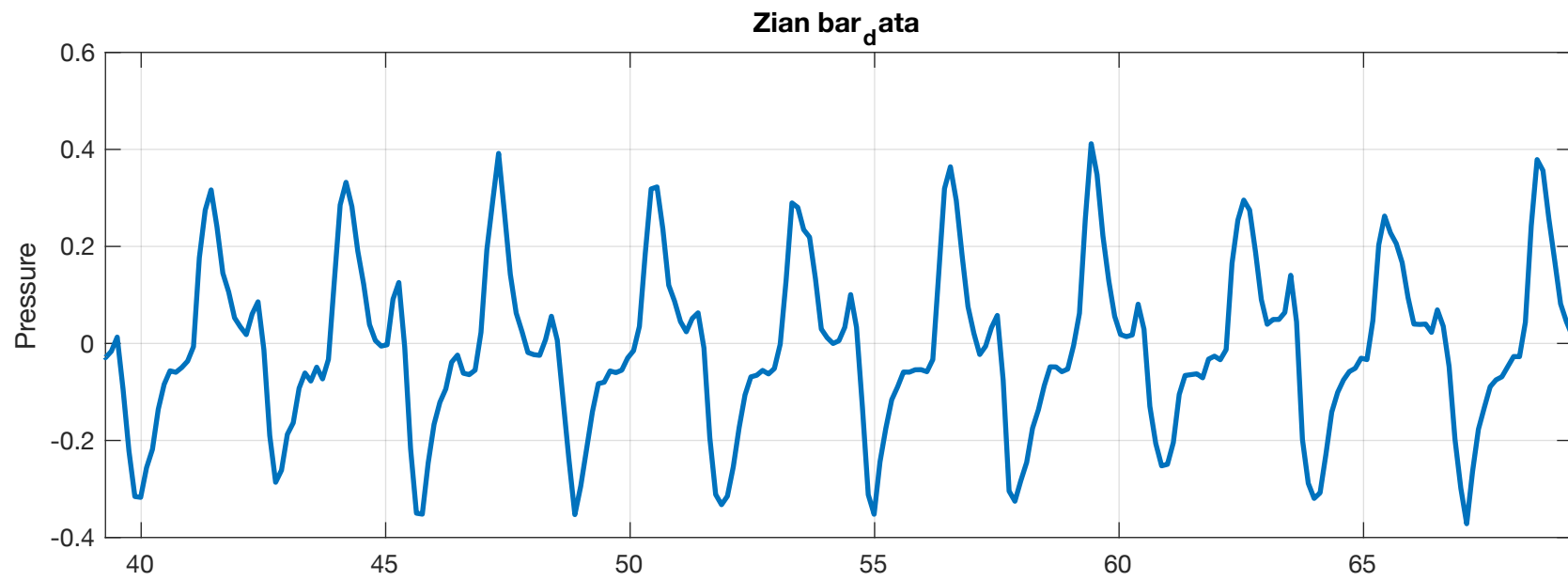
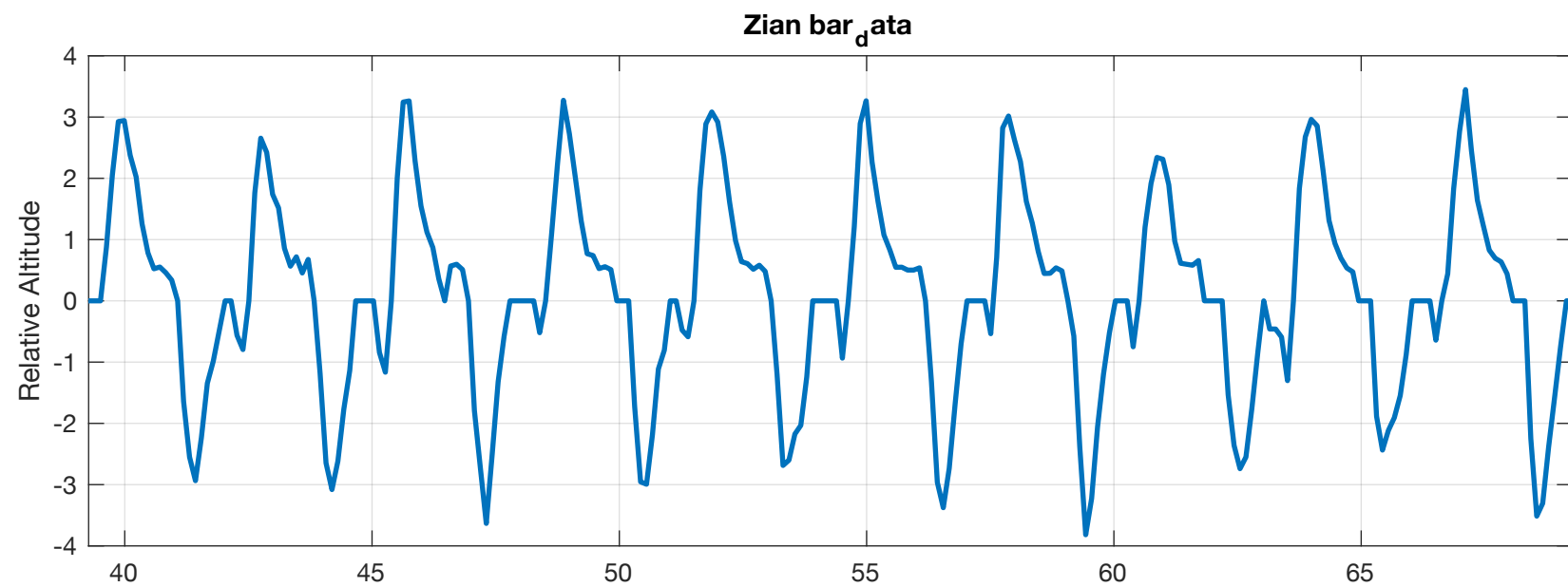
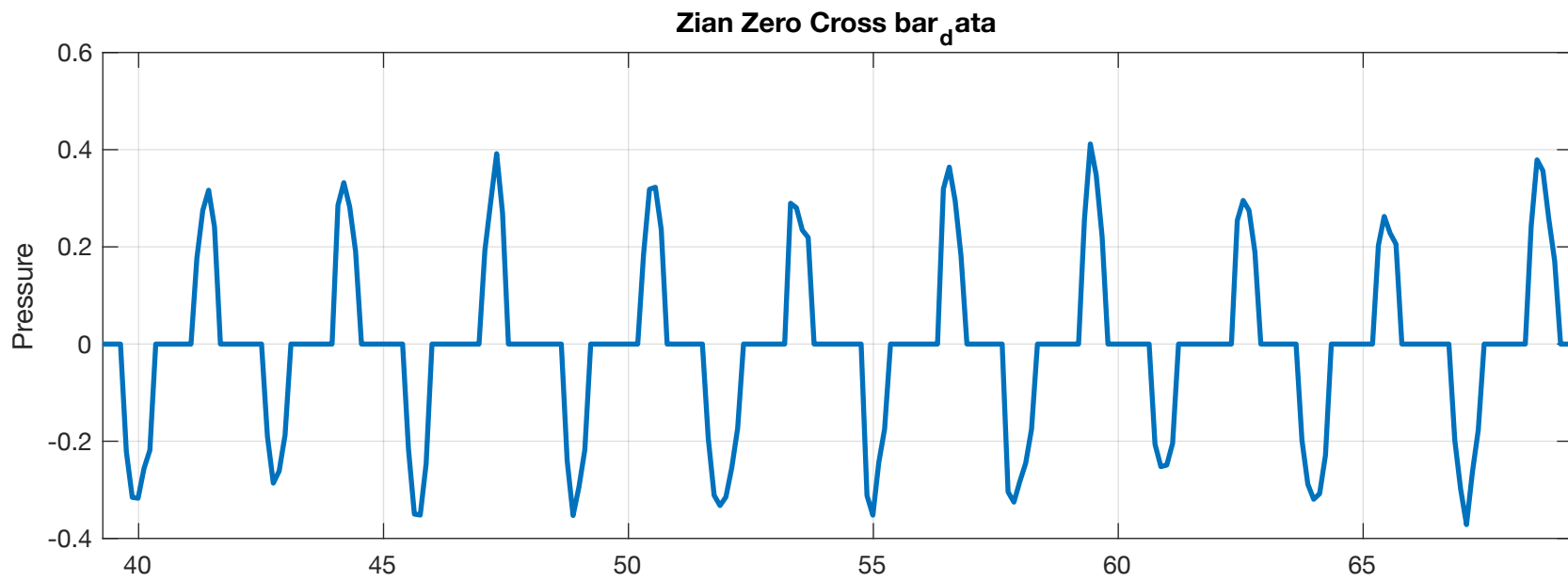
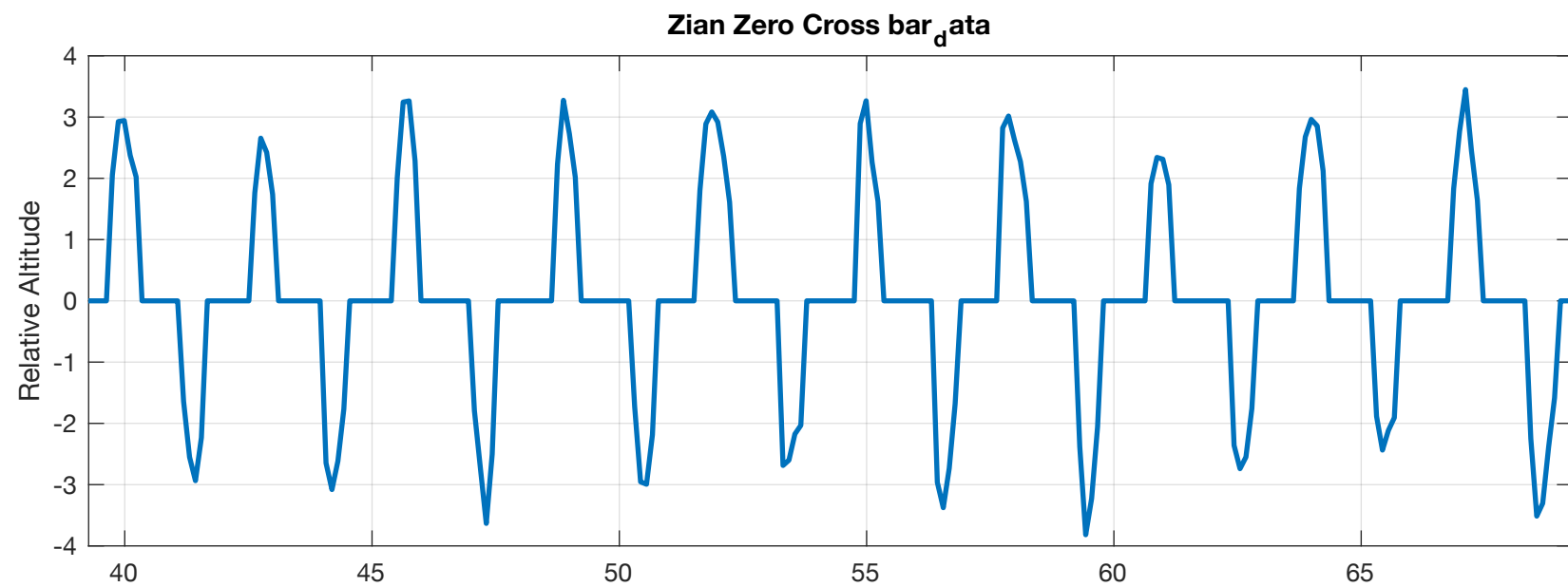
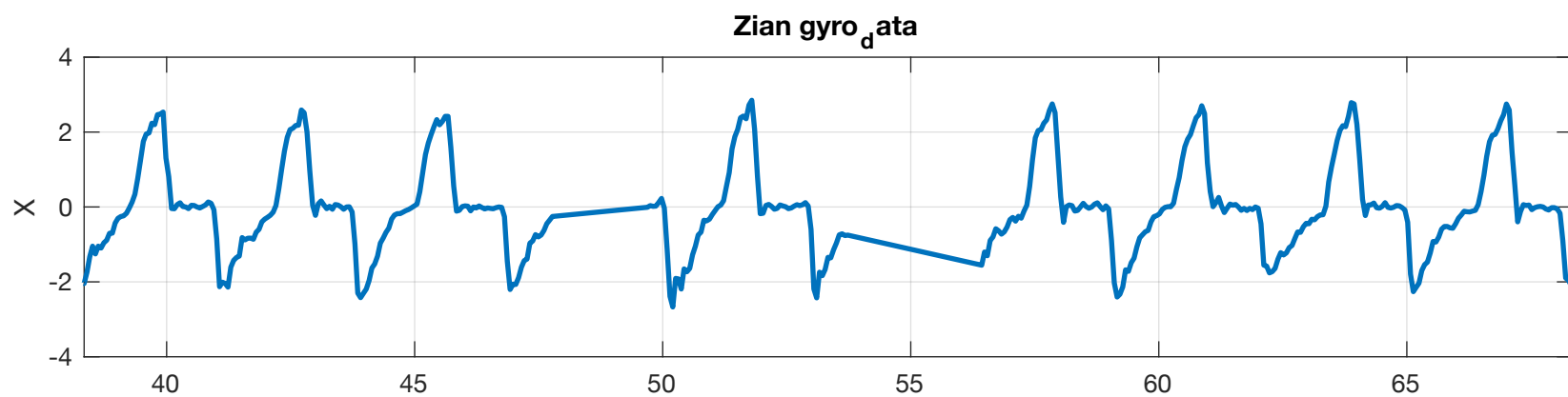
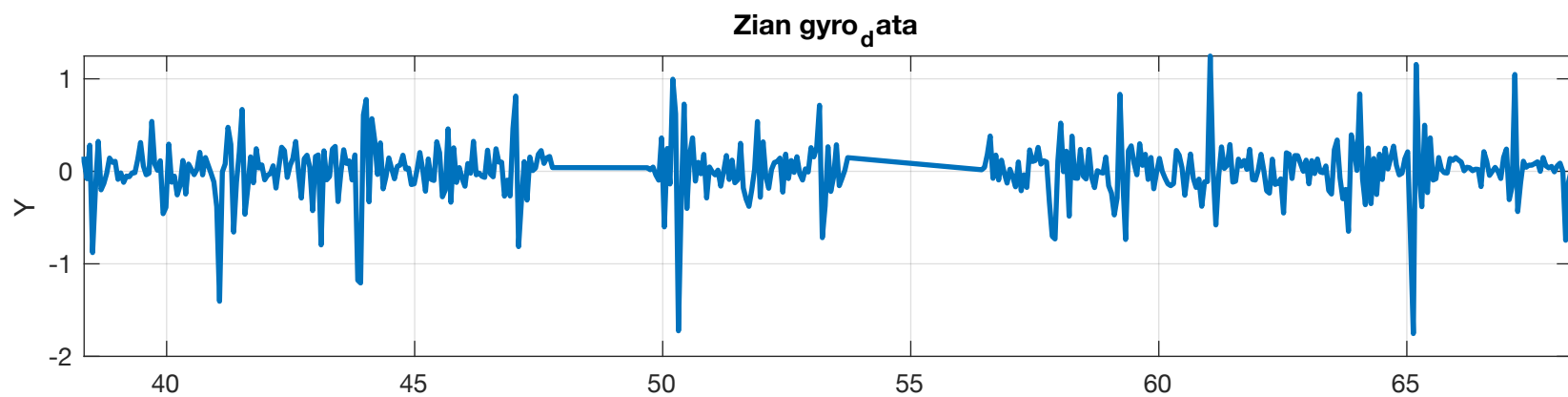


