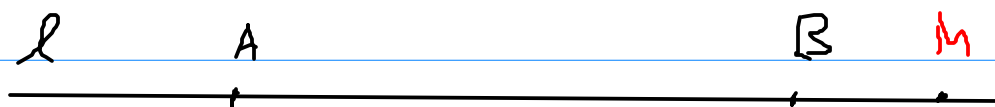


Seminar W2 - 9.7



l line in the Euclidean plane

$$A, B \in l$$

Say we fix a reference system.

Then $\forall M \in l \exists! \lambda \in \mathbb{R}$ s.t.:

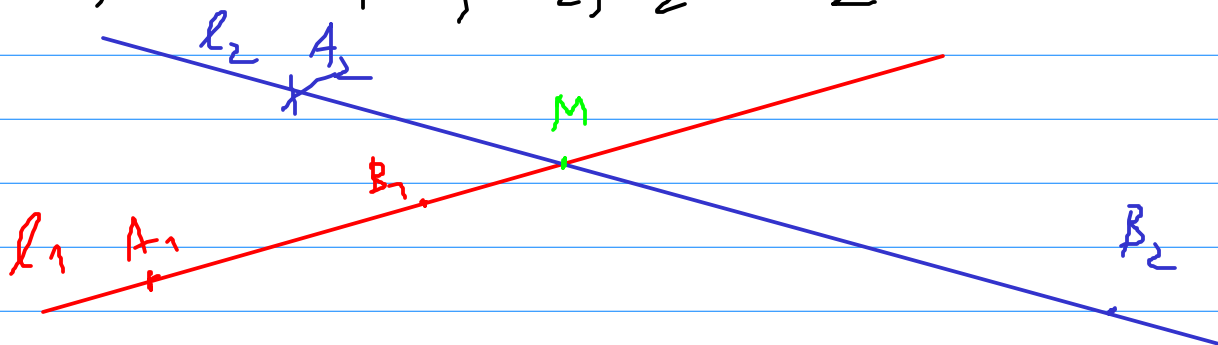
$$\vec{r}_M = \lambda \vec{r}_A + (1 - \lambda) \vec{r}_B$$

$$\exists! M \in [AB] \text{ and } \frac{AM}{MB} = \alpha \in \mathbb{R}$$

$$\Rightarrow \vec{r}_M = \frac{\alpha}{\alpha+1} \vec{r}_B + \frac{1}{\alpha+1} \vec{r}_A$$

Let l_1, l_2 be lines, $l_1 \cap l_2 = \{M\}$

Let $A_1, B_1 \in l_1$, $A_2, B_2 \in l_2$



Objective : Find \vec{r}_M

Template for proofs involving concurrence of lines

Step 1 : Write M as a point on both lines:

(1) $M \in \ell_1 \Rightarrow \exists \lambda \in \mathbb{R} : \vec{r}_M = \lambda \vec{r}_{A_1} + (1-\lambda) \vec{r}_{B_1}$

(2) $M \in \ell_2 \Rightarrow \exists \mu \in \mathbb{R} : \vec{r}_M = \mu \vec{r}_{A_2} + (1-\mu) \vec{r}_{B_2}$

$$\Rightarrow \lambda \vec{r}_{A_1} + (1-\lambda) \vec{r}_{B_1} = \mu \vec{r}_{A_2} + (1-\mu) \vec{r}_{B_2} \quad (*)$$

Step 2 : We choose two linearly independent vectors \vec{u} and \vec{w}

Step 3 : We write $(*)$ in the basis (\vec{u}, \vec{w})

(we write $\vec{r}_{A_1}, \vec{r}_{A_2}, \vec{r}_{B_1}, \vec{r}_{B_2}$ as linear combinations of \vec{u} and \vec{w})

Step 4: We have obtained:

$$\alpha(\lambda, \mu) \cdot \vec{u} + \beta(\lambda, \mu) \cdot \vec{w} = \vec{0}$$

$$\vec{u}, \vec{w} \text{ lin. indep.} \Rightarrow (S) \begin{cases} \alpha(\lambda, \mu) = 0 \\ \beta(\lambda, \mu) = 0 \end{cases}$$

Step 5: Solve the system (S) and obtain λ (or μ)

Step 6: Replace λ (or μ) in (1) (or (2))

