

## Practice Problems:

### Basis of subspace:

1.

Find a basis and dimension of the subspace  $W$  of  $\mathbf{R}^3$  where

(a)  $W = \{(a, b, c) : a + b + c = 0\}$ , (b)  $W = \{(a, b, c) : (a = b = c)\}$

(a) Note that  $W \neq \mathbf{R}^3$ , because, for example,  $(1, 2, 3) \notin W$ . Thus,  $\dim W < 3$ . Note that  $u_1 = (1, 0, -1)$  and  $u_2 = (0, 1, -1)$  are two independent vectors in  $W$ . Thus,  $\dim W = 2$ , and so  $u_1$  and  $u_2$  form a basis of  $W$ .

(b) The vector  $u = (1, 1, 1) \in W$ . Any vector  $w \in W$  has the form  $w = (k, k, k)$ . Hence,  $w = ku$ . Thus,  $u$  spans  $W$  and  $\dim W = 1$ .

2.

Let  $V$  be the vector space of  $2 \times 2$  matrices over  $K$ . Let  $W$  be the subspace of symmetric matrices. Show that  $\dim W = 3$ , by finding a basis of  $W$ .

Recall that a matrix  $A = [a_{ij}]$  is symmetric if  $A^T = A$ , or, equivalently, each  $a_{ij} = a_{ji}$ . Thus,  $A = \begin{bmatrix} a & b \\ b & d \end{bmatrix}$  denotes an arbitrary  $2 \times 2$  symmetric matrix. Setting (i)  $a = 1, b = 0, d = 0$ ; (ii)  $a = 0, b = 1, d = 0$ ; (iii)  $a = 0, b = 0, d = 1$ , we obtain the respective matrices:

$$E_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad E_2 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad E_3 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

We claim that  $S = \{E_1, E_2, E_3\}$  is a basis of  $W$ ; that is, (a)  $S$  spans  $W$  and (b)  $S$  is linearly independent.

(a) The above matrix  $A = \begin{bmatrix} a & b \\ b & d \end{bmatrix} = aE_1 + bE_2 + dE_3$ . Thus,  $S$  spans  $W$ .

(b) Suppose  $xE_1 + yE_2 + zE_3 = 0$ , where  $x, y, z$  are unknown scalars. That is, suppose

$$x \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + y \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} + z \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad \text{or} \quad \begin{bmatrix} x & y \\ y & z \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Setting corresponding entries equal to each other yields  $x = 0, y = 0, z = 0$ . Thus,  $S$  is linearly independent. Therefore,  $S$  is a basis of  $W$ , as claimed.

### Interpolation:

1. Find a polynomial  $p(x)$  of degree 3, such that  $p(0) = 1, p'(0) = 2, p(1) = 4, p'(1) = 4$ .
2. Find the equation of circle passing through points  $(2, -2), (3, 5)$  and  $(-4, 6)$ .

### Linear Transformation:

1. Which of the following map is linear transform:

- $T_1 : \mathbb{R}^2 \rightarrow \mathbb{R}^2, T_1(x, y) = (|x|, 0)$ .
- $T_2 : \mathbb{P}_2 \rightarrow \mathbb{R}^2, T_2(a_0 + a_1t + a_2t^2) = (a_0 + a_1, a_2)$
- $T_3 : \mathbb{P}_2 \rightarrow \mathbb{R}^3, T_3(a_0 + a_1t + a_2t^2) = (a_1 - a_2, a_0 + 1)$
- $T_4 : \mathbb{M}_{2 \times 2} \rightarrow \mathbb{R}^3, T_4 \left( \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = (a + d, b + c, a)$ .
- $T_5 : \mathbb{M}_{2 \times 2} \rightarrow \mathbb{R}^3, T_5(A) = A^T$ .

