

v8::internal::maglev
::anonymous_namespace
{maglev-interpreter-frame
-state::cc}::NodeInfoEmpty

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graph LR; A["v8::internal::maglev::anonymous_namespace {maglev-interpreter-frame -state::cc}::NodeInfoEmpty"] --> B["v8::internal::maglev::NodeInfo::possible_maps_are_known"]; A --> C["v8::internal::maglev::NodeInfo::type"];
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v8::internal::maglev
::NodeInfo::possible
_maps_are_known

v8::internal::maglev
::NodeInfo::type