

HW 1: 1.54, 1.55, 1.56, 1.57, 1.59, 1.62, 1.63, 1.64

1.54.)  $\nabla = r^2 \cos\theta \hat{r} + r^2 \cos\phi \hat{\theta} + r^2 \sin\phi \hat{\phi}$

LHS:  $\nabla \cdot \nabla = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \nabla_r) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (\sin\theta \nabla_\theta) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \phi} \nabla_\phi$

$\nabla \cdot \nabla = \frac{1}{r^2} \frac{\partial}{\partial r} (r^4 \cos\theta) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (r^2 \sin\theta \cos\phi)$

$\phi \text{ left } \theta \cos\theta + \frac{1}{r \sin\theta} \frac{\partial}{\partial \phi} (-r^2 \cos\theta \sin\phi)$

$\cancel{\theta} = \cancel{r} *$

$$= \frac{4r^3 \cos\theta}{r^2} + \frac{r^2 \cos\theta \cos\phi}{r \sin\theta} + \left( -\frac{r^2 \cos\theta \cos\phi}{r \sin\theta} \right)$$

$\nabla \cdot \nabla = 4r \cos\theta + 2 \frac{r^2 \cos\theta \cos\phi}{\sin\theta}$  whoops forgot negative till later!

$(\cancel{r}) \frac{1}{dr} = \frac{1}{r^2 \sin\theta dr d\theta d\phi}$

$$\int (\nabla \cdot \nabla) dr = \int \left( 4r \cos\theta + 2 \frac{r^2 \cos\theta \cos\phi}{\sin\theta} \right) r^2 \sin\theta dr d\theta d\phi$$

$\checkmark$  writing  $\nabla \cdot \nabla$  is hard  $\cancel{\theta} \cancel{r} = \cancel{r} \cancel{\theta}$

$$= \int \left( 4r^3 \sin\theta \cos\theta + 2r^3 \cos\theta \cos\phi \right) dr d\theta d\phi$$

$$\int_0^{2\pi} \int_0^{\pi} \int_0^r 4r^3 \sin\theta \cos\theta dr d\theta d\phi = \frac{4\pi}{2} \int_0^r \int_0^{\pi/2} r^3 \sin\theta \cos\theta dr d\theta$$

let  $u = \sin\theta \Rightarrow du = \cos\theta d\theta$

$$\frac{4\pi}{2} \int_0^r \int_0^{\pi/2} r^3 u dr du = \frac{4\pi}{2} \int_0^r r^3 \left[ \frac{u^2}{2} \right]_0^{\pi/2} dr$$

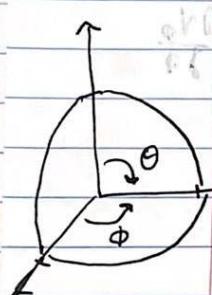
$$= \frac{4\pi}{2} \int_0^r r^3 \left[ \frac{\sin^2\theta}{2} \right]_0^{\pi/2} dr = \frac{4\pi}{2} \int_0^r \frac{1}{2} r^3 dr$$

$$= \pi \int_0^r r^3 dr = \boxed{\frac{\pi r^4}{4}}$$

1.74.) RHS:  $r = \text{constant}$ , so,

$$\nabla \cdot \vec{v} = \frac{\partial}{\partial r} (r^2 \cos \theta \sin \phi) + \frac{\partial}{\partial \theta} (\sin \theta \cos \phi) + \frac{\partial}{\partial \phi} (\sin \theta \sin \phi) = 0$$

$$d\vec{a} = d\theta d\phi \hat{r} = r^2 \sin \theta d\theta d\phi \hat{r}$$



$$(\vec{v} \cdot d\vec{a}) = (r^2 \cos \theta \hat{r} + r^2 \cos \phi \hat{\theta} - r^2 \cos \theta \sin \phi \hat{\phi}) \cdot (r^2 \sin \theta d\theta d\phi \hat{r})$$

$$(\vec{v} \cdot d\vec{a}) = r^4 \sin \theta \cos \theta d\theta d\phi$$

$$\begin{aligned} \vec{v} \cdot d\vec{a} &= \int_{\theta=0}^{\pi} \int_{\phi=0}^{\pi/2} r^4 \sin \theta \cos \theta d\theta d\phi \\ &= \pi R^4 \int_{\theta=0}^{\pi/2} \sin \theta \cos \theta d\theta \\ &\quad \text{by part 4} \\ &= \frac{\pi R^4}{2} \left[ \frac{\sin^2 \theta}{2} \right]_0^{\pi/2} = \frac{\pi R^4}{2} \left( \frac{1}{2} - 0 \right) \end{aligned}$$

$$\boxed{\text{RHS} = \frac{\pi R^4}{2}}$$

LHS = RHS so Gauss' thm is verified. ✓

$$\text{Observe } \int_0^{\pi} \int_0^{\pi/2} \int_0^{\pi} \vec{v} \cdot d\vec{a} = \int_0^{\pi} \int_0^{\pi/2} \int_0^{\pi} \vec{v} \cdot d\vec{a}$$

where  $\vec{v} = \vec{v}(r, \theta, \phi)$

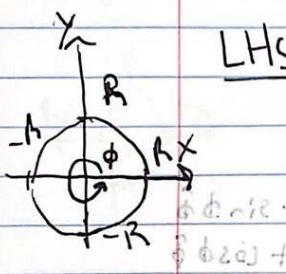
$$\int_0^{\pi} \int_0^{\pi/2} \int_0^{\pi} \vec{v} \cdot d\vec{a} = \int_0^{\pi} \int_0^{\pi/2} \int_0^{\pi} \vec{v} \cdot d\vec{a}$$

