Matrix representation of an inner product space:

Let V be an inner product space $X = \{V_1, V_2, \dots, V_n\}$ be a basis of V. Suppose X and Y be two vectors in Y then X = [X] =

where $[x]_{\alpha}$ is the co-ordinate matrix of x with respect to α $[y]_{\alpha}$ is the co-ordinate matrix of y with respect to α A = [aij] where $aij = \langle p_i, p_j \rangle$ we call A is the matrix associated with the given inner product.

Pb:1 Consider 1R3 with basis Leinez, e33 and $\langle (x_1, x_2, x_3), (y_1, y_2, y_3) \rangle = x_1 y_1 + 3 x_2 y_2 + 5 x_3 y_3$ Find the matrix representation of the above inner product. Soln:- we calculate the following. $\langle 9, 9 \rangle = \langle (1,0,0) \rangle (1,0,0) \rangle = 1$ $\langle e_1, e_2 \rangle = \langle ((0,0), (0,1,0) \rangle = 0$ $\langle e_{1}, e_{3} \rangle = \langle (1_{1}, 0_{10}) \rangle \langle (0_{1}, 0_{11}) \rangle = 0$ $\langle c_2, e_1 \rangle = \langle e_1, e_2 \rangle = 0$ $\langle c_2, c_2 \rangle = \langle (0, 1, 0), (0, 1, 0) \rangle = 3$ $\langle e_{2}, e_{3} \rangle = \langle (0, 1, 0), (0, 0, 1) \rangle = 0$ < e 3, e1> = < e1, e3> =0 $\langle e_3 | e_2 \rangle = \langle e_2 | e_3 \rangle = 0$ $\langle e_3, e_3 \rangle = \langle (0,0,1), (0,0,1) \rangle = 5$ The required malina $A = \begin{cases} \langle e_{1}, e_{1} \rangle & \langle e_{1}, e_{2} \rangle & \langle e_{1}, e_{3} \rangle \\ \langle e_{2}, e_{1} \rangle & \langle e_{2}, e_{2} \rangle & \langle e_{2}, e_{3} \rangle \\ \langle e_{3}, e_{1} \rangle & \langle e_{3}, e_{2} \rangle & \langle e_{3}, e_{3} \rangle \end{cases} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$

#bi2 Consider
$$P_{2}(R)$$
 with basis \\ \left\{\text{it}\} \geq (1) \\ \text{b}} \\

\[
\left\{\text{fit}\} \geq (1) \\
\text{Find} \quad \text{te matrix representation of the object inner product.} \\

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\frac{\sin_{1} \cdot v_{2}}{\sin_{1} \cdot v_{2}} = \text{it} \sin_{2} = \text{it} \\

\left\{v_{1}, v_{2}} = \left\{1, \text{b}} = \int \left\{1 \text{dt}} = \left\{\frac{1}{2}\right\} = \left\{1} \\

\left\{v_{1}, v_{2}} = \left\{1, \text{b}} = \int \left\{1 \text{dt}} = \left\{\frac{1}{2}\right\} = \left\{2} \\

\left\{v_{2}, v_{3}} = \left\{1, \text{b}} = \int \left\{1 \text{dt}} = \left\{\frac{1}{2}\right\} = \left\{2} \\

\left\{v_{3}, v_{3}} = \left\{1, \text{b}} = \int \left\{1 \text{dt}} = \left\{\frac{1}{2}\right\} = \left\{4} \\

\left\{v_{3}, v_{3}} = \left\{1, \text{b}} = \left\{1 \text{dt}} = \left\{1 \text{dt}} \right\} = \left\{4} \\

\left\{0_{3}, v_{3}} = \left\{0_{3}, v_{3}} = \left\{2} \\

\left\{0_{3}, v_{3}} = \left\{2, v_{3}, v_{3}} = \left\{4} \\

\left\{0_{3}, v_{3}} = \left\{2, v_{3}, v_{3}} = \left\{4} \\

\left\{0_{3}, v_{3}} \left\{2, v_{3}, v_{3}, v_{3}} \left\{2, v_{3}, v_{3}, v_{3}} \left\{2, v_{3}, v_{3},