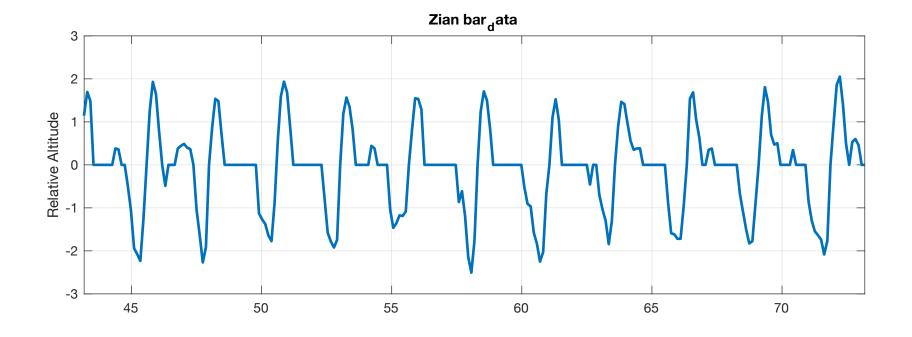
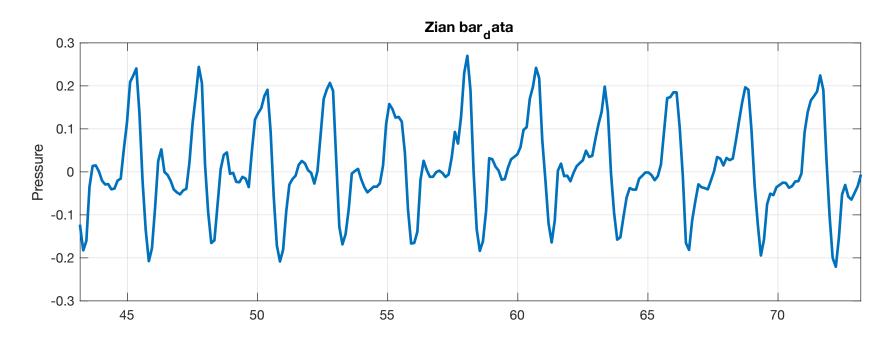
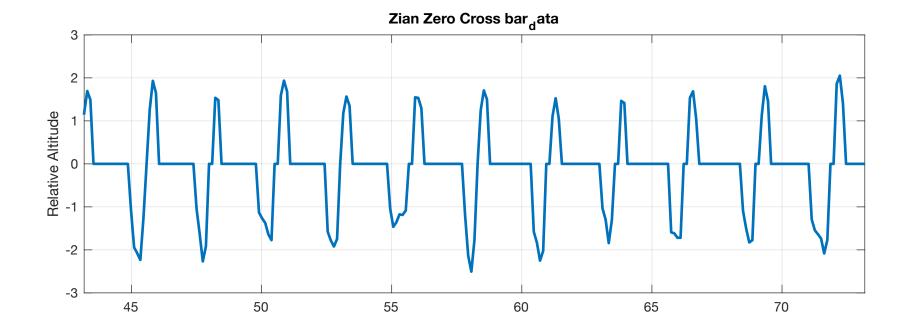
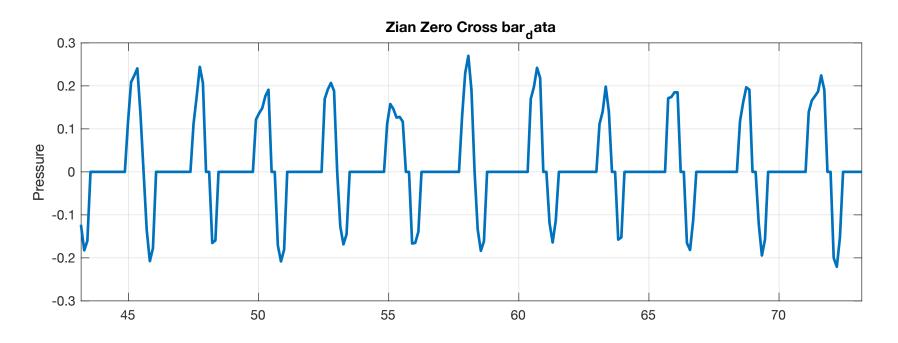


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-466.000	-380.000	-122.000	-89.500	"accel_data"
'Y'	-463.000	-321.000	-105.000	-87.000	"accel_data"
'X'	-490.000	-417.000	-136.000	-112.500	"accel_data"

