机器人技术第二次作业

说明:程序中附带了10个实例,解除注释即可运行!

源程序:

```
//package robo;
import java.awt.AWTException;
import java.awt.Robot;
import java.awt.event.InputEvent;
import java.awt.event.KeyEvent;
import java.util.ArrayList;
import java.util.List;
//点类
class Point {
    private float x;
    private float y;
    public Point(float x, float y) {
        this. x = x;
        this. y = y;
    }
    public void prt() {
        System.out.println("点 Point, 点位置 ("+this.x+","+this.y+")");
    }
    // getter&setter
    public float getX() {
        return x;
    }
    public void setX(float x) {
        this. x = x;
    }
    public float getY() {
        return y;
    }
    public void setY(float y) {
        this. y = y;
    }
```

```
}
//直线类
class Line {
    private float A, B, C;
    public Line(float A, float B, float C) {
        this. A = A;
        this. B = B;
        this. C = C;
    }
    public void prt() {
        System.out.println("直线 Line, 方程为 { " + this.A + " x + " + this.B + " y
+ " + this.C + " = 0 }");
    }
    public float getA() {
        return A;
    }
    public void setA(float a) {
       A = a;
    }
    public float getB() {
        return B;
    }
    public void setB(float b) {
        B = b;
    }
    public float getC() {
        return C;
    }
    public void setC(float c) {
       C = c;
    }
}
```

```
//圆类
class Circle {
    private Point Center;// 圆心 point
    private float Rad;// 圆的半径
    public Circle (Point center, float rad) {
        this. setCenter(center);
        this. Rad = rad;
   }
    public void prt() {
        System.out.println(
                ″圆 Circle, 圆心 ("+this.Center.getX()+", "+this.Center.getY()
+ " ), 半径 " + this. Rad + "");
   }
    public Point getCenter() {
        return Center;
   }
    public void setCenter(Point center) {
        this.Center = center;
   }
    public float getRad() {
        return Rad;
   }
    public void setRad(float rad) {
        Rad = rad;
   }
}
//矩形类
class Rect {
    private static Point Q;// 四个顶点
    private static Point W;
    private static Point E;
    private static Point R;
    public Rect (Point A, Point B, Point C, Point D) {//指定所有顶点,适合任意矩形
        setQ(A);
        setW(B);
        setE(C);
```

```
setR(D);
    }
    public Rect (Point P, Point Q) {//指定一条对角线,适合
        if(P. getX() < Q. getX() && P. getY() > Q. getY()) {//左上到右下
            setQ(P);
            setE(Q);
            Point D = new Point (P. getX(), Q. getY());
            Point B = new Point (Q. getX(), P. getY());
            setW(B):
            setR(D);
        else {//右上到左下
            setW(P);
            setR(Q):
            Point A = new Point (Q. getX(), P. getY());
            Point C = new Point (P. getX(), Q. getY());
            setQ(A);
            setE(C);
        }
   }
    public void prt() {
        System.out.println("\n 矩形 Rect ");
        System.out.println("{ 顶点 Q , 点位置 ( " + Q.getX() + " , " + Q.getY() +
" ) }");
        System.out.println("{ 顶点 W , 点位置 ( " + W.getX() + " , " + W.getY() +
" ) }");
        System.out.println("{ 顶点 E , 点位置 ( " + E.getX() + " , " + E.getY() +
" ) }");
        System.out.println("{ 顶点 R, 点位置 ("+R.getX()+","+R.getY()+")}");
   }
    public static Point getQ() {
        return Q;
   }
    public void setQ(Point q) {
        Q = q;
    }
    public static Point getW() {
        return W;
   }
```

```
public void setW(Point w) {
        W = W;
   }
    public static Point getE() {
        return E;
   }
    public void setE(Point e) {
        E = e:
   }
    public static Point getR() {
        return R;
    }
    public void setR(Point r) {
        R = r;
    }
}
class Seg {// 线段类
   Point P1, P2;
    public Seg(Point A, Point B) {
        P1 = A;
        P2 = B;
   }
}
//几何计算类
class geo_cal {
    static double eps = 0.00001F;
    public static void clear() throws AWTException {// 清屏指令
