$$AR(2)$$
 Model
$$V_{t} = \Phi_{0} + \Phi_{1} V_{t-1} + \Phi_{2} V_{t-2} + \Omega_{t}, U_{ar}(\Omega_{t}) = 6a^{2}$$

1. Stationarity condition:  

$$(1-\phi, B-\phi_2 B^2) V_{\xi} = \phi_3 + \alpha_{\xi}$$

$$(-\phi_1 x - \phi_1 x^2 = 0) \Rightarrow x$$

requirement for stationarity: 12/2/ for all mot

AR(1): 
$$1-4, x=0 \Rightarrow x=\frac{1}{4}$$

2. 
$$E(Y_t) = \frac{\phi_0}{1 - \phi_1 - \phi_2}$$

$$E(Y_{+}) = E(\varphi_{0} + \varphi_{1}Y_{+-1} + \varphi_{2}Y_{+-2} + Q_{+})$$

$$= E(\varphi_{0}) + \varphi_{1} E(Y_{+-1}) + \varphi_{2} E(Y_{+-2}) + E(Q_{+})$$

$$\Rightarrow \overline{-}(Y_{t}) = \frac{\phi_{0}}{(-\phi_{1} - \phi_{2})}$$

3. 
$$Var(r_{+}) = \frac{6a^{2}}{1 - \phi_{1}^{2} - \phi_{2}^{2} - 2\phi_{1}\phi_{2}\rho_{1}}$$

$$= \frac{\varphi_{1}^{2} V_{an}(Y_{6}) + \varphi_{2}^{2} V_{an}(Y_{6-2}) + V_{an}(\alpha_{4})}{+2 \varphi_{1} \varphi_{2} Cov(Y_{6-1}, Y_{6-2})} + V_{an}(\alpha_{4})$$

$$+2 \varphi_{1} \varphi_{2} Cov(Y_{6-1}, Y_{6-2}) = 0$$

$$+2 \varphi_{2} Cov(Y_{6-2}, \alpha_{4}) = 0$$

$$= \frac{\varphi_{1}^{2} V_{an}(Y_{4}) + \varphi_{2}^{2} V_{an}(Y_{4}) + Sa^{2}}{+2 \varphi_{1} \varphi_{2} \varphi_{1}} + Q_{1} \varphi_{2} \varphi_{1} \varphi_{$$

$$= \frac{1}{V_{01}(Y_{t})} + \frac{1}{V_{2}(Y_{t})} + \frac{1}$$

5. Mean-adjusted format:  

$$(Y_{t}-u) = \phi_{1}(Y_{t-1}-u) + \phi_{2}(Y_{t-2}-u) + Q_{t}$$
where  $u = E(Y_{t}) = \frac{\phi_{0}}{1-\phi_{1}-\phi_{2}}$ 

$$MA(i)$$
 Model  
 $Y_t = u + a_t - 0a_{t-1}$ ,  $Var(a_t) = 6a^2$ 

1. Stationary: always stationary

2. Mean: 
$$E(Y_{\xi}) = M$$
  
 $E(Y_{\xi}) = E(M + A_{\xi} - 0A_{\xi-1})$   
 $= E(M) + E(A_{\xi}) - 0 E(A_{\xi-1})$   
 $= M$ 

3. Variance: 
$$Var(Y_{t}) = (1+0^{2})6a^{2}$$
 $Var(Y_{t}) = Var(y_{t}+a_{t}-0a_{t-1})$ 
 $= Var(a_{t}) + 0^{2}Var(a_{t-1})$ 
 $= 20 \text{ GoV}(a_{t},a_{t-1}) = 0$ 
 $= 6a^{2} + 0^{2}6a^{2}$  .  $\text{GoV}(a_{t},a_{j})$ 
 $= (1+0^{2})6a^{2}$ 
 $= 6a^{2} + 6a^{2} + 6a^{2}$ 

