

ONNX Implementation for Air Crash Probability Analysis with Flight Data EASA ATC public data.

This project focuses on the implementation of ONNX for predicting the likelihood of air crashes caused by unexpected flight path fluctuations. The dataset utilized originates from EASA Air Traffic control public data, encompassing information from various Air Traffic Control sources.

How to Run:

1. Create a virtual environment.
2. Activate the virtual environment.
3. Install all the requirements using the `requirements.txt` file:

```
pip install -r requirements.txt
```

4. Run `ATC.ipynb` to perform exploratory data analysis (EDA) and data exploration. This notebook includes steps for data pre-processing and initial analysis.
5. Execute `onnx_1.ipynb` to develop the predictive model. This notebook focuses on the first level of accident probability prediction using critical data such as latitude, longitude, and airspeeds.
6. Launch `ONNX_2.ipynb` for a comprehensive analysis of flight path fluctuations and identification of high-risk geographic locations. This notebook also explores the potential for issuing "Mayday" messages in high-risk zones during flight.

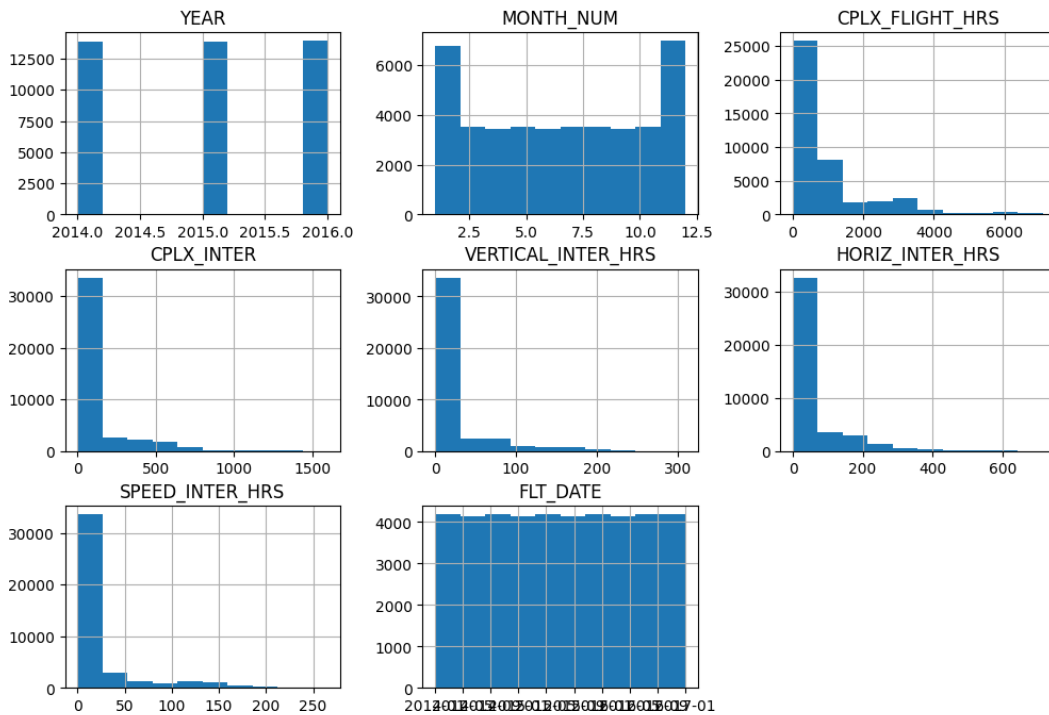
Future Scope:

The current system can be developed as streaming system with live streaming data. For which stream processing and batch processing of data can be done using Apache spark streaming and Kafka which can process live data in our model for predictions.

