

## MA(2) Model

$$r_t = \mu + a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2}, \quad \text{Var}(a_t) = \sigma_a^2$$

1. Stationarity: always stationary

2. Mean:  $\bar{E}(r_t) = \mu$

$$\begin{aligned}\bar{E}(r_t) &= \bar{E}(\mu + a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2}) \\ &= \bar{E}(\mu) + \underbrace{\bar{E}(a_t)}_{=0} - \theta_1 \underbrace{\bar{E}(a_{t-1})}_{=0} - \theta_2 \underbrace{\bar{E}(a_{t-2})}_{=0} \\ &= \mu\end{aligned}$$

3. Variance:

$$\begin{aligned}\text{Var}(r_t) &= \text{Var}(\mu + a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2}) \\ &= \text{Var}(a_t) + \theta_1^2 \text{Var}(a_{t-1}) + \theta_2^2 \text{Var}(a_{t-2}) \\ &\quad - 2\theta_1 \underbrace{\text{Cov}(a_t, a_{t-1})}_{=0} \\ &\quad - 2\theta_2 \underbrace{\text{Cov}(a_t, a_{t-2})}_{=0} \\ &\quad + 2\theta_1 \theta_2 \underbrace{\text{Cov}(a_{t-1}, a_{t-2})}_{=0} \\ &= \sigma_a^2 + \theta_1^2 \sigma_a^2 + \theta_2^2 \sigma_a^2 \\ &= (1 + \theta_1^2 + \theta_2^2) \sigma_a^2\end{aligned}$$

4. Autocovariance:  $\text{Cov}(a_k, a_j) = \begin{cases} 0, & \text{if } k \neq j \\ \sigma_a^2, & \text{if } k = j \end{cases}$

$$\begin{aligned}
 \text{lag 1: } \text{cov}(Y_t, Y_{t-1}) &= \text{cov}(\mu + a_t - \theta_1 \underbrace{a_{t-1}}_{\text{red}}, \mu + \underbrace{a_{t-1}}_{\text{red}} - \theta_1 \underbrace{a_{t-2}}_{\text{blue}} - \theta_2 \underbrace{a_{t-3}}_{\text{blue}}) \\
 &= -\theta_1 \text{cov}(a_{t-1}, a_{t-1}) + \theta_2 \theta_1 \text{cov}(a_{t-2}, a_{t-2}) \\
 &= -\theta_1 \sigma_a^2 + \theta_2 \theta_1 \sigma_a^2 \\
 &= \theta_1 (\theta_2 - 1) \sigma_a^2
 \end{aligned}$$

$$\begin{aligned}
 \text{lag 2: } \text{cov}(Y_t, Y_{t-2}) &= \text{cov}(\mu + a_t - \theta_1 a_{t-1} - \theta_2 \underbrace{a_{t-2}}_{\text{blue}}, \mu + \underbrace{a_{t-2}}_{\text{blue}} - \theta_1 a_{t-3} - \theta_2 a_{t-4}) \\
 &= -\theta_2 \text{cov}(a_{t-2}, a_{t-2}) \\
 &= -\theta_2 \sigma_a^2
 \end{aligned}$$

$$\begin{aligned}
 \text{lag } l \ (l \geq 3): \text{cov}(Y_t, Y_{t-l}) &= \text{cov}(\mu + a_t - \theta_1 a_{t-1} - \theta_2 a_{t-2}, \mu + \underbrace{a_{t-l}}_{l=3 \ a_{t-3}} - \theta_1 \underbrace{a_{t-l-1}}_{l=4 \ a_{t-4}} - \theta_2 \underbrace{a_{t-l-2}}_{l=5 \ a_{t-5}}) \\
 &= 0
 \end{aligned}$$

$\vdots \quad \vdots \quad \vdots \quad \vdots$   
 $\vdots \quad \vdots \quad \vdots \quad \vdots$

5. Autocorrelation:

$$\rho_1 = \frac{\text{cov}(Y_t, Y_{t-1})}{\text{Var}(Y_t)} = \frac{\theta_1 (\theta_2 - 1) \cancel{\sigma_a^2}}{(1 + \theta_1^2 + \theta_2^2) \cancel{\sigma_a^2}}$$

$$\rho_2 = \frac{\text{cov}(Y_t, Y_{t-2})}{\text{Var}(Y_t)} = \frac{-\theta_2 \cancel{\sigma_a^2}}{(1 + \theta_1^2 + \theta_2^2) \cancel{\sigma_a^2}}$$

$$\text{var}(r_t) = (1 + \theta_1^2 + \theta_2^2) \sigma_a^2$$

$$L \geq 3: \rho_L = \frac{\text{cov}(r_t, r_{t-L})}{\text{var}(r_t)} = 0$$

MA(2) model has 2-period memory!

