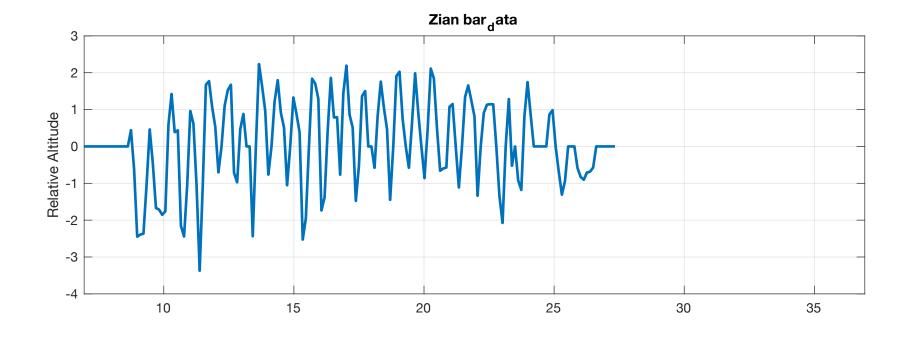
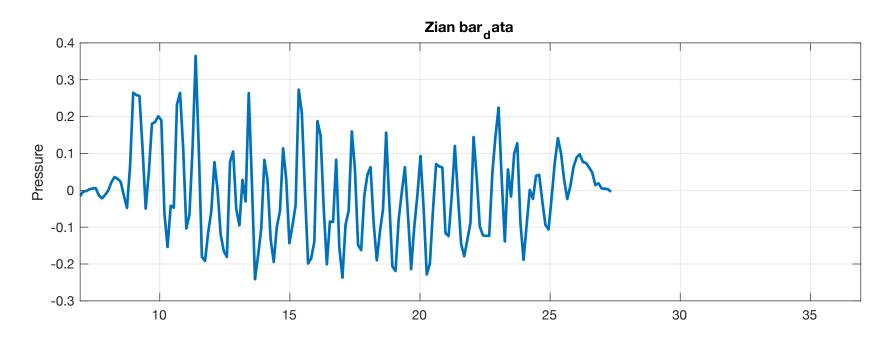
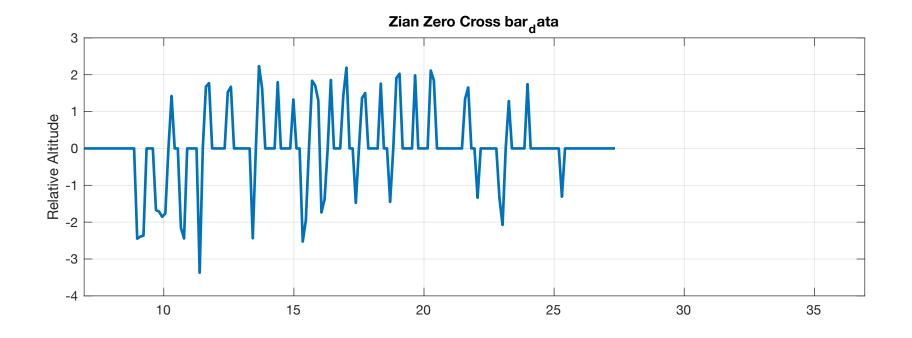
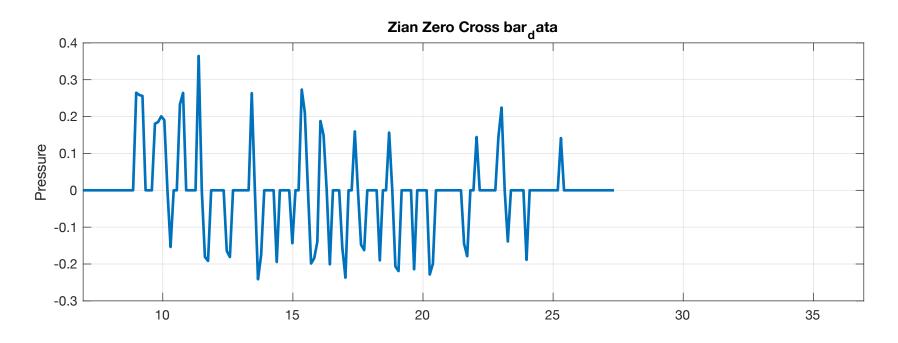


'Y' -132.000 -50.000 -7.000 -4.000 "accel_data	Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
<del>-</del>	'Z'	-158.000	-142.000	-24.000	3.000	"accel_data"
'Y' 166,000 114,000 17,000 0,500 "accol data	'Υ'	-132.000	-50.000	-7.000	-4.000	"accel_data"
7 -100.000 -114.000 -17.000 -9.500 accel_data	'X'	-166.000	-114.000	-17.000	-9.500	"accel_data"

