

C/C++ Program Design cs205

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Improve Your Source Code

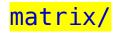




Suggestions to your Project 3

- Use size_t for mat.cols and mat.rows
- Use memcpy() to copy data. Element assignment has a lower efficiency.
- Use 1D array (float*) nor 2D array (float**) for matrix data.
- Redundant computation in loops
- Do parameter checking in functions: null pointers, dimension matching in matrix operations, etc.
- Do not bind the create matrix function with file I/O.
- File name: 1.c, 2.c, 3.h
- Good implementation VS good homework.







Derived Classes





Inheritance

- Inherit members (attributes and functions) from one class
 - Base class (parent)
 - Derived class (child)
- C++ supports multiple inheritance and multilevel inheritance

```
class Derived: public Base1, public Base2

class Base
{
    public:
        int a;
        int b;
};
class Derived: public Base
{
    public:
        int c;
};
```



Constructors

- To instantiate a derived class object
 - Allocate memory
 - Derived constructor is invoked
 - ✓ Base object is constructed by a base constructor
 - ✓ Member initializer list initializes members
 - ✓ To execute the body of the derived constructor

```
class Derived: public Base
{
  public:
    int c;
    Derived(int c): Base(c - 2, c - 1), c(c)
    {
        ...
    }
};
```





Destructors

- The destructor of the derived class is invoked first,
- Then the destructor of the base class.



Access Control





Member Access

- Public members
 - Accessible anywhere
- Private members
 - Only accessible to the members

```
class Person {
                                   and friends of that class
  private:
    int n; // private member
  public:
    // this->n is accessible
    Person(): n(10) {}
    // other n is accessible
    Person(const Person& other) : n(other.n) {}
    // this->n is accessible
    void set(int n) {this->n = n;}
    // this->n and other.n are accessible
    void set(const Person& other) {this->n = other.n;}
};
```





Member Access

```
// a non-member non-friend function
void compare(Base& b, Derived& d)
{
    // b.n++; // Error
    // d.n++; // Error
}
```

- Protected members
 - > Accessible to the members and friends of that class
 - Accessible to the members and friends of the derived class

```
class Base
{
  protected:
    int n;
  private:
    void foo1(Base& b)
    {
        n++; // Okay
        b.n++; // Okay
    }
};
```

```
class Derived : public Base
{
    void foo2(Base& b, Derived& d)
    {
        n++; //0kay
        this->n++; //0kay
        //b.n++; //Error.
        d.n++; //0kay
    }
};
```





Public Inheritance

- Public members of the base class
 - > Still be public in the derived class
 - Accessible anywhere
- Protected members of the base class
 - Still be protected in the derived class
 - Accessible in the derived class only
- Private members of the base class
 - Not accessible in the derived class

```
class Derived : public Base
{
    ...
}
```





Protected Inheritance

- Public members and protected members of the base class
 - > Be **protected** in the derived class
 - Accessible in the derived class only
- Private members of the base class
 - Not accessible in the derived class

```
class Derived : protect Base
{
    ...
}
```





Private Inheritance

- Public members and protected members of the base class
 - > Be **private** in the derived class
 - Accessible in the derived class only
- Private members of the base class
 - Not accessible in the derived class

```
class Derived : private Base
{
    ...
}
```





Virtual Functions





Virtual Functions

Let's look at the example first, what will be the output?

```
class Person
                                          Person * p = new Student();
  public:
                                          p->print(); // call Person::print()?
    void print()
        cout << "Name: " << name << endl;</pre>
};
class Student: public Person
  public:
    void print()
        cout << "Name: " << name;</pre>
        cout << ". ID: " << id << endl;
   virtual.cpp
```



Virtual Functions

- But if we define print() function as a virtual function, the output will be different.
- Static binding: the compiler decides which function to call
- **Dynamic** binding: the called function is decided at runtime.

 Keyword virtual makes the function virtual for the base and all derived classes.





Virtual Destructors

• If a destructor is not virtual, only the destructor of the base class is executed in the follow examples.

```
Person * p = new Student("xue", "2020");
p->print();
...
delete p; //if its destructor is not virtual
```





Inheritance and Dynamic Memory Allocation





Question

• If a base class uses dynamic memory allocation, and redefines a copy constructor and assignment operator

 Case 1: If no dynamic memory allocation in the derived class, no special operations are needed

 Case 2: if dynamic memory is allocated in the derived class, you should redefine a copy constructor and an assignment operator.





Case 2

```
class MyMap: pubic MyString
    char * keyname;
  public:
   MyMap(const char * key, const char * value)
   MyMap(const MyMap & mm): MyString(mm.buf_len, mm.characters)
    //allocate memory for keyname
    //and hard copy from mm to *this
   MyMap & operator=(const MyMap &mm)
      MyString::operator=(mm);
       //allocate memory for keyname
       //and hard copy from mm to *this
       return *this;
```





