## **Introduction to Filters**

## **Scope and Background Reading**

This section is Based on the section **Filtering** from Chapter 5 of <u>Benoit Boulet</u>, <u>Fundamentals of Signals and Systems (https://ebookcentral.proquest.com/lib/swansea-ebooks/reader.action?</u>

<u>ppg=221&doclD=3135971&tm=1518715953782)</u> from the **Recommended Reading List**.

This material is an introduction to analogue filters. You will find much more in-depth coverage on <u>Pages 11-1</u> — 11-48 of Karris (https://ebookcentral.proquest.com/lib/swansea-ebooks/reader.action? <u>ppg=429&doclD=3384197&tm=1518716026573</u>).

## **Agenda**

- · Frequency Selective Filters
- Ideal low-pass filter
- Butterworth low-pass filter
- · High-pass filter
- · Bandpass filter

#### Introduction

- Filter design is an important application of the Fourier transform
- Filtering is a rich topic often taught in graduate courses so we give only an introduction.
- Our introduction will illustrate the usefulness of the frequency domain viewpoint.
- We will explore how filters can shape the spectrum of a signal.

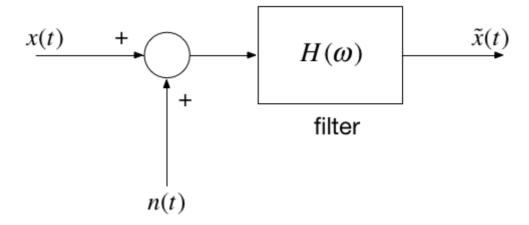
Other applications of the Fourier transform are sampling theory (introduced next week) and modulation.

## **Frequency Selective Filters**

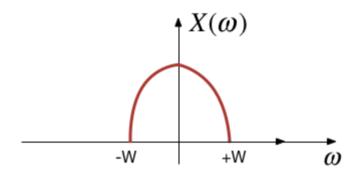
An ideal frequency-selective filter is a system that let's the frequency components of a signal through undistorted while frequency components at other components are completely cut off.

- The range of frequencies which are let through belong to the pass Band
- The range of frequencies which are cut-off by the filter are called the **stopband**
- A typical scenario where filtering is needed is when noise n(t) is added to a signal x(t) but that signal has most of its energy outside the bandwidth of a signal.

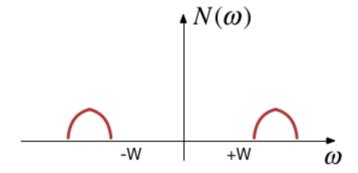
## **Typical filtering problem**



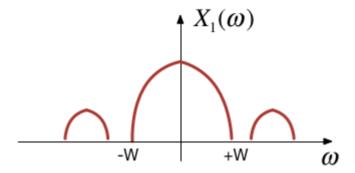
## Signal



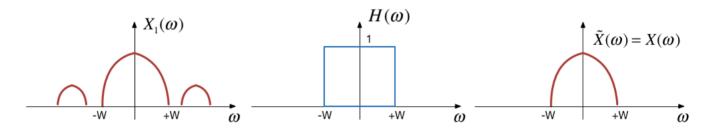
## **Out-of Bandwidth Noise**



### **Signal plus Noise**



### **Filtering**



#### **Motivating example**

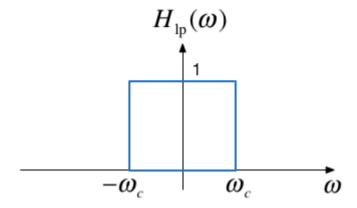
See the notes in the <u>OneNote Class Room notebook (https://swanseauniversity-my.sharepoint.com/personal/c\_p\_jobling\_swansea\_ac\_uk/\_layouts/15/WopiFrame.aspx?sourcedoc={540d6da0-390f-4f0a-914e-</u>

### **Ideal Low-Pass Filter**

An ideal low pass filter cuts-off frequencies higher than its *cutoff frequency*,  $\omega_c$ .