        Robot r = new Robot();
        r.mousePress(InputEvent.BUTTON3_MASK); // 按下鼠标右键
        r.mouseRelease(InputEvent.BUTTON3_MASK); // 释放鼠标右键
        r.keyPress(KeyEvent.VK_CONTROL); // 按下Ctrl 键
        r.keyPress(KeyEvent.VK_R); // 按下 R 键
        r.keyRelease(KeyEvent.VK_R); // 释放 R 键
```

```
r.keyRelease(KeyEvent.VK_CONTROL); // 释放Ctrl键
       r. delay (100);
   }
   // 直线判断
   public static float xGetY(float A, float B, float C, float x) {// 已知直线上 x
求y
        float y;
       if (A == 0) {
           // 平行于 x 轴
            y = -C / B;
           return y;
       \} else if (B == 0) {
           return 0; // 若平行于 y 轴, 默认返回与 x 轴交点
       } else {
           y = (-C - A * x) / B;
           return y;
       }
   }
    public static float yGetX(float A, float B, float C, float y) {// 已知直线上y
求x
        float x:
        if (A == 0) {
           return 0;// 直线与 x 轴平行
        } else if (B == \frac{0}{1}) {
           x = -C / A;
           return x;
       } else {
           x = (-C - B * y) / A;
           return x;
       }
   }
    public static int L2L(Line L1, Line L2) {// 求直线交点
       // 重合返回6,相交返回1,平行返回0,报错-1
        float px = 0, py = 0; // 作为返回值的参数
        float A1, A2, B1, B2, C1, C2;
        float m;
       L1. prt();
       L2. prt();
       // 参数赋值
```

```
A1 = L1. getA();
        B1 = L1. getB();
        C1 = L1. getC();
       A2 = L2. getA();
        B2 = L2. getB();
       C2 = L2. getC();
       m = A1 * B2 - A2 * B1;
       // 计算开始
        if ((A1 == 0 && A2 == 0 && B1 * C2 == B2 * C1) || (B1 == 0 && B2 == 0 && A1
* C2 == A2 * C1)
               (A1 * A2 * B1 * B2 != 0 && A1 / A2 == B1 / B2 && B1 / B2 == C1 /
C2)) {
            System. out. println("两直线重合!");
           return 6;
       }
        if (A1 != 0 && B1 != 0 && A2 != 0 && B2 != 0) {// 都不平行于轴
            if (Math.abs(m) < 0.0005f) {// 平行
               System. out. println("两直线平行!");
               return 0;
           } else {// 有交点
               px = (B1 * C2 - B2 * C1) / (A1 * B2 - A2 * B1);
               py = (A2 * C1 - A1 * C2) / (A1 * B2 - A2 * B1);
               System.out.println("两直线交点为: (" + px + ", " + py + ")!");
               return 1;
           }
        } else {// 有直线平行于轴
            if ((A1 == 0 && A2 == 0) | (B1 == 0 && B2 == 0)) {// 都平行于轴
               System. out. println("两直线平行!");
               return 0:
           } else if (A1 == 0 || B1 == 0) {// L1 平行于坐标轴
               if (A1 == 0) {// x轴
                   py = -C1 / B1;
                   px = yGetX(A2, B2, C2, py);
                   System.out.println("两直线交点为: ("+px+", "+py+")!");
                   return 1;
               } else {// y轴
                   px = -C1 / A1;
                   py = xGetY(A2, B2, C2, px);
                   System.out.println("两直线交点为: ("+px+", "+py+")!");
                   return 1;
               }
           } else if (A2 == 0 || B2 == 0) {// L2 平行于坐标轴
               if (A2 == 0) {// x轴
```

```
py = -C2 / B2;
                    px = yGetX(A1, B1, C1, py);
                    System. out. println ("两直线交点为: (" + px + ", " + py + ")!");
                    return 1;
                } else {// y轴
                    px = -C2 / A2;
                    py = xGetY(A1, B1, C1, px);
                    System. out. println ("两直线交点为: (" + px + ", " + py + ")!");
                    return 1;
                }
            }
        return -1;
   }
    public static float P2LD(Point P, Line L) {// 求点到直线的距离
        float A = L. getA();
        float B = L. getB();
        float C = L. getC();
        return (float) (Math. abs (A * P. getX() + B * P. getY() + C) / (Math. sqrt(A * A
+ B * B)));
   }
    // 圆判断
    public static void L2C(Circle Cir, Line L) {// 求直线和圆的交点
        // Point[] points = null;//可能会有多个交点
        float A = L. getA();