6. Forecast  $\Rightarrow$  HW Problem Set 2

ARMA(1, 1)

$$r_t = \phi_0 + \phi_1 \underbrace{r_{t-1}} + a_t - \theta_1 \underbrace{a_{t-1}}, \text{var}(a_t) = \sigma_a^2$$

$$\text{ARMA}(1, 1): \phi_1 \neq 0, \theta_1 \neq 0$$

$$\text{AR}(1): \phi_1 \neq 0, \theta_1 = 0$$

$$\text{MA}(1): \phi_1 = 0, \theta_1 \neq 0$$

1. Stationarity: same as AR(1):  $|\phi_1| < 1$

$$(1 - \phi_1 B) r_t = \phi_0 + a_t - \theta_1 a_{t-1}$$

$$1 - \phi_1 x = 0 \Rightarrow x = \frac{1}{\phi_1}$$

$$|x| > 1 \Rightarrow |\phi_1| < 1$$

2. Invertibility: same as MA(1):  $|\theta_1| < 1$

$$ARMA(1,1) \Rightarrow AR(\infty)$$

$$3. \text{ Mean: } \bar{E}(r_t) = \frac{\phi_0}{1 - \phi_1}$$

$$\begin{aligned} \bar{E}(r_t) &= \bar{E}(\phi_0 + \phi_1 r_{t-1} + a_t - \theta_1 a_{t-1}) \\ &= \bar{E}(\phi_0) + \phi_1 \bar{E}(r_{t-1}) + \underbrace{\bar{E}(a_t)}_{=0} - \theta_1 \underbrace{\bar{E}(a_{t-1})}_{=0} \\ &= \phi_0 + \phi_1 \bar{E}(r_t) \end{aligned}$$

$$\Rightarrow \bar{E}(r_t) = \frac{\phi_0}{1 - \phi_1}$$

4. Variance:

$$\begin{aligned} \text{Var}(r_t) &= \text{Var}(\phi_0 + \phi_1 r_{t-1} + a_t - \theta_1 a_{t-1}) \\ &= \phi_1^2 \text{Var}(r_{t-1}) + \text{Var}(a_t) + \theta_1^2 \text{Var}(a_{t-1}) \end{aligned}$$

$$+ 2\phi_1 \underbrace{\text{Cov}(r_{t-1}, a_t)}_{=0} = 0$$

$$- 2\phi_1 \theta_1 \underbrace{\text{Cov}(r_{t-1}, a_{t-1})}_{= \sigma_a^2} = \sigma_a^2$$

$$- 2\theta_1 \underbrace{\text{Cov}(a_t, a_{t-1})}_{=0} = 0$$

$$= \phi_1^2 \text{Var}(r_t) + \sigma_a^2 + \theta_1^2 \sigma_a^2 - 2\phi_1 \theta_1 \sigma_a^2$$

$$= \phi_1^2 \text{Var}(r_t) + (1 + \theta_1^2 - 2\phi_1 \theta_1) \sigma_a^2$$

$$\Rightarrow \boxed{\text{Var}(r_t) = \frac{(1 + \theta_1^2 - 2\phi_1 \theta_1) \sigma_a^2}{1 - \phi_1^2}}$$

$$AR(1): \theta_1 = 0$$

$$\text{Var}(r_t) = \frac{\sigma_a^2}{1 - \phi_1^2}$$

$$MA(1): \phi_1 = 0$$

$$\text{Var}(r_t) = (1 + \theta_1^2) \sigma_a^2$$

$$\bullet \text{Cov}(r_t, a_t) = \dots, \phi + \theta r_{t-1} \dots$$

$$\begin{aligned}
 &= \phi_1 \underbrace{\text{cov}(r_{t-2}, a_{t-1})}_{=0} \\
 &\quad + \underbrace{\text{cov}(a_{t-1}, a_{t-1})}_{= \sigma_a^2} \\
 &\quad - \theta_1 \underbrace{\text{cov}(a_{t-2}, a_{t-1})}_{=0} \\
 &= \sigma_a^2
 \end{aligned}$$

5. Autocovariance:

$$\begin{aligned}
 \text{lag 1: } &\text{cov}(r_t, r_{t-1}) \\
 &= \text{cov}(\phi_0 + \phi_1 r_{t-1} + a_t - \theta_1 a_{t-1}, r_{t-1}) \\
 &= \phi_1 \text{Var}(r_{t-1}) + \underbrace{\text{cov}(a_t, r_{t-1})}_{=0} - \theta_1 \underbrace{\text{cov}(a_{t-1}, r_{t-1})}_{= \sigma_a^2} \\
 &= \phi_1 \text{Var}(r_t) - \theta_1 \sigma_a^2
 \end{aligned}$$

$$\begin{aligned}
 \text{lag } L (L \geq 2): &\text{cov}(r_t, r_{t-L}) \\
 &= \text{cov}(\phi_0 + \phi_1 r_{t-1} + a_t - \theta_1 a_{t-1}, r_{t-L}) \\
 &= \phi_1 \text{cov}(r_{t-1}, r_{t-L}) + \underbrace{\text{cov}(a_t, r_{t-L})}_{=0} - \theta_1 \underbrace{\text{cov}(a_{t-1}, r_{t-L})}_{=0} \\
 &= \phi_1 \text{cov}(r_t, r_{t-(L-1)})
 \end{aligned}$$

