

# UNNIKRISHNAN R. MENON

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## Education

**B.Tech in Electrical and Electronics Engineering**  
Vellore Institute of Technology, Vellore  
Current CGPA (6 semesters): 8.40

02/2017 – Present

**Class 12 Board Examination (CBSE): 94.2%**  
Summer Fields School, New Delhi

2017

**Class 10 Board Examination (CBSE): 10 CGPA**  
Summer Fields School, New Delhi

2015

## Research Interests

- Cryptography
- Artificial Intelligence
- Quantum Computing
- Computer Vision
- Reinforcement Learning
- Astrophysics
- Socket Programming
- Genetic Algorithms

## Technical Skills

- **Microcontroller** – Arduino, Raspberry Pi, 8051 Assembler, Nexys4 DDR Artix-7 FPGA, NVIDIA Jetson Nano
- **Programming Languages** – Python, C/C++, Java, Javascript, Assembly, Verilog, CUDA
- **Mathematical Packages** – MATLAB, R
- **Typesetting Software** – L<sup>A</sup>T<sub>E</sub>X
- **Other** – TensorFlow, Keras, OpenAI Gym, NumPy, Qiskit

## Publications

1. Menon, U., Hudlikar, A., and Panda, D. (2020). Scytale - an evolutionary cryptosystem. *International Journal of Computer Science and Network*, 9(4):153–159
2. Bhowmik, A. and Menon, U. (2020c). Mes – modern encryption standard. *International Journal of Computer Applications*, 176(36):21–27
3. Bhowmik, A. and Menon, U. (2020a). Dragon crypto – an innovative cryptosystem. *International Journal of Computer Applications*, 176(29):37–41
4. Bhowmik, A. and Menon, U. (2020b). Enhancing the ntru cryptosystem. *International Journal of Computer Applications*, 176(29):46–53

## Extracurricular

<b>Technical Advisory Board</b> roboVITics, the official robotics club of VIT	02/2020 – Present
<b>Technical Head of Electrical Department</b> roboVITics, the official robotics club of VIT	02/2019 – 02/2020
<b>High Power Circuit Designer</b> Team Orcus, <i>Designed a 120 lbs combat robot that has performed well in international RoboWars.</i>	07/2018 – 01/2020
<ul style="list-style-type: none"><li>• Finished in top 7 internationally at RoboWars, TechFest'18, IIT Bombay</li><li>• Secured third position in RoboWars, Kurukshetra'19, Anna University</li></ul>	
<b>Core-Committee Member</b> roboVITics, the official robotics club of VIT	12/2017 – 02/2019
<ul style="list-style-type: none"><li>• Successfully completed multiple robotics projects involving Machine Learning, Computer Vision, Artificial Intelligence, IoT etc.</li></ul>	

## Achievements

<b>Winner of Urban Innovation Track at HackMIT 2020</b> <i>Developed a Reinforcement Learning Algorithm for project NavScape and won the Urban Innovation Track prize.</i>	09/2020
<b>Winner of HackerTech 2019</b> <i>Secured First Position in this 24 hr long Hackathon where I worked on project SPARC (Smart Power Allocation using Reinforced Clusters).</i>	12/2019
<b>Winner of VIT Hack 2019</b> <i>Won VITHack organized by VIT University in collaboration with Honeywell</i>	09/2019
<b>Access Denied Hackathon 2019</b> <i>Got Special Mention price in Logistics and Transportation from GitHub.</i>	03/2019
<b>Winner of Developer's Sprint of Code Hackathon by CodeChef</b> <i>Secured the First Position in this 36 hour Hackathon. I worked on the hardware and a facial emotion recognizer for a ingenious electoral system.</i>	02/2019
<b>Quora Top Writer 2018</b> <i>Got the coveted Top Writer's Quill on my Quora profile for writing quality technical content. Got New York Time's subscription and a t-shirt as a reward from Quora</i>	01/2018
<b>6 NEO Observations (All India Asteroid Search Campaign)</b> <i>Used Astrometrica to detect potential celestial objects and ended up spotting 6 Near Earth Objects.</i>	2016

## Personal Projects

03/2020 – 04/2020 <b>Self learning Quadruped</b>	<ul style="list-style-type: none"><li>• Augmented Random Search Algorithm based AI that teaches a robotic quadruped to walk.</li></ul>
01/2020 – 02/2020 <b>Sudoku Vision</b>	<ul style="list-style-type: none"><li>• An application that can detect sudoku puzzles placed in front of a camera and solves them in real time automatically.</li></ul>

09/2019 – 10/2019

### **Path Prediction for Smart Vehicles**

- A Path Prediction Algorithm which forecasts future path taken using RNN–LSTMs and on top of that optimizes the predicted trajectory using Deep Q-Learning Algorithm.

08/2019 – Present

### **Riff–Raff Encryption**

- Decimal (Negative/Positive, Unranged) Encryption for Unbreakable, Impenetrable Security. (Patent Pending)

12/2018 – 02/2019

### **Self Learning Crawler**

- This bot combines the Q Learning algorithm with a robotic arm to come up with an optimum policy for moving forward

05/2019 – 12/2019

### **RSA Encrypted Password Online Storage**

- This code can be used to save your passwords or other confidential data remotely to a server with a layer of RSA encryption (coded from scratch) without any worries of it getting hacked.

02/2019 – 02/2019

### **Comprehensive Electoral Solution Suite**

- Secured First Position in DEVSOC'19

01/2019 – 02/2019

### **Prepaid Energy Credits based Power Distribution System**

- Machine learning based algorithm for predicting power usage in a common household.

10/2018 – Present

### **AI Development for Video Games**

- Deployed genetic algorithms and other advanced reinforcement learning algorithms in various Video Game environments like Super Mario, Pacman, Snakes, Flappy Birds etc.

05/2018 – 06/2018

### **TensorFlow ChatBot**

- An RNN and LSTM based Chatbot that responds well to meaningful queries.

02/2018 – 04/2018

### **Autonomous Rubik's Cube Solver**

- Developed an algorithm in under 800 lines of C++ code that predicts the correct moves to solve a scrambled  $3 \times 3 \times 3$  Rubik's Cube.

## **References**

**Awnon Bhowmik, College Laboratory Technician**

Department of Mathematics

CUNY Borough of Manhattan Community College

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