Step 7: We have obtained a formula:

$$\vec{h}_n = k_1 \cdot \vec{u} + k_2 \cdot \vec{w}$$

2.1. $\triangle ABC$, G centroid, H orthocenter

I incenter, O circumcenter

↓
point where all the

perpendicular bisectors

meet

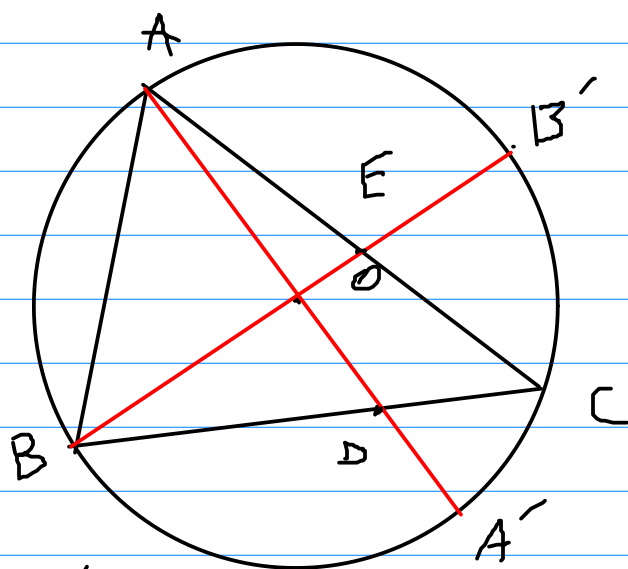
We fix a reference system.

$$(a) \quad \vec{r}_G = \frac{\vec{r}_A + \vec{r}_B + \vec{r}_C}{3}$$

$$(b) \quad \vec{r}_I = \frac{a \vec{r}_A + b \vec{r}_B + c \vec{r}_C}{a+b+c}, \quad \begin{aligned} a &= BC \\ b &= CA \\ c &= AB \end{aligned}$$

$$(c) \quad \vec{r}_H = \frac{\tan A \cdot \vec{r}_A + \tan B \cdot \vec{r}_B + \tan C \cdot \vec{r}_C}{\tan A + \tan B + \tan C}$$

$$(d) \quad \vec{r}_O = \frac{\sin 2A \cdot \vec{r}_A + \sin 2B \cdot \vec{r}_B + \sin 2C \cdot \vec{r}_C}{\sin 2A + \sin 2B + \sin 2C}$$



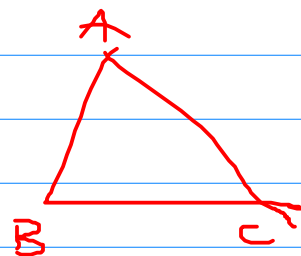
We draw the diameters AA' and BB'

$$AA' \cap BC = \{D\}, \quad BB' \cap CA = \{E\}$$

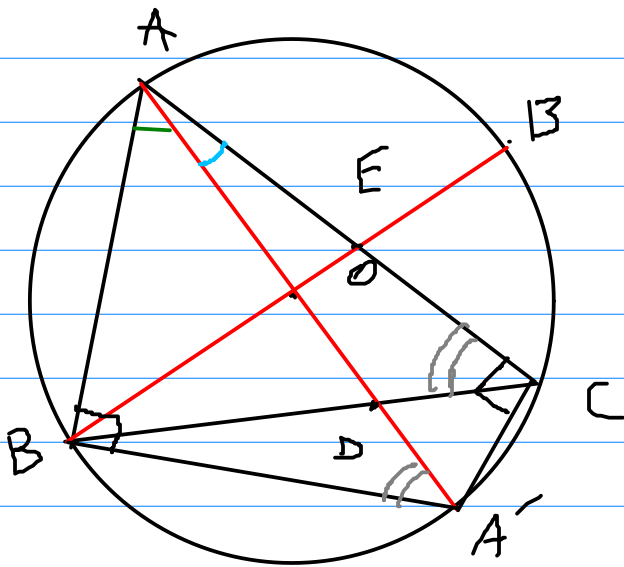
Prove that
$$\frac{BD}{DC} = \frac{\sin(2C)}{\sin(2B)}$$

The sine theorem: in $\triangle ABC$.

