```
from google.colab import files
files.upload()

<IPython.core.display.HTML object>

Saving kaggle.json to kaggle.json
{'kaggle.json':
b'{"username":"khushi0405","key":"fc5598b1513e4a53ff4ff859d817dd36"}'}
!mkdir ~/.kaggle
!cp kaggle.json ~/.kaggle/
!chmod 600 ~/.kaggle/kaggle.json
!kaggle competitions download -c dogs-vs-cats

Downloading dogs-vs-cats.zip to /content
100% 810M/812M [00:10<00:00, 127MB/s]
100% 812M/812M [00:10<00:00, 79.2MB/s]
!unzip -o -qq dogs-vs-cats.zip
!unzip -o -qq train.zip</pre>
```

1. Consider the Cats & Dogs example. Start initially with a training sample of 1000, a validation sample of 500, and a test sample of 500 (like in the text). Use any technique to reduce overfitting and improve performance in developing a network that you train from scratch. What performance did you achieve?

Creating directory named cats vs dogs small to store the images into 3 subsets and Dividing the training sample of 1000, a validation sample of 500, and a test sample of 500

```
import os
import shutil
import pathlib

shutil.rmtree("cats_vs_dogs_small/train/cat")

original_dir = pathlib.Path("train")
new_base_dir = pathlib.Path("cats_vs_dogs_small")

def make_subset(subset_name, start_index, end_index):
    for category in ("cat", "dog"):
        dir = new_base_dir / subset_name / category
        os.makedirs(dir, exist_ok = True)
        fnames = [f"{category}.{i}.jpg" for i in range(start_index, end_index)]
        for fname in fnames:
            shutil.copyfile(src=original_dir / fname,
```

```
dst=dir / fname)
make_subset("train", start_index=0, end index=500)
make_subset("validation", start_index=1000, end_index=1250)
make subset("test", start index=1500, end index=1750)
from tensorflow import keras
from tensorflow.keras import layers
from tensorflow.keras.utils import image dataset from directory
from tensorflow.keras.callbacks import EarlyStopping
from tensorflow.keras.callbacks import ModelCheckpoint
from io import BytesIO
from zipfile import ZipFile
train dataset = image dataset from directory(
    new_base_dir / "train",
    image size=(180, 180),
    batch size=32)
validation dataset = image dataset from directory(
    new base dir / "validation",
    image size=(180, 180),
    batch size=32)
test dataset = image dataset from directory(
    new base dir / "test",
    image size=(180, 180),
    batch size=32)
Found 1000 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
for data batch, labels batch in train dataset:
    print("data batch shape:", data_batch.shape)
    print("labels batch shape:", labels_batch.shape)
    break
data batch shape: (32, 180, 180, 3)
labels batch shape: (32,)
```

Model - 1 MaxPooling Operation with Increase in filters from 32 to 256 in 5 Input Layers : Instantiating a small convnet for dogs vs. cats classification

```
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=64, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
```

```
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.Flatten()(x)
outputs = layers.Dense(1, activation="sigmoid")(x)

model = keras.Model(inputs=inputs, outputs=outputs)
model.summary()
```

Model: "model"

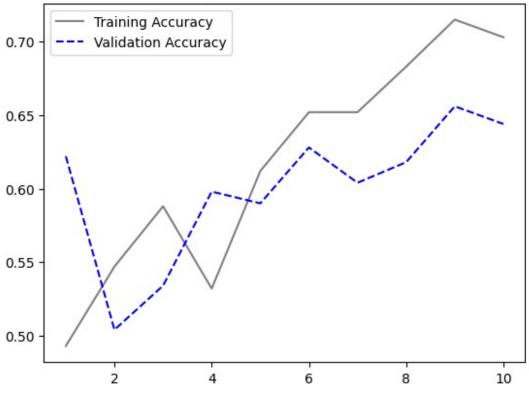
Layer (type)	Output Shape	Param #
input_1 (InputLayer)	[(None, 180, 180, 3)]	0
rescaling (Rescaling)	(None, 180, 180, 3)	0
conv2d (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, 89, 89, 32)	0
conv2d_1 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_1 (MaxPoolin g2D)</pre>	(None, 43, 43, 64)	0
conv2d_2 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, 20, 20, 128)	0
conv2d_3 (Conv2D)	(None, 18, 18, 256)	295168
<pre>max_pooling2d_3 (MaxPoolin g2D)</pre>	(None, 9, 9, 256)	0
conv2d_4 (Conv2D)	(None, 7, 7, 256)	590080
flatten (Flatten)	(None, 12544)	0
dense (Dense)	(None, 1)	12545

Total params: 991041 (3.78 MB) Trainable params: 991041 (3.78 MB) Non-trainable params: 0 (0.00 Byte)

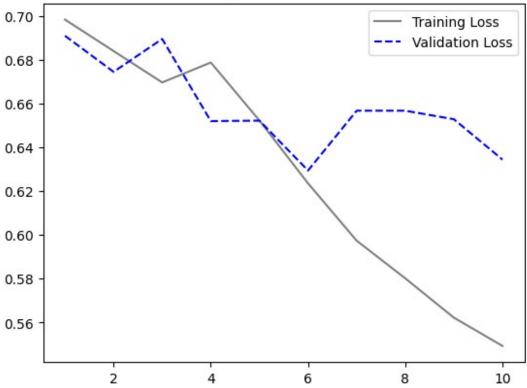
```
model.compile(loss="binary crossentropy",
         optimizer="adam",
         metrics=["accuracy"])
# Saving the results of the model
callbacks = ModelCheckpoint(
        filepath= "model1.keras",
        save best only= True,
       monitor= "val_loss"
        )
# Fitting/Running the Model
Model 1 = model.fit(
      train dataset,
      epochs= 10,
      validation data= validation dataset,
      callbacks= callbacks)
Epoch 1/10
accuracy: 0.4930 - val loss: 0.6910 - val accuracy: 0.6220
Epoch 2/10
accuracy: 0.5470 - val loss: 0.6745 - val accuracy: 0.5040
Epoch 3/10
accuracy: 0.5880 - val loss: 0.6895 - val accuracy: 0.5340
Epoch 4/10
accuracy: 0.5320 - val loss: 0.6520 - val accuracy: 0.5980
Epoch 5/10
accuracy: 0.6120 - val loss: 0.6522 - val accuracy: 0.5900
Epoch 6/10
32/32 [============= ] - 109s 3s/step - loss: 0.6236 -
accuracy: 0.6520 - val loss: 0.6294 - val accuracy: 0.6280
accuracy: 0.6520 - val loss: 0.6567 - val accuracy: 0.6040
Epoch 8/10
accuracy: 0.6830 - val loss: 0.6567 - val accuracy: 0.6180
Epoch 9/10
32/32 [============== ] - 112s 3s/step - loss: 0.5622 -
accuracy: 0.7150 - val loss: 0.6528 - val accuracy: 0.6560
Epoch 10/10
accuracy: 0.7030 - val loss: 0.6344 - val accuracy: 0.6440
```

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import requests
import seaborn as sns
import zipfile
import io
import os
import shutil
import pathlib
%matplotlib inline
accuracy = Model 1.history["accuracy"]
val accuracy = Model 1.history["val accuracy"]
loss = Model 1.history["loss"]
val loss = Model 1.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
plt.plot(epochs, val accuracy, color="blue",linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```





# Training and Validation Loss



Evaluating the performance of Model\_1 on test set

Using Measures to Avoid Overfitting

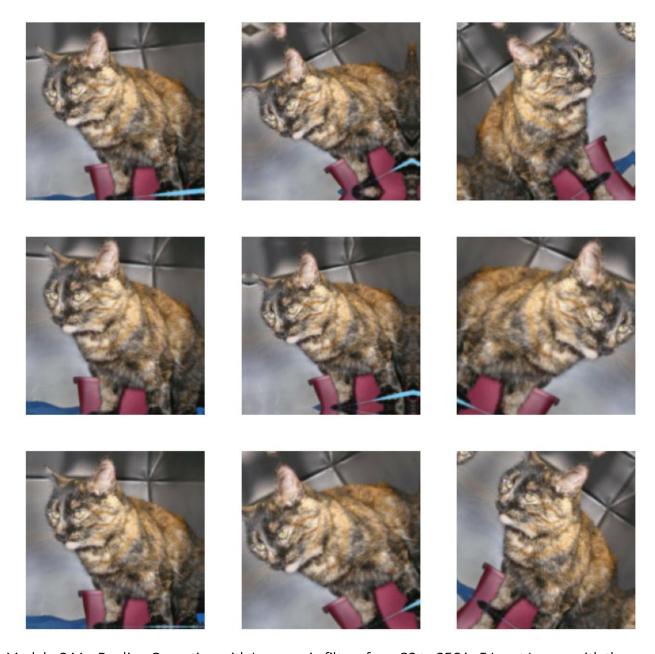
Data Augmentation

```
import logging
logging.getLogger('tensorflow').disabled = True
```

Using few of the techniques such as random flip, random zoom, random rotation so as to create augmented versions of the image

Looking at the augmented images

```
plt.figure(figsize=(10, 10))
for images, _ in train_dataset.take(1):
    for i in range(9):
        augmented_images = data_augmentation(images)
        ax = plt.subplot(3, 3, i + 1)
        plt.imshow(augmented_images[0].numpy().astype("uint8"))
        plt.axis("off")
```



Model - 2 MaxPooling Operation with Increase in filters from 32 to 256 in 5 Input Layers with the data being used from the Augmented Images and a droput rate of 0.5\*

```
inputs = keras.Input(shape=(180, 180, 3))
x = data_augmentation(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=64, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
```

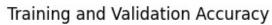
```
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
```

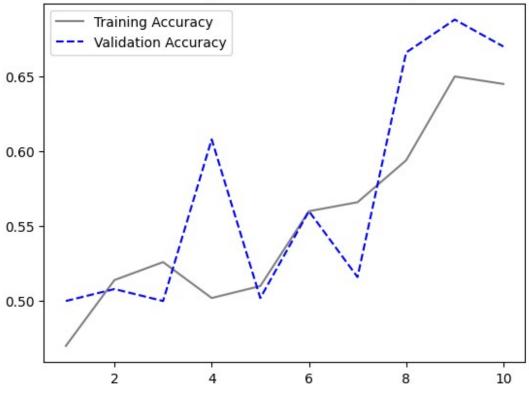
#### Training the model 2

```
# Compiling the model
model.compile(loss="binary crossentropy",
          optimizer="adam",
          metrics=["accuracy"])
# Saving the results of the model
callbacks = ModelCheckpoint(
         filepath= "model2.keras",
         save best only= True,
         monitor= "val loss")
# Fitting/Running the Model
Model 2 = model.fit(
       train dataset,
       epochs= 10,
       validation_data= validation_dataset,
       callbacks= callbacks)
Epoch 1/10
accuracy: 0.4700 - val loss: 0.6925 - val accuracy: 0.5000
Epoch 2/10
accuracy: 0.5140 - val loss: 0.6918 - val accuracy: 0.5080
Epoch 3/10
accuracy: 0.5260 - val_loss: 0.6931 - val_accuracy: 0.5000
Epoch 4/10
accuracy: 0.5020 - val loss: 0.6908 - val accuracy: 0.6080
Epoch 5/10
32/32 [============= ] - 117s 4s/step - loss: 0.6923 -
accuracy: 0.5100 - val loss: 0.6911 - val accuracy: 0.5020
Epoch 6/10
32/32 [============= ] - 113s 4s/step - loss: 0.6850 -
accuracy: 0.5600 - val loss: 0.7064 - val accuracy: 0.5600
Epoch 7/10
32/32 [============== ] - 127s 4s/step - loss: 0.6908 -
```

