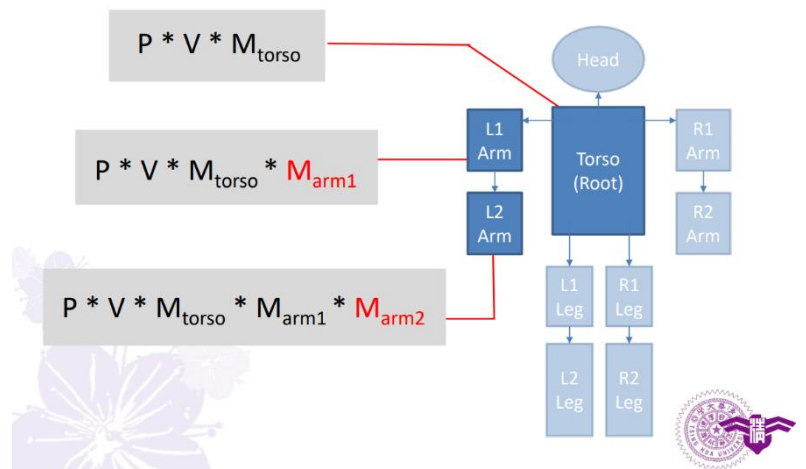


Screenshot



The relationship stack of robot body parts



Functions

Robot move: W A S D

Camera move: cursor move along x-axis

Zoom in/out: mouse wheel

Pause: SPACE

IDE: visual studio 2019