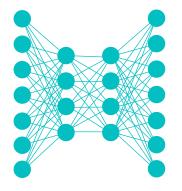
Lecture Notes for

Neural Networks and Machine Learning



Semi-supervised Loss Incorporation





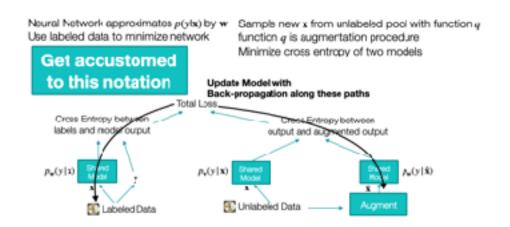
Logistics and Agenda

- Logistics
 - Lab one due soon!!
- Agenda
 - Consistency Loss
 - Temporal Output Discrepancy
 - Student Paper Presentation
- Next Time
 - Multi-modal and Multi-Task
 - Multi-task demo and Town Hall
 - Finish Demos



Last Time

$$\begin{split} \min_{\mathbf{w}} \frac{\text{cross entropy}}{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(\mathbf{y} \mid \mathbf{x})] + \lambda} & \text{consistency in augmentation} \\ \mathcal{D}_{\mathit{KL}}\left(p_{\mathbf{w}}(\mathbf{y} \mid \hat{\mathbf{x}}) \mid \mid p_{\mathbf{w}}(\mathbf{y} \mid \hat{\mathbf{x}})\right) \\ \mathcal{D}_{\mathit{KL}}(f \mid \mid g) &= -\sum f(\mathbf{x}) \cdot \log \frac{g(\mathbf{x})}{f(\mathbf{x})} \text{ definition of Kullback-Leibler KLI Divergence} \\ \mathcal{D}_{\mathit{KL}}(p(\mathbf{y} \mid \mathbf{x}) \mid \mid p(\mathbf{y} \mid \hat{\mathbf{x}})) &= -\sum p(\mathbf{y} \mid \mathbf{x}) \cdot \log \frac{p(\mathbf{y} \mid \hat{\mathbf{x}})}{p(\mathbf{y} \mid \mathbf{x})} = -\sum p(\mathbf{y} \mid \mathbf{x}) \cdot (\log p(\mathbf{y} \mid \hat{\mathbf{x}}) - \log p(\mathbf{y} \mid \mathbf{x})) \\ &= -\sum p(\mathbf{y} \mid \mathbf{x}) \cdot \log p(\mathbf{y} \mid \hat{\mathbf{x}}) + \sum p(\mathbf{y} \mid \mathbf{x}) \cdot \log p(\mathbf{y} \mid \mathbf{x}) \\ &= \mathbf{E}_{\mathbf{x} \in U, \hat{\mathbf{x}} \leftarrow q(\hat{\mathbf{x}} \mid \mathbf{x})} \left[-\log p(\mathbf{y} \mid \hat{\mathbf{x}}) \right] + \mathbf{E}_{\mathbf{x} \in U} \left[\log p(\mathbf{y} \mid \mathbf{x}) \right]_{\text{ignoresolator}} \\ &= \operatorname{cross entropy of unsupervised labels} & \operatorname{entropy of unsupervised labels} \\ &= \operatorname{after augmentation} \end{aligned}$$







| 59-80 50-20561 - 50-55 |
|---|
| ±7 (AD96) |
| |
| (u5 (4056) (u6)4056) |
| pool5 (3x3,256,2) pool5 (3x3,256,2) |
| com5 (3x3,236,1) (com5 (3x3,256,1) |
| com4 (8x2,384,1) com4 (8x2,384,2) |
| coerd (3x3,364,1) coerd (3x3,364,1) |
| LTM2 LTM2 |
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| convi (5-d.,184,2) conv2 (ix5,384,2) |
| UNE |
| pool1 (3x1,96,2) pool1 (3x1,94,3) |
| com/4 (1.1x11,06,4) (senv1 (11x11,06,4) |
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Unsupervised Visual Supresentation Learning by Contact Production

