AR, MA and ARMA

1.
$$AR(1) \Rightarrow MA(\infty)$$
 $AR(1): Y_{\xi} = \varphi_0 + \varphi_1 Y_{\xi-1} + \alpha_{\xi}$
 $Mean-adjusted AR(1):$
 $X_{\xi} = \varphi_1 \times_{\xi-1} + \alpha_{\xi}$

where $X_{\xi} = Y_{\xi-M}, M = \overline{C}(Y_{\xi}) = \frac{\varphi_0}{1-\varphi_1}$
 $X_{\xi} = \varphi_1 \times_{\xi-1} + \alpha_{\xi}$
 $= \varphi_1(\varphi_1 \times_{\xi-2} + \varphi_{\xi-1}) + \alpha_{\xi}$
 $= \varphi_1^2(\varphi_1 \times_{\xi-3} + \varphi_{\xi-2}) + \varphi_1 \alpha_{\xi-1} + \alpha_{\xi}$
 $= \varphi_1^2(\varphi_1 \times_{\xi-3} + \varphi_1^2 \alpha_{\xi-2} + \varphi_1 \alpha_{\xi-1} + \alpha_{\xi})$
 $= \varphi_1^k \times_{\xi-k} + \varphi_1^{k+1} \alpha_{\xi-(k-1)} + \varphi_1^{k-2} \alpha_{\xi-(k-2)}$
 $+ \dots + \varphi_1 \alpha_{\xi-1} + \alpha_{\xi}$

When $k \Rightarrow \infty$, $\varphi_1^k \times_{\xi-k} \to 0$
 $(|\varphi_1| < | \Rightarrow \varphi_1^k \times_{\xi-k} \to 0)$

$$X_{t} = \sum_{k=0}^{\infty} \varphi_{i}^{k} \alpha_{t-k}$$

$$= \alpha_{t} + \varphi_{i} \alpha_{t-1} + \varphi_{i}^{2} \alpha_{t-2} + \varphi_{i}^{3} \alpha_{t-3} + \cdots$$

$$X_{t} = \gamma_{t} - M$$

$$\Rightarrow \boxed{\Upsilon_{t} = \mu_{t} + \sum_{k=0}^{\infty} \varphi_{k}^{k} \alpha_{t-k}}$$

$$AR(i) \Rightarrow MA(\infty)$$

General Form of Linear TS Model:

$$K = M + \sum_{k=0}^{\infty} Y_k a_{k-k}, \quad Y_0 = 1$$

$$(MA(\infty))$$

ARCI): 4k = OK

- $\begin{array}{c} AR(P) \\ ARMA(P,Q) \end{array} \Rightarrow MA(\infty)$
- 2. MA(1) => AR(00) Chack Week 7 In Class Notes Invertibility of MA(1): 10,1<1

$$\begin{array}{ccc}
 & MA(&) & \longrightarrow & AR(&) \\
ARMACP.&(2) & \longrightarrow & & & & & \\
\end{array}$$

Unit - Root Nonstationary Models

1. Random Walk

(Pt is log stock price, Yt = Pt-Pt-1 = at)

D AR(1) model with
$$\phi_1 = 1$$

 $P_+ = \phi_1 P_{t-1} + a_t$

Unit Root:

$$\underbrace{1-x=0} \Rightarrow x=[$$

2 Mean:

$$P_{t} = P_{t-1} + \alpha_{t}$$

$$= P_{t-2} + \alpha_{t-1} + \alpha_{t}$$

$$= P_{t-3} + \alpha_{t-2} + \alpha_{t-1} + \alpha_{t}$$

$$= P_{t} + \alpha_{t-2} + \alpha_{t-1} + \alpha_{t-1} + \alpha_{t-1} + \alpha_{t}$$

$$= P_{0} + \alpha_{1} + \alpha_{2} + \cdots + \alpha_{t-1} + \alpha_{t}$$

$$= P_{0} + \alpha_{1} + \alpha_{2} + \cdots + \alpha_{t-1} + \alpha_{t}$$

$$= (P_{0}) + E(\alpha_{1} + \alpha_{2} + \cdots + \alpha_{t-1} + \alpha_{t})$$

$$= P_{0}$$

(3) Variance:

$$Var(P_{t}) = Var(P_{t-1} + Q_{t})$$

$$= Var(P_{t-1}) + Var(Q_{t}) + 2 \omega u(P_{t-1}, Q_{t})$$

$$= Var(P_{t-1}) + G^{2}$$

$$Var(P_{t}) \neq Var(P_{t-1}) \Rightarrow Von stationary$$

$$Var(P_{t}) = Var(P_{t-1}) + Q_{t} + Q_{t-1} + Q_{t}$$

$$= Var(Q_{t}) + Var(Q_{2}) + \dots + Var(Q_{t-1}) + Var(Q_{t})$$

$$= t \cdot G^{2}$$

$$depends on time t$$

when tow, Var (Pt) -> 0

$$= Var(P_S) = S \cdot 6a^2$$

3 Autocomelations:

$$=\frac{SG^2}{\sqrt{+G^2-SG^2}}=\sqrt{\frac{S}{+}}<1$$

if 5 is not far away from t

$$\hat{P}_{n}(i) = E(P_{n+1}|F_{n})$$

$$= E(P_{n} + Q_{n+1}|F_{n})$$

$$= E(P_{n} + Q_{n+1}|F_{n})$$

$$= R_{t-1} + Q_{t}$$

$$\hat{\mathcal{C}}_{n}(i) = \hat{\mathcal{C}}_{n+1} - \hat{\mathcal{C}}_{n}(i)$$

