



Faculty of Engineering
Cairo University
Computer Engineering Department



Snakino

An Embedded Systems Project

Submitted to:

Dr. Bassem Ibrahim

Table of Contents

Team Members.....	4
Introduction.....	5
Components Description	6
Arduino UNO	6
Description.....	6
Specifications	6
Reason of usage	6
Schematic.....	7
Price	7
8x8 Led Matrix + MAX7219 module	7
Description.....	7
Specifications	7
Reason of usage	8
Schematic.....	8
Wiring Instructions.....	8
Price	8
Analog Joystick.....	8
Description.....	8
Specifications	9
Reason of usage	9
Schematic.....	9
Wiring Instructions.....	9
Price	9
Buzzer	10
Description.....	10
Specifications	10

Reason of usage	10
Schematic.....	10
Wiring Instructions.....	10
Price	10
Design Models	11
Functional Diagram	11
Timing Diagram.....	12
Finite State Machine	13
Sequence Chart.....	14
Design Schematic	15
Real connections view.....	16

Team Members

Name	Section	Bench Number
Ahmed Nasser Ahmed Abdrabo	1	8
Ahmed Hisham Eid Elmorsy	1	9
Abdelrahman Ahmed Mohamed Farid	1	33
Youssef Walid Hassan	2	34

Introduction

Snakino is a 2-player snake game, where each player competes against the other, the end-goal of the game for a player is to survive longer than the other player.

Each player controls his/her snake using an analog joystick, if a player hits the wall of the grid or hits the other snake, he/she loses.

Food is spawned across the grid in random points, any snake eats that food will have its length increase by one, which will make it harder for the other player to navigate across the map, and will make it easier for the longer snake to win the game.

Whenever the game ends, a buzzer will play different sound tones. If it buzzes once, it means that player 1 won the game, if it buzzes twice, it means that player 2 won the game.

At the beginning of each game, each player must signal that he is ready by clicking on the button on the analog stick.

If the power to the microcontroller is lost, the game will resume at the place it was at when the power returns, each player must signal that he/she is ready again before resuming the game.

Components Description

Arduino UNO

Description

Arduino Uno is a microcontroller board based on the ATmega328P (datasheet). It has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a 16 MHz ceramic resonator (CSTCE16M0V53-R0), a USB connection, a power jack, an ICSP header and a reset button. It contains everything needed to support the microcontroller; simply connect it to a computer with a USB cable or power it with AC-to-DC adapter or battery to get started. You can tinker with your Uno without worrying too much about doing something wrong, worst-case scenario you can replace the chip for a few dollars and start over again.

Specifications

- Microcontroller: ATmega328
- Operating Voltage: 5V
- Input Voltage (recommended): 7-12V
- Input Voltage (limits): 6-20V
- Digital I/O Pins: 14 (of which 6 provide PWM output)
- Analog Input Pins: 6
- DC Current per I/O Pin: 40 mA
- DC Current for 3.3V Pin: 50 mA
- Flash Memory: 32 KB (ATmega328) of which 0.5 KB used by bootloader
- SRAM: 2 KB (ATmega328)
- EEPROM: 1 KB (ATmega328)
- Clock Speed: 16 MHz

Reason of usage

Used to coordinate components and control the system.