Unsupervised Consistency Loss (review)

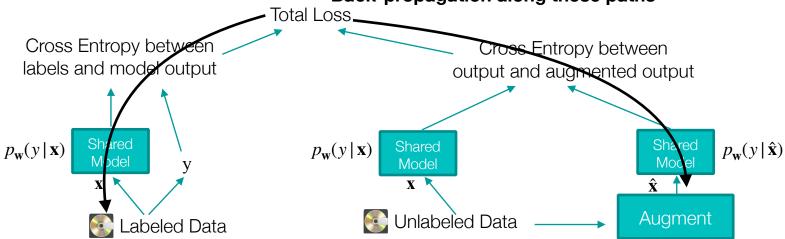
$$\min_{\mathbf{w}} \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{w}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\mathbf{no} \text{ back prop}} + \lambda \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y$$

Neural Network approximates $p(y|\mathbf{x})$ by \mathbf{w} Use labeled data to minimize network

Sample new \mathbf{x} from unlabeled pool with function q function q is augmentation procedure Minimize cross entropy of two models

Get accustomed to this notation

Update Model with Back-propagation along these paths



Unsupervised Data Augmentation (UDA) for Consistency Training, Xie et al., Neurlps 2019



$$\min \underbrace{\overline{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}}_{\mathbf{w}} + \lambda \underbrace{\qquad \qquad \qquad \qquad }_{\mathit{KL}} \left(p_{\mathbf{w}}(y \,|\, \mathbf{x}) \,|\, |p_{\mathbf{w}}(y \,|\, \hat{\mathbf{x}}) \right)}$$

$$E[g] = \sum p(g) \cdot g$$
 definition of expected value

$$E[-\log p_{\mathbf{w}}(y\,|\,\mathbf{x})] = -\sum p(y) \cdot \log p_{\mathbf{w}}(y\,|\,\mathbf{x}) \quad \text{insert -log probability, log likelihood}$$

$$NLL(y, p_{\mathbf{w}}(y \mid \mathbf{x})) = -\sum_{c} p(y = c) \cdot \log p_{\mathbf{w}}(y = c \mid \mathbf{x})$$
 negative log likelihood

$$CE(f,g) = -\sum f(x) \cdot \log g(x)$$
 cross entropy of two functions

$$CE(y, p_{\mathbf{w}}(y \mid \mathbf{x})) = -\sum_{c} (y = c) \cdot \log p_{\mathbf{w}}(y = c \mid \mathbf{x})$$
 if $y = c$ is a probability, these are same equation

cce = tf.keras.losses.CategoricalCrossentropy()
cce(y_true, y_pred)



$$\min_{\mathbf{w}} \underbrace{\mathbf{E}_{\mathbf{x},y \in L}[-\log p_{\mathbf{w}}(y \,|\, \mathbf{x})]}_{\text{Cross entropy}} + \lambda \underbrace{\qquad \qquad \qquad }_{KL} \left(p_{\mathbf{w}}(y \,|\, \mathbf{x}) \,|\, |p_{\mathbf{w}}(y \,|\, \hat{\mathbf{x}}) \right)}_{\text{Cross entropy}}$$

$$\begin{split} \mathcal{D}_{\mathit{KL}}(f \,|\, |\, g) &= -\sum f(\mathbf{x}) \cdot \log \frac{g(\mathbf{x})}{f(\mathbf{x})} \text{ definition of Kullback-Leibler (KL) Divergence} \\ \mathcal{D}_{\mathit{KL}}(p_{\mathbf{w}}(y \,|\, \mathbf{x}) \,|\, |\, p_{\mathbf{w}}(y \,|\, \hat{\mathbf{x}})) \\ \mathcal{D}_{\mathit{KL}}(p(y \,|\, \mathbf{x}) \,|\, |\, p(y \,|\, \hat{\mathbf{x}})) &= -\sum p(y \,|\, \mathbf{x}) \cdot \log \frac{p(y \,|\, \hat{\mathbf{x}})}{p(y \,|\, \mathbf{x})} = -\sum p(y \,|\, \mathbf{x}) \cdot \left(\log p(y \,|\, \hat{\mathbf{x}}) - \log p(y \,|\, \mathbf{x})\right) \\ &= -\sum p(y \,|\, \mathbf{x}) \cdot \log p(y \,|\, \hat{\mathbf{x}}) + \sum p(y \,|\, \mathbf{x}) \cdot \log p(y \,|\, \mathbf{x}) \end{split}$$