        float B = L. getB();
        float C = L. getC();
        float Rad = Cir.getRad();
        Cir.prt();
        L. prt();
        float dis = P2LD(Cir.getCenter(), L);
        if (Math.abs(dis) > Rad) {// 没有交点
            System.out.println("直线和圆相离!");
            return;
        } else if (Math.abs(dis - Cir.getRad()) < 0.0000001f) {// 相切
            float angle = (float) Math. atan(-A / B);
            float ix = (float) (Cir.getCenter().getX() + Rad * Math.cos(Math.PI +
angle));
```

```
float iy = (float) (Cir.getCenter().getX() + Rad * Math.sin(Math.PI +
angle)):
           System. out. println("直线和圆相切,交点为: (" + ix + ", " + iy + ")!");
           return;
       } else {// 相交
           if (Math. abs(B) < 0.00001f) {// L与y轴平行
               float h = (float) Math. sqrt (Rad * Rad - dis * dis);// 求未知边长
               float x = -C / A; // L 上所有点的横坐标
               float v1 = Cir.getCenter().getY() + h;
               float y2 = Cir.getCenter().getY() - h;
               System. out. println ("直线和圆相交,一个交点为: ("+x+","+y1+
")!");
               System.out.println("另一个交点为: (" + x + ", " + y2 + ")!");
           } else {// L 是一般直线
               float k = -A / B; // 化成 y = kx + b 的形式
               float b = -C / B;
               float c = Cir.getCenter().getX();
               float d = Cir.getCenter().getY();
               float r = Cir.getRad();
               // 以下直接套公式
               float x1 = (float) (-(Math. sqrt(
                       (k * k + 1) * r * r - c * c * k * k + (2 * c * d + 2 * b *
c) * k - d * d - 2 * b * d - b * b)
                      + (d + b) * k + c) / (k * k + 1);
               float x2 = (float) ((Math. sqrt(
                       (k * k + 1) * r * r - c * c * k * k + (2 * c * d + 2 * b *
c) * k - d * d - 2 * b * d - b * b
                      - (d + b) * k - c) / (k * k + 1);
               k * k + 2 * c * d * k
                      + 2 * b * c * k - d * d - 2 * b * d - b * b) + c) + d * k *
k - b) / (k * k + 1));
               float y2 = (float) (-(k * (-Math. sqrt(k * k * r * r + r * r - c * c
* k * k + 2 * c * d * k
                      + 2 * b * c * k - d * d - 2 * b * d - b * b) + c) + d * k *
k - b) / (k * k + 1);
```

```
System.out.println("直线和圆相交,一个交点为: (" + x1 + ", " + y1
+ ")!");
                System. out. println ("另一个交点为: (" + x2 + ", " + y2 + ")!");
            }
        }
    }
   // 矩形判断
    public static Point minus (Point A, Point B) {// 自定义运算
        Point v = new Point(A. getX() - B. getX(), A. getY() - B. getY());
        return v:
   }
    public static float multi(Point A, Point B) {
        return A. getX() * B. getY() - A. getY() * B. getX();
    }
    public static int inter(Point A, Point B, Seg S1)/// 判断直线 AB 是否与线段 S1(CD)
相交
    {
        Point C = S1.P1;
        Point D = S1.P2;
        if ((multi(minus(C, A), minus(B, A)) * multi(minus(D, A), minus(B, A))) < eps)
            return 1;
        return 0;
   }
    public static Point inter_point (Point A, Point B, Seg S1)/// 返回直线 AB 和线段
S1(CD)的交点
    {
        Point C = S1.P1;
        Point D = S1.P2;
        if (inter(A, B, S1) == 0) {
            System.out.println("不相交!");
            return null;
        }
        float area1 = Math.abs(multi(minus(B, A), minus(C, A)));
        float area2 = Math.abs(multi(minus(B, A), minus(D, A)));
        float x = (areal * D. getX() + area2 * C. getX()) / (area1 + area2);
        float y = (area1 * D. getY() + area2 * C. getY()) / (area1 + area2);
        Point p = new Point(x, y);
```

```
System.out.println("直线与矩形边 (" + C.getX() + ", " + C.getY() + ")"+
" -- " + " ( " + D.getX() + " , "
                + D.getY() + " ) " + "交点是:" + p.getX() + " , " + p.getY());
//
        return p;
    }
    public static Point[] getP(Line L) {// 输入直线求直线上的点
        Point[] points = new Point[2];
