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//
          Filippo Ambroglini : filippo.ambroglini@pg.infn.it
//
#include "TrackerConstructionConfig4.hh"
#include "G4NistManager.hh"
#include "HEPDSWMaterial.hh"
#include "G4Box.hh"
#include "G4SubtractionSolid.hh"
#include "G4UnionSolid.hh"
#include "G4LogicalVolume.hh"
#include "G4PVPlacement.hh"
#include "G4PVReplica.hh"
#include "G4GeometryManager.hh"
#include "G4PhysicalVolumeStore.hh"
#include "G4LogicalVolumeStore.hh"
#include "G4SolidStore.hh"
#include "G4VisAttributes.hh"
#include "G4SDManager.hh"
#include "TrackerSD.hh"
#include "G4UImanager.hh"
#include "G4UnitsTable.hh"
#include "G4PhysicalConstants.hh"
#include "G4SystemOfUnits.hh"
#include <iomanip>
TrackerConstructionConfig4::TrackerConstructionConfig4()
 :fSolidTracker(0),fSolidLayer(0),fSolidCFFrameHole(0),fSolidCFFrame(0),
  fSolidPoronFrameHole(0),fSolidPoronFrame(0),fSolidSiliconPlate(0),fSolidSilic
  fSolidLadderBox(0),fSolidLadder(0),fSolidKaptonS(0),fSolidKaptonK(0),fSolidHy
brid(0),
  fSolidHeatSink(0),fSolidRingK(0),fSolidRingS(0),
  fLogicTracker(0),fLogicLayer(0),fLogicCFFrame(0),fLogicPoronFrame(0),fLogicSi
liconPlateP(0),fLogicSiliconPlateM(0),
  fLogicSiliconSensor(0), fLogicLadderBox(0), fLogicLadder(0), fLogicKaptonS(0), fL
ogicKaptonK(0),
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   fLogicHybrid(0),fLogicHeatSink(0),fLogicRingK(0),fLogicRingS(0),
   fPhysiTracker(0),fPhysiLayer(0),fPhysiCFFrame(0),fPhysiPoronFrame(0),fPhysiLa
dderBox(0),
   fPhysiLadder(0),fPhysiRingK(0),fPhysiKaptonK(0),fPhysiHybridK(0),fPhysiSilico
nPlateP(0),
  fPhysiSiliconSensorP(0),fPhysiSiliconPlateM(0),fPhysiSiliconSensorM(0),fPhysi
KaptonS(0),
 fPhysiHybridS(0),fPhysiRingS(0),fPhysiHeatSink(0)
 pMaterial = new HEPDSWMaterial();
 fLayerNumber = 2;
 fLadderNumber = 3;
 fTracker_X = 267.3*mm;
 fTracker_Y = 305.5*mm;
 fTracker Z = 20.0*mm;
 fLayer X = 267.3*mm;
 fLayer_Y = 305.5*mm;
 fLayer_Z = 10.0*mm;
 fCFFrame_X = 267.3*mm;
 fCFFrame_Y = 305.5*mm;
 fCFFrame_Z = 10.0*mm;
  fCFMiddleFrameHole_X = 255.3*mm;
  fCFMiddleFrameHole_Y = 305.5*mm;
 fCFMiddleFrameHole_Z = 6.3*mm;
  fCFFrameHole1_X = 247.9*mm;
 fCFFrameHole1 Y = 60.5*mm;
 fCFFrameHole1_Z = 6.0*mm;
 fCFFrameHole2_X = 72.6*mm;
 fCFFrameHole2 Y = 215.0*mm;
 fCFFrameHole2_Z = 11.0*mm;
 fPoronFrame X = 255.3*mm;
 fPoronFrame_Y = 299.5*mm;
 fPoronFrame Z = 6.3*mm;
 fPoronMiddleFrameHole_X = 247.3*mm;
 fPoronMiddleFrameHole Y = 299.5*mm;
 fPoronMiddleFrameHole_Z = 2.8*mm;
 fPoronFrameHole1 X = 247.9 * mm;
 fPoronFrameHole1 Y = 66.5*mm;
 fPoronFrameHole1_Z = 7.0*mm;
 fPoronFrameHole2 X = 72.6*mm;
 fPoronFrameHole2_Y = 224.3*mm;
 fPoronFrameHole2_Z = 7.0*mm;
  fSiSens_X = 77.606*mm;
 fSiSens_Y = 109.65*mm;
  fSiSens_Z = 0.3*mm;
 fSiActiveSens_X = 71.606*mm;
  fSiActiveSens_Y = 105.85*mm;
 fSiActiveSens_Z = 0.3*mm;
  fLadderBox_X = 246.9*mm;
  fLadderBox_Y = 295.5*mm;
  fLadderBox Z = 2.8*mm;
  fLadderBoxEnd_X = 246.9*mm;
 fLadderBoxEnd\ Y = 60.5*mm;
  fLadderBoxEnd_Z = 4.41*mm;