Schematic

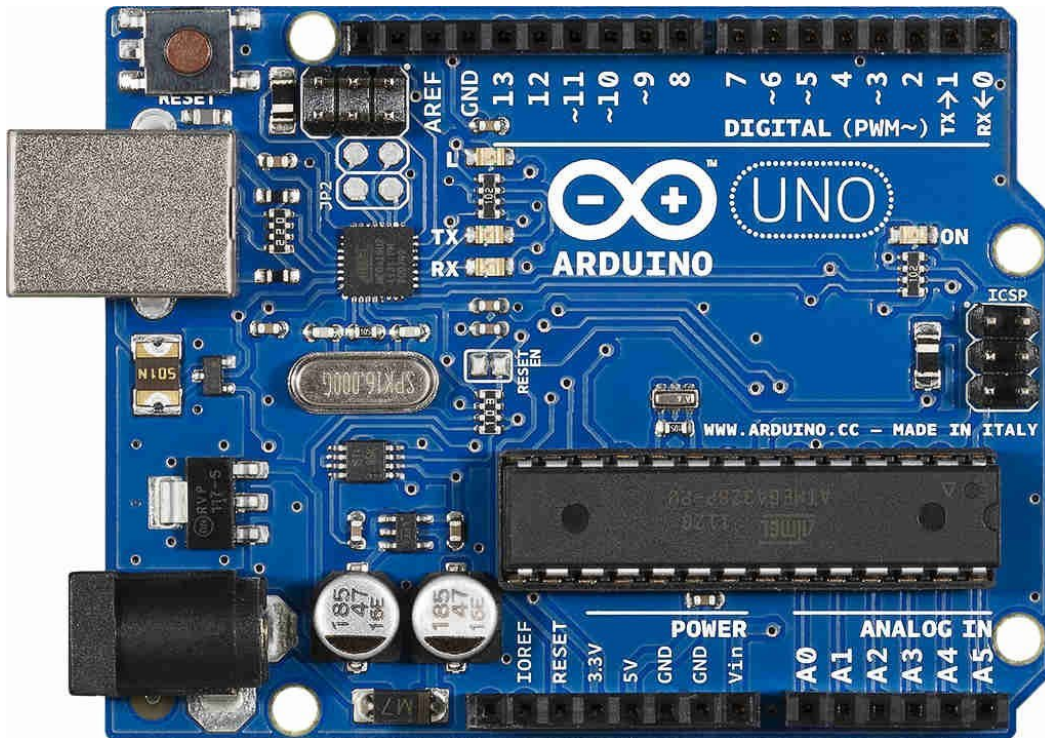


Figure 1: Arduino Uno

Price

EGP 155

8x8 Led Matrix + MAX7219 module

Description

An 8x8 cathode red led matrix, powered with a MAX7219 module which interfaces with the led matrix and keeps the state recorded on the state.

Specifications

- A single module can drive an 8 x 8 common cathode lattice
- Operating voltage: 5V
- Size: 5 x 3.2 x 1.5 cm (L x W x H)
- LED color: red
- With four screws hole, aperture 3mm
- With input and output interfaces, supports multiple modules cascade

Reason of usage

4 of this are used to display the game on a 16x16 led matrix.