$$\int_0^{\pi} \int_0^{\pi/2} \int_0^{\pi} \vec{v} \cdot d\vec{a} = \int_0^{\pi} \int_0^{\pi/2} \int_0^{\pi} \vec{v} \cdot d\vec{a}$$

$$\boxed{\int_0^{\pi} \int_0^{\pi/2} \int_0^{\pi} \vec{v} \cdot d\vec{a} = \int_0^{\pi} \int_0^{\pi/2} \int_0^{\pi} \vec{v} \cdot d\vec{a}}$$

$$1.55.) \quad \vec{v} = ax\hat{i} + bx\hat{j} \quad \nabla \times \vec{v} = \hat{k} \quad : 2HJ (27.1)$$

LHS:  $(\nabla \times \vec{v}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ ax & bx & \phi \end{vmatrix} = \hat{i}(0 - \frac{\partial}{\partial y}\phi) - \hat{j}(0 - \frac{\partial}{\partial x}\phi) + \hat{k}(\frac{\partial}{\partial x}bx - \frac{\partial}{\partial y}ax)$



using cylindrical coordinates -- since  $z = \text{const.} = b$   
 $d\vec{a} = r d\theta s d\phi \hat{z} = s ds d\phi \hat{z}$

now  $(\nabla \times \vec{v}) \cdot d\vec{a} = (b-a)\hat{z} \cdot s ds d\phi \hat{z}$

$$(\hat{\phi} \cos \theta \hat{x} + \hat{\phi} \sin \theta \hat{y})(b-a)\hat{z} + (\hat{\theta} \cos \theta \hat{x} - \hat{\theta} \sin \theta \hat{y})(\phi - a) \hat{z} = \vec{v}$$

$$\begin{aligned} (\nabla \times \vec{v}) \cdot d\vec{a} &= (b-a) \int_s^R s ds d\phi \hat{z} \\ &+ \hat{\theta} \cos \theta \hat{x} + \hat{\theta} \sin \theta \hat{y} \end{aligned}$$

$$\phi \cos \theta \hat{x} + \phi \sin \theta \hat{y} = 2\pi(b-a) \int_0^R s ds \hat{z} \cdot \vec{v} = \boxed{2\pi(b-a)R^2}$$

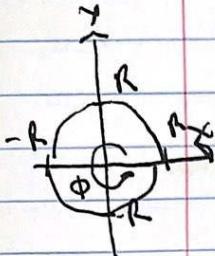
$$\phi \cos \theta \hat{x} + \phi \sin \theta \hat{y} = \pi(b-a) \left[ \frac{s^2}{2} \right]_0^R = \boxed{\pi R^2(b-a)}$$

$$\phi \cos \theta \hat{x} + \phi \sin \theta \hat{y} \quad \boxed{A(\text{end})}$$

$$\phi \cos \theta = nb \quad \phi \sin \theta = n$$

1.55.) RHS:  $\vec{v} = a\gamma \hat{x} + b\gamma \hat{y}$

Ans (22.1)



$$s = R, \theta = \phi \Rightarrow d\vec{l} = d\vec{l}_\phi = s d\phi \hat{\phi}$$

$$\begin{aligned}\hat{x} &= \cos\phi \hat{i} - \sin\phi \hat{j} & y &= s \sin\phi \\ \hat{y} &= \sin\phi \hat{i} + \cos\phi \hat{j} & x &= s \cos\phi\end{aligned}$$

$$\begin{aligned}\Rightarrow \vec{v} &= a(s \sin\phi)(\cos\phi \hat{i} - \sin\phi \hat{j}) + b(s \cos\phi)(\sin\phi \hat{i} + \cos\phi \hat{j}) \\ &= as \sin\phi \cos\phi \hat{i} - as \sin^2\phi \hat{j} + bs \cos\phi \sin\phi \hat{i} + bs \cos^2\phi \hat{j} \\ &= (a+b)s \sin\phi \cos\phi \hat{i} + (bs \cos^2\phi - as \sin^2\phi) \hat{j}\end{aligned}$$

$$\vec{v} \cdot d\vec{l} = (bs^2 \cos^2\phi - as^2 \sin^2\phi) d\phi$$

$$* \cos^2\phi = 1 - \sin^2\phi$$

$$= (bs^2(1 - \sin^2\phi) - as^2 \sin^2\phi) d\phi$$

$$\begin{aligned}&= (bs^2 - bs^2 \sin^2\phi - as^2 \sin^2\phi) d\phi \\ &= (bs^2 - (b+a)s^2 \sin^2\phi) d\phi\end{aligned}$$

$$\oint_P \vec{v} \cdot d\vec{l} = \oint_P (bs^2 - (b+a)s^2 \sin^2\phi) d\phi$$

$$= \oint_P bs^2 d\phi - \oint_P (b+a)s^2 \sin^2\phi d\phi \quad * s=R$$

$$= \int_0^{2\pi} bs^2 d\phi - \int_0^{2\pi} (b+a)s^2 \sin^2\phi d\phi$$

$$= (2\pi b R^2) - (b+a) R^2 \int_0^{2\pi} \sin^2\phi d\phi$$

$$= 2\pi b R^2 - (b+a) R^2 \left[ \frac{\phi}{2} - \frac{1}{4} \sin(2\phi) \right]_0^{2\pi}$$

solved via integral table

1.55.) cont.