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 fLadder X = 82.3*mm;
 fLadder_Y = 295.5*mm;
 fLadder Z = 2.8*mm;
 fLadderEnd_X = 82.3*mm;
 fLadderEnd Y = 60.5*mm;
 fLadderEnd Z = 4.41*mm;
 fKaptonS X = 72.0*mm;
 fKaptonS Y = 9.01*mm;
 fKaptonS Z = 2.4*mm;
 fKaptonK X = 68.7*mm;
 fKaptonK_Y = 222.69*mm;
 fKaptonK_Z = 0.1*mm;
  fHybrid X = 76*mm;
 fHybrid Y = 60*mm;
 fHybrid_Z = 0.5*mm;
 fHeatSink_X = 78.3*mm;
 fHeatSink_Y = 60*mm;
 fHeatSink_Z = 2.32*mm;
 fRingK X = 82.3*mm;
 fRingK_Y = 295.5*mm;
 fRingK_Z = 2.8*mm;
  fRingKHole1_X = 78.3*mm;
 fRingKHole1_Y = 295.5*mm;
 fRingKHole1 Z = 2*mm;
 fRingKHole2_X = 72.6*mm;
 fRingKHole2_Y = 215*mm;
 fRingKHole2 Z = 2.9*mm;
 fRingKHole3 X = 72.6*mm;
 fRingKHole3 Y = 63.5*mm;
 fRingKHole3_Z = 2.9*mm;
  fRingS_X = 78*mm;
 fRingS_Y = 221*mm;
 fRingS_Z = 1*mm;
  fRingSHole_X = 72.6*mm;
 fRingSHole_Y = 215*mm;
 fRingSHole_Z = 1.5*mm;
 ComputeObjectsPositioning();
 siliconMaterial = "Silicon";
 cfiberMaterial = "CarbonFiber";
 kaptonMaterial = "Kapton";
 poronMaterial = "Poron";
TrackerConstructionConfig4::~TrackerConstructionConfig4()
 if (pMaterial) delete pMaterial;
void TrackerConstructionConfig4::ComputeObjectsPositioning(){
 transCFFrameHole0 Y =-6*mm;
 transCFFrameHoleO_Z =-0.15*mm;
 transCFFrameHole1_Y =-(fCFFrame_Y/2.-fCFFrameHole1_Y/2.);
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transCFFrameHole1 Z =-3*mm;
transCFFrameHole2_X =82.5*mm;
transCFFrameHole2_Y =fCFFrame_Y/2.-fCFFrameHole2_Y/2.-22*mm;
transCFFrameHole3 X =0;
transCFFrameHole3_Y =fCFFrame_Y/2.-fCFFrameHole2_Y/2.-22*mm;
transCFFrameHole4_X =-82.5*mm;
transCFFrameHole4 Y =fCFFrame Y/2.-fCFFrameHole2 Y/2.-22*mm;
transCFFrameHole5_X =82.5*mm;
transCFFrameHole5_Y =fCFFrame_Y/2.-fCFFrameHole2_Y/2.-248*mm;
transCFFrameHole6 X =0;
transCFFrameHole6_Y =fCFFrame_Y/2.-fCFFrameHole2_Y/2.-248*mm;
transCFFrameHole7_X =-82.5*mm;
transCFFrameHole7_Y =fCFFrame_Y/2.-fCFFrameHole2_Y/2.-248*mm;
transPoronFrameHole0_Y =-4*mm;
transPoronFrameHole0_Z =-0.61*mm;
transPoronFrameHole1_Y =-(fPoronFrame_Y/2.-fPoronFrameHole1_Y/2.);
transPoronFrameHole2_X =82.5*mm;
transPoronFrameHole2_Y =fPoronFrame_Y/2.-fPoronFrameHole2_Y/2.-6.7*mm;
transPoronFrameHole3_X =0;
transPoronFrameHole3_Y =fPoronFrame_Y/2.-fPoronFrameHole2_Y/2.-6.7*mm;
transPoronFrameHole4_X =-82.5*mm;
transPoronFrameHole4_Y =fPoronFrame_Y/2.-fPoronFrameHole2_Y/2.-6.7*mm;;
transRingKHole1_Y = -9*mm;
transRingKHole1_Z = fRingK_Z/2.-fRingKHole1_Z/2.-1*mm;
transRingKHole2_Y = fRingK_Y/2.-fRingKHole2_Y/2.-12*mm;
transRingKHole3_Y = fRingK_Y/2.-fRingKHole3_Y/2.-233*mm;
transRingSHole_Y = fRingS_Y/2.-fRingSHole_Y/2.-3*mm;
transLadderBox Y = -(fLadderBox Y/2.-fLadderBoxEnd Y/2.);
transLadderBox_Z = fLadderBox_Z/2.-fLadderBoxEnd_Z/2.;
transLadder_Y = -(fLadder_Y/2.-fLadderEnd_Y/2.);
transLadder Z = fLadder Z/2.-fLadderEnd Z/2.;
transKaptonS_Y = 0.1*mm;
transKaptonS Z = -0.1*mm;
fPhysiTracker_X = 0;
fPhysiTracker_Y = -23.55;
fPhysiTracker_Z = 353.2*mm;
fPhysiPoronFrame_X = 0;
