Contents

1 Basic

1.1 Default Code

```
//Challenge: Accepted
//#pragma GCC optimize("Ofast")
#include <bits/stdc++.h>
using namespace std;

#define io ios_base::sync_with_stdio(0);cin.tie(0);cerr.tie
    (0)
#define iter(v) v.begin(),v.end()
#define SZ(v) int(v.size())
#define pb emplace_back
#define ff first
#define ss second

using ll = long long;
using pii = pair<int, int>;
using pll = pair<ll, ll>;

#ifdef zisk
void debug(){cerr << "\n";}
template<class T, class ... U>
void debug(T a, U ... b){cerr << a << " ", debug(b...);}
template<class T> void pary(T l, T r){
  while (l != r) cerr << *l << " ", l++;
  cerr << "\n";
}
#else
#define debug(...) void()
#define pary(...) void()
#endif

template<class A, class B>
ostream& operator<<(ostream& o, pair<A,B> p)
{ return o << '(' << p.ff << ',' << p.ss << ')'; }

int main(){
  io;
}
```

1.2 .vimrc

```
sy on
se nu rnu bs=2 sw=4 ts=4 hls ls=2 si acd bo=all mouse=a
map <F9> :w<bar>!g++ "%" -o %:r -std=c++17 -Wall -Wextra -
    Wshadow -O2 -Dzisk -g -fsanitize=undefined,address<CR>
map <F8> :!./%:r<CR>
inoremap {<CR> {<CR>}<ESC>ko
# -D_GLIBCXX_ASSERTIONS, -D_GLIBCXX_DEBUG
```

1.3 Fast IO

```
// from JAW
inline int my_getchar() {
  const int N = 1<<20;
  static char buf[N];
  static char *p = buf , *end = buf;
  if(p == end) {
    if((end = buf + fread(buf , 1 , N , stdin)) == buf)
        return EOF;
    p = buf;
  }
  return *p++;
}

inline int readint(int &x) {
  static char c , neg;
  while((c = my_getchar()) < '-') {
    if(c == EOF) return 0;
  }
  neg = (c == '-') ? -1 : 1;
  x = (neg == 1) ? c - '0' : 0;
  while((c = my_getchar()) >= '0') x = (x << 3) + (x << 1)
      + (c - '0');
  x *= neg;
  return 1;
}

const int kBufSize = 524288;
char inbuf[kBufSize];
char buf_[kBufSize]; size_t size_;
inline void Flush_() { write(1, buf_, size_); size_ = 0; }
inline void CheckFlush_(size_t sz) { if (sz + size_ >
    kBufSize) Flush_(); }

inline void PutInt(int a) {
  static char tmp[22] = "01234567890123456789\n";
  CheckFlush_(10);
  if(a < 0){
    *(buf_ + size_) = '-';
    a = ~a + 1;
    size_++;
  }
  int tail = 20;
  if (!a) {
    tmp[--tail] = '0';
  } else {
    for (; a; a /= 10) tmp[--tail] = (a % 10) ^ '0';
  }
  memcpy(buf_ + size_, tmp + tail, 21 - tail);
  size_ += 21 - tail;
}

int main(){
  Flush_();
  return 0;
}
```

1.4 Random

```
mt19937 rng(chrono::system_clock::now().time_since_epoch().
    count());
```

1.5 Checker

```
#!/usr/bin/env bash
set -e
while :; do
    python3 gen.py > test.txt
    diff <(./a.exe < test.txt) <(./b.exe < test.txt)
done
```

1.6 PBDS Tree

```
#include <bits/extc++.h>
using namespace __gnu_pbds;
using Tree = tree<int, null_type, less<>, rb_tree_tag,
    tree_order_node_statistics_update>;
// .find_by_order(x)
// .order_of_key(x)
```

2 Data Structure

2.1 Heavy-Light Decomposition

```
struct Heavy_light_Decomposition { // 1-base
  int n, up[maxn], dep[maxn], to[maxn], siz[maxn], pa[maxn
      ];
  int C, ti[maxn], ord[maxn], wdown[maxn], edge[maxn], et =
       0;
  vector<pii> G[maxn];
  void init(int _n) {
    n = _n, C = 0, et = 1;
    for (int i = 1;i <= n;i++)
      G[i].clear(), to[i] = 0;
  }
  void add_edge(int a, int b, int w) {
    G[a].push_back(pii(b, et)), G[b].push_back(pii(a, et));
    edge[et++] = w;
  }
  void dfs(int u, int f, int d) {
    siz[u] = 1, pa[u] = f, dep[u] = d;
    for (auto &v: G[u])
      if (v.ff != f) {
        dfs(v.ff, u, d+1), siz[u] += siz[v];
        if (siz[to[u]] < siz[v]) to[u] = v;
      }
  }
  void cut(int u, int link) {
    ti[u] = C;
    ord[C++] = u, up[u] = link;
    if (!to[u]) return;
    cut(to[u], link);
    for (auto v:G[u]) {
      if (v.ff != pa[u] && v.ff != to[u]) cut(v.ff, v.ff);
    }
  }
  void build() { dfs(1, 1, 1), cut(1, 1); }
  int query(int a, int b) {
    int ta = up[a], tb = up[b], re = 0;
    while (ta != tb)
      if (dep[ta] < dep[tb])
        /*query*/, tb = up[b = pa[tb]];
      else /*query*/, ta = up[a = pa[ta]];
    if (a == b) return re;
    if (ti[a] > ti[b]) swap(a, b);
    /*query*/
    return re;
  }
};
```

2.2 Link Cut Tree

```
struct Splay { // LCT + PATH add
  static Splay nil;
```

```
Splay *ch[2], *f;
int rev;
int sz;
ll val, sum, tag;
Splay() : rev(0), sz(1), val(1), sum(1), tag(0) {
  f = ch[0] = ch[1] = &nil;
}
bool isr() { return f->ch[0] != this && f->ch[1] != this;
     }
int dir() { return f->ch[0] == this ? 0 : 1; }
void setCh(Splay *c, int d) {
  ch[d] = c;
  if (c != &nil) c->f = this;
  pull();
}
void push() {
  for(int i = 0; i < 2; i++){
    if(ch[i] == &nil) continue;
    if(rev) swap(ch[i]->ch[0], ch[i]->ch[1]), ch[i]->rev
        ^= 1;
    if(tag != 0){
      ch[i]->tag += tag;
      ch[i]->val += tag;
      ch[i]->sum += tag * ch[i]->sz;
    }
  }
  tag = 0;
  rev = 0;
}
void pull() {
  // take care of the nil!
  sz = 1;
  sum = val;
  for(int i = 0; i < 2; i++){
    if(ch[i] == &nil) continue;
    ch[i]->f = this;
    sz += ch[i]->sz;
    sum += ch[i]->sum;
  }
}
void rotate(){
  Splay *p = f;
  int d = dir();
  if (!p->isr()) p->f->setCh(this, p->dir());
  else f = p->f;
  p->setCh(ch[!d], d);
  setCh(p, !d);
  p->pull(), pull();

}
void update(){
  if(f != &nil) f->update();
  push();
}
void splay(){
  update();
  for(Splay* fa; fa = f, !isr(); rotate())
    if(!fa->isr()) (fa->dir() == dir() ? fa : this)->
        rotate();
}
Splay *access(Splay* q = &nil){
  splay();
  setCh(q, 1);
  pull();
  if (f != &nil) return f->access(this);
  else return q;
}
void root_path(){access(), splay();}
void chroot() {root_path(), swap(ch[0], ch[1]), rev = 1,
    push(), pull();}
void split(Splay* y){chroot(), y->root_path();}
void link(Splay* y){root_path(), y->chroot(), setCh(y, 1)
    ;}
void cut(Splay* y) {split(y), y->push(), y->ch[0] = y->ch
    [0]->f = &nil;}
Splay *get_root(){
  root_path();
    auto q = this;
    for(; q->ch[0] != &nil; q = q->ch[0]) q->push();
    return q;
  }
  Splay *lca(Splay* y){
    access(), y->root_path();
    return y->f == &nil ? &nil : y->f;
  }
  bool conn(Splay* y){return get_root() == y->get_root();}
} Splay::nil;
```

2.3 Treap

```
struct node {
  int data, sz;
  node *l, *r;
  node(int k) : data(k), sz(1), l(0), r(0) {}
  void up() {
    sz = 1;
    if (l) sz += l->sz;
    if (r) sz += r->sz;
  }
  void down() {}
};
int sz(node *a) { return a ? a->sz : 0; }
node *merge(node *a, node *b) {
  if (!a || !b) return a ? a : b;
  if (rand() % (sz(a) + sz(b)) < sz(a))
    return a->down(), a->r = merge(a->r, b), a->up(),
           a;
  return b->down(), b->l = merge(a, b->l), b->up(), b;
}
void split(node *o, node *&a, node *&b, int k) {
  if (!o) return a = b = 0, void();
  o->down();
  if (o->data <= k)
    a = o, split(o->r, a->r, b, k), a->up();
  else b = o, split(o->l, a, b->l, k), b->up();
}
void split2(node *o, node *&a, node *&b, int k) {
  if (sz(o) <= k) return a = o, b = 0, void();
  o->down();
  if (sz(o->l) + 1 <= k)
    a = o, split2(o->r, a->r, b, k - sz(o->l) - 1);
  else b = o, split2(o->l, a, b->l, k);
  o->up();
}
node *kth(node *o, int k) {
  if (k <= sz(o->l)) return kth(o->l, k);
  if (k == sz(o->l) + 1) return o;
  return kth(o->r, k - sz(o->l) - 1);
}
int Rank(node *o, int key) {
  if (!o) return 0;
  if (o->data < key)
    return sz(o->l) + 1 + Rank(o->r, key);
  else return Rank(o->l, key);
}
bool erase(node *&o, int k) {
  if (!o) return 0;
  if (o->data == k) {
    node *t = o;
    o->down(), o = merge(o->l, o->r);
    delete t;
    return 1;
  }
  node *&t = k < o->data ? o->l : o->r;
  return erase(t, k) ? o->up(), 1 : 0;
}
void insert(node *&o, int k) {
  node *a, *b;
  split(o, a, b, k),
    o = merge(a, merge(new node(k), b));
}
void interval(node *&o, int l, int r) {
  node *a, *b, *c;
```

```
  split2(o, a, b, l - 1), split2(b, b, c, r);
  // operate
  o = merge(a, merge(b, c));
}
```

2.4 KD Tree

```
namespace kdt {
  int root, lc[maxn], rc[maxn], xl[maxn], xr[maxn],
  yl[maxn], yr[maxn];
  point p[maxn];
  int build(int l, int r, int dep = 0) {
    if (l == r) return -1;
    function<bool(const point &, const point &)> f =
      [dep](const point &a, const point &b) {
        if (dep & 1) return a.x < b.x;
        else return a.y < b.y;
      };
    int m = (l + r) >> 1;
    nth_element(p + l, p + m, p + r, f);
    xl[m] = xr[m] = p[m].x;
    yl[m] = yr[m] = p[m].y;
    lc[m] = build(l, m, dep + 1);
    if (~lc[m]) {
      xl[m] = min(xl[m], xl[lc[m]]);
      xr[m] = max(xr[m], xr[lc[m]]);
      yl[m] = min(yl[m], yl[lc[m]]);
      yr[m] = max(yr[m], yr[lc[m]]);
    }
    rc[m] = build(m + 1, r, dep + 1);
    if (~rc[m]) {
      xl[m] = min(xl[m], xl[rc[m]]);
      xr[m] = max(xr[m], xr[rc[m]]);
      yl[m] = min(yl[m], yl[rc[m]]);
      yr[m] = max(yr[m], yr[rc[m]]);
    }
    return m;
  }
  bool bound(const point &q, int o, long long d) {
    double ds = sqrt(d + 1.0);
    if (q.x < xl[o] - ds || q.x > xr[o] + ds ||
        q.y < yl[o] - ds || q.y > yr[o] + ds)
      return false;
    return true;
  }
  long long dist(const point &a, const point &b) {
    return (a.x - b.x) * 1ll * (a.x - b.x) +
      (a.y - b.y) * 1ll * (a.y - b.y);
  }
  void dfs(
      const point &q, long long &d, int o, int dep = 0) {
    if (!bound(q, o, d)) return;
    long long cd = dist(p[o], q);
    if (cd != 0) d = min(d, cd);
    if ((dep & 1) && q.x < p[o].x ||
        !(dep & 1) && q.y < p[o].y) {
      if (~lc[o]) dfs(q, d, lc[o], dep + 1);
      if (~rc[o]) dfs(q, d, rc[o], dep + 1);
    } else {
      if (~rc[o]) dfs(q, d, rc[o], dep + 1);
      if (~lc[o]) dfs(q, d, lc[o], dep + 1);
    }
  }
  void init(const vector<point> &v) {
    for (int i = 0; i < v.size(); ++i) p[i] = v[i];
    root = build(0, v.size());
  }
  long long nearest(const point &q) {
    long long res = 1e18;
    dfs(q, res, root);
    return res;
  }
} // namespace kdt
```

2.5 Leftist Tree

```
struct node {
  ll v, data, sz, sum;
  node *l, *r;
  node(ll k)
    : v(0), data(k), sz(1), l(0), r(0), sum(k) {}
};
ll sz(node *p) { return p ? p->sz : 0; }
ll V(node *p) { return p ? p->v : -1; }
ll sum(node *p) { return p ? p->sum : 0; }
node *merge(node *a, node *b) {
  if (!a || !b) return a ? a : b;
  if (a->data < b->data) swap(a, b);
  a->r = merge(a->r, b);
  if (V(a->r) > V(a->l)) swap(a->r, a->l);
  a->v = V(a->r) + 1, a->sz = sz(a->l) + sz(a->r) + 1;
  a->sum = sum(a->l) + sum(a->r) + a->data;
  return a;
}
void pop(node *&o) {
  node *tmp = o;
  o = merge(o->l, o->r);
  delete tmp;
}
```

3 Flow & Matching

3.1 Dinic

```
struct Dinic { // 0-based, O(V^2E), unit flow: O(min(V
    ^{2/3}E, E^{3/2})), bipartite matching: O(sqrt(V)E)
  struct edge {
    ll to, cap, flow, rev;
  };

  int n, s, t;
  vector<vector<edge>> g;
  vector<int> dis, ind;

  void init(int _n) {
    n = _n;
    g.assign(n, vector<edge>());
  }
  void reset() {
    for (int i = 0; i < n; ++i)
      for (auto &j : g[i]) j.flow = 0;
  }
  void add_edge(int u, int v, ll cap) {
    g[u].pb(edge{v, cap, 0, SZ(g[v])});
    g[v].pb(edge{u, 0, 0, SZ(g[u]) - 1});
    //change g[v] to cap for undirected graphs
  }
  bool bfs() {
    dis.assign(n, -1);
    queue<int> q;
    q.push(s), dis[s] = 0;
    while (!q.empty()) {
      int cur = q.front(); q.pop();
      for (auto &e : g[cur]) {
        if (dis[e.to] == -1 && e.flow != e.cap) {
          q.push(e.to);
          dis[e.to] = dis[cur] + 1;
        }
      }
    }
    return dis[t] != -1;
  }
  ll dfs(int u, ll cap) {
    if (u == t || !cap) return cap;
    for (int &i = ind[u]; i < SZ(g[u]); ++i) {
      edge &e = g[u][i];
      if (dis[e.to] == dis[u] + 1 && e.flow != e.cap) {
        ll df = dfs(e.to, min(e.cap - e.flow, cap));
        if (df) {
          e.flow += df;
          g[e.to][e.rev].flow -= df;
```

```
        return df;
      }
    }
  }
  dis[u] = -1;
  return 0;
}
ll maxflow(int _s, int _t) {
  s = _s; t = _t;
  ll flow = 0, df;
  while (bfs()) {
    ind.assign(n, 0);
    while ((df = dfs(s, INF))) flow += df;
  }
  return flow;
}
};
```

3.2 Bounded Flow

```
struct BoundedFlow : Dinic {
  vector<ll> tot;
  void init(int _n) {
    Dinic::init(_n + 2);
    tot.assign(n, 0);
  }
  void add_edge(int u, int v, ll lcap, ll rcap) {
    tot[u] -= lcap, tot[v] += lcap;
    g[u].pb(edge{v, rcap, lcap, SZ(g[v])});
    g[v].pb(edge{u, 0, 0, SZ(g[u]) - 1});
  }
  bool feasible() {
    ll sum = 0;
    int vs = n - 2, vt = n - 1;
    for(int i = 0; i < n - 2; ++i)
      if(tot[i] > 0)
        add_edge(vs, i, 0, tot[i]), sum += tot[i];
      else if(tot[i] < 0) add_edge(i, vt, 0, -tot[i]);
    if(sum != maxflow(vs, vt)) sum = -1;
    for(int i = 0; i < n - 2; i++)
      if(tot[i] > 0)
        g[vs].pop_back(), g[i].pop_back();
      else if(tot[i] < 0)
        g[i].pop_back(), g[vt].pop_back();
    return sum != -1;
  }
  ll boundedflow(int _s, int _t) {
    add_edge(_t, _s, 0, INF);
    if(!feasible()) return -1;
    ll x = g[_t].back().flow;
    g[_t].pop_back(), g[_s].pop_back();
    return x - maxflow(_t, _s); // min
    //return x + maxflow(_s, _t); // max
  }
};
```

