ARTIFICIAL INTELLIGENCE ASSIGNMENT 01 (1) Rationality refers to the ability of an agent to make decisions that optimize its goals or objectives given the available information and resources - OBJECTIVE - DRIVEN: Rational agents consistently select actions are likely to achieve their objections based on their understanding of the environment and consequences their actions MAXIMIZING UTILITY: Selecting actions that maximize expected utility or minimize expected asts, aiming to achieve the best possible outcome given the circumstances - ENVIRONMENT INTERACTION: Guides agents to interact with their envisonments by analyzing available information psediction outcomes, and selecting actions that lead to desirable results. Eq: In self-driving cass, rationality means ravigating throad toaffic while minimizing sisk of accidents and reaching the dostination efficiently - DECISION_MAKING PROCESS - Rotional agents consider their beliefs about the world, their goals, potential consequences of their actions when traking decisions: - OUTCOME- ORIENTED: Rationality focuses on achieving clesisable outcomes in various domains, including physical navigation, strategic decision-making and personalized recromendation (2) An envisonment is the context in which an agent operates, consisting of everything outside the agent that can potentially affect its behaviour -Some envisonments provide agents with complete information about their state

- Deterministic environments have predictable outcomes for given actions, while stochastic environments involve randomness or uncertainty.
- In episodic envisonments, each episode is independent of others, while in sequential envisonments, actions influence future states
- Static environments remain unchanged while the agent is acting, whereas dynamic environments may change during execution
- -Environments can have discrete states and actions or continuous
- The characteristics of the envisonment heavily influence the design of agents, affecting their perception, decision-making and learning mechanisms.
- -Agents must adapt their strategies and behaviours based on the nature of the environment to achieve their objectives effectively.
 - Eg: Chess: The game environment is fully observable, deterministic, sequential, and discrete: Agents like chesplaying programs utilize search algorithms to explore possible future states and make optimal moves:
 - Uncestainty CHALLENGES:
 - (1) Uncertainty Dealing with incomplete or uncertain importantion
 - (a) Complexity-Navigating complex envisonments with numerous possible states and actions.
 - (3) Dynamics Adopting to changes in the envisonment over time
 - (A) Trade-offs-Balancing exploration (toying new actions) with exploitation (using known actions).
- (3) STRUCTURE OF INTELLIGENT AGENTS :
 - Perception Receives in puts from the environment through sensors
 - -Decision-Making: Processes information to select actions
- N Action: Executes actions to affect the envisonment.
 - knowledge Base: Stores impormation for decision-making
 - -Goal: Objectives or tasks the agent aims to achieve
 - TYPES OF AGENTS:
 - Simple reflex agents: Act based solely on current percept, mapping directly to actions:
- w Model-based reflex agents: Maintain internal state to track aspects of the world that are not directly observable

-Goal-Based agents: Plan actions to achieve specific goals, considering future states -Utility-based agents: Figurate actions based on utility functions to maximize outcomes - Learning agents: Improve performance over time through leasning from experience. INTERACTION OF COMPONENTS - Perception gathers information from the environment -knowledge base stores information used for decisions -Decision-making processes information to select appropriate -Actions are executed to affect the envisonment, leading to new perceptions Eg: Simple Reflex Agents: Automated vaceuum deaners that change direction when encountering obstacles (A) ROLF OF PROBLEM-SOLVING AGENTS: -Am to find solutions to given tasks or digether -Analyse problems, formulate them into a suitable representation, and search fire solutions using various FORMULATION OF PROBLEMS: -Proteens are typically formulated by defining the initial state, possible actions, transition model, gal test and - Famulation provides a startural sepsementation of the FOR EDUCATIONAL USE

PROCESS OF PROBLEM-SOLVING BY SEARCHING:

- -Analysis: Problem-solving agents analyze the given problem to understand its structure and requirements.
- -Formulation: They formulate the problem into a suitable representation, such as a state space or a graph.
- Seasch: Problem solving agents use rasious seasch algorithm to explose problem space and Aird solutions
- Evaluation: They evaluate potential solutions based on contesion such as optimality, completeness, and efficiency.
- Execution: Execute set of actions to achieve goal

METHODS USED FOR SEARCHING:

- -Unimborned search algorithms BFS, DFS
- -Informed seasch algorithms -A* seasch, Heusistic
- -Local seasch algorithms Hill Climbing, simulated annealing Adversarial seasch algorithms Minimax, alpha-beta pouning
- Eg: Route Planning: Finding the stratest path between two locations using algorithms like Dijkstocis or A* search