

PHYS Ch.1 HW

1.54, 55, 56, 57, 59,

62, 63, 64

1.54 $\vec{v} = r^2 \cos \theta \hat{r} + r^2 \cos \phi \hat{\theta} - r^2 \cos \theta \sin \phi \hat{\phi}$

$$\nabla \cdot \vec{v} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta v_\theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (\sin \theta v_\phi)$$

// $v_r = r^2 \cos \theta, v_\theta = r^2 \cos \phi, v_\phi = -r^2 \cos \theta \sin \phi$

① $\frac{1}{r^2} \frac{\partial}{\partial r} (r^4 \cos \theta) = \frac{1}{r^2} (4r^3 \cos \theta) = 4r \cos \theta$

② $\frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (r^2 \sin \theta \cos \phi) = \frac{1}{r \sin \theta} (r^2 \cos \theta \cos \phi) = \frac{r \cos \theta \cos \phi}{\sin \theta}$

③ $\frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (-r^2 \cos \theta \sin \phi) = \frac{1}{r \sin \theta} (-r^2 \cos \theta \cos \phi) = -\frac{r \cos \theta \cos \phi}{\sin \theta}$

$$\int_V \nabla \cdot \vec{v} = 4r \cos \theta = \int_0^R \int_0^{2\pi} \int_0^{\pi/2} 4r \cos \theta r^2 \sin \theta dr d\theta d\phi = 4 \int_0^R r^3 dr \int_0^{2\pi} d\phi \int_0^{\pi/2} \cos \theta \sin \theta d\theta$$

$$= 4 \left[\frac{1}{4} r^4 \right]_0^R \cdot \int_0^{2\pi} d\phi \cdot \int_0^{\pi/2} \cos \theta \sin \theta d\theta$$

// $\int_0^{2\pi} d\phi = 2\pi$
// $\int_0^{\pi/2} \cos \theta \sin \theta d\theta = \int_0^{\pi/2} u du = \left[\frac{u^2}{2} \right]_0^{\pi/2} = \frac{1}{2}$

$\int_V \nabla \cdot \vec{v} = R^4 \cdot \left(\frac{1}{2} \right) \cdot \left(\frac{\pi}{2} \right) = \frac{\pi R^4}{4}$ ✓

① $\phi = 90^\circ$ ② $\theta = 0^\circ$ ③ $\phi = 0^\circ$ ④ $r = R$

$\int_S \vec{v} \cdot d\vec{a} = \int_A \vec{v} \cdot d\vec{a} + \int_B \vec{v} \cdot d\vec{a} + \int_C \vec{v} \cdot d\vec{a} + \int_D \vec{v} \cdot d\vec{a}$ // $v_r = r^2 \cos \theta, v_\theta = r^2 \cos \phi, v_\phi = -r^2 \cos \theta \sin \phi$

① $\int_S \hat{\phi} dr d\theta = \int_0^R \int_0^{\pi/2} -r^2 \cos \theta \sin \phi r dr d\theta$ // $\phi = 90^\circ \Rightarrow \sin \phi = 1 \Rightarrow \int_0^R r^3 dr \int_0^{\pi/2} \cos \theta d\theta$

$-\left[\frac{1}{4} r^4 \right]_0^R \left[\sin \theta \right]_0^{\pi/2} = -\frac{1}{4} R^4 (1-0) = -\frac{1}{4} R^4$

② $\int_S \hat{\theta} dr d\phi = \int_0^R \int_0^{2\pi} r^2 \cos \phi r dr d\phi = \int_0^R r^3 dr \int_0^{2\pi} \cos \phi d\phi = \frac{1}{4} R^4 (\sin \phi)_0^{2\pi} = \frac{1}{4} R^4 (1) = \frac{1}{4} R^4$

③ $\int_S \hat{r} dr d\theta = \int_0^R \int_0^{\pi/2} -r^2 \cos \theta \sin \phi r dr d\theta$ // $\phi = 0^\circ, \sin(0) = 0 \Rightarrow \int_0^R \int_0^{\pi/2} 0 dr d\theta = 0$

④ $\int_S \hat{r} d\theta d\phi = \int_0^{\pi/2} \int_0^{2\pi} r^2 \cos \theta r^2 \sin \theta d\theta d\phi = \int_0^{\pi/2} r^4 \cos \theta \sin \theta d\theta \int_0^{2\pi} d\phi$