3.3 MCMF

```
struct MCMF { // 0-based, O(SPFA * |f|)
  struct edge {
    ll from, to, cap, flow, cost, rev;
  };
  int n;
  int s, t; ll mx;
  //mx: maximum amount of flow
  vector<vector<edge>> g;
  vector<ll> dis, up;
  bool BellmanFord(ll &flow, ll &cost) {
    vector<edge*> past(n);
    vector<int> inq(n);
    dis.assign(n, INF); up.assign(n, 0);
    queue<int> q;
    q.push(s), inq[s] = 1;
    up[s] = mx - flow, past[s] = 0, dis[s] = 0;
    while (!q.empty()) {
      int u = q.front();
      q.pop(), inq[u] = 0;
      if (!up[u]) continue;
      for (auto &e : g[u])
        if (e.flow != e.cap &&
            dis[e.to] > dis[u] + e.cost) {
          dis[e.to] = dis[u] + e.cost, past[e.to] = &e;
          up[e.to] = min(up[u], e.cap - e.flow);
          if (!inq[e.to]) inq[e.to] = 1, q.push(e.to);
        }
    }
    if (dis[t] == INF) return 0;
    flow += up[t], cost += up[t] * dis[t];
    for (ll i = t; past[i]; i = past[i]->from) {
      auto &e = *past[i];
      e.flow += up[t], g[e.to][e.rev].flow -= up[t];
    }
    return 1;
  }
  pll MinCostMaxFlow(int _s, int _t) {
    s = _s, t = _t;
    ll flow = 0, cost = 0;
    while (BellmanFord(flow, cost));
    return pll(flow, cost);
  }
  void init(int _n, ll _mx) {
    n = _n, mx = _mx;
    g.assign(n, vector<edge>());
  }
  void add_edge(int a, int b, ll cap, ll cost) {
    g[a].pb(edge{a, b, cap, 0, cost, SZ(g[b])});
    g[b].pb(edge{b, a, 0, 0, -cost, SZ(g[a]) - 1});
  }
};
```

3.4 Min Cost Circulation

```
struct MinCostCirculation { // 0-based, O(VE * ElogC)
  struct edge {
    ll from, to, cap, fcap, flow, cost, rev;
  };
  int n;
  vector<edge*> past;
  vector<vector<edge>> g;
  vector<ll> dis;
  void BellmanFord(int s) {
    vector<int> inq(n);
    dis.assign(n, INF);
    queue<int> q;
    auto relax = [&](int u, ll d, edge *e) {
      if (dis[u] > d) {
        dis[u] = d, past[u] = e;
        if (!inq[u]) inq[u] = 1, q.push(u);
      }
    };
    relax(s, 0, 0);
    while (!q.empty()) {
      int u = q.front();
      q.pop(), inq[u] = 0;
      for (auto &e : g[u])
        if (e.cap > e.flow)
          relax(e.to, dis[u] + e.cost, &e);
    }
  }
  void try_edge(edge &cur) {
    if (cur.cap > cur.flow) return ++cur.cap, void();
    BellmanFord(cur.to);
    if (dis[cur.from] + cur.cost < 0) {
      ++cur.flow, --g[cur.to][cur.rev].flow;
      for (int i = cur.from; past[i]; i = past[i]->from) {
        auto &e = *past[i];
        ++e.flow, --g[e.to][e.rev].flow;
      }
    }
    ++cur.cap;
  }
```

```
  void solve(int mxlg) { // mxlg >= log(max cap)
    for (int b = mxlg; b >= 0; --b) {
      for (int i = 0; i < n; ++i)
        for (auto &e : g[i])
          e.cap *= 2, e.flow *= 2;
      for (int i = 0; i < n; ++i)
        for (auto &e : g[i])
          if (e.fcap >> b & 1)
            try_edge(e);
    }
  }
  void init(int _n) {
    n = _n;
    past.assign(n, nullptr);
    g.assign(n, vector<edge>());
  }
  void add_edge(ll a, ll b, ll cap, ll cost) {
    g[a].pb(edge{a, b, 0, cap, 0, cost, SZ(g[b]) + (a == b)
        });
    g[b].pb(edge{b, a, 0, 0, 0, -cost, SZ(g[a]) - 1});
  }
};
```

3.5 Gomory Hu

```
void GomoryHu(Dinic &flow) { // 0-based
  int n = flow.n;
  vector<int> par(n);
  for (int i = 1; i < n; ++i) {
    flow.reset();
    add_edge(i, par[i], flow.maxflow(i, par[i]));
    for (int j = i + 1; j < n; ++j)
      if (par[j] == par[i] && ~flow.dis[j])
        par[j] = i;
  }
}
```

3.6 ISAP Algorithm

```
struct Maxflow { //to be modified
  static const int MAXV = 20010;
  static const int INF = 1000000;
  struct Edge {
    int v, c, r;
    Edge(int _v, int _c, int _r)
      : v(_v), c(_c), r(_r) {}
  };
  int s, t;
  vector<Edge> G[MAXV * 2];
  int iter[MAXV * 2], d[MAXV * 2], gap[MAXV * 2], tot;
  void init(int x) {
    tot = x + 2;
    s = x + 1, t = x + 2;
    for (int i = 0; i <= tot; i++) {
      G[i].clear();
      iter[i] = d[i] = gap[i] = 0;
    }
  }
  void addEdge(int u, int v, int c) {
    G[u].push_back(Edge(v, c, SZ(G[v])));
    G[v].push_back(Edge(u, 0, SZ(G[u]) - 1));
  }
  int dfs(int p, int flow) {
    if (p == t) return flow;
    for (int &i = iter[p]; i < SZ(G[p]); i++) {
      Edge &e = G[p][i];
      if (e.c > 0 && d[p] == d[e.v] + 1) {
        int f = dfs(e.v, min(flow, e.c));
        if (f) {
          e.c -= f;
          G[e.v][e.r].c += f;
          return f;
        }
      }
    }
    if ((--gap[d[p]]) == 0) d[s] = tot;
    else {
      d[p]++;
      iter[p] = 0;
      ++gap[d[p]];
    }
    return 0;
  }
  int solve() {
    int res = 0;
    gap[0] = tot;
    for (res = 0; d[s] < tot; res += dfs(s, INF))
      ;
    return res;
  }
} flow;
```

3.7 Stoer Wagner Algorithm

```
struct StoerWagner { // 0-based, O(V^3)
  int n;
  vector<int> vis, del;
  vector<ll> wei;
  vector<vector<ll>> edge;
  void init(int _n) {
    n = _n;
    del.assign(n, 0);
    edge.assign(n, vector<ll>(n));
  }
  void add_edge(int u, int v, ll w) {
    edge[u][v] += w, edge[v][u] += w;
  }
  void search(int &s, int &t) {
    vis.assign(n, 0); wei.assign(n, 0);
    s = t = -1;
    while (1) {
      ll mx = -1, cur = 0;
      for (int i = 0; i < n; ++i)
        if (!del[i] && !vis[i] && mx < wei[i])
          cur = i, mx = wei[i];
      if (mx == -1) break;
      vis[cur] = 1, s = t, t = cur;
      for (int i = 0; i < n; ++i)
        if (!vis[i] && !del[i]) wei[i] += edge[cur][i];
    }
  }
  ll solve() {
    ll ret = INF;
    for (int i = 0, x=0, y=0; i < n-1; ++i) {
      search(x, y), ret = min(ret, wei[y]), del[y] = 1;
      for (int j = 0; j < n; ++j)
        edge[x][j] = (edge[j][x] += edge[y][j]);
    }
    return ret;
  }
};
```

3.8 Bipartite Matching

```
//min vertex cover: take all unmatched vertices in L and
    find alternating tree,
//ans is not reached in L + reached in R
// O(VE)
int n; //1-base, max matching
int mx[maxn], my[maxn];
bool adj[maxn][maxn], vis[maxn];
bool dfs(int u) {
  if (vis[u]) return 0;
  vis[u] = 1;
  for (int v = 1;v <= n;v++) {
    if (!adj[u][v]) continue;
    if (!my[v] || (my[v] && dfs(my[v]))) {
      mx[u] = v, my[v] = u;
      return 1;
    }
```

```
  }
  return 0;
}
// O(E sqrt(V)), O(E Log V) for random sparse graphs
struct Bipartite_Matching { // 0-base
  int l, r;
  int mp[maxn], mq[maxn];
  int dis[maxn], cur[maxn];
  vector<int> G[maxn];
  bool dfs(int u) {
    for (int &i = cur[u]; i < SZ(G[u]); ++i) {
      int e = G[u][i];
      if (!~mq[e] || (dis[mq[e]] == dis[u] + 1 && dfs(mq[e
          ])))
        return mp[mq[e] = u] = e, 1;
    }
    dis[u] = -1;
    return 0;
  }
  bool bfs() {
    int rt = 0;
    queue<int> q;
    fill_n(dis, l, -1);
    for (int i = 0; i < l; ++i)
      if (!~mp[i])
        q.push(i), dis[i] = 0;
    while (!q.empty()) {
      int u = q.front();
      q.pop();
      for (int e : G[u])
        if (!~mq[e])
          rt = 1;
        else if (!~dis[mq[e]]) {
          q.push(mq[e]);
          dis[mq[e]] = dis[u] + 1;
        }
    }
    return rt;
  }
  int matching() {
    int rt = 0;
    fill_n(mp, l, -1);
    fill_n(mq, r, -1);
    while (bfs()) {
      fill_n(cur, l, 0);
      for (int i = 0; i < l; ++i)
        if (!~mp[i] && dfs(i))
          ++rt;
    }
    return rt;
  }
  void add_edge(int s, int t) {
    G[s].pb(t);
  }
  void init(int _l, int _r) {
    l = _l, r = _r;
    for (int i = 0; i < l; ++i)
      G[i].clear();
  }
} match;
```

3.9 Hungarian Algorithm

```
struct KM{ //1-base, max perfect matching in O(n^3)
  int n;
  int c[maxn][maxn];
  int lx[maxn], ly[maxn], mx[maxn], my[maxn], slack[maxn];
  bool vx[maxn], vy[maxn];
  bool dfs(int p, bool ch) {
    if (vx[p]) return 0;
    vx[p] = 1;
    for (int v = 1;v <= n;v++) {
      slack[v] = min(slack[v], lx[p] + ly[v] - c[p][v]);
      if (lx[p] + ly[v] - c[p][v] > 0) continue;
      vy[v] = 1;
      if (!my[v] || dfs(my[v], ch)) {
        if (ch) mx[p] = v, my[v] = p;
        return 1;
      }
    }
    return 0;
  }
  ll solve() {
    for (int i = 1;i <= n;i++){
      lx[i] = -inf;
      for (int j = 1;j <= n;j++) lx[i] = max(lx[i], a[i][j
          ]);
    }
    for (int i = 1;i <= n;i++) {
      for (int j = 1;j <= n;j++) vx[j] = vy[j] = 0;
      for (int j = 1;j <= n;j++) slack[j] = inf;
      if (dfs(i, 1)) continue;
      bool aug = 0;
      while (!aug) {
        for (int j = 1;j <= n;j++) {
          if (!vy[j] && slack[j] == 0) {
            vy[j] = 1;
            if (dfs(my[j], 0)) {
              aug = 1;
              break;
            }
          }
        }
        if (aug) break;
        int delta = inf;
        for (int j = 1;j <= n;j++) {
          if (!vy[j]) delta = min(delta, slack[j]);
        }
        for (int j = 1;j <= n;j++) {
          if (vx[j]) lx[j] -= delta;
          if (vy[j]) ly[j] += delta;
          else {
            slack[j] -= delta;
            if (slack[j] == 0 && !my[j]) aug = 1;
          }
        }
      }
      for (int j = 1;j <= n;j++) vx[j] = vy[j] = 0;
      dfs(i, 1);
    }
    ll ans = 0;
    for (int i = 1;i <= n;i++) ans += lx[i] + ly[i];
    return ans;
  }
};
```

3.10 Max Simple Graph Matching

```
struct GenMatch { // 1-base
  int V, pr[N];
  bool el[N][N], inq[N], inp[N], inb[N];
  int st, ed, nb, bk[N], djs[N], ans;
  void init(int _V) {
    V = _V;
    for (int i = 0; i <= V; ++i) {
      for (int j = 0; j <= V; ++j) el[i][j] = 0;
      pr[i] = bk[i] = djs[i] = 0;
      inq[i] = inp[i] = inb[i] = 0;
    }
  }
  void add_edge(int u, int v) {
    el[u][v] = el[v][u] = 1;
  }
  int lca(int u, int v) {
    fill_n(inp, V + 1, 0);
    while (1)
      if (u = djs[u], inp[u] = true, u == st) break;
      else u = bk[pr[u]];
    while (1)
      if (v = djs[v], inp[v]) return v;
      else v = bk[pr[v]];
    return v;
```

```
  }
  void upd(int u) {
    for (int v; djs[u] != nb;) {
      v = pr[u], inb[djs[u]] = inb[djs[v]] = true;
      u = bk[v];
      if (djs[u] != nb) bk[u] = v;
    }
  }
  void blo(int u, int v, queue<int> &qe) {
    nb = lca(u, v), fill_n(inb, V + 1, 0);
    upd(u), upd(v);
    if (djs[u] != nb) bk[u] = v;
    if (djs[v] != nb) bk[v] = u;
    for (int tu = 1; tu <= V; ++tu)
      if (inb[djs[tu]])
        if (djs[tu] = nb, !inq[tu])
          qe.push(tu), inq[tu] = 1;
  }
  void flow() {
    fill_n(inq + 1, V, 0), fill_n(bk + 1, V, 0);
    iota(djs + 1, djs + V + 1, 1);
    queue<int> qe;
    qe.push(st), inq[st] = 1, ed = 0;
    while (!qe.empty()) {
      int u = qe.front();
      qe.pop();
      for (int v = 1; v <= V; ++v)
        if (el[u][v] && djs[u] != djs[v] &&
            pr[u] != v) {
          if ((v == st) ||
              (pr[v] > 0 && bk[pr[v]] > 0)) {
            blo(u, v, qe);
          } else if (!bk[v]) {
            if (bk[v] = u, pr[v] > 0) {
              if (!inq[pr[v]]) qe.push(pr[v]);
            } else {
              return ed = v, void();
            }
          }
        }
    }
  }
  void aug() {
    for (int u = ed, v, w; u > 0;)
      v = bk[u], w = pr[v], pr[v] = u, pr[u] = v,
        u = w;
  }
  int solve() {
    fill_n(pr, V + 1, 0), ans = 0;
    for (int u = 1; u <= V; ++u)
      if (!pr[u])
        if (st = u, flow(), ed > 0) aug(), ++ans;
    return ans;
  }
};
```

3.11 Stable Marriage

Initialize $m \in M$ and $w \in W$ to *free*
while $\exists$ *free* man m who has a woman w to propose to **do**
  $w \leftarrow$ first woman on m's list to whom m has not yet proposed
  if $\exists$ some pair (m', w) **then**
    if w prefers m to m' **then**
      $m' \leftarrow$ *free*
      $(m, w) \leftarrow$ *engaged*
    end if
  else
    $(m, w) \leftarrow$ *engaged*
  end if
end while

