$$V_{t} = \phi_{0} + \phi_{1}V_{t-1} + \Omega_{t}$$
,  $Var(\Omega_{t}) = 6a^{2}$   
(Weak)

1. Stationarity condition: 
$$|\Phi_1| < 1$$

$$(1-\Phi,B) = \Phi_0 + \Phi_{\epsilon}$$

$$(1-\Phi,Z = 0 \Rightarrow z = 0)$$

$$(1-\Phi,Z = 0 \Rightarrow z = 0)$$

$$|x| > |\Rightarrow |\phi| < |$$

2. 
$$E(Y_t) = \frac{\phi_0}{1-\phi_1}$$

$$E(V_{t}) = E(\phi_{0} + \phi_{1} V_{t-1} + \phi_{t})$$

$$= E(\phi_{0}) + \phi_{1} E(V_{t-1}) + E(\phi_{t}) = 0$$

$$= \phi_{0} + \phi_{1} E(V_{t})$$

$$\Rightarrow E(V_{t}) = \frac{\phi_{0}}{1 - \phi_{1}}$$

3. 
$$Var(Y_{\epsilon}) = \frac{6a^{2}}{1-\phi_{i}^{2}}$$

$$Var(r_{\ell}) = Var(\phi_{\delta} + \phi_{\ell} r_{\ell-1} + \alpha_{\ell})$$

$$= \phi_{\ell}^{2} Var(r_{\ell-1}) + Var(\alpha_{\ell})$$

$$\begin{array}{l}
+2\Phi_{1}\cos((Y_{k-1},A_{k})) = 0 \\
=\Phi_{1}^{2} V_{\alpha r}(Y_{k}) + \delta_{\alpha}^{2} \\
\Rightarrow V_{\alpha r}(Y_{k}) = \frac{\delta_{\alpha}^{2}}{1-\Phi_{1}^{2}} \\
4. \quad P_{1} = \Phi_{1}, \quad P_{2} = \Phi_{1}^{2}, \dots, P_{K} = \Phi_{1}^{K} \\
P_{1} = \frac{\cos((Y_{k}, Y_{k-1}))}{V_{\alpha r}(Y_{k})} = \frac{\cos((\varphi_{0} + \varphi_{1}Y_{k-1} + A_{k}, Y_{k-1}))}{V_{\alpha r}(Y_{k})} \\
= \frac{\cos((\varphi_{0}, Y_{k-1}))}{V_{\alpha r}(Y_{k})} + \Phi_{1} \cos((Y_{k-1}, Y_{k-1})) + \cos((A_{k}, Y_{k-1}))}{V_{\alpha r}(Y_{k})} \\
= \frac{\Phi_{1} V_{\alpha r}(Y_{k-1})}{V_{\alpha r}(Y_{k})} = \Phi_{1} \quad \text{weak obstimusing} \\
P_{2} = \frac{\cos((Y_{k}, Y_{k-2}))}{V_{\alpha r}(Y_{k})} = \frac{\cos((\varphi_{0} + \varphi_{1}Y_{k-1} + A_{k}, Y_{k-2}))}{V_{\alpha r}(Y_{k})} \\
= \frac{\Phi_{1} \cos((Y_{k-1}, Y_{k-2}))}{V_{\alpha r}(Y_{k})} + \Phi_{1} \cos((Y_{k-1}, Y_{k-2})) + \cos((Y_{k}, Y_{k-1}))}{V_{\alpha r}(Y_{k})} \\
= \frac{\Phi_{1} \cos((Y_{k-1}, Y_{k-2}))}{V_{\alpha r}(Y_{k})} \quad \text{weak obstimusing} \\
= \Phi_{1} \cos((Y_{k-1}, Y_{k-2})) + \Phi_{2} \cos((Y_{k}, Y_{k-1})) \\
= \Phi_{1} \cos((Y_{k-1}, Y_{k-2})) + \Phi_{2} \cos((Y_{k}, Y_{k-1})) \\
= \Phi_{1} \cos((Y_{k-1}, Y_{k-2})) - \Phi_{2} = \Phi_{2}
\end{array}$$

$$=\frac{\Phi_{i} Cov(\Upsilon_{t}, \Upsilon_{t-(k-i)})}{Var(\Upsilon_{t})}=\Phi_{i} C_{k-i}$$

$$k=3$$
,  $l_3 = 0$ ,  $l_2 = 0$ ,  $l_3 = 0$ ,  $l_4 = 0$ ,  $l_$ 

$$\Rightarrow (r_{\ell} - u) = \Phi_{\ell}(r_{\ell-1} - u) + \alpha_{\ell}$$

where 
$$u = \overline{C}(Y_t) = \frac{\overline{\varphi}_0}{1 - \overline{\varphi}_t}$$

Suppose we are at time n

(a) 1-step ahead forecest: 
$$F_n = \{x_1, x_2, ..., x_n\}$$
  
 $\hat{X}_n(1) = \bar{F}(X_{n+1} | \bar{F}_n)$ 

$$= \varphi_1 \times_n = \overline{E}(\alpha_{n+1}) = 0$$

$$\hat{e}_{n(1)} = \chi_{n+1} - \hat{\chi}_{n(1)}$$

$$= \phi_i \chi_n + a_{n+1} - \phi_i \chi_n$$

$$=$$
  $\triangle_{n+1}$ 

$$\hat{\chi}_{n(\lambda)} = E(\chi_{n+\lambda} | F_n)$$

(e) 2-step ahead forecost error:

$$\hat{e}_{n}(2) = \chi_{n+2} - \hat{\chi}_{n}(2)$$

$$= \varphi_{1} \chi_{n+1} + \alpha_{n+2} - \varphi_{1}^{2} \chi_{n}$$

$$= \varphi_{1} \left( \frac{1}{2} \chi_{n} + \alpha_{n+1} \right) + \alpha_{n+2} - \varphi_{2}^{2} \chi_{n}$$

$$= \varphi_{1} \alpha_{n+1} + \alpha_{n+2}$$

(f) Variance of 2-step ahead forceast error:

$$= \oint_{1}^{2} V_{av}(a_{n+1}) + V_{av}(a_{n+2}) + 2 \oint_{1} Cov(a_{n+1}, a_{n+2}) = 0$$

$$= \phi_1^2 b_a^2 + b_a^2$$