Examples in OpenCV





Derived cv::Mat_

Template matrix class derived from cv::Mat, a wrapper, more C++ style.

```
modules/core/include/opencv2/core/mat.hpp
2198 template<typename _Tp> class Mat_ : public Mat
       2199
       2200
              public:
       2201
                  typedef Tp value type;
       2202
                   typedef typename DataType<_Tp>::channel_type channel_type;
       2203
                  typedef MatIterator_<_Tp> iterator;
       2204
                   typedef MatConstIterator < Tp> const iterator;
       2205
       2206
                   //! default constructor
       2207
                  Mat () CV NOEXCEPT;
       2208
                   //! equivalent to Mat(_rows, _cols, DataType<_Tp>::type)
       2209
                   Mat_(int _rows, int _cols);
                   //! constructor that sets each matrix element to specified value
       2210
       2211
                   Mat_(int _rows, int _cols, const _Tp& value);
       2212
                   //! equivalent to Mat(_size, DataType<_Tp>::type)
       2213
                   explicit Mat (Size size);
       2214
                   //! constructor that sets each matrix element to specified value
       2215
                   Mat_(Size _size, const _Tp& value);
```



cv::Matx

 A template class for small matrices whose type and size are known at compilation time.

modules/core/include/opencv2/core/matx.hpp

```
template<typename _Tp, int m, int n> class Matx
100
101
     public:
102
         enum {
103
                 rows
                          = m,
104
                 cols
                          = n,
105
                 channels = rows*cols,
106
     #ifdef OPENCV_TRAITS_ENABLE_DEPRECATED
107
                          = traits::Type<_Tp>::value,
                 depth
                          = CV_MAKETYPE(depth, channels),
108
                 type
109
     #endif
                 shortdim = (m < n ? m : n)
110
111
               };
112
113
         typedef _Tp
                                                 value_type;
114
         typedef Matx<_Tp, m, n>
                                                 mat_type;
         typedef Matx<_Tp, shortdim, 1> diag_type;
115
116
          //! default constructor
         Matx();
```

cv::Vec

modules/core/include/opencv2/core/matx.hpp

```
template<typename _Tp, int cn> class Vec : public Matx<_Tp, cn, 1>
public:
                                                            Vec<float, 3> xyz(1.2f, 2.3f, 3.4f);
    typedef _Tp value_type;
    enum {
           channels = cn,
#ifdef OPENCV_TRAITS_ENABLE_DEPRECATED
           depth
                    = Matx<_Tp, cn, 1>::depth,
                    = CV MAKETYPE(depth, channels),
           type
#endif
           _dummy_enum_finalizer = 0
         };
    //! default constructor
    Vec();
    Vec(_Tp v0); //!< 1-element vector constructor</pre>
    Vec(_Tp v0, _Tp v1); //!< 2-element vector constructor</pre>
    Vec(_Tp v0, _Tp v1, _Tp v2); //!< 3-element vector constructor</pre>
    Vec(_Tp v0, _Tp v1, _Tp v2, _Tp v3); //!< 4-element vector construct</pre>
    Vec(_Tp v0, _Tp v1, _Tp v2, _Tp v3, _Tp v4); //!< 5-element vector collection</pre>
```



Combined with typedef

modules/core/include/opencv2/core/matx.hpp

```
409
     typedef Vec<uchar, 2> Vec2b;
     typedef Vec<uchar, 3> Vec3b;
410
     typedef Vec<uchar, 4> Vec4b;
411
412
413
     typedef Vec<short, 2> Vec2s;
     typedef Vec<short, 3> Vec3s;
414
     typedef Vec<short, 4> Vec4s;
415
416
417
     typedef Vec<ushort, 2> Vec2w;
418
     typedef Vec<ushort, 3> Vec3w;
419
     typedef Vec<ushort, 4> Vec4w;
420
     typedef Vec<int, 2> Vec2i;
421
     typedef Vec<int, 3> Vec3i;
422
423
     typedef Vec<int, 4> Vec4i;
     typedef Vec<int, 6> Vec6i;
424
425
     typedef Vec<int, 8> Vec8i;
426
     typedef Vec<float, 2> Vec2f;
427
428
     typedef Vec<float, 3> Vec3f;
     typedef Vec<float, 4> Vec4f;
429
     typedef Vec<float. 6> Vec6f:
430
```

```
Vec<float, 3> xyz(1.2f, 2.3f, 3.4f);
Vec3f xyz(1.2f, 2.3f, 3.4f);
```



Combined with typedef

```
221
     typedef Matx<float, 1, 2> Matx12f;
222
     typedef Matx<double, 1, 2> Matx12d;
223
     typedef Matx<float, 1, 3> Matx13f;
224
     typedef Matx<double, 1, 3> Matx13d;
225
     typedef Matx<float, 1, 4> Matx14f;
226
     typedef Matx<double, 1, 4> Matx14d;
     typedef Matx<float, 1, 6> Matx16f;
227
228
     typedef Matx<double, 1, 6> Matx16d;
229
230
     typedef Matx<float, 2, 1> Matx21f;
231
     typedef Matx<double, 2, 1> Matx21d;
232
     typedef Matx<float, 3, 1> Matx31f;
233
     typedef Matx<double, 3, 1> Matx31d;
234
     typedef Matx<float, 4, 1> Matx41f;
235
     typedef Matx<double, 4, 1> Matx41d;
     typedef Matx<float, 6, 1> Matx61f;
236
237
     typedef Matx<double, 6, 1> Matx61d;
238
239
     typedef Matx<float, 2, 2> Matx22f;
240
     typedef Matx<double, 2, 2> Matx22d;
     typedef Matx<float, 2, 3> Matx23f;
241
     typedef Matx<double, 2, 3> Matx23d:
```