4 Geometry

4.1 Geometry Template

```
using ld = ll;
using pdd = pair<ld, ld>;
using Line = pair<pdd, pdd>;
#define X first
#define Y second
// ld eps = 1e-7;

pdd operator+(pdd a, pdd b)
{ return {a.X + b.X, a.Y + b.Y}; }
pdd operator-(pdd a, pdd b)
{ return {a.X - b.X, a.Y - b.Y}; }
pdd operator*(ld i, pdd v)
{ return {i * v.X, i * v.Y}; }
pdd operator*(pdd v, ld i)
{ return {i * v.X, i * v.Y}; }
pdd operator/(pdd v, ld i)
{ return {v.X / i, v.Y / i}; }
ld dot(pdd a, pdd b)
{ return a.X * b.X + a.Y * b.Y; }
ld cross(pdd a, pdd b)
{ return a.X * b.Y - a.Y * b.X; }
ld abs2(pdd v)
{ return v.X * v.X + v.Y * v.Y; };
ld abs(pdd v)
{ return sqrt(abs2(v)); };
int sgn(ld v)
{ return v > 0 ? 1 : (v < 0 ? -1 : 0); }
// int sgn(ld v){ return v > eps ? 1 : ( v < -eps ? -1 : 0)
    ; }
int ori(pdd a, pdd b, pdd c)
{ return sgn(cross(b - a, c - a)); }
bool collinearity(pdd a, pdd b, pdd c)
{ return ori(a, b, c) == 0; }
bool btw(pdd p, pdd a, pdd b)
{ return collinearity(p, a, b) && sgn(dot(a - p, b - p)) <=
     0; }

bool seg_intersect(Line a, Line b){
  pdd p1, p2, p3, p4;
  tie(p1, p2) = a; tie(p3, p4) = b;
  if(btw(p1, p3, p4) || btw(p2, p3, p4) || btw(p3, p1, p2)
      || btw(p4, p1, p2))
    return true;
  return ori(p1, p2, p3) * ori(p1, p2, p4) < 0 &&
    ori(p3, p4, p1) * ori(p3, p4, p2) < 0;
}
pdd intersect(Line a, Line b){
  pdd p1, p2, p3, p4;
  tie(p1, p2) = a; tie(p3, p4) = b;
  ld a123 = cross(p2 - p1, p3 - p1);
  ld a124 = cross(p2 - p1, p4 - p1);
  return (p4 * a123 - p3 * a124) / (a123 - a124);
}
pdd perp(pdd p1)
{ return pdd(-p1.Y, p1.X); }
pdd projection(pdd p1, pdd p2, pdd p3)
{ return p1 + (p2 - p1) * dot(p3 - p1, p2 - p1) / abs2(p2 -
     p1); }
pdd reflection(pdd p1, pdd p2, pdd p3)
{ return p3 + perp(p2 - p1) * cross(p3 - p1, p2 - p1) /
    abs2(p2 - p1) * 2; }
pdd linearTransformation(pdd p0, pdd p1, pdd q0, pdd q1,
    pdd r) {
  pdd dp = p1 - p0, dq = q1 - q0, num(cross(dp, dq), dot(dp
      , dq));
  return q0 + pdd(cross(r - p0, num), dot(r - p0, num)) /
      abs2(dp);
} // from line p0--p1 to q0--q1, apply to r
```

4.2 Convex Hull

```
vector<int> getConvexHull(vector<pdd>& pts){
  vector<int> id(SZ(pts));
  iota(iter(id), 0);
  sort(iter(id), [&](int x, int y){ return pts[x] < pts[y];
      });
```

```
  vector<int> hull;
  for(int tt = 0; tt < 2; tt++){
    int sz = SZ(hull);
    for(int j : id){
      pdd p = pts[j];
      while(SZ(hull) - sz >= 2 &&
          cross(pts[hull.back()] - pts[hull[SZ(hull) - 2]],
            p - pts[hull[SZ(hull) - 2]]) <= 0)
        hull.pop_back();
      hull.pb(j);
    }
    hull.pop_back();
    reverse(iter(id));
  }
  return hull;
}
```

4.3 Minimum Enclosing Circle

```
using ld = long double;
pair<pdd, ld> circumcenter(pdd a, pdd b, pdd c);
pair<pdd, ld> MinimumEnclosingCircle(vector<pdd> &pts){
  random_shuffle(iter(pts));
  pdd c = pts[0];
  ld r = 0;
  for(int i = 1; i < SZ(pts); i++){
    if(abs(pts[i] - c) <= r) continue;
    c = pts[i]; r = 0;
    for(int j = 0; j < i; j++){
      if(abs(pts[j] - c) <= r) continue;
      c = (pts[i] + pts[j]) / 2;
      r = abs(pts[i] - c);
      for(int k = 0; k < j; k++){
        if(abs(pts[k] - c) > r)
          tie(c, r) = circumcenter(pts[i], pts[j], pts[k]);
      }
    }
  }
  return {c, r};
}
```

4.4 Minkowski Sum

```
void reorder_poly(vector<pdd>& pnts){
  int mn = 0;
  for(int i = 1; i < (int)pnts.size(); i++)
    if(pnts[i].Y < pnts[mn].Y || (pnts[i].Y == pnts[mn].Y
        && pnts[i].X < pnts[mn].X))
      mn = i;
  rotate(pnts.begin(), pnts.begin() + mn, pnts.end());
}

vector<pdd> minkowski(vector<pdd> P, vector<pdd> Q){
  reorder_poly(P);
  reorder_poly(Q);
  int psz = P.size();
  int qsz = Q.size();
  P.pb(P[0]); P.pb(P[1]); Q.pb(Q[0]); Q.pb(Q[1]);
  vector<pdd> ans;
  int i = 0, j = 0;
  while(i < psz || j < qsz){
    ans.pb(P[i] + Q[j]);
    int t = sgn(cross(P[i + 1] - P[i], Q[j + 1] - Q[j]));
    if(t >= 0) i++;
    if(t <= 0) j++;
  }
  return ans;
}
```

4.5 Polar Angle Comparator

```
// -1: a // b (if same), 0/1: a < b
int cmp(pll a, pll b, bool same = true){
#define is_neg(k) (sgn(k.Y) < 0 || (sgn(k.Y) == 0 && sgn(k.
    X) < 0))
  int A = is_neg(a), B = is_neg(b);
  if(A != B)
    return A < B;
  if(sgn(cross(a, b)) == 0)
    return same ? abs2(a) < abs2(b) : -1;
  return sgn(cross(a, b)) > 0;
}
```

4.6 Half Plane Intersection

```
// from 8BQube
pll area_pair(Line a, Line b)
{ return pll(cross(a.Y - a.X, b.X - a.X), cross(a.Y - a.X,
    b.Y - a.X)); }
bool isin(Line l0, Line l1, Line l2) {
  // Check inter(l1, l2) strictly in l0
  auto [a02X, a02Y] = area_pair(l0, l2);
  auto [a12X, a12Y] = area_pair(l1, l2);
  if (a12X - a12Y < 0) a12X *= -1, a12Y *= -1;
  return (__int128) a02Y * a12X - (__int128) a02X * a12Y >
      0; // C^4
}
/* Having solution, check size > 2 */
/* --^-- Line.X --^-- Line.Y --^-- */
vector<Line> halfPlaneInter(vector<Line> arr) {
  sort(iter(arr), [&](Line a, Line b) -> int {
    if (cmp(a.Y - a.X, b.Y - b.X, 0) != -1)
      return cmp(a.Y - a.X, b.Y - b.X, 0);
    return ori(a.X, a.Y, b.Y) < 0;
  });
  deque<Line> dq(1, arr[0]);
  for (auto p : arr) {
    if (cmp(dq.back().Y - dq.back().X, p.Y - p.X, 0) == -1)
      continue;
    while (SZ(dq) >= 2 && !isin(p, dq[SZ(dq) - 2], dq.back
        ()))
      dq.pop_back();
    while (SZ(dq) >= 2 && !isin(p, dq[0], dq[1]))
      dq.pop_front();
    dq.pb(p);
  }
  while (SZ(dq) >= 3 && !isin(dq[0], dq[SZ(dq) - 2], dq.
      back()))
    dq.pop_back();
  while (SZ(dq) >= 3 && !isin(dq.back(), dq[0], dq[1]))
    dq.pop_front();
  return vector<Line>(iter(dq));
}
```

4.7 Dynamic Convex Hull

```
struct Line{
  ll a, b, l = MIN, r = MAX;
  Line(ll a, ll b): a(a), b(b) {}
  ll operator()(ll x) const{
    return a * x + b;
  }
  bool operator<(Line b) const{
    return a < b.a;
  }
  bool operator<(ll b) const{
    return r < b;
  }
};

ll iceil(ll a, ll b){
  if(b < 0) a *= -1, b *= -1;
  if(a > 0) return (a + b - 1) / b;
  else return a / b;
}

ll intersect(Line a, Line b){
  return iceil(a.b - b.b, b.a - a.a);
```

```
}

struct DynamicConvexHull{
  multiset<Line, less<>> ch;

  void add(Line ln){
    auto it = ch.lower_bound(ln);
    while(it != ch.end()){
      Line tl = *it;
      if(tl(tl.r) <= ln(tl.r)){
        it = ch.erase(it);
      }
      else break;
    }
    auto it2 = ch.lower_bound(ln);
    while(it2 != ch.begin()){
      Line tl = *prev(it2);
      if(tl(tl.l) <= ln(tl.l)){
        it2 = ch.erase(prev(it2));
      }
      else break;
    }
    it = ch.lower_bound(ln);
    if(it != ch.end()){
      Line tl = *it;
      if(tl(tl.l) >= ln(tl.l)) ln.r = tl.l - 1;
      else{
        ll pos = intersect(ln, tl);
        tl.l = pos;
        ln.r = pos - 1;
        ch.erase(it);
        ch.insert(tl);
      }
    }
    it2 = ch.lower_bound(ln);
    if(it2 != ch.begin()){
      Line tl = *prev(it2);
      if(tl(tl.r) >= ln(tl.r)) ln.l = tl.r + 1;
      else{
        ll pos = intersect(tl, ln);
        tl.r = pos - 1;
        ln.l = pos;
        ch.erase(prev(it2));
        ch.insert(tl);
      }
    }
    if(ln.l <= ln.r) ch.insert(ln);
  }

  ll query(ll pos){
    auto it = ch.lower_bound(pos);
    if(it == ch.end()) return 0;
    return (*it)(pos);
  }
};
```

4.8 3D Point

```
// Copy from 8BQube
struct Point {
  double x, y, z;
  Point(double _x = 0, double _y = 0, double _z = 0): x(_x)
      , y(_y), z(_z){}
  Point(pdd p) { x = p.X, y = p.Y, z = abs2(p); }
};
Point operator-(Point p1, Point p2)
{ return Point(p1.x - p2.x, p1.y - p2.y, p1.z - p2.z); }
Point operator+(Point p1, Point p2)
{ return Point(p1.x + p2.x, p1.y + p2.y, p1.z + p2.z); }
Point operator*(Point p1, double v)
{ return Point(p1.x * v, p1.y * v, p1.z * v); }
Point operator/(Point p1, double v)
{ return Point(p1.x / v, p1.y / v, p1.z / v); }
Point cross(Point p1, Point p2)
{ return Point(p1.y * p2.z - p1.z * p2.y, p1.z * p2.x - p1.
    x * p2.z, p1.x * p2.y - p1.y * p2.x); }
double dot(Point p1, Point p2)
{ return p1.x * p2.x + p1.y * p2.y + p1.z * p2.z; }
double abs(Point a)
{ return sqrt(dot(a, a)); }
Point cross3(Point a, Point b, Point c)
{ return cross(b - a, c - a); }
double area(Point a, Point b, Point c)
{ return abs(cross3(a, b, c)); }
double volume(Point a, Point b, Point c, Point d)
{ return dot(cross3(a, b, c), d - a); }
//Azimuthal angle (longitude) to x-axis in interval [-pi,
    pi]
double phi(Point p) { return atan2(p.y, p.x); }
//Zenith angle (latitude) to the z-axis in interval [0, pi]
double theta(Point p) { return atan2(sqrt(p.x * p.x + p.y *
     p.y), p.z); }
Point masscenter(Point a, Point b, Point c, Point d)
{ return (a + b + c + d) / 4; }
pdd proj(Point a, Point b, Point c, Point u) {
// proj. u to the plane of a, b, and c
  Point e1 = b - a;
  Point e2 = c - a;
  e1 = e1 / abs(e1);
  e2 = e2 - e1 * dot(e2, e1);
  e2 = e2 / abs(e2);
  Point p = u - a;
  return pdd(dot(p, e1), dot(p, e2));
}
Point rotate_around(Point p, double angle, Point axis) {
  double s = sin(angle), c = cos(angle);
  Point u = axis / abs(axis);
  return u * dot(u, p) * (1 - c) + p * c + cross(u, p) * s;
}
```

4.9 ConvexHull3D

```
struct convex_hull_3D {
struct Face {
  int a, b, c;
  Face(int ta, int tb, int tc): a(ta), b(tb), c(tc) {}
}; // return the faces with pt indexes
vector<Face> res;
vector<Point> P;
convex_hull_3D(const vector<Point> &_P): res(), P(_P) {
// all points coplanar case will WA, O(n^2)
  int n = SZ(P);
  if (n <= 2) return; // be careful about edge case
  // ensure first 4 points are not coplanar
  swap(P[1], *find_if(iter(P), [&](auto p) { return sgn(
      abs2(P[0] - p)) != 0; }));
  swap(P[2], *find_if(iter(P), [&](auto p) { return sgn(
      abs2(cross3(p, P[0], P[1]))) != 0; }));
  swap(P[3], *find_if(iter(P), [&](auto p) { return sgn(
      volume(P[0], P[1], P[2], p)) != 0; }));
  vector<vector<int>> flag(n, vector<int>(n));
  res.emplace_back(0, 1, 2); res.emplace_back(2, 1, 0);
  for (int i = 3; i < n; ++i) {
    vector<Face> next;
    for (auto f : res) {
      int d = sgn(volume(P[f.a], P[f.b], P[f.c], P[i]));
      if (d <= 0) next.pb(f);
      int ff = (d > 0) - (d < 0);
      flag[f.a][f.b] = flag[f.b][f.c] = flag[f.c][f.a] = ff
          ;
    }
    for (auto f : res) {
      auto F = [&](int x, int y) {
        if (flag[x][y] > 0 && flag[y][x] <= 0)
          next.emplace_back(x, y, i);
      };
      F(f.a, f.b); F(f.b, f.c); F(f.c, f.a);
    }
    res = next;
  }
}
bool same(Face s, Face t) {
```

```
  if (sgn(volume(P[s.a], P[s.b], P[s.c], P[t.a])) != 0)
      return 0;
  if (sgn(volume(P[s.a], P[s.b], P[s.c], P[t.b])) != 0)
      return 0;
  if (sgn(volume(P[s.a], P[s.b], P[s.c], P[t.c])) != 0)
      return 0;
  return 1;
}
int polygon_face_num() {
  int ans = 0;
  for (int i = 0; i < SZ(res); ++i)
    ans += none_of(res.begin(), res.begin() + i, [&](Face g
        ) { return same(res[i], g); });
  return ans;
}
double get_volume() {
  double ans = 0;
  for (auto f : res)
    ans += volume(Point(0, 0, 0), P[f.a], P[f.b], P[f.c]);
  return fabs(ans / 6);
}
double get_dis(Point p, Face f) {
  Point p1 = P[f.a], p2 = P[f.b], p3 = P[f.c];
  double a = (p2.y - p1.y) * (p3.z - p1.z) - (p2.z - p1.z)
      * (p3.y - p1.y);
  double b = (p2.z - p1.z) * (p3.x - p1.x) - (p2.x - p1.x)
      * (p3.z - p1.z);
  double c = (p2.x - p1.x) * (p3.y - p1.y) - (p2.y - p1.y)
      * (p3.x - p1.x);
  double d = 0 - (a * p1.x + b * p1.y + c * p1.z);
  return fabs(a * p.x + b * p.y + c * p.z + d) / sqrt(a * a
       + b * b + c * c);
}
};
// n^2 delaunay: facets with negative z normal of
// convexhull of (x, y, x^2 + y^2), use a pseudo-point
// (0, 0, inf) to avoid degenerate case
```

