

1 Trajectory Model

1.1 Forces and the Equation of Motion

Treating a droplet as a particle, with radius R_d , the equation of motion for a charged droplet translating vertically along the central axis of a finite square charged dielectric sheet is given by

$$my'' = -\mathbf{F}_D - \mathbf{F}_E, \quad y(0) = R_d, \quad y'(0) = U_0, \quad (1)$$

where m is the droplet mass, $y'' = \frac{d^2y}{dt^2}$ is the droplet acceleration, \mathbf{F}_D is the drag force, and \mathbf{F}_E is the electrostatic force. The initial conditions are such that the droplet leaves its resting position R_d at $t = 0$, with initial velocity U_0 . The signs of the forces on the right side of Equation 1 indicate that they act in the opposite direction of the droplet motion. In this section we aim specify models for the various forces in this equation.

If we assume an intermediate range of Reynolds numbers $\mathbb{Re} \equiv \frac{2UR_d}{\nu}$, $1 < \mathbb{Re} < 1000$ then the drag is quadratic,

$$\mathbf{F}_D = \frac{1}{2}C_D\rho Ay'^2,$$

where C_D is the drag coefficient, ρ is the density of the surrounding fluid medium (air, in this case), and A is the frontal area of the droplet. For this range of Reynolds numbers we may also approximate the drag coefficient by

the well known Abraham correlation [ref.](#)

$$C_D = \frac{24}{9.06^2} \left(1 + \frac{9.06}{\sqrt{\text{Re}}} \right)^2$$

Modeling the electrostatic force is somewhat more involved, but we will adopt the standard electrohydrodynamic (EHD) approximation model because of the dramatic simplifications it offers [ref.](#) We first assume a DC electric field, such that $Re\langle\epsilon\rangle \approx \text{constant}$, where ϵ is the dielectric permittivity of the respective media. We also assume that currents are small such that the effects of magnetic fields can be neglected. For the validity of this assumption to hold the characteristic time scale for electrical phenomena $\tau_e = \epsilon\epsilon_0/\sigma_e \ll 1$, where τ is the ratio of absolute dielectric permittivity $\kappa = \epsilon\epsilon_0$, to conductivity σ_e , of the medium [ref]. [Given the respective conductivity, and permittivity of water \(\$\sigma_e = 2.5 \cdot 10^{-4} \text{ } \Omega^{-1}\text{cm}^{-1}\$ \), we estimate \$\tau_e \approx 7 \times 10^{-8} \text{ s}\$.](#) This assumption also allows us to assume that the net charge present in the medium surrounding the droplets remains approximately constant during the typical time interval of a low-gravity experiment, and no transfers of charge occur after the droplet leaves the surface.

If we suppose that electrical forces acting on free charges and dipoles in a fluid are transferred directly to the fluid itself, then this overall electrical body force will be the the divergence of the Maxwell stress tensor τ_m , by

$$\mathbf{F}_E = \nabla \cdot \tau_m = \nabla \cdot \left(\epsilon\epsilon_0 \mathbf{E}\mathbf{E} - \frac{1}{2} \epsilon\epsilon_0 \mathbf{E} \cdot \mathbf{E} \delta \right),$$

where \mathbf{F}_E is the electric body force per unit volume, and δ is the delta function. The product of the electric field vectors is the dyadic product.

The classical Korteweg-Helmholtz force density formulation of the Maxwell stress tensor is usually expressed as [\[ref\]](#)

$$\mathbf{F}_E = \rho_f \mathbf{E} + \frac{1}{2} |\mathbf{E}|^2 \nabla \epsilon - \nabla \left(\frac{1}{2} \rho \left(\frac{\partial \epsilon}{\partial \rho} \right)_T |\mathbf{E}|^2 \right). \quad (2)$$

The first term in this expression, equivalently written as $q\mathbf{E}$, is the well known Coulombic force or electrophoretic force, which arises from the presence of free charge in an external electric field. The second term is the force arising from polarization stresses due to a nonuniform field acting across a gradient in permittivity. This force is widely termed the dielectrophoretic force (DEP). The third term describes forces due to electrostriction. It has been noted by Melcher and Hurwitz that the electrostriction term is the gradient of a scalar and can thus be cannononically lumped together with the hydrostatic pressure for incompressible fluids) [\[ref\]](#); we neglect it in our analysis.