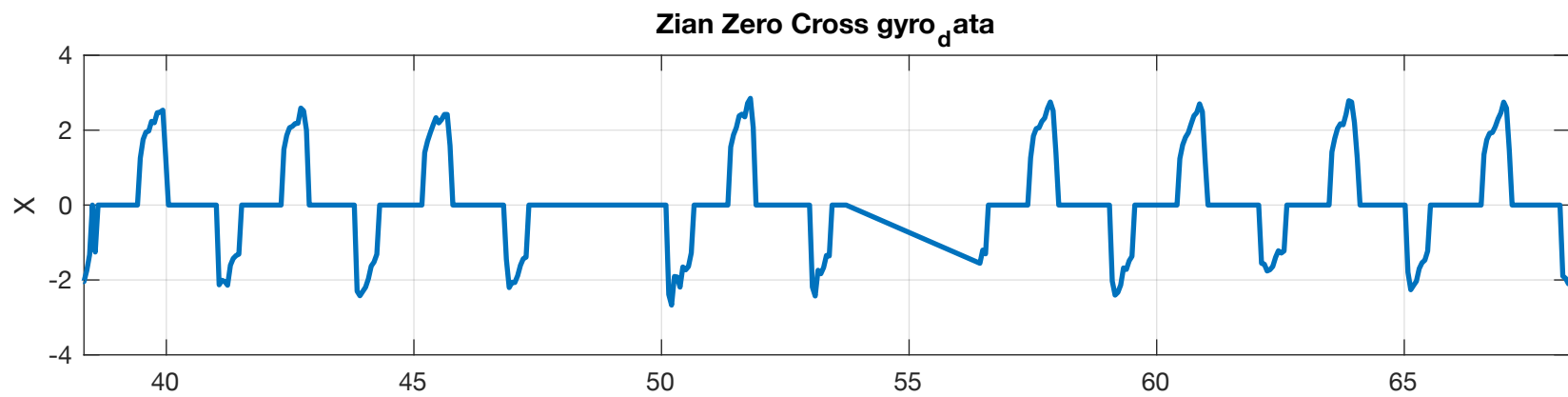
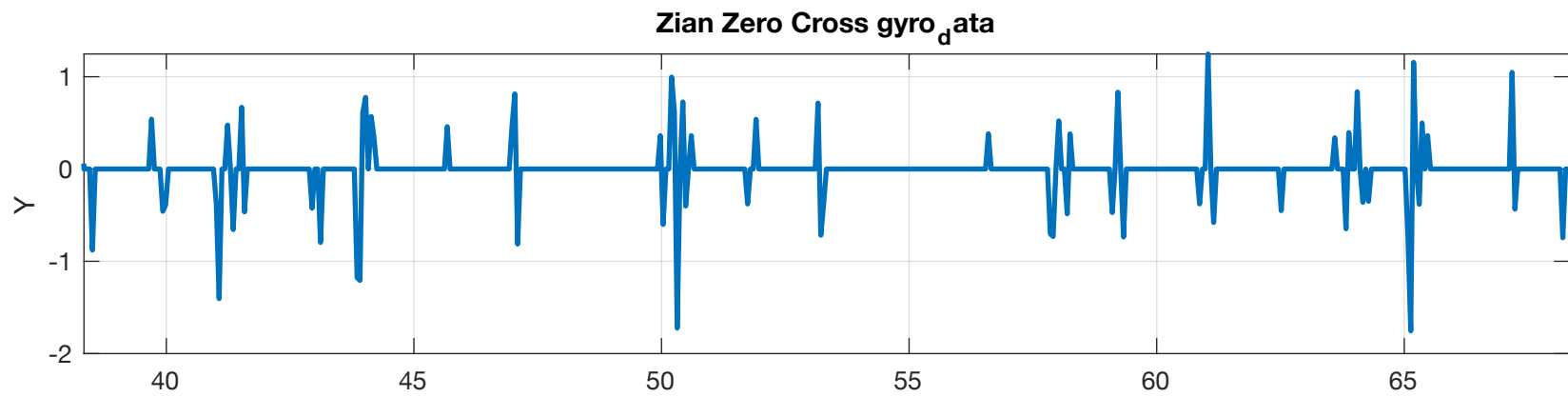
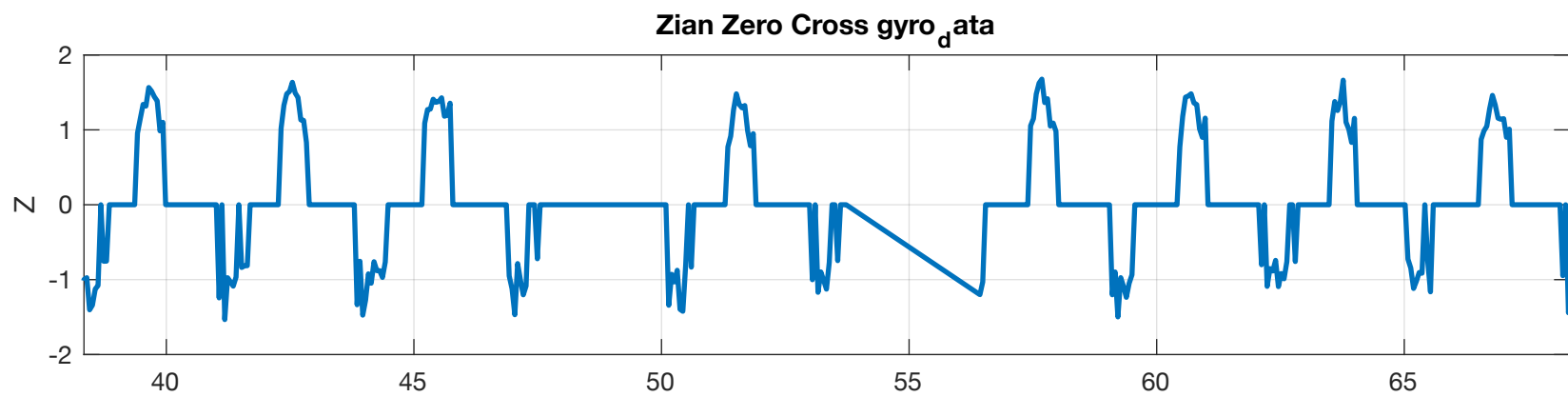
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-400.000	-299.000	-126.000	-88.500	"accel_data"
'Y'	-401.000	-264.000	-104.000	-115.000	"accel_data"
