

---

# 2(e) Roots of the Standard Equation

## Table of Contents

code .....	1
Comparison Analysis: .....	8

Author: Pushkar Antony PS Number: 99003729 Date: 7th April 2021. Version: 1.0.

## code

```
clc;
zeta=1;
TF=tf([1],[1,(2*zeta),1])
sys = tf([1],[1,(2*zeta),1])
figure
subplot(2,3,1)
S = stepinfo(sys)
[z,p,k]= tf2zp([1],[1,(2*zeta),1])
zplane(z,p)

zeta=0.7 ;
TF=tf([1],[1,(2*zeta),1])
sys = tf([1],[1,(2*zeta),1])
subplot(2,3,2)
S = stepinfo(sys)
[z,p,k]= tf2zp([1],[1,(2*zeta),1])
zplane(z,p)

zeta=2;
TF=tf([1],[1,(2*zeta),1])
sys = tf([1],[1,(2*zeta),1])
subplot(2,3,3)
S = stepinfo(sys)
[z,p,k]= tf2zp([1],[1,(2*zeta),1])
zplane(z,p)

zeta=-1.85;
TF=tf([1],[1,(2*zeta),1])
sys = tf([1],[1,(2*zeta),1])
subplot(2,3,4)
S = stepinfo(sys)
[z,p,k]= tf2zp([1],[1,(2*zeta),1])
zplane(z,p)

zeta=-0.4;
TF=tf([1],[1,(2*zeta),1])
sys = tf([1],[1,(2*zeta),1])
subplot(2,3,5)
S = stepinfo(sys)
[z,p,k]= tf2zp([1],[1,(2*zeta),1])
```

```
zplane(z,p)

zeta=-2.45;
TF=tf([1],[1,(2*zeta),1])
sys = tf([1],[1,(2*zeta),1])
subplot(2,3,6)
S = stepinfo(sys)
[z,p,k]= tf2zp([1],[1,(2*zeta),1])
zplane(z,p)
```

*TF =*

$$\frac{1}{s^2 + 2s + 1}$$

*Continuous-time transfer function.*

*sys =*

$$\frac{1}{s^2 + 2s + 1}$$

*Continuous-time transfer function.*

*S =*

*struct with fields:*

```
    RiseTime: 3.3579
    SettlingTime: 5.8339
    SettlingMin: 0.9000
    SettlingMax: 0.9994
    Overshoot: 0
    Undershoot: 0
    Peak: 0.9994
    PeakTime: 9.7900
```

*z =*

*0x1 empty double column vector*

*p =*

```
-1
-1
```

$k =$

1

$TF =$

$$\frac{1}{s^2 + 1.4 s + 1}$$

Continuous-time transfer function.

$sys =$

$$\frac{1}{s^2 + 1.4 s + 1}$$

Continuous-time transfer function.

$S =$

struct with fields:

RiseTime: 2.1268  
SettlingTime: 5.9789  
SettlingMin: 0.9001  
SettlingMax: 1.0460  
Overshoot: 4.5986  
Undershoot: 0  
Peak: 1.0460  
PeakTime: 4.4078

$z =$

0x1 empty double column vector

$p =$

-0.7000 + 0.7141i  
-0.7000 - 0.7141i

$k =$

1

$TF =$

$$\frac{1}{s^2 + 4s + 1}$$

Continuous-time transfer function.

sys =

$$\frac{1}{s^2 + 4s + 1}$$

Continuous-time transfer function.

S =

struct with fields:

```

    RiseTime: 8.2308
    SettlingTime: 14.8789
    SettlingMin: 0.9017
    SettlingMax: 0.9993
    Overshoot: 0
    Undershoot: 0
    Peak: 0.9993
    PeakTime: 27.3269

```

z =

0×1 empty double column vector

p =

```

-3.7321
-0.2679

```

k =

1

TF =

$$\frac{1}{s^2 - 3.7s + 1}$$

Continuous-time transfer function.