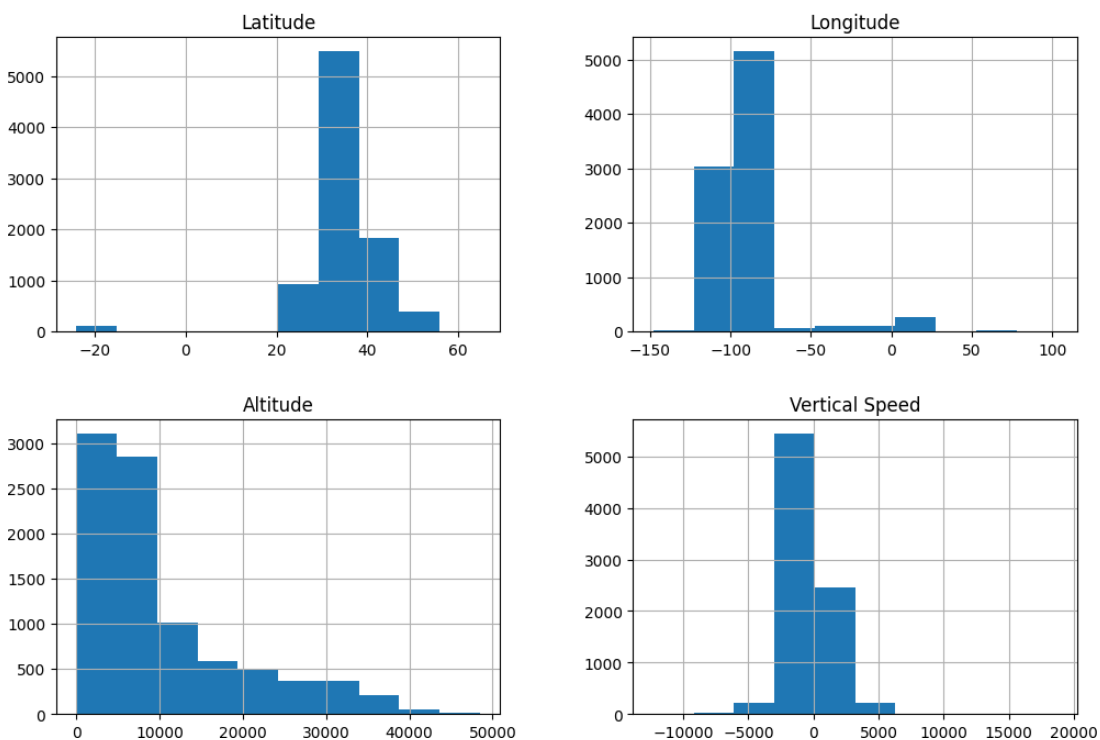
Runs and Plots from Project Analysis.

