

```
std::conditional_t  
< start_offset==end  
_offset, DataOnlyBodyDescriptor,  
FixedRangeBodyDescriptor<  
start_offset, end_offset > >
```

```
v8::internal::FixedBodyDescriptor  
< start_offset, end_offset, size >
```

```
v8::internal::FixedExposed  
TrustedObjectBodyDescriptor  
< T, kTag >
```

```
graph RL; A[v8::internal::FixedExposedTrustedObjectBodyDescriptor<T, kTag>] --> B[v8::internal::FixedBodyDescriptor<start_offset, end_offset, size>]; B --> C[std::conditional_t<start_offset==end_offset, DataOnlyBodyDescriptor, FixedRangeBodyDescriptor<start_offset, end_offset>>];
```