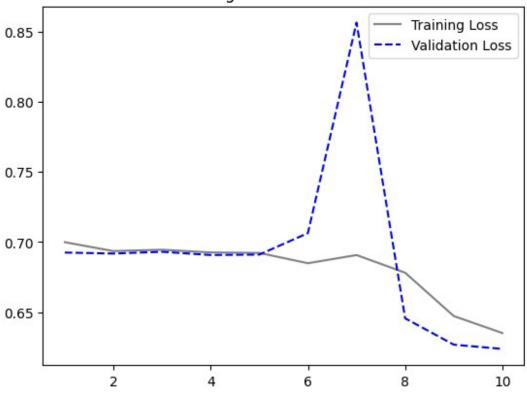
Visualizing the Training and Validation Accuracy/Loss 2

```
accuracy = Model 2.history["accuracy"]
val accuracy = Model 2.history["val accuracy"]
loss = Model 2.history["loss"]
val loss = Model 2.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
plt.plot(epochs, val accuracy, color="blue",linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```





# Training and Validation Loss



Comparing the Model 1 and Model 2: we can clearly see that the accuracy rate of model 2 is higher than model 1

Model - 3 MaxPooling Operation with Increase in filters from 32 to 512 in 6 Input Layers with the use of Augmented Images and Dropout rate of 0.5

```
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=512, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = lavers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.summary()
Model: "model 2"
Layer (type)
                             Output Shape
                                                        Param #
                             [(None, 180, 180, 3)]
 input 3 (InputLayer)
 sequential (Sequential)
                             (None, 180, 180, 3)
                                                        0
 rescaling 2 (Rescaling)
                             (None, 180, 180, 3)
```

conv2d_10 (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d_8 (MaxPoolin g2D)</pre>	(None, 89, 89, 32)	0
conv2d_11 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_9 (MaxPoolin g2D)</pre>	(None, 43, 43, 64)	0
conv2d_12 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_10 (MaxPooli ng2D)</pre>	(None, 20, 20, 128)	0
conv2d_13 (Conv2D)	(None, 18, 18, 256)	295168
<pre>max_pooling2d_11 (MaxPooli ng2D)</pre>	(None, 9, 9, 256)	0
conv2d_14 (Conv2D)	(None, 7, 7, 256)	590080
<pre>max_pooling2d_12 (MaxPooli ng2D)</pre>	(None, 3, 3, 256)	0
conv2d_15 (Conv2D)	(None, 1, 1, 512)	1180160
flatten_2 (Flatten)	(None, 512)	0
dropout_1 (Dropout)	(None, 512)	0
	(None, 1)	513

### Training the model 3

```
filepath= "model3.keras",
      save best only= True,
      monitor= "val loss")
# Model Fit
Model 3 = model.fit(
     train dataset,
     epochs= 10,
     validation data= validation dataset,
     callbacks = callbacks)
Epoch 1/10
accuracy: 0.4860 - val loss: 0.6926 - val accuracy: 0.5000
Epoch 2/10
accuracy: 0.4960 - val loss: 0.6932 - val accuracy: 0.5000
accuracy: 0.4940 - val loss: 0.6930 - val accuracy: 0.5000
Epoch 4/10
accuracy: 0.5240 - val loss: 0.6835 - val accuracy: 0.5520
Epoch 5/10
accuracy: 0.5320 - val_loss: 0.6858 - val_accuracy: 0.5620
Epoch 6/10
accuracy: 0.5620 - val loss: 0.6832 - val accuracy: 0.5380
Epoch 7/10
accuracy: 0.5730 - val loss: 0.6690 - val accuracy: 0.6160
Epoch 8/10
accuracy: 0.6080 - val loss: 0.6348 - val accuracy: 0.6380
Epoch 9/10
accuracy: 0.6480 - val_loss: 0.6342 - val_accuracy: 0.6320
Epoch 10/10
accuracy: 0.6320 - val loss: 0.6503 - val accuracy: 0.6120
```

Visualizing the Training and Validation Accuracy/Loss 2

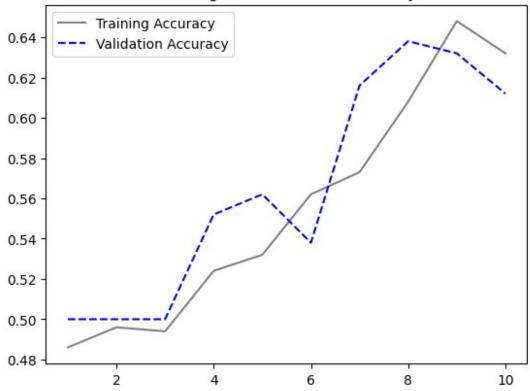
```
accuracy = Model_3.history["accuracy"]
val_accuracy = Model_3.history["val_accuracy"]
loss = Model_3.history["loss"]
```

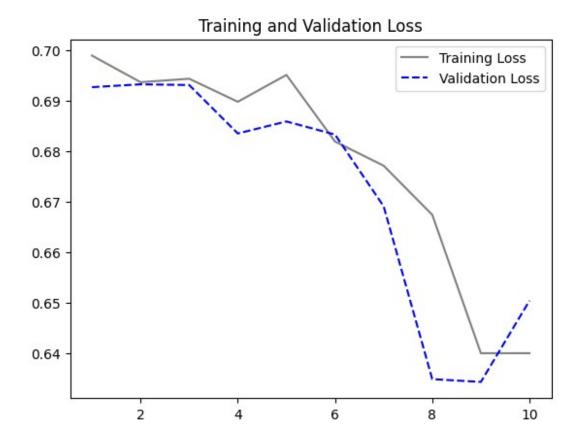
```
val_loss = Model_3.history["val_loss"]

epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
plt.plot(epochs, val_accuracy, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()

plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val_loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```

### Training and Validation Accuracy





Evaluating the performance of Model\_2 on the test set

Model - 4 MaxPooling Operation with Increase in filters from 64 to 1024 in 5 Input Layers with the use of Augmented Images and Dropout rate of 0.6

```
inputs = keras.Input(shape=(180,180,3))
x = data_augmentation(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=64, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
```

```
x = layers.Conv2D(filters=512, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=1024, kernel_size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.6)(x)

outputs = layers.Dense(1, activation="sigmoid")(x)

model = keras.Model(inputs=inputs, outputs=outputs)

model.summary()
```

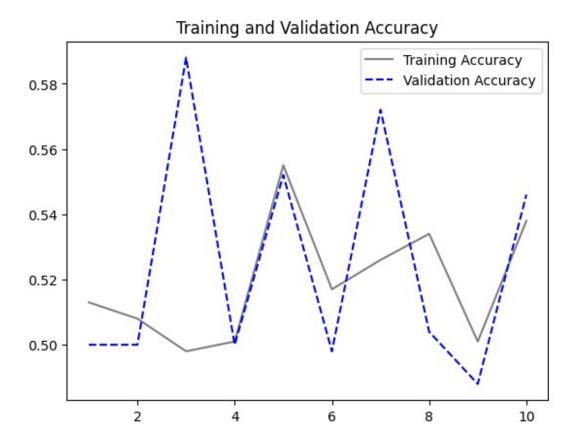
Model: "model\_3"

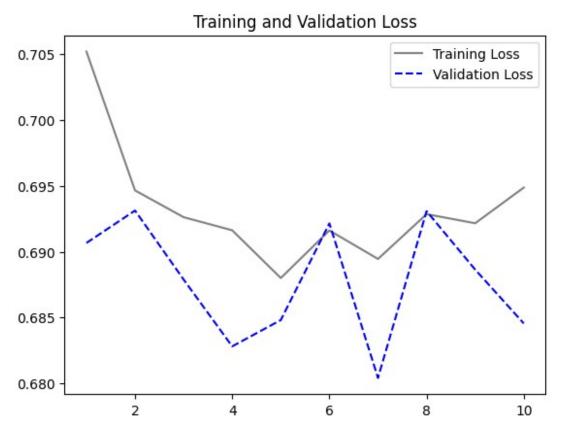
Layer (type)	Output Shape	Param #
input_4 (InputLayer)	[(None, 180, 180, 3)]	0
sequential (Sequential)	(None, 180, 180, 3)	0
<pre>rescaling_3 (Rescaling)</pre>	(None, 180, 180, 3)	0
conv2d_16 (Conv2D)	(None, 178, 178, 64)	1792
<pre>max_pooling2d_13 (MaxPooli ng2D)</pre>	(None, 89, 89, 64)	0
conv2d_17 (Conv2D)	(None, 87, 87, 128)	73856
<pre>max_pooling2d_14 (MaxPooli ng2D)</pre>	(None, 43, 43, 128)	0
conv2d_18 (Conv2D)	(None, 41, 41, 256)	295168
<pre>max_pooling2d_15 (MaxPooli ng2D)</pre>	(None, 20, 20, 256)	0
conv2d_19 (Conv2D)	(None, 18, 18, 512)	1180160
<pre>max_pooling2d_16 (MaxPooli ng2D)</pre>	(None, 9, 9, 512)	0
conv2d_20 (Conv2D)	(None, 7, 7, 1024)	4719616
flatten_3 (Flatten)	(None, 50176)	0
dropout_2 (Dropout)	(None, 50176)	0
dense_3 (Dense)	(None, 1)	50177

```
Total params: 6320769 (24.11 MB)
Trainable params: 6320769 (24.11 MB)
Non-trainable params: 0 (0.00 Byte)
# Compiling the Model
model.compile(loss= "binary crossentropy",
          optimizer= "adam",
          metrics= ['accuracy'])
# Monitoring the best validation loss using Callbacks
callbacks = ModelCheckpoint(
        filepath = "model4.keras",
        save best only= True,
        monitor= "val loss"
# Model Fit
Model 4 = model.fit(
       train dataset,
       epochs= 10,
       validation data= validation dataset,
       callbacks = callbacks
Epoch 1/10
- accuracy: 0.5130 - val loss: 0.6907 - val_accuracy: 0.5000
Epoch 2/10
- accuracy: 0.5080 - val loss: 0.6931 - val accuracy: 0.5000
Epoch 3/10
- accuracy: 0.4980 - val loss: 0.6879 - val accuracy: 0.5880
Epoch 4/10
- accuracy: 0.5010 - val loss: 0.6828 - val accuracy: 0.5000
Epoch 5/10
- accuracy: 0.5550 - val loss: 0.6848 - val accuracy: 0.5520
Epoch 6/10
32/32 [============== ] - 390s 12s/step - loss: 0.6916
- accuracy: 0.5170 - val_loss: 0.6922 - val_accuracy: 0.4980
Epoch 7/10
32/32 [============== ] - 388s 12s/step - loss: 0.6895
- accuracy: 0.5260 - val_loss: 0.6804 - val_accuracy: 0.5720
Epoch 8/10
```

Visualizing the Training and Validation Accuracy/Loss 2

```
accuracy = Model 4.history["accuracy"]
val accuracy = Model 4.history["val accuracy"]
loss = Model 4.history["loss"]
val loss = Model 4.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
plt.plot(epochs, val accuracy, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val_loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```





Summary of Question 1: Using 1000 as the training sample, we did attempt to create 4 models. Let's now evaluate the accuracy and loss of all four models to determine which produces the best results.

Model 1: five input layers, filters ranging from 32 to 256

Model 2: five input layers, augmented images, filters ranging from 32 to 256, and a 0.5 dropout rate

Model 3: six input layers, augmented images, filters ranging from 32 to 512, and a 0.5 dropout rate

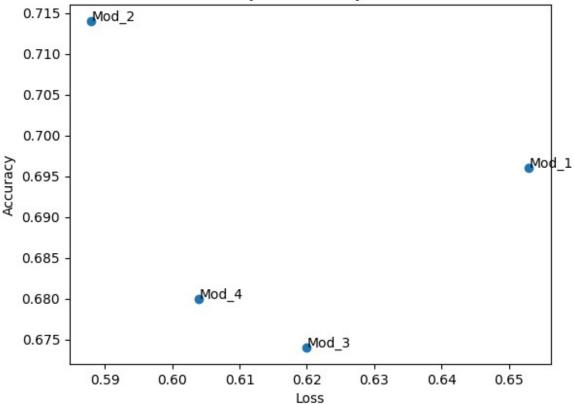
Model 4: five input layers, augmented images, filters ranging from 32 to 1024, and a 0.6 dropout rate

