

1.54)

$$\vec{v} = r^2 \cos \theta \hat{r} + r^2 \cos \phi \hat{\theta} - r^2 \cos \theta \sin \phi \hat{\phi}$$

$$\oint \vec{F} \cdot d\vec{s} = \iiint \text{div}(\vec{F}) dV$$

$$\nabla \cdot \vec{v} = \frac{\partial}{\partial r}(r^2 \cos \theta) + \frac{\partial}{\partial \theta}(r^2 \cos \phi) - \frac{\partial}{\partial \phi}(r^2 \cos \theta \sin \phi)$$

$$= 2r \cos \theta + r^2 \cos \phi - r^2 \cos \theta \cos \phi$$

$$= r(2 \cos \theta + r \cos \phi - r \cos \theta \cos \phi)$$

$$\hat{r} = \frac{1}{r}$$

$$\hat{\theta} = \frac{1}{r \sin \theta}$$

$$\hat{\phi} = \frac{1}{r \sin \theta}$$

$$v = r^2 \cos \theta \hat{r} + r^2 \cos \phi \hat{\theta} - r^2 \cos \theta \sin \phi \hat{\phi}$$

1.54

$$\nabla \cdot \vec{v} = \frac{1}{r^2} \frac{\partial}{\partial r}(V_1) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}(V_2) - \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi}(V_3)$$

$$= \frac{1}{r^2} (4r^3 \cos \theta) + \frac{1}{r \sin \theta} (r^2 \cos \theta \cos \phi) - \frac{1}{r \sin \theta} (r^2 \cos \theta \cos \phi)$$

$$= 4r \cos \theta + \frac{1}{\sin \theta} (r \cos \theta \cos \phi) - \frac{1}{\sin \theta} (r \cos \theta \cos \phi)$$

$$= \frac{r \cos \theta}{\sin \theta} (4 \sin \theta + \cancel{\cos \phi} - \cancel{\cos \phi})$$

$$\boxed{= 4r \cos \theta}$$

$$\int \nabla \cdot \vec{v} \, d\vec{r} \quad [0, R] \quad [0, \pi/2]$$

$$= \iiint (4r \cos \theta) r^2 \sin \theta \, dr \, d\theta \, d\phi$$

$$= \int_0^{\pi/2} \int_0^{\pi/2} \int_0^R (4r^3 \cos \theta \sin \theta) \, dr \, d\theta \, d\phi$$

$$= \frac{\pi}{2} \int_0^{\pi/2} \int_0^R (4r^3 \cos \theta \sin \theta) \, dr \, d\theta$$

$$= \frac{\pi}{2}$$

$$= \frac{4r^3 \pi}{2} \int_0^{\pi/2} \int_0^R \cos \theta \sin \theta \, dr \, d\theta$$

$$u = \sin \theta \, d\theta$$

$$du = \cos \theta \, d\theta$$

$$d\theta = \frac{du}{\cos \theta}$$

$$\cos \theta$$

$$= 2r^3 \pi \int_0^{\pi/2} \int_0^R \cos \theta \, dr \, d\theta$$

$$u = \sin \theta$$

$$u = 0$$

$$u = \sin(\pi/2)$$

$$u = 0$$

$$= \frac{2r^3 \pi}{2} \int_0^R \frac{u}{2} \, dr$$

$$= \frac{2r^3 \pi}{2} \left(\frac{1}{4} - \frac{1}{8} \right)$$

$$= 2r^3 \pi (0-0) \int_0^R dr$$

$$= \frac{2r^3 \pi}{8} \int_0^R dr$$

$$= \frac{2r^3 \pi}{8} \left(\frac{1}{4} - \frac{1}{8} \right)$$

$$= 2\pi r^3 \int_0^R dr$$

$$= 2\pi \int_0^R r^3 dr$$

$$= 2\pi \frac{R^4}{4}$$

$$\boxed{= \frac{\pi R^4}{2}}$$

1.55

$$V = ay\hat{x} + bx\hat{y}$$

[0, R]

$$\iint_S (\nabla \times \vec{A}) \cdot d\vec{s} \\ = \oint \vec{A} \cdot d\vec{r}$$

$$\nabla \times V = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 0y & bx & 0 \\ p_x & p_y & p_z \end{vmatrix}$$

