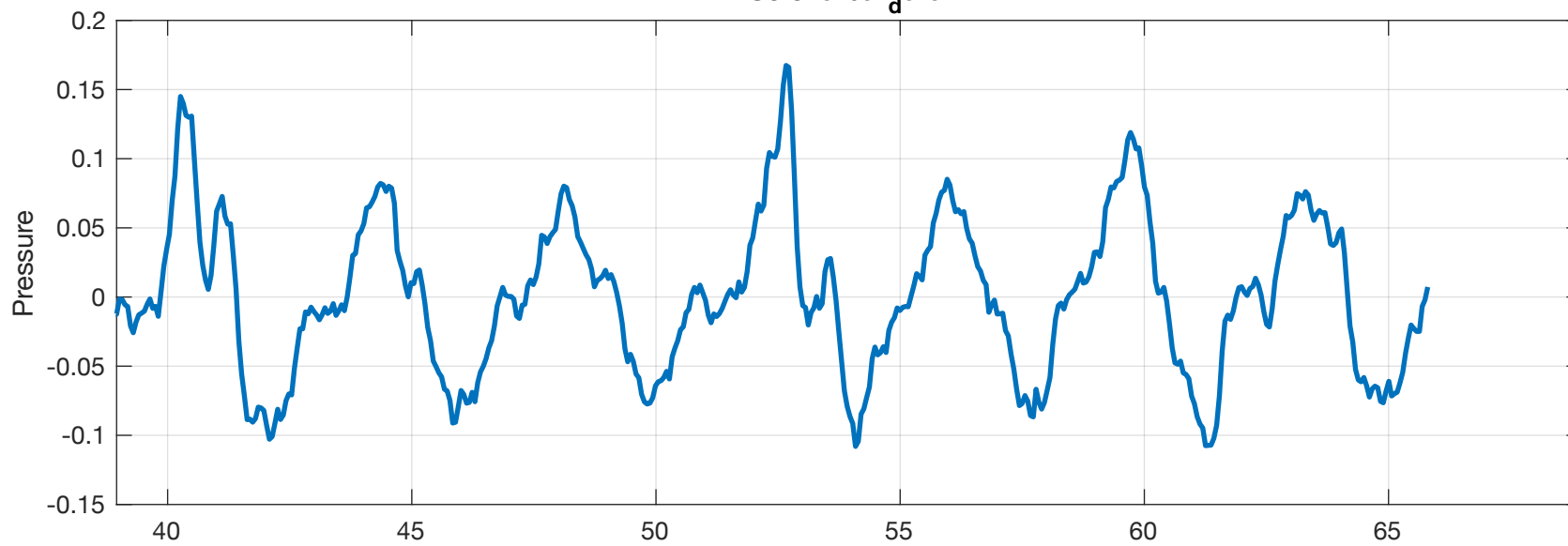


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-163.000	-130.000	-40.000	-51.000	"accel_data"
'Y'	-201.000	-154.000	-59.000	-61.000	"accel_data"
'X'	-177.000	-149.000	-45.000	-55.000	"accel_data"

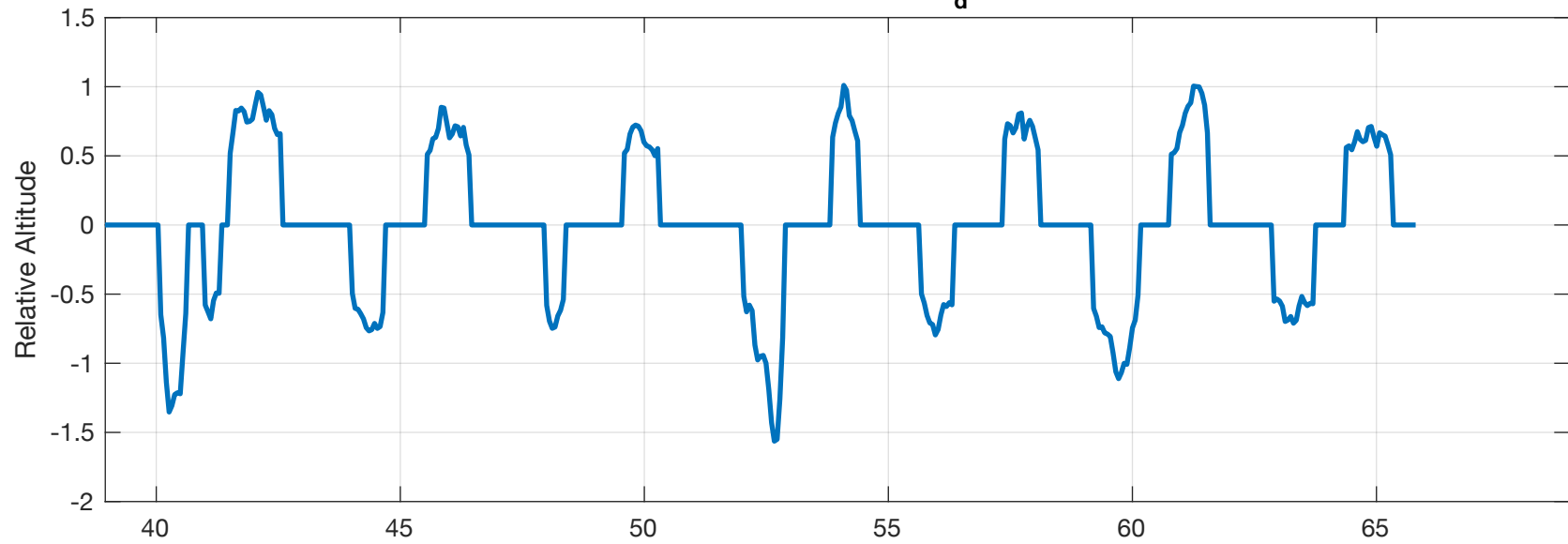
Selena bar_data