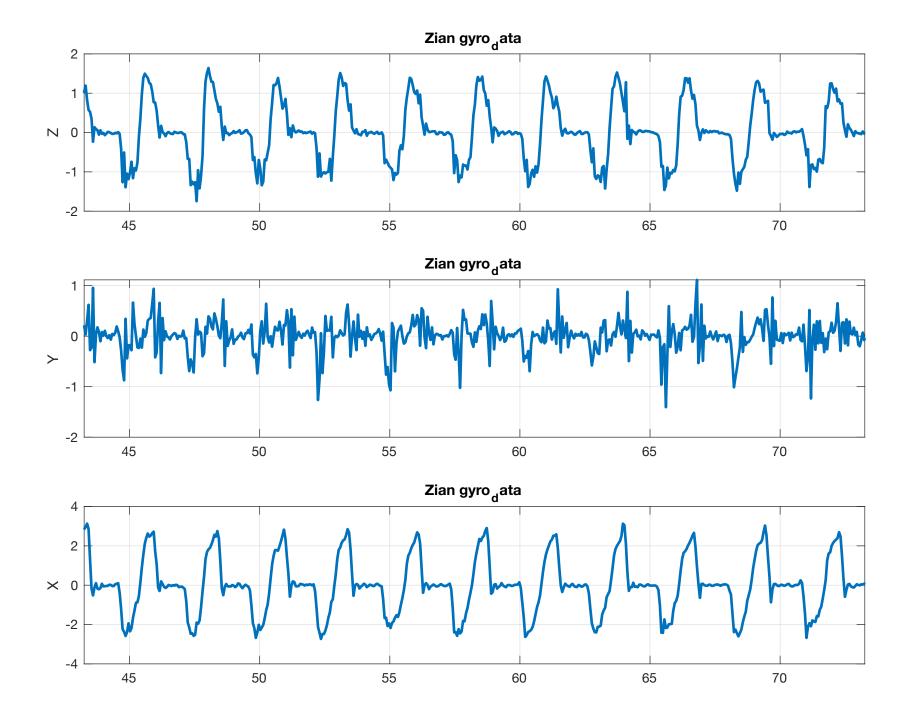


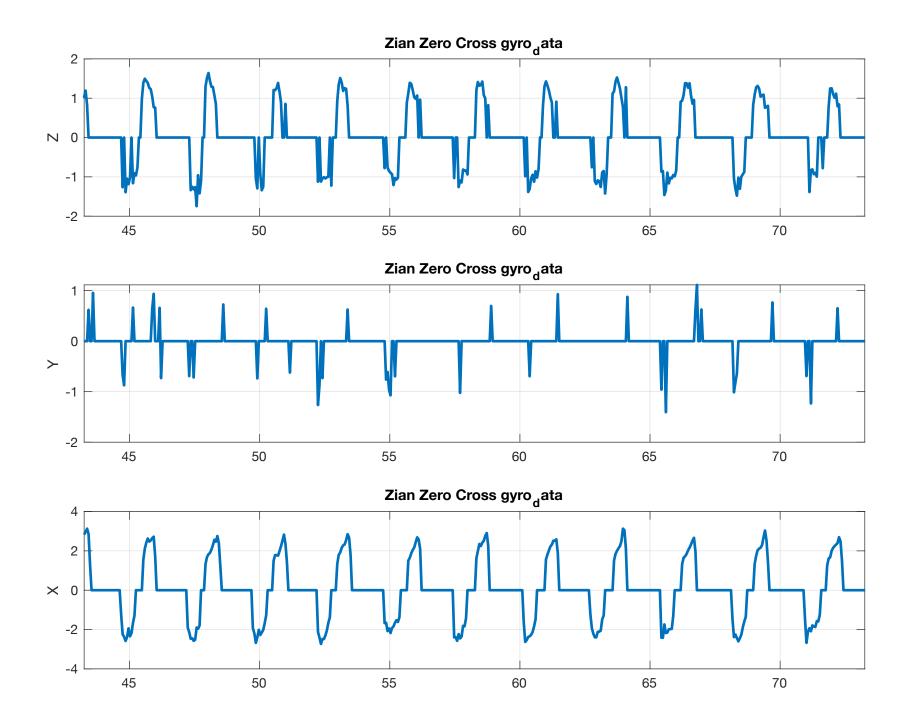




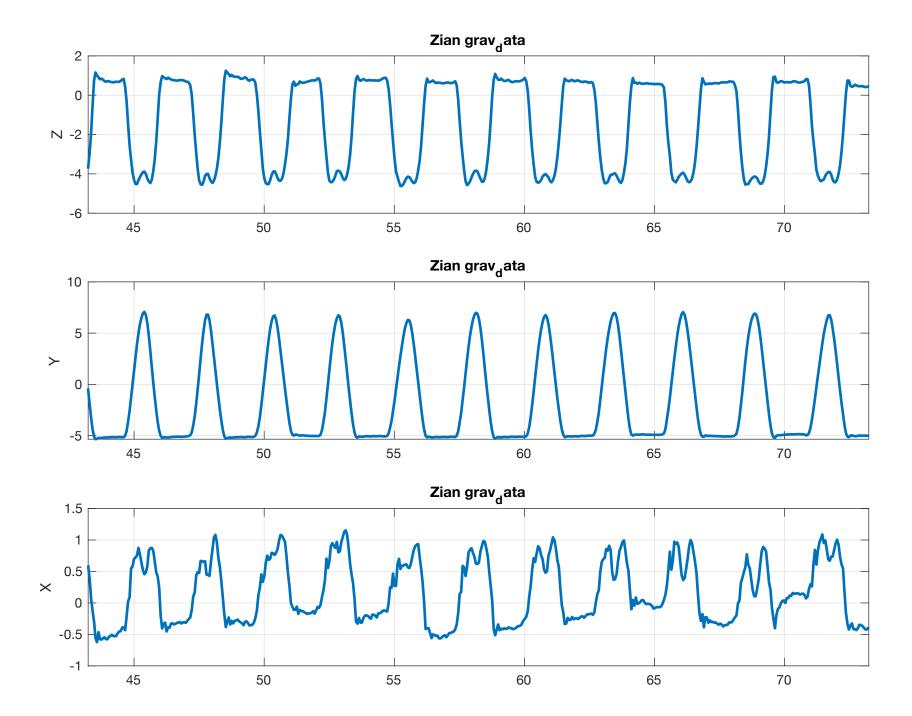


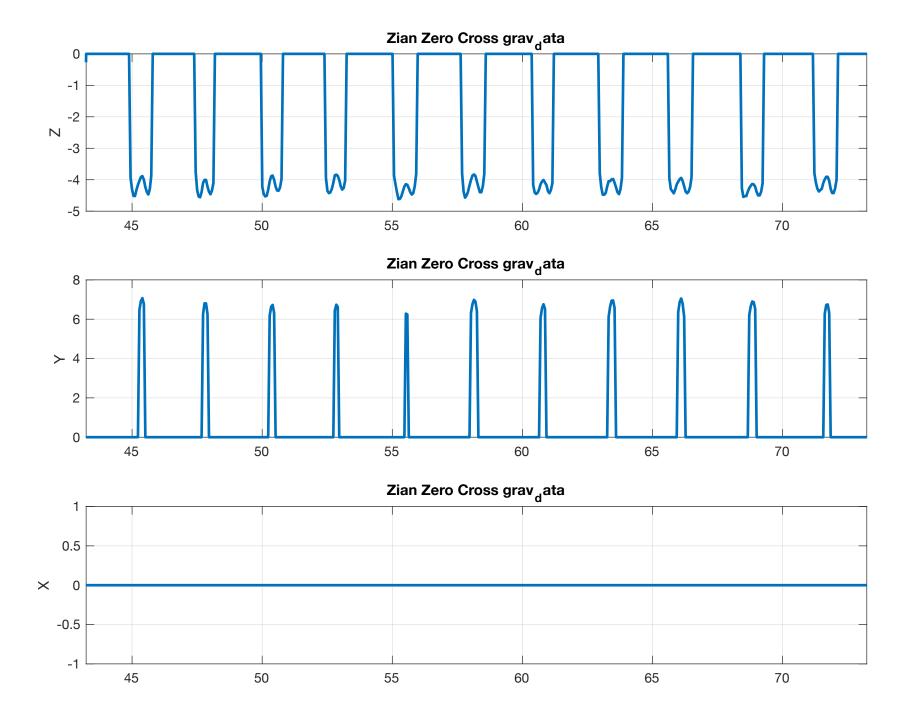
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-30.000	-24.000	5.000	0.000	"bar_data"
"Pressure"	-60.000	-36.000	-2.000	0.000	"bar_data"



