

① Unit 4.

$$U(x) = k(x^4 - x^2)$$

② $F=0$ $F(x) = \int k(x^4 - x^2) dx$

$x=??$ $F(x) = k\left(\frac{x^5}{5} - \frac{x^3}{3}\right) + C$

$$0 = k\left(\frac{x^5}{5} - \frac{x^3}{3}\right) + C$$

Unit 4

① $U(x) = k(x^4 - x^2)$

$$F(x) = k(4x^3 - 2x) = 0$$

② $F=0$ $F(x) = -(U(x))'$

$$4x^3 - 2x = 0$$

$x=??$ $F(x) = -\frac{dU(x)}{dx}$

$$2x(2x^2 - 1) = 0$$

$$x=0 \text{ \& } x = \pm \frac{1}{\sqrt{2}}$$

∴ force is zero when $x=0$, $x = \frac{1}{\sqrt{2}}$ & $x = -\frac{1}{\sqrt{2}}$.

③ so critical pts are $0, \pm \frac{1}{\sqrt{2}}$. checking on $U(x)$.

$$U(0) = k(0^4 - 0^2) = 0, \quad U\left(\frac{1}{\sqrt{2}}\right) = k\left(\left(\frac{1}{\sqrt{2}}\right)^4 - \left(\frac{1}{\sqrt{2}}\right)^2\right) = k\left(\frac{1}{4} - \frac{1}{2}\right) = -\frac{1}{4}k$$

$$U\left(-\frac{1}{\sqrt{2}}\right) = k\left(\left(\frac{1}{\sqrt{2}}\right)^4 - \left(\frac{1}{\sqrt{2}}\right)^2\right) = -\frac{1}{4}k$$

∴ so the maximum displacement it could achieve is ~~1/2~~ when $x = \frac{1}{\sqrt{2}}$ that is from the origin is $\frac{1}{\sqrt{2}}$ since the system has been perturbed to the right

① Unit 4: (part 2)

② $m = 1 \text{ kg}$
 $\mu = 0.5$

① $F = 5\hat{i} \text{ N}$

$$\Delta x = (1-0)\hat{i} + (0-0)\hat{j} = 1\hat{i} \text{ m}$$

$$W_a = F \cdot \Delta x = 5\hat{i} \cdot (1\hat{i}) = 5 \text{ J}$$

② $F = 5\hat{j} \text{ N}$

$$\Delta x = (1-1)\hat{i} + (1-0)\hat{j} = 1\hat{j} \text{ m}$$

$$W_b = F \cdot \Delta x = (5\hat{j}) \cdot (1\hat{j}) = 5 \text{ J}$$

③ $F = -5\hat{i} \text{ N}$

$$\Delta x = (0-1)\hat{i} + (1-1)\hat{j} = -1\hat{i} \text{ m}$$

$$W_c = F \cdot \Delta x = (-5\hat{i}) \cdot (-1\hat{i}) = 5 \text{ J}$$

④ $F = -5\hat{j} \text{ N}$

$$\Delta x = (0-0)\hat{i} + (0-1)\hat{j} = -1\hat{j} \text{ m}$$

$$W_d = F \cdot \Delta x = (-5\hat{j}) \cdot (-1\hat{j}) = 5 \text{ J}$$

⑤ $W_{\text{total}} = W_a + W_b + W_c + W_d$

$$W_{\text{total}} = 5 + 5 + 5 + 5 = \underline{20 \text{ J}}$$

⑥ If force of friction was conservative,
because the path is closed.

$$\underline{W_f = 0 \text{ J}}$$

② Unit 5: Linear Momentum.