fPhysiPoronFrame_Y = -(fCFFrame_Y/2.-fPoronFrame_Y/2.);
fPhysiPoronFrame_Z = -0.15*mm;
fPhysiLadderBox_X = 0;
fPhysiLadderBox_Y = -(fCFFrame_Y/2.-fLadderBox_Y/2.);
fPhysiLadderBox_Z = -0.76*mm;
fPhysiRingK_X = 0;
fPhysiRingK_Y = 0;
fPhysiRingK_Z = 0;
fPhysiKaptonK_X = 0;
fPhysiKaptonK_Y = fLadder_Y/2.-fKaptonK_Y/2.-12.71*mm;
fPhysiKaptonK_Z = fLadder_Z/2.-fKaptonK_Z/2.-1.09*mm;
fPhysiHybridK_X = 0;
fPhysiHybridK_Y = -(fLadder_Y/2.-fHybrid_Y/2.);
fPhysiHybridK_Z = 0.06*mm;
fPhysiSiliconPlateP_X = 0;
fPhysiSiliconPlateP_Y = fLadder_Y/2.-fSiSens_Y/2.-9.5*mm;
fPhysiSiliconPlateP_Z = fLadder_Z/2.-fSiSens_Z/2.-1.24*mm;
fPhysiSiliconSensorP_X = 0;
fPhysiSiliconSensorP_Y = fSiSens_Y/2.-fSiActiveSens_Y/2.-3*mm;
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                      new G4SubtractionSolid("CFFrame4",
                                               new G4SubtractionSolid("CFFrame3",
                                                                      new G4Subt.ra
ctionSolid("CFFrame2",
   new G4SubtractionSolid("CFFrame1",
                           new G4Box("CFFrameBox",fCFFrame X/2.,fCFFrame Y/2.,fCF
Frame \mathbb{Z}/2.),
                           new G4Box("CFMiddleFrameHole",fCFMiddleFrameHole X/2.,fC
FMiddleFrameHole Y/2.,fCFMiddleFrameHole Z/2.),
                           myRot, transCFFrameHole0),
   new G4Box("CFBottomFrameHole",fCFFrameHole1 X/2.,fCFFrameHole1 Y/2.,fCFFrameHol
e1 Z/2.),
   myRot, transCFFrameHole1),
                                                                       fSolidCFFram
eHole, myRot, transCFFrameHole2),
                                               fSolidCFFrameHole, myRot, transCFFram
eHole3),
                       fSolidCFFrameHole, myRot, transCFFrameHole4),
       fSolidCFFrameHole, myRot, transCFFrameHole5),
                                                                  fSolidCFFrameHol
e, myRot, transCFFrameHole6),
                                          fSolidCFFrameHole, myRot, transCFFrameHol
e7);
  G4ThreeVector transPoronFrameHole0(0,transPoronFrameHole0_Y,transPoronFrameHol
  G4ThreeVector transPoronFrameHole1(0,transPoronFrameHole1 Y,0);
  G4ThreeVector transPoronFrameHole2(transPoronFrameHole2 X.transPoronFrameHole2)
  G4ThreeVector transPoronFrameHole3(transPoronFrameHole3 X.transPoronFrameHole3
 Y,0);
  G4ThreeVector transPoronFrameHole4(transPoronFrameHole4_X,transPoronFrameHole4
 Y,0);
  fSolidPoronFrameHole = new G4Box("fSolidPoronFrameHole",fPoronFrameHole2_X/2.,fPor
onFrameHole2_Y/2.,fPoronFrameHole2_Z/2.);
  fSolidPoronFrame = new G4SubtractionSolid("fSolidPoronFrame",
                                             new G4SubtractionSolid("PoronFrame4",
                                                                     new G4Subtrac
tionSolid("PoronFrame3",
  new G4SubtractionSolid("PoronFrame2".
                          new G4SubtractionSolid("PoronFrame1",
                                                  new G4Box("PoronFrameBox",fPoronF
rame_X/2.,fPoronFrame_Y/2.,fPoronFrame_Z/2.),
