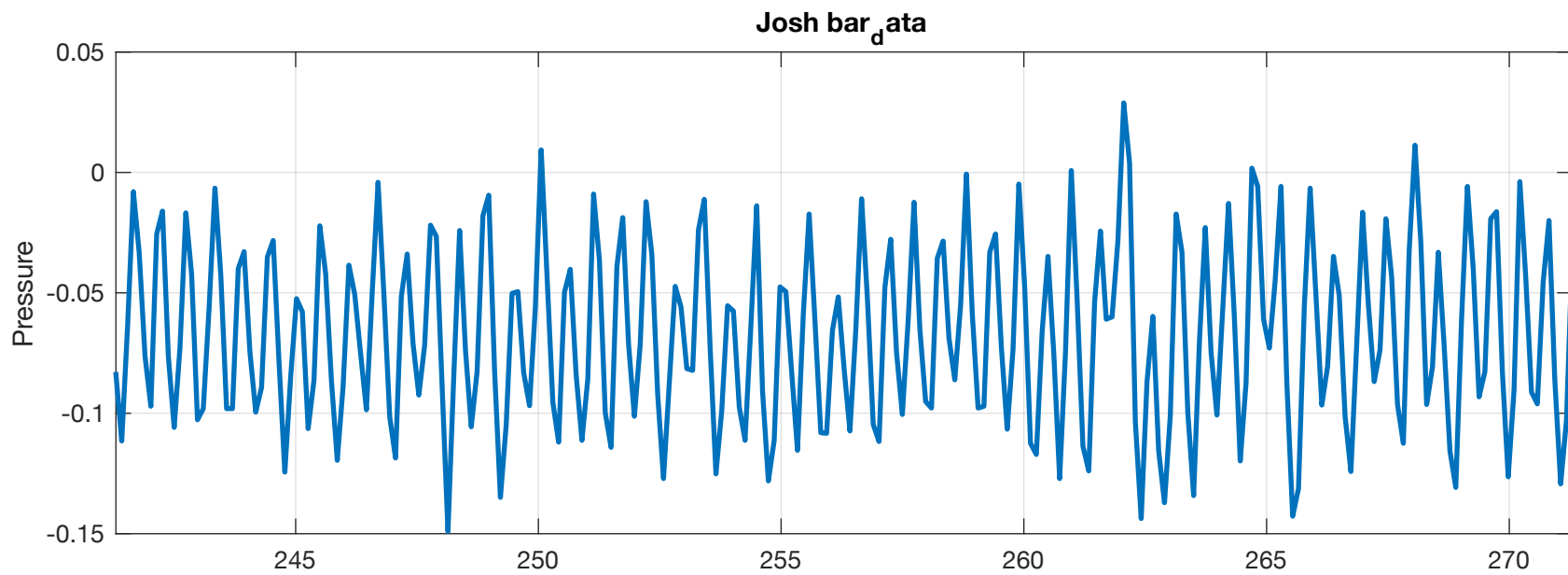
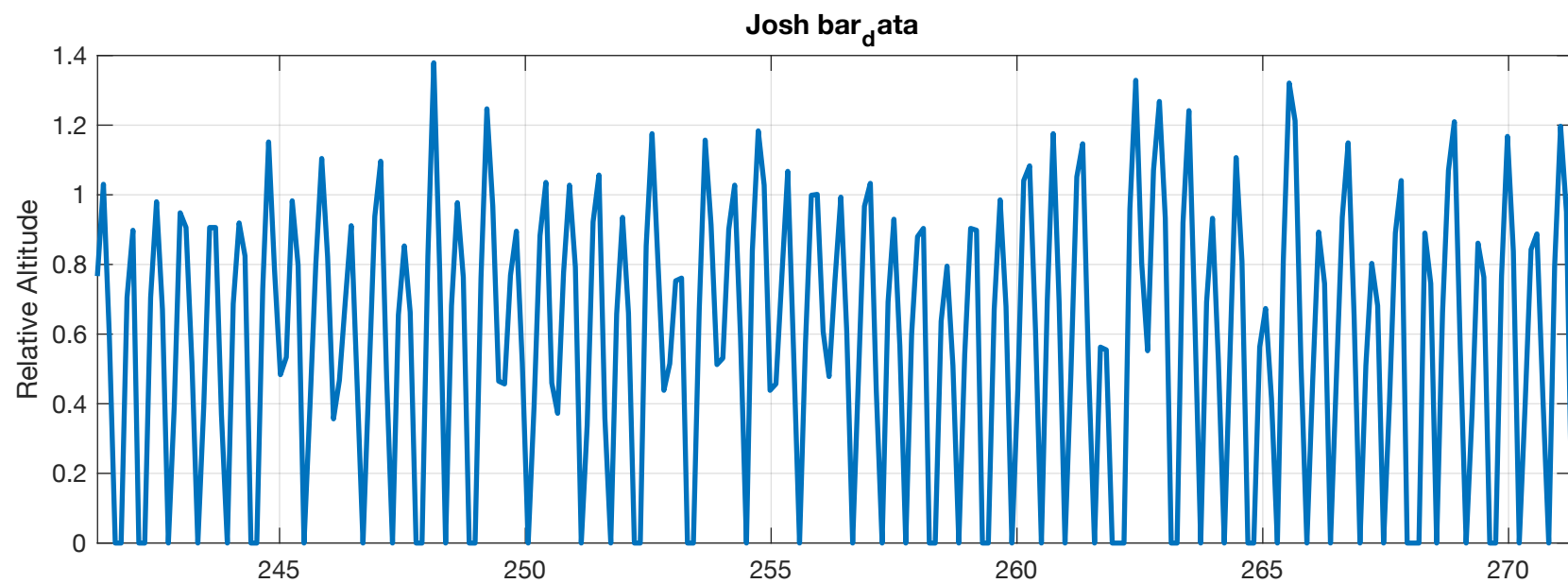