Schematic

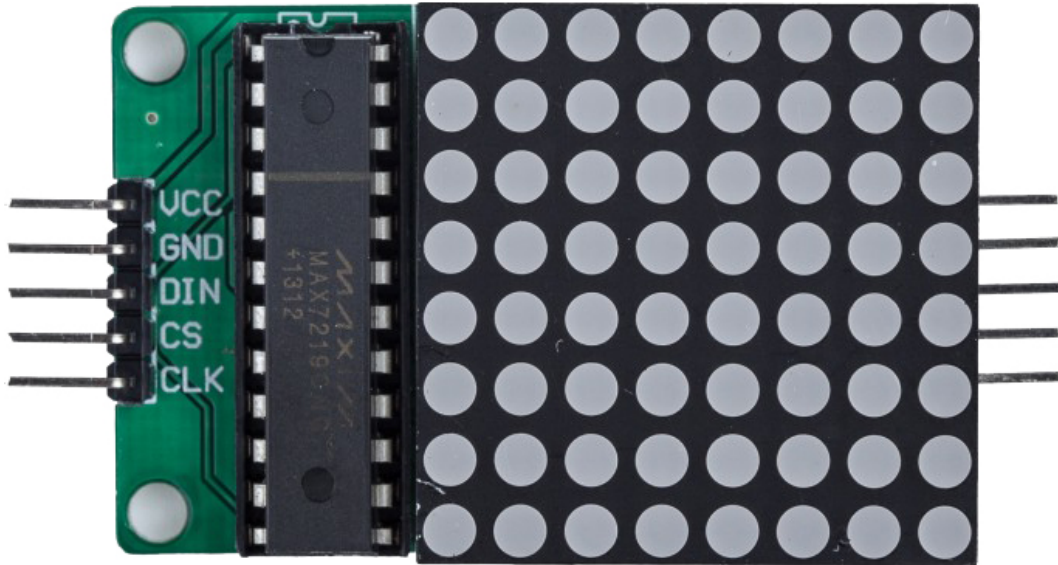


Figure 2: 8x8 Led Matrix + MAX7219

Wiring Instructions

- VCC: Connected to a 5V source
- GND: Connected to ground source
- DIN: SPI DIN pin
- CS: Chip select SPI pin
- CLK: Clock SPI pin.

Multiple MAX7219 can be connected with each other in a daisy-chain fashion and we will only need to interface with one through the Arduino.

Price

55 EGP

Analog Joystick

Description

An analog stick with a clickable button that gives the X and Y offset through an analog output to the Arduino.

Specifications

- Power: 0.01W
- Interface: Dual 10K potentiometers with common ground
- Operating temp range: +32°F to +158°F (0°C to +70°C)

Reason of usage

2 of this are used to control the direction of movement of each snake

Schematic



Figure 3: Analog Joystick

Wiring Instructions

- GND: ground
- +5V: 5V DC
- VRx: voltage proportional to x position
- VRy: voltage proportional to y position
- SW: switch pushbutton

Price

50 EGP

Buzzer

Description

A 6v buzzer

Specifications

- Rated Frequency: 4,100Hz
- Operating Voltage: 6 Vdc
- Current Consumption: 7mA @ 6Vdc
- Sound Pressure Level(30cm): 70dB @ 6Vdc
- Dimensions: 13mm Diameter, 7mm High, Pin Spacing – 7mm.
- Label Color: Blue

Reason of usage

One of this is used to indicate who won the game, and to indicate which player clicked ready.

