

Data Analysis and Machine Learning: From Decision Trees to Forests and all that

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Decision trees, overarching aims

Decision trees are supervised learning algorithms used for both, classification and regression tasks.

The main idea of decision trees is to find those descriptive features which contain the most **information** regarding the target feature and then split the dataset along the values of these features such that the target feature values for the resulting underlying datasets are as pure as possible.

The descriptive features which reproduce best the target/output features are normally said to be the most informative ones. The process of finding the **most informative** feature is done until we accomplish a stopping criteria where we then finally end up in so called **leaf nodes**.

A decision tree is typically divided into a **root node**, the **interior nodes**, and the final **leaf nodes** or just **leaves**. These entities are then connected by so-called **branches**.

The leaf nodes contain the predictions we will make for new query instances presented to our trained model. This is possible since the model has learned the underlying structure of the training data and hence can, given some assumptions, make predictions about the target feature value (class) of unseen query instances.

A typical Decision Tree with its pertinent Jargon, Classification Problem

In the figure here we present a decision tree obtained from a classification problem

A typical Decision Tree with its pertinent Jargon, Regression Problem

In the figure we present a decision tree obtained from a simple regression problem

General Features

The overarching approach to decision trees is a top-down approach.

- A leaf provides the classification of a given instance.
- A node specifies a test of some attribute of the instance.
- A branch corresponds to a possible values of an attribute.
- An instance is classified by starting at the root node of the tree, testing the attribute specified by this node, then moving down the tree branch corresponding to the value of the attribute in the given example.

This process is then repeated for the subtree rooted at the new node.

How do we set it up?

In simplified terms, the process of training a decision tree and predicting the target features of query instances is as follows:

1. Present a dataset containing of a number of training instances characterized by a number of descriptive features and a target feature
2. Train the decision tree model by continuously splitting the target feature along the values of the descriptive features using a measure of information gain during the training process
3. Grow the tree until we accomplish a stopping criteria create leaf nodes which represent the *predictions* we want to make for new query instances
4. Show query instances to the tree and run down the tree until we arrive at leaf nodes

Then we are essentially done!

Decision trees and Regression

Building a tree, regression

There are mainly two steps

1. We split the predictor space (the set of possible values x_1, x_2, \dots, x_p) into J distinct and non-overlapping regions, R_1, R_2, \dots, R_J .

2. For every observation that falls into the region R_j , we make the same prediction, which is simply the mean of the response values for the training observations in R_j .

How do we construct the regions R_1, \dots, R_J ? In theory, the regions could have any shape. However, we choose to divide the predictor space into high-dimensional rectangles, or boxes, for simplicity and for ease of interpretation of the resulting predictive model. The goal is to find boxes R_1, \dots, R_J that minimize the MSE, given by

$$\sum_{j=1}^J \sum_{i \in R_j} (y_i - \bar{y}_{R_j})^2,$$

where \bar{y}_{R_j} is the mean response for the training observations within box j .

A top-down approach, recursive binary splitting

Unfortunately, it is computationally infeasible to consider every possible partition of the feature space into J boxes. The common strategy is to take a top-down approach

The approach is top-down because it begins at the top of the tree (all observations belong to a single region) and then successively splits the predictor space; each split is indicated via two new branches further down on the tree. It is greedy because at each step of the tree-building process, the best split is made at that particular step, rather than looking ahead and picking a split that will lead to a better tree in some future step.

Making a tree

In order to implement the recursive binary splitting we start by selecting the predictor x_j and a cutpoint s that splits the predictor space into two regions R_1 and R_2

$$\{X | x_j < s\},$$

and

$$\{X | x_j \geq s\},$$

so that we obtain the lowest MSE, that is

$$\sum_{i: x_i \in R_1} (y_i - \bar{y}_{R_1})^2 + \sum_{i: x_i \in R_2} (y_i - \bar{y}_{R_2})^2,$$

which we want to minimize by considering all predictors x_1, x_2, \dots, x_p . We consider also all possible values of s for each predictor. These values could be determined by randomly assigned numbers or by starting at the midpoint and then proceed till we find an optimal value.

For any j and s , we define the pair of half-planes where \bar{y}_{R_1} is the mean response for the training observations in $R_1(j, s)$, and \bar{y}_{R_2} is the mean response for the training observations in $R_2(j, s)$.

Finding the values of j and s that minimize the above equation can be done quite quickly, especially when the number of features p is not too large.

Next, we repeat the process, looking for the best predictor and best cutpoint in order to split the data further so as to minimize the MSE within each of the resulting regions. However, this time, instead of splitting the entire predictor space, we split one of the two previously identified regions. We now have three regions. Again, we look to split one of these three regions further, so as to minimize the MSE. The process continues until a stopping criterion is reached; for instance, we may continue until no region contains more than five observations.

