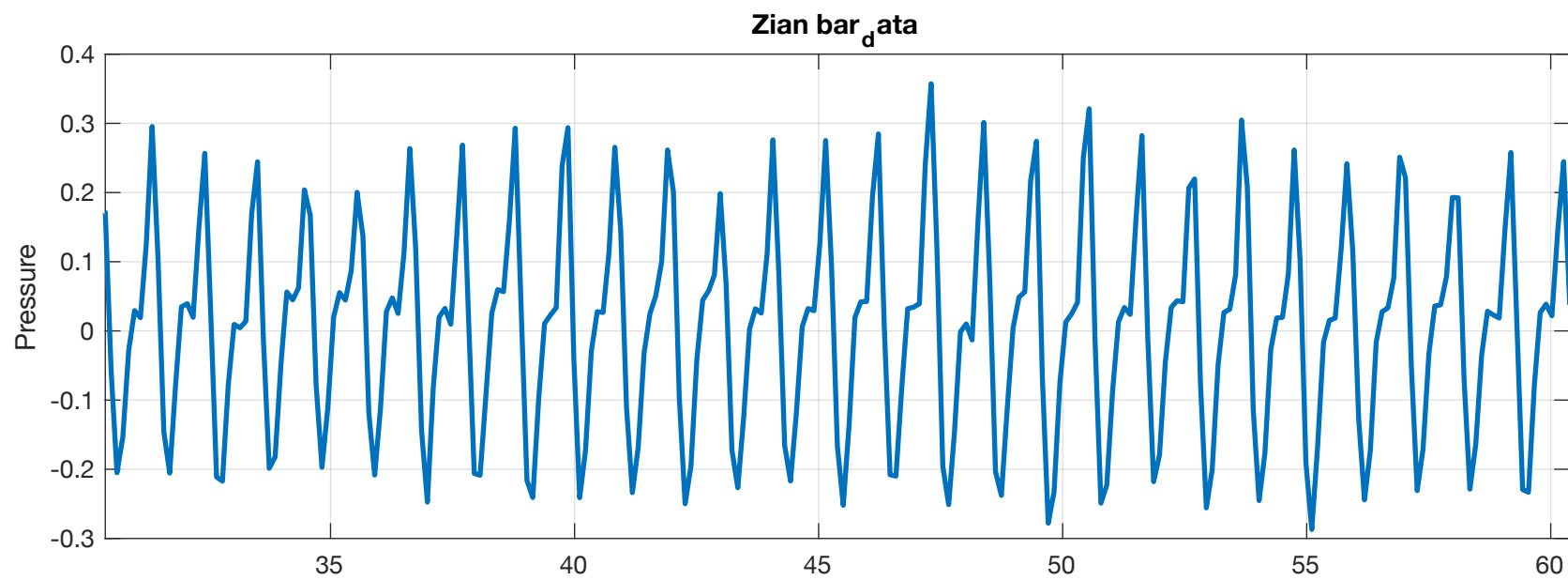
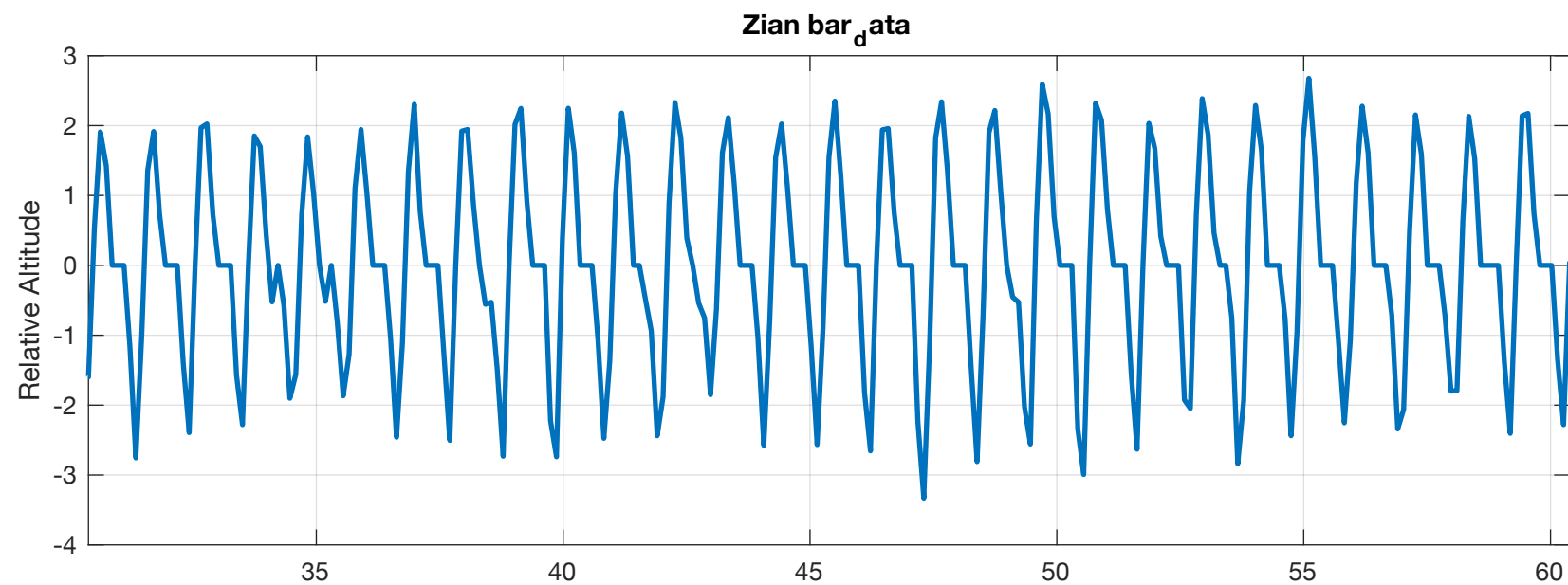
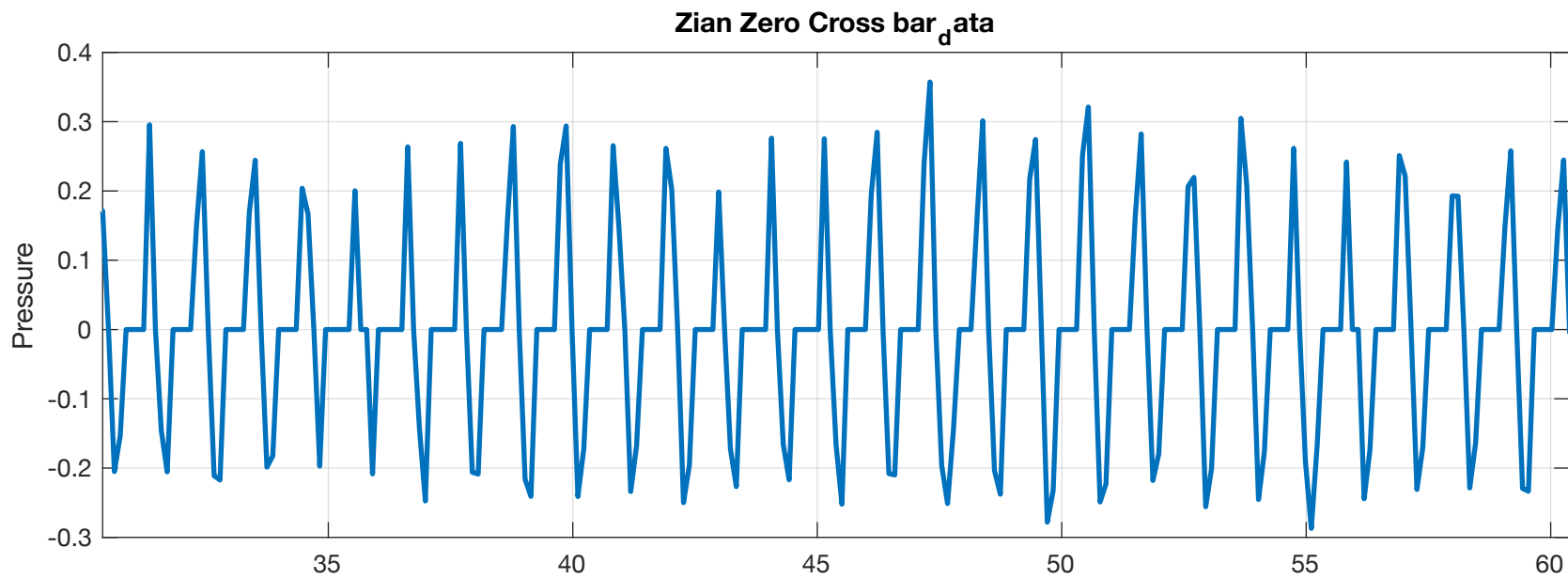
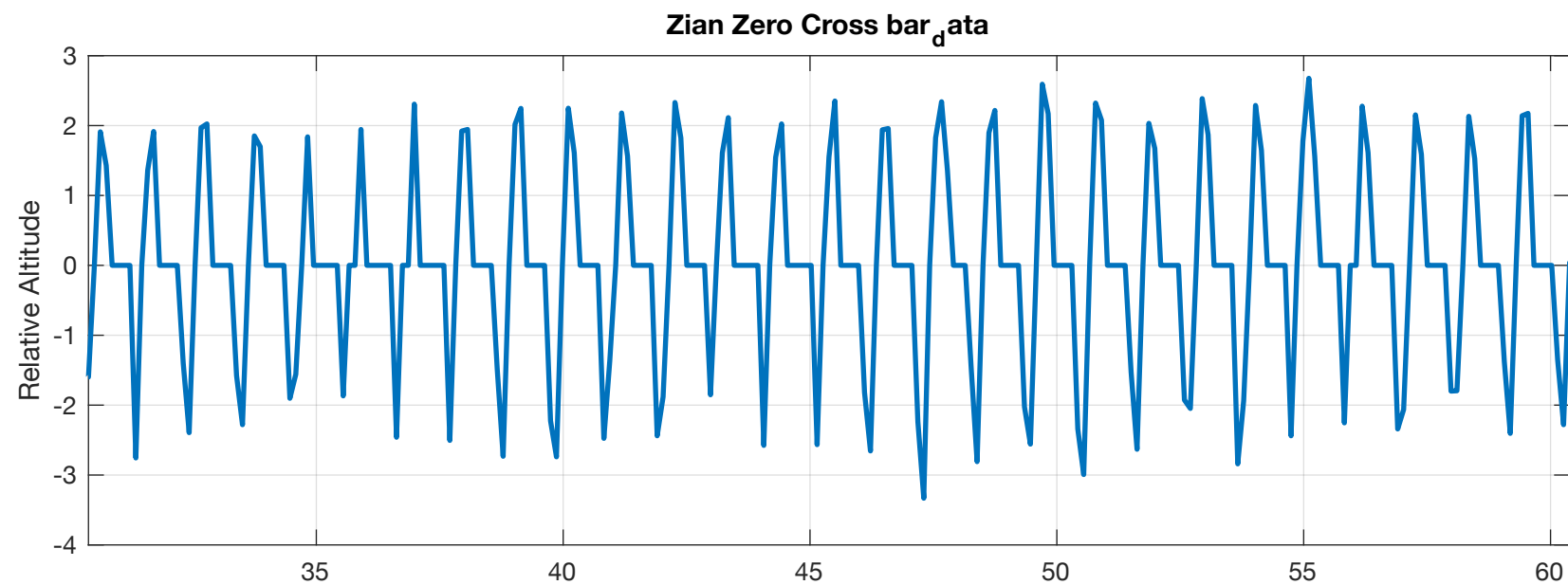
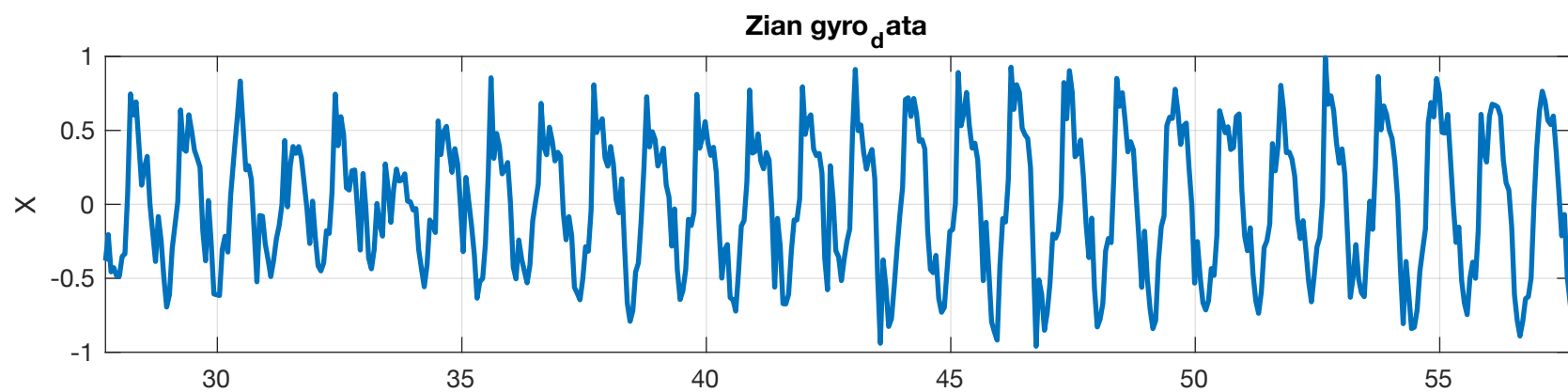
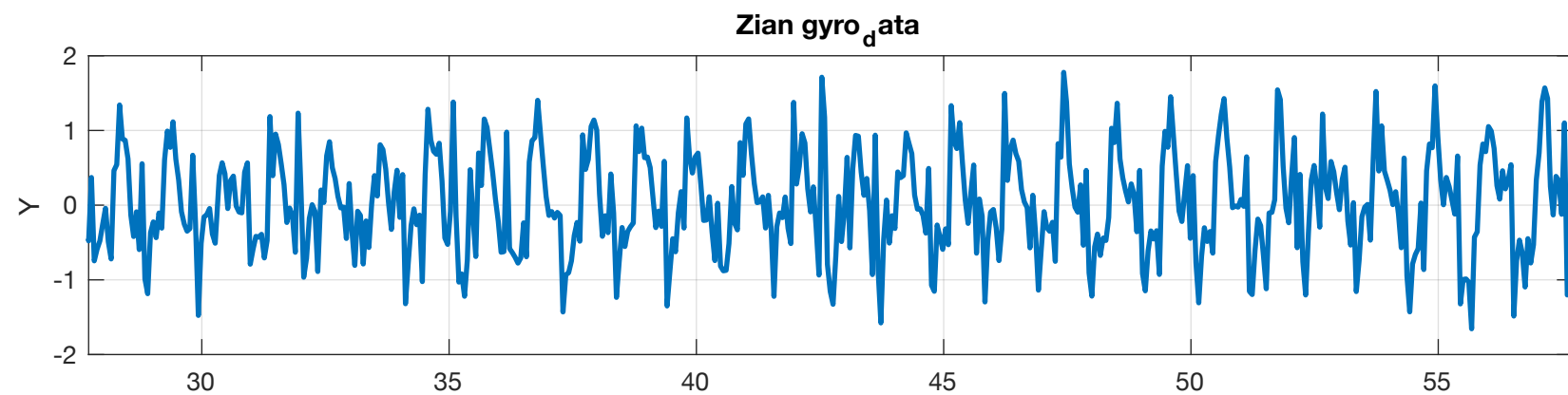