$$\rho + \rho \hat{x} \cdot \hat{x} \cdot \hat{x} = \frac{1}{4} \text{ RHS} \quad (22)$$

$$= 2\pi b R^2 h = (b+u) R^2 \left[ \frac{\pi}{2} \right], \quad R=2$$

$$= 2\pi b R^2 - \pi b R^2 - \pi u R^2 = 0$$

$$\phi^{r \omega \omega d} - \cancel{\phi^{r \omega \omega d}} + i \phi^{r \omega \omega d} = \cancel{\phi}$$

$$= \pi b R^2 - \pi u R^2$$

$$(\phi^{r \omega \omega d} + 2\phi^{r \omega \omega d} - \cancel{\phi^{r \omega \omega d}}) \pi R^2 = (b+u) \pi R^2 \quad \checkmark$$

$$\phi^{r \omega \omega d} + 2\phi^{r \omega \omega d} \phi^{r \omega \omega d} + \phi^{r \omega \omega d} - 2\phi^{r \omega \omega d} \phi^{r \omega \omega d} =$$

LHS = RHS thus Stokes' thm is verified.

$$\phi (\phi^{r \omega \omega d} - \phi^{r \omega \omega d}) + 2\phi^{r \omega \omega d} (d_u) =$$

$$\phi b (\phi^{r \omega \omega d} - \phi^{r \omega \omega d}) = \tilde{b} \cdot \tilde{v}$$

$$\phi^{r \omega \omega d} - \cancel{\phi^{r \omega \omega d}} = \phi^{r \omega \omega d} \quad \checkmark$$

$$\phi b (\phi^{r \omega \omega d} - (\phi^{r \omega \omega d} - 1)^2 \cancel{cd}) =$$

$$\phi b (\phi^{r \omega \omega d} - \phi^{r \omega \omega d} - \cancel{cd}) =$$

$$\phi b (\phi^{r \omega \omega d} - (n+d) - \cancel{cd}) =$$

$$\phi b (\phi^{r \omega \omega d} - (n+d) - \cancel{cd}) = \tilde{b} \cdot \tilde{v}$$

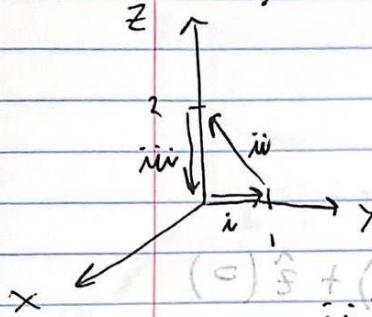
$$\phi b \phi^{r \omega \omega d} - \cancel{\phi b \phi^{r \omega \omega d}} = \phi b \cancel{cd} =$$

$$\phi b \phi^{r \omega \omega d} - \cancel{\phi b \phi^{r \omega \omega d}} = \phi b \cancel{cd} =$$

$$(\phi b \phi^{r \omega \omega d} - \cancel{\phi b \phi^{r \omega \omega d}}) - (\phi b \cancel{cd}) =$$

$$[(\phi b \phi^{r \omega \omega d} - \cancel{\phi b \phi^{r \omega \omega d}}) - \cancel{(\phi b \cancel{cd})}] =$$

$$1.56.) \quad \vec{v} = 6\hat{x} + yz^2(\hat{y} + (3y+2)\hat{z}) \Rightarrow \vec{v} = \vec{v} \text{ AND } (\vec{v} \cdot d\vec{l})$$



$$ii.) \quad x=0, z=0 \quad d\vec{l} = dy\hat{y}$$

$$\vec{v} \cdot d\vec{l} = yz^2 dy = 0 dy$$

$$\int \vec{v} \cdot d\vec{l} = \emptyset$$

$$(0)\hat{x} + (0)\hat{y} - (5y^2 - 8)\hat{z} = |(0, 0, -5y^2 + 8)| = \vec{v} \times \vec{v}$$

$$iii.) \quad x=0, z=-2y+2$$

$$dx=0 \quad dz = -2dy \Rightarrow d\vec{l} = dy\hat{y} + dz\hat{z} = dy\hat{y} + (-2dy)\hat{z}$$

$$\vec{v} \cdot d\vec{l} = yz^2 dy + (3y+2)(-2dy)$$

$$= y(-2y+2)^2 dy + (-6y + 4y - 4) dy$$

$$= (y(4y^2 + 4 - 8y) - 2y - 4) dy$$

$$= (4y^3 - 8y^2 + 2y - 4) dy$$

$$\int \vec{v} \cdot d\vec{l} = \int (4y^3 - 8y^2 + 2y - 4) dy = \left[ y^4 - \frac{8}{3}y^3 + y^2 - 4y \right]_0^1$$

$$= -1 + \frac{8}{3} - 1 + 4 = -\frac{8}{3} + 2 =$$

$$iii.) \quad x=0, y=0, dx=0, dy=0 \Rightarrow d\vec{l} = dz\hat{z}$$

$$\vec{v} \cdot d\vec{l} = (3y+2)dz = 2dz$$

$$\int_2^0 2dz = - \int_0^2 2dz = - \left[ \frac{z^2}{2} \right]_0^2 = -2$$

$$\text{So, } 0 + \frac{8}{3} + 2 + (-2) = \frac{8}{3}$$

$$+ 2 - \frac{8}{3} + 1 = \left[ y^4 - \frac{8}{3}y^3 + y^2 - 4y \right]_0^1 =$$

$$\frac{8}{3} -$$

bottom note back:

$$1.5(b) \text{ cont. } \vec{v} = 6\hat{x} + yz^2\hat{y} + (3y+z)\hat{z} \Rightarrow \vec{v} = \vec{v} \quad (\text{dP.})$$

