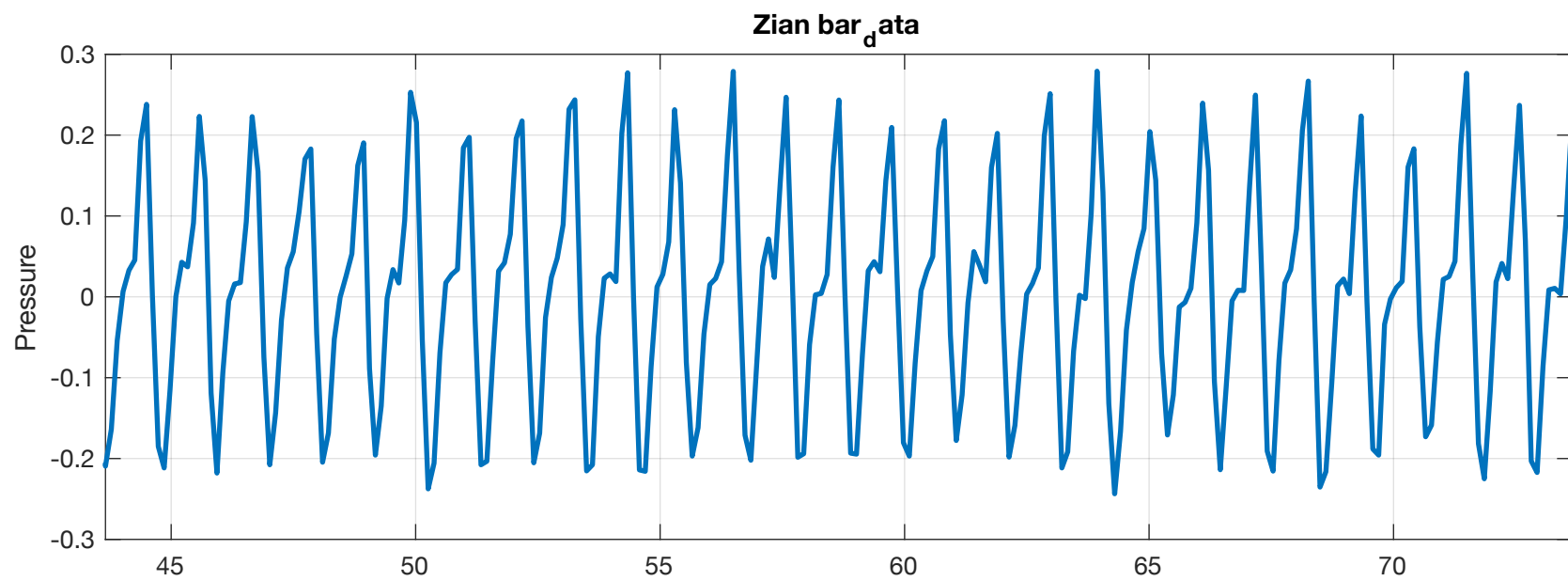
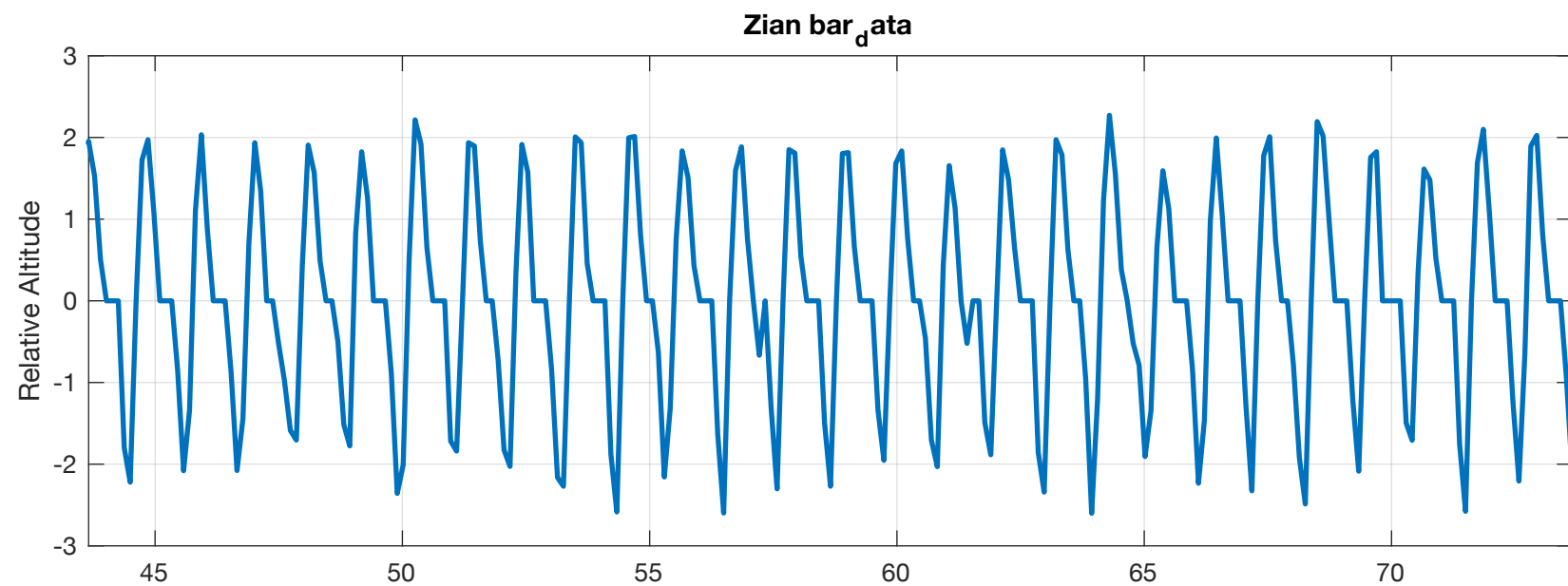
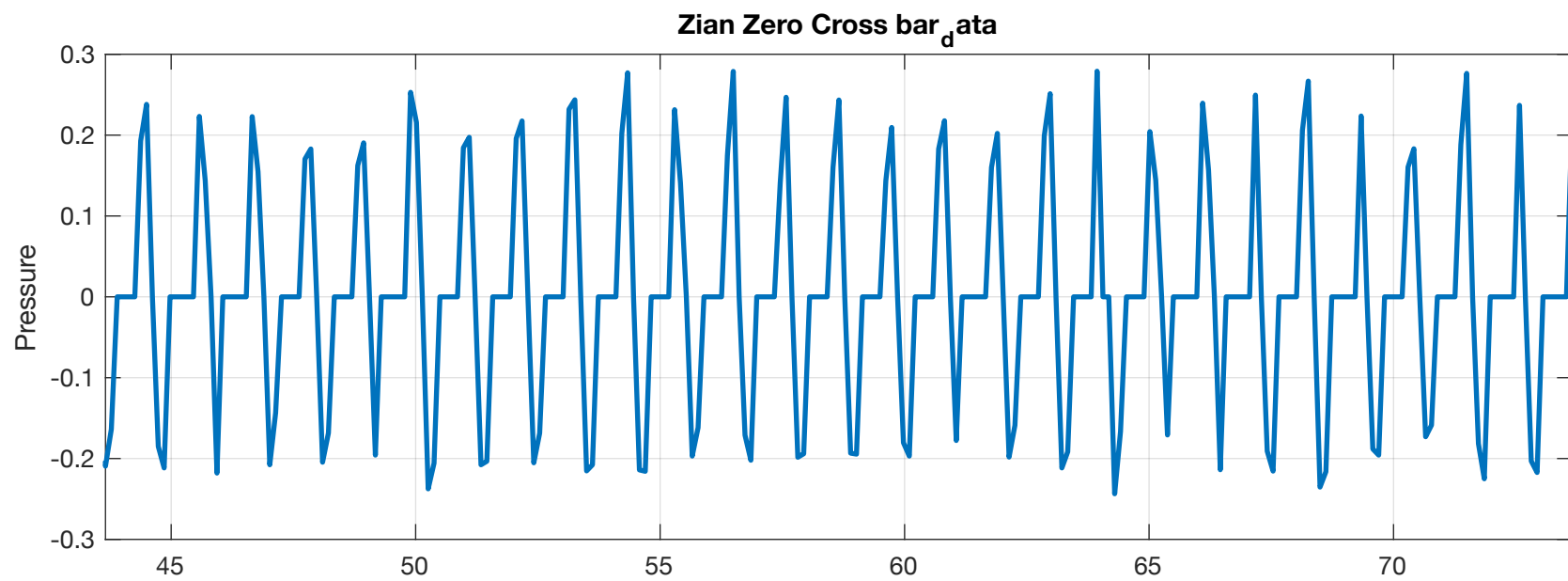
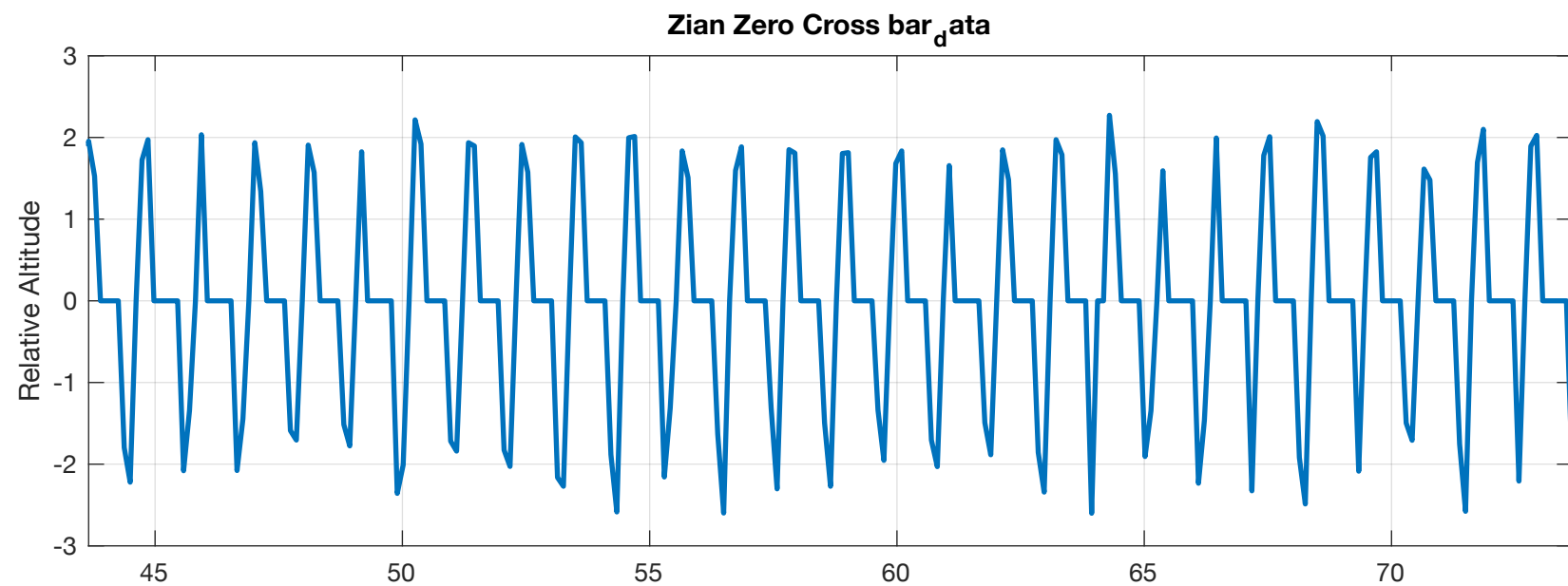
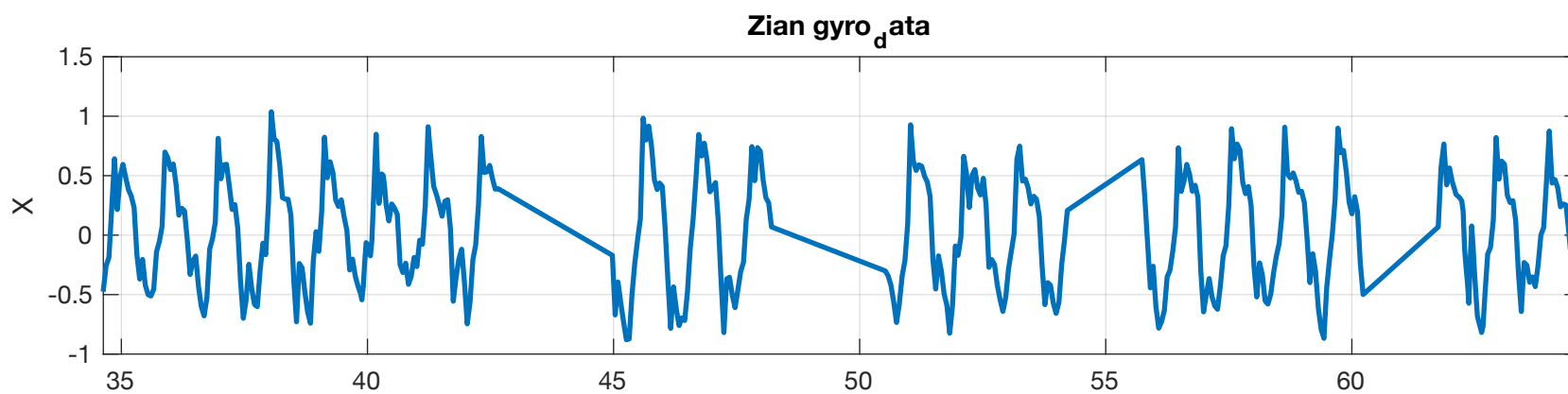
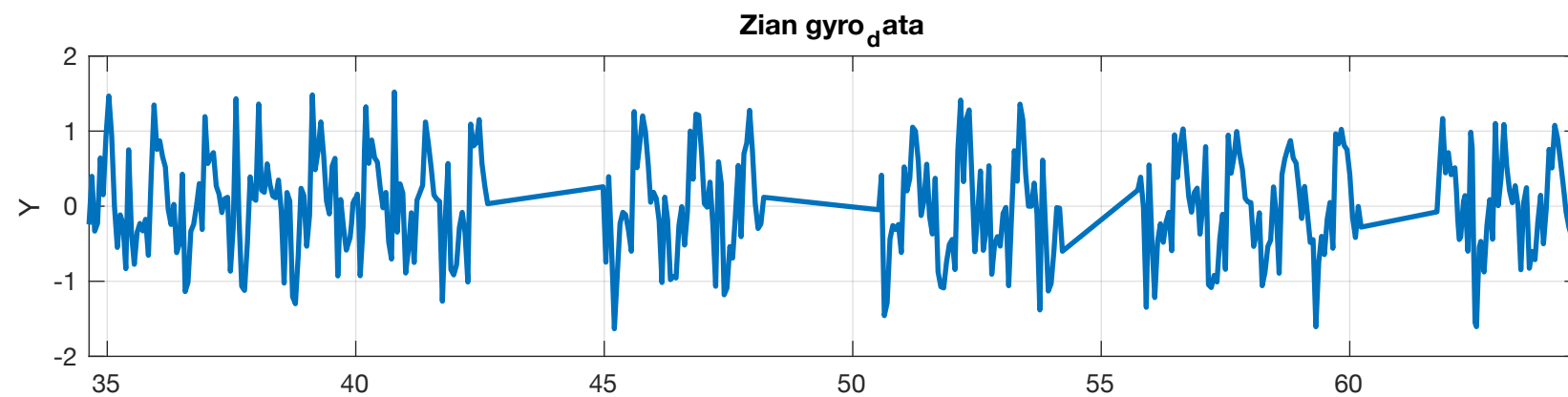
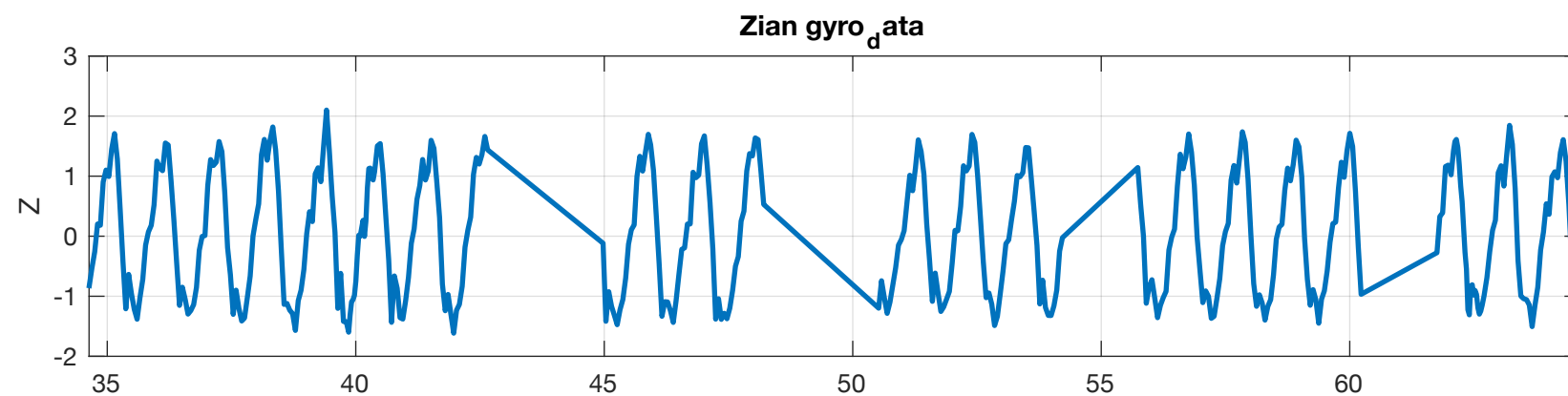