4.10 Circle Operations

```
// from 8BQube
const double PI=acos(-1);
vector<pdd> circleLineIntersection(pdd c, double r, pdd a,
    pdd b) {
  pdd p = a + (b - a) * dot(c - a, b - a) / abs2(b - a);
  double s = cross(b - a, c - a), h2 = r * r - s * s / abs2
      (b - a);
  if (sgn(h2) < 0) return {};
  if (sgn(h2) == 0) return {p};
  pdd h = (b - a) / abs(b - a) * sqrt(h2);
  return {p - h, p + h};
}
double _area(pdd pa, pdd pb, double r){
  if(abs(pa)<abs(pb)) swap(pa, pb);
  if(abs(pb)<eps) return 0;
  double S, h, theta;
  double a=abs(pb),b=abs(pa),c=abs(pb-pa);
  double cosB = dot(pb,pb-pa) / a / c, B = acos(cosB);
  double cosC = dot(pa,pb) / a / b, C = acos(cosC);
  if(a > r){
    S = (C/2)*r*r;
    h = a*b*sin(C)/c;
    if (h < r && B < PI/2) S -= (acos(h/r)*r*r - h*sqrt(r*r
        -h*h));
  }
  else if(b > r){
    theta = PI - B - asin(sin(B)/r*a);
    S = .5*a*r*sin(theta) + (C-theta)/2*r*r;
  }
  else S = .5*sin(C)*a*b;
  return S;
}
double areaPolyCircle(const vector<pdd> poly,const pdd &O,
    const double r){
  double S=0;
  for(int i=0;i<SZ(poly);++i)
    S+=_area(poly[i]-O,poly[(i+1)%SZ(poly)]-O,r)*ori(O,poly
        [i],poly[(i+1)%SZ(poly)]);
  return fabs(S);
}
bool CCinter(Cir &a, Cir &b, pdd &p1, pdd &p2) {
  pdd o1 = a.O, o2 = b.O;
  double r1 = a.R, r2 = b.R, d2 = abs2(o1 - o2), d = sqrt(
      d2);
  if(d < max(r1, r2) - min(r1, r2) || d > r1 + r2) return
      0;
  pdd u = (o1 + o2) * 0.5 + (o1 - o2) * ((r2 * r2 - r1 * r1
      ) / (2 * d2));
  double A = sqrt((r1 + r2 + d) * (r1 - r2 + d) * (r1 + r2
      - d) * (-r1 + r2 + d));
  pdd v = pdd(o1.Y - o2.Y, -o1.X + o2.X) * A / (2 * d2);
  p1 = u + v, p2 = u - v;
  return 1;
}
vector<Line> CCtang( const Cir& c1 , const Cir& c2 , int
    sign1 ){
  vector<Line> ret;
  double d_sq = abs2( c1.O - c2.O );
  if (sgn(d_sq) == 0) return ret;
  double d = sqrt(d_sq);
  pdd v = (c2.O - c1.O) / d;
  double c = (c1.R - sign1 * c2.R) / d; // cos t
  if (c * c > 1) return ret;
  double h = sqrt(max( 0.0, 1.0 - c * c)); // sin t
  for (int sign2 = 1; sign2 >= -1; sign2 -= 2) {
    pdd n = pdd(v.X * c - sign2 * h * v.Y,
        v.Y * c + sign2 * h * v.X);
    pdd p1 = c1.O + n * c1.R;
    pdd p2 = c2.O + n * (c2.R * sign1);
    if (sgn(p1.X - p2.X) == 0 and
        sgn(p1.Y - p2.Y) == 0)
      p2 = p1 + perp(c2.O - c1.O);
    ret.pb(Line(p1, p2));
  }
  return ret;
}
```

4.11 Delaunay Triangulation

```
/* Delaunay Triangulation:
Given a sets of points on 2D plane, find a
triangulation such that no points will strictly
inside circumcircle of any triangle. */
struct Edge {
  int id; // oidx[id]
  list<Edge>::iterator twin;
  Edge(int _id = 0):id(_id) {}
};
struct Delaunay { // 0-base
  int n, oidx[N];
  list<Edge> head[N]; // result udir. graph
  pll p[N];
  void init(int _n, pll _p[]) {
    n = _n, iota(oidx, oidx + n, 0);
    for (int i = 0; i < n; ++i) head[i].clear();
    sort(oidx, oidx + n, [&](int a, int b)
    { return _p[a] < _p[b]; });
    for (int i = 0; i < n; ++i) p[i] = _p[oidx[i]];
    divide(0, n - 1);
  }
  void addEdge(int u, int v) {
    head[u].push_front(Edge(v));
    head[v].push_front(Edge(u));
    head[u].begin()->twin = head[v].begin();
    head[v].begin()->twin = head[u].begin();
  }
  void divide(int l, int r) {
    if (l == r) return;
    if (l + 1 == r) return addEdge(l, l + 1);
    int mid = (l + r) >> 1, nw[2] = {l, r};
    divide(l, mid), divide(mid + 1, r);
    auto gao = [&](int t) {
```

```
      pll pt[2] = {p[nw[0]], p[nw[1]]};
      for (auto it : head[nw[t]]) {
        int v = ori(pt[1], pt[0], p[it.id]);
        if (v > 0 || (v == 0 && abs2(pt[t ^ 1] - p[it.id])
            < abs2(pt[1] - pt[0])))
          return nw[t] = it.id, true;
      }
      return false;
    };
    while (gao(0) || gao(1));
    addEdge(nw[0], nw[1]); // add tangent
    while (true) {
      pll pt[2] = {p[nw[0]], p[nw[1]]};
      int ch = -1, sd = 0;
      for (int t = 0; t < 2; ++t)
          for (auto it : head[nw[t]])
              if (ori(pt[0], pt[1], p[it.id]) > 0 && (ch ==
                  -1 || in_cc({pt[0], pt[1], p[ch]}, p[it.
                 id])))
                 ch = it.id, sd = t;
      if (ch == -1) break; // upper common tangent
      for (auto it = head[nw[sd]].begin(); it != head[nw[sd
          ]].end(); )
        if (seg_strict_intersect(pt[sd], p[it->id], pt[sd ^
            1], p[ch]))
          head[it->id].erase(it->twin), head[nw[sd]].erase(
              it++);
        else ++it;
      nw[sd] = ch, addEdge(nw[0], nw[1]);
    }
  }
} tool;
```

4.12 Voronoi Diagram

```
// all coord. is even, you may want to call halfPlaneInter
    after then
vector<vector<Line>> vec;
void build_voronoi_line(int n, pll *arr) {
  tool.init(n, arr); // Delaunay
  vec.clear(), vec.resize(n);
  for (int i = 0; i < n; ++i)
    for (auto e : tool.head[i]) {
      int u = tool.oidx[i], v = tool.oidx[e.id];
      pll m = (arr[v] + arr[u]) / 2LL, d = perp(arr[v] -
          arr[u]);
      vec[u].pb(Line(m, m + d));
    }
}
```

4.13 Polygon Union

```
// from 8BQube
ld rat(pll a, pll b) {
  return sgn(b.X) ? (ld)a.X / b.X : (ld)a.Y / b.Y;
} // all poly. should be ccw
ld polyUnion(vector<vector<pll>> &poly) {
  ld res = 0;
  for (auto &p : poly)
    for (int a = 0; a < SZ(p); ++a) {
      pll A = p[a], B = p[(a + 1) % SZ(p)];
      vector<pair<ld, int>> segs = {{0, 0}, {1, 0}};
      for (auto &q : poly) {
        if (&p == &q) continue;
        for (int b = 0; b < SZ(q); ++b) {
          pll C = q[b], D = q[(b + 1) % SZ(q)];
          int sc = ori(A, B, C), sd = ori(A, B, D);
          if (sc != sd && min(sc, sd) < 0) {
            ld sa = cross(D - C, A - C), sb = cross(D - C,
                B - C);
            segs.pb(sa / (sa - sb), sgn(sc - sd));
          }
          if (!sc && !sd && &q < &p && sgn(dot(B - A, D - C
              )) > 0) {
            segs.pb(rat(C - A, B - A), 1);
            segs.pb(rat(D - A, B - A), -1);
          }
        }
      }
      sort(iter(segs));
      for (auto &s : segs) s.X = clamp(s.X, 0.0, 1.0);
      ld sum = 0;
      int cnt = segs[0].second;
      for (int j = 1; j < SZ(segs); ++j) {
        if (!cnt) sum += segs[j].X - segs[j - 1].X;
        cnt += segs[j].Y;
      }
      res += cross(A, B) * sum;
    }
  return res / 2;
}
```

4.14 Tangent Point to Convex Hull

```
// from 8BQube
/* The point should be strictly out of hull
  return arbitrary point on the tangent line */
pii get_tangent(vector<pll> &C, pll p) {
  auto gao = [&](int s) {
    return cyc_tsearch(SZ(C), [&](int x, int y)
    { return ori(p, C[x], C[y]) == s; });
  };
  return pii(gao(1), gao(-1));
} // return (a, b), ori(p, C[a], C[b]) >= 0
```

5 Graph

5.1 Block Cut Tree

```
struct BCC{
  vector<int> v, e, cut;
};
struct BlockCutTree{ // 0-based, allow multi edges but not
    allow loops
  int n, m, cnt = 0;
  // n:|V|, m:|E|, cnt:|bcc|
  vector<BCC> bcc;
  vector<vector<pii>> g; // original graph
  vector<pii> edges; // 0-based
  vector<vector<int>> vbcc;
  // vbcc[i] = BCCs containing vertex i, vbcc[i].size()>1
      iff i is an articulation
  vector<int> ebcc;
  // edge i is a bridge iff bcc[ebcc[i]].e.size() == 1
  // block cut tree:
  // adj[bcc i]: bcc[i].cut
  // adj[cut i]: vbcc[i]

  BlockCutTree(int _n, vector<pii> _edges):
      n(_n), m(SZ(_edges)), g(_n), edges(_edges), vbcc(_n),
          ebcc(SZ(_edges)){
    for(int i = 0; i < m; i++){
      auto [u, v] = edges[i];
      g[u].pb(pii(v, i)); g[v].pb(pii(u, i));
    }
  }

  void build(){
    vector<int> in(n, -1), low(n, -1);
    vector<vector<int>> up(n);
    vector<int> stk;
    int ts = 0;
    auto _dfs = [&](auto dfs, int now, int par, int pe) ->
        void{
      if(pe != -1) up[now].pb(pe);
      in[now] = low[now] = ts++;
      stk.pb(now);
      for(auto [v, e] : g[now]){
        if(e == pe) continue;
```

```
      if(in[v] != -1){
        if(in[v] < in[now]) up[now].pb(e);
        low[now] = min(low[now], in[v]);
        continue;
      }
      dfs(dfs, v, now, e);
      low[now] = min(low[now], low[v]);
    }
    if((now != par && low[now] >= in[par]) || (now == par
        && SZ(g[now]) == 0)){
      bcc.pb();
      while(true){
        int v = stk.back();
        stk.pop_back();
        vbcc[v].pb(cnt);
        bcc[cnt].v.pb(v);
        for(int e : up[v]){
          ebcc[e] = cnt;
          bcc[cnt].e.pb(e);
        }
        if(v == now) break;
      }
      if(now != par){
        vbcc[par].pb(cnt);
        bcc[cnt].v.pb(par);
      }
      cnt++;
    }
  };
  for(int i = 0; i < n; i++){
    if(in[i] == -1) _dfs(_dfs, i, i, -1);
  }
  for(int i = 0; i < cnt; i++)
    for(int j : bcc[i].v)
      if(SZ(vbcc[j]) > 1) bcc[i].cut.pb(j);
  }
};
```

5.2 2-SAT

```
struct SAT{ // 0-based, [n, 2n) is neg of [0, n)
  int n;
  vector<vector<int>> g, rg;
  bool ok = true;
  vector<bool> ans;

  void init(int _n){
    n = _n;
    g.resize(2 * n);
    rg.resize(2 * n);
    ans.resize(n);
  }
  int neg(int v){
    return v < n ? v + n : v - n;
  }
  void addEdge(int u, int v){
    g[u].pb(v);
    rg[v].pb(u);
  }
  void addClause(int a, int b){
    addEdge(neg(a), b);
    addEdge(neg(b), a);
  }
  void build(){
    vector<bool> vst(2 * n, false);
    vector<int> tmp, scc(2 * n, -1);
    int cnt = 1;
    function<void(int)> dfs = [&](int now){
      vst[now] = true;
      for(int i : rg[now]){
        if(vst[i]) continue;
        dfs(i);
      }
      tmp.pb(now);
    };
    for(int i = 0; i < 2 * n; i++){
      if(!vst[i]) dfs(i);
    }
    reverse(all(tmp));
    function<void(int, int)> dfs2 = [&](int now, int id){
      scc[now] = id;
      for(int i : g[now]){
        if(scc[i] != -1) continue;
        dfs2(i, id);
      }
    };
    for(int i : tmp){
      if(scc[i] == -1) dfs2(i, cnt++);
    }
    debug(scc);
    for(int i = 0; i < n; i++){
      if(scc[i] == scc[neg(i)]){
        ok = false;
        return;
      }
      if(scc[i] < scc[neg(i)]) ans[i] = true;
      else ans[i] = false;
    }
  }

};
```

5.3 Dominator Tree

```
// copy from 8BQube
struct dominator_tree { // 1-base
  vector<int> G[N], rG[N];
  int n, pa[N], dfn[N], id[N], Time;
  int semi[N], idom[N], best[N];
  vector<int> tree[N]; // dominator_tree
  void init(int _n) {
    n = _n;
    for (int i = 1; i <= n; ++i)
      G[i].clear(), rG[i].clear();
  }
  void add_edge(int u, int v) {
    G[u].pb(v), rG[v].pb(u);
  }
  void dfs(int u) {
    id[dfn[u] = ++Time] = u;
    for (auto v : G[u])
      if (!dfn[v]) dfs(v), pa[dfn[v]] = dfn[u];
  }
  int find(int y, int x) {
    if (y <= x) return y;
    int tmp = find(pa[y], x);
    if (semi[best[y]] > semi[best[pa[y]]])
      best[y] = best[pa[y]];
    return pa[y] = tmp;
  }
  void tarjan(int root) {
    Time = 0;
    for (int i = 1; i <= n; ++i) {
      dfn[i] = idom[i] = 0;
      tree[i].clear();
      best[i] = semi[i] = i;
    }
    dfs(root);
    for (int i = Time; i > 1; --i) {
      int u = id[i];
      for (auto v : rG[u])
        if (v = dfn[v]) {
          find(v, i);
          semi[i] = min(semi[i], semi[best[v]]);
        }
      tree[semi[i]].pb(i);
      for (auto v : tree[pa[i]]) {
        find(v, pa[i]);
        idom[v] =
          semi[best[v]] == pa[i] ? pa[i] : best[v];
      }
      tree[pa[i]].clear();
```

```
    }
    for (int i = 2; i <= Time; ++i) {
      if (idom[i] != semi[i]) idom[i] = idom[idom[i]];
      tree[id[idom[i]]].pb(id[i]);
    }
  }
};
```

5.4 Virtual Tree

```
// copy from 8BQube
vector<int> vG[N];
int top, st[N];

void insert(int u) {
  if (top == -1) return st[++top] = u, void();
  int p = LCA(st[top], u);
  if (p == st[top]) return st[++top] = u, void();
  while (top >= 1 && dep[st[top - 1]] >= dep[p])
    vG[st[top - 1]].pb(st[top]), --top;
  if (st[top] != p)
    vG[p].pb(st[top]), --top, st[++top] = p;
  st[++top] = u;
}

void reset(int u) {
  for (int i : vG[u]) reset(i);
  vG[u].clear();
}

void solve(vector<int> &v) {
  top = -1;
  sort(ALL(v),
      [&](int a, int b) { return dfn[a] < dfn[b]; });
  for (int i : v) insert(i);
  while (top > 0) vG[st[top - 1]].pb(st[top]), --top;
  // do something
  reset(v[0]);
}
```

5.5 Directed Minimum Spanning Tree

```
const ll INF = LLONG_MAX;
struct edge{
  int u = -1, v = -1;
  ll w = INF;
  int id = -1;
};

// 0-based, E[i].id = i
bool DMST(int n, vector<edge> &E, int root, vector<edge> &
    sol){
  vector<int> id(n), vis(n);
  vector<edge> in(n);
  for(edge e : E)
    if(e.u != e.v && e.w < in[e.v].w && e.v != root)
      in[e.v] = e;
  for(int i = 0; i < n; i++)
    if(i != root && in[i].u == -1) return false; // no sol
  int cnt = 0;
  fill(iter(id), -1); fill(iter(vis), -1);
  for(int u = 0; u < n; u++){
    int v = u;
    while(vis[v] != u && id[v] == -1 && in[v].u != -1)
      vis[v] = u, v = in[v].u;
    if(v != root && id[v] == -1){
      for(int x = in[v].u; x != v; x = in[x].u)
        id[x] = cnt;
      id[v] = cnt++;
    }
  }
  if(!cnt) return sol = in, true; // no cycle
  for(int u = 0; u < n; u++)
    if(id[u] == -1) id[u] = cnt++;
  vector<edge> nE;
  for(int i = 0; i < SZ(E); i++){
    edge tmp = E[i];
    tmp.u = id[tmp.u], tmp.v = id[tmp.v];
    if(in[E[i].v].w != INF) tmp.w -= in[E[i].v].w;
    nE.pb(tmp);
  }
  vector<edge> tsol;
  if(!DMST(cnt, nE, id[root], tsol)) return false;
  sol.resize(n);
  for(int i = 0; i < cnt; i++){
    if(i == id[root]) continue;
    int t = tsol[i].id;
    sol[E[t].v] = E[t];
  }
  for(int i = 0; i < n; i++)
    if(sol[i].id == -1) sol[i] = in[i];
  return true;
}
```