It is common to approximate the polarization stress by idealizing the droplet as a simple dipole using the effective dipole moment method first suggested by Pohl and Jones [\[ref\]](#) [\[ref\]](#). This approach can be related back to the force density by means of a Taylor series expansion of \mathbf{E} in the limit of a small gradient [\[ref\]](#). The DEP force is distinct from the Coulombic force in that net charge is not required, and that the force vector goes in the direction of the gradient of the field, $\nabla |\mathbf{E}|^2$, rather than in the direction of \mathbf{E} . The DEP force is related to the dipole moment (induced or permanent) of polarizable media which has a tendency to align the dipole with the electric field. If there is a gradient in the field then for a finite separation of charge

one end of the dipole will feel a stronger electric field than the other, resulting in a net force. Whether the force is positive or negative in the direction of the electric field gradient depends on the difference of dielectric permittivities between the fluids, rather than on the polarity of \mathbf{E} itself. It bears repeating that droplets will polarize in a uniform field, but since there is no gradient in the field the forces felt by the dipoles are symmetric and there is no net force. The dipole moment of a spherical linear-dielectric particle immersed in a dielectric medium is given by

$$\mu = V_d \mathbf{P} = \frac{4}{3} \pi R_d^3 \mathbf{P}, \quad (3)$$

where $\mathbf{P} = (\kappa_1 - 1) \epsilon_0 \mathbf{E}_{iz} = \chi_e \epsilon_0 \mathbf{E}_{iz}$ is the polarization moment, and R_d is the particle radius, $\kappa_1 = \frac{\epsilon}{\epsilon_0}$ being the relative dielectric constant of the medium (air in this case), $\chi_e = \kappa_1 - 1$ being the electric susceptibility of the dielectric medium, and \mathbf{E}_{iz} is the z -coordinate component of the electric field internal to the sphere, assuming the external electric field to be oriented parallel to the z -axis. The excess polarization \mathbf{P}_e , in the sphere is given by

$$\mathbf{P}_e = (\kappa_2 - \kappa_1) \epsilon_0 \mathbf{E}_{iz} = \frac{3\kappa_1}{\kappa_2 + 2\kappa_1} \mathbf{E}_{iz}, \quad (4)$$

where κ_2 is the relative dielectric constant of the spherical particle. Taking together equations 3, and 4 we find that the effective dipole moment of the particle is given by

$$\mu = 4\pi R_d^3 \left(\frac{\kappa_2 - \kappa_1}{\kappa_2 + 2\kappa_1} \right) \kappa_1 \epsilon_0 \mathbf{E}, \quad (5)$$

and the force felt by the dipole is

$$\begin{aligned}\mathbf{F}_{DEP} &= (\mathbf{P}_e \cdot \nabla) \mathbf{E} \\ &= 2\pi R_d^3 \kappa_1 \epsilon_0 K \nabla E^2,\end{aligned}\tag{6}$$

where it is an asthetically pleasing shorthand to refer to the permittivity ratio by $K = \frac{\kappa_2 - \kappa_1}{\kappa_2 + 2\kappa_1}$, which is also known as the Clausius-Mossotti factor. In cases where $K < 0$, or $K > 0$ the particle will be repelled or attracted to regions of strong field respectively. In our experiment, taking the relative dielectric constants to be $\kappa_1 \approx 1$ and $\kappa_2 \approx 80$, we have $K \approx 0.96$. We also note that the equivalent dipole approximation requires an assumption of small physical scale of the particle relative to the lengthscale of nonuniformity of the field, which in this case we take to be the length of the charged superhydrophobic surface ($L = 25 \text{ mm} \gg a \approx 2.5 \text{ mm}$).

When the droplet is close to the dielectric surface, the net charge on the droplet will tend to polarize the dielectric, perturbing the electric field. The polarization bound charge in the dielectric will be of the opposite sign of the net droplet charge and thus there will be a force of attraction. This so-called image force is a correction to the Colomb force due to the external electric field only, and can be found by the method of images [ref](#). The image force \mathbf{F}_I , is given by

$$\mathbf{F}_I = \frac{kq^2}{16\pi\epsilon_0} y^{-2} \hat{\mathbf{j}},\tag{7}$$

where the factor k is a function of the dielectric surface susceptibility $k =$

$\frac{\chi_e}{\chi_e+2}$, and $\hat{\mathbf{j}}$ is a unit vector normal to the dielectric surface.

