

# Lab 1 W.D. QING CUI ZHANG.

Recover sparse signal from under-sampled observations.

## Exercise 1

From  $y = Ax$ .

As  $A$  is defined as  $m \times n$  matrix.

$x$  is an  $n \times 1$  matrix,

$$x = A^T y.$$

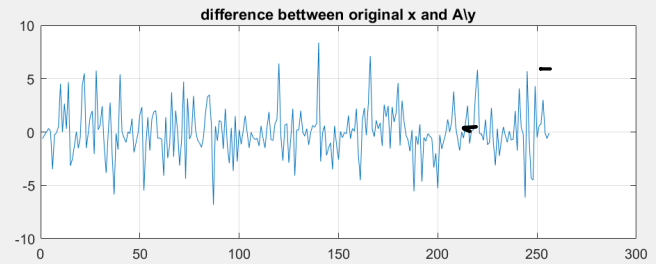
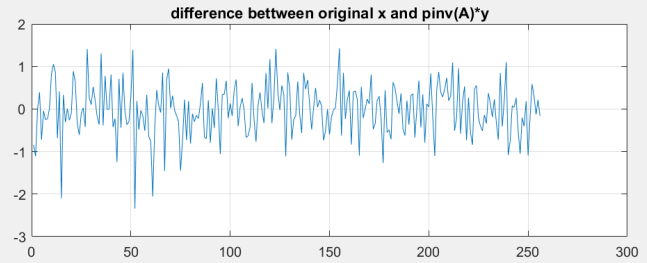
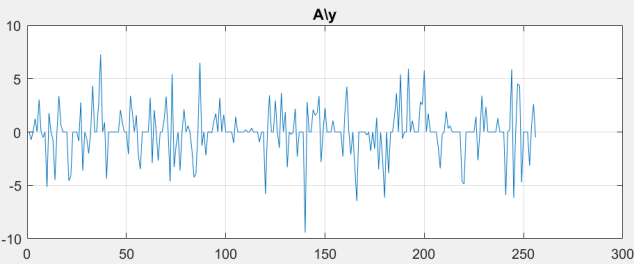
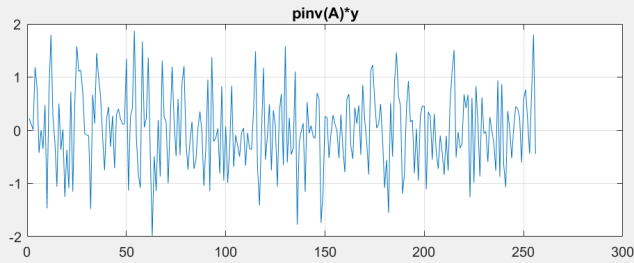
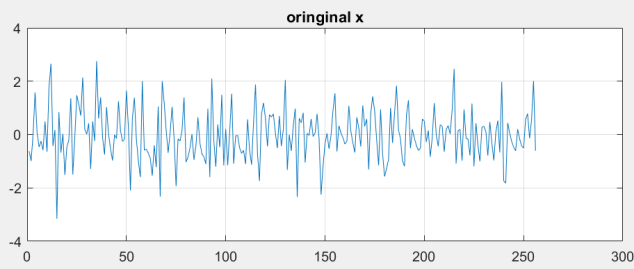
$x$  is the original signal to be recovered.

$y$  is the vector of measurements.

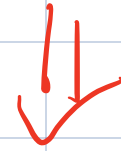
$A$  is the measurements matrix.

Assume  $\ell_2$ -norm, aim to normalize each column of  $A$ .

In matlab using 'normc ( )'



Pseudoinverse Method :  $\hat{x}_1 = \text{pinv}(A)y$   
 Least Squares Method :  $\hat{x}_2 = A^+ y$



In matlab using  
 $x = A \backslash y$

Compare each signal with original  
 signal in Matlab, discover that they are  
 different with each other.

## Exercise 2.

Exit : 1. tolerance level  $10^{-6}$

2. iterations 20

0 MP : 1. Obtain  $\text{supp}(C)$  by using  
 $\text{max}(\text{abs}(C))$

Residual obtain by  $\text{union}(C)$

2.  $A_S^+ y$  obtained in Matlab  
 $\text{pinv}(A_S) \cdot y$ .