```
Model_1 = (0.647, 0.604)
Model_2 = (0.659, 0.600)
Model_3 = (0.653,0.636)
Model_4 = (0.685, 0.562)

Models = ("Mod_1", "Mod_2", "Mod_3", "Mod_4")
Loss = (Model_1[0], Model_2[0], Model_3[0], Model_4[0])
Accuracy = (Model_1[1], Model_2[1], Model_3[1], Model_4[1])

fig, ax = plt.subplots()
ax.scatter(Loss, Accuracy)
for i, txt in enumerate(Models):
    ax.annotate(txt, (Loss[i], Accuracy[i] ))
plt.title("Summary for Accuracy and Loss")
plt.ylabel("Accuracy")
plt.xlabel("Loss")
```





Conclusions: Based on the graph above, we can say that model 2 is the best among the rest, having the most accuracy and the least amount of loss; model 4 has the greatest loss.

Recommendation: Since model 2 is the most effective of the four models, we should select it. It has five input layers, augmented images, a dropout rate of 0.5, and filters ranging from 32 to 256.

1. Increase your training sample size. You may pick any amount. Keep the validation and test samples the same as above. Optimize your network (again training from scratch). What performance did you achieve?

Considering Training Sample - 2000

```
import os, shutil, pathlib

original_dir = pathlib.Path("train")
new_base_dir = pathlib.Path("cats_vs_dogs")

def make_subset(subset_name, start_index, end_index):
    for category in ("cat", "dog"):
        dir = new_base_dir / subset_name / category
        os.makedirs(dir)
        fnames = [f"{category}.{i}.jpg" for i in range(start_index, end_index)]
```

Data Pre-Processing: Using image\_dataset\_from\_directory to read images

```
train_dataset = image_dataset_from_directory(
    new_base_dir / "train",
    image_size=(180, 180),
    batch_size=32)
validation_dataset = image_dataset_from_directory(
    new_base_dir / "validation",
    image_size=(180, 180),
    batch_size=32)
test_dataset = image_dataset_from_directory(
    new_base_dir / "test",
    image_size=(180, 180),
    batch_size=32)

Found 2000 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
```

Viewing the size of the images

Model - 5 MaxPooling Operation with Increase in filters from 32 to 256 in 5 Input Layers with the data being used from the Augmented Images and a droput rate of 0.5 (Training Sample - 2000)

```
inputs = keras.Input(shape=(180, 180, 3))
x = data_augmentation_1(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=64, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
```

```
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.summary()
```

Model: "model\_4"

Layer (type)	Output Shape	Param #
input_5 (InputLayer)	[(None, 180, 180, 3)]	0
sequential_1 (Sequential)	(None, 180, 180, 3)	0
rescaling_4 (Rescaling)	(None, 180, 180, 3)	0
conv2d_21 (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d_17 (MaxPooli ng2D)</pre>	(None, 89, 89, 32)	0
conv2d_22 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_18 (MaxPooli ng2D)</pre>	(None, 43, 43, 64)	0
conv2d_23 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_19 (MaxPooli ng2D)</pre>	(None, 20, 20, 128)	0
conv2d_24 (Conv2D)	(None, 18, 18, 256)	295168
<pre>max_pooling2d_20 (MaxPooli ng2D)</pre>	(None, 9, 9, 256)	0
conv2d_25 (Conv2D)	(None, 7, 7, 256)	590080
flatten_4 (Flatten)	(None, 12544)	0
dropout_3 (Dropout)	(None, 12544)	0
dense_4 (Dense)	(None, 1)	12545

```
Total params: 991041 (3.78 MB)
Trainable params: 991041 (3.78 MB)
Non-trainable params: 0 (0.00 Byte)
```

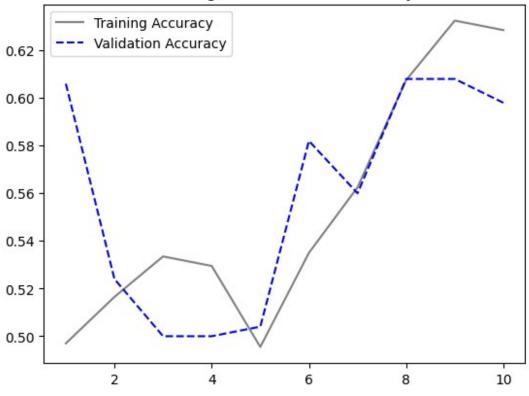
#### Training the model 5

```
# Compiling the Model
model.compile(loss= "binary crossentropy",
         optimizer= "adam",
        metrics= ['accuracy'])
# Monitoring the best validation loss using Callbacks
callbacks = ModelCheckpoint(
       filepath = "model5.keras",
       save_best_only= True,
       monitor= "val loss"
# Model Fit
Model 5 = model.fit(
      train dataset,
      epochs= 10,
      validation data= validation dataset,
      callbacks= callbacks
Epoch 1/10
accuracy: 0.4970 - val loss: 0.6849 - val accuracy: 0.6060
Epoch 2/10
accuracy: 0.5165 - val_loss: 0.6929 - val_accuracy: 0.5240
Epoch 3/10
accuracy: 0.5335 - val loss: 0.6945 - val accuracy: 0.5000
Epoch 4/10
accuracy: 0.5295 - val_loss: 0.6898 - val_accuracy: 0.5000
Epoch 5/10
accuracy: 0.4955 - val loss: 0.6868 - val accuracy: 0.5040
Epoch 6/10
accuracy: 0.5350 - val loss: 0.6676 - val accuracy: 0.5820
Epoch 7/10
accuracy: 0.5625 - val loss: 0.6794 - val accuracy: 0.5600
```

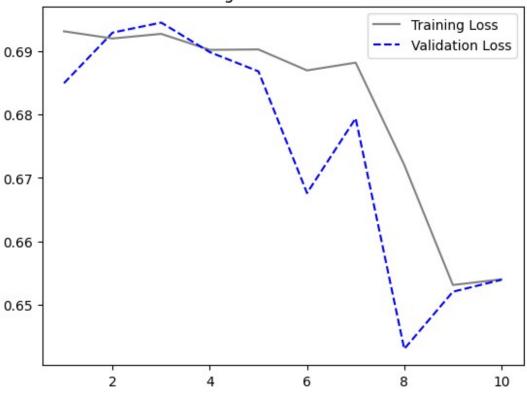
Visualizing the Training and Validation Accuracy/Loss 2

```
accuracy = Model 5.history["accuracy"]
val accuracy = Model 5.history["val accuracy"]
loss = Model 5.history["loss"]
val loss = Model 5.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
plt.plot(epochs, val accuracy, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```





# Training and Validation Loss



Summary: The second model built just with 1000 training samples resulted in 71% accuracy whereas the same model with an further increase in training samples to 2000 spiked the accuracy to 81% i.e. 10% increase in the accuracy.

Model - 6 Strides Operation with Padding being "Same" with Increase in filters from 32 to 256 in 5 Input Layers with the data being used from the Augmented Images and a droput rate of 0.5 (Training Sample - 2000)

```
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation 1(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel_size=3, strides=2,
activation="relu", padding="same")(x)
x = layers.Conv2D(filters=64, kernel size=3, strides=2,
activation="relu", padding="same")(x)
x = layers.Conv2D(filters=128, kernel size=3, strides=2,
activation="relu", padding="same")(x)
x = layers.Conv2D(filters=256, kernel size=3, strides=2,
activation="relu", padding="same")(x)
x = layers.Conv2D(filters=256, kernel size=3, strides=2,
activation="relu", padding="same")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.summary()
Model: "model 5"
Layer (type)
                             Output Shape
                                                        Param #
 input_6 (InputLayer)
                             [(None, 180, 180, 3)]
                                                        0
 sequential 1 (Sequential) (None, 180, 180, 3)
                                                        0
 rescaling 5 (Rescaling)
                             (None, 180, 180, 3)
                                                        0
```

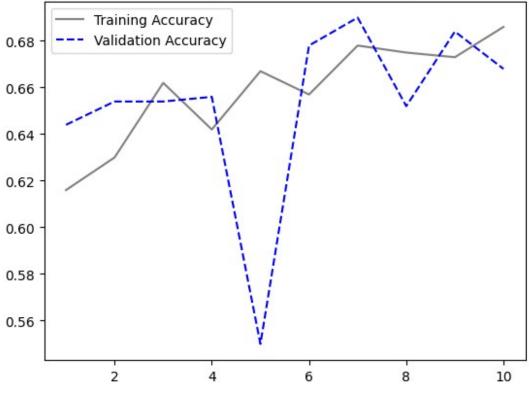
```
conv2d 26 (Conv2D)
                          (None, 90, 90, 32)
                                                 896
 conv2d 27 (Conv2D)
                          (None, 45, 45, 64)
                                                 18496
 conv2d 28 (Conv2D)
                          (None, 23, 23, 128)
                                                 73856
conv2d 29 (Conv2D)
                          (None, 12, 12, 256)
                                                 295168
conv2d 30 (Conv2D)
                          (None, 6, 6, 256)
                                                 590080
flatten_5 (Flatten)
                          (None, 9216)
                                                 0
dropout 4 (Dropout)
                          (None, 9216)
                                                 0
dense 5 (Dense)
                                                 9217
                          (None, 1)
Total params: 987713 (3.77 MB)
Trainable params: 987713 (3.77 MB)
Non-trainable params: 0 (0.00 Byte)
# Compiling the Model
model.compile(loss= "binary_crossentropy",
            optimizer= "adam",
            metrics= ['accuracy'])
# Monitoring the best validation loss using Callbacks
callbacks = ModelCheckpoint(
          filepath = "model6.keras",
          save best only= True,
          monitor= "val loss"
# Model Fit
Model 6 = model.fit(
        train dataset,
         epochs= 10,
         validation data= validation dataset,
         callbacks= callbacks
         )
Epoch 1/10
accuracy: 0.6160 - val loss: 0.6394 - val accuracy: 0.6440
Epoch 2/10
accuracy: 0.6300 - val loss: 0.6201 - val accuracy: 0.6540
```

```
Epoch 3/10
accuracy: 0.6620 - val loss: 0.6141 - val accuracy: 0.6540
Epoch 4/10
accuracy: 0.6420 - val loss: 0.6304 - val accuracy: 0.6560
Epoch 5/10
accuracy: 0.6670 - val loss: 0.7656 - val accuracy: 0.5500
Epoch 6/10
32/32 [============== ] - 135s 4s/step - loss: 0.6236 -
accuracy: 0.6570 - val loss: 0.5965 - val accuracy: 0.6780
Epoch 7/10
accuracy: 0.6780 - val loss: 0.6018 - val accuracy: 0.6900
Epoch 8/10
accuracy: 0.6750 - val loss: 0.6250 - val accuracy: 0.6520
Epoch 9/10
accuracy: 0.6730 - val loss: 0.5852 - val accuracy: 0.6840
Epoch 10/10
32/32 [============= ] - 131s 4s/step - loss: 0.6055 -
accuracy: 0.6860 - val loss: 0.6071 - val accuracy: 0.6680
```