Schematic



Figure 4: 6V Buzzer

Wiring Instructions

- 6V pin: Connected to high voltage
- GND pin: Connected to ground

Price

5 EGP

Design Models

Functional Diagram

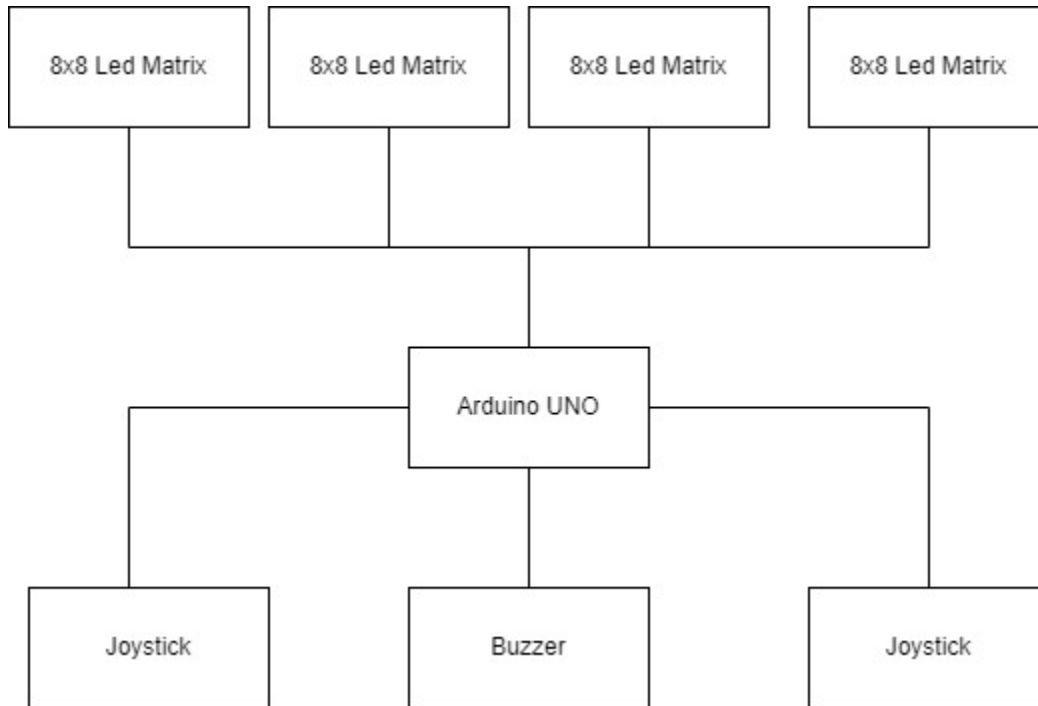


Figure 5: Functional Diagram

The microcontroller works as the middle layer between the inputs of the joystick and the outputs of each led matrix and the buzzer.

Timing Diagram

The system is event based, we regularly check joystick inputs, calculate the new system states if one game step has passed, and then we print the new system states over to the led matrices.

The system can only process one event at a time, but because there is no blocking operations in the code, the game functions as if everything is asynchronous.