$$\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C} = 2R$$



R = radius of the circumscribed circle



$$\begin{aligned} \frac{BD}{DC} &= \frac{A_{ABD}}{A_{ADC}} = \\ &= \frac{AB \cdot AD \cdot \sin(\widehat{BAD})}{AC \cdot AD \cdot \sin(\widehat{CAD})} = \\ &= \frac{c}{b} \cdot \frac{\sin(\widehat{BAD})}{\sin(\widehat{CAD})} \end{aligned}$$

$$AA' \text{ diameter} \Rightarrow m(\widehat{ABA'}) = m(\widehat{ACA'}) = \frac{\pi}{2}$$

$$\widehat{ACB} \equiv \widehat{AA'B} \equiv \widehat{AB} \Rightarrow m(\widehat{A'AB}) = \frac{\pi}{2} - m(\widehat{AAB}) <$$

$$= \frac{\pi}{2} - \hat{C}$$

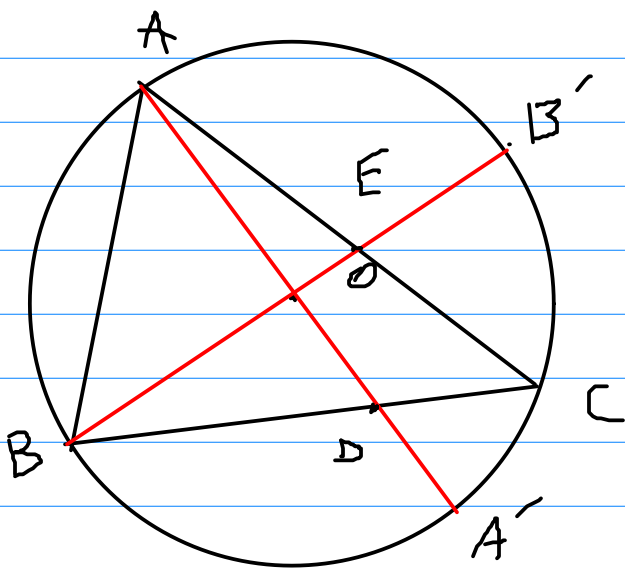
$$m(\widehat{A'AC}) = \frac{\pi}{2} - \hat{B} \Rightarrow \frac{\sin(\widehat{BAD})}{\sin(\widehat{CAD})} = \frac{\sin(\frac{\pi}{2} - C)}{\sin(\frac{\pi}{2} - B)} =$$

$$= \frac{\cos C}{\cos B}$$

$$\text{From the sine theorem } \frac{c}{b} = \frac{\sin C}{\sin B}$$

$$\Rightarrow \frac{BD}{DC} = \frac{\sin C}{\sin B} \cdot \frac{\cos C}{\cos B} = \frac{\sin 2C}{\sin 2B}$$

Now we can come back to 1.1 d



We need to show

$$\vec{r}_O = \frac{\sin 2A \cdot \vec{r}_A + \sin 2B \cdot \vec{r}_B + \sin 2C \cdot \vec{r}_C}{\sin 2A + \sin 2B + \sin 2C}$$

We will denote

$$\sin 2A =: \alpha$$

$$\sin 2B =: \beta$$

$$\sin 2C =: \gamma$$

$$\Rightarrow \frac{BD}{DC} = \frac{\gamma}{\beta}, \quad \frac{AE}{EC} = \frac{\gamma}{\alpha}$$

$$O \in AD \Rightarrow \exists \lambda \in \mathbb{R}: \vec{r}_O = \lambda \vec{r}_A + (1-\lambda) \vec{r}_D$$

$$O \in BE \Rightarrow \exists \mu \in \mathbb{R}: \vec{r}_O = \mu \vec{r}_B + (1-\mu) \vec{r}_E$$

$$\vec{r}_D = \frac{1}{\frac{\gamma}{\beta} + 1} \cdot \vec{r}_B + \frac{\frac{\gamma}{\beta}}{\frac{\gamma}{\beta} + 1} \vec{r}_C = \frac{\beta}{\beta + \gamma} \vec{r}_B + \frac{\gamma}{\beta + \gamma} \vec{r}_C$$

$$\vec{r}_F = \frac{1}{\frac{\alpha}{\delta} + 1} \vec{r}_A + \frac{\frac{\delta}{\alpha}}{\frac{\alpha}{\delta} + 1} \vec{r}_C = \frac{\alpha}{\alpha + \delta} \vec{r}_A + \frac{\delta}{\alpha + \delta} \vec{r}_C$$