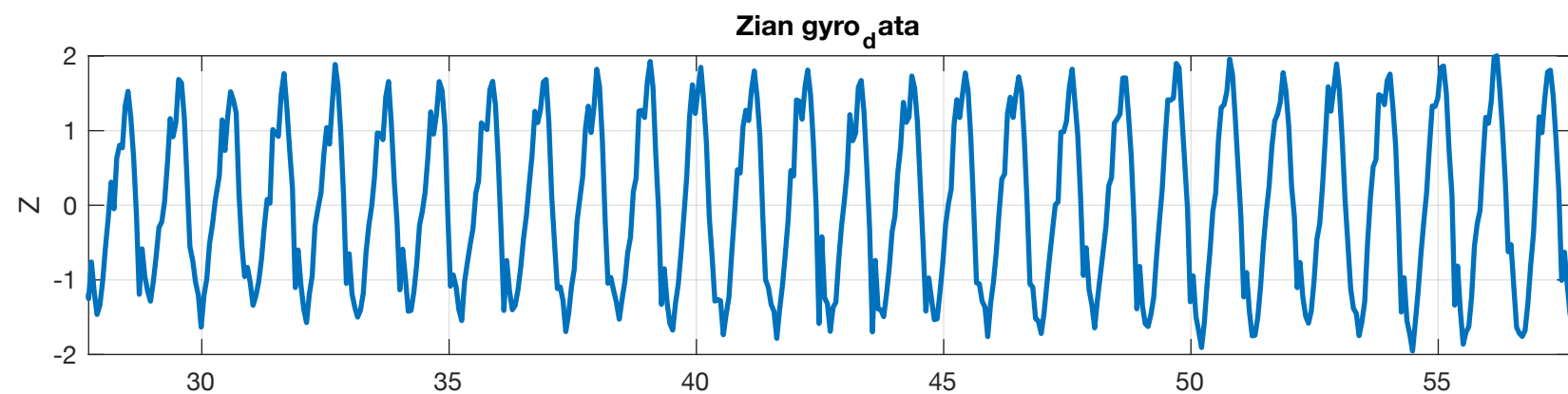


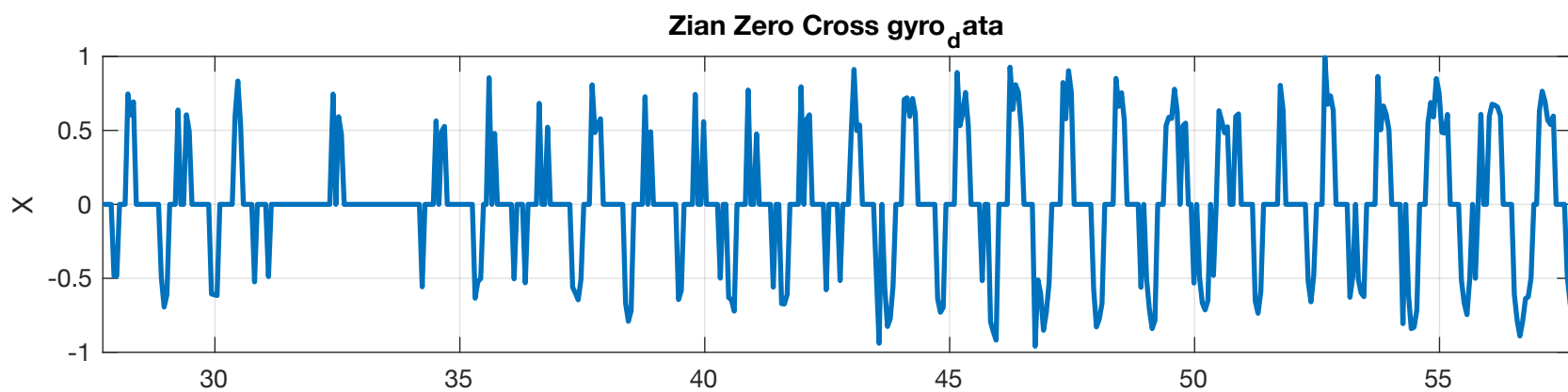
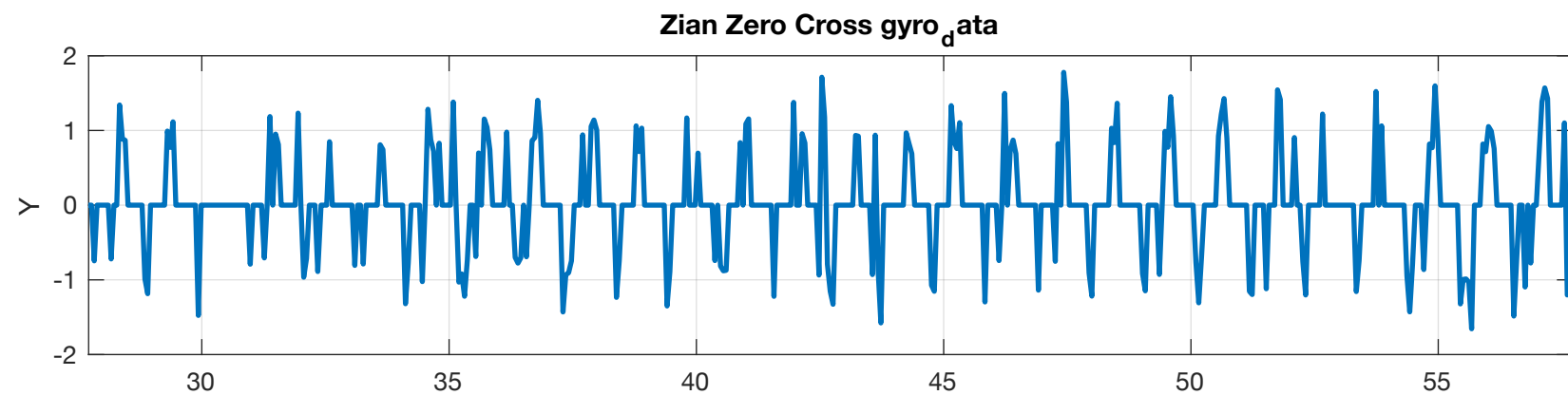
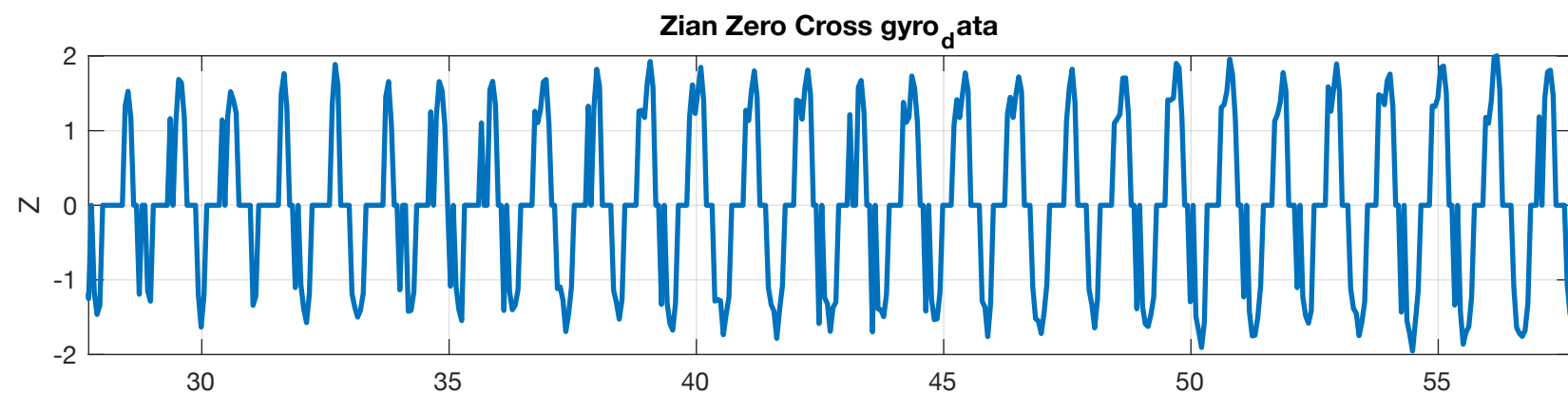
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-299.000	-106.000	20.000	66.500	"accel_data"