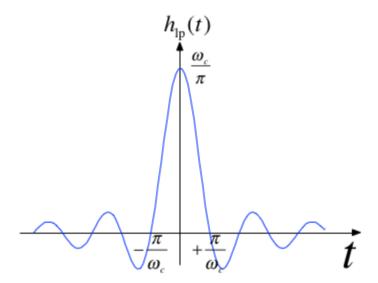
$$H_{\rm lp}(\omega) = \begin{cases} 1, & |\omega| < \omega_c \\ 0, & |\omega| \ge \omega_c \end{cases}$$

## Frequency response



## Impulse response

$$h_{\mathrm{lp}}(t) = \frac{\omega_c}{\pi} \mathrm{sinc}\left(\frac{\omega_c}{\pi}t\right)$$



## **Filtering is Convolution**

The output of an LTI system with impulse response

$$h(t) \Leftrightarrow H(\omega)$$

subject to an input signal

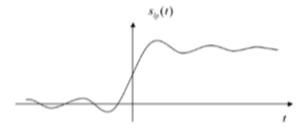
$$x(t) \Leftrightarrow X(\omega)$$

is given by

$$y(t) = h(t) * x(t) \Leftrightarrow Y(\omega) = H(\omega)X(\omega)$$

#### Issues with the "ideal" filter

This is the step response:



(reproduced from Boulet Fig. 5.23 p. 205)

Ripples in the impulse resonse would be undesireable, and because the impulse response is non-causal it cannot actually be implemented.

## **Butterworth low-pass filter**

N-th Order Butterworth Filter

$$|H_B(\omega)| = \frac{1}{\left(1 + \left(\frac{\omega}{\omega_c}\right)^{2N}\right)^{\frac{1}{2}}}$$

#### **Remarks**

- DC gain is  $|H_B(j0)| = 1$
- Attenuation at the cut-off frequency is  $|H_B(j\omega_c)|=1/\sqrt{2}$  for any N

More about the Butterworth filter: Wikipedia Article (http://en.wikipedia.org/wiki/Butterworth\_filter)

#### **Example 5: Second-order BW Filter**

The second-order butterworth Filter is defined by is Characteristic Equation (CE):

$$p(s) = s^2 + \omega_c \sqrt{2}s + \omega_c^2 = 0^*$$

Calculate the roots of p(s) (the poles of the filter transfer function) in both Cartesian and polar form.

**Note**: This has the same characteristic as a control system with damping ratio  $\zeta = 1/\sqrt{2}$  and  $\omega_n = \omega_c!$ 

Solution			

## Example 6

Derive the differential equation relating the input x(t) to output y(t) of the 2nd-Order Butterworth Low-Pass Filter with cutoff frequency  $\omega_c$ .

Solution			

# Example 7

Determine the frequency response  $H_B(\omega) = Y(\omega)/X(\omega)$ 

Sol	ution	
Ма	gnitude of frequency response of a 2nd-order Butterworth Filter	
In	[1]:	
WC	= 100;	
Tran	sfer function	

```
In [2]:
```

```
H = tf(wc^2,[1, wc*sqrt(2), wc^2])
```

H =

```
10000
-----s^2 + 141.4 s + 10000
```

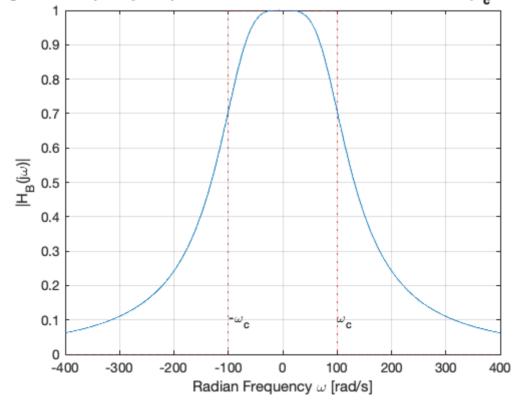
Continuous-time transfer function.