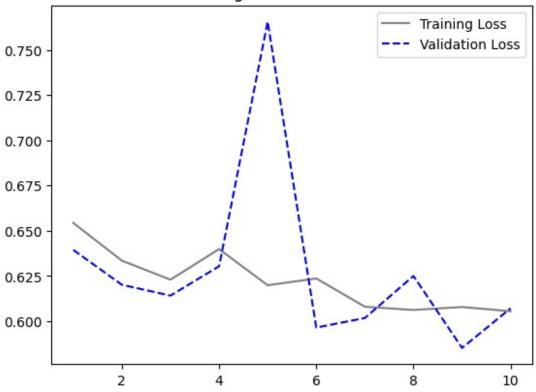
Visualizing the Training and Validation Accuracy/Loss

```
accuracy = Model 6.history["accuracy"]
val accuracy = Model 6.history["val accuracy"]
loss = Model 6.history["loss"]
val loss = Model 6.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
plt.plot(epochs, val accuracy, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```







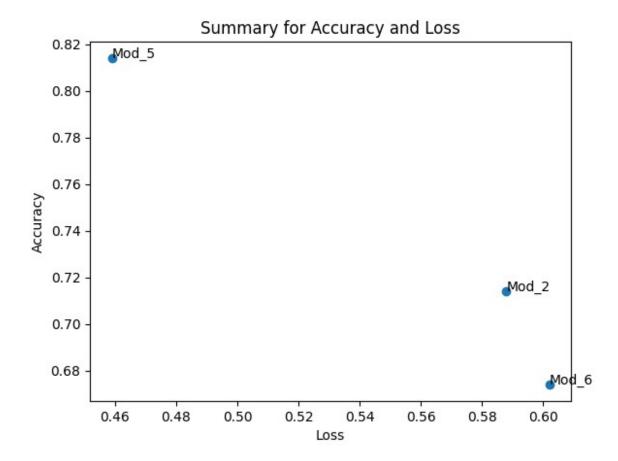


Summay of Question 2: Using 2000 as the training sample, we did attempt to create two more models. Let's now examine the three models' accuracy and loss to see which produces the best results.

Model 2: droput rate of 0.5, five input layers, augmented images, filters ranging from 32 to 256, and training size of 1000

Model 5: augmented images with a dropout rate of 0.5, five input layers, filters ranging from 32 to 256, and 2000 training samples

```
Model 1 = (0.647, 0.604)
Model 2 = (0.659, 0.600)
Model 3 = (0.653, 0.636)
Model 4 = (0.685, 0.562)
Model 5 = (0.676, 0.614)
Model 6 = (0.636, 0.668)
Models 2 = ("Mod 2", "Mod 5", "Mod 6")
Loss 2 = (Model 2[0], Model 5[0], Model 6[0])
Accuracy 2 = (Model 2[1], Model 5[1], Model 6[1])
fig, ax = plt.subplots()
ax.scatter(Loss 2,Accuracy 2)
for i, txt in enumerate(Models 2):
    ax.annotate(txt, (Loss 2[i], Accuracy 2[i] ))
plt.title("Summary for Accuracy and Loss")
plt.vlabel("Accuracy")
plt.xlabel("Loss")
plt.show()
```



When the models' performances were compared, it was found that the model did not gain much from using strides with padding. With the addition of a Max Pooling Layer, Model 5 outperformed the Strides model in accuracy by 14%. Moreover, an improved accuracy of 81% was attained by fine-tuning the network and expanding the training dataset from 1000 to 2000 samples.

We plotted Models 5 and 6 to answer the second question and provide a visual comparison of their performance. The graphs clearly show that Model 5 had the lowest loss of 45.9% and the highest accuracy of all the models, reaching 81%. The model performed significantly better once the training samples were increased to 2000 and various augmented photos were added.

1. Now change your training sample so that you achieve better performance than those from Steps 1 and 2. This sample size may be larger, or smaller than those in the previous steps. The objective is to find the ideal training sample size to get best prediction results

As we saw in above graph that with the increase in training sample size the Accuracy is also increasing hence will increase the sample size to 3000 and 5000 for better performance

Training Sample 3000

```
import os, shutil, pathlib
original_dir = pathlib.Path("train")
new_base_dir = pathlib.Path("cats_vs_dogs_1")
```

```
def make subset(subset name, start index, end index):
    for category in ("cat", "dog"):
        dir = new base dir / subset name / category
        os.makedirs(dir)
        fnames = [f"{category}.{i}.jpg" for i in range(start_index,
end index)]
        for fname in fnames:
            shutil.copyfile(src=original dir / fname,
                            dst=dir / fname)
make_subset("train", start_index=0, end_index=1500)
make_subset("validation", start_index=1000, end_index=1250)
make subset("test", start index=1500, end index=1750)
train dataset = image dataset from directory(
    new base dir / "train",
    image size=(180, 180),
    batch size=32)
validation dataset = image dataset from directory(
    new base dir / "validation",
    image size=(180, 180),
    batch size=32)
test dataset = image dataset from directory(
    new base dir / "test",
    image size=(180, 180),
    batch size=32)
Found 3000 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
for data batch, labels batch in train dataset:
    print("data batch shape:", data_batch.shape)
    print("labels batch shape:", labels batch.shape)
    break
data batch shape: (32, 180, 180, 3)
labels batch shape: (32,)
```

Using few of the techniques such as random flip, random zoom, random rotation so as to create augmented versions of the image

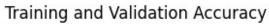
Model - 7 MaxPooling Operation with Increase in filters from 32 to 256 in 5 Input Layers with the

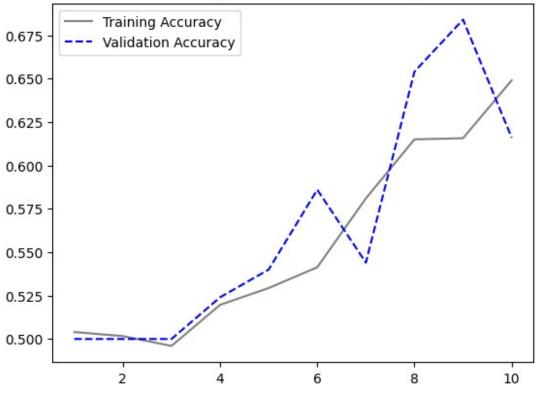
```
data being used from the Augmented Images and a droput rate of 0.5 (Training Sample - 3000)
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation_2(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.summary()
Model: "model 1"
```

Layer (type)	Output Shape	Param #
input_2 (InputLayer)	[(None, 180, 180, 3)]	0
<pre>sequential_1 (Sequential)</pre>	(None, 180, 180, 3)	0
<pre>rescaling_1 (Rescaling)</pre>	(None, 180, 180, 3)	0
conv2d_5 (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d_4 (MaxPoolin g2D)</pre>	(None, 89, 89, 32)	0
conv2d_6 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_5 (MaxPoolin g2D)</pre>	(None, 43, 43, 64)	0
conv2d_7 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_6 (MaxPoolin g2D)</pre>	(None, 20, 20, 128)	0
conv2d_8 (Conv2D)	(None, 18, 18, 256)	295168

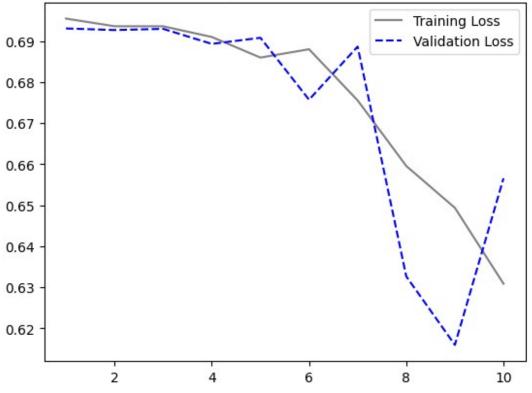
```
max pooling2d 7 (MaxPoolin (None, 9, 9, 256)
                                           0
g2D)
conv2d 9 (Conv2D)
                       (None, 7, 7, 256)
                                           590080
flatten 1 (Flatten)
                       (None, 12544)
                                           0
dropout 1 (Dropout)
                       (None, 12544)
                                           0
dense 1 (Dense)
                       (None, 1)
                                           12545
Total params: 991041 (3.78 MB)
Trainable params: 991041 (3.78 MB)
Non-trainable params: 0 (0.00 Byte)
# Compiling the Model
model.compile(loss= "binary_crossentropy",
          optimizer= "adam",
          metrics= ['accuracy'])
# Monitoring the best validation loss using Callbacks
callbacks = ModelCheckpoint(
         filepath = "model7.keras",
         save_best_only= True,
         monitor= "val loss"
# Model Fit
Model 7 = model.fit(
       train dataset,
       epochs= 10,
       validation data= validation dataset,
        callbacks= callbacks
Epoch 1/10
accuracy: 0.5040 - val loss: 0.6931 - val accuracy: 0.5000
Epoch 2/10
accuracy: 0.5017 - val loss: 0.6927 - val accuracy: 0.5000
Epoch 3/10
accuracy: 0.4960 - val loss: 0.6930 - val accuracy: 0.5000
Epoch 4/10
accuracy: 0.5197 - val loss: 0.6893 - val accuracy: 0.5240
```

```
Epoch 5/10
accuracy: 0.5293 - val loss: 0.6908 - val accuracy: 0.5400
Epoch 6/10
94/94 [============== ] - 314s 3s/step - loss: 0.6880 -
accuracy: 0.5413 - val loss: 0.6757 - val accuracy: 0.5860
Epoch 7/10
accuracy: 0.5810 - val loss: 0.6887 - val accuracy: 0.5440
Epoch 8/10
accuracy: 0.6150 - val loss: 0.6327 - val accuracy: 0.6540
Epoch 9/10
accuracy: 0.6157 - val loss: 0.6160 - val accuracy: 0.6840
Epoch 10/10
accuracy: 0.6490 - val loss: 0.6566 - val accuracy: 0.6160
accuracy = Model 7.history["accuracy"]
val accuracy = Model 7.history["val accuracy"]
loss = Model 7.history["loss"]
val loss = Model 7.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
plt.plot(epochs, val accuracy, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```





# Training and Validation Loss



In the previous Model 6, we attempted to replace the conventional max pooling operation with strides, but the results were not as promising as expected. and in model 7 we used Maxpooling only. Therefore, we are exploring a hybrid approach that combines both max pooling and strides to evaluate the performance of this new model.

Max pooling is a downsampling operation that reduces the spatial dimensions of the feature map, aiming to capture the most prominent features while discarding less relevant information. On the other hand, strides determine the step rate of the sliding window used to extract and learn the features from the data. This hybrid approach aims to leverage the advantages of both techniques, potentially enhancing the model's ability to capture intricate patterns and features while maintaining computational efficiency.

