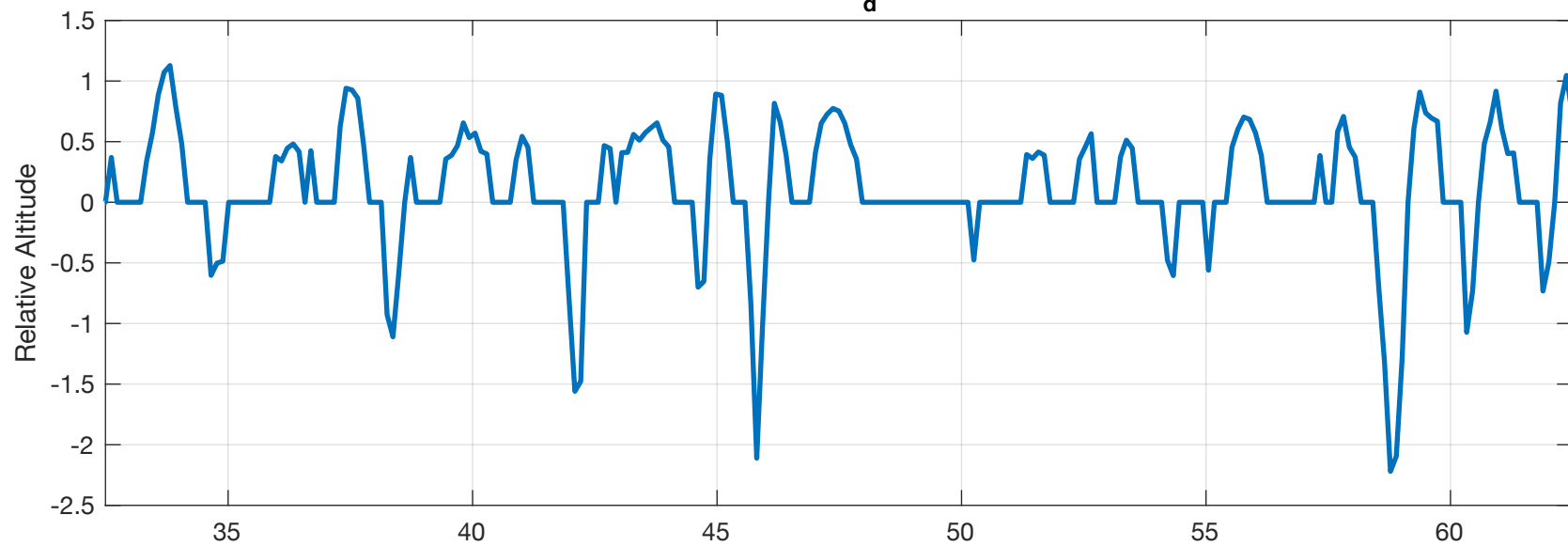
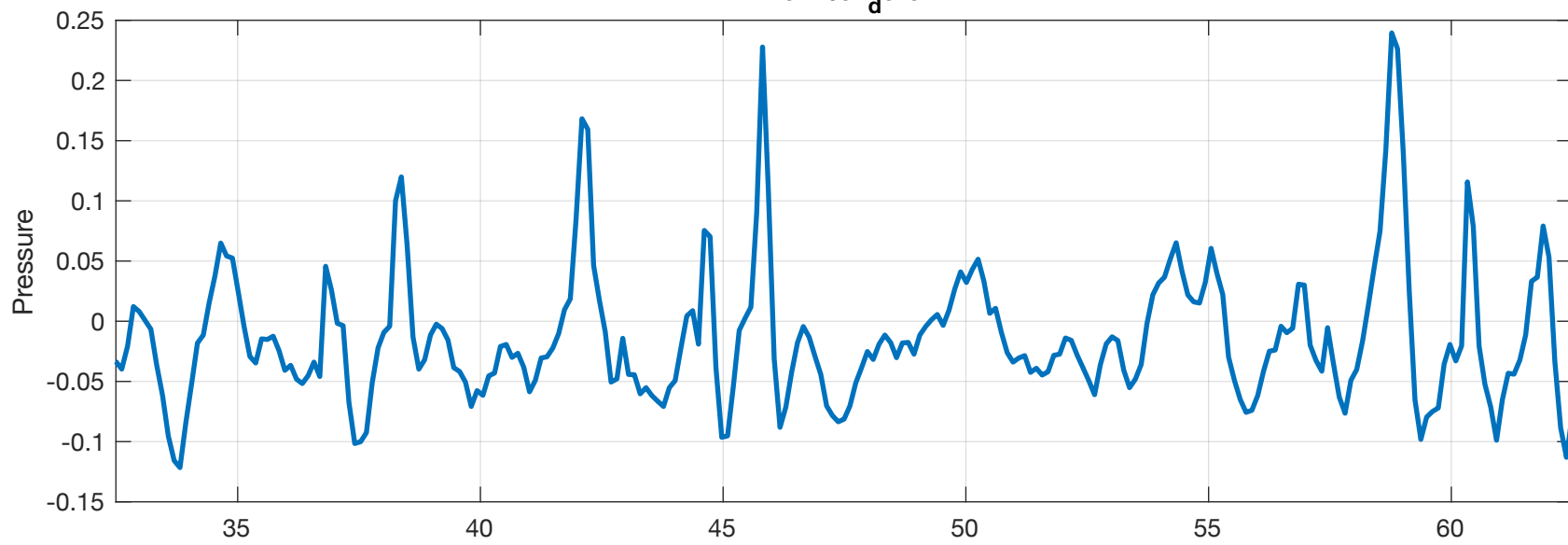


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-611.000	-401.000	-141.000	-109.500	"accel_data"
'Y'	-726.000	-582.000	-203.000	-117.500	"accel_data"
'X'	-661.000	-471.000	-176.000	-105.500	"accel_data"

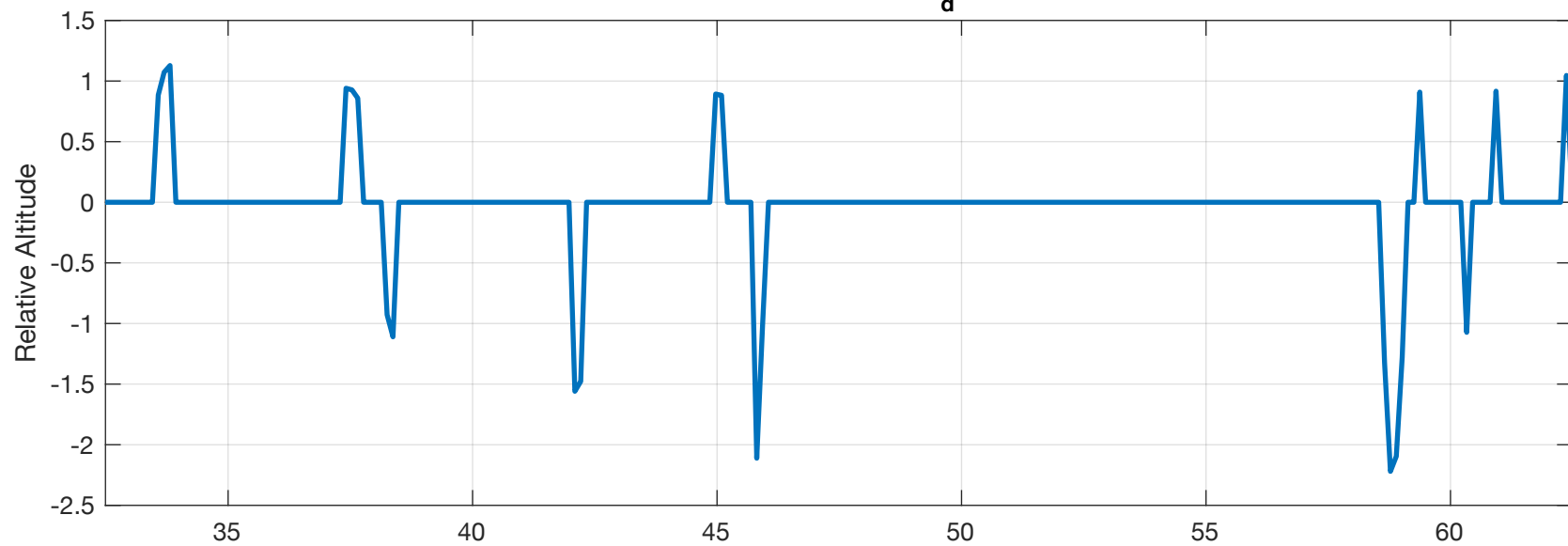
