Spring Force Lab 2: Series and Parallel Springs

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1 Introduction

Recall that the spring force is given by

$$\vec{s} = -k\Delta \vec{x} \tag{1}$$

In the above equation, k is a constant and $\Delta \vec{x}$ is the displacement of the spring. What if we are dealing with more than one spring? One example is the suspension of a truck, where the weight of the truck rests on four springs.

2 PhET Module

Please navigate to: https://phet.colorado.edu/en/simulations/hookes-law. There are three tabs: introduction, systems, and energy. Click on introduction and familiarize yourself with the controls. We can compress and stretch a spring by varying the applied force, and the spring constant k can be varied as well. Note that k must have units of Newtons per meter.

- 1. Click on the double spring tab at right, and convince yourself that a higher spring constant k leads to lower displacement for the same applied force.
- 2. Now click on the systems tab at the bottom. When two springs are both connected to the red clamp, the springs are said to be *in parallel*. When the left spring is connected to the right spring, and the right spring is connected to the clamp, the springs are said to be *in series*.
- 3. Check all the boxes in the gray control panel on the right hand side. This will display force and displacement vectors, as well as the value of the total displacement.

3 Measurements

We will now probe the difference between springs that are in series and in parallel.

- 1. Choose the *in parallel* version of the setup, and select two equal spring constants.
- 2. Using Excel or Google Sheets, collect two columns of data: displacement versus force applied.
- 3. Calculate the slope, which should be the overall effective spring constant, k. How does it compare to k_1 and k_2 , the individual spring constants of the springs?
- 4. Repeat steps 1-3 for the *in series* version of the setup. How does the effective spring constant compare to k_1 and k_2 , the individual spring constants of the springs?

4 Conclusion

Using Equation 1, we can explain the *in parallel* results:

$$\vec{F}_{\text{net}} = -k_1 \Delta \vec{x} - k_2 \Delta \vec{x} = -(k_1 + k_2) \Delta \vec{x} \tag{2}$$

$$\vec{F}_{\text{net}} = -(k_1 + k_2)\Delta \vec{x} \tag{3}$$

$$\vec{F}_{\text{net}} = -k_{\text{eff}} \Delta \vec{x} \tag{4}$$

$$k_{\text{eff}} = k_1 + k_2 \tag{5}$$

Bonus: How do you explain the *in series* behavior of the effective spring constant?