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		#define SZ(v) (int)v.size()	
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5.9 Minimum Mean Cycle	15	void debug(){cerr << "\n";}	
5.10 Minimum Steiner Tree	15	template<class T, class ... U>	
		void debug(T a, U ... b){cerr << a << " ", debug(b...);}	
6 Math	16	template<class T> void pary(T l, T r){	
6.1 Extended Euclidean Algorithm	16	while (l != r) cerr << *l << " ", l++;	
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1.2 .vimrc

```
sy on
se nu rnu bs=2 sw=4 ts=4 hls ls=2 si acd bo=all mouse=a
map <F9> :w<bar>!g++ "%" -o %:r -std=c++17 -Wall -Wextra -
    Wshadow -O2 -Dzisk -g -fsanitize=undefined,address<CR>
map <F8> :!./%:r<CR>
inoremap {<CR> {<CR>}<ESC>ko
```

1.3 Windows Setup

1. Open Sublime Text
2. Alt+Shift+2, Ctrl+K, Ctrl+Shift+Up
3. Create input.txt and output.txt
4. Preferences -> Settings -> 左邊最下面複製到右邊，把 Vintage 刪掉
5. Tools -> Build System -> New Build System

```
compile.bat $file_base_name
```

```
Save at AppData/Roaming/Sublime Text 3/Packages/User/test Tools
-> Build System -> test
```

compile.bat:

```
g++ %1.cpp -o %1 -std=c++17 -O2 ^
-Wall -Wextra -Wshadow -Dzisk ^
-Wl,--stack,268435456 -g -gdb3 -D_GLIBCXX_ASSERTIONS ^
&& %1.exe < input.txt > output.txt
```

1.4 Debug

- Compile flags: -D_GLIBCXX_ASSERTIONS, -D_GLIBCXX_DEBUG (slow), -gdb3
- GDB: break <function>, continue, bt

1.5 Fast IO

```
// from JAW
inline int my_getchar() {
    const int N = 1<<20;
    static char buf[N];
    static char *p = buf, *end = buf;
    if(p == end) {
        if((end = buf + fread(buf, 1, N, stdin)) == buf)
            return EOF;
        p = buf;
    }
    return *p++;
}

inline int readint(int &x) {
    static char c, neg;
    while((c = my_getchar()) < '-') {
        if(c == EOF) return 0;
    }
    neg = (c == '-') ? -1 : 1;
    x = (neg == 1) ? c - '0' : 0;
    while((c = my_getchar()) >= '0') x = (x << 3) + (x << 1)
        + (c - '0');
    x *= neg;
    return 1;
}

const int kBufSize = 524288;
char inbuf[kBufSize];
char buf[kBufSize]; size_t size_;
inline void Flush_() { write(1, buf, size_); size_ = 0; }
inline void CheckFlush_(size_t sz) { if (sz + size_ >
    kBufSize) Flush_(); }

inline void PutInt(int a) {
    static char tmp[22] = "01234567890123456789\n";
    CheckFlush_(10);
```

```
if(a < 0){
    *(buf_ + size_) = '-';
    a = ~a + 1;
    size_++;
}
int tail = 20;
if (!a) {
    tmp[--tail] = '0';
} else {
    for (; a; a /= 10) tmp[--tail] = (a % 10) ^ '0';
}
memcpy(buf_ + size_, tmp + tail, 21 - tail);
size_ += 21 - tail;
}

int main(){
    Flush_();
    return 0;
}
```

1.6 Random

```
mt19937 rng(chrono::system_clock::now().time_since_epoch().
    count());
```

1.7 Checker

```
#!/usr/bin/env bash
set -e
while ;; do
    python3 gen.py > test.txt
    diff <./a.exe < test.txt <./b.exe < test.txt
done
```

1.8 PBDS Tree

```
#include <bits/extc++.h>
using namespace __gnu_pbds;
using Tree = tree<int, null_type, less<, rb_tree_tag,
    tree_order_node_statistics_update>;
// .find_by_order(x)
// .order_of_key(x)
```

2 Data Structure

2.1 Heavy-Light Decomposition

```
struct Heavy_light_Decomposition { // 1-base
    int n, up[maxn], dep[maxn], to[maxn], siz[maxn], pa[maxn]
        ];
    int C, ti[maxn], ord[maxn], wdown[maxn], edge[maxn], et =
        0;
    vector<pii> G[maxn];
    void init(int _n) {
        n = _n, C = 0, et = 1;
        for (int i = 1; i <= n; i++)
            G[i].clear(), to[i] = 0;
    }
    void add_edge(int a, int b, int w) {
        G[a].push_back(pii(b, et)), G[b].push_back(pii(a, et));
        edge[et++] = w;
    }
    void dfs(int u, int f, int d) {
        siz[u] = 1, pa[u] = f, dep[u] = d;
        for (auto &v: G[u])
            if (v.ff != f) {
                dfs(v.ff, u, d+1), siz[u] += siz[v];
                if (siz[to[u]] < siz[v]) to[u] = v;
            }
    }
    void cut(int u, int link) {
```

```

    ti[u] = C;
    ord[C++] = u, up[u] = link;
    if (!to[u]) return;
    cut(to[u], link);
    for (auto v:G[u]) {
        if (v.ff != pa[u] && v.ff != to[u]) cut(v.ff, v.ff);
    }
}
void build() { dfs(1, 1, 1), cut(1, 1); }
int query(int a, int b) {
    int ta = up[a], tb = up[b], re = 0;
    while (ta != tb)
        if (dep[ta] < dep[tb])
            /*query*/, tb = up[b = pa[tb]];
        else /*query*/, ta = up[a = pa[ta]];
    if (a == b) return re;
    if (ti[a] > ti[b]) swap(a, b);
    /*query*/
    return re;
}
};

```

2.2 Link Cut Tree

```

struct Splay { // LCT + PATH add
    static Splay nil;
    Splay *ch[2], *f;
    int rev;
    int sz;
    ll val, sum, tag;
    Splay() : rev(0), sz(1), val(1), sum(1), tag(0) {
        f = ch[0] = ch[1] = &nil;
    }
    bool isr() { return f->ch[0] != this && f->ch[1] != this; }
    int dir() { return f->ch[0] == this ? 0 : 1; }
    void setCh(Splay *c, int d) {
        ch[d] = c;
        if (c != &nil) c->f = this;
        pull();
    }
    void push() {
        for(int i = 0; i < 2; i++){
            if(ch[i] == &nil) continue;
            if(rev) swap(ch[i]->ch[0], ch[i]->ch[1]), ch[i]->rev
                ^= 1;
            if(tag != 0){
                ch[i]->tag += tag;
                ch[i]->val += tag;
                ch[i]->sum += tag * ch[i]->sz;
            }
        }
        tag = 0;
        rev = 0;
    }
    void pull() {
        // take care of the nil!
        sz = 1;
        sum = val;
        for(int i = 0; i < 2; i++){
            if(ch[i] == &nil) continue;
            ch[i]->f = this;
            sz += ch[i]->sz;
            sum += ch[i]->sum;
        }
    }
    void rotate(){
        Splay *p = f;
        int d = dir();
        if (!p->isr()) p->f->setCh(this, p->dir());
        else f = p->f;
        p->setCh(ch[!d], d);
        setCh(p, !d);
        p->pull(), pull();
    }
}

```

```

void update(){
    if(f != &nil) f->update();
    push();
}
void splay(){
    update();
    for(Splay* fa; fa = f, !isr(); rotate())
        if(!fa->isr()) (fa->dir() == dir() ? fa : this)->
            rotate();
}
Splay *access(Splay* q = &nil){
    splay();
    setCh(q, 1);
    pull();
    if (f != &nil) return f->access(this);
    else return q;
}
void root_path(){access(), splay();}
void chroot() {root_path(), swap(ch[0], ch[1]), rev = 1,
    push(), pull();}
void split(Splay* y){chroot(), y->root_path();}
void link(Splay* y){root_path(), y->chroot(), setCh(y, 1)
    ;}
void cut(Splay* y) {split(y), y->push(), y->ch[0] = y->ch
    [0]->f = &nil;}
Splay *get_root(){
    root_path();
    auto q = this;
    for(; q->ch[0] != &nil; q = q->ch[0]) q->push();
    return q;
}
Splay *lca(Splay* y){
    access(), y->root_path();
    return y->f == &nil ? &nil : y->f;
}
bool conn(Splay* y){return get_root() == y->get_root();}
} Splay::nil;

```

2.3 Treap

```

struct node {
    int data, sz;
    node *l, *r;
    node(int k) : data(k), sz(1), l(0), r(0) {}
    void up() {
        sz = 1;
        if (l) sz += l->sz;
        if (r) sz += r->sz;
    }
    void down() {}
};
int sz(node *a) { return a ? a->sz : 0; }
node *merge(node *a, node *b) {
    if (!a || !b) return a ? a : b;
    if (rand() % (sz(a) + sz(b)) < sz(a))
        return a->down(), a->r = merge(a->r, b), a->up(),
            a;
    return b->down(), b->l = merge(a, b->l), b->up(), b;
}
void split(node *o, node *&a, node *&b, int k) {
    if (!o) return a = b = 0, void();
    o->down();
    if (o->data <= k)
        a = o, split(o->r, a->r, b, k), a->up();
    else b = o, split(o->l, a, b->l, k), b->up();
}
void split2(node *o, node *&a, node *&b, int k) {
    if (sz(o) <= k) return a = o, b = 0, void();
    o->down();
    if (sz(o->l) + 1 <= k)
        a = o, split2(o->r, a->r, b, k - sz(o->l) - 1);
    else b = o, split2(o->l, a, b->l, k);
    o->up();
}
node *kth(node *o, int k) {
    if (k <= sz(o->l)) return kth(o->l, k);
}

```

```

    if (k == sz(o->l) + 1) return o;
    return kth(o->r, k - sz(o->l) - 1);
}
int Rank(node *o, int key) {
    if (!o) return 0;
    if (o->data < key)
        return sz(o->l) + 1 + Rank(o->r, key);
    else return Rank(o->l, key);
}
bool erase(node *o, int k) {
    if (!o) return 0;
    if (o->data == k) {
        node *t = o;
        o->down(), o = merge(o->l, o->r);
        delete t;
        return 1;
    }
    node *t = k < o->data ? o->l : o->r;
    return erase(t, k) ? o->up(), 1 : 0;
}
void insert(node *o, int k) {
    node *a, *b;
    split(o, a, b, k),
        o = merge(a, merge(new node(k), b));
}
void interval(node *o, int l, int r) {
    node *a, *b, *c;
    split2(o, a, b, l - 1), split2(b, b, c, r);
    // operate
    o = merge(a, merge(b, c));
}

```

2.4 KD Tree

```

namespace kdt {
    int root, lc[maxn], rc[maxn], xl[maxn], xr[maxn],
        yl[maxn], yr[maxn];
    point p[maxn];
    int build(int l, int r, int dep = 0) {
        if (l == r) return -1;
        function<bool(const point &, const point &)> f =
            [dep](const point &a, const point &b) {
                if (dep & 1) return a.x < b.x;
                else return a.y < b.y;
            };
        int m = (l + r) >> 1;
        nth_element(p + l, p + m, p + r, f);
        xl[m] = xr[m] = p[m].x;
        yl[m] = yr[m] = p[m].y;
        lc[m] = build(l, m, dep + 1);
        if (~lc[m]) {
            xl[m] = min(xl[m], xl[lc[m]]);
            xr[m] = max(xr[m], xr[lc[m]]);
            yl[m] = min(yl[m], yl[lc[m]]);
            yr[m] = max(yr[m], yr[lc[m]]);
        }
        rc[m] = build(m + 1, r, dep + 1);
        if (~rc[m]) {
            xl[m] = min(xl[m], xl[rc[m]]);
            xr[m] = max(xr[m], xr[rc[m]]);
            yl[m] = min(yl[m], yl[rc[m]]);
            yr[m] = max(yr[m], yr[rc[m]]);
        }
        return m;
    }
    bool bound(const point &q, int o, long long d) {
        double ds = sqrt(d + 1.0);
        if (q.x < xl[o] - ds || q.x > xr[o] + ds ||
            q.y < yl[o] - ds || q.y > yr[o] + ds)
            return false;
        return true;
    }
    long long dist(const point &a, const point &b) {
        return (a.x - b.x) * 111 * (a.x - b.x) +
            (a.y - b.y) * 111 * (a.y - b.y);
    }
}

```

```

void dfs(
    const point &q, long long &d, int o, int dep = 0) {
    if (!bound(q, o, d)) return;
    long long cd = dist(p[o], q);
    if (cd != 0) d = min(d, cd);
    if ((dep & 1) && q.x < p[o].x ||
        !(dep & 1) && q.y < p[o].y) {
        if (~lc[o]) dfs(q, d, lc[o], dep + 1);
        if (~rc[o]) dfs(q, d, rc[o], dep + 1);
    } else {
        if (~rc[o]) dfs(q, d, rc[o], dep + 1);
        if (~lc[o]) dfs(q, d, lc[o], dep + 1);
    }
}
void init(const vector<point> &v) {
    for (int i = 0; i < v.size(); ++i) p[i] = v[i];
    root = build(0, v.size());
}
long long nearest(const point &q) {
    long long res = 1e18;
    dfs(q, res, root);
    return res;
}
} // namespace kdt

```

3 Flow & Matching

3.1 Dinic

```

struct MaxFlow { // 1-base
    struct edge {
        int to, cap, flow, rev;
    };
    vector<edge> g[maxn];
    int s, t, dis[maxn], ind[maxn], n;

    void init(int _n) {
        n = _n + 2;
        s = _n + 1, t = _n + 2;
        for (int i = 0; i <= n; ++i) g[i].clear();
    }
    void reset() {
        for (int i = 0; i <= n; ++i)
            for (auto &j : g[i]) j.flow = 0;
    }
    void add_edge(int u, int v, int cap) {
        g[u].pb(edge{v, cap, 0, (int)g[v].size()});
        g[v].pb(edge{u, 0, 0, (int)g[u].size() - 1});
        //change g[v] to cap for undirected graphs
    }
    bool bfs() {
        fill(dis, dis+n+1, -1);
        queue<int> q;
        q.push(s), dis[s] = 0;
        while (!q.empty()) {
            int cur = q.front(); q.pop();
            for (auto &e : g[cur]) {
                if (dis[e.to] == -1 && e.flow != e.cap) {
                    q.push(e.to);
                    dis[e.to] = dis[cur] + 1;
                }
            }
        }
        return dis[t] != -1;
    }
    int dfs(int u, int cap) {
        if (u == t || !cap) return cap;
        for (int &i = ind[u]; i < (int)g[u].size(); ++i) {
            edge &e = g[u][i];
            if (dis[e.to] == dis[u] + 1 && e.flow != e.cap) {
                int df = dfs(e.to, min(e.cap - e.flow, cap));
                if (df) {
                    e.flow += df;
                    g[e.to][e.rev].flow -= df;
                    return df;
                }
            }
        }
    }
}

```

```

    }
}
}
dis[u] = -1;
return 0;
}
int maxflow() {
    int flow = 0, df;
    while (bfs()) {
        fill(ind, ind+n+1, 0);
        while ((df = dfs(s, inf))) flow += df;
    }
    return flow;
}
}
}flow;

```

3.2 Bounded Flow

```

struct Dinic { // 1-base
    struct edge {
        int to, cap, flow, rev;
    };
    vector<edge> g[maxn];
    int n, s, t, dis[maxn], ind[maxn], cnt[maxn];
    const int inf = 1e9;

    void init(int _n) {
        n = _n + 2;
        s = _n + 1, t = _n + 2;
        for (int i = 0; i <= n; ++i) g[i].clear(), cnt[i] = 0;
    }
    //reset, bfs, dfs same as Dinic
    void add_edge(int u, int v, int lcap, int rcap) {
        cnt[u] -= lcap, cnt[v] += lcap;
        g[u].pb(edge{v, rcap, lcap, (int)g[v].size()});
        g[v].pb(edge{u, 0, 0, (int)g[u].size() - 1});
    }
    int maxflow(int _s, int _t) {
        s = _s, t = _t;
        int flow = 0, df;
        while (bfs()) {
            fill(ind, ind+n+1, 0);
            while ((df = dfs(s, inf))) flow += df;
        }
        return flow;
    }
    bool feasible() {
        int sum = 0;
        for (int i = 1; i <= n - 2; ++i)
            if (cnt[i] > 0)
                add_edge(n - 1, i, 0, cnt[i]), sum += cnt[i];
            else if (cnt[i] < 0) add_edge(i, n, 0, -cnt[i]);
        if (sum != maxflow(n - 1, n)) sum = -1;
        for (int i = 1; i <= n - 2; ++i)
            if (cnt[i] > 0)
                g[n - 1].pop_back(), g[i].pop_back();
            else if (cnt[i] < 0)
                g[i].pop_back(), g[n].pop_back();
        return sum != -1;
    }
    int boundedflow(int _s, int _t) {
        add_edge(_t, _s, 0, inf);
        if (!feasible()) return -1; // infeasible flow
        int x = g[_t].back().flow;
        g[_t].pop_back(), g[_s].pop_back();
        /* Minimum feasible flow */
        int y = maxflow(_t, _s);
        return x-y;

        /* Maximum feasible flow
        int y = maxflow(_s, _t);
        return x+y;
        */
    }
};

