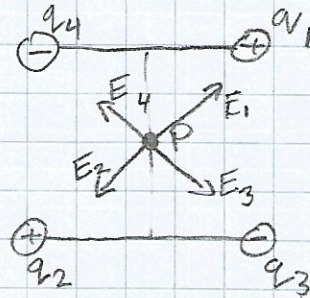
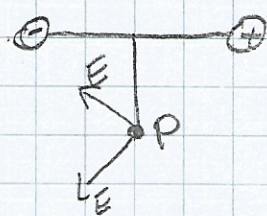
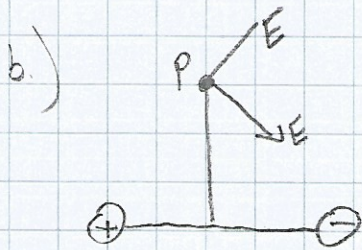


1) a) $\vec{\tau} = \vec{r} \times \vec{F}$ $\vec{p} = q\vec{d}$ $\vec{F}_+ = +q\vec{E}$
 $\vec{F}_- = -q\vec{E}$

Torque = Force \times Distance

$$\vec{\tau} = q\vec{E} \times \vec{d} \Rightarrow \boxed{\vec{\tau} = \vec{p} \times \vec{E}}$$



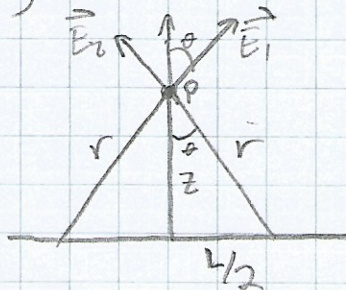
Should be zero

Dipole $\Rightarrow \vec{p} = q\vec{d}$ $E = k \frac{q}{r}$ $|q_1| = |q_2|$ $|r_1| = |r_2|$ $|E_1| = |E_2|$

Opposite directions: $\vec{E}_1 + \vec{E}_2 = 0$ $\vec{E}_3 + \vec{E}_4 = 0$

$$\boxed{\vec{E}_{\text{net}} = 0}$$

2) a) $Q = \lambda L$



$$d\vec{E} = \frac{k dq \hat{r}}{r^2}$$

$$= \frac{k \lambda dx (z\hat{z} - x\hat{x})}{(z^2 + x^2)^{3/2}}$$

$$\vec{r} = \vec{r}_1 - \vec{r}_2$$

$$\vec{r}_1 = z\hat{z} - x\hat{x}$$

$$r^2 = z^2 + x^2$$

$$\hat{r} = \frac{\vec{r}}{r} = \frac{z\hat{z} - x\hat{x}}{(z^2 + x^2)^{1/2}}$$

$$\int d\vec{E} = \int_{-L/2}^{L/2} \frac{k \lambda dx (z\hat{z} - x\hat{x})}{(z^2 + x^2)^{3/2}}$$

$$\vec{E} = k \lambda \left\{ z\hat{z} \int_{-L/2}^{L/2} \frac{dx}{(z^2 + x^2)^{3/2}} - \hat{x} \int_{-L/2}^{L/2} \frac{x dx}{(z^2 + x^2)^{3/2}} \right\}$$

$$x = z \tan(\theta)$$

$$dx = z \sec^2 \theta d\theta$$

$$x dx = z^2 \tan \theta \sec^2 \theta d\theta$$

$$\vec{E} = k\lambda \left\{ \frac{z^2 \hat{z}}{z^3} \int_{\theta_1}^{\theta_2} \frac{z \sec^2 \theta d\theta}{(z^2 + z^2 \tan^2 \theta)^{3/2}} - \dots \right\}$$

$$= k\lambda \left\{ \frac{z^2 \hat{z}}{z^3} \int_{\theta_1}^{\theta_2} \frac{\sec^2 \theta d\theta}{(1 + \tan^2 \theta)^{3/2}} - \dots \right\}$$

$$= k\lambda \left\{ \frac{z^1}{z} \int_{\theta_1}^{\theta_2} \frac{\sec^2 \theta d\theta}{\sec^3 \theta} - \dots \right\}$$

$$= k\lambda \left\{ \frac{\hat{z}}{z} \int_{\theta_1}^{\theta_2} \cos \theta d\theta - \dots \right\}$$

$$= k\lambda \left\{ \frac{\hat{z}}{z} \sin \theta \Big|_{\theta_1}^{\theta_2} - \hat{x} \int_{\theta_1}^{\theta_2} \frac{z^2 \tan \theta \sec^2 \theta d\theta}{z^3 \sec^3 \theta d\theta} \right\}$$