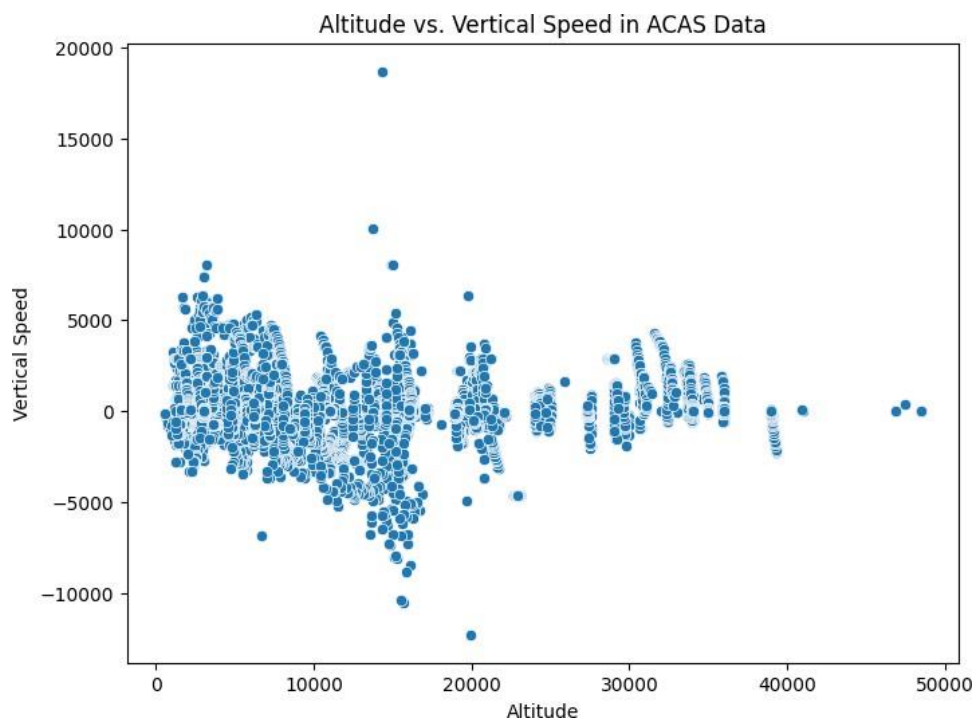
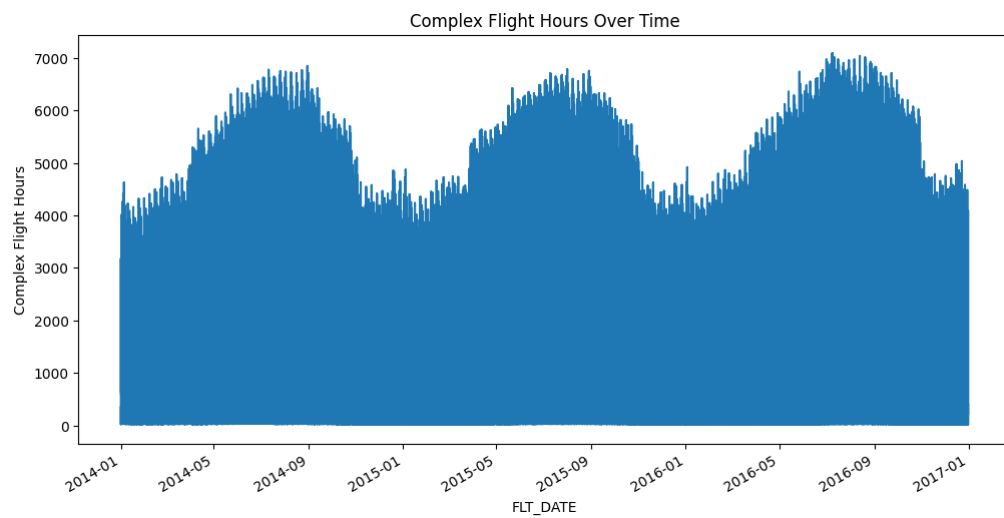
EDA Steps:

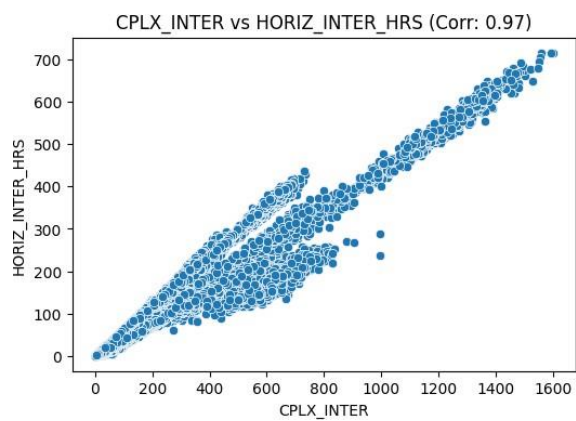
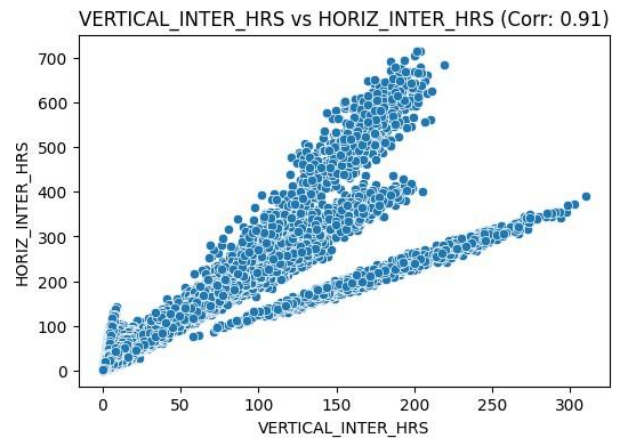