$$\int (\nabla \times \vec{v}) \cdot d\vec{a}$$

$\rho_{\text{air}} = 1.225 \text{ kg/m}^3$

$$x=0 \Rightarrow dx=0 \Rightarrow d\vec{a} = dy\hat{z}$$

$$\nabla \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 6 & yz^2 & (3y+z) \end{vmatrix} = \hat{x}(3-2yz) - \hat{y}(0) + \hat{z}(0)$$

$$3(6) - 2(0) = 18 \quad \text{and} \quad 6yz^2 = 6(0)^2 = 0$$

$$(\nabla \times \vec{v}) \cdot d\vec{a} = (3-2yz) dy dz$$

$$18(1) - 2(0) = 18$$

$$y=0 \rightarrow 18 - 2(0)(0) = 18$$

$$18 - 2(0) = 18$$

$$\int (\nabla \times \vec{v}) \cdot d\vec{a} = \int_0^1 \int_0^1 (3-2yz) dy dz$$

$$= \int_0^1 [3z - yz^2]_0^1 dy =$$

$$18 - 2(0) = 18 \quad \text{and} \quad 0 = 0 \quad 0 = 0 \quad 0 = 0 \quad (\text{iii})$$

$$= \int_0^1 (-6y+6) dy = y(4y^2+4-8y)$$

$$= \int_0^1 (-6y+6) dy = 54$$

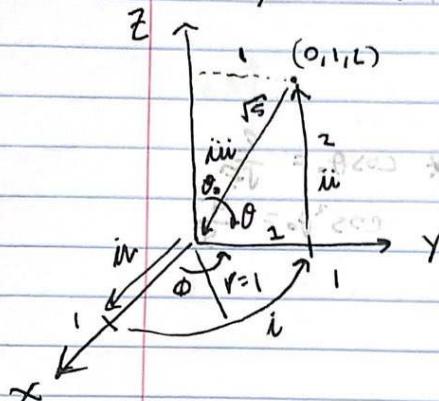
$$= \int_0^1 (-4y^3 + 8y^2 - 10y + 6) dy =$$

$$= \left[ -y^4 + \frac{8}{3}y^3 - 5y^2 + 6y \right]_0^1 = -1 + \frac{8}{3} - 5 + 6$$

$$= \boxed{\frac{8}{3}}$$

$\therefore$  Stokes theorem verified

$$1.57.) \quad \vec{v} = (r \cos^2 \theta) \hat{r} - (r \cos \theta \sin \theta) \hat{\theta} + 3r \hat{\phi} \quad (\text{f?})$$



i.)  $r=1, \theta=\frac{\pi}{2} \Rightarrow dr=0, d\theta=0$   
 $\Rightarrow d\vec{l} = dl_\theta \hat{\phi} = r \sin \theta d\phi \hat{\phi}$

$$\vec{v} \cdot d\vec{l} = 3r^2 \sin \theta d\phi = 3d\phi$$

$$\int_{\frac{\pi}{2}}^{\frac{3\pi}{2}} 3d\phi = \frac{3\pi}{2}$$

ii.)  $\phi = \frac{\pi}{2}, \cos \phi = \frac{1}{r}, \sin \phi = \frac{1}{r} \Rightarrow r = \frac{1}{\sin \phi}$

$$d\phi = 0, dr = \frac{1}{\sin^2 \phi} \cos \phi d\phi$$

$$d\vec{l} = dl_r \hat{r} + dl_\theta \hat{\theta} = dr \hat{r} + r d\phi \hat{\theta}$$

$$= -\frac{1}{\sin^2 \phi} \cos \phi d\phi \hat{r} + \frac{1}{\sin \phi} d\phi \hat{\theta}$$

$$\vec{v} \cdot d\vec{l} = -\frac{r \cos^3 \theta}{\sin^2 \theta} d\phi + (-r \cos \theta) d\phi = -\frac{\cos^3 \theta}{\sin^2 \theta} d\phi + \left(\frac{-\cos \theta}{\sin \theta}\right) d\phi$$

$$= -\frac{\cos \theta}{\sin \theta} \left( \frac{\cos^2 \theta + \sin^2 \theta}{\sin^2 \theta} \right) d\phi$$

$$= -\frac{\cos \theta}{\sin \theta} \left( \frac{1}{\sin^2 \theta} \right) d\phi = -\frac{\cos \theta}{\sin \theta} \left( \frac{1}{\sin^2 \theta} \right) d\phi$$

$$= -\frac{\cos \theta}{\sin^3 \theta} d\phi$$

$$\int \vec{v} \cdot d\vec{l} = \int_{\frac{\pi}{2}}^{\theta_0} -\frac{\cos \theta}{\sin^3 \theta} d\phi = - \int_{\frac{\pi}{2}}^{\theta_0} -\frac{1}{u^3} du = - \left[ \frac{1}{2} \frac{1}{u^2} \right]_{\frac{\pi}{2}}^{\theta_0}$$

$$u = \sin \theta \Rightarrow du = \cos \theta d\theta$$

$$= -\frac{1}{2} \left[ -\frac{1}{\sin^2 \theta} \right]_{\frac{\pi}{2}}^{\theta_0} \quad * \sin \theta_0 = \frac{1}{\sqrt{5}}$$

$$= -\frac{1}{2} \left[ -\frac{1}{\sin^2 \theta_0} + \frac{1}{\sin^2 \left(\frac{\pi}{2}\right)} \right]$$

