

1. Derive an expression for the step response of a Continuous Time LTI system. Hint: Start with the general Convolution Integral formula and substitute $x(t) = u(t)$ and $s(t) = y(t)$

$$x(t) = u(t) = \begin{cases} 1 & \text{if } t > 0 \\ \frac{1}{2} & \text{if } t = 0 \\ 0 & \text{if } t < 0 \end{cases}$$

$$s(t) = y(t) = \int_{-\infty}^t h(\tau) d\tau$$

$$s(t) = \int_{-\infty}^{\infty} u(\tau) h(t - \tau) d\tau = \int_0^{\infty} h(t - \tau) d\tau = \int_{\infty}^0 h(t - \tau) d\tau = \int_{-\infty}^{\infty} h(\tau) d\tau$$

2. Given two Continuous Time functions defined as shown below.

$$x_1(t) = \begin{cases} -t + 1 & \text{for } 1 > t > 0 \\ 0, & \text{otherwise} \end{cases}$$

$$x_2(t) = u(t)$$

Compute the Convolution Integral $x_1(t) * x_2(t)$?

$$u(t) = \begin{cases} 1 & \text{if } t > 0 \\ \frac{1}{2} & \text{if } t = 0 \\ 0 & \text{if } t < 0 \end{cases}$$

$$x_1(t) * x_2(t) = \int_{-\infty}^{\infty} x_1(\tau) x_2(t - \tau) d\tau$$

$$x_1(t) * x_2(t) = \int_0^1 (-\tau + 1)(1) d\tau = \left[-\frac{\tau^2}{2} + \tau \right]_0^1 = \left[-\frac{1^2}{2} + 1 - 0 \right] = \frac{1}{2} \text{ when } t \geq 1$$

$$\left[\frac{-\tau^2}{2} + \tau \right] u(t) \text{ when } 1 > t > 0$$

$$0 \text{ when } 0 \geq t$$

$$y(t) = \begin{cases} \frac{1}{2} & \text{when } t \geq 1 \\ \frac{-t^2}{2} + t & \text{when } 1 > t > 0 \\ 0 & \text{when } 0 \geq t \end{cases}$$