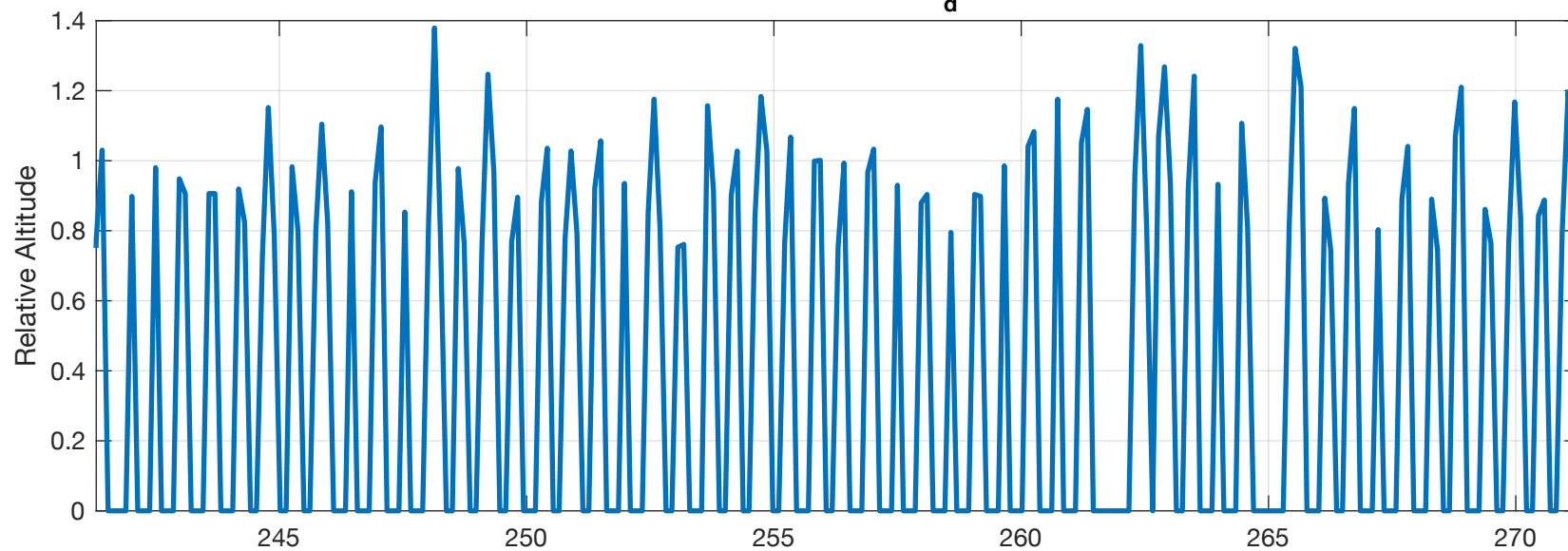