Zian bar<sub>d</sub>ata



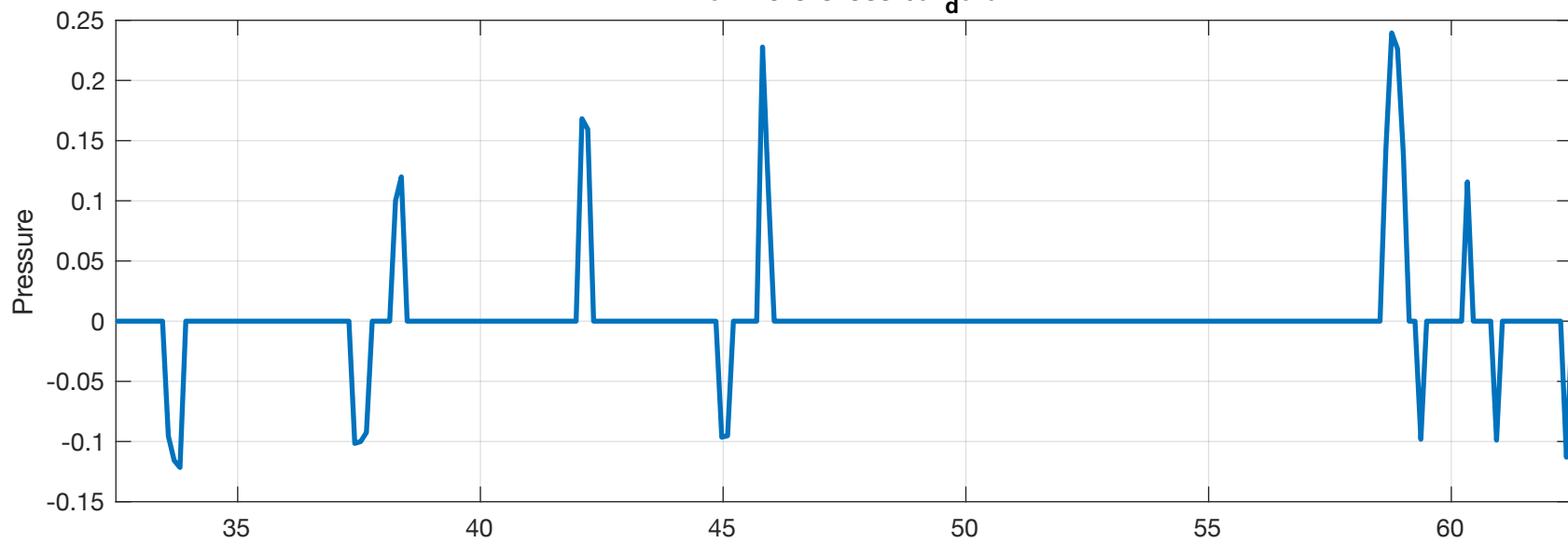
Zian bar<sub>d</sub>ata



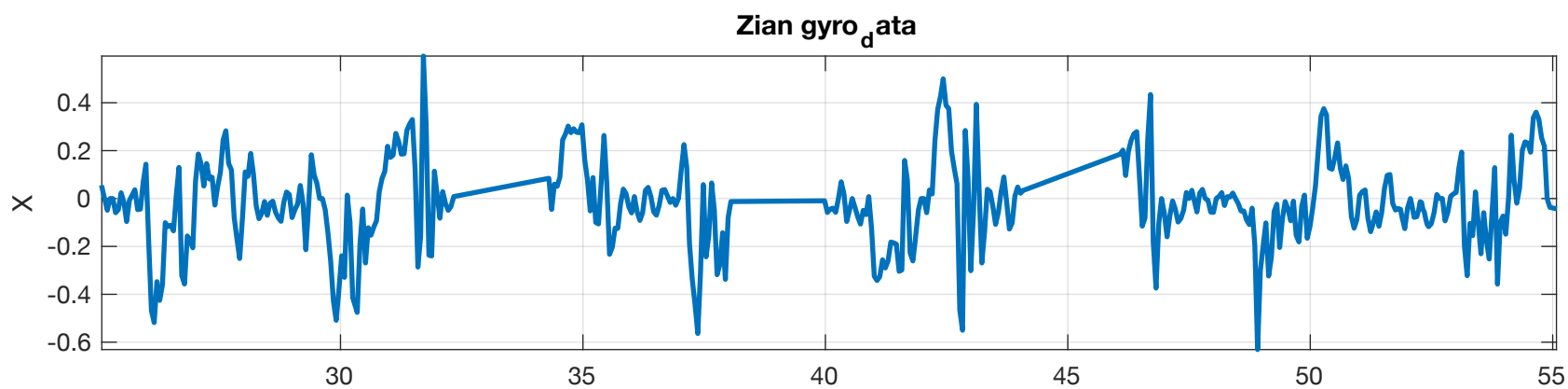
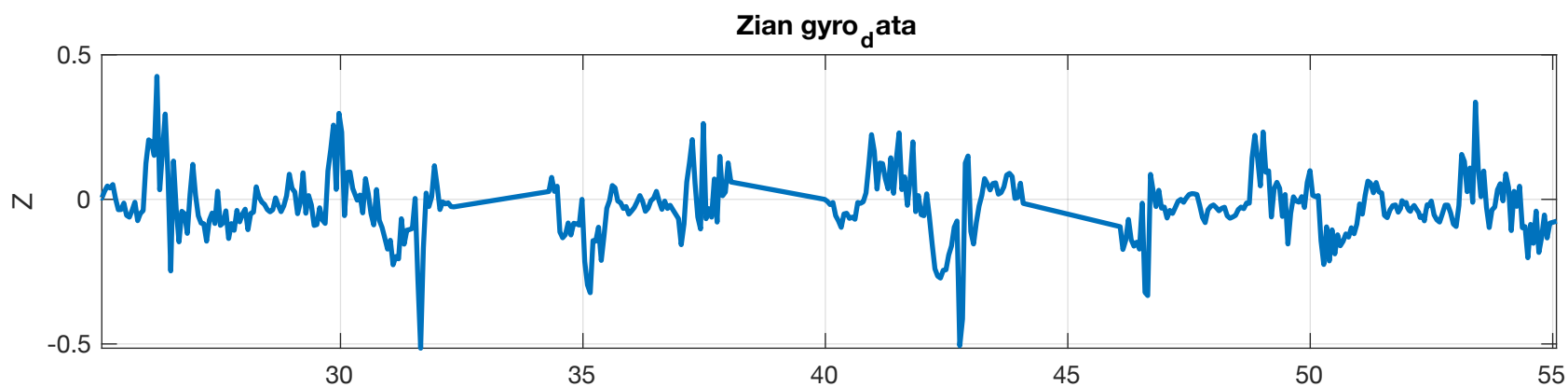
Zian Zero Cross  $\bar{\varphi}_{ata}$

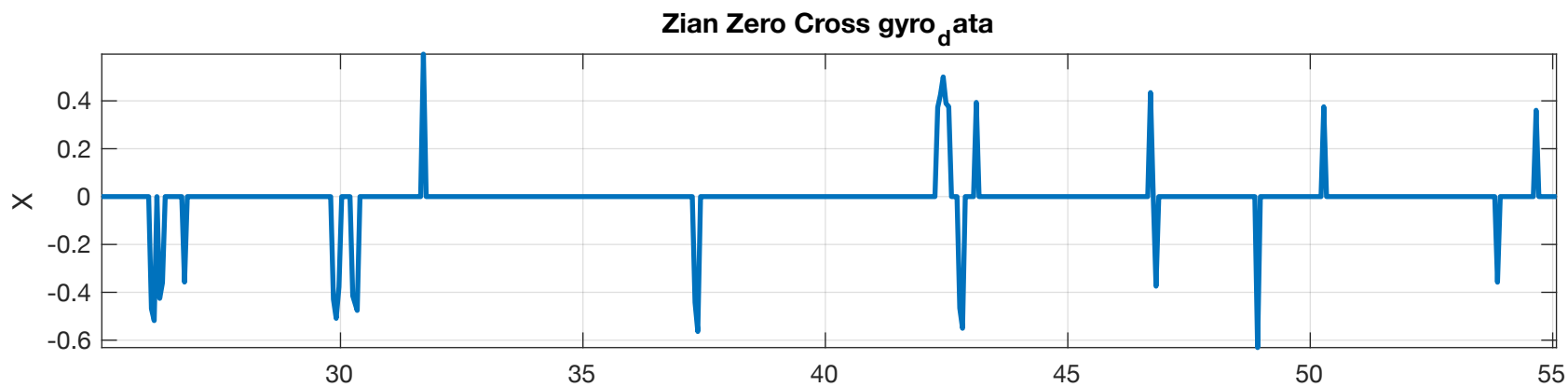
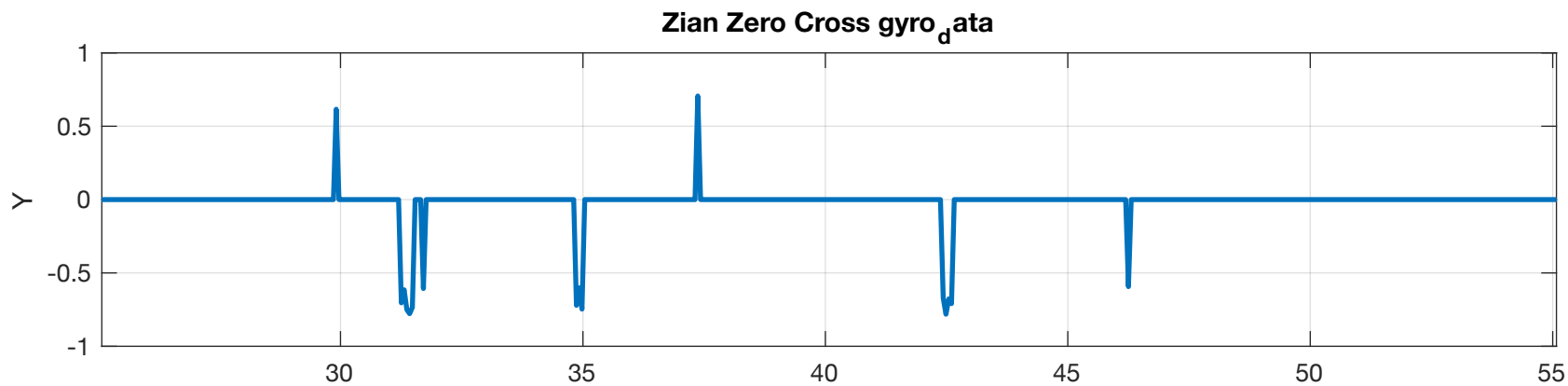
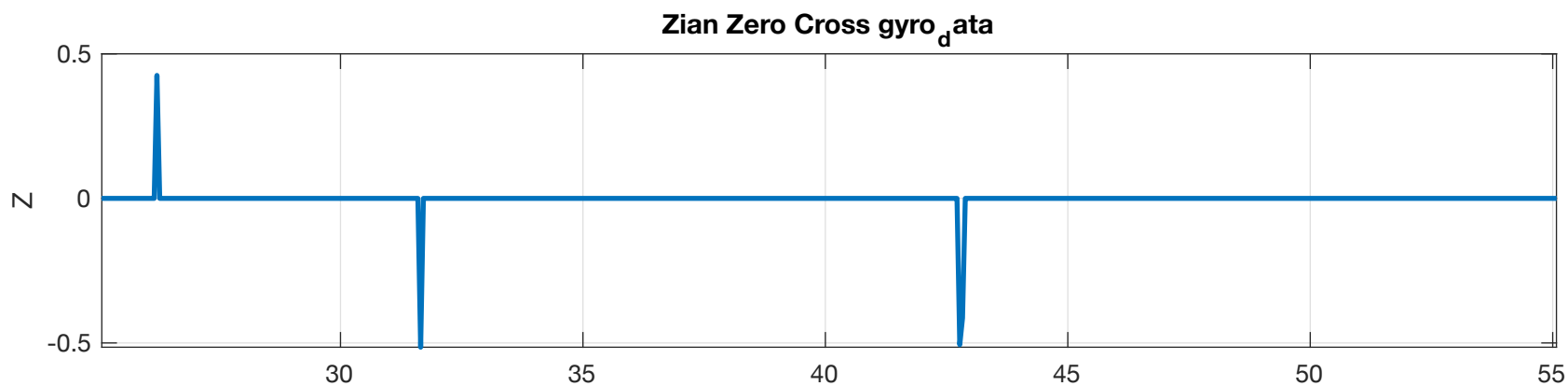