By substituting Equations 6, 7 into Equation 2 we have

$$\begin{aligned}\mathbf{F}_E &= q\mathbf{E} + \mathbf{F}_{DEP} + \mathbf{F}_I \\ &= q\mathbf{E} + \frac{kq^2}{16\pi\epsilon_0}y^{-2}\hat{\mathbf{j}} + 2\pi R_d^3\kappa_1\epsilon_0 K\nabla E^2,\end{aligned}$$

and the 1-D governing equation becomes

$$\begin{aligned}my'' &= -\frac{1}{2}C_D\rho Ay'^2 - qE - \frac{kq^2}{16\pi\epsilon_0}y^{-2} - 2\pi R_d^3\kappa_1\epsilon_0 K\nabla E^2, \\ y(0) &= R, \quad y'(0) = U_0.\end{aligned}\tag{8}$$

By comparing DEP and Coulombic terms in Equation 8, we note that a condition to neglect the DEP term is

$$1 \gg \frac{R_d^2\kappa_2\epsilon_0 KE_0}{q}$$

As this condition holds in all cases under study we herefore neglect the DEP force in our analysis.

1.2 The Electric Field

If we consider the charged dielectric surface of our experiments to be a square sheet of charge lying in the xz -plane with width L , the symmetry of the problem happily lets us obtain the y -component of the electric field \mathbf{E}_y by direct integration [ref](#). In particular it is easy to constuct the electric field due to a finite plane of charge by supooerposition of the electric fields of a series

of line charges. By symmetry the electric field points along the y -axis; for a point along the y -axis the position vector is $\mathbf{r} = (x^2 + y^2 + z^2)^{1/2} \hat{\mathbf{r}}$. The y -component of \mathbf{E} is given by $\mathbf{E}_y \cos \theta = \mathbf{E}_y y / \mathbf{r}$. Then if the charge in an element of area, $dxdz$ is $\sigma dxdz$ the electric field \mathbf{E}_y is

$$\mathbf{E}_y = \frac{\sigma y}{4\pi\epsilon_0} \int_{L/2}^{L/2} \int_{L/2}^{L/2} (x^2 + y^2 + z^2)^{3/2} dxdz \hat{\mathbf{r}},$$

where σ is the surface charge density. This can be easily integrated to obtain an expression for the electric field in terms of y ,

$$\mathbf{E}_y = \frac{\sigma y}{\pi\epsilon_0} \tan^{-1} \left(\frac{L^2}{y\sqrt{2L^2 + y^2}} \right). \quad (9)$$

By taking Taylor series expansions in large and small limits we can intuit a bit about the behavior of this field. In the limit $L \rightarrow \infty$, $y \ll L$ the argument of the function tends towards infinity and

$$\lim_{x \rightarrow \infty} \tan^{-1}(x) = \frac{\pi}{2},$$

and thus

$$\mathbf{E}_y \approx \frac{\sigma}{4\pi\epsilon_0} \hat{\mathbf{j}} \quad y \ll L, \quad (10)$$

which is constant, and equivalent to the electric field due to an infinite plane of charge. In the limit of $y \gg L$, the argument of the arctangent function can be approximated by

$$\frac{L^2}{2y(2L^2 + 4y^2)^{1/2}} = \frac{L^2}{4y^2(1 + L^2/2y^2)^{1/2}} \approx \frac{L^2}{4y^2}.$$

For small x , $\tan^{-1}(x) \sim x$ and we thus find the familiar electric field due to a point charge

$$\mathbf{E}_y \approx \frac{\sigma L^2}{4\pi\epsilon_0} y^{-2} \hat{\mathbf{j}} \quad y \gg L. \quad (11)$$

With the characteristic electric field given by $E_0 = \frac{\sigma}{4\pi\epsilon_0}$, both these regimes can be clearly seen in the plot of \mathbf{E}_y shown in Figure 1.

