

*Annotated
Version*

Machine Learning Course - CS-433

Gaussian Mixture Models

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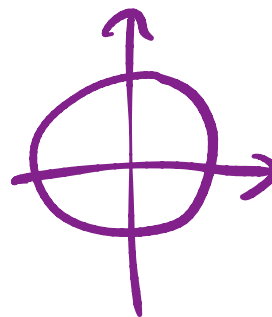
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credits to Mohammad Emtiyaz Khan & Rüdiger Urbanke

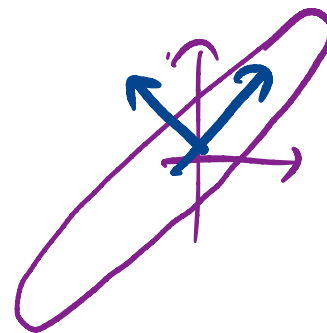
EPFL

Motivation

K-means forces the clusters to be *spherical*, but sometimes it is desirable to have *elliptical* clusters. Another issue is that, in K-means, each example *can only belong to one cluster*, but this may not always be a good choice, e.g. for data points that are near the "border". Both of these problems are solved by using Gaussian Mixture Models.



$$\Sigma = \mathbf{I}$$



$$\Sigma \text{ general}$$

Clustering with Gaussians

The first issue is resolved by using full covariance matrices Σ_k instead of *isotropic* covariances.

①

$$p(\mathbf{X} | \mu, \Sigma, \mathbf{z}) = \prod_{n=1}^N \prod_{k=1}^K [\mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)]^{z_{nk}}$$

parameters :

$$\mu \in \mathbb{R}^{D \times K}$$

$$\Sigma \in \mathbb{R}^{D \times D \times K}$$

$$\pi \in \mathbb{R}^K$$

Soft-clustering

The second issue is resolved by defining z_n to be a random variable. Specifically, define $z_n \in \{1, 2, \dots, K\}$ that follows a *multinomial distribution*.

②

random variable (vector 0...1...0)

$$p(z_n = k) = \pi_k \text{ where } \pi_k > 0, \forall k \text{ and } \sum_{k=1}^K \pi_k = 1$$

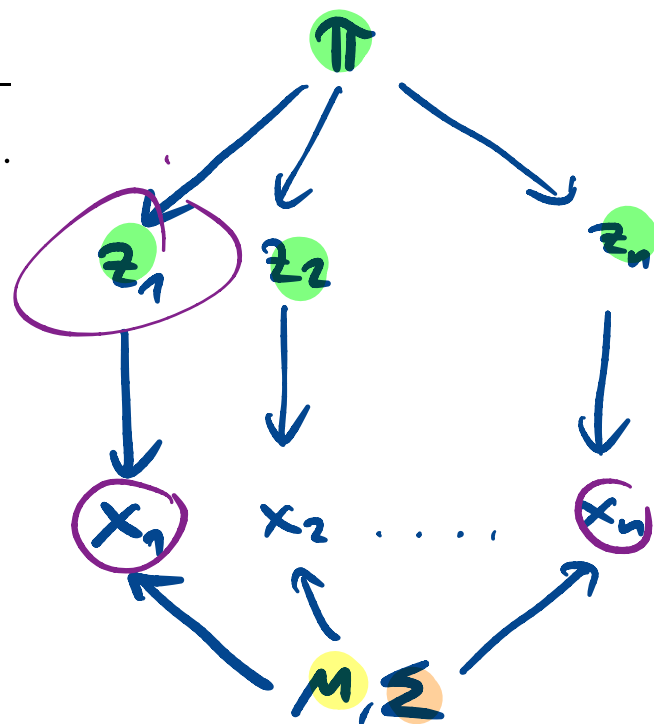
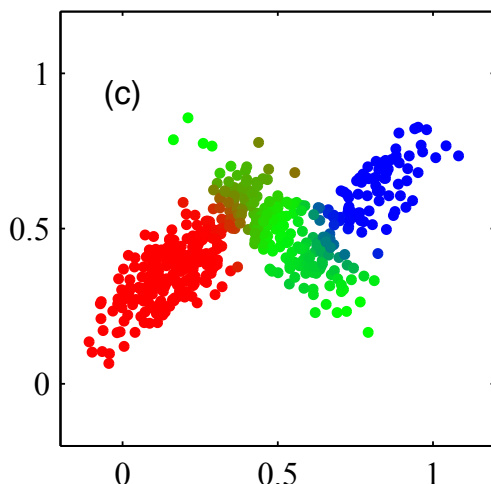
0...1...0
z_{k-th entry}

importance of cluster k

$$z_n = (0 \dots 1 \dots 0)$$

$$z_{nk} = \begin{cases} 1 \\ 0 \end{cases}$$

This leads to **soft-clustering** as opposed to having “hard” assignments.