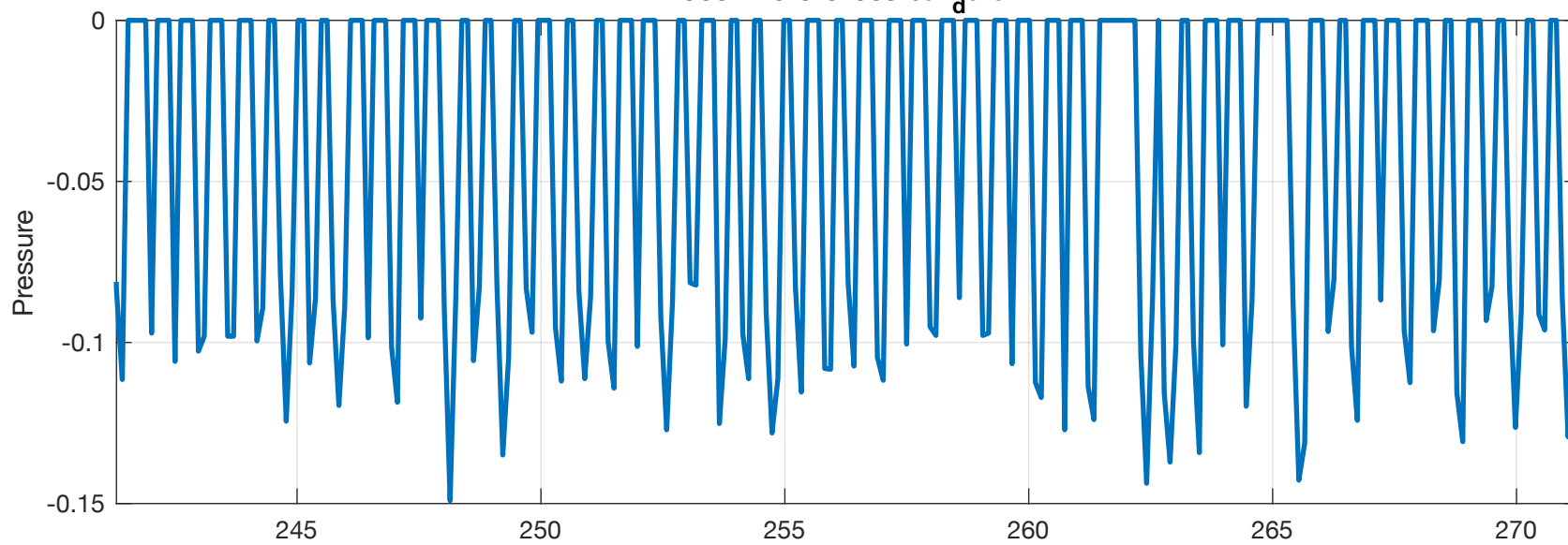
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-4187	-2752	-1147	-1634	"accel_data"
'Y'	-2884	-2739	-1242	-1647	"accel_data"
'X'	-2825	-2211	-988	-1051	"accel_data"