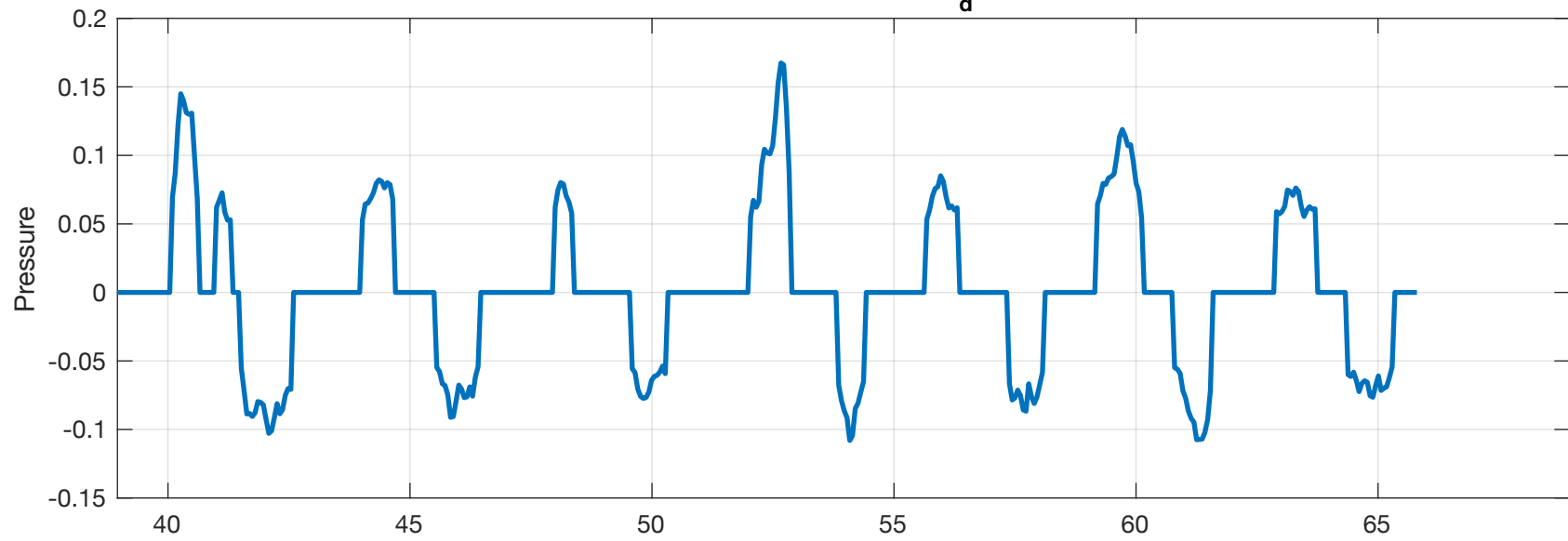
Selena bar_data



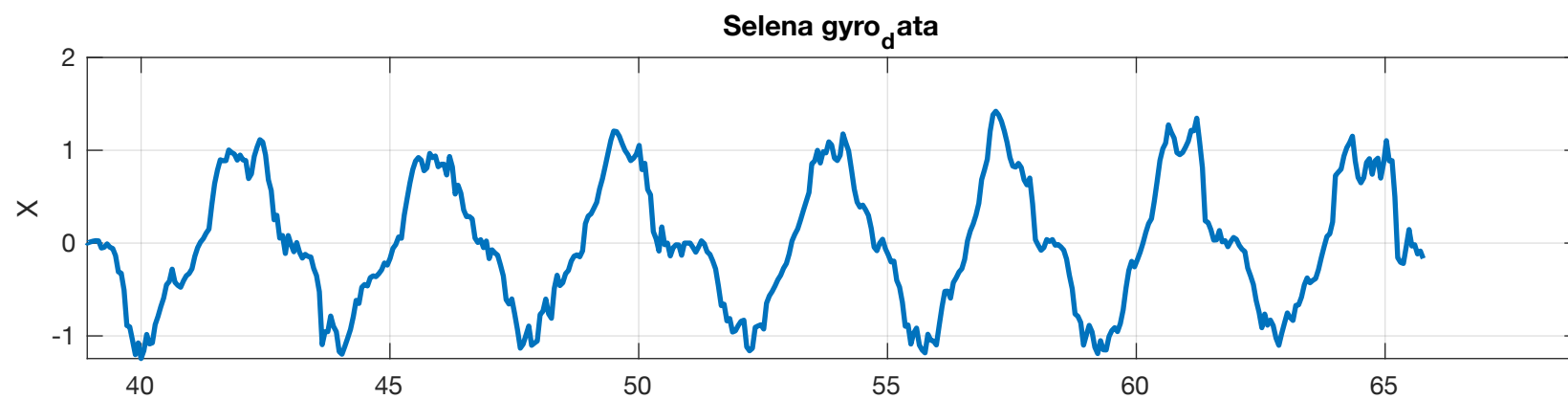
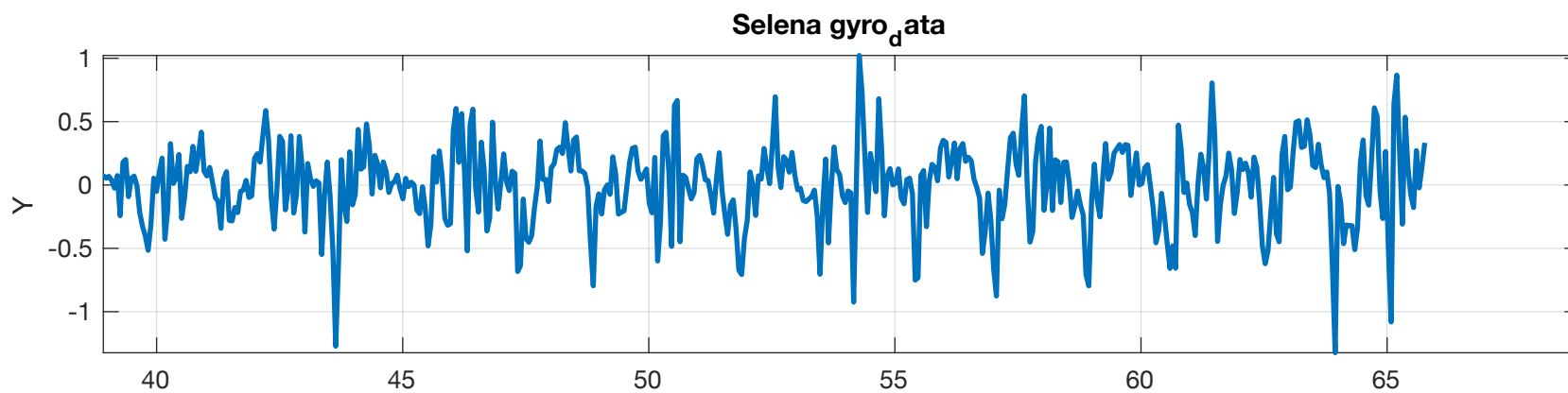
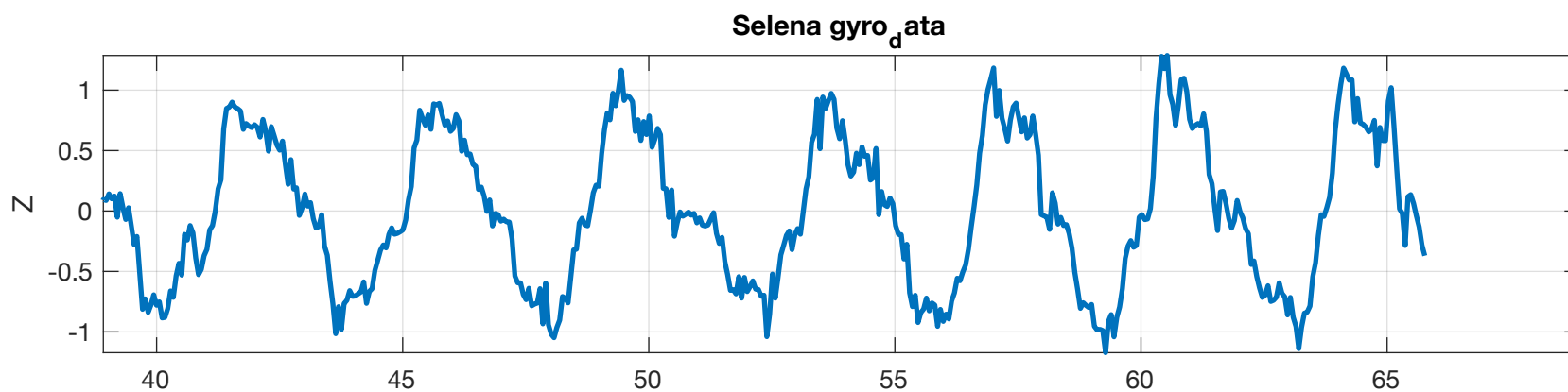
Selena Zero Cross bar_data



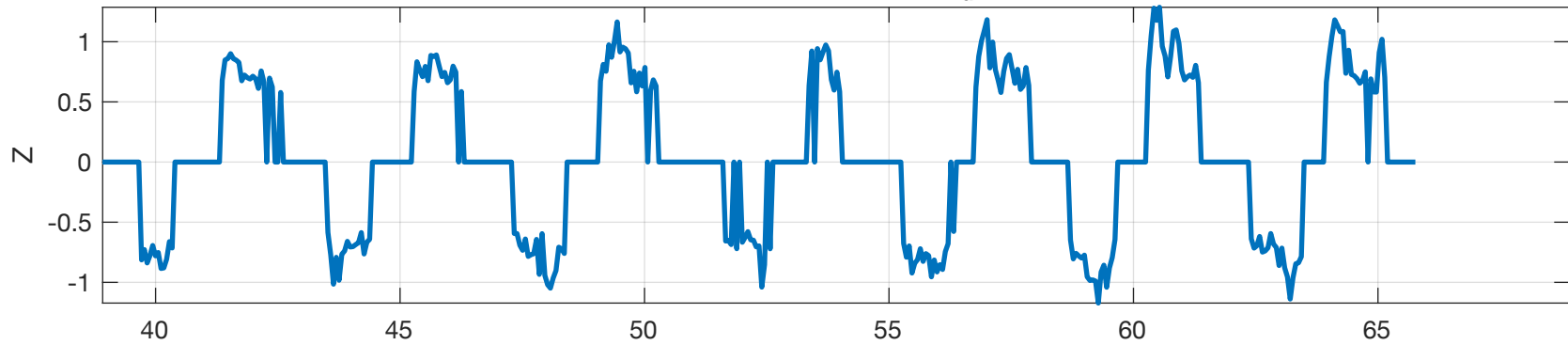
Selena Zero Cross bar_data



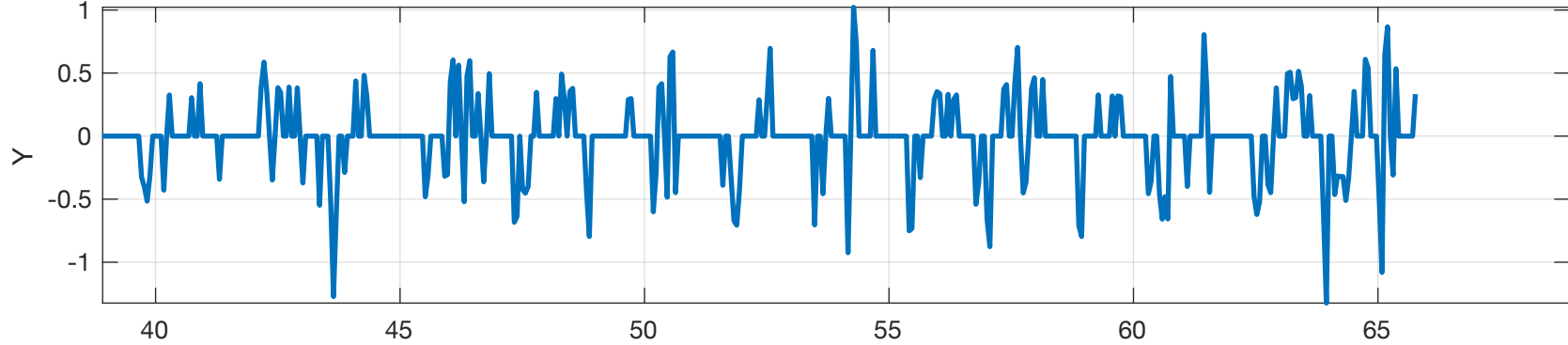
