

```
def is_dag_util(graph, vertex, visited, stack):
```

```
    visited[vertex] = True
```

```
    stack[vertex] = True
```

```
    for i in graph.outbound[vertex]:
```

```
        if not visited[i]:
```

```
            if is_dag_util(graph, i, visited, stack):
```

```
                return True
```

```
        elif stack[i]:
```

```
            return True
```

```
    stack[vertex] = False
```

```
    return False
```

```
def is_dag(graph):
```

```
    visited = {vertex: False for vertex in graph.inbound.keys()}
```

```
    stack = {vertex: False for vertex in graph.inbound.keys()}
```

```
    for i in graph.inbound.keys():
```

```
        if not visited[i]:
```

```
            if is_dag_util(graph, i, visited, stack):
```

```
                return False #not acyclic
```

```
    return True
```

```
def topo_sort(graph):
```

```
    if is_dag(graph):
```

```
        visited = {v: False for v in graph.inbound.keys()}
```

```
        stack = []
```

```
        for i in graph.inbound.keys():
```

```

        if not visited[i]:
            visit(graph, i, visited, stack)

    start = 0
    end = len(stack) - 1

    while start < end:
        stack[start], stack[end] = stack[end], stack[start]
        start += 1
        end -= 1

    return stack
else:
    return None

```

```

def visit(graph, vertex, visited, stack):
    visited[vertex] = True

    for neighbor in graph.outbound[vertex]:
        if not visited[neighbor]:
            visit(graph, neighbor, visited, stack)

    stack.append(vertex)

```

```

def highest_cost_path(graph, start, end):
    if is_dag(graph):
        topological_vertices = topo_sort(graph)

        dist = {v: float('-inf') for v in graph.inbound.keys()}
        prev = {v: None for v in graph.inbound.keys()}
        dist[start] = 0

```

```

    for vertex in topological_vertices:
        if dist[vertex] != float('-inf'):
            for neighbour in graph.iterate_out(vertex):
                if dist[neighbour] < dist[vertex] + graph.get_cost(vertex,
neighbour):
                    dist[neighbour] = dist[vertex] + graph.get_cost(vertex,
neighbour)
                    prev[neighbour] = vertex

    if dist[end] == float('-inf'):
        return None

    path = [end]
    end2 = end
    while prev[end2] is not None:
        path.append(prev[end2])
        end2 = prev[end2]

    path.reverse()
    return [path, dist[end]]
else:
    print("The graph is not acyclic, we can not find the highest cost
path!")

```