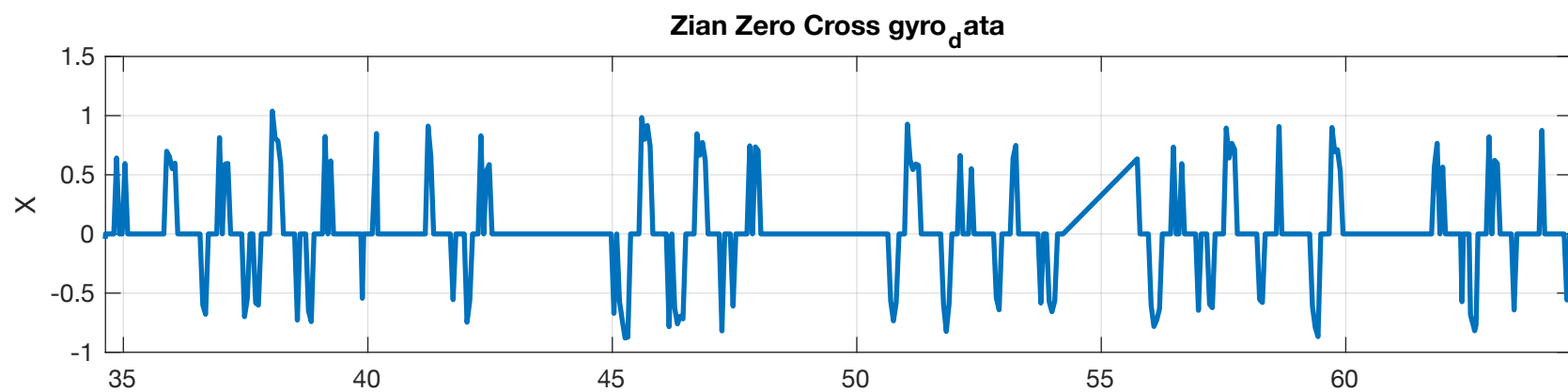
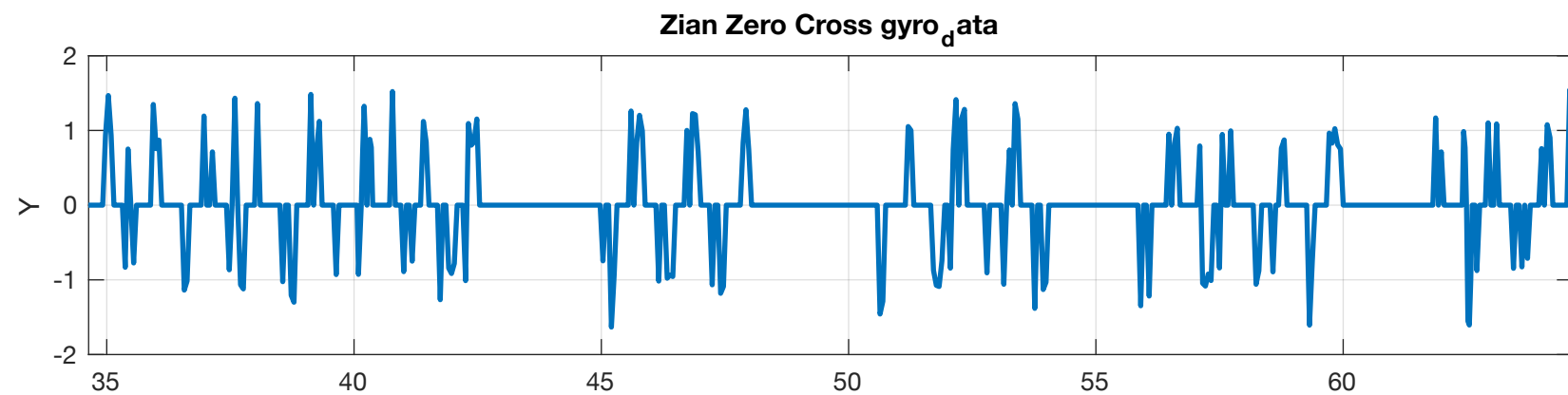
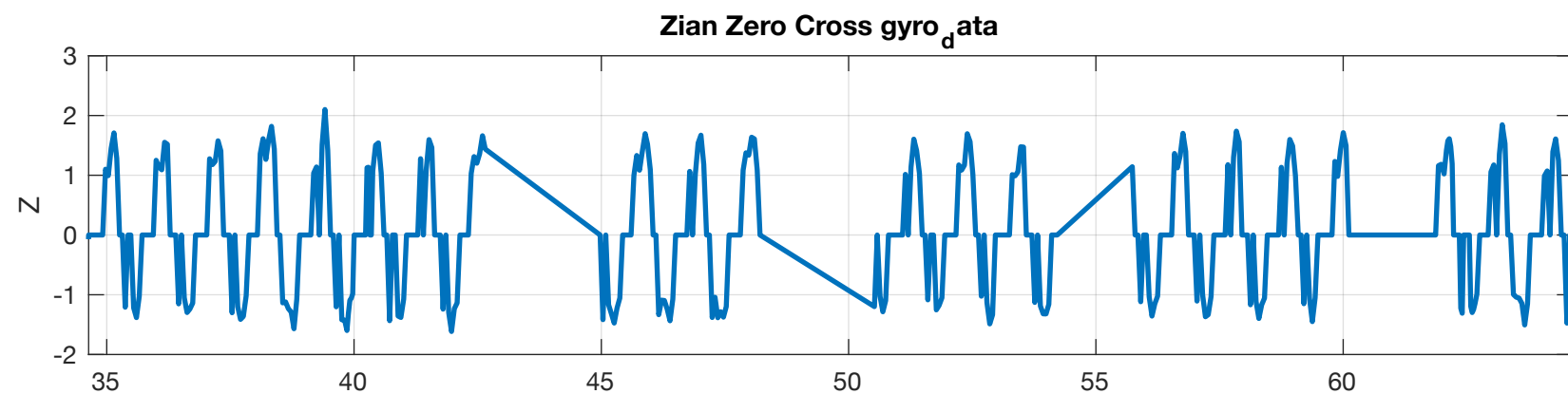
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-498.000	-182.000	12.000	87.500	"accel_data"
'Y'	-259.000	-171.000	89.000	0.000	"accel_data"