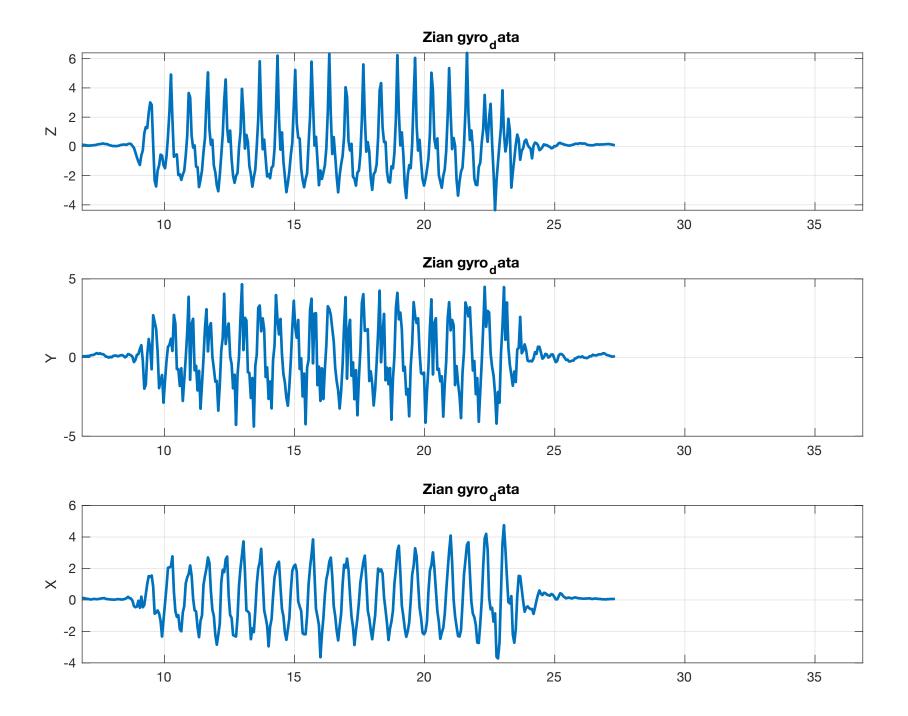


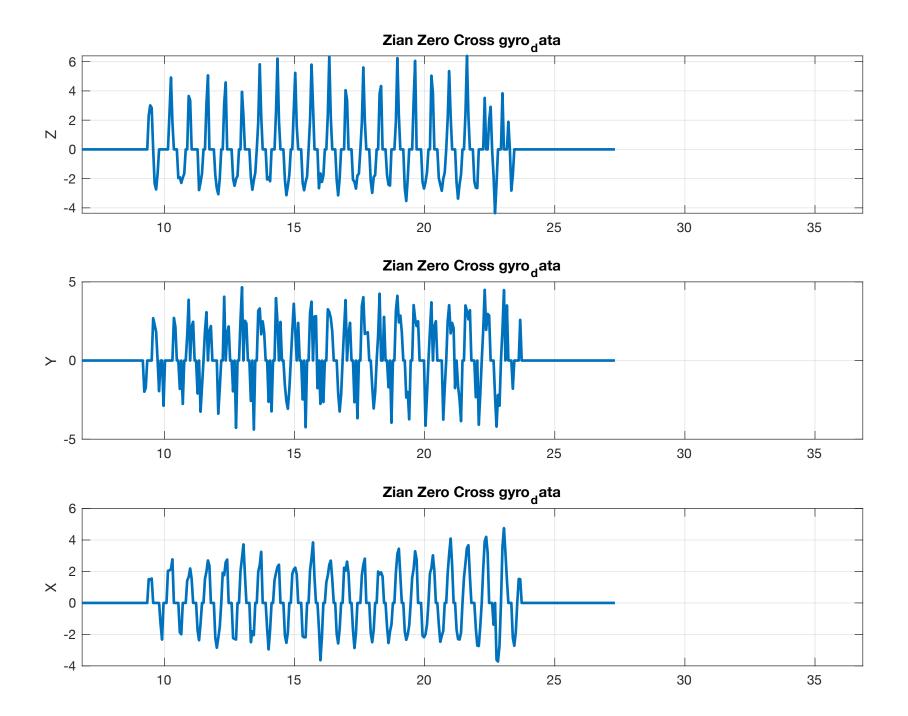




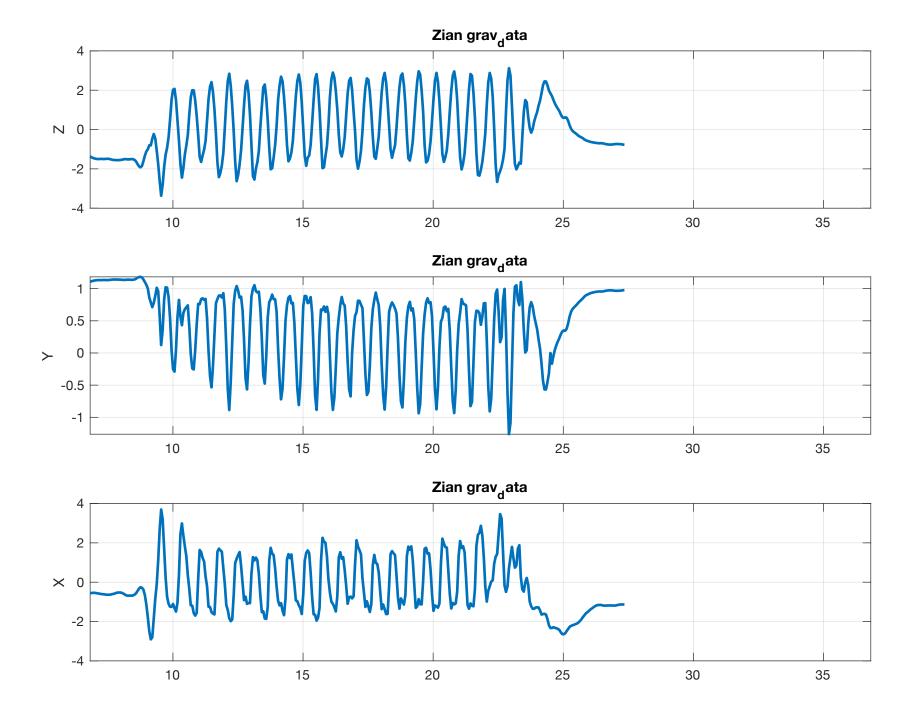


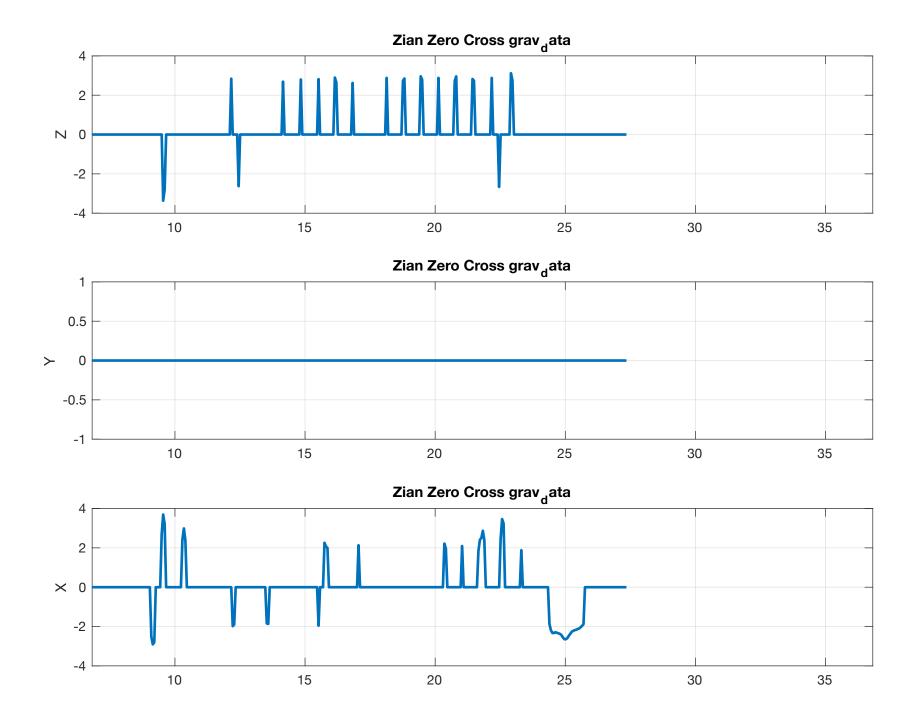
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	5.000	9.000	29.000	23.500	"bar_data"
"Pressure"	-2.000	2.000	26.000	23.500	"bar_data"