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-37.000	-18.000	1.000	0.000	"bar_data"
"Pressure"	-89.000	-48.000	-4.000	0.000	"bar_data"



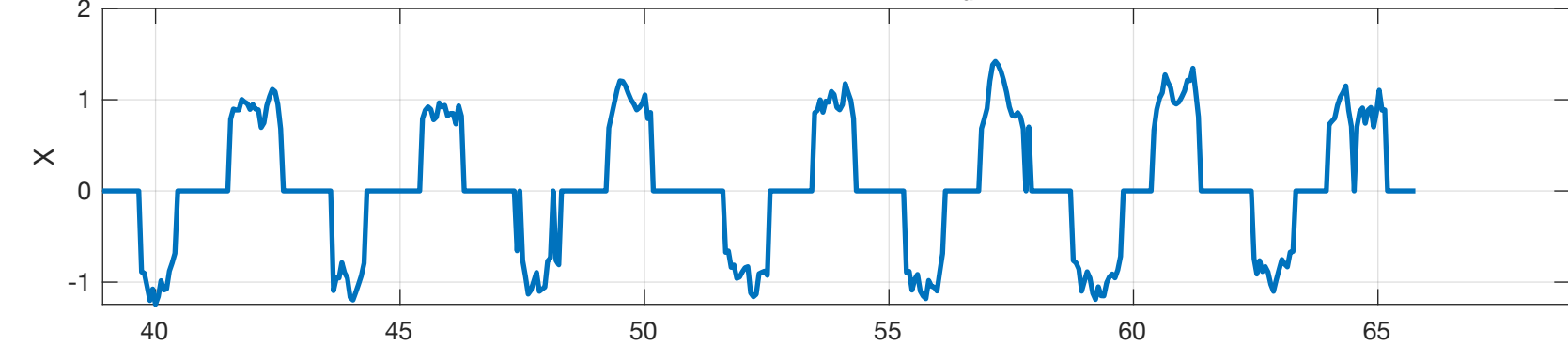
Selena Zero Cross gyro_data



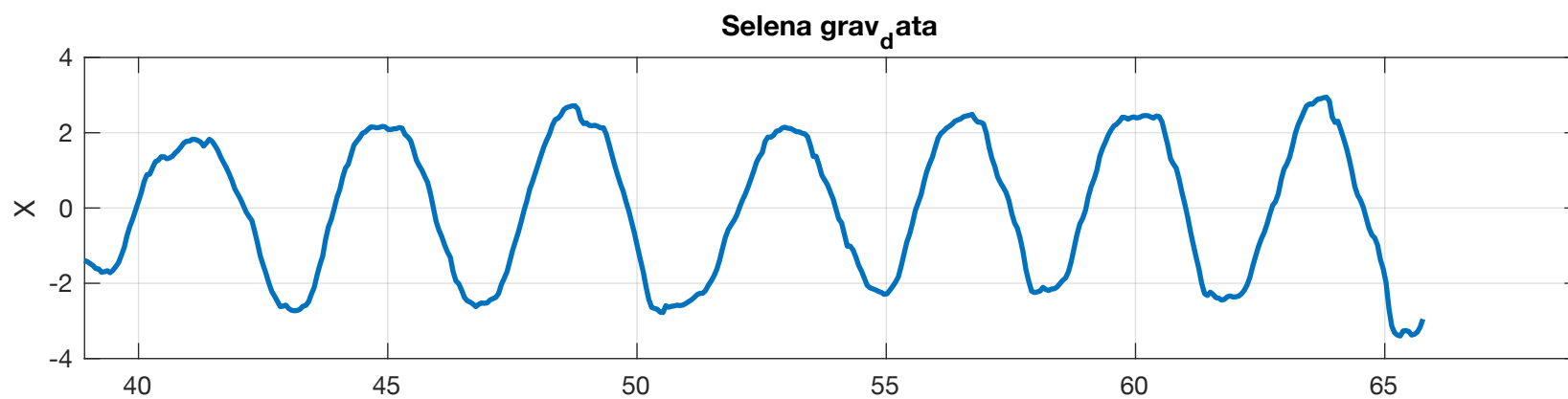
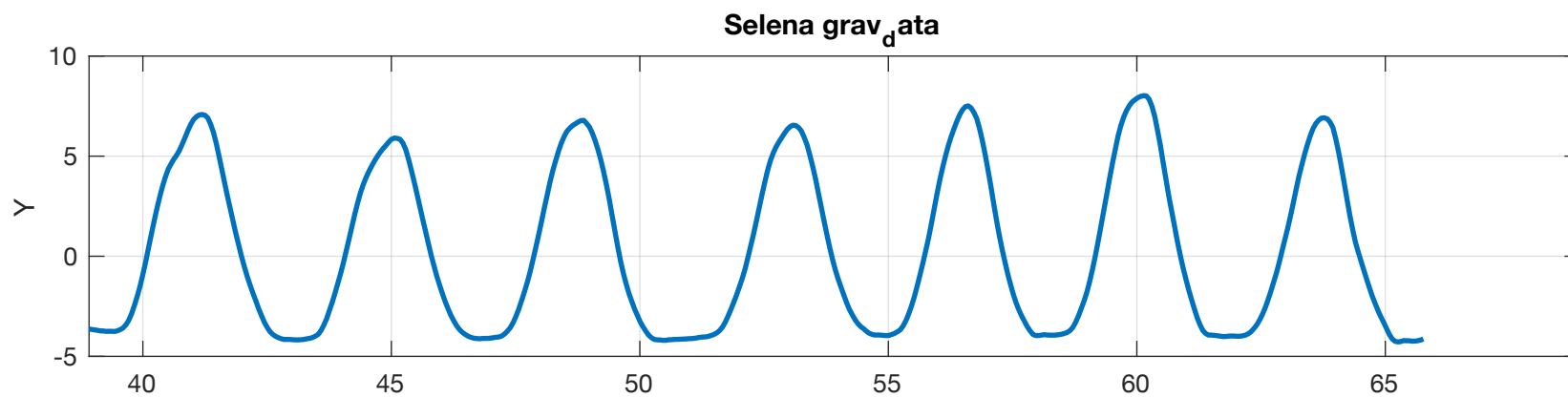