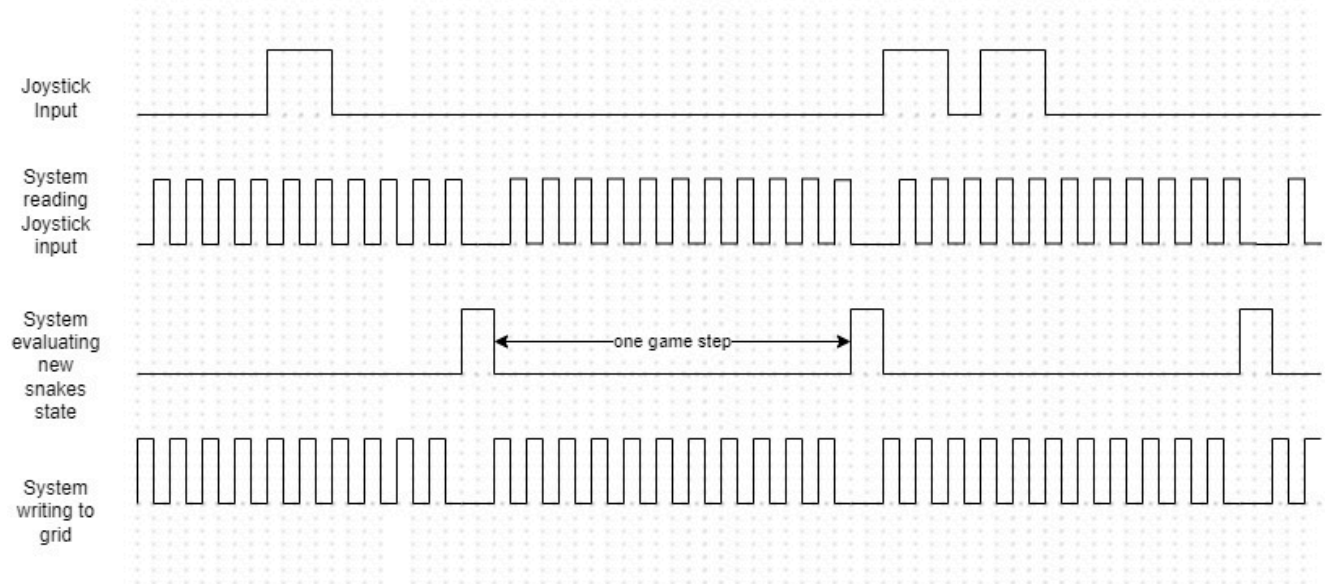


Figure 6: Timing Diagram

Finite State Machine