Because $\lambda \vec{r}_A + (1-\lambda) \vec{r}_D = \mu \vec{r}_B + (1-\mu) \vec{r}_E$

we have:

$$\lambda \vec{r}_A + \frac{\beta(1-\lambda)}{\beta + \delta} \vec{r}_B + \frac{\delta(1-\lambda)}{\beta + \delta} \vec{r}_C =$$

$$= \mu \vec{r}_B + \frac{\alpha(1-\mu)}{\alpha + \delta} \vec{r}_A + \frac{\delta(1-\mu)}{\alpha + \delta} \vec{r}_C$$

$$\Rightarrow \left(\lambda - \frac{\alpha(1-\mu)}{\alpha + \delta} \right) \vec{r}_A + \left(\frac{\beta(1-\lambda)}{\beta + \delta} - \mu \right) \vec{r}_B + \left(\frac{\delta(1-\lambda)}{\beta + \delta} - \frac{\delta(1-\mu)}{\alpha + \delta} \right) \vec{r}_C = \vec{0}$$

$\triangle ABC$ is non-degenerate $\Rightarrow \vec{AB}$ and \vec{AC} are

linearly independent, $\vec{u} := \vec{AB}$, $\vec{w} := \vec{AC}$

$$\Rightarrow \vec{r}_B = \vec{r}_A + \vec{u}, \quad \vec{r}_C = \vec{r}_A + \vec{w}$$

We perform the substitutions:

$$\left(\lambda - \frac{\alpha(1-\mu)}{\alpha+\delta} \right) \vec{r}_A + \left(\frac{\beta(1-\lambda)}{\beta+\delta} - \mu \right) \cdot (\vec{r}_A + \vec{u}) + \left(\frac{\delta(1-\lambda)}{\beta+\delta} - \frac{\delta(1-\mu)}{\alpha+\delta} \right) \cdot (\vec{r}_A + \vec{u}) = \vec{0}$$

$$\Rightarrow \left(\lambda - \frac{\alpha(1-\mu)}{\alpha+\delta} + \frac{\beta(1-\lambda)}{\beta+\delta} - \mu + \frac{\delta(1-\lambda)}{\beta+\delta} - \frac{\delta(1-\mu)}{\alpha+\delta} \right) \vec{r}_A + \left(\frac{\beta(1-\lambda)}{\beta+\delta} - \mu \right) \cdot \vec{u} + \left(\frac{\delta(1-\lambda)}{\beta+\delta} - \frac{\delta(1-\mu)}{\alpha+\delta} \right) \cdot \vec{u} = \vec{0}$$

$$\Rightarrow \left(\frac{\beta(1-\lambda)}{\beta+\delta} - \mu \right) \cdot \vec{u} + \left(\frac{\delta(1-\lambda)}{\beta+\delta} - \frac{\delta(1-\mu)}{\alpha+\delta} \right) \cdot \vec{u} = \vec{0}$$

$$\Rightarrow \begin{cases} \frac{\beta(1-\lambda)}{\beta+\delta} = \mu \\ \frac{\delta(1-\lambda)}{\beta+\delta} - \frac{\gamma}{\alpha+\delta} \cdot (1-\mu) = 0 \end{cases}$$

$$\Rightarrow \frac{\delta(1-\lambda)}{\beta+\delta} - \frac{\gamma}{\alpha+\delta} \cdot \left(1 - \frac{\beta(1-\lambda)}{\beta+\delta} \right) = 0$$

$$\Rightarrow \frac{\delta}{\beta+\delta} - \frac{\lambda\delta}{\beta+\delta} - \frac{\gamma}{\alpha+\delta} +$$

$$+ \frac{\beta\delta}{(\alpha+\delta)(\beta+\delta)} - \frac{\beta\delta\lambda}{(\alpha+\delta)(\beta+\delta)} = 0$$

$$\Rightarrow \lambda = \frac{\frac{\delta}{\beta+\delta} - \frac{\gamma}{\alpha+\delta} + \frac{\beta\delta}{(\alpha+\delta)(\beta+\delta)}}{\frac{\gamma}{\beta+\delta} + \frac{\beta\delta}{(\alpha+\delta)(\beta+\delta)}}$$