#### Magnitude frequency response

#### In [3]:

```
w = -400:400;
mHlp = 1./(sqrt(1 + (w./wc).^4));
plot(w,mHlp)
grid
ylabel('|H_B(j\omega)|')
title('Magnitude Frequency Response for 2nd-Order LP Butterworth Filter (\omega_c = 100 rad/s)')
xlabel('Radian Frequency \omega [rad/s]')
text(100,0.1,'\omega_c')
text(-100,0.1,'-\omega_c')
hold on
plot([-400,-100,-100,100,100,400],[0,0,1,1,0,0],'r:')
hold off
```

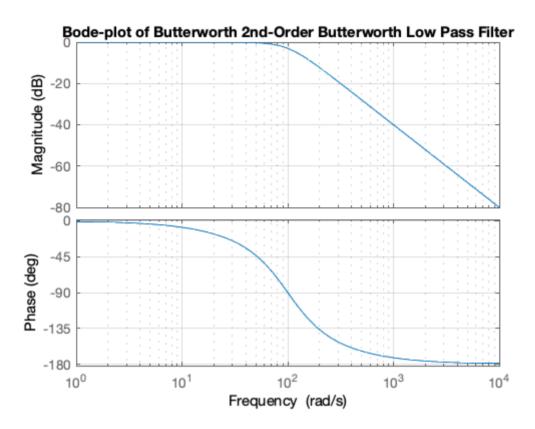
## Magnitude Frequency Response for 2nd-Order LP Butterworth Filter ( $\omega_c$ = 100 rad



#### Bode plot

```
In [4]:
```

bode(H)
grid
title('Bode-plot of Butterworth 2nd-Order Butterworth Low Pass Filter')



## Example 8

Determine the impulse and step response of a butterworth low-pass filter.

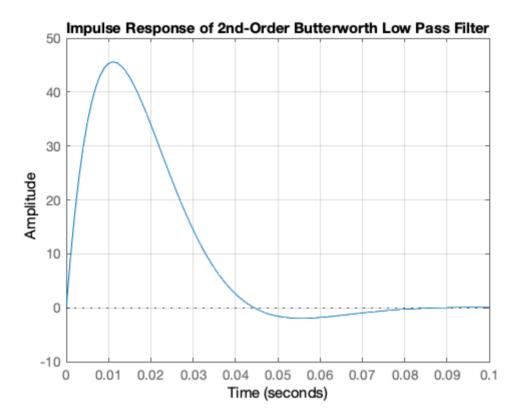
You will find this Fourier transform pair useful:

$$e^{-at} \sin \omega_0 t \ u_0(t) \Leftrightarrow \frac{\omega_0}{(j\omega + a)^2 + \omega_0^2}$$

Solu	ition		
lmn:	ulaa raananaa		
πηρι	ulse response		

#### In [5]:

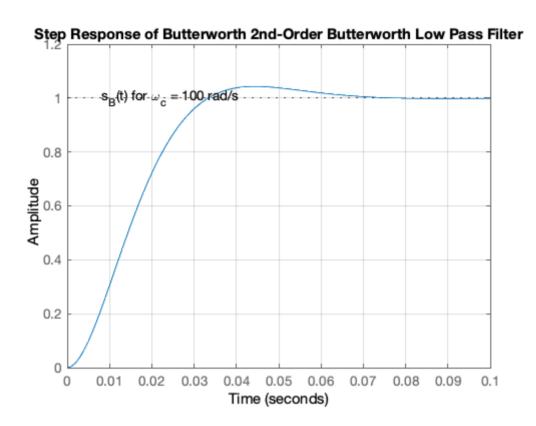
```
impulse(H,0.1)
grid
title('Impulse Response of 2nd-Order Butterworth Low Pass Filter')
```



Step response

```
In [6]:
```

```
step(H,0.1)
title('Step Response of Butterworth 2nd-Order Butterworth Low Pass Filter')
grid
text(0.008,1,'s_B(t) for \omega_c = 100 rad/s')
```

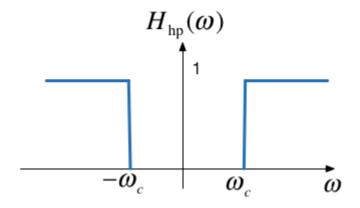


## **High-pass filter**

An ideal highpass filter cuts-off frequencies lower than its *cutoff frequency*,  $\omega_c$ .