① $m = 20 \times 10^{-25} \text{ kg}$

$$P_i = P_f$$

$$u_1 = 350 \text{ m/s}$$

$$m_1 u_1 + m_2 u_2 = MV$$

$$u_2 = -350 \text{ m/s}$$

$$u = \frac{m_1 u_1 + m_2 u_2}{M} = \frac{m(u_1 + u_2)}{M}$$

$$u = ??$$

$$= \frac{20 \times 10^{-25} (0)}{40 \times 10^{-25}} = \underline{0 \text{ m/s}}$$

∴ Answer is ①! 0 m s^{-1}

$$\textcircled{2} m_1 = m_2$$

$$\theta = 45^\circ$$

$$v_f = ??$$

$$u_1 = u_2 = v$$

$$|P_{\text{total}}| = \sqrt{|P_1|^2 + |P_2|^2 + 2|P_1||P_2|\cos\theta}$$

$$|P_{\text{total}}| = \sqrt{(mv)^2 + (mv)^2 + 2(mv)(mv)\frac{\sqrt{2}}{2}}$$

$$= \sqrt{2(mv)^2 + \sqrt{2}(mv)^2}$$

$$= \sqrt{(mv)^2(2 + \sqrt{2})}$$

$$|P_{\text{total}}| = mv \sqrt{2 + \sqrt{2}}$$

$$P = mv,$$

$$v_f = \frac{|P_{\text{total}}|}{m_{\text{total}}}, \quad m_{\text{total}} = m + m = 2m$$

$$v_f = \frac{mv \sqrt{2 + \sqrt{2}}}{2m}$$

$$v_f = \frac{v \sqrt{2 + \sqrt{2}}}{2}$$

∴ final velocity →

② Unit 5! (part 2)

③ $F = 4000\text{ N}$ ① $\Delta p = F \Delta t$

$t = 0.2\text{ s}$ $= 4000\text{ N} \times 0.2\text{ s}$

$\Delta p = ??$ $= 800\text{ N s}$

④ $u = 2.8\text{ m/s}$ $\Delta p = m(v_f - v_i)$

$m = 200\text{ kg}$ $v_f = \frac{\Delta p}{m} + v_i$

$v = ??$ $= \frac{800}{200} + 2.8 = \underline{\underline{-1.2\text{ m/s}}}$

\therefore The final velocity is 1.2 m/s in the opposite direction.

④ The Answer is ③: Elastic

⑤ $m_1 = 30,000\text{ kg}$ ① $m_1 v_1 + m_2 v_2 = M v_f$

$u_1 = 0.85\text{ m/s}$ $30,000(0.85) = 140,000 v_f$

$m_2 = 110,000\text{ kg}$ $v_f = \frac{140,000}{140,000} = 0.182\text{ m/s}$

$v_f = ??$

\therefore The final velocity is 0.182 m/s .

⑥ $KE_i = \frac{1}{2} m_1 v_1^2 = \frac{1}{2} 30,000 (0.85)^2 = 10,837.5\text{ J}$

$KE_f = \frac{1}{2} m_2 v_f^2 = \frac{1}{2} (140,000) (0.182)^2 = 2,316.76\text{ J}$

$\Delta KE = KE_i - KE_f$

$= 10,837.5 - 2,316.76\text{ J}$

$= \underline{\underline{8,520.74\text{ J}}}$

\therefore the kinetic energy lost is $8,520.74\text{ J}$.

② Unit 5: (part 3).

⑥ $m_1 = m$ before $x_1(t) = x_{1,0} - vt$, where $x_{1,0}$ is m_1 initial position
 $m_2 = 2m$ $x_2(t) = x_{2,0} + vt$, where $x_{2,0}$ is m_2 initial position
 $v_{\text{each}} = v$
 $x_{\text{COM}} = \frac{m x_1(t) + 2m x_2(t)}{m + 2m}$

$\xrightarrow{2m}$ \xleftarrow{m} $x_{\text{COM}} = \frac{m(x_{1,0} - vt) + 2m(x_{2,0} + vt)}{3m}$

$$x_{\text{COM}} = \frac{x_{1,0} + 2x_{2,0}}{3} + \frac{v}{3}t$$

~~Although~~ After $m + 2m = 3m$ (sticking)

$$p_{\text{bef}} = p_{\text{aft}}$$

$$p_{\text{bef}} = m(-v) + 2m(v) = mv$$

$$p_{\text{aft}} = 3m v_{\text{COM}}$$

$$v_{\text{COM}} = \frac{v}{3}$$

∴ Although the collision is inelastic, momentum is conserved and the COM move with a velocity of $\frac{v}{3}$ and its position is found by $x_{\text{COM}}(t) = \frac{x_{1,0} + 2x_{2,0}}{3} + \frac{v}{3}t$

③ Unit 6: fixed-axis rotation & angular momentum.