                                                  new G4Box("PoronMiddleFrameHole",fP
oronMiddleFrameHole_X/2.,fPoronMiddleFrameHole_Y/2.,fPoronMiddleFrameHole_Z/2.),
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                                                  myRot, transPoronFrameHole0),
                         new G4Box("PoronBottomFrameHole",fPoronFrameHole1 X/2.,fPo
ronFrameHole1_Y/2.,fPoronFrameHole1_Z/2.),
                         myRot, transPoronFrameHole1),
 fSolidPoronFrameHole, myRot, transPoronFrameHole2),
                                                                      fSolidPoronFr
ameHole, myRot, transPoronFrameHole3),
                                             fSolidPoronFrameHole, myRot, transPoro
nFrameHole4);
 fSolidSiliconPlate = new G4Box("fSolidSiliconPlate",fSiSens_X/2.,fSiSens_Y/2.,fSi
Sens_Z/2.);
 fSolidSiliconSensor = new G4Box("fSolidSiliconSensor",fSiActiveSens_X/2.,fSiActive
Sens Y/2., fSiActiveSens Z/2.);
 G4ThreeVector transLadderBox(0,transLadderBox_Y,transLadderBox_Z);
                       = new G4UnionSolid("fSolidLadderBox",
 fSolidLadderBox
                                           new G4Box("LadderBox",fLadderBox_X/2.,f
LadderBox_Y/2.,fLadderBox_Z/2.),
                                           new G4Box("LadderBoxEnd",fLadderBoxEnd_
X/2.,fLadderBoxEnd_Y/2.,fLadderBoxEnd_Z/2.),
                                           myRot,transLadderBox);
 G4ThreeVector transLadder(0,transLadder_Y,transLadder_Z);
 fSolidLadder
                      = new G4UnionSolid("fSolidLadder",
                                          new G4Box("Ladder",fLadder_X/2.,fLadder_
Y/2.,fLadder_Z/2.),
                                          new G4Box("LadderEnd",fLadderEnd X/2.,fL
adderEnd Y/2.,fLadderEnd Z/2.),
                                          myRot,transLadder);
 G4ThreeVector transKaptonS(0,transKaptonS Y,transKaptonS Z);
                       = new G4SubtractionSolid("fSolidKaptonS"
 fSolidKaptonS
                                                  new G4Box("fKaptonS1", fKaptonS X/
2., fKaptonS_Y/2., fKaptonS_Z/2.),
                                                 new G4Box("fKaptonS2",fKaptonS_X/
2.+3*mm, fKaptonS_Y/2., fKaptonS_Z/2.),
                                                  myRot, transKaptonS);
 fSolidKaptonK
                       = new G4Box("fSolidKaptonK",fKaptonK_X/2.,fKaptonK_Y/2.,fKa
ptonK Z/2.);
 fSolidHybrid
                       = new G4Box("fSolidHybrid",fHybrid_X/2.,fHybrid_Y/2.,fHybrid
_Z/2.);
 fSolidHeatSink
                       = new G4Box("fSolidHeatSink",fHeatSink_X/2.,fHeatSink_Y/2.,f
HeatSink_Z/2.);
 G4ThreeVector transRingKHole1(0,transRingKHole1_Y,transRingKHole1_Z);
 G4ThreeVector transRingKHole2(0,transRingKHole2_Y,0);
 G4ThreeVector transRingKHole3(0,transRingKHole3_Y,0);
 fSolidRingK = new G4SubtractionSolid("fSolidRingK",
                                        new G4SubtractionSolid("RingKStep2",
                                                                new G4SubtractionS
