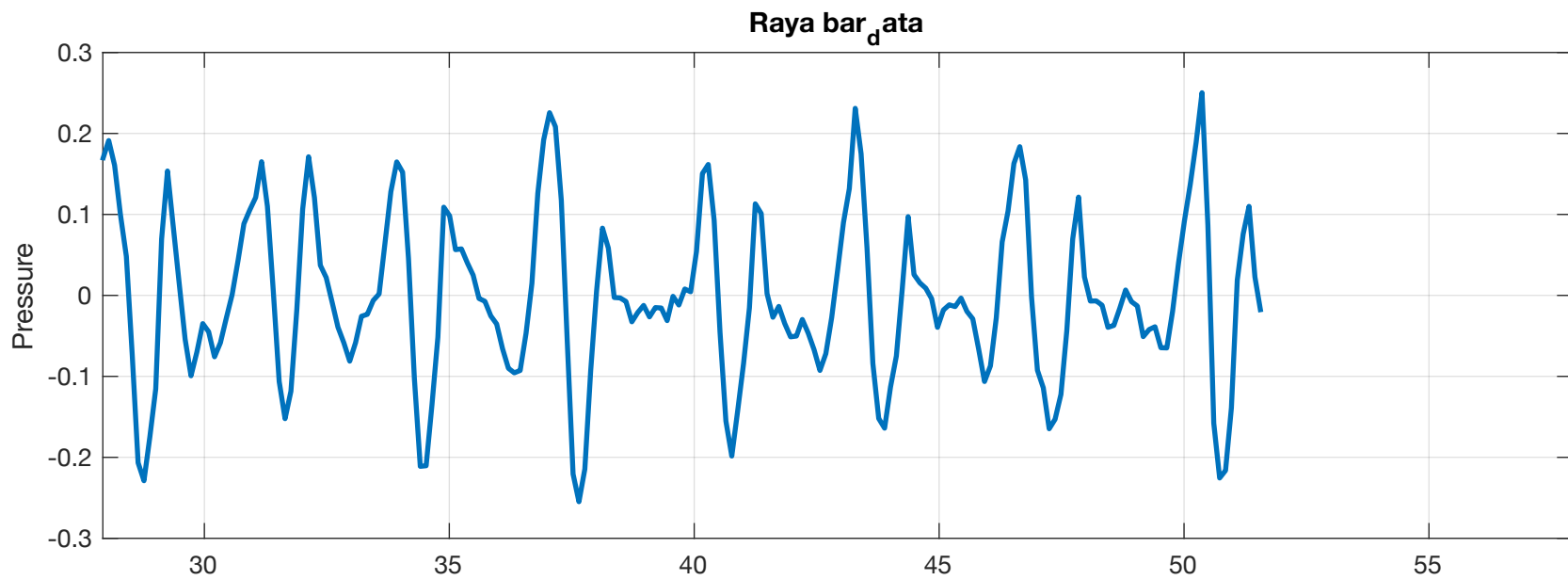
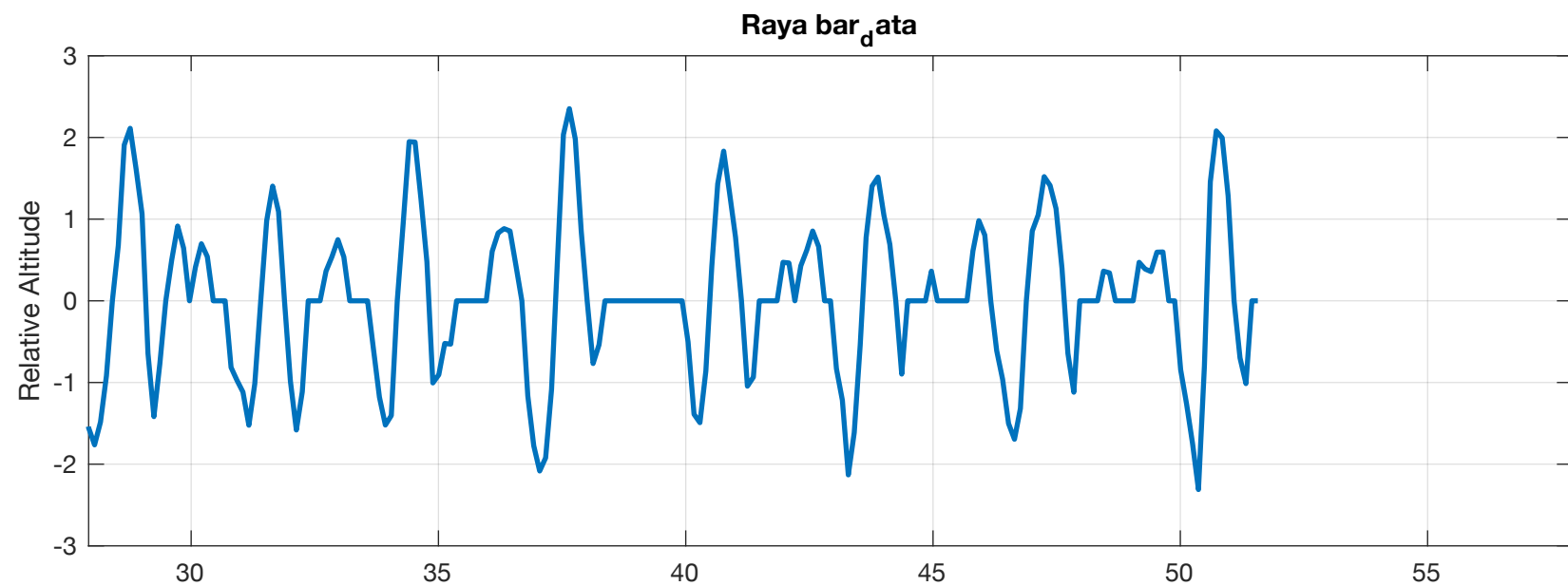
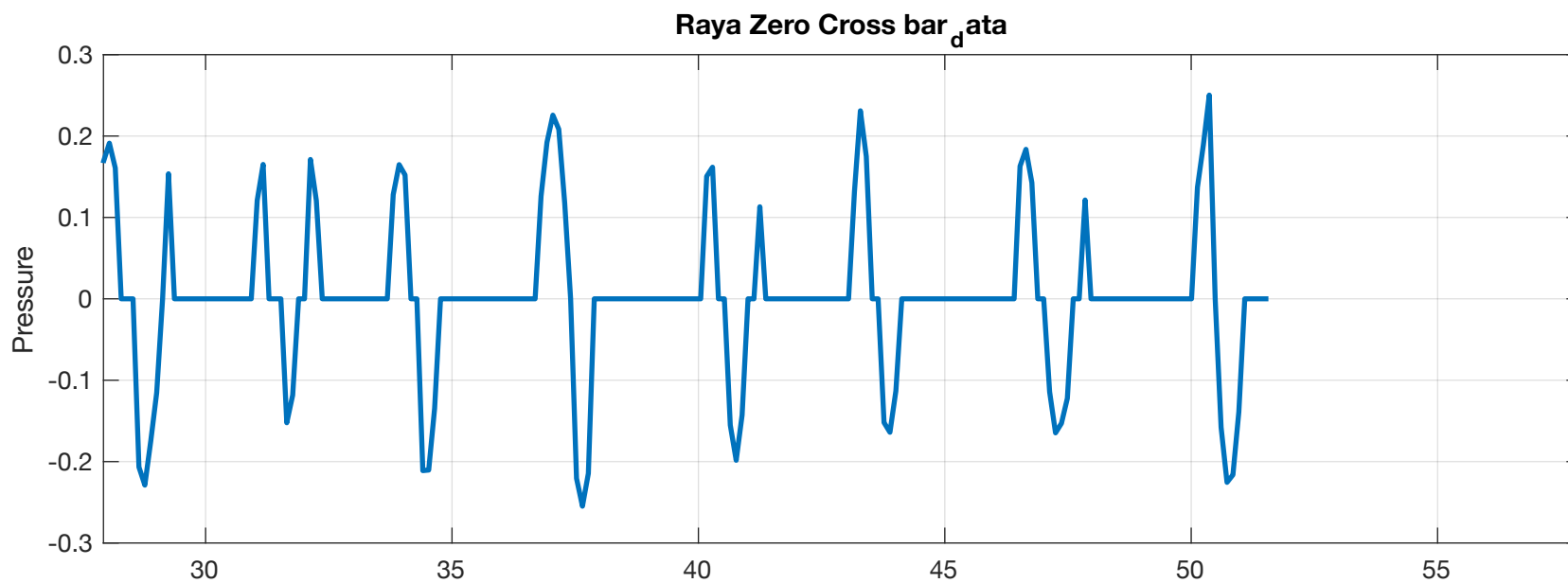
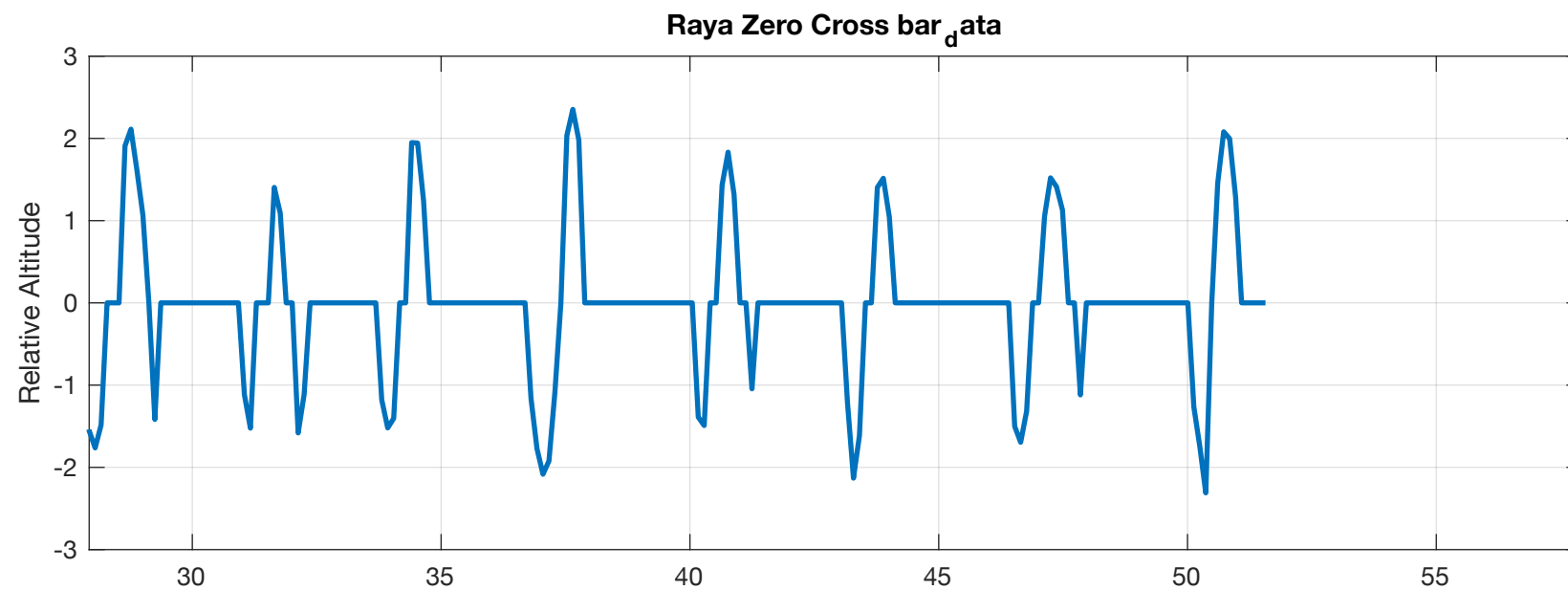
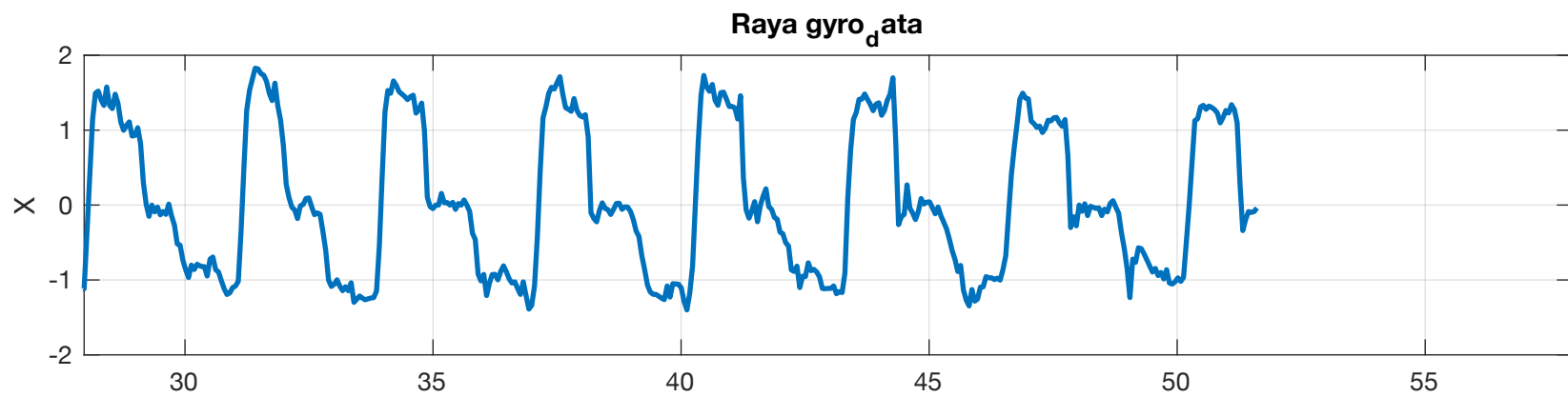
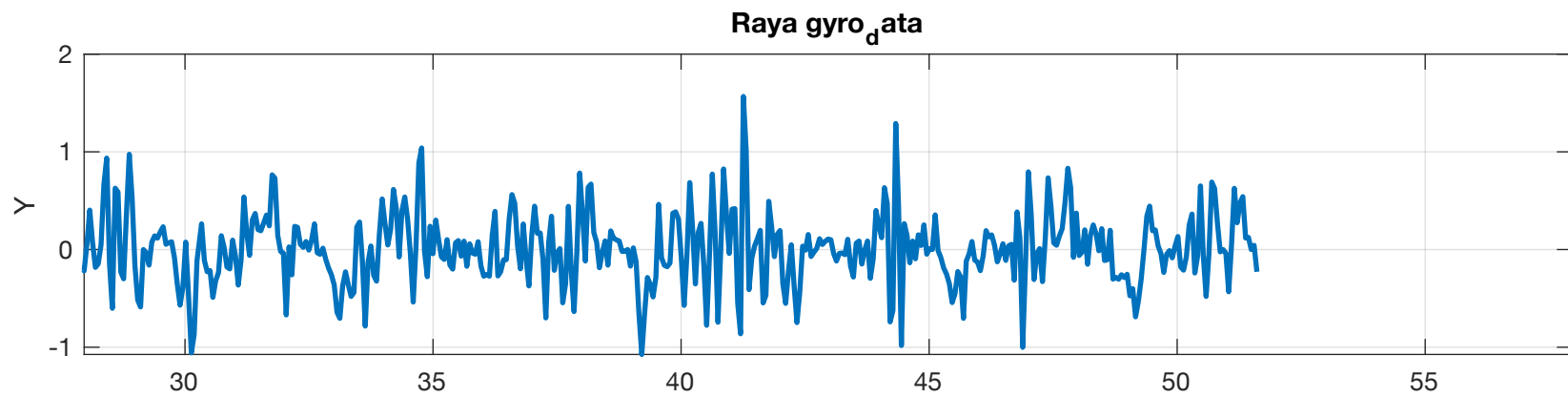