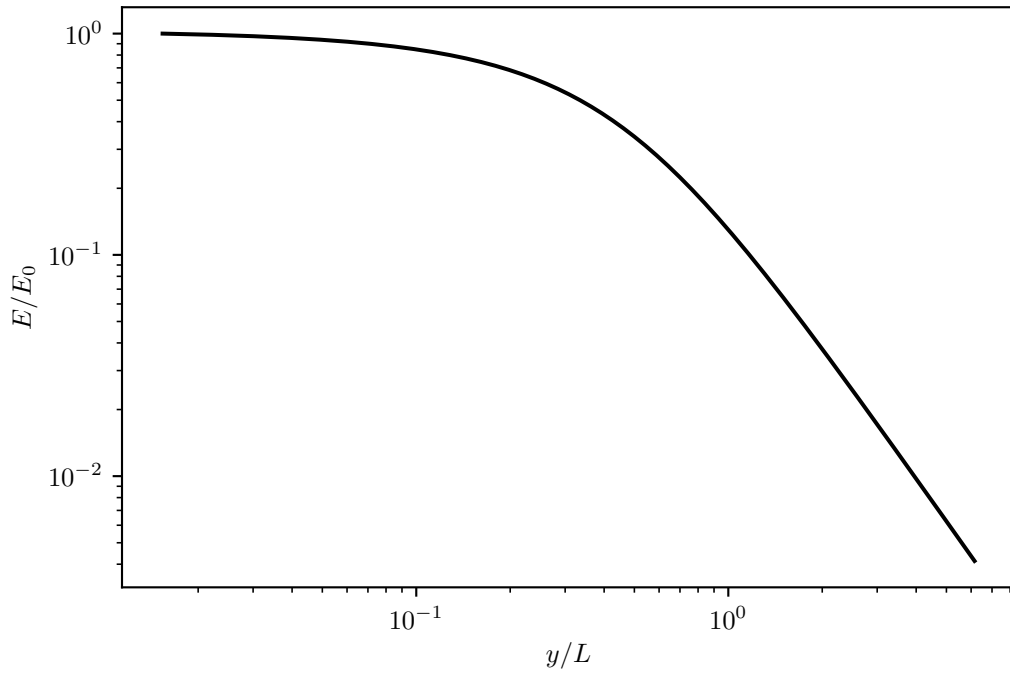


Figure 1: A log-log plot of the magnitude of the non-dimensional electric field, \mathbf{E}_y .

1.3 Scaling

Introducing scaled variables

$$\bar{t} = \frac{t}{t_c}, \quad \bar{y} = \frac{y}{y_c},$$

where y_c and t_c are characteristic length and time scales respectively, and using the coordinate transformation $y(0) - R = 0$, the governing equation becomes

$$\begin{aligned}\bar{y}'' &= -\frac{1}{2} \frac{C_D \rho A y_c}{m} \bar{y}'^2 - \frac{q E_0 t_c^2}{m y_c} \bar{E} - \frac{k q^2 t_c^2}{16 \pi \epsilon_0 R^2 m y_c} \frac{1}{\left(\frac{y_c}{R} \bar{y} + 1\right)^2}, \\ \bar{y}(0) &= 0, \quad \bar{y}'(0) = \frac{U_0 t_c}{y_c}.\end{aligned}\tag{12}$$

We note several dimensionless groups

$$\Pi_1 = \frac{C_D \rho A y_c}{2m}, \quad \Pi_2 = \frac{q E_0 t_c^2}{m y_c}, \quad \Pi_3 = \frac{k q^2 t_c^2}{16 \pi \epsilon_0 R^2 m y_c}, \quad \Pi_4 = \frac{y_c}{R}.$$