'X'	-435.000	-376.000	-132.000	-154.000	"accel_data"



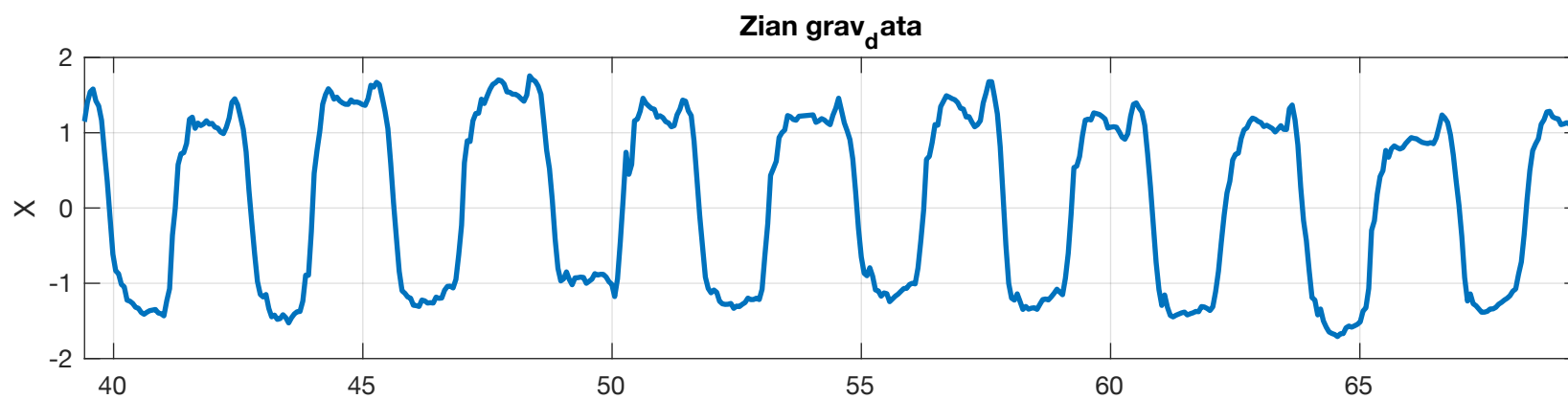
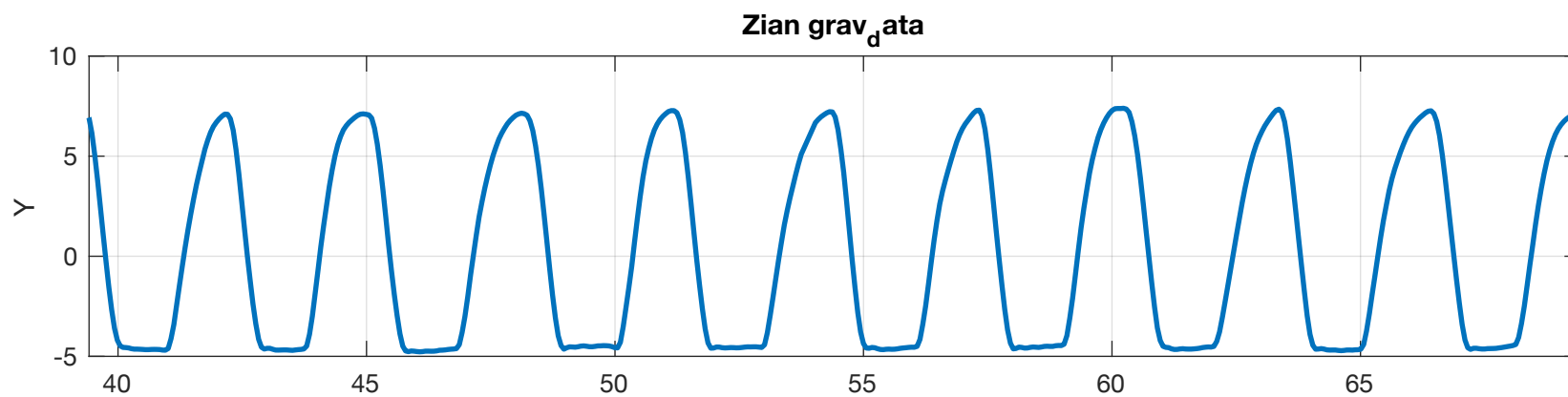
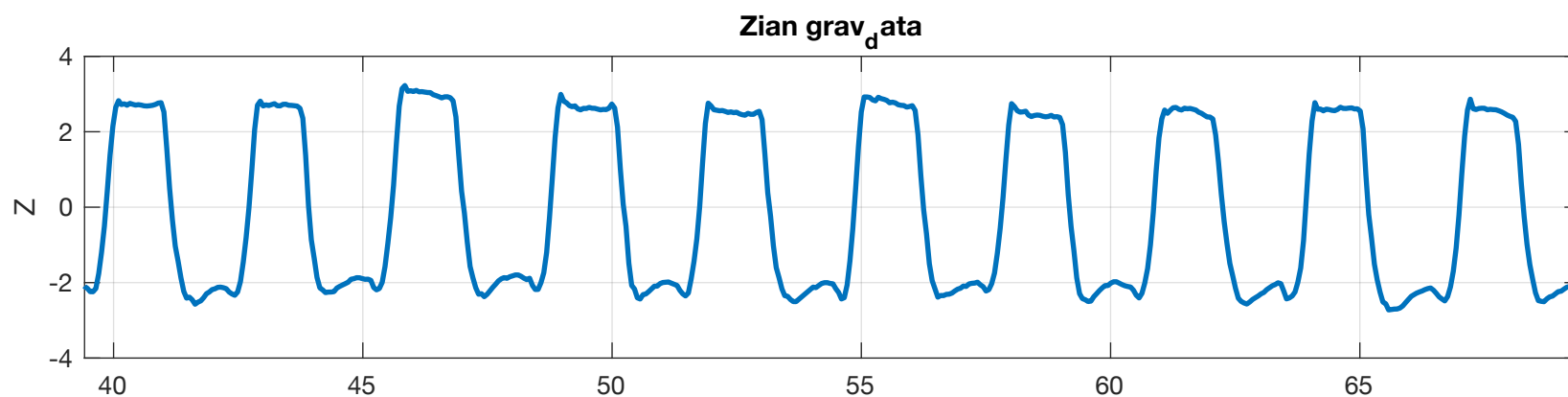


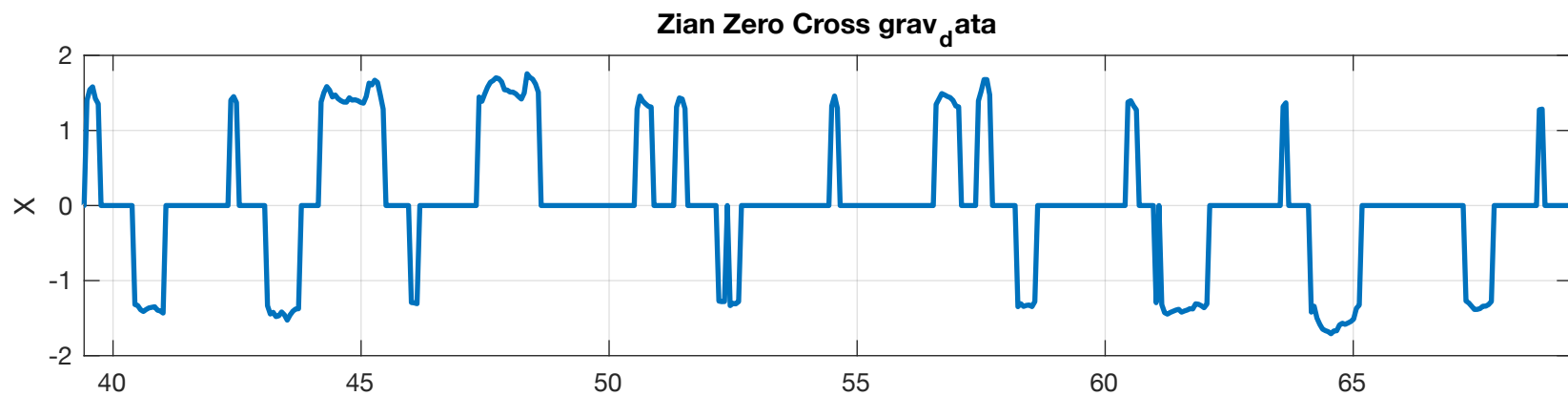
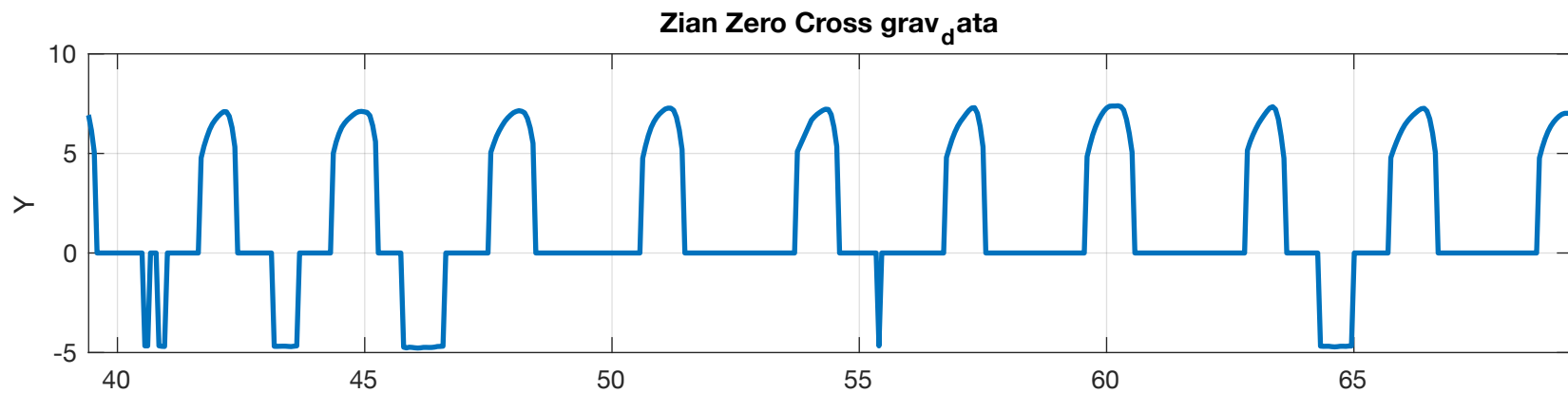