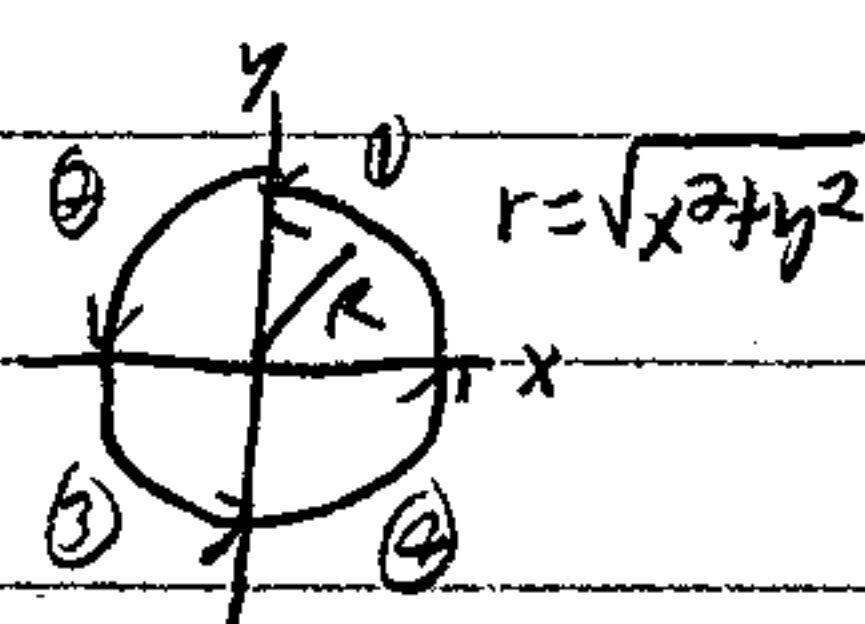
// $u = \cos \theta, du = -\sin \theta d\theta \Rightarrow \int_0^{\pi/2} u du = \left[\frac{u^2}{2} \right]_0^{\pi/2} = \left[\frac{\cos^2 \theta}{2} \right]_0^{\pi/2} = \left[0 + \frac{1}{2} \right] = \frac{1}{2}$

$R^4 \left(\frac{1}{2} \right) \left(\frac{\pi}{2} \right) = \frac{\pi R^4}{4}$ ✓

$\int_S \vec{v} \cdot d\vec{a} = -\frac{1}{4} R^4 + \frac{1}{4} R^4 + 0 + \frac{\pi R^4}{4} = \frac{\pi R^4}{4}$

1.55 Check Stokes Theorem: $\int_S (\nabla \times \vec{v}) \cdot d\vec{a} = \oint_P \vec{v} \cdot d\vec{l}$; $\vec{v} = ay\hat{x} + bx\hat{y}$

$\nabla \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ ay & bx & 0 \end{vmatrix} = \frac{\partial}{\partial x} (bx) \hat{z} - \frac{\partial}{\partial y} (ay) \hat{z} = (b-a)\hat{z}$



$\int_S (\nabla \times \vec{v}) \cdot d\vec{a} = \int_0^{2\pi} \int_0^R (b-a) r dr d\theta = (b-a) \int_0^{2\pi} d\theta \int_0^R r dr = (b-a) \left[\frac{r^2}{2} \right]_0^R (2\pi) = (b-a) \frac{R^2}{2} (2\pi) = \pi R^2 (b-a)$

$\oint_P \vec{v} \cdot d\vec{l} = \int_0^{2\pi} \vec{v} \cdot d\vec{l}$ // $x = r \cos \theta, y = r \sin \theta, dx = -r \sin \theta d\theta, dy = r \cos \theta d\theta$

// $\vec{v} = a(r \sin \theta) \hat{x} + b(r \cos \theta) \hat{y} = ar \sin \theta \hat{x} + br \cos \theta \hat{y}$

$\int_0^{2\pi} \vec{v} \cdot d\vec{l} = \int_0^{2\pi} ar \sin \theta (-r \sin \theta d\theta) + br \cos \theta (r \cos \theta d\theta) = -ar^2 \int_0^{2\pi} \sin^2 \theta d\theta + br^2 \int_0^{2\pi} \cos^2 \theta d\theta$

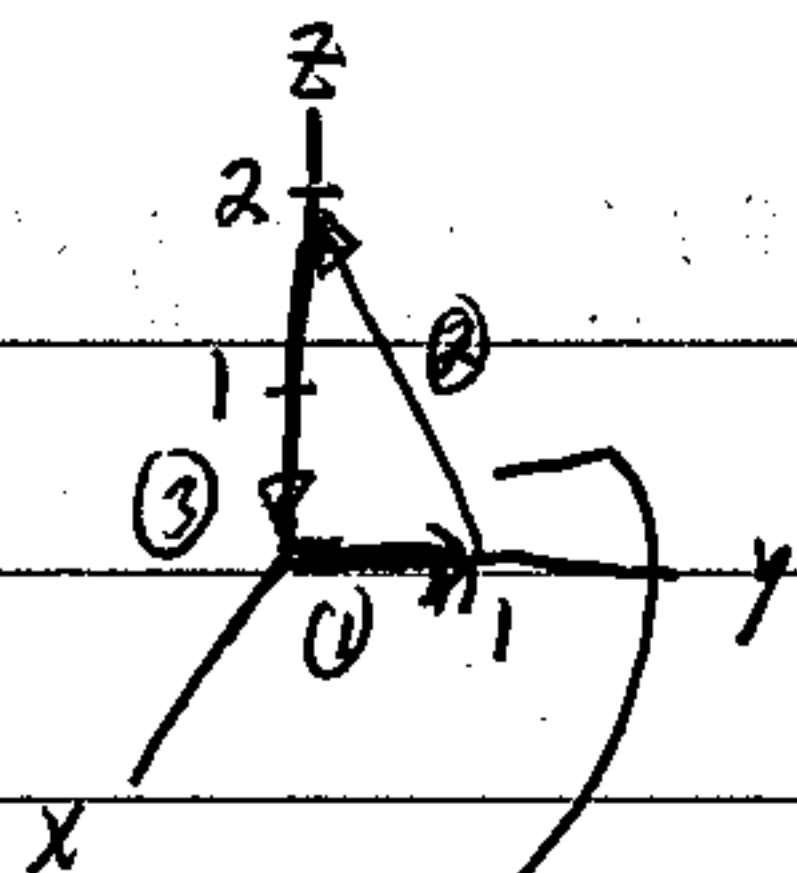
$-ar^2 \int_0^{2\pi} \frac{1 - \cos(2\theta)}{2} d\theta + br^2 \int_0^{2\pi} \frac{1 + \cos(2\theta)}{2} d\theta = -ar^2 \left[\frac{\theta}{2} - \frac{\sin(2\theta)}{4} \right]_0^{2\pi} + br^2 \left[\frac{\theta}{2} + \frac{\sin(2\theta)}{4} \right]_0^{2\pi}$