5.6 Fast DMST

```
struct Edge { int a, b; ll w; };
struct Node { /// lazy skew heap node
  Edge key;
  Node *l, *r;
  ll delta;
  void prop() {
    key.w += delta;
    if (l) l->delta += delta;
    if (r) r->delta += delta;
    delta = 0;
  }
  Edge top() { prop(); return key; }
};
Node *merge(Node *a, Node *b) {
  if (!a || !b) return a ?: b;
  a->prop(), b->prop();
  if (a->key.w > b->key.w) swap(a, b);
  swap(a->l, (a->r = merge(b, a->r)));
  return a;
}
void pop(Node*& a) { a->prop(); a = merge(a->l, a->r); }

pair<ll, vi> dmst(int n, int r, vector<Edge>& g) {
  RollbackUF uf(n); // need to implement this
  vector<Node*> heap(n);
  for (Edge e : g) heap[e.b] = merge(heap[e.b], new Node{e
      });
  ll res = 0;
  vi seen(n, -1), path(n), par(n);
  seen[r] = r;
  vector<Edge> Q(n), in(n, {-1,-1}), comp;
  deque<tuple<int, int, vector<Edge>>> cycs;
  rep(s,0,n) {
    int u = s, qi = 0, w;
    while (seen[u] < 0) {
      if (!heap[u]) return {-1,{}};
      Edge e = heap[u]->top();
      heap[u]->delta -= e.w, pop(heap[u]);
      Q[qi] = e, path[qi++] = u, seen[u] = s;
      res += e.w, u = uf.find(e.a);
      if (seen[u] == s) { /// found cycle, contract
        Node* cyc = 0;
        int end = qi, time = uf.time();
        do cyc = merge(cyc, heap[w = path[--qi]]);
        while (uf.join(u, w));
        u = uf.find(u), heap[u] = cyc, seen[u] = -1;
        cycs.push_front({u, time, {&Q[qi], &Q[end]}});
      }
    }
    rep(i,0,qi) in[uf.find(Q[i].b)] = Q[i];
  }

  for (auto& [u,t,comp] : cycs) { // restore sol (optional)
    uf.rollback(t);
    Edge inEdge = in[u];
```

```
    for (auto& e : comp) in[uf.find(e.b)] = e;
    in[uf.find(inEdge.b)] = inEdge;
  }
  rep(i,0,n) par[i] = in[i].a;
  return {res, par};
}
```

5.7 Vizing

```
// find D+1 edge coloring of a graph with max deg D
struct vizing { // returns edge coloring in adjacent matrix
     G. 1 - based
  const int N = 105;
  int C[N][N], G[N][N], X[N], vst[N], n; // ans: G[i][j]
  void init(int _n) { n = _n; // n = |V|+1
    for (int i = 0; i <= n; ++i)
      for (int j = 0; j <= n; ++j)
        C[i][j] = G[i][j] = 0;
  }
  void solve(vector<pii> &E) {
    auto update = [&](int u)
    { for (X[u] = 1; C[u][X[u]]; ++X[u]); };
    auto color = [&](int u, int v, int c) {
      int p = G[u][v];
      G[u][v] = G[v][u] = c;
      C[u][c] = v, C[v][c] = u;
      C[u][p] = C[v][p] = 0;
      if (p) X[u] = X[v] = p;
      else update(u), update(v);
      return p;
    };
    auto flip = [&](int u, int c1, int c2) {
      int p = C[u][c1];
      swap(C[u][c1], C[u][c2]);
      if (p) G[u][p] = G[p][u] = c2;
      if (!C[u][c1]) X[u] = c1;
      if (!C[u][c2]) X[u] = c2;
      return p;
    };
    fill_n(X + 1, n, 1);
    for (int t = 0; t < SZ(E); ++t) {
      int u = E[t].X, v0 = E[t].Y, v = v0, c0 = X[u], c =
          c0, d;
      vector<pii> L;
      fill_n(vst + 1, n, 0);
      while (!G[u][v0]) {
        L.emplace_back(v, d = X[v]);
        if (!C[v][c]) for (int a = SZ(L) - 1; a >= 0; --a)
            c = color(u, L[a].X, c);
        else if (!C[u][d]) for (int a = SZ(L) - 1; a >= 0;
            --a) color(u, L[a].X, L[a].Y);
        else if (vst[d]) break;
        else vst[d] = 1, v = C[u][d];
      }
      if (!G[u][v0]) {
        for (; v; v = flip(v, c, d), swap(c, d));
        if (int a; C[u][c0]) {
          for (a = SZ(L) - 2; a >= 0 && L[a].Y != c; --a);
          for (; a >= 0; --a) color(u, L[a].X, L[a].Y);
        }
        else --t;
      }
    }
  }
};
```

5.8 Maximum Clique

```
struct MaxClique { // fast when N <= 100
  bitset<N> G[N], cs[N];
  int ans, sol[N], q, cur[N], d[N], n;
  void init(int _n) {
    n = _n;
    for (int i = 0; i < n; ++i) G[i].reset();
  }
  void add_edge(int u, int v) {
    G[u][v] = G[v][u] = 1;
  }
  void pre_dfs(vector<int> &r, int l, bitset<N> mask) {
    if (l < 4) {
      for (int i : r) d[i] = (G[i] & mask).count();
      sort(ALL(r), [&](int x, int y) { return d[x] > d[y];
          });
    }
    vector<int> c(SZ(r));
    int lft = max(ans - q + 1, 1), rgt = 1, tp = 0;
    cs[1].reset(), cs[2].reset();
    for (int p : r) {
      int k = 1;
      while ((cs[k] & G[p]).any()) ++k;
      if (k > rgt) cs[++rgt + 1].reset();
      cs[k][p] = 1;
      if (k < lft) r[tp++] = p;
    }
    for (int k = lft; k <= rgt; ++k)
      for (int p = cs[k]._Find_first(); p < N; p = cs[k].
          _Find_next(p))
        r[tp] = p, c[tp] = k, ++tp;
    dfs(r, c, l + 1, mask);
  }
  void dfs(vector<int> &r, vector<int> &c, int l, bitset<N>
       mask) {
    while (!r.empty()) {
      int p = r.back();
      r.pop_back(), mask[p] = 0;
      if (q + c.back() <= ans) return;
      cur[q++] = p;
      vector<int> nr;
      for (int i : r) if (G[p][i]) nr.pb(i);
      if (!nr.empty()) pre_dfs(nr, l, mask & G[p]);
      else if (q > ans) ans = q, copy_n(cur, q, sol);
      c.pop_back(), --q;
    }
  }
  int solve() {
    vector<int> r(n);
    ans = q = 0, iota(ALL(r), 0);
    pre_dfs(r, 0, bitset<N>(string(n, '1')));
    return ans;
  }
};
```

5.9 Number of Maximal Clique

```
struct BronKerbosch { // 1-base
  int n, a[N], g[N][N];
  int S, all[N][N], some[N][N], none[N][N];
  void init(int _n) {
    n = _n;
    for (int i = 1; i <= n; ++i)
      for (int j = 1; j <= n; ++j) g[i][j] = 0;
  }
  void add_edge(int u, int v) {
    g[u][v] = g[v][u] = 1;
  }
  void dfs(int d, int an, int sn, int nn) {
    if (S > 1000) return; // pruning
    if (sn == 0 && nn == 0) ++S;
    int u = some[d][0];
    for (int i = 0; i < sn; ++i) {
      int v = some[d][i];
      if (g[u][v]) continue;
      int tsn = 0, tnn = 0;
      copy_n(all[d], an, all[d + 1]);
      all[d + 1][an] = v;
      for (int j = 0; j < sn; ++j)
        if (g[v][some[d][j]])
          some[d + 1][tsn++] = some[d][j];
      for (int j = 0; j < nn; ++j)
        if (g[v][none[d][j]])
          none[d + 1][tnn++] = none[d][j];
```

```
      dfs(d + 1, an + 1, tsn, tnn);
      some[d][i] = 0, none[d][nn++] = v;
    }
  }
  int solve() {
    iota(some[0], some[0] + n, 1);
    S = 0, dfs(0, 0, n, 0);
    return S;
  }
};
```

5.10 Minimum Mean Cycle

```
// from 8BQube
ll road[N][N]; // input here
struct MinimumMeanCycle {
  ll dp[N + 5][N], n;
  pll solve() {
    ll a = -1, b = -1, L = n + 1;
    for (int i = 2; i <= L; ++i)
      for (int k = 0; k < n; ++k)
        for (int j = 0; j < n; ++j)
          dp[i][j] =
            min(dp[i - 1][k] + road[k][j], dp[i][j]);
    for (int i = 0; i < n; ++i) {
      if (dp[L][i] >= INF) continue;
      ll ta = 0, tb = 1;
      for (int j = 1; j < n; ++j)
        if (dp[j][i] < INF &&
          ta * (L - j) < (dp[L][i] - dp[j][i]) * tb)
          ta = dp[L][i] - dp[j][i], tb = L - j;
      if (ta == 0) continue;
      if (a == -1 || a * tb > ta * b) a = ta, b = tb;
    }
    if (a != -1) {
      ll g = __gcd(a, b);
      return pll(a / g, b / g);
    }
    return pll(-1LL, -1LL);
  }
  void init(int _n) {
    n = _n;
    for (int i = 0; i < n; ++i)
      for (int j = 0; j < n; ++j) dp[i + 2][j] = INF;
  }
};
```

5.11 Minimum Steiner Tree

```
// from 8BQube
// O(V 3^T + V^2 2^T)
struct SteinerTree { // 0-base
  static const int T = 10, N = 105, INF = 1e9;
  int n, dst[N][N], dp[1 << T][N], tdst[N];
  int vcost[N]; // the cost of vertexs
  void init(int _n) {
    n = _n;
    for (int i = 0; i < n; ++i) {
      for (int j = 0; j < n; ++j) dst[i][j] = INF;
      dst[i][i] = vcost[i] = 0;
    }
  }
  void add_edge(int ui, int vi, int wi) {
    dst[ui][vi] = min(dst[ui][vi], wi);
  }
  void shortest_path() {
    for (int k = 0; k < n; ++k)
      for (int i = 0; i < n; ++i)
        for (int j = 0; j < n; ++j)
          dst[i][j] =
            min(dst[i][j], dst[i][k] + dst[k][j]);
  }
  int solve(const vector<int> &ter) {
    shortest_path();
    int t = SZ(ter);
    for (int i = 0; i < (1 << t); ++i)
      for (int j = 0; j < n; ++j) dp[i][j] = INF;
    for (int i = 0; i < n; ++i) dp[0][i] = vcost[i];
    for (int msk = 1; msk < (1 << t); ++msk) {
      if (!(msk & (msk - 1))) {
        int who = __lg(msk);
        for (int i = 0; i < n; ++i)
          dp[msk][i] =
            vcost[ter[who]] + dst[ter[who]][i];
      }
      for (int i = 0; i < n; ++i)
        for (int submsk = (msk - 1) & msk; submsk;
             submsk = (submsk - 1) & msk)
          dp[msk][i] = min(dp[msk][i],
            dp[submsk][i] + dp[msk ^ submsk][i] -
              vcost[i]);
      for (int i = 0; i < n; ++i) {
        tdst[i] = INF;
        for (int j = 0; j < n; ++j)
          tdst[i] =
            min(tdst[i], dp[msk][j] + dst[j][i]);
      }
      for (int i = 0; i < n; ++i) dp[msk][i] = tdst[i];
    }
    int ans = INF;
    for (int i = 0; i < n; ++i)
      ans = min(ans, dp[(1 << t) - 1][i]);
    return ans;
  }
};
```

6 Math

6.1 Extended Euclidean Algorithm

```
// ax+ny = 1, ax+ny == ax == 1 (mod n)
void extgcd(ll x,ll y,ll &g,ll &a,ll &b) {
  if (y == 0) g=x,a=1,b=0;
  else extgcd(y,x%y,g,b,a),b-=(x/y)*a;
}
```

6.2 Floor & Ceil

```
int ifloor(int a,int b){
  return a / b - (a % b && (a < 0) ^ (b < 0));
}
int iceil(int a,int b){
  return a / b + (a % b && (a < 0) ^ (b > 0));
}
```

6.3 Legendre

```
// the Jacobi symbol is a generalization of the Legendre
    symbol,
// such that the bottom doesn't need to be prime.
// (n|p) -> same as Legendre
// (n|ab) = (n|a)(n|b)
// work with long long
int Jacobi(int a, int m) {
  int s = 1;
  for (; m > 1; ) {
    a %= m;
    if (a == 0) return 0;
    const int r = __builtin_ctz(a);
    if ((r & 1) && ((m + 2) & 4)) s = -s;
    a >>= r;
    if (a & m & 2) s = -s;
    swap(a, m);
  }
  return s;
}
```

```
// 0: a == 0
// -1: a isn't a quad res of p
// else: return X with X^2 % p == a
// doesn't work with long long
int QuadraticResidue(int a, int p) {
  if (p == 2) return a & 1;
  const int jc = Jacobi(a, p);
  if (jc == 0) return 0;
  if (jc == -1) return -1;
  int b, d;
  for (; ; ) {
    b = rand() % p;
    d = (1LL * b * b + p - a) % p;
    if (Jacobi(d, p) == -1) break;
  }
  int f0 = b, f1 = 1, g0 = 1, g1 = 0, tmp;
  for (int e = (1LL + p) >> 1; e; e >>= 1) {
    if (e & 1) {
      tmp = (1LL * g0 * f0 + 1LL * d * (1LL * g1 * f1 % p))
           % p;
      g1 = (1LL * g0 * f1 + 1LL * g1 * f0) % p;
      g0 = tmp;
    }
    tmp = (1LL * f0 * f0 + 1LL * d * (1LL * f1 * f1 % p)) %
         p;
    f1 = (2LL * f0 * f1) % p;
    f0 = tmp;
  }
  return g0;
}
```

6.4 Simplex

```
#pragma once

typedef double T; // long double, Rational, double + mod<P
    >...
typedef vector<T> vd;
typedef vector<vd> vvd;

const T eps = 1e-8, inf = 1/.0;
#define MP make_pair
#define ltj(X) if(s == -1 || MP(X[j],N[j]) < MP(X[s],N[s]))
     s=j

struct LPSolver {
  int m, n;
  vi N, B;
  vvd D;

  LPSolver(const vvd& A, const vd& b, const vd& c) :
    m(sz(b)), n(sz(c)), N(n+1), B(m), D(m+2, vd(n+2)) {
      rep(i,0,m) rep(j,0,n) D[i][j] = A[i][j];
      rep(i,0,m) { B[i] = n+i; D[i][n] = -1; D[i][n+1] = b[
          i];}
      rep(j,0,n) { N[j] = j; D[m][j] = -c[j]; }
      N[n] = -1; D[m+1][n] = 1;
    }

  void pivot(int r, int s) {
    T *a = D[r].data(), inv = 1 / a[s];
    rep(i,0,m+2) if (i != r && abs(D[i][s]) > eps) {
      T *b = D[i].data(), inv2 = b[s] * inv;
      rep(j,0,n+2) b[j] -= a[j] * inv2;
      b[s] = a[s] * inv2;
    }
    rep(j,0,n+2) if (j != s) D[r][j] *= inv;
    rep(i,0,m+2) if (i != r) D[i][s] *= -inv;
    D[r][s] = inv;
    swap(B[r], N[s]);
  }

  bool simplex(int phase) {
    int x = m + phase - 1;
    for (;;) {
      int s = -1;
      rep(j,0,n+1) if (N[j] != -phase) ltj(D[x]);
      if (D[x][s] >= -eps) return true;
      int r = -1;
      rep(i,0,m) {
        if (D[i][s] <= eps) continue;
        if (r == -1 || MP(D[i][n+1] / D[i][s], B[i])
            < MP(D[r][n+1] / D[r][s], B[r])) r = i;
      }
      if (r == -1) return false;
      pivot(r, s);
    }
  }

  T solve(vd &x) {
    int r = 0;
    rep(i,1,m) if (D[i][n+1] < D[r][n+1]) r = i;
    if (D[r][n+1] < -eps) {
      pivot(r, n);
      if (!simplex(2) || D[m+1][n+1] < -eps) return -inf;
      rep(i,0,m) if (B[i] == -1) {
        int s = 0;
        rep(j,1,n+1) ltj(D[i]);
        pivot(i, s);
      }
    }
    bool ok = simplex(1); x = vd(n);
    rep(i,0,m) if (B[i] < n) x[B[i]] = D[i][n+1];
    return ok ? D[m][n+1] : inf;
  }
};
```

