

# Bifurcation of coherent structures in nonlocally coupled system

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## Reaction-Diffusion Models

Bifurcation to coherent structures in RD system

$$U_t = D\Delta_x U + F(U; \mu).$$

Assume

- $U = U(x) \in \mathbb{R}^k, x \in \mathbb{R}^n$ ;
- $\mu \in \mathbb{R}^p$  parameter, nonlinearity  $N$  satisfies  $N(0; \mu) = 0$ .

Radially symmetric patterns are studied in [1] using spatial dynamics techniques.

- ① rewrite the stationary equation as an autonomous system of ODE;
- ② center manifold reduction to get complete characterization.

## Nonlocal Diffusion Models

Nonlocal diffusion is ubiquitous in modeling of natural phenomena [2]

- ① neural field models:  $u_t = -K * S(u)$ ,
- ② water wave equations:  $u_t = (Mu - u^2)_x$ ,  $M$  a pseudo-differential operator with symbol  $(\tanh(\xi)/\xi)^{1/2}$ .

Can we find similar patterns in these models?

- ① water wave solitons (figure from Ablowitz, Baldwin 2012)



Figure 1: waterwave

- ② neural field spikes (figure from Crochet, Petersen 2011)

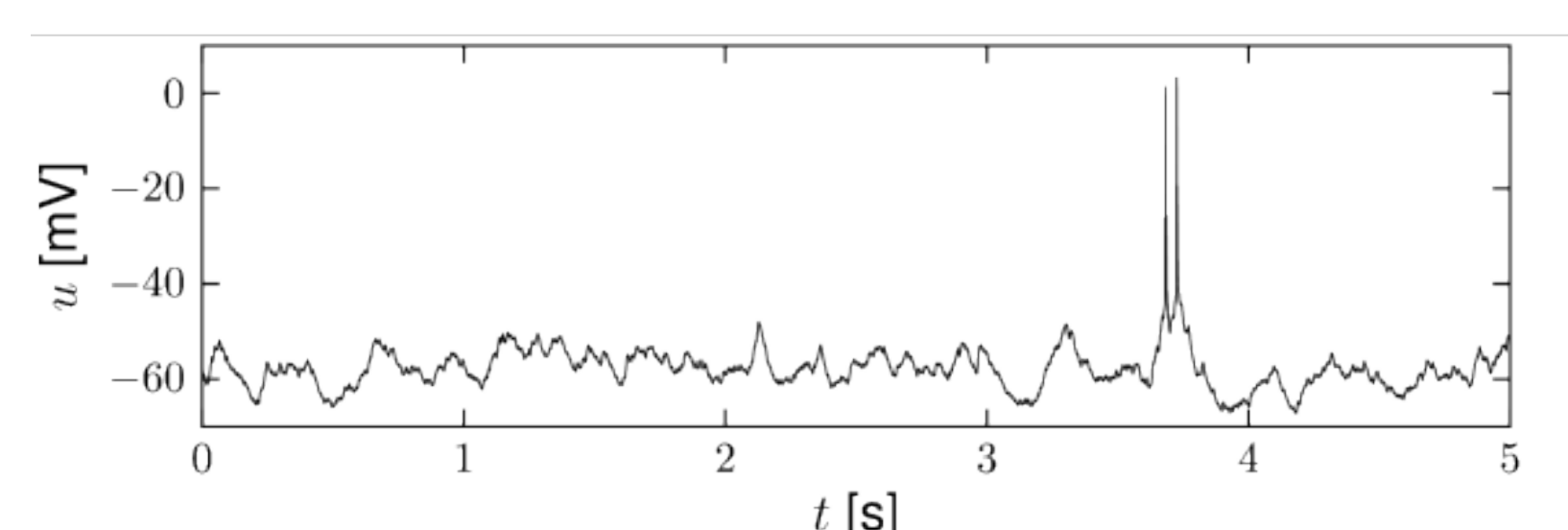


Figure 2: neural field spike

## A Bifurcation Problem

We study the following system of equations for  $U(x) \in \mathbb{R}^k$  with  $x \in \mathbb{R}^n$

$$U + K * U - N(U; \mu) = 0. \quad (1)$$

**Effective linear diffusive coupling (L):**

- $K$  is a matrix of convolution kernels with finite second moments,  $K(x), |x|^2 K(x) \in L^1(\mathbb{R}^n)$
- $K$  is symmetric,  $K(\gamma x) = K(x)$  for all  $\gamma \in \Gamma \subset O(n)$ . With  $\text{Fix}(\Gamma) = \{0\}$ .
- The Fourier determinant  $D(\xi) = \det(I + \bar{K}(\xi))$  has  $D(0) = 0, D'(0) = 0, D''(0) \neq 0$ .

Let  $e$  span the kernel of  $I + \bar{K}(0)$ , choose  $e^*$  span the cokernel.