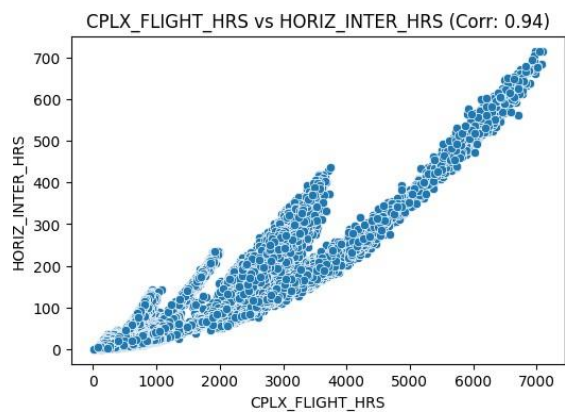
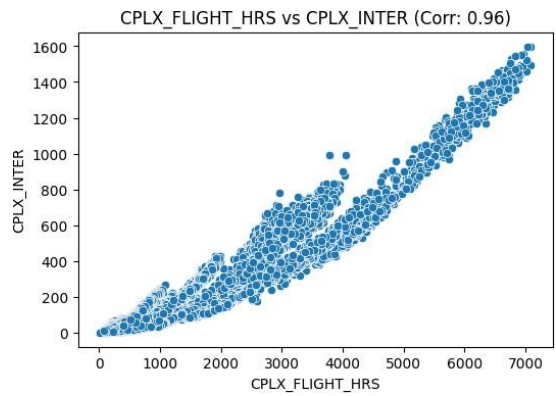
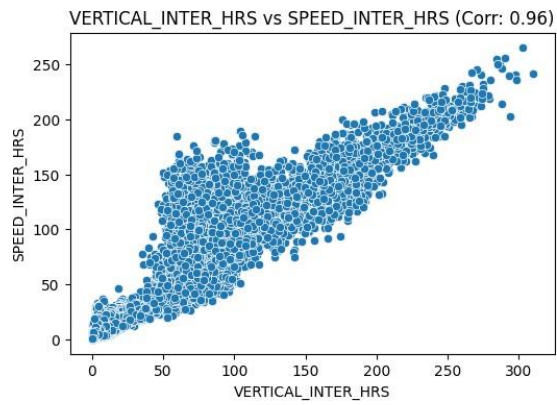
Distribution of TRF Complexity Features