$$= \Omega_{n+1}$$

$$Var(\hat{e}_{n(1)}) = Var(\hat{a}_{n+1}) = \hat{b}_{a}^{2}$$

•
$$\hat{P}_n(2) = \hat{E}(\hat{P}_{n+2}|\hat{F}_n)$$

$$=\overline{C}\left(\left|\gamma_{n+1}+\alpha_{n+2}\right|\overline{\alpha}\right)$$

$$\hat{\mathbb{C}}_{n}(2) = P_{n+2} - \hat{P}_{n}(2)$$

$$= P_{n} + \alpha_{n+1} + \alpha_{n+2} - P_{n}$$

$$= \alpha_{n+1} + \alpha_{n+2}$$

$$Var(\hat{\mathbb{C}}_{n}(2)) = Var(\alpha_{n+1} + \alpha_{n+2})$$

$$= Var(\alpha_{n+1}) + Var(\alpha_{n+2}) + 2 \omega V(\alpha_{n+1}, \alpha_{n+2})$$

$$= 2 \delta_{n}^{2}$$

$$= 2 \delta_{n}^{2}$$
• $\hat{P}_{n}(L) = \hat{\mathbb{C}}(P_{n} + L | \hat{\Gamma}_{n})$

$$= \hat{\mathbb{C}}(P_{n} + \alpha_{n+1} + \alpha_{n+2} + ... + \alpha_{n+L} | \hat{\Gamma}_{n})$$

$$= \hat{\mathbb{C}}(P_{n} | \hat{\Gamma}_{n}) + \hat{\mathbb{C}}(\alpha_{n+1} + \alpha_{n+2} + ... + \alpha_{n+L} | \hat{\Gamma}_{n})$$

$$= P_{n}$$

$$\hat{\mathbb{C}}_{n}(L) = P_{n+1} - \hat{P}_{n}(L)$$

$$= \alpha_{n+1} + \alpha_{n+2} + ... + \alpha_{n+L}$$

$$= \alpha_{n+1} + \alpha_{n+2} + ... + \alpha_{n+L}$$

$$= L \cdot \delta_{n}^{2}$$
When $L \Rightarrow 0$, $Var(\hat{\mathbb{C}}_{n}(L)) \Rightarrow \infty$

- 1 has an unit root
- 2 Non stationary
- 3) strong memory
- (4) has a time trend with slope M Pt = W+ Pt-1 + Qt
 - = M+ (M+R-2+A+-1) + A+
 - = 2 U + R-2 + Q+-1 + Q+
 - = 2 W + (M + Pt-3 + at-2) + at-1 + at
 - = 3 W+ Pt-3+ Qt-2+ Qt-1+ Qt
 - =(t·u) + Po + Q, + Q2 + ~+ Q+, + Q+
- 3. Differencing

1st difference: rt = Pt-Pt-1= aPt

- $P_{t} = P_{t-1} + a_{t} \implies Y_{t} = a_{t}$ $P_{t} = ARIMA(0, 1, 0)$
- $P_{t} : ARIMA(0,1,0)$
- Pt = U+Pt-1+Pt-1+ at +02t-2 Pt: ARIMA ([,], 2)
- $\Rightarrow r_{t} = u + p_{1}r_{t-1} + a_{t} + 0_{2}a_{t-2}$ $r_{t} = \Delta r_{t} = R_{t} R_{t-1}$
- · R= M+ P, P, + P, AR-1+ Q, + O, Q, Q, 2 R: ARIMA (2,0,2)
- $\Rightarrow P_{t} = \mu + \phi_{1} P_{t-1} + \phi_{2} (P_{t-1} P_{t-2}) + \alpha_{t} + 0_{2} \alpha_{t-2}$ $= \mu + (\phi_{1} + \phi_{2}) P_{t-1} \phi_{2} P_{t-2} + \alpha_{t} + 0_{2} \alpha_{t-2}$
 - when $\phi_1 = 1$, P_t : ARIMA(1,1,2) $\phi_1 + 1$, P_t : ARIMA(2,0,2)

4. Unit-Koot test

$$\begin{array}{c}
(\Delta P_{t-1} = P_{t-1} - P_{t-2}) \\
\Delta P_{t-2} = P_{t-2} - P_{t-3}
\end{array}$$

$$H_0 \Rightarrow \Delta R = C_{+} + \sum_{i=1}^{p-1} \varphi_i \Delta R_{-i} + \alpha_{+}$$

$$\Delta P_{+} \sim AR(P-1)$$

Augmented Dicky-Fuller test

P Value > 5% => Pt has an unit mot

· Alternative form of the model

Pt= Ct + BPt-1+ St Prape-i+ at

Pt-Pt-1

Pt-Pt-1