 $p(y \mid \mathbf{x}) \approx p(y)$ if **x** is a very large subset of the entire domain and $p_{\mathbf{w}}$ is a good *variational* approximation

So this is
$$= \mathbf{E}_{\mathbf{x} \in U, \hat{\mathbf{x}} \leftarrow q(\hat{\mathbf{x}} | \mathbf{x})} \left[-\log p(y | \hat{\mathbf{x}}) \right] + \mathbf{E}_{\mathbf{x} \in U} \left[\log p(y | \mathbf{x}) \right]_{\text{ignore}}$$

cross entropy of unsupervised labels after augmentation

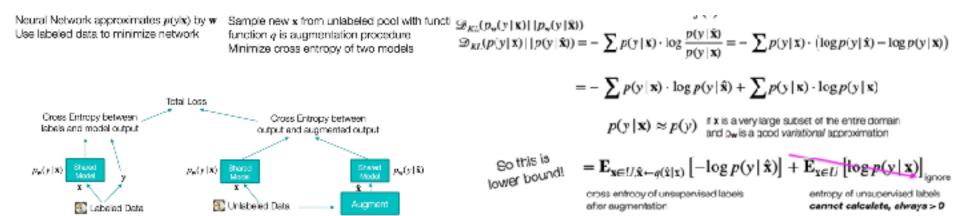
entropy of unsupervised labels cannot calculate, always > 0

cce = tf.keras.losses.CategoricalCrossentropy()
cce(y_pred, y_pred_augmented)



Aside:

We have just seen two motivations:



intuition of final product

keep labels consistent, any measure would be okay

mathematics with heavy approximation

cross entropy is lower bound for KL divergence, which is a nice measure



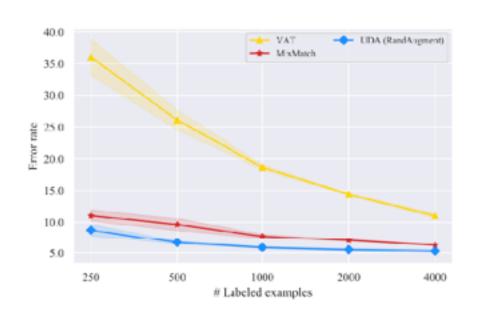
Unsupervised Consistency Loss

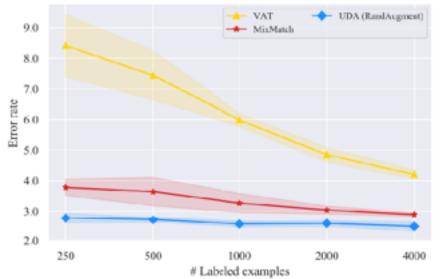
| Augmentation (# Sup examples) | Sup (50k) | Semi-Sup (4k) |
|----------------------------------|--------------|------------------|
| Crop & flip | 5.36 | 16.17 |
| Cutout | 4.42 | 6.42 |
| RandAugment | 4.23 | 5.29 |

Table 1: Error rates on CIFAR-10.

| Augmentation (# Sup examples) | Sup (650k) | Semi-sup (2.5k) | |
|----------------------------------|---------------|--------------------|--|
| X | 38.36 | 50.80 | |
| Switchout | 37.24 | 43.38 | |
| Back-translation | 36.71 | 41.35 | |

Table 2: Error rate on Yelp-5.





