

Autonomous_Robotics_with_ROS_for_mmWave Manifest

12-14-2017

Manifest ID - SRAS00004585

Legend

(explanation of the fields in the Manifest Table below)

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Autonomous_Robotics_with_ROS_for_mmWave Manifest Table

See the Legend above for a description of these columns.

Software Name	Version	License Type	Delivered As	Modified by TI		
turtlebot_mmwave_launchers package	1.0	BSD-3-Clause	Source	N/A	Location	[installed path]/ turtlebot_mmwave_launchers/
					Obtained from	TI
ROS navigation/move_base package	1.14.2	BSD-3-Clause	Source	YES	Location	[installed path]/navigation/move_base/
					Obtained from	https://github.com/ros-planning/navigation.git
ROS navigation/rotate_recovery package	1.14.2	BSD-3-Clause	Source	YES	Location	[installed path]/navigation/rotate_recovery/
					Obtained from	https://github.com/ros-planning/navigation.git
ROS turtlebot packages	N/A	BSD-3-Clause	Source	YES	Location	[installed path]/turtlebot/
					Obtained from	https://github.com/turtlebot

Credits

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Autonomous_Robotics_with_ROS_for_mmWave Licenses

turtlebot_mmwave_launchers package:

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