Gaussian mixture model

Together, the **likelihood** and the **prior** define the **joint** distribution of Gaussian mixture model (GMM):

Bayes Rule:

$$p(a, b) = p(a|b) p(b)$$

joint

$$p(\mathbf{X}, \mathbf{z} | \mu, \Sigma, \pi)$$

$$= \prod_{n=1}^N p(\mathbf{x}_n | z_n, \mu, \Sigma) p(z_n | \pi)$$

likelihood (1) *prior* (2)

$$= \prod_{n=1}^N \prod_{k=1}^K [\mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)]^{z_{nk}} \prod_{k=1}^K [\pi_k]^{z_{nk}}$$

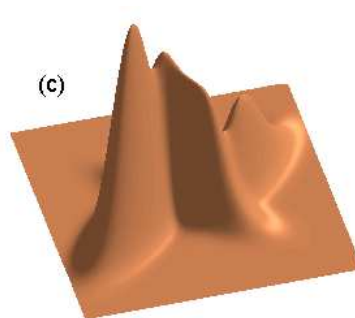
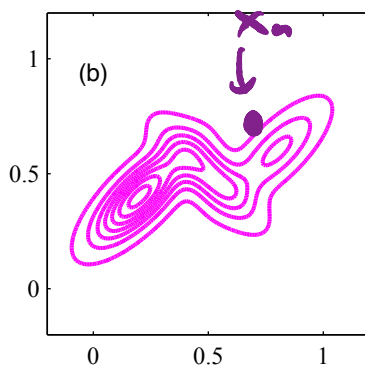
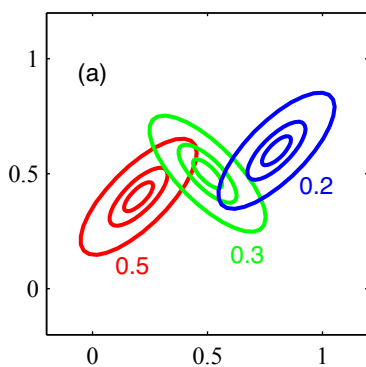
Here, \mathbf{x}_n are observed data vectors, z_n are **latent** unobserved variables, and the unknown **parameters** are given by $\theta := \{\mu_1, \dots, \mu_K, \Sigma_1, \dots, \Sigma_K, \pi\}$.

Marginal likelihood

GMM is a latent variable model with z_n being the unobserved (latent) variables. An advantage of treating z_n as latent variables instead of parameters is that we can marginalize them out to get a cost function that does not depend on z_n , i.e. as if z_n never existed.

Specifically, we get the following marginal likelihood by marginalizing z_n out from the likelihood:

$$p(\mathbf{x}_n | \theta) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)$$



Deriving cost functions this way is good for statistical efficiency. Without a latent variable model, the number of parameters grows at rate $\mathcal{O}(N)$. After marginalization, the growth is reduced to $\mathcal{O}(D^2 K)$ (assuming $D, K \ll N$).

joint:

$$p(\mathbf{x}_n, z_n)$$

marginal:

$$p(\mathbf{x}_n) = \sum_{k=1}^K p(\mathbf{x}_n, z_n=k)$$

$$= \sum_k \underbrace{p(\mathbf{x}_n | z)}_{\text{N of cluster } k} \underbrace{p(z)}_{\pi_k}$$

$$z: N \cdot K$$

$$\theta: \begin{matrix} \mu & K \cdot D \\ \Sigma & K \cdot D^2 \\ \pi & K \end{matrix}$$

Maximum likelihood

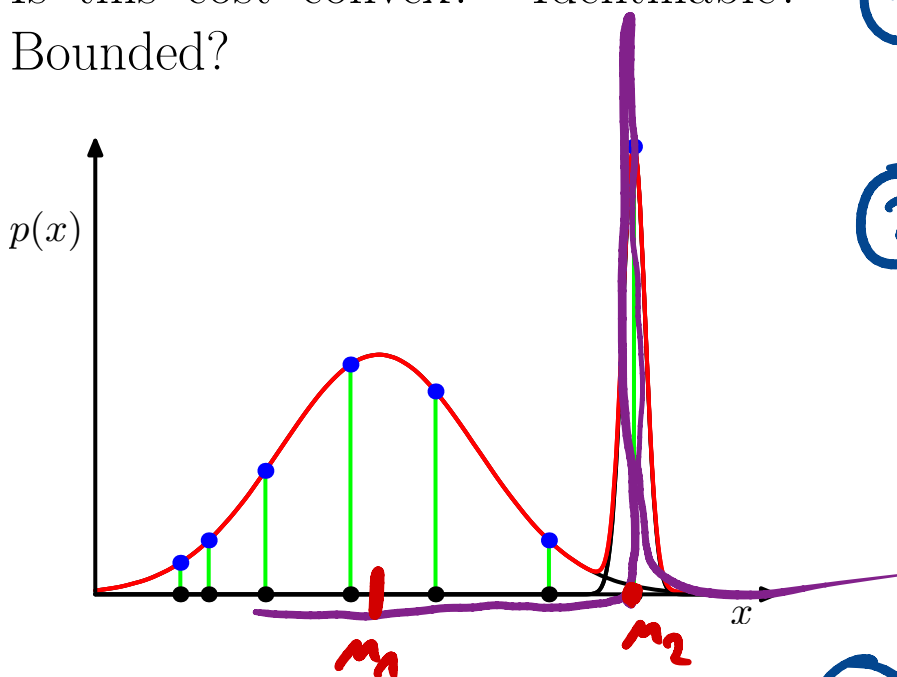
To get a maximum (marginal) likelihood estimate of θ , we maximize the following:

$$\max_{\theta} \sum_{n=1}^N \log \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)$$

marginal likelihood

$$\log \left(p(\mathbf{x}^{\text{all}}_{\mathbf{x}_n} | \theta) \right) = \sum_{n=1}^N \log p(\mathbf{x}_n | \theta) = \sum_k \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)$$

Is this cost convex? Identifiable? Bounded?



① non-convex
(see k-means)

② non-unique optima
permutation of $1 \dots k$
 $k \rightarrow k'$ $\pi_k \rightarrow \pi_{k'}$
 $\mu_k \rightarrow \mu_{k'}$
 $\Sigma_k \rightarrow \Sigma_{k'}$

③ unbounded
 $\Sigma_k = \sigma_k \mathbf{I}$
↑ scalar width

width $\sigma_k \rightarrow 0$