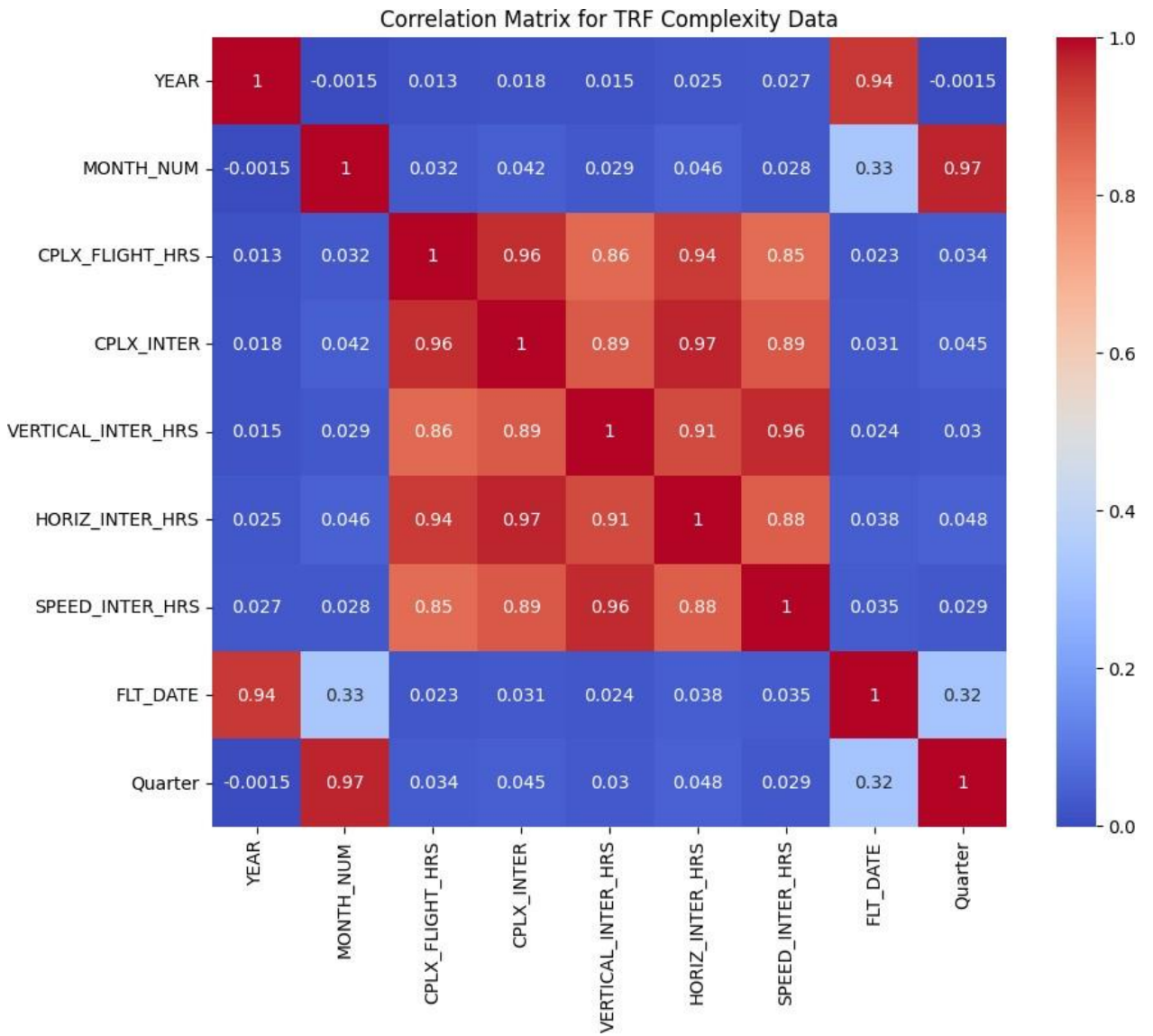


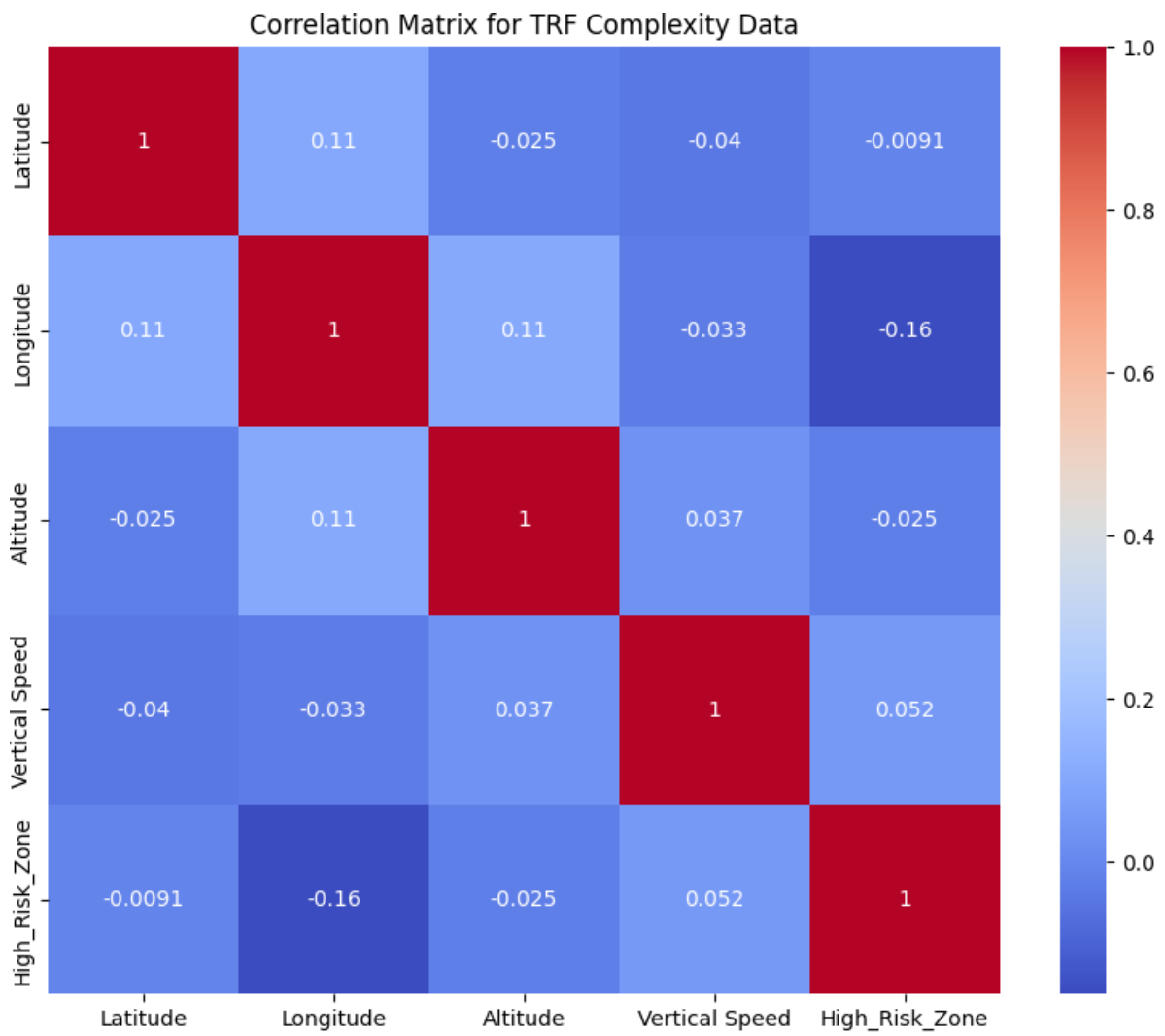
Distribution of ACAS Features









