## **Generating Data Phase:**

```
x = zeros(100, 1); % # of iterations
y = zeros(100, 1); % # of iterations
s = zeros(2, 100);
x(1) = 1;
y(1) = 1;
s(:,1) = [x(1); y(1)];
f = 2;
g = 0;
h = 2;
u = zeros(100, 1); % # of iterations
for i = 1:100 % # of iterations
    if i == 1
        u(i) = 1;
    else
        u(i) = 0;
    end
end
```

I am assuming x\_i-1, y\_i-1, s\_i-1 equal to 1, 1, [1; 1], respectively.

I called them x(1), y(1), s(1) due to matlab notations.

Also, I am assuming f, g, h as 2, 0, 2, repectively.

For u, I used the impulse reponse, such as u\_1 (which repesents u at time 0) equals 1, and all other values of u equals 0.

```
for i = 2:100 % # of iterations
    x(i) = f*x(i-1) + g*u(i);
    y(i) = h*x(i);
    s(:, i) = [x(i); y(i)];
end
```

Below, I showed 10 values from x and y, respectively.

```
disp(x(1:10, 1));

    1
    2
    4
    8
    16
    32
    64
    128
    256
    512

disp(y(1:10, 1));
```

1 4

```
8
16
32
64
128
256
512
1024
```

Also, below are 5 columns of s, which is made up of [x; y] combined.

```
disp(s(:, 1:5))

1 2 4 8 16
1 4 8 16 32
```

## Estimating the system parameters:

Note: I used the explicit scheme.

```
n = 0.1; % learning rate
f = zeros(100, 1); % # of iterations
g = zeros(100, 1); % # of iterations
h = zeros(100, 1); % # of iterations
f(1) = 0;
g(1) = 0;
h(1) = 0;
```

I set the leaning rate to be 0.1

Moreover, I assumed the initial condition for f, g, h to be zeros.

```
I = [0 1];
e = zeros(100, 1); % # of iterations
d = zeros(100, 1); % # of iterations

for i = 1:100 % # of iterations
    d(i) = y(i) .* 1.17;
end
```

In the previous code, I tried to generate d (desired output) randomly based on the results we got for y.

```
for i = 2:100 % # of iterations
    e(i) = d(i) - y(i);
    f(i) = f(i-1) + n*e(i)*I*s(:, i-1);
    g(i) = g(i-1) + n*e(i)*h(i-1)*u(i);
    h(i) = h(i-1) + n*e(i)*y(i-1) + n*e(i)*g(i-1)*u(i);
end

Results = [f g h];
table(Results)
```

		Results	
2	0.068	0	0.068
3	0.612	0	0.612
4	2.788	0	2.788
5	11.492	0	11.492
6	46.308	0	46.308
7	185.572	0	185.572
8	742.628	0	742.628
9	2970.852	0	2970.852
10	11883.748	0	11883.748
11	47535.332	0	47535.332
12	190141.668	0	190141.668
13	760567.012	0	760567.012
14	3042268.388	0	3042268.388
15	12169073	0	12169073
16	48676295	0	48676295
17	194705183	0	194705183
18	778820736	0	778820736
19	311528294	0	311528294
20	124611317	0	124611317
21	498445271	0	498445271
22	199378108	0	199378108
23	797512434	0	797512434
24	319004973	0	319004973
25	127601989	0	127601989
26	510407957	0	510407957
27	204163183	0	204163183
28	816652732	0	816652732
29	3.2666109297	0	3.2666109297
30	1.3066443718	0	1.3066443718
31	5.2265774875	0	5.2265774875
32	2.0906309950	0	2.0906309950
33	8.3625239800	0	8.3625239800
34	3.3450095920	0	3.3450095920

		Results
35	1.3380038368	0 1.3380038368
36	5.3520153472	0 5.3520153472
37	2.1408061389	0 2.1408061389
38	8.5632245556	0 8.5632245556
39	3.4252898222	0 3.4252898222
40	1.3701159288	0 1.3701159288
41	5.4804637155	0 5.4804637155
42	2.1921854862	0 2.1921854862
43	8.7687419449	0 8.7687419449
44	3.5074967779	0 3.5074967779
45	1.4029987111	0 1.4029987111
46	5.6119948447	0 5.6119948447
47	2.2447979379	0 2.2447979379
48	8.9791917516	0 8.9791917516
49	3.5916767006	0 3.5916767006
50	1.4366706802	0 1.4366706802
51	5.7466827210	0 5.7466827210
52	2.2986730884	0 2.2986730884
53	9.1946923536	0 9.1946923536
54	3.6778769414	0 3.6778769414
55	1.4711507765	0 1.4711507765
56	5.8846031063	0 5.8846031063
57	2.3538412425	0 2.3538412425
58	9.4153649701	0 9.4153649701
59	3.7661459880	0 3.7661459880
60	1.5064583952	0 1.5064583952
61	6.0258335808	0 6.0258335808
62	2.4103334323	0 2.4103334323
63	9.6413337294	0 9.6413337294
64	3.8565334917	0 3.8565334917
65	1.5426133967	0 1.5426133967
66	6.1704535868	0 6.1704535868
67	2.4681814347	0 2.4681814347

		Results
68	9.8727257389	0 9.8727257389
69	3.9490902955	0 3.9490902955
70	1.5796361182	0 1.5796361182
71	6.3185444729	0 6.3185444729
72	2.5274177891	0 2.5274177891
73	1.0109671156	0 1.0109671156
74	4.0438684626	0 4.0438684626
75	1.6175473850	0 1.6175473850
76	6.4701895402	0 6.4701895402
77	2.5880758161	0 2.5880758161
78	1.0352303264	0 1.0352303264
79	4.1409213057	0 4.1409213057
80	1.6563685223	0 1.6563685223
81	6.6254740892	0 6.6254740892
82	2.6501896356	0 2.6501896356
83	1.0600758542	0 1.0600758542
84	4.2403034171	0 4.2403034171
85	1.6961213668	0 1.6961213668
86	6.7844854673	0 6.7844854673
87	2.7137941869	0 2.7137941869
88	1.0855176747	0 1.0855176747
89	4.3420706991	0 4.3420706991
90	1.7368282796	0 1.7368282796
91	6.9473131185	0 6.9473131185
92	2.7789252474	0 2.7789252474
93	1.1115700989	0 1.1115700989
94	4.4462803958	0 4.4462803958
95	1.7785121583	0 1.7785121583
96	7.1140486334	0 7.1140486334
97	2.8456194533	0 2.8456194533
98	1.1382477813	0 1.1382477813
99	4.5529911254	0 4.5529911254
100	1.8211964501	0 1.8211964501