6.5 Floor Sum

```
// from 8BQube
ll floor_sum(ll n, ll m, ll a, ll b) {
  ll ans = 0;
  if (a >= m)
    ans += (n - 1) * n * (a / m) / 2, a %= m;
  if (b >= m)
    ans += n * (b / m), b %= m;
  ll y_max = (a * n + b) / m, x_max = (y_max * m - b);
  if (y_max == 0) return ans;
  ans += (n - (x_max + a - 1) / a) * y_max;
  ans += floor_sum(y_max, a, m, (a - x_max % a) % a);
  return ans;
}// sum^{n-1}_0 floor((a * i + b) / m) in log(n + m + a + b
    )
```

6.6 DiscreteLog

```
int DiscreteLog(int s, int x, int y, int m) {
  constexpr int kStep = 32000;
  unordered_map<int, int> p;
  int b = 1;
  for (int i = 0; i < kStep; ++i) {
    p[y] = i;
    y = 1LL * y * x % m;
    b = 1LL * b * x % m;
  }
  for (int i = 0; i < m + 10; i += kStep) {
    s = 1LL * s * b % m;
    if (p.find(s) != p.end()) return i + kStep - p[s];
  }
  return -1;
}
int DiscreteLog(int x, int y, int m) {
  if (m == 1) return 0;
  int s = 1;
  for (int i = 0; i < 100; ++i) {
    if (s == y) return i;
    s = 1LL * s * x % m;
  }
  if (s == y) return 100;
  int p = 100 + DiscreteLog(s, x, y, m);
  if (fpow(x, p, m) != y) return -1;
```

```
  return p; //returns: x^p = y (mod m)
}
```

6.7 Miller Rabin & Pollard Rho

```
// n < 4,759,123,141      3 : 2, 7, 61
// n < 1,122,004,669,633  4 : 2, 13, 23, 1662803
// n < 3,474,749,660,383  6 : primes <= 13
// n < 2^64              7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
ll mul(ll a, ll b, ll n){
  return (__int128)a * b % n;
}
bool Miller_Rabin(ll a, ll n) {
  if ((a = a % n) == 0) return 1;
  if (n % 2 == 0) return n == 2;
  ll tmp = (n - 1) / ((n - 1) & (1 - n));
  ll t = __lg(((n - 1) & (1 - n))), x = 1;
  for (; tmp; tmp >>= 1, a = mul(a, a, n))
    if (tmp & 1) x = mul(x, a, n);
  if (x == 1 || x == n - 1) return 1;
  while (--t)
    if ((x = mul(x, x, n)) == n - 1) return 1;
  return 0;
}
bool prime(ll n){
  vector<ll> tmp = {2, 325, 9375, 28178, 450775, 9780504,
      1795265022};
  for(ll i : tmp)
    if(!Miller_Rabin(i, n)) return false;
  return true;
}
map<ll, int> cnt;
void PollardRho(ll n) {
  if (n == 1) return;
  if (prime(n)) return ++cnt[n], void();
  if (n % 2 == 0) return PollardRho(n / 2), ++cnt[2], void
      ();
  ll x = 2, y = 2, d = 1, p = 1;
#define f(x, n, p) ((mul(x, x, n) + p) % n)
  while (true) {
    if (d != n && d != 1) {
      PollardRho(n / d);
      PollardRho(d);
      return;
    }
    if (d == n) ++p;
    x = f(x, n, p), y = f(f(y, n, p), n, p);
    d = gcd(abs(x - y), n);
  }
}
```

6.8 XOR Basis

```
const int digit = 60; // [0, 2^digit)
struct Basis{
  int total = 0, rank = 0;
  vector<ll> b;
  Basis(): b(digit) {}
  bool add(ll v){ // Gauss Jordan Elimination
    total++;
    for(int i = digit - 1; i >= 0; i--){
      if(!(1LL << i & v)) continue;
      if(b[i] != 0){
        v ^= b[i];
        continue;
      }
      for(int j = 0; j < i; j++)
        if(1LL << j & v) v ^= b[j];
      for(int j = i + 1; j < digit; j++)
        if(1LL << i & b[j]) b[j] ^= v;
      b[i] = v;
      rank++;
      return true;
    }
      return false;
  }
  ll getmax(ll x = 0){
    for(ll i : b) x = max(x, x ^ i);
    return x;
  }
  ll getmin(ll x = 0){
    for(ll i : b) x = min(x, x ^ i);
    return x;
  }
  bool can(ll x){
    return getmin(x) == 0;
  }
  ll kth(ll k){ // kth smallest, 0-indexed
    vector<ll> tmp;
    for(ll i : b) if(i) tmp.pb(i);
    ll ans = 0;
    for(int i = 0; i < SZ(tmp); i++)
      if(1LL << i & k) ans ^= tmp[i];
    return ans;
  }
};
```

6.9 Linear Equation

```
vector<int> RREF(vector<vector<ll>> &mat){
  int N = mat.size(), M = mat[0].size();
  int rk = 0;
  vector<int> cols;
  for (int i = 0;i < M;i++) {
    int cnt = -1;
    for (int j = N-1;j >= rk;j--)
      if(mat[j][i] != 0) cnt = j;
    if(cnt == -1) continue;
    swap(mat[rk], mat[cnt]);
    ll lead = mat[rk][i];
    for (int j = 0;j < M;j++) mat[rk][j] /= lead;
    for (int j = 0;j < N;j++) {
      if(j == rk) continue;
      ll tmp = mat[j][i];
      for (int k = 0;k < M;k++)
        mat[j][k] -= mat[rk][k] * tmp;
    }
    cols.pb(i);
    rk++;
  }
  return cols;
}
struct LinearEquation{
  bool ok;
  vector<ll> par; //particular solution (Ax = b)
  vector<vector<ll>> homo; //homogenous (Ax = 0)
  vector<vector<ll>> rref;
  //first M columns are matrix A
  //last column of eq is vector b
  void solve(const vector<vector<ll>> &eq){
    int M = (int)eq[0].size() - 1;
    rref = eq;
    auto piv = RREF(rref);
    int rk = piv.size();
    if(piv.size() && piv.back() == M){
      ok = 0;return;
    }
    ok = 1;
    par.resize(M);
    vector<bool> ispiv(M);
    for (int i = 0;i < rk;i++) {
      par[piv[i]] = rref[i][M];
      ispiv[piv[i]] = 1;
    }
    for (int i = 0;i < M;i++) {
      if (ispiv[i]) continue;
      vector<ll> h(M);
      h[i] = 1;
      for (int j = 0;j < rk;j++) h[piv[j]] = -rref[j][i];
      homo.pb(h);
```

```
    }
  }
}
```

6.10 Chinese Remainder Theorem

```
pll solve_crt(ll x1, ll m1, ll x2, ll m2){
  ll g = gcd(m1, m2);
  if ((x2 - x1) % g) return {0, 0}; // no sol
  m1 /= g; m2 /= g;
  ll _, p, q;
  extgcd(m1, m2, _, p, q); // p <= C
  ll lcm = m1 * m2 * g;
  ll res = ((__int128)p * (x2 - x1) % lcm * m1 % lcm + x1)
      % lcm;
  // be careful with overflow, C^3
  return {(res + lcm) % lcm, lcm}; // (x, m)
}
```

6.11 Sqrt Decomposition

```
// for all i in [l, r], floor(n / i) = x
for(int l = 1, r; l <= n; l = r + 1){
  int x = ifloor(n, l);
  r = ifloor(n, x);
}
// for all i in [l, r], ceil(n / i) = x
for(int l, r = n; r >= 1; r = l - 1){
  int x = iceil(n, r);
  l = iceil(n, x);
}
```

7 Misc

7.1 Cyclic Ternary Search

```
/* bool pred(int a, int b);
f(0) ~ f(n - 1) is a cyclic-shift U-function
return idx s.t. pred(x, idx) is false forall x*/
int cyc_tsearch(int n, auto pred) {
  if (n == 1) return 0;
  int l = 0, r = n; bool rv = pred(1, 0);
  while (r - l > 1) {
    int m = (l + r) / 2;
    if (pred(0, m) ? rv: pred(m, (m + 1) % n)) r = m;
    else l = m;
  }
  return pred(l, r % n) ? l : r % n;
}
```

7.2 Matroid

我們稱一個二元組 $M=(E,\mathcal{I})$ 為一個擬陣，其中 $\mathcal{I}\subseteq 2^E$ 為 E 的子集所形成的**非空**集合，若：

- 若 $S\in\mathcal{I}$ 以及 $S'\subsetneq S$，則 $S'\in\mathcal{I}$
- 對於 $S_1,S_2\in\mathcal{I}$ 滿足 $|S_1|<|S_2|$，存在 $e\in S_2\setminus S_1$ 使得 $S_1\cup\{e\}\in\mathcal{I}$

除此之外，我們有以下的定義：

- 位於 $\mathcal{I}$ 中的集合我們稱之為獨立集（independent set），反之不在 $\mathcal{I}$ 中的我們稱為相依集（dependent set）
- 極大的獨立集為基底（base）、極小的相依集為迴路（circuit）
- 一個集合 Y 的秩（rank）$r(Y)$ 為該集合中最大的獨立子集，也就是 $r(Y)=\max\{|X|\mid X\subseteq Y \text{ 且} X\in\mathcal{I}\}$

性質：

1. $X\subseteq Y\wedge Y\in\mathcal{I}\implies X\in\mathcal{I}$
2. $X\subseteq Y\wedge X\notin\mathcal{I}\implies Y\notin\mathcal{I}$
3. 若 B 與 B' 皆是基底且 $B\subseteq B'$，則 $B=B'$
   若 C 與 C' 皆是迴路且 $C\subseteq C'$，則 $C=C'$
4. $e\in E\wedge X\subseteq E\implies r(X)\le r(X\cup\{e\})\le r(X)+1$ i.e. 加入一個元素後秩不會降底，最多增加 1
5. $\forall Y\subseteq E,\exists X\subseteq Y, r(X)=|X|=r(Y)$

一些等價的性質：

1. 對於所有 $X\subseteq E$，X 的極大獨立子集都有相同的大小
2. 對於 $B_1,B_2\in\mathcal{B}\wedge B_1\neq B_2$，對於所有 $e_1\in B_1\setminus B_2$，存在 $e_2\in B_2\setminus B_1$ 使得 $(B_1\setminus\{e_1\})\cup\{e_2\}\in\mathcal{B}$
3. 對於 $X,Y\in\mathcal{I}$ 且 $|X|<|Y|$，存在 $e\in Y\setminus X$ 使得 $X\cup\{e\}\in\mathcal{B}$
4. 如果 $r(X\cup\{e_1\})=r(X\cup\{e_2\})=r(X)$，則 $r(X\cup\{e_1,e_2\})=r(X)$。
   如果 $r(X\cup\{e\})=r(X)$ 對於所有 $e\in E'$ 都成立，則 $r(X\cup E')=r(X)$。

擬陣交

Data: 兩個擬陣 $M_1=(E,\mathcal{I}_1)$ 以及 $M_2=(E,\mathcal{I}_2)$
Result: I 為最大的位於 $\mathcal{I}_1\cap\mathcal{I}_2$ 中的獨立集
$I\leftarrow\emptyset$
$X_1\leftarrow\{e\in E\setminus I\mid I\cup\{e\}\in\mathcal{I}_1\}$
$X_2\leftarrow\{e\in E\setminus I\mid I\cup\{e\}\in\mathcal{I}_2\}$
while $X_1\neq\emptyset$ 且 $X_2\neq\emptyset$ **do**
  if $e\in X_1\cap X_2$ **then**
    $I\leftarrow I\cup\{e\}$
  else
    構造交換圖 $\mathcal{D}_{M_1,M_2}(I)$
    在交換圖上找到一條 X_1 到 X_2 且沒有捷徑的路徑 P
    $I\leftarrow I\triangle P$
  end if
  $X_1\leftarrow\{e\in E\setminus I\mid I\cup\{e\}\in\mathcal{I}_1\}$
  $X_2\leftarrow\{e\in E\setminus I\mid I\cup\{e\}\in\mathcal{I}_2\}$
end while

8 Polynomial

8.1 FWHT

```
/* x: a[j], y: a[j + (L >> 1)]
or: (y += x * op), and: (x += y * op)
xor: (x, y = (x + y) * op, (x - y) * op)
invop: or, and, xor = -1, -1, 1/2 */
void fwt(int *a, int n, int op) { //or
  for (int L = 2; L <= n; L <<= 1)
    for (int i = 0; i < n; i += L)
      for (int j = i; j < i + (L >> 1); ++j)
        a[j + (L >> 1)] += a[j] * op;
}
const int N = 21;
int f[N][1 << N], g[N][1 << N], h[N][1 << N], ct[1 << N];
void subset_convolution(int *a, int *b, int *c, int L) {
  // c_k = \sum_{i | j = k, i & j = 0} a_i * b_j
  int n = 1 << L;
  for (int i = 1; i < n; ++i)
    ct[i] = ct[i & (i - 1)] + 1;
  for (int i = 0; i < n; ++i)
    f[ct[i]][i] = a[i], g[ct[i]][i] = b[i];
  for (int i = 0; i <= L; ++i)
    fwt(f[i], n, 1), fwt(g[i], n, 1);
  for (int i = 0; i <= L; ++i)
    for (int j = 0; j <= i; ++j)
      for (int x = 0; x < n; ++x)
        h[i][x] += f[j][x] * g[i - j][x];
  for (int i = 0; i <= L; ++i) fwt(h[i], n, -1);
  for (int i = 0; i < n; ++i) c[i] = h[ct[i]][i];
}
```

8.2 FFT

```
// Errichto: FFT for double works when the result < 1e15,
    and < 1e18 with long double

using val_t = complex<double>;
template<int MAXN>
struct FFT {
  const double PI = acos(-1);
  val_t w[MAXN];
  FFT() {
```

```
    for (int i = 0; i < MAXN; ++i) {
      double arg = 2 * PI * i / MAXN;
      w[i] = val_t(cos(arg), sin(arg));
    }
  }
  void bitrev(vector<val_t> &a, int n) //same as NTT
  void trans(vector<val_t> &a, int n, bool inv = false) {
    bitrev(a, n);
    for (int L = 2; L <= n; L <<= 1) {
      int dx = MAXN / L, dl = L >> 1;
      for (int i = 0; i < n; i += L) {
        for (int j = i, x = 0; j < i + dl; ++j, x += dx) {
          val_t tmp = a[j + dl] * (inv ? conj(w[x]) : w[x])
              ;
          a[j + dl] = a[j] - tmp;
          a[j] += tmp;
        }
      }
    }
    if (inv) {
      for (int i = 0; i < n; ++i) a[i] /= n;
    }
  }
  //multiplying two polynomials A * B:
  //fft.trans(A, siz, 0), fft.trans(B, siz, 0):
  //A[i] *= B[i], fft.trans(A, siz, 1);
};
```

8.3 NTT

```
//(2^16)+1, 65537, 3
//7*17*(2^23)+1, 998244353, 3
//1255*(2^20)+1, 1315962881, 3
//51*(2^25)+1, 1711276033, 29
// only works when sz(A) + sz(B) - 1 <= MAXN
template<int MAXN, ll P, ll RT> //MAXN must be 2^k
struct NTT {
  ll w[MAXN];
  ll mpow(ll a, ll n);
  ll minv(ll a) { return mpow(a, P - 2); }
  NTT() {
    ll dw = mpow(RT, (P - 1) / MAXN);
    w[0] = 1;
    for (int i = 1; i < MAXN; ++i) w[i] = w[i - 1] * dw % P
        ;
  }
  void bitrev(vector<ll> &a, int n) {
    int i = 0;
    for (int j = 1; j < n - 1; ++j) {
      for (int k = n >> 1; (i ^= k) < k; k >>= 1);
      if (j < i) swap(a[i], a[j]);
    }
  }
  void operator()(vector<ll> &a, int n, bool inv = false) {
       //0 <= a[i] < P
    bitrev(a, n);
    for (int L = 2; L <= n; L <<= 1) {
      int dx = MAXN / L, dl = L >> 1;
      for (int i = 0; i < n; i += L) {
        for (int j = i, x = 0; j < i + dl; ++j, x += dx) {
          ll tmp = a[j + dl] * w[x] % P;
          if ((a[j + dl] = a[j] - tmp) < 0) a[j + dl] += P;
          if ((a[j] += tmp) >= P) a[j] -= P;
        }
      }
    }
    if (inv) {
      reverse(a.begin()+1, a.begin()+n);
      ll invn = minv(n);
      for (int i = 0; i < n; ++i) a[i] = a[i] * invn % P;
    }
  }
};
```