```

3.3 Gomory Hu

```

MaxFlow Dinic;
int g[MAXN];
void GomoryHu(int n) { // 0-base
    fill_n(g, n, 0);
    for (int i = 1; i < n; ++i) {
        Dinic.reset();
        add_edge(i, g[i], Dinic.maxflow(i, g[i]));
        for (int j = i + 1; j <= n; ++j)
            if (g[j] == g[i] && ~Dinic.dis[j])
                g[j] = i;
    }
}

```

3.4 Hungarian Algorithm

```

struct KM { //1-base, max perfect matching in  $O(n^3)$ 
    int n;
    int c[maxn][maxn];
    int lx[maxn], ly[maxn], mx[maxn], my[maxn], slack[maxn];
    bool vx[maxn], vy[maxn];
    bool dfs(int p, bool ch) {
        if (vx[p]) return 0;
        vx[p] = 1;
        for (int v = 1; v <= n; v++) {
            slack[v] = min(slack[v], lx[p] + ly[v] - c[p][v]);
            if (lx[p] + ly[v] - c[p][v] > 0) continue;
            vy[v] = 1;
            if (!my[v] || dfs(my[v], ch)) {
                if (ch) mx[p] = v, my[v] = p;
                return 1;
            }
        }
        return 0;
    }
    ll solve() {
        for (int i = 1; i <= n; i++) {
            lx[i] = -inf;
            for (int j = 1; j <= n; j++) lx[i] = max(lx[i], a[i][j]);
        }
        for (int i = 1; i <= n; i++) {
            for (int j = 1; j <= n; j++) vx[j] = vy[j] = 0;
            for (int j = 1; j <= n; j++) slack[j] = inf;
            if (dfs(i, 1)) continue;
            bool aug = 0;
            while (!aug) {
                for (int j = 1; j <= n; j++) {
                    if (!vy[j] && slack[j] == 0) {
                        vy[j] = 1;
                        if (dfs(my[j], 0)) {
                            aug = 1;
                            break;
                        }
                    }
                }
            }
            if (aug) break;
            int delta = inf;
            for (int j = 1; j <= n; j++) {
                if (!vy[j]) delta = min(delta, slack[j]);
            }
            for (int j = 1; j <= n; j++) {
                if (vx[j]) lx[j] -= delta;
                if (vy[j]) ly[j] += delta;
                else {
                    slack[j] -= delta;
                    if (slack[j] == 0 && !my[j]) aug = 1;
                }
            }
        }
        for (int j = 1; j <= n; j++) vx[j] = vy[j] = 0;
        dfs(i, 1);
    }
    ll ans = 0;
    for (int i = 1; i <= n; i++) ans += lx[i] + ly[i];
}

```

```

    return ans;
}
};

```

3.5 ISAP Algorithm

```

struct Maxflow { //to be modified
    static const int MAXV = 20010;
    static const int INF = 1000000;
    struct Edge {
        int v, c, r;
        Edge(int _v, int _c, int _r)
            : v(_v), c(_c), r(_r) {}
    };
    int s, t;
    vector<Edge> G[MAXV * 2];
    int iter[MAXV * 2], d[MAXV * 2], gap[MAXV * 2], tot;
    void init(int x) {
        tot = x + 2;
        s = x + 1, t = x + 2;
        for (int i = 0; i <= tot; i++) {
            G[i].clear();
            iter[i] = d[i] = gap[i] = 0;
        }
    }
    void addEdge(int u, int v, int c) {
        G[u].push_back(Edge(v, c, SZ(G[v])));
        G[v].push_back(Edge(u, 0, SZ(G[u]) - 1));
    }
    int dfs(int p, int flow) {
        if (p == t) return flow;
        for (int &i = iter[p]; i < SZ(G[p]); i++) {
            Edge &e = G[p][i];
            if (e.c > 0 && d[p] == d[e.v] + 1) {
                int f = dfs(e.v, min(flow, e.c));
                if (f) {
                    e.c -= f;
                    G[e.v][e.r].c += f;
                    return f;
                }
            }
        }
        if (--gap[d[p]] == 0) d[s] = tot;
        else {
            d[p]++;
            iter[p] = 0;
            ++gap[d[p]];
        }
        return 0;
    }
    int solve() {
        int res = 0;
        gap[0] = tot;
        for (res = 0; d[s] < tot; res += dfs(s, INF))
            ;
        return res;
    }
} flow;

```

3.6 Bipartite Matching

```

//min vertex cover: take unmatched vertex in L and find
//alternating tree,
//ans is not reached in L + reached in R
// O(VE)
int n; //1-base, max matching
int mx[maxn], my[maxn];
bool adj[maxn][maxn], vis[maxn];
bool dfs(int u) {
    if (vis[u]) return 0;
    vis[u] = 1;
    for (int v = 1; v <= n; v++) {
        if (!adj[u][v]) continue;
        if (!my[v] || (my[v] && dfs(my[v]))) {
            mx[u] = v, my[v] = u;

```

```

        return 1;
    }
}
return 0;
}
// O(E sqrt(V)), O(E log V) for random sparse graphs
struct Bipartite_Matching { // 0-base
    int l, r;
    int mp[maxn], mq[maxn];
    int dis[maxn], cur[maxn];
    vector<int> G[maxn];
    bool dfs(int u) {
        for (int &i = cur[u]; i < SZ(G[u]); ++i) {
            int e = G[u][i];
            if (!mq[e] || (dis[mq[e]] == dis[u] + 1 && dfs(mq[e])))
                return mp[mq[e] = u] = e, 1;
        }
        dis[u] = -1;
        return 0;
    }
    bool bfs() {
        int rt = 0;
        queue<int> q;
        fill_n(dis, l, -1);
        for (int i = 0; i < l; ++i)
            if (!mp[i])
                q.push(i), dis[i] = 0;
        while (!q.empty()) {
            int u = q.front();
            q.pop();
            for (int e : G[u])
                if (!mq[e])
                    rt = 1;
                else if (!dis[mq[e]]) {
                    q.push(mq[e]);
                    dis[mq[e]] = dis[u] + 1;
                }
        }
        return rt;
    }
    int matching() {
        int rt = 0;
        fill_n(mp, l, -1);
        fill_n(mq, r, -1);
        while (bfs()) {
            fill_n(cur, l, 0);
            for (int i = 0; i < l; ++i)
                if (!mp[i] && dfs(i))
                    ++rt;
        }
        return rt;
    }
    void add_edge(int s, int t) {
        G[s].pb(t);
    }
    void init(int _l, int _r) {
        l = _l, r = _r;
        for (int i = 0; i < l; ++i)
            G[i].clear();
    }
} match;

```

3.7 Max Simple Graph Matching

```

struct GenMatch { // 1-base
    int V, pr[N];
    bool el[N][N], inq[N], inp[N], inb[N];
    int st, ed, nb, bk[N], djs[N], ans;
    void init(int _V) {
        V = _V;
        for (int i = 0; i <= V; ++i) {
            for (int j = 0; j <= V; ++j) el[i][j] = 0;
            pr[i] = bk[i] = djs[i] = 0;
            inq[i] = inp[i] = inb[i] = 0;
        }
    }

```

```

}
void add_edge(int u, int v) {
    el[u][v] = el[v][u] = 1;
}
int lca(int u, int v) {
    fill_n(inp, V + 1, 0);
    while (1)
        if (u = djs[u], inp[u] = true, u == st) break;
        else u = bk[pr[u]];
    while (1)
        if (v = djs[v], inp[v]) return v;
        else v = bk[pr[v]];
    return v;
}
void upd(int u) {
    for (int v; djs[u] != nb;) {
        v = pr[u], inb[djs[u]] = inb[djs[v]] = true;
        u = bk[v];
        if (djs[u] != nb) bk[u] = v;
    }
}
void blo(int u, int v, queue<int> &qe) {
    nb = lca(u, v), fill_n(inb, V + 1, 0);
    upd(u), upd(v);
    if (djs[u] != nb) bk[u] = v;
    if (djs[v] != nb) bk[v] = u;
    for (int tu = 1; tu <= V; ++tu)
        if (inb[djs[tu]])
            if (djs[tu] = nb, !inq[tu])
                qe.push(tu), inq[tu] = 1;
}
void flow() {
    fill_n(inq + 1, V, 0), fill_n(bk + 1, V, 0);
    iota(djs + 1, djs + V + 1, 1);
    queue<int> qe;
    qe.push(st), inq[st] = 1, ed = 0;
    while (!qe.empty()) {
        int u = qe.front();
        qe.pop();
        for (int v = 1; v <= V; ++v)
            if (el[u][v] && djs[u] != djs[v] &&
                pr[u] != v) {
                if ((v == st) ||
                    (pr[v] > 0 && bk[pr[v]] > 0)) {
                    blo(u, v, qe);
                } else if (!bk[v]) {
                    if (bk[v] = u, pr[v] > 0) {
                        if (!inq[pr[v]]) qe.push(pr[v]);
                    } else {
                        return ed = v, void();
                    }
                }
            }
    }
}
void aug() {
    for (int u = ed, v, w; u > 0;)
        v = bk[u], w = pr[v], pr[v] = u, pr[u] = v,
        u = w;
}
int solve() {
    fill_n(pr, V + 1, 0), ans = 0;
    for (int u = 1; u <= V; ++u)
        if (!pr[u])
            if (st = u, flow(), ed > 0) aug(), ++ans;
    return ans;
}
};

```

3.8 MCMF

```

struct MCMF { // 0-base
    struct edge {
        ll from, to, cap, flow, cost, rev;
    } * past[maxn];
    vector<edge> G[maxn];

```

```

    bitset<maxn> inq;
    ll dis[maxn], up[maxn], s, t, mx, n;
    bool BellmanFord(ll &flow, ll &cost) {
        fill(dis, dis + n, inf);
        queue<ll> q;
        q.push(s), inq.reset(), inq[s] = 1;
        up[s] = mx - flow, past[s] = 0, dis[s] = 0;
        while (!q.empty()) {
            ll u = q.front();
            q.pop(), inq[u] = 0;
            if (!up[u]) continue;
            for (auto &e : G[u])
                if (e.flow != e.cap &&
                    dis[e.to] > dis[u] + e.cost) {
                    dis[e.to] = dis[u] + e.cost, past[e.to] = &e;
                    up[e.to] = min(up[u], e.cap - e.flow);
                    if (!inq[e.to]) inq[e.to] = 1, q.push(e.to);
                }
        }
        if (dis[t] == inf) return 0;
        flow += up[t], cost += up[t] * dis[t];
        for (ll i = t; past[i]; i = past[i]->from) {
            auto &e = *past[i];
            e.flow += up[t], G[e.to][e.rev].flow -= up[t];
        }
        return 1;
    }
    ll MinCostMaxFlow(ll _s, ll _t, ll &cost) {
        s = _s, t = _t, cost = 0;
        ll flow = 0;
        while (BellmanFord(flow, cost));
        return flow;
    }
    void init(ll _n, ll _mx) {
        n = _n, mx = _mx;
        for (int i = 0; i < n; ++i) G[i].clear();
    }
    void add_edge(ll a, ll b, ll cap, ll cost) {
        G[a].pb(edge{a, b, cap, 0, cost, G[b].size()});
        G[b].pb(edge{b, a, 0, 0, -cost, G[a].size() - 1});
    }
};

```

3.9 Min Cost Circulation

```

//to be modified
struct Edge { int to, cap, rev, cost; };
vector<Edge> g[kN];
int dist[kN], pv[kN], ed[kN];
bool mark[kN];
int NegativeCycle(int n) {
    memset(mark, false, sizeof(mark));
    memset(dist, 0, sizeof(dist));
    int upd = -1;
    for (int i = 0; i <= n; ++i) {
        for (int j = 0; j < n; ++j) {
            int idx = 0;
            for (auto &e : g[j]) {
                if (e.cap > 0 && dist[e.to] > dist[j] + e.cost) {
                    dist[e.to] = dist[j] + e.cost;
                    pv[e.to] = j, ed[e.to] = idx;
                    if (i == n) {
                        upd = j;
                        while (!mark[upd]) mark[upd] = true, upd = pv[upd];
                        return upd;
                    }
                }
            }
            idx++;
        }
    }
    return -1;
}
int Solve(int n) {
    int rt = -1, ans = 0;

```

```

while ((rt = NegativeCycle(n)) >= 0) {
    memset(mark, false, sizeof(mark));
    vector<pair<int, int>> cyc;
    while (!mark[rt]) {
        cyc.emplace_back(pv[rt], ed[rt]);
        mark[rt] = true;
        rt = pv[rt];
    }
    reverse(cyc.begin(), cyc.end());
    int cap = kInf;
    for (auto &i : cyc) {
        auto &e = g[i.first][i.second];
        cap = min(cap, e.cap);
    }
    for (auto &i : cyc) {
        auto &e = g[i.first][i.second];
        e.cap -= cap;
        g[e.to][e.rev].cap += cap;
        ans += e.cost * cap;
    }
}
return ans;
}

```

3.10 SW Mincut

```

// stoer wagner algorithm: global min cut
const int maxn = 505;
struct SW { // O(V^3) 0-based
    int n, vis[maxn], del[maxn];
    int edge[maxn][maxn], wei[maxn];
    void init(int _n) {
        n = _n;
        fill(del, del+n, 0);
        for (int i = 0; i < n; i++) fill(edge[i], edge[i] + n, 0);
    }
    void addEdge(int u, int v, int w) {
        edge[u][v] += w, edge[v][u] += w;
    }
    void search(int &s, int &t) {
        fill(vis, vis+n, 0);
        fill(wei, wei+n, 0);
        s = t = -1;
        while (1) {
            int ma = -1, cur = 0;
            for (int i = 0; i < n; ++i)
                if (!del[i] && !vis[i] && ma < wei[i])
                    cur = i, ma = wei[i];
            if (mx == -1) break;
            vis[cur] = 1, s = t, t = cur;
            for (int i = 0; i < n; ++i)
                if (!vis[i] && !del[i]) wei[i] += edge[cur][i];
        }
    }
    int solve() {
        int ret = INF;
        for (int i = 0, x=0, y=0; i < n-1; ++i) {
            search(x, y), ret = min(res, wei[y]), del[y] = 1;
            for (int j = 0; j < n; ++j)
                edge[x][j] = (edge[j][x] += edge[y][j]);
        }
        return ret;
    }
};

```

3.11 Stable Marriage

- 1: Initialize $m \in M$ and $w \in W$ to free
- 2: **while** \exists free man m who has a woman w to propose to **do**
- 3: $w \leftarrow$ first woman on m 's list to whom m has not yet proposed
- 4: **if** \exists some pair (m', w) **then**
- 5: **if** w prefers m to m' **then**
- 6: $m' \leftarrow$ free
- 7: $(m, w) \leftarrow$ engaged

```

8:         end if
9:     else
10:          $(m, w) \leftarrow$  engaged
11:     end if
12: end while