(a) CIFAR-10

Unsupervised Data Augmentation (UDA) for Consistency Training, Xie et al., Neurlps 2019



(b) SVHN

Unsupervised Consistency Loss

| Method | Model | # Param | CIFAR-10 (4k) | SVHN (1k) |
|--|------------|---------|------------------|-----------------|
| Π-Model (Laine & Aila, 2016) | Conv-Large | 3.1M | 12.36 ± 0.31 | 4.82 ± 0.17 |
| Mean Teacher (Tarvainen & Valpola, 2017) | Conv-Large | 3.1M | 12.31 ± 0.28 | 3.95 ± 0.19 |
| VAT + EntMin (Miyato et al., 2018) | Conv-Large | 3.1M | 10.55 ± 0.05 | 3.86 ± 0.11 |
| SNTG (Luo et al., 2018) | Conv-Large | 3.1M | 10.93 ± 0.14 | 3.86 ± 0.27 |
| VAdD (Park et al., 2018) | Conv-Large | 3.1M | 11.32 ± 0.11 | 4.16 ± 0.08 |
| Fast-SWA (Athiwaratkun et al., 2018) | Conv-Large | 3.1M | 9.05 | - |
| ICT (Verma et al., 2019) | Conv-Large | 3.1M | 7.29 ± 0.02 | 3.89 ± 0.04 |
| Pseudo-Label (Lee, 2013) | WRN-28-2 | 1.5M | 16.21 ± 0.11 | 7.62 ± 0.29 |
| LGA + VAT (Jackson & Schulman, 2019) | WRN-28-2 | 1.5M | 12.06 ± 0.19 | 6.58 ± 0.36 |
| mixmixup (Hataya & Nakayama, 2019) | WRN-28-2 | 1.5M | 10 | - |
| ICT (Verma et al., 2019) | WRN-28-2 | 1.5M | 7.66 ± 0.17 | 3.53 ± 0.07 |
| MixMatch (Berthelot et al., 2019) | WRN-28-2 | 1.5M | 6.24 ± 0.06 | 2.89 ± 0.06 |

| Methods | SSL | 10% | 100% |
|-----------------------------|-----|--------------------------------|--------------------------------|
| ResNet-50 w. RandAugment | × | 55.09 / 77.26 58.84 / 80.56 | 77.28 / 93.73 78.43 / 94.37 |
| UDA (RandAugment) | / | 68.78 / 88.80 | 79.05 / 94.49 |

Table 5: Top-1 / top-5 accuracy on ImageNet with 10% and 100% of the labeled set. We use image size 224 and 331 for the 10% and 100% experiments respectively.

Other Measures of Consistency: TOD

- Main idea: use unsupervised labels to prevent overfitting
- Temporal Output Discrepancy (TOD) (Huang et al., ICCV21)