$\vec{v} = -ar^2 \pi$

$\oint_P \vec{v} \cdot d\vec{l} = \vec{v}_x + \vec{v}_y = -ar^2 \pi + br^2 \pi$ // $r = R \Rightarrow (b-a)R^2 \pi$ ✓

$$1.56. \int_S (\nabla \times \vec{v}) \cdot d\vec{a} = \oint_P \vec{v} \cdot d\vec{l} ; \vec{v} = 6x\hat{i} + yz^2\hat{j} + (3y+2z)\hat{k}$$

$$\oint_P \vec{v} \cdot d\vec{l} = \int_C \vec{v} \cdot d\vec{l} + \int_C \vec{v} \cdot d\vec{l} + \int_C \vec{v} \cdot d\vec{l}$$



$$① d\vec{l} = +dy\hat{j} \Rightarrow \vec{v} \cdot d\vec{l} = yz^2 dy \Rightarrow \text{if } y=0 \text{ then } \vec{v} \cdot d\vec{l} = 0 \Rightarrow \int \vec{v} \cdot d\vec{l} = 0$$

$$② \text{ // parametrization // } d\vec{l} = dy\hat{j} + dz\hat{k} \Rightarrow \vec{v} \cdot d\vec{l} = yz^2 dy + (3y+2z) dz$$

$$\text{ // } z = 2-2y, dz = -2dy$$

$$\vec{v} \cdot d\vec{l} = y(2-2y)^2 dy + (3y+2(2-2y))(-2dy) = y(4-8y+4y^2)dy + (-2y-4)dy = 4y^3 - 8y^2 - 2y - 4 dy$$

$$\int \vec{v} \cdot d\vec{l} = \int_0^1 (4y^3 - 8y^2 - 2y - 4) dy = \left[y^4 - \frac{8y^3}{3} - y^2 - 4y \right]_0^1 = \frac{14}{3}$$

$$③ d\vec{l} = dy\hat{k} \Rightarrow \vec{v} \cdot d\vec{l} = (3y+2z) dz \text{ // } y=2 \text{ // } \vec{v} \cdot d\vec{l} = 2 dz$$

$$-\int_2^0 2 dz = -\left[\frac{2z^2}{2} \right]_2^0 = -2$$

$$\oint_P \vec{v} \cdot d\vec{l} = 0 + \frac{14}{3} - 2 = \frac{8}{3} \checkmark$$

$$\nabla \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 6x & yz^2 & 3y+2z \end{vmatrix} = \hat{i}(3-2yz) - \hat{j}(0) + \hat{k}(0) \Rightarrow \nabla \times \vec{v} = (3-2yz)\hat{i}$$

$$\int (\nabla \times \vec{v}) \cdot d\vec{a} = \int \int (3-2yz) dy dz \Rightarrow \int_0^2 dz \int_{-1/2}^{1/2} (3-yz) dy \Rightarrow \int_0^2 dz \left[3y - \frac{1}{2}yz^2 \right]_{-1/2}^{1/2} = \int_0^2 dz \left[3(1-\frac{1}{2}z) - z(1-\frac{1}{2}z)^2 \right]$$

$$= \int_0^2 dz \left[3 - \frac{3}{2}z - z(1-z+\frac{1}{4}z^2) \right] = \int_0^2 dz \left[3 - \frac{3}{2}z - z + z^2 + \frac{1}{4}z^3 \right] = \int_0^2 \left[3 - \frac{5}{2}z + z^2 + \frac{1}{4}z^3 \right] dz$$

$$= \left[3z - \frac{5}{4}z^2 + \frac{1}{3}z^3 + \frac{1}{16}z^4 \right]_0^2 = \left[6 - 5 + \frac{8}{3} + 1 \right] = \frac{8}{3} \checkmark$$

1.57