'X'	-465.000	-381.000	98.000	-1.500	"accel_data"



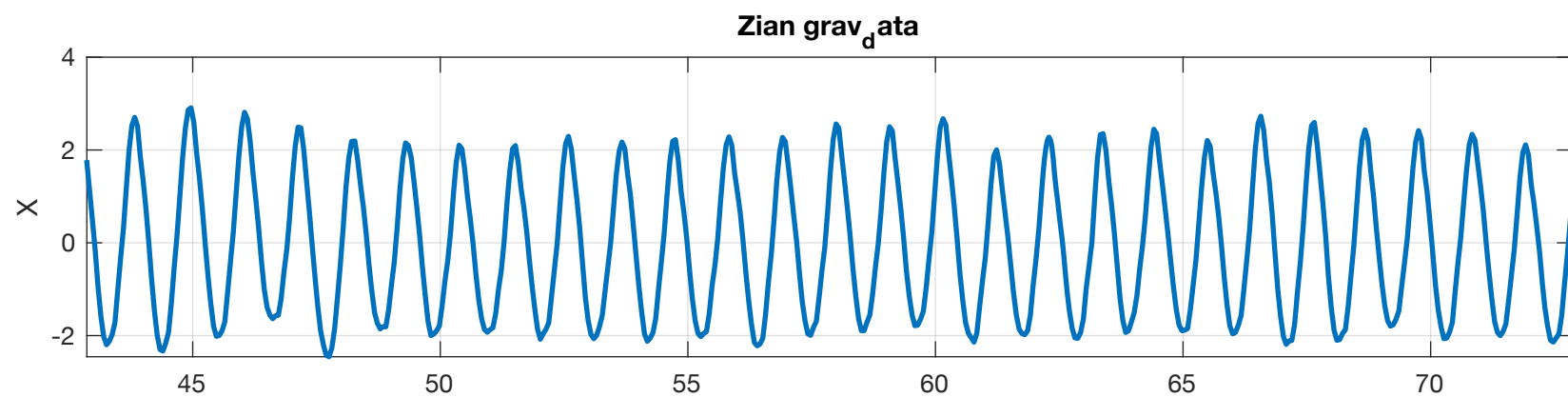
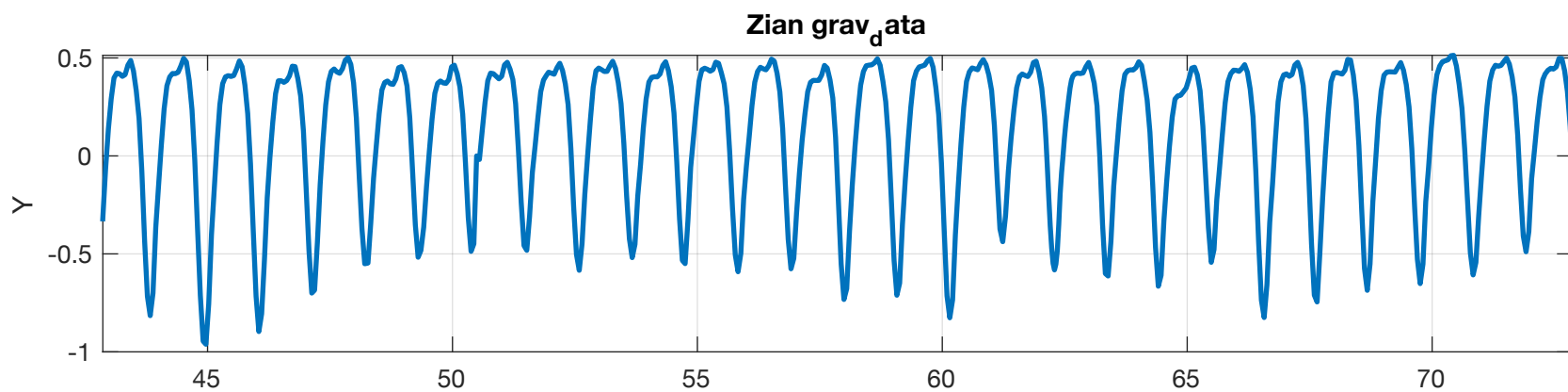
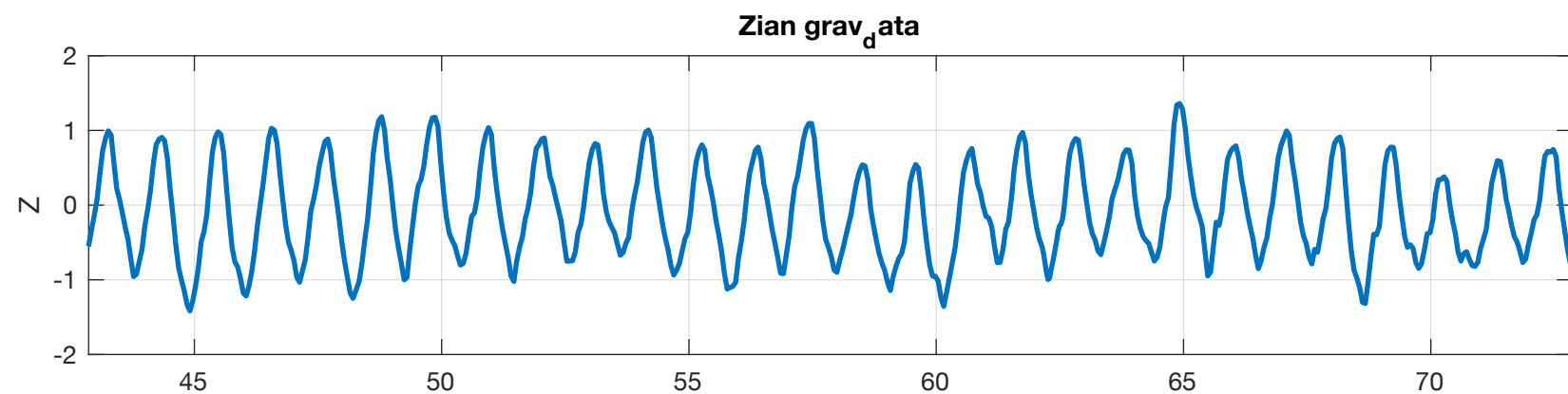


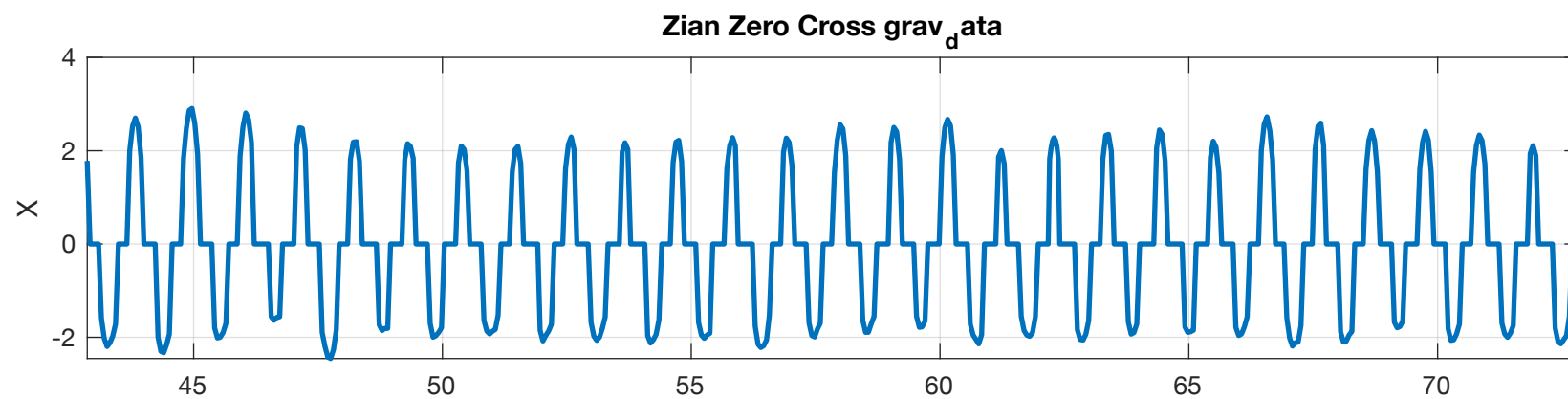
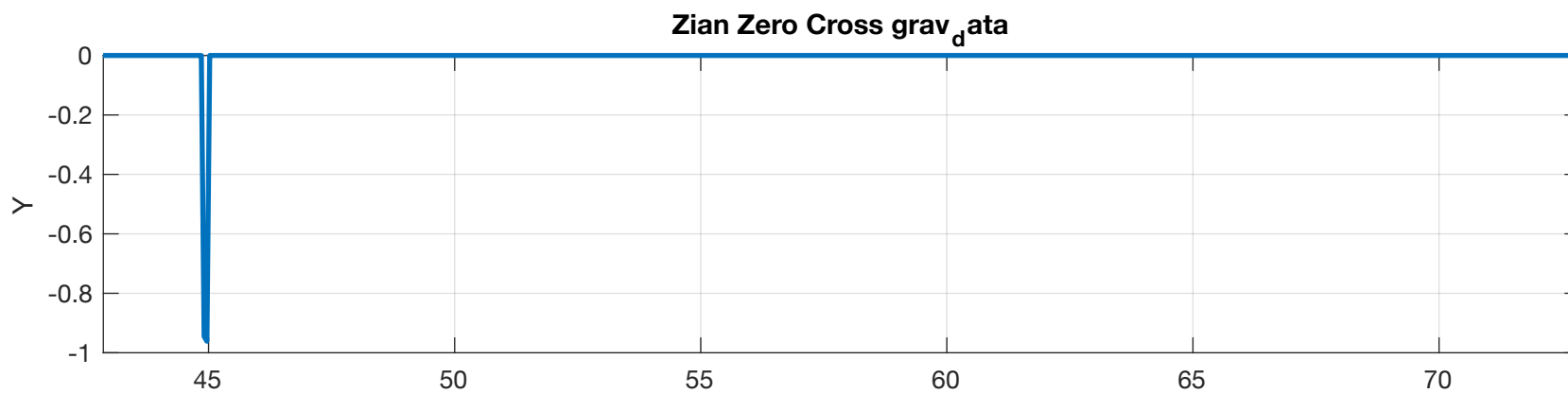
