## LITERATURE REVIEW

S.NO	Title	Author	Year	Inference
	Hand-gesture-	1. M. Jacob		•This paper
	based sterile	2. J. Wachs	2013	presents a method
	interface for the	3. R. Packer		to improve the
	operating room	4. JAMIAs		navigation and
	using contextual			manipulation of
1	cuesfor the			radiological
	navigation of			images througha
	radiological			sterile hand
	images.			gesture recognition
				interface basedon
				attentional
				contextual cues.
				•Computer
				vision algorithms
				were developed
				to extract
				intention and
				attention cues
				from the
				surgeon's
				behavior and
				combine them
				with sensory data
				from a
				commodity depth
				camera.
				• The developed
				interface was
				tested in a
				usability
				experiment to
				assess the effectiveness of
				effectiveness of

				the new
				interface.
2	A gesture- based tool forsterile browsing of radiology images.	1. J. Wachs, 2. H. Stern, 3. Y. Edan 4. M. Gillam, 5. J.Handler, 6.C.Feied, 7.Mark S. Smith	2008	•This paper presents "Gestix," a vision-based hand gesture capture and recognition system that interprets in realtime the user's gestures for navigation and manipulation of images in an electronic medical record (EMR)database .• "Gestix" was tested during a brain biopsy procedure. In the in vivo experiment, this interface prevented the surgeon's focus shift and change of location while achieving a rapid intuitive reaction and easyinteraction .
3	Gesture- controlled image system positioning forminimally invasive interventions	<ol> <li>Benjamin</li> <li>Fritsch,</li> <li>T.Hoffmann,</li> <li>A.Mewes,</li> <li>G. Rose</li> </ol>	2021	• Abstract This work examines how a touchless interaction concept contributes to

				an efficient, direct, and sterile interaction workflow during CT- guided interventions.  • Two hand gesture sets were designed specifically under consideration of the clinical workflow and the hardware capabilities.
•	A gesture-controlled projection display for CT-guided interventions	1. A. Mewes, 2. P.Saalfeld, 3. Oleksandr Riabikin, 4. M. Skalej, 5. C. Hansen	2015	• A gesture set to control basic functions of intervention software such as gestures for 2D image exploration, 3Dobject manipulation and selection and is well suited to become an integral part of future interventional suites. • Purpose The interaction with interventional imaging systems within a sterile environment is

				a challengingtask
				for
				physicians
	Gesture-	1. Rolf Wipfli	2016	•Under the
	Controlled Image	2. V. Dubois-		premise that
	Management for	Ferrière,		mouse cannot be
	OperatingRoom	3.		used directly
		SylvainBudry4.		during surgery,
		P.Hoffmeyer,		gesture- controlled
5		5.C. Lovis		approaches
				demonstrate tobe
				superior to oral
				instructions for
				image
				manipulation.
				•Objective In this
				work, we aim at
				comparing
				formally three
				different
				interaction modes
				for image
				manipulation that
				are usablein a
				surgery setting:
				1) A gesture-
				controlled
				approach using
				Kinect ®;
				<b>2)</b> oral
				instructions to a
				third part
				dedicated to
				manipulate the
				images;
				3) direct
				manipulation
				using a mouse.
				asing a mouse.

6	Introducing a brain-computer interface to facilitate intraoperative medical imaging contol	1.H.Esfandiari, 2.PascalTroxler 3.S.Hodel 4.DanielSuter 5.M.Farshad, 6.Nicola Cavalcanti, 7. O.Wetzel, 8.SylvanoMani a9.F.Cornaz, 10.Farah Selman,	2022	• Background Safe and accurate execution of surgeries to date mainly rely on preoperative plans generated based on preoperative imaging. • Frequent intraoperative interaction with such patient images during the intervention is needed, which is currently a cumbersome process given that such images are generally displayed on peripheral two- dimensional (2D) monitors and controlled through interface devices that are outside the sterile filed.
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