8.4 Polynomial Operation

```
// Copy from 8BQube
#define fi(s, n) for (int i = (int)(s); i < (int)(n); ++i)
template<int MAXN, ll P, ll RT> // MAXN = 2^k
struct Poly : vector<ll> { // coefficients in [0, P)
  using vector<ll>::vector;
  static inline NTT<MAXN, P, RT> ntt;
  int n() const { return (int)size(); } // n() >= 1
  Poly(const Poly &p, int m) : vector<ll>(m) {
    copy_n(p.data(), min(p.n(), m), data());
  }
  Poly& irev() { return reverse(data(), data() + n()), *
      this; }
  Poly& isz(int m) { return resize(m), *this; }
  Poly& iadd(const Poly &rhs) { // n() == rhs.n()
    fi(0, n()) if (((*this)[i] += rhs[i]) >= P) (*this)[i]
        -= P;
    return *this;
  }
  Poly& imul(ll k) {
    fi(0, n()) (*this)[i] = (*this)[i] * k % P;
    return *this;
  }
  Poly Mul(const Poly &rhs) const {
    int m = 1;
    while (m < n() + rhs.n() - 1) m <<= 1;
    assert(m <= MAXN);
    Poly X(*this, m), Y(rhs, m);
    ntt(X, m), ntt(Y, m);
    fi(0, m) X[i] = X[i] * Y[i] % P;
    ntt(X, m, true);
    return X.isz(n() + rhs.n() - 1);
  }
  Poly Inv() const { // (*this)[0] != 0, 1e5/95ms, 2*sz<=
      MAXN
    if (n() == 1) return {ntt.minv((*this)[0])};
    int m = 1;
    while (m < n() * 2) m <<= 1;
    assert(m <= MAXN);
    Poly Xi = Poly(*this, (n() + 1) / 2).Inv().isz(m);
    Poly Y(*this, m);
    ntt(Xi, m), ntt(Y, m);
    fi(0, m) {
      Xi[i] *= (2 - Xi[i] * Y[i]) % P;
      if ((Xi[i] %= P) < 0) Xi[i] += P;
    }
    ntt(Xi, m, true);
    return Xi.isz(n());
  }
  Poly& shift_inplace(const ll &c) { // 2 * sz <= MAXN
    int n = this->n();
    vector<ll> fc(n), ifc(n);
    fc[0] = ifc[0] = 1;
    for (int i = 1; i < n; i++){
      fc[i] = fc[i-1] * i % P;
      ifc[i] = ntt.minv(fc[i]);
    }
    for (int i = 0; i < n; i++) (*this)[i] = (*this)[i] *
        fc[i] % P;
    Poly g(n);
    ll cp = 1;
    for (int i = 0; i < n; i++) g[i] = cp * ifc[i] % P, cp
        = cp * c % P;
    *this = (*this).irev().Mul(g).isz(n).irev();
    for (int i = 0; i < n; i++) (*this)[i] = (*this)[i] *
        ifc[i] % P;
    return *this;
  }
  Poly shift(const ll &c) const { return Poly(*this).
      shift_inplace(c); }
  Poly _Sqrt() const { // Jacobi((*this)[0], P) = 1
    if (n() == 1) return {QuadraticResidue((*this)[0], P)};
    Poly X = Poly(*this, (n() + 1) / 2)._Sqrt().isz(n());
    return X.iadd(Mul(X.Inv()).isz(n())).imul(P / 2 + 1);
  }
  Poly Sqrt() const { // 2 * sz <= MAXN
```

```
  Poly a;
  bool has = 0;
  for(int i = 0; i < n(); i++){
    if((*this)[i]) has = 1;
    if(has) a.push_back((*this)[i]);
  }
  if(!has) return *this;
  if( (n() + a.n()) % 2 || Jacobi(a[0], P) != 1) {
    return Poly();
  }
  a=a.isz((n() + a.n()) / 2)._Sqrt();
  int sz = a.n();
  a.isz(n());
  rotate(a.begin(), a.begin() + sz, a.end());
  return a;
}
pair<Poly, Poly> DivMod(const Poly &rhs) const { // (rhs
    .)back() != 0
  if (n() < rhs.n()) return {{0}, *this};
  const int m = n() - rhs.n() + 1;
  Poly X(rhs); X.irev().isz(m);
  Poly Y(*this); Y.irev().isz(m);
  Poly Q = Y.Mul(X.Inv()).isz(m).irev();
  X = rhs.Mul(Q), Y = *this;
  fi(0, n()) if ((Y[i] -= X[i]) < 0) Y[i] += P;
  return {Q, Y.isz(max(1, rhs.n() - 1))};
}
Poly Dx() const {
  Poly ret(n() - 1);
  fi(0, ret.n()) ret[i] = (i + 1) * (*this)[i + 1] % P;
  return ret.isz(max(1, ret.n()));
}
Poly Sx() const {
  Poly ret(n() + 1);
  fi(0, n()) ret[i + 1] = ntt.minv(i + 1) * (*this)[i] %
      P;
  return ret;
}
Poly _tmul(int nn, const Poly &rhs) const {
  Poly Y = Mul(rhs).isz(n() + nn - 1);
  return Poly(Y.data() + n() - 1, Y.data() + Y.n());
}
vector<ll> _eval(const vector<ll> &x, const vector<Poly>
    &up) const {
  const int m = (int)x.size();
  if (!m) return {};
  vector<Poly> down(m * 2);
  // down[1] = DivMod(up[1]).second;
  // fi(2, m * 2) down[i] = down[i / 2].DivMod(up[i]).
      second;
  down[1] = Poly(up[1]).irev().isz(n()).Inv().irev().
      _tmul(m, *this);
  fi(2, m * 2) down[i] = up[i ^ 1]._tmul(up[i].n() - 1,
      down[i / 2]);
  vector<ll> y(m);
  fi(0, m) y[i] = down[m + i][0];
  return y;
}
static vector<Poly> _tree1(const vector<ll> &x) {
  const int m = (int)x.size();
  vector<Poly> up(m * 2);
  fi(0, m) up[m + i] = {(x[i] ? P - x[i] : 0), 1};
  for (int i = m - 1; i > 0; --i) up[i] = up[i * 2].Mul(
      up[i * 2 + 1]);
  return up;
}
vector<ll> Eval(const vector<ll> &x) const { // 1e5, 1s
  auto up = _tree1(x); return _eval(x, up);
}
static Poly Interpolate(const vector<ll> &x, const vector
    <ll> &y) { // 1e5, 1.4s
  const int m = (int)x.size();
  vector<Poly> up = _tree1(x), down(m * 2);
  vector<ll> z = up[1].Dx()._eval(x, up);
  fi(0, m) z[i] = y[i] * ntt.minv(z[i]) % P;
  fi(0, m) down[m + i] = {z[i]};
  for (int i = m - 1; i > 0; --i) down[i] = down[i * 2].
      Mul(up[i * 2 + 1]).iadd(down[i * 2 + 1].Mul(up[i *
      2]));
  return down[1];
}
Poly Ln() const { // (*this)[0] == 1, 2*sz<=MAXN
  return Dx().Mul(Inv()).Sx().isz(n());
}
Poly Exp() const { // (*this)[0] == 0,2*sz<=MAXN
  if (n() == 1) return {1};
  Poly X = Poly(*this, (n() + 1) / 2).Exp().isz(n());
  Poly Y = X.Ln(); Y[0] = P - 1;
  fi(0, n()) if ((Y[i] = (*this)[i] - Y[i]) < 0) Y[i] +=
      P;
  return X.Mul(Y).isz(n());
}
// M := P(P - 1). If k >= M, k := k % M + M.
Poly Pow(ll k) const { // 2*sz<=MAXN
  int nz = 0;
  while (nz < n() && !(*this)[nz]) ++nz;
  if (nz * min(k, (ll)n()) >= n()) return Poly(n());
  if (!k) return Poly(Poly {1}, n());
  Poly X(data() + nz, data() + nz + n() - nz * k);
  const ll c = ntt.mpow(X[0], k % (P - 1));
  return X.Ln().imul(k % P).Exp().imul(c).irev().isz(n())
      .irev();
}
static ll LinearRecursion(const vector<ll> &a, const
    vector<ll> &coef, ll n) { // a_n = \sum c_j a_(n-j)
  const int k = (int)a.size();
  assert((int)coef.size() == k + 1);
  Poly C(k + 1), W(Poly {1}, k), M = {0, 1};
  fi(1, k + 1) C[k - i] = coef[i] ? P - coef[i] : 0;
  C[k] = 1;
  while (n) {
    if (n % 2) W = W.Mul(M).DivMod(C).second;
    n /= 2, M = M.Mul(M).DivMod(C).second;
  }
  ll ret = 0;
  fi(0, k) ret = (ret + W[i] * a[i]) % P;
  return ret;
}
};
#undef fi
using Poly_t = Poly<1 << 20, 998244353, 3>;
// template<> decltype(Poly_t::ntt) Poly_t::ntt = {};
```

8.5 Generating Function

8.5.1 Ordinary Generating Function

- $C(x) = A(rx)$: $c_n = r^n a_n$ 的一般生成函數。
- $C(x) = A(x) + B(x)$: $c_n = a_n + b_n$ 的一般生成函數。
- $C(x) = A(x)B(x)$: $c_n = \sum_{i=0}^{n} a_i b_{n-i}$ 的一般生成函數。
- $C(x) = A(x)^k$: $c_n = \sum_{i_1+i_2+\ldots+i_k=n} a_{i_1} a_{i_2} \ldots a_{i_k}$ 的一般生成函數。
- $C(x) = xA(x)'$: $c_n = na_n$ 的一般生成函數。
- $C(x) = \frac{A(x)}{1-x}$: $c_n = \sum_{i=0}^{n} a_i$ 的一般生成函數。
- $C(x) = A(1) + x\frac{A(1)-A(x)}{1-x}$: $c_n = \sum_{i=n}^{\infty} a_i$ 的一般生成函數。

常用展開式

- $\frac{1}{1-x} = 1 + x + x^2 + \ldots + x^n + \ldots$
- $(1+x)^a = \sum_{n=0}^{\infty} \binom{a}{n} x^n$, $\binom{a}{n} = \frac{a(a-1)(a-2)\ldots(a-n+1)}{n!}$.

常見生函

- 卡特蘭數：$f(x) = \frac{1-\sqrt{1-4x}}{2x}$

8.5.2 Exponential Generating Function

$a_0, a_1, \ldots$ 的指數生成函數：

$$\hat{A}(x) = \sum_{i=0}^{\infty} \frac{a_i}{i!} = a_0 + a_1 x + \frac{a_2}{2!}x^2 + \frac{a_3}{3!}x^3 + \ldots$$

- $\hat{C}(x) = \hat{A}(x) + \hat{B}(x)$: $c_n = a_n + b_n$ 的指數生成函數
- $\hat{C}(x) = \hat{A}^{(k)}(x)$: $c_n = a_{n+k}$ 的指數生成函數
- $\hat{C}(x) = x\hat{A}(x)$: $c_n = na_n$ 的指數生成函數
- $\hat{C}(x) = \hat{A}(x)\hat{B}(x)$: $c_n = \sum_{k=0}^{n}\binom{n}{i}a_k b_{n-k}$ 的指數生成函數
- $\hat{C}(x) = \hat{A}(x)^k$: $\sum_{i_1+i_2+\cdots+i_k=n}\binom{n}{i_1,i_2,\ldots,i_k}a_i a_{i_2}\ldots a_{i_k}$ 的指數生成函數
- $\hat{C}(x) = \exp(A(x))$: 假設 $A(x)$ 是一個分量 (component) 的生成函數，那 $\hat{C}(x)$ 是將 n 個有編號的東西分成若干個分量的指數生成函數

8.6 Bostan Mori

```
NTT<262144, 998244353, 3> ntt;
// Finds the k-th coefficient of P / Q in O(d log d log k)
// size of NTT has to > 2 * d
ll BostanMori(vector<ll> P, vector<ll> Q, long long k) {
  int d = max((int)P.size(), (int)Q.size() - 1);
  P.resize(d, 0);
  Q.resize(d + 1, 0);
  int sz = (2 * d + 1 == 1 ? 2 : (1 << (__lg(2 * d) + 1)));
  while(k) {
    vector<ll> Qneg(sz);
    for(int i = 0; i < (int)Q.size(); i++){
      Qneg[i] = Q[i] * ((i & 1) ? -1 : 1);
      if(Qneg[i] < 0) Qneg[i] += mod;
    }
    ntt(Qneg, sz, false);

    vector<ll> U(sz), V(sz);
    for(int i = 0; i < (int)P.size(); i++)
      U[i] = P[i];
    for(int i = 0; i < (int)Q.size(); i++)
      V[i] = Q[i];

    ntt(U, sz, false);
    ntt(V, sz, false);
    for(int i = 0; i < sz; i++)
      U[i] = U[i] * Qneg[i] % mod;
    for(int i = 0; i < sz; i++)
      V[i] = V[i] * Qneg[i] % mod;
    ntt(U, sz, true);
    ntt(V, sz, true);

    for(int i = k & 1; i <= 2 * d - 1; i += 2)
      P[i >> 1] = U[i];
    for(int i = 0; i <= 2 * d; i += 2)
      Q[i >> 1] = V[i];
    k >>= 1;
  }
  return P[0] * ntt.minv(Q[0]) % mod;
}
```

9 String

9.1 KMP Algorithm

```
void kmp(string s){
  int siz = s.size();
  vector<int> f(siz, 0);
  f[0] = 0;
  for (int i = 1;i < siz;i++) {
    f[i] = f[i-1];
    bool zero = 0;
    while (s[f[i]] != s[i]) {
      if (f[i] == 0) {
        zero = 1;
        break;
      }
      f[i] = f[f[i]-1];
    }
    if (!zero) f[i]++;
  }
}
```

9.2 Manacher Algorithm

```
vector<int> manacher(string s) {
  int n = s.size();
  vector<int> v(n);
  int pnt = -1, len = 1;
  for (int i = 0;i < n;i++) {
    int cor = 2 * pnt - i;
    if (cor >= 0) v[i] = min(v[cor], cor - pnt + len);
    while (i+v[i] < n && i-v[i] >= 0 && s[i+v[i]] == s[i-v[
        i]]) v[i]++;
    if (i + v[i] >= pnt + len) pnt = i, len = v[i];
  }
  for (int i = 0;i < n;i++) v[i] = 2 * v[i] - 1;
  return v;
}
```

9.3 MCP

```
string mcp(string s) { //Duval algorithm for Lyndon
    factorization
  s += s;
  int n = s.size(), i = 0, ans = 0;
  while (i < n/2) {
    ans = i;
    int j = i+1, k=i;
    while (j < n && s[k] <= s[j]) {
      if (s[k] < s[j]) k = i;
      else k++;
      j++;
    }
    while (i <= k) i += j - k;
  }
  return s.substr(ans, n/2);
}
```

9.4 Suffix Array

```
struct SuffixArray { //tested
  vector<int> sa, lcp, rank; //lcp[i] is lcp of sa[i] and
      sa[i-1]
  //sa[0] = s.size();
  SuffixArray(string& s, int lim=256) { // or basic_string<
      int>
    int n = s.size() + 1, k = 0, a, b;
    vector<int> x(n, 0), y(n), ws(max(n, lim));
    rank.resize(n);
    for (int i = 0;i < n-1;i++) x[i] = (int)s[i];
    sa = lcp = y, iota(sa.begin(), sa.end(), 0);
    for (int j = 0, p = 0; p < n; j = max(1, j * 2), lim =
        p) {
      p = j, iota(y.begin(), y.end(), n - j);
      for (int i = 0;i < n;i++) if (sa[i] >= j) y[p++] = sa
          [i] - j;
      for (int &i : ws) i = 0;
      for (int i = 0;i < n;i++) ws[x[i]]++;
      for (int i = 1;i < lim;i++) ws[i] += ws[i - 1];
      for (int i = n; i--;) sa[--ws[x[y[i]]]] = y[i];
      swap(x, y), p = 1, x[sa[0]] = 0;
      for(int i = 1;i < n;i++) a = sa[i - 1], b = sa[i], x[
          b] =
        (y[a] == y[b] && y[a + j] == y[b + j]) ? p - 1 : p
            ++;
    }
    for (int i = 1;i < n;i++) rank[sa[i]] = i;
```

```
    for (int i = 0, j; i < n - 1; lcp[rank[i++]] = k)
      for (k && k--, j = sa[rank[i] - 1];
          s[i + k] == s[j + k]; k++);
  }
};
```