        float A = L. getA():
        float B = L. getB();
        float C = L. getC();
        if (B == 0) {// 该线平行于 y 轴
            points[0] = new Point(-C / A, -1);
            points[1] = new Point(-C / A, 1);
        } else if (A == 0) \{// x \text{ in} \}
            points[0] = new Point(-1, -C / B);
            points[1] = new Point(1, -C / B);
        } else {
            points[0] = new Point(-1, xGetY(A, B, C, -1));
            points[1] = new Point(1, xGetY(A, B, C, 1));
        }
        return points;
    }
    public static Line getL(Seg S1) {// 求线段所在的直线
        Point P = S1.P1;
        Point Q = S1.P2;
        float X1 = P. getX();
        float X2 = Q. getX();
        float Y1 = P. getY();
        float Y2 = Q. getY();
        float A = Y2 - Y1;
        float B = X1 - X2;
        float C = X2 * Y1 - X1 * Y2;
        return new Line (A, B, C);
    }
    public static boolean cp (Point A, Point B) {//比较两点坐标是否相同
        float X1 = A. getX();
        float X2 = B. getX();
```

```
float Y1 = A. getY();
    float Y2 = B. getY();
    if (Math. abs (X1 - X2) < eps && Math. abs (Y1 - Y2) < eps) {
        return true;
    }
    else {
        return false;
    }
}
public static void R2L(Rect rec, Line L) throws AWTException {// 矩形与直线交点
    // 变量声明,取得 L 上两点 P1, P2
    Point[] points = getP(L);
    Point P1 = points[0];
    Point P2 = points[1];
    int[] flg = new int[5];// 标志哪些边相交
    Point[] cop = new Point[5];// 交点数组
    Seg[] bian = new Seg[5];
    for (int i = 0; i < 5; i++) {
        cop[i] = new Point (9999, 9999);
    }
    // 矩形顶点, 各边为 QW, WE, ER, RQ
    Point Q = Rect. getQ();
    Point W = Rect.getW();
    Point E = Rect.getE();
    Point R = Rect. getR();
    // 各边定义为线段
    Seg B1 = new Seg(Q, W);
    Seg B2 = new Seg(W, E);
    Seg B3 = new Seg(E, R);
    Seg B4 = new Seg(R, Q);
    Line L1 = getL(B1);
    Line L2 = getL(B2);
    Line L3 = getL(B3);
    Line L4 = getL(B4);
    int flag;// 重合标志位
    flag = (L2L(L, L1) + L2L(L, L2) + L2L(L, L3) + L2L(L, L4));
```

```
// System.out.println(flag);
        int flag_in;
        flg[1] = inter(P1, P2, B1);// 1表示与该边相交
        flg[2] = inter(P1, P2, B2);
        flg[3] = inter(P1, P2, B3);
        flg[4] = inter(P1, P2, B4);
        flag_in = flg[1] + flg[2] + flg[3] + flg[4];
        bian[1] = B1;
        bian[2] = B2;
        bian[3] = B3;
        bian[4] = B4;
        rec.prt();
        System. out. println("");
        L. prt();
        System. out. println("");
        System.out.println("结果为----
        if (flag > 5) {// 直线与某边重合
            System. out. println("直线与矩形边重合!");
            return:
        else\ if\ (inter(P1, P2, B1) = 0 \&\&\ inter(P1, P2, B2) = 0 \&\&\ inter(P1, P2, B2) = 0 \&\&\ inter(P1, P2, B2)
B3) == 0
                && inter(P1, P2, B4) == 0) {// 与四条边都不相交
            System. out. println("直线与矩形不相交!");
        } else {// 一般相交情况
            if (flag_in == 2) {// 相切或者与两个边相交
                for (int i = 1; i < 5; i++) {
                    if (flg[i] == 1) {//
                        cop[i] = inter point(P1, P2, bian[i]);
                    }
                }
            } else if (flag_in == 3) {// 过一个顶点且与另一边相交
                for (int i = 1; i < 5; i++) {
                    if (flg[i] == 1) {//
                        cop[i] = inter_point(P1, P2, bian[i]);
                    }
                }
            } else {// 过对角线
                for (int i = 1; i < 5; i++) {
                    if (flg[i] == 1) {//
                        cop[i] = inter_point(P1, P2, bian[i]);
```

```
}
               }
           }
        }
       // 判断结束,交点已存储到 cop 数组中
        // 打印输出
//
       for (int i = 1; i < 5; i++) {
            if (cop[i].getX() != 9999 && cop[i].getY() != 9999) {//
               System.out.println("交点是: {" + cop[i].getX() + ", " + cop[i].getY()
//
+ " }");
//