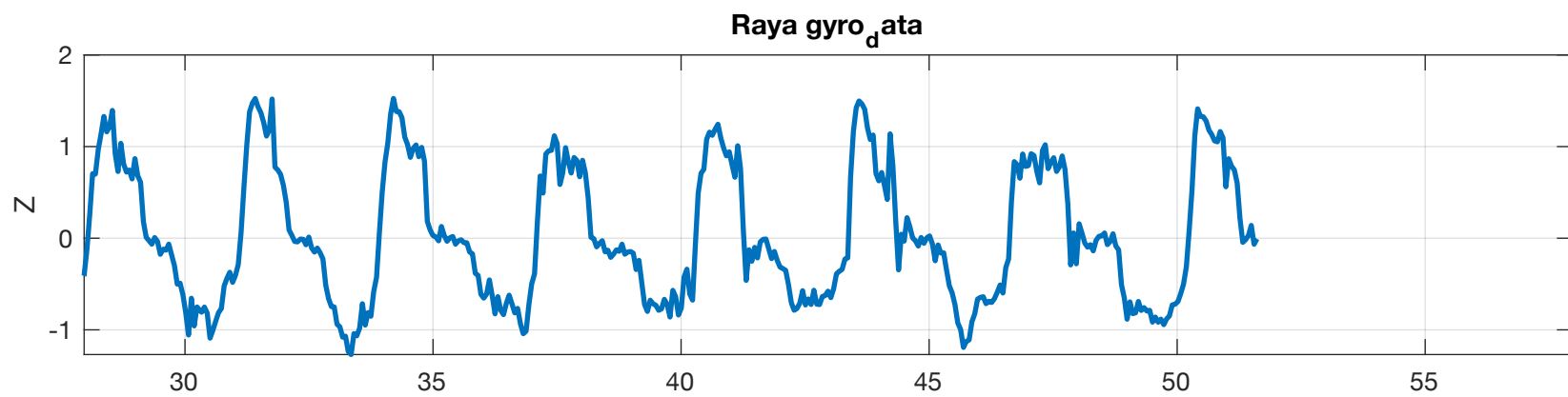


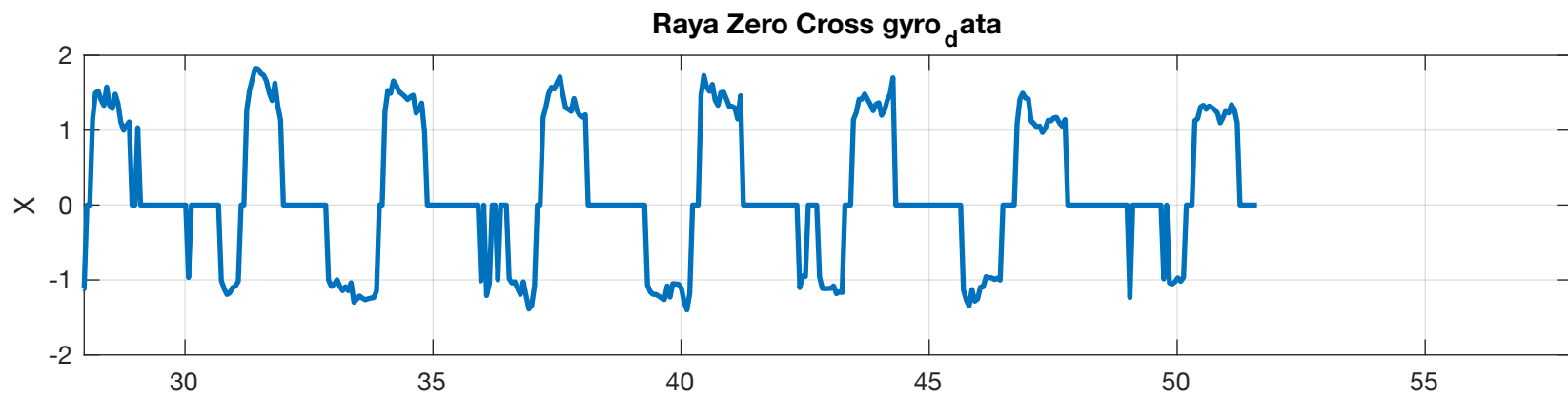
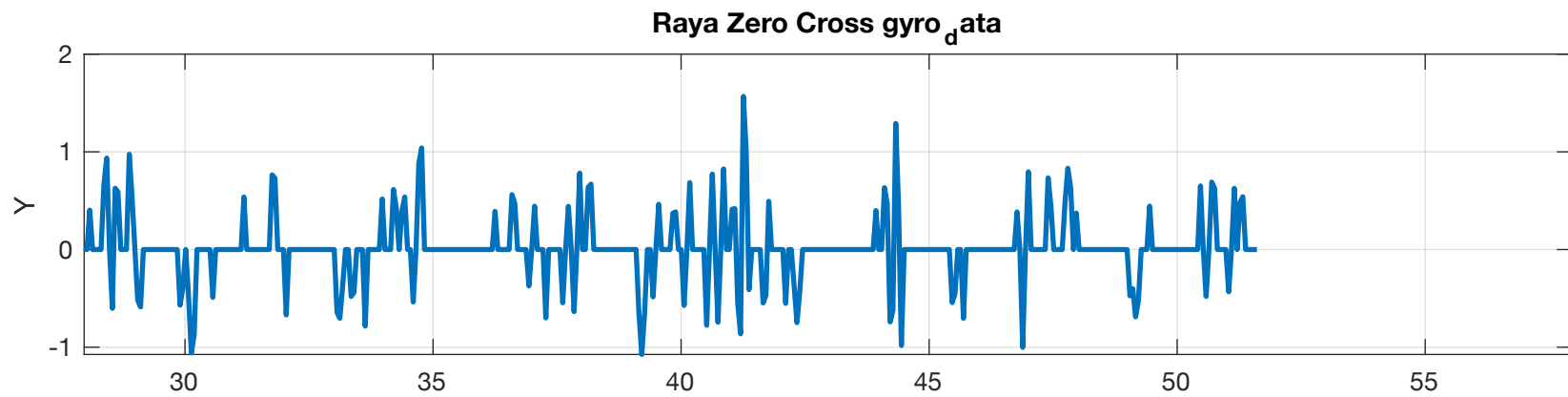
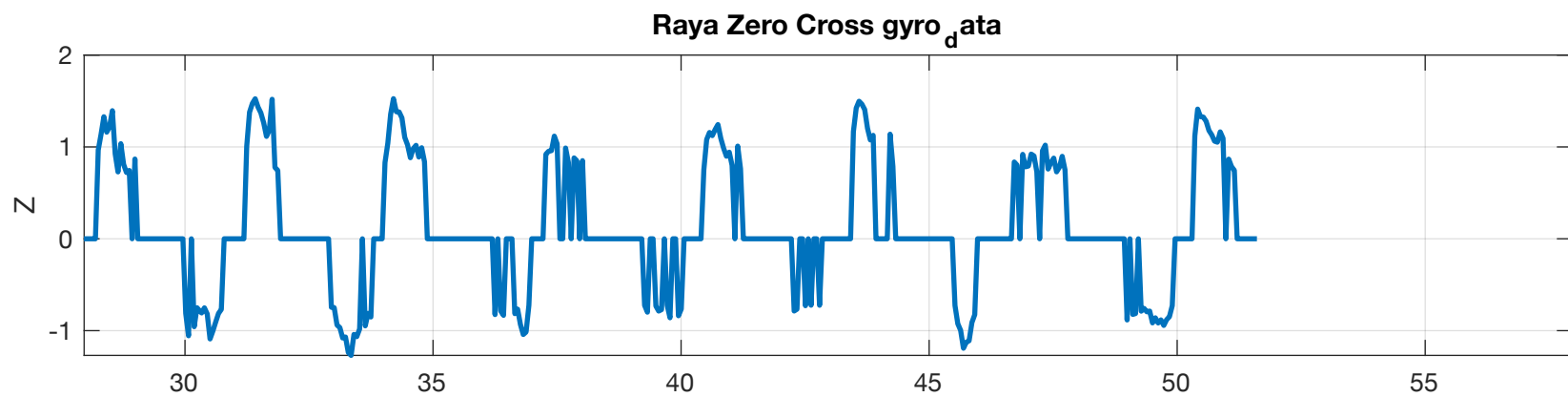
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-155	