①. $t = 1.33 \text{ s/rot}$ $\frac{1 \text{ rot}}{1.33 \text{ s}} \times \frac{60 \text{ s}}{1 \text{ min}} = 60/1.33 \text{ rpm} = 45.1 \text{ rpm}$
 $\text{rpm} = ??$ $\approx 45 \text{ rpm}$

$\omega = ??$ $3 \frac{45 \text{ rot}}{1 \text{ min}} \cdot \frac{2\pi \text{ rad}}{1 \text{ rot}} \cdot \frac{1 \text{ min}}{60 \text{ s}} = 1.5 \text{ rad/s}$
 $= 1.5 \times 3.14 \text{ rad/s}$
 $= 4.71 \text{ rad/s}$

\therefore Answer is (B)

② $a_c = ??$

\therefore Answer is (D) 2.2 m/s^2

③ $a_c = \omega^2 r$

When $\omega \rightarrow 10\omega$

$a_c = (10\omega)^2 r$

$a_c = 100\omega^2 r$

\therefore Answer is (D): $\omega \rightarrow 10\omega$

④ $\omega = 200 \text{ rpm}$ $f_c = ma_c$

$r = 12 \text{ cm}$

$f_c = m\omega^2 r$

$m = 10 \text{ g}$

$= \frac{10}{1000} \times \left(\frac{200\pi}{30}\right)^2 \times \frac{12}{100} = 0.53 \text{ N}$

$f_c = ??$

\therefore Answer is (B): 0.53 N

⑤ $m = 0.5 \text{ kg}$

$I = \sum m_i r_i^2 = D I = I_{\text{cm}} + m r^2 = 2 m r^2$

⑥ $\omega = 4 \text{ rev/s}$

$K.E._T = K.E._R + K.E._T$

$v_c = 8 \text{ m/s}$

$= \frac{1}{2} I \omega^2 + \frac{1}{2} m v_c^2$

$K.E._T = ??$

$= \frac{1}{2} (2 m r^2) \omega^2 + \frac{1}{2} m v_c^2$

$= 0.5 r^2 (4(2\pi))^2 + \frac{1}{2} (1) (64)$

$= 32 \pi^2 r^2 + 32$

$= 32 (\pi^2 r^2 + 1)$ but $v = \omega r$

$= 32 (\pi^2 (\frac{1}{\pi}) + 1)$

$= 64 \text{ J}$

$r = \frac{v}{\omega} = \frac{8}{8\pi} = \frac{1}{\pi}$

3 Unit 6 (part 2)

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(b) $L = ??$ $L = I\omega$

$$= 2mr^2\omega$$

$$= 2(0.5)\left(\frac{1}{\pi}\right)^2 8\pi$$

$$= 8/\pi = \underline{2.55 \text{ kg m}^2/\text{s}}$$

(c) $h = ??$

At the highest point $K.E = P.E$

$$62 = mgh$$

$$h = \frac{62}{(1)(9.8)} = \underline{6.53 \text{ m}}$$

(6) $\vec{r} = 5\hat{i} + 5\hat{j} \text{ cm}$ (a) $\vec{\tau} = \vec{r} \times \vec{F}$

$$\vec{F} = -10\hat{i} + 10\hat{j} \text{ N} \quad = \begin{vmatrix} 5/100 & 5/100 \\ -10 & 10 \end{vmatrix}$$

$$\tau = ??$$

$$= 5/10 - 5(-1/10)$$

$$= 0.5 + 0.5 = \underline{1 \text{ N.m} \hat{k}}$$

(b) $\tau = 2\vec{r} \times \vec{F} = 2(\vec{r} \times \vec{F}) = 2(1) = \underline{2 \text{ N.m} \hat{k}}$