$$(0-0)\hat{x} - (0-0)\hat{y}, (b-a)\hat{z}$$

$$= (b-a)\hat{z}$$

$$= \oint V \cdot d\vec{l}$$

$$= \oint ay dx + bx dy$$

$$x^2 + y^2 = R^2$$

$$y^2 = R^2 - x^2 \quad 2y dy + 2x dx = 0$$

$$y = \sqrt{R^2 - x^2} \quad 2x dx = -2y dy \\ dy = -\left(\frac{x}{y}\right) dx$$

$$= \int ay dx + bx \left(-\frac{x}{y}\right) dx$$

$$= \int \frac{1}{y} (ay^2 - bx^2) dx$$

$$= \int_0^{2\pi} \frac{a(R^2 - x^2) - bx^2}{\sqrt{R^2 - x^2}} dx$$

$$= \int \frac{a(R^2 - x^2)}{\sqrt{R^2 - x^2}} - \int \frac{bx^2}{\sqrt{R^2 - x^2}} dx$$

$$= a \int_0^R \frac{R^2 - x^2}{\sqrt{R^2 - x^2}} dx - b \int \frac{x^2}{\sqrt{R^2 - x^2}} dx$$

$$x = R \sin(\theta)$$

$$dx = R \cos(\theta) d\theta$$

$$= a \int_0^R \frac{R^2 - x^2}{\sqrt{R^2 - x^2}} dx - b \int \frac{x^2}{\sqrt{R^2 - x^2}} dx$$

$$x = R \sin(\theta)$$

$$dx = R \cos(\theta) d\theta$$

$$= a \int_0^R \frac{R^2 - R^2 \sin^2(\theta)}{\sqrt{R^2 - R^2 \sin^2(\theta)}} (R \cos(\theta) d\theta)$$

$$= a \int_0^R \frac{R^2 (1 - \sin^2(\theta))}{R \sqrt{1 - \sin^2(\theta)}} (R \cos(\theta) d\theta)$$

$$= a \int_0^R \frac{R \cos^2(\theta)}{\cos(\theta)} R \cos(\theta) d\theta$$

$$= a R^2 \int_0^R \cos^2(\theta) d\theta$$

$$= a R^2 \left[-2 \cos(\theta) \sin(\theta) \right]_0^1$$

$$= -2a R^2 \left[\cos(1) \sin(1) - \cos(0) \sin(0) \right]$$

$$= \int a (R^2 - x^2)^{1/2} - \frac{b x^2}{(R^2 - x^2)^{1/2}} dx$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$uv = \int v du$$

$$u = t^2$$

$$v = t$$

$$du = 2t dt$$

1.56)

$$\vec{V} = 6\hat{x} + yz^2\hat{y} + (3y+z)\hat{z}$$

$$\nabla \times \vec{V} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 6 & yz^2 & (3y+z) \end{vmatrix}$$

$$= (3-2yz)\hat{x} + 0 + 0$$

$$= \iint (3-2yz) dy dz$$

$$= \int_0^1 \int_0^{2-2y} (3-2yz) dy dz$$

$$= \int_0^1 3z - yz^2 \Big|_0^{2-2y} dy$$

$$= \int_0^1 3(2-2y) - y(2-2y)^2 dy$$

$$= 6 - 6y - y(4y^2 - 8y + 4)$$

$$= 6 - 6y - (4y^3 - 8y^2 + 4y) = 6 - 6y - 4y^3 + 8y^2 - 4y$$

$$= -(4y^3 - 8y^2 + 10y - 6)$$

$$= \int_0^1 (4y^3 - 8y^2 + 10y - 6) dy$$

$$= \left(y^4 - \frac{8}{3}y^3 + 5y^2 - 6y \right) \Big|_0^1$$

$$= -\left(1 - \frac{8}{3} + 5 - 6 \right)$$

$$= -\left(-\frac{8}{3} \right)$$

$$= \boxed{\frac{8}{3}}$$

$$f \cdot \vec{v} \cdot d\vec{s} = \iint (\nabla \times \vec{V}) \cdot d\vec{s}$$

$$d\vec{s} = dy dz \hat{x}$$

$$z = 2-2y$$

$$z: [0, 2-2y]$$

$$y: [0, 1]$$

$$\frac{(2-2y)(2-2y)^2}{4-4y+4y^2-4y}$$

1.57)

$$\int_C \vec{F} \cdot d\vec{r} = \iint_S \nabla \times \vec{V} \cdot d\vec{s}$$

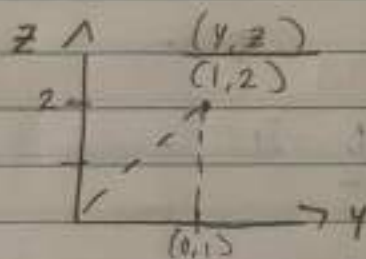
$$\vec{V} = (r \cos^2 \theta) \hat{r} - (r \cos \theta \sin \theta) \hat{\theta} + 3r \hat{\phi}$$