-132	-44	-29.5000	"accel_data"
'Y'	-147	-113	-36	-32.5000	"accel_data"
'X'	-147	-119	-39	-40.5000	"accel_data"



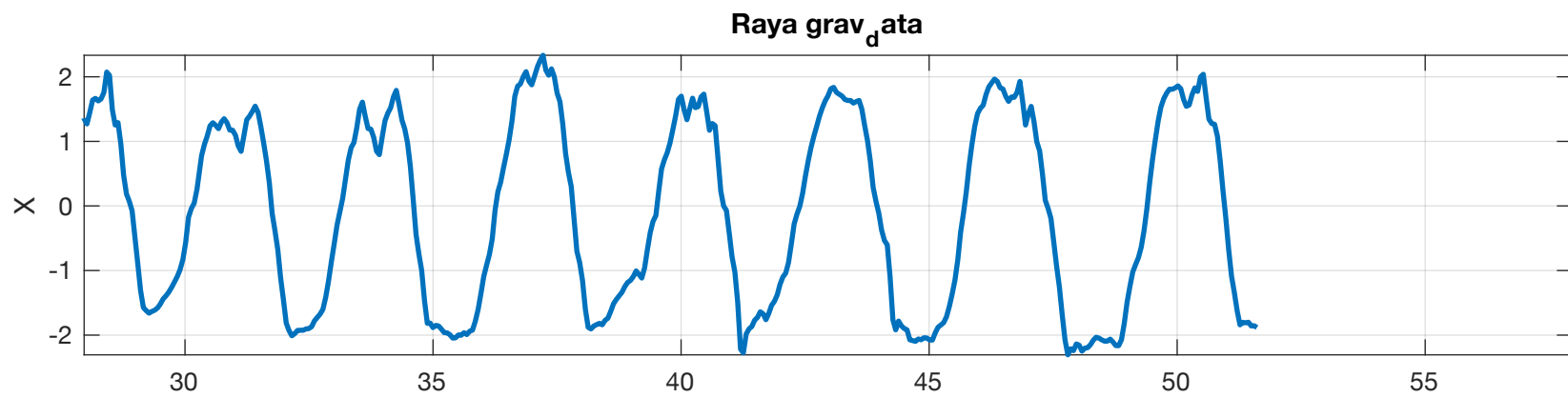
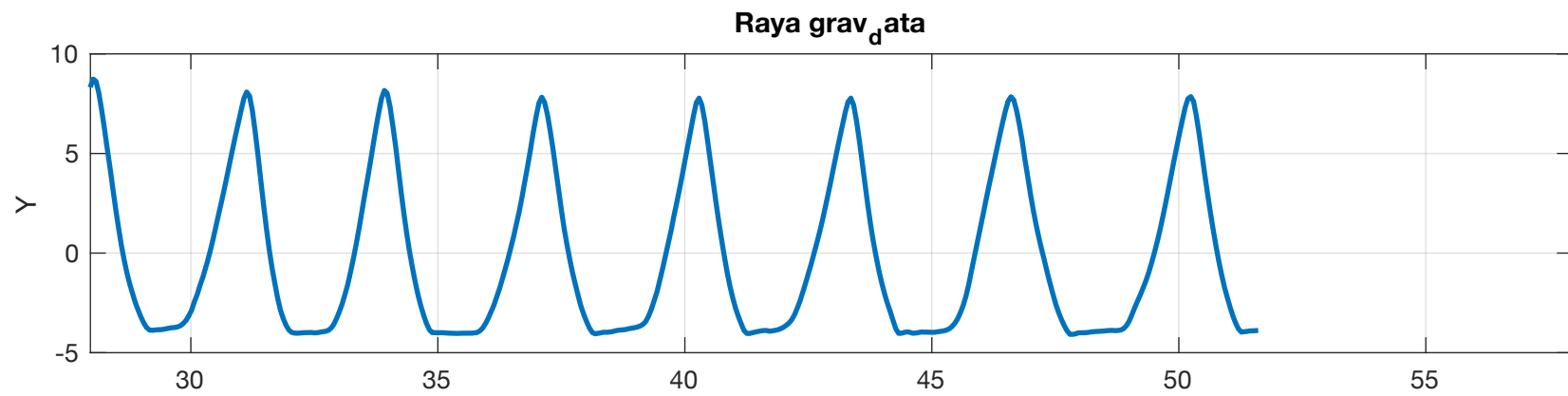
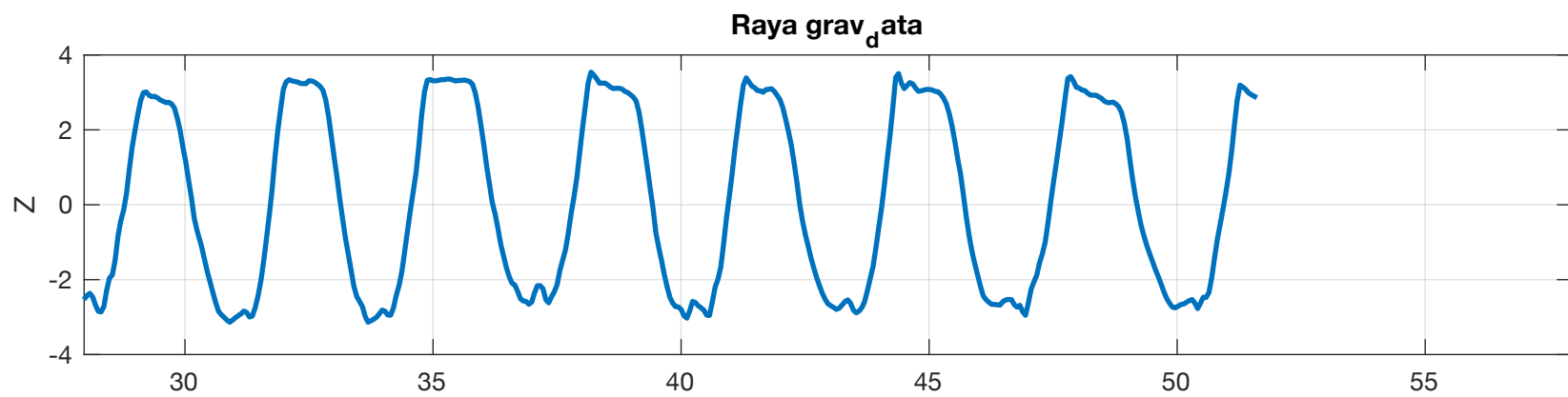