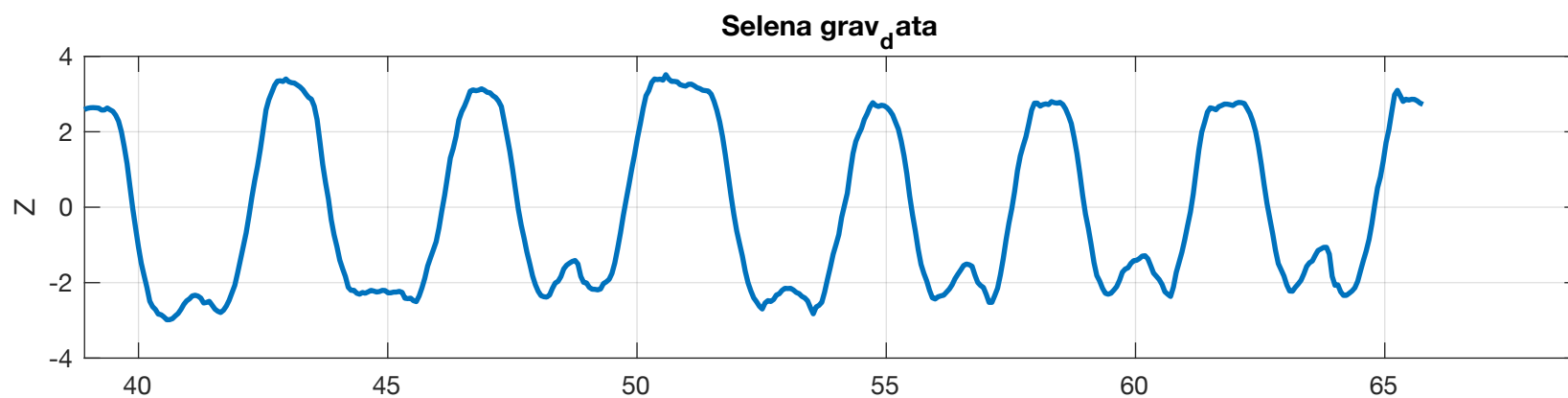
Selena Zero Cross gyro_data

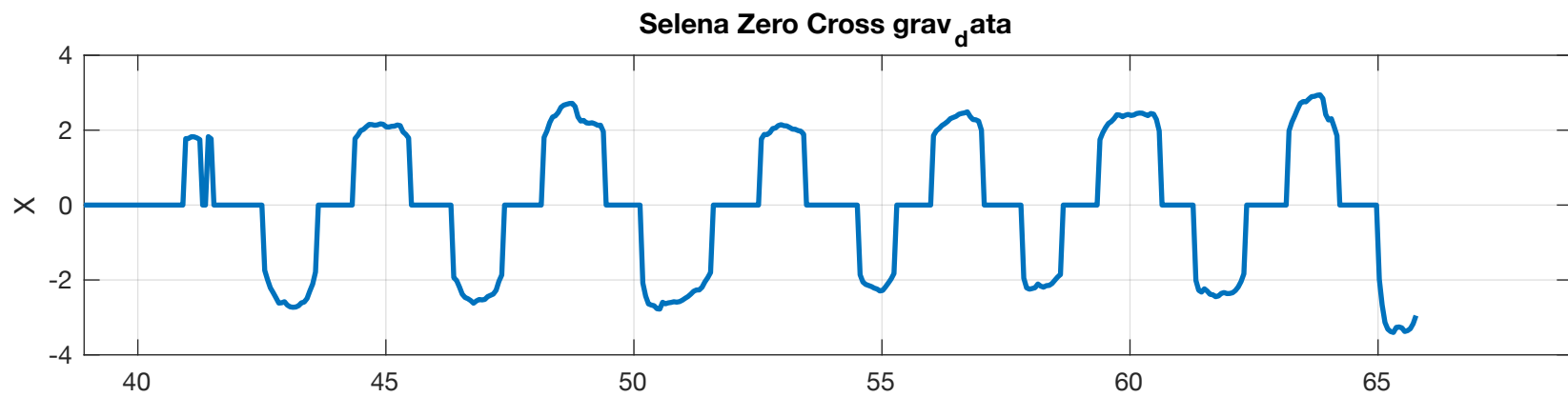
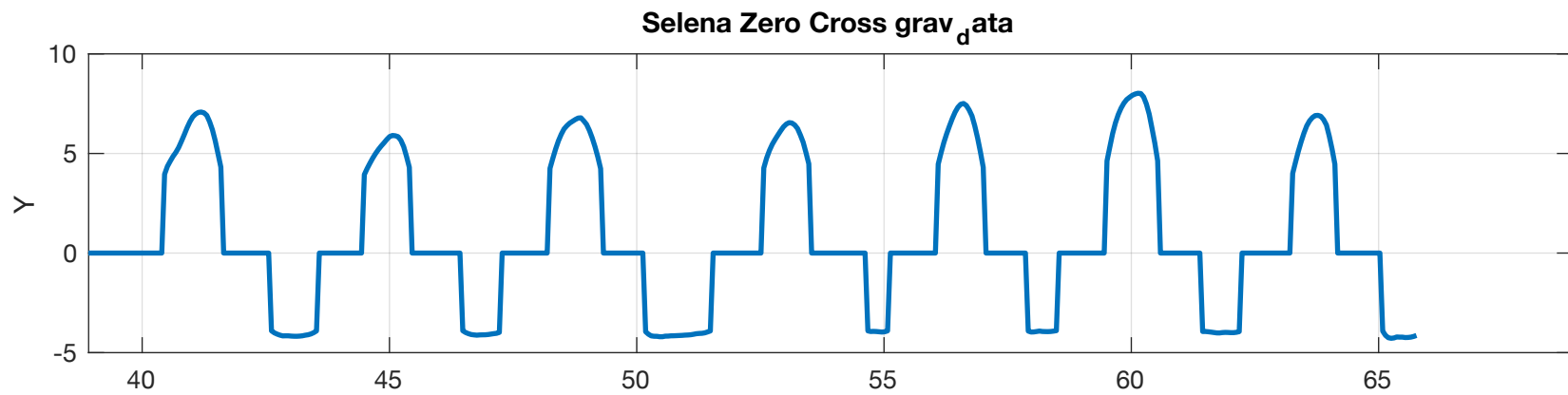
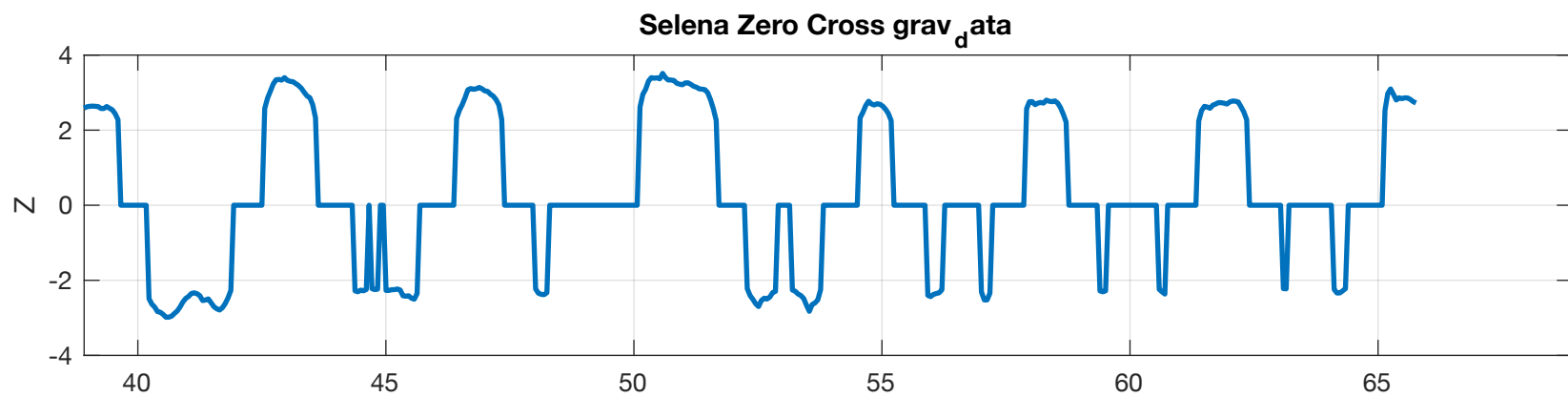


Selena Zero Cross gyro_data

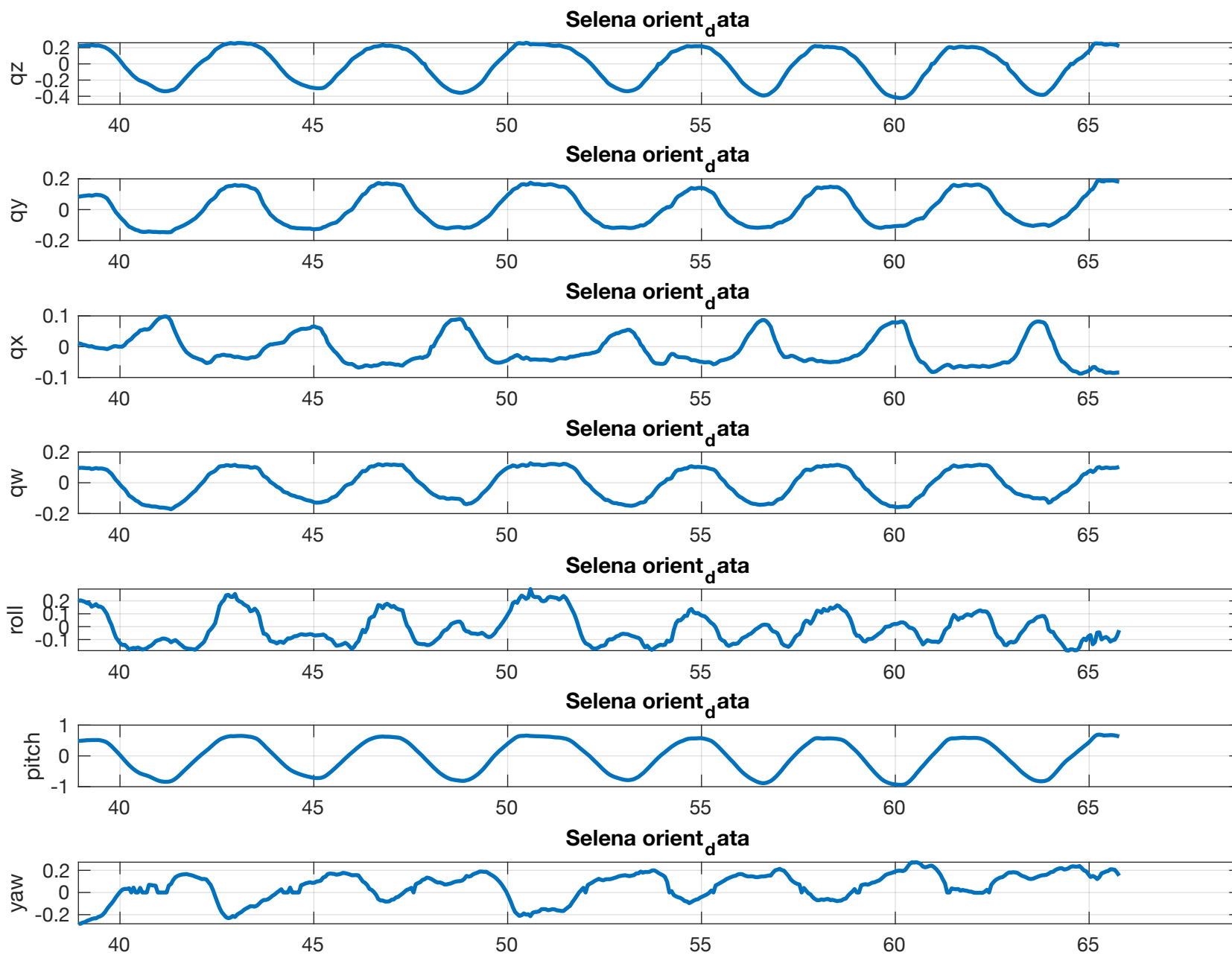


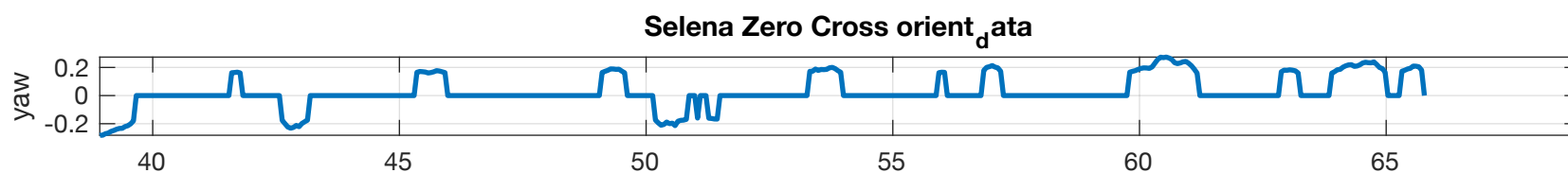