```

4 Geometry

4.1 Geometry Template

```

using ld = ll;
using pdd = pair<ld, ld>;
using Line = pair<pdd, pdd>;
#define X first
#define Y second
// ld eps = 1e-7;

pdd operator+(pdd a, pdd b)
{ return {a.X + b.X, a.Y + b.Y}; }
pdd operator-(pdd a, pdd b)
{ return {a.X - b.X, a.Y - b.Y}; }
pdd operator*(ld i, pdd v)
{ return {i * v.X, i * v.Y}; }
pdd operator*(pdd v, ld i)
{ return {i * v.X, i * v.Y}; }
pdd operator/(pdd v, ld i)
{ return {v.X / i, v.Y / i}; }
ld dot(pdd a, pdd b)
{ return a.X * b.X + a.Y * b.Y; }
ld cross(pdd a, pdd b)
{ return a.X * b.Y - a.Y * b.X; }
ld abs2(pdd v)
{ return v.X * v.X + v.Y * v.Y; }
ld abs(pdd v)
{ return sqrt(abs2(v)); }
int sgn(ld v)
{ return v > 0 ? 1 : (v < 0 ? -1 : 0); }
// int sgn(ld v){ return v > eps ? 1 : ( v < -eps ? -1 : 0)
// ; }

int ori(pdd a, pdd b, pdd c)
{ return sgn(cross(b - a, c - a)); }
bool collinearity(pdd a, pdd b, pdd c)
{ return ori(a, b, c) == 0; }
bool btw(pdd p, pdd a, pdd b)
{ return collinearity(p, a, b) && sgn(dot(a - p, b - p)) <= 0; }

bool seg_intersect(Line a, Line b){
    pdd p1, p2, p3, p4;
    tie(p1, p2) = a; tie(p3, p4) = b;
    if(btw(p1, p3, p4) || btw(p2, p3, p4) || btw(p3, p1, p2)
        || btw(p4, p1, p2))
        return true;
    return ori(p1, p2, p3) * ori(p1, p2, p4) < 0 &&
        ori(p3, p4, p1) * ori(p3, p4, p2) < 0;
}

pdd intersect(Line a, Line b){
    pdd p1, p2, p3, p4;
    tie(p1, p2) = a; tie(p3, p4) = b;
    ld a123 = cross(p2 - p1, p3 - p1);
    ld a124 = cross(p2 - p1, p4 - p1);
    return (p4 * a123 - p3 * a124) / (a123 - a124);
}

pdd perp(pdd p1)
{ return pdd(-p1.Y, p1.X); }
pdd projection(pdd p1, pdd p2, pdd p3)
{ return p1 + (p2 - p1) * dot(p3 - p1, p2 - p1) / abs2(p2 - p1); }
pdd reflection(pdd p1, pdd p2, pdd p3)
{ return p3 + perp(p2 - p1) * cross(p3 - p1, p2 - p1) / abs2(p2 - p1) * 2; }
pdd linearTransformation(pdd p0, pdd p1, pdd q0, pdd q1, pdd r) {
    pdd dp = p1 - p0, dq = q1 - q0, num(cross(dp, dq), dot(dp, dq));
}

```



```

    return q0 + pdd(cross(r - p0, num), dot(r - p0, num)) /
        abs2(dp);
} // from line p0--p1 to q0--q1, apply to r

```

4.2 Convex Hull

```

vector<int> getConvexHull(vector<pdd>& pts){
    vector<int> id(SZ(pts));
    iota(iter(id), 0);
    sort(iter(id), [&](int x, int y){ return pts[x] < pts[y];
    });
    vector<int> hull;
    for(int tt = 0; tt < 2; tt++){
        int sz = SZ(hull);
        for(int j : id){
            pdd p = pts[j];
            while(SZ(hull) - sz >= 2 &&
                cross(pts[hull.back()] - pts[hull[SZ(hull) - 2]],
                    p - pts[hull[SZ(hull) - 2]]) <= 0)
                hull.pop_back();
            hull.pb(j);
        }
        hull.pop_back();
        reverse(iter(id));
    }
    return hull;
}

```

4.3 Minimum Enclosing Circle

```

using ld = long double;
pair<pdd, ld> circumcenter(pdd a, pdd b, pdd c);
pair<pdd, ld> MinimumEnclosingCircle(vector<pdd> &pts){
    random_shuffle(iter(pts));
    pdd c = pts[0];
    ld r = 0;
    for(int i = 1; i < SZ(pts); i++){
        if(abs(pts[i] - c) <= r) continue;
        c = pts[i]; r = 0;
        for(int j = 0; j < i; j++){
            if(abs(pts[j] - c) <= r) continue;
            c = (pts[i] + pts[j]) / 2;
            r = abs(pts[i] - c);
            for(int k = 0; k < j; k++){
                if(abs(pts[k] - c) > r)
                    tie(c, r) = circumcenter(pts[i], pts[j], pts[k]);
            }
        }
    }
    return {c, r};
}

```

4.4 Minkowski Sum

```

void reorder_poly(vector<pdd>& pnts){
    int mn = 0;
    for(int i = 1; i < (int)pnts.size(); i++)
        if(pnts[i].Y < pnts[mn].Y || (pnts[i].Y == pnts[mn].Y
            && pnts[i].X < pnts[mn].X))
            mn = i;
    rotate(pnts.begin(), pnts.begin() + mn, pnts.end());
}

```

```

vector<pdd> minkowski(vector<pdd> P, vector<pdd> Q){
    reorder_poly(P);
    reorder_poly(Q);
    int psz = P.size();
    int qsz = Q.size();
    P.pb(P[0]); P.pb(P[1]); Q.pb(Q[0]); Q.pb(Q[1]);
    vector<pdd> ans;
    int i = 0, j = 0;
    while(i < psz || j < qsz){
        ans.pb(P[i] + Q[j]);
    }
}

```

```

    int t = sgn(cross(P[i + 1] - P[i], Q[j + 1] - Q[j]));
    if(t >= 0) i++;
    if(t <= 0) j++;
}
return ans;
}

```

4.5 Polar Angle Comparator

```

// -1: a // b (if same), 0/1: a < b
int cmp(pll a, pll b, bool same = true){
#define is_neg(k) (sgn(k.Y) < 0 || (sgn(k.Y) == 0 && sgn(k.X) < 0))
    int A = is_neg(a), B = is_neg(b);
    if(A != B)
        return A < B;
    if(sgn(cross(a, b)) == 0)
        return same ? abs2(a) < abs2(b) : -1;
    return sgn(cross(a, b)) > 0;
}

```

4.6 Half Plane Intersection

```

// from 8BQube
pll area_pair(Line a, Line b)
{ return pll(cross(a.Y - a.X, b.X - a.X), cross(a.Y - a.X,
    b.Y - a.X)); }
bool isin(Line l0, Line l1, Line l2) {
    // Check inter(l1, l2) strictly in l0
    auto [a02X, a02Y] = area_pair(l0, l2);
    auto [a12X, a12Y] = area_pair(l1, l2);
    if (a12X - a12Y < 0) a12X *= -1, a12Y *= -1;
    return (__int128) a02Y * a12X - (__int128) a02X * a12Y >
        0; // C^4
}
/* Having solution, check size > 2 */
/* --^-- Line.X --^-- Line.Y --^-- */
vector<Line> halfPlaneInter(vector<Line> arr) {
    sort(iter(arr), [&](Line a, Line b) -> int {
        if (cmp(a.Y - a.X, b.Y - b.X, 0) != -1)
            return cmp(a.Y - a.X, b.Y - b.X, 0);
        return ori(a.X, a.Y, b.Y) < 0;
    });
    deque<Line> dq(1, arr[0]);
    for (auto p : arr) {
        if (cmp(dq.back().Y - dq.back().X, p.Y - p.X, 0) == -1)
            continue;
        while (SZ(dq) >= 2 && !isin(p, dq[SZ(dq) - 2], dq.back()))
            dq.pop_back();
        while (SZ(dq) >= 2 && !isin(p, dq[0], dq[1]))
            dq.pop_front();
        dq.pb(p);
    }
    while (SZ(dq) >= 3 && !isin(dq[0], dq[SZ(dq) - 2], dq.back()))
        dq.pop_back();
    while (SZ(dq) >= 3 && !isin(dq.back(), dq[0], dq[1]))
        dq.pop_front();
    return vector<Line>(iter(dq));
}

```

4.7 Dynamic Convex Hull

```

struct Line{
    ll a, b, l = MIN, r = MAX;
    Line(ll a, ll b): a(a), b(b) {}
    ll operator()(ll x) const{
        return a * x + b;
    }
    bool operator<(Line b) const{
        return a < b.a;
    }
}

```

```

    bool operator<(ll b) const{
        return r < b;
    }
};

ll ceil(ll a, ll b){
    if(b < 0) a *= -1, b *= -1;
    if(a > 0) return (a + b - 1) / b;
    else return a / b;
}

ll intersect(Line a, Line b){
    return ceil(a.b - b.b, b.a - a.a);
}

struct DynamicConvexHull{
    multiset<Line, less<>> ch;

    void add(Line ln){
        auto it = ch.lower_bound(ln);
        while(it != ch.end()){
            Line tl = *it;
            if(tl(tl.r) <= ln(tl.l)){
                it = ch.erase(it);
            }
            else break;
        }
        auto it2 = ch.lower_bound(ln);
        while(it2 != ch.begin()){
            Line tl = *prev(it2);
            if(tl(tl.l) <= ln(tl.l)){
                it2 = ch.erase(prev(it2));
            }
            else break;
        }
        it = ch.lower_bound(ln);
        if(it != ch.end()){
            Line tl = *it;
            if(tl(tl.l) >= ln(tl.l)) ln.r = tl.l - 1;
            else{
                ll pos = intersect(ln, tl);
                tl.l = pos;
                ln.r = pos - 1;
                ch.erase(it);
                ch.insert(tl);
            }
        }
        it2 = ch.lower_bound(ln);
        if(it2 != ch.begin()){
            Line tl = *prev(it2);
            if(tl(tl.r) >= ln(tl.r)) ln.l = tl.r + 1;
            else{
                ll pos = intersect(tl, ln);
                tl.r = pos - 1;
                ln.l = pos;
                ch.erase(prev(it2));
                ch.insert(tl);
            }
        }
        if(ln.l <= ln.r) ch.insert(ln);
    }

    ll query(ll pos){
        auto it = ch.lower_bound(pos);
        if(it == ch.end()) return 0;
        return (*it)(pos);
    }
};

```

4.8 3D Point

// Copy from 8BQube

```

struct Point {
    double x, y, z;
    Point(double _x = 0, double _y = 0, double _z = 0): x(_x)
        , y(_y), z(_z){}

```

```

    Point(pdd p) { x = p.X, y = p.Y, z = abs2(p); }
};

Point operator-(Point p1, Point p2)
{ return Point(p1.x - p2.x, p1.y - p2.y, p1.z - p2.z); }
Point operator+(Point p1, Point p2)
{ return Point(p1.x + p2.x, p1.y + p2.y, p1.z + p2.z); }
Point operator*(Point p1, double v)
{ return Point(p1.x * v, p1.y * v, p1.z * v); }
Point operator/(Point p1, double v)
{ return Point(p1.x / v, p1.y / v, p1.z / v); }
Point cross(Point p1, Point p2)
{ return Point(p1.y * p2.z - p1.z * p2.y, p1.z * p2.x - p1.
    x * p2.z, p1.x * p2.y - p1.y * p2.x); }
double dot(Point p1, Point p2)
{ return p1.x * p2.x + p1.y * p2.y + p1.z * p2.z; }
double abs(Point a)
{ return sqrt(dot(a, a)); }
Point cross3(Point a, Point b, Point c)
{ return cross(b - a, c - a); }
double area(Point a, Point b, Point c)
{ return abs(cross3(a, b, c)); }
double volume(Point a, Point b, Point c, Point d)
{ return dot(cross3(a, b, c), d - a); }
//Azimuthal angle (Longitude) to x-axis in interval [-pi,
    pi]
double phi(Point p) { return atan2(p.y, p.x); }
//Zenith angle (Latitude) to the z-axis in interval [0, pi]
double theta(Point p) { return atan2(sqrt(p.x * p.x + p.y *
    p.y), p.z); }
Point masscenter(Point a, Point b, Point c, Point d)
{ return (a + b + c + d) / 4; }
pdd proj(Point a, Point b, Point c, Point u) {
    // proj. u to the plane of a, b, and c
    Point e1 = b - a;
    Point e2 = c - a;
    e1 = e1 / abs(e1);
    e2 = e2 - e1 * dot(e2, e1);
    e2 = e2 / abs(e2);
    Point p = u - a;
    return pdd(dot(p, e1), dot(p, e2));
}
Point rotate_around(Point p, double angle, Point axis) {
    double s = sin(angle), c = cos(angle);
    Point u = axis / abs(axis);
    return u * dot(u, p) * (1 - c) + p * c + cross(u, p) * s;
}

```

4.9 ConvexHull3D

```

struct convex_hull_3D {
    struct Face {
        int a, b, c;
        Face(int ta, int tb, int tc): a(ta), b(tb), c(tc) {}
    }; // return the faces with pt indexes
    vector<Face> res;
    vector<Point> P;
    convex_hull_3D(const vector<Point> &_P): res(), P(_P) {
        // all points coplanar case will WA, O(n^2)
        int n = SZ(P);
        if (n <= 2) return; // be careful about edge case
        // ensure first 4 points are not coplanar
        swap(P[1], *find_if(iter(P), [&](auto p) { return sgn(
            abs2(P[0] - p)) != 0; }));
        swap(P[2], *find_if(iter(P), [&](auto p) { return sgn(
            abs2(cross3(p, P[0], P[1])) != 0; }));
        swap(P[3], *find_if(iter(P), [&](auto p) { return sgn(
            volume(P[0], P[1], P[2], p)) != 0; }));
        vector<vector<int>> flag(n, vector<int>(n));
        res.emplace_back(0, 1, 2); res.emplace_back(2, 1, 0);
        for (int i = 3; i < n; ++i) {
            vector<Face> next;
            for (auto f : res) {
                int d = sgn(volume(P[f.a], P[f.b], P[f.c], P[i]));
                if (d <= 0) next.pb(f);
                int ff = (d > 0) - (d < 0);
            }

```

```

    flag[f.a][f.b] = flag[f.b][f.c] = flag[f.c][f.a] = ff
    ;
}
for (auto f : res) {
    auto F = [&](int x, int y) {
        if (flag[x][y] > 0 && flag[y][x] <= 0)
            next.emplace_back(x, y, i);
    };
    F(f.a, f.b); F(f.b, f.c); F(f.c, f.a);
}
res = next;
}
}
bool same(Face s, Face t) {
    if (sgn(volume(P[s.a], P[s.b], P[s.c], P[t.a])) != 0)
        return 0;
    if (sgn(volume(P[s.a], P[s.b], P[s.c], P[t.b])) != 0)
        return 0;
    if (sgn(volume(P[s.a], P[s.b], P[s.c], P[t.c])) != 0)
        return 0;
    return 1;
}
int polygon_face_num() {
    int ans = 0;
    for (int i = 0; i < SZ(res); ++i)
        ans += none_of(res.begin(), res.begin() + i, [&](Face g) {
            return same(res[i], g);
        });
    return ans;
}
double get_volume() {
    double ans = 0;
    for (auto f : res)
        ans += volume(Point(0, 0, 0), P[f.a], P[f.b], P[f.c]);
    return fabs(ans / 6);
}
double get_dis(Point p, Face f) {
    Point p1 = P[f.a], p2 = P[f.b], p3 = P[f.c];
    double a = (p2.y - p1.y) * (p3.z - p1.z) - (p2.z - p1.z)
        * (p3.y - p1.y);
    double b = (p2.z - p1.z) * (p3.x - p1.x) - (p2.x - p1.x)
        * (p3.z - p1.z);
    double c = (p2.x - p1.x) * (p3.y - p1.y) - (p2.y - p1.y)
        * (p3.x - p1.x);
    double d = 0 - (a * p1.x + b * p1.y + c * p1.z);
    return fabs(a * p.x + b * p.y + c * p.z + d) / sqrt(a * a
        + b * b + c * c);
}
};
// n^2 delaunay: facets with negative z normal of
// convexhull of (x, y, x^2 + y^2), use a pseudo-point
// (0, 0, inf) to avoid degenerate case