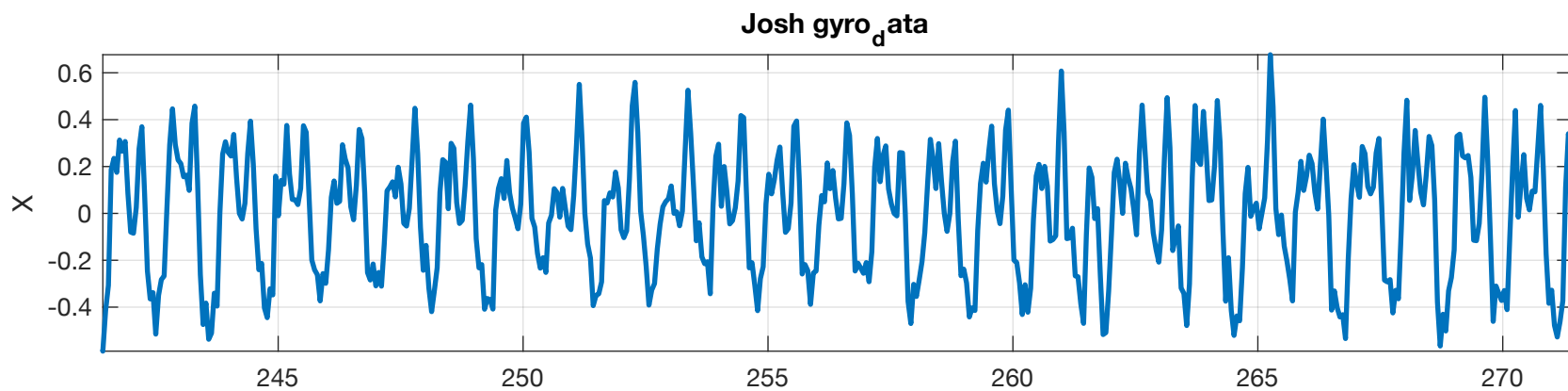
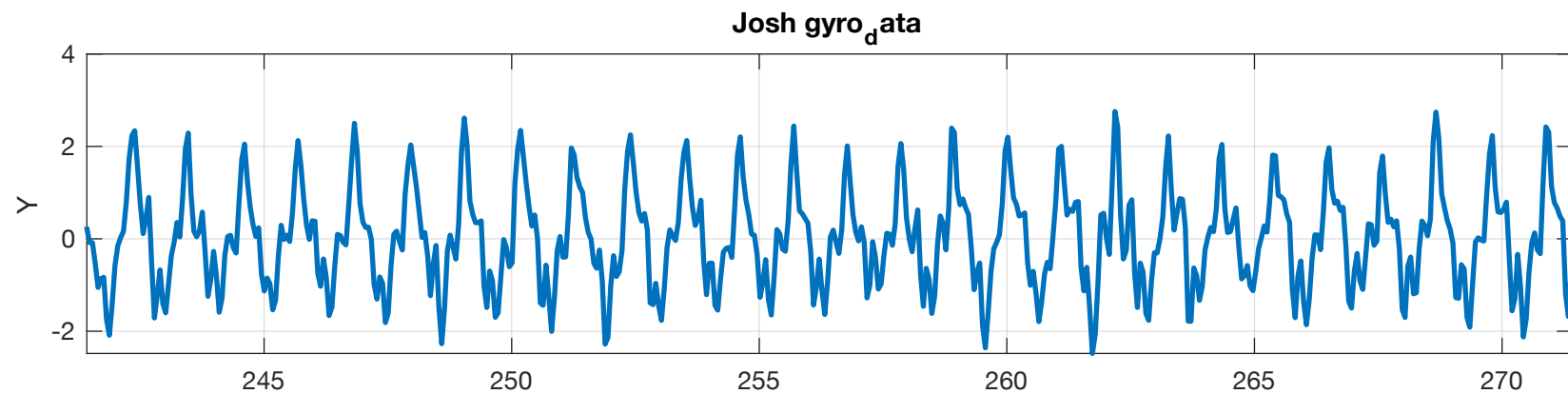
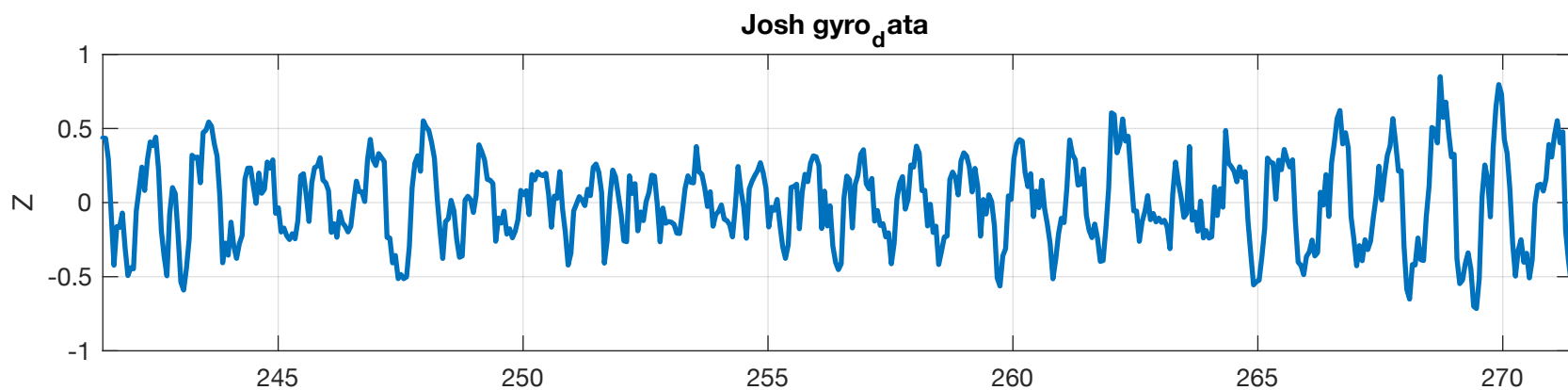
Josh Zero Cross bar_data