1.3.1 Inertial Electro-Image Limit

In the limit of small y , t we expect inertia to scale as Coulombic and image force. With $y_c \sim U_0 t_c$ and picking t_c such that Coulombic force is $\mathcal{O}(1)$

$$t_c \sim \frac{m U_0}{q E_0}, \quad y_c \sim \frac{m U_0^2}{q E_0}.$$

With these scales the governing equation then becomes

$$\begin{aligned}\bar{y}'' &= -1 - \mathbb{I}m \frac{1}{(\mathbb{E}u \bar{y} + 1)^2}, \\ \bar{y}(0) &= 0, \quad \bar{y}'(0) = 1.\end{aligned}\tag{13}$$

with

$$\mathbb{I}m \equiv \frac{k q}{16 \pi \epsilon_0 R_d^2 E_0} = \Pi_3, \quad \mathbb{E}u \equiv \frac{m U_0^2}{q E_0} = \Pi_4,$$

where \mathbb{Im} is the Image number, and denotes the ratio of image forces to the Coulombic force of the unperturbed field, and where \mathbb{Eu} is the electrostatic Euler number, and is a ratio of inertia to electrostatic force.

1.3.2 Inertial Electro-Viscous Limit

In the limit of large y , t we expect droplet inertia to scale as Coulombic force and drag. In this case there are several obvious choices of scales:

1. $y_c \sim U_0 t_c$ and make Coulomb force $\mathcal{O}(1)$.
2. $y_c \sim R_d$ or L , $t_c \sim \frac{L}{U_0}$ but this makes the governing equation singular.
3. $y_c \sim R_d$ or L , $t_c \sim \left(\frac{Lm}{qE_0}\right)^{1/2}$.
4. $y_c \sim R_d$ or L , and making Coulomb force $\mathcal{O}(1)$.

In Case 3, the characterisitc time is $t_c \sim \left(\frac{4\pi R_d^2}{qE_0 L}\right)^2$ and the non-dimensional governing equation is given by

$$\bar{y}'' = -\frac{C_D \rho A L}{2m} \bar{y}'^2 - \frac{1}{\left(\frac{L}{R} \bar{y} + 1\right)^2},$$

$$\bar{y}(0) = \frac{R}{L}, \quad \bar{y}'(0) = \left(\frac{4\pi U_0^2 R_d^2}{qE_0 L^3}\right)^{1/2} = \frac{R}{L} \sqrt{\mathbb{Eu}_+}.$$

where $\mathbb{Eu}_+ = \frac{4\pi m U_0^2}{qE_0 L}$ is a long time scaled electrostatic Euler number. We prefer the approach with the greatest physical simplicity, fewest Pi terms, and has homogenous initial conditions.

In Case 1, the characteristic dimensions are

$$t_c \sim \frac{R^2}{L^2} \frac{4\pi m U_0}{qE_0}, \quad y_c \sim \frac{R^2}{L^2} \frac{4\pi m U_0^2}{qE_0}.$$

With this scaling the non-dimensional governing equation is

$$\begin{aligned}\bar{y}'' &= -\mathbb{D}g\mathbb{E}u_+\bar{y}'^2 - \frac{1}{(\mathbb{E}u_+\bar{y}+1)^2}, \\ \bar{y}(0) &= 0, \quad \bar{y}'(0) = 1\end{aligned}\tag{14}$$

where $\mathbb{D}g = \frac{C_D\rho_a}{\rho_l}$. This is the preferred scaling.

1.4 Asymptotic Estimates

1.4.1 Inertial Electro-Image Limit

With $\epsilon = \mathbb{E}u$, where ϵ is a small parameter, and $\alpha = \mathbb{I}m$,

$$\begin{aligned}\bar{y}(\bar{t}) &= \bar{t} + \frac{\bar{t}^2}{2}(-1 - \alpha) + \epsilon \left(\frac{\alpha\bar{t}^3}{3} + \frac{\alpha\bar{t}^4}{12}(-1 - \alpha) \right) \\ &+ \epsilon^2 \left(-\frac{\alpha\bar{t}^4}{4} + \frac{\alpha\bar{t}^5}{60}(9 + 11\alpha) + \frac{\alpha\bar{t}^6}{360}(-9 - 20\alpha - 11\alpha^2) \right) + \mathcal{O}(\epsilon^3)\end{aligned}$$