olid("RingKStep1",
     new G4Box("RingKBlock",fRingK_X/2.,fRingK_Y/2.,fRingK_Z/2.),
     new G4Box("RingKHole1",fRingKHole1_X/2.,fRingKHole1_Y/2.,fRingKHole1_Z/2.),
     myRot, transRingKHole1),
                                                                new G4Box("RingKHol
e2", fRingKHole2_X/2., fRingKHole2_Y/2., fRingKHole2_Z/2.),
                                                                myRot, transRingKHo
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le2),
                                        new G4Box("RingKHole3",fRingKHole3_X/2.,fR
ingKHole3 Y/2., fRingKHole3 Z/2.),
                                         myRot,transRingKHole3);
  G4ThreeVector transRingSHole(0,transRingSHole Y,0);
  fSolidRingS = new G4SubtractionSolid("fSolidRingS"
                                        new G4Box("RingSBlock",fRingS_X/2.,fRingS_
Y/2.,fRingS_Z/2.),
                                        new G4Box("RingSHole",fRingSHole_X/2.,fRin
gSHole Y/2., fRingSHole Z/2.),
                                        myRot,transRingSHole);
                       = new G4LogicalVolume(fSolidTracker, vacuum, "fLogicTracker");
  fLogicTracker
  fLogicLayer
                       = new G4LogicalVolume(fSolidLayer, vacuum, "fLogicLayer");
                       = new G4LogicalVolume(fSolidCFFrame,cfMat,"fLogicCFFrame");
  fLogicCFFrame
  fLogicPoronFrame
                       = new G4LogicalVolume(fSolidPoronFrame,poronMat,"fLogicPoron
Frame ");
  fLogicSiliconPlateP = new G4LogicalVolume(fSolidSiliconPlate,silMat,"fLogicSilico
nPlateP");
 fLogicSiliconPlateM = new G4LogicalVolume(fSolidSiliconPlate,silMat,"fLogicSilico
nPlateM");
  fLogicSiliconSensor = new G4LogicalVolume(fSolidSiliconSensor, silMat, "fLogicSilic
onSensor");
  fLogicLadderBox
                       = new G4LogicalVolume(fSolidLadderBox, vacuum, "fLogicLadderBox
                       = new G4LogicalVolume(fSolidLadder,vacuum, "fLogicLadder");
  fLogicLadder
  fLogicKaptonS
                       = new G4LogicalVolume(fSolidKaptonS, kapMat, "fLogicKaptonS");
  fLogicKaptonK
                       = new G4LogicalVolume(fSolidKaptonK, kapMat, "fLogicKaptonK");
                       = new G4LogicalVolume(fSolidHybrid,fr4Mat, "fLogicHybrid");
  fLogicHybrid
  fLogicHeatSink
                       = new G4LogicalVolume(fSolidHeatSink,copperMat,"fLogicHeatSin
k");
                       = new G4LogicalVolume(fSolidRingK,cfMat,"fLogicRingK");
  fLogicRingK
  fLogicRingS
                       = new G4LogicalVolume(fSolidRingS,cfMat, "fLogicRingS");
  fLogicSiliconSensor->SetSensitiveDetector(tkSD);
  G4RotationMatrix * rotTracker = new G4RotationMatrix;
  rotTracker->rotateZ(180*deg);
  rotTracker->rotateX(180*deg);
  fPhysiTracker = new G4PVPlacement(rotTracker,
                                     G4ThreeVector(fPhysiTracker_X,fPhysiTracker_
Y,fPhysiTracker_Z),
                                      "Tracker",
                                      fLogicTracker.