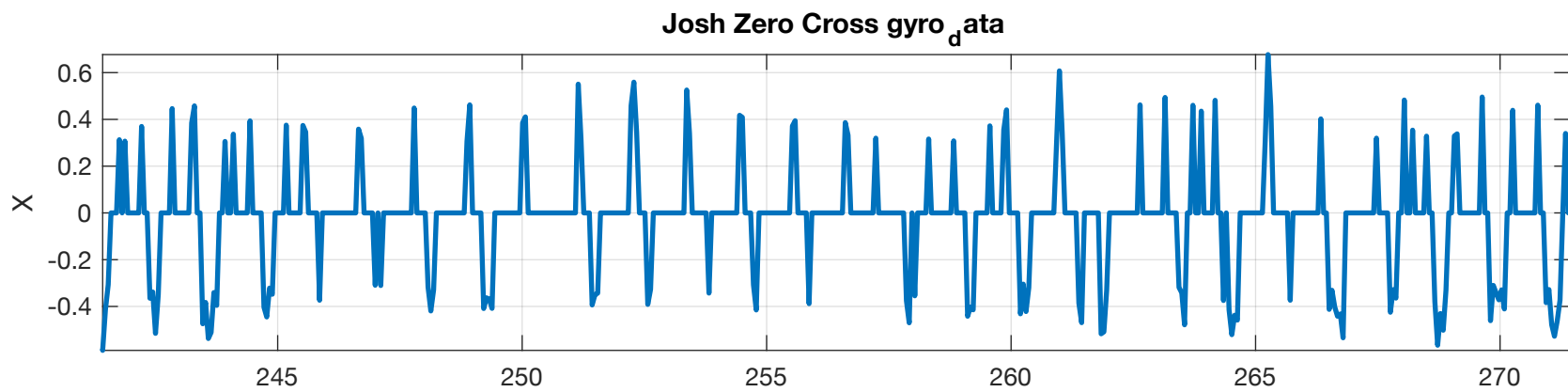
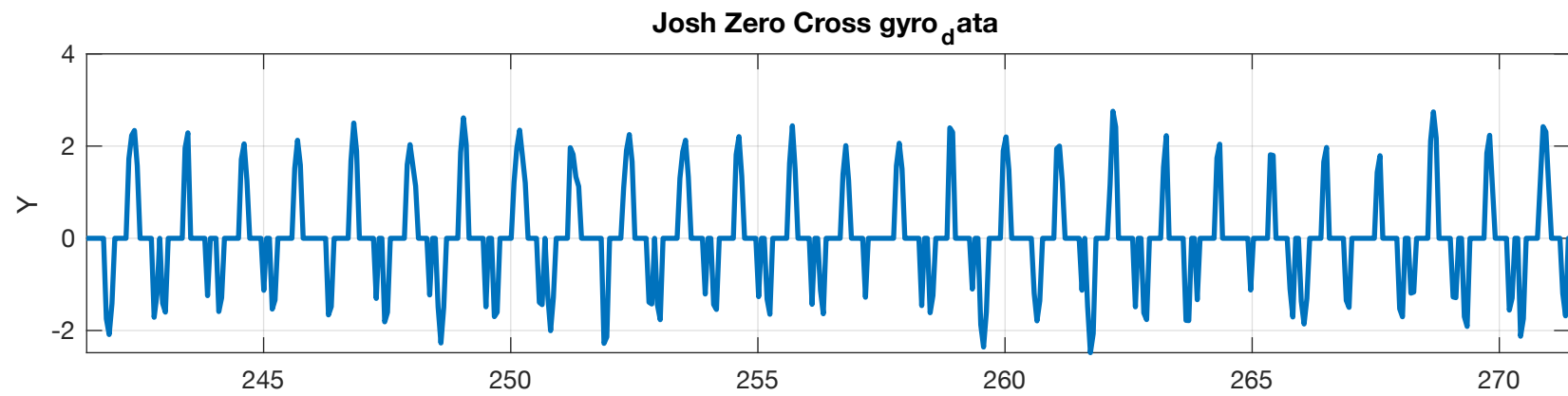
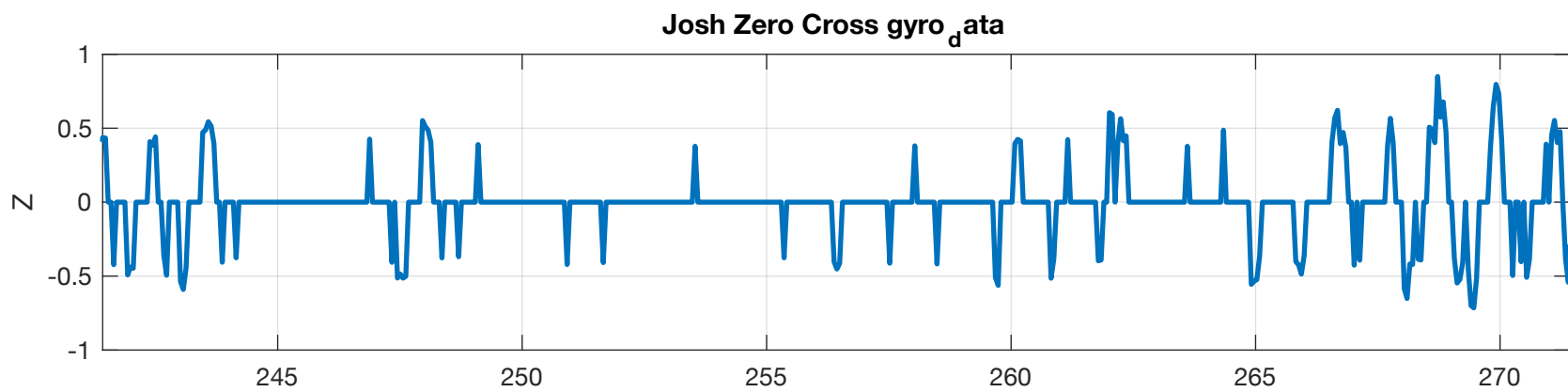