$$= -\frac{1}{2} [-5 + 1] = +\frac{4}{2} = 2$$

1.57.) cont. iii)  $\phi = \frac{\pi}{2}$ ,  $\theta = 0 \Rightarrow d\phi = 0$ ,  $d\theta = 0$ . (FP)

$$\Rightarrow d\vec{l} = dl_r \hat{r} = dr \hat{r}$$

$$\begin{aligned}\vec{r} \cdot d\vec{l} &= r \cos^2 \theta dr \hat{r} \\ &= \frac{4}{5} r dr\end{aligned}$$

$$\cos \theta_0 = \frac{2}{\sqrt{5}}$$

$$\cos^2 \theta_0 = \frac{4}{5}$$

$$\begin{aligned}\int_{\frac{1}{5}}^0 \frac{4}{5} r dr &= \frac{4}{5} \left[ \frac{r^2}{2} \right]_{\frac{1}{5}}^0 \\ &= \frac{4}{5} \left( -\frac{1}{2} \right) = -\frac{4}{2} = -2\end{aligned}$$

iv.)  $\phi = 0$ ,  $\theta = \frac{\pi}{2} \Rightarrow d\phi = d\theta = 0$  (ii)

$$\begin{aligned}\Rightarrow d\vec{l} &= dl_r \hat{r} = dr \hat{r} \\ \vec{r} \cdot d\vec{l} &= r \cos^2 \theta dr = 0 \quad (\cos \theta = \cos \frac{\pi}{2} = 0)\end{aligned}$$

$$\int \vec{v} d\vec{l} = \phi.$$

$$\text{So, } \frac{3\pi}{2} + 2 - 2 + \phi = \boxed{\frac{3\pi}{2}}$$

$$1.57.) \text{ Given } \vec{J} = r \cos^2 \theta \hat{r} - (r \cos \theta \sin \theta) \hat{\theta} + 3r \hat{\phi}$$

$$\nabla \times \vec{J} = \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta \cdot 3r) - \frac{\partial}{\partial \phi} (r \cos \theta \sin \theta) \right] \hat{r}$$

$$+ \frac{1}{r} \left[ \frac{1}{\sin \theta} \frac{\partial}{\partial \phi} (r \cos^2 \theta) - \frac{\partial}{\partial r} (r \cdot 3r) \right] \hat{\theta}$$

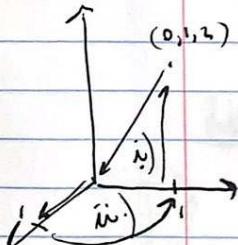
$$+ \frac{1}{r} \left[ \frac{\partial}{\partial r} (r \cos \theta \sin \theta) - \frac{\partial}{\partial \theta} (r \cos^2 \theta) \right] \hat{\phi}$$

$$= \frac{1}{r \sin \theta} [3r \cos \theta - \phi] \hat{r} + \frac{1}{r} [0 - 6r] \hat{\theta}$$

$$( \cancel{r \cos \theta \sin \theta}) + \frac{1}{r} [-2r \cos \theta \sin \theta + 2r \cos \theta \sin \theta] \hat{\phi}$$

$$= 3 \frac{\cos \theta}{\sin \theta} \hat{r} (0 - 6) + \cancel{r \cos \theta \sin \theta} \hat{\phi}$$

$$\nabla \times \vec{J} = 3 \frac{\cos \theta}{\sin \theta} \hat{r} - 6 \hat{\theta}$$



$$i.) d\vec{a} = -dr_r d\theta_r \hat{\phi} = -r dr d\theta \hat{\phi}$$

$$(\nabla \times \vec{J} \cdot d\vec{a}) = 0 \Rightarrow \int_{0 \rightarrow 2\pi} \nabla \times \vec{J} \cdot d\vec{a} = 0$$

$$ii.) d\vec{a} = -dr_r d\theta_r \hat{\phi} = -r \sin \theta dr d\theta \hat{\phi}$$

~~then  $\theta = \frac{\pi}{2}$~~   $\rightarrow = -r dr d\theta \hat{\phi}$

$$(\nabla \times \vec{J} \cdot d\vec{a}) = 6r dr d\theta \hat{\phi}$$

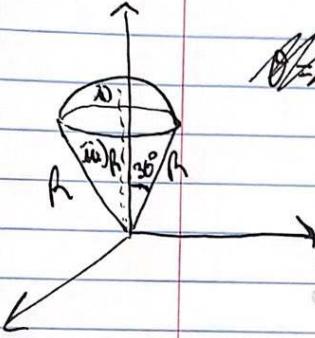
$$\int_{S} (\nabla \times \vec{J} \cdot d\vec{a}) = \int_0^r \int_0^{2\pi} 6r dr d\theta = \frac{6\pi}{2} \int_0^r r dr$$

$$= 3\pi \left[ \frac{r^2}{2} \right]_0^1 = \frac{3\pi}{2}$$

$$\text{So, } 0 + \frac{3\pi}{2} = \boxed{\frac{3\pi}{2}}$$

and Stokes' theorem is verified.

$$1.59.) \quad \vec{v} = r^2 \sin\theta \hat{r} + Ur^2 \cos\theta \hat{\theta} + r^2 \tan\theta \hat{\phi}$$



$$d\tau = r^2 \sin\theta dr d\theta d\phi$$

$$\nabla \cdot \vec{v} = 2r \sin\theta + (-Ur^2 \sin\theta) + 0$$

$$= 2r \sin\theta - Ur^2 \sin\theta \quad * \theta = 30^\circ$$

$$\nabla \cdot \vec{v} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v^r \sin\theta) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (\sin\theta v^r \cos\theta)$$

$$+ \frac{1}{r \sin\theta} \frac{\partial}{\partial \phi} (r^2 v^r \tan\theta)$$

$$= \frac{4r^3}{r^2} \sin\theta + \frac{4r}{\sin\theta} (\cos^2\theta - \sin^2\theta)$$