      }
        //考虑到过顶点的情况,需要删除重复的
        Point[] out = new Point[5];
        for (int i = 0; i < 5; i++) {
            out[i] = new Point(9999, 9999);
        }
        for (int i = 1; i < 5; i++) {//去重循环
            int sflag = 0;
            for (int j = 1; j < 5; j++) {
               if(cp(out[j], cop[i])) {
                   sflag = 1;
               }
            }
            if(sflag = 1) {
               continue;
            }
            else {
               out[i] = cop[i];
           }
        }
        int k = 0;
        for (int i = 1; i < 5; i++) {//输出
            if (out[i].getX() != 9999 && out[i].getY() != 9999) {//
               k++;
           }
```

```
}
        System.out.println("直线与矩形共有 " + k + " 个交点: ");
        for (int i = 1; i < 5; i++) {//输出
            if (out[i].getX() != 9999 && out[i].getY() != 9999) {//
               System.out.println(" { " + out[i].getX() + " , " + out[i].getY() +
" }");
           }
       }
   }
}
public class Inter_Test {// 主测试程序
    /*
    * 说明 测试用例已经提供,解除注释即可使用 需要输入的参数已经列出
    */
    public static void main(String[] argc) throws AWTException {// 主函数
       /*
        * 测试直线交点;
        * 需要输入两条直线的参数;
        */
       // 实例 1: 一般相交
//
       Line L1 = new Line(9, 5, 3);
//
       Line L2 = \text{new Line}(9, 0, 0);
//
        geo cal. L2L(L1, L2);
       // 实例 2: 重合
//
       Line L1 = \text{new Line}(4, 6, 8);
//
       Line L2 = \text{new Line}(2, 3, 4);
//
        geo_cal. L2L(L1, L2);
       // 实例 3: 平行
//
       Line L1 = new Line(9, 5, 3);
//
       Line L2 = \text{new Line}(9, 5, 0);
//
       geo_cal. L2L(L1, L2);
        /*
        * 测试直线与圆交点;
        * 需要输入圆心、半径、直线参数;
```

```
*/
```

```
// 实例 1: 直线与圆相交
//
        Point p1 = new Point(0, 0);
//
        Line L3 = new Line (2, 0.5f, -1);
//
        Circle C1 = new Circle(p1, 1);
//
//
        geo_cal. L2C(C1, L3);
        // 实例 2: 直线与圆相切
//
        Point p1 = new Point(1, 1);
//
        Line L3 = new Line(1, 0, -2);
//
        Circle C1 = new Circle(p1, 1);
//
//
        geo_cal. L2C(C1, L3);
        // 实例 3: 直线与圆相离
//
        Point p1 = new Point(1, 1);
//
        Line L3 = new Line (1, 0, -7);
//
        Circle C1 = new Circle(p1, 1);
//
//
        geo_cal. L2C(C1, L3);
        /*
         * 测试直线与矩形交点
        * 以下都定义了4个顶点;
         * 在计算某边与坐标轴平行的矩形时,可选择 AC 或 BD (对角线)作为参数;
         * 如果要计算一般的矩形,需要输入全部顶点;
        */
        // 实例 1: 两个交点,其中一个是顶点
        Point A = new Point(-1, 1);
        Point B = new Point(1, 1);
        Point C = new Point(1, 0);
        Point D = new Point (-1, 0);
        Rect Rec1 = new Rect(B, D);
        Line LT = new Line (-1, -1, 1);
        geo_cal.R2L(Rec1, LT);
        // 实例 2: 直线和一条边重合
//
        Point A = \text{new Point}(-1, 1);
//
        Point B = new Point(1, 1);
//
        Point C = \text{new Point}(1, 0);
```

```
//
         Point D = \text{new Point}(-1, 0);
//
//
         Rect Rec1 = new Rect (A, C);
//
         Line LT = new Line (1, 0, -1);
//
         geo cal. R2L (Rec1, LT);
         // 实例 3: 直线过对角线
//
         Point A = \text{new Point}(-1, 1);
//
         Point B = new Point(1, 1):
//
         Point C = \text{new Point}(1, -1);
         Point D = new Point (-1, -1);
//
//
         Rect Rec1 = new Rect(B, D);//只用两个顶点定义
//
         Line LT = new Line (1, -1, 0);
//
         geo_cal. R2L (Rec1, LT);
         // 实例 4: 一般相交,有两个交点
//
         Point A = \text{new Point}(0, 2);
//
         Point B = \text{new Point}(2, 2);
         Point C = \text{new Point}(2, 0);
//
         Point D = \text{new Point}(0, 0);
//
//
         Rect Rec1 = new Rect (A, C);
//
         Line LT = new Line (1, 1, -1);
//
         geo cal. R2L (Rec1, LT);
    }
}
```

运行截图:

<terminated> Inter Test [Java Application] C:\Java\bin\javaw.exe (2020年4月11 直线 Line , 方程为 { 4.0 x + 6.0 y + 直线 Line , 方程为 { 2.0 x + 3.0 y + 两直线重合!