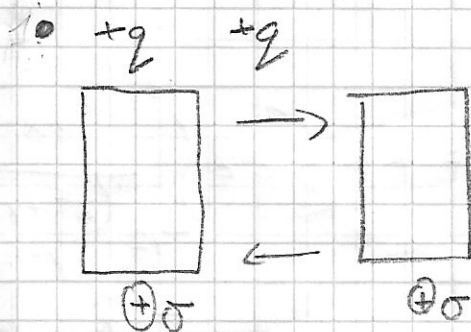
$$\vec{E} = \frac{k\lambda \hat{z}}{z} (\sin \theta_2 - \sin \theta_1) \quad \sin \theta_1 = \frac{-L/2}{z}$$

$$= \frac{k\lambda L \hat{z}}{z} \left(z^2 + \frac{1}{4} L^2 \right)^{-1/2}$$

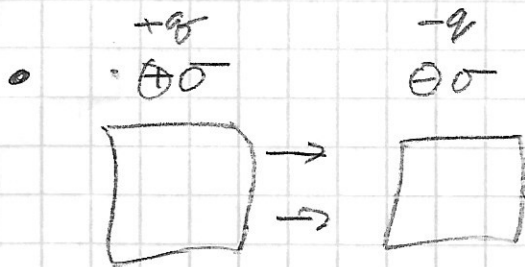
$$\boxed{\vec{E} = \frac{k\lambda L \hat{z}}{z^2} \left(1 + \frac{1}{4} \left(\frac{L}{z} \right)^2 \right)^{-1/2}}$$

$$E \sim \frac{kQ \hat{z}}{z^2} \quad Q = \lambda L \quad z \gg L$$

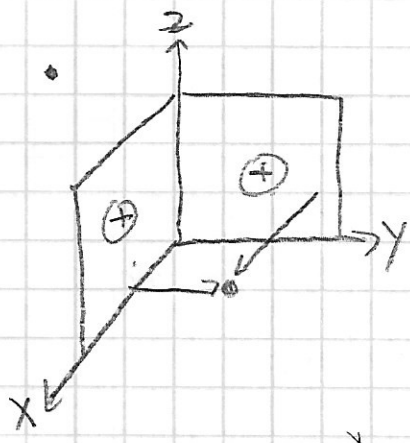
2) 2) $\sigma / (2\epsilon_0)$



$$E_{\text{Tot}} = \frac{\sigma}{2\epsilon_0} - \frac{\sigma}{2\epsilon_0} = \boxed{0}$$



$$E_{\text{tot}} = \frac{\sigma}{2\epsilon_0} + \frac{\sigma}{2\epsilon_0} = \boxed{\frac{\sigma}{\epsilon_0}}$$



$$E_{\text{tot}} = E_x + E_y$$

$$\begin{aligned} \frac{\sigma}{2\epsilon_0} \hat{x} + \frac{\sigma}{2\epsilon_0} \hat{y} &= \sqrt{\left(\frac{\sigma}{2\epsilon_0}\right)^2 + \left(\frac{\sigma}{2\epsilon_0}\right)^2} \\ &= \frac{\sigma}{\epsilon_0} = \boxed{\frac{\sigma}{\epsilon_0}} \end{aligned}$$

$$3) \quad - \int_a^b \vec{E} \cdot d\vec{\ell} = (V(b) - V(a))$$

$$\hookrightarrow V(r) = - \int_0^r E \cdot d\ell \quad (2.21)$$

$$\begin{aligned} \frac{V(b) - V(a)}{1} &= - \int_0^b E \cdot d\ell + \int_0^a E \cdot d\ell \\ &= - \int_0^b E \cdot d\ell - \int_a^0 E \cdot d\ell = - \int_a^b E \cdot d\ell \end{aligned}$$

$$V(\vec{r}) = - \int_{\infty}^r E(r') dr'$$

$$E = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r} \quad \rightarrow \quad = \frac{-1}{4\pi\epsilon_0} \int_{\infty}^r \frac{q}{r'^2} dr'$$

$$= \frac{1}{4\pi\epsilon_0} \frac{q}{r'} \Big|_{\infty}^r = \frac{1}{4\pi\epsilon_0} \frac{q}{r} = \boxed{\frac{kq}{r}}$$