(c) $\tau = 30 \text{ Ncm}$

$$\tau = \vec{r} \times \vec{F} = rF \sin \theta \text{ (assuming they're } \perp)$$

$$\tau = rF$$

$$r = \frac{5}{100}\hat{i} + \frac{5}{100}\hat{j} \text{ m}$$

$$|\vec{r}| = \sqrt{\left(\frac{5}{100}\right)^2 + \left(\frac{5}{100}\right)^2}$$

$$F = \frac{\tau}{r} = \frac{30/100}{0.0707} = \frac{3}{0.707} = \underline{4.24 \text{ N}}$$

$$= \sqrt{\frac{1}{400} + \frac{1}{400}}$$

$$= \sqrt{\frac{1800}{216 \times 10^4}}$$

$$= \sqrt{\frac{1}{200}}$$

$$= \underline{0.0707}$$

3: Unit 6 (part 3).

⑦ $I = \frac{1}{2} MR^2$

$\omega(t) = 10t + 60 \text{ rpm}$

$T = ??$

$T = I \alpha$

$T = I \frac{d\omega}{dt}$

$= \frac{1}{2} MR^2 \left(\frac{10\pi}{30} \right)$

$T = \frac{\pi}{6} MR^2 \text{ N.m}$

$\alpha = \frac{d\omega(t)}{dt}$

$\frac{d\omega}{dt} = 10 \text{ rpm}$

⑧ $m = 100 \text{ kg}$ (a) $L = I \omega$

$r = 1.5 \text{ m}$

$\omega = 30 \text{ rpm}$

$L = ??$

$= \frac{1}{2} mr^2 \omega$

$= \frac{1}{2} (100) (1.5)^2 \frac{30\pi}{30}$

$= 50 (2.25) \pi$

$= \underline{353.5 \text{ kg m}^2/\text{s}}$

⑨ $m = 40 \text{ kg}$

$\omega_N = ??$

$L_i = L_f$

$353.5 = I_N \omega_N$

$\omega_N = \frac{353.5}{I_N}$

$\omega_N = \frac{353.5}{202.5} \times \frac{30}{\pi}$

$= \underline{16.67 \text{ rpm}}$

$I_N = \frac{1}{2} mr^2 + md^2$

$= \frac{1}{2} mr^2 + mr^2$

$= \frac{1}{2} (100) (1.5)^2 + 40 (1.5)^2$

$= 50 (1.5)^2 + 40 (1.5)^2$

$= 1.5^2 (90)$

$= 2.25 (90)$

$= \underline{202.5 \text{ kg m}^2/\text{s}}$

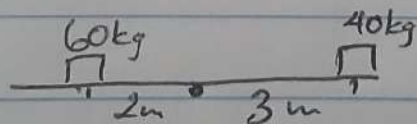
④ Unit 7: Statics.

① $m_1 = 40 \text{ kg}$

$r_1 = 3 \text{ m}$

$m_2 = 60 \text{ kg}$

$r = 2 \text{ m}$



$\tau_1 = r_1 \times F_1$

$= 3 \times 40$

$\tau_1 = 120 \text{ Nm}$

$\tau_2 = r_2 \times F_2$

$= 2 \times 60$

$= 120 \text{ Nm}$

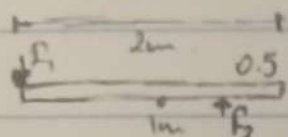
$\tau_{\text{net}} = \Delta \tau = \tau_2 - \tau_1$

$= 120 - 120 = 0$

\therefore there is no net torque

① the system will remain motionless.

② $l = 2m$



$x = 0.5m$

Criteria 1.

$m = 20kg$

$F_{net} = 0$

$F_1 + F_2 = W$

$F_1 + F_2 = 20(9.8)$

$F_1 + F_2 = 196N \text{ --- (1)}$

$F_2 = 196 - 65.3 = 132.6$

$F_1 = 65.3N$ ~~upward~~ downward

$F_2 = 132.6$ upward.

Criteria 2.

$T_{net} = 0$ choosing F_2 as the pivot.

$T_1 = F_1 \cdot 1.5$

$T_W = W \cdot 0.5 = 20(9.8)(0.5)$

$T_W = 98Nm$

$T_1 + T_W = 0 \quad T_1 = -T_W$

$F_1(1.5) = -(-98)$

$F_1 = 98/1.5 = 65.3$