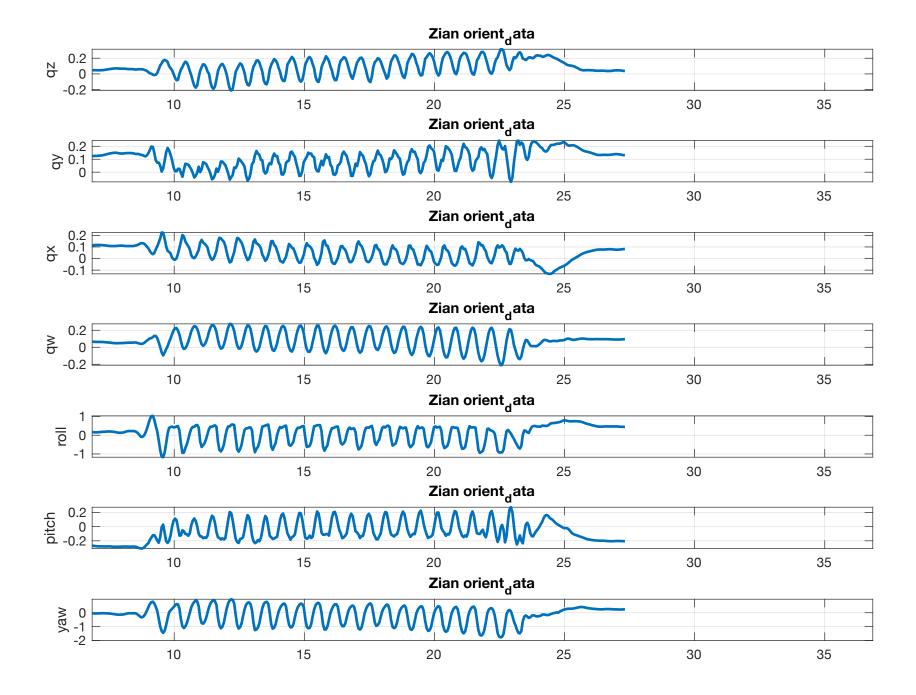


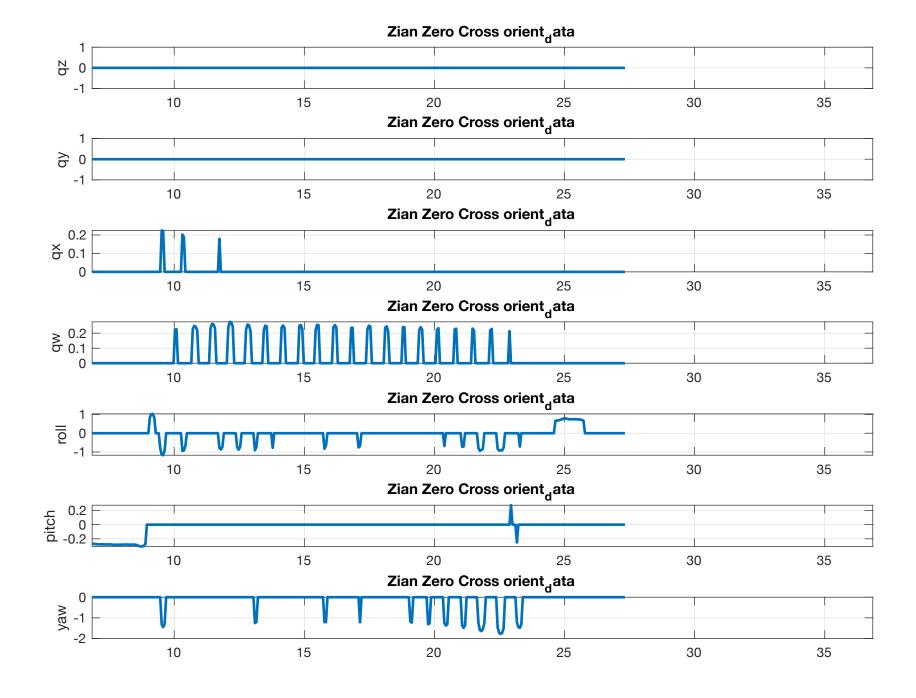
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-45.000	-34.000	11.000	17.500	"gyro_data"
'Υ'	-77.000	-42.000	8.000	5.000	"gyro_data"
'X'	-32.000	-24.000	15.000	17.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-2.000	15.000	31.000	30.500	"grav_data"
'Y'	-18.000	-16.000	24.000	40.000	"grav_data"
'X'	-23.000	5.000	23.000	31.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-12.000	-12.000	25.000	39.000	"orient_data"
'qy'	-21.000	-21.000	18.000	39.000	"orient_data"
'qx'	-1.000	1.000	30.000	37.500	"orient_data"
'qw'	-5.000	-4.000	30.000	29.500	"orient_data"
'roll'	-15.000	-11.000	24.000	31.000	"orient_data"
'pitch'	-14.000	14.000	25.000	37.000	"orient_data"
'yaw'	-4.000	6.000	28.000	33.500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Z"	'zero_cross'	3.000
'bar_data'	"Pressure"	'findpeaks'	2.000
'gyro_data'	"Y"	'zero_cross'	5.000
'grav_data'	"Z"	'findpeaks'	2.000
'orient data'	"qx"	'findpeaks'	1.000