3. Given two Discrete Time functions defined as shown below.

$$x[n] = (-2)^n u[n]$$

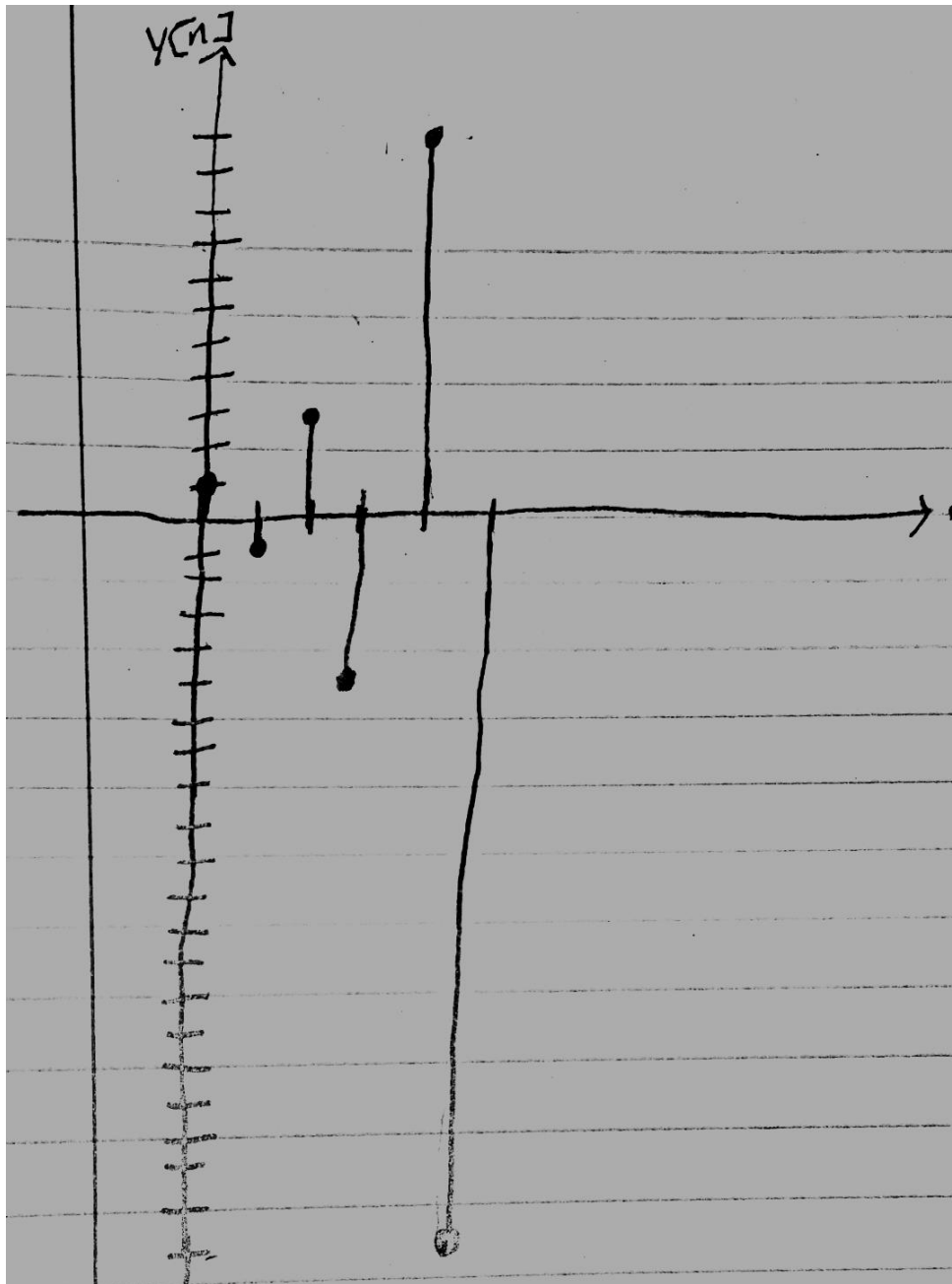
$$h[n] = u[n]$$

Compute the Convolution Sum $x[n] * h[n]$?

$$u[n] = \begin{cases} 1 & \text{if } n \geq 0 \\ 0 & \text{if } n < 0 \end{cases}$$

$$y[n] = \sum_{k=0}^{\infty} (-2)^k$$

$$y[0] = 1; y[1] = -1; y[2] = 3; y[3] = -5; y[4] = 11; y[5] = -21;$$



4. Change $h[n] = u[n - 3]$ in Problem 3 and re-compute the convolution sum.

$$u[n] = \begin{cases} 1 & \text{if } n \geq 3 \\ 0 & \text{if } n < 3 \end{cases}$$

$$y[n] = \sum_{k=0}^{n-3} (-2)^k$$

$$y[3] = 1; y[4] = -1; y[5] = 3; y[6] = -5; y[7] = 11; y[8] = -21;$$

5. We have established that $x[n] * \delta[n] = x[n]$. What will be the value of the convolution $x[n] * \delta[n - \beta]$? Explain your answer.

$$\delta[n] = \begin{cases} 1 & \text{if } n = \beta \\ 0 & \text{if } n \neq \beta \end{cases}$$

$$y[n] = x[n] * \delta[n - \beta] = \sum_{k=-\infty}^{\infty} x[k] \delta[n - \beta - k]$$

$$\boxed{x[n] * \delta[n - \beta] = x[n - \beta]}$$

6. Is an LTI system with $h[n] = u[n]$

$$u[n] = \begin{cases} 1 & \text{if } n \geq 0 \\ 0 & \text{if } n < 0 \end{cases}$$

- Causal? Yes, $h[n] = 0$ when $n < 0$
 - Stable? No, because $\sum_{k=-\infty}^{\infty} |u[k]| = \infty$. If it were less than ∞ , it would be stable.
 - Memoryless? No, because $u[n]$ is 1 or 0 when $n \neq 0$. If $h[n]$ were only 0 when $n \neq 0$, then it would be memoryless.
7. Consider two Discrete Time LTI systems—S1 and S2-- connected in cascade. The impulse response of the two systems are:

$$S1: h_1 = \delta[n + 1]$$

$$S2: h_2 = \delta[n - 3]$$

What is the resultant impulse response of the cascade system?

$$\delta[n] = \begin{cases} 1 & \text{if } n = 0 \\ 0 & \text{if } n \neq 0 \end{cases}$$

$$h_1 * h_2 = \delta[n + 1] * \delta[n - 3]$$

$$y[n] = \sum_{k=-\infty}^{\infty} \delta[k + 1] \delta[n - 3 - k]$$

$$y[0] = 0; y[1] = 0; y[2] = 1; y[3] = 0;$$

$$\boxed{h[n] = \begin{cases} 1 & \text{if } n = 2 \\ 0 & \text{if } n \neq 2 \end{cases}}$$