+ 0

$$= 4r \sin\theta + 4r \frac{\cos^2\theta}{\sin\theta} = 4r \sin\theta$$

$$\nabla \cdot \vec{v} = 4r \frac{\cos^2\theta}{\sin\theta} = (ab - bcd)$$

$$\int (\nabla \cdot \vec{v}) d\tau = \int 4r \frac{\cos^2\theta}{\sin\theta} r^2 \sin\theta dr d\theta d\phi$$

$$= \int 4r^3 \cos^2\theta dr d\theta d\phi$$

$$\int_{0}^{R} \int_{0}^{\pi} \int_{0}^{2\pi} 4r^3 \cos^2\theta dr d\theta d\phi = 2\pi \int_{0}^{\pi} \int_{0}^{R} 4r^3 \cos^2\theta dr d\theta$$

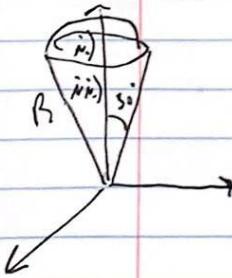
$$= \left[ \frac{4r^4}{4} \cos^2\theta \right] =$$

$$= \left[ \frac{R^4}{4} \cos^2\theta \right] =$$

1.59.) cont.

$$\begin{aligned}
 & \text{obj} = 2\pi \left[ r^4 \right]_0^R \int_0^{\frac{\pi}{6}} \cos^2 \theta d\theta \quad (\because * \cos^2 \theta = \frac{1}{2}(1 + \cos(2\theta)))
 \\
 &= \frac{2\pi R^4}{2} \int_0^{\frac{\pi}{6}} (1 + \cos 2\theta) d\theta \\
 &= \frac{2\pi R^4}{2} \left[ \frac{\pi}{6} + \int_0^{\frac{\pi}{6}} \cos(2\theta) d\theta \right] \quad u = 2\theta \Rightarrow du = 2d\theta \\
 &= \frac{2\pi R^4}{2} \left[ \frac{\pi}{6} + \frac{1}{2} \left\{ \sin(2\theta) \right\}_0^{\frac{\pi}{6}} \right] \quad d\theta = \frac{1}{2} du \\
 &= \pi R^4 \left( \frac{\pi}{6} + \frac{1}{2} \left( \frac{\sqrt{3}}{2} - 0 \right) \right) \\
 &= \boxed{\pi R^4 \left( \frac{\pi}{6} + \frac{\sqrt{3}}{4} \right)}
 \end{aligned}$$

RHS:  $\vec{V} = r^2 \sin \theta \hat{r} + r^2 \cos \theta \hat{\theta} + r^2 \tau \sin \theta \hat{\phi}$



i)  $r = R \Rightarrow dr = 0$   
 $d\vec{a} = d\theta d\phi \hat{r} = r^2 \sin \theta d\theta d\phi \hat{r}$

$$\begin{aligned}
 \vec{V} \cdot d\vec{a} &= (r^2 \sin \theta)^2 d\theta d\phi = r^4 \sin^2 \theta d\theta d\phi = R^4 \sin^2 \theta d\theta d\phi \\
 \int \vec{V} \cdot d\vec{a} &= R^4 \int_0^{\frac{\pi}{6}} \int_0^{2\pi} \sin^2 \theta d\theta d\phi = 2\pi R^4 \int_0^{\frac{\pi}{6}} \sin^2 \theta d\theta
 \end{aligned}$$

$$\begin{aligned}
 &= 2\pi R^4 \int_0^{\frac{\pi}{6}} \frac{1}{2} (1 - \cos(2\theta)) d\theta \quad (* \sin^2 \theta = \frac{1}{2}(1 - \cos(2\theta))) \\
 &= \pi R^4 \left[ \frac{\pi}{6} - \left[ \frac{\sin 2\theta}{2} \right]_0^{\frac{\pi}{6}} \right] = \pi R^4 \left( \frac{\pi}{6} - \frac{\sqrt{3}}{4} \right)
 \end{aligned}$$

1.59.) cont. ii.)  $\theta = 30^\circ \Rightarrow d\theta = 0$

$$\Rightarrow d\vec{a} = dr d\phi \hat{\theta} = r \sin \theta dr d\phi \hat{\theta}$$
$$= \frac{\sqrt{3}}{2} dr d\phi \hat{\theta}$$

$$\vec{V} \cdot d\vec{a} = 24r^2 \cos \theta \left( \frac{r}{2} dr d\phi \right) = 2\sqrt{3} \left( \frac{\sqrt{3}}{2} dr d\phi \right)$$
$$= \sqrt{3} r^3 dr d\phi$$

$$\int \vec{V} \cdot d\vec{a} = \int_0^{2\pi} \int_0^R r^3 dr d\phi$$

$$= 2\sqrt{3}\pi \left[ \frac{r^4}{4} \right]_0^R$$
$$= \frac{\sqrt{3}\pi R^4}{2}$$

$$\text{So, } \pi R^4 \left( \frac{\pi}{6} - \frac{\sqrt{3}}{4} \right) + \frac{\sqrt{3}\pi R^4}{2} = \pi R^4 \left( \frac{\pi}{6} + \frac{2\sqrt{3}}{4} - \frac{\sqrt{3}}{4} \right)$$
$$= \pi R^4 \left( \frac{\pi}{6} + \frac{\sqrt{3}}{2} \right)$$

∴ LHS = RHS and Green's Thm. is verified.