$$\nabla \times \vec{V} = \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{\phi} \\ r & r \cos \theta & r \sin \theta \\ \frac{\partial}{\partial r} & \frac{1}{r} \frac{\partial}{\partial \theta} & \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \end{vmatrix}$$

$$\begin{pmatrix} r \cos^2 \theta \\ -r \cos \theta \sin \theta \\ 3r \end{pmatrix}$$

$$\begin{pmatrix} 0 - 0, 3 - 0, (-\cos \theta \sin \theta - 2r \cos(\theta) \sin(\theta)) \\ -2r \left(\frac{\cos \theta \sin \theta}{2r} + \cos \theta \sin \theta \right) \end{pmatrix}$$

$$= 3 \hat{\theta} - 2r \left(\frac{\cos \theta \sin \theta}{2r} + \cos \theta \sin \theta \right) \hat{\phi}$$

need r, θ, z

$$= \int$$

1.50)

I have no idea what
I am doing."

$$\vec{V} = r^2 \sin \theta \hat{r} + 4r^2 \cos \theta \hat{\theta} + r^2 \tan \theta \hat{\phi}$$

$$\nabla \cdot \vec{V} = \frac{1}{r} (4r^3 \sin \theta) + \frac{1}{r \sin \theta} (4r^2 \sin^2 \theta) \hat{\theta} + \frac{1}{\sin \theta} (r^2 \sin \theta \tan \theta) \hat{\phi}$$

$$\nabla \cdot \vec{V} = 2r \sin \theta - 4r^2 \sin \theta + 0$$

$$= 2r (\sin \theta - 4r \sin \theta)$$

$$= \int_0^{\pi/6} \int_0^{\pi} \int_0^{\pi} (2r \sin \theta - 4r^2 \sin \theta) (r^2 \sin \theta) r dr d\theta d\phi \quad \frac{\sqrt{3}}{4} \cdot \frac{1}{2}$$

$$= \int_0^{\pi/6} \int_0^{\pi} (2r^3 \sin^2 \theta - 4r^4 \sin^2 \theta) \big|_0^{\pi} d\theta d\phi \quad \frac{\pi}{6} \cdot \frac{1}{2}$$

$$= \int_0^{\pi/6} (4\pi r^3 \sin^2 \theta - 8\pi r^4 \sin^2 \theta) dr d\theta$$

$$= \int_0^{\pi/6} 4\pi r \left(\frac{r^3}{2} - \frac{\cos(\theta) \sin(\theta)}{2} \right) - 8\pi r^4 \left(\frac{r^3}{2} - \frac{\cos(\theta) \sin(\theta)}{2} \right) \bigg|_0^{\pi/6} d\theta$$

$$= \int_0^{\pi/6} 4\pi r^3 \left(\frac{\pi}{12} - \frac{\sqrt{3}/2 (\frac{1}{2})}{2} \right) - 8\pi r^4 \left(\frac{\pi}{12} - \frac{\sqrt{3}/2 (\frac{1}{2})}{2} \right) d\theta$$

$$= \int_0^{\pi/6} 4\pi r^3 \left(\frac{\pi}{12} - \frac{\sqrt{3}}{8} \right) - 8\pi r^4 \left(\frac{2\pi - 3\sqrt{3}}{24} \right) d\theta$$

$$= \int_0^{\pi/6} 4\pi r^3 \left(\frac{2\pi - 3\sqrt{3}}{24} \right) - 8\pi r^4 \left(\frac{2\pi - 3\sqrt{3}}{24} \right) d\theta$$

$$= \int_0^R \frac{2\pi - 3\sqrt{3}(\pi)}{6} r^3 - \frac{2\pi - 3\sqrt{3}(\pi)}{3} r^4 dr$$

$$= \left[\frac{2\pi - 3\sqrt{3}(\pi)}{6} \left(\frac{R^4}{4} \right) - \frac{2\pi - 3\sqrt{3}(\pi)}{3} \left(\frac{R^5}{5} \right) \right] \bigg|_0^R$$