```

4.10 Circle Operations

```

// from 8BQube
const double PI=acos(-1);
vector<pdd> circleLineIntersection(pdd c, double r, pdd a,
    pdd b) {
    pdd p = a + (b - a) * dot(c - a, b - a) / abs2(b - a);
    double s = cross(b - a, c - a), h2 = r * r - s * s / abs2
        (b - a);
    if (sgn(h2) < 0) return {};
    if (sgn(h2) == 0) return {p};
    pdd h = (b - a) / abs(b - a) * sqrt(h2);
    return {p - h, p + h};
}
double _area(pdd pa, pdd pb, double r){
    if(abs(pa)<abs(pb)) swap(pa, pb);
    if(abs(pb)<eps) return 0;
    double S, h, theta;
    double a=abs(pb),b=abs(pa),c=abs(pb-pa);
    double cosB = dot(pb,pb-pa) / a / c, B = acos(cosB);
    double cosC = dot(pa,pb) / a / b, C = acos(cosC);
    if(a > r){
        S = (C/2)*r*r;
        h = a*b*sin(C)/c;
    }
    if (h < r && B < PI/2) S -= (acos(h/r)*r*r - h*sqrt(r*r
        -h*h));
}
else if(b > r){
    theta = PI - B - asin(sin(B)/r*a);
    S = .5*a*r*sin(theta) + (C-theta)/2*r*r;
}
else S = .5*sin(C)*a*b;
return S;
}
double areaPolyCircle(const vector<pdd> poly,const pdd &O,
    const double r){
    double S=0;
    for(int i=0;i<SZ(poly);++i)
        S+=_area(poly[i]-O,poly[(i+1)%SZ(poly)]-O,r)*ori(0,poly
            [i],poly[(i+1)%SZ(poly)]);
    return fabs(S);
}
bool CCinter(Cir &a, Cir &b, pdd &p1, pdd &p2) {
    pdd o1 = a.O, o2 = b.O;
    double r1 = a.R, r2 = b.R, d2 = abs2(o1 - o2), d = sqrt(
        d2);
    if(d < max(r1, r2) - min(r1, r2) || d > r1 + r2) return
        0;
    pdd u = (o1 + o2) * 0.5 + (o1 - o2) * ((r2 * r2 - r1 * r1
        ) / (2 * d2));
    double A = sqrt((r1 + r2 + d) * (r1 - r2 + d) * (r1 + r2
        - d) * (-r1 + r2 + d));
    pdd v = pdd(o1.Y - o2.Y, -o1.X + o2.X) * A / (2 * d2);
    p1 = u + v, p2 = u - v;
    return 1;
}
vector<Line> CCTang( const Cir& c1 , const Cir& c2 , int
    sign1 ){
    vector<Line> ret;
    double d_sq = abs2( c1.O - c2.O );
    if (sgn(d_sq) == 0) return ret;
    double d = sqrt(d_sq);
    pdd v = (c2.O - c1.O) / d;
    double c = (c1.R - sign1 * c2.R) / d; // cos t
    if (c * c > 1) return ret;
    double h = sqrt(max( 0.0, 1.0 - c * c)); // sin t
    for (int sign2 = 1; sign2 >= -1; sign2 -= 2) {
        pdd n = pdd(v.X * c - sign2 * h * v.Y,
            v.Y * c + sign2 * h * v.X);
        pdd p1 = c1.O + n * c1.R;
        pdd p2 = c2.O + n * (c2.R * sign1);
        if (sgn(p1.X - p2.X) == 0 and
            sgn(p1.Y - p2.Y) == 0)
            p2 = p1 + perp(c2.O - c1.O);
        ret.pb(Line(p1, p2));
    }
    return ret;
}

```

```

    if (h < r && B < PI/2) S -= (acos(h/r)*r*r - h*sqrt(r*r
        -h*h));
}
else if(b > r){
    theta = PI - B - asin(sin(B)/r*a);
    S = .5*a*r*sin(theta) + (C-theta)/2*r*r;
}
else S = .5*sin(C)*a*b;
return S;
}
double areaPolyCircle(const vector<pdd> poly,const pdd &O,
    const double r){
    double S=0;
    for(int i=0;i<SZ(poly);++i)
        S+=_area(poly[i]-O,poly[(i+1)%SZ(poly)]-O,r)*ori(0,poly
            [i],poly[(i+1)%SZ(poly)]);
    return fabs(S);
}
bool CCinter(Cir &a, Cir &b, pdd &p1, pdd &p2) {
    pdd o1 = a.O, o2 = b.O;
    double r1 = a.R, r2 = b.R, d2 = abs2(o1 - o2), d = sqrt(
        d2);
    if(d < max(r1, r2) - min(r1, r2) || d > r1 + r2) return
        0;
    pdd u = (o1 + o2) * 0.5 + (o1 - o2) * ((r2 * r2 - r1 * r1
        ) / (2 * d2));
    double A = sqrt((r1 + r2 + d) * (r1 - r2 + d) * (r1 + r2
        - d) * (-r1 + r2 + d));
    pdd v = pdd(o1.Y - o2.Y, -o1.X + o2.X) * A / (2 * d2);
    p1 = u + v, p2 = u - v;
    return 1;
}
vector<Line> CCTang( const Cir& c1 , const Cir& c2 , int
    sign1 ){
    vector<Line> ret;
    double d_sq = abs2( c1.O - c2.O );
    if (sgn(d_sq) == 0) return ret;
    double d = sqrt(d_sq);
    pdd v = (c2.O - c1.O) / d;
    double c = (c1.R - sign1 * c2.R) / d; // cos t
    if (c * c > 1) return ret;
    double h = sqrt(max( 0.0, 1.0 - c * c)); // sin t
    for (int sign2 = 1; sign2 >= -1; sign2 -= 2) {
        pdd n = pdd(v.X * c - sign2 * h * v.Y,
            v.Y * c + sign2 * h * v.X);
        pdd p1 = c1.O + n * c1.R;
        pdd p2 = c2.O + n * (c2.R * sign1);
        if (sgn(p1.X - p2.X) == 0 and
            sgn(p1.Y - p2.Y) == 0)
            p2 = p1 + perp(c2.O - c1.O);
        ret.pb(Line(p1, p2));
    }
    return ret;
}
}

```

4.11 Delaunay Triangulation

```

/* Delaunay Triangulation:
Given a sets of points on 2D plane, find a
triangulation such that no points will strictly
inside circumcircle of any triangle. */
struct Edge {
    int id; // oidx[id]
    list<Edge>::iterator twin;
    Edge(int _id = 0):id(_id) {}
};
struct Delaunay { // 0-base
    int n, oidx[N];
    list<Edge> head[N]; // result udir. graph
    p11 p[N];
    void init(int _n, p11 _p[]) {
        n = _n, iota(oidx, oidx + n, 0);
        for (int i = 0; i < n; ++i) head[i].clear();
        sort(oidx, oidx + n, [&](int a, int b)
            { return _p[a] < _p[b]; });
        for (int i = 0; i < n; ++i) p[i] = _p[oidx[i]];
    }
}

```

```

    divide(0, n - 1);
}
void addEdge(int u, int v) {
    head[u].push_front(Edge(v));
    head[v].push_front(Edge(u));
    head[u].begin()->twin = head[v].begin();
    head[v].begin()->twin = head[u].begin();
}
void divide(int l, int r) {
    if (l == r) return;
    if (l + 1 == r) return addEdge(l, l + 1);
    int mid = (l + r) >> 1, nw[2] = {l, r};
    divide(l, mid), divide(mid + 1, r);
    auto gao = [&](int t) {
        pll pt[2] = {p[nw[0]], p[nw[1]]};
        for (auto it : head[nw[t]]) {
            int v = ori(pt[1], pt[0], p[it.id]);
            if (v > 0 || (v == 0 && abs2(pt[t ^ 1] - p[it.id])
                < abs2(pt[1] - pt[0])))
                return nw[t] = it.id, true;
        }
        return false;
    };
    while (gao(0) || gao(1));
    addEdge(nw[0], nw[1]); // add tangent
    while (true) {
        pll pt[2] = {p[nw[0]], p[nw[1]]};
        int ch = -1, sd = 0;
        for (int t = 0; t < 2; ++t)
            for (auto it : head[nw[t]])
                if (ori(pt[0], pt[1], p[it.id]) > 0 && (ch ==
                    -1 || in_cc({pt[0], pt[1], p[ch]}, p[it.
                        id])))
                    ch = it.id, sd = t;
        if (ch == -1) break; // upper common tangent
        for (auto it = head[nw[sd]].begin(); it != head[nw[sd]
            ].end(); )
            if (seg_strict_intersect(pt[sd], p[it->id], pt[sd ^
                1], p[ch]))
                head[it->id].erase(it->twin), head[nw[sd]].erase(
                    it++);
            else ++it;
        nw[sd] = ch, addEdge(nw[0], nw[1]);
    }
}
} tool;

```

4.12 Voronoi Diagram

// all coord. is even, you may want to call halfPlaneInter
after then

```

vector<vector<Line>> vec;
void build_voronoi_line(int n, pll *arr) {
    tool.init(n, arr); // Delaunay
    vec.clear(), vec.resize(n);
    for (int i = 0; i < n; ++i)
        for (auto e : tool.head[i]) {
            int u = tool.oidx[i], v = tool.oidx[e.id];
            pll m = (arr[v] + arr[u]) / 2LL, d = perp(arr[v] -
                arr[u]);
            vec[u].pb(Line(m, m + d));
        }
}

```

4.13 Polygon Union

```

// from 8BQube
ld rat(pll a, pll b) {
    return sgn(b.X) ? (ld)a.X / b.X : (ld)a.Y / b.Y;
} // all poly. should be cconv
ld polyUnion(vector<vector<pll>> &poly) {
    ld res = 0;
    for (auto &p : poly)
        for (int a = 0; a < SZ(p); ++a) {
            pll A = p[a], B = p[(a + 1) % SZ(p)];

```

```

        vector<pair<ld, int>> segs = {{0, 0}, {1, 0}};
        for (auto &q : poly) {
            if (&p == &q) continue;
            for (int b = 0; b < SZ(q); ++b) {
                pll C = q[b], D = q[(b + 1) % SZ(q)];
                int sc = ori(A, B, C), sd = ori(A, B, D);
                if (sc != sd && min(sc, sd) < 0) {
                    ld sa = cross(D - C, A - C), sb = cross(D - C,
                        B - C);
                    segs.pb(sa / (sa - sb), sgn(sc - sd));
                }
                if (!sc && !sd && &q < &p && sgn(dot(B - A, D - C
                    )) > 0) {
                    segs.pb(rat(C - A, B - A), 1);
                    segs.pb(rat(D - A, B - A), -1);
                }
            }
        }
        sort(iter(segs));
        for (auto &s : segs) s.X = clamp(s.X, 0.0, 1.0);
        ld sum = 0;
        int cnt = segs[0].second;
        for (int j = 1; j < SZ(segs); ++j) {
            if (!cnt) sum += segs[j].X - segs[j - 1].X;
            cnt += segs[j].Y;
        }
        res += cross(A, B) * sum;
    }
    return res / 2;
}

```

4.14 Tangent Point to Convex Hull

```

// from 8BQube
/* The point should be strictly out of hull
   return arbitrary point on the tangent line */
pii get_tangent(vector<pll> &C, pll p) {
    auto gao = [&](int s) {
        return cyc_tsearch(SZ(C), [&](int x, int y)
            { return ori(p, C[x], C[y]) == s; });
    };
    return pii(gao(1), gao(-1));
} // return (a, b), ori(p, C[a], C[b]) >= 0

```

5 Graph

5.1 Block Cut Tree

```

struct BCC{
    vector<int> v, e, cut;
};
struct BlockCutTree{ // 0-based, allow multi edges but not
    allow loops
    int n, m, cnt = 0;
    // n:|V|, m:|E|, cnt:|bcc|
    vector<BCC> bcc;
    vector<vector<pii>> g; // original graph
    vector<pii> edges; // 0-based
    vector<vector<int>> vbcc;
    // vbcc[i] = BCCs containing vertex i, vbcc[i].size()>1
    // iff i is an articulation
    vector<int> ebcc;
    // edge i is a bridge iff bcc[ebcc[i]].e.size() == 1
    // block cut tree:
    // adj[bcc i]: bcc[i].cut
    // adj[cut i]: vbcc[i]

```

```

    BlockCutTree(int _n, vector<pii> _edges):
        n(_n), m(SZ(_edges)), g(_n), edges(_edges), vbcc(_n),
        ebcc(SZ(_edges)){
        for(int i = 0; i < m; i++){
            auto [u, v] = edges[i];
            g[u].pb(pii(v, i)); g[v].pb(pii(u, i));
        }
    }

```

```

}

void build(){
    vector<int> in(n, -1), low(n, -1);
    vector<vector<int>> up(n);
    vector<int> stk;
    int ts = 0;
    auto _dfs = [&](auto dfs, int now, int par, int pe) ->
        void{
        if(pe != -1) up[now].pb(pe);
        in[now] = low[now] = ts++;
        stk.pb(now);
        for(auto [v, e] : g[now]){
            if(e == pe) continue;
            if(in[v] != -1){
                if(in[v] < in[now]) up[now].pb(e);
                low[now] = min(low[now], in[v]);
                continue;
            }
            dfs(dfs, v, now, e);
            low[now] = min(low[now], low[v]);
        }
        if((now != par && low[now] >= in[par]) || (now == par
            && SZ(g[now]) == 0)){
            bcc.pb();
            while(true){
                int v = stk.back();
                stk.pop_back();
                vbcc[v].pb(cnt);
                bcc[cnt].v.pb(v);
                for(int e : up[v]){
                    ebcc[e] = cnt;
                    bcc[cnt].e.pb(e);
                }
                if(v == now) break;
            }
            if(now != par){
                vbcc[par].pb(cnt);
                bcc[cnt].v.pb(par);
            }
            cnt++;
        }
    };
    for(int i = 0; i < n; i++){
        if(in[i] == -1) _dfs(_dfs, i, i, -1);
    }
    for(int i = 0; i < cnt; i++){
        for(int j : bcc[i].v)
            if(SZ(vbcc[j]) > 1) bcc[i].cut.pb(j);
    }
};

```

5.2 2-SAT

```

struct SAT{ // 0-based, [n, 2n) is neg of [0, n)
    int n;
    vector<vector<int>> g, rg;
    bool ok = true;
    vector<bool> ans;

    void init(int _n){
        n = _n;
        g.resize(2 * n);
        rg.resize(2 * n);
        ans.resize(n);
    }
    int neg(int v){
        return v < n ? v + n : v - n;
    }
    void addEdge(int u, int v){
        g[u].pb(v);
        rg[v].pb(u);
    }
    void addClause(int a, int b){
        addEdge(neg(a), b);
        addEdge(neg(b), a);
    }
};

```

```

}
void build(){
    vector<bool> vst(2 * n, false);
    vector<int> tmp, scc(2 * n, -1);
    int cnt = 1;
    function<void(int)> dfs = [&](int now){
        vst[now] = true;
        for(int i : rg[now]){
            if(vst[i]) continue;
            dfs(i);
        }
        tmp.pb(now);
    };
    for(int i = 0; i < 2 * n; i++){
        if(!vst[i]) dfs(i);
    }
    reverse(all(tmp));
    function<void(int, int)> dfs2 = [&](int now, int id){
        scc[now] = id;
        for(int i : g[now]){
            if(scc[i] != -1) continue;
            dfs2(i, id);
        }
    };
    for(int i : tmp){
        if(scc[i] == -1) dfs2(i, cnt++);
    }
    debug(scc);
    for(int i = 0; i < n; i++){
        if(scc[i] == scc[neg(i)]){
            ok = false;
            return;
        }
        if(scc[i] < scc[neg(i)]) ans[i] = true;
        else ans[i] = false;
    }
};

```

5.3 Dominator Tree

```

// copy from 8BQube
struct dominator_tree { // 1-based
    vector<int> G[N], rG[N];
    int n, pa[N], dfn[N], id[N], Time;
    int semi[N], idom[N], best[N];
    vector<int> tree[N]; // dominator_tree
    void init(int _n) {
        n = _n;
        for (int i = 1; i <= n; ++i)
            G[i].clear(), rG[i].clear();
    }
    void add_edge(int u, int v) {
        G[u].pb(v), rG[v].pb(u);
    }
    void dfs(int u) {
        id[dfn[u] = ++Time] = u;
        for (auto v : G[u])
            if (!dfn[v]) dfs(v), pa[dfn[v]] = dfn[u];
    }
    int find(int y, int x) {
        if (y <= x) return y;
        int tmp = find(pa[y], x);
        if (semi[best[y]] > semi[best[pa[y]]])
            best[y] = best[pa[y]];
        return pa[y] = tmp;
    }
    void tarjan(int root) {
        Time = 0;
        for (int i = 1; i <= n; ++i) {
            dfn[i] = idom[i] = 0;
            tree[i].clear();
            best[i] = semi[i] = i;
        }
        dfs(root);
    }
};