SP : Initialization

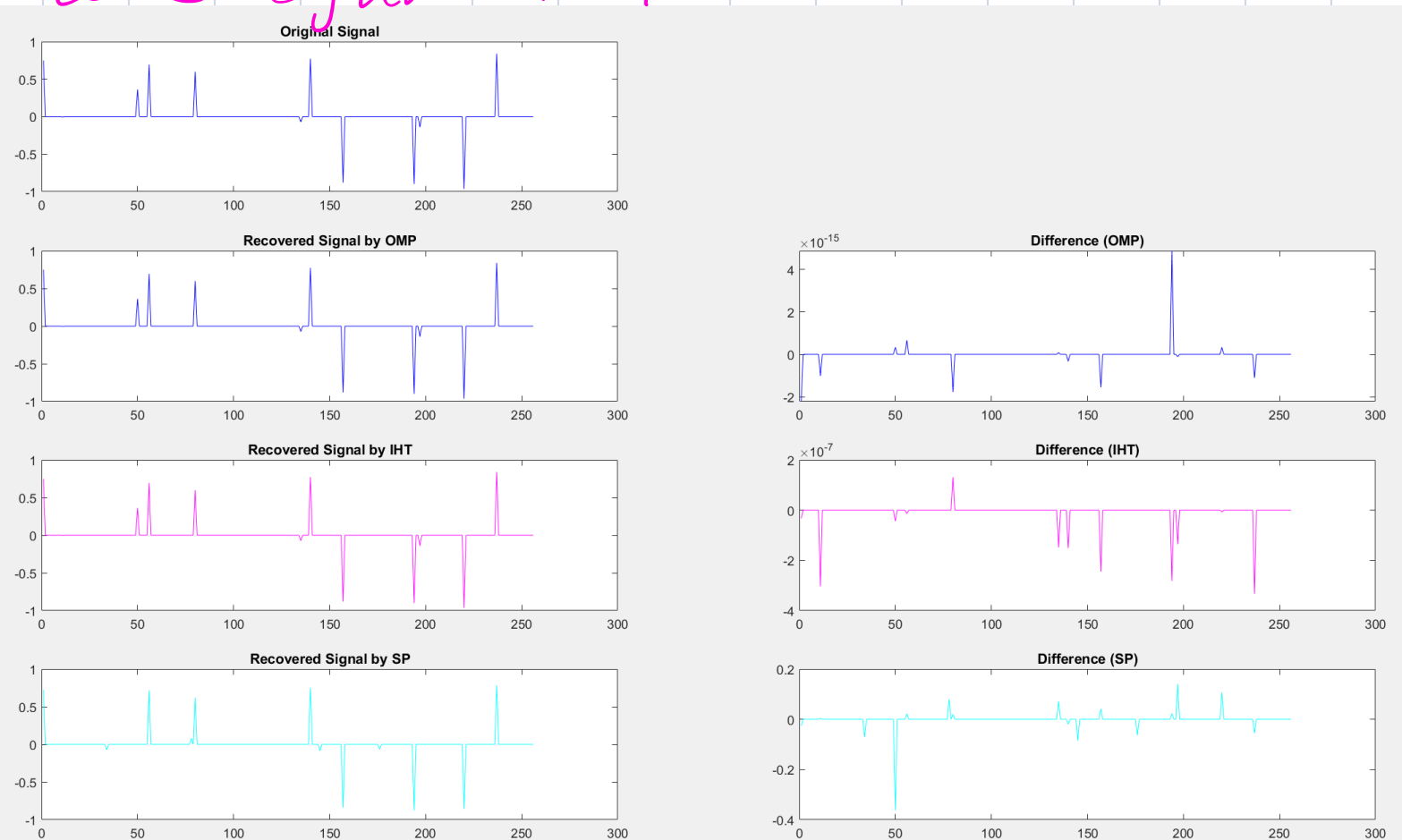
$S = \text{supp}(H_S(A_S^+ y))$  is interpreted  
in Matlab as  $\text{find}(\text{abs}(C) > 0.1 \times \text{abs})$   
the threshold is set at 0.1

$$b_S^+ = A_S^+ y \Rightarrow b_T = A \setminus y;$$

IHS: Write a function of IHS,  
which keeps  $S$  the largest  
magnitude components as its input,  
and set the rest as 0.

Matlab figure :-

OMP add one index at a time to the  
support set. SP. expand the support  
set by  $S$  indices and shrink it back  
to  $S$  afterwards.



ITT updates the estimate directly.  
Without maintaining a support set.