Zian Zero Cross  $\bar{\varphi}_{ata}$



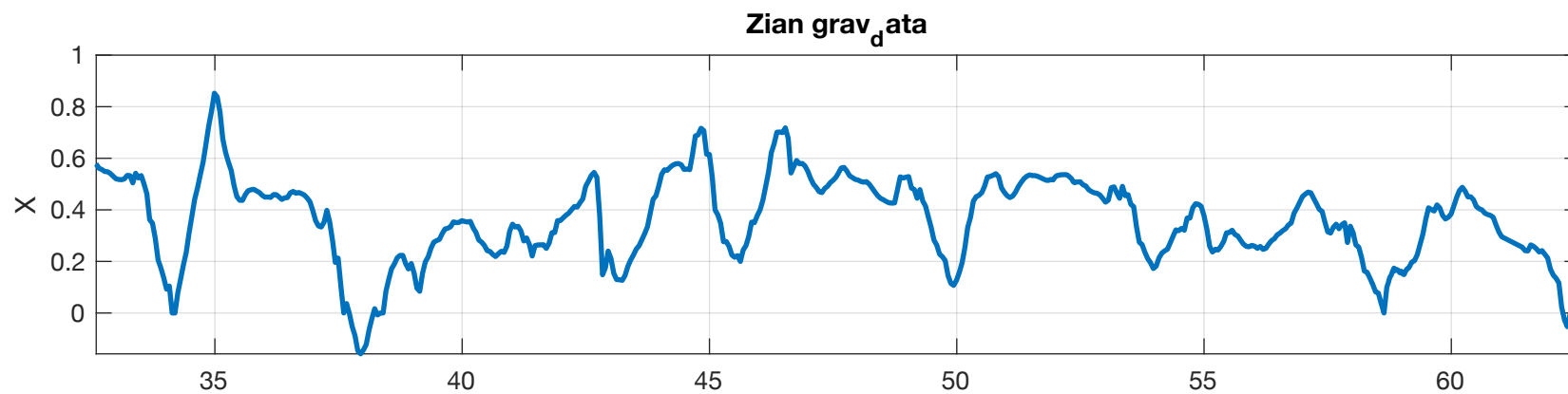
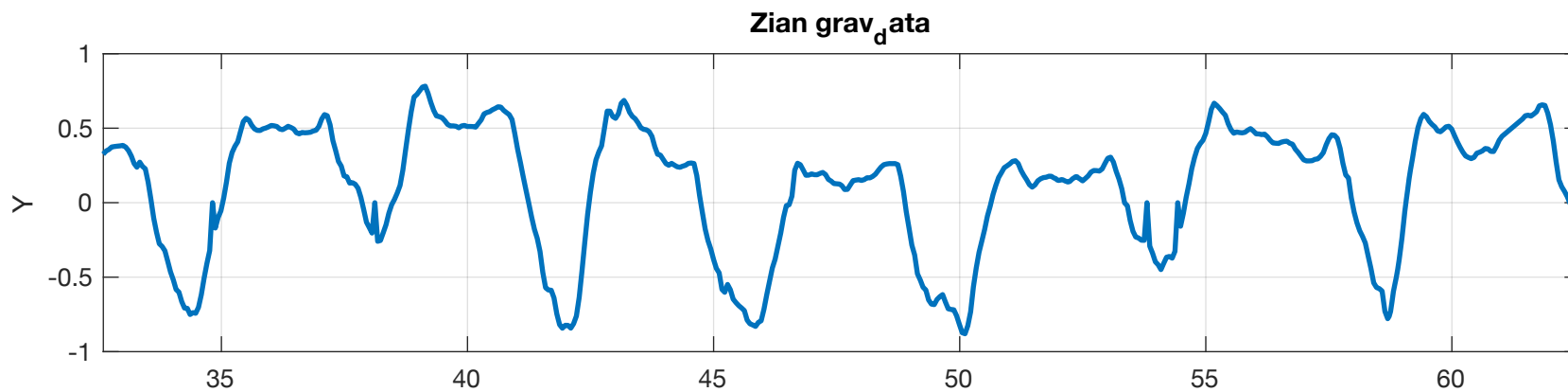
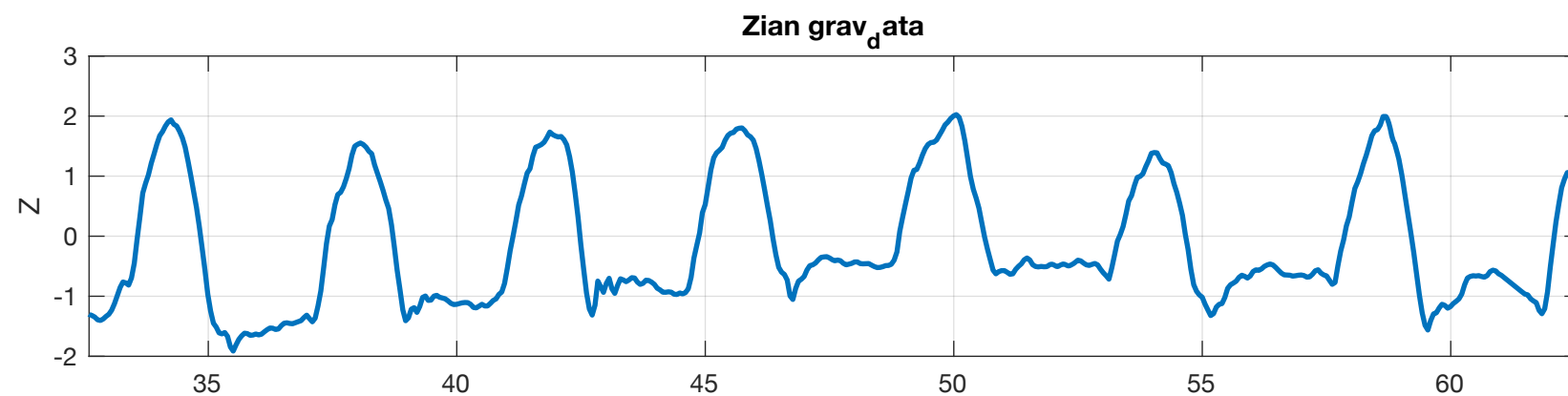
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-88.000	-71.000	-10.000	-16.500	"bar_data"
"Pressure"	-138.000	-86.000	-16.000	-16.500	"bar_data"

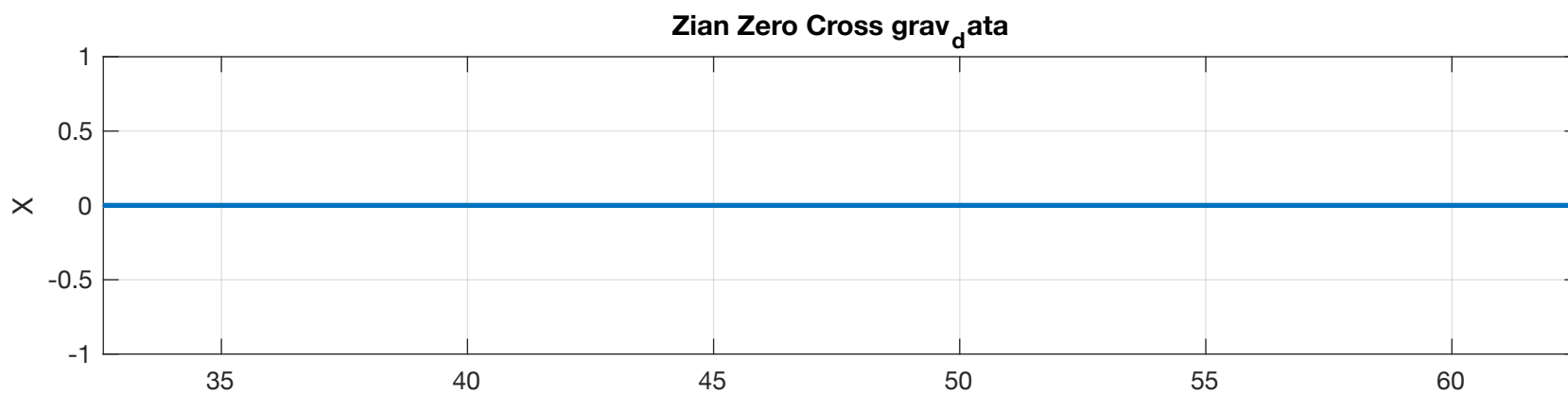