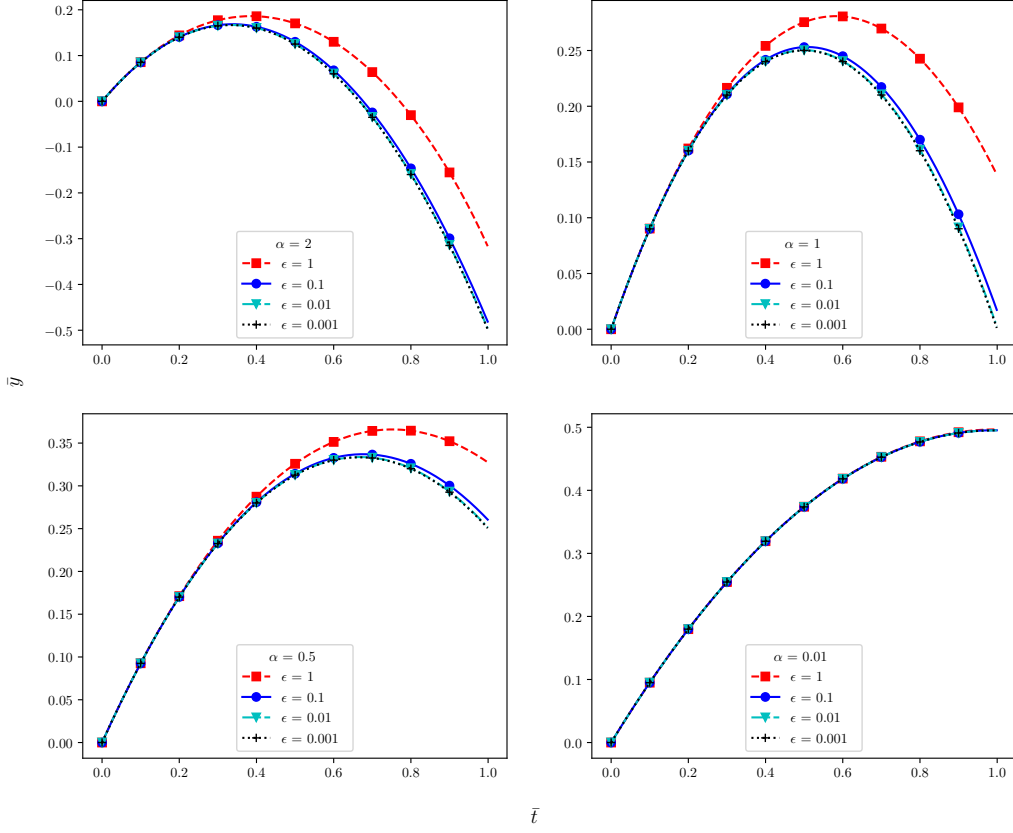


Figure 2: Text.

1.4.2 Inertial Electro-Viscous Limit

Asymptotic estimate of the trajectory. With $\epsilon = \mathbb{E}u_+$, where ϵ is a small parameter, and $\beta = \mathbb{D}g$,

$$\begin{aligned} \bar{y}(\bar{t}) = & \bar{t} - \frac{\bar{t}^2}{2} + \epsilon \left(\frac{\bar{t}^3}{3} (1 + \beta) + \frac{\bar{t}^4}{12} (-1 - \beta) - \frac{\beta \bar{t}^2}{2} \right) \\ & + \epsilon^2 \left(\frac{\bar{t}^4}{12} (-3 - 3\beta - 4\beta^2) + \frac{\bar{t}^5}{60} (11 + 10\beta + 8\beta^2) + \frac{\bar{t}^6}{360} (-11 - 10\beta - 8\beta^2) + \frac{\beta^2 \bar{t}^3}{3} \right) \\ & + \mathcal{O}(\epsilon^3) \end{aligned}$$