Model - 8 MaxPooling + Strides of Step-Size 2 Operation with Increase in filters from 32 to 256 in 5 Input Layers with the data being used from the Augmented Images and a droput rate of 0.5 (Training Sample - 3000)

```
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation 2(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2, strides=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2, strides=2)(x)
x = layers.Conv2D(filters=128, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2,strides=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.summary()
Model: "model"
Layer (type)
                           Output Shape
                                                   Param #
_____
```

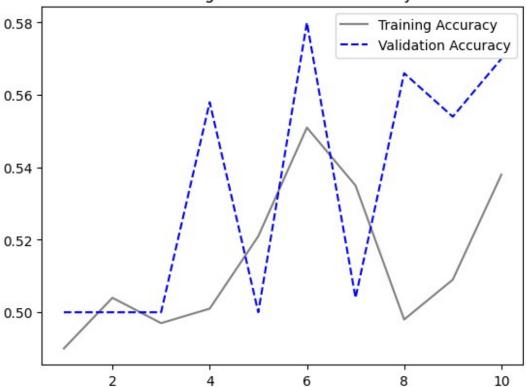
```
input 2 (InputLayer)
                              [(None, 180, 180, 3)]
                                                         0
 sequential (Sequential)
                              (None, 180, 180, 3)
                                                         0
 rescaling (Rescaling)
                              (None, 180, 180, 3)
                                                         0
 conv2d (Conv2D)
                                                         896
                              (None, 178, 178, 32)
max pooling2d (MaxPooling2
                              (None, 89, 89, 32)
                                                         0
D)
 conv2d 1 (Conv2D)
                              (None, 87, 87, 64)
                                                         18496
max pooling2d 1 (MaxPoolin
                              (None, 43, 43, 64)
                                                         0
g2D)
 conv2d 2 (Conv2D)
                              (None, 41, 41, 128)
                                                         73856
max pooling2d 2 (MaxPoolin
                              (None, 20, 20, 128)
                                                         0
q2D)
 conv2d 3 (Conv2D)
                              (None, 18, 18, 256)
                                                         295168
max pooling2d 3 (MaxPoolin
                              (None, 9, 9, 256)
                                                         0
 g2D)
 conv2d 4 (Conv2D)
                              (None, 7, 7, 256)
                                                         590080
 flatten (Flatten)
                              (None, 12544)
                                                         0
                              (None, 12544)
 dropout (Dropout)
 dense (Dense)
                              (None, 1)
                                                         12545
Total params: 991041 (3.78 MB)
Trainable params: 991041 (3.78 MB)
Non-trainable params: 0 (0.00 Byte)
# Compiling the Model
model.compile(loss= "binary crossentropy",
              optimizer= "adam",
              metrics= ['accuracy'])
# Monitoring the best validation loss using Callbacks
callbacks = ModelCheckpoint(
            filepath = "model8.keras",
            save best only= True,
```

```
monitor= "val loss"
# Model Fit
Model_8 = model.fit(
      train dataset,
      epochs= 10,
      validation data= validation dataset,
      callbacks= callbacks
      )
Epoch 1/10
accuracy: 0.4900 - val loss: 0.6916 - val accuracy: 0.5000
Epoch 2/10
accuracy: 0.5040 - val_loss: 0.6938 - val_accuracy: 0.5000
Epoch 3/10
accuracy: 0.4970 - val loss: 0.6931 - val accuracy: 0.5000
Epoch 4/10
accuracy: 0.5010 - val loss: 0.6925 - val accuracy: 0.5580
Epoch 5/10
accuracy: 0.5210 - val_loss: 0.6929 - val_accuracy: 0.5000
Epoch 6/10
32/32 [============= ] - 118s 4s/step - loss: 0.6911 -
accuracy: 0.5510 - val loss: 0.6772 - val accuracy: 0.5800
Epoch 7/10
accuracy: 0.5350 - val loss: 0.6859 - val accuracy: 0.5040
Epoch 8/10
accuracy: 0.4980 - val loss: 0.6915 - val accuracy: 0.5660
Epoch 9/10
accuracy: 0.5090 - val loss: 0.6877 - val accuracy: 0.5540
Epoch 10/10
32/32 [============== ] - 117s 4s/step - loss: 0.6873 -
accuracy: 0.5380 - val loss: 0.6739 - val accuracy: 0.5700
accuracy = Model 8.history["accuracy"]
val accuracy = Model 8.history["val accuracy"]
loss = Model 8.historv["loss"]
val loss = Model 8.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
```

```
plt.plot(epochs, val_accuracy, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()

plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val_loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```

# Training and Validation Accuracy



Training and Validation Loss

0.695

0.690

0.685

0.680

0.675

Training Loss

2

Validation Loss

4

6

8

10

Model - 9 MaxPooling + Strides of Step-Size 2 with Padding turned on Operation with Increase in filters from 32 to 512 in 5 Input Layers with the data being used from the Augmented Images and a droput rate of 0.5 (Training Sample - 3000)

```
inputs = keras.Input(shape=(180, 180, 3))
x = data_augmentation_2(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2, strides=2, padding="same")(x)
x = layers.Conv2D(filters=64, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2, strides=2, padding="same")(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2, strides=2, padding="same")(x)
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
```

```
x = layers.MaxPooling2D(pool_size=2, strides=2, padding="same")(x)
x = layers.Conv2D(filters=512, kernel_size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.summary()
```

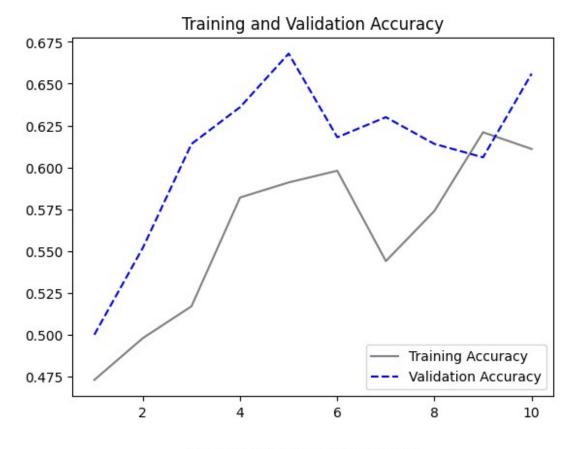
Model: "model\_1"

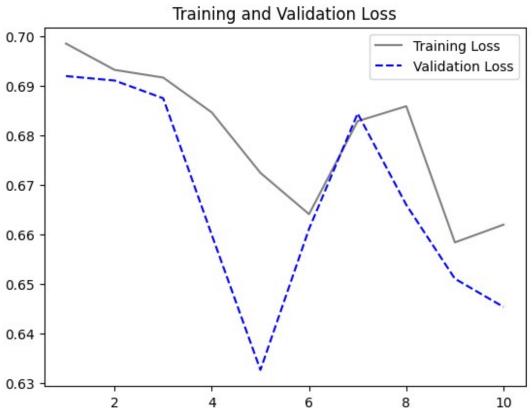
Layer (type)	Output Shape	Param #
input_3 (InputLayer)	[(None, 180, 180, 3)]	0
sequential (Sequential)	(None, 180, 180, 3)	0
rescaling_1 (Rescaling)	(None, 180, 180, 3)	0
conv2d_5 (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d_4 (MaxPoolin g2D)</pre>	(None, 89, 89, 32)	0
conv2d_6 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_5 (MaxPoolin g2D)</pre>	(None, 44, 44, 64)	0
conv2d_7 (Conv2D)	(None, 42, 42, 128)	73856
<pre>max_pooling2d_6 (MaxPoolin g2D)</pre>	(None, 21, 21, 128)	0
conv2d_8 (Conv2D)	(None, 19, 19, 256)	295168
<pre>max_pooling2d_7 (MaxPoolin g2D)</pre>	(None, 10, 10, 256)	0
conv2d_9 (Conv2D)	(None, 8, 8, 512)	1180160
flatten_1 (Flatten)	(None, 32768)	0
dropout_1 (Dropout)	(None, 32768)	0
dense_1 (Dense)	(None, 1)	32769

Total params: 1601345 (6.11 MB)

```
Trainable params: 1601345 (6.11 MB)
Non-trainable params: 0 (0.00 Byte)
# Compiling the Model
model.compile(loss= "binary_crossentropy",
         optimizer= "adam",
         metrics= ['accuracy'])
# Monitoring the best validation loss using Callbacks
callbacks = ModelCheckpoint(
       filepath = "model9.keras",
       save best only= True,
       monitor= "val_loss"
# Model Fit
Model 9 = model.fit(
      train dataset,
      epochs= 10,
      validation data= validation dataset,
      callbacks callbacks
Epoch 1/10
accuracy: 0.4730 - val loss: 0.6920 - val accuracy: 0.5000
Epoch 2/10
accuracy: 0.4980 - val loss: 0.6911 - val accuracy: 0.5520
Epoch 3/10
accuracy: 0.5170 - val loss: 0.6875 - val accuracy: 0.6140
Epoch 4/10
accuracy: 0.5820 - val loss: 0.6599 - val accuracy: 0.6360
Epoch 5/10
accuracy: 0.5910 - val loss: 0.6327 - val accuracy: 0.6680
Epoch 6/10
accuracy: 0.5980 - val loss: 0.6611 - val accuracy: 0.6180
Epoch 7/10
accuracy: 0.5440 - val loss: 0.6844 - val accuracy: 0.6300
Epoch 8/10
accuracy: 0.5740 - val loss: 0.6660 - val accuracy: 0.6140
Epoch 9/10
```

```
accuracy: 0.6210 - val loss: 0.6511 - val accuracy: 0.6060
Epoch 10/10
accuracy: 0.6110 - val loss: 0.6454 - val accuracy: 0.6560
accuracy = Model_9.history["accuracy"]
val accuracy = Model 9.history["val accuracy"]
loss = Model 9.history["loss"]
val loss = Model 9.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
plt.plot(epochs, val accuracy, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val_loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```





Now let's examine which model performs best with a training sample of 3000. Note: In this instance, training was done differently for models 8 and 9, using strides with maxpooling and strides with padding enabled.

Model 6: Trides Operation with "Same" Padding, 32–512 filtering, 5 input layers, 0.5 dropout rate, and 3000 training samples

Model 7: MaxPooling Operation; 5 Input Layers; 32 to 512 Filters; 0.5 Dropout Rate; 3000 Training Samples

Model 8: MaxPooling + Step-Size 2 Strides, 5 Input Layers, 32 to 512 Filters, 0.5 Drop-Rate, 3000 Training Sample

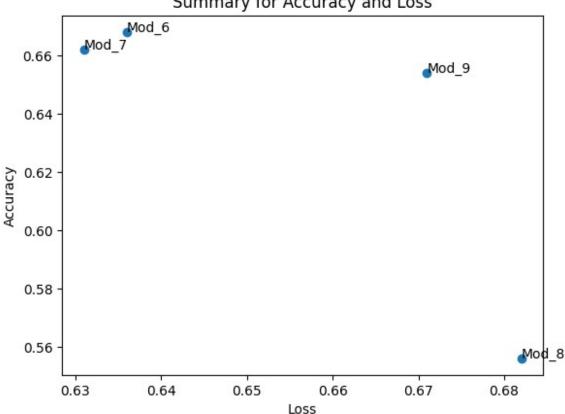
Model 9: maxpooling + Step-Size 2 Strides with Padding Enabled, 5 Input Layers, 32-to 512 Filters, and a dropout rate of Now let's examine which model performs best with a training sample of 3000. Note: In this instance, training was done differently for models 8 and 9, using strides with maxpooling and strides with padding enabled.

```
Model_7 = (0.631,0.662)
Model_8 = (0.682,0.556)
Model_9 = (0.671,0.654)

Models_3 = ("Mod_6","Mod_7","Mod_8","Mod_9")
Loss_3 = (Model_6[0],Model_7[0],Model_8[0],Model_9[0])
Accuracy_3 = (Model_6[1],Model_7[1],Model_8[1],Model_9[1])

fig, ax = plt.subplots()
ax.scatter(Loss_3,Accuracy_3)
for i, txt in enumerate(Models_3):
    ax.annotate(txt, (Loss_3[i],Accuracy_3[i]))
plt.title("Summary for Accuracy and Loss")
plt.ylabel("Accuracy")
plt.xlabel("Loss")
```





Here we can clearly see that the model which was built with 5 layers using maxpooling along with strides and padding on was giving the highest accuracy i.e. 65 % with least loss amoung the other 2 models i.e. 40%.

Now, we are increasing the training sample to 5000 and building a model from scratch to check it's performance on the unseen data.