'Y'	-127.000	-91.000	70.000	2.000	"accel_data"
'X'	-259.000	-206.000	70.000	14.000	"accel_data"



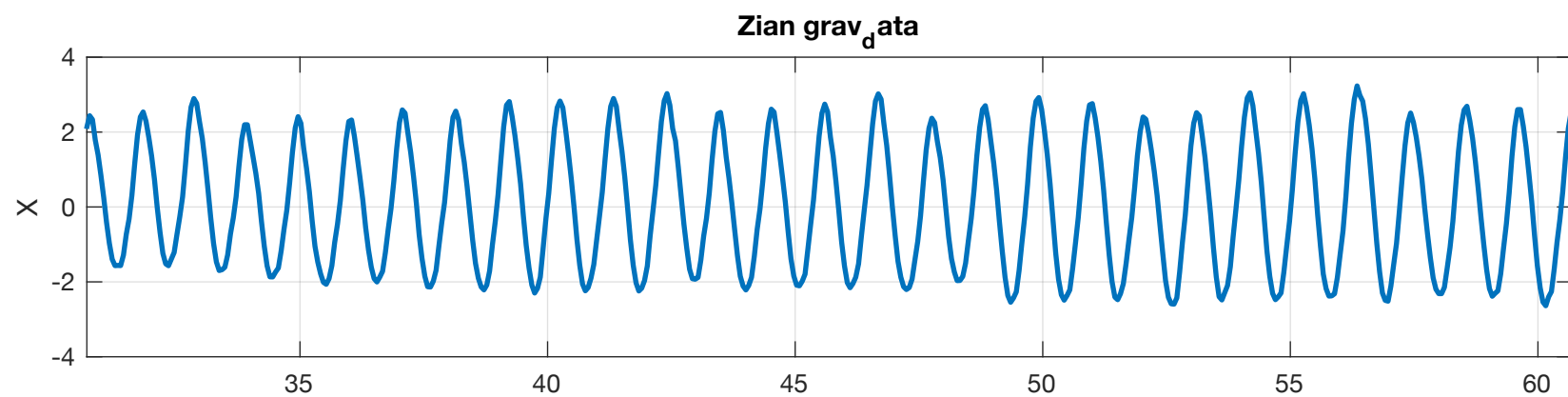
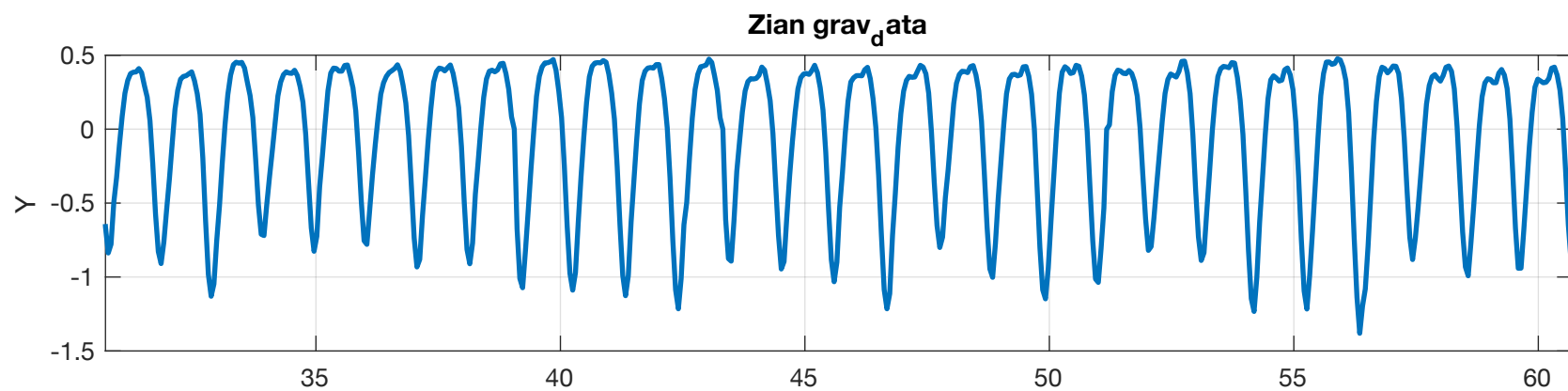
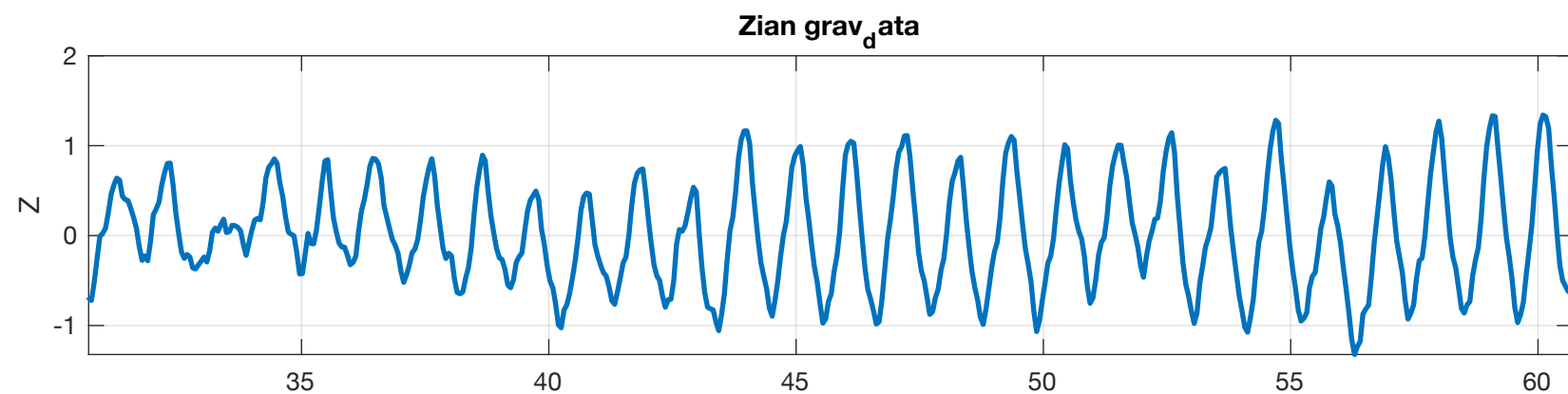


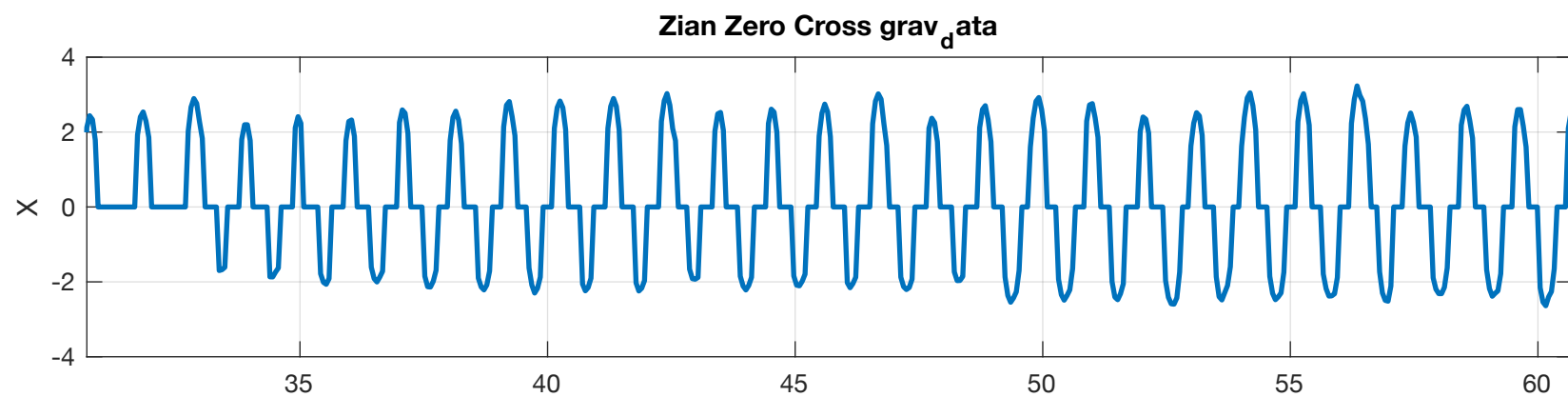