## A Bifurcation Problem-Continued

**Transcritical bifurcation in kinetics (TC):**

- We assume a transcritical bifurcation scenario:

$$\begin{aligned} N(0; \mu) &= 0, \\ \langle e^*, D_{u\mu} N(0; 0)e \rangle &\neq 0, \\ \langle e^*, D_{uu} N(0; 0)[e, e] \rangle &\neq 0 \end{aligned}$$

- $N$  is smooth, so the superposition operator  $U(\cdot) \mapsto N(U(\cdot))$  is smooth.

We then find a pseudo-differential operator  $L$  and invertible matrix  $P, Q$  so that

$$LP(I_k + K*)Q = \text{diag}(M, I_{k-1}),$$

with  $M = (1 - \Delta)^{-1}\Delta$  and system decouples into two equations for a scalar function  $v_c$  and a  $\mathbb{R}^{k-1}$  valued function  $v_h$ .

## Main Result

Fix  $n < 6$  and  $\ell > n/2$ . Assume Hypotheses (L) and (TC), equation (1) has a solution of the form

$$U(x; \mu) = -\beta^{-1}\alpha\mu[v_*(\sqrt{\alpha\mu}x) + w(x; \mu)]e + v_\perp(x; \mu)$$

where  $v_*$  is the unique positive ground state of  $\Delta v - v + v^2 = 0$ ,  $w \in H^\ell(\mathbb{R}^n)$  is a corrector which converges to 0 as  $\mu \rightarrow 0$ , lastly,  $v_\perp$  satisfy  $\langle e, v_\perp \rangle = 0$  and  $\|v_\perp\| = O(\mu^2)$ .

## Sketch of Proof

- Work with function space

$$H_\Gamma^\ell = \{u \in H^\ell, u(\gamma x) = u(x), \gamma \in \Gamma\};$$

- Set  $\varepsilon = \sqrt{\alpha\mu}$ , then **rescale** by  $v_c = -\beta^{-1}\varepsilon^2\tilde{v}_c(\varepsilon x)$ ,  $v_h = \varepsilon^2\tilde{v}_h(\varepsilon x)$ , reduce equation

$$\varepsilon^{-2}m^\varepsilon\Delta\tilde{v}_c = \tilde{v}_c - \tilde{v}_c^2 + O(\varepsilon^2) \quad (2)$$

$$\tilde{v}_h = O(\varepsilon^2) \quad (3)$$

with  $m^\varepsilon$  the rescaled pseudo-differential operator, with symbol  $(1 + \varepsilon^2|\xi|^2)^{-1}$ ;

- Solve (3) to express  $\tilde{v}_h$  in terms of  $\tilde{v}_c$  by a fixed point argument. Get a reduced scalar bifurcation equation;
- Substitute the ansatz  $\tilde{v}_c = v_* + w$ , get an equation in  $w$ .

## Sketch of Proof-Continued

- Observe  $(m^\varepsilon)^{-1} : H^\ell \rightarrow H^{\ell-2}$  is well-defined, with  $\|(m^\varepsilon)^{-1} - 1\| = O(\varepsilon^2)$  as  $\varepsilon \rightarrow 0$ ;
- **Precondition** equation  $\tilde{v}_c$  by the operator  $(m^\varepsilon)^{-1}$ , simplify, get
 
$$0 = \Delta w - (w - 2v_*w - w^2) - ((m^\varepsilon)^{-1} - 1)(w - 2v_*w - w^2 + \Delta v_*) + O(\varepsilon^2).$$
 Denote the right hand by  $F(w; \varepsilon)$ , note  $F(w; \varepsilon) \rightarrow 0$  in  $L^2$  as  $(w; \varepsilon) \rightarrow (0; 0)$ , also,  $D_w F$  is continuous near  $(0, 0)$ , with

$$D_w F(0; 0) = \Delta - 1 + 2v_*,$$

which is nondegenerate and invertible from  $H_\Gamma^\ell$  to  $H_\Gamma^{\ell-2}$ , these facts allow the set up of an Newton iteration scheme to continue  $F(w; \varepsilon) = 0$  from  $H_\Gamma^\ell$  to  $H_\Gamma^{\ell-2}$  near  $(0; 0)$ .

## Properties of the Spike

- ① The spike constructed here is not necessarily exponentially localized, it depends on the localization of the convolution kernel  $K$ . For  $K$  algebraically localized we get algebraically localized spike due to the corrector  $w$ .
- ② Typical examples of  $\Gamma$  can be all of  $O(n)$  or subgroups by reflection across a hyperplane. Generalize the studies on radial symmetry in the local case.

## Further Directions

- ① Stability: probably unstable in NF and stable in water-wave problems. Notice no Evans function techniques available due to nonlocality. A perturbative argument is possible.
- ② Transition to large  $\mu$ : for  $\mu$  large, it can be shown many discontinuous solutions exist by implicit function theorem. How do things look in between large  $\mu$  and small  $\mu$ ?

## References

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- [3] Grégory Faye and Arnd Scheel. Center manifolds without a phase space. *arXiv preprint arXiv:1611.07487*, 2016.
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