Training Sample - 5000

```
import os, shutil, pathlib
original dir = pathlib.Path("train")
new base dir = pathlib.Path("cats vs dogs 2")
def make_subset(subset_name, start_index, end_index):
    for category in ("cat", "dog"):
        dir = new base dir / subset name / category
        os.makedirs(dir)
        fnames = [f"{category}.{i}.jpg" for i in range(start_index,
end index)]
        for fname in fnames:
            shutil.copyfile(src=original_dir / fname,
                            dst=dir / fname)
```

```
make subset("train", start index=0, end index=2500)
make subset("validation", start index=1000, end index=1250)
make subset("test", start index=1500, end index=1750)
train dataset = image dataset from directory(
    new base dir / "train",
    image size=(180, 180),
    batch size=32)
validation dataset = image dataset from directory(
    new_base_dir / "validation",
    image size=(180, 180),
    batch size=32)
test dataset = image dataset from directory(
    new base dir / "test",
    image size=(180, 180),
    batch size=32)
Found 5000 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
for data batch, labels batch in train dataset:
    print("data batch shape:", data batch.shape)
    print("labels batch shape:", labels batch.shape)
    break
data batch shape: (32, 180, 180, 3)
labels batch shape: (32,)
data augmentation 3 = keras.Sequential(
        layers.RandomFlip("horizontal"),
        layers.RandomRotation(0.15),
        layers.RandomZoom(0.25)
    ]
)
```

Model - 10 MaxPooling Operation with Increase in filters from 32 to 256 in 5 Input Layers with the data being used from the Augmented Images and a droput rate of 0.5 (Training Sample - 5000)

```
inputs = keras.Input(shape=(180, 180, 3))
x = data_augmentation_3(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=64, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
```

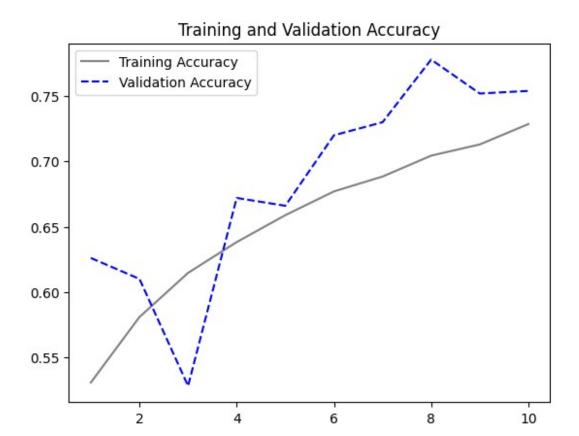
```
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel_size=3, activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
model.summary()
```

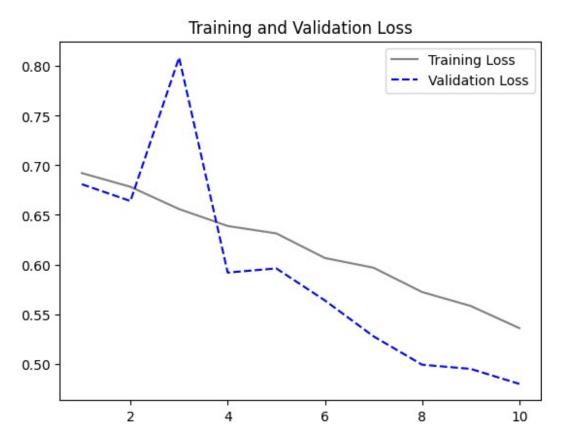
Model: "model"

Layer (type)	Output Shape	Param #
input_1 (InputLayer)	[(None, 180, 180, 3)]	0
<pre>sequential_3 (Sequential)</pre>	(None, 180, 180, 3)	0
rescaling (Rescaling)	(None, 180, 180, 3)	0
conv2d (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, 89, 89, 32)	0
conv2d_1 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_1 (MaxPoolin g2D)</pre>	(None, 43, 43, 64)	0
conv2d_2 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, 20, 20, 128)	0
conv2d_3 (Conv2D)	(None, 18, 18, 256)	295168
<pre>max_pooling2d_3 (MaxPoolin g2D)</pre>	(None, 9, 9, 256)	0
conv2d_4 (Conv2D)	(None, 7, 7, 256)	590080
flatten (Flatten)	(None, 12544)	0
dropout (Dropout)	(None, 12544)	0
dense (Dense)	(None, 1)	12545

```
Total params: 991041 (3.78 MB)
Trainable params: 991041 (3.78 MB)
Non-trainable params: 0 (0.00 Byte)
# Compiling the Model
model.compile(loss= "binary_crossentropy",
         optimizer= "adam",
         metrics= ['accuracy'])
# Monitoring the best validation loss using Callbacks
callbacks = ModelCheckpoint(
       filepath = "model10.keras",
       save best only= True,
       monitor= "val loss"
# Model Fit
Model 10 = model.fit(
      train dataset,
      epochs= 10,
      validation data= validation dataset,
      callbacks = callbacks
Epoch 1/10
- accuracy: 0.5306 - val loss: 0.6810 - val accuracy: 0.6260
Epoch 2/10
- accuracy: 0.5808 - val loss: 0.6641 - val accuracy: 0.6100
Epoch 3/10
- accuracy: 0.6146 - val loss: 0.8086 - val accuracy: 0.5280
Epoch 4/10
- accuracy: 0.6382 - val loss: 0.5919 - val accuracy: 0.6720
Epoch 5/10
- accuracy: 0.6588 - val loss: 0.5961 - val accuracy: 0.6660
Epoch 6/10
- accuracy: 0.6770 - val loss: 0.5638 - val accuracy: 0.7200
Epoch 7/10
- accuracy: 0.6884 - val loss: 0.5276 - val accuracy: 0.7300
Epoch 8/10
- accuracy: 0.7044 - val loss: 0.4990 - val accuracy: 0.7780
```

```
Epoch 9/10
- accuracy: 0.7130 - val loss: 0.4948 - val accuracy: 0.7520
Epoch 10/10
- accuracy: 0.7286 - val loss: 0.4797 - val accuracy: 0.7540
accuracy = Model 10.history["accuracy"]
val accuracy = Model 10.history["val accuracy"]
loss = Model 10.history["loss"]
val loss = Model 10.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, color="grey", label="Training Accuracy")
plt.plot(epochs, val accuracy, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
```





Three of the four models we built were trained on a sample size of three thousand. The best-performing model has an accuracy of 55.4%. Interestingly, the accuracy increased to 74.4% when we increased the training sample to 5000. Thus, we conclude that a training sample size of 5000 significantly improves the model's performance. As for the likely cause of the validation loss being less than the training loss, the split approach that was used is probably a factor. Here, the validation and test sets are fixed at 500 apiece, but the training sample is almost five thousand times larger. Furthermore, it is crucial to recognize that regularizations, like dropout or L1 and L2 regularizers, are important during training and contribute to the training computation.

1. Repeat Steps 1-3, but now using a pretrained network. The sample sizes you use in Steps 2 and 3 for the pretrained network may be the same or different from those using the network where you trained from scratch. Again, use any and all optimization techniques to get best performance

Leveraging a Pre-Trained Model - VGG16

```
conv base = keras.applications.vgg16.VGG16(
   weights="imagenet",
   include_top=False,
   input shape=(180, 180, 3)
Downloading data from https://storage.googleapis.com/tensorflow/keras-
applications/vgg16/vgg16 weights tf dim ordering tf kernels notop.h5
conv base.summary()
Model: "vgg16"
Layer (type)
                          Output Shape
                                                  Param #
input 1 (InputLayer)
                          [(None, 180, 180, 3)]
                                                  0
block1 conv1 (Conv2D)
                          (None, 180, 180, 64)
                                                  1792
 block1 conv2 (Conv2D)
                          (None, 180, 180, 64)
                                                  36928
                          (None, 90, 90, 64)
 block1 pool (MaxPooling2D)
                                                  0
```

```
block2 conv1 (Conv2D)
                              (None, 90, 90, 128)
                                                        73856
 block2 conv2 (Conv2D)
                              (None, 90, 90, 128)
                                                        147584
 block2 pool (MaxPooling2D)
                              (None, 45, 45, 128)
 block3 conv1 (Conv2D)
                              (None, 45, 45, 256)
                                                        295168
                              (None, 45, 45, 256)
 block3 conv2 (Conv2D)
                                                        590080
 block3_conv3 (Conv2D)
                              (None, 45, 45, 256)
                                                        590080
                              (None, 22, 22, 256)
 block3 pool (MaxPooling2D)
 block4_conv1 (Conv2D)
                              (None, 22, 22, 512)
                                                        1180160
 block4 conv2 (Conv2D)
                              (None, 22, 22, 512)
                                                        2359808
                              (None, 22, 22, 512)
 block4 conv3 (Conv2D)
                                                        2359808
 block4 pool (MaxPooling2D)
                              (None, 11, 11, 512)
 block5 conv1 (Conv2D)
                              (None, 11, 11, 512)
                                                        2359808
                              (None, 11, 11, 512)
 block5 conv2 (Conv2D)
                                                        2359808
 block5_conv3 (Conv2D)
                              (None, 11, 11, 512)
                                                        2359808
 block5 pool (MaxPooling2D)
                              (None, 5, 5, 512)
Total params: 14714688 (56.13 MB)
Trainable params: 14714688 (56.13 MB)
Non-trainable params: 0 (0.00 Byte)
#extracting VGG 16 features and Labels
def get_features_and_labels(dataset):
    all features = []
    all labels = []
    for images, labels in dataset:
        preprocessed images =
keras.applications.vgg16.preprocess input(images)
        features = conv base.predict(preprocessed images)
        all features.append(features)
        all labels.append(labels)
    return np.concatenate(all features), np.concatenate(all labels)
train_features, train_labels = get features and labels(train dataset)
val features, val labels =
```

```
get features and labels(validation dataset)
test features, test labels = get features and labels(test dataset)
1/1 [======] - 14s 14s/step
1/1 [======] - 14s 14s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 14s 14s/step
1/1 [======] - 12s 12s/step
1/1 [======] - 12s 12s/step
1/1 [======= ] - 13s 13s/step
1/1 [======] - 13s 13s/step
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1/1 [======] - 13s 13s/step
1/1 [======] - 12s 12s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 10s 10s/step
1/1 [======] - 12s 12s/step
1/1 [======= ] - 13s 13s/step
1/1 [=======] - 9s 9s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 16s 16s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 14s 14s/step
1/1 [=======] - 14s 14s/step
1/1 [======] - 10s 10s/step
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```