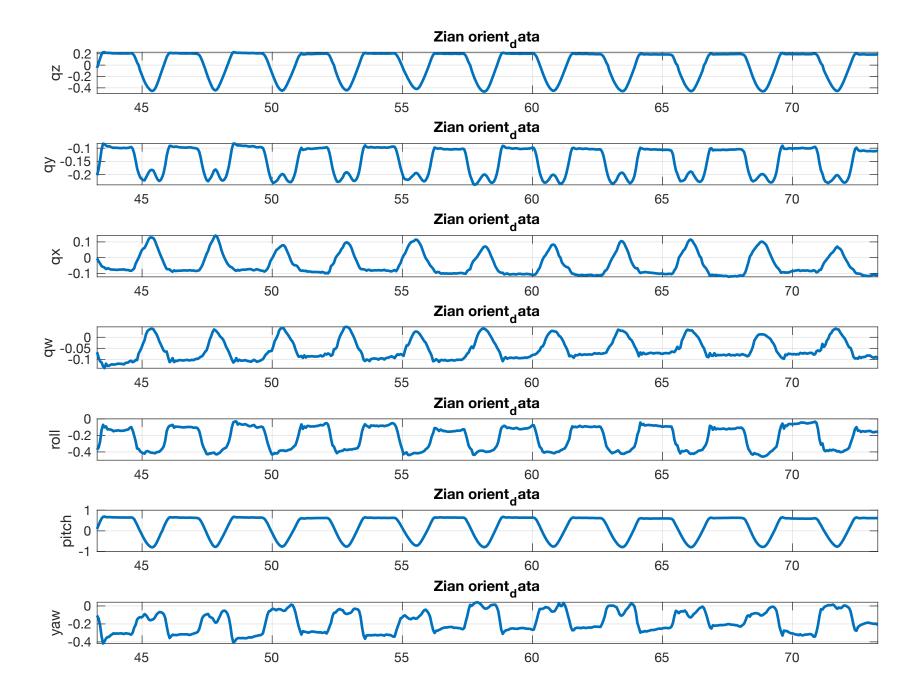


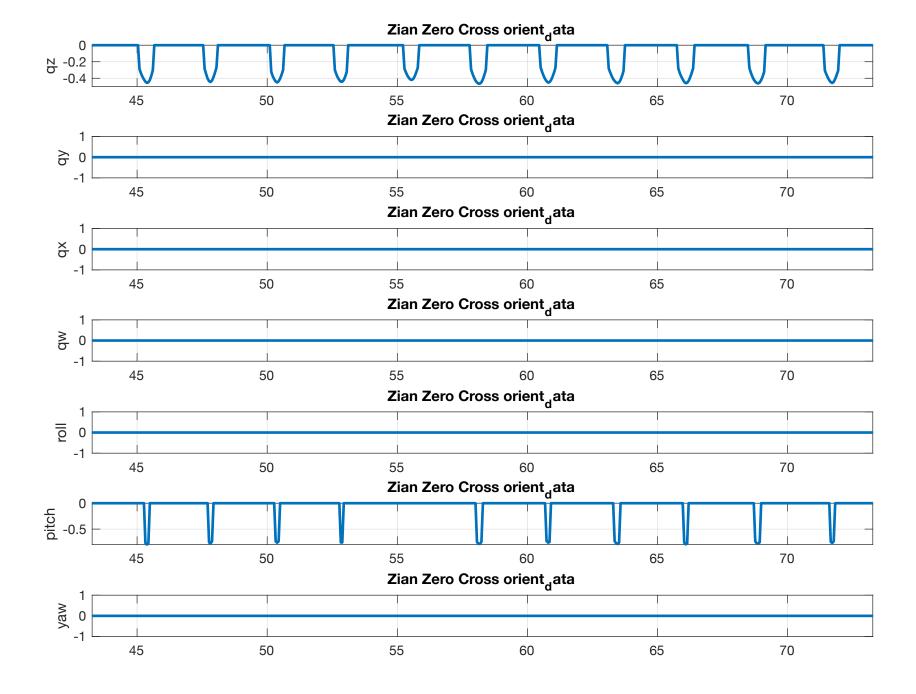
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-279.000	-164.000	-35.000	-16.000	"gyro_data"
'Y'	-367.000	-321.000	-84.000	-7.000	"gyro_data"
'X'	-191.000	-120.000	-30.000	0.000	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-138.000	-110.000	-21.000	12.500	"grav_data"
'Y'	-108.000	0.000	0.000	12.500	"grav_data"
'X'	-199.000	-74.000	-11.000	25.000	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-116.000	-116.000	-5.000	12.500	"orient_data"
'qy'	-127.000	25.000	25.000	25.000	"orient_data"
'qx'	-153.000	0.000	0.000	25.000	"orient_data"
'qw'	-181.000	-2.000	0.000	25.000	"orient_data"
'roll'	-202.000	25.000	25.000	25.000	"orient_data"
'pitch'	-107.000	-107.000	-4.000	14.000	"orient_data"
'yaw'	-168.000	7.000	14.000	25.000	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Υ"	'zero_cross'	87.000
'bar_data'	"Relative Altitude"	'zero_cross'	0.000
'gyro_data'	"X"	'zero_cross'	0.000
'grav_data'	"Υ"	'findpeaks_above_zero'	0.000
'orient_data'	"qx"	'findpeaks_above_zero'	0.000