- $T_6 : \mathbb{P}_3 \rightarrow \mathbb{P}_2, T_6(p(t)) = \frac{d}{dt}p(t).$

2. Check the invertibility of the following linear transformations and also find the inverse transform if exist:

- $T_1 : \mathbb{R}^2 \rightarrow \mathbb{R}^2, T_1(x, y) = (x + y, x - y)$
- $T_2 : \mathbb{R}^3 \rightarrow \mathbb{R}^3, T_2(x, y, z) = (2x + 3y, z - 4y, x + z)$
- $T_3 : \mathbb{P}_2 \rightarrow \mathbb{R}^3, T_3(a_0 + a_1t + a_2t^2) = (a_0 - a_1, 0, a_1 - a_2).$
- $T_4 : \mathbb{P}_2 \rightarrow \mathbb{R}^3, T_4(a_0 + a_1t + a_2t^2) = (0, a_2 - a_0, a_1 - a_3).$
- $T_5 : \mathbb{P}_2 \rightarrow \mathbb{R}^3, T_5(p(t)) = T_3(p(t)) + T_4(p(t)).$

3. Find the matrix of transformation of the following linear transformations:

- $T_1 : \mathbb{P}_2 \rightarrow \mathbb{R}^3, T_1(a_0 + a_1t + a_2t^2) = (a_0 - a_1, 0, a_1 - a_3).$  Find  $[T]_\alpha^\beta$ ,  $\alpha$  and  $\beta$  are the standard basis of  $\mathbb{P}_2$  and  $\mathbb{R}^3$  respectively.
- $T_2 : \mathbb{R}^3 \rightarrow \mathbb{R}^4, T_2(x, y, z) = (x + 2y, y + 3z, y - z, x + z).$  find  $[T]_\alpha^\beta$  and  $[T]_\alpha^\gamma$ , where  $\alpha$  is the standard basis of  $\mathbb{R}^3$ ,  $\beta$  is the standard basis of  $\mathbb{R}^4$  and  $\gamma = \{(1, 1, 1, 1), (1, 1, 1, 0), (1, 1, 0, 0), (1, 0, 0, 0)\}.$
- $T_3 : \mathbb{R}^4 \rightarrow \mathbb{R}^4, T_3(x, y, z, w) = (x + 2y, y + 3z, w + y - z, x + z).$  Find  $[T]_\alpha$  and hence find  $[T]_\beta$  using similarity transform, where  $\alpha$  is the standard basis of  $\mathbb{R}^4$  and  $\beta = \{(1, 1, 1, 1), (1, 1, 1, 0), (1, 1, 0, 0), (1, 0, 0, 0)\}.$
- Given  $T_4 : \mathbb{R}^3 \rightarrow \mathbb{R}^3, T_4(x, y, z) = (2x, y + z, 3y)$  and  $T_5 : \mathbb{R}^3 \rightarrow \mathbb{R}^3, T_5(x, y, z) = (-x, y - z, 4y).$  Also  $\alpha$  are  $\beta$  are the bases of  $\mathbb{R}^3$ , where  $\alpha$  is the standard basis and  $\beta = \{(1, 0, 1), (0, 1, 1), (1, 1, 0)\}.$  Then find (i)  $[T_4]_\alpha^\beta$  (ii)  $[T_5]_\alpha^\beta$  (iii)  $[T_4 + T_5]_\alpha^\beta$  (iv)  $[T_4^{-1}]_\alpha^\beta$  (v)  $[T_5^{-1}]_\alpha^\beta$  (vi)  $[(T_4 + T_5)^{-1}]_\alpha^\beta.$

**Gram-Schmidt ortho-normalization process:**

1.  $\alpha = \{(2, 3, 1, 1), (1, 0, 2, 5), (2, 1, 3, 0), (1, 1, 1, 1)\}$  is a basis of  $\mathbb{R}^4$ . Use the Gram-Schmidt ortho-normalization process to transform  $\alpha$  into orth-onormal basis.
2.  $\beta = \{2 + t, 2t^2, 3 - t^2\}$  is a basis of  $\mathbb{P}_2$ . Use the G-S ortho-normalization process to transform  $\beta$  into ortho-normal basis.

**Matrix representation of linear transform:**

1.  $(\mathbb{R}^3, \langle \rangle)$  is an inner product space with  $\{(1, 0, 0), (1, 1, 1), (1, 1, 0)\}$  as basis of  $\mathbb{R}^3$ . Find the matrix representation of the inner product.
2.  $(\mathbb{P}_2, \langle \rangle)$  is an inner product space with  $\{1 + t, t, 2t^2\}$  as basis of  $\mathbb{P}_2$ . Find the matrix representation of the inner product.

**QR-Decomposition/Factorization:**

1. Find the QR factorization of the following matrices

(i)  $\begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 0 \\ 2 & 3 & -1 \end{bmatrix}$  (ii)  $\begin{bmatrix} 1 & -1 & 0 & 1 \\ -1 & 2 & -1 & 2 \\ 4 & 2 & 2 & 1 \end{bmatrix}.$