```
1/1 [======] - 13s 13s/step
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1/1 [======] - 14s 14s/step
1/1 [======] - 10s 10s/step
1/1 [======= ] - 13s 13s/step
1/1 [======] - 14s 14s/step
1/1 [======] - 10s 10s/step
1/1 [=======] - 13s 13s/step
1/1 [======] - 12s 12s/step
```

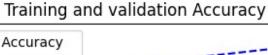
```
1/1 [======= ] - 14s 14s/step
1/1 [======] - 13s 13s/step
1/1 [======= ] - 14s 14s/step
1/1 [======] - 11s 11s/step
1/1 [======] - 14s 14s/step
1/1 [=======] - 10s 10s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 14s 14s/step
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1/1 [======] - 14s 14s/step
1/1 [======] - 10s 10s/step
1/1 [=======] - 13s 13s/step
1/1 [======] - 14s 14s/step
```

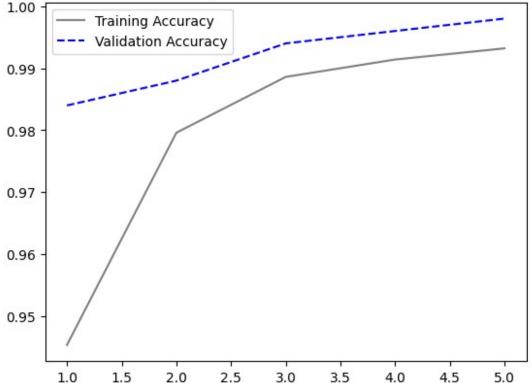
```
1/1 [======= ] - 13s 13s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 10s 10s/step
1/1 [======] - 15s 15s/step
1/1 [======] - 14s 14s/step
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1/1 [=======] - 10s 10s/step
1/1 [======] - 14s 14s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 10s 10s/step
1/1 [======= ] - 3s 3s/step
1/1 [======] - 11s 11s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 11s 11s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 15s 15s/step
1/1 [======] - 11s 11s/step
1/1 [======] - 14s 14s/step
1/1 [======] - 11s 11s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 14s 14s/step
1/1 [======] - 10s 10s/step
1/1 [======] - 12s 12s/step
1/1 [======] - 7s 7s/step
1/1 [======] - 14s 14s/step
1/1 [======] - 14s 14s/step
1/1 [======] - 14s 14s/step
1/1 [======] - 12s 12s/step
1/1 [======] - 10s 10s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 14s 14s/step
1/1 [======= ] - 10s 10s/step
1/1 [======] - 13s 13s/step
1/1 [======] - 12s 12s/step
1/1 [======] - 14s 14s/step
1/1 [=======] - 6s 6s/step
train features.shape
(5000, 5, 5, 512)
```

VGG - Model 1 Dense Layer with 256 Nodes and Droput Rate of 0.5 and optimizer being rmsprop with the Original Images

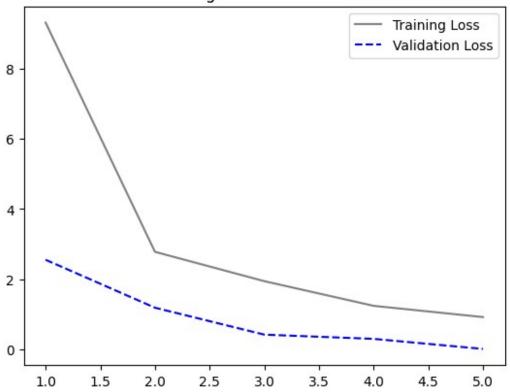
```
# Defining and Training the densely connected classifier
# The last dense stacked layer and the classifier
inputs = keras.Input(shape=(5, 5, 512))
x = layers.Flatten()(inputs)
x = layers.Dense(256)(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs, outputs)
# Compiling the Model
model.compile(loss="binary crossentropy",
          optimizer="rmsprop",
          metrics=["accuracy"])
# Using CallBacks to monitor the best val loss
callbacks = ModelCheckpoint(
         filepath="vgg model1.keras",
         save best only=True,
         monitor="val loss")
# Model Fit
VGG Model 1 = model.fit(
          train features, train labels,
          epochs= 5,
          validation_data= (val_features, val_labels),
          callbacks = callbacks)
Epoch 1/5
- accuracy: 0.9454 - val loss: 2.5510 - val accuracy: 0.9840
Epoch 2/5
- accuracy: 0.9796 - val loss: 1.1836 - val accuracy: 0.9880
Epoch 3/5
- accuracy: 0.9886 - val loss: 0.4150 - val accuracy: 0.9940
Epoch 4/5
- accuracy: 0.9914 - val loss: 0.2949 - val accuracy: 0.9960
Epoch 5/5
- accuracy: 0.9932 - val loss: 0.0078 - val accuracy: 0.9980
```

```
acc = VGG Model 1.history["accuracy"]
val acc = VGG Model 1.history["val accuracy"]
loss = VGG Model 1.history["loss"]
val loss = VGG Model 1.history["val loss"]
epochs = range(1, len(acc) + 1)
plt.plot(epochs, acc, color="grey", label="Training Accuracy")
plt.plot(epochs, val acc, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and validation Loss")
plt.legend()
plt.show()
```





## Training and validation Loss



#### VGG - Model 2 (1000 Training Samples)

We have configured the pre-trained model to retain its existing weights during training, only allowing the densely connected networks and the classifier to adjust their weights during the training process.

This approach helps prevent overfitting as the pre-trained model remains unchanged, providing a stable foundation for the model. Moreover, when dealing with limited training data and constrained computational resources, freezing the pre-trained model training can be particularly advantageous.

To illustrate the impact of this configuration, we can print the list of trainable weights both before and after freezing the pre-trained model.

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	<del></del>	$\overline{}$

```
block4 conv3 (Conv2D)
                             (None, 22, 22, 512)
                                                        2359808
 block4 pool (MaxPooling2D)
                            (None, 11, 11, 512)
 block5 conv1 (Conv2D)
                             (None, 11, 11, 512)
                                                        2359808
 block5 conv2 (Conv2D)
                             (None, 11, 11, 512)
                                                        2359808
 block5 conv3 (Conv2D)
                             (None, 11, 11, 512)
                                                        2359808
 block5 pool (MaxPooling2D)
                            (None, 5, 5, 512)
Total params: 14714688 (56.13 MB)
Trainable params: 0 (0.00 Byte)
Non-trainable params: 14714688 (56.13 MB)
```

VGG - Model 2 Dense Layer with 256 Nodes and Droput Rate of 0.5 and optimizer being rmsprop with the Augmented Images

```
# Data Augmentation -Adding a data augmentation stage to provide
augmented training samples and a classifier to the convolutional base
data augmentation = keras.Sequential(
        layers.RandomFlip("horizontal"),
        layers.RandomRotation(0.1),
        layers.RandomZoom(0.2),
    ]
)
# Adding the Classifier and Dense Network
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation(inputs)
x = keras.applications.vgg16.preprocess input(x)
x = conv base(x)
x = layers.Flatten()(x)
x = layers.Dense(256)(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs, outputs)
# Compiling the Model
model.compile(loss="binary_crossentropy",
              optimizer="rmsprop",
              metrics=["accuracy"])
# Using CallBacks to monitor the best val loss
```

```
callbacks = ModelCheckpoint(
           filepath= "vgg model2.keras",
           save best only= True,
           monitor= "val loss")
# Model Fit
VGG Model 2 = model.fit(
             train dataset,
             epochs= 1,
             validation data=validation dataset,
             callbacks=callbacks)
accuracy: 0.9194
                                        Traceback (most recent call
TypeError
last)
<ipython-input-25-8b7794c6da1b> in <cell line: 13>()
    12 # Model Fit
---> 13 VGG Model 2 = model.fit(
     14
                     train dataset,
     15
                     epochs= 1,
/usr/local/lib/python3.10/dist-packages/keras/src/utils/traceback util
s.py in error handler(*args, **kwargs)
    68
                   # To get the full stack trace, call:
    69
                   # `tf.debugging.disable traceback filtering()`
                   raise e.with traceback(filtered tb) from None
---> 70
    71
               finally:
    72
                   del filtered tb
/usr/local/lib/python3.10/dist-packages/keras/src/saving/serialization
_lib.py in _get_class_or_fn config(obj)
               return object registration.get registered name(obj)
   393
   394
           else:
--> 395
               raise TypeError(
   396
                   f"Cannot serialize object {obj} of type
{type(obj)}. "
                   "To be serializable, "
   397
TypeError: Cannot serialize object Ellipsis of type <class
'ellipsis'>. To be serializable, a class must implement the
`get config()` method.
acc = VGG Model 2.history["accuracy"]
val acc = VGG Model 2.history["val accuracy"]
```

```
loss = VGG Model 2.history["loss"]
val loss = VGG Model 2.history["val loss"]
epochs = range(1, len(acc) + 1)
plt.plot(epochs, acc, color="grey", label="Training Accuracy")
plt.plot(epochs, val acc, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and validation Loss")
plt.legend()
plt.show()
best model = keras.models.load model("vgg model2.keras")
VGG_Model_2_Results= best_model.evaluate(test_dataset)
print(f'Loss: {VGG Model 2 Results[0]:.3f}')
print(f'Accuracy: {VGG Model 2 Results[1]:.3f}')
```

#### Fine Tuning the VGG\_Model\_2

```
conv_base.trainable = True
for layer in conv_base.layers[:-4]:
    layer.trainable = False

conv_base.summary()

Model: "vgg16"
```

Layer (type)	Output Shape	Param #
input_2 (InputLayer)	[(None, 180, 180, 3)]	0
block1_conv1 (Conv2D)	(None, 180, 180, 64)	1792
block1_conv2 (Conv2D)	(None, 180, 180, 64)	36928
<pre>block1_pool (MaxPooling2D)</pre>	(None, 90, 90, 64)	0
block2_conv1 (Conv2D)	(None, 90, 90, 128)	73856
block2_conv2 (Conv2D)	(None, 90, 90, 128)	147584
<pre>block2_pool (MaxPooling2D)</pre>	(None, 45, 45, 128)	0
block3_conv1 (Conv2D)	(None, 45, 45, 256)	295168

```
block3 conv2 (Conv2D)
                              (None, 45, 45, 256)
                                                        590080
 block3 conv3 (Conv2D)
                              (None, 45, 45, 256)
                                                        590080
 block3 pool (MaxPooling2D)
                             (None, 22, 22, 256)
 block4 conv1 (Conv2D)
                              (None, 22, 22, 512)
                                                        1180160
 block4 conv2 (Conv2D)
                              (None, 22, 22, 512)
                                                        2359808
 block4_conv3 (Conv2D)
                              (None, 22, 22, 512)
                                                        2359808
                              (None, 11, 11, 512)
 block4 pool (MaxPooling2D)
                                                        0
 block5 conv1 (Conv2D)
                              (None, 11, 11, 512)
                                                        2359808
 block5 conv2 (Conv2D)
                              (None, 11, 11, 512)
                                                        2359808
 block5 conv3 (Conv2D)
                              (None, 11, 11, 512)
                                                        2359808
 block5 pool (MaxPooling2D) (None, 5, 5, 512)
Total params: 14714688 (56.13 MB)
Trainable params: 7079424 (27.01 MB)
Non-trainable params: 7635264 (29.13 MB)
train dataset = image dataset from directory(
    new base dir / "train",
    image size=(180, 180),
    batch size=32)
validation dataset = image dataset from directory(
    new_base_dir / "validation",
    image size=(180, 180),
    batch size=32)
test_dataset = image_dataset_from_directory(
    new_base dir / "test",
    image size=(180, 180),
    batch size=32)
Found 5000 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
Found 500 files belonging to 2 classes.
# Data Augmentation
data augmentation 4 = keras.Sequential(
        layers.RandomFlip("horizontal"),
```

```
layers.RandomRotation(0.15),
       layers.RandomZoom(0.25),
   ]
)
# Adding the Classifier and Dense Network
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation 4(inputs)
x = keras.applications.vgg16.preprocess input(x)
x = conv base(x)
x = layers.Flatten()(x)
x = layers.Dense(256)(x)
x = layers.Dropout(0.5)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs, outputs)
# Compiling the Model
model.compile(loss="binary crossentropy",
             optimizer="adam",
             metrics=["accuracy"])
# Using CallBacks to monitor the best val loss
callbacks = ModelCheckpoint(
           filepath= "vgg_model3.keras",
           save best only= True,
           monitor= "val_loss")
# Model Fit
VGG Model 3 = model.fit(
             train dataset,
             epochs= 1,
             validation data=validation dataset,
             callbacks=callbacks)
Epoch 1/5
accuracy: 0.4998
TypeError
                                        Traceback (most recent call
last)
<ipython-input-51-cb290e0aa497> in <cell line: 35>()
    33
    34 # Model Fit
---> 35 VGG Model 3 = model.fit(
    36
                     train dataset,
    37
                     epochs= 5,
```

```
/usr/local/lib/python3.10/dist-packages/keras/src/utils/traceback util
s.py in error handler(*args, **kwargs)
                    # To get the full stack trace, call:
     69
                    # `tf.debugging.disable traceback filtering()`
---> 70
                    raise e.with traceback(filtered tb) from None
     71
                finally:
                    del filtered tb
     72
/usr/local/lib/python3.10/dist-packages/keras/src/saving/serialization
_lib.py in _get class or fn config(obj)
    393
                return object registration.get registered name(obj)
    394
            else:
--> 395
                raise TypeError(
                    f"Cannot serialize object {obj} of type
    396
{type(obj)}. "
                    "To be serializable, "
    397
TypeError: Cannot serialize object Ellipsis of type <class
'ellipsis'>. To be serializable, a class must implement the
`get config()` method.
acc = VGG_Model_3.history["accuracy"]
val acc = VGG Model 3.history["val accuracy"]
loss = VGG Model 3.history["loss"]
val loss = VGG Model 3.history["val loss"]
epochs = range(1, len(acc) + 1)
plt.plot(epochs, acc, color="grey", label="Training Accuracy")
plt.plot(epochs, val acc, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and Validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.show()
best model = keras.models.load model("vgg model3.keras")
VGG Model 3 Results = best model.evaluate(test dataset)
print(f"Loss: {VGG Model 3 Results[0]:.3f}")
print(f"Accuracy: {VGG_Model_3_Results[1]:.3f}")
```

In our efforts to optimize VGG\_Model3, we have chosen to freeze the initial four layers. This strategy aims to prevent the model from overfitting and allows it to concentrate solely on learning the distinctive features relevant to our particular classification task. Consequently, we have configured the pre-trained layers to remain unaltered during training, while simultaneously ensuring that the first four layers remain frozen. These optimizations are instrumental in enhancing the model's performance when dealing with a training sample size of 5000.