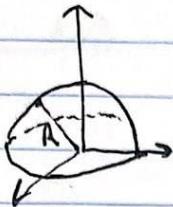
$$\text{where } \vec{a} = \phi \hat{\theta} \hat{r} + \theta \hat{\phi} \hat{r} = \phi \hat{\theta} \hat{r} + (\sin \theta \hat{\phi}) = \hat{a} \cdot \vec{r}$$

$$\text{also } \vec{a} \cdot \vec{n} = \vec{a} \cdot \hat{n} = \phi \hat{\theta} \hat{r} \cdot \hat{n} = \phi \hat{\theta} \hat{r}$$

$$((0.5)(0.5) + 1)(0.5) = 0.75 \cdot 0.5 = 0.375$$

$$\left( \frac{\pi}{6} - \frac{\sqrt{3}}{4} \right) \cdot \pi R^2 = \left( \frac{\pi(0.5)(0.5)}{6} - \frac{\sqrt{3}}{4} \right) \cdot \pi R^2 =$$

1.62) a.)



$$r=R \Rightarrow dr=0$$

$$\Rightarrow d\vec{a} = dl\phi dl\theta = r^2 \sin\theta d\theta d\phi \hat{r}$$

$$a = \int_S d\vec{a} = \iint_0^{2\pi} R^2 \sin\theta d\theta d\phi$$

$$= 2\pi R^2 \int_0^{\pi/2} \sin\theta d\theta$$

$$= 2\pi R^2 [-\cos\theta]_0^{\pi/2}$$

$$= 2\pi R^2 [0 - (-1)] = [2\pi R^2 \hat{r}]$$

b.)  $\oint_S T d\vec{a} = \int_S (\nabla T) d\tau$  according to the hint.

If  $F = I \Rightarrow \oint_S d\vec{a}$  is  $\vec{n}$  of a closed surface

$$\oint_S T d\vec{a} = \int_S (\nabla T) d\tau = 0.$$

c.) Suppose  $a_1 \neq a_2$  for two surfaces sharing the same boundary. Now imagine adding those surfaces to create a closed surface, then

$$\oint_S d\vec{a} = d_1 - d_2 = 0, \text{ but}$$

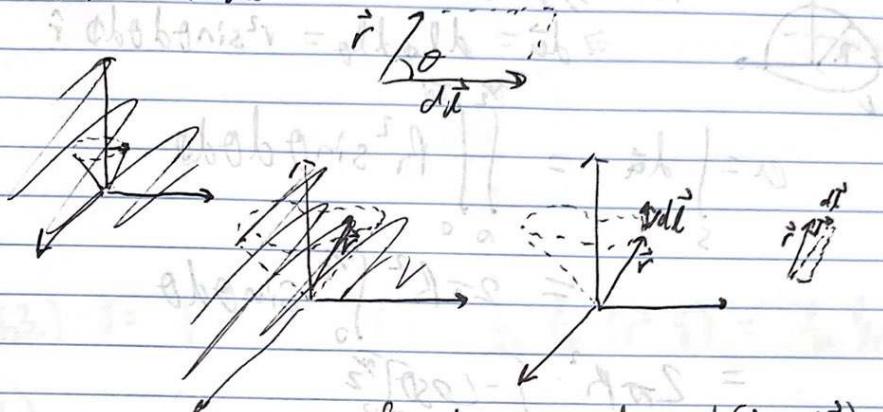
$$d_1 \neq d_2.$$

Contradiction!

Thus  $a_1 = a_2$ .

1.62) cont.

a)  $\vec{r} \times d\vec{l}$



for this case  $d\vec{a} = \frac{1}{2}(\vec{r} \times d\vec{l})$

since  $(-\vec{r} \times d\vec{l})$  is the angle of the rectangle formed (since there is a  $90^\circ$  angle b/w  $\vec{r}, d\vec{l}$ )

If we integrate all these ...

$$\oint d\vec{a} = \oint \frac{1}{2}(\vec{r} \times d\vec{l}).$$

e)  $\oint (\vec{C} \cdot \vec{r}) d\vec{l}$  Following the hint:  $\oint \nabla T \times d\vec{a} = - \oint T d\vec{l}$

Let  $T = \vec{C} \cdot \vec{r}$

$$\nabla T = \nabla(\vec{C} \cdot \vec{r}) = \vec{C} \times (\nabla \times \vec{r}) + \vec{r} \times (\nabla \times \vec{C})$$

$$+ (\vec{C} \cdot \nabla) \vec{r} + (\vec{r} \cdot \nabla) \vec{C}$$

\*  $\nabla \times \vec{r} = \vec{0}$

$$= \vec{0} + \vec{r} \times \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{vmatrix} + (C_x \frac{\partial}{\partial x} + C_y \frac{\partial}{\partial y} + C_z \frac{\partial}{\partial z})(\vec{r})$$

$$+ (x \frac{\partial C_x}{\partial x} + y \frac{\partial C_y}{\partial y} + z \frac{\partial C_z}{\partial z})(\vec{C}) \quad \text{zero since } \vec{C} \text{ is const.}$$

$$= (C_x \hat{x} + C_y \hat{y} + C_z \hat{z}) \times (\hat{x} + \hat{y} + \hat{z})$$