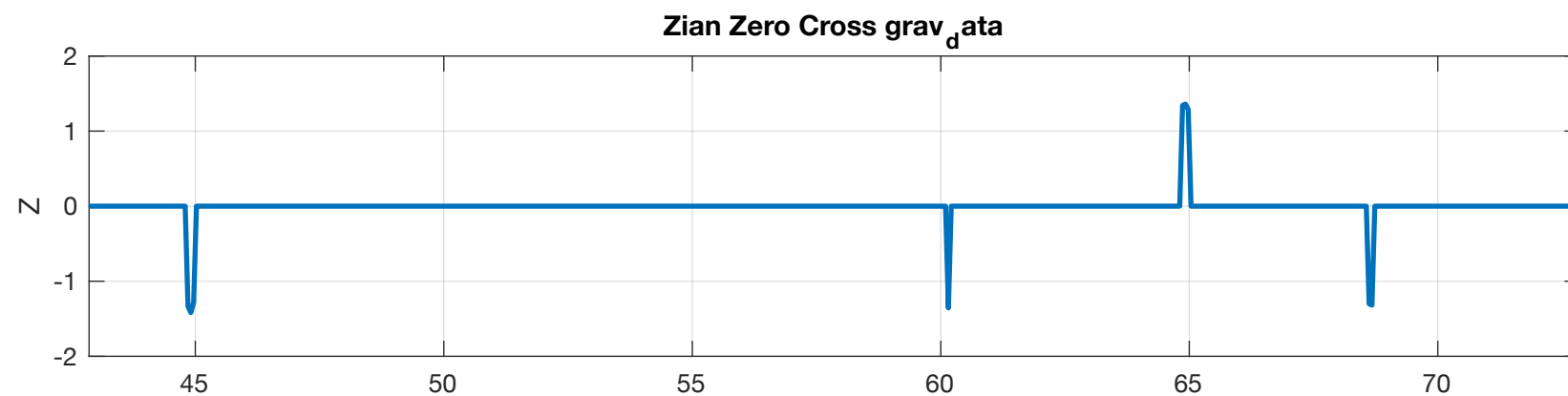
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
"Relative Altitude"	130.000	145.000	245.000	148.250	"bar_data"
"Pressure"	60.000	68.000	211.000	148.250	"bar_data"



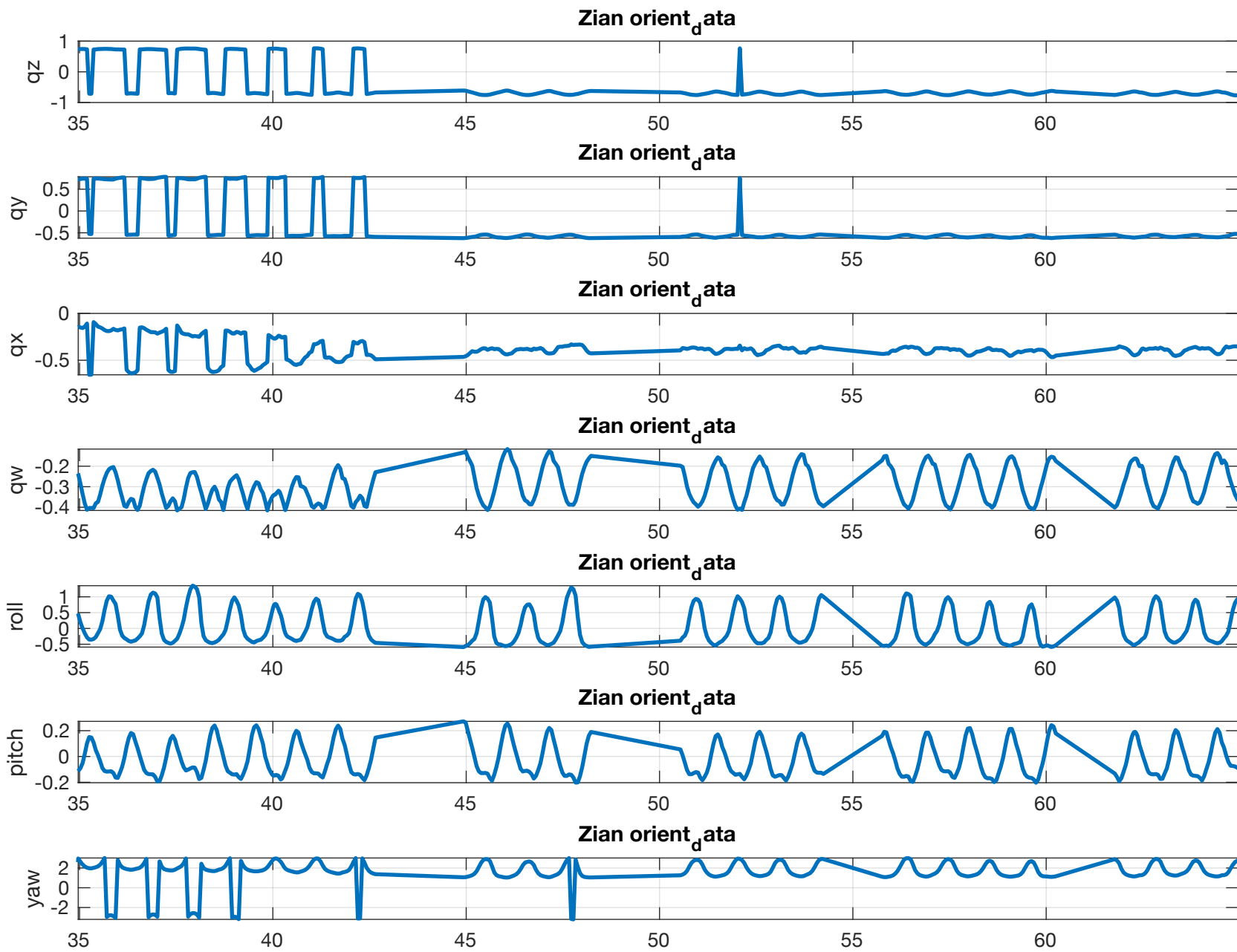