$\begin{matrix} r_{t-2} \\ r_{t-3} \\ \vdots \end{matrix}$

6. Autocorrelations:

$$\text{lag 1: } \rho_1 = \frac{\text{cov}(r_t, r_{t-1})}{\sigma_r^2}$$

$$\begin{aligned}
 & \text{Var}(r_t) \\
 &= \frac{\phi_1 \text{Var}(r_t) - \theta_1 \sigma_a^2}{\text{Var}(r_t)} \\
 &= \phi_1 - \frac{\theta_1 \sigma_a^2}{\text{Var}(r_t)} \neq \phi_1
 \end{aligned}$$

$$\text{AR}(1): \theta_1 = 0, \rho_1 = \phi_1$$

$$\text{lag } L \ (L \geq 2): \rho_L = \frac{\text{cov}(r_t, r_{t-L})}{\text{Var}(r_t)}$$

$$= \frac{\phi_1 \text{cov}(r_t, r_{t-(L-1)})}{\text{Var}(r_t)}$$

$$= \phi_1 \rho_{L-1}$$

$$\rho_2 = \phi_1 \rho_1$$

$$\rho_3 = \phi_1 \rho_2 = \phi_1 (\phi_1 \rho_1) = \phi_1^2 \rho_1$$

$$\rho_4 = \phi_1 \rho_3 = \phi_1 (\phi_1^2 \rho_1) = \phi_1^3 \rho_1$$

$$\vdots$$

$$\rho_k = \phi_1^{k-1} \rho_1$$

$$\text{AR}(1): \theta_1 = 0, \rho_L = \phi_1 \rho_{L-1}$$

7. Forecast: At time origin  $n$

① 1-step ahead forecast:

$$\begin{aligned}
\hat{Y}_n(1) &= E(Y_{n+1} | \bar{F}_n) \\
&= E(\phi_0 + \phi_1 r_n + a_{n+1} - \theta_1 a_n | \bar{F}_n) \\
&= E(\phi_0 | \bar{F}_n) + \phi_1 E(r_n | \bar{F}_n) + \underbrace{E(a_{n+1} | \bar{F}_n)}_{=0} - \theta_1 E(a_n | \bar{F}_n) \\
&= \phi_0 + \phi_1 r_n - \theta_1 a_n
\end{aligned}$$

(2) 1-step ahead forecast error:

$$\begin{aligned}
\hat{e}_n(1) &= r_{n+1} - \hat{Y}_n(1) \\
&= \phi_0 + \phi_1 r_n + a_{n+1} - \theta_1 a_n - (\phi_0 + \phi_1 r_n - \theta_1 a_n) \\
&= a_{n+1}
\end{aligned}$$

$$\text{Var}(\hat{e}_n(1)) = \text{Var}(a_{n+1}) = \sigma_a^2$$

(3) Multi-step ahead forecast :  $l \geq 2$

$$\begin{aligned}
\hat{Y}_n(l) &= E(r_{n+l} | \bar{F}_n) \\
&= E(\phi_0 + \phi_1 r_{n+l-1} + a_{n+l} - \theta_1 a_{n+l-1} | \bar{F}_n) \\
&= \phi_0 + \phi_1 E(r_{n+l-1} | \bar{F}_n) + \underbrace{E(a_{n+l} | \bar{F}_n)}_{=0} - \theta_1 E(a_{n+l-1} | \bar{F}_n) \\
&= \phi_0 + \phi_1 \hat{Y}_n(l-1)
\end{aligned}$$

$\begin{matrix} a_{n+1} \\ a_{n+2} \\ \vdots \end{matrix}$

$$\hat{Y}_n(2) = \phi_0 + \phi_1 \hat{Y}_n(1)$$

$$\hat{Y}_n(3) = \phi_0 + \phi_1 \hat{Y}_n(2)$$

$$\hat{Y}_n(4) = \phi_0 + \phi_1 \hat{Y}_n(3)$$

$$r_n(4) = \psi_0 + \phi_1 r_n(3)$$

$$\vdots \qquad \qquad \qquad \vdots$$

④ Multi-step ahead forecast error:

$$\hat{e}_n(L) = r_{n+L} - \hat{r}_n(L)$$

$$= \phi_0 + \phi_1 r_{n+L-1} + a_{n+L} - \theta_1 a_{n+L-1}$$

$$- (\phi_0 + \phi_1 \hat{r}_n(L-1))$$

$$= a_{n+L} - \theta_1 a_{n+L-1} + \phi_1 (r_{n+L-1} - \hat{r}_n(L-1))$$

$$= a_{n+L} - \theta_1 a_{n+L-1} + \phi_1 \hat{e}_n(L-1)$$