$$\Rightarrow \lambda = \frac{\alpha + \gamma - \beta - \gamma + \beta}{(\alpha + \gamma) + \beta} = \frac{\alpha}{\alpha + \beta + \gamma}$$

$$\vec{r}_O = \lambda \vec{r}_A + \frac{\beta(1-\lambda)}{\beta + \gamma} \vec{r}_B + \frac{\gamma(1-\lambda)}{\beta + \gamma} \vec{r}_C$$

$$\Rightarrow \vec{r}_O = \frac{\alpha}{\alpha + \beta + \gamma} \vec{r}_A + \frac{\beta}{\alpha + \beta + \gamma} \vec{r}_B + \frac{\gamma}{\alpha + \beta + \gamma} \vec{r}_C$$

$$1 - \lambda = 1 - \frac{\alpha}{\alpha + \beta + \gamma} = \frac{\beta + \gamma}{\alpha + \beta + \gamma}$$

$$\frac{\beta}{\beta + \gamma} (1 - \lambda) = \frac{\beta}{\beta + \gamma} \cdot \frac{\beta + \gamma}{\alpha + \beta + \gamma} = \frac{\beta}{\alpha + \beta + \gamma}$$

2.1. $\widehat{BOB'}$ nonzero angle

$$A \in [OB], A' \in [OB']$$

$$\overrightarrow{OA} =: \vec{u} \quad \overrightarrow{OA'} =: \vec{u'}$$

$$\overrightarrow{OB} = m \cdot \vec{u} \quad \overrightarrow{OB'} = m \cdot \vec{u'}$$