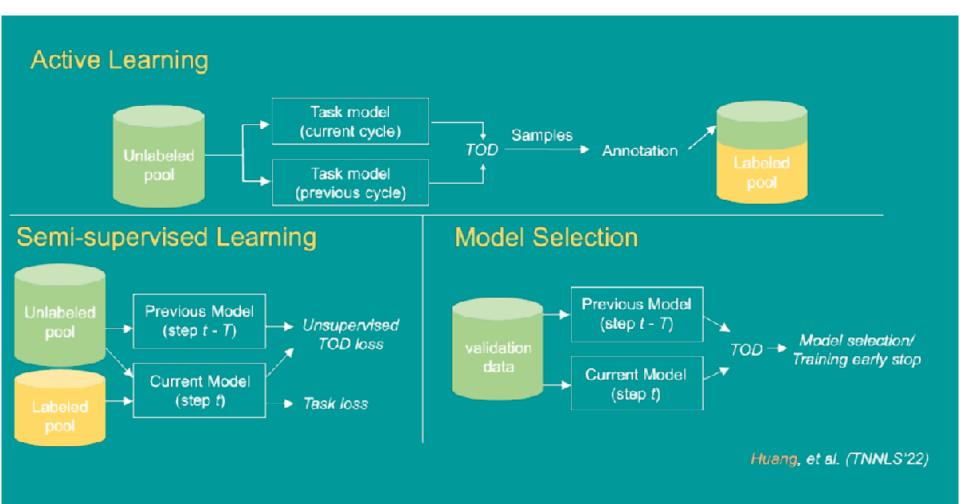


Discrepancy

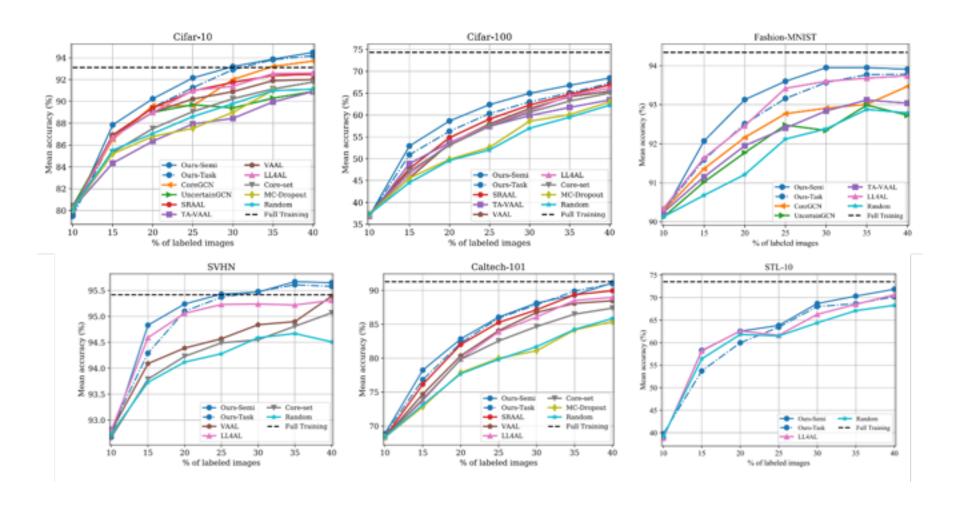
$$\|p_{\mathbf{W}_{t+T}}(y\,|\,\mathbf{\hat{x}}) - p_{\mathbf{W}_t}(y\,|\,\mathbf{\hat{x}})\|$$
 under certain conditions, this is a valid Wasserstein distance

$$\min_{\mathbf{w}} \underbrace{\mathbf{E}_{\mathbf{x}, y \in L}[-\log p_{\mathbf{w}_{t+T}}(y \mid \mathbf{x})]}_{\text{cross entropy}} + \underbrace{\lambda \cdot \mathbf{E}_{\hat{\mathbf{x}} \in U} \left[\left\| p_{\mathbf{W}_{t+T}}(y \mid \hat{\mathbf{x}}) - p_{\mathbf{W}_{t}}(y \mid \hat{\mathbf{x}}) \right\| \right]}_{\text{discrepancy}}$$

Using Temporal Discrepancy



Active Learning with TOD





Paper Presentation: GPT-3

Language Models are Few-Shot Learners

| Tom B. Bro | wn* Benjamin | Mann* Nick | Ryder* Me | lanie Subbiah* | |
|---------------------------|-------------------|--------------------|------------------|--------------------|--|
| Jared Kaplan [†] | Prafulla Dhariwal | Arvind Neelakantan | Pranav Shyam | Girish Sastry | |
| Amanda Askell | Sandhini Agarwal | Ariel Herbert-Voss | Gretchen Krueger | Tom Henighan | |
| Rewon Child | Aditya Ramesh | Daniel M. Ziegler | Jeffrey Wu | Clemens Winter | |
| Christopher He | esse Mark Chen | Eric Sigler | Mateusz Litwin | Scott Gray | |
| Benjar | min Chess | Chess Jack Clark | | Christopher Berner | |
| Sam McCan | ndlish Alec Ra | idford Bya S | Sutskever 1 | Dario Amodei | |

OpenAI



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