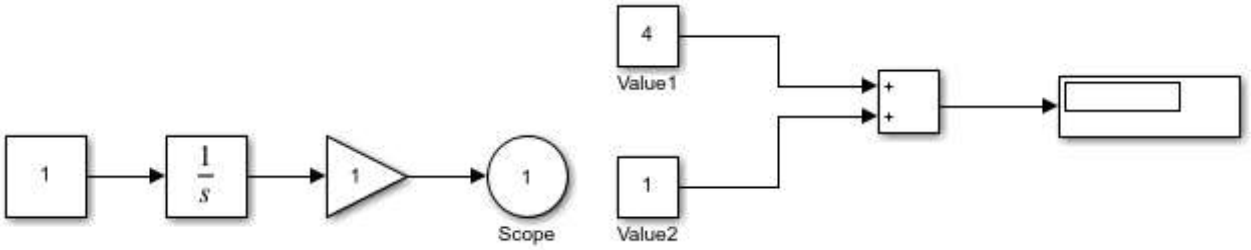
```
clc;
%%auto build
open_system(new_system('model_auto'));
add_block('simulink/Commonly Used Blocks/Constant', 'model_auto/Constant');
set_param('model_auto/Constant','position',[140,80,180,120]);
add_block('simulink/Commonly Used Blocks/Integrator','model_auto/Integrator');
set_param('model_auto/Integrator','position',[220,80,260,120]);
add_line('model_auto','Constant/1','Integrator/1');
add_block('simulink/Commonly Used Blocks/Gain','model_auto/Gain');
set_param('model_auto/Gain','position',[300,80,340,120]);
add_line('model_auto','Integrator/1','Gain/1');
add_block('simulink/Commonly Used Blocks/Out1','model_auto/Scope');
set_param('model_auto/Scope','position',[380,80,420,120]);
add_line('model_auto','Gain/1','Scope/1');

%%auto fetch and replace
RootParameterNames = fieldnames(get_param(0,'ObjectParameters'));
load_system('add_script')
GlobalParameterValue = get_param(0,'CurrentSystem')
ModelParameterValue = get_param('add_script','ModelVersion')
BlockPaths = find_system('add_script','Type','Block')

add_script
set_param('add_script','Solver','ode15s','StopTime','90')

%%auto find
text = fileread('gravity_algorithm.pdf');
Lines = strsplit(text,newline);
k=1;
for i=1:length(Lines)
    if contains(Lines{i},"<a")
        newStr = extractBetween(Lines{i},"<a",">");
        for j=1:length(newStr)
            ValueStorage{k}=newStr{j};
            k=k+1;
        end
    end
end
ValueStorage=vertcat("HTML Tag Value2",'ValueStorage');
ValueStorage_XLS=cellstr(ValueStorage);
xlswrite("gravity.xlsx",ValueStorage_XLS);
```

```
GlobalParameterValue =

    'add_script'


ModelParameterValue =

    '1.2'


BlockPaths =

  4×1 cell array

    {'add_script/Add'    }
    {'add_script/Display'}
    {'add_script/Value1' }
    {'add_script/Value2' }
```



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