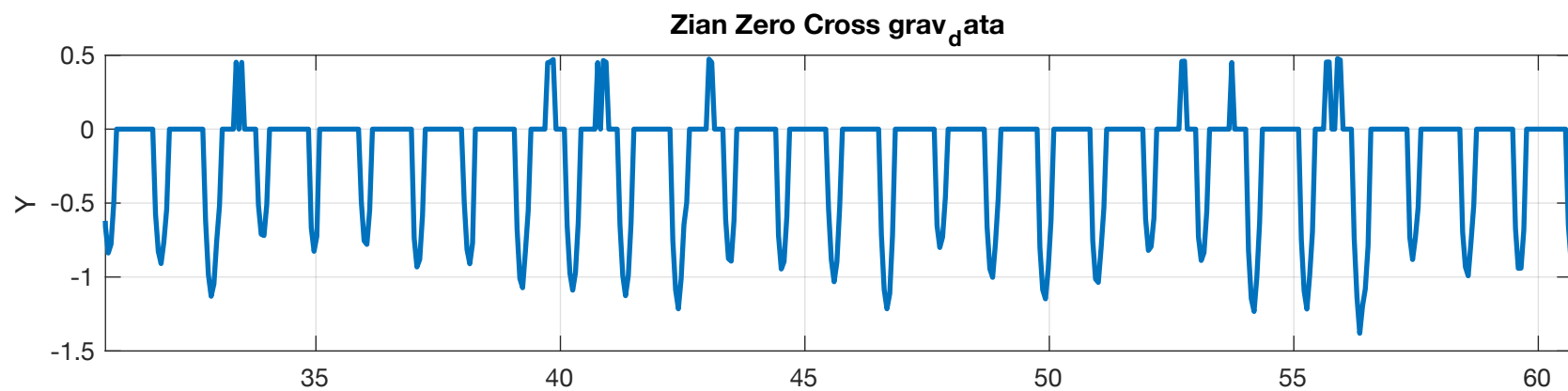
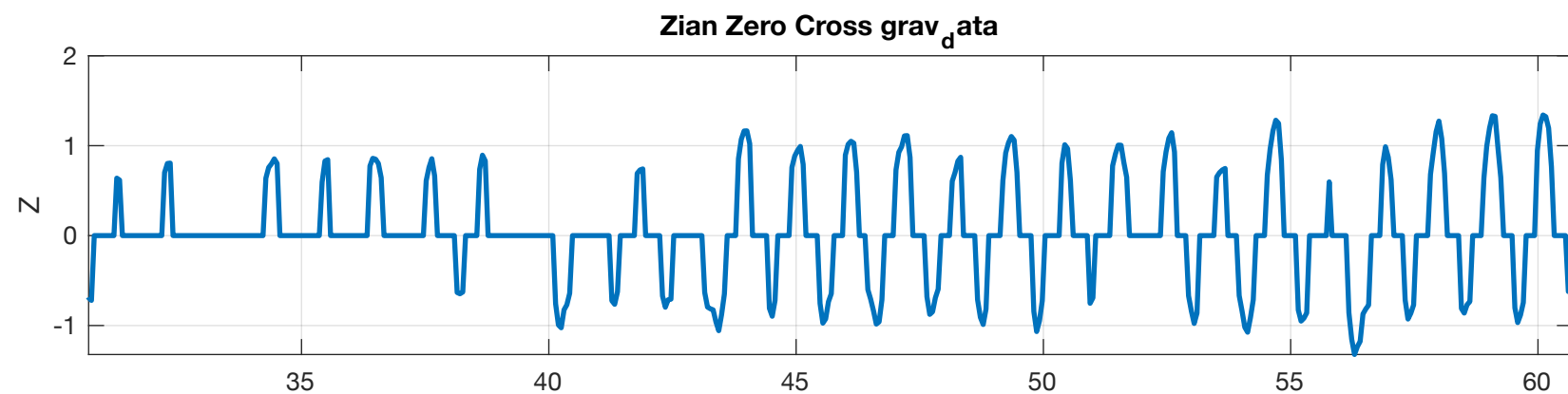
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	80.000	99.000	158.000	101.000	"bar_data"
"Pressure"	26.000	30.000	126.000	101.000	"bar_data"



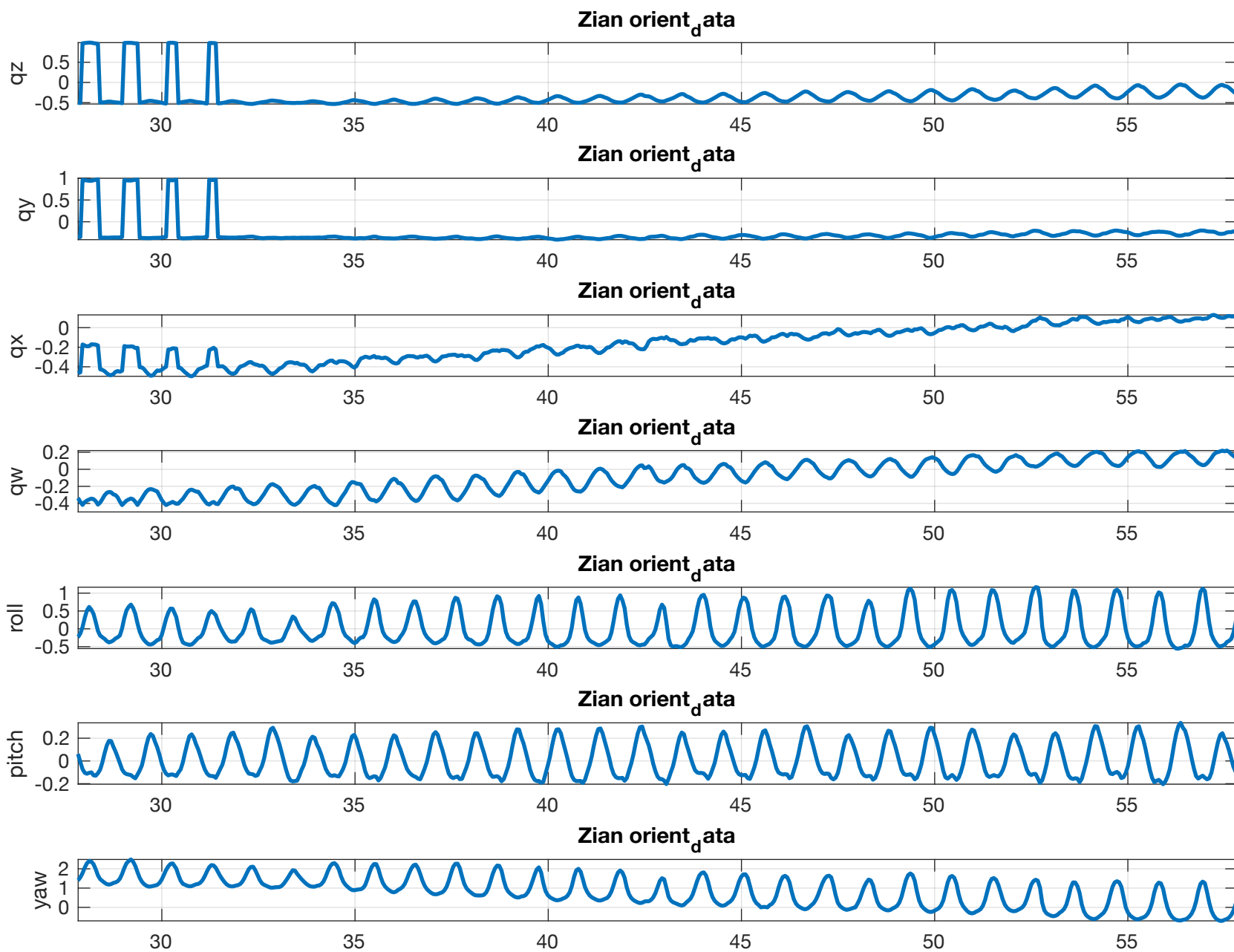