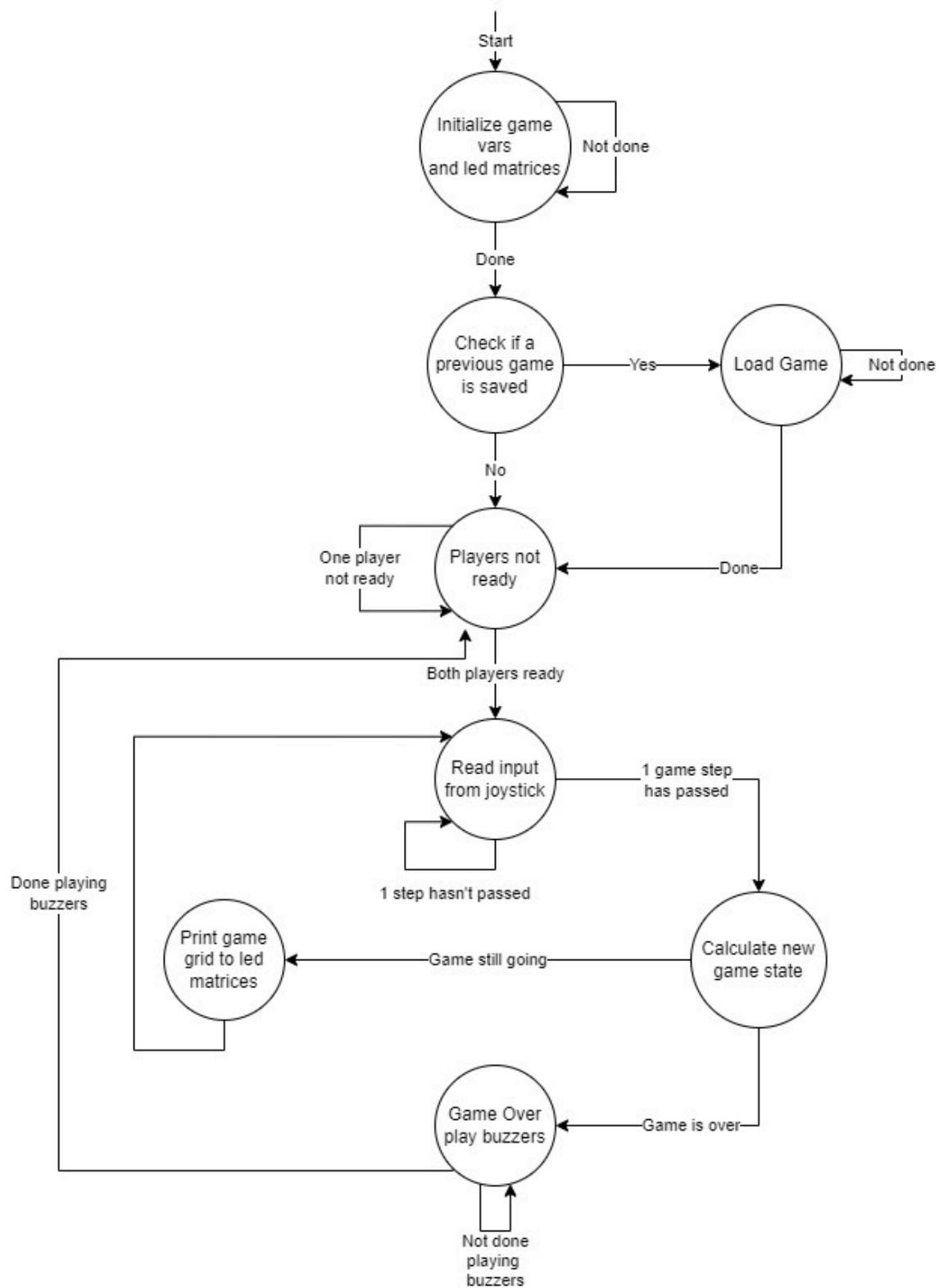


Figure 7: Finite State Machine

Sequence Chart

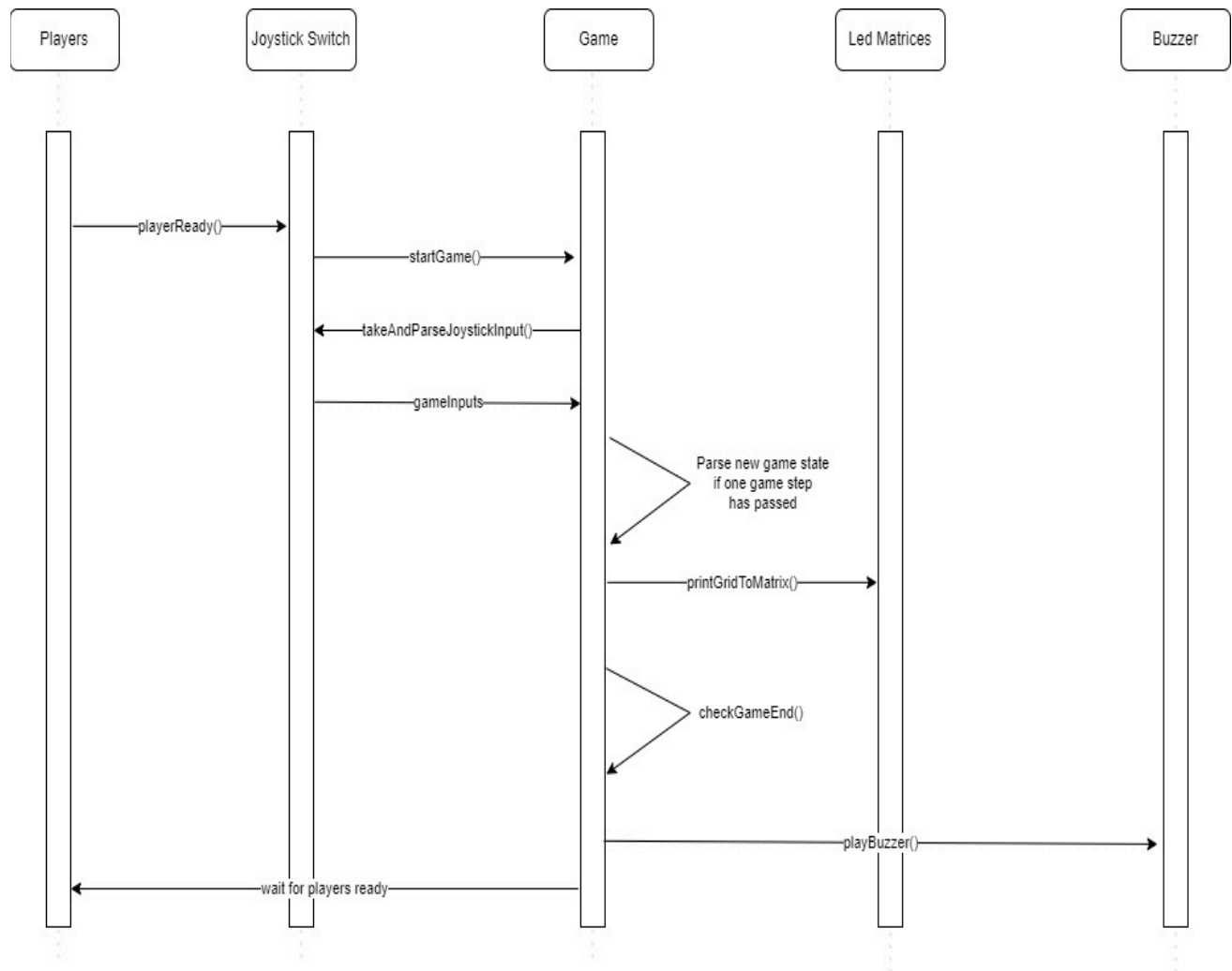