`sys =`

$$\frac{1}{s^2 - 3.7 s + 1}$$

*Continuous-time transfer function.*

`S =`

*struct with fields:*

*RiseTime: NaN*  
*SettlingTime: NaN*  
*SettlingMin: NaN*  
*SettlingMax: NaN*  
*Overshoot: NaN*  
*Undershoot: NaN*  
*Peak: Inf*  
*PeakTime: Inf*

`z =`

*0×1 empty double column vector*

`p =`

*3.4064*  
*0.2936*

`k =`

*1*

`TF =`

$$\frac{1}{s^2 - 0.8 s + 1}$$

*Continuous-time transfer function.*

`sys =`

$$\frac{1}{s^2 - 0.8 s + 1}$$

$$s^2 - 0.8 s + 1$$

Continuous-time transfer function.

$S =$

struct with fields:

```

    RiseTime: NaN
    SettlingTime: NaN
    SettlingMin: NaN
    SettlingMax: NaN
    Overshoot: NaN
    Undershoot: NaN
    Peak: Inf
    PeakTime: Inf

```

$z =$

0×1 empty double column vector

$p =$

```

    0.4000 + 0.9165i
    0.4000 - 0.9165i

```

$k =$

1

$TF =$

$$\frac{1}{s^2 - 4.9 s + 1}$$

Continuous-time transfer function.

$sys =$

$$\frac{1}{s^2 - 4.9 s + 1}$$

Continuous-time transfer function.

$S =$

*struct with fields:*

*RiseTime: NaN*  
*SettlingTime: NaN*  
*SettlingMin: NaN*  
*SettlingMax: NaN*  
*Overshoot: NaN*  
*Undershoot: NaN*  
*Peak: Inf*  
*PeakTime: Inf*

*z =*

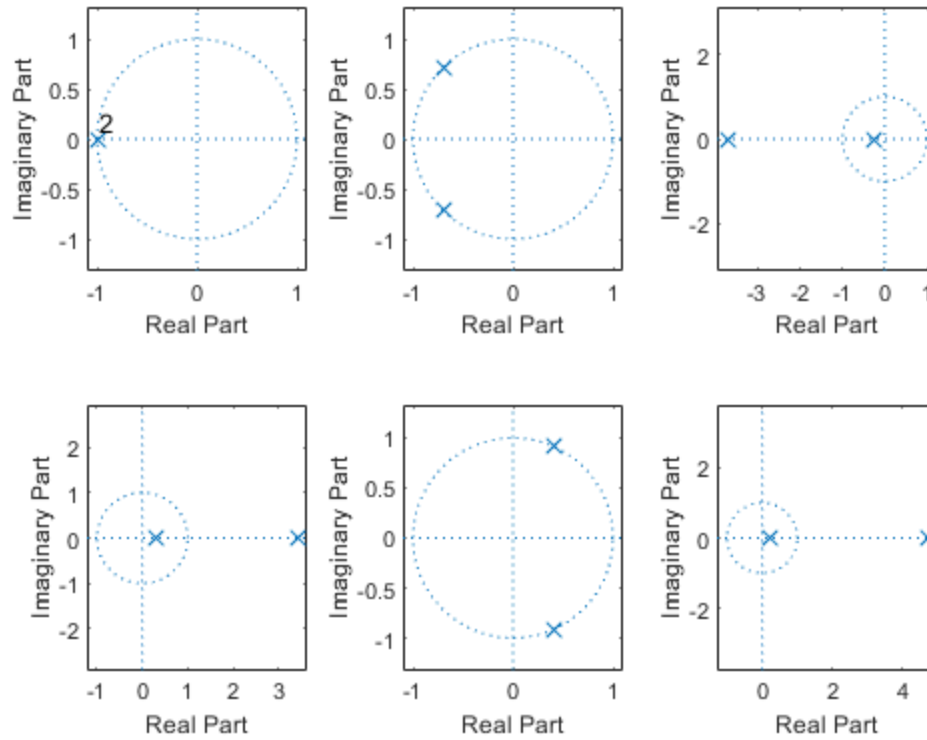
*0×1 empty double column vector*

*p =*

*4.6866*  
*0.2134*

*k =*

*1*



## Comparison Analysis:

1st value lie on negative x axis means: Critically-damped case & stable  
 2nd value lie in 2nd & 3rd quadrant means: Under-damp case & stable  
 3rd value lie on negative x axis means: Overdamped case & stable  
 4th value lie on positive x axis means: unstable  
 5th value lie on 1st & 4th quadrant means: unstable  
 6th value lie on positive x axis means: unstable

*Published with MATLAB® R2020b*