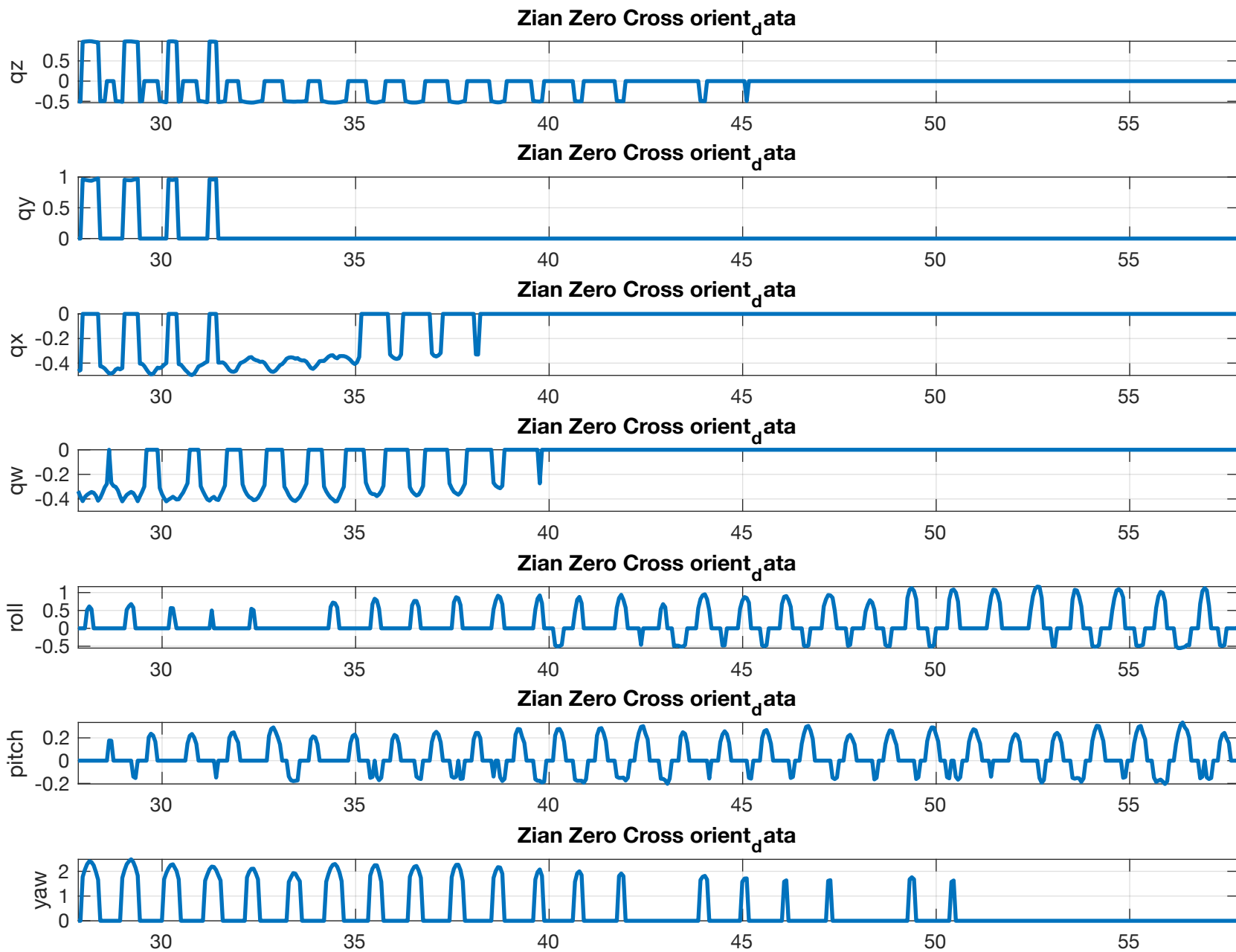
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-76.000	12.000	111.000	70.500	"gyro_data"
'Y'	-264.000	-144.000	61.000	43.000	"gyro_data"
'X'	-166.000	-67.000	106.000	70.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	56.000	88.000	154.000	117.250	"grav_data"
'Y'	32.000	35.000	141.000	137.500	"grav_data"
'X'	94.000	100.000	170.000	106.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	71.000	126.000	159.000	147.750	"orient_data"
'qy'	-26.000	61.000	151.000	184.250	"orient_data"
'qx'	-28.000	107.000	172.000	180.000	"orient_data"
'qw'	48.000	120.000	180.000	168.000	"orient_data"
'roll'	94.000	107.000	166.000	134.500	"orient_data"
'pitch'	51.000	109.000	139.000	112.500	"orient_data"
'yaw'	101.000	132.000	182.000	166.250	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Y"	'zero_cross'	2.000
'bar_data'	"Pressure"	'findpeaks'	26.000
'gyro_data'	"Z"	'findpeaks_above_zero'	12.000
'grav_data'	"Y"	'findpeaks'	32.000
'orient_data'	"qy"	'findpeaks'	26.000