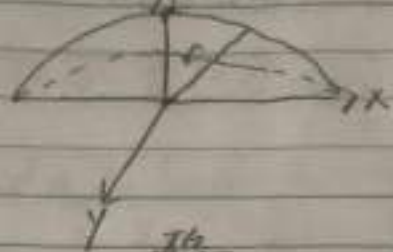
1.62)

$$a = \int_0^{\pi/2} da$$

Sphere so $\theta \in [0, \pi/2]$

$$d\vec{a} = r^2 \sin\theta d\theta d\phi$$

a)



$$\hat{r} = \cos\theta \hat{z}$$

$$a = \int_0^{2\pi} \int_0^{\pi/2} \cos\theta \sin\theta r^2 d\theta d\phi$$

$$a = 2\pi r^2 \int_0^{\pi/2} \cos\theta \sin\theta d\theta$$

$$a = 2\pi r^2 \int_0^{\pi/2} \cos\theta u \left(\frac{du}{\cos\theta} \right)$$

$$a = 2\pi r^2 \int_0^{\pi/2} u du$$

$$a = 2\pi r^2 \left[\frac{u^2}{2} \right]_0^{\pi/2}$$

$$a = \pi r^2 \sin^2 \theta \Big|_0^{\pi/2}$$

$$a = \pi r^2$$

$$a = \pi r^2 \hat{z}$$

$$u = \sin\theta d\theta$$

$$du = \cos\theta d\theta$$

$$d\theta = \frac{du}{\cos\theta}$$

$$+ \text{boundary } \cos\theta$$

(2)

(4)

b)

$$a = \int_S da$$

$$\oint \nabla T = \oint \vec{T} \cdot d\vec{a}$$

$$T = 1$$

$$\nabla T = 0$$

$$\oint_0 = \int da$$

$$\boxed{\oint_0 = \int da}$$

c)

$$a_1 = a_2$$

$$\boxed{a_1 - a_2 = 0}$$

d) $a = \frac{1}{2} \oint r \times d\vec{l}$

e)

$$\oint (\vec{c} \cdot \vec{r}) d\vec{l} = a \times \vec{c}$$

$$T = \vec{c} \cdot \vec{r}$$

$$\nabla T = \nabla (\vec{c} \cdot \vec{r})$$

$$1.63) \quad V = \frac{\hat{r}}{r}$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\hat{r} = \frac{\mathbf{r}}{r}$$

$$d\mathbf{l} = dx \hat{x} + dy \hat{y} + dz \hat{z}$$

$$\nabla V = P_x \hat{x} + P_y \hat{y} + P_z \hat{z}$$

$$P_x = \frac{\partial}{\partial x} (x^2 + y^2 + z^2)^{1/2} = \frac{1}{2} (x^2 + y^2 + z^2)^{-1/2} (2x)$$

$$P_x = \frac{x}{(x^2 + y^2 + z^2)^{1/2}}$$

$$\nabla V = \frac{x \hat{x} + y \hat{y} + z \hat{z}}{\sqrt{x^2 + y^2 + z^2}}$$

$$\nabla \cdot V = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{1}{r}) = \frac{1}{r^2} \frac{\partial}{\partial r} (r) = 0$$

$$\oint_V d\mathbf{a} = \int \left(\frac{1}{R^2} \hat{r} \right) (R^2 \sin\theta d\theta d\phi \hat{r})$$

$$= \left(\int_0^\pi \sin\theta d\theta \right) \left(\int_0^{2\pi} d\phi \right) = 4\pi$$

$$\nabla \cdot (r^n \hat{r}) = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 r^n) = \frac{1}{r^2} \frac{\partial}{\partial r} (r^{n+2})$$

$$= \frac{1}{r^2} (n+2) r^{n+1} = (n+2) r^{n-1}$$

$$n = -2 \rightarrow \nabla \cdot V = 4\pi \delta^3(r)$$

$$\nabla \cdot \left(\frac{\hat{r}}{r^2} \right) = 4\pi \delta^3(r)$$

b)

$$\nabla \wedge (\hat{r} \hat{r}) = 0$$

$$\int (\nabla \wedge \mathbf{v}) \cdot d\mathbf{T} = 0 = - \oint \mathbf{v} \times d\mathbf{a}$$

$$\mathbf{V} = \hat{r} \hat{r}$$

$$\hat{r} \times \hat{r} = 0$$

$$d\mathbf{a} = R^2 \sin\theta d\theta d\phi \hat{r}$$

$$\mathbf{V} \times d\mathbf{a} = (\hat{r} \hat{r}) \times (R^2 \sin\theta d\theta d\phi \hat{r})$$

$$\boxed{\mathbf{V} \wedge d\mathbf{a} = 0}$$