4. Antocovarianne:

$$\begin{aligned} & (\log 1): & Cov(\Upsilon_{t}, \Upsilon_{t-1}) \\ & = cov(\mathcal{U}_{t}, \Lambda_{t-1}) - O\alpha_{t-1}, \mathcal{U}_{t} + \Omega_{t-1} - O\alpha_{t-2}) \\ & = cov(\Omega_{t}, \Lambda_{t-1}) - Ocov(\Omega_{t}, \Lambda_{t-2}) \\ & - Ocov(\Omega_{t-1}, \Omega_{t-1}) + O^{2} cov(\Omega_{t-1}, \Omega_{t-2}) \\ & = -Ocov(\Omega_{t-1}, \Omega_{t-1}) + O^{2} cov(\Omega_{t-1}, \Omega_{t-2}) \end{aligned}$$

$$lag 2 : cov(Y_{t}, Y_{t-2})$$

$$= cov(IX + a_{t} - 0a_{t-1}, IX + a_{t-2} - 0a_{t-3})$$

$$= cov(IX + a_{t-2} - 0cov(a_{t}, a_{t-3})$$

$$- 0 cov(a_{t-1}, a_{t-2}) + 0^{2} cov(a_{t-1}, a_{t-3})$$

$$= 0$$

$$lag L(I \ge 2) : cov(Y_{t}, Y_{t-1})$$

$$= cov(IX + a_{t} - 0a_{t-1}, IX + a_{t-1} - 0a_{t-1-1})$$

$$= 0$$

$$a_{t-2} = a_{t-3}$$

$$a_{t-3} = a_{t-4}$$

$$\vdots$$

$$lag | : C_{1} = \frac{cov(Y_{t}, Y_{t-1})}{V_{a_{1}(Y_{t})}} = \frac{-06a^{2}}{(I + 0^{2})c^{2}} = \frac{-0}{I + I0^{2}}$$

6. Forecast: at time origin n

DI-step ahead forecast:

$$\widehat{\Gamma}_{n}(I) = \overline{E}(\Upsilon_{n+1} | \overline{\Gamma}_{n})$$
 $= \overline{E}(\Upsilon_{n+1} - Oan) | \overline{\Gamma}_{n})$ 
 $= \overline{E}(\Upsilon_{n+1} - Oan) | \overline{\Gamma}_{n}$ 

$$= U - OQ_n$$

$$\hat{e}_{n}(i) = \gamma_{n+1} - \hat{\gamma}_{n}(i)$$

- var(vint) TO var(vint(-1))

- 
$$20 cov(Antl, Antl-1) = 0$$

=  $6a^2 + 0^2 6a^2$ 

=  $(1+0^2) 6a^2 = Var(Y_E)$ 

7. Invertibility: MA(1)  $\Rightarrow$  AR(0)

Condition:  $101 < 1$ 
 $Y_E = M + 0 = 00 = 0$ 
 $2 = -M + Y_E + 00 = 0$ 

=  $-(1+0)M + Y_E + 0Y_E + 0^2 (-M + Y_E - 2 + 00 = 0)$ 

=  $-(1+0)M + Y_E + 0Y_E + 0^2 (-M + Y_E - 2 + 00 = 0)$ 

=  $-(1+0+0^2)M + Y_E + 0Y_E + 0^2 (-M + Y_E - 2 + 00 = 0)$ 

=  $-(1+0+0^2)M + Y_E + 0Y_E + 0^2 (-M + Y_E - 2 + 00 = 0)$ 

=  $-(1+0+0^2)M + Y_E + 0Y_E + 0^2 (-M + Y_E - 2 + 00 = 0)$ 

when  $1 \Rightarrow 0$ ,  $0^{(H)} \Rightarrow 0$  if  $101 < 1$ 
 $101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 < 101 <$ 

$$\Rightarrow Y_{t} = \frac{1-0}{1-0}M - \frac{2}{5}O^{i}Y_{t-j} + Q_{t}$$

$$MA(1) \Rightarrow AR(\infty)!!$$

$$|\Theta| \leq |\Theta| \leq |\Theta|$$