Pruning the tree

The above procedure is rather straightforward, but leads often to overfitting and unnecessarily large and complicated trees. The basic idea is to grow a large tree T_0 and then prune it back in order to obtain a subtree. A smaller tree with fewer splits (fewer regions) can lead to smaller variance and better interpretation at the cost of a little more bias.

The so-called Cost complexity pruning algorithm gives us a way to do just this. Rather than considering every possible subtree, we consider a sequence of trees indexed by a nonnegative tuning parameter α .

Cost complexity pruning

For each value of α there corresponds a subtree $T \in T_0$ such that

$$\sum_{m=1}^{\bar{T}} \sum_{i: x_i \in R_m} (y_i - \bar{y}_{R_m})^2 + \alpha \bar{T},$$

is as small as possible. Here \bar{T} is the number of terminal nodes of the tree T , R_m is the rectangle (i.e. the subset of predictor space) corresponding to the m -th terminal node.

The tuning parameter α controls a trade-off between the subtree's complexity and its fit to the training data. When $\alpha = 0$, then the subtree T will simply equal T_0 , because then the above equation just measures the training error. However, as α increases, there is a price to pay for having a tree with many terminal nodes. The above equation will tend to be minimized for a smaller subtree.

It turns out that as we increase α from zero branches get pruned from the tree in a nested and predictable fashion, so obtaining the whole sequence of subtrees as a function of α is easy. We can select a value of α using a validation set or using cross-validation. We then return to the full data set and obtain the subtree corresponding to α .

Schematic Regression Procedure

Building a Regression Tree.

1. Use recursive binary splitting to grow a large tree on the training data, stopping only when each terminal node has fewer than some minimum number of observations.
2. Apply cost complexity pruning to the large tree in order to obtain a sequence of best subtrees, as a function of α .
3. Use for example K -fold cross-validation to choose α . Divide the training observations into K folds. For each $k = 1, 2, \dots, K$ we:
 - repeat steps 1 and 2 on all but the k -th fold of the training data.
 - Then we evaluate the mean squared prediction error on the data in the left-out k -th fold, as a function of α .
 - Finally we average the results for each value of α , and pick α to minimize the average error.
4. Return the subtree from Step 2 that corresponds to the chosen value of α .

A Classification Tree

A classification tree is very similar to a regression tree, except that it is used to predict a qualitative response rather than a quantitative one. Recall that for a regression tree, the predicted response for an observation is given by the mean response of the training observations that belong to the same terminal node. In contrast, for a classification tree, we predict that each observation belongs to the most commonly occurring class of training observations in the region to which it belongs. In interpreting the results of a classification tree, we are often interested not only in the class prediction corresponding to a particular terminal node region, but also in the class proportions among the training observations that fall into that region.

Growing a classification tree

The task of growing a classification tree is quite similar to the task of growing a regression tree. Just as in the regression setting, we use recursive binary splitting to grow a classification tree. However, in the classification setting, the MSE cannot be used as a criterion for making the binary splits. A natural alternative to MSE is the **classification error rate**. Since we plan to assign an observation in a given region to the most commonly occurring error rate class of training observations in that region, the classification error rate is simply the fraction of the training observations in that region that do not belong to the most common class.

When building a classification tree, either the Gini index or the entropy are typically used to evaluate the quality of a particular split, since these two approaches are more sensitive to node purity than is the classification error rate.

Classification tree, how to split nodes

If our targets are the outcome of a classification process that takes for example $k = 1, 2, \dots, K$ values, the only thing we need to think of is to set up the splitting criteria for each node.

We define a PDF p_{mk} that represents the number of observations of a class k in a region R_m with N_m observations. We represent this likelihood function in terms of the proportion $I(y_i = k)$ of observations of this class in the region R_m as

$$p_{mk} = \frac{1}{N_m} \sum_{x_i \in R_m} I(y_i = k).$$

We let p_{mk} represent the majority class of observations in region m . The three most common ways of splitting a node are given by

- Misclassification error

$$p_{mk} = \frac{1}{N_m} \sum_{x_i \in R_m} I(y_i \neq k) = 1 - p_{mk}.$$

- Gini index g

$$g = \sum_{k=1}^K p_{mk}(1 - p_{mk}).$$

- Information entropy or just entropy s

$$s = - \sum_{k=1}^K p_{mk} \log p_{mk}.$$

The CART (Classification and Regression Tree) algorithm

The above functions (gini, entropy and misclassification error) are important components of the so-called CART algorithm. We will discuss this algorithm first before we move on to the information gain algorithm ID3.

Entropy and the ID3 algorithm

ID3, learns decision trees by constructing them topdown, beginning with the question **which attribute should be tested at the root of the tree?**

1. Each instance attribute is evaluated using a statistical test to determine how well it alone classifies the training examples.

2. The best attribute is selected and used as the test at the root node of the tree.
3. A descendant of the root node is then created for each possible value of this attribute.
4. Training examples are sorted to the appropriate descendant node.
5. The entire process is then repeated using the training examples associated with each descendant node to select the best attribute to test at that point in the tree.
6. This forms a greedy search for an acceptable decision tree, in which the algorithm never backtracks to reconsider earlier choices.