Josh Zero Cross bar_data

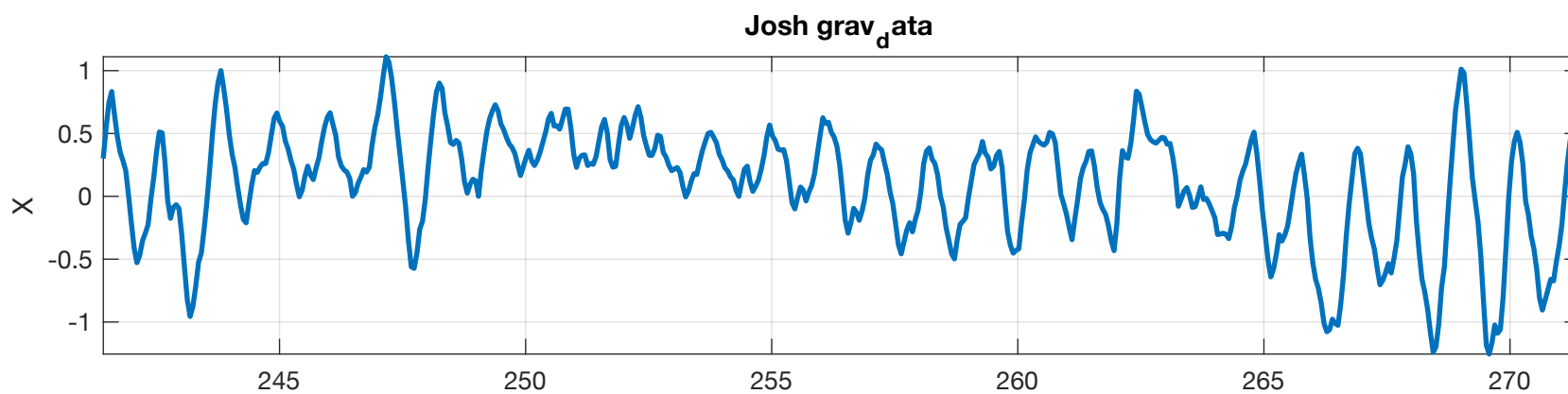
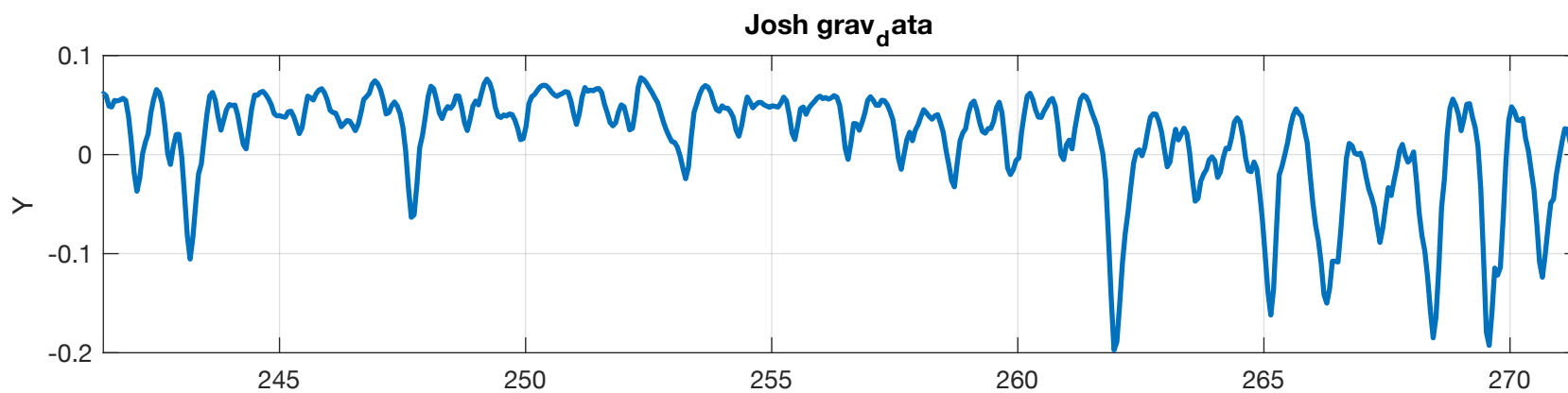
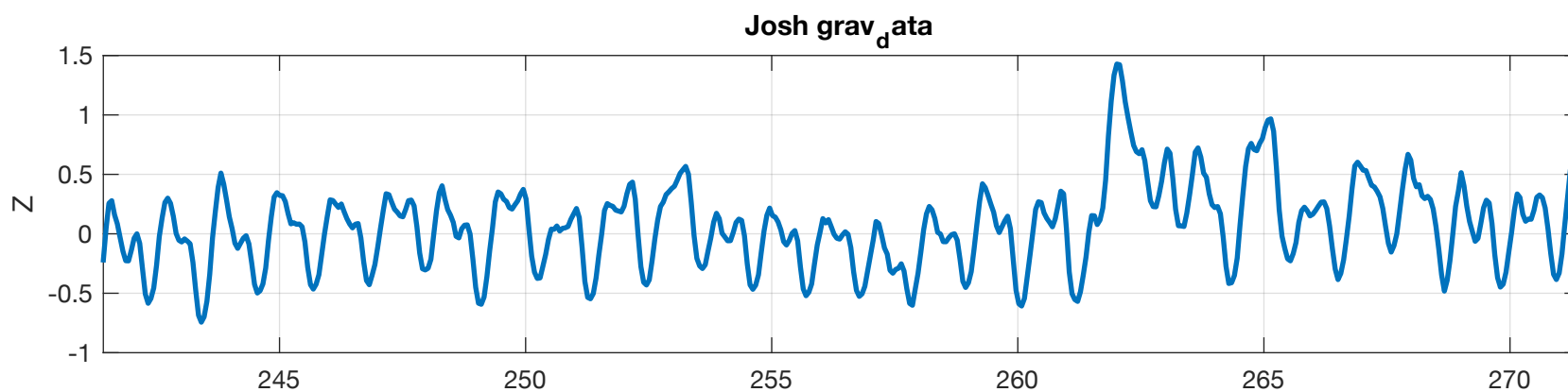


