Lab Sesión 12

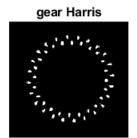
Yimin Pan (G12)

```
clc;
clear;
I1 = imread("gear.tif");
I2 = imread('rabbit.jpg');
```

Experiment 1

```
R1 = harris(I1);
corners = im2bw(R1); % binary image
ImRes = imoverlay(I1,corners,[1 0 0]);
figure; subplot(1,3,1); imshow(I1); title('original gear');
subplot(1,3,2); imshow(R1); title('gear Harris');
subplot(1,3,3); imshow(ImRes); title('overlay corner');
```





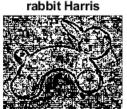


Experiment 2

```
for j = 1:m
    if (R2(i,j) > th)
        corners(i,j) = 1;
    end
end
end
ImRes = imoverlay(I2,corners,[1 0 0]);
figure; subplot(1,3,1); imshow(I2); title('original rabbit');
subplot(1,3,2); imshow(R2); title('rabbit Harris');
subplot(1,3,3); imshow(ImRes); title("overlay corner");
```

original rabbit

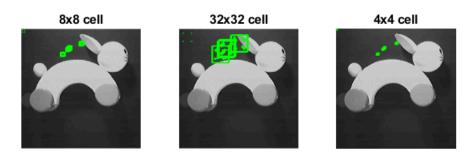








```
% Histogram of orientation
% still too much points, we select some for the plot
[rows, cols] = find(corners);
points = [rows cols];
selected = points(1:50,:);
[hog, validPoints, ptVis] = extractHOGFeatures(I2,selected,'CellSize',[8 8]);
figure; subplot(1,3,1); imshow(I2); hold on; plot(ptVis,'Color','green'); title("8x8 cell");
[hog2, validPoints2, ptVis2] = extractHOGFeatures(I2,selected, 'CellSize',[32 32]);
subplot(1,3,2); imshow(I2); hold on; plot(ptVis2,'Color','green'); title("32x32 cell");
[hog3, validPoints3, ptVis3] = extractHOGFeatures(I2,selected, 'CellSize',[4 4]);
subplot(1,3,3); imshow(I2); hold on; plot(ptVis3,'Color','green'); title("4x4 cell");
```



The features of the points are in the hogx variables.

```
function R = harris(I)
    [Ix Iy] = imgradientxy(I,'sobel');  % partial derivative with sobel
    g = fspecial('gaussian',3,2);  % gaussian filter of size 5 and std 2
    Ix = imfilter(Ix, g);
    Iy = imfilter(Iy, g);
    Ix2 = imfilter(Ix.^2, g);
    Iy2 = imfilter(Iy.^2, g);
    Ixy = imfilter(Ix.*Iy, g);
    k = 0.04;
    R = (Ix2.*Iy2-(Ixy.^2)) -k*((Ix2+Iy2).^2);  % apply formula
end
```