

# Yash Srivastav

SENIOR UNDERGRADUATE · COMPUTER SCIENCE AND ENGINEERING

Indian Institute of Technology, Kanpur

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## EDUCATIONAL QUALIFICATIONS

Year	Degree	Institution(Board)	CGPA/%
July'17 – June'21 (expected)	B.Tech, ME & Minor in IME	Indian Institute of Technology, Kanpur	9.2/10.0
2017	ISC – XII	City Montessori School, Lucknow (CISCE)	95.5%
2015	ICSE – X	St. Francis' College, Lucknow (CISCE)	95%

## HONORS AND ACHIEVEMENTS

- 2019 **2nd in 15+ teams**, Student AUV Competition (SAVE), organised by **NIOT, Chennai** in 2019 Chennai
- 2017 **Top 0.7%**, JEE Advanced (amongst 160,000 candidates)
- 2017 **Top 0.001%**, JEE Main (amongst 1.3 million candidates)
- 2016 **Top 1% (U.P)**, National Standard Examination in **Physics**, 2016, appeared for INPho India
- Top 1% (India)**, National Standard Examination in **Chemistry**, 2016, appeared for INChO India

## WORK EXPERIENCE

### Intelligent Systems Lab

SUPERVISOR: MR. RAVI PRAKASH, DOCTORAL STUDENT

- Ported outdated available ROS code to operate on current development platform using ROS Kinetic on Ubuntu 14.04
- Actualized setup for simulation using **Rviz and Gazebo** for Universal Robots manipulator on a Guardian Robot
- Tweaked the hardware drivers and changed odometry publishers to fix position drift estimated by motor encoders
- Assisted in final aim to create collaborative autonomous robots capable of building walls, extinguishing fires

Robotics Intern

April 2019 - Present

### New York Office, IIT Kanpur

SUPERVISOR: PROF. MANINDRA AGRAWAL

- Worked on **Scala with Akka-HTTP** for scalable and concurrent multi threading using functional programming
- Documented and compiled the entire collection of backend Application Programming Interfaces using **PostMan**
- Fixed bugs in the Scala backend, and collaborated using Phabricator, while developing an upcoming social platform

Backend Software Intern

May 2018 - July 2018

## SKILLS

## RELEVANT COURSEWORK

Engineering Design and Graphics (A\*)

Fundamentals of Computing (A\*)

Theory of Mechanisms and Machines (i)

Dynamics (A)

Mechanics Of Solids (A)

Multi-Variable Calculus

Fluid Mechanics (A)

Thermodynamics (A)

Introduction to Robotics (i)

Probability & Statistics

Complex Analysis

Energy Systems (i)

A\*: Grade for exceptional performance, i: In progress, A: grade

## PROJECTS

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Developed and tested acoustic localization system capable of estimating the Direction of Arrival of ultrasonic underwater signals from pinger, using **STFT** and **Cross-Correlation**

Tuned and tested Cascaded PID Controller on the vehicle, enabling it to perform waypoint navigation & visual servoing

**Realtime Onboard Dense RGB-D Mapping on UAVs** Enter onboard Gazebo-ROS-Mapping on UAVs simulate vehicle model in a hydrodynamically realistic environment

MENTOR: PROF. MANGAL KOTHARI

May 2019 - Present

- Studied and experimented various techniques related to 3D mapping of environment using monocular and stereo cameras on Jetson TX2 for onboard implementation
- Evaluated approaches for shortcomings and processing requirements while focussing on the scarce size, computation and energy resources on Unmanned Aerial Vehicles (UAVs)

**Mechanical Quadruped**

Course Project - TA202

MENTOR: PROF. SHANTANU BHATTACHARYA

4th Semester

- Designed and simulated a four-legged assembly that uses Jansen's linkage mechanism to walk using **Solidworks**
- Made a working model of the same under constraints of size and materials using manufacturing processes such as lathing, milling and drilling

**Chat-IITK**

Advanced Track Project - ESC101

MENTOR: PROF. PUROSHOTTAM KAR

2nd Semester

- Designed and developed a chat application on NodeJS, Express, and MongoDB, selected in **12** out of 400+ students
- Implemented real-time chat using Socket-IO with PassportJS for extensively implemented **authentication** and **cookie handling** for session management
- **Database management** implemented using MongoDB, and application deployed online on Heroku's server

## POSITIONS OF RESPONSIBILITY

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**Team AUV-IITK**

Science and Technology Council

SOFTWARE TEAM LEAD

April 2019 - Present

- Spearheading a group of 8 people working on the software of Anahita, planning and implementing technical changes
- Maintaining software stack of Autonomous Vehicle, deployed on Git, developed using ROS, OpenCV and Gazebo

- **Secretary**, Robotics Club, IIT Kanpur 2018-19
- **Secretary**, Consulting Hobby Group, IIT Kanpur 2018-19
- **Student Guide**, Counselling Service, 2018-19
- **Academic Mentor**, Counselling Service, 2018-19

## MISCELLANEOUS

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- **Runners Up** in robotic soccer event *Wild Soccer*, and *Visualise*, in inter-hall competition
- Developed an application which generated summaries of the latest news based on the current trending hashtags on Twitter as **code.fun.do** submission
- Developed basic platform game on game development framework **Unity** using JavaScript & C#, updated on Github