Figure 8: Sequence Chart

Design Schematic

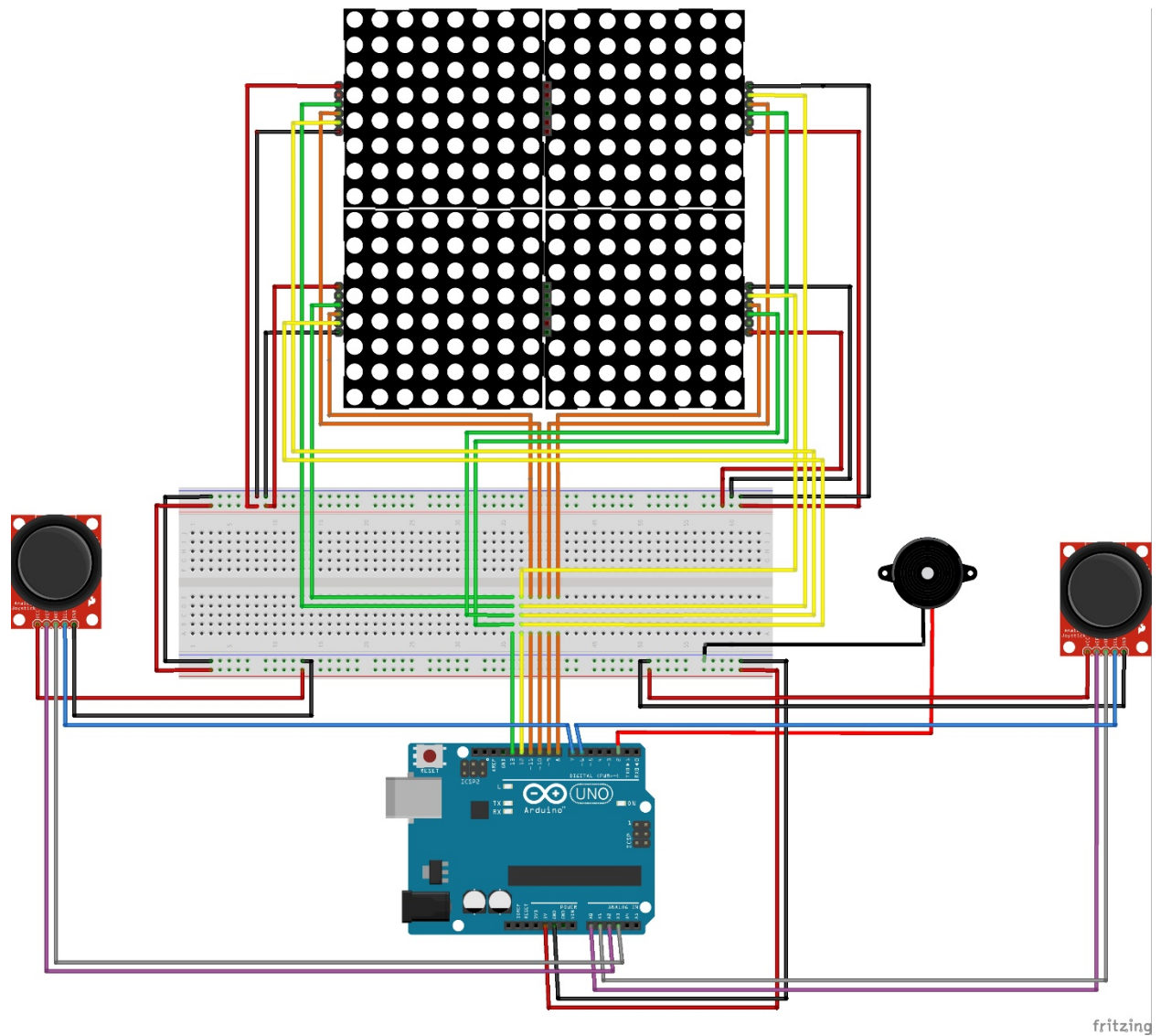


Figure 9: Design Schematic