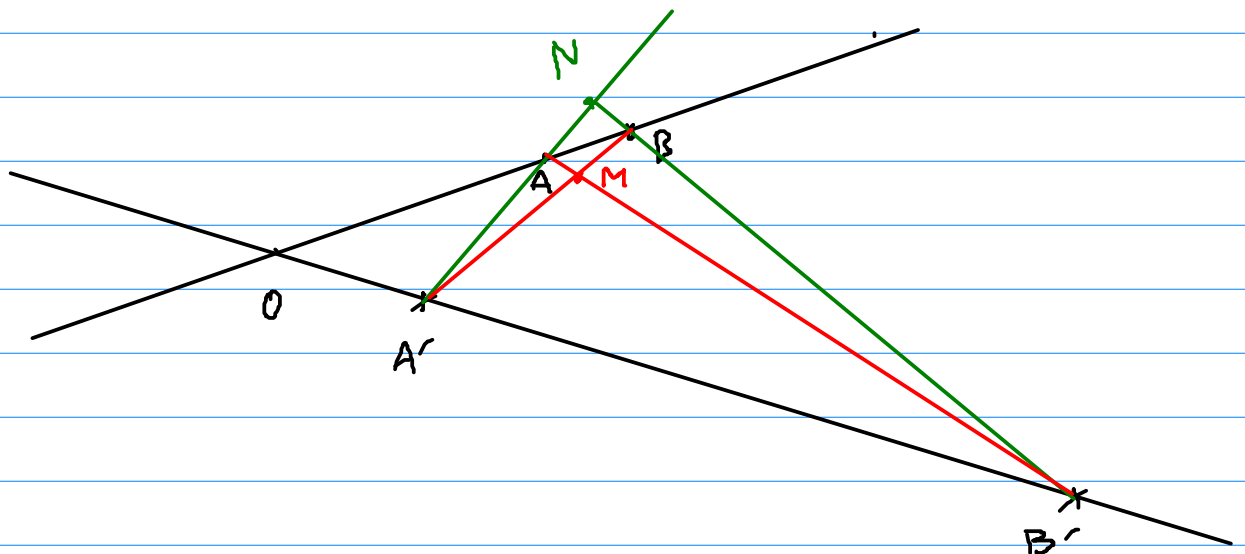
$$AA' \cap BB' = \{N\}$$

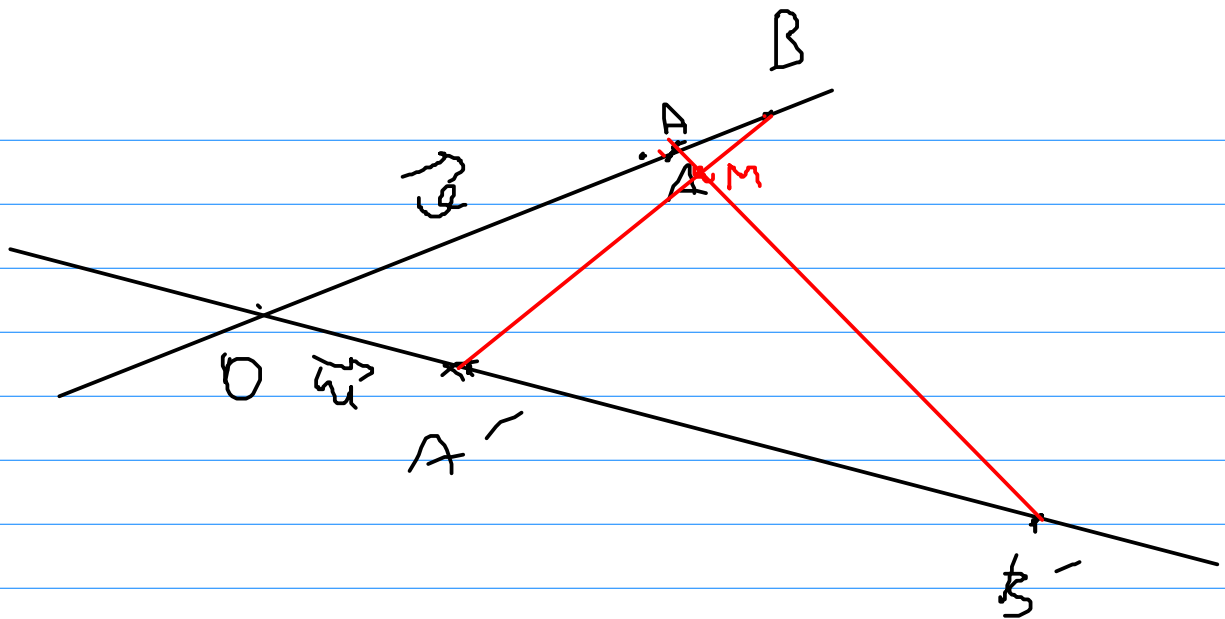
$$AB' \cap BA' = \{M\}$$

Show that

$$\overrightarrow{ON} = m \cdot \frac{1-n}{1-mn} \overrightarrow{OA} + n \cdot \frac{1-m}{1-mn} \overrightarrow{OA'}$$

$$\overrightarrow{OM} = m \cdot \frac{n-1}{n-m} \overrightarrow{OA} + n \cdot \frac{m-1}{m-n} \overrightarrow{OA'}$$





$$\begin{aligned}\vec{OM} &= \lambda \vec{OA} + (1-\lambda) \vec{OB'} \\ &= \mu \cdot \vec{OA'} + (1-\mu) \vec{OB}\end{aligned}$$

$$\begin{aligned}\Rightarrow \vec{OM} &= \lambda \vec{u} + (1-\lambda) \cdot n \cdot \vec{w} \\ &= \mu \cdot m \cdot \vec{u} + (1-\mu) \cdot \vec{w} \\ \Rightarrow (\lambda - \mu m) \cdot \vec{u} + ((1-\lambda)n - 1 + \mu) \cdot \vec{w} &= \vec{0}\end{aligned}$$

$\vec{BOB'}$ non zero $\Rightarrow \vec{u}, \vec{w}$ lin. indep.

$$\Rightarrow \begin{cases} \lambda - \mu m = 0 \\ (1-\lambda)n - 1 + \mu = 0 \end{cases}$$

$$\Rightarrow \lambda = \mu m$$

$$\Rightarrow (1 - \mu m)n - 1 + \mu = 0$$

$$\Rightarrow \mu(-mn + 1) + n - 1 = 0$$

$$\Rightarrow \mu = \frac{1-n}{1-mn} \Rightarrow 1-\mu = \frac{n-mn}{1-mn}$$

$$\begin{aligned} \vec{OM} &= \mu \cdot m \cdot \vec{u} + (1-\mu) \cdot \vec{w} = \\ &= \frac{m(1-n)}{1-mn} \cdot \vec{u} + \frac{n(1-m)}{1-mn} \cdot \vec{w} \end{aligned}$$

Same thing for \vec{ON}