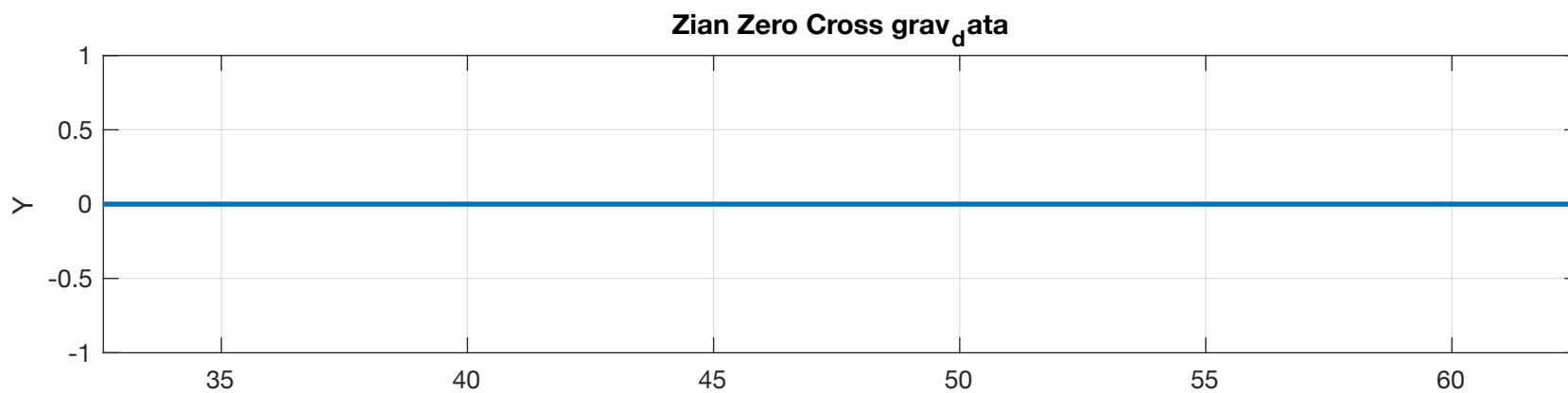
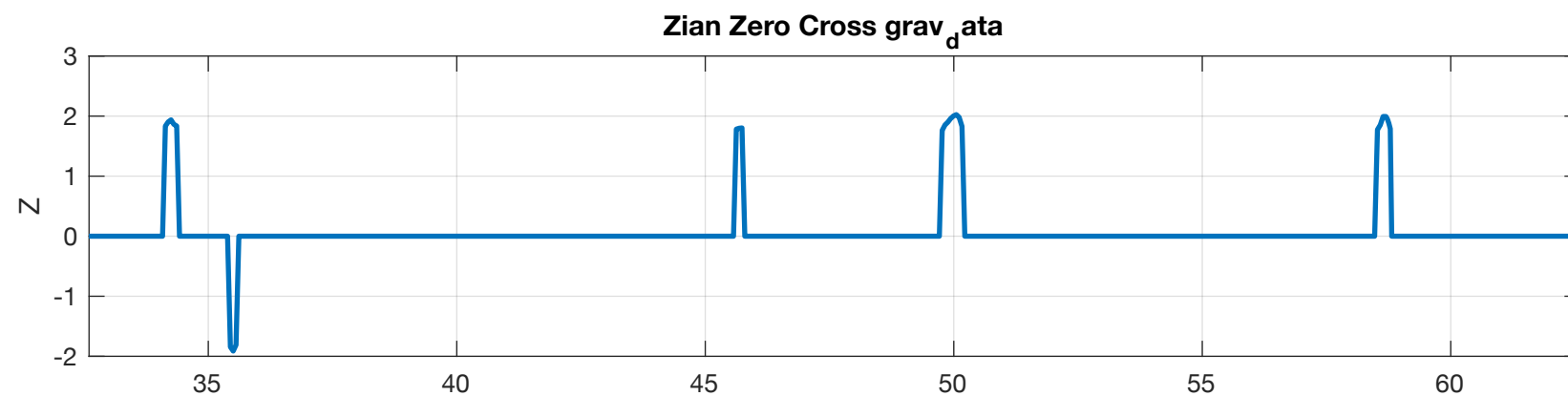




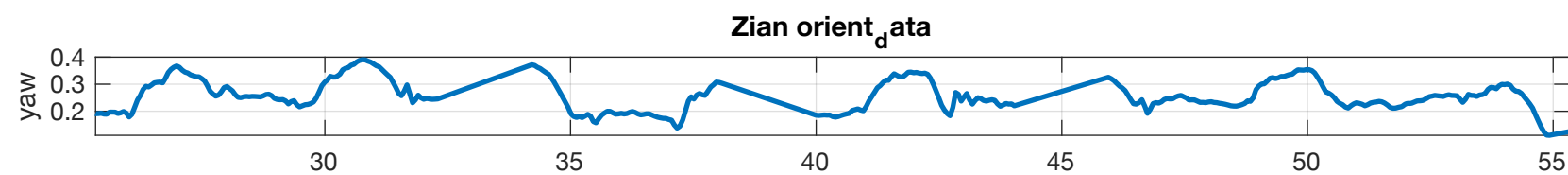
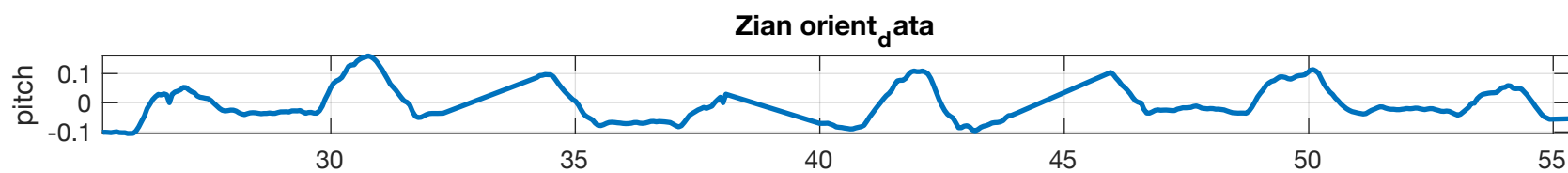
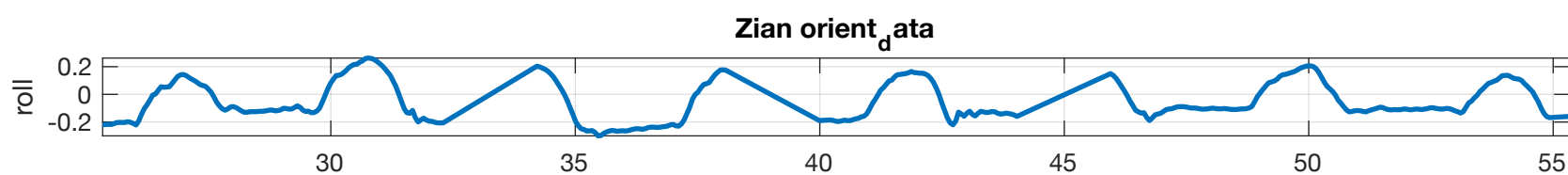
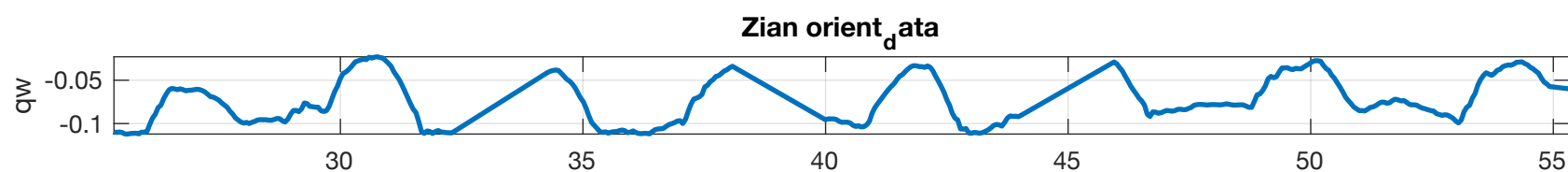
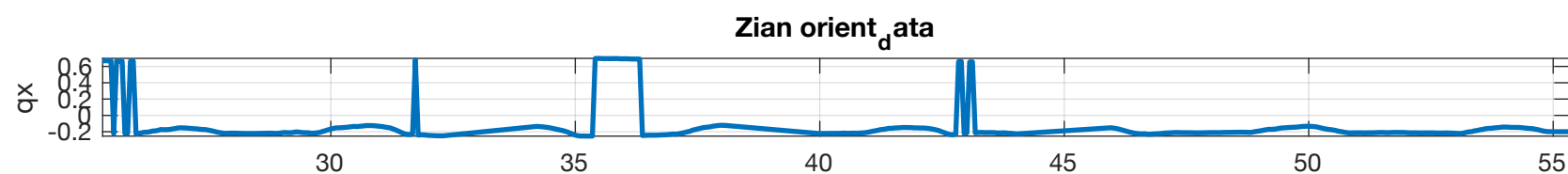
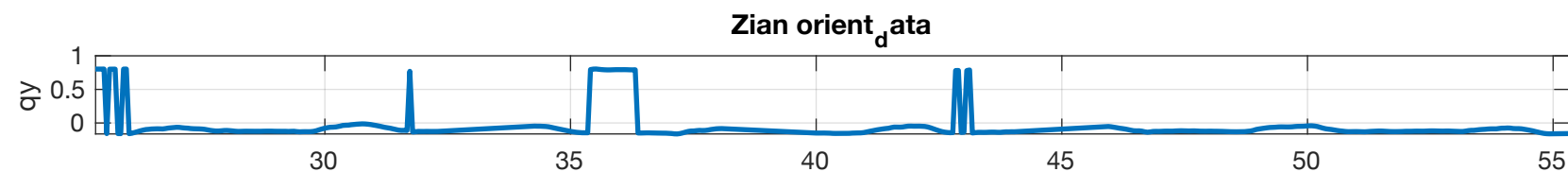