9.5 Suffix Automaton

```
// from 8BQube
// at most 2n-1 states, 3n-4 edges

// to find longest common substring for multiple strings
    S_1, ..., S_k
// assign a special (distinct) character D_i to each string
// let T = S_1 D_1 ... S_k D_k, then build SAM of T
// answer is state with max length reachable to all D_i
const int maxn = 1000010;
struct SAM { //1 base
  vector<int> adj[maxn];
  int tot, root, lst, par[maxn], mx[maxn], fi[maxn], iter;
  //mx:maxlen of node, mx[par[i]]+1:minlen of node
  //fi: first endpos
  //corresponding substring of node can be found by fi and
      mx
  int nxt[maxn][33];
  int newNode() {
    int res = ++tot;
    fill(nxt[res], nxt[res] + 33, 0);
    par[res] = mx[res] = 0;
    fi[res] = iter;
    return res;
  }
  void init() {
    tot = 0;
    iter = 0;
    root = newNode();
    par[root] = 0, mx[root] = 0;
    lst = root;
  }
  void push(int c) {
    int p = lst;
    int np = newNode();
    mx[np] = mx[p] + 1;
    for (; p && nxt[p][c] == 0; p = par[p])
      nxt[p][c] = np;
    if (p == 0) par[np] = root;
    else {
      int q = nxt[p][c];
      if (mx[p] + 1 == mx[q]) par[np] = q;
      else {
        int nq = newNode();
        mx[nq] = mx[p] + 1;
        for (int i = 0; i < 33; i++)
          nxt[nq][i] = nxt[q][i];
        par[nq] = par[q];
        fi[nq] = fi[q];
        par[q] = nq;
        par[np] = nq;
        for (; p && nxt[p][c] == q; p = par[p])
          nxt[p][c] = nq;
      }
    }
    lst = np;
  }

  void push(string str) {
    for (int i = 0; str[i]; i++) {
      iter++;
      push(str[i] - 'a' + 1);
    }
  }
  ll get_diff_strings(){
    ll tot = 0;
    for(int i = 1; i <= tot; i++) tot += mx[i] - mx[par[i
        ]];
    return tot;
  }
  bool in[maxn];
  int cnt[maxn]; //cnt is number of occurences of node
  void count() {
    for (int i = 1; i <= tot; ++i)
      ++in[par[i]];
    queue<int> q;
    for (int i = 1; i <= tot; ++i)
      if (!in[i]) q.push(i);
    while (!q.empty()) {
      int u = q.front();
      q.pop();
      cnt[par[u]] += cnt[u];
      if (!--in[par[u]])
        q.push(par[u]);
    }
  }
} sam;
```

9.6 Z-value Algorithm

```
vector<int> z_function(string const& s) {
  int n = s.size();
  vector<int> z(n);
  for (int i = 1, l = 0, r = 0; i < n; i++) {
    if (i <= r) z[i] = min(r-i+1, z[i-l]);
    while (i + z[i] < n && s[z[i]] == s[i+z[i]])
      z[i]++;
    if (i + z[i] - 1 > r)
      l = i, r = i + z[i] - 1;
  }
  return z;
}
```

9.7 Main Lorentz

```
vector<int> z_function(string const& s);
int get_z(vector<int> const& z, int i) {
  return (0 <= i && i < SZ(z)) ? z[i] : 0;
}
vector<pair<int, int>> rep;

void convert_to_rep(int shift, bool left, int cntr, int l,
    int k1, int k2) {
  int lef = max(1, l-k2), rig = min(l, k1);
  int minl, maxl;
  if (left) {
    rig = min(rig, l-1);
    minl = shift + cntr - rig, maxl = shift+cntr-lef;
  } else {
    minl = shift + cntr - l - rig + 1, maxl = shift + cntr
        - l - lef + 1;
  }
  //left endpoint: [minl, maxl], length: 2*l
}

void find_rep(string s, int shift = 0) {
  int n = s.size();
  if (n == 1) return;

  int nu = n / 2;
  int nv = n - nu;
  string u = s.substr(0, nu);
  string v = s.substr(nu);
  string ru(u.rbegin(), u.rend());
  string rv(v.rbegin(), v.rend());

  find_rep(u, shift);
  find_rep(v, shift + nu);

  vector<int> z1 = z_function(ru);
  vector<int> z2 = z_function(v + '#' + u);
  vector<int> z3 = z_function(ru + '#' + rv);
  vector<int> z4 = z_function(v);
```

```
  for (int cntr = 0; cntr < n; cntr++) {
    int l, k1, k2;
    if (cntr < nu) {
      l = nu - cntr;
      k1 = get_z(z1, nu - cntr);
      k2 = get_z(z2, nv + 1 + cntr);
    } else {
      l = cntr - nu + 1;
      k1 = get_z(z3, nu + 1 + nv - 1 - (cntr - nu));
      k2 = get_z(z4, (cntr - nu) + 1);
    }
    if (k1 + k2 >= l)
      convert_to_rep(shift, cntr < nu, cntr, l, k1, k2);
  }
}
```

9.8 AC Automaton

```
const int maxn = 300005, maxc = 26;
struct AC_Automaton { //1-base
  int nx[maxn][maxc], fl[maxn], cnt[maxn], pri[maxn], tot;
  //pri: bfs order of trie (0-base)
  int newnode() {
    tot++;
    fill(nx[tot], nx[tot] + maxc, -1);
    return tot;
  }
  void init() { tot = 0, newnode(); }
  int input(string &s) { // return the end_node of string
    int X = 1;
    for (char c : s) {
      if (!~nx[X][c - 'a']) nx[X][c - 'a'] = newnode();
      X = nx[X][c - 'a'];
    }
    return X;
  }
  void make_fl() { //fail link
    queue<int> q;
    q.push(1), fl[1] = 0;
    for (int t = 0; !q.empty();) {
      int R = q.front();
      q.pop(), pri[t++] = R;
      for (int i = 0; i < maxc; ++i)
        if (~nx[R][i]) {
          int X = nx[R][i], Z = fl[R];
          for (; Z && !~nx[Z][i];) Z = fl[Z];
          fl[X] = Z ? nx[Z][i] : 1, q.push(X);
        }
    }
  }
  void get_v(string &s) {
    //number of times prefix appears in strings
    int X = 1;
    fill(cnt, cnt + tot+1, 0);
    for (char c : s) {
      while (X && !~nx[X][c - 'a']) X = fl[X];
      X = X ? nx[X][c - 'a'] : 1, ++cnt[X];
    }
    for (int i = tot-1; i > 0; --i)
      cnt[fl[pri[i]]] += cnt[pri[i]];
  }
} ac;
```

10 Formula

10.1 Recurrences

If $a_n = c_1 a_{n-1} + \cdots + c_k a_{n-k}$, and $r_1, \ldots, r_k$ are distinct roots of $x^k + c_1 x^{k-1} + \cdots + c_k$, there are $d_1, \ldots, d_k$ s.t.

$$a_n = d_1 r_1^n + \cdots + d_k r_k^n.$$

Non-distinct roots r become polynomial factors, e.g. $a_n = (d_1 n + d_2) r^n$.

10.2 Geometry

10.2.1 Rotation Matrix

$$\begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$$

- rotate $90°$: $(x, y) \to (-y, x)$
- rotate $-90°$: $(x, y) \to (y, -x)$

10.2.2 Triangles

Side lengths: a, b, c

Semiperimeter: $p = \dfrac{a+b+c}{2}$

Area: $A = \sqrt{p(p-a)(p-b)(p-c)}$

Circumradius: $R = \dfrac{abc}{4A}$

Inradius: $r = \dfrac{A}{p}$

Length of median (divides triangle into two equal-area triangles): $m_a = \frac{1}{2}\sqrt{2b^2 + 2c^2 - a^2}$

Length of bisector (divides angles in two): $s_a = \sqrt{bc\left(1 - \left(\dfrac{a}{b+c}\right)^2\right)}$

Law of sines: $\dfrac{\sin\alpha}{a} = \dfrac{\sin\beta}{b} = \dfrac{\sin\gamma}{c} = \dfrac{1}{2R}$

Law of cosines: $a^2 = b^2 + c^2 - 2bc\cos\alpha$

Law of tangents: $\dfrac{a+b}{a-b} = \dfrac{\tan\dfrac{\alpha+\beta}{2}}{\tan\dfrac{\alpha-\beta}{2}}$

Incenter:
$P_1 = (x_1, y_1), P_2 = (x_2, y_2), P_3 = (x_3, y_3)$
$s_1 = \overline{P_2P_3}, s_2 = \overline{P_1P_3}, s_3 = \overline{P_1P_2}$
$\dfrac{s_1P_1 + s_2P_2 + s_3P_3}{s_1 + s_2 + s_3}$

Circumcenter:
$P_0 = (0, 0), P_1 = (x_1, y_1), P_2 = (x_2, y_2)$
$x_c = \frac{1}{2} \times \dfrac{y_2(x_1^2 + y_1^2) - y_1(x_2^2 + y_2^2)}{-x_2y_1 + x_1y_2}$
$y_c = \frac{1}{2} \times \dfrac{x_2(x_1^2 + y_1^2) - x_1(x_2^2 + y_2^2)}{-x_1y_2 + x_2y_1}$

Check if (x_0, y_0) is in the circumcircle:

$$\begin{vmatrix} x_1 - x_0 & y_1 - y_0 & (x_1^2 + y_1^2) - (x_0^2 + y_0^2) \\ x_2 - x_0 & y_2 - y_0 & (x_2^2 + y_2^2) - (x_0^2 + y_0^2) \\ x_3 - x_0 & y_3 - y_0 & (x_3^2 + y_3^2) - (x_0^2 + y_0^2) \end{vmatrix}$$

0: on edge, > 0: inside, < 0: outside

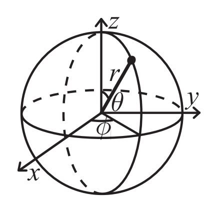
10.2.3 Quadrilaterals

With side lengths a, b, c, d, diagonals e, f, diagonals angle θ, area A and magic flux $F = b^2 + d^2 - a^2 - c^2$:

$$4A = 2ef \cdot \sin\theta = F\tan\theta = \sqrt{4e^2f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is $180°$, $ef = ac + bd$, and $A = \sqrt{(p-a)(p-b)(p-c)(p-d)}$.

10.2.4 Spherical coordinates



$$x = r\sin\theta\cos\phi \qquad r = \sqrt{x^2 + y^2 + z^2}$$
$$y = r\sin\theta\sin\phi \qquad \theta = \mathrm{acos}(z/\sqrt{x^2 + y^2 + z^2})$$
$$z = r\cos\theta \qquad \phi = \mathrm{atan2}(y, x)$$

10.2.5 Green's Theorem

$$\iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right) dxdy = \oint_{L+} (Pdx + Qdy)$$

$$\text{Area} = \frac{1}{2}\oint_L x\ dy - y\ dx$$

Circular sector:

$$\begin{aligned} x &= x_0 + r\cos\theta \\ y &= y_0 + r\sin\theta \\ A &= r\int_\alpha^\beta (x_0 + \cos\theta)\cos\theta + (y_0 + \sin\theta)\sin\theta\ d\theta \\ &= r(r\theta + x_0\sin\theta - y_0\cos\theta)|_\alpha^\beta \end{aligned}$$

10.2.6 Point-Line Duality

$$p = (a, b) \leftrightarrow p^* : y = ax - b$$

- $p \in l \iff l^* \in p^*$
- p_1, p_2, p_3 are collinear $\iff p_1^*, p_2^*, p_3^*$ intersect at a point
- p lies above $l \iff l^*$ lies above p^*
- lower convex hull $\leftrightarrow$ upper envelope

10.3 Trigonometry

$$\sinh x = \frac{1}{2}(e^x - e^{-x}) \qquad \cosh x = \frac{1}{2}(e^x + e^{-x})$$

$$\sin n\pi = 0 \qquad \cos n\pi = (-1)^n$$

$$\begin{aligned} \sin(\alpha+\beta) &= \sin\alpha\cos\beta + \cos\alpha\sin\beta \\ \cos(\alpha+\beta) &= \cos\alpha\cos\beta - \sin\alpha\sin\beta \\ \sin(2\alpha) &= 2\cos\alpha\sin\alpha \\ \cos(2\alpha) &= \cos^2\alpha - \sin^2\alpha \\ &= 2\cos^2\alpha - 1 \\ &= 1 - 2\sin^2\alpha \end{aligned}$$

$$\begin{aligned} \tan(\alpha+\beta) &= \frac{\tan\alpha + \tan\beta}{1 - \tan\alpha\tan\beta} \\ \sin\alpha + \sin\beta &= 2\sin\frac{\alpha+\beta}{2}\cos\frac{\alpha-\beta}{2} \\ \cos\alpha + \cos\beta &= 2\cos\frac{\alpha+\beta}{2}\cos\frac{\alpha-\beta}{2} \\ \sin\alpha\sin\beta &= \frac{1}{2}(\cos(\alpha-\beta) - \cos(\alpha+\beta)) \\ \sin\alpha\cos\beta &= \frac{1}{2}(\sin(\alpha+\beta) + \sin(\alpha-\beta)) \\ \cos\alpha\sin\beta &= \frac{1}{2}(\sin(\alpha+\beta) - \sin(\alpha-\beta)) \\ \cos\alpha\cos\beta &= \frac{1}{2}(\cos(\alpha-\beta) + \cos(\alpha+\beta)) \end{aligned}$$

$$(V+W)\tan(\alpha-\beta)/2 = (V-W)\tan(\alpha+\beta)/2$$

where V, W are lengths of sides opposite angles α, β.

$$\begin{aligned} a\cos x + b\sin x &= r\cos(x - \phi) \\ a\sin x + b\cos x &= r\sin(x + \phi) \end{aligned}$$

where $r = \sqrt{a^2+b^2}, \phi = \operatorname{atan2}(b, a)$.

10.4 Derivatives/Integrals

Integration by parts:

$$\int_a^b f(x)g(x)dx = [F(x)g(x)]_a^b - \int_a^b F(x)g'(x)dx$$

$$\begin{aligned} \frac{d}{dx}\arcsin x &= \frac{1}{\sqrt{1-x^2}} & \frac{d}{dx}\arccos x &= -\frac{1}{\sqrt{1-x^2}} \\ \frac{d}{dx}\tan x &= 1 + \tan^2 x & \frac{d}{dx}\arctan x &= \frac{1}{1+x^2} \\ \int \tan ax &= -\frac{\ln|\cos ax|}{a} & \int x\sin ax &= \frac{\sin ax - ax\cos ax}{a^2} \\ \int e^{-x^2} &= \frac{\sqrt{\pi}}{2}\operatorname{erf}(x) & \int xe^{ax} &= \frac{e^{ax}}{a^2}(ax - 1) \\ \int \sin^2(x) &= \frac{x}{2} - \frac{1}{4}\sin 2x & \int \sin^3 x &= \frac{1}{12}\cos 3x - \frac{3}{4}\cos x \\ \int \cos^2(x) &= \frac{x}{2} + \frac{1}{4}\sin 2x & \int \cos^3 x &= \frac{1}{12}\sin 3x + \frac{3}{4}\sin x \\ \int x\sin x &= \sin x - x\cos x & \int x\cos x &= \cos x + x\sin x \\ \int xe^x &= e^x(x-1) & \int x^2e^x &= e^x(x^2 - 2x + 2) \end{aligned}$$

$$\begin{aligned} \int x^2\sin x &= 2x\sin x - (x^2 - 2)\cos x \\ \int x^2\cos x &= 2x\cos x + (x^2 - 2)\sin x \\ \int e^x\sin x &= \frac{1}{2}e^x(\sin x - \cos x) \\ \int e^x\cos x &= \frac{1}{2}e^x(\sin x + \cos x) \\ \int xe^x\sin x &= \frac{1}{2}e^x(x\sin x - x\cos x + \cos x) \\ \int xe^x\cos x &= \frac{1}{2}e^x(x\sin x + x\cos x - \sin x) \end{aligned}$$

10.5 Sums

$$c^a + c^{a+1} + \cdots + c^b = \frac{c^{b+1} - c^a}{c - 1}, c \neq 1$$

$$\begin{aligned} 1 + 2 + 3 + \cdots + n &= \frac{n(n+1)}{2} \\ 1^2 + 2^2 + 3^2 + \cdots + n^2 &= \frac{n(2n+1)(n+1)}{6} \\ 1^3 + 2^3 + 3^3 + \cdots + n^3 &= \frac{n^2(n+1)^2}{4} \\ 1^4 + 2^4 + 3^4 + \cdots + n^4 &= \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30} \end{aligned}$$

10.6 Series

$$\begin{aligned} e^x &= 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \ldots, (-\infty < x < \infty) \\ \ln(1+x) &= x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \ldots, (-1 < x \leq 1) \\ \sqrt{1+x} &= 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{2x^3}{32} - \frac{5x^4}{128} + \ldots, (-1 \leq x \leq 1) \\ \sin x &= x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \ldots, (-\infty < x < \infty) \\ \cos x &= 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \ldots, (-\infty < x < \infty) \end{aligned}$$