The ID3 algorithm selects, which attribute to test at each node in the tree.

We would like to select the attribute that is most useful for classifying examples.

What is a good quantitative measure of the worth of an attribute?

Information gain measures how well a given attribute separates the training examples according to their target classification.

The ID3 algorithm uses this information gain measure to select among the candidate attributes at each step while growing the tree.

Implementing the ID3 Algorithm

more text to come here, material presented during lecture Friday Oct 25.

Cancer Data again now with Decision Trees

Another example, the moons again

Playing around with regions

Regression trees

Final regressor code

Pros and cons of trees, pros

- White box, easy to interpret model. Some people believe that decision trees more closely mirror human decision-making than do the regression and classification approaches discussed earlier (think of support vector machines)
- Trees are very easy to explain to people. In fact, they are even easier to explain than linear regression!
- No feature normalization needed

- Tree models can handle both continuous and categorical data (Classification and Regression Trees)
- Can model nonlinear relationships
- Can model interactions between the different descriptive features
- Trees can be displayed graphically, and are easily interpreted even by a non-expert (especially if they are small)

Disadvantages

- Unfortunately, trees generally do not have the same level of predictive accuracy as some of the other regression and classification approaches
- If continuous features are used the tree may become quite large and hence less interpretable
- Decision trees are prone to overfit the training data and hence do not well generalize the data if no stopping criteria or improvements like pruning, boosting or bagging are implemented
- Small changes in the data may lead to a completely different tree. This issue can be addressed by using ensemble methods like bagging, boosting or random forests
- Unbalanced datasets where some target feature values occur much more frequently than others may lead to biased trees since the frequently occurring feature values are preferred over the less frequently occurring ones.
- If the number of features is relatively large (high dimensional) and the number of instances is relatively low, the tree might overfit the data
- Features with many levels may be preferred over features with less levels since for them it is *more easy* to split the dataset such that the sub datasets only contain pure target feature values. This issue can be addressed by preferring for instance the information gain ratio as splitting criteria over information gain

However, by aggregating many decision trees, using methods like bagging, random forests, and boosting, the predictive performance of trees can be substantially improved.

Bagging

The **plain** decision trees suffer from high variance. This means that if we split the training data into two parts at random, and fit a decision tree to both halves, the results that we get could be quite different. In contrast, a procedure with low variance will yield similar results if applied repeatedly to distinct data sets;

linear regression tends to have low variance, if the ratio of n to p is moderately large.

Bootstrap aggregation, or just **bagging**, is a general-purpose procedure for reducing the variance of a statistical learning method.

Bagging typically results in improved accuracy over prediction using a single tree. Unfortunately, however, it can be difficult to interpret the resulting model. Recall that one of the advantages of decision trees is the attractive and easily interpreted diagram that results.

However, when we bag a large number of trees, it is no longer possible to represent the resulting statistical learning procedure using a single tree, and it is no longer clear which variables are most important to the procedure. Thus, bagging improves prediction accuracy at the expense of interpretability. Although the collection of bagged trees is much more difficult to interpret than a single tree, one can obtain an overall summary of the importance of each predictor using the MSE (for bagging regression trees) or the Gini index (for bagging classification trees). In the case of bagging regression trees, we can record the total amount that the MSE is decreased due to splits over a given predictor, averaged over all B possible trees. A large value indicates an important predictor. Similarly, in the context of bagging classification trees, we can add up the total amount that the Gini index is decreased by splits over a given predictor, averaged over all B trees.

Simple example, head or tail

Random forests

Random forests provide an improvement over bagged trees by way of a small tweak that decorrelates the trees.

As in bagging, we build a number of decision trees on bootstrapped training samples. But when building these decision trees, each time a split in a tree is considered, a random sample of m predictors is chosen as split candidates from the full set of p predictors. The split is allowed to use only one of those m predictors.

A fresh sample of m predictors is taken at each split, and typically we choose

$$m \approx \sqrt{p}.$$

In building a random forest, at each split in the tree, the algorithm is not even allowed to consider a majority of the available predictors.

The reason for this is rather clever. Suppose that there is one very strong predictor in the data set, along with a number of other moderately strong predictors. Then in the collection of bagged variable importance random forest trees, most or all of the trees will use this strong predictor in the top split. Consequently, all of the bagged trees will look quite similar to each other. Hence the predictions from the bagged trees will be highly correlated. Unfortunately, averaging many highly correlated quantities does not lead to as large of a reduction in variance as averaging many uncorrelated quantities. In particular,

this means that bagging will not lead to a substantial reduction in variance over a single tree in this setting.

A simple scikit-learn example

Please, not the moons again!

Bagging examples

Then random forests

Boosting and more

More material to come here.