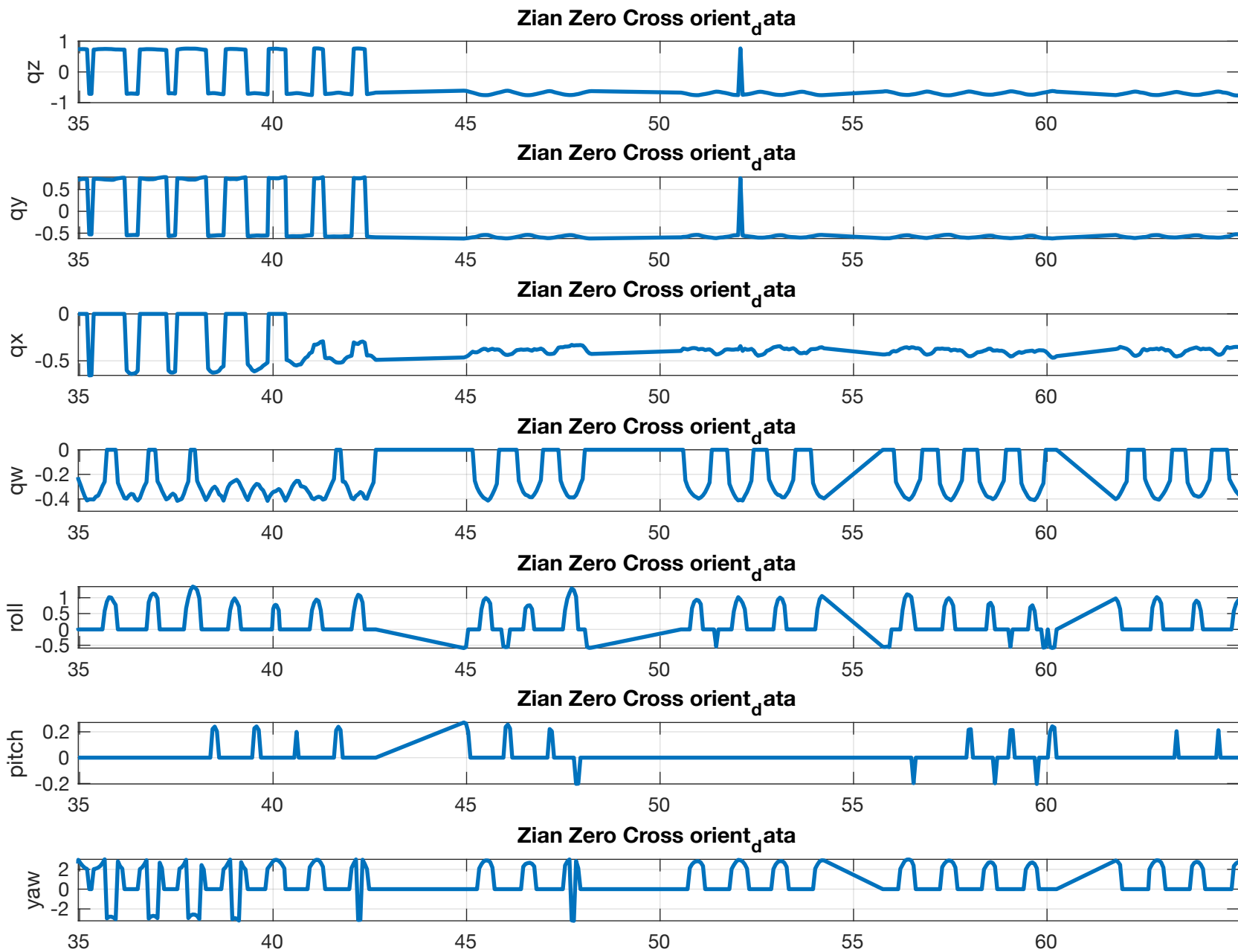
Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	-112.000	31.000	175.000	115.500	"gyro_data"
'Y'	-343.000	-181.000	118.000	105.500	"gyro_data"
'X'	-186.000	-45.000	168.000	142.250	"gyro_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'Z'	88.000	131.000	239.000	281.750	"grav_data"
'Y'	14.000	25.000	180.000	296.250	"grav_data"
'X'	123.000	136.000	248.000	151.250	"grav_data"





Axis	findpeaks	findpeaks_above_zero	double_findpeaks	zero_cross	Sensor
'qz'	112.000	172.000	259.000	279.000	"orient_data"
'qy'	-2.000	95.000	237.000	285.000	"orient_data"
'qx'	-33.000	139.000	245.000	280.500	"orient_data"
'qw'	123.000	200.000	272.000	263.750	"orient_data"
'roll'	135.000	172.000	254.000	221.250	"orient_data"
'pitch'	79.000	163.000	213.000	255.750	"orient_data"
'yaw'	116.000	183.000	255.000	235.500	"orient_data"

Sensor	Sensor Axis	Method	Error
'accel_data'	"Y"	'zero_cross'	0.000
'bar_data'	"Pressure"	'findpeaks'	60.000
'gyro_data'	"Z"	'findpeaks_above_zero'	31.000
'grav_data'	"Y"	'findpeaks'	14.000
'orient_data'	"qy"	'findpeaks'	2.000