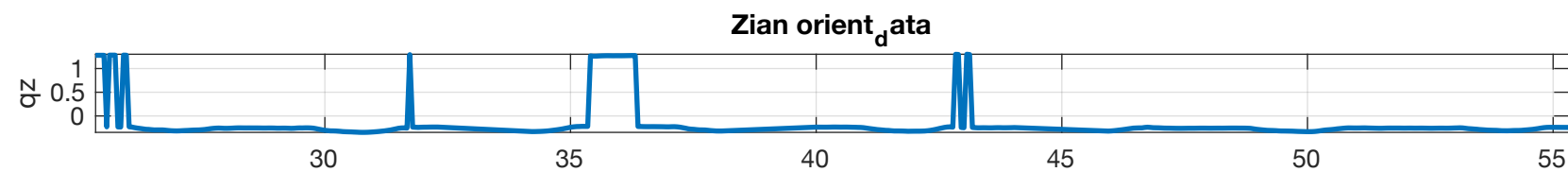


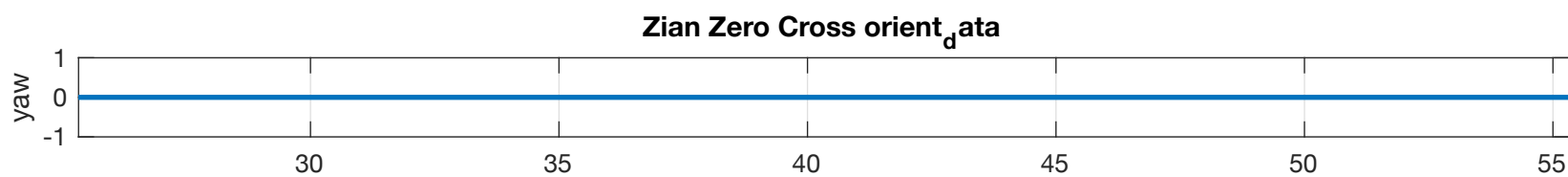
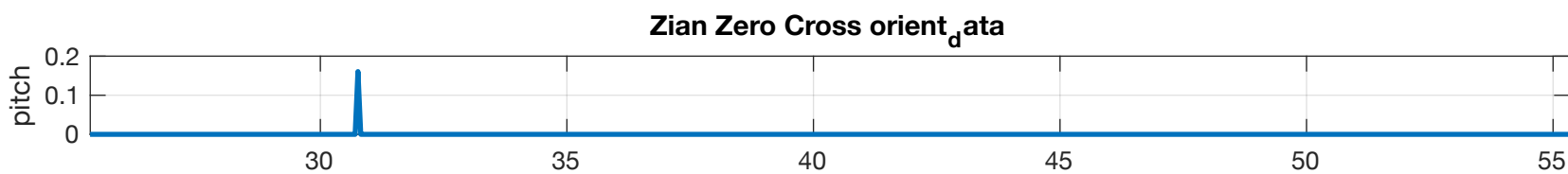
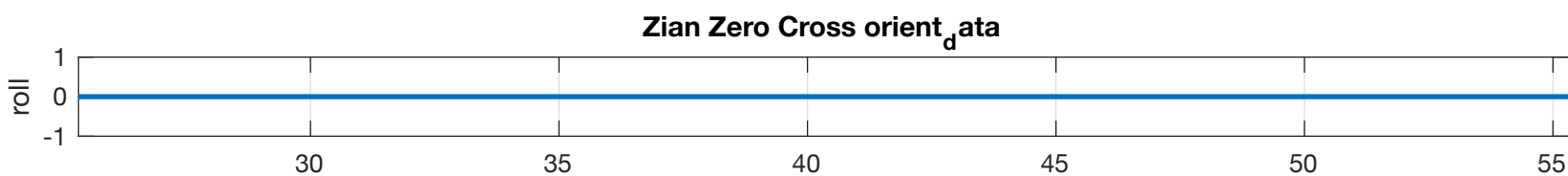
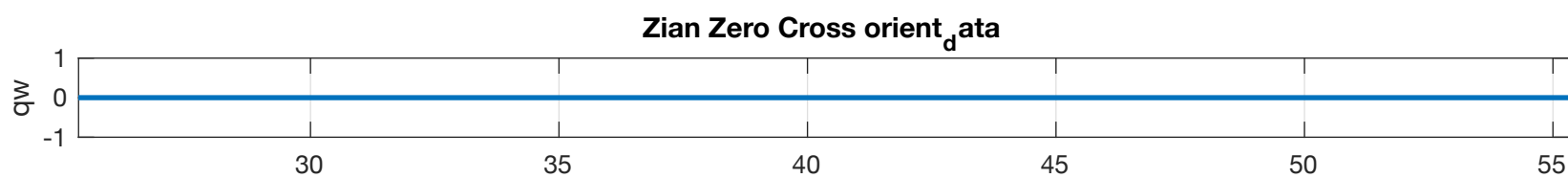
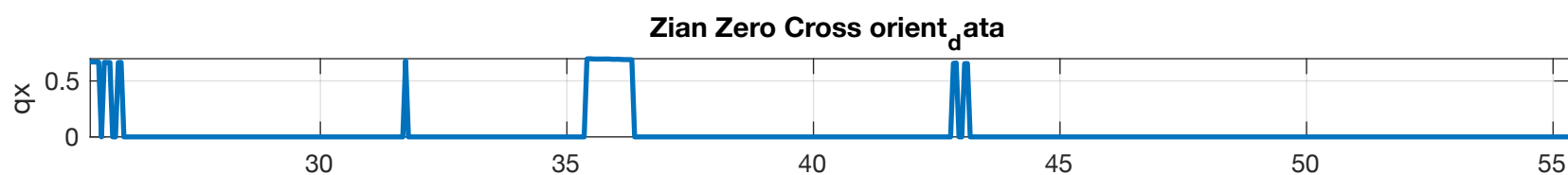
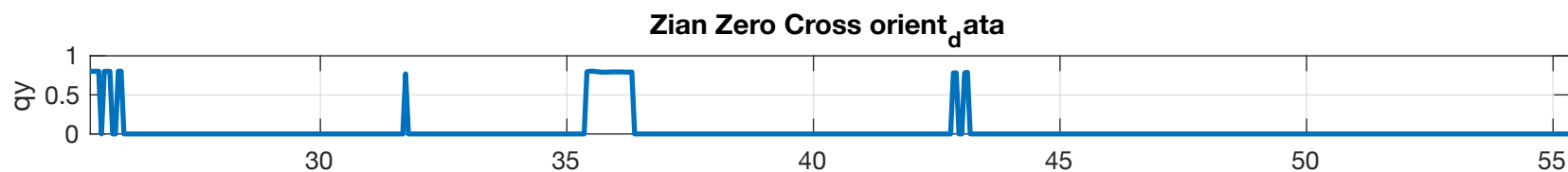
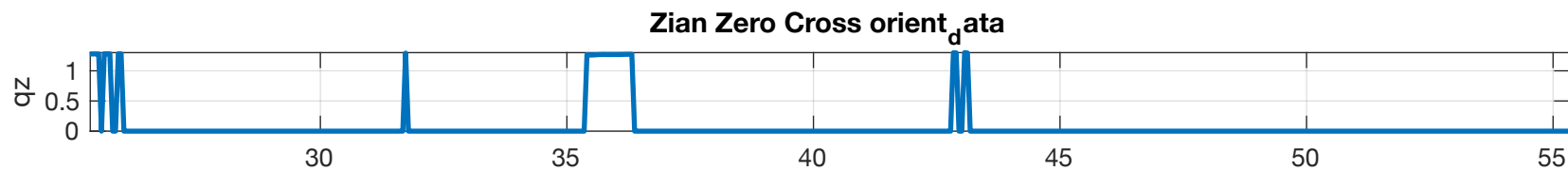
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-417.000	-208.000	-80.000	14.500	"gyro_data"
'Y'	-447.000	-248.000	-79.000	5.500	"gyro_data"
'X'	-357.000	-226.000	-87.000	-10.500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-226.000	-65.000	-11.000	16.500	"grav_data"
'Y'	-209.000	-172.000	-35.000	23.000	"grav_data"
'X'	-296.000	-261.000	-55.000	23.500	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-175.000	-16.000	10.000	20.000	"orient_data"
'qy'	-183.000	-17.000	11.000	20.000	"orient_data"
'qx'	-206.000	-27.000	5.000	19.500	"orient_data"
'qw'	-174.000	-7.000	13.000	24.000	"orient_data"
'roll'	-169.000	-29.000	-2.000	20.500	"orient_data"
'pitch'	-154.000	-25.000	1.000	23.000	"orient_data"
'yaw'	-230.000	-201.000	-34.000	24.500	"orient_data"

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Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'zero_cross'	105.500
'bar_data'	"Relative Altitude"	'double_findpeaks'	10.000
'gyro_data'	"Y"	'zero_cross'	5.500
'grav_data'	"Z"	'double_findpeaks'	11.000
'orient_data'	"pitch"	'double_findpeaks'	1.000