Real connections view

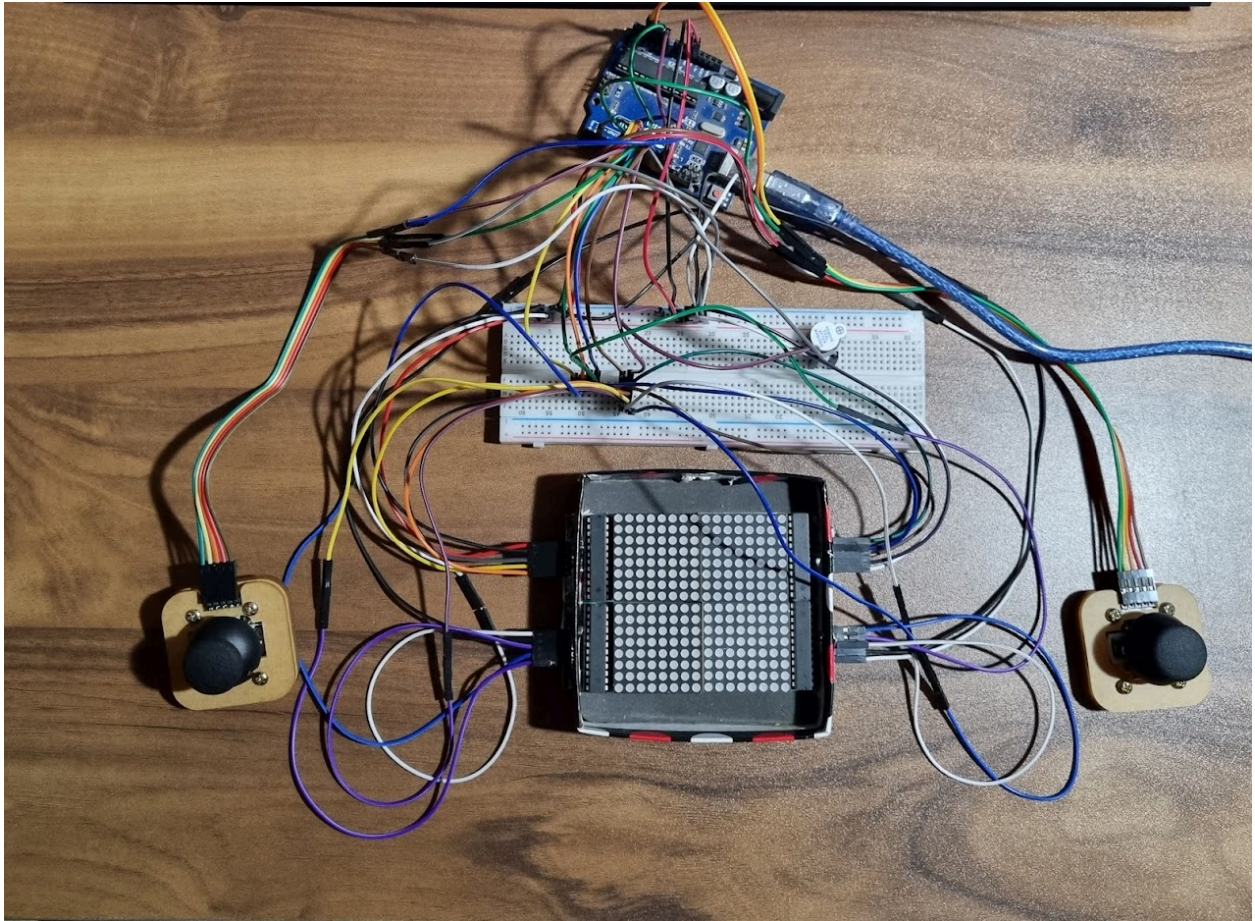


Figure 10: Real connections view