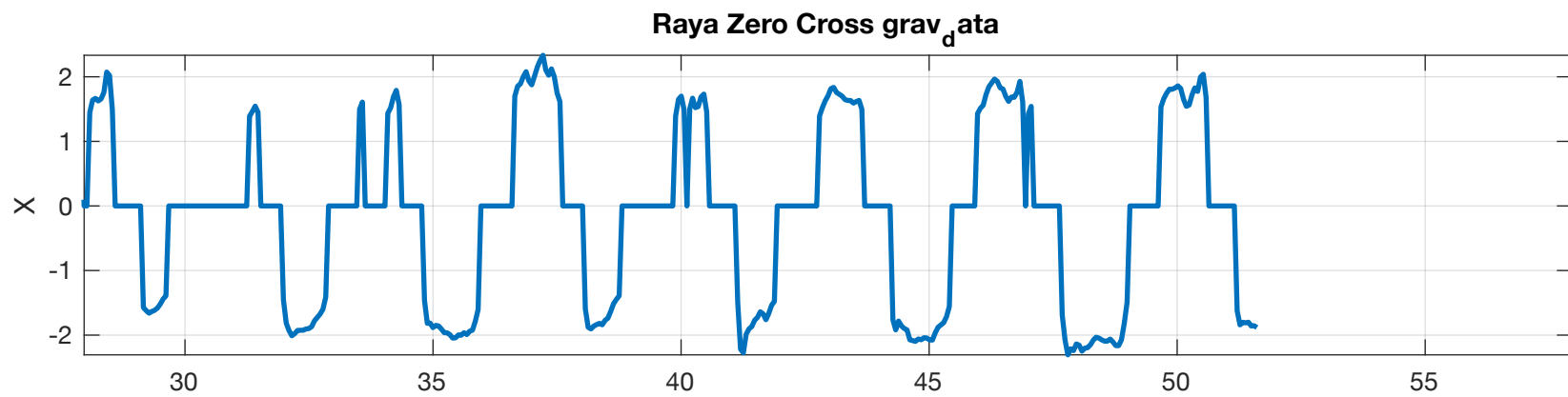
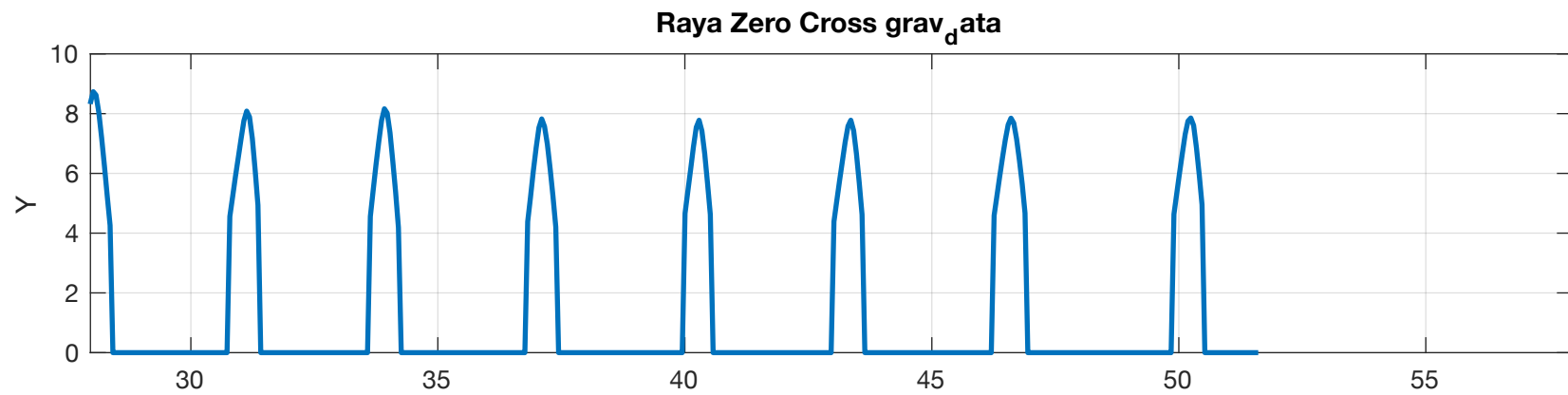
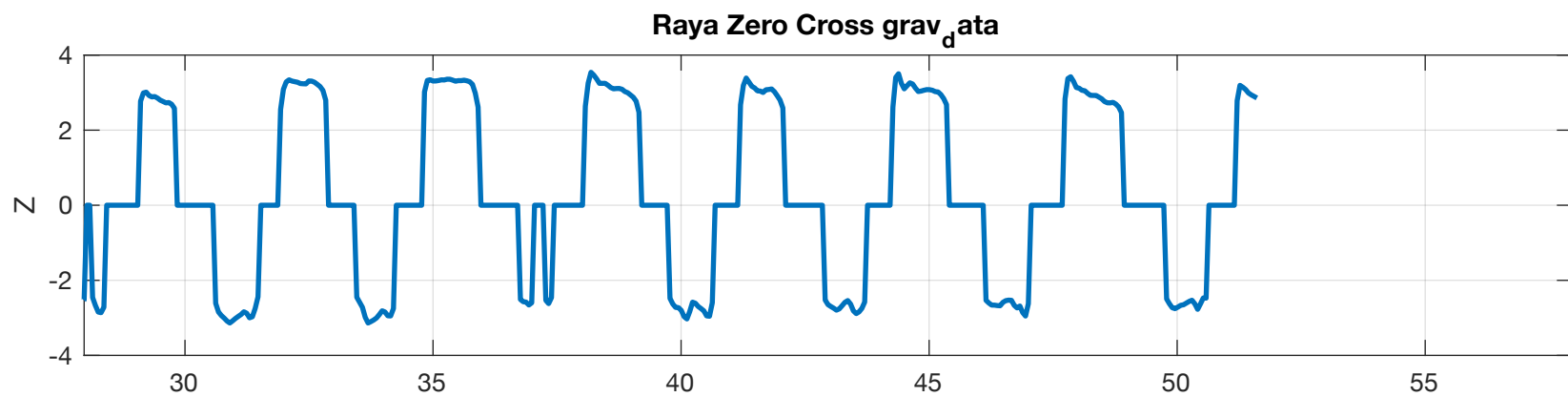
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-17	-14	1	-2.5000	"bar_data"