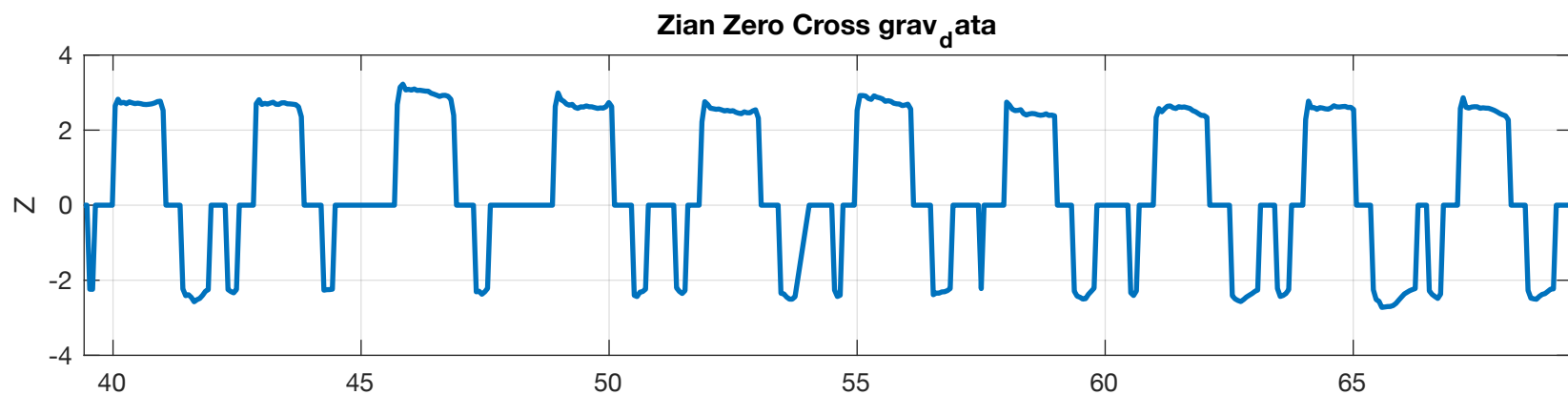
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-69.000	-48.000	-24.000	-25.000	"bar_data"
"Pressure"	-82.000	-53.000	-26.000	-25.000	"bar_data"



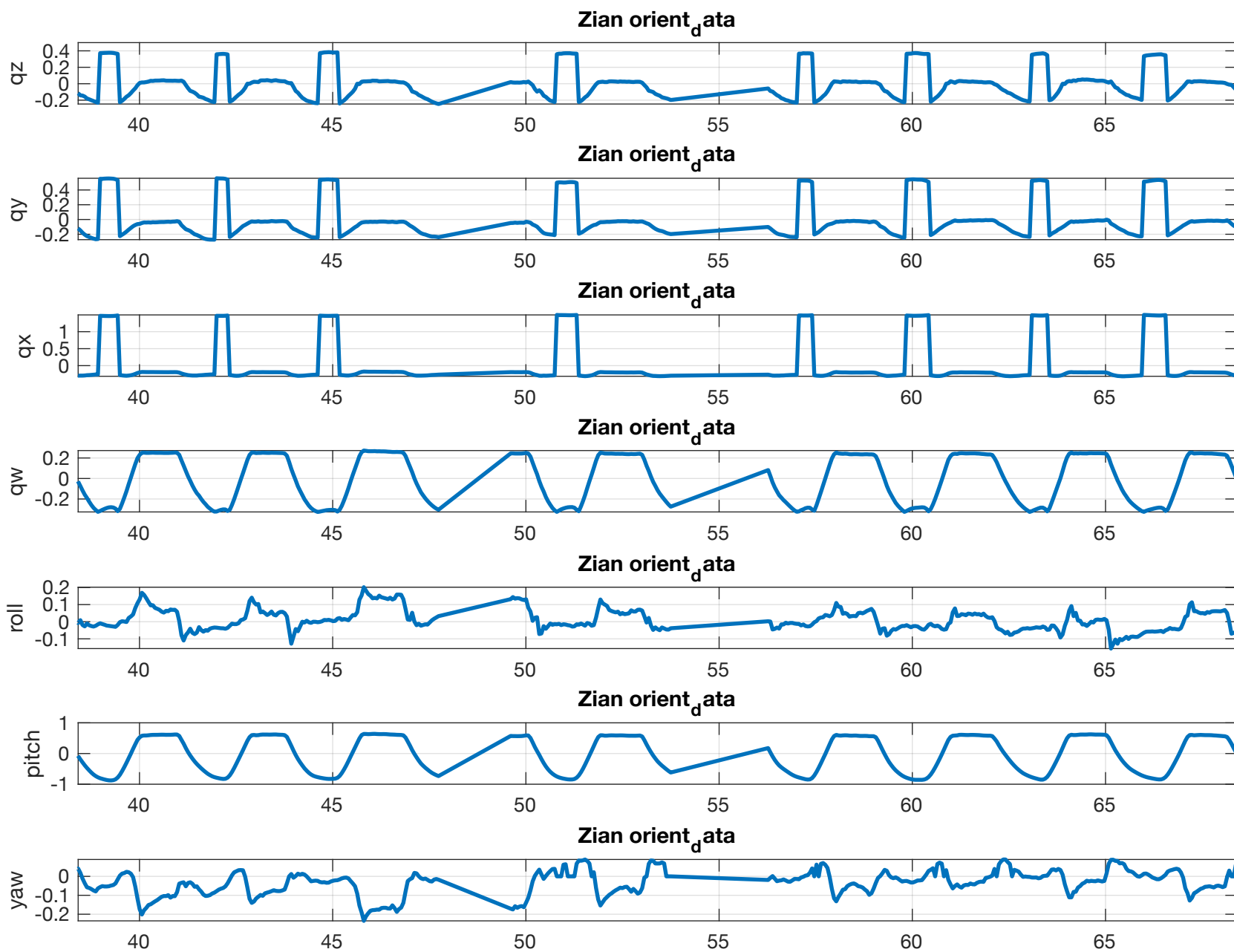