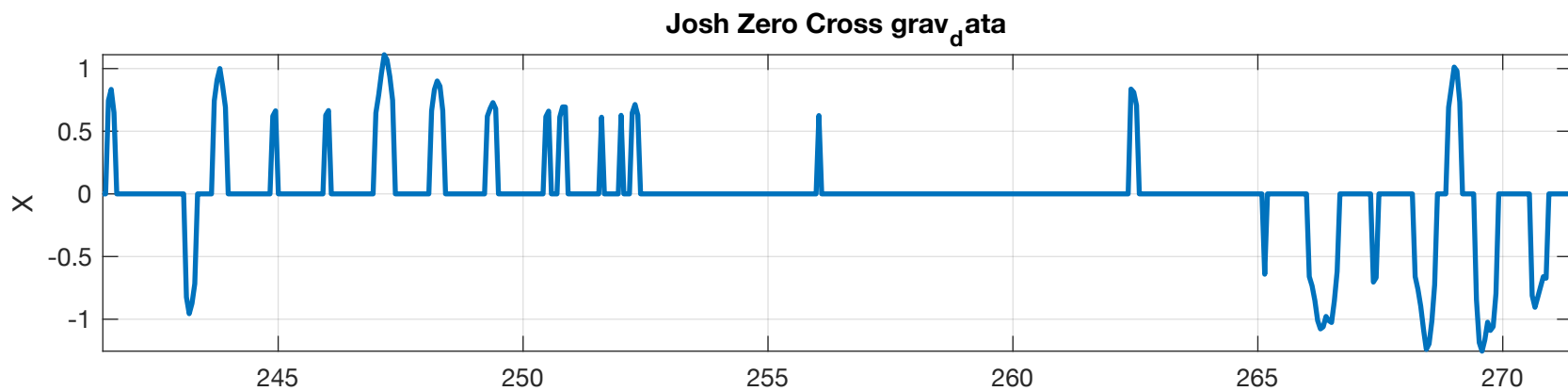
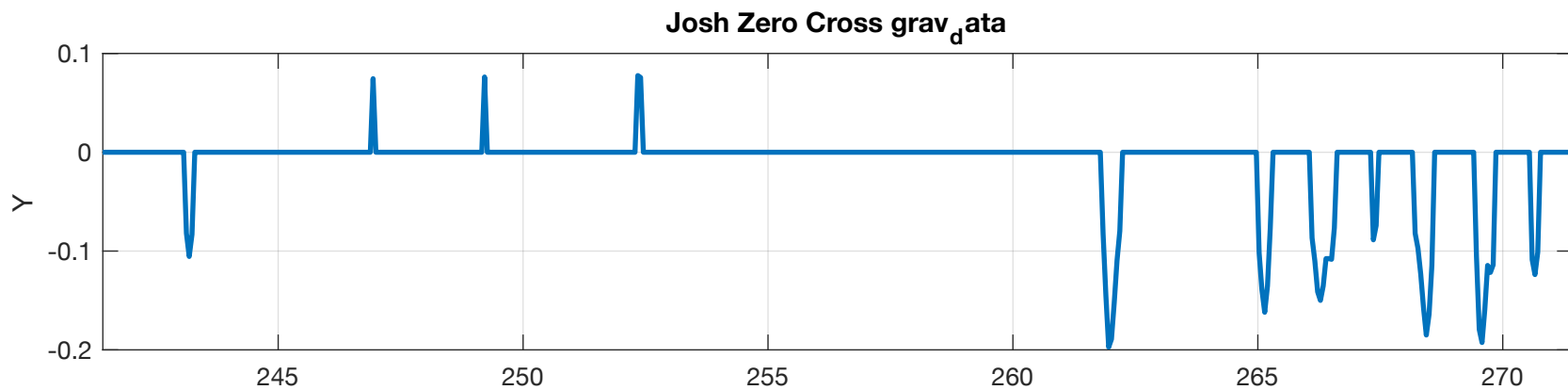
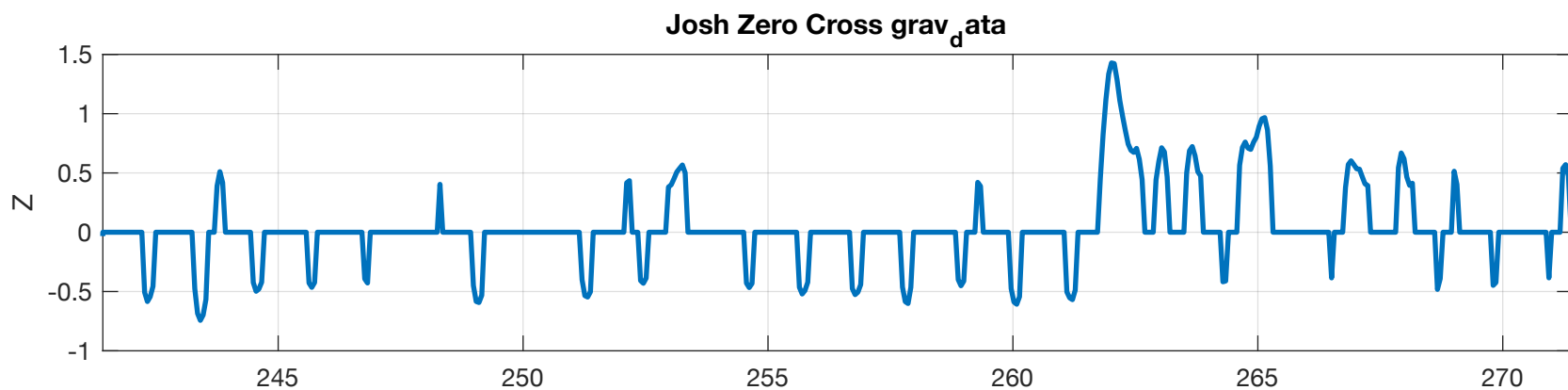
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	-1657	-913	-387	-690.5000	"bar_data"
"Pressure"	-1678	-954	-375	-690.5000	"bar_data"