```

```

for (int i = Time; i > 1; --i) {
    int u = id[i];
    for (auto v : rG[u])
        if (v = dfn[v]) {
            find(v, i);
            semi[i] = min(semi[i], semi[best[v]]);
        }
    tree[semi[i]].pb(i);
    for (auto v : tree[pa[i]]) {
        find(v, pa[i]);
        idom[v] =
            semi[best[v]] == pa[i] ? pa[i] : best[v];
    }
    tree[pa[i]].clear();
}
for (int i = 2; i <= Time; ++i) {
    if (idom[i] != semi[i]) idom[i] = idom[idom[i]];
    tree[id[idom[i]]].pb(id[i]);
}
}
};

```

5.4 Virtual Tree

// copy from 8BQube

```

vector<int> vG[N];
int top, st[N];

```

```

void insert(int u) {
    if (top == -1) return st[++top] = u, void();
    int p = LCA(st[top], u);
    if (p == st[top]) return st[++top] = u, void();
    while (top >= 1 && dep[st[top - 1]] >= dep[p])
        vG[st[top - 1]].pb(st[top]), --top;
    if (st[top] != p)
        vG[p].pb(st[top]), --top, st[++top] = p;
    st[++top] = u;
}

```

```

void reset(int u) {
    for (int i : vG[u]) reset(i);
    vG[u].clear();
}

```

```

void solve(vector<int> &v) {
    top = -1;
    sort(ALL(v),
        [&](int a, int b) { return dfn[a] < dfn[b]; });
    for (int i : v) insert(i);
    while (top > 0) vG[st[top - 1]].pb(st[top]), --top;
    // do something
    reset(v[0]);
}

```

5.5 Directed Minimum Spanning Tree

```
const ll INF = LLONG_MAX;
```

```

struct edge{
    int u = -1, v = -1;
    ll w = INF;
    int id = -1;
};

```

// 0-based, E[i].id = i

```

bool DMST(int n, vector<edge> &E, int root, vector<edge> &
    sol){
    vector<int> id(n), vis(n);
    vector<edge> in(n);
    for(edge e : E)
        if(e.u != e.v && e.w < in[e.v].w && e.v != root)
            in[e.v] = e;
    for(int i = 0; i < n; i++)
        if(i != root && in[i].u == -1) return false; // no sol
    int cnt = 0;
    fill(iter(id), -1); fill(iter(vis), -1);

```

```

for(int u = 0; u < n; u++){
    int v = u;
    while(vis[v] != u && id[v] == -1 && in[v].u != -1)
        vis[v] = u, v = in[v].u;
    if(v != root && id[v] == -1){
        for(int x = in[v].u; x != v; x = in[x].u)
            id[x] = cnt;
        id[v] = cnt++;
    }
}
if(!cnt) return sol = in, true; // no cycle
for(int u = 0; u < n; u++)
    if(id[u] == -1) id[u] = cnt++;
vector<edge> nE;
for(int i = 0; i < SZ(E); i++){
    edge tmp = E[i];
    tmp.u = id[tmp.u], tmp.v = id[tmp.v];
    if(in[E[i].v].w != INF) tmp.w -= in[E[i].v].w;
    nE.pb(tmp);
}
vector<edge> tsol;
if(!DMST(cnt, nE, id[root], tsol)) return false;
sol.resize(n);
for(int i = 0; i < cnt; i++){
    if(i == id[root]) continue;
    int t = tsol[i].id;
    sol[E[t].v] = E[t];
}
for(int i = 0; i < n; i++)
    if(sol[i].id == -1) sol[i] = in[i];
return true;
}

```

5.6 Vizing

// find D+1 edge coloring of a graph with max deg D

```

struct vizing { // returns edge coloring in adjacent matrix
    G. 1 - based

```

```

    const int N = 105;
    int C[N][N], G[N][N], X[N], vst[N], n; // ans: G[i][j]
    void init(int _n) { n = _n; // n = |V|+1
        for (int i = 0; i <= n; ++i)
            for (int j = 0; j <= n; ++j)
                C[i][j] = G[i][j] = 0;
    }

```

```

    void solve(vector<pii> &E) {
        auto update = [&](int u) {
            for (X[u] = 1; C[u][X[u]]; ++X[u]);
        };
        auto color = [&](int u, int v, int c) {
            int p = G[u][v];
            G[u][v] = G[v][u] = c;
            C[u][c] = v, C[v][c] = u;
            C[u][p] = C[v][p] = 0;
            if (p) X[u] = X[v] = p;
            else update(u), update(v);
            return p;
        };
    }

```

```

    auto flip = [&](int u, int c1, int c2) {
        int p = C[u][c1];
        swap(C[u][c1], C[u][c2]);
        if (p) G[u][p] = G[p][u] = c2;
        if (!C[u][c1]) X[u] = c1;
        if (!C[u][c2]) X[u] = c2;
        return p;
    };

```

```

    fill_n(X + 1, n, 1);
    for (int t = 0; t < SZ(E); ++t) {
        int u = E[t].X, v0 = E[t].Y, v = v0, c0 = X[u], c =
            c0, d;
        vector<pii> L;
        fill_n(vst + 1, n, 0);
        while (!G[u][v0]) {
            L.emplace_back(v, d = X[v]);
            if (!C[v][c]) for (int a = SZ(L) - 1; a >= 0; --a)
                c = color(u, L[a].X, c);

```

```

    else if (!C[u][d]) for (int a = SZ(L) - 1; a >= 0;
        --a) color(u, L[a].X, L[a].Y);
    else if (vst[d]) break;
    else vst[d] = 1, v = C[u][d];
}
if (!G[u][v0]) {
    for (; v; v = flip(v, c, d), swap(c, d));
    if (int a; C[u][c0]) {
        for (a = SZ(L) - 2; a >= 0 && L[a].Y != c; --a);
        for (; a >= 0; --a) color(u, L[a].X, L[a].Y);
    }
    else --t;
}
}
}
};

```

5.7 Maximum Clique

```

struct MaxClique { // fast when N <= 100
    bitset<N> G[N], cs[N];
    int ans, sol[N], q, cur[N], d[N], n;
    void init(int _n) {
        n = _n;
        for (int i = 0; i < n; ++i) G[i].reset();
    }
    void add_edge(int u, int v) {
        G[u][v] = G[v][u] = 1;
    }
    void pre_dfs(vector<int> &r, int l, bitset<N> mask) {
        if (l < 4) {
            for (int i : r) d[i] = (G[i] & mask).count();
            sort(ALL(r), [&](int x, int y) { return d[x] > d[y]; });
        }
        vector<int> c(SZ(r));
        int lft = max(ans - q + 1, 1), rgt = 1, tp = 0;
        cs[1].reset(), cs[2].reset();
        for (int p : r) {
            int k = 1;
            while ((cs[k] & G[p]).any()) ++k;
            if (k > rgt) cs[++rgt + 1].reset();
            cs[k][p] = 1;
            if (k < lft) r[tp++] = p;
        }
        for (int k = lft; k <= rgt; ++k)
            for (int p = cs[k]._Find_first(); p < N; p = cs[k]._Find_next(p))
                r[tp] = p, c[tp] = k, ++tp;
        dfs(r, c, l + 1, mask);
    }
    void dfs(vector<int> &r, vector<int> &c, int l, bitset<N> mask) {
        while (!r.empty()) {
            int p = r.back();
            r.pop_back(), mask[p] = 0;
            if (q + c.back() <= ans) return;
            cur[q++] = p;
            vector<int> nr;
            for (int i : r) if (G[p][i]) nr.pb(i);
            if (!nr.empty()) pre_dfs(nr, l, mask & G[p]);
            else if (q > ans) ans = q, copy_n(cur, q, sol);
            c.pop_back(), --q;
        }
    }
    int solve() {
        vector<int> r(n);
        ans = q = 0, iota(ALL(r), 0);
        pre_dfs(r, 0, bitset<N>(string(n, '1')));
        return ans;
    }
};

```

5.8 Number of Maximal Clique

```

struct BronKerbosch { // 1-base
    int n, a[N], g[N][N];
    int S, all[N][N], some[N][N], none[N][N];
    void init(int _n) {
        n = _n;
        for (int i = 1; i <= n; ++i)
            for (int j = 1; j <= n; ++j) g[i][j] = 0;
    }
    void add_edge(int u, int v) {
        g[u][v] = g[v][u] = 1;
    }
    void dfs(int d, int an, int sn, int nn) {
        if (S > 1000) return; // pruning
        if (sn == 0 && nn == 0) ++S;
        int u = some[d][0];
        for (int i = 0; i < sn; ++i) {
            int v = some[d][i];
            if (g[u][v]) continue;
            int tsu = 0, tnn = 0;
            copy_n(all[d], an, all[d + 1]);
            all[d + 1][an] = v;
            for (int j = 0; j < sn; ++j)
                if (g[v][some[d][j]])
                    some[d + 1][tsu++] = some[d][j];
            for (int j = 0; j < nn; ++j)
                if (g[v][none[d][j]])
                    none[d + 1][tnn++] = none[d][j];
            dfs(d + 1, an + 1, tsu, tnn);
            some[d][i] = 0, none[d][nn++] = v;
        }
    }
    int solve() {
        iota(some[0], some[0] + n, 1);
        S = 0, dfs(0, 0, n, 0);
        return S;
    }
};

```

5.9 Minimum Mean Cycle

```

// from 8BQube
ll road[N][N]; // input here
struct MinimumMeanCycle {
    ll dp[N + 5][N], n;
    pll solve() {
        ll a = -1, b = -1, L = n + 1;
        for (int i = 2; i <= L; ++i)
            for (int k = 0; k < n; ++k)
                for (int j = 0; j < n; ++j)
                    dp[i][j] =
                        min(dp[i - 1][k] + road[k][j], dp[i][j]);
        for (int i = 0; i < n; ++i) {
            if (dp[L][i] >= INF) continue;
            ll ta = 0, tb = 1;
            for (int j = 1; j < n; ++j)
                if (dp[j][i] < INF &&
                    ta * (L - j) < (dp[L][i] - dp[j][i]) * tb)
                    ta = dp[L][i] - dp[j][i], tb = L - j;
            if (ta == 0) continue;
            if (a == -1 || a * tb > ta * b) a = ta, b = tb;
        }
        if (a != -1) {
            ll g = __gcd(a, b);
            return pll(a / g, b / g);
        }
        return pll(-1LL, -1LL);
    }
    void init(int _n) {
        n = _n;
        for (int i = 0; i < n; ++i)
            for (int j = 0; j < n; ++j) dp[i + 2][j] = INF;
    }
};

```

5.10 Minimum Steiner Tree

```
// from 8BQube
// O(V 3^T + V^2 2^T)
struct SteinerTree { // 0-base
    static const int T = 10, N = 105, INF = 1e9;
    int n, dst[N][N], dp[1 << T][N], tdst[N];
    int vcost[N]; // the cost of vertexs
    void init(int _n) {
        n = _n;
        for (int i = 0; i < n; ++i) {
            for (int j = 0; j < n; ++j) dst[i][j] = INF;
            dst[i][i] = vcost[i] = 0;
        }
    }
    void add_edge(int ui, int vi, int wi) {
        dst[ui][vi] = min(dst[ui][vi], wi);
    }
    void shortest_path() {
        for (int k = 0; k < n; ++k)
            for (int i = 0; i < n; ++i)
                for (int j = 0; j < n; ++j)
                    dst[i][j] =
                        min(dst[i][j], dst[i][k] + dst[k][j]);
    }
    int solve(const vector<int> &ter) {
        shortest_path();
        int t = SZ(ter);
        for (int i = 0; i < (1 << t); ++i)
            for (int j = 0; j < n; ++j) dp[i][j] = INF;
        for (int i = 0; i < n; ++i) dp[0][i] = vcost[i];
        for (int msk = 1; msk < (1 << t); ++msk) {
            if (!(msk & (msk - 1))) {
                int who = __lg(msk);
                for (int i = 0; i < n; ++i)
                    dp[msk][i] =
                        vcost[ter[who]] + dst[ter[who]][i];
            }
            for (int i = 0; i < n; ++i)
                for (int submsk = (msk - 1) & msk; submsk; submsk = (submsk - 1) & msk)
                    dp[msk][i] = min(dp[msk][i],
                        dp[submsk][i] + dp[msk ^ submsk][i] -
                        vcost[i]);
            for (int i = 0; i < n; ++i) {
                tdst[i] = INF;
                for (int j = 0; j < n; ++j)
                    tdst[i] =
                        min(tdst[i], dp[msk][j] + dst[j][i]);
            }
            for (int i = 0; i < n; ++i) dp[msk][i] = tdst[i];
        }
        int ans = INF;
        for (int i = 0; i < n; ++i)
            ans = min(ans, dp[(1 << t) - 1][i]);
        return ans;
    }
};
```

6 Math

6.1 Extended Euclidean Algorithm

```
// ax+ny = 1, ax+ny == ax == 1 (mod n)
void extgcd(ll x, ll y, ll &g, ll &a, ll &b) {
    if (y == 0) g=x, a=1, b=0;
    else extgcd(y, x%y, g, b, a), b-=(x/y)*a;
}
```

6.2 Floor & Ceil

```
int ifloor(int a, int b){
    return a / b - (a % b && (a < 0) ^ (b < 0));
}
int iceil(int a, int b){
    return a / b + (a % b && (a < 0) ^ (b > 0));
}
```

```
}
```

6.3 Legendre

// the Jacobi symbol is a generalization of the Legendre symbol,

// such that the bottom doesn't need to be prime.

// (n/p) -> same as Legendre

// (n/ab) = (n/a)(n/b)

// work with long long

```
int Jacobi(int a, int m) {
    int s = 1;
    for (; m > 1; ) {
        a %= m;
        if (a == 0) return 0;
        const int r = __builtin_ctz(a);
        if ((r & 1) && ((m + 2) & 4)) s = -s;
        a >>= r;
        if (a & m & 2) s = -s;
        swap(a, m);
    }
    return s;
}
```

// 0: a == 0

// -1: a isn't a quad res of p

// else: return X with X^2 % p == a

// doesn't work with long long

```
int QuadraticResidue(int a, int p) {
    if (p == 2) return a & 1;
    const int jc = Jacobi(a, p);
    if (jc == 0) return 0;
    if (jc == -1) return -1;
    int b, d;
    for (; ; ) {
        b = rand() % p;
        d = (1LL * b * b + p - a) % p;
        if (Jacobi(d, p) == -1) break;
    }
    int f0 = b, f1 = 1, g0 = 1, g1 = 0, tmp;
    for (int e = (1LL + p) >> 1; e; e >>= 1) {
        if (e & 1) {
            tmp = (1LL * g0 * f0 + 1LL * d * (1LL * g1 * f1 % p))
                % p;
            g1 = (1LL * g0 * f1 + 1LL * g1 * f0) % p;
            g0 = tmp;
        }
        tmp = (1LL * f0 * f0 + 1LL * d * (1LL * f1 * f1 % p)) %
            p;
        f1 = (2LL * f0 * f1) % p;
        f0 = tmp;
    }
    return g0;
}
```

6.4 Simplex

```
#pragma once
```

```
typedef double T; // Long double, Rational, double + mod<P>
>...
```

```
typedef vector<T> vd;
```

```
typedef vector<vd> vvd;
```

```
const T eps = 1e-8, inf = 1/.0;
```

```
#define MP make_pair
```

```
#define ltj(X) if(s == -1 || MP(X[j], N[j]) < MP(X[s], N[s]))
    s=j
```

```
struct LPSolver {
```

```
    int m, n;
```

```
    vi N, B;
```

```
    vvd D;
```

```
    LPSolver(const vvd& A, const vd& b, const vd& c) :
```



```

m(sz(b)), n(sz(c)), N(n+1), B(m), D(m+2, vd(n+2)) {
    rep(i,0,m) rep(j,0,n) D[i][j] = A[i][j];
    rep(i,0,m) { B[i] = n+1; D[i][n] = -1; D[i][n+1] = b[
        i];}
    rep(j,0,n) { N[j] = j; D[m][j] = -c[j]; }
    N[n] = -1; D[m+1][n] = 1;
}

void pivot(int r, int s) {
    T *a = D[r].data(), inv = 1 / a[s];
    rep(i,0,m+2) if (i != r && abs(D[i][s]) > eps) {
        T *b = D[i].data(), inv2 = b[s] * inv;
        rep(j,0,n+2) b[j] -= a[j] * inv2;
        b[s] = a[s] * inv2;
    }
    rep(j,0,n+2) if (j != s) D[r][j] *= inv;
    rep(i,0,m+2) if (i != r) D[i][s] *= -inv;
    D[r][s] = inv;
    swap(B[r], N[s]);
}

bool simplex(int phase) {
    int x = m + phase - 1;
    for (;;) {
        int s = -1;
        rep(j,0,n+1) if (N[j] != -phase) ltj(D[x]);
        if (D[x][s] >= -eps) return true;
        int r = -1;
        rep(i,0,m) {
            if (D[i][s] <= eps) continue;
            if (r == -1 || MP(D[i][n+1] / D[i][s], B[i])
                < MP(D[r][n+1] / D[r][s], B[r])) r = i;
        }
        if (r == -1) return false;
        pivot(r, s);
    }
}

T solve(vd &x) {
    int r = 0;
    rep(i,1,m) if (D[i][n+1] < D[r][n+1]) r = i;
    if (D[r][n+1] < -eps) {
        pivot(r, n);
        if (!simplex(2) || D[m+1][n+1] < -eps) return -inf;
        rep(i,0,m) if (B[i] == -1) {
            int s = 0;
            rep(j,1,n+1) ltj(D[i]);
            pivot(i, s);
        }
    }
    bool ok = simplex(1); x = vd(n);
    rep(i,0,m) if (B[i] < n) x[B[i]] = D[i][n+1];
    return ok ? D[m][n+1] : inf;
}
};