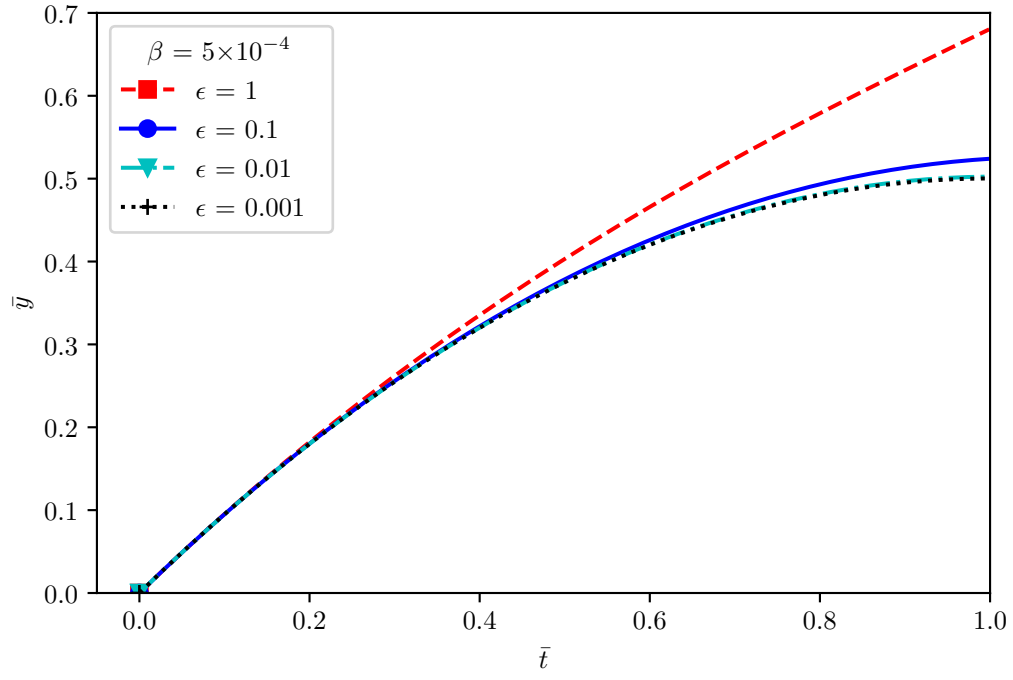


Figure 3: Text.

Times for returns

$$t_c = 2 + \epsilon \left(\frac{4}{3} - \frac{2\beta}{3} \right) + \epsilon^2 \left(\frac{4}{5} - \frac{4\beta}{3} + \frac{2\beta^2}{5} \right)$$

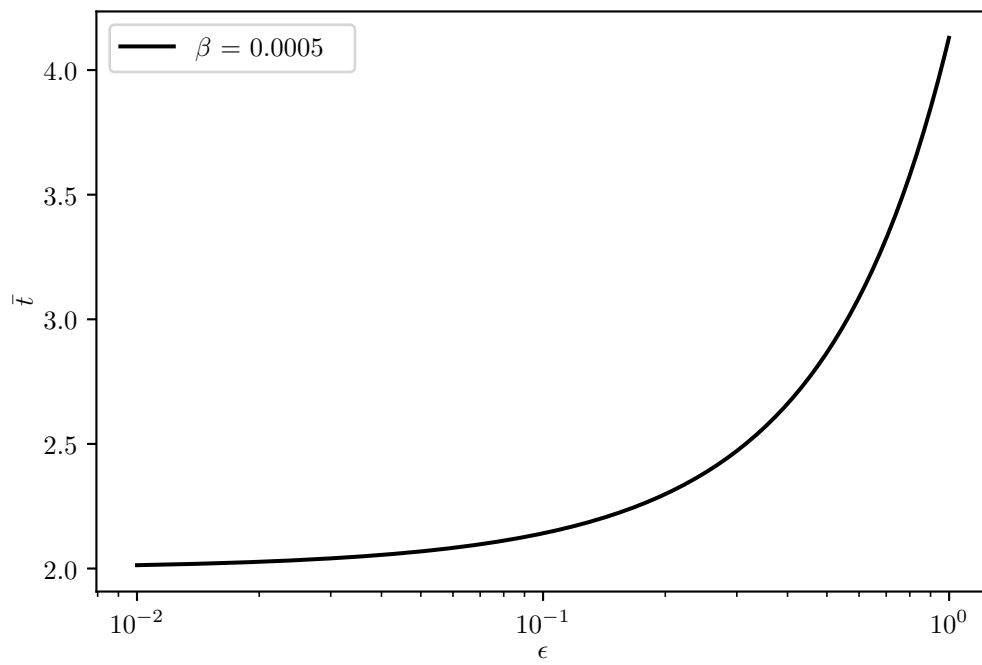


Figure 4: Text.