```
conv base.trainable = True
for layer in conv_base.layers[:-4]:
   layer.trainable = False
model.compile(loss="binary crossentropy",
             optimizer=keras.optimizers.Adam(learning rate=1e-5),
             metrics=["accuracy"])
callbacks = ModelCheckpoint(
           filepath="fine tuning vgg model3.keras",
           save best only=True,
           monitor="val loss")
FineTuned VGG Model 3 = model.fit(
                      train_dataset,
                      epochs= 1,
                      validation data=validation dataset,
                      callbacks=callbacks)
accuracy: 0.9618
TypeError
                                        Traceback (most recent call
<ipython-input-31-28af0c3e5bc0> in <cell line: 12>()
    10
    11
---> 12 FineTuned VGG Model 3 = model.fit(
    13
                              train dataset,
    14
                              epochs= 1,
/usr/local/lib/python3.10/dist-packages/keras/src/utils/traceback util
s.py in error handler(*args, **kwargs)
                   # To get the full stack trace, call:
    68
    69
                   # `tf.debugging.disable traceback filtering()`
                   raise e.with traceback(filtered tb) from None
---> 70
    71
               finally:
    72
                   del filtered tb
/usr/local/lib/python3.10/dist-packages/keras/src/saving/serialization
```

```
lib.py in get class or fn config(obj)
                return object registration.get registered name(obj)
    393
    394
            else:
--> 395
                raise TypeError(
    396
                    f"Cannot serialize object {obj} of type
{type(obj)}. "
                    "To be serializable, "
    397
TypeError: Cannot serialize object Ellipsis of type <class
'ellipsis'>. To be serializable, a class must implement the
`get config()` method.
acc = FineTuned VGG Model 3.history["accuracy"]
val acc = FineTuned VGG Model 3.history["val accuracy"]
loss = FineTuned VGG Model 3.history["loss"]
val loss = FineTuned VGG Model 3.history["val loss"]
epochs = range(1, len(acc) + 1)
plt.plot(epochs, acc, color="grey", label="Training Accuracy")
plt.plot(epochs, val acc, color="blue", linestyle="dashed",
label="Validation Accuracy")
plt.title("Training and validation Accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, color="grey", label="Training Loss")
plt.plot(epochs, val loss, color="blue", linestyle="dashed",
label="Validation Loss")
plt.title("Training and validation Loss")
plt.legend()
plt.show()
best model = keras.models.load model("fine tuning vgg model3.keras")
FineTuned VGG Model 3 Results = best model.evaluate(test dataset)
print(f"Loss: {FineTuned VGG Model 3 Results[0]:.3f}")
print(f"Accuracy: {FineTuned VGG Model 3 Results[1]:.3f}")
```

Now, having constructed a total of 15 models, with two models serving as fine-tuned versions of the initial ones, we are poised to conduct a comparative analysis to determine the best-performing models in two distinct categories: Scratch Models and Pre-Trained Models. Our immediate focus is to evaluate the best model developed from scratch. This evaluation entails comparing the loss and accuracy metrics of the 10 models built across four different training samples. The primary objective is to ascertain the optimal training sample size for the task of classifying cats and dogs.

Model 1: filters from 32 to 256, 5 Input Layers

Model 2: filters from 32 to 256, 5 Input Layers, Augmented Images and Droput rate of 0.5

Model 3: filters from 32 to 512, 6 Input Layers, Augmented Images and Dropout rate of 0.5

Model 4: filters from 64 to 1024, 5 Input Layers, Augmented Images and Dropout rate of 0.6

Model 5: filters from 32 to 256, 5 Input Layers, Augmented Images and Droput rate of 0.5, training size 2000

Model 6: filters from 32 to 256, 5 Input Layers, Augmented Images and Droput rate of 0.5, training size 2000, Padding being same

Model 7: MaxPooling Operation, filters from 32 to 512, 5 Input Layers, Augmented Images, droput rate of 0.5, Training Sample - 3000

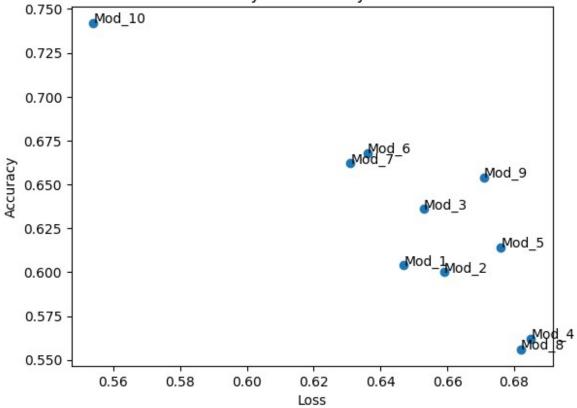
Model 8: MaxPooling + Strides of Step-Size 2, filters from 32 to 512, 5 Input Layers, Augmented Images, droput rate of 0.5, Training Sample - 3000

Model 9: MaxPooling + Strides of Step-Size 2 with Padding turned on, filters from 32 to 512, 5 Input Layers, Augmented Images, droput rate of 0.5, Training Sample - 3000

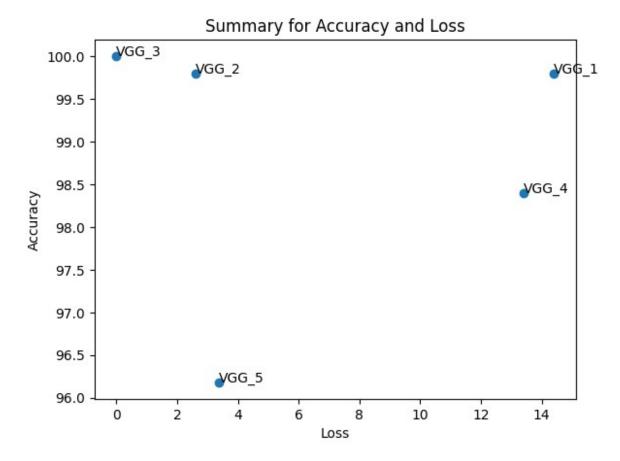
Model 10: filters from 32 to 512, 5 Input Layers, Augmented Images, droput rate of 0.5, Training Sample - 5000

```
Model 10 = (0.554, 0.742)
Models 4 =
 ("Mod \ \overline{1}","Mod \ 2","Mod \ 3","Mod \ 4","Mod \ 5","Mod \ 6","Mod \ 7","Mod \ 8","Mod \ 8","Mod \ 9","Mod \ 9",
9", "Mod 10")
Loss 4 =
 (Model 1[0], Model 2[0], Model 3[0], Model 4[0], Model 5[0], Model 6[0], Model 6[0]
el 7[0], Model 8[0], Model 9[0], Model 10[0])
Accuracy 4 =
 (Model 1[1], Model 2[1], Model 3[1], Model 4[1], Model 5[1], Model 6[1], Model 4[1]
el_7[1], Model_8[1], Model_9[1], Model_10[1])
fig, ax = plt.subplots()
ax.scatter(Loss 4, Accuracy 4)
for i, txt in enumerate(Models 4):
                 ax.annotate(txt, (Loss 4[i], Accuracy 4[i] ))
plt.title("Summary for Accuracy and Loss")
plt.ylabel("Accuracy")
plt.xlabel("Loss")
plt.show()
```

### Summary for Accuracy and Loss



```
# Pre-Trained Models
VGG Model 1 = (14.4, 99.8)
VGG Model 2 = (2.6, 99.8)
FineTuned VGG Model 2 = (0.00, 100)
VGG Model 3 = (13.4, 98.4)
FineTuned VGG Model 3 = (3.36, 96.18)
Models_5 = ("VGG_1","VGG_2","VGG_3","VGG_4","VGG_5")
Loss 5 =
(VGG_Model_1[0], VGG_Model_2[0], FineTuned_VGG_Model_2[0], VGG_Model_3[0]
,FineTuned_VGG_Model_3[0])
Accuracy 5 =
(VGG Model 1[1], VGG Model 2[1], FineTuned VGG Model 2[1], VGG Model 3[1]
,FineTuned VGG Model 3[1])
fig, ax = plt.subplots()
ax.scatter(Loss 5,Accuracy 5)
for i, txt in enumerate(Models 5):
    ax.annotate(txt, (Loss_5[i],Accuracy_5[i] ))
plt.title("Summary for Accuracy and Loss")
plt.ylabel("Accuracy")
plt.xlabel("Loss")
```



In the realm of pre-trained models, it was Model\_1 and model\_3, or the FineTuned\_VGG\_Model\_2 and FineTuned\_VGG\_Model\_3, that stood out as the top performer, boasting an impressive 100% accuracy and a mere 0.00% loss. Constructed with 2000 and 5000 training samples, this model was optimized using the Adam optimizer with a learning rate of 0.000001.

Conclusion: The above analysis indicate that the accuracy of a model is intricately tied to both the volume of the training data and the underlying architecture, particularly when the model is directly trained with its own data. Conversely, when utilizing a pretrained model, the accuracy is contingent on the specific set of test samples being evaluated. It's noteworthy that certain sets of samples may pose more challenges than others, and robust performance on one set may not fully generalize to all other sets. ign have a significant effect on test accuracy. Remarkably, adding three modern architectures—batch normalization, depthwise separable convolutions, and residual connections—to a simple scratch model and combining dropout and data augmentation methods resulted in a significant boost in test accuracy. Additionally, increasing the number of training data samples from 1,000 to 3,000 produced notable increases in test accuracy. When the training dataset was further expanded to 6,000 samples, test accuracy values were reached that were similar to those of pretrained models. This is explained by the overfitting phenomenon, which occurs when there are not enough samples for the model to adequately generalize to new data. A bigger dataset gives the model access to a greater

Recommendations: The accuracy of the simple scratch model experienced a significant boost, from 0.696 to 0.88.4, with an increase in the training data from 1,000 to 3,000 samples. With 3,000 training samples, incorporating three modern architectures, along with data augmentation and dropout techniques, resulted in a test accuracy close to 83.2%. Furthermore, when the model was trained with 5,000 samples, the test accuracy was 88%. it is recommended to prioritize Model 10 from the scratch models due to its superior accuracy.

for pre trained fine tuned model model, we got 100% accuracy and hence I also belive that it is not always best to use pretrained models in all situations. The case for distinguishing between cat and dog pictures used in this task is context-independent – meaning that the background or context of the picture does not affect the dog versus cat distinction. Therefore, in the case of a pretrained model that distinguishes images, it can be used in any image distinction task as long as the sample images are in the same category as the target used to train the model.