"Pressure"	-25	-14	1	-2.5000	"bar_data"



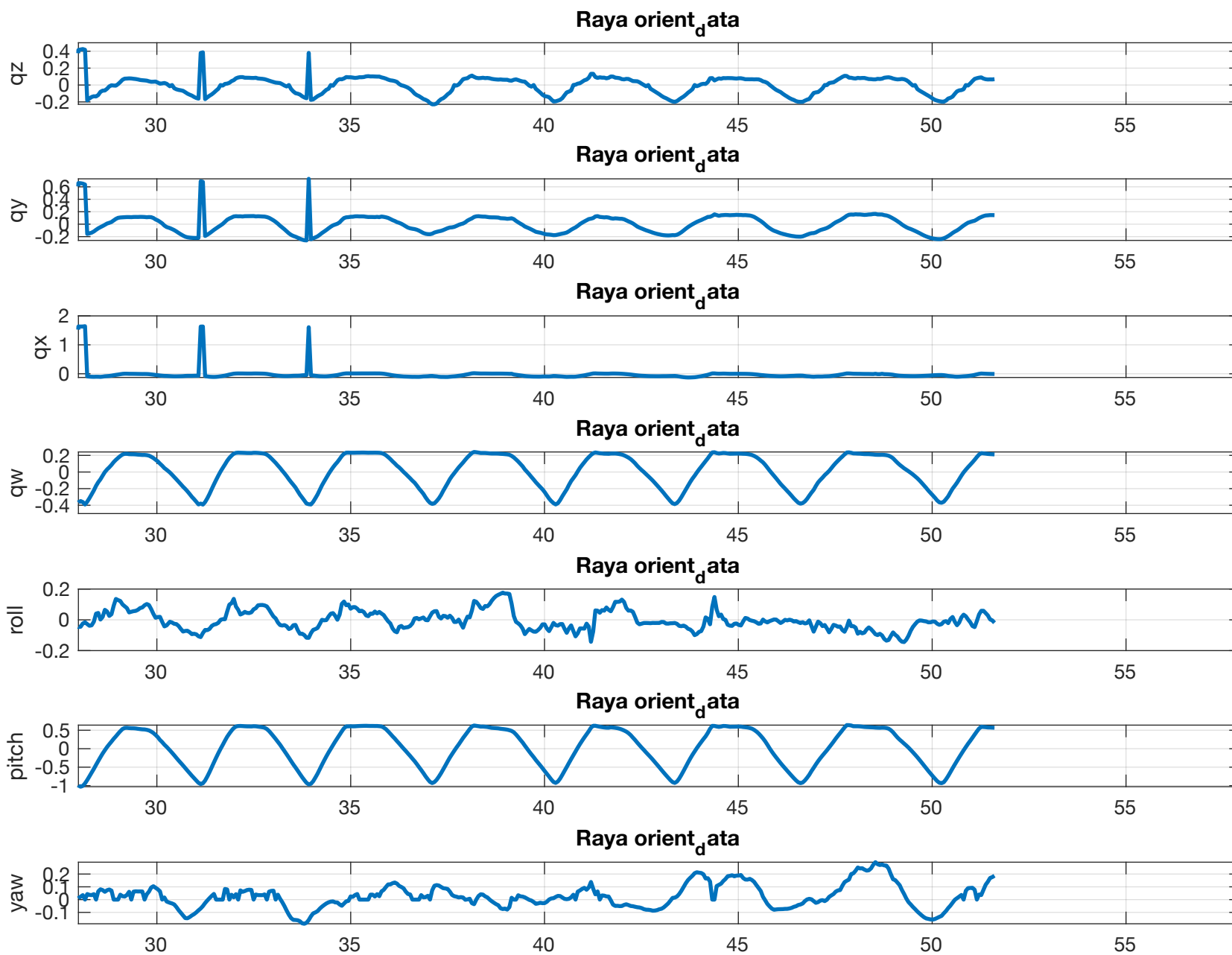


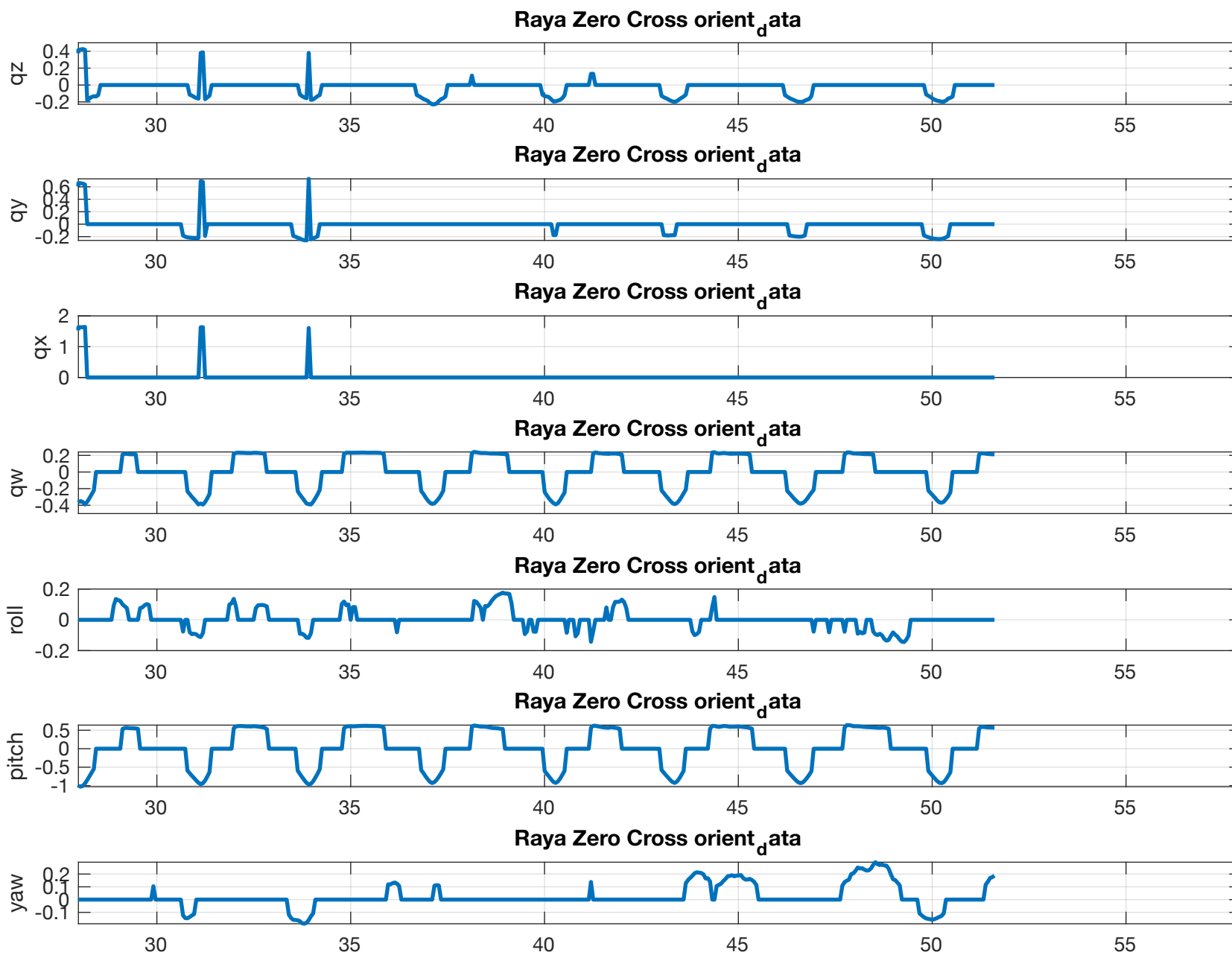
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-113	-48	-11	-12.5000	"gyro_data"
'Y'	-135	-114	-36	-32.5000	"gyro_data"
'X'	-109	-51	-11	-4.5000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-26	-15	-1	-1.2500	"grav_data"
'Y'	-10	0	4	5	"grav_data"
'X'	-40	-22	-3	-2.2500	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-56	-41	-9	-1	"orient_data"
'qy'	-35	-34	-4	1	"orient_data"
'qx'	-32	-14	-1	7.5000	"orient_data"
'qw'	-16	-12	1	0.2500	"orient_data"
'roll'	-89	-46	-8	-6	"orient_data"
'pitch'	-11	-11	3	0.2500	"orient_data"
'yaw'	-65	-48	-10	3.7500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'zero_cross'	29.5
'bar_data'	"Relative Altitude"	'double_findpeaks'	1
'gyro_data'	"X"	'zero_cross'	4.5
'grav_data'	"Y"	'findpeaks_above_zero'	0
'orient_data'	"qw"	'zero_cross'	0.25