```

6.5 Floor Sum

```

// from 8BQube
ll floor_sum(ll n, ll m, ll a, ll b) {
    ll ans = 0;
    if (a >= m)
        ans += (n - 1) * n * (a / m) / 2, a %= m;
    if (b >= m)
        ans += n * (b / m), b %= m;
    ll y_max = (a * n + b) / m, x_max = (y_max * m - b);
    if (y_max == 0) return ans;
    ans += (n - (x_max + a - 1) / a) * y_max;
    ans += floor_sum(y_max, a, m, (a - x_max % a) % a);
    return ans;
}
// sum^{n-1}_0 floor((a * i + b) / m) in Log(n + m + a + b)

```

6.6 DiscreteLog

```

int DiscreteLog(int s, int x, int y, int m) {
    constexpr int kStep = 32000;
    unordered_map<int, int> p;
    int b = 1;
    for (int i = 0; i < kStep; ++i) {
        p[y] = i;
        y = 1LL * y * x % m;
        b = 1LL * b * x % m;
    }
    for (int i = 0; i < m + 10; i += kStep) {
        s = 1LL * s * b % m;
        if (p.find(s) != p.end()) return i + kStep - p[s];
    }
    return -1;
}

int DiscreteLog(int x, int y, int m) {
    if (m == 1) return 0;
    int s = 1;
    for (int i = 0; i < 100; ++i) {
        if (s == y) return i;
        s = 1LL * s * x % m;
    }
    if (s == y) return 100;
    int p = 100 + DiscreteLog(s, x, y, m);
    if (fpow(x, p, m) != y) return -1;
    return p; //returns: x^p = y (mod m)
}

```

6.7 Miller Rabin & Pollard Rho

```

// n < 4,759,123,141      3 : 2, 7, 61
// n < 1,122,004,669,633  4 : 2, 13, 23, 1662803
// n < 3,474,749,660,383  6 : primes <= 13
// n < 2^64              7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
ll mul(ll a, ll b, ll n){
    return (__int128)a * b % n;
}

bool Miller_Rabin(ll a, ll n) {
    if ((a = a % n) == 0) return 1;
    if (n % 2 == 0) return n == 2;
    ll tmp = (n - 1) / ((n - 1) & (1 - n));
    ll t = __lg(((n - 1) & (1 - n))), x = 1;
    for (; tmp; tmp >>= 1, a = mul(a, a, n))
        if (tmp & 1) x = mul(x, a, n);
    if (x == 1 || x == n - 1) return 1;
    while (--t)
        if ((x = mul(x, x, n)) == n - 1) return 1;
    return 0;
}

bool prime(ll n){
    vector<ll> tmp = {2, 325, 9375, 28178, 450775, 9780504,
        1795265022};
    for(ll i : tmp)
        if(!Miller_Rabin(i, n)) return false;
    return true;
}

map<ll, int> cnt;
void PollardRho(ll n) {
    if (n == 1) return;
    if (prime(n)) return ++cnt[n], void();
    if (n % 2 == 0) return PollardRho(n / 2), ++cnt[2], void();
    ll x = 2, y = 2, d = 1, p = 1;
#define f(x, n, p) ((mul(x, x, n) + p) % n)
    while (true) {
        if (d != n && d != 1) {
            PollardRho(n / d);
            PollardRho(d);
            return;
        }
        if (d == n) ++p;
        x = f(x, n, p), y = f(f(y, n, p), n, p);
        d = gcd(abs(x - y), n);
    }
}

```

6.8 XOR Basis

```
const int digit = 60; // [0, 2^digit)
struct Basis{
    int total = 0, rank = 0;
    vector<ll> b;
    Basis(): b(digit) {}
    bool add(ll v){ // Gauss Jordan Elimination
        total++;
        for(int i = digit - 1; i >= 0; i--){
            if(!(1LL << i & v)) continue;
            if(b[i] != 0){
                v ^= b[i];
                continue;
            }
            for(int j = 0; j < i; j++){
                if(1LL << j & v) v ^= b[j];
            }
            for(int j = i + 1; j < digit; j++){
                if(1LL << i & b[j]) b[j] ^= v;
            }
            b[i] = v;
            rank++;
            return true;
        }
        return false;
    }
    ll getmax(ll x = 0){
        for(ll i : b) x = max(x, x ^ i);
        return x;
    }
    ll getmin(ll x = 0){
        for(ll i : b) x = min(x, x ^ i);
        return x;
    }
    bool can(ll x){
        return getmin(x) == 0;
    }
    ll kth(ll k){ // kth smallest, 0-indexed
        vector<ll> tmp;
        for(ll i : b) if(i) tmp.pb(i);
        ll ans = 0;
        for(int i = 0; i < SZ(tmp); i++){
            if(1LL << i & k) ans ^= tmp[i];
        }
        return ans;
    }
};
```

6.9 Linear Equation

```
vector<int> RREF(vector<vector<ll>> &mat){
    int N = mat.size(), M = mat[0].size();
    int rk = 0;
    vector<int> cols;
    for (int i = 0; i < M; i++) {
        int cnt = -1;
        for (int j = N-1; j >= rk; j--){
            if(mat[j][i] != 0) cnt = j;
        }
        if(cnt == -1) continue;
        swap(mat[rk], mat[cnt]);
        ll lead = mat[rk][i];
        for (int j = 0; j < M; j++) mat[rk][j] /= lead;
        for (int j = 0; j < N; j++) {
            if(j == rk) continue;
            ll tmp = mat[j][i];
            for (int k = 0; k < M; k++)
                mat[j][k] -= mat[rk][k] * tmp;
        }
        cols.pb(i);
        rk++;
    }
    return cols;
}
struct LinearEquation{
    bool ok;
    vector<ll> par; //particular solution (Ax = b)
    vector<vector<ll>> homo; //homogenous (Ax = 0)
    vector<vector<ll>> rref;
```

```
//first M columns are matrix A
//last column of eq is vector b
void solve(const vector<vector<ll>> &eq){
    int M = (int)eq[0].size() - 1;
    rref = eq;
    auto piv = RREF(rref);
    int rk = piv.size();
    if(piv.size() && piv.back() == M){
        ok = 0; return;
    }
    ok = 1;
    par.resize(M);
    vector<bool> ispiv(M);
    for (int i = 0; i < rk; i++) {
        par[piv[i]] = rref[i][M];
        ispiv[piv[i]] = 1;
    }
    for (int i = 0; i < M; i++) {
        if (ispiv[i]) continue;
        vector<ll> h(M);
        h[i] = 1;
        for (int j = 0; j < rk; j++) h[piv[j]] = -rref[j][i];
        homo.pb(h);
    }
}
```

6.10 Chinese Remainder Theorem

```
pll solve_crt(ll x1, ll m1, ll x2, ll m2){
    ll g = gcd(m1, m2);
    if ((x2 - x1) % g) return {0, 0}; // no sol
    m1 /= g; m2 /= g;
    ll _, p, q;
    extgcd(m1, m2, _, p, q); // p <= C
    ll lcm = m1 * m2 * g;
    ll res = ((__int128)p * (x2 - x1) % lcm * m1 % lcm + x1)
        % lcm;
    // be careful with overflow, C^3
    return {(res + lcm) % lcm, lcm}; // (x, m)
}
```

6.11 Sqrt Decomposition

```
// for all i in [l, r], floor(n / i) = x
for(int l = 1, r; l <= n; l = r + 1){
    int x = ifloor(n, l);
    r = ifloor(n, x);
}
// for all i in [l, r], ceil(n / i) = x
for(int l, r = n; r >= 1; r = l - 1){
    int x = iceil(n, r);
    l = iceil(n, x);
}
```

7 Misc

7.1 Cyclic Ternary Search

```
/* bool pred(int a, int b);
f(0) ~ f(n - 1) is a cyclic-shift U-function
return idx s.t. pred(x, idx) is false forall x*/
int cyc_tsearch(int n, auto pred) {
    if (n == 1) return 0;
    int l = 0, r = n; bool rv = pred(1, 0);
    while (r - l > 1) {
        int m = (l + r) / 2;
        if (pred(0, m) ? rv : pred(m, (m + 1) % n)) r = m;
        else l = m;
    }
    return pred(1, r % n) ? l : r % n;
}
```

7.2 Matroid

我們稱一個二元組 $M = (E, \mathcal{I})$ 為一個擬陣，其中 $\mathcal{I} \subseteq 2^E$ 為 E 的子集所形成的非空集合，若：

- 若 $S \in \mathcal{I}$ 以及 $S' \subsetneq S$ ，則 $S' \in \mathcal{I}$
- 對於 $S_1, S_2 \in \mathcal{I}$ 滿足 $|S_1| < |S_2|$ ，存在 $e \in S_2 \setminus S_1$ 使得 $S_1 \cup \{e\} \in \mathcal{I}$

除此之外，我們有以下的定義：

- 位於 \mathcal{I} 中的集合我們稱之為獨立集（independent set），反之不在 \mathcal{I} 中的我們稱為相依集（dependent set）
- 極大的獨立集為基底（base）、極小的相依集為迴路（circuit）
- 一個集合 Y 的秩(rank) $r(Y)$ 為該集合中最大的獨立子集，也就是 $r(Y) = \max\{|X| \mid X \subseteq Y \text{ 且 } X \in \mathcal{I}\}$

性質：

1. $X \subseteq Y \wedge Y \in \mathcal{I} \implies X \in \mathcal{I}$
2. $X \subseteq Y \wedge X \notin \mathcal{I} \implies Y \notin \mathcal{I}$
3. 若 B 與 B' 皆是基底且 $B \subseteq B'$ ，則 $B = B'$
若 C 與 C' 皆是迴路且 $C \subseteq C'$ ，則 $C = C'$
4. $e \in E \wedge X \subseteq E \implies r(X) \leq r(X \cup \{e\}) \leq r(X) + 1$ i.e. 加入一個元素後秩不會降底，最多增加 1
5. $\forall Y \subseteq E, \exists X \subseteq Y, r(X) = |X| = r(Y)$

一些等價的性質：

1. 對於所有 $X \subseteq E$ ， X 的極大獨立子集都有相同的大小
2. 對於 $B_1, B_2 \in \mathcal{B} \wedge B_1 \neq B_2$ ，對於所有 $e_1 \in B_1 \setminus B_2$ ，存在 $e_2 \in B_2 \setminus B_1$ 使得 $(B_1 \setminus \{e_1\}) \cup \{e_2\} \in \mathcal{B}$
3. 對於 $X, Y \in \mathcal{I}$ 且 $|X| < |Y|$ ，存在 $e \in Y \setminus X$ 使得 $X \cup \{e\} \in \mathcal{B}$
4. 如果 $r(X \cup \{e_1\}) = r(X \cup \{e_2\}) = r(X)$ ，則 $r(X \cup \{e_1, e_2\}) = r(X)$ 。
如果 $r(X \cup \{e\}) = r(X)$ 對於所有 $e \in E'$ 都成立，則 $r(X \cup E') = r(X)$ 。

擬陣交

```
Data: 兩個擬陣  $M_1 = (E, \mathcal{I}_1)$  以及  $M_2 = (E, \mathcal{I}_2)$ 
Result:  $I$  為最大的位於  $\mathcal{I}_1 \cap \mathcal{I}_2$  中的獨立集
 $I \leftarrow \emptyset$ 
 $X_1 \leftarrow \{e \in E \setminus I \mid I \cup \{e\} \in \mathcal{I}_1\}$ 
 $X_2 \leftarrow \{e \in E \setminus I \mid I \cup \{e\} \in \mathcal{I}_2\}$ 
while  $X_1 \neq \emptyset$  且  $X_2 \neq \emptyset$  do
    if  $e \in X_1 \cap X_2$  then
         $I \leftarrow I \cup \{e\}$ 
    else
        構造交換圖  $\mathcal{D}_{M_1, M_2}(I)$ 
        在交換圖上找到一條  $X_1$  到  $X_2$  且沒有捷徑的路徑  $P$ 
         $I \leftarrow I \Delta P$ 
    end if
     $X_1 \leftarrow \{e \in E \setminus I \mid I \cup \{e\} \in \mathcal{I}_1\}$ 
     $X_2 \leftarrow \{e \in E \setminus I \mid I \cup \{e\} \in \mathcal{I}_2\}$ 
end while
```

8 Polynomial

8.1 FWHT

```
/* x: a[j], y: a[j + (L >> 1)]
or: (y += x * op), and: (x += y * op)
xor: (x, y = (x + y) * op, (x - y) * op)
invop: or, and, xor = -1, -1, 1/2 */
void fwt(int *a, int n, int op) { //or
    for (int L = 2; L <= n; L <= 1)
        for (int i = 0; i < n; i += L)
            for (int j = i; j < i + (L >> 1); ++j)
                a[j + (L >> 1)] += a[j] * op;
}
const int N = 21;
int f[N][1 << N], g[N][1 << N], h[N][1 << N], ct[1 << N];
void subset_convolution(int *a, int *b, int *c, int L) {
    // c_k = \sum_{i | j = k, i & j = \emptyset} a_i * b_j
    int n = 1 << L;
    for (int i = 1; i < n; ++i)
        ct[i] = ct[i & (i - 1)] + 1;
    for (int i = 0; i < n; ++i)
        f[ct[i]][i] = a[i], g[ct[i]][i] = b[i];
    for (int i = 0; i <= L; ++i)
```

```
        fwt(f[i], n, 1), fwt(g[i], n, 1);
    for (int i = 0; i <= L; ++i)
        for (int j = 0; j <= i; ++j)
            for (int x = 0; x < n; ++x)
                h[i][x] += f[j][x] * g[i - j][x];
    for (int i = 0; i <= L; ++i) fwt(h[i], n, -1);
    for (int i = 0; i < n; ++i) c[i] = h[ct[i]][i];
}
```

8.2 FFT

```
using val_t = complex<double>;
template<int MAXN>
struct FFT {
    const double PI = acos(-1);
    val_t w[MAXN];
    FFT() {
        for (int i = 0; i < MAXN; ++i) {
            double arg = 2 * PI * i / MAXN;
            w[i] = val_t(cos(arg), sin(arg));
        }
    }
    void bitrev(vector<val_t> &a, int n) //same as NTT
    void trans(vector<val_t> &a, int n, bool inv = false) {
        bitrev(a, n);
        for (int L = 2; L <= n; L <= 1) {
            int dx = MAXN / L, dl = L >> 1;
            for (int i = 0; i < n; i += L) {
                for (int j = i, x = 0; j < i + dl; ++j, x += dx) {
                    val_t tmp = a[j + dl] * (inv ? conj(w[x]) : w[x]);
                    a[j + dl] = a[j] - tmp;
                    a[j] += tmp;
                }
            }
        }
        if (inv) {
            for (int i = 0; i < n; ++i) a[i] /= n;
        }
    }
    //multiplying two polynomials A * B:
    //fft.trans(A, siz, 0), fft.trans(B, siz, 0):
    //A[i] *= B[i], fft.trans(A, siz, 1);
};
```

8.3 NTT

```
//(2^16)+1, 65537, 3
//7*17*(2^23)+1, 998244353, 3
//1255*(2^20)+1, 1315962881, 3
//51*(2^25)+1, 1711276033, 29
// only works when sz(A) + sz(B) - 1 <= MAXN
template<int MAXN, ll P, ll RT> //MAXN must be 2^k
struct NTT {
    ll w[MAXN];
    ll mpow(ll a, ll n);
    ll minv(ll a) { return mpow(a, P - 2); }
    NTT() {
        ll dw = mpow(RT, (P - 1) / MAXN);
        w[0] = 1;
        for (int i = 1; i < MAXN; ++i) w[i] = w[i - 1] * dw % P;
    }
    void bitrev(vector<ll> &a, int n) {
        int i = 0;
        for (int j = 1; j < n - 1; ++j) {
            for (int k = n >> 1; (i ^= k) < k; k >>= 1);
            if (j < i) swap(a[i], a[j]);
        }
    }
    void operator()(vector<ll> &a, int n, bool inv = false) {
        //0 <= a[i] < P
        bitrev(a, n);
        for (int L = 2; L <= n; L <= 1) {
            int dx = MAXN / L, dl = L >> 1;
```

```

    for (int i = 0; i < n; i += L) {
        for (int j = i, x = 0; j < i + dl; ++j, x += dx) {
            ll tmp = a[j + dl] * w[x] % P;
            if ((a[j + dl] = a[j] - tmp) < 0) a[j + dl] += P;
            if ((a[j] += tmp) >= P) a[j] -= P;
        }
    }
}
if (inv) {
    reverse(a.begin()+1, a.begin()+n);
    ll invn = minv(n);
    for (int i = 0; i < n; ++i) a[i] = a[i] * invn % P;
}
}
};

```

8.4 Polynomial Operation

```

// Copy from 8BQube
#define fi(s, n) for (int i = (int)(s); i < (int)(n); ++i)
template<int MAXN, ll P, ll RT> // MAXN = 2^k
struct Poly : vector<ll> { // coefficients in [0, P)
    using vector<ll>::vector;
    static NTT<MAXN, P, RT> ntt;
    int n() const { return (int)size(); } // n() >= 1
    Poly(const Poly &p, int m) : vector<ll>(m) {
        copy_n(p.data(), min(p.n(), m), data());
    }
    Poly& irev() { return reverse(data(), data() + n()), *this; }
    Poly& isz(int m) { return resize(m), *this; }
    Poly& iadd(const Poly &rhs) { // n() == rhs.n()
        fi(0, n()) if (((*this)[i] += rhs[i]) >= P) (*this)[i] -= P;
        return *this;
    }
    Poly& imul(ll k) {
        fi(0, n()) (*this)[i] = (*this)[i] * k % P;
        return *this;
    }
    Poly Mul(const Poly &rhs) const {
        int m = 1;
        while (m < n() + rhs.n() - 1) m <= 1;
        assert(m <= MAXN);
        Poly X(*this, m), Y(rhs, m);
        ntt(X, m), ntt(Y, m);
        fi(0, m) X[i] = X[i] * Y[i] % P;
        ntt(X, m, true);
        return X.isz(n() + rhs.n() - 1);
    }
    Poly Inv() const { // (*this)[0] != 0, 1e5/95ms, 2*sz<= MAXN
        if (n() == 1) return {ntt.minv((*this)[0])};
        int m = 1;
        while (m < n() * 2) m <= 1;
        assert(m <= MAXN);
        Poly Xi = Poly(*this, (n() + 1) / 2).Inv().isz(m);
        Poly Y(*this, m);
        ntt(Xi, m), ntt(Y, m);
        fi(0, m) {
            Xi[i] *= (2 - Xi[i] * Y[i]) % P;
            if ((Xi[i] %= P) < 0) Xi[i] += P;
        }
        ntt(Xi, m, true);
        return Xi.isz(n());
    }
    Poly& shift_inplace(const ll &c) { // 2 * sz <= MAXN
        int n = this->n();
        vector<ll> fc(n), ifc(n);
        fc[0] = ifc[0] = 1;
        for (int i = 1; i < n; ++i){
            fc[i] = fc[i-1] * i % P;
            ifc[i] = ntt.minv(fc[i]);
        }
        for (int i = 0; i < n; ++i) (*this)[i] = (*this)[i] *
            fc[i] % P;
    }
};

```

```

Poly g(n);
ll cp = 1;
for (int i = 0; i < n; i++) g[i] = cp * ifc[i] % P, cp
    = cp * c % P;
*this = (*this).irev().Mul(g).isz(n).irev();
for (int i = 0; i < n; i++) (*this)[i] = (*this)[i] *
    ifc[i] % P;
return *this;
}
Poly shift(const ll &c) const { return Poly(*this).
    shift_inplace(c); }
Poly _Sqrt() const { // Jacobi((*this)[0], P) = 1
    if (n() == 1) return {QuadraticResidue((*this)[0], P)};
    Poly X = Poly(*this, (n() + 1) / 2)._Sqrt().isz(n());
    return X.iadd(Mul(X.Inv()).isz(n())).imul(P / 2 + 1);
}
Poly Sqrt() const { // 2 * sz <= MAXN
    Poly a;
    bool has = 0;
    for(int i = 0; i < n(); i++){
        if((*this)[i]) has = 1;
        if(has) a.push_back((*this)[i]);
    }
    if(!has) return *this;
    if( (n() + a.n()) % 2 || Jacobi(a[0], P) != 1) {
        return Poly();
    }
    a=a.isz((n() + a.n()) / 2)._Sqrt();
    int sz = a.n();
    a.isz(n());
    rotate(a.begin(), a.begin() + sz, a.end());
    return a;
}
pair<Poly, Poly> DivMod(const Poly &rhs) const { // (rhs
    .)back() != 0
    if (n() < rhs.n()) return {{0}, *this};
    const int m = n() - rhs.n() + 1;
    Poly X(rhs); X.irev().isz(m);
    Poly Y(*this); Y.irev().isz(m);
    Poly Q = Y.Mul(X.Inv()).isz(m).irev();
    X = rhs.Mul(Q), Y = *this;
    fi(0, n()) if ((Y[i] -= X[i]) < 0) Y[i] += P;
    return {Q, Y.isz(max(1, rhs.n() - 1))};
}
Poly Dx() const {
    Poly ret(n() - 1);
    fi(0, ret.n()) ret[i] = (i + 1) * (*this)[i + 1] % P;
    return ret.isz(max(1, ret.n()));
}
Poly Sx() const {
    Poly ret(n() + 1);
    fi(0, n()) ret[i + 1] = ntt.minv(i + 1) * (*this)[i] %
        P;
    return ret;
}
Poly _tmul(int nn, const Poly &rhs) const {
    Poly Y = Mul(rhs).isz(n() + nn - 1);
    return Poly(Y.data() + n() - 1, Y.data() + Y.n());
}
vector<ll> _eval(const vector<ll> &x, const vector<Poly>
    &up) const {
    const int m = (int)x.size();
    if (!m) return {};
    vector<Poly> down(m * 2);
    // down[1] = DivMod(up[1]).second;
    // fi(2, m * 2) down[i] = down[i / 2].DivMod(up[i]).
        second;
    down[1] = Poly(up[1]).irev().isz(n()).Inv().irev().
        _tmul(m, *this);
    fi(2, m * 2) down[i] = up[i ^ 1]._tmul(up[i].n() - 1,
        down[i / 2]);
    vector<ll> y(m);
    fi(0, m) y[i] = down[m + i][0];
    return y;
}
static vector<Poly> _tree1(const vector<ll> &x) {
    const int m = (int)x.size();
}

```

```

vector<Poly> up(m * 2);
fi(0, m) up[m + i] = {(x[i] ? P - x[i] : 0), 1};
for (int i = m - 1; i > 0; --i) up[i] = up[i * 2].Mul(
    up[i * 2 + 1]);
return up;
}
vector<ll> Eval(const vector<ll> &x) const { // 1e5, 1s
    auto up = _tree1(x); return _eval(x, up);
}
static Poly Interpolate(const vector<ll> &x, const vector
    <ll> &y) { // 1e5, 1.4s
    const int m = (int)x.size();
    vector<Poly> up = _tree1(x), down(m * 2);
    vector<ll> z = up[1].Dx()._eval(x, up);
    fi(0, m) z[i] = y[i] * ntt.minv(z[i]) % P;
    fi(0, m) down[m + i] = {z[i]};
    for (int i = m - 1; i > 0; --i) down[i] = down[i * 2].
        Mul(up[i * 2 + 1]).iadd(down[i * 2 + 1].Mul(up[i *
            2]));
    return down[1];
}
Poly Ln() const { // (*this)[0] == 1, 2*sz<=MAXN
    return Dx().Mul(Inv()).Sx().isz(n());
}
Poly Exp() const { // (*this)[0] == 0, 2*sz<=MAXN
    if (n() == 1) return {1};
    Poly X = Poly(*this, (n() + 1) / 2).Exp().isz(n());
    Poly Y = X.Ln(); Y[0] = P - 1;
    fi(0, n()) if ((Y[i] = (*this)[i] - Y[i]) < 0) Y[i] +=
        P;
    return X.Mul(Y).isz(n());
}
// M := P(P - 1). If k >= M, k := k % M + M.
Poly Pow(ll k) const { // 2*sz<=MAXN
    int nz = 0;
    while (nz < n() && !(*this)[nz]) ++nz;
    if (nz * min(k, (ll)n()) >= n()) return Poly(n());
    if (!k) return Poly(Poly {1}, n());
    Poly X(data() + nz, data() + nz + n() - nz * k);
    const ll c = ntt.mpow(X[0], k % (P - 1));
    return X.Ln().imul(k % P).Exp().imul(c).irev().isz(n())
        .irev();
}
static ll LinearRecursion(const vector<ll> &a, const
    vector<ll> &coef, ll n) { // a_n = \sum c_j a_{n-j}
    const int k = (int)a.size();
    assert((int)coef.size() == k + 1);
    Poly C(k + 1), W(Poly {1}, k), M = {0, 1};
    fi(1, k + 1) C[k - i] = coef[i] ? P - coef[i] : 0;
    C[k] = 1;
    while (n) {
        if (n % 2) W = W.Mul(M).DivMod(C).second;
        n /= 2, M = M.Mul(M).DivMod(C).second;
    }
    ll ret = 0;
    fi(0, k) ret = (ret + W[i] * a[i]) % P;
    return ret;
}
};
#undef fi
using Poly_t = Poly<1 << 20, 998244353, 3>;
template<> decltype(Poly_t::ntt) Poly_t::ntt = {};

```

8.5 Generating Function

8.5.1 Ordinary Generating Function

- $C(x) = A(rx)$: $c_n = r^n a_n$ 的一般生成函數。
- $C(x) = A(x) + B(x)$: $c_n = a_n + b_n$ 的一般生成函數。
- $C(x) = A(x)B(x)$: $c_n = \sum_{i=0}^n a_i b_{n-i}$ 的一般生成函數。
- $C(x) = A(x)^k$: $c_n = \sum_{i_1+i_2+\dots+i_k=n} a_{i_1} a_{i_2} \dots a_{i_k}$ 的一般生成函數。
- $C(x) = xA(x)'$: $c_n = na_n$ 的一般生成函數。

- $C(x) = \frac{A(x)}{1-x}$: $c_n = \sum_{i=0}^n a_i$ 的一般生成函數。
- $C(x) = A(1) + x \frac{A(1)-A(x)}{1-x}$: $c_n = \sum_{i=n}^{\infty} a_i$ 的一般生成函數。

常用展開式

- $\frac{1}{1-x} = 1 + x + x^2 + \dots + x^n + \dots$
- $(1+x)^a = \sum_{n=0}^{\infty} \binom{a}{n} x^n$, $\binom{a}{n} = \frac{a(a-1)(a-2)\dots(a-n+1)}{n!}$.

常見生函

- 卡特蘭數: $f(x) = \frac{1-\sqrt{1-4x}}{2x}$

8.5.2 Exponential Generating Function

a_0, a_1, \dots 的指數生成函數:

$$\hat{A}(x) = \sum_{i=0}^{\infty} \frac{a_i}{i!} = a_0 + a_1 x + \frac{a_2}{2!} x^2 + \frac{a_3}{3!} x^3 + \dots$$

- $\hat{C}(x) = \hat{A}(x) + \hat{B}(x)$: $c_n = a_n + b_n$ 的指數生成函數
- $\hat{C}(x) = \hat{A}^{(k)}(x)$: $c_n = a_{n+k}$ 的指數生成函數
- $\hat{C}(x) = x\hat{A}(x)$: $c_n = na_n$ 的指數生成函數
- $\hat{C}(x) = \hat{A}(x)\hat{B}(x)$: $c_n = \sum_{k=0}^n \binom{n}{k} a_k b_{n-k}$ 的指數生成函數
- $\hat{C}(x) = \hat{A}(x)^k$: $\sum_{i_1+i_2+\dots+i_k=n} \binom{n}{i_1, i_2, \dots, i_k} a_{i_1} a_{i_2} \dots a_{i_k}$ 的指數生成函數
- $\hat{C}(x) = \exp(A(x))$: 假設 $A(x)$ 是一個分量 (component) 的生成函數，那麼 $\hat{C}(x)$ 是將 n 個有編號的東西分成若干個分量的指數生成函數

9 String

9.1 KMP Algorithm

```

void kmp(string s){
    int siz = s.size();
    vector<int> f(siz, 0);
    f[0] = 0;
    for (int i = 1; i < siz; i++) {
        f[i] = f[i-1];
        bool zero = 0;
        while (s[f[i]] != s[i]) {
            if (f[i] == 0) {
                zero = 1;
                break;
            }
            f[i] = f[f[i]-1];
        }
        if (!zero) f[i]++;
    }
}

```

9.2 Manacher Algorithm

```

vector<int> manacher(string s) {
    int n = s.size();
    vector<int> v(n);
    int pnt = -1, len = 1;
    for (int i = 0; i < n; i++) {
        int cor = 2 * pnt - i;
        if (cor >= 0) v[i] = min(v[cor], cor - pnt + len);
        while (i+v[i] < n && i-v[i] >= 0 && s[i+v[i]] == s[i-v[i]]) v[i]++;
        if (i + v[i] >= pnt + len) pnt = i, len = v[i];
    }
    for (int i = 0; i < n; i++) v[i] = 2 * v[i] - 1;
    return v;
}

```

9.3 MCP

```
string mcp(string s) { //Duval algorithm for Lyndon
    factorization
    s += s;
    int n = s.size(), i = 0, ans = 0;
    while (i < n/2) {
        ans = i;
        int j = i+1, k=i;
        while (j < n && s[k] <= s[j]) {
            if (s[k] < s[j]) k = i;
            else k++;
            j++;
        }
        while (i <= k) i += j - k;
    }
    return s.substr(ans, n/2);
}
```

9.4 Suffix Array

```
struct SuffixArray { //tested
    vector<int> sa, lcp, rank; //lcp[i] is lcp of sa[i] and
    sa[i-1]
    SuffixArray(string& s, int lim=256) { // or basic_string<
    int>
        int n = s.size() + 1, k = 0, a, b;
        vector<int> x(n, 0), y(n), ws(max(n, lim));
        rank.resize(n);
        for (int i = 0; i < n-1; i++) x[i] = (int)s[i];
        sa = lcp = y, iota(sa.begin(), sa.end(), 0);
        for (int j = 0, p = 0; p < n; j = max(1, j * 2), lim =
        p) {
            p = j, iota(y.begin(), y.end(), n - j);
            for (int i = 0; i < n; i++) if (sa[i] >= j) y[p++] = sa
            [i] - j;
            for (int &i : ws) i = 0;
            for (int i = 0; i < n; i++) ws[x[i]]++;
            for (int i = 1; i < lim; i++) ws[i] += ws[i - 1];
            for (int i = n; i--;) sa[--ws[x[y[i]]]] = y[i];
            swap(x, y), p = 1, x[sa[0]] = 0;
            for (int i = 1; i < n; i++) a = sa[i - 1], b = sa[i], x[
            b] =
                (y[a] == y[b] && y[a + j] == y[b + j]) ? p - 1 : p
                ++;
        }
        for (int i = 1; i < n; i++) rank[sa[i]] = i;
        for (int i = 0, j; i < n - 1; lcp[rank[i++]] = k)
            for (k && k--, j = sa[rank[i] - 1];
                s[i + k] == s[j + k]; k++);
    }
};
```

9.5 Suffix Automaton

```
// from 8BQube
// at most 2n-1 states, 3n-4 edges

// to find Longest common substring for multiple strings
    S_1, ..., S_k
// assign a special (distinct) character D_i to each string
// let T = S_1 D_1 ... S_k D_k, then build SAM of T
// answer is state with max length reachable to all D_i
const int maxn = 1000010;
struct SAM { //1 base
    vector<int> adj[maxn];
    int tot, root, lst, par[maxn], mx[maxn], fi[maxn], iter;
    //mx: maxlen of node, mx[par[i]]+1:minlen of node
    //fi: first endpos
    //corresponding substring of node can be found by fi and
    mx
    int nxt[maxn][33];
    int newNode() {
        int res = ++tot;
```

```
        fill(nxt[res], nxt[res] + 33, 0);
        par[res] = mx[res] = 0;
        fi[res] = iter;
        return res;
    }
    void init() {
        tot = 0;
        iter = 0;
        root = newNode();
        par[root] = 0, mx[root] = 0;
        lst = root;
    }
    void push(int c) {
        int p = lst;
        int np = newNode();
        mx[np] = mx[p] + 1;
        for (; p && nxt[p][c] == 0; p = par[p])
            nxt[p][c] = np;
        if (p == 0) par[np] = root;
        else {
            int q = nxt[p][c];
            if (mx[p] + 1 == mx[q]) par[np] = q;
            else {
                int nq = newNode();
                mx[nq] = mx[p] + 1;
                for (int i = 0; i < 33; i++)
                    nxt[nq][i] = nxt[q][i];
                par[nq] = par[q];
                fi[nq] = fi[q];
                par[q] = nq;
                par[np] = nq;
                for (; p && nxt[p][c] == q; p = par[p])
                    nxt[p][c] = nq;
            }
        }
        lst = np;
    }
    void push(string str) {
        for (int i = 0; str[i]; i++) {
            iter++;
            push(str[i] - 'a' + 1);
        }
    }
    ll get_diff_strings(){
        ll tot = 0;
        for (int i = 1; i <= tot; i++) tot += mx[i] - mx[par[i]
        ]];
        return tot;
    }
    bool in[maxn];
    int cnt[maxn]; //cnt is number of occurrences of node
    void count() {
        for (int i = 1; i <= tot; ++i)
            ++in[par[i]];
        queue<int> q;
        for (int i = 1; i <= tot; ++i)
            if (!in[i]) q.push(i);
        while (!q.empty()) {
            int u = q.front();
            q.pop();
            cnt[par[u]] += cnt[u];
            if (!--in[par[u]])
                q.push(par[u]);
        }
    }
} sam;
```

9.6 Z-value Algorithm

```
vector<int> z_function(string const& s) {
    int n = s.size();
    vector<int> z(n);
    for (int i = 1, l = 0, r = 0; i < n; i++) {
        if (i <= r) z[i] = min(r-i+1, z[i-l]);
        while (i + z[i] < n && s[z[i]] == s[i+z[i]])
```

```

    z[i]++;
    if (i + z[i] - 1 > r)
        l = i, r = i + z[i] - 1;
}
return z;
}

```

9.7 Main Lorentz

```

vector<int> z_function(string const& s);
int get_z(vector<int> const& z, int i) {
    return (0 <= i && i < SZ(z)) ? z[i] : 0;
}
vector<pair<int, int>> rep;

void convert_to_rep(int shift, bool left, int cntr, int l,
    int k1, int k2) {
    int lef = max(1, l-k2), rig = min(l, k1);
    int minl, maxl;
    if (left) {
        rig = min(rig, l-1);
        minl = shift + cntr - rig, maxl = shift+cntr-lef;
    } else {
        minl = shift + cntr - 1 - rig + 1, maxl = shift + cntr
            - 1 - lef + 1;
    }
    //left endpoint: [minl, maxl], length: 2*l
}

void find_rep(string s, int shift = 0) {
    int n = s.size();
    if (n == 1) return;

    int nu = n / 2;
    int nv = n - nu;
    string u = s.substr(0, nu);
    string v = s.substr(nu);
    string ru(u.rbegin(), u.rend());
    string rv(v.rbegin(), v.rend());

    find_rep(u, shift);
    find_rep(v, shift + nu);

    vector<int> z1 = z_function(ru);
    vector<int> z2 = z_function(v + '#' + u);
    vector<int> z3 = z_function(ru + '#' + rv);
    vector<int> z4 = z_function(v);

    for (int cntr = 0; cntr < n; cntr++) {
        int l, k1, k2;
        if (cntr < nu) {
            l = nu - cntr;
            k1 = get_z(z1, nu - cntr);
            k2 = get_z(z2, nv + 1 + cntr);
        } else {
            l = cntr - nu + 1;
            k1 = get_z(z3, nu + 1 + nv - 1 - (cntr - nu));
            k2 = get_z(z4, (cntr - nu) + 1);
        }
        if (k1 + k2 >= 1)
            convert_to_rep(shift, cntr < nu, cntr, l, k1, k2);
    }
}

```

9.8 AC Automaton

```

const int maxn = 300005, maxc = 26;
struct AC_Automaton { //1-base
    int nx[maxn][maxc], fl[maxn], cnt[maxn], pri[maxn], tot;
    //pri: bfs order of trie (0-base)
    int newnode() {
        tot++;
        fill(nx[tot], nx[tot] + maxc, -1);
        return tot;
    }
}

```

```

void init() { tot = 0, newnode(); }
int input(string &s) { // return the end_node of string
    int X = 1;
    for (char c : s) {
        if (!nx[X][c - 'a']) nx[X][c - 'a'] = newnode();
        X = nx[X][c - 'a'];
    }
    return X;
}

void make_fl() { //fail link
    queue<int> q;
    q.push(1), fl[1] = 0;
    for (int t = 0; !q.empty(); ) {
        int R = q.front();
        q.pop(), pri[t++] = R;
        for (int i = 0; i < maxc; ++i)
            if (~nx[R][i]) {
                int X = nx[R][i], Z = fl[R];
                for (; Z && !nx[Z][i];) Z = fl[Z];
                fl[X] = Z ? nx[Z][i] : 1, q.push(X);
            }
    }
}

void get_v(string &s) {
    //number of times prefix appears in strings
    int X = 1;
    fill(cnt, cnt + tot+1, 0);
    for (char c : s) {
        while (X && !nx[X][c - 'a']) X = fl[X];
        X = X ? nx[X][c - 'a'] : 1, ++cnt[X];
    }
    for (int i = tot-1; i > 0; --i)
        cnt[fl[pri[i]]] += cnt[pri[i]];
}
} ac;

```

10 Formula

10.1 Recurrences

If $a_n = c_1 a_{n-1} + \dots + c_k a_{n-k}$, and r_1, \dots, r_k are distinct roots of $x^k + c_1 x^{k-1} + \dots + c_k$, there are d_1, \dots, d_k s.t.

$$a_n = d_1 r_1^n + \dots + d_k r_k^n.$$

Non-distinct roots r become polynomial factors, e.g. $a_n = (d_1 n + d_2) r^n$.

10.2 Geometry

10.2.1 Rotation Matrix

$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

- rotate 90° : $(x, y) \rightarrow (-y, x)$
- rotate -90° : $(x, y) \rightarrow (y, -x)$

10.2.2 Triangles

Side lengths: a, b, c

$$\text{Semiperimeter: } p = \frac{a+b+c}{2}$$

$$\text{Area: } A = \sqrt{p(p-a)(p-b)(p-c)}$$

$$\text{Circumradius: } R = \frac{abc}{4A}$$

$$\text{Inradius: } r = \frac{A}{p}$$

Length of median (divides triangle into two equal-area triangles): $m_a = \frac{1}{2} \sqrt{2b^2 + 2c^2 - a^2}$

$$\text{Length of bisector (divides angles in two): } s_a = \sqrt{bc \left(1 - \left(\frac{a}{b+c} \right)^2 \right)}$$

$$\text{Law of sines: } \frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c} = \frac{1}{2R}$$

$$\text{Law of cosines: } a^2 = b^2 + c^2 - 2bc \cos \alpha$$

Law of tangents: $\frac{a+b}{a-b} = \frac{\tan \frac{\alpha+\beta}{2}}{\tan \frac{\alpha-\beta}{2}}$

Incenter:

$$P_1 = (x_1, y_1), P_2 = (x_2, y_2), P_3 = (x_3, y_3)$$

$$s_1 = P_2P_3, s_2 = P_1P_3, s_3 = P_1P_2$$

$$s_1P_1 + s_2P_2 + s_3P_3$$

$$\frac{s_1 + s_2 + s_3}{3}$$

Circumcenter:

$$P_0 = (0, 0), P_1 = (x_1, y_1), P_2 = (x_2, y_2)$$

$$x_c = \frac{1}{2} \times \frac{y_2(x_1^2 + y_1^2) - y_1(x_2^2 + y_2^2)}{-x_2y_1 + x_1y_2}$$

$$y_c = \frac{1}{2} \times \frac{x_2(x_1^2 + y_1^2) - x_1(x_2^2 + y_2^2)}{-x_1y_2 + x_2y_1}$$

Check if (x_0, y_0) is in the circumcircle:

$$\begin{vmatrix} x_1 - x_0 & y_1 - y_0 & (x_1^2 + y_1^2) - (x_0^2 + y_0^2) \\ x_2 - x_0 & y_2 - y_0 & (x_2^2 + y_2^2) - (x_0^2 + y_0^2) \\ x_3 - x_0 & y_3 - y_0 & (x_3^2 + y_3^2) - (x_0^2 + y_0^2) \end{vmatrix}$$

0: on edge, > 0: inside, < 0: outside

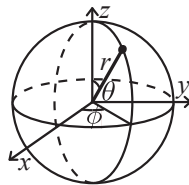
10.2.3 Quadrilaterals

With side lengths a, b, c, d , diagonals e, f , diagonals angle θ , area A and magic flux $F = b^2 + d^2 - a^2 - c^2$:

$$4A = 2ef \cdot \sin \theta = F \tan \theta = \sqrt{4e^2f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is 180° , $ef = ac + bd$, and $A = \sqrt{(p-a)(p-b)(p-c)(p-d)}$.

10.2.4 Spherical coordinates



$$\begin{aligned} x &= r \sin \theta \cos \phi & r &= \sqrt{x^2 + y^2 + z^2} \\ y &= r \sin \theta \sin \phi & \theta &= \arccos(z/\sqrt{x^2 + y^2 + z^2}) \\ z &= r \cos \theta & \phi &= \operatorname{atan2}(y, x) \end{aligned}$$

10.2.5 Green's Theorem

$$\iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy = \oint_{L^+} (P dx + Q dy)$$

$$\text{Area} = \frac{1}{2} \oint_L x dy - y dx$$

Circular sector:

$$x = x_0 + r \cos \theta$$

$$y = y_0 + r \sin \theta$$

$$\begin{aligned} A &= r \int_{\alpha}^{\beta} (x_0 + \cos \theta) \cos \theta + (y_0 + \sin \theta) \sin \theta d\theta \\ &= r(r\theta + x_0 \sin \theta - y_0 \cos \theta)|_{\alpha}^{\beta} \end{aligned}$$

10.2.6 Point-Line Duality

$$p = (a, b) \leftrightarrow p^* : y = ax - b$$

- $p \in l \iff l^* \in p^*$
- p_1, p_2, p_3 are collinear $\iff p_1^*, p_2^*, p_3^*$ intersect at a point
- p lies above $l \iff l^*$ lies above p^*
- lower convex hull \leftrightarrow upper envelope

10.3 Trigonometry

$$\sinh x = \frac{1}{2}(e^x - e^{-x}) \quad \cosh x = \frac{1}{2}(e^x + e^{-x})$$

$$\sin n\pi = 0 \quad \cos n\pi = (-1)^n$$

$$\sin(\alpha + \beta) = \sin \alpha \cos \beta + \cos \alpha \sin \beta$$

$$\cos(\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta$$

$$\sin(2\alpha) = 2 \cos \alpha \sin \alpha$$

$$\cos(2\alpha) = \cos^2 \alpha - \sin^2 \alpha$$

$$= 2 \cos^2 \alpha - 1$$

$$= 1 - 2 \sin^2 \alpha$$

$$\tan(\alpha + \beta) = \frac{\tan \alpha + \tan \beta}{1 - \tan \alpha \tan \beta}$$

$$\sin \alpha + \sin \beta = 2 \sin \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$

$$\cos \alpha + \cos \beta = 2 \cos \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$

$$\sin \alpha \sin \beta = \frac{1}{2}(\cos(\alpha - \beta) - \cos(\alpha + \beta))$$

$$\sin \alpha \cos \beta = \frac{1}{2}(\sin(\alpha + \beta) + \sin(\alpha - \beta))$$

$$\cos \alpha \sin \beta = \frac{1}{2}(\sin(\alpha + \beta) - \sin(\alpha - \beta))$$

$$\cos \alpha \cos \beta = \frac{1}{2}(\cos(\alpha - \beta) + \cos(\alpha + \beta))$$

$$(V + W) \tan(\alpha - \beta)/2 = (V - W) \tan(\alpha + \beta)/2$$

where V, W are lengths of sides opposite angles α, β .

$$a \cos x + b \sin x = r \cos(x - \phi)$$

$$a \sin x + b \cos x = r \sin(x + \phi)$$

where $r = \sqrt{a^2 + b^2}$, $\phi = \operatorname{atan2}(b, a)$.

10.4 Derivatives/Integrals

Integration by parts:

$$\int_a^b f(x)g(x)dx = [F(x)g(x)]_a^b - \int_a^b F(x)g'(x)dx$$

$$\frac{d}{dx} \arcsin x = \frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx} \arccos x = -\frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx} \tan x = 1 + \tan^2 x$$

$$\frac{d}{dx} \arctan x = \frac{1}{1+x^2}$$

$$\int \tan ax = -\frac{\ln |\cos ax|}{a}$$

$$\int x \sin ax = \frac{\sin ax - ax \cos ax}{a^2}$$

$$\int e^{-x^2} = \frac{\sqrt{\pi}}{2} \operatorname{erf}(x)$$

$$\int x e^{ax} = \frac{e^{ax}}{a^2} (ax - 1)$$

$$\int \sin^2(x) = \frac{x}{2} - \frac{1}{4} \sin 2x$$

$$\int \sin^3 x = \frac{1}{12} \cos 3x - \frac{3}{4} \cos x$$

$$\int \cos^2(x) = \frac{x}{2} + \frac{1}{4} \sin 2x$$

$$\int \cos^3 x = \frac{1}{12} \sin 3x + \frac{3}{4} \sin x$$

$$\int x \sin x = \sin x - x \cos x$$

$$\int x \cos x = \cos x + x \sin x$$

$$\int x e^x = e^x (x - 1)$$

$$\int x^2 e^x = e^x (x^2 - 2x + 2)$$

$$\int x^2 \sin x = 2x \sin x - (x^2 - 2) \cos x$$

$$\int x^2 \cos x = 2x \cos x + (x^2 - 2) \sin x$$

$$\int e^x \sin x = \frac{1}{2} e^x (\sin x - \cos x)$$

$$\int e^x \cos x = \frac{1}{2} e^x (\sin x + \cos x)$$

$$\int x e^x \sin x = \frac{1}{2} e^x (x \sin x - x \cos x + \cos x)$$

$$\int x e^x \cos x = \frac{1}{2} e^x (x \sin x + x \cos x - \sin x)$$

10.5 Sums

$$c^a + c^{a+1} + \cdots + c^b = \frac{c^{b+1} - c^a}{c - 1}, c \neq 1$$

$$1 + 2 + 3 + \cdots + n = \frac{n(n+1)}{2}$$

$$1^2 + 2^2 + 3^2 + \cdots + n^2 = \frac{n(2n+1)(n+1)}{6}$$

$$1^3 + 2^3 + 3^3 + \cdots + n^3 = \frac{n^2(n+1)^2}{4}$$

$$1^4 + 2^4 + 3^4 + \cdots + n^4 = \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}$$

10.6 Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \cdots, (-\infty < x < \infty)$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \cdots, (-1 < x \leq 1)$$

$$\sqrt{1+x} = 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{2x^3}{32} - \frac{5x^4}{128} + \cdots, (-1 \leq x \leq 1)$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots, (-\infty < x < \infty)$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \cdots, (-\infty < x < \infty)$$