

Ray Karr DSP Problem set #3

2. $f(t) = a_1 \cos(2\pi f_1 t) + a_2 \cos(2\pi f_2 t)$

$$\int_{-\infty}^{\infty} (a_1 \cos(2\pi f_1 t_1) + a_2 \cos(2\pi f_2 t)) \delta(t - t_1) dt$$

$$f(t_1) = a_1 \cos(2\pi f_1 \circ t_1) + a_2 \cos(2\pi f_2 \circ t_1)$$

$$\begin{aligned} f(t_1) &= a_1 \cdot 1 + a_2 \cdot 1 \\ &= a_1 + a_2 \end{aligned}$$

$$\int_{-\infty}^{\infty} (a_1 \cos(2\pi f_1 t) + a_2 \cos(2\pi f_2 t)) \delta(t - t_2) dt$$

$$f(t_2) = a_1 \cos(2\pi f_1 t_2) + a_2 \cos(2\pi f_2 t_2)$$

$$f(t_2) = a_1 \cos(\pi) + a_2 \cos(2\pi)$$

$$\begin{aligned} f(t_2) &= a_1 \cdot (-1) + a_2 \cdot 1 \\ &= -a_1 + a_2 \end{aligned}$$

3. $F(f) = \int_{-\infty}^{\infty} a \delta(t - t_0) e^{-j2\pi ft} dt$

$$F(f) = a e^{-j2\pi f t_0}$$

$$|F(f)| = a$$

$$b. \phi(f) = -2\pi f t_0$$

c. $T_g = -\frac{d\phi}{dw}$

$$\frac{d\phi}{dw} = -\frac{t_0}{\pi}$$

$$= \frac{t_0}{\pi} \cdot \pi$$

$$= T_g = t_0$$

3. Fourier Transforms and Basic Filters

$$S(f) = \int_{-\infty}^{\infty} s(t) e^{-j2\pi ft} dt$$

$$= a \delta(t - t_0) e^{-j2\pi ft_0}$$

$$S(f) = a e^{-j2\pi ft_0}$$

$$b. Y(f) = \frac{S(f)}{1 + j\omega T}$$

$$= \frac{ae^{-j2\pi ft_0}}{1 + j(2\pi f)T}$$

$$|Y(f)| = \frac{|a|}{|1 + j(2\pi f)T|}$$

$$|Y(f)| = \frac{|a|}{\sqrt{1 + (2\pi f T)^2}}$$

$$c. H(f) = \frac{j\omega T}{1 + j\omega T}$$

$$S(f) \cdot H(f) = \frac{ae^{-j2\pi ft_0}}{1 + j(2\pi f)T} \cdot j(2\pi f)T$$

$$\omega = 2\pi f$$

$$|Y(f)| = \frac{|a| \cdot (2\pi f T)}{\sqrt{1 + (2\pi f T)^2}}$$

$$= \frac{|a|(2\pi f T)}{\sqrt{1 + (2\pi f T)^2}}$$

Roy Nach DSP Problem set #3

$$2. H(f) = \frac{1}{1 + j2\pi f\gamma}$$

$$T_g(f) = -\frac{d}{df} \left[-\tan^{-1}(2\pi f\gamma) \right]$$

$$= \frac{2\pi\gamma}{1 + (2\pi f\gamma)^2}$$

$$\text{low pass} = \frac{2\pi\gamma}{1 + (2\pi f\gamma)^2}$$

$$\frac{j\omega\gamma}{1 + j\omega\gamma} = \frac{j2\pi f\gamma}{1 + j2\pi f\gamma}$$

$$\frac{\gamma}{2} - \tan^{-1}(2\pi f\gamma)$$

$$= -\frac{d}{df} \left[\frac{\gamma}{2} - \tan^{-1}(2\pi f\gamma) \right]$$

$$\text{high pass filter} = \frac{2\pi\gamma}{1 + (2\pi f\gamma)^2}$$

$$3. (a) f(t) = \int_{-\infty}^{\infty} \frac{q}{2} (\delta(f-f_0) + \delta(f+f_0)) e^{j2\pi ft} df$$

$$\frac{q}{2} \int_{-\infty}^{\infty} \delta(f+f_0) e^{j2\pi ft} df = \frac{q}{2} e^{-j2\pi f_0 t}$$

$$\frac{q}{2} (e^{j2\pi f_0 t} + e^{-j2\pi f_0 t})$$

$$f(t) = a \cos(2\pi f_0 t)$$

$$= a \cos(2\pi f_0 t)$$

$$b. S(f) = \frac{q}{2j} (\delta(f-f_0) - \delta(f+f_0))$$

$$= \frac{q}{2j} \int_{-\infty}^{\infty} \delta(f-f_0) e^{j2\pi ft} dt - \frac{q}{2j} \int_{-\infty}^{\infty} \delta(f+f_0) e^{-j2\pi ft} dt$$

$$f(t) = \frac{q}{2j} (e^{j2\pi f_0 t} - e^{-j2\pi f_0 t})$$

$$= e^{j\alpha} - e^{-j\alpha} \neq 2j \sin(\alpha)$$

$$f(t) = a \sin(2\pi f_0 t)$$

Ray Rauh DSP Problem set #3

$$1. A\{x[n]\} = 2x[n] - 1$$

$$\begin{aligned}A\{x_1[n]\}x_2[n] &= 2(x_1[n] + x_2[n]) - 1 \\&= 2x_1[n] + 2x_2[n] - 1 \\&= 2x_1[n] + 2x_2[n] - 2\end{aligned}$$

System A is not linear due to it not following the additivity property. $2x_1[n] + 2x_2[n] - 1 \neq 2x_1[n] + 2x_2[n] - 2$

System B

$$B\{x[n]\} = 0.5x[n]$$

$$\begin{aligned}B\{x_1[n]\} + B\{x_2[n]\} &= 0.5x_1[n] + 0.5x_2[n]\end{aligned}$$

System B is linear.

$$B. A'\{x[n]\} = 2x[n]$$

$$\begin{aligned}A'\{x_1[n]\} + A'\{x_2[n]\} &= 2x_1[n] + 2x_2[n]\end{aligned}$$

$$B\{x[n]\} = 0.5x[n]$$

$$\begin{aligned}A'\{B\{x[n]\}\} &= A'\{0.5x[n]\} \\&= x[n]\end{aligned}$$

$$B\{A'\{x[n]\}\} = B\{2x[n]\} = 0.5(2x[n]) = x[n]$$

System A is not linear and System B is linear.