
2(d) Movement of Poles.

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Description: Movement of poles is shown along the real and img axis

```
clc;
poles = [-10+20i -10-20i -5+10i -5-10i -10+10i -10-10i 3+10i 3-10i
-5+0i +5+0i -10+0i +10-0i ];
zeros = [0 0];
gain = 0.9;
s=zpk(zeros,poles,gain);
pzplot(s)
[wn,zeta] = damp(s)
```

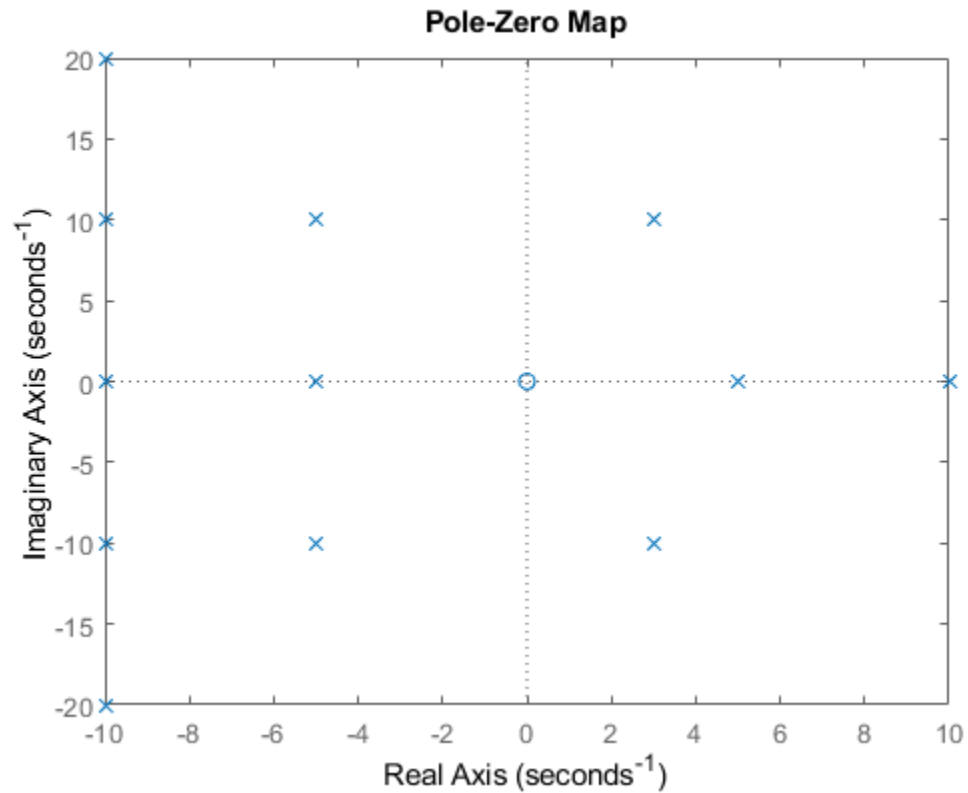
wn =

```
5.0000
5.0000
10.0000
10.0000
10.4403
10.4403
11.1803
11.1803
14.1421
14.1421
22.3607
22.3607
```

zeta =

```
1.0000
-1.0000
1.0000
-1.0000
-0.2873
-0.2873
0.4472
0.4472
0.7071
```

0.7071
 0.4472
 0.4472



Analysis

If we move along the roots along the ω_n , the frequency of the system increases. Overshoot remains same. If we move along the $j\omega$ axis, overshoot of system increases. frequency of system increases. If we move along zeta ω_n axis or sigma, Overshoot increases, frequency decreases on right side movement. Overshoot decreases, frequency increases on left side movement.

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