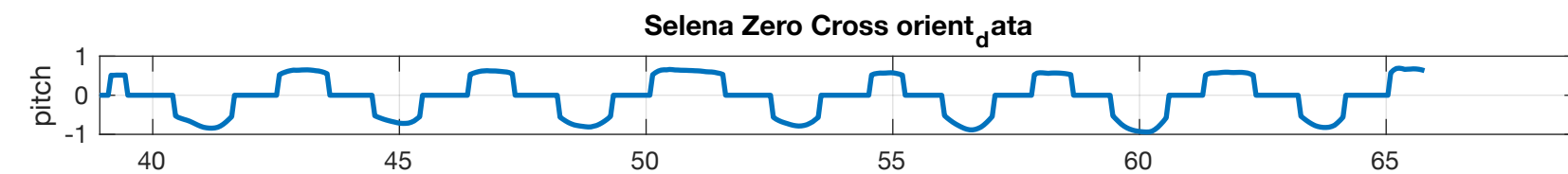
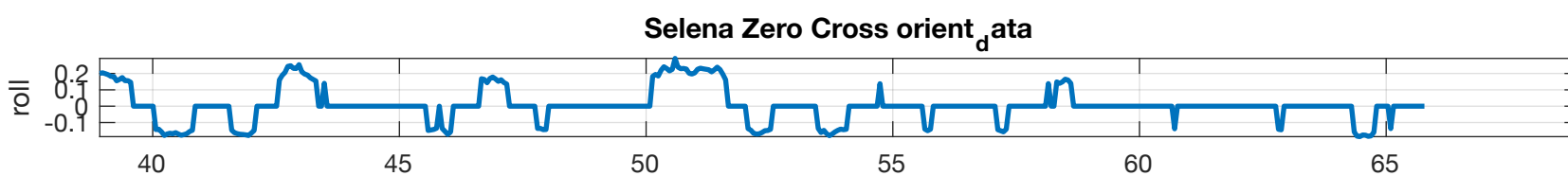
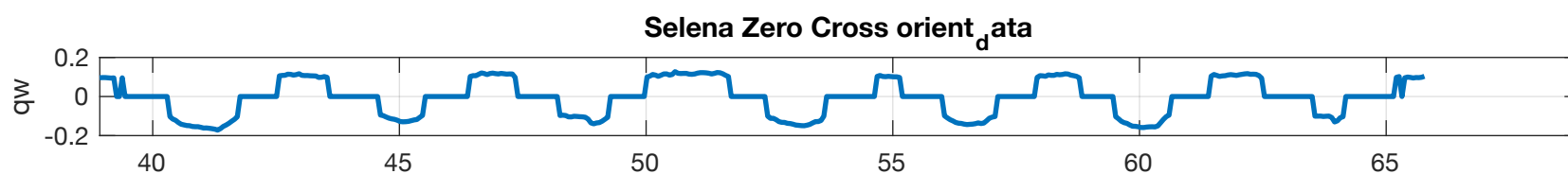
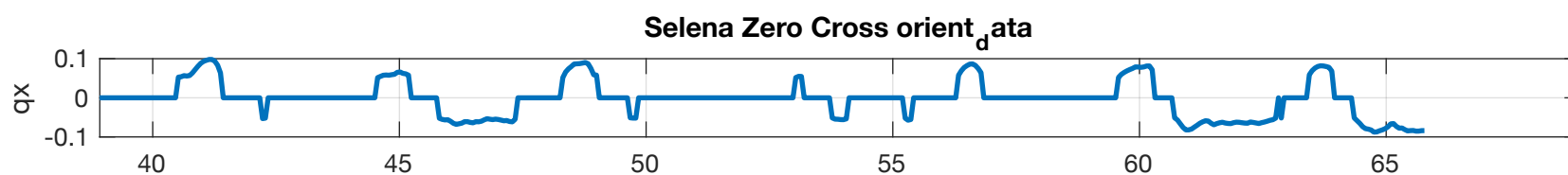
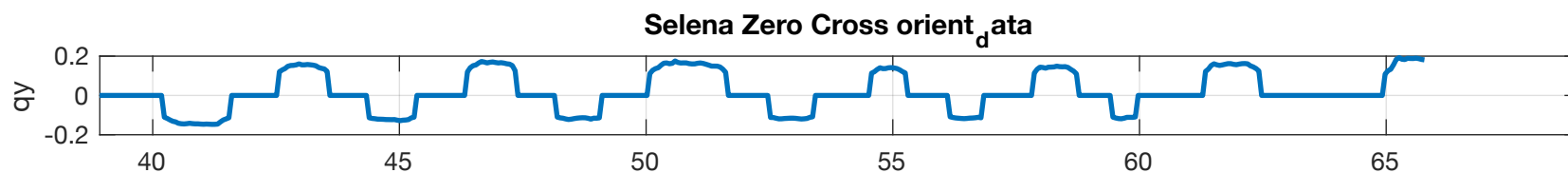
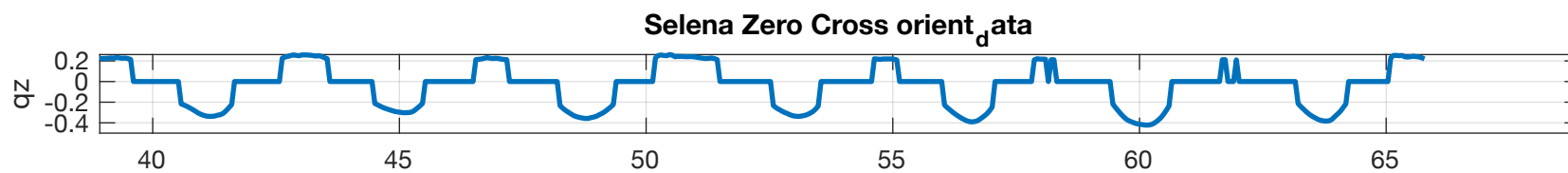
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-152.000	-80.000	-14.000	-5.500	"gyro_data"
'Y'	-160.000	-133.000	-30.000	-39.750	"gyro_data"
'X'	-113.000	-59.000	-9.000	-2.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-37.000	-19.000	-2.000	-2.250	"grav_data"
'Y'	-11.000	1.000	4.000	1.750	"grav_data"
'X'	-35.000	-18.000	1.000	1.250	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-27.000	-24.000	3.000	0.250	"orient_data"
'qy'	-40.000	-23.000	-1.000	2.250	"orient_data"
'qx'	-52.000	-18.000	1.000	1.750	"orient_data"
'qw'	-46.000	-36.000	-3.000	-1.250	"orient_data"
'roll'	-69.000	-31.000	-4.000	-2.500	"orient_data"
'pitch'	-13.000	-13.000	3.000	0.750	"orient_data"
'yaw'	-67.000	-41.000	-3.000	1.500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'double_findpeaks'	40.000
'bar_data'	"Relative Altitude"	'zero_cross'	0.000
'gyro_data'	"X"	'zero_cross'	2.000
'grav_data'	"Y"	'findpeaks_above_zero'	1.000
'orient_data'	"qz"	'zero_cross'	0.250