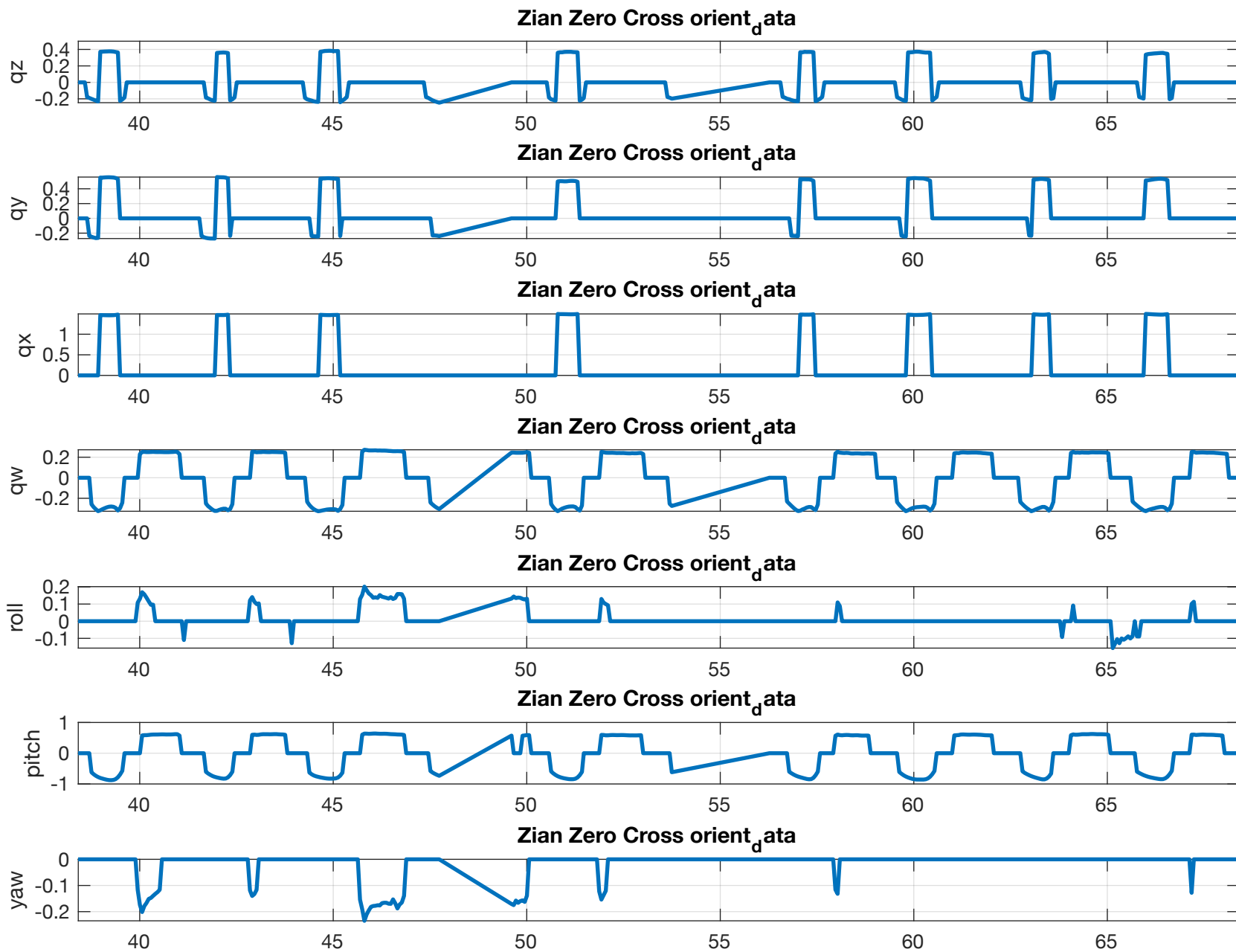
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-306.000	-164.000	-48.000	-34.500	"gyro_data"
'Y'	-413.000	-377.000	-122.000	-98.000	"gyro_data"
'X'	-209.000	-129.000	-48.000	-25.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-164.000	-115.000	-43.000	-36.750	"grav_data"
'Y'	-94.000	-26.000	-25.000	-21.000	"grav_data"
'X'	-209.000	-116.000	-51.000	-33.250	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-175.000	-157.000	-52.000	-35.500	"orient_data"
'qy'	-171.000	-56.000	-31.000	-21.000	"orient_data"
'qx'	-160.000	-50.000	-27.000	-11.500	"orient_data"
'qw'	-126.000	-103.000	-37.000	-25.500	"orient_data"
'roll'	-300.000	-164.000	-61.000	-20.250	"orient_data"
'pitch'	-89.000	-88.000	-24.000	-25.250	"orient_data"
'yaw'	-203.000	-121.000	-48.000	-13.250	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'zero_cross'	88.500
'bar_data'	"Relative Altitude"	'double_findpeaks'	24.000
'gyro_data'	"X"	'zero_cross'	25.000
'grav_data'	"Y"	'zero_cross'	21.000
'orient_data'	"qx"	'zero_cross'	11.500