                                     motherVolume,
                                     false, 0, true);
  fPhysiLayer = new G4PVReplica("Layer",
                                 fLogicLayer,
                                 fPhysiTracker,
                                 kZAxis,
                                 fLayerNumber,
                                 fLayer_Z);
  fPhysiCFFrame = new G4PVPlacement(0,
                                      G4ThreeVector(0,0,0),
                                      "CFFrame",
                                      fLogicCFFrame,
                                      fPhysiLayer,
                                     false,0,true);
  fPhysiPoronFrame = new G4PVPlacement(0,
                                         G4ThreeVector(fPhysiPoronFrame_X,fPhysiPo
ronFrame_Y,fPhysiPoronFrame_Z),
                                         "PoronFrame",
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                                         fLogicPoronFrame
                                         fPhysiLayer,
                                        false, 0, true);
 fPhysiLadderBox = new G4PVPlacement(0
                                        G4ThreeVector(fPhysiLadderBox_X,fPhysiLadd
erBox Y,fPhysiLadderBox Z),
                                        "LadderBox",
                                        fLogicLadderBox,
                                        fPhysiLayer,
                                        false, 0, true);
 fPhysiLadder = new G4PVReplica("Ladder",
                                  fLogicLadder,
                                  fPhysiLadderBox,
                                  kXAxis,
                                  fLadderNumber,
                                  fLadder X);
 fPhysiRingK = new G4PVPlacement(0,
                                   G4ThreeVector(fPhysiRingK_X,fPhysiRingK_Y,fPhy
siRingK Z),
                                   fLogicRingK,
                                   fPhysiLadder,
                                   false, 0, true);
 fPhysiKaptonK = new G4PVPlacement(0,
                                     G4ThreeVector(fPhysiKaptonK_X,fPhysiKaptonK_
Y,fPhysiKaptonK Z),
                                      "KaptonK",
                                     fLogicKaptonK,
                                     fPhysiLadder,
                                     false, 0, true);
 fPhysiHybridK = new G4PVPlacement(0,
                                     G4ThreeVector(fPhysiHybridK_X,fPhysiHybridK_
Y.fPhysiHybridK Z).
                                      "HybridK"
                                     fLogicHybrid,
                                     fPhysiLadder.
                                     false, 0, true);
 fPhysiSiliconPlateP = new G4PVPlacement(0,
                                            G4ThreeVector(fPhysiSiliconPlateP_X,fP
hysiSiliconPlateP_Y,fPhysiSiliconPlateP_Z)
                                            "SiliconPlateP",
                                            fLogicSiliconPlateP,
                                            fPhysiLadder.