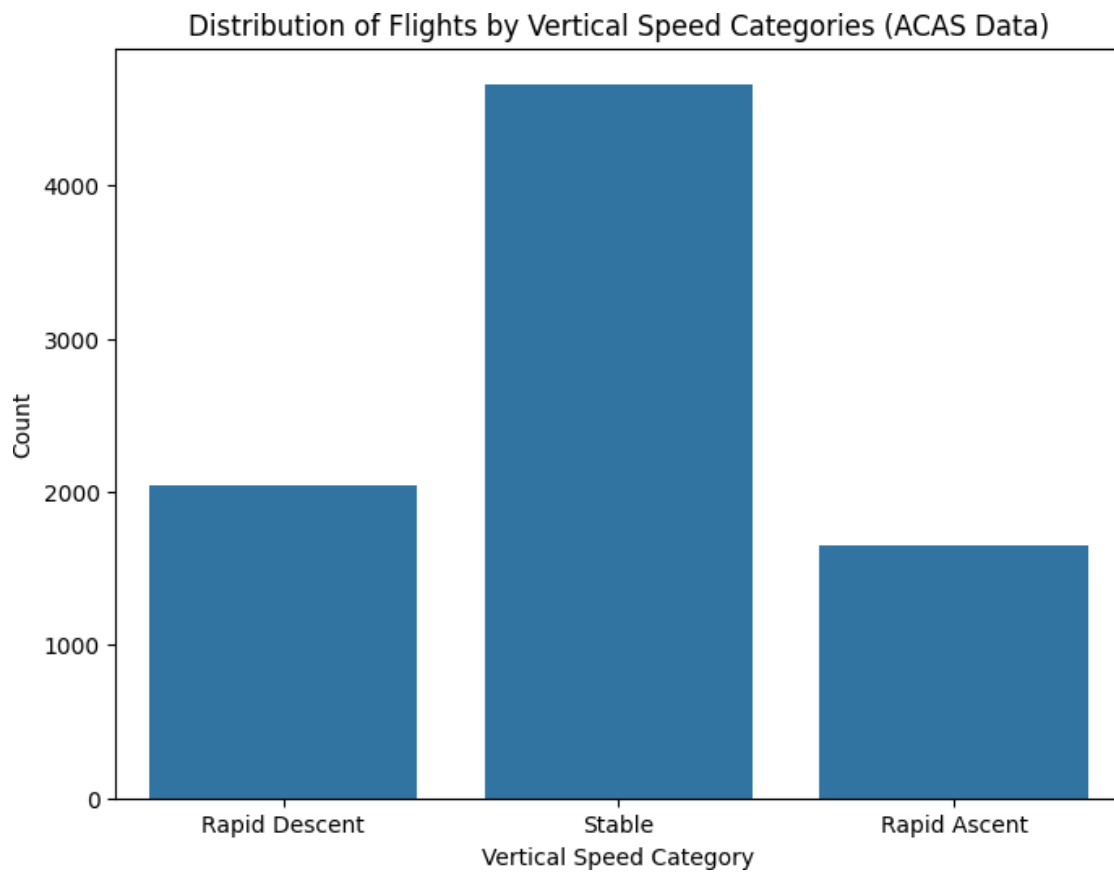
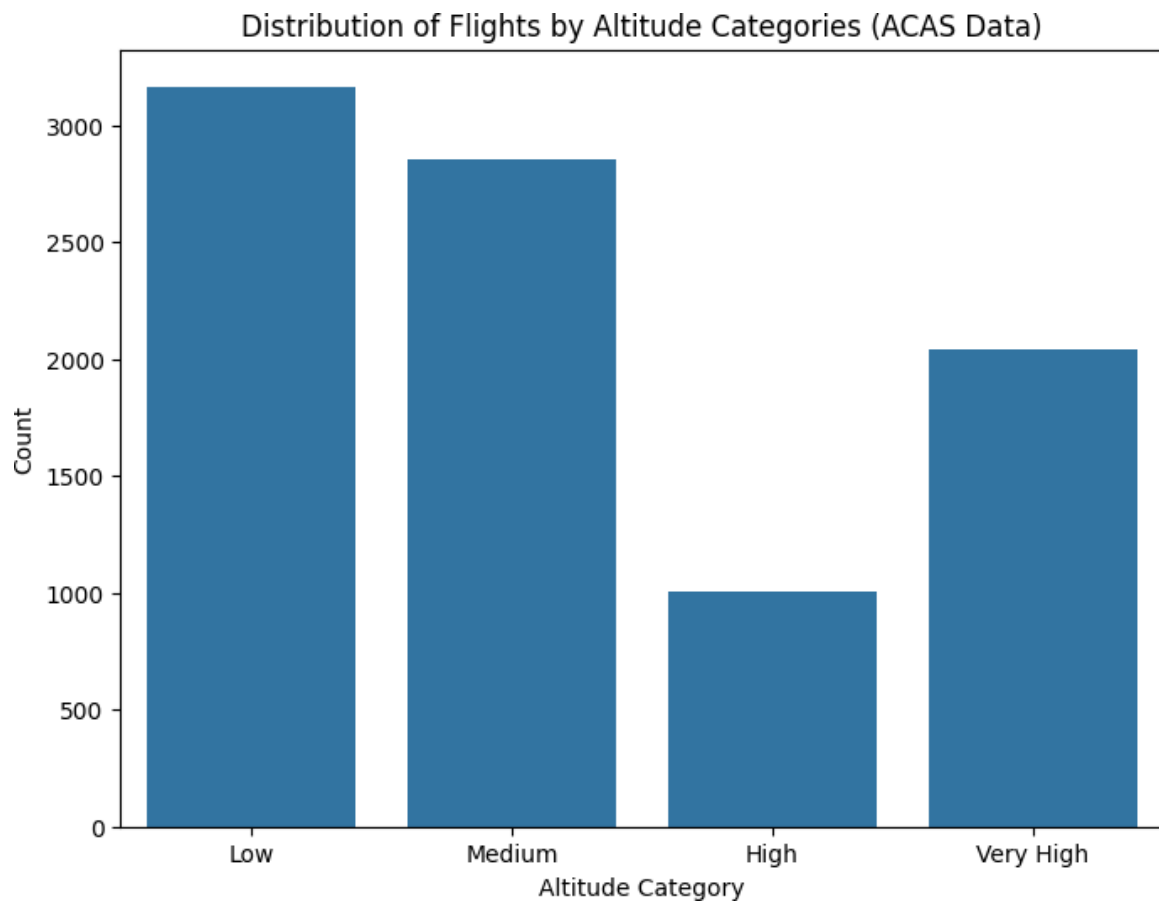


Proportion of Flights in High-Risk Zones (ACAS Data)

Inside High-Risk Zone



Outside High-Risk Zone



Visualizations' with ONNX implementation:

