Type *Markdown* and LaTeX: α^2

Ninjacart : Image classification using CNN and transfer learning

```
In [ ]:
```

```
Link - https://colab.research.google.com/drive/1A6jRmhFRFHIFiUYou7HDzlwT6F6MC8bk?usp=sharing
Summary and Insights:
    CNN from Scratch: 14,21,148 params
Validation accuracy - 93.38%
Test Accuracy - 88.03
2. VGG: 3,16,71,740 params
Validation accuracy - 96.12%
Test Accuracy - 87.18 %
3. Resnet: 7,51,21,020
Validation accuracy - 98.00%%
Test Accuracy - 90.88%
4. Mobilenet: 1,27,55,900
Validation accuracy - 98.25%
Test Accuracy - 92.31%
The best model is Mobilenet as it has the least number of parameters and the best testing accur-
To train a CNN we will need a lot of images. Tensorboard showed in the last page of the notebool
In [ ]:
!gdown 1clZX-lV_MLxKHSyeyTheX50CQtNCUcqT
# Downloading the Data
Downloading...
From: https://drive.google.com/uc?id=1clZX-1V_MLxKHSyeyTheX5OCQtNCUcqT (https://d
rive.google.com/uc?id=1clZX-lV MLxKHSyeyTheX50CQtNCUcqT)
To: /content/ninjacart_data.zip
100% 275M/275M [00:08<00:00, 31.4MB/s]
In [ ]:
import shutil
shutil.rmtree('ninjacart_data')
```

```
In [ ]:
```

```
!unzip /content/ninjacart_data.zip
# Unziped the data
Archive: /content/ninjacart_data.zip
   creating: ninjacart_data/test/
   creating: ninjacart data/test/indian market/
 inflating: ninjacart data/test/indian market/bhl.jpeg
  inflating: ninjacart_data/test/indian market/bhv.jpeg
 inflating: ninjacart_data/test/indian market/bn.jpeg
 inflating: ninjacart data/test/indian market/hjx.jpeg
 inflating: ninjacart data/test/indian market/igis.jpeg
 inflating: ninjacart_data/test/indian market/in.jpeg
 inflating: ninjacart_data/test/indian market/india-4898453__340.jpg
 inflating: ninjacart data/test/indian market/indianmarket10.jpeg
 inflating: ninjacart data/test/indian market/indianmarket12.jpeg
 inflating: ninjacart data/test/indian market/indianmarket13.jpeg
 inflating: ninjacart_data/test/indian market/indianmarket14.jpeg
 inflating: ninjacart data/test/indian market/indianmarket15.jpeg
 inflating: ninjacart data/test/indian market/indianmarket18.jpeg
 inflating: ninjacart_data/test/indian market/indianmarket19.jpeg
 inflating: ninjacart_data/test/indian market/indianmarket20.jpeg
 inflating: ninjacart_data/test/indian market/indianmarket21.jpeg
In [ ]:
```

```
# Import common libraries
import os
import glob
import random
import numpy as np
import pandas as pd
import sklearn.metrics as metrics
import seaborn as sns
import matplotlib.pyplot as plt
%matplotlib inline
import tensorflow as tf
from tensorflow.keras.preprocessing.image import load_img, img_to_array, random_shift
from tensorflow.keras.preprocessing.image import array_to_img
import tensorflow as tf
from tensorflow import keras # this allows <keras.> instead of <tf.keras.>
from tensorflow.keras import layers # this allows <layers.> instead of <tf.keras.layers.>
tf.keras.utils.set_random_seed(111) # set random seed
import os
import numpy as np
import tensorflow as tf
tf.keras.utils.set random seed(111)
from tensorflow import keras
from tensorflow.keras import layers, regularizers
import matplotlib.pyplot as plt
import seaborn as sns
import sklearn.metrics as metrics
import keras
from keras.models import Sequential
from keras.layers import Dense, Activation, Dropout, Flatten, Conv2D, MaxPooling2D
from keras.layers import BatchNormalization
import numpy as np
from tensorflow.keras.callbacks import TensorBoard
# To supress any warnings during the flow
import warnings
warnings.filterwarnings('ignore')
```

```
class_dirs = os.listdir("ninjacart_data/train") # list all directories inside "train" folder
image_dict = {} # dict to store image array(key) for every class(value)
count_dict = {} # dict to store count of files(key) for every class(value)
# iterate over all class_dirs
for cls in class_dirs:
    # get list of all paths inside the subdirectory
    file_paths = glob.glob(f'ninjacart_data/train/{cls}/*')
    # count number of files in each class and add it to count_dict
    count_dict[cls] = len(file_paths)
    # select random item from list of image paths
    image_path = random.choice(file_paths)
# load image using keras utility function and save it in image_dict
    image_dict[cls] = tf.keras.utils.load_img(image_path)
```

```
plt.figure(figsize=(15, 12))
# iterate over dictionary items (class label, image array)
for i, (cls,img) in enumerate(image_dict.items()):
    # create a subplot axis
    ax = plt.subplot(3, 4, i + 1)
    # plot each image
    plt.imshow(img)
    # set "class name" along with "image size" as title
    plt.title(f'{cls}, {img.size}')
    plt.axis("off")
# Plotting a few images from each class for viewing
# We can conclude that image sizes are not constant
```





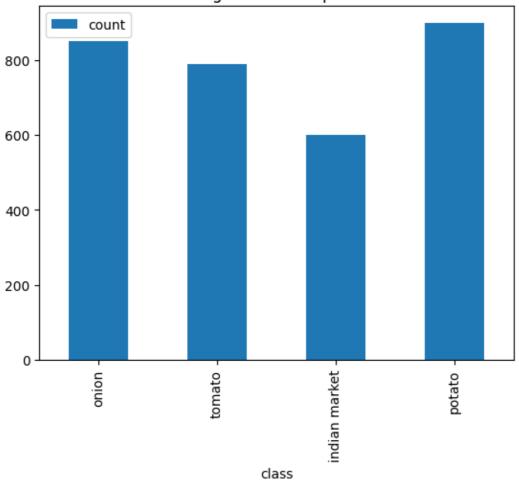




Out[7]:

<Axes: title={'center': 'Training Data Count per class'}, xlabel='class'>

Training Data Count per class



Data augmentation to make sample size as 1000 for each class

- Random Crop
- 2. Image rotation
- 3. Random flip

In []:

```
class dirs = os.listdir("ninjacart_data/train") # list all directories inside "train" folder
image_dict = {} # dict to store image array(key) for every class(value)
count_dict = {} # dict to store count of files(key) for every class(value)
# iterate over all class dirs
for cls in class dirs:
    # get list of all paths inside the subdirectory
   file paths = glob.glob(f'ninjacart data/train/{cls}/*')
   last=len(file_paths)
   list_path=random.choices(file_paths,k=1000-last)
    print(len(list_path))
   for i in range(0,len(list_path)-2,3):
     #print(i,cls)
     img = load_img(list_path[i], target_size=(300,300))
     x = img to array(img)
     x_crop = tf.image.random_crop(value=x, size=(224, 224, 3))
     array_to_img(x_crop)
     out_filename = f'{str(i)}.jpg'
     img.save(f'ninjacart_data/train/{cls}/' + out_filename)
     img = load_img(list_path[i+1], target_size=(300,300))
     x = img_to_array(img)
     x_rot=tf.keras.preprocessing.image.random_rotation(x, rg=125,channel_axis = 2, row_axis=0
     array to img(x rot)
     out_filename = f'{str(i+1)}.jpg'
     img.save(f'ninjacart_data/train/{cls}/'+ out_filename)
     img = load_img(list_path[i+2],target_size=(300,300))
     x = img_to_array(img)
     x_flip = tf.image.random_flip_left_right(x, 10)
     array to img(x flip)
     out filename = f'{str(i+2)}.jpg'
     img.save(f'ninjacart data/train/{cls}/' + out filename)
```

211

401

102

```
class_dirs = os.listdir("ninjacart_data/train") # list all directories inside "train" folder
image_dict = {} # dict to store image array(key) for every class(value)
count_dict = {} # dict to store count of files(key) for every class(value)
# iterate over all class_dirs
for cls in class_dirs:
    # get list of all paths inside the subdirectory
    file_paths = glob.glob(f'ninjacart_data/train/{cls}/*')
    # count number of files in each class and add it to count_dict
    count_dict[cls] = len(file_paths)
    # select random item from list of image paths
    image_path = random.choice(file_paths)
# load image using keras utility function and save it in image_dict
    image_dict[cls] = tf.keras.utils.load_img(image_path)
```

```
plt.figure(figsize=(15, 12))
# iterate over dictionary items (class label, image array)
for i, (cls,img) in enumerate(image_dict.items()):
    # create a subplot axis
    ax = plt.subplot(3, 4, i + 1)
    # plot each image
    plt.imshow(img)
    # set "class name" along with "image size" as title
    plt.title(f'{cls}, {img.size}')
    plt.axis("off")

# Checking image in each class
```









```
## Let's now Plot the Data Distribution of Training Data across Classes

df_count_train = pd.DataFrame({
    "class": count_dict.keys(),  # keys of count_dict are class labels
    "count": count_dict.values(),  # value of count_dict contain counts of each class
})
print("Count of training samples per class:\n", df_count_train)

# draw a bar plot using pandas in-built plotting function
df_count_train.plot.bar(x='class', y='count', title="Training Data Count per class")

# All classes have image count close to 1000
# Now it is a balanced dataset
```

Out[11]:

<Axes: title={'center': 'Training Data Count per class'}, xlabel='class'>



Creating Validation Data Set of size 200 each

```
In [ ]:
```

```
import os
import random
from shutil import move
train_dir = 'ninjacart_data/train'
validation_dir = 'ninjacart_data/validation'
# Create the validation directory if it does not exist
if not os.path.exists(validation dir):
    os.mkdir(validation_dir)
# Get a list of all the files in the train directory
files = os.listdir(train_dir)
for i in files:
  os.mkdir(f'ninjacart data/validation/{i}')
for i in files:
  files = os.listdir(f'ninjacart data/train/{i}')
  #print(len(files))
  random_files = random.sample(files, 200)
  #print(len(files))
  # Move the selected files to the validation directory
  for file in random files:
      move(f'ninjacart_data/train/{i}/' + file, f'ninjacart_data/validation/{i}/' + file)
```

```
class_dirs = os.listdir("ninjacart_data/train") # list all directories inside "train" folder
image_dict = {} # dict to store image array(key) for every class(value)
count_dict = {} # dict to store count of files(key) for every class(value)
# iterate over all class_dirs
for cls in class_dirs:
    # get list of all paths inside the subdirectory
    file_paths = glob.glob(f'ninjacart_data/train/{cls}/*')
    # count number of files in each class and add it to count_dict
    count_dict[cls] = len(file_paths)
```

In []:

```
count_dict
```

```
Out[14]:
```

```
{'onion': 799, 'tomato': 799, 'indian market': 798, 'potato': 800}
```

```
class_dirs = os.listdir("ninjacart_data/validation") # list all directories inside "train" folde
image_dict = {} # dict to store image array(key) for every class(value)
count_dict = {} # dict to store count of files(key) for every class(value)
# iterate over all class_dirs
for cls in class_dirs:
    # get list of all paths inside the subdirectory
    file_paths = glob.glob(f'ninjacart_data/validation/{cls}/*')
# count number of files in each class and add it to count_dict
count_dict[cls] = len(file_paths)
```

```
In [ ]:
count_dict
# We have 200 images in validation dataset (20% from training data)
Out[16]:
{'onion': 200, 'tomato': 200, 'indian market': 200, 'potato': 200}
```

Loading Data

In []:

```
def load_data(base_dir="ninjacart_data"):
    print('\nLoading Data...')
    train_data = tf.keras.utils.image_dataset_from_directory(
        f"{base_dir}/train", shuffle=True, label_mode='categorical'
)
    val_data = tf.keras.utils.image_dataset_from_directory(
        f"{base_dir}/validation", shuffle=False, label_mode='categorical'
)
    test_data = tf.keras.utils.image_dataset_from_directory(
        f"{base_dir}/test", shuffle=False, label_mode='categorical'
)
    return train_data, val_data, test_data, train_data.class_names
```

```
train_data, val_data, test_data, class_names = load_data()
```

```
Loading Data...
Found 3196 files belonging to 4 classes.
Found 800 files belonging to 4 classes.
Found 351 files belonging to 4 classes.
```

Setting image dimension and rescaling images

```
In [ ]:
```

```
def preprocess(train_data, val_data, test_data, target_height=256, target_width=256):

# Data Processing Stage with resizing and rescaling operations
data_preprocess = keras.Sequential(
    name="data_preprocess",
    layers=[
        layers.Resizing(target_height, target_width),
        layers.Rescaling(1.0/255),
    ]
)

# Perform Data Processing on the train, val, test dataset
train_ds = train_data.map(lambda x, y: (data_preprocess(x), y), num_parallel_calls=tf.data.AUTO
test_ds = test_data.map(lambda x, y: (data_preprocess(x),
```

```
In [ ]:
```

```
In [ ]:
```

```
train_ds, val_ds, test_ds = preprocess(train_data, val_data, test_data)
```

```
In [ ]:
```

```
L2Reg = tf.keras.regularizers.L2(12=1e-6)
# Regularizers
```

```
In [ ]:
```

```
def scheduler(epoch, lr):
    if epoch < 20:
        return lr
    if epoch < 35:
        return 0.0001
    if epoch < 50:
        return 0.00001
    if epoch < 80:
        return 0.000001
    if epoch < 80:
        return 0.000001
    else:
        return 0.0000001</pre>
```

Function for fitting

1. Saving weights

2. Learning rate scheduler

```
In [ ]:
```

Function to plot accuracy and confusion matrix

```
def print_accuracy_stats(model, ds, class_names,ckpt_path):
   model.load weights(ckpt path)
   true_onehot = tf.concat([y for x, y in ds], axis=0)
   true_categories = tf.argmax(true_onehot, axis=1)
   y_pred = model.predict(ds)
   predicted categories = tf.argmax(y pred, axis=1)
   test_acc = metrics.accuracy_score(true_categories, predicted_categories) * 100
   print(f'\n Accuracy: {test_acc:.2f}%\n')
# Note: This doesn't work with shuffled datasets
def plot_confusion_matrix(model, ds, class_names,ckpt_path):
    model.load_weights(ckpt_path)
   true onehot = tf.concat([y for x, y in ds], axis=0)
   true categories = tf.argmax(true onehot, axis=1)
   y pred = model.predict(ds)
   predicted_categories = tf.argmax(y_pred, axis=1)
   cm = metrics.confusion matrix(true categories, predicted categories) # last batch
    sns.heatmap(cm, annot=True, xticklabels=class names, yticklabels=class names, cmap="YlGnBu"
   plt.show()
```

```
In [ ]:
```

CNN Classifier model from scratch

Tensorboard

```
In [ ]:
```

```
%load_ext tensorboard
log_folder='logs/1'
%reload_ext tensorboard
!rm -rf logs
tb_callback=TensorBoard(log_dir=log_folder,histogram_freq=1)
```

```
model1 = keras.Sequential(
        name="model cnn",
        layers=[
            layers.Conv2D(filters=16, kernel_size=(3,3), padding="same", input_shape=(256,256,
                            kernel regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.MaxPooling2D(),
            layers.Conv2D(filters=32, kernel size=(5,5), padding="same",
                            kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.MaxPooling2D(),
            layers.Conv2D(filters=64, kernel_size=(6,6), padding="same",
                            kernel regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.MaxPooling2D(),
            layers.Conv2D(filters=128, kernel_size=(7,7), padding="same",
                            kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.MaxPooling2D(),
            layers.Conv2D(filters=256, kernel_size=(8,8), padding="same",
                            kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.MaxPooling2D(),
            layers.Conv2D(filters=512, kernel_size=(8,8), padding="same",
                            kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.MaxPooling2D(),
            layers.GlobalAveragePooling2D(),
            layers.Flatten(),
            layers.Dense(units=512, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=256, kernel regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=128, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.3),
```

```
layers.Dense(units=64, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.3),
            layers.Dense(units=32, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=16, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=8, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.1),
            layers.Dense(units=4, activation='softmax')
        ]
    )
In [ ]:
```

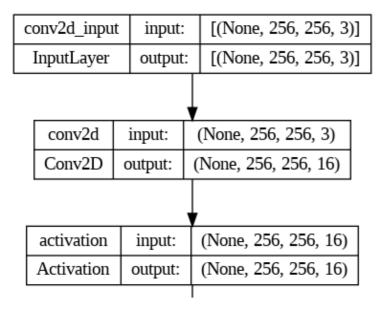
model1.summary()

Model: "model_cnn"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 256, 256, 16)	448
activation (Activation)	(None, 256, 256, 16)	0
<pre>batch_normalization (BatchMormalization)</pre>	N (None, 256, 256, 16)	64
<pre>max_pooling2d (MaxPooling2D)</pre>	None, 128, 128, 16)	0
conv2d_1 (Conv2D)	(None, 128, 128, 32)	12832
<pre>activation_1 (Activation)</pre>	(None, 128, 128, 32)	0
<pre>batch_normalization_1 (Batch_normalization_1)</pre>	(None, 128, 128, 32)	128

```
tf.keras.utils.plot_model(model1, show_shapes=True)
```

Out[28]:

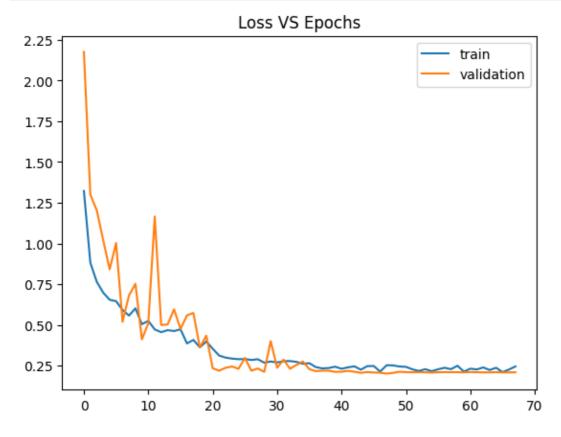


In []:

model_fit1 = compile_train_v1(model1, train_ds, val_ds,tb_callback,ckpt_path="/tmp/checkpoint1"

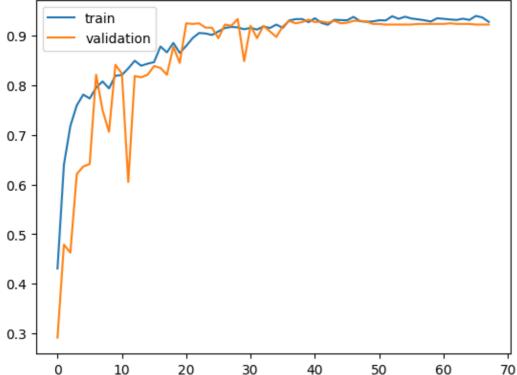
```
Epoch 1/100
100/100 [=============== ] - 47s 222ms/step - loss: 1.3223 - acc
uracy: 0.4305 - val_loss: 2.1755 - val_accuracy: 0.2912 - lr: 0.0010
Epoch 2/100
100/100 [============== ] - 19s 182ms/step - loss: 0.8822 - acc
uracy: 0.6399 - val_loss: 1.2996 - val_accuracy: 0.4787 - lr: 0.0010
Epoch 3/100
100/100 [============== ] - 19s 180ms/step - loss: 0.7648 - acc
uracy: 0.7181 - val_loss: 1.2037 - val_accuracy: 0.4625 - lr: 0.0010
Epoch 4/100
100/100 [============= ] - 18s 175ms/step - loss: 0.6984 - acc
uracy: 0.7597 - val_loss: 1.0190 - val_accuracy: 0.6212 - lr: 0.0010
Epoch 5/100
100/100 [============== ] - 19s 180ms/step - loss: 0.6549 - acc
uracy: 0.7813 - val_loss: 0.8417 - val_accuracy: 0.6363 - lr: 0.0010
Epoch 6/100
100/100 [=============== ] - 19s 184ms/step - loss: 0.6462 - acc
uracy: 0.7735 - val_loss: 1.0029 - val_accuracy: 0.6413 - lr: 0.0010
Epoch 7/100
100/100
                                       10- 170----
                                                     1---- 0 5031
```

```
epochs = model_fit1.epoch
loss = model_fit1.history["loss"]
val_loss = model_fit1.history["val_loss"]
plt.plot(epochs, loss, label="train")
plt.plot(epochs, val_loss, label="validation")
plt.legend()
plt.title("Loss VS Epochs")
plt.show()
```



```
epochs = model_fit1.epoch
loss = model_fit1.history["accuracy"]
val_loss = model_fit1.history["val_accuracy"]
plt.plot(epochs, loss, label="train")
plt.plot(epochs, val_loss, label="validation")
plt.legend()
plt.title("Loss VS Epochs")
plt.show()
```





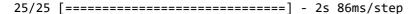
In []:

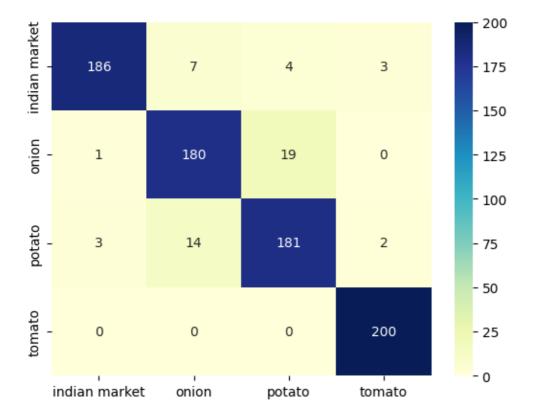
```
print_accuracy_stats(model1, test_ds, class_names,"/tmp/checkpoint1")
# Test Accuracy for CNN from scratch is 91.74%
```

11/11 [=======] - 3s 225ms/step

Accuracy: 88.03%

```
plot_confusion_matrix(model1, val_ds, class_names,"/tmp/checkpoint1")
# Confusion matrix for validation data
```





In []:

```
print_accuracy_stats(model1, val_ds, class_names,"/tmp/checkpoint1")
# TValidation Accuracy for CNN from scratch is 91.74%
```

```
25/25 [======== ] - 3s 119ms/step
```

Accuracy: 93.38%

In []:

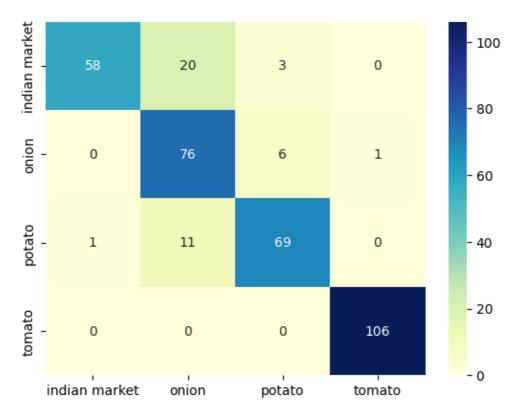
```
print_accuracy_stats(model1, test_ds, class_names,"/tmp/checkpoint1")
```

```
11/11 [======] - 1s 107ms/step
```

Accuracy: 88.03%

```
plot_confusion_matrix(model1, test_ds, class_names,"/tmp/checkpoint1")
```

11/11 [=======] - 1s 108ms/step



In []:

#%tensorboard --logdir logs

VGG

```
#%load_ext tensorboard
log_folder='logs/2'
#%reload_ext tensorboard
#!rm -rf logs
tb_callback=TensorBoard(log_dir=log_folder,histogram_freq=1)
```

```
pretrained_model = tf.keras.applications.VGG16(weights='imagenet', include_top=False, input_sha
pretrained model.trainable=False
vgg16 model = tf.keras.Sequential([
    pretrained model,
    tf.keras.layers.Flatten(),
    #tf.keras.layers.Dense(10, activation='softmax')
            layers.Dense(units=512, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=256, kernel regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=128, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.3),
            layers.Dense(units=64, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.3),
            layers.Dense(units=32, kernel regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=16, kernel regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=8, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.1),
            layers.Dense(units=4, activation='softmax')
])
```

vgg16_model.summary()

Model: "sequential"

Hodel: Sequencial		
Layer (type)	Output Shape	Param #
vgg16 (Functional)	(None, 8, 8, 512)	14714688
flatten_1 (Flatten)	(None, 32768)	0
dense_8 (Dense)	(None, 512)	16777728
activation_13 (Activation)	(None, 512)	0
<pre>batch_normalization_13 (Bat chNormalization)</pre>	(None, 512)	2048
dropout_7 (Dropout)	(None, 512)	0
dense_9 (Dense)	(None, 256)	131328
activation_14 (Activation)	(None, 256)	0
<pre>batch_normalization_14 (Bat chNormalization)</pre>	(None, 256)	1024
dropout_8 (Dropout)	(None, 256)	0
dense_10 (Dense)	(None, 128)	32896
activation_15 (Activation)	(None, 128)	0
<pre>batch_normalization_15 (Bat chNormalization)</pre>	(None, 128)	512
dropout_9 (Dropout)	(None, 128)	0
dense_11 (Dense)	(None, 64)	8256
activation_16 (Activation)	(None, 64)	0
<pre>batch_normalization_16 (Bat chNormalization)</pre>	(None, 64)	256
dropout_10 (Dropout)	(None, 64)	0
dense_12 (Dense)	(None, 32)	2080
activation_17 (Activation)	(None, 32)	0
<pre>batch_normalization_17 (Bat chNormalization)</pre>	(None, 32)	128
dropout_11 (Dropout)	(None, 32)	0
dense_13 (Dense)	(None, 16)	528
activation_18 (Activation)	(None, 16)	0
<pre>batch_normalization_18 (Bat chNormalization)</pre>	(None, 16)	64
dropout_12 (Dropout)	(None, 16)	0
dense_14 (Dense)	(None, 8)	136

```
activation_19 (Activation) (None, 8) 0

batch_normalization_19 (Bat (None, 8) 32 chNormalization)

dropout_13 (Dropout) (None, 8) 0

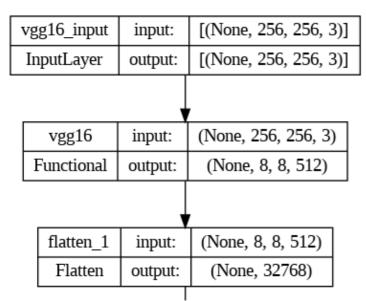
dense_15 (Dense) (None, 4) 36
```

Total params: 31,671,740
Trainable params: 16,955,020
Non-trainable params: 14,716,720

In []:

```
tf.keras.utils.plot_model(vgg16_model, show_shapes=True)
```

Out[41]:

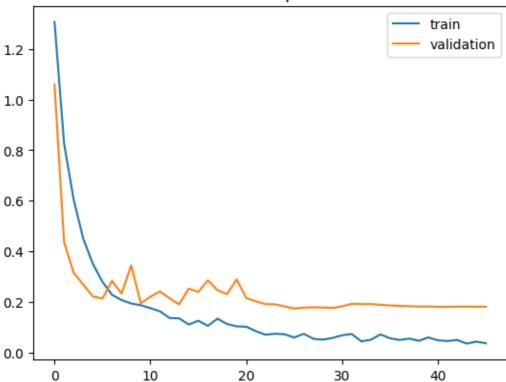


```
model_fit2 = compile_train_v1(vgg16_model, train_ds, val_ds,tb_callback,ckpt_path="/tmp/checkpo
```

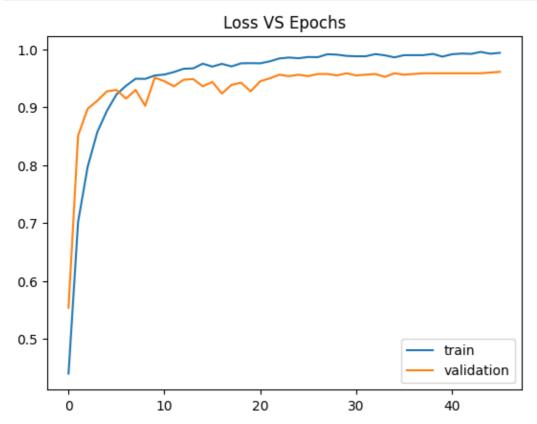
```
Epoch 1/100
100/100 [================= ] - 50s 373ms/step - loss: 1.3063 - acc
uracy: 0.4399 - val_loss: 1.0592 - val_accuracy: 0.5537 - lr: 0.0010
Epoch 2/100
100/100 [================ ] - 32s 315ms/step - loss: 0.8256 - acc
uracy: 0.7021 - val_loss: 0.4367 - val_accuracy: 0.8512 - lr: 0.0010
Epoch 3/100
100/100 [============== ] - 31s 310ms/step - loss: 0.6044 - acc
uracy: 0.7972 - val_loss: 0.3156 - val_accuracy: 0.8975 - lr: 0.0010
Epoch 4/100
100/100 [=============== ] - 32s 320ms/step - loss: 0.4501 - acc
uracy: 0.8570 - val_loss: 0.2691 - val_accuracy: 0.9112 - lr: 0.0010
Epoch 5/100
100/100 [================ ] - 31s 307ms/step - loss: 0.3513 - acc
uracy: 0.8936 - val_loss: 0.2220 - val_accuracy: 0.9275 - lr: 0.0010
Epoch 6/100
100/100 [============== ] - 32s 315ms/step - loss: 0.2802 - acc
uracy: 0.9221 - val loss: 0.2142 - val accuracy: 0.9300 - lr: 0.0010
Epoch 7/100
```

```
epochs = model_fit2.epoch
loss = model_fit2.history["loss"]
val_loss = model_fit2.history["val_loss"]
plt.plot(epochs, loss, label="train")
plt.plot(epochs, val_loss, label="validation")
plt.legend()
plt.title("Loss VS Epochs")
plt.show()
```

Loss VS Epochs



```
epochs = model_fit2.epoch
loss = model_fit2.history["accuracy"]
val_loss = model_fit2.history["val_accuracy"]
plt.plot(epochs, loss, label="train")
plt.plot(epochs, val_loss, label="validation")
plt.legend()
plt.title("Loss VS Epochs")
plt.show()
```



In []:

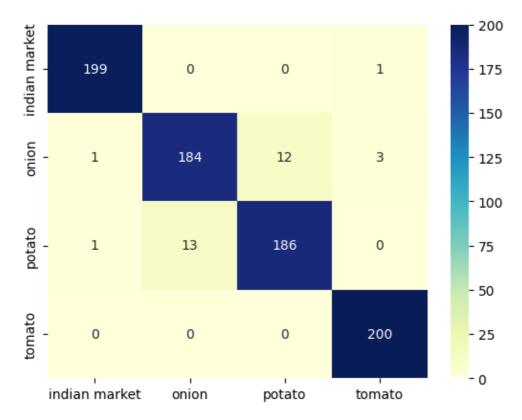
```
print_accuracy_stats(vgg16_model, test_ds, class_names,"/tmp/checkpoint2")
```

11/11 [======] - 7s 708ms/step

Accuracy: 87.18%

```
plot_confusion_matrix(vgg16_model, val_ds, class_names,"/tmp/checkpoint2")
```

25/25 [========] - 4s 181ms/step



In []:

print_accuracy_stats(vgg16_model, val_ds, class_names,"/tmp/checkpoint2")

25/25 [=========] - 4s 178ms/step

Accuracy: 96.12%

In []:

print_accuracy_stats(vgg16_model, test_ds, class_names,"/tmp/checkpoint2")

11/11 [=======] - 2s 171ms/step

Accuracy: 87.18%

```
plot_confusion_matrix(vgg16_model, test_ds, class_names,"/tmp/checkpoint2")
```





In []:

#%tensorboard --logdir logs

ResNet

```
#%Load_ext tensorboard
log_folder='logs/3'
#%reLoad_ext tensorboard
#!rm -rf Logs
tb_callback=TensorBoard(log_dir=log_folder,histogram_freq=1)
```

```
pretrained_model = tf.keras.applications.resnet_v2.ResNet152V2(weights='imagenet', include_top=
pretrained model.trainable=False
resnet = tf.keras.Sequential([
    pretrained_model,
    tf.keras.layers.Flatten(),
    #tf.keras.layers.Dense(10, activation='softmax')
            layers.Dense(units=128, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.3),
            layers.Dense(units=64, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.3),
            layers.Dense(units=32, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=16, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=8, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.1),
            layers.Dense(units=4, activation='softmax')
])
```

resnet.summary()

Model: "sequential_1"

Layer (type)	Output Shape 	Param # =======
resnet152v2 (Functional)	(None, 8, 8, 2048)	58331648
<pre>flatten_2 (Flatten)</pre>	(None, 131072)	0
dense_16 (Dense)	(None, 128)	16777344
activation_20 (Activation)	(None, 128)	0
<pre>batch_normalization_20 (Bat chNormalization)</pre>	(None, 128)	512
dropout_14 (Dropout)	(None, 128)	0
dense_17 (Dense)	(None, 64)	8256
activation_21 (Activation)	(None, 64)	0
<pre>batch_normalization_21 (Bat chNormalization)</pre>	(None, 64)	256
dropout_15 (Dropout)	(None, 64)	0
dense_18 (Dense)	(None, 32)	2080
activation_22 (Activation)	(None, 32)	0
<pre>batch_normalization_22 (Bat chNormalization)</pre>	(None, 32)	128
dropout_16 (Dropout)	(None, 32)	0
dense_19 (Dense)	(None, 16)	528
activation_23 (Activation)	(None, 16)	0
<pre>batch_normalization_23 (Bat chNormalization)</pre>	(None, 16)	64
dropout_17 (Dropout)	(None, 16)	0
dense_20 (Dense)	(None, 8)	136
activation_24 (Activation)	(None, 8)	0
<pre>batch_normalization_24 (Bat chNormalization)</pre>	(None, 8)	32
dropout_18 (Dropout)	(None, 8)	0
dense_21 (Dense)	(None, 4)	36

Total params: 75,121,020 Trainable params: 16,788,876 Non-trainable params: 58,332,144

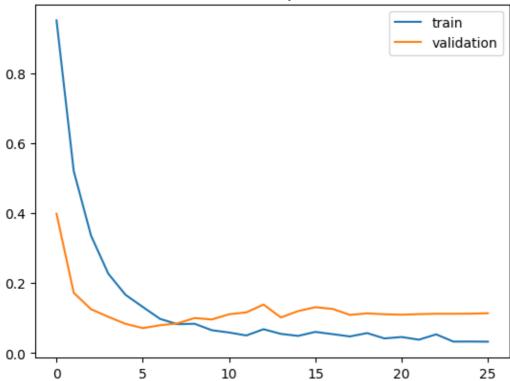
tf.keras.utils.plot_model(resnet, show_shapes=True) Out[54]: [(None, 256, 256, 3)] resnet152v2_input input: InputLayer [(None, 256, 256, 3)] output: resnet152v2 (None, 256, 256, 3) input: Functional (None, 8, 8, 2048) output: (None, 8, 8, 2048) flatten_2 input: (None, 131072) Flatten output:

model_fit3 = compile_train_v1(resnet, train_ds, val_ds,tb_callback,ckpt_path="/tmp/checkpoint3"

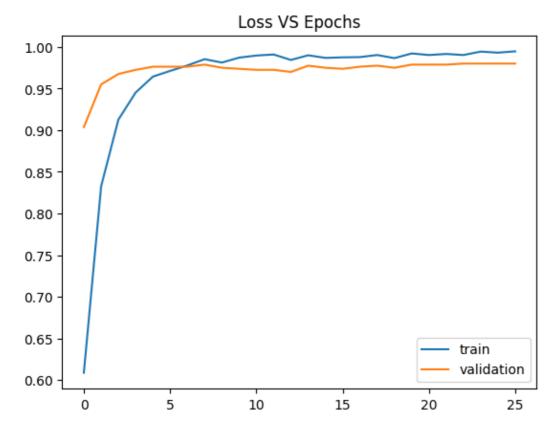
```
Epoch 1/100
100/100 [================ ] - 78s 615ms/step - loss: 0.9522 - accura
cy: 0.6089 - val_loss: 0.3988 - val_accuracy: 0.9038 - lr: 0.0010
Epoch 2/100
100/100 [================= ] - 60s 598ms/step - loss: 0.5206 - accura
cy: 0.8326 - val_loss: 0.1724 - val_accuracy: 0.9550 - lr: 0.0010
Epoch 3/100
100/100 [================ ] - 58s 571ms/step - loss: 0.3361 - accura
cy: 0.9127 - val loss: 0.1256 - val accuracy: 0.9675 - lr: 0.0010
Epoch 4/100
cy: 0.9452 - val_loss: 0.1038 - val_accuracy: 0.9725 - lr: 0.0010
Epoch 5/100
100/100 [============= ] - 59s 586ms/step - loss: 0.1667 - accura
cy: 0.9643 - val_loss: 0.0837 - val_accuracy: 0.9762 - lr: 0.0010
Epoch 6/100
100/100 [================= ] - 56s 557ms/step - loss: 0.1320 - accura
cy: 0.9712 - val_loss: 0.0715 - val_accuracy: 0.9762 - lr: 0.0010
Epoch 7/100
100/100 [=============== ] - 55s 547ms/step - loss: 0.0979 - accura
cy: 0.9778 - val loss: 0.0797 - val accuracy: 0.9762 - lr: 0.0010
Epoch 8/100
100/100 [================= ] - 57s 567ms/step - loss: 0.0827 - accura
cy: 0.9853 - val_loss: 0.0850 - val_accuracy: 0.9787 - lr: 0.0010
Epoch 9/100
100/100 [================= ] - 54s 535ms/step - loss: 0.0839 - accura
cy: 0.9812 - val_loss: 0.1002 - val_accuracy: 0.9750 - lr: 0.0010
Epoch 10/100
100/100 [=============== ] - 58s 575ms/step - loss: 0.0655 - accura
cy: 0.9872 - val_loss: 0.0962 - val_accuracy: 0.9737 - lr: 0.0010
Epoch 11/100
100/100 [================= ] - 58s 573ms/step - loss: 0.0589 - accura
cy: 0.9897 - val_loss: 0.1111 - val_accuracy: 0.9725 - lr: 0.0010
Epoch 12/100
100/100 [=============== ] - 54s 539ms/step - loss: 0.0504 - accura
cy: 0.9909 - val_loss: 0.1165 - val_accuracy: 0.9725 - lr: 0.0010
Epoch 13/100
100/100 [=============== ] - 54s 538ms/step - loss: 0.0683 - accura
cy: 0.9844 - val_loss: 0.1389 - val_accuracy: 0.9700 - lr: 0.0010
Epoch 14/100
100/100 [================= ] - 54s 535ms/step - loss: 0.0550 - accura
cy: 0.9900 - val_loss: 0.1019 - val_accuracy: 0.9775 - lr: 0.0010
Epoch 15/100
100/100 [=============== ] - 58s 575ms/step - loss: 0.0492 - accura
cy: 0.9869 - val loss: 0.1202 - val accuracy: 0.9750 - lr: 0.0010
Epoch 16/100
100/100 [================= ] - 58s 573ms/step - loss: 0.0607 - accura
cy: 0.9875 - val_loss: 0.1313 - val_accuracy: 0.9737 - lr: 0.0010
Epoch 17/100
100/100 [================ ] - 58s 577ms/step - loss: 0.0542 - accura
cy: 0.9878 - val_loss: 0.1264 - val_accuracy: 0.9762 - lr: 0.0010
Epoch 18/100
100/100 [=============== ] - 57s 562ms/step - loss: 0.0476 - accura
cy: 0.9903 - val_loss: 0.1093 - val_accuracy: 0.9775 - lr: 0.0010
Epoch 19/100
100/100 [================ ] - 55s 551ms/step - loss: 0.0573 - accura
cy: 0.9865 - val_loss: 0.1137 - val_accuracy: 0.9750 - lr: 0.0010
Epoch 20/100
100/100 [================= ] - 54s 539ms/step - loss: 0.0420 - accura
cy: 0.9922 - val_loss: 0.1111 - val_accuracy: 0.9787 - lr: 0.0010
Epoch 21/100
100/100 [=============== ] - 55s 542ms/step - loss: 0.0460 - accura
cy: 0.9903 - val_loss: 0.1098 - val_accuracy: 0.9787 - lr: 1.0000e-04
Epoch 22/100
```

```
epochs = model_fit3.epoch
loss = model_fit3.history["loss"]
val_loss = model_fit3.history["val_loss"]
plt.plot(epochs, loss, label="train")
plt.plot(epochs, val_loss, label="validation")
plt.legend()
plt.title("Loss VS Epochs")
plt.show()
```





```
epochs = model_fit3.epoch
loss = model_fit3.history["accuracy"]
val_loss = model_fit3.history["val_accuracy"]
plt.plot(epochs, loss, label="train")
plt.plot(epochs, val_loss, label="validation")
plt.legend()
plt.title("Loss VS Epochs")
plt.show()
```



In []:

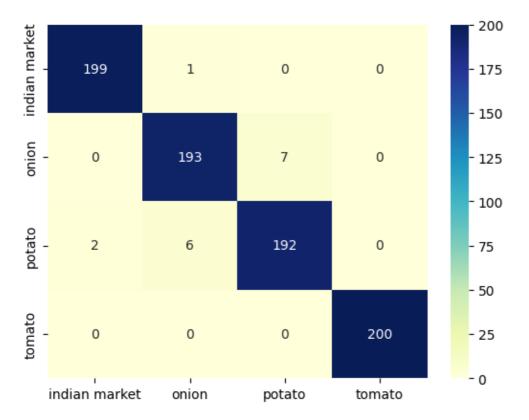
```
print_accuracy_stats(resnet, test_ds, class_names,"/tmp/checkpoint3")
```

11/11 [======] - 7s 446ms/step

Accuracy: 90.88%

```
plot_confusion_matrix(resnet, val_ds, class_names,"/tmp/checkpoint3")
```

25/25 [========] - 7s 281ms/step



In []:

print_accuracy_stats(resnet, val_ds, class_names,"/tmp/checkpoint3")

25/25 [========] - 7s 275ms/step

Accuracy: 98.00%

In []:

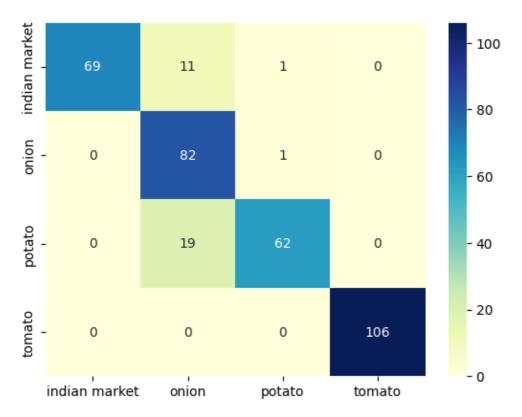
print_accuracy_stats(resnet, test_ds, class_names,"/tmp/checkpoint3")

11/11 [=======] - 3s 271ms/step

Accuracy: 90.88%

```
plot_confusion_matrix(resnet, test_ds, class_names,"/tmp/checkpoint3")
```

11/11 [=======] - 3s 276ms/step



In []:

#%tensorboard --logdir logs

In []:

Mobilenet

In []:

```
#%load_ext tensorboard
log_folder='logs/4'
#%reload_ext tensorboard
#!rm -rf logs
tb_callback=TensorBoard(log_dir=log_folder,histogram_freq=1)
```

```
pretrained_model = tf.keras.applications.mobilenet_v2.MobileNetV2(weights='imagenet', include_t
pretrained model.trainable=False
mobilenet = tf.keras.Sequential([
    pretrained_model,
    tf.keras.layers.Flatten(),
    #tf.keras.layers.Dense(10, activation='softmax')
            layers.Dense(units=128, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.3),
            layers.Dense(units=64, kernel regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.3),
            layers.Dense(units=32, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=16, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.2),
            layers.Dense(units=8, kernel_regularizer = L2Reg),
            layers.Activation("relu"),
            layers.BatchNormalization(),
            layers.Dropout(0.1),
            layers.Dense(units=4, activation='softmax')
])
```

WARNING:tensorflow:`input_shape` is undefined or non-square, or `rows` is not in [96, 128, 160, 192, 224]. Weights for input shape (224, 224) will be loaded as the default.

mobilenet.summary()

Model: "sequential_2"

Lavon (+una)	Output Chana	Danam #
Layer (type)	Output Shape ============	Param # =======
<pre>mobilenetv2_1.00_224 (Funct ional)</pre>	(None, 8, 8, 1280)	2257984
flatten_3 (Flatten)	(None, 81920)	0
dense_22 (Dense)	(None, 128)	10485888
activation_25 (Activation)	(None, 128)	0
<pre>batch_normalization_25 (Bat chNormalization)</pre>	(None, 128)	512
dropout_19 (Dropout)	(None, 128)	0
dense_23 (Dense)	(None, 64)	8256
activation_26 (Activation)	(None, 64)	0
<pre>batch_normalization_26 (Bat chNormalization)</pre>	(None, 64)	256
dropout_20 (Dropout)	(None, 64)	0
dense_24 (Dense)	(None, 32)	2080
activation_27 (Activation)	(None, 32)	0
<pre>batch_normalization_27 (Bat chNormalization)</pre>	(None, 32)	128
dropout_21 (Dropout)	(None, 32)	0
dense_25 (Dense)	(None, 16)	528
activation_28 (Activation)	(None, 16)	0
<pre>batch_normalization_28 (Bat chNormalization)</pre>	(None, 16)	64
dropout_22 (Dropout)	(None, 16)	0
dense_26 (Dense)	(None, 8)	136
activation_29 (Activation)	(None, 8)	0
<pre>batch_normalization_29 (Bat chNormalization)</pre>	(None, 8)	32
dropout_23 (Dropout)	(None, 8)	0
dense_27 (Dense)	(None, 4)	36

Total params: 12,755,900 Trainable params: 10,497,420 Non-trainable params: 2,258,480

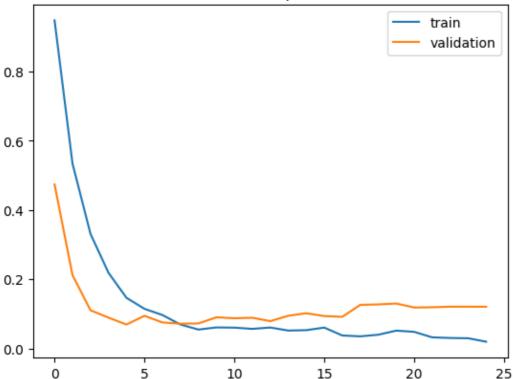
tf.keras.utils.plot_model(mobilenet, show_shapes=True) Out[67]: mobilenetv2_1.00_224_input input: [(None, 256, 256, 3)] InputLayer output: [(None, 256, 256, 3)] mobilenetv2_1.00_224 (None, 256, 256, 3) input: Functional (None, 8, 8, 1280) output: (None, 8, 8, 1280) flatten_3 input: (None, 81920) Flatten output:

model_fit4 = compile_train_v1(mobilenet, train_ds, val_ds,tb_callback,ckpt_path="/tmp/checkpoin

