



# ❖ CASE STUDIES IN FILTER DESIGN (Digital Domain)

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## ❖ Case 1: Low-Pass Filter for Smoothing a Noisy Signal

### 🔧 Requirement:

Remove high-frequency noise  $>1\text{kHz}$  from a speech signal sampled at  $8\text{kHz}$ .

### ⚙️ Filter Type:

FIR Low-pass filter

### ❖ Insight:

Design  $h[n]$  to suppress frequencies above cutoff. Sinc-based kernel tapered with window (to control side lobes).

## Python:

```
from scipy.signal import firwin, lfilter, freqz
import numpy as np
import matplotlib.pyplot as plt

fs = 8000          # Sampling frequency
cutoff = 1000      # Desired cutoff in Hz
numtaps = 51       # Filter length

h = firwin(numtaps, cutoff, fs=fs)

# Plot impulse response h[n]
plt.stem(h, basefmt=" ")
plt.title("Impulse Response h[n] - Low-Pass Filter")
plt.xlabel("n"); plt.ylabel("Amplitude"); plt.grid()
plt.show()

# Frequency response
w, H = freqz(h, worN=8000, fs=fs)
plt.plot(w, 20*np.log10(np.abs(H)))
plt.title("Frequency Response")
plt.xlabel("Frequency (Hz)"); plt.ylabel("Magnitude (dB)"); plt.grid()
plt.show()
```

## Result:

- $h[n]$  looks like a sinc wave, windowed to suppress ripples.
  - Frequency response shows clean cutoff at 1kHz.
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## ❖ Case 2: High-Pass Filter to Remove DC/Slow Drift

### 🎯 Requirement:

Remove low-frequency drift or DC bias (e.g., baseline wander in biosignals).

### ⚙️ Filter Type:

FIR High-pass

### ❖ Insight:

Design  $h[n]$  to kill 0 Hz (DC). Usually symmetrical with alternating sign pattern.

### ❖ Python:

```
h = firwin(51, 300, fs=2000, pass_zero=False) # High-pass: cutoff = 300 Hz

plt.stem(h, basefmt=" ")
plt.title("h[n] - High-Pass Filter")
plt.xlabel("n"); plt.ylabel("Amplitude"); plt.grid()
plt.show()

w, H = freqz(h, worN=8000, fs=2000)
plt.plot(w, 20*np.log10(np.abs(H)))
plt.title("Frequency Response - High Pass")
plt.xlabel("Frequency (Hz)"); plt.ylabel("Magnitude (dB)"); plt.grid()
plt.show()
```

### 🔍 Result:

- $h[n]$  shows positive and negative swings (to cancel slow changes).
  - DC (0 Hz) is strongly attenuated.
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## 🎯 Case 3: Band-Pass Filter for Voice Detection (300–3000 Hz)

### 🎯 Requirement:

Extract the speech component from a broadband signal (as in SDR or telephony).

### ⚙️ Filter Type:

FIR Band-pass

### 💡 Insight:

Keep only the frequencies between 300–3000 Hz, reject below and above.

### 💡 Python:

```
h = firwin(101, [300, 3000], fs=8000, pass_zero=False)

plt.stem(h, basefmt=" ")
plt.title("h[n] - Band-Pass Filter (300-3000 Hz)")
plt.grid(); plt.xlabel("n"); plt.ylabel("Amplitude")
plt.show()

w, H = freqz(h, worN=8000, fs=8000)
plt.plot(w, 20*np.log10(np.abs(H)))
plt.title("Band-Pass Filter Response")
plt.xlabel("Frequency (Hz)"); plt.ylabel("Magnitude (dB)")
plt.grid(); plt.show()
```

### 🔍 Result:

- $h[n]$  is a band-limited sinc-shaped waveform.
  - Frequency response passes only 300–3000 Hz — ideal for voice.
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# ● Case 4: Notch Filter to Remove 50 Hz Powerline Interference

## 🎯 Requirement:

Eliminate 50 Hz hum from a signal (e.g., ECG or audio).

## ⚙️ Filter Type:

FIR Band-stop (Notch)

## 💡 Insight:

Design a dip in the frequency response centered at 50 Hz.

## 💡 Python:

```
h = firwin(201, [48, 52], fs=1000, pass_zero=True)

plt.stem(h, basefmt=" ")
plt.title("h[n] - Notch Filter (50 Hz)")
plt.grid(); plt.xlabel("n"); plt.ylabel("Amplitude")
plt.show()

w, H = freqz(h, worN=8000, fs=1000)
plt.plot(w, 20*np.log10(np.abs(H)))
plt.title("Notch Filter Response (50 Hz)")
plt.xlabel("Frequency (Hz)"); plt.ylabel("Magnitude (dB)")
plt.grid(); plt.show()
```

## 🔍 Result:

- Deep notch around 50 Hz.
  - $h[n]$  is symmetric and longer — needed for sharp notching.
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## ❖ Case 5: Matched Filter for Known Pulse Detection

### 🎯 Requirement:

Detect a known signal shape (e.g., radar return, chirp).

### ⚙️ Filter Type:

Matched filter = time-reversed version of target signal

### ❖ Insight:

Maximum correlation when signal and filter align.

### ❖ Python:

```
pulse = np.concatenate([np.ones(10), np.zeros(90)]) # Simulated short pulse
h = pulse[::-1] # Matched filter: time-reversed

plt.stem(h, basefmt=" ")
plt.title("h[n] - Matched Filter")
plt.grid(); plt.xlabel("n"); plt.ylabel("Amplitude")
plt.show()
```

### 🔍 Result:

- Output of convolution peaks when the signal aligns with pulse.
  - Used in radar, sonar, signal synchronization.
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## ✓ Summary Table

Case	Filter Type	Purpose	Key Feature of $h[n]$
1	Low-pass	Remove noise	Sinc-like, smooth
2	High-pass	Remove drift	Alternating signs
3	Band-pass	Extract voice	Band-limited sinc
4	Notch	Kill 50 Hz	Deep zero at 50 Hz
5	Matched	Detect shape	Time-reversed target