$$H_{\rm hp}(\omega) = \begin{cases} 0, & |\omega| \le \omega_c \\ 1, & |\omega| > \omega_c \end{cases}$$

## Frequency response



## Responses

Frequency response

$$H_{\rm hp}(\omega) = 1 - H_{\rm lp}(\omega)$$

Impulse response

$$h_{\rm hp}(t) = \delta(t) - h_{\rm lp}(t)$$

## Example 9

Determine the frequency response of a 2nd-order butterworth highpass filter

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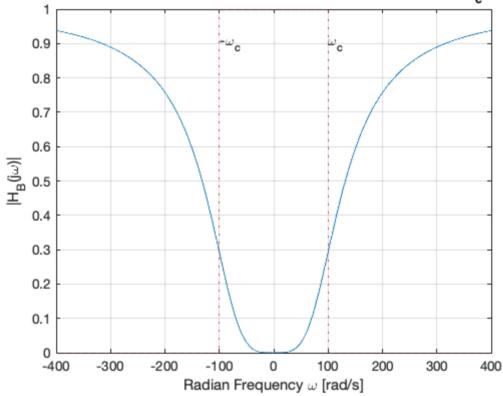
ft4

Magnitude frequency response

In [7]:

```
w = -400:400;
plot(w,1-mHlp)
grid
ylabel('|H_B(j\omega)|')
title('Magnitude Frequency Response for 2nd-Order HP Butterworth Filter (\omega_
c = 100 rad/s)')
xlabel('Radian Frequency \omega [rad/s]')
text(100,0.9,'\omega_c')
text(-100,0.9,'-\omega_c')
hold on
plot([-400,-100,-100,100,100,400],[0,0,1,1,0,0],'r:')
hold off
```

# //agnitude Frequency Response for 2nd-Order HP Butterworth Filter ( $\omega_{c}$ = 100 ra



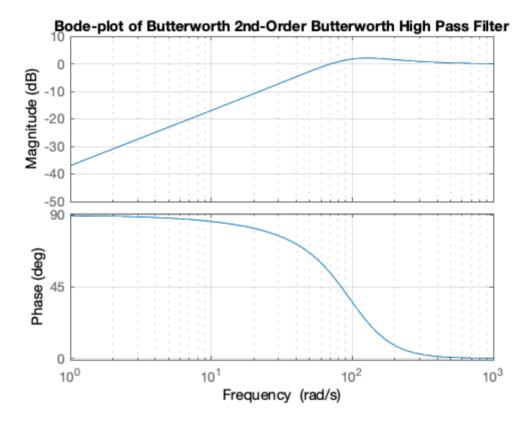
High-pass filter

```
In [8]:
```

```
Hhp = 1 - H
bode(Hhp)
grid
title('Bode-plot of Butterworth 2nd-Order Butterworth High Pass Filter')
```

Hhp =

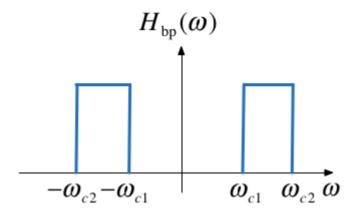
Continuous-time transfer function.



## **Band-pass filter**

An ideal bandpass filter cuts-off frequencies lower than its first cutoff frequency  $\omega_{c1}$ , and higher than its second cutoff frequency  $\omega_{c2}$ .

$$H_{\rm bp}(\omega) = \begin{cases} 1, & \omega_{c1} < |\omega| < \omega_{c2} \\ 0, & \text{otherwise} \end{cases}$$



#### **Bandpass filter design**

A bandpass filter can be obtained by multiplying the frequency responses of a lowpass filter by a highpass filter.

$$H_{\rm bp}(\omega) = H_{\rm hp}(\omega)H_{\rm lp}(\omega)$$

- The highpass filter should have cut-off frequency of  $\omega_{c1}$
- The lowpass filter should have cut-off frequency of  $\omega_{c2}$

To generate all the plots shown in this presentation, you can use butter2 ex.m (matlab/butter2 ex.m)

## **Summary**

- Frequency-Selective Filters
- · Ideal low-pass filter
- · Butterworth low-pass filter
- High-pass filter
- · Bandpass filter