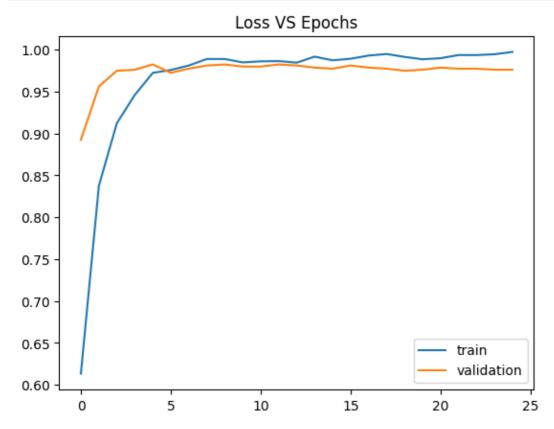
```
Epoch 1/100
100/100 [================ ] - 27s 193ms/step - loss: 0.9483 - accura
cy: 0.6133 - val_loss: 0.4741 - val_accuracy: 0.8925 - lr: 0.0010
Epoch 2/100
100/100 [================= ] - 18s 172ms/step - loss: 0.5342 - accura
cy: 0.8376 - val_loss: 0.2118 - val_accuracy: 0.9563 - lr: 0.0010
Epoch 3/100
100/100 [================ ] - 18s 179ms/step - loss: 0.3310 - accura
cy: 0.9124 - val loss: 0.1104 - val accuracy: 0.9750 - lr: 0.0010
Epoch 4/100
cy: 0.9462 - val_loss: 0.0891 - val_accuracy: 0.9762 - lr: 0.0010
Epoch 5/100
100/100 [============ ] - 18s 175ms/step - loss: 0.1464 - accura
cy: 0.9725 - val_loss: 0.0692 - val_accuracy: 0.9825 - lr: 0.0010
Epoch 6/100
100/100 [================ ] - 17s 165ms/step - loss: 0.1146 - accura
cy: 0.9759 - val_loss: 0.0944 - val_accuracy: 0.9725 - lr: 0.0010
Epoch 7/100
100/100 [=============== ] - 18s 168ms/step - loss: 0.0966 - accura
cy: 0.9812 - val_loss: 0.0752 - val_accuracy: 0.9775 - lr: 0.0010
Epoch 8/100
100/100 [================= ] - 18s 171ms/step - loss: 0.0692 - accura
cy: 0.9890 - val_loss: 0.0716 - val_accuracy: 0.9812 - lr: 0.0010
Epoch 9/100
100/100 [================= ] - 17s 165ms/step - loss: 0.0546 - accura
cy: 0.9890 - val_loss: 0.0723 - val_accuracy: 0.9825 - lr: 0.0010
Epoch 10/100
100/100 [=============== ] - 18s 174ms/step - loss: 0.0608 - accura
cy: 0.9850 - val_loss: 0.0900 - val_accuracy: 0.9800 - lr: 0.0010
Epoch 11/100
100/100 [================= ] - 17s 169ms/step - loss: 0.0602 - accura
cy: 0.9862 - val_loss: 0.0874 - val_accuracy: 0.9800 - lr: 0.0010
Epoch 12/100
100/100 [================= ] - 18s 167ms/step - loss: 0.0566 - accura
cy: 0.9865 - val_loss: 0.0887 - val_accuracy: 0.9825 - lr: 0.0010
Epoch 13/100
100/100 [================ ] - 17s 166ms/step - loss: 0.0605 - accura
cy: 0.9847 - val_loss: 0.0790 - val_accuracy: 0.9812 - lr: 0.0010
Epoch 14/100
100/100 [================= ] - 18s 175ms/step - loss: 0.0518 - accura
cy: 0.9919 - val_loss: 0.0946 - val_accuracy: 0.9787 - lr: 0.0010
Epoch 15/100
100/100 [=============== ] - 17s 165ms/step - loss: 0.0529 - accura
cy: 0.9875 - val loss: 0.1018 - val accuracy: 0.9775 - lr: 0.0010
Epoch 16/100
100/100 [================= ] - 18s 169ms/step - loss: 0.0603 - accura
cy: 0.9894 - val_loss: 0.0937 - val_accuracy: 0.9812 - lr: 0.0010
Epoch 17/100
100/100 [================ ] - 17s 169ms/step - loss: 0.0376 - accura
cy: 0.9931 - val_loss: 0.0915 - val_accuracy: 0.9787 - lr: 0.0010
Epoch 18/100
100/100 [=============== ] - 19s 184ms/step - loss: 0.0350 - accura
cy: 0.9950 - val_loss: 0.1259 - val_accuracy: 0.9775 - lr: 0.0010
Epoch 19/100
100/100 [================ ] - 17s 167ms/step - loss: 0.0397 - accura
cy: 0.9916 - val_loss: 0.1273 - val_accuracy: 0.9750 - lr: 0.0010
Epoch 20/100
100/100 [================= ] - 17s 165ms/step - loss: 0.0516 - accura
cy: 0.9887 - val_loss: 0.1298 - val_accuracy: 0.9762 - lr: 0.0010
Epoch 21/100
100/100 [=============== ] - 18s 170ms/step - loss: 0.0481 - accura
cy: 0.9900 - val_loss: 0.1184 - val_accuracy: 0.9787 - lr: 1.0000e-04
Epoch 22/100
```

```
epochs = model_fit4.epoch
loss = model_fit4.history["loss"]
val_loss = model_fit4.history["val_loss"]
plt.plot(epochs, loss, label="train")
plt.plot(epochs, val_loss, label="validation")
plt.legend()
plt.title("Loss VS Epochs")
plt.show()
```

Loss VS Epochs



```
epochs = model_fit4.epoch
loss = model_fit4.history["accuracy"]
val_loss = model_fit4.history["val_accuracy"]
plt.plot(epochs, loss, label="train")
plt.plot(epochs, val_loss, label="validation")
plt.legend()
plt.title("Loss VS Epochs")
plt.show()
```



In []:

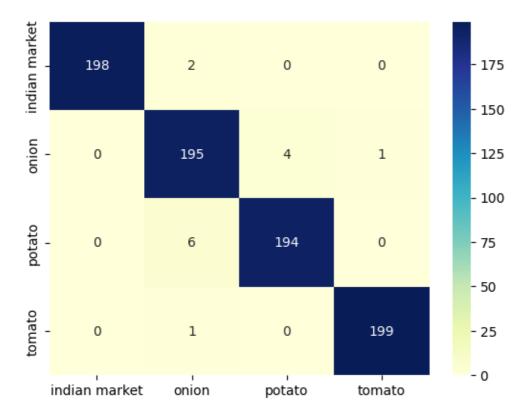
```
print_accuracy_stats(mobilenet, test_ds, class_names,"/tmp/checkpoint4")
```

11/11 [=======] - 4s 251ms/step

Accuracy: 92.31%

```
plot_confusion_matrix(mobilenet, val_ds, class_names,"/tmp/checkpoint4")
```

25/25 [=========] - 2s 94ms/step



In []:

print_accuracy_stats(mobilenet, val_ds, class_names,"/tmp/checkpoint4")

25/25 [=========] - 3s 115ms/step

Accuracy: 98.25%

In []:

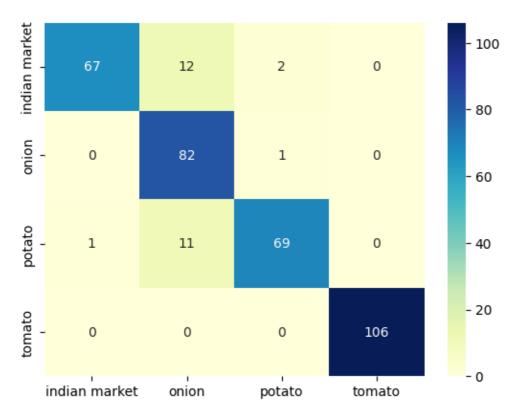
print_accuracy_stats(mobilenet, test_ds, class_names,"/tmp/checkpoint4")

11/11 [======] - 1s 111ms/step

Accuracy: 92.31%

plot_confusion_matrix(mobilenet, test_ds, class_names,"/tmp/checkpoint4")

11/11 [=======] - 1s 114ms/step



In []:	

In []:

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In []:
%tensorboardlogdir logs
<ipython.core.display.javascript object=""></ipython.core.display.javascript>
In []:
In []:
In []: