

Contents

1 Basic	1
1.1 Default Code	1
1.2 .vimrc	1
1.3 Fast IO	1
2 Data Structure	2
2.1 Heavy-Light Decomposition	2
2.2 Li-Chao Tree	2
2.3 Link Cut Tree	3
2.4 Treap	3
3 Flow Matching	4
3.1 Bounded Flow	4
3.2 Dinic	4
3.3 Gomory Hu	5
3.4 Hungarian Algorithm	5
3.5 ISAP Algorithm	5
3.6 KM Algorithm	6
3.7 Max Simple Graph Matching	6
3.8 MCMF	6
3.9 Min Cost Circulation	7
3.10 SW Mincut	7
4 Geometry	7
4.1 Geometry Template	7
4.2 Convex Hull	8
4.3 Minimum Enclosing Circle	8
4.4 Minkowski Sum	8
4.5 Polar Angle Comparator	8
4.6 Half Plane Intersection	8
4.7 Dynamic Convex Hull	9
4.8 3D Point	9
4.9 ConvexHull3D	9
4.10 Circle Operations	10
4.11 Delaunay Triangulation	11
4.12 Voronoi Diagram	12
5 Graph	12
5.1 Block Cut Tree	12
5.2 2-SAT	12
5.3 Dominator Tree	13
5.4 Virtual Tree	13
5.5 Directed Minimum Spanning Tree	13
5.6 Vizing	14
6 Math	14
6.1 Extended Euclidean Algorithm	14
6.2 Floor & Ceil	14
6.3 Legendre	14
6.4 Simplex	15
6.5 Floor Sum	15
6.6 Miller Rabin & Pollard Rho	15
6.7 XOR Basis	16
7 Misc	16
7.1 Fraction	16
7.2 Matroid	16
8 Polynomial	17
8.1 FFT	17
8.2 NTT	17
8.3 Polynomial Operation	17
8.4 Generating Function	18
8.4.1 Ordinary Generating Function	18
8.4.2 Exponential Generating Function	18
9 String	18
9.1 Rolling Hash	18
9.2 KMP Algorithm	18
9.3 Manacher Algorithm	19
9.4 MCP	19
9.5 Suffix Array	19
9.6 Suffix Array Automaton	19
9.7 Z-value Algorithm	20
9.8 Main Lorentz	20
9.9 AC Automaton	20

10 Formula	21
10.1 Recurrences	21
10.2 Geometry	21
10.2.1 Triangles	21
10.2.2 Quadrilaterals	21
10.2.3 Spherical coordinates	21
10.2.4 Green's Theorem	21
10.3 Trigonometry	21
10.4 Derivatives/Integrals	22
10.5 Sums	22
10.6 Series	22
10.7 Probability theory	22
10.7.1 Discrete distributions	22
10.7.2 Continuous distributions	22
10.8 Markov chains	23

1 Basic

1.1 Default Code

```
//Challenge: Accepted
//#pragma GCC optimize("Ofast")
#include <bits/stdc++.h>
using namespace std;

#define io ios_base::sync_with_stdio(0);cin.tie(0);cerr.tie(0)
#define iter(v) v.begin(),v.end()
#define SZ(v) (int)v.size()
#define pb emplace_back
#define mp make_pair
#define ff first
#define ss second

using ll = long long;
using pii = pair<int, int>;
using pll = pair<ll, ll>;

#ifdef zisk
void debug(){cerr << "\n";}
template<class T, class ... U>
void debug(T a, U ... b){cerr << a << " ", debug(b...);}
template<class T> void pary(T l, T r){
    while (l != r) cerr << *l << " ", l++;
    cerr << "\n";
}
#else
#define debug(...) void()
#define pary(...) void()
#endif
template<class A, class B>
ostream& operator<<(ostream& o, pair<A,B> p)
{ return o << '(' << p.ff << ',' << p.ss << ')'; }

int main(){
    io;
}
```

1.2 .vimrc

```
sy on
se nu rnu bs=2 sw=4 ts=4 hls ls=2 si acd bo=all mouse=a et
map <F9> :w<bar>!g++ "%" -o %:r -std=c++17 -Wall -Wextra -
    Wshadow -Dzisk -g -fsanitize=undefined,address<CR>
map <F8> :!./%:r<CR>
map <C-a> <ESC>ggVG
inoremap {<CR> {<CR>}<ESC>ko
```

1.3 Fast IO

```
// from JAW
inline int my_getchar() {
    const int N = 1<<20;
```

```

static char buf[N];
static char *p = buf , *end = buf;
if(p == end) {
    if((end = buf + fread(buf , 1 , N , stdin)) == buf)
        return EOF;
    p = buf;
}
return *p++;
}

inline int readint(int &x) {
    static char c , neg;
    while((c = my_getchar()) < '-') {
        if(c == EOF) return 0;
    }
    neg = (c == '-') ? -1 : 1;
    x = (neg == 1) ? c - '0' : 0;
    while((c = my_getchar()) >= '0') x = (x << 3) + (x << 1)
        + (c - '0');
    x *= neg;
    return 1;
}

const int kBufSize = 524288;
char inbuf[kBufSize];
char buf[kBufSize]; size_t size_;
inline void Flush_() { write(1, buf_, size_); size_ = 0; }
inline void CheckFlush_(size_t sz) { if (sz + size_ >
    kBufSize) Flush_(); }

inline void PutInt(int a) {
    static char tmp[22] = "01234567890123456789\n";
    CheckFlush_(10);
    if(a < 0){
        *(buf_ + size_) = '-';
        a = ~a + 1;
        size_++;
    }
    int tail = 20;
    if (!a) {
        tmp[--tail] = '0';
    } else {
        for (; a; a /= 10) tmp[--tail] = (a % 10) ^ '0';
    }
    memcpy(buf_ + size_, tmp + tail, 21 - tail);
    size_ += 21 - tail;
}

int main(){
    Flush_();
    return 0;
}

```

2 Data Structure

2.1 Heavy-Light Decomposition

```

struct Heavy_light_Decomposition { // 1-base
    int n, up[maxn], dep[maxn], to[maxn], siz[maxn], pa[maxn];
    int C, ti[maxn], ord[maxn], wdown[maxn], edge[maxn], et = 0;
    vector<pii> G[maxn];
    void init(int _n) {
        n = _n, C = 0, et = 1;
        for (int i = 1; i <= n; i++)
            G[i].clear(), to[i] = 0;
    }
    void add_edge(int a, int b, int w) {
        G[a].push_back(pii(b, et)), G[b].push_back(pii(a, et));
        edge[et++] = w;
    }
    void dfs(int u, int f, int d) {
        siz[u] = 1, pa[u] = f, dep[u] = d;
        for (auto &v: G[u])

```

```

        if (v.ff != f) {
            dfs(v.ff, u, d+1), siz[u] += siz[v];
            if (siz[to[u]] < siz[v]) to[u] = v;
        }
    }
    void cut(int u, int link) {
        ti[u] = C;
        ord[C++] = u, up[u] = link;
        if (!to[u]) return;
        cut(to[u], link);
        for (auto v:G[u]) {
            if (v.ff != pa[u] && v.ff != to[u]) cut(v.ff, v.ff);
        }
    }
    void build() { dfs(1, 1, 1), cut(1, 1); }
    int query(int a, int b) {
        int ta = up[a], tb = up[b], re = 0;
        while (ta != tb)
            if (dep[ta] < dep[tb])
                /*query*/, tb = up[b = pa[tb]];
            else /*query*/, ta = up[a = pa[ta]];
        if (a == b) return re;
        if (ti[a] > ti[b]) swap(a, b);
        /*query*/
        return re;
    }
};

```

2.2 Li-Chao Tree

```

struct LiChao_min {
    struct line {
        ll m, c;
        line(ll _m = 0, ll _c = 0) {
            m = _m;
            c = _c;
        }
        ll eval(ll x) { return m * x + c; }
    };
    struct node {
        node *l, *r;
        line f;
        node(line v) {
            f = v;
            l = r = NULL;
        }
    };
    typedef node *pnode;
    pnode root;
    int sz;
#define mid ((l + r) >> 1)
    void insert(line &v, int l, int r, pnode &nd) {
        if (!nd) {
            nd = new node(v);
            return;
        }
        ll trl = nd->f.eval(l), trr = nd->f.eval(r);
        ll vl = v.eval(l), vr = v.eval(r);
        if (trl <= vl && trr <= vr) return;
        if (trl > vl && trr > vr) {
            nd->f = v;
            return;
        }
        if (trl > vl) swap(nd->f, v);
        if (nd->f.eval(mid) < v.eval(mid))
            insert(v, mid + 1, r, nd->r);
        else swap(nd->f, v), insert(v, l, mid, nd->l);
    }
    ll query(int x, int l, int r, pnode &nd) {
        if (!nd) return inf;
        if (l == r) return nd->f.eval(x);
        if (mid >= x)
            return min(
                nd->f.eval(x), query(x, l, mid, nd->l));
        return min(
            nd->f.eval(x), query(x, mid + 1, r, nd->r));
    }
};

```

```

}
/* -sz <= query_x <= sz */
void init(int _sz) {
    sz = _sz + 1;
    root = NULL;
}
void add_line(ll m, ll c) {
    line v(m, c);
    insert(v, -sz, sz, root);
}
ll query(ll x) { return query(x, -sz, sz, root); }
};

```

2.3 Link Cut Tree

```

struct Splay { // subtree-sum, path-max
    static Splay nil;
    Splay *ch[2], *f;
    int val, rev, size, vir, id, type;
    pii ma;
    Splay(int _val = 0, int _id = 0)
        : val(_val), rev(0), size(0), vir(0), id(_id) {
        ma = make_pair(val, id);
        f = ch[0] = ch[1] = &nil;
        type = 0;
    }
    bool isr() { //is root
        return f->ch[0] != this && f->ch[1] != this;
    }
    int dir() { return f->ch[0] == this ? 0 : 1; }
    void setCh(Splay *c, int d) {
        ch[d] = c;
        if (c != &nil) c->f = this;
        pull();
    }
    void push() {
        if (!rev) return;
        swap(ch[0], ch[1]);
        if (ch[0] != &nil) ch[0]->rev ^= 1;
        if (ch[1] != &nil) ch[1]->rev ^= 1;
        rev = 0;
    }
    void pull() {
        // take care of the nil!
        size = ch[0]->size + ch[1]->size + vir + type;
        ma = max(make_pair(val, id), max(ch[0]->ma, ch[1]->ma));
        if (ch[0] != &nil) ch[0]->f = this;
        if (ch[1] != &nil) ch[1]->f = this;
    }
} Splay::nil;
Splay *nil = &Splay::nil;
void rotate(Splay *x) {
    Splay *p = x->f;
    int d = x->dir();
    if (!p->isr()) p->f->setCh(x, p->dir());
    else x->f = p->f;
    p->setCh(x->ch[!d], d);
    x->setCh(p, !d);
    p->pull(), x->pull();
}
void splay(Splay *x) {
    vector<Splay*> splayVec;
    for (Splay *q = x;; q = q->f) {
        splayVec.pb(q);
        if (q->isr()) break;
    }
    reverse(iter(splayVec));
    for (auto it : splayVec) it->push();
    while (!x->isr()) {
        if (x->f->isr()) rotate(x);
        else if (x->dir() == x->f->dir())
            rotate(x->f), rotate(x);
        else rotate(x), rotate(x);
    }
}

```

```

Splay *access(Splay *x) {
    Splay *q = nil;
    for (; x != nil; x = x->f){
        splay(x);
        x->vir -= q->size; x->vir += x->ch[1]->size;
        x->setCh(q, 1); x->pull();
        q = x;
    }
    return q;
}
void root_path(Splay *x) { access(x), splay(x); }
void chroot(Splay *x) {
    root_path(x), x->rev ^= 1;
    x->push(), x->pull();
}
void split(Splay *x, Splay *y) {
    chroot(x), root_path(y);
}
void link(Splay *x, Splay *y) {
    chroot(x), root_path(y);
    x->f = y; y->vir += x->size;
}
void cut(Splay *x, Splay *y) {
    split(x, y);
    y->push();
    y->ch[0] = y->ch[0]->f = nil;
    y->pull();
}
Splay *get_root(Splay *x) {
    for (root_path(x); x->ch[0] != nil; x = x->ch[0])
        x->push();
    splay(x);
    return x;
}
bool conn(Splay *x, Splay *y) {
    return get_root(x) == get_root(y);
}
Splay *lca(Splay *x, Splay *y) {
    access(x), root_path(y);
    if (y->f == nil) return y;
    return y->f;
}
void change(Splay *x, int val) {
    splay(x), x->val = val, x->pull();
}
pii query(Splay *x, Splay *y) {
    split(x, y);
    return y->ma;
}

```

2.4 Treap

```

struct node {
    int data, sz;
    node *l, *r;
    node(int k) : data(k), sz(1), l(0), r(0) {}
    void up() {
        sz = 1;
        if (l) sz += l->sz;
        if (r) sz += r->sz;
    }
    void down() {}
};
int sz(node *a) { return a ? a->sz : 0; }
node *merge(node *a, node *b) {
    if (!a || !b) return a ? a : b;
    if (rand() % (sz(a) + sz(b)) < sz(a))
        return a->down(), a->r = merge(a->r, b), a->up(),
            a;
    return b->down(), b->l = merge(a, b->l), b->up(), b;
}
void split(node *o, node *&a, node *&b, int k) {
    if (!o) return a = b = 0, void();
    o->down();
    if (o->data <= k)
        a = o, split(o->r, a->r, b, k), a->up();
}

```

```

    else b = o, split(o->l, a, b->l, k), b->up();
}
void split2(node *o, node *&a, node *&b, int k) {
    if (sz(o) <= k) return a = o, b = 0, void();
    o->down();
    if (sz(o->l) + 1 <= k)
        a = o, split2(o->r, a->r, b, k - sz(o->l) - 1);
    else b = o, split2(o->l, a, b->l, k);
    o->up();
}
node *kth(node *o, int k) {
    if (k <= sz(o->l)) return kth(o->l, k);
    if (k == sz(o->l) + 1) return o;
    return kth(o->r, k - sz(o->l) - 1);
}
int Rank(node *o, int key) {
    if (!o) return 0;
    if (o->data < key)
        return sz(o->l) + 1 + Rank(o->r, key);
    else return Rank(o->l, key);
}
bool erase(node *&o, int k) {
    if (!o) return 0;
    if (o->data == k) {
        node *t = o;
        o->down(), o = merge(o->l, o->r);
        delete t;
        return 1;
    }
    node *&t = k < o->data ? o->l : o->r;
    return erase(t, k) ? o->up(), 1 : 0;
}
void insert(node *&o, int k) {
    node *a, *b;
    split(o, a, b, k),
        o = merge(a, merge(new node(k), b));
}
void interval(node *&o, int l, int r) {
    node *a, *b, *c;
    split2(o, a, b, l - 1), split2(b, b, c, r);
    // operate
    o = merge(a, merge(b, c));
}

```

3 Flow Matching

3.1 Bounded Flow

```

struct Dinic { // 1-base
    struct edge {
        int to, cap, flow, rev;
    };
    vector<edge> g[maxN];
    int n, s, t, dis[maxN], ind[maxN], cnt[maxN];
    const int inf = 1e9;

    void init(int _n) {
        n = _n + 2;
        s = _n + 1, t = _n + 2;
        for (int i = 0; i <= n; ++i) g[i].clear(), cnt[i] = 0;
    }
    void reset() {
        for (int i = 0; i <= n; ++i)
            for (auto &j : g[i]) j.flow = 0;
    }
    void add_edge(int u, int v, int lcap, int rcap) {
        cnt[u] -= lcap, cnt[v] += lcap;
        g[u].pb(edge{v, rcap, 0, (int)g[v].size()});
        g[v].pb(edge{u, 0, 0, (int)g[u].size() - 1});
    }
    void add_edge(int u, int v, int cap) {
        g[u].pb(edge{v, cap, 0, (int)g[v].size()});
        g[v].pb(edge{u, 0, 0, (int)g[u].size() - 1});
        //change g[v] to cap for undirected graphs
    }
}

```

```

bool bfs() {
    fill(dis, dis+n+1, -1);
    queue<int> q;
    q.push(s), dis[s] = 0;
    while (!q.empty()) {
        int cur = q.front(); q.pop();
        for (auto &e : g[cur]) {
            if (dis[e.to] == -1 && e.flow != e.cap) {
                q.push(e.to);
                dis[e.to] = dis[cur] + 1;
            }
        }
    }
    return dis[t] != -1;
}
int dfs(int u, int cap) {
    if (u == t || !cap) return cap;
    for (int &i = ind[u]; i < (int)g[u].size(); ++i) {
        edge &e = g[u][i];
        if (dis[e.to] == dis[u] + 1 && e.flow != e.cap) {
            int df = dfs(e.to, min(e.cap - e.flow, cap));
            if (df) {
                e.flow += df;
                g[e.to][e.rev].flow -= df;
                return df;
            }
        }
    }
    dis[u] = -1;
    return 0;
}
int maxflow(int _s, int _t) {
    s = _s, t = _t;
    int flow = 0, df;
    while (bfs()) {
        fill(ind, ind+n+1, 0);
        while ((df = dfs(s, inf))) flow += df;
    }
    return flow;
}
bool feasible() {
    int sum = 0;
    for (int i = 1; i <= n - 2; ++i)
        if (cnt[i] > 0)
            add_edge(n - 1, i, cnt[i]), sum += cnt[i];
        else if (cnt[i] < 0) add_edge(i, n, -cnt[i]);
    if (sum != maxflow(n - 1, n)) sum = -1;
    for (int i = 1; i <= n - 2; ++i)
        if (cnt[i] > 0)
            g[n - 1].pop_back(), g[i].pop_back();
        else if (cnt[i] < 0)
            g[i].pop_back(), g[n].pop_back();
    return sum != -1;
}
int boundedflow(int _s, int _t) {
    add_edge(_t, _s, inf);
    if (!feasible()) return -1; // infeasible flow
    int x = g[_t].back().flow;
    g[_t].pop_back(), g[_s].pop_back();

    int y = maxflow(_t, _s);
    return x-y;
}
};

```

3.2 Dinic

```

struct MaxFlow { // 1-base
    struct edge {
        int to, cap, flow, rev;
    };
    vector<edge> g[maxn];
    int s, t, dis[maxn], ind[maxn], n;

    void init(int _n) {
        n = _n + 2;
    }
}

```

```

    s = _n + 1, t = _n + 2;
    for (int i = 0; i <= n; ++i) g[i].clear();
}
void reset() {
    for (int i = 0; i <= n; ++i)
        for (auto &j : g[i]) j.flow = 0;
}
void add_edge(int u, int v, int cap) {
    g[u].pb(edge{v, cap, 0, (int)g[v].size()});
    g[v].pb(edge{u, 0, 0, (int)g[u].size() - 1});
    //change g[v] to cap for undirected graphs
}
bool bfs() {
    fill(dis, dis+n+1, -1);
    queue<int> q;
    q.push(s), dis[s] = 0;
    while (!q.empty()) {
        int cur = q.front(); q.pop();
        for (auto &e : g[cur]) {
            if (dis[e.to] == -1 && e.flow != e.cap) {
                q.push(e.to);
                dis[e.to] = dis[cur] + 1;
            }
        }
    }
    return dis[t] != -1;
}
int dfs(int u, int cap) {
    if (u == t || !cap) return cap;
    for (int &i = ind[u]; i < (int)g[u].size(); ++i) {
        edge &e = g[u][i];
        if (dis[e.to] == dis[u] + 1 && e.flow != e.cap) {
            int df = dfs(e.to, min(e.cap - e.flow, cap));
            if (df) {
                e.flow += df;
                g[e.to][e.rev].flow -= df;
                return df;
            }
        }
    }
    dis[u] = -1;
    return 0;
}
int maxflow() {
    int flow = 0, df;
    while (bfs()) {
        fill(ind, ind+n+1, 0);
        while ((df = dfs(s, inf))) flow += df;
    }
    return flow;
}
}f;
}f;

```

3.3 Gomory Hu

```

MaxFlow Dinic;
int g[MAXN];
void GomoryHu(int n) { // 0-base
    fill_n(g, n, 0);
    for (int i = 1; i < n; ++i) {
        Dinic.reset();
        add_edge(i, g[i], Dinic.maxflow(i, g[i]));
        for (int j = i + 1; j <= n; ++j)
            if (g[j] == g[i] && ~Dinic.dis[j])
                g[j] = i;
    }
}

```

3.4 Hungarian Algorithm

```

int c[maxn][maxn]; //hungarian algorithm in O(n^3)
//1 base
int lx[maxn], ly[maxn], mx[maxn], my[maxn];
bool vx[maxn], vy[maxn];
int slack[maxn];

```

```

int tot;
bool dfs(int n, bool ch) {
    if (vx[n]) return false;
    vx[n] = 1;
    for (int v = 1; v <= tot; v++) {
        slack[v] = min(slack[v], lx[n] + ly[v] - c[n][v]);
        if (lx[n] + ly[v] - c[n][v] > 0) continue;
        vy[v] = 1;
        if (!my[v] || dfs(my[v], ch)) {
            if (ch) mx[n] = v, my[v] = n;
            return true;
        }
    }
    return false;
}
int main() {
    for (int i = 1; i <= n; i++) {
        for (int j = 1; j <= n; j++) vx[j] = vy[j] = 0;
        for (int j = 1; j <= n; j++) slack[j] = 1<<30;
        if (dfs(i, 1)) continue;
        bool aug = 0;
        while (!aug) {
            for (int j = 1; j <= n; j++) {
                if (!vy[j] && slack[j] == 0) {
                    vy[j] = 1;
                    if (dfs(my[j], 0)) {
                        aug = 1;
                        break;
                    }
                }
            }
            if (aug) break;
            int delta = 1<<30;
            for (int j = 1; j <= n; j++) {
                if (!vy[j]) delta = min(delta, slack[j]);
            }
            for (int j = 1; j <= n; j++) {
                if (vx[j]) lx[j] -= delta;
                if (vy[j]) ly[j] += delta;
                else {
                    slack[j] -= delta;
                    if (slack[j] == 0 && !my[j]) aug = 1;
                }
            }
        }
        for (int j = 1; j <= n; j++) vx[j] = vy[j] = 0;
        dfs(i, 1);
    }
}

```

3.5 ISAP Algorithm

```

struct Maxflow { //to be modified
    static const int MAXV = 20010;
    static const int INF = 1000000;
    struct Edge {
        int v, c, r;
        Edge(int _v, int _c, int _r)
            : v(_v), c(_c), r(_r) {}
    };
    int s, t;
    vector<Edge> G[MAXV * 2];
    int iter[MAXV * 2], d[MAXV * 2], gap[MAXV * 2], tot;
    void init(int x) {
        tot = x + 2;
        s = x + 1, t = x + 2;
        for (int i = 0; i <= tot; i++) {
            G[i].clear();
            iter[i] = d[i] = gap[i] = 0;
        }
    }
    void addEdge(int u, int v, int c) {
        G[u].push_back(Edge(v, c, SZ(G[v])));
        G[v].push_back(Edge(u, 0, SZ(G[u]) - 1));
    }
    int dfs(int p, int flow) {

```

```

if (p == t) return flow;
for (int &i = iter[p]; i < SZ(G[p]); i++) {
    Edge &e = G[p][i];
    if (e.c > 0 && d[p] == d[e.v] + 1) {
        int f = dfs(e.v, min(flow, e.c));
        if (f) {
            e.c -= f;
            G[e.v][e.r].c += f;
            return f;
        }
    }
}
if ((--gap[d[p]]) == 0) d[s] = tot;
else {
    d[p]++;
    iter[p] = 0;
    ++gap[d[p]];
}
return 0;
}
int solve() {
    int res = 0;
    gap[0] = tot;
    for (res = 0; d[s] < tot; res += dfs(s, INF))
        ;
    return res;
}
} flow;

```

3.6 KM Algorithm

```

int n, m; //1-base, max matching
int mx[maxn], my[maxn];
bool adj[maxn][maxn], vis[maxn];
bool dfs(int n) {
    if (vis[n]) return false;
    vis[n] = 1;
    for (int v = 1; v <= n; v++) {
        if (!adj[n][v]) continue;
        if (!my[v] || (my[v] && dfs(my[v]))) {
            mx[n] = v, my[v] = n;
            return true;
        }
    }
    return false;
}
//min vertex cover: take unmatched vertex in L and find
//alternating tree,
//ans is not reached in L + reached in R

```

3.7 Max Simple Graph Matching

```

struct GenMatch { // 1-base
    int V, pr[N];
    bool el[N][N], inq[N], inp[N], inb[N];
    int st, ed, nb, bk[N], djs[N], ans;
    void init(int _V) {
        V = _V;
        for (int i = 0; i <= V; ++i) {
            for (int j = 0; j <= V; ++j) el[i][j] = 0;
            pr[i] = bk[i] = djs[i] = 0;
            inq[i] = inp[i] = inb[i] = 0;
        }
    }
    void add_edge(int u, int v) {
        el[u][v] = el[v][u] = 1;
    }
    int lca(int u, int v) {
        fill_n(inp, V + 1, 0);
        while (1)
            if (u = djs[u], inp[u] = true, u == st) break;
            else u = bk[pr[u]];
        while (1)
            if (v = djs[v], inp[v]) return v;
            else v = bk[pr[v]];
    }
}

```

```

return v;
}
void upd(int u) {
    for (int v; djs[u] != nb;) {
        v = pr[u], inb[djs[u]] = inb[djs[v]] = true;
        u = bk[v];
        if (djs[u] != nb) bk[u] = v;
    }
}
void blo(int u, int v, queue<int> &qe) {
    nb = lca(u, v), fill_n(inb, V + 1, 0);
    upd(u), upd(v);
    if (djs[u] != nb) bk[u] = v;
    if (djs[v] != nb) bk[v] = u;
    for (int tu = 1; tu <= V; ++tu)
        if (inb[djs[tu]])
            if (djs[tu] = nb, !inq[tu])
                qe.push(tu), inq[tu] = 1;
}
void flow() {
    fill_n(inq + 1, V, 0), fill_n(bk + 1, V, 0);
    iota(djs + 1, djs + V + 1, 1);
    queue<int> qe;
    qe.push(st), inq[st] = 1, ed = 0;
    while (!qe.empty()) {
        int u = qe.front();
        qe.pop();
        for (int v = 1; v <= V; ++v)
            if (el[u][v] && djs[u] != djs[v] &&
                pr[u] != v) {
                if ((v == st) ||
                    (pr[v] > 0 && bk[pr[v]] > 0)) {
                    blo(u, v, qe);
                } else if (!bk[v]) {
                    if (bk[v] = u, pr[v] > 0) {
                        if (!inq[pr[v]]) qe.push(pr[v]);
                    } else {
                        return ed = v, void();
                    }
                }
            }
    }
}
void aug() {
    for (int u = ed, v, w; u > 0;)
        v = bk[u], w = pr[v], pr[v] = u, pr[u] = v,
        u = w;
}
int solve() {
    fill_n(pr, V + 1, 0), ans = 0;
    for (int u = 1; u <= V; ++u)
        if (!pr[u])
            if (st = u, flow(), ed > 0) aug(), ++ans;
    return ans;
}
};

```

3.8 MCMF

```

struct MCMF { // 0-base
    struct edge {
        ll from, to, cap, flow, cost, rev;
    } * past[maxn];
    vector<edge> G[maxn];
    bitset<maxn> inq;
    ll dis[maxn], up[maxn], s, t, mx, n;
    bool BellmanFord(ll &flow, ll &cost) {
        fill(dis, dis + n, inf);
        queue<ll> q;
        q.push(s), inq.reset(), inq[s] = 1;
        up[s] = mx - flow, past[s] = 0, dis[s] = 0;
        while (!q.empty()) {
            ll u = q.front();
            q.pop(), inq[u] = 0;
            if (!up[u]) continue;
            for (auto &e : G[u])

```

```

    if (e.flow != e.cap &&
        dis[e.to] > dis[u] + e.cost) {
        dis[e.to] = dis[u] + e.cost, past[e.to] = &e;
        up[e.to] = min(up[u], e.cap - e.flow);
        if (!inq[e.to]) inq[e.to] = 1, q.push(e.to);
    }
}
if (dis[t] == inf) return 0;
flow += up[t], cost += up[t] * dis[t];
for (ll i = t; past[i]; i = past[i]->from) {
    auto &e = *past[i];
    e.flow += up[t], G[e.to][e.rev].flow -= up[t];
}
return 1;
}
ll MinCostMaxFlow(ll _s, ll _t, ll &cost) {
    s = _s, t = _t, cost = 0;
    ll flow = 0;
    while (BellmanFord(flow, cost));
    return flow;
}
void init(ll _n, ll _mx) {
    n = _n, mx = _mx;
    for (int i = 0; i < n; ++i) G[i].clear();
}
void add_edge(ll a, ll b, ll cap, ll cost) {
    G[a].pb(edge{a, b, cap, 0, cost, G[b].size()});
    G[b].pb(edge{b, a, 0, 0, -cost, G[a].size() - 1});
}
};

```

3.9 Min Cost Circulation

```

//to be modified
struct Edge { int to, cap, rev, cost; };
vector<Edge> g[kN];
int dist[kN], pv[kN], ed[kN];
bool mark[kN];
int NegativeCycle(int n) {
    memset(mark, false, sizeof(mark));
    memset(dist, 0, sizeof(dist));
    int upd = -1;
    for (int i = 0; i <= n; ++i) {
        for (int j = 0; j < n; ++j) {
            int idx = 0;
            for (auto &e : g[j]) {
                if (e.cap > 0 && dist[e.to] > dist[j] + e.cost) {
                    dist[e.to] = dist[j] + e.cost;
                    pv[e.to] = j, ed[e.to] = idx;
                    if (i == n) {
                        upd = j;
                        while (!mark[upd]) mark[upd] = true, upd = pv[upd];
                        return upd;
                    }
                }
            }
            idx++;
        }
    }
    return -1;
}
int Solve(int n) {
    int rt = -1, ans = 0;
    while ((rt = NegativeCycle(n)) >= 0) {
        memset(mark, false, sizeof(mark));
        vector<pair<int, int>> cyc;
        while (!mark[rt]) {
            cyc.emplace_back(pv[rt], ed[rt]);
            mark[rt] = true;
            rt = pv[rt];
        }
        reverse(cyc.begin(), cyc.end());
        int cap = kInf;
        for (auto &i : cyc) {
            auto &e = g[i.first][i.second];

```

```

            cap = min(cap, e.cap);
        }
        for (auto &i : cyc) {
            auto &e = g[i.first][i.second];
            e.cap -= cap;
            g[e.to][e.rev].cap += cap;
            ans += e.cost * cap;
        }
    }
    return ans;
}

```

3.10 SW Mincut

```

// stoer wagner algorithm: global min cut
const int maxn = 505;
struct SW { // O(V^3) 0-based
    int n, vis[maxn], del[maxn];
    int edge[maxn][maxn], wei[maxn];
    void init(int _n) {
        n = _n;
        fill(del, del+n, 0);
        for (int i = 0; i < n; ++i) fill(edge[i], edge[i] + n, 0);
    }
    void addEdge(int u, int v, int w) {
        edge[u][v] += w, edge[v][u] += w;
    }
    void search(int &s, int &t) {
        fill(vis, vis+n, 0);
        fill(wei, wei+n, 0);
        s = t = -1;
        while (1) {
            int ma = -1, cur = 0;
            for (int i = 0; i < n; ++i)
                if (!del[i] && !vis[i] && ma < wei[i])
                    cur = i, ma = wei[i];
            if (mx == -1) break;
            vis[cur] = 1, s = t, t = cur;
            for (int i = 0; i < n; ++i)
                if (!vis[i] && !del[i]) wei[i] += edge[cur][i];
        }
    }
    int solve() {
        int ret = INF;
        for (int i = 0, x=0, y=0; i < n-1; ++i) {
            search(x, y), ret = min(res, wei[y]), del[y] = 1;
            for (int j = 0; j < n; ++j)
                edge[x][j] = (edge[j][x] += edge[y][j]);
        }
        return ret;
    }
};

```

4 Geometry

4.1 Geometry Template

```

using ld = ll;
using pdd = pair<ld, ld>;
using Line = pair<pdd, pdd>;
#define X first
#define Y second
// ld eps = 1e-7;

pdd operator+(pdd a, pdd b)
{ return {a.X + b.X, a.Y + b.Y}; }
pdd operator-(pdd a, pdd b)
{ return {a.X - b.X, a.Y - b.Y}; }
pdd operator*(ld i, pdd v)
{ return {i * v.X, i * v.Y}; }
pdd operator*(pdd v, ld i)
{ return {i * v.X, i * v.Y}; }
pdd operator/(pdd v, ld i)

```

```

{ return {v.X / i, v.Y / i}; }
ld dot(pdd a, pdd b)
{ return a.X * b.X + a.Y * b.Y; }
ld cross(pdd a, pdd b)
{ return a.X * b.Y - a.Y * b.X; }
ld abs2(pdd v)
{ return v.X * v.X + v.Y * v.Y; };
ld abs(pdd v)
{ return sqrt(abs2(v)); };
int sgn(ld v)
{ return v > 0 ? 1 : (v < 0 ? -1 : 0); }
// int sgn(ld v){ return v > eps ? 1 : ( v < -eps ? -1 : 0)
; }
int ori(pdd a, pdd b, pdd c)
{ return sgn(cross(b - a, c - a)); }
bool collinearity(pdd a, pdd b, pdd c)
{ return ori(a, b, c) == 0; }
bool btw(pdd p, pdd a, pdd b)
{ return collinearity(p, a, b) && sgn(dot(a - p, b - p)) <=
0; }

bool seg_intersect(Line a, Line b){
    pdd p1, p2, p3, p4;
    tie(p1, p2) = a; tie(p3, p4) = b;
    if(btw(p1, p3, p4) || btw(p2, p3, p4) || btw(p3, p1, p2)
        || btw(p4, p1, p2))
        return true;
    return ori(p1, p2, p3) * ori(p1, p2, p4) < 0 &&
        ori(p3, p4, p1) * ori(p3, p4, p2) < 0;
}
pdd intersect(Line a, Line b){
    pdd p1, p2, p3, p4;
    tie(p1, p2) = a; tie(p3, p4) = b;
    ld a123 = cross(p2 - p1, p3 - p1);
    ld a124 = cross(p2 - p1, p4 - p1);
    return (p4 * a123 - p3 * a124) / (a123 - a124);
}
pdd perp(pdd p1)
{ return pdd(-p1.Y, p1.X); }
pdd projection(pdd p1, pdd p2, pdd p3)
{ return p1 + (p2 - p1) * dot(p3 - p1, p2 - p1) / abs2(p2 -
p1); }

```

4.2 Convex Hull

```

vector<int> getConvexHull(vector<pdd>& pts){
    vector<int> id(SZ(pts));
    iota(iter(id), 0);
    sort(iter(id), [&](int x, int y){ return pts[x] < pts[y];
    });
    vector<int> hull;
    for(int tt = 0; tt < 2; tt++){
        int sz = SZ(hull);
        for(int j : id){
            pdd p = pts[j];
            while(SZ(hull) - sz >= 2 &&
                cross(pts[hull.back()] - pts[hull[SZ(hull) - 2]],
                    p - pts[hull[SZ(hull) - 2]]) <= 0)
                hull.pop_back();
            hull.pb(j);
        }
        hull.pop_back();
        reverse(iter(id));
    }
    return hull;
}

```

4.3 Minimum Enclosing Circle

```

using ld = long double;
pair<pdd, ld> circumcenter(pdd a, pdd b, pdd c);
pair<pdd, ld> MinimumEnclosingCircle(vector<pdd> &pts){
    random_shuffle(iter(pts));
    pdd c = pts[0];
    ld r = 0;

```

```

    for(int i = 1; i < SZ(pts); i++){
        if(abs(pts[i] - c) <= r) continue;
        c = pts[i]; r = 0;
        for(int j = 0; j < i; j++){
            if(abs(pts[j] - c) <= r) continue;
            c = (pts[i] + pts[j]) / 2;
            r = abs(pts[i] - c);
            for(int k = 0; k < j; k++){
                if(abs(pts[k] - c) > r)
                    tie(c, r) = circumcenter(pts[i], pts[j], pts[k]);
            }
        }
    }
    return {c, r};
}

```

4.4 Minkowski Sum

```

void reorder_poly(vector<pdd>& pnts){
    int mn = 0;
    for(int i = 1; i < (int)pnts.size(); i++)
        if(pnts[i].Y < pnts[mn].Y || (pnts[i].Y == pnts[mn].Y
            && pnts[i].X < pnts[mn].X))
            mn = i;
    rotate(pnts.begin(), pnts.begin() + mn, pnts.end());
}

vector<pdd> minkowski(vector<pdd> P, vector<pdd> Q){
    reorder_poly(P);
    reorder_poly(Q);
    int psz = P.size();
    int qsz = Q.size();
    P.pb(P[0]); P.pb(P[1]); Q.pb(Q[0]); Q.pb(Q[1]);
    vector<pdd> ans;
    int i = 0, j = 0;
    while(i < psz || j < qsz){
        ans.pb(P[i] + Q[j]);
        int t = sgn(cross(P[i + 1] - P[i], Q[j + 1] - Q[j]));
        if(t >= 0) i++;
        if(t <= 0) j++;
    }
    return ans;
}

```

4.5 Polar Angle Comparator

```

// -1: a // b (if same), 0/1: a < b
int cmp(p11 a, p11 b, bool same = true){
#define is_neg(k) (sgn(k.Y) < 0 || (sgn(k.Y) == 0 && sgn(k.
X) < 0))
    int A = is_neg(a), B = is_neg(b);
    if(A != B)
        return A < B;
    if(sgn(cross(a, b)) == 0)
        return same ? abs2(a) < abs2(b) : -1;
    return sgn(cross(a, b)) > 0;
}

```

4.6 Half Plane Intersection

```

// from 8BQube
p11 area_pair(Line a, Line b)
{ return p11(cross(a.Y - a.X, b.X - a.X), cross(a.Y - a.X,
    b.Y - a.X)); }
bool isin(Line l0, Line l1, Line l2) {
    // Check inter(l1, l2) strictly in l0
    auto [a02X, a02Y] = area_pair(l0, l2);
    auto [a12X, a12Y] = area_pair(l1, l2);
    if (a12X - a12Y < 0) a12X *= -1, a12Y *= -1;
    return ((__int128) a02Y * a12X - ((__int128) a02X * a12Y >
        0; // C^4
}
/* Having solution, check size > 2 */

```



```

/* --^-- Line.X --^-- Line.Y --^-- */
vector<Line> halfPlaneInter(vector<Line> arr) {
    sort(iter(arr), [&](Line a, Line b) -> int {
        if (cmp(a.Y - a.X, b.Y - b.X, 0) != -1)
            return cmp(a.Y - a.X, b.Y - b.X, 0);
        return ori(a.X, a.Y, b.Y) < 0;
    });
    deque<Line> dq(1, arr[0]);
    for (auto p : arr) {
        if (cmp(dq.back().Y - dq.back().X, p.Y - p.X, 0) == -1)
            continue;
        while (SZ(dq) >= 2 && !isin(p, dq[SZ(dq) - 2], dq.back()))
            dq.pop_back();
        while (SZ(dq) >= 2 && !isin(p, dq[0], dq[1]))
            dq.pop_front();
        dq.pb(p);
    }
    while (SZ(dq) >= 3 && !isin(dq[0], dq[SZ(dq) - 2], dq.back()))
        dq.pop_back();
    while (SZ(dq) >= 3 && !isin(dq.back(), dq[0], dq[1]))
        dq.pop_front();
    return vector<Line>(iter(dq));
}

```

4.7 Dynamic Convex Hull

```

struct Line{
    ll a, b, l = MIN, r = MAX;
    Line(ll a, ll b): a(a), b(b) {}
    ll operator()(ll x) const{
        return a * x + b;
    }
    bool operator<(Line b) const{
        return a < b.a;
    }
    bool operator<(ll b) const{
        return r < b;
    }
};

ll iceil(ll a, ll b){
    if(b < 0) a *= -1, b *= -1;
    if(a > 0) return (a + b - 1) / b;
    else return a / b;
}

ll intersect(Line a, Line b){
    return iceil(a.b - b.b, b.a - a.a);
}

struct DynamicConvexHull{
    multiset<Line, less<>> ch;

    void add(Line ln){
        auto it = ch.lower_bound(ln);
        while(it != ch.end()){
            Line tl = *it;
            if(tl(tl.r) <= ln(tl.r)){
                it = ch.erase(it);
            }
            else break;
        }
        auto it2 = ch.lower_bound(ln);
        while(it2 != ch.begin()){
            Line tl = *prev(it2);
            if(tl(tl.l) <= ln(tl.l)){
                it2 = ch.erase(prev(it2));
            }
            else break;
        }
        it = ch.lower_bound(ln);
        if(it != ch.end()){
            Line tl = *it;
            if(tl(tl.l) >= ln(tl.l)) ln.r = tl.l - 1;

```

```

        else{
            ll pos = intersect(ln, tl);
            tl.l = pos;
            ln.r = pos - 1;
            ch.erase(it);
            ch.insert(tl);
        }
    }
    it2 = ch.lower_bound(ln);
    if(it2 != ch.begin()){
        Line tl = *prev(it2);
        if(tl(tl.r) >= ln(tl.r)) ln.l = tl.r + 1;
        else{
            ll pos = intersect(tl, ln);
            tl.r = pos - 1;
            ln.l = pos;
            ch.erase(prev(it2));
            ch.insert(tl);
        }
    }
    if(ln.l <= ln.r) ch.insert(ln);
}

ll query(ll pos){
    auto it = ch.lower_bound(pos);
    if(it == ch.end()) return 0;
    return (*it)(pos);
}
};

```

4.8 3D Point

```

// Copy from 8BQube
struct Point {
    double x, y, z;
    Point(double _x = 0, double _y = 0, double _z = 0): x(_x), y(_y), z(_z){}
    Point(pdd p) { x = p.X, y = p.Y, z = abs2(p); }
};

Point operator-(const Point &p1, const Point &p2)
{ return Point(p1.x - p2.x, p1.y - p2.y, p1.z - p2.z); }
Point cross(const Point &p1, const Point &p2)
{ return Point(p1.y * p2.z - p1.z * p2.y, p1.z * p2.x - p1.x * p2.z, p1.x * p2.y - p1.y * p2.x); }
double dot(const Point &p1, const Point &p2)
{ return p1.x * p2.x + p1.y * p2.y + p1.z * p2.z; }
double abs(const Point &a)
{ return sqrt(dot(a, a)); }
Point cross3(const Point &a, const Point &b, const Point &c)
{ return cross(b - a, c - a); }
double area(Point a, Point b, Point c)
{ return abs(cross3(a, b, c)); }
double volume(Point a, Point b, Point c, Point d)
{ return dot(cross3(a, b, c), d - a); }
pdd proj(Point a, Point b, Point c, Point u) {
    // proj. u to the plane of a, b, and c
    Point e1 = b - a;
    Point e2 = c - a;
    e1 = e1 / abs(e1);
    e2 = e2 - e1 * dot(e2, e1);
    e2 = e2 / abs(e2);
    Point p = u - a;
    return pdd(dot(p, e1), dot(p, e2));
}

```

4.9 ConvexHull3D

```

// Copy from 8BQube
struct CH3D {
    struct face{int a, b, c; bool ok;} F[8 * N];
    double dblcmp(Point &p, face &f)
    {return dot(cross3(P[f.a], P[f.b], P[f.c]), p - P[f.a]);}
    int g[N][N], num, n;
    Point P[N];

```

```

void deal(int p,int a,int b) {
    int f = g[a][b];
    face add;
    if (F[f].ok) {
        if (dblcmp(P[p],F[f]) > eps) dfs(p,f);
        else
            add.a = b, add.b = a, add.c = p, add.ok = 1, g[p][b]
                = g[a][p] = g[b][a] = num, F[num++] = add;
    }
}

void dfs(int p, int now) {
    F[now].ok = 0;
    deal(p, F[now].b, F[now].a), deal(p, F[now].c, F[now].b),
        deal(p, F[now].a, F[now].c);
}

bool same(int s,int t){
    Point &a = P[F[s].a];
    Point &b = P[F[s].b];
    Point &c = P[F[s].c];
    return fabs(volume(a, b, c, P[F[t].a])) < eps && fabs(
        volume(a, b, c, P[F[t].b])) < eps && fabs(volume(a,
            b, c, P[F[t].c])) < eps;
}

void init(int _n){n = _n, num = 0;}
void solve() {
    face add;
    num = 0;
    if(n < 4) return;
    if([&](){
        for (int i = 1; i < n; ++i)
            if (abs(P[0] - P[i]) > eps)
                return swap(P[1], P[i]), 0;
        return 1;
    }() || [&](){
        for (int i = 2; i < n; ++i)
            if (abs(cross3(P[i], P[0], P[1])) > eps)
                return swap(P[2], P[i]), 0;
        return 1;
    }() || [&](){
        for (int i = 3; i < n; ++i)
            if (fabs(dot(cross(P[0] - P[1], P[1] - P[2]), P[0]
                - P[i])) > eps)
                return swap(P[3], P[i]), 0;
        return 1;
    }())return;
    for (int i = 0; i < 4; ++i) {
        add.a = (i + 1) % 4, add.b = (i + 2) % 4, add.c = (i
            + 3) % 4, add.ok = true;
        if (dblcmp(P[i],add) > 0) swap(add.b, add.c);
        g[add.a][add.b] = g[add.b][add.c] = g[add.c][add.a] =
            num;
        F[num++] = add;
    }
    for (int i = 4; i < n; ++i)
        for (int j = 0; j < num; ++j)
            if (F[j].ok && dblcmp(P[i],F[j]) > eps) {
                dfs(i, j);
                break;
            }
    for (int tmp = num, i = (num = 0); i < tmp; ++i)
        if (F[i].ok) F[num++] = F[i];
}

double get_area() {
    double res = 0.0;
    if (n == 3)
        return abs(cross3(P[0], P[1], P[2])) / 2.0;
    for (int i = 0; i < num; ++i)
        res += area(P[F[i].a], P[F[i].b], P[F[i].c]);
    return res / 2.0;
}

double get_volume() {
    double res = 0.0;
    for (int i = 0; i < num; ++i)
        res += volume(Point(0, 0, 0), P[F[i].a], P[F[i].b], P
            [F[i].c]);
    return fabs(res / 6.0);
}

```

```

int triangle() {return num;}
int polygon() {
    int res = 0;
    for (int i = 0, flag = 1; i < num; ++i, res += flag,
        flag = 1)
        for (int j = 0; j < i && flag; ++j)
            flag &= !same(i,j);
    return res;
}

Point getcent(){
    Point ans(0, 0, 0), temp = P[F[0].a];
    double v = 0.0, t2;
    for (int i = 0; i < num; ++i)
        if (F[i].ok == true) {
            Point p1 = P[F[i].a], p2 = P[F[i].b], p3 = P[F[i].c]
                ;
            t2 = volume(temp, p1, p2, p3) / 6.0;
            if (t2 > 0)
                ans.x += (p1.x + p2.x + p3.x + temp.x) * t2, ans.
                    y += (p1.y + p2.y + p3.y + temp.y) * t2, ans.
                        z += (p1.z + p2.z + p3.z + temp.z) * t2, v +=
                            t2;
        }
    ans.x /= (4 * v), ans.y /= (4 * v), ans.z /= (4 * v);
    return ans;
}

double pointmindis(Point p) {
    double rt = 99999999;
    for(int i = 0; i < num; ++i)
        if(F[i].ok == true) {
            Point p1 = P[F[i].a], p2 = P[F[i].b], p3 = P[F[i].c]
                ;
            double a = (p2.y - p1.y) * (p3.z - p1.z) - (p2.z -
                p1.z) * (p3.y - p1.y);
            double b = (p2.z - p1.z) * (p3.x - p1.x) - (p2.x -
                p1.x) * (p3.z - p1.z);
            double c = (p2.x - p1.x) * (p3.y - p1.y) - (p2.y -
                p1.y) * (p3.x - p1.x);
            double d = 0 - (a * p1.x + b * p1.y + c * p1.z);
            double temp = fabs(a * p.x + b * p.y + c * p.z + d)
                / sqrt(a * a + b * b + c * c);
            rt = min(rt, temp);
        }
    return rt;
}
};

```

4.10 Circle Operations

```

// from 8BQube
const double PI=acos(-1);
vector<pdd> circleLineIntersection(pdd c, double r, pdd a,
    pdd b) {
    pdd p = a + (b - a) * dot(c - a, b - a) / abs2(b - a);
    double s = cross(b - a, c - a), h2 = r * r - s * s / abs2
        (b - a);
    if (h2 < 0) return {};
    if (h2 == 0) return {p};
    pdd h = (b - a) / abs(b - a) * sqrt(h2);
    return {p - h, p + h};
}

double _area(pdd pa, pdd pb, double r){
    if(abs(pa)<abs(pb)) swap(pa, pb);
    if(abs(pb)<eps) return 0;
    double S, h, theta;
    double a=abs(pb),b=abs(pa),c=abs(pb-pa);
    double cosB = dot(pb,pb-pa) / a / c, B = acos(cosB);
    double cosC = dot(pa,pb) / a / b, C = acos(cosC);
    if(a > r){
        S = (C/2)*r*r;
        h = a*b*sin(C)/c;
        if (h < r && B < PI/2) S -= (acos(h/r)*r*r - h*sqrt(r*r
            -h*h));
    }
    else if(b > r){
        theta = PI - B - asin(sin(B)/r*a);
    }
}

```

```

    S = .5*a*r*sin(theta) + (C-theta)/2*r*r;
}
else S = .5*sin(C)*a*b;
return S;
}
double areaPolyCircle(const vector<pdd> poly, const pdd &O,
    const double r){
    double S=0;
    for(int i=0; i<SZ(poly); ++i)
        S += _area(poly[i]-O, poly[(i+1)%SZ(poly)]-O, r)*ori(O, poly
            [i], poly[(i+1)%SZ(poly)]);
    return fabs(S);
}
bool CCinter(Cir &a, Cir &b, pdd &p1, pdd &p2) {
    pdd o1 = a.O, o2 = b.O;
    double r1 = a.R, r2 = b.R, d2 = abs2(o1 - o2), d = sqrt(
        d2);
    if(d < max(r1, r2) - min(r1, r2) || d > r1 + r2) return
        0;
    pdd u = (o1 + o2) * 0.5 + (o1 - o2) * ((r2 * r2 - r1 * r1
        ) / (2 * d2));
    double A = sqrt((r1 + r2 + d) * (r1 - r2 + d) * (r1 + r2
        - d) * (-r1 + r2 + d));
    pdd v = pdd(o1.Y - o2.Y, -o1.X + o2.X) * A / (2 * d2);
    p1 = u + v, p2 = u - v;
    return 1;
}
vector<Line> CCTang( const Cir& c1 , const Cir& c2 , int
    sign1 ){
    vector<Line> ret;
    double d_sq = abs2( c1.O - c2.O );
    if (sgn(d_sq) == 0) return ret;
    double d = sqrt(d_sq);
    pdd v = (c2.O - c1.O) / d;
    double c = (c1.R - sign1 * c2.R) / d; // cos t
    if (c * c > 1) return ret;
    double h = sqrt(max( 0.0, 1.0 - c * c )); // sin t
    for (int sign2 = 1; sign2 >= -1; sign2 -= 2) {
        pdd n = pdd(v.X * c - sign2 * h * v.Y,
            v.Y * c + sign2 * h * v.X);
        pdd p1 = c1.O + n * c1.R;
        pdd p2 = c2.O + n * (c2.R * sign1);
        if (sgn(p1.X - p2.X) == 0 and
            sgn(p1.Y - p2.Y) == 0)
            p2 = p1 + perp(c2.O - c1.O);
        ret.pb(Line(p1, p2));
    }
    return ret;
}

```

4.11 Delaunay Triangulation

```

// from 8BQube
/* Delaunay Triangulation:
Given a sets of points on 2D plane, find a
triangulation such that no points will strictly
inside circumcircle of any triangle.
find : return a triangle contain given point
add_point : add a point into triangulation
A Triangle is in triangulation iff. its has_chd is 0.
Region of triangle u: iterate each u.edge[i].tri,
each points are u.p[(i+1)%3], u.p[(i+2)%3]
Voronoi diagram: for each triangle in triangulation,
the bisector of all its edges will split the region.
nearest point will belong to the triangle containing it
*/
const ll inf = MAXC * MAXC * 100; // Lower_bound unknown
struct Tri;
struct Edge {
    Tri* tri; int side;
    Edge(): tri(0), side(0){}
    Edge(Tri* _tri, int _side): tri(_tri), side(_side){}
};
struct Tri {
    pll p[3];
    Edge edge[3];

```

```

    Tri* chd[3];
    Tri() {}
    Tri(const pll& p0, const pll& p1, const pll& p2) {
        p[0] = p0; p[1] = p1; p[2] = p2;
        chd[0] = chd[1] = chd[2] = 0;
    }
    bool has_chd() const { return chd[0] != 0; }
    int num_chd() const {
        return !!chd[0] + !!chd[1] + !!chd[2];
    }
    bool contains(pll const& q) const {
        for (int i = 0; i < 3; ++i)
            if (ori(p[i], p[(i + 1) % 3], q) < 0)
                return 0;
        return 1;
    }
} pool[N * 10], *tris;
void edge(Edge a, Edge b) {
    if(a.tri) a.tri->edge[a.side] = b;
    if(b.tri) b.tri->edge[b.side] = a;
}
struct Trig { // Triangulation
    Trig() {
        the_root = // Tri should at least contain all points
            new(tris++) Tri(pll(-inf, -inf), pll(inf + inf, -inf),
                pll(-inf, inf + inf));
    }
    Tri* find(pll p) { return find(the_root, p); }
    void add_point(const pll &p) { add_point(find(the_root, p),
        p); }
    Tri* the_root;
    static Tri* find(Tri* root, const pll &p) {
        while (1) {
            if (!root->has_chd())
                return root;
            for (int i = 0; i < 3 && root->chd[i]; ++i)
                if (root->chd[i]->contains(p)) {
                    root = root->chd[i];
                    break;
                }
        }
        assert(0); // "point not found"
    }
    void add_point(Tri* root, pll const& p) {
        Tri* t[3];
        /* split it into three triangles */
        for (int i = 0; i < 3; ++i)
            t[i] = new(tris++) Tri(root->p[i], root->p[(i + 1) %
                3], p);
        for (int i = 0; i < 3; ++i)
            edge(Edge(t[i], 0), Edge(t[(i + 1) % 3], 1));
        for (int i = 0; i < 3; ++i)
            edge(Edge(t[i], 2), root->edge[(i + 2) % 3]);
        for (int i = 0; i < 3; ++i)
            root->chd[i] = t[i];
        for (int i = 0; i < 3; ++i)
            flip(t[i], 2);
    }
    void flip(Tri* tri, int pi) {
        Tri* trj = tri->edge[pi].tri;
        int pj = tri->edge[pi].side;
        if (!trj) return;
        if (!in_cc(tri->p[0], tri->p[1], tri->p[2], trj->p[pj])
            ) return;
        /* flip edge between tri, trj */
        Tri* trk = new(tris++) Tri(tri->p[(pi + 1) % 3], trj->p[
            pj], tri->p[pi]);
        Tri* trl = new(tris++) Tri(trj->p[(pj + 1) % 3], tri->p[
            pi], trj->p[pj]);
        edge(Edge(trk, 0), Edge(trl, 0));
        edge(Edge(trk, 1), tri->edge[(pi + 2) % 3]);
        edge(Edge(trk, 2), trj->edge[(pj + 1) % 3]);
        edge(Edge(trl, 1), trj->edge[(pj + 2) % 3]);
        edge(Edge(trl, 2), tri->edge[(pi + 1) % 3]);
        tri->chd[0] = trk; tri->chd[1] = trl; tri->chd[2] = 0;
        trj->chd[0] = trk; trj->chd[1] = trl; trj->chd[2] = 0;
        flip(trk, 1); flip(trk, 2);
    }

```

```

    flip(trl, 1); flip(trl, 2);
}
};
vector<Tri*> triang; // vector of all triangle
set<Tri*> vst;
void go(Tri* now) { // store all tri into triang
    if (vst.find(now) != vst.end())
        return;
    vst.insert(now);
    if (!now->has_chd())
        return triang.pb(now);
    for (int i = 0; i < now->num_chd(); ++i)
        go(now->chd[i]);
}
void build(int n, pll* ps) { // build triangulation
    tris = pool; triang.clear(); vst.clear();
    random_shuffle(ps, ps + n);
    Trig tri; // the triangulation structure
    for (int i = 0; i < n; ++i)
        tri.add_point(ps[i]);
    go(tri.the_root);
}

```

4.12 Voronoi Diagram

```

// from 8BQube
vector<Line> ls[N];
pll arr[N];
Line make_line(pdd p, Line l) {
    pdd d = 1.Y - 1.X; d = perp(d);
    pdd m = (1.X + 1.Y) / 2;
    l = Line(m, m + d);
    if (ori(1.X, 1.Y, p) < 0)
        l = Line(m + d, m);
    return l;
}
double calc_area(int id) {
    // use to calculate the area of point "strictly in the
    // convex hull"
    vector<Line> hpi = halfPlaneInter(ls[id]);
    vector<pdd> ps;
    for (int i = 0; i < SZ(hpi); ++i)
        ps.pb(intersect(hpi[i].X, hpi[i].Y, hpi[(i + 1) % SZ(
            hpi)].X, hpi[(i + 1) % SZ(hpi)].Y));
    double rt = 0;
    for (int i = 0; i < SZ(ps); ++i)
        rt += cross(ps[i], ps[(i + 1) % SZ(ps)]);
    return fabs(rt) / 2;
}
void solve(int n, pii *oarr) {
    map<pll, int> mp;
    for (int i = 0; i < n; ++i)
        arr[i] = pll(oarr[i].X, oarr[i].Y), mp[arr[i]] = i;
    build(n, arr); // Triangulation
    for (auto *t : triang) {
        vector<int> p;
        for (int i = 0; i < 3; ++i)
            if (mp.find(t->p[i]) != mp.end())
                p.pb(mp[t->p[i]]);
        for (int i = 0; i < SZ(p); ++i)
            for (int j = i + 1; j < SZ(p); ++j) {
                Line l(oarr[p[i]], oarr[p[j]]);
                ls[p[i]].pb(make_line(oarr[p[i]], l));
                ls[p[j]].pb(make_line(oarr[p[j]], l));
            }
    }
}

```

5 Graph

5.1 Block Cut Tree

```

struct BlockCutTree{
    vector<vector<int>> tree; // 1-based

```

```

    vector<int> node;
    vector<int> type; // 0:square, 1:circle

    bool iscut(int v){
        return type[node[v]] == 1;
    }

    vector<int> getbcc(int v){
        if(!iscut(v)) return {node[v]};
        vector<int> ans;
        for(int i : tree[node[v]])
            ans.pb(i);
        return ans;
    }

```

```

    void build(int n, vector<vector<int>>& g){
        tree.resize(2 * n + 1);
        type.resize(2 * n + 1);
        node.resize(n + 1, -1);
        vector<int> in(n + 1);
        vector<int> low(n + 1);
        stack<int> st;

```

```

        int ts = 1;
        int bcc = 1;
        auto addv = [&](int id, int v){
            if(node[v] == -1){
                node[v] = id;
                return;
            }
            if(type[node[v]] == 0){
                int o = node[v];
                node[v] = bcc++;
                type[node[v]] = 1;
                tree[o].pb(node[v]);
                tree[node[v]].pb(o);
            }
            tree[id].pb(node[v]);
            tree[node[v]].pb(id);
        };
        function<void(int, int)> dfs = [&](int now, int p){
            in[now] = low[now] = ts++;
            st.push(now);
            int child = 0;
            for(int i : g[now]){
                if(i == p) continue;
                if(in[i]){
                    low[now] = min(low[now], in[i]);
                    continue;
                }
                child++;
                dfs(i, now);
                low[now] = min(low[now], low[i]);

                if(low[i] >= in[now]){
                    int nowid = bcc++;
                    while(true){
                        int x = st.top();
                        st.pop();
                        addv(nowid, x);
                        if(x == i) break;
                    }
                    addv(nowid, now);
                }
            }
            if(child == 0 && now == p) addv(bcc++, now);
        };
        dfs(1, 1);
    }
};

```

5.2 2-SAT

```

struct SAT{ // 0-based, [n, 2n) is neg of [0, n)
    int n;
    vector<vector<int>> g, rg;

```

```

bool ok = true;
vector<bool> ans;

void init(int _n){
    n = _n;
    g.resize(2 * n);
    rg.resize(2 * n);
    ans.resize(n);
}

int neg(int v){
    return v < n ? v + n : v - n;
}

void addEdge(int u, int v){
    g[u].pb(v);
    rg[v].pb(u);
}

void addClause(int a, int b){
    addEdge(neg(a), b);
    addEdge(neg(b), a);
}

void build(){
    vector<bool> vst(2 * n, false);
    vector<int> tmp, scc(2 * n, -1);
    int cnt = 1;
    function<void(int)> dfs = [&](int now){
        vst[now] = true;
        for(int i : rg[now]){
            if(vst[i]) continue;
            dfs(i);
        }
        tmp.pb(now);
    };
    for(int i = 0; i < 2 * n; i++){
        if(!vst[i]) dfs(i);
    }
    reverse(all(tmp));
    function<void(int, int)> dfs2 = [&](int now, int id){
        scc[now] = id;
        for(int i : g[now]){
            if(scc[i] != -1) continue;
            dfs2(i, id);
        }
    };
    for(int i : tmp){
        if(scc[i] == -1) dfs2(i, cnt++);
    }
    debug(scc);
    for(int i = 0; i < n; i++){
        if(scc[i] == scc[neg(i)]){
            ok = false;
            return;
        }
        if(scc[i] < scc[neg(i)]) ans[i] = true;
        else ans[i] = false;
    }
}

};

```

5.3 Dominator Tree

```

// copy from 8BQube
struct dominator_tree { // 1-base
    vector<int> G[N], rG[N];
    int n, pa[N], dfn[N], id[N], Time;
    int semi[N], idom[N], best[N];
    vector<int> tree[N]; // dominator_tree
    void init(int _n) {
        n = _n;
        for (int i = 1; i <= n; ++i)
            G[i].clear(), rG[i].clear();
    }
    void add_edge(int u, int v) {
        G[u].pb(v), rG[v].pb(u);
    }
    void dfs(int u) {

```

```

        id[dfn[u] = ++Time] = u;
        for (auto v : G[u])
            if (!dfn[v]) dfs(v), pa[dfn[v]] = dfn[u];
    }
    int find(int y, int x) {
        if (y <= x) return y;
        int tmp = find(pa[y], x);
        if (semi[best[y]] > semi[best[pa[y]]])
            best[y] = best[pa[y]];
        return pa[y] = tmp;
    }
    void tarjan(int root) {
        Time = 0;
        for (int i = 1; i <= n; ++i) {
            dfn[i] = idom[i] = 0;
            tree[i].clear();
            best[i] = semi[i] = i;
        }
        dfs(root);
        for (int i = Time; i > 1; --i) {
            int u = id[i];
            for (auto v : rG[u])
                if (v = dfn[v]) {
                    find(v, i);
                    semi[i] = min(semi[i], semi[best[v]]);
                }
            tree[semi[i]].pb(i);
            for (auto v : tree[pa[i]]) {
                find(v, pa[i]);
                idom[v] =
                    semi[best[v]] == pa[i] ? pa[i] : best[v];
            }
            tree[pa[i]].clear();
        }
        for (int i = 2; i <= Time; ++i) {
            if (idom[i] != semi[i]) idom[i] = idom[idom[i]];
            tree[id[idom[i]]].pb(id[i]);
        }
    }
};

```

5.4 Virtual Tree

```

// copy from 8BQube
vector<int> vG[N];
int top, st[N];

void insert(int u) {
    if (top == -1) return st[++top] = u, void();
    int p = LCA(st[top], u);
    if (p == st[top]) return st[++top] = u, void();
    while (top >= 1 && dep[st[top - 1]] >= dep[p])
        vG[st[top - 1]].pb(st[top]), --top;
    if (st[top] != p)
        vG[p].pb(st[top]), --top, st[++top] = p;
    st[++top] = u;
}

void reset(int u) {
    for (int i : vG[u]) reset(i);
    vG[u].clear();
}

```

```

void solve(vector<int> &v) {
    top = -1;
    sort(ALL(v),
        [&](int a, int b) { return dfn[a] < dfn[b]; });
    for (int i : v) insert(i);
    while (top > 0) vG[st[top - 1]].pb(st[top]), --top;
    // do something
    reset(v[0]);
}

```

5.5 Directed Minimum Spanning Tree

```

const ll INF = LLONG_MAX;
struct edge{
    int u = -1, v = -1;
    ll w = INF;
    int id = -1;
};

// 0-based, E[i].id = i
bool DMST(int n, vector<edge> &E, int root, vector<edge> &
    sol){
    vector<int> id(n), vis(n);
    vector<edge> in(n);
    for(edge e : E)
        if(e.u != e.v && e.w < in[e.v].w && e.v != root)
            in[e.v] = e;
    for(int i = 0; i < n; i++)
        if(i != root && in[i].u == -1) return false; // no sol
    int cnt = 0;
    fill(iter(id), -1); fill(iter(vis), -1);
    for(int u = 0; u < n; u++){
        int v = u;
        while(vis[v] != u && id[v] == -1 && in[v].u != -1)
            vis[v] = u, v = in[v].u;
        if(v != root && id[v] == -1){
            for(int x = in[v].u; x != v; x = in[x].u)
                id[x] = cnt;
            id[v] = cnt++;
        }
    }
    if(!cnt) return sol = in, true; // no cycle
    for(int u = 0; u < n; u++)
        if(id[u] == -1) id[u] = cnt++;
    vector<edge> nE;
    for(int i = 0; i < SZ(E); i++){
        edge tmp = E[i];
        tmp.u = id[tmp.u], tmp.v = id[tmp.v];
        if(in[E[i].v].w != INF) tmp.w -= in[E[i].v].w;
        nE.pb(tmp);
    }
    vector<edge> tsol;
    if(!DMST(cnt, nE, id[root], tsol)) return false;
    sol.resize(n);
    for(int i = 0; i < cnt; i++){
        if(i == id[root]) continue;
        int t = tsol[i].id;
        sol[E[t].v] = E[t];
    }
    for(int i = 0; i < n; i++)
        if(sol[i].id == -1) sol[i] = in[i];
    return true;
}

```

5.6 Vizing

```

// find D+1 edge coloring of a graph with max deg D
struct vizing { // returns edge coloring in adjacent matrix
    G. 1 - based
    const int N = 105;
    int C[N][N], G[N][N], X[N], vst[N], n; // ans: G[i][j]
    void init(int _n) { n = _n; // n = |V|+1
        for (int i = 0; i <= n; ++i)
            for (int j = 0; j <= n; ++j)
                C[i][j] = G[i][j] = 0;
    }
    void solve(vector<pii> &E) {
        auto update = [&](int u)
        { for (X[u] = 1; C[u][X[u]]; ++X[u]); };
        auto color = [&](int u, int v, int c) {
            int p = G[u][v];
            G[u][v] = G[v][u] = c;
            C[u][c] = v, C[v][c] = u;
            C[u][p] = C[v][p] = 0;
            if (p) X[u] = X[v] = p;
            else update(u), update(v);
            return p;
        };
    }
};

```

```

auto flip = [&](int u, int c1, int c2) {
    int p = C[u][c1];
    swap(C[u][c1], C[u][c2]);
    if (p) G[u][p] = G[p][u] = c2;
    if (!C[u][c1]) X[u] = c1;
    if (!C[u][c2]) X[u] = c2;
    return p;
};
fill_n(X + 1, n, 1);
for (int t = 0; t < SZ(E); ++t) {
    int u = E[t].X, v0 = E[t].Y, v = v0, c0 = X[u], c =
        c0, d;
    vector<pii> L;
    fill_n(vst + 1, n, 0);
    while (!G[u][v0]) {
        L.emplace_back(v, d = X[v]);
        if (!C[v][c]) for (int a = SZ(L) - 1; a >= 0; --a)
            c = color(u, L[a].X, c);
        else if (!C[u][d]) for (int a = SZ(L) - 1; a >= 0;
            --a) color(u, L[a].X, L[a].Y);
        else if (vst[d]) break;
        else vst[d] = 1, v = C[u][d];
    }
    if (!G[u][v0]) {
        for (; v; v = flip(v, c, d), swap(c, d));
        if (int a; C[u][c0]) {
            for (a = SZ(L) - 2; a >= 0 && L[a].Y != c; --a);
            for (; a >= 0; --a) color(u, L[a].X, L[a].Y);
        }
        else --t;
    }
}
};

```

6 Math

6.1 Extended Euclidean Algorithm

```

// ax+ny = 1, ax+ny == ax == 1 (mod n)
void extgcd(ll x, ll y, ll &g, ll &a, ll &b) {
    if (y == 0) g = x, a = 1, b = 0;
    else extgcd(y, x%y, g, b, a), b -= (x/y)*a;
}

```

6.2 Floor & Ceil

```

int floor_div(int a, int b){
    return a/b - (a%b && a < 0 ^ b < 0);
}
int ceil_div(int a, int b){
    return a/b + (a%b && a < 0 ^ b > 0);
}

```

6.3 Legendre

```

// the Jacobi symbol is a generalization of the Legendre
// symbol,
// such that the bottom doesn't need to be prime.
// (n/p) -> same as Legendre
// (n/ab) = (n/a)(n/b)
// work with Long Long
int Jacobi(int a, int m) {
    int s = 1;
    for (; m > 1; ) {
        a %= m;
        if (a == 0) return 0;
        const int r = __builtin_ctz(a);
        if ((r & 1) && ((m + 2) & 4)) s = -s;
        a >>= r;
        if (a & m & 2) s = -s;
        swap(a, m);
    }
}

```

```

    }
    return s;
}

// 0: a == 0
// -1: a isn't a quad res of p
// else: return X with X^2 % p == a
// doesn't work with Long Long
int QuadraticResidue(int a, int p) {
    if (p == 2) return a & 1;
    const int jc = Jacobi(a, p);
    if (jc == 0) return 0;
    if (jc == -1) return -1;
    int b, d;
    for ( ; ; ) {
        b = rand() % p;
        d = (1LL * b * b + p - a) % p;
        if (Jacobi(d, p) == -1) break;
    }
    int f0 = b, f1 = 1, g0 = 1, g1 = 0, tmp;
    for (int e = (1LL + p) >> 1; e >= 1; e >>= 1) {
        if (e & 1) {
            tmp = (1LL * g0 * f0 + 1LL * d * (1LL * g1 * f1 % p))
                % p;
            g1 = (1LL * g0 * f1 + 1LL * g1 * f0) % p;
            g0 = tmp;
        }
        tmp = (1LL * f0 * f0 + 1LL * d * (1LL * f1 * f1 % p)) %
            p;
        f1 = (2LL * f0 * f1) % p;
        f0 = tmp;
    }
    return g0;
}

```

6.4 Simplex

```

#pragma once

typedef double T; // Long double, Rational, double + mod<P>
>...
typedef vector<T> vd;
typedef vector<vd> vvd;

const T eps = 1e-8, inf = 1/.0;
#define MP make_pair
#define ltj(X) if(s == -1 || MP(X[j],N[j]) < MP(X[s],N[s]))
    s=j

struct LPSolver {
    int m, n;
    vi N, B;
    vvd D;

    LPSolver(const vvd& A, const vd& b, const vd& c) :
        m(sz(b)), n(sz(c)), N(n+1), B(m), D(m+2, vd(n+2)) {
        rep(i,0,m) rep(j,0,n) D[i][j] = A[i][j];
        rep(i,0,m) { B[i] = n+i; D[i][n] = -1; D[i][n+1] = b[i]; }
        rep(j,0,n) { N[j] = j; D[m][j] = -c[j]; }
        N[n] = -1; D[m+1][n] = 1;
    }

    void pivot(int r, int s) {
        T *a = D[r].data(), inv = 1 / a[s];
        rep(i,0,m+2) if (i != r && abs(D[i][s]) > eps) {
            T *b = D[i].data(), inv2 = b[s] * inv;
            rep(j,0,n+2) b[j] -= a[j] * inv2;
            b[s] = a[s] * inv2;
        }
        rep(j,0,n+2) if (j != s) D[r][j] *= inv;
        rep(i,0,m+2) if (i != r) D[i][s] *= -inv;
        D[r][s] = inv;
        swap(B[r], N[s]);
    }
}

```

```

bool simplex(int phase) {
    int x = m + phase - 1;
    for (;;) {
        int s = -1;
        rep(j,0,n+1) if (N[j] != -phase) ltj(D[x]);
        if (D[x][s] >= -eps) return true;
        int r = -1;
        rep(i,0,m) {
            if (D[i][s] <= eps) continue;
            if (r == -1 || MP(D[i][n+1] / D[i][s], B[i])
                < MP(D[r][n+1] / D[r][s], B[r])) r = i;
        }
        if (r == -1) return false;
        pivot(r, s);
    }
}

T solve(vd &x) {
    int r = 0;
    rep(i,1,m) if (D[i][n+1] < D[r][n+1]) r = i;
    if (D[r][n+1] < -eps) {
        pivot(r, n);
        if (!simplex(2) || D[m+1][n+1] < -eps) return -inf;
        rep(i,0,m) if (B[i] == -1) {
            int s = 0;
            rep(j,1,n+1) ltj(D[i]);
            pivot(i, s);
        }
    }
    bool ok = simplex(1); x = vd(n);
    rep(i,0,m) if (B[i] < n) x[B[i]] = D[i][n+1];
    return ok ? D[m][n+1] : inf;
}
};

```

6.5 Floor Sum

```

// from 8BQube
ll floor_sum(ll n, ll m, ll a, ll b) {
    ll ans = 0;
    if (a >= m)
        ans += (n - 1) * n * (a / m) / 2, a %= m;
    if (b >= m)
        ans += n * (b / m), b %= m;
    ll y_max = (a * n + b) / m, x_max = (y_max * m - b);
    if (y_max == 0) return ans;
    ans += (n - (x_max + a - 1) / a) * y_max;
    ans += floor_sum(y_max, a, m, (a - x_max % a) % a);
    return ans;
} // sum^{n-1}_0 floor((a * i + b) / m) in log(n + m + a + b)
)

```

6.6 Miller Rabin & Pollard Rho

```

// n < 4,759,123,141      3 : 2, 7, 61
// n < 1,122,004,669,633  4 : 2, 13, 23, 1662803
// n < 3,474,749,660,383  6 : pirmes <= 13
// n < 2^64               7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
ll mul(ll a, ll b, ll n){
    return (__int128)a * b % n;
}

bool Miller_Rabin(ll a, ll n) {
    if ((a = a % n) == 0) return 1;
    if (n % 2 == 0) return n == 2;
    ll tmp = (n - 1) / ((n - 1) & (1 - n));
    ll t = __lg(((n - 1) & (1 - n))), x = 1;
    for ( ; tmp; tmp >>= 1, a = mul(a, a, n))
        if (tmp & 1) x = mul(x, a, n);
    if (x == 1 || x == n - 1) return 1;
    while (--t)
        if ((x = mul(x, x, n)) == n - 1) return 1;
    return 0;
}

bool prime(ll n){

```

```

vector<ll> tmp = {2, 325, 9375, 28178, 450775, 9780504,
1795265022};
for(ll i : tmp)
    if(!Miller_Rabin(i, n)) return false;
return true;
}
map<ll, int> cnt;
void PollardRho(ll n) {
    if (n == 1) return;
    if (prime(n)) return ++cnt[n], void();
    if (n % 2 == 0) return PollardRho(n / 2), ++cnt[2], void
    ();
    ll x = 2, y = 2, d = 1, p = 1;
#define f(x, n, p) ((mul(x, x, n) + p) % n)
    while (true) {
        if (d != n && d != 1) {
            PollardRho(n / d);
            PollardRho(d);
            return;
        }
        if (d == n) ++p;
        x = f(x, n, p), y = f(f(y, n, p), n, p);
        d = gcd(abs(x - y), n);
    }
}
}

```

6.7 XOR Basis

```

const int digit = 60; // [0, 2^digit)
struct Basis{
    int total = 0, rank = 0;
    vector<ll> b;
    Basis(): b(digit) {}
    bool add(ll v){ // Gauss Jordan Elimination
        total++;
        for(int i = digit - 1; i >= 0; i--){
            if(!(1LL << i & v)) continue;
            if(b[i] != 0){
                v ^= b[i];
                continue;
            }
            for(int j = 0; j < i; j++){
                if(1LL << j & v) v ^= b[j];
            }
            for(int j = i + 1; j < digit; j++){
                if(1LL << i & b[j]) b[j] ^= v;
            }
            b[i] = v;
            rank++;
            return true;
        }
        return false;
    }
    ll getmax(ll x = 0){
        for(ll i : b) x = max(x, x ^ i);
        return x;
    }
    ll getmin(ll x = 0){
        for(ll i : b) x = min(x, x ^ i);
        return x;
    }
    bool can(ll x){
        return getmin(x) == 0;
    }
}
ll kth(ll k){ // kth smallest, 0-indexed
    vector<ll> tmp;
    for(ll i : b) if(i) tmp.pb(i);
    ll ans = 0;
    for(int i = 0; i < SZ(tmp); i++){
        if(1LL << i & k) ans ^= tmp[i];
    }
    return ans;
}
}

```

7 Misc

7.1 Fraction

```

struct Frac{
    ll p, q; // p / q
    Frac(ll _p, ll _q): p(_p), q(_q) { if(q < 0) p = -p, q =
        -q; }
};
Frac operator-(Frac a) { return Frac(-a.p, a.q); }
Frac operator+(Frac a, Frac b){
    ll q = a.q * b.q;
    ll p = a.p * b.q + b.p * a.q;
    return Frac(p, q);
}
Frac inv(Frac a){ return Frac(a.q, a.p); }
Frac operator-(Frac a, Frac b) { return a + (-b); }
Frac operator*(Frac a, Frac b) { return Frac({a.p * b.p, a.
    q * b.q}); }
Frac operator/(Frac a, Frac b) { return a * inv(b); }
ostream& operator<<(ostream& o, Frac a) { return o << a.p
    << '/' << a.q; }

```

7.2 Matroid

我們稱一個二元組 $M = (E, \mathcal{I})$ 為一個擬陣，其中 $\mathcal{I} \subseteq 2^E$ 為 E 的子集所形成的非空集合，若：

- 若 $S \in \mathcal{I}$ 以及 $S' \subsetneq S$ ，則 $S' \in \mathcal{I}$
- 對於 $S_1, S_2 \in \mathcal{I}$ 滿足 $|S_1| < |S_2|$ ，存在 $e \in S_2 \setminus S_1$ 使得 $S_1 \cup \{e\} \in \mathcal{I}$

除此之外，我們有以下的定義：

- 位於 \mathcal{I} 中的集合我們稱之為獨立集 (independent set)，反之不在 \mathcal{I} 中的我們稱為相依集 (dependent set)
- 極大的獨立集為基底 (base)、極小的相依集為迴路 (circuit)
- 一個集合 Y 的秩 (rank) $r(Y)$ 為該集中最大的獨立子集，也就是 $r(Y) = \max\{|X| \mid X \subseteq Y \text{ 且 } X \in \mathcal{I}\}$

性質：

1. $X \subseteq Y \wedge Y \in \mathcal{I} \implies X \in \mathcal{I}$
2. $X \subseteq Y \wedge X \notin \mathcal{I} \implies Y \notin \mathcal{I}$
3. 若 B 與 B' 皆是基底且 $B \subseteq B'$ ，則 $B = B'$
若 C 與 C' 皆是迴路且 $C \subseteq C'$ ，則 $C = C'$
4. $e \in E \wedge X \subseteq E \implies r(X) \leq r(X \cup \{e\}) \leq r(X) + 1$ i.e. 加入一個元素後秩不會降底，最多增加 1
5. $\forall Y \subseteq E, \exists X \subseteq Y, r(X) = |X| = r(Y)$

一些等價的性質：

1. 對於所有 $X \subseteq E$ ， X 的極大獨立子集都有相同的大小
2. 對於 $B_1, B_2 \in \mathcal{B} \wedge B_1 \neq B_2$ ，對於所有 $e_1 \in B_1 \setminus B_2$ ，存在 $e_2 \in B_2 \setminus B_1$ 使得 $(B_1 \setminus \{e_1\}) \cup \{e_2\} \in \mathcal{B}$
3. 對於 $X, Y \in \mathcal{I}$ 且 $|X| < |Y|$ ，存在 $e \in Y \setminus X$ 使得 $X \cup \{e\} \in \mathcal{B}$
4. 如果 $r(X \cup \{e_1\}) = r(X \cup \{e_2\}) = r(X)$ ，則 $r(X \cup \{e_1, e_2\}) = r(X)$ 。
如果 $r(X \cup \{e\}) = r(X)$ 對於所有 $e \in E'$ 都成立，則 $r(X \cup E') = r(X)$ 。

擬陣交

Data: 兩個擬陣 $M_1 = (E, \mathcal{I}_1)$ 以及 $M_2 = (E, \mathcal{I}_2)$

Result: I 為最大的位於 $\mathcal{I}_1 \cap \mathcal{I}_2$ 中的獨立集

$I \leftarrow \emptyset$

$X_1 \leftarrow \{e \in E \setminus I \mid I \cup \{e\} \in \mathcal{I}_1\}$

$X_2 \leftarrow \{e \in E \setminus I \mid I \cup \{e\} \in \mathcal{I}_2\}$

while $X_1 \neq \emptyset$ 且 $X_2 \neq \emptyset$ do

if $e \in X_1 \cap X_2$ then

$I \leftarrow I \cup \{e\}$

else

構造交換圖 $\mathcal{D}_{M_1, M_2}(I)$

在交換圖上找到一條 X_1 到 X_2 且沒有捷徑的路徑 P

$I \leftarrow I \Delta P$

end if

$X_1 \leftarrow \{e \in E \setminus I \mid I \cup \{e\} \in \mathcal{I}_1\}$

$X_2 \leftarrow \{e \in E \setminus I \mid I \cup \{e\} \in \mathcal{I}_2\}$

end while

8 Polynomial

8.1 FFT

```
using val_t = complex<double>;
template<int MAXN>
struct FFT {
    const double PI = acos(-1);
    val_t w[MAXN];
    FFT() {
        for (int i = 0; i < MAXN; ++i) {
            double arg = 2 * PI * i / MAXN;
            w[i] = val_t(cos(arg), sin(arg));
        }
    }
    void bitrev(vector<val_t> &a, int n) //same as NTT
    void trans(vector<val_t> &a, int n, bool inv = false) {
        bitrev(a, n);
        for (int L = 2; L <= n; L <= 1) {
            int dx = MAXN / L, dl = L >> 1;
            for (int i = 0; i < n; i += L) {
                for (int j = i, x = 0; j < i + dl; ++j, x += dx) {
                    val_t tmp = a[j + dl] * (inv ? conj(w[x]) : w[x]);
                    a[j + dl] = a[j] - tmp;
                    a[j] += tmp;
                }
            }
        }
        if (inv) {
            for (int i = 0; i < n; ++i) a[i] /= n;
        }
    }
    //multiplying two polynomials A * B:
    //fft.trans(A, siz, 0), fft.trans(B, siz, 0):
    //A[i] *= B[i], fft.trans(A, siz, 1);
};
```

8.2 NTT

```
//to be modified
//(2^16)+1, 65537, 3
//7*17*(2^23)+1, 998244353, 3
//1255*(2^20)+1, 1315962881, 3
//51*(2^25)+1, 1711276033, 29
template<int MAXN, ll P, ll RT> //MAXN must be 2^k
struct NTT {
    ll w[MAXN];
    ll mpow(ll a, ll n);
    ll minv(ll a) { return mpow(a, P - 2); }
    NTT() {
        ll dw = mpow(RT, (P - 1) / MAXN);
        w[0] = 1;
        for (int i = 1; i < MAXN; ++i) w[i] = w[i - 1] * dw % P;
    }
    void bitrev(vector<ll> &a, int n) {
        int i = 0;
        for (int j = 1; j < n - 1; ++j) {
            for (int k = n >> 1; (i ^ k) < k; k >>= 1);
            if (j < i) swap(a[i], a[j]);
        }
    }
    void operator()(vector<ll> &a, int n, bool inv = false) {
        //0 <= a[i] < P
        bitrev(a, n);
        for (int L = 2; L <= n; L <= 1) {
            int dx = MAXN / L, dl = L >> 1;
            for (int i = 0; i < n; i += L) {
                for (int j = i, x = 0; j < i + dl; ++j, x += dx) {
                    ll tmp = a[j + dl] * w[x] % P;
                    if ((a[j + dl] = a[j] - tmp) < 0) a[j + dl] += P;
                    if ((a[j] += tmp) >= P) a[j] -= P;
                }
            }
        }
        if (inv) {
            for (int i = 0; i < n; ++i) a[i] /= n;
        }
    }
};
```

```
if (inv) {
    reverse(a.begin()+1, a.begin()+n);
    ll invn = minv(n);
    for (int i = 0; i < n; ++i) a[i] = a[i] * invn % P;
}
};
```

8.3 Polynomial Operation

```
// Copy from 8BQube
#define fi(s, n) for (int i = (int)(s); i < (int)(n); ++i)
template<int MAXN, ll P, ll RT> // MAXN = 2^k
struct Poly : vector<ll> { // coefficients in [0, P)
    using vector<ll>::vector;
    static NTT<MAXN, P, RT> ntt;
    int n() const { return (int)size(); } // n() >= 1
    Poly(const Poly &p, int m) : vector<ll>(m) {
        copy_n(p.data(), min(p.n(), m), data());
    }
    Poly& irev() { return reverse(data(), data() + n()), *this; }
    Poly& isz(int m) { return resize(m), *this; }
    Poly& iadd(const Poly &rhs) { // n() == rhs.n()
        fi(0, n()) if ((*this)[i] += rhs[i]) >= P) (*this)[i] -= P;
        return *this;
    }
    Poly& imul(ll k) {
        fi(0, n()) (*this)[i] = (*this)[i] * k % P;
        return *this;
    }
    Poly Mul(const Poly &rhs) const {
        int m = 1;
        while (m < n() + rhs.n() - 1) m <= 1;
        Poly X(*this, m), Y(rhs, m);
        ntt(X.data(), m), ntt(Y.data(), m);
        fi(0, m) X[i] = X[i] * Y[i] % P;
        ntt(X.data(), m, true);
        return X.isz(n() + rhs.n() - 1);
    }
    Poly Inv() const { // (*this)[0] != 0, 1e5/95ms
        if (n() == 1) return {ntt.minv((*this)[0])};
        int m = 1;
        while (m < n() * 2) m <= 1;
        Poly Xi = Poly(*this, (n() + 1) / 2).Inv().isz(m);
        Poly Y(*this, m);
        ntt(Xi.data(), m), ntt(Y.data(), m);
        fi(0, m) {
            Xi[i] *= (2 - Xi[i] * Y[i]) % P;
            if ((Xi[i] %= P) < 0) Xi[i] += P;
        }
        ntt(Xi.data(), m, true);
        return Xi.isz(n());
    }
    Poly Sqrt() const { // Jacobi((*this)[0], P) = 1, 1e5/235ms
        if (n() == 1) return {QuadraticResidue((*this)[0], P)};
        Poly X = Poly(*this, (n() + 1) / 2).Sqrt().isz(n());
        return X.iadd(Mul(X.Inv()).isz(n())).imul(P / 2 + 1);
    }
    pair<Poly, Poly> DivMod(const Poly &rhs) const { // (rhs.back() != 0)
        if (n() < rhs.n()) return {{0}, *this};
        const int m = n() - rhs.n() + 1;
        Poly X(rhs); X.irev().isz(m);
        Poly Y(*this); Y.irev().isz(m);
        Poly Q = Y.Mul(X.Inv()).isz(m).irev();
        X = rhs.Mul(Q), Y = *this;
        fi(0, n()) if ((Y[i] -= X[i]) < 0) Y[i] += P;
        return {Q, Y.isz(max(1, rhs.n() - 1))};
    }
    Poly Dx() const {
        Poly ret(n() - 1);
        fi(0, ret.n()) ret[i] = (i + 1) * (*this)[i + 1] % P;
        return ret.isz(max(1, ret.n()));
    }
};
```

```

}
Poly Sx() const {
    Poly ret(n() + 1);
    fi(0, n()) ret[i + 1] = ntt.minv(i + 1) * (*this)[i] %
        P;
    return ret;
}
Poly _tmul(int nn, const Poly &rhs) const {
    Poly Y = Mul(rhs).isz(n() + nn - 1);
    return Poly(Y.data() + n() - 1, Y.data() + Y.n());
}
vector<ll> _eval(const vector<ll> &x, const vector<Poly>
    &up) const {
    const int m = (int)x.size();
    if (!m) return {};
    vector<Poly> down(m * 2);
    // down[1] = DivMod(up[1]).second;
    // fi(2, m * 2) down[i] = down[i / 2].DivMod(up[i]).
        second;
    down[1] = Poly(up[1]).irev().isz(n()).Inv().irev().
        _tmul(m, *this);
    fi(2, m * 2) down[i] = up[i ^ 1]._tmul(up[i].n() - 1,
        down[i / 2]);
    vector<ll> y(m);
    fi(0, m) y[i] = down[m + i][0];
    return y;
}
static vector<Poly> _tree1(const vector<ll> &x) {
    const int m = (int)x.size();
    vector<Poly> up(m * 2);
    fi(0, m) up[m + i] = {(x[i] ? P - x[i] : 0), 1};
    for (int i = m - 1; i > 0; --i) up[i] = up[i * 2].Mul(
        up[i * 2 + 1]);
    return up;
}
vector<ll> Eval(const vector<ll> &x) const { // 1e5, 1s
    auto up = _tree1(x); return _eval(x, up);
}
static Poly Interpolate(const vector<ll> &x, const vector
    <ll> &y) { // 1e5, 1.4s
    const int m = (int)x.size();
    vector<Poly> up = _tree1(x), down(m * 2);
    vector<ll> z = up[1].Dx()._eval(x, up);
    fi(0, m) z[i] = y[i] * ntt.minv(z[i]) % P;
    fi(0, m) down[m + i] = {z[i]};
    for (int i = m - 1; i > 0; --i) down[i] = down[i * 2].
        Mul(up[i * 2 + 1]).iadd(down[i * 2 + 1].Mul(up[i *
        2]));
    return down[1];
}
Poly Ln() const { // (*this)[0] == 1, 1e5/170ms
    return Dx().Mul(Inv()).Sx().isz(n());
}
Poly Exp() const { // (*this)[0] == 0, 1e5/360ms
    if (n() == 1) return {1};
    Poly X = Poly(*this, (n() + 1) / 2).Exp().isz(n());
    Poly Y = X.Ln(); Y[0] = P - 1;
    fi(0, n()) if ((Y[i] = (*this)[i] - Y[i]) < 0) Y[i] +=
        P;
    return X.Mul(Y).isz(n());
}
// M := P(P - 1). If k >= M, k := k % M + M.
Poly Pow(ll k) const {
    int nz = 0;
    while (nz < n() && !(*this)[nz]) ++nz;
    if (nz * min(k, (ll)n()) >= n()) return Poly(n());
    if (!k) return Poly(Poly {1}, n());
    Poly X(data() + nz, data() + nz + n() - nz * k);
    const ll c = ntt.mpow(X[0], k % (P - 1));
    return X.Ln().imul(k % P).Exp().imul(c).irev().isz(n())
        .irev();
}
static ll LinearRecursion(const vector<ll> &a, const
    vector<ll> &coef, ll n) { // a_n = \sum c_j a_{n-j}
    const int k = (int)a.size();
    assert((int)coef.size() == k + 1);
    Poly C(k + 1), W(Poly {1}, k), M = {0, 1};

```

```

    fi(1, k + 1) C[k - i] = coef[i] ? P - coef[i] : 0;
    C[k] = 1;
    while (n) {
        if (n % 2) W = W.Mul(M).DivMod(C).second;
        n /= 2, M = M.Mul(M).DivMod(C).second;
    }
    ll ret = 0;
    fi(0, k) ret = (ret + W[i] * a[i]) % P;
    return ret;
}
};
#undef fi
using Poly_t = Poly<131072 * 2, 998244353, 3>;
template<> decltype(Poly_t::ntt) Poly_t::ntt = {};

```

8.4 Generating Function

8.4.1 Ordinary Generating Function

- $C(x) = A(rx)$: $c_n = r^n a_n$ 的一般生成函數。
- $C(x) = A(x) + B(x)$: $c_n = a_n + b_n$ 的一般生成函數。
- $C(x) = A(x)B(x)$: $c_n = \sum_{i=0}^n a_i b_{n-i}$ 的一般生成函數。
- $C(x) = A(x)^k$: $c_n = \sum_{i_1+i_2+\dots+i_k=n} a_{i_1} a_{i_2} \dots a_{i_k}$ 的一般生成函數。
- $C(x) = xA(x)'$: $c_n = na_n$ 的一般生成函數。
- $C(x) = \frac{A(x)}{1-x}$: $c_n = \sum_{i=0}^n a_i$ 的一般生成函數。
- $C(x) = A(1) + x \frac{A(1)-A(x)}{1-x}$: $c_n = \sum_{i=n}^{\infty} a_i$ 的一般生成函數。

常用展開式

- $\frac{1}{1-x} = 1 + x + x^2 + \dots + x^n + \dots$
- $(1+x)^a = \sum_{n=0}^{\infty} \binom{a}{n} x^n$, $\binom{a}{n} = \frac{a(a-1)(a-2)\dots(a-n+1)}{n!}$.

常見生函

- 卡特蘭數: $f(x) = \frac{1-\sqrt{1-4x}}{2x}$

8.4.2 Exponential Generating Function

a_0, a_1, \dots 的指數生成函數：

$$\hat{A}(x) = \sum_{i=0}^{\infty} \frac{a_i}{i!} = a_0 + a_1 x + \frac{a_2}{2!} x^2 + \frac{a_3}{3!} x^3 + \dots$$

- $\hat{C}(x) = \hat{A}(x) + \hat{B}(x)$: $c_n = a_n + b_n$ 的指數生成函數
- $\hat{C}(x) = \hat{A}^{(k)}(x)$: $c_n = a_{n+k}$ 的指數生成函數
- $\hat{C}(x) = x\hat{A}(x)$: $c_n = na_n$ 的指數生成函數
- $\hat{C}(x) = \hat{A}(x)\hat{B}(x)$: $c_n = \sum_{k=0}^n \binom{n}{k} a_k b_{n-k}$ 的指數生成函數
- $\hat{C}(x) = \hat{A}(x)^k$: $\sum_{i_1+i_2+\dots+i_k=n} \binom{n}{i_1, i_2, \dots, i_k} a_{i_1} a_{i_2} \dots a_{i_k}$ 的指數生成函數
- $\hat{C}(x) = \exp(A(x))$: 假設 $A(x)$ 是一個分量 (component) 的生成函數，那 $\hat{C}(x)$ 是將 n 個有編號的東西分成若干個分量的指數生成函數

9 String

9.1 Rolling Hash

```

int n;
string s;
vector<ll> h, rh;
vector<ll> kp;
const ll K = 26, MOD = 1000000007;

void topos(ll &a){
    a = (a % MOD + MOD) % MOD;
}

int ord(char c){

```

```

    return c - 'a';
}

pll geth(int l, int r){
    if(l > r) return mp(0, 0);
    ll ans = h[r] - h[l - 1] * kp[r - 1 + 1];
    topos(ans);
    return mp(ans, r - 1 + 1);
}

pll getrh(int l, int r){
    if(l > r) return mp(0, 0);
    l = n - l + 1;
    r = n - r + 1;
    swap(l, r);
    ll ans = rh[r] - rh[l - 1] * kp[r - 1 + 1];
    topos(ans);
    return mp(ans, r - 1 + 1);
}

pll concat(pll a, pll b){
    ll ans = a.F * kp[b.S] + b.F;
    ans %= MOD;
    return mp(ans, a.S + b.S);
}

void build(){
    n = s.size();
    s = " " + s;

    h.resize(n + 1);
    rh.resize(n + 1);
    kp.resize(n + 1);
    kp[0] = 1;
    for(int i = 1; i <= n; i++){
        kp[i] = kp[i - 1] * K % MOD;
    }
    for(int i = 1; i <= n; i++){
        h[i] = h[i - 1] * K % MOD + ord(s[i]);
        h[i] %= MOD;
        rh[i] = rh[i - 1] * K % MOD + ord(s[n - i + 1]);
        rh[i] %= MOD;
    }
}

```

9.2 KMP Algorithm

```

void kmp(string s){
    int siz = s.size();
    vector<int> f(siz, 0);
    f[0] = 0;
    for (int i = 1; i < siz; i++) {
        f[i] = f[i-1];
        bool zero = 0;
        while (s[f[i]] != s[i]) {
            if (f[i] == 0) {
                zero = 1;
                break;
            }
            f[i] = f[f[i]-1];
        }
        if (!zero) f[i]++;
    }
}

```

9.3 Manacher Algorithm

```

vector<int> manacher(string s) {
    int n = s.size();
    vector<int> v(n);
    int pnt = -1, len = 1;
    for (int i = 0; i < n; i++) {
        int cor = 2 * pnt - i;
        if (cor >= 0) v[i] = min(v[cor], cor - pnt + len);
    }
}

```

```

    while (i+v[i] < n && i-v[i] >= 0 && s[i+v[i]] == s[i-v[i]]) v[i]++;
    if (i + v[i] >= pnt + len) pnt = i, len = v[i];
}
for (int i = 0; i < n; i++) v[i] = 2 * v[i] - 1;
return v;
}

```

9.4 MCP

```

string mcp(string s) { //Duval algorithm for Lyndon
    factorization
    s += s;
    int n = s.size(), i = 0, ans = 0;
    while (i < n/2) {
        ans = i;
        int j = i+1, k=i;
        while (j < n && s[k] <= s[j]) {
            if (s[k] < s[j]) k = i;
            else k++;
            j++;
        }
        while (i <= k) i += j - k;
    }
    return s.substr(ans, n/2);
}

```

9.5 Suffix Array

```

struct SuffixArray { //tested
    vector<int> sa, lcp, rank; //lcp[i] is lcp of sa[i] and
    sa[i-1]
    SuffixArray(string& s, int lim=256) { // or basic_string<
        int>
        int n = s.size() + 1, k = 0, a, b;
        vector<int> x(n, 0), y(n), ws(max(n, lim));
        rank.resize(n);
        for (int i = 0; i < n-1; i++) x[i] = (int)s[i];
        sa = lcp = y, iota(sa.begin(), sa.end(), 0);
        for (int j = 0, p = 0; p < n; j = max(1, j * 2), lim =
            p) {
            p = j, iota(y.begin(), y.end(), n - j);
            for (int i = 0; i < n; i++) if (sa[i] >= j) y[p++] = sa
                [i] - j;
            for (int &i : ws) i = 0;
            for (int i = 0; i < n; i++) ws[x[i]]++;
            for (int i = 1; i < lim; i++) ws[i] += ws[i - 1];
            for (int i = n; i--;) sa[--ws[x[y[i]]]] = y[i];
            swap(x, y), p = 1, x[sa[0]] = 0;
            for (int i = 1; i < n; i++) a = sa[i - 1], b = sa[i], x[
                b] =
                (y[a] == y[b] && y[a + j] == y[b + j]) ? p - 1 : p
                    ++;
        }
        for (int i = 1; i < n; i++) rank[sa[i]] = i;
        for (int i = 0, j; i < n - 1; lcp[rank[i+]] = k)
            for (k && k--, j = sa[rank[i] - 1];
                s[i + k] == s[j + k]; k++);
    }
};

```

9.6 Suffix Array Automaton

```

// from 8BQube
const int MAXM = 1000010;
struct SAM {
    int tot, root, lst, mom[MAXM], mx[MAXM];
    int nxt[MAXM][33], cnt[MAXM], in[MAXM];
    int newNode() {
        int res = ++tot;
        fill(nxt[res], nxt[res] + 33, 0);
        mom[res] = mx[res] = cnt[res] = in[res] = 0;
        return res;
    }
}

```

```

}
void init() {
    tot = 0;
    root = newNode();
    mom[root] = 0, mx[root] = 0;
    lst = root;
}
void push(int c) {
    int p = lst;
    int np = newNode();
    mx[np] = mx[p] + 1;
    for (; p && nxt[p][c] == 0; p = mom[p])
        nxt[p][c] = np;
    if (p == 0) mom[np] = root;
    else {
        int q = nxt[p][c];
        if (mx[p] + 1 == mx[q]) mom[np] = q;
        else {
            int nq = newNode();
            mx[nq] = mx[p] + 1;
            for (int i = 0; i < 33; i++)
                nxt[nq][i] = nxt[q][i];
            mom[nq] = mom[q];
            mom[q] = nq;
            mom[np] = nq;
            for (; p && nxt[p][c] == q; p = mom[p])
                nxt[p][c] = nq;
        }
    }
    lst = np, cnt[np] = 1;
}
void push(char *str) {
    for (int i = 0; str[i]; i++)
        push(str[i] - 'a' + 1);
}
void count() {
    for (int i = 1; i <= tot; ++i)
        ++in[mom[i]];
    queue<int> q;
    for (int i = 1; i <= tot; ++i)
        if (!in[i]) q.push(i);
    while (!q.empty()) {
        int u = q.front();
        q.pop();
        cnt[mom[u]] += cnt[u];
        if (!--in[mom[u]])
            q.push(mom[u]);
    }
}
} sam;

```

9.7 Z-value Algorithm

```

vector<int> z_function(string const& s) {
    int n = s.size();
    vector<int> z(n);
    for (int i = 1, l = 0, r = 0; i < n; i++) {
        if (i <= r) z[i] = min(r-i+1, z[i-l]);
        while (i + z[i] < n && s[z[i]] == s[i+z[i]])
            z[i]++;
        if (i + z[i] - 1 > r)
            l = i, r = i + z[i] - 1;
    }
    return z;
}

```

9.8 Main Lorentz

```

vector<int> z_function(string const& s);
int get_z(vector<int> const& z, int i) {
    return (0 <= i && i < SZ(z)) ? z[i] : 0;
}
vector<pair<int, int>> rep;

```

```

void convert_to_rep(int shift, bool left, int cntr, int l,
    int k1, int k2) {
    for (int l1 = max(1, 1 - k2); l1 <= min(l, k1); l1++) {
        if (left && l1 == 1) break;
        int l2 = 1 - l1;
        int pos = shift + (left ? cntr - l1 : cntr - 1 - l1 + 1);
        rep.emplace_back(pos, pos + 2*l - 1);
    }
}

```

```

void find_rep(string s, int shift = 0) {
    int n = s.size();
    if (n == 1) return;

    int nu = n / 2;
    int nv = n - nu;
    string u = s.substr(0, nu);
    string v = s.substr(nu);
    string ru(u.rbegin(), u.rend());
    string rv(v.rbegin(), v.rend());

    find_rep(u, shift);
    find_rep(v, shift + nu);
}

```

```

vector<int> z1 = z_function(ru);
vector<int> z2 = z_function(v + '#' + u);
vector<int> z3 = z_function(ru + '#' + rv);
vector<int> z4 = z_function(v);

```

```

for (int cntr = 0; cntr < n; cntr++) {
    int l, k1, k2;
    if (cntr < nu) {
        l = nu - cntr;
        k1 = get_z(z1, nu - cntr);
        k2 = get_z(z2, nv + 1 + cntr);
    } else {
        l = cntr - nu + 1;
        k1 = get_z(z3, nu + 1 + nv - 1 - (cntr - nu));
        k2 = get_z(z4, (cntr - nu) + 1);
    }
    if (k1 + k2 >= 1)
        convert_to_rep(shift, cntr < nu, cntr, l, k1, k2);
}
}

```

9.9 AC Automaton

```

// copy from nontoi
struct AhoCorasick {
    enum { P = 26, st = 'a' };
    struct node { // zero-based
        array<int, P> ch = {0};
        int fail = 0, cnt = 0, dep = 0;
    };
    int cnt;
    vector<node> v;
    vector<int> ans;
    void init_(int mx) {
        v.clear();
        cnt = 1, v.resize(mx);
        v[0].fail = 0;
    }
    void insert(string s) {
        int p = 0, dep = 1;
        for(auto i : s) {
            int c = i - st;
            if(!v[p].ch[c]) {
                v[cnt].dep = dep;
                v[p].ch[c] = cnt++;
            }
            p = v[p].ch[c], dep++;
        }
        v[p].cnt++;
    }
    void build(vector<string> s) {

```

```

for(auto i : s) insert(i);
queue<int> q;
for(int i = 0; i < P; i++) {
    if(v[0].ch[i]) q.push(v[0].ch[i]);
}
while(q.size()) {
    int p = q.front();
    q.pop();
    for(int i = 0; i < P; i++) if(v[p].ch[i]) {
        int to = v[p].ch[i], cur = v[p].fail;
        while(cur && !v[cur].ch[i]) cur = v[cur].fail;
        if(v[cur].ch[i]) cur = v[cur].ch[i];
        v[to].fail = cur;
        v[to].cnt += v[cur].cnt;
        q.push(to);
    }
}
}
void traverse(string s) {
    int p = 0;
    ans.assign(cnt, 0);
    for(auto i : s) {
        int c = i - st;
        while(p && !v[p].ch[c]) p = v[p].fail;
        if(v[p].ch[c]) {
            p = v[p].ch[c];
            ans[p]++; v[p].cnt;
        }
    }
    vector<int> ord(cnt, 0);
    iota(all(ord), 0);
    sort(all(ord), [&](int a, int b) { return v[a].dep > v[b].dep; });
    for(auto i : ord) ans[v[i].fail] += ans[i];
    return;
}
int go(string s) {
    int p = 0;
    for(auto i : s) {
        int c = i - st;
        assert(v[p].ch[c]);
        p = v[p].ch[c];
    }
    return ans[p];
}
};

```

10 Formula

10.1 Recurrences

If $a_n = c_1 a_{n-1} + \dots + c_k a_{n-k}$, and r_1, \dots, r_k are distinct roots of $x^k + c_1 x^{k-1} + \dots + c_k$, there are d_1, \dots, d_k s.t.

$$a_n = d_1 r_1^n + \dots + d_k r_k^n.$$

Non-distinct roots r become polynomial factors, e.g. $a_n = (d_1 n + d_2) r^n$.

10.2 Geometry

10.2.1 Triangles

Side lengths: a, b, c

$$\text{Semiperimeter: } p = \frac{a+b+c}{2}$$

$$\text{Area: } A = \sqrt{p(p-a)(p-b)(p-c)}$$

$$\text{Circumradius: } R = \frac{abc}{4A}$$

$$\text{Inradius: } r = \frac{A}{p}$$

Length of median (divides triangle into two equal-area triangles): $m_a = \frac{1}{2} \sqrt{2b^2 + 2c^2 - a^2}$

$$\text{Length of bisector (divides angles in two): } s_a = \sqrt{bc \left(1 - \left(\frac{a}{b+c} \right)^2 \right)}$$

$$\text{Law of sines: } \frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c} = \frac{1}{2R}$$

$$\text{Law of cosines: } a^2 = b^2 + c^2 - 2bc \cos \alpha$$

$$\text{Law of tangents: } \frac{a+b}{a-b} = \frac{\tan \frac{\alpha+\beta}{2}}{\tan \frac{\alpha-\beta}{2}}$$

Incenter:

$$P_1 = (x_1, y_1), P_2 = (x_2, y_2), P_3 = (x_3, y_3)$$

$$s_1 = P_2 P_3, s_2 = P_1 P_3, s_3 = P_1 P_2$$

$$\frac{s_1 P_1 + s_2 P_2 + s_3 P_3}{s_1 + s_2 + s_3}$$

Circumcenter:

$$P_0 = (0, 0), P_1 = (x_1, y_1), P_2 = (x_2, y_2)$$

$$x_c = \frac{1}{2} \times \frac{y_2(x_1^2 + y_1^2) - y_1(x_2^2 + y_2^2)}{-x_2 y_1 + x_1 y_2}$$

$$y_c = \frac{1}{2} \times \frac{x_2(x_1^2 + y_1^2) - x_1(x_2^2 + y_2^2)}{-x_1 y_2 + x_2 y_1}$$

Check if (x_0, y_0) is in the circumcircle:

$$\begin{vmatrix} x_1 - x_0 & y_1 - y_0 & (x_1^2 + y_1^2) - (x_0^2 + y_0^2) \\ x_2 - x_0 & y_2 - y_0 & (x_2^2 + y_2^2) - (x_0^2 + y_0^2) \\ x_3 - x_0 & y_3 - y_0 & (x_3^2 + y_3^2) - (x_0^2 + y_0^2) \end{vmatrix}$$

0: on edge, > 0: inside, < 0: outside

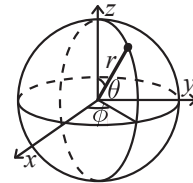
10.2.2 Quadrilaterals

With side lengths a, b, c, d , diagonals e, f , diagonals angle θ , area A and magic flux $F = b^2 + d^2 - a^2 - c^2$:

$$4A = 2ef \cdot \sin \theta = F \tan \theta = \sqrt{4e^2 f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is 180° , $ef = ac + bd$, and $A = \sqrt{(p-a)(p-b)(p-c)(p-d)}$.

10.2.3 Spherical coordinates



$$\begin{aligned} x &= r \sin \theta \cos \phi & r &= \sqrt{x^2 + y^2 + z^2} \\ y &= r \sin \theta \sin \phi & \theta &= \arccos(z / \sqrt{x^2 + y^2 + z^2}) \\ z &= r \cos \theta & \phi &= \text{atan2}(y, x) \end{aligned}$$

10.2.4 Green's Theorem

$$\iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy = \oint_{L^+} (P dx + Q dy)$$

$$\text{Area} = \frac{1}{2} \oint_L x dy - y dx$$

Circular sector:

$$x = x_0 + r \cos \theta$$

$$y = y_0 + r \sin \theta$$

$$\begin{aligned} A &= r \int_{\alpha}^{\beta} (x_0 + \cos \theta) \cos \theta + (y_0 + \sin \theta) \sin \theta d\theta \\ &= r(r\theta + x_0 \sin \theta - y_0 \cos \theta) \Big|_{\alpha}^{\beta} \end{aligned}$$

10.3 Trigonometry

$$\sinh x = \frac{1}{2}(e^x - e^{-x}) \quad \cosh x = \frac{1}{2}(e^x + e^{-x})$$

$$\sin n\pi = 0 \quad \cos n\pi = (-1)^n$$

$$\sin(\alpha + \beta) = \sin \alpha \cos \beta + \cos \alpha \sin \beta$$

$$\cos(\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta$$

$$\sin(2\alpha) = 2 \cos \alpha \sin \alpha$$

$$\cos(2\alpha) = \cos^2 \alpha - \sin^2 \alpha$$

$$= 2 \cos^2 \alpha - 1$$

$$= 1 - 2 \sin^2 \alpha$$

$$\tan(\alpha + \beta) = \frac{\tan \alpha + \tan \beta}{1 - \tan \alpha \tan \beta}$$

$$\sin \alpha + \sin \beta = 2 \sin \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$

$$\cos \alpha + \cos \beta = 2 \cos \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$

$$\sin \alpha \sin \beta = \frac{1}{2} (\cos(\alpha - \beta) - \cos(\alpha + \beta))$$

$$\sin \alpha \cos \beta = \frac{1}{2} (\sin(\alpha + \beta) + \sin(\alpha - \beta))$$

$$\cos \alpha \sin \beta = \frac{1}{2} (\sin(\alpha + \beta) - \sin(\alpha - \beta))$$

$$\cos \alpha \cos \beta = \frac{1}{2} (\cos(\alpha - \beta) + \cos(\alpha + \beta))$$

$$(V + W) \tan(\alpha - \beta)/2 = (V - W) \tan(\alpha + \beta)/2$$

where V, W are lengths of sides opposite angles α, β .

$$a \cos x + b \sin x = r \cos(x - \phi)$$

$$a \sin x + b \cos x = r \sin(x + \phi)$$

where $r = \sqrt{a^2 + b^2}$, $\phi = \text{atan2}(b, a)$.

10.4 Derivatives/Integrals

Integration by parts:

$$\int_a^b f(x)g(x)dx = [F(x)g(x)]_a^b - \int_a^b F(x)g'(x)dx$$

$$\frac{d}{dx} \arcsin x = \frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx} \arccos x = -\frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx} \tan x = 1 + \tan^2 x$$

$$\frac{d}{dx} \arctan x = \frac{1}{1+x^2}$$

$$\int \tan ax = -\frac{\ln |\cos ax|}{a}$$

$$\int x \sin ax = \frac{\sin ax - ax \cos ax}{a^2}$$

$$\int e^{-x^2} = \frac{\sqrt{\pi}}{2} \text{erf}(x)$$

$$\int x e^{ax} = \frac{e^{ax}}{a^2} (ax - 1)$$

$$\int \sin^2(x) = \frac{x}{2} - \frac{1}{4} \sin 2x$$

$$\int \sin^3 x = \frac{1}{12} \cos 3x - \frac{3}{4} \cos x$$

$$\int \cos^2(x) = \frac{x}{2} + \frac{1}{4} \sin 2x$$

$$\int \cos^3 x = \frac{1}{12} \sin 3x + \frac{3}{4} \sin x$$

$$\int x \sin x = \sin x - x \cos x$$

$$\int x \cos x = \cos x + x \sin x$$

$$\int x e^x = e^x (x - 1)$$

$$\int x^2 e^x = e^x (x^2 - 2x + 2)$$

$$\int x^2 \sin x = 2x \sin x - (x^2 - 2) \cos x$$

$$\int x^2 \cos x = 2x \cos x + (x^2 - 2) \sin x$$

$$\int e^x \sin x = \frac{1}{2} e^x (\sin x - \cos x)$$

$$\int e^x \cos x = \frac{1}{2} e^x (\sin x + \cos x)$$

$$\int x e^x \sin x = \frac{1}{2} e^x (x \sin x - x \cos x + \cos x)$$

$$\int x e^x \cos x = \frac{1}{2} e^x (x \sin x + x \cos x - \sin x)$$

10.5 Sums

$$c^a + c^{a+1} + \cdots + c^b = \frac{c^{b+1} - c^a}{c - 1}, c \neq 1$$

$$1 + 2 + 3 + \cdots + n = \frac{n(n+1)}{2}$$

$$1^2 + 2^2 + 3^2 + \cdots + n^2 = \frac{n(2n+1)(n+1)}{6}$$

$$1^3 + 2^3 + 3^3 + \cdots + n^3 = \frac{n^2(n+1)^2}{4}$$

$$1^4 + 2^4 + 3^4 + \cdots + n^4 = \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}$$

10.6 Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \cdots, (-\infty < x < \infty)$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \cdots, (-1 < x \leq 1)$$

$$\sqrt{1+x} = 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{2x^3}{32} - \frac{5x^4}{128} + \cdots, (-1 \leq x \leq 1)$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots, (-\infty < x < \infty)$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \cdots, (-\infty < x < \infty)$$

10.7 Probability theory

Let X be a discrete random variable with probability $p_X(x)$ of assuming the value x . It will then have an expected value (mean) $\mu = \mathbb{E}(X) = \sum_x x p_X(x)$ and variance $\sigma^2 = V(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \sum_x (x - \mathbb{E}(X))^2 p_X(x)$ where σ is the standard deviation. If X is instead continuous it will have a probability density function $f_X(x)$ and the sums above will instead be integrals with $p_X(x)$ replaced by $f_X(x)$.

Expectation is linear:

$$\mathbb{E}(aX + bY) = a\mathbb{E}(X) + b\mathbb{E}(Y)$$

For independent X and Y ,

$$V(aX + bY) = a^2 V(X) + b^2 V(Y).$$

10.7.1 Discrete distributions

Binomial distribution The number of successes in n independent yes/no experiments, each which yields success with probability p is $\text{Bin}(n, p)$, $n = 1, 2, \dots$, $0 \leq p \leq 1$.

$$p(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

$$\mu = np, \sigma^2 = np(1-p)$$

$\text{Bin}(n, p)$ is approximately $\text{Po}(np)$ for small p .

First success distribution The number of trials needed to get the first success in independent yes/no experiments, each which yields success with probability p is $\text{Fs}(p)$, $0 \leq p \leq 1$.

$$p(k) = p(1-p)^{k-1}, k = 1, 2, \dots$$

$$\mu = \frac{1}{p}, \sigma^2 = \frac{1-p}{p^2}$$

Poisson distribution The number of events occurring in a fixed period of time t if these events occur with a known average rate κ and independently of the time since the last event is $\text{Po}(\lambda)$, $\lambda = t\kappa$.

$$p(k) = e^{-\lambda} \frac{\lambda^k}{k!}, k = 0, 1, 2, \dots$$

$$\mu = \lambda, \sigma^2 = \lambda$$

10.7.2 Continuous distributions

Uniform distribution If the probability density function is constant between a and b and 0 elsewhere it is $\text{U}(a, b)$, $a < b$.

$$f(x) = \begin{cases} \frac{1}{b-a} & a < x < b \\ 0 & \text{otherwise} \end{cases}$$

$$\mu = \frac{a+b}{2}, \sigma^2 = \frac{(b-a)^2}{12}$$

Exponential distribution The time between events in a Poisson process is $\text{Exp}(\lambda)$, $\lambda > 0$.

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & x < 0 \end{cases}$$

$$\mu = \frac{1}{\lambda}, \sigma^2 = \frac{1}{\lambda^2}$$

Normal distribution Most real random values with mean μ and variance σ^2 are well described by $\mathcal{N}(\mu, \sigma^2)$, $\sigma > 0$.

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

If $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$ and $X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$ then

$$aX_1 + bX_2 + c \sim \mathcal{N}(\mu_1 + \mu_2 + c, a^2\sigma_1^2 + b^2\sigma_2^2)$$

10.8 Markov chains

A *Markov chain* is a discrete random process with the property that the next state depends only on the current state. Let X_1, X_2, \dots be a sequence of random variables generated by the Markov process. Then there is a transition matrix $\mathbf{P} = (p_{ij})$, with $p_{ij} = \Pr(X_n = i | X_{n-1} = j)$, and $\mathbf{p}^{(n)} = \mathbf{P}^n \mathbf{p}^{(0)}$ is the probability distribution for X_n (i.e., $p_i^{(n)} = \Pr(X_n = i)$), where $\mathbf{p}^{(0)}$ is the initial distribution.

π is a stationary distribution if $\pi = \pi \mathbf{P}$. If the Markov chain is *irreducible* (it is possible to get to any state from any state), then $\pi_i = \frac{1}{\mathbb{E}(T_i)}$ where $\mathbb{E}(T_i)$ is the expected time between two visits in state i . π_j / π_i is the expected number of visits in state j between two visits in state i .

For a connected, undirected and non-bipartite graph, where the transition probability is uniform among all neighbors, π_i is proportional to node i 's degree.

A Markov chain is *ergodic* if the asymptotic distribution is independent of the initial distribution. A finite Markov chain is ergodic iff it is irreducible and *aperiodic* (i.e., the gcd of cycle lengths is 1). $\lim_{k \rightarrow \infty} \mathbf{P}^k = \mathbf{1}\pi$.

A Markov chain is an **A-chain** if the states can be partitioned into two sets **A** and **G**, such that all states in **A** are absorbing ($p_{ii} = 1$), and all states in **G** leads to an absorbing state in **A**. The probability for absorption in state $i \in \mathbf{A}$, when the initial state is j , is $a_{ij} = p_{ij} + \sum_{k \in \mathbf{G}} a_{ik} p_{kj}$. The expected time until absorption, when the initial state is i , is $t_i = 1 + \sum_{k \in \mathbf{G}} p_{ki} t_k$.