                                            false, 0, true);
 fPhysiSiliconSensorP = new G4PVPlacement(0,
                                             G4ThreeVector(fPhysiSiliconSensorP_X,
fPhysiSiliconSensorP_Y,fPhysiSiliconSensorP_Z),
                                            "SiliconSensorP",
                                            fLogicSiliconSensor,
                                            fPhysiSiliconPlateP,
                                            false,0,true);
 fPhysiSiliconPlateM = new G4PVPlacement(0,
                                            G4ThreeVector(fPhysiSiliconPlateM_X,fP
hysiSiliconPlateM_Y,fPhysiSiliconPlateM_Z)
                                            "SiliconPlateM",
                                            fLogicSiliconPlateM,
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                                           fPhysiLadder,
                                           false,0,true);
 fPhysiSiliconSensorM = new G4PVPlacement(0,
                                            G4ThreeVector(fPhysiSiliconSensorM X,
fPhysiSiliconSensorM Y,fPhysiSiliconSensorM Z),
                                           "SiliconSensorM",
                                           fLogicSiliconSensor,
                                           fPhysiSiliconPlateM,
                                           false, 0, true);
 fPhysiKaptonS = new G4PVPlacement(0,
                                     G4ThreeVector(fPhysiKaptonS_X,fPhysiKaptonS_
Y, fPhysiKaptonS Z),
                                     "KaptonS",
                                     fLogicKaptonS,
                                     fPhysiLadder,
                                     false, 0, true);
 fPhysiHybridS = new G4PVPlacement(0,
                                     G4ThreeVector(fPhysiHybridS_X,fPhysiHybridS_
Y,fPhysiHybridS_Z),
                                     "HybridS",
                                     fLogicHybrid,
                                     fPhysiLadder,
                                     false, 0, true);
 fPhysiHeatSink = new G4PVPlacement(0,
                                     G4ThreeVector(fPhysiHeatSink_X,fPhysiHeatSin
k Y,fPhysiHeatSink Z),
                                     "HeatSink",
                                     fLogicHeatSink,
                                     fPhysiLadder,
                                     false, 0, true);
 fPhysiRingS = new G4PVPlacement(0.
                                  G4ThreeVector(fPhysiRingS_X,fPhysiRingS_Y,fPhy
siRingS_Z),
                                   "RingS"
                                  fLogicRingS,
                                  fPhysiLadder,
                                  false, 0, true);
  //Visualization Attribute
 G4VisAttributes* attBlue = new G4VisAttributes(G4Colour::Blue());
 attBlue->SetVisibility(true);
 attBlue->SetForceAuxEdgeVisible(true);
 fLogicSiliconPlateP->SetVisAttributes(attBlue);
 fLogicSiliconPlateM->SetVisAttributes(attBlue);
 G4VisAttributes* attGray = new G4VisAttributes(G4Colour::Gray());
 attGray->SetVisibility(true);
 attGray->SetForceAuxEdgeVisible(true);
 fLogicSiliconSensor->SetVisAttributes(attGray);
 G4VisAttributes* attYellow = new G4VisAttributes(G4Colour::Yellow());
 attYellow->SetVisibility(true);
 attYellow->SetForceAuxEdgeVisible(true);
 fLogicPoronFrame->SetVisAttributes(attYellow);
 G4VisAttributes* attMagenta = new G4VisAttributes(G4Colour::Magenta());
 attMagenta->SetVisibility(true);
 attMagenta->SetForceAuxEdgeVisible(true);
 fLogicKaptonS->SetVisAttributes(attMagenta);
```

TrackerConstructionConfig4.cc Jan 09, 15 16:56 Page 11/11 fLogicKaptonK->SetVisAttributes(attMagenta); G4VisAttributes* attBrown = **new** G4VisAttributes(G4Colour::Brown()); attBrown->SetVisibility(true); attBrown->SetForceAuxEdgeVisible(true); fLogicCFFrame->SetVisAttributes(attBrown); fLogicRingK->SetVisAttributes(attBrown); fLogicRingS->SetVisAttributes(attBrown); G4VisAttributes* attGreen = **new** G4VisAttributes(G4Colour::Green()); attGreen->SetVisibility(true); attGreen->SetForceAuxEdgeVisible(true); fLogicHybrid->SetVisAttributes(attGreen); G4VisAttributes* attRed = **new** G4VisAttributes(G4Colour::Red()); attRed->SetVisibility(true); attRed->SetForceAuxEdgeVisible(true); fLogicHybrid->SetVisAttributes(attRed); G4VisAttributes* attBlack = **new** G4VisAttributes(G4Colour::Black()); attBlack->SetVisibility(true); attBlack->SetForceAuxEdgeVisible(true); fLogicHeatSink->SetVisAttributes(attBlack); G4VisAttributes * attInvisible = new G4VisAttributes(); attInvisible->SetVisibility(false); attInvisible->SetForceAuxEdgeVisible(false); fLogicTracker->SetVisAttributes(attInvisible); fLogicLayer->SetVisAttributes(attInvisible); fLogicLadderBox->SetVisAttributes(attInvisible); fLogicLadder->SetVisAttributes(attInvisible);