$$\nabla T = C_x \hat{x} + C_y \hat{y} + C_z \hat{z} = \vec{C}$$

$$1.62.) \text{ cont. e.) so, } \oint (\vec{C} \cdot \vec{dl}) = - \int \vec{i} \times d\vec{a} \quad (\text{d.e.})$$

$$= - \vec{i} \times d\vec{a} \quad \text{since } \vec{i} \text{ const. vel.}$$

$$= - \vec{i} \times \vec{a}$$

$$= \vec{a} \times \vec{i}$$

$$1.63.) \vec{v} = \frac{1}{r} \vec{r} \quad \nabla \cdot \vec{v} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{1}{r}) = \frac{1}{r^2} \frac{\partial}{\partial r} r(r) = \frac{1}{r^2}$$

$$\text{e.) } \int (\nabla \cdot v) dV = \int \frac{1}{r^2} (r^2 \sin \theta) dr d\theta d\phi \quad (\text{P.d.})$$

Let  $V$  be a sphere of radius  $R$ :

$$\int_0^{2\pi} \int_0^{\pi} \int_0^R \frac{1}{r^2} r^2 \sin \theta dr d\theta d\phi = 2\pi R \int_0^{\pi} \sin \theta d\theta$$

$$= 2\pi R [-\cos \theta]_0^\pi = 2\pi R [1 + 1]$$

$$= 4\pi R.$$

$$\oint \vec{v} \cdot d\vec{a} + r=R \Rightarrow dr=0 \Rightarrow d\vec{a} = d\theta d\phi \hat{r} = r^2 \sin \theta d\theta d\phi \hat{r}$$

$$\vec{v} \cdot d\vec{a} = \frac{1}{r} r^2 \sin \theta d\theta d\phi$$

$$\oint \vec{v} \cdot d\vec{a} = R \int_0^{2\pi} \int_0^{\pi} \sin \theta d\theta d\phi = 2\pi R \int_0^{\pi} \sin \theta d\theta$$

$$= 4\pi R.$$

So thm. checks out.

$$\nabla \cdot (r^n \hat{r}) = \frac{d}{dr} (r^n) = nr^{n-1}$$

1.63.) b.)

$$\nabla \times \vec{V} = \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \phi} (\sin \theta V_\theta) - \frac{\partial V_r}{\partial \theta} \right] \hat{r} + \frac{1}{r} \left[ \frac{1}{\sin \theta} \frac{\partial V_r}{\partial \phi} - \frac{\partial}{\partial r} \left( \frac{V_\theta}{\sin \theta} \right) \right] \hat{\theta} + \frac{1}{r} \left[ \frac{\partial}{\partial r} \left( r V_\theta \right) - \frac{\partial V_r}{\partial \theta} \right] \hat{\phi}$$

$$\nabla \times \vec{V} = \boxed{0 = \nabla \times r^n \hat{r}}$$

1.64.)

$$D(r, t) \equiv -\frac{1}{4\pi} \nabla^2 \frac{1}{\sqrt{r^2 + t^2}} = \boxed{J_0(r, t)}$$

a.)  $\nabla^2 \frac{1}{\sqrt{r^2 + t^2}} = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{1}{\sqrt{r^2 + t^2}} \right)$

$$= \frac{1}{r^2} \frac{d}{dr} \left( r^2 \left( -\frac{1}{2} \frac{1}{(r^2 + t^2)^{3/2}} 2r \right) \right)$$

$$= \frac{1}{r^2} \frac{d}{dr} \left( -\frac{r^3}{(r^2 + t^2)^{3/2}} \right)$$

$$= \frac{1}{r^2} \frac{d}{dr} \left( -r^3 (r^2 + t^2)^{-3/2} \right)$$

$$= \frac{1}{r^2} \left( -3r^2 (r^2 + t^2)^{-3/2} + (-r^3) \left( -\frac{3}{2} \right) (r^2 + t^2)^{-5/2} 2r \right)$$

$$= \frac{1}{r^2} \left( \frac{-3r^2 (r^2 + t^2)}{(r^2 + t^2)^{5/2}} + \frac{3r^4}{(r^2 + t^2)^{5/2}} \right)$$

$$= \frac{3r^2 - 3r^2 - 3t^2}{(r^2 + t^2)^{5/2}} = \frac{-3t^2}{(r^2 + t^2)^{5/2}}$$

$$\Rightarrow D(r, t) = \frac{-1}{4\pi} \left( \frac{-3t^2}{(r^2 + t^2)^{5/2}} \right) = \boxed{\frac{3t^2}{4\pi (r^2 + t^2)^{5/2}}}$$

1.b4.) cont.

b.)  $D(0, t) = \frac{3e^2}{4\pi t^5} = \frac{3}{4\pi t^3}$

$$\lim_{t \rightarrow 0} \frac{3}{4\pi t^3} = \infty \quad \checkmark$$

c.)  $D(r, t) = \frac{3e^2}{4\pi(r^2 + t^2)^{5/2}}$

$$\lim_{r \rightarrow 0} D(r, t) = \frac{0}{4\pi r^5} = 0. \quad \checkmark$$

d.)  $\int_0^\infty D(r, t) 4\pi r^2 dr = \int_0^\infty \frac{3e^2}{4\pi(r^2 + t^2)^{5/2}} 4\pi r^2 dr$   
 $= 3e^2 \int_0^\infty \frac{r^2}{(r^2 + t^2)^{5/2}} dr$

*dore  
using  
sugr*  $\rightarrow = 3e^2 \left( \frac{1}{3e^2} \right) = 1$