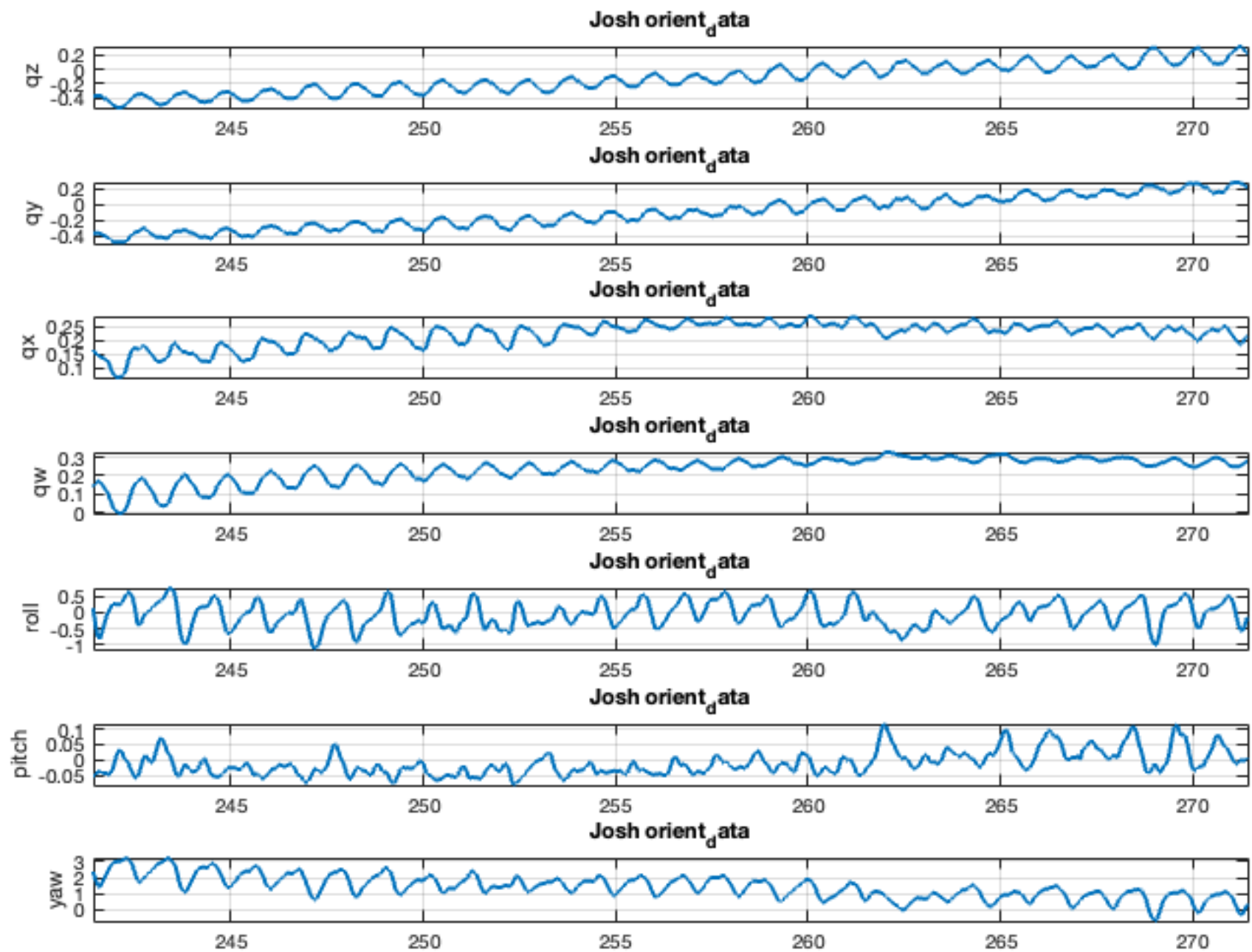


Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-3727	-2714	-1003	-909.5000	"gyro_data"
'Y'	-3067	-2041	-859	-1147.5000	"gyro_data"
'X'	-3724	-2738	-1156	-1306.2500	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-1773	-1586	-664	-635.7500	"grav_data"
'Y'	-1979	-1808	-700	-262.5000	"grav_data"
'X'	-1509	-1226	-468	-453.7500	"grav_data"



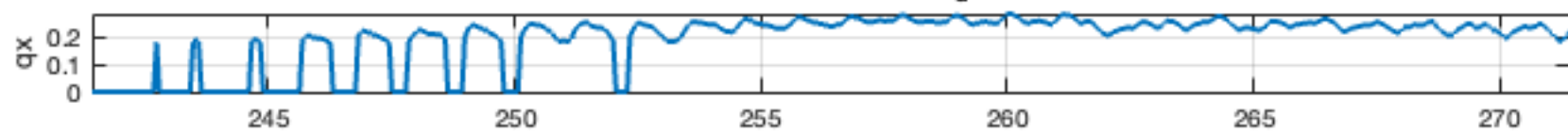
Josh Zero Cross orient_data



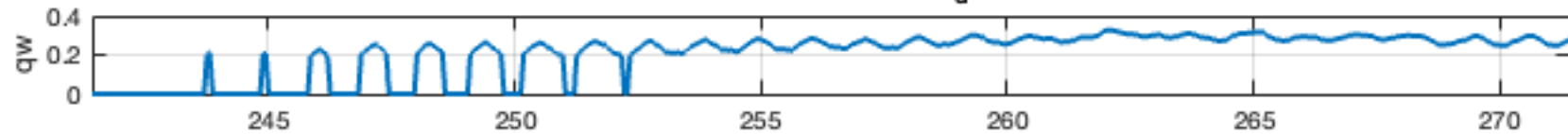
Josh Zero Cross orient_data



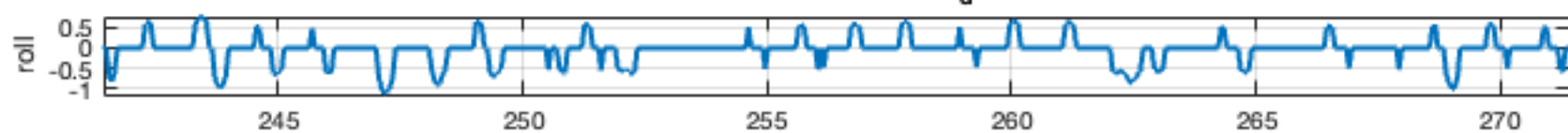
Josh Zero Cross orient_data



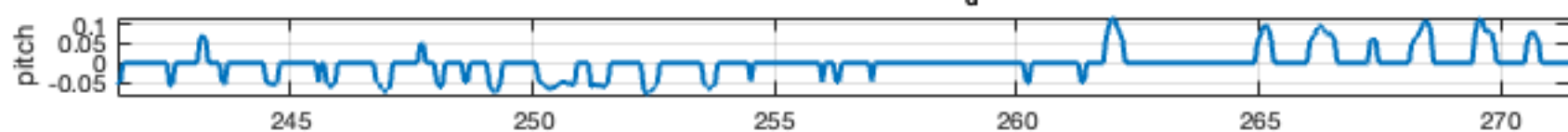
Josh Zero Cross orient_data



Josh Zero Cross orient_data



Josh Zero Cross orient_data



Josh Zero Cross orient_data



Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	-1173	-627	-222	-199.2500	"orient_data"
'qy'	-1768	-939	-372	-177.5000	"orient_data"
'qx'	-1955	-1117	-464	-81.5000	"orient_data"
'qw'	-1165	-793	-276	-133	"orient_data"
'roll'	-1374	-1096	-474	-635.7500	"orient_data"
'pitch'	-2009	-1163	-655	-499.7500	"orient_data"
'yaw'	-1698	-1056	-473	-494.7500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"X"	'double_findpeaks'	988
'bar_data'	"Pressure"	'double_findpeaks'	375
'gyro_data'	"Y"	'double_findpeaks'	859
'grav_